Annex B: Probe and dipole description and calibration certificates

B.1 Probe, measurement chain description, specification and calibration certificate

DASY Dosimetric Assessment System by Schmid & Partner Engineering AG

Applications

Support & Downloads

Products

- DASY4 Packages
- EASY4
- Probes
  - ET3DV6 - Isotropic Dos-Probe
  - ES3DV3 - Isotropic Dos-Probe
  - EX3DV4 - Isotropic Dos-Probe
  - ET1DV3 - D-Probe
  - EUV3 - Universal Vector E-Probe
  - H3DV6 - Isotropic H-Probe
  - HUV4 - Universal Vector H-Probe
  - T1V3 - Temp-Probe
  - DP1 - Dummy-Probe
- Data Acquisition System
- Software
- Phantoms
- Robots
- Validation Kits & Calibration Dipoles
- Hearing Aid Compatibility (HAC) Ext
- Tissue Simulating Liquids

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ER3DV6 ISOTROPIC E-FIELD PROBE FOR GENERAL NEAR-FIELD MEASUREMENTS

Download Product Flyer (PDF, 192kB)

Construction	One dipole parallel, two dipoles normal to probe axis Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycolether)
Calibration	In air from 100 MHz to 3.0 GHz (absolute accuracy ±6.0%, k=2)
Frequency	100 MHz to > 6 GHz; Linearity: ± 0.2 dB (100 MHz to 3 GHz)
Directivity	± 0.2 dB in air (rotation around probe axis) ± 0.4 dB in air (rotation normal to probe axis)
Dynamic Range	2 V/m to > 1000 V/m; Linearity: ± 0.2 dB
Dimensions	Overall length: 330 mm (Tip: 16 mm) Tip diameter: 8 mm (Body: 12 mm) Distance from probe tip to dipole centers: 2.5 mm
Application	General near-field measurements up to 6 GHz Field component measurements Fast automatic scanning in phantoms

http://www.dasy4.com/er3.htm

DASY Dosimetric Assessment System by Schmid & Partner Engineering AG

Applications

Support & Downloads

Products

- DASY4 Packages
- EASY4
- Probes
  - ET3DV6 - Isotropic Dos-Probe
  - ES3DV3 - Isotropic Dos-Probe
  - EX3DV4 - Isotropic Dos-Probe
  - ET1DV3 - D-Probe
  - ER3DV6 - Isotropic E-Probe
  - EUV3 - Universal Vector E-Probe
  - HUV4 - Universal Vector H-Probe
  - T1V3 - Temp-Probe
  - DP1 - Dummy-Probe
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H3DV6 3-DIMENSIONAL H-FIELD PROBE FOR SMALL BAND APPLICATIONS

Download Product Flyer (PDF, 192kB)

Construction	Three concentric loop sensors with 3.8 mm loop diameters Resistively loaded detector diodes for linear response Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycolether)
Frequency	200 MHz to 3 GHz (absolute accuracy ± 6.0%, k=2); Output linearized
Directivity	± 0.25 dB (spherical isotropy error)
Dynamic Range	10 mA/m to 2 A/m at 1 GHz
E-Field Interference	< 10% at 3 GHz (for plane wave)
Dimensions	Overall length: 330 mm (Tip: 40 mm) Tip diameter: 6 mm (Body: 12 mm) Distance from probe tip to dipole centers: 3 mm
Application	General magnetic near-field measurements up to 3 GHz Field component measurements Surface current measurements Measurements in air or liquids Low interaction with the measured field

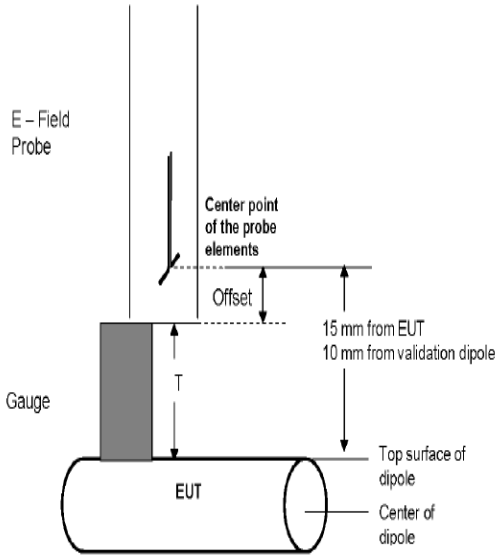
http://www.dasy4.com/h3d.htm

All measurements were performed to the nearest element point as per the C63.19 standard. Offset distances were entered in the DASY4 software so that the measurement was to the nearest element.

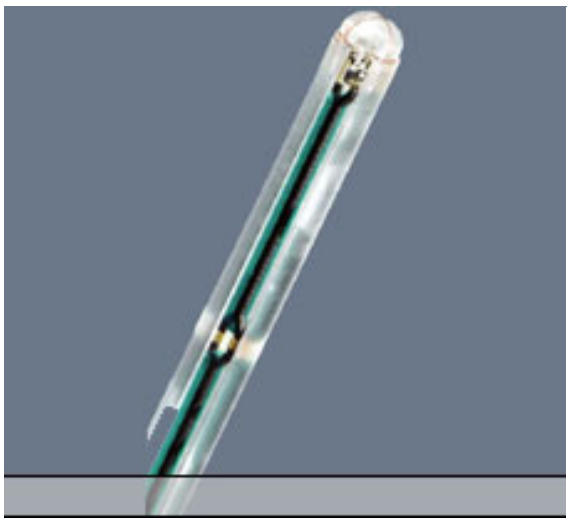
Figures 1 and 2, provided by the manufacturer, illustrate detail of the probe tip and its dimensions.

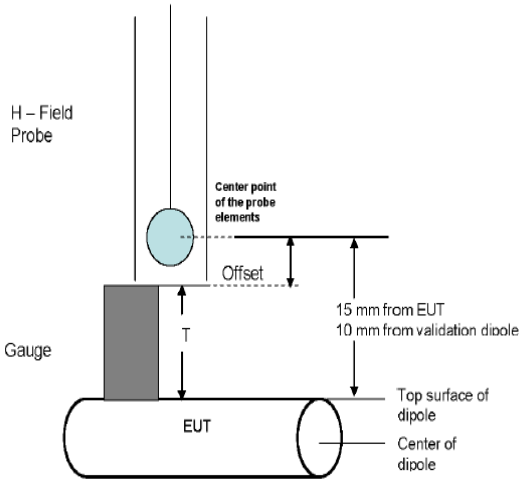
ER3DV6 E-Field probe: The distances from the probe tip to the closest points on the dipole sensors are 1.45mm for X and Y and 1.25mm for Z. From the probe tip to the center of the sensors is 2.5mm.

H3DV6 H-Field probe: The distance from the probe tip to the closest point of the X, Y and Z loop sensors is 1.1mm. From the probe tip to the center of the sensor is 3.00mm.



E-Field Probe (ER3DV6)





H-Field Probe (H3DV6)

The following information is from the system manufacturer user manual describing the process chain:

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i} \tag{20.1}$$

with V_i = compensated signal of channel i (i = x, y, z)
U_i = input signal of channel i (i = x, y, z)
cf = crest factor of exciting field (DASY parameter)
dcp_i = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$\text{E} - \text{fieldprobes}: \quad E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

$$\text{H} - \text{fieldprobes}: \quad H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1} f + a_{i2} f^2}{f}$$

with V_i = compensated signal of channel i (i = x, y, z)
$Norm_i$ = sensor sensitivity of channel i (i = x, y, z)
$\mu V/(V/m)^2$ for E-field Probes
$ConvF$ = sensitivity enhancement in solution
a_{ij} = sensor sensitivity factors for H-field probes
f = carrier frequency [GHz]
E_i = electric field strength of channel i in V/m
H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2} \tag{20.2}$$

The measurement / integration time per point is > 500 ms, as per the system manufacturer:

The time response of the field probes has been assessed by exposing the probe to a well-controlled field producing signals larger than HAC E- and H-fields of class M4. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/off switch of the power source with an integration time of 500 ms and a probe response time of <5 ms. In the current implementation, DASY4 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization. The tolerances for the different systems had the worst-case of 2.6%.

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Accreditation No.: SCS 108

Client RTS (RIM Testing Services) **Certificate No:** ER3-2286_Jan10

CALIBRATION CERTIFICATE

Object: ER3DV6 - SN:2286

Calibration procedure(s): QA CAL-02.v5 and QA CAL-25.v2
Calibration procedure for E-field probes optimized for close near field evaluations in air

Calibration date: January 8, 2010

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	1-Apr-09 (No. 217-01030)	Apr-10
Power sensor E4412A	MY41495277	1-Apr-09 (No. 217-01030)	Apr-10
Power sensor E4412A	MY41498087	1-Apr-09 (No. 217-01030)	Apr-10
Reference 3 dB Attenuator	SN: S5054 (3c)	31-Mar-09 (No. 217-01026)	Mar-10
Reference 20 dB Attenuator	SN: S5086 (20b)	31-Mar-09 (No. 217-01028)	Mar-10
Reference 30 dB Attenuator	SN: S5129 (30b)	31-Mar-09 (No. 217-01027)	Mar-10
Reference Probe ER3DV6	SN: 2328	3-Oct-09 (No. ER3-2328_Oct09)	Oct-10
DAE4	SN: 789	23-Dec-09 (No. DAE4-789_Dec09)	Dec-10

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	
Approved by:	Niels Kuster	Quality Manager	

Issued: January 8, 2010

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: ER3-2286_Jan10 Page 1 of 10

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Accreditation No.: SCS 108

Glossary:

NORMx,y,z	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., ϑ = 0 is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1309-2005, " IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization ϑ = 0 for XY sensors and ϑ = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- *NORM(f)x,y,z = NORMx,y,z * frequency_response* (see Frequency Response Chart).
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C* are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. *VR* is the maximum calibration range expressed in RMS voltage across the diode.
- *Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle*: The angle is assessed using the information gained by determining the *NORMx* (no uncertainty required).

Probe ER3DV6

SN:2286

Manufactured:	September 18, 2002
Last calibrated:	January 8, 2009
Recalibrated:	January 8, 2010

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

ER3DV6 SN:2286 January 8, 2010

DASY - Parameters of Probe: ER3DV6 SN:2286

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (μV/(V/m)^2)	2.23	1.50	1.54	± 10.1%
DCP (mV)[A]	94.9	94.8	95.7	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc[E] (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	± 1.5 %
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

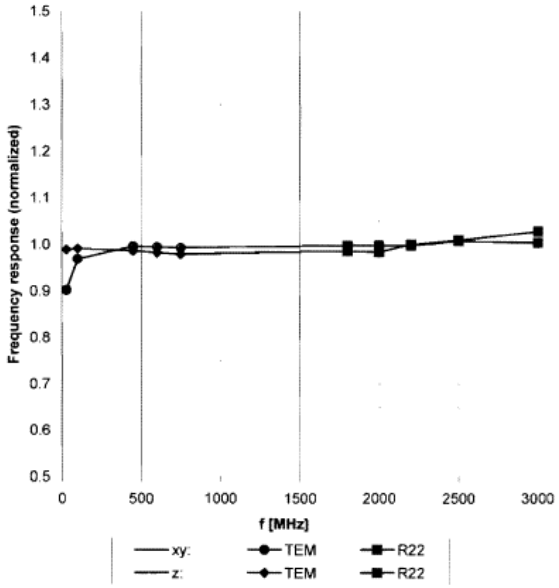
[A] numerical linearization parameter: uncertainty not required

[E] Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

ER3DV6 SN:2286 January 8, 2010

Frequency Response of E-Field

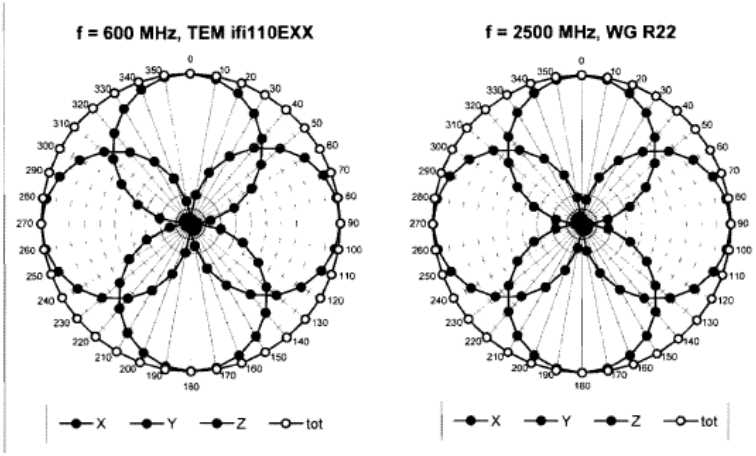
(TEM-Cell:ifi110 EXX, Waveguide R22)



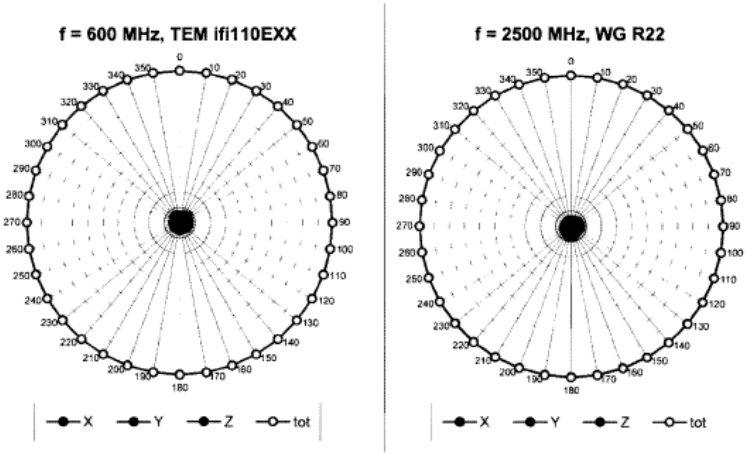
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

ER3DV6 SN:2286 January 8, 2010

Receiving Pattern (ϕ), ϑ = 0°

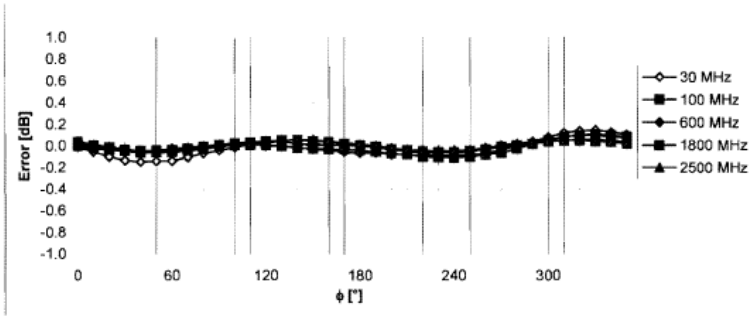


Receiving Pattern (ϕ), ϑ = 90°



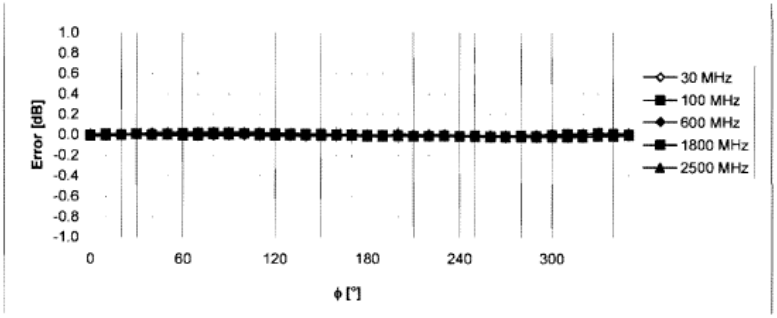
ER3DV6 SN:2286 **January 8, 2010**

Receiving Pattern (ϕ), ϑ = 0°



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Receiving Pattern (ϕ), ϑ = 90°

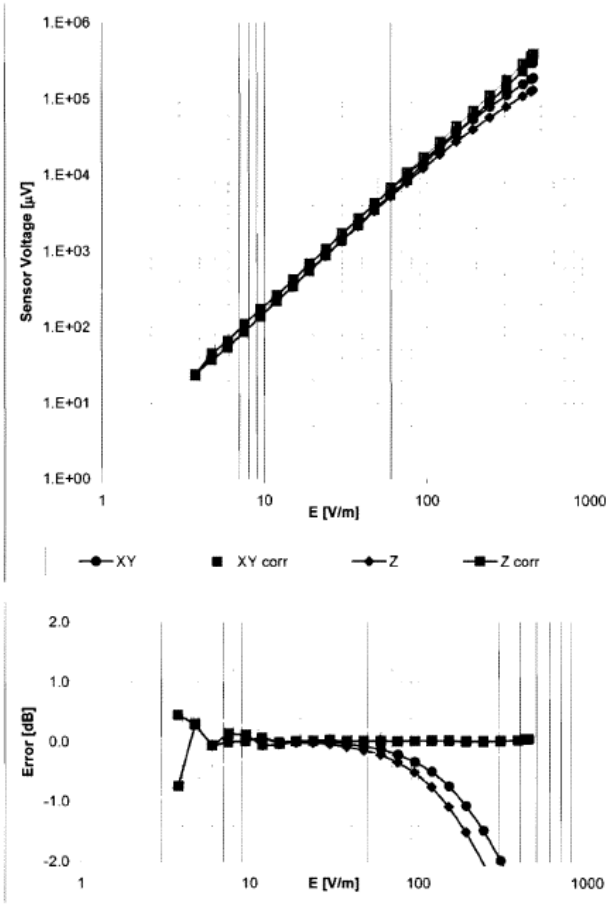


Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

ER3DV6 SN:2286 January 8, 2010

Dynamic Range f(E-field)

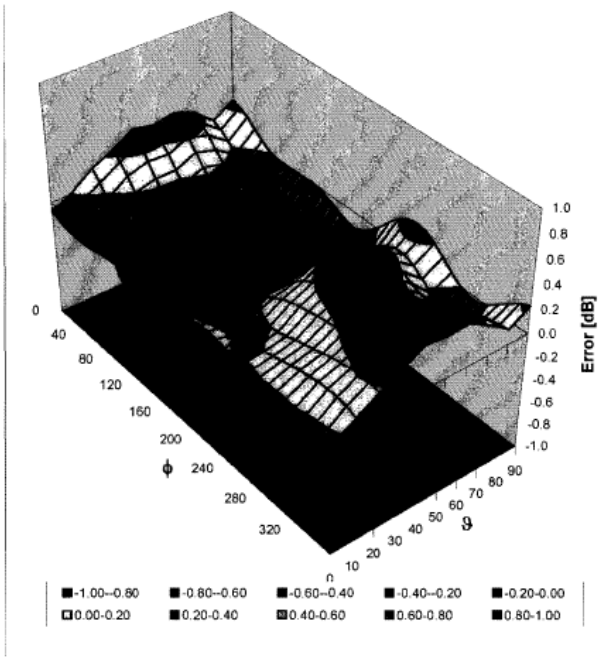
(Waveguide R22, f = 1800 MHz)



Uncertainty of Linearity Assessment: ± 0.6% (k=2)

ER3DV6 SN:2286 January 8, 2010

Deviation from Isotropy in Air
Error (ϕ, ϑ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-9.5
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8.0 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

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Accreditation No.: SCS 108

Client RTS (RIM Testing Services) **Certificate No: H3-6105_Nov09**

CALIBRATION CERTIFICATE

Object: H3DV6 - SN:6105

Calibration procedure(s): QA CAL-03.v5 and QA CAL-25.v2
Calibration procedure for H-field probes optimized for close near field evaluations in air

Calibration date: November 13, 2009

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	1-Apr-09 (No. 217-01030)	Apr-10
Power sensor E4412A	MY41495277	1-Apr-09 (No. 217-01030)	Apr-10
Power sensor E4412A	MY41498087	1-Apr-09 (No. 217-01030)	Apr-10
Reference 3 dB Attenuator	SN: S5054 (3c)	31-Mar-09 (No. 217-01026)	Mar-10
Reference 20 dB Attenuator	SN: S5086 (20b)	31-Mar-09 (No. 217-01028)	Mar-10
Reference 30 dB Attenuator	SN: S5129 (30b)	31-Mar-09 (No. 217-01027)	Mar-10
Reference Probe H3DV6	SN: 6182	3-Oct-09 (No. H3-6182_Oct09)	Oct-10
DAE4	SN: 789	19-Dec-08 (No. DAE4-789_Dec08)	Dec-09

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	
Approved by:	Niels Kuster	Quality Manager	

Issued: November 13, 2009

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Accreditation No.: SCS 108

Glossary:

NORMx,y,z	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., ϑ = 0 is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1309-2005, " IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization ϑ = 0 for XY sensors and ϑ = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- *X,Y,Z(f)_a0a1a2= X,Y,Z_a0a1a2* frequency_response* (see Frequency Response Chart).
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C* are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. *VR* is the maximum calibration range expressed in RMS voltage across the diode.
- *Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle*: The angle is assessed using the information gained by determining the *X_a0a1a2* (no uncertainty required).

Probe H3DV6

SN:6105

Manufactured:	January 5, 2002
Last calibrated:	November 10, 2008
Recalibrated:	November 13, 2009

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

DASY - Parameters of Probe: H3DV6 SN:6105

Basic Calibration Parameters

		Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (A/m / √(μV))	a0	2.89E-3	2.67E-3	3.00E-3	± 5.1%
Norm (A/m / √(μV))	a1	6.03E-5	3.03E-5	-9.91E-5	± 5.1%
Norm (A/m / √(μV))	a2	-1.23E-5	3.46E-6	1.02E-5	± 5.1%
DCP (mV)[A]		89.5	84.4	83.4	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc[E] (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	± 1.5%
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

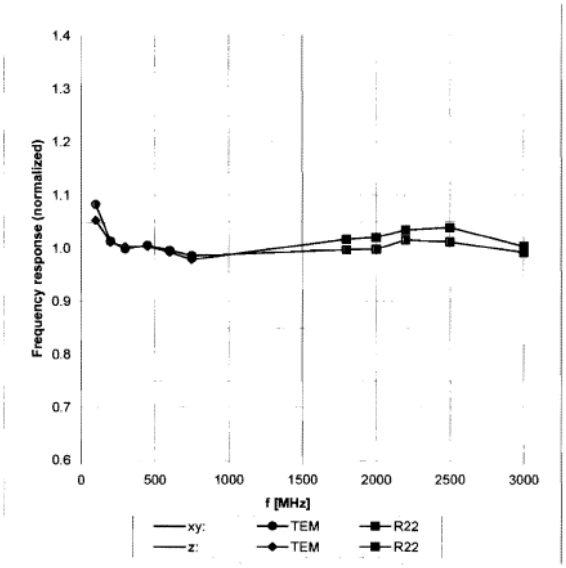
[A] numerical linearization parameter: uncertainty not required

[E] Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

H3DV6 SN:6105 November 13, 2009

Frequency Response of H-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)

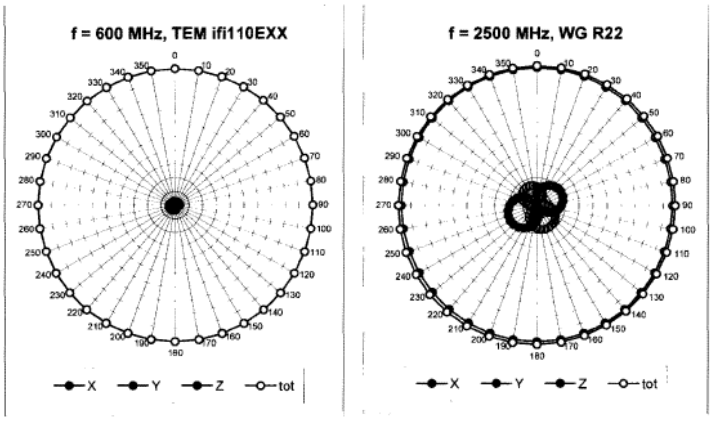


Uncertainty of Frequency Response of H-field: ± 6.3% (k=2)

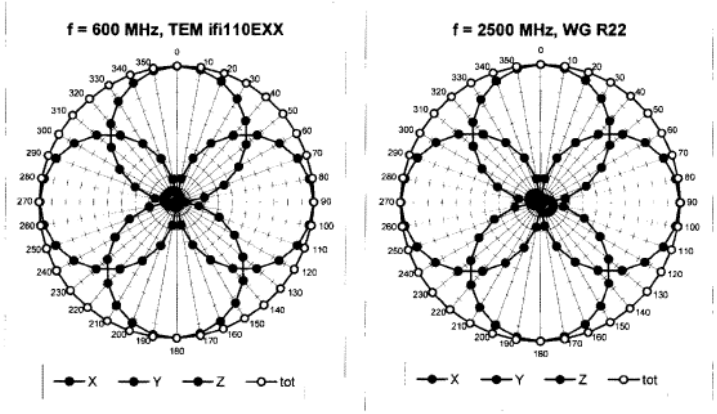
ervices

H3DV6 SN:6105 November 13, 2009

Receiving Pattern (ϕ), ϑ = 90°



Receiving Pattern (ϕ), ϑ = 0°



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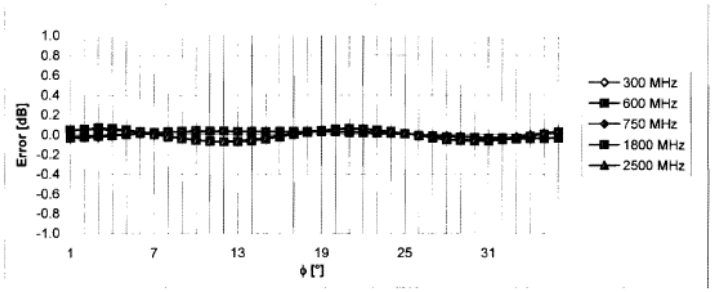
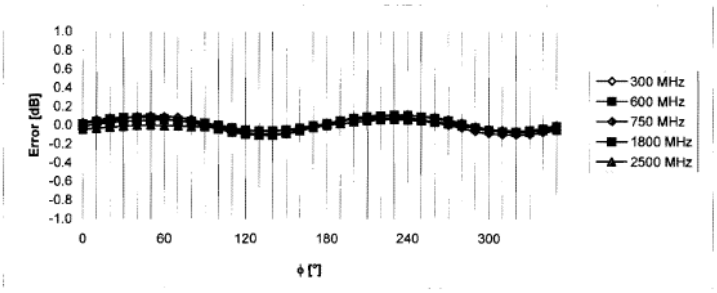
H3DV6 SN:6105 November 13, 2009

Receiving Pattern (ϕ), ϑ = 90°



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Receiving Pattern (ϕ), ϑ = 0°



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

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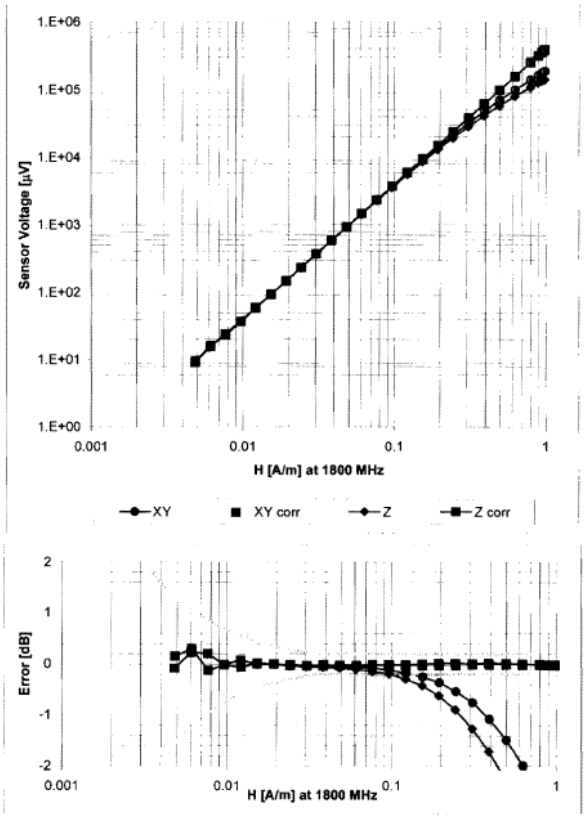
H3DV6 SN:6105 November 13, 2009

Dynamic Range f(H-field)

(Waveguide R22, f = 1800 MHz)



Uncertainty of Linearity Assessment: ± 0.6% (k=2)

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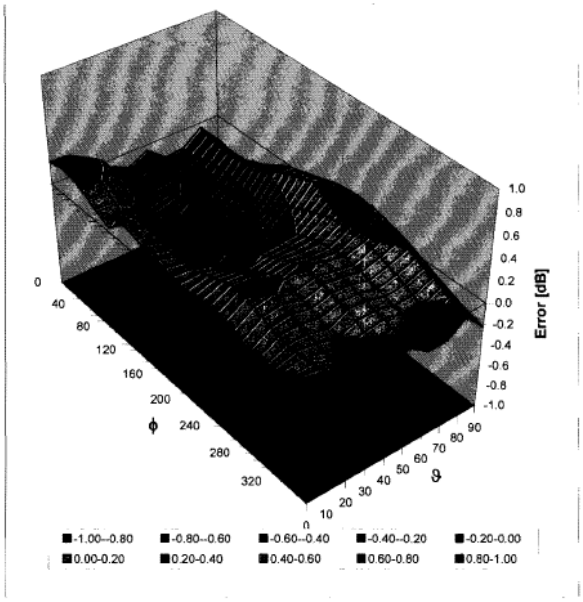
Deviation from Isotropy in Air
Error (ϕ, ϑ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-243.0
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6.0 mm
Probe Tip to Sensor X Calibration Point	3 mm
Probe Tip to Sensor Y Calibration Point	3 mm
Probe Tip to Sensor Z Calibration Point	3 mm