|   | CTC advanced  |  |  |  |  |  |
|---|---|--|--|--|--|--|
| Bundesnetzagentur       TEST REPORT         Test Report No.: 1-5466/17-01-04       Image: Comparison of the part of the par |   |  |  |  |  |  |
| BNetzA-CAB-02/21-102  Testing Laboratory Applicant  |   |  |  |  |  |  |
| CTC advanced GmbHPHONAK Communications AGUntertuerkheimer Strasse 6 – 10Laenggasse 1766117 Saarbruecken/Germany3280 Murten/SWITZERLANDPhone: + 49 681 5 98 - 0Phone: +41 2 66 72 96 72Fax: + 49 681 5 98 - 9075Phone: +41 2 66 72 96 72Internet: http://www.ctcadvanced.comContact: Neviana Nikoloskie-mail: mail@ctcadvanced.comContact: Neviana Nikoloskie-mail: mail@ctcadvanced.comPhone: +41 2 66 72 92 42The testing laboratory (area of testing) is accredited<br>according to DIN EN ISO/IEC 17025 (2005) by the<br>Deutsche Akkreditierungsstelle GmbH (DAkkS)<br>The accreditation is valid for the scope of testing<br>procedures as stated in the accreditation certificate with<br>the registration number: D-PL-12076-01-03ManufacturerPHONAK Communications AG<br>Laenggasse 17<br>3280 Murten/SWITZERLANDPhone: +41 2 66 72 92 42   |   |  |  |  |  |  |
| (SAR) in the Human H  | <b>Test Standards</b><br>ce for Determining the Peak Spatial-Average Specific Absorption Rate<br>lead from Wireless Communications Devices: Measurement Techniques<br>osure Compliance of Radiocommunication Apparatus (All Frequency<br>o section 3 of this test report. |  |  |  |  |  |
| Taat l  | tom   |  |  |  |  |  |
| Test ItemKind of test item:Radio microphone for hearing impairedDevice type:portable deviceModel name:Roger SelectS/N serial number:1749CY001FCC-ID:KWCTX27IC:2262A-TX27Product Marketing Name (PMN):Roger SelectHardware Version Identification No. (HVIN):Roger SelectHardware status:V3.1Software status:V3.1Software status:V1.0.36358_beta01Frequency:BT 2450 MHz and<br>Roger Tx proprietary (ISM 2450 MHz)Antenna:integrated antennaBattery option:3.8 V DC by battery packAccessories:Test sample status:identical prototypeExposure category:general population / uncontrolled environmentThis test report is electronically signed and valid without handwriting signature. For verification of the electronic  |   |  |  |  |  |  |

This test report is electronically signed and valid without handwriting signature. For verification of the electronic signatures, the public keys can be requested at the testing laboratory.

## **Test Report authorised:**

Alexander Hnatovskiy Lab Manager Radio Communications & EMC

# **Test performed:**

Marco Scigliano Testing Manager Radio Communications & EMC



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## 2 General information

#### 2.1 Notes and disclaimer

The test results of this test report relate exclusively to the test item specified in this test report. CTC advanced GmbH does not assume responsibility for any conclusions and generalisations drawn from the test results with regard to other specimens or samples of the type of the equipment represented by the test item. The test report may only be reproduced or published in full. Reproduction or publication of extracts from the report requires the prior written approval of CTC advanced GmbH.

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In no case this test report can be considered as a Letter of Approval.

#### 2.2 Application details

| Date of receipt of order:          | 2017-12-13 |
|------------------------------------|------------|
| Date of receipt of test item:      | 2018-01-03 |
| Start of test:                     | 2018-01-05 |
| End of test:                       | 2018-01-05 |
| Person(s) present during the test: |            |

#### 2.3 Statement of compliance

The SAR values found for the Roger Select Radio microphone for hearing impaired are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1 g tissue according to the FCC rule §2.1093, the ANSI/IEEE C 95.1:1992, the NCRP Report Number 86 for uncontrolled environment, according to the Health Canada's Safety Code 6 and the Industry Canada Radio Standards Specification RSS-102 for General Population/Uncontrolled exposure.



# 2.4 Technical details

| Band tested for this test report | Technology    | Lowest transmit frequency/MHz | Highest transmit frequency/MHz | Lowest receive Frequency/MHz | Highest receive Frequency/MHz | Kind of modulation | Power Class | Tested power control level | Test channel low | Test channel middle | Test channel high | Max. avg. output power/dBm |
|----------------------------------|---------------|-------------------------------|--------------------------------|------------------------------|-------------------------------|--------------------|-------------|----------------------------|------------------|---------------------|-------------------|----------------------------|
| $\square$                        | BT 2450       | 2402                          | 2480                           | 2402                         | 2480                          | GFSK               | 3           | max                        | 0                | 39                  | 78                | -0.1                       |
| $\square$                        | Roger Tx 2450 | 2402                          | 2480                           | 2402                         | 2480                          | CW                 |             | max                        | 0                | 39                  | 78                | 16.0                       |



# 3 Test standards/ procedures references

| Test Standard                 | Version                     | Test Standard Description  |  |
|-------------------------------|-----------------------------|--|--|
| IEEE 1528-2013                | 2013-06                     | Recommended Practice for Determining the Peak Spatial-<br>Average Specific Absorption Rate (SAR) in the Human<br>Head from Wireless Communications Devices:<br>Measurement Techniques  |  |
| RSS-102 Issue 5               | 2015-03                     | Radio Frequency Exposure Compliance of Radiocommuni-<br>cation Apparatus (All Frequency Bands)   |  |
| Canada's Safety<br>Code No. 6 | 2015-06                     | Limits of Human Exposure to Radiofrequency Electromag-<br>netic Fields in the Frequency Range from 3 kHz to 300 GHz  |  |
| IEEE Std. C95-3               | 2002                        | IEEE Recommended Practice for the Measurement of<br>Potentially Hazardous Electromagnetic Fields – RF and<br>Microwave   |  |
| IEEE Std. C95-1               | 2005                        | IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.  |  |
| IEC 62209-2                   | 2010                        | Human exposure to radio frequency fields from hand-held<br>and bodymounted wireless communication devices.<br>Human models, instrumentation, and procedures.<br>Procedure to determine the specific absorption rate (SAR)<br>for wireless communication devices used in close<br>proximity to the human body (frequency range of 30 MHz<br>to 6 GHz) |  |
| FCC KDBs:                     |                             |  |  |
| KDB 865664D01v01              | August 7,<br>2015           | FCC OET SAR measurement requirements 100 MHz to 6 GHz  |  |
| KDB 865664D02v01              | October 23,                 | RF Exposure Compliance Reporting and Documentation   |  |
| KDB 447498D01v06              | 2015<br>October 23,<br>2015 | Considerations<br>Mobile and Portable Devices RF Exposure Procedures and<br>Equipment Authorization Policies   |  |



#### 3.1 RF exposure limits

| Human Exposure                                  | Uncontrolled Environment<br>General Population | Controlled Environment<br>Occupational |
|---|--|--|
| Spatial Peak SAR*<br>(Brain and Trunk)          | 1.60 mW/g                                      | 8.00 mW/g                              |
| Spatial Average SAR**<br>(Whole Body)           | 0.08 mW/g                                      | 0.40 mW/g                              |
| Spatial Peak SAR***<br>(Hands/Feet/Ankle/Wrist) | 4.00 mW/g                                      | 20.00 mW/g                             |

Table 1: RF exposure limits

The limit applied in this test report is shown in bold letters

Notes:

- The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time
- \*\* The Spatial Average value of the SAR averaged over the whole body.
- \*\*\* The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).



## 4 Summary of Measurement Results

| No deviations from the technical specifications ascertained |  |       |     |  |
|---|--|-------|-----|--|
| Deviations from the technical specifications ascertained    |  |       |     |  |
| Maximum SAR value (W/kg)                                    |  |       |     |  |
| reported limit  |  |       |     |  |
| body worn 0 mm distance for 1g                              |  | 1.405 | 1.6 |  |

#### 4.1 SAR measurement variability and measurement uncertainty analysis

This analysis is required for worst case results larger than 0.8 W/kg.

| frequency band | highest original measurement  | repeated measurement | ratio <1.2 |
|----------------|-------------------------------|----------------------|------------|
|                | result at worst case position |                      |            |
|                | (W/kg)                        | position (W/kg)      |            |
| RogerTx 2450   | 1.070                         | 1.150                | 1.07       |

#### 5 Test Environment

| Ambient temperature:       | 20 – 24 °C           |
|----------------------------|----------------------|
| Tissue Simulating liquid:  | 20 – 24 °C           |
| Relative humidity content: | 40 – 50 %            |
| Air pressure:              | not relevant for thi |

Air pressure:not relevant for this kind of testingPower supply:230 V / 50 Hz

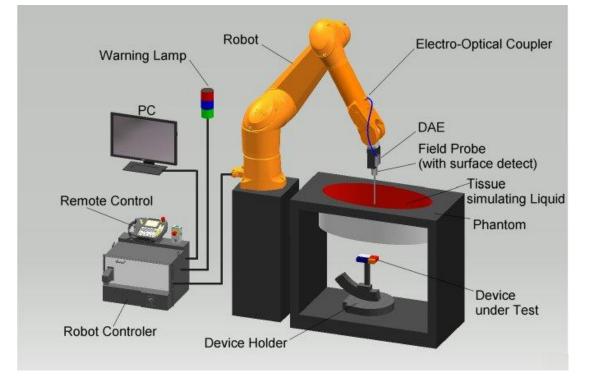
Exact temperature values for each test are shown in the table(s) under 7.1 and/or on the measurement plots.



#### 6 Test Set-up

### 6.1 Measurement system

## 6.1.1 System Description



- The DASY system for performing compliance tests consists of the following items:
- A standard high precision 6-axis robot (Stäubli RX/TX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e. an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid.
- A data acquisition electronic (DAE) which performs the signal amplification, signal multiplexing, ADconversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The <u>Electro-Optical Coupler (EOC)</u> performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the DASY measurement server.
- The DASY measurement server, which performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. A computer operating Windows 7.
- DASY software and SEMCAD data evaluation software.
- Remote control with teach panel and additional circuitry for robot safety such as warning lamps, etc.
- The generic twin phantom enabling the testing of left-hand and right-hand usage.
- The triple flat and eli phantom for the testing of handheld and body-mounted wireless devices.
- The device holder for handheld mobile phones and mounting device adaptor for laptops
- Tissue simulating liquid mixed according to the given recipes.
- System check dipoles allowing to validate the proper functioning of the system.



### 6.1.2 Test environment

The DASY measurement system is placed in a laboratory room within an environment which avoids influence on SAR measurements by ambient electromagnetic fields and any reflection from the environment. The pictures at the beginning of the photo documentation show a complete view of the test environment. The system allows the measurement of SAR values larger than 0.005 mW/g.

### 6.1.3 **Probe description**

| Isotropic E-Field Probe ES3DV3 for Dosimetric Measurements   |   |  |  |  |  |
|--|---|--|--|--|--|
| Technical data according to manufacturer information   |   |  |  |  |  |
| Construction   | Symmetrical design with triangular core   |  |  |  |  |
|  | Interleaved sensors   |  |  |  |  |
|  | Built-in shielding against static charges   |  |  |  |  |
|  | PEEK enclosure material (resistant to organic solvents,   |  |  |  |  |
|  | e.g., butyl diglycol)   |  |  |  |  |
| Calibration  | Calibration certificate in Appendix D   |  |  |  |  |
| Frequency  | 10 MHz to 3 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 3   |  |  |  |  |
| Trequency  | GHz)  |  |  |  |  |
| Directivity  | $\pm 0.2$ dB in HSL (rotation around probe axis)  |  |  |  |  |
|  | ± 0.3 dB in HSL (rotation normal to probe axis)   |  |  |  |  |
| Dynamic range  | 5 μW/g to > 100 mW/g; Linearity: ± 0.2 dB   |  |  |  |  |
| Dimensions   | Overall length: 330 mm  |  |  |  |  |
|  | Tip length: 20 mm   |  |  |  |  |
|  | Body diameter: 12 mm  |  |  |  |  |
|  | Tip diameter: 3.9 mm  |  |  |  |  |
|  | Distance from probe tip to dipole centers: 2.0 mm   |  |  |  |  |
| Application  | General dosimetry up to 3 GHz   |  |  |  |  |
|  | Compliance tests of mobile phones   |  |  |  |  |
|  | Fast automatic scanning in arbitrary phantoms (ES3DV3)  |  |  |  |  |
|  |   |  |  |  |  |
|  | e EX3DV4 for Dosimetric Measurements  |  |  |  |  |
| Technical data   | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information   |  |  |  |  |
|  | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core  |  |  |  |  |
| Technical data   | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core<br>Interleaved sensors   |  |  |  |  |
| Technical data   | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core<br>Interleaved sensors<br>Built-in shielding against static charges  |  |  |  |  |
| Technical data   | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core<br>Interleaved sensors<br>Built-in shielding against static charges<br>PEEK enclosure material (resistant to organic solvents, e.g.,   |  |  |  |  |
| Technical data<br>Construction   | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core<br>Interleaved sensors<br>Built-in shielding against static charges<br>PEEK enclosure material (resistant to organic solvents, e.g.,<br>DGBE)  |  |  |  |  |
| Technical data<br>Construction   | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core<br>Interleaved sensors<br>Built-in shielding against static charges<br>PEEK enclosure material (resistant to organic solvents, e.g.,<br>DGBE)<br>ISO/IEC 17025 calibration service available.  |  |  |  |  |
| Technical data<br>Construction   | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core<br>Interleaved sensors<br>Built-in shielding against static charges<br>PEEK enclosure material (resistant to organic solvents, e.g.,<br>DGBE)  |  |  |  |  |
| Technical data<br>Construction   | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core<br>Interleaved sensors<br>Built-in shielding against static charges<br>PEEK enclosure material (resistant to organic solvents, e.g.,<br>DGBE)<br>ISO/IEC 17025 calibration service available.<br>10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to<br>6 GHz)  |  |  |  |  |
| Technical data<br>Construction<br>Calibration<br>Frequency   | e EX3DV4 for Dosimetric Measurements         according to manufacturer information         Symmetrical design with triangular core         Interleaved sensors         Built-in shielding against static charges         PEEK enclosure material (resistant to organic solvents, e.g., DGBE)         ISO/IEC 17025 calibration service available.         10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz)         ± 0.3 dB in HSL (rotation around probe axis)  |  |  |  |  |
| Technical data<br>Construction<br>Calibration<br>Frequency   | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core<br>Interleaved sensors<br>Built-in shielding against static charges<br>PEEK enclosure material (resistant to organic solvents, e.g.,<br>DGBE)<br>ISO/IEC 17025 calibration service available.<br>10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to<br>6 GHz)  |  |  |  |  |
| Technical data<br>Construction<br>Calibration<br>Frequency<br>Directivity  | e EX3DV4 for Dosimetric Measurements         according to manufacturer information         Symmetrical design with triangular core         Interleaved sensors         Built-in shielding against static charges         PEEK enclosure material (resistant to organic solvents, e.g., DGBE)         ISO/IEC 17025 calibration service available.         10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz)         ± 0.3 dB in HSL (rotation around probe axis)         ± 0.5 dB in tissue material (rotation normal to probe axis)  |  |  |  |  |
| Technical data<br>Construction<br>Calibration<br>Frequency<br>Directivity  | e EX3DV4 for Dosimetric Measurements<br>according to manufacturer information<br>Symmetrical design with triangular core<br>Interleaved sensors<br>Built-in shielding against static charges<br>PEEK enclosure material (resistant to organic solvents, e.g.,<br>DGBE)<br>ISO/IEC 17025 calibration service available.<br>10 MHz to >6 GHz (dosimetry); Linearity: $\pm 0.2$ dB (30 MHz to<br>6 GHz)<br>$\pm 0.3$ dB in HSL (rotation around probe axis)<br>$\pm 0.5$ dB in tissue material (rotation normal to probe axis)<br>$10 \ \mu$ W/g to > 100 mW/g; Linearity: $\pm 0.2$ dB (noise: typically<1<br>$\mu$ W/g)<br>Overall length: 337 mm (Tip: 20mm)  |  |  |  |  |
| Technical data       Construction       Calibration       Frequency       Directivity       Dynamic range                              | <ul> <li>EX3DV4 for Dosimetric Measurements         <ul> <li>according to manufacturer information</li> </ul> </li> <li>Symmetrical design with triangular core         <ul> <li>Interleaved sensors</li> <li>Built-in shielding against static charges</li> <li>PEEK enclosure material (resistant to organic solvents, e.g., DGBE)</li> <li>ISO/IEC 17025 calibration service available.</li> <li>10 MHz to &gt;6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz)</li> <li>± 0.3 dB in HSL (rotation around probe axis)</li> <li>± 0.5 dB in tissue material (rotation normal to probe axis)</li> <li>10 µW/g to &gt; 100 mW/g; Linearity: ± 0.2 dB (noise: typically&lt;1 µW/g)</li> </ul> </li> <li>Overall length: 337 mm (Tip: 20mm)         <ul> <li>Tip length: 2.5 mm (Body: 12mm)</li> </ul> </li> </ul>   |  |  |  |  |
| Technical data         Construction         Calibration         Frequency         Directivity         Dynamic range         Dimensions | <ul> <li>EX3DV4 for Dosimetric Measurements <ul> <li>according to manufacturer information</li> </ul> </li> <li>Symmetrical design with triangular core <ul> <li>Interleaved sensors</li> <li>Built-in shielding against static charges</li> <li>PEEK enclosure material (resistant to organic solvents, e.g., DGBE)</li> <li>ISO/IEC 17025 calibration service available.</li> <li>10 MHz to &gt;6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz)</li> <li>± 0.3 dB in HSL (rotation around probe axis)</li> <li>± 0.5 dB in tissue material (rotation normal to probe axis)</li> <li>10 µW/g to &gt; 100 mW/g; Linearity: ± 0.2 dB (noise: typically&lt;1 µW/g)</li> <li>Overall length: 337 mm (Tip: 20mm)</li> <li>Tip length: 2.5 mm (Body: 12mm)</li> <li>Typical distance from probe tip to dipole centers: 1mm</li> </ul> </li> </ul>   |  |  |  |  |
| Technical data       Construction       Calibration       Frequency       Directivity       Dynamic range                              | <ul> <li>e EX3DV4 for Dosimetric Measurements <ul> <li>according to manufacturer information</li> <li>Symmetrical design with triangular core</li> <li>Interleaved sensors</li> <li>Built-in shielding against static charges</li> <li>PEEK enclosure material (resistant to organic solvents, e.g., DGBE)</li> <li>ISO/IEC 17025 calibration service available.</li> <li>10 MHz to &gt;6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz)</li> <li>± 0.3 dB in HSL (rotation around probe axis)</li> <li>± 0.5 dB in tissue material (rotation normal to probe axis)</li> <li>10 µW/g to &gt; 100 mW/g; Linearity: ± 0.2 dB (noise: typically&lt;1 µW/g)</li> <li>Overall length: 337 mm (Tip: 20mm)</li> <li>Tip length: 2.5 mm (Body: 12mm)</li> <li>Typical distance from probe tip to dipole centers: 1mm</li> <li>High precision dosimetric measurements in any exposure</li> </ul> </li> </ul> |  |  |  |  |
| Technical data         Construction         Calibration         Frequency         Directivity         Dynamic range         Dimensions | <ul> <li>EX3DV4 for Dosimetric Measurements         <ul> <li>according to manufacturer information</li> <li>Symmetrical design with triangular core</li></ul></li></ul>   |  |  |  |  |
| Technical data         Construction         Calibration         Frequency         Directivity         Dynamic range         Dimensions | <ul> <li>e EX3DV4 for Dosimetric Measurements <ul> <li>according to manufacturer information</li> <li>Symmetrical design with triangular core</li> <li>Interleaved sensors</li> <li>Built-in shielding against static charges</li> <li>PEEK enclosure material (resistant to organic solvents, e.g., DGBE)</li> <li>ISO/IEC 17025 calibration service available.</li> <li>10 MHz to &gt;6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz)</li> <li>± 0.3 dB in HSL (rotation around probe axis)</li> <li>± 0.5 dB in tissue material (rotation normal to probe axis)</li> <li>10 µW/g to &gt; 100 mW/g; Linearity: ± 0.2 dB (noise: typically&lt;1 µW/g)</li> <li>Overall length: 337 mm (Tip: 20mm)</li> <li>Tip length: 2.5 mm (Body: 12mm)</li> <li>Typical distance from probe tip to dipole centers: 1mm</li> <li>High precision dosimetric measurements in any exposure</li> </ul> </li> </ul> |  |  |  |  |



### 6.1.4 Phantom description

The used SAM Phantom meets the requirements specified in FCC KDB865664 D01 for Specific Absorption Rate (SAR) measurements.

The phantom consists of a fibreglass shell integrated in a wooden table. It allows left-hand and right-hand head as well as body-worn measurements with a maximum liquid depth of 18 cm in head position and 22 cm in planar position (body measurements). The thickness of the Phantom shell is 2 mm +/- 0.1 mm.



-ear reference point right hand side

✓ ear reference point left hand side

reference point flat position



Triple Modular Phantom consists of three identical modules which can be installed and removed separately without emptying the liquid. It includes three reference points for phantom installation. Covers prevent evaporation of the liquid. Phantom material is resistant to DGBE based tissue simulating liquids.



## 6.1.5 Device holder description

The DASY device holder has two scales for device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The plane between the ear openings and the mouth tip has a rotation angle of 65°. The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. This device holder is used for standard mobile phones or PDA's only. If necessary an additional support of polystyrene material is used.



Larger DUT's (e.g. notebooks) cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values.

Therefore those devices are normally only tested at the flat part of the SAM.



#### 6.1.6 Scanning procedure

- The DASY installation includes predefined files with recommended procedures for measurements and system check. They are read-only document files and destined as fully defined but unmeasured masks. All test positions (head or body-worn) are tested with the same configuration of test steps differing only in the grid definition for the different test positions.
- The "reference" and "drift" measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the DUT's output power and should vary max. +/- 5 %.
- The highest integrated SAR value is the main concern in compliance test applications. These values can mostly be found at the inner surface of the phantom and cannot be measured directly due to the sensor offset in the probe. To extrapolate the surface values, the measurement distances to the surface must be known accurately. A distance error of 0.5mm could produce SAR errors of 6% at 1800 MHz. Using predefined locations for measurements is not accurate enough. Any shift of the phantom (e.g., slight deformations after filling it with liquid) would produce high uncertainties. For an automatic and accurate detection of the phantom surface, the DASY5 system uses the mechanical surface detection. The detection is always at touch, but the probe will move backward from the surface the indicated distance before starting the measurement.
- The "area scan" measures the SAR above the DUT or verification dipole on a parallel plane to the surface. It is used to locate the approximate location of the peak SAR with 2D spline interpolation. The robot performs a stepped movement along one grid axis while the local electrical field strength is measured by the probe. The probe is touching the surface of the SAM during acquisition of measurement values. The scan uses different grid spacings for different frequency measurements. Standard grid spacing for head measurements in frequency ranges ≤ 2GHz is 15 mm in x- and y-dimension. For higher frequencies a finer resolution is needed, thus for the grid spacing is reduced according the following table:

| Area scan grid spacing for different frequency ranges |              |  |  |  |
|---|--------------|--|--|--|
| Frequency range                                       | Grid spacing |  |  |  |
| ≤ 2 GHz   | ≤ 15 mm      |  |  |  |
| 2 – 4 GHz   | ≤ 12 mm      |  |  |  |
| 4 – 6 GHz   | ≤ 10 mm      |  |  |  |

Grid spacing and orientation have no influence on the SAR result. For special applications where the standard scan method does not find the peak SAR within the grid, e.g. mobile phones with flip cover, the grid can be adapted in orientation. Results of this coarse scan are shown in annex B.

• A "zoom scan" measures the field in a volume around the 2D peak SAR value acquired in the previous "coarse" scan. It uses a fine meshed grid where the robot moves the probe in steps along all the 3 axis (x, y and z-axis) starting at the bottom of the Phantom. The grid spacing for the cube measurement is varied according to the measured frequency range, the dimensions are given in the following table:

| Zoom scan grid spacing and volume for different frequency ranges |                            |                         |                          |  |  |
|--|----------------------------|-------------------------|--------------------------|--|--|
| Frequency range  | Grid spacing for x, y axis | Grid spacing for z axis | Minimum zoom scan volume |  |  |
| ≤ 2 GHz  | ≤ 8 mm                     | ≤ 5 mm                  | ≥ 30 mm                  |  |  |
| 2 – 3 GHz  | ≤ 5 mm*                    | ≤ 5 mm                  | ≥ 28 mm                  |  |  |
| 3 – 4 GHz  | ≤ 5 mm*                    | ≤ 4 mm                  | ≥ 28 mm                  |  |  |
| 4 – 5 GHz  | ≤ 4 mm*                    | ≤ 3 mm                  | ≥ 25 mm                  |  |  |
| 5 – 6 GHz  | ≤ 4 mm*                    | ≤ 2 mm                  | ≥ 22 mm                  |  |  |

\* When zoom scan is required and the reported SAR from the area scan based 1-g SAR estimation procedures of KDB Publication 447498 is  $\leq$  1.4 W/kg,  $\leq$  8 mm,  $\leq$  7 mm and  $\leq$  5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

DASY is also able to perform repeated zoom scans if more than 1 peak is found during area scan. In this document, the evaluated peak 1g and 10g averaged SAR values are shown in the 2D-graphics in annex B. Test results relevant for the specified standard (see section 3) are shown in table form in section 7.



### 6.1.7 Spatial Peak SAR Evaluation

The spatial peak SAR - value for 1 and 10 g is evaluated after the Cube measurements have been done. The basis of the evaluation are the SAR values measured at the points of the fine cube grid consisting of all points in the three directions x, y and z. The algorithm that finds the maximal averaged volume is separated into three different stages.

- The data between the dipole center of the probe and the surface of the phantom are extrapolated. This data cannot be measured since the center of the dipole is 1 to 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is about 1 mm (see probe calibration sheet). The extrapolated data from a cube measurement can be visualized by selecting 'Graph Evaluated'.
- The maximum interpolated value is searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10 g) are computed using the 3d-spline interpolation algorithm. If the volume cannot be evaluated (i.e., if a part of the grid was cut off by the boundary of the measurement area) the evaluation will be started on the corners of the bottom plane of the cube.
- All neighbouring volumes are evaluated until no neighbouring volume with a higher average value is found.

#### Extrapolation

The extrapolation is based on a least square algorithm [W. Gander, Computermathematik, p.168-180]. Through the points in the first 3 cm along the z-axis, polynomials of order four are calculated. These polynomials are then used to evaluate the points between the surface and the probe tip. The points, calculated from the surface, have a distance of 1 mm from each other.

#### Interpolation

The interpolation of the points is done with a 3d-Spline. The 3d-Spline is composed of three one-dimensional splines with the "Not a knot"-condition [W. Gander, Computermathematik, p.141-150] (x, y and z -direction) [Numerical Recipes in C, Second Edition, p.123ff ].

#### Volume Averaging

At First the size of the cube is calculated. Then the volume is integrated with the trapezoidal algorithm. 8000 points (20x20x20) are interpolated to calculate the average.

#### Advanced Extrapolation

DASY uses the advanced extrapolation option which is able to compensate boundary effects on E-field probes.



#### 6.1.8 Data Storage and Evaluation

#### Data Storage

The DASY software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension ".DA4", ".DA5x". The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm<sup>2</sup>], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

#### Data Evaluation by SEMCAD

The SEMCAD software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

| Probe parameters:  | <ul> <li>Sensitivity</li> <li>Conversion factor</li> </ul> | Normi, aio, ai1, ai2<br>ConvFi |
|--------------------|--|--------------------------------|
|                    | - Diode compression point                                  | Dcpi                           |
| Device parameters: | - Frequency  | f                              |
|                    | - Crest factor   | cf                             |
| Media parameters:  | - Conductivity   | $\sigma$                       |
|                    | - Density  | $\rho$                         |

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics.



If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot cf/dcp_i$$

| with | Vi   | = compensated signal of channel i | (i = x, y, z)    |
|------|------|-----------------------------------|------------------|
|      | Ui   | = input signal of channel i       | (i = x, y, z)    |
|      | cf   | = crest factor of exciting field  | (DASY parameter) |
|      | dcpi | = diode compression point         | (DASY parameter) |

From the compensated input signals the primary field data for each channel can be evaluated:

| E-field p | robes:                                       | $E_i = (V_i / Norm_i \cdot ConvF)^{1/2}$  |                                |  |  |  |  |  |
|-----------|--|---|--------------------------------|--|--|--|--|--|
| H-field p | robes:                                       | $H_i = (V_i)^{1/2} \cdot (a_{i0} + a_{i1}f + a_{i2}f^2)/f$  |                                |  |  |  |  |  |
| with      | Vi<br>Normi<br>ConvF<br>aij<br>f<br>Ei<br>Hi | <ul> <li>= compensated signal of channel i</li> <li>= sensor sensitivity of channel i<br/>[mV/(V/m)<sup>2</sup>] for E-field Probes</li> <li>= sensitivity enhancement in solution</li> <li>= sensor sensitivity factors for H-field probes</li> <li>= carrier frequency [GHz]</li> <li>= electric field strength of channel i in V/m</li> <li>= magnetic field strength of channel i in A/m</li> </ul> | (i = x, y, z)<br>(i = x, y, z) |  |  |  |  |  |

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = (E_x^2 + E_y^2 + E_z^2)^{1/2}$$

The primary field data are used to calculate the derived field units.

$$SAR = (E_{tot}^2 \cdot \sigma) / (\rho \cdot 1000)$$

| with | SAR<br>E <sub>tot</sub> | <ul> <li>local specific absorption rate in mW/g</li> <li>total field strength in V/m</li> </ul> |
|------|-------------------------|---|
|      | $\sigma$                | = conductivity in [mho/m] or [Siemens/m]  |
|      | ρ                       | = equivalent tissue density in g/cm <sup>3</sup>  |

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid. The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = E_{tot}^2 / 3770$$
 or  $P_{pwe} = H_{tot}^2 \cdot 37.7$ 

with

P<sub>pwe</sub> = equivalent power density of a plane wave in mW/cm<sup>2</sup>

E<sub>tot</sub> = total electric field strength in V/m

H<sub>tot</sub> = total magnetic field strength in A/m



## 6.1.9 Tissue simulating liquids: dielectric properties

The following materials are used for producing the tissue-equivalent materials.

(Liquids used for tests described in section 7. are marked with  $\boxtimes$ ):

| Ingredients<br>(% of weight) | Frequency (MHz) |      |      |       |       |       |       |       |         |  |  |  |  |
|------------------------------|-----------------|------|------|-------|-------|-------|-------|-------|---------|--|--|--|--|
| frequency                    | 450             | 750  | 835  | 900   | 1450  | 1750  | 1900  | 2450  | 5000    |  |  |  |  |
| band                         |                 |      |      |       |       |       |       |       |         |  |  |  |  |
| Water                        | 51.16           | 51.7 | 52.4 | 56.0  | 71.40 | 71.45 | 71.56 | 71.65 | 64 - 78 |  |  |  |  |
| Salt (NaCl)                  | 1.49            | 0.9  | 1.40 | 0.76  | 0.55  | 0.5   | 0.39  | 0.3   | 2 - 3   |  |  |  |  |
| Sugar                        | 46.78           | 47.2 | 45.0 | 41.76 | 0.0   | 0.0   | 0.0   | 0.0   | 0.0     |  |  |  |  |
| HEC                          | 0.52            | 0.0  | 1.0  | 1.21  | 0.0   | 0.0   | 0.0   | 0.0   | 0.0     |  |  |  |  |
| Bactericide                  | 0.05            | 0.1  | 0.1  | 0.27  | 0.1   | 0.1   | 0.1   | 0.1   | 0.0     |  |  |  |  |
| Tween 20                     | 0.0             | 0.0  | 0.0  | 0.0   | 27.95 | 27.95 | 27.95 | 27.95 | 0.0     |  |  |  |  |
| Emulsifiers                  | 0.0             | 0.0  | 0.0  | 0.0   | 0.0   | 0.0   | 0.0   | 0.0   | 9 - 15  |  |  |  |  |
| Mineral Oil                  | 0.0             | 0.0  | 0.0  | 0.0   | 0.0   | 0.0   | 0.0   | 0.0   | 11 - 18 |  |  |  |  |

Water: De-ionized,  $16M\Omega$ + resistivity

HEC: Hydroxyethyl Cellulose

Table 2: Body tissue dielectric properties

Salt: 99+% Pure Sodium ChlorideVSugar: 98+% Pure SucroseHTween 20: Polyoxyethylene (20) sorbitan monolaurate

#### 6.1.10 Tissue simulating liquids: parameters

| Liquid        | From           | Target b     | ody tissue   | N            | Measurement body tissue |       |         |      |                     |  |  |
|---------------|----------------|--------------|--------------|--------------|-------------------------|-------|---------|------|---------------------|--|--|
| Liquid<br>MSL | Freq.<br>(MHz) | Permittivity | Conductivity | Permittivity | Dev.                    | Condu | ctivity | Dev. | Measurement<br>date |  |  |
| IVIOL         |                | Fernituvity  | (S/m)        | Fernituvity  | Dev.                    | "ع    | (S/m)   | Dev. | uale                |  |  |
| 2450          | 2402           | 52.76        | 1.90         | 50.9         | -3.5%                   | 14.34 | 1.92    | 0.6% | 2017-01-05          |  |  |
|               | 2440           | 52.71        | 1.94         | 50.9         | -3.5%                   | 14.47 | 1.96    | 1.2% |                     |  |  |
|               | 2450           | 52.70        | 1.95         | 50.9         | -3.4%                   | 14.50 | 1.98    | 1.3% |                     |  |  |
|               | 2480           | 52.66        | 1.99         | 50.8         | -3.5%                   | 14.58 | 2.01    | 0.9% |                     |  |  |

Table 3: Parameter of the body tissue simulating liquid

Note: The dielectric properties have been measured using the contact probe method at 22°C.



# 6.1.11 Measurement uncertainty evaluation for SAR test

| $\begin{array}{c c c c c c c c c c c c c c c c c c c $  |                              | DASY5          | Uncertainty  | DASY5 Uncertainty Budget |         |         |            |               |                  |  |  |  |  |  |
|---|------------------------------|----------------|--------------|--------------------------|---------|---------|------------|---------------|------------------|--|--|--|--|--|
| Source of uncertainty $\pm \%$ Distribution       (1g)       (1g)       (1g) $\pm \%$ $\psi_{eff}$ Measurement System $\pm \%$ Distribution       (1g)       (1g) $\pm \%$ $\psi_{eff}$ Probe calibration $\pm 6.0$ $\%$ Normal       1       1 $1 \pm 6.0$ $\pm 6.0$ $\%$ $\phi_{eff}$ Axial isotropy $\pm 4.7$ $\%$ Rectangular $\sqrt{3}$ $0.7$ $0.7$ $\pm 1.9$ $\%$ $\pm 0.6$ $\%$ Hemispherical isotropy $\pm 4.7$ $\%$ Rectangular $\sqrt{3}$ $0.7$ $0.7$ $\pm 1.9$ $\%$ $\phi$ $\infty$ Boundary effects $\pm 1.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm 0.6$ $\%$ $\infty$ $\infty$ System detection limits $\pm 1.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm 0.5$ $\pm 0.5$ $\infty$ $\infty$ Response time $\pm 0.8$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm 1.7$ $\%$ $\pm 1.7$ $\%$ $\infty$ $\infty$ Reablen  | According to IEEE            | 1528/2003 ar   | d IEC 62209- | 1 for the                | e 300 l | MHz - 3 | 3 GHz rang | e             |                  |  |  |  |  |  |
| Measurement System         image: bold of the system         image: bo  | Source of                    | certainty Valu | Probability  | Divisor                  | Ci      | Ci      | Standar    | d Uncertainty | $v_i^2$ or       |  |  |  |  |  |
| $\begin{array}{c c c c c c c c c c c c c c c c c c c $  | uncertainty                  | ± %            | Distribution |                          | (1g)    | (10g)   | ± %, (1g)  | ± %, (10g)    | V <sub>eff</sub> |  |  |  |  |  |
| Axial isotropy $\pm$ 4.7       %       Rectangular $\sqrt{3}$ 0.7       0.7 $\pm$ 1.9       % $\pm$ 1.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 2.7       % $\infty$ <   | Measurement System           |                |              |                          |         |         |            |               |                  |  |  |  |  |  |
| Hemispherical isotropy $\pm$ 9.6       %       Rectangular $\sqrt{3}$ 0.7       0.7 $\pm$ 3.9       % $\infty$ Normal       1       1 $\pm$ 3.9       % $\pm$ 3.9       % $\infty$   | Probe calibration            | ± 6.0 %        | Normal       |                          | 1       | 1       | ± 6.0 %    |               | ∞                |  |  |  |  |  |
| Boundary effects $\pm$ 1.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.6       % $\pm$ 0.6       % $\infty$ $\infty$ Probe linearity $\pm$ 4.7       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.6       % $\pm$ 0.7       % $\infty$ $\infty$ System detection limits $\pm$ 1.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.6       % $\pm$ 0.6       % $\infty$ $\infty$ Readout electronics $\pm$ 0.8       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.5       % $\infty$ Response time $\pm$ 0.8       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.5       % $\infty$ Repaired int onise $\pm$ 2.6       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ $\infty$ RF ambient reflections $\pm$ 0.4       %       Rectangular $\sqrt{3}$ 1       1 $\pm$   | Axial isotropy               |                | Rectangular  |                          | 0.7     | 0.7     |            |               | ∞                |  |  |  |  |  |
| Probe linearity       ±       4.7       %       Rectangular $\sqrt{3}$ 1       1       ±       2.7       %       ±       2.7       %       ∞         System detection limits       ±       1.0       %       Rectangular $\sqrt{3}$ 1       1       ±       2.7       % $\approx$ Readout electronics       ±       0.3       %       Normal       1       1       ±       0.6       %       ±       0.6       % $\infty$ Readout electronics       ±       0.3       %       Normal       1       1       ±       0.6       % $\infty$ Response time       ±       0.8       %       Rectangular $\sqrt{3}$ 1       1       ±       0.5       % $\infty$ Integration time       ±       2.6       %       Rectangular $\sqrt{3}$ 1       1       ±       1.7       % $\infty$ RF ambient noise       ±       3.0       %       Rectangular $\sqrt{3}$ 1       1       ±       1.7       % $\infty$ Probe positioner       ±       0.4       %       Rectangular $\sqrt{3}$ 1   | Hemispherical isotropy       | ± 9.6 %        | Rectangular  |                          | 0.7     | 0.7     |            |               | ∞                |  |  |  |  |  |
| System detection limits $\pm$ 1.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.6       % $\pm$ 0.6       % $\infty$ Readout electronics $\pm$ 0.3       %       Normal       1       1       1       1 $\pm$ 0.6       % $\pm$ 0.3       % $\infty$ Response time $\pm$ 0.8       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.5       % $\infty$ Integration time $\pm$ 2.6       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.5       % $\infty$ RF ambient noise $\pm$ 3.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ RF ambient reflections $\pm$ 3.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ Probe positioning $\pm$ 2.9       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ Max SAR evaluation $\pm$   | Boundary effects             |                | Rectangular  |                          |         |         |            |               | ∞                |  |  |  |  |  |
| Readout electronics $\pm$ 0.3       %       Normal       1       1       1       1 $\pm$ 0.3       % $\infty$ Response time $\pm$ 0.8       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.3       % $\infty$ Integration time $\pm$ 2.6       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.5       % $\infty$ RF ambient noise $\pm$ 3.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ RF ambient noise $\pm$ 3.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ Probe positioner $\pm$ 0.4       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ Probe positioning $\pm$ 2.9       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ Max SAR evaluation $\pm$ 1.0       %       Rectangular $\sqrt{3}$ 1       1   | Probe linearity              | ± 4.7 %        | Rectangular  |                          | 1       | 1       | ± 2.7 %    | ± 2.7 %       | 8                |  |  |  |  |  |
| Response time $\pm$ 0.8       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.5       % $\pm$ 0.5       % $\infty$ Integration time $\pm$ 2.6       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.5       % $\infty$ RF ambient noise $\pm$ 3.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\pm$ 1.7       % $\pm$ 1.7       % $\pm$ 1.7       % $\infty$ $\infty$ RF ambient reflections $\pm$ 3.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\pm$ 1.7       % $\infty$ $\infty$ Probe positioner $\pm$ 0.4       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ $\infty$ Probe positioning $\pm$ 2.9       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ $\infty$ Device positioning $\pm$ 2.9       %  | System detection limits      | ± 1.0 %        | Rectangular  | √ 3                      | 1       | 1       | ± 0.6 %    | ± 0.6 %       | 8                |  |  |  |  |  |
| Integration time $\pm$ $\pm$ $2.6$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $1.5$ $\%$ $\pm$ $1.6$ $\%$ $\pm$ $1.5$ $\%$ $\infty$ $\infty$ RF ambient noise $\pm$ $3.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $1.7$ $\%$ $\pm$ $1.7$ $\%$ $\infty$ Probe positioner $\pm$ $0.4$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $1.7$ $\%$ $\infty$ Probe positioning $\pm$ $2.9$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $1.7$ $\%$ $\infty$ Max.SAR evaluation $\pm$ $1.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $1.7$ $\%$ $\infty$ Device positioning $\pm$ $2.9$ $\%$ Normal $1$ $1$ $1$ $\pm$ $2.9$ $\%$ $145$ Device positioning $\pm$ $2.9$ $\%$ Normal $1$ $1$ <  | Readout electronics          | ± 0.3 %        | Normal       | 1                        | 1       | 1       | ± 0.3 %    | ± 0.3 %       | 8                |  |  |  |  |  |
| RF ambient noise $\pm$ $\pm$ $3.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $1.7$ $\%$ $\infty$ RF ambient reflections $\pm$ $3.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $1.7$ $\%$ $\pm$ $1.7$ $\%$ $\infty$ Probe positioner $\pm$ $0.4$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $1.7$ $\%$ $\pm$ $1.7$ $\%$ $\infty$ Probe positioning $\pm$ $2.9$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $0.2$ $\%$ $\infty$ Max.SAR evaluation $\pm$ $1.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $0.6$ $\%$ $\infty$ Device positioning $\pm$ $2.9$ $\%$ Normal $1$ $1$ $1$ $1$ $\pm$ $2.9$ $\%$ $145$ Device holder uncertainty $\pm$ $3.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ <   | Response time                | ± 0.8 %        | Rectangular  | √ 3                      | 1       | 1       | ± 0.5 %    | ± 0.5 %       | 8                |  |  |  |  |  |
| RF ambient reflections $\pm$ 3.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\pm$ 1.7       % $\infty$ Probe positioner $\pm$ 0.4       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.2       % $\infty$ Probe positioning $\pm$ 2.9       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.2       % $\infty$ Max.SAR evaluation $\pm$ 2.9       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ Max.SAR evaluation $\pm$ 1.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\infty$ Test Sample Related   | Integration time             | ± 2.6 %        | Rectangular  | √ 3                      | 1       | 1       | ± 1.5 %    | ± 1.5 %       | 8                |  |  |  |  |  |
| Probe positioner $\pm$ $0.4$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $0.2$ $\%$ $\infty$ Probe positioning $\pm$ $2.9$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $0.2$ $\%$ $\infty$ Max.SAR evaluation $\pm$ $1.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $0.6$ $\%$ $\pm$ $0.6$ $\%$ $\pm$ $0.6$ $\%$ $\infty$ $\infty$ Max.SAR evaluation $\pm$ $1.0$ $\%$ Rectangular $\sqrt{3}$ $1$ $1$ $\pm$ $0.6$ $\%$ $\pm$ $0.6$ $\%$ $\infty$ Test Sample Related $                                   -$   | RF ambient noise             | ± 3.0 %        | Rectangular  | √ 3                      | 1       | 1       | ± 1.7 %    | ± 1.7 %       | 8                |  |  |  |  |  |
| Probe positioning $\pm$ 2.9       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 1.7       % $\pm$ 0.6       % $\pm$ 1.4       % $\pm$ 1.4       % $\pm$ 0.6       % $\pm$ 0.6       % $\pm$ 0.6  | RF ambient reflections       | ± 3.0 %        | Rectangular  |                          | 1       | 1       | ± 1.7 %    | ± 1.7 %       | 8                |  |  |  |  |  |
| Max. SAR evaluation $\pm$ 1.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 0.6       % $\pm$ 0.6 <td>Probe positioner</td> <td>± 0.4 %</td> <td>Rectangular</td> <td>√ 3</td> <td>1</td> <td>1</td> <td>± 0.2 %</td> <td>± 0.2 %</td> <td>8</td>  | Probe positioner             | ± 0.4 %        | Rectangular  | √ 3                      | 1       | 1       | ± 0.2 %    | ± 0.2 %       | 8                |  |  |  |  |  |
| Test Sample Related       Image: second secon | Probe positioning            | ± 2.9 %        | Rectangular  | √ 3                      | 1       | 1       | ± 1.7 %    | ± 1.7 %       | 8                |  |  |  |  |  |
| $\begin{array}{c c c c c c c c c c c c c c c c c c c $  | Max.SAR evaluation           | ± 1.0 %        | Rectangular  | √ 3                      | 1       | 1       | ± 0.6 %    | ± 0.6 %       | 8                |  |  |  |  |  |
| Device holder uncertainty $\pm$ 3.6       %       Normal       1       1       1 $\pm$ 3.6       % $\pm$ 3.6  | Test Sample Related          |                |              |                          |         |         |            |               |                  |  |  |  |  |  |
| Power drift $\pm$ 5.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 2.9       % $\pm$ 2.9       % $\propto$ Phantom and Set-up $\pm$ 4.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 2.9       % $\pm$ 2.9       % $\propto$ Phantom uncertainty $\pm$ 4.0       %       Rectangular $\sqrt{3}$ 1       1 $\pm$ 2.3       % $\propto$ Liquid conductivity (target) $\pm$ 5.0       %       Rectangular $\sqrt{3}$ 0.64       0.43 $\pm$ 1.8       % $\pm$ 1.2       % $\infty$ Liquid conductivity (meas.) $\pm$ 5.0       %       Rectangular $\sqrt{3}$ 0.64       0.43 $\pm$ 1.8       % $\pm$ 1.2       % $\infty$ Liquid permittivity (target) $\pm$ 5.0       %       Rectangular $\sqrt{3}$ 0.66       0.49 $\pm$ 1.7 $\%$ $\pm$ 1.4       % $\infty$ Liquid permittivity (meas.) $\pm$ 5.0       %       Rectangu   | Device positioning           | ± 2.9 %        | Normal       | 1                        | 1       | 1       | ± 2.9 %    | ± 2.9 %       | 145              |  |  |  |  |  |
| Phantom and Set-up $\pm$ 4.0 %Rectangular $\sqrt{3}$ 11 $\pm$ 2.3 % $\pm$ $2.3$ %Phantom uncertainty $\pm$ 4.0 %Rectangular $\sqrt{3}$ 11 $\pm$ 2.3 % $\pm$ $2.3$ % $\infty$ Liquid conductivity (target) $\pm$ 5.0 %Rectangular $\sqrt{3}$ 0.640.43 $\pm$ 1.8 % $\pm$ 1.2 % $\infty$ Liquid conductivity (meas.) $\pm$ 5.0 %Rectangular $\sqrt{3}$ 0.640.43 $\pm$ 1.8 % $\pm$ 1.2 % $\infty$ Liquid permittivity (target) $\pm$ 5.0 %Rectangular $\sqrt{3}$ 0.60.49 $\pm$ 1.7 % $\pm$ 1.4 % $\infty$ Liquid permittivity (meas.) $\pm$ 5.0 %Rectangular $\sqrt{3}$ 0.60.49 $\pm$ 1.7 % $\pm$ 1.4 % $\infty$ Liquid permittivity (meas.) $\pm$ 5.0 %Rectangular $\sqrt{3}$ 0.60.49 $\pm$ 1.7 % $\pm$ 1.4 % $\infty$ Liquid permittivity (meas.) $\pm$ 5.0 %Rectangular $\sqrt{3}$ 0.60.49 $\pm$ 1.7 % $\pm$ 1.4 % $\infty$ Liquid permittivity (meas.) $\pm$ 5.0 %Rectangular $\sqrt{3}$ 0.60.49 $\pm$ 1.7 % $\pm$ 1.4 % $\infty$ Combined Std. $\pm$   | Device holder uncertainty    | ± 3.6 %        | Normal       | 1                        | 1       | 1       |            | ± 3.6 %       | 5                |  |  |  |  |  |
| $\begin{array}{c c c c c c c c c c c c c c c c c c c $  | Power drift                  | ± 5.0 %        | Rectangular  | √ 3                      | 1       | 1       | ± 2.9 %    | ± 2.9 %       | 8                |  |  |  |  |  |
| Liquid conductivity (target) $\pm$ 5.0%Rectangular $\sqrt{3}$ 0.640.43 $\pm$ 1.8% $\pm$ 1.2% $\infty$ Liquid conductivity (meas.) $\pm$ 5.0%Rectangular $\sqrt{3}$ 0.640.43 $\pm$ 1.8% $\pm$ 1.2% $\infty$ Liquid permittivity (target) $\pm$ 5.0%Rectangular $\sqrt{3}$ 0.60.49 $\pm$ 1.7% $\pm$ 1.4% $\infty$ Liquid permittivity (meas.) $\pm$ 5.0%Rectangular $\sqrt{3}$ 0.60.49 $\pm$ 1.7% $\pm$ 1.4% $\infty$ Combined Std. $\pm$ $\pm$ 1.1% $\pm$ 10.8%387   | Phantom and Set-up           |                |              |                          |         |         |            |               |                  |  |  |  |  |  |
| Liquid conductivity (meas.) $\pm$ $5.0$ $\%$ Rectangular $\sqrt{3}$ $0.64$ $0.43$ $\pm$ $1.8$ $\%$ $\pm$ $1.2$ $\%$ $\infty$ Liquid permittivity (target) $\pm$ $5.0$ $\%$ Rectangular $\sqrt{3}$ $0.64$ $0.43$ $\pm$ $1.8$ $\%$ $\pm$ $1.2$ $\%$ $\infty$ Liquid permittivity (target) $\pm$ $5.0$ $\%$ Rectangular $\sqrt{3}$ $0.6$ $0.49$ $\pm$ $1.7$ $\%$ $\pm$ $1.4$ $\%$ $\infty$ Liquid permittivity (meas.) $\pm$ $5.0$ $\%$ Rectangular $\sqrt{3}$ $0.6$ $0.49$ $\pm$ $1.7$ $\%$ $\pm$ $1.4$ $\%$ $\infty$ Combined Std. $=$   | Phantom uncertainty          | ± 4.0 %        | Rectangular  | √ 3                      | 1       | 1       | ± 2.3 %    | ± 2.3 %       | 8                |  |  |  |  |  |
| Liquid permittivity (target) $\pm$ 5.0 %Rectangular $\sqrt{3}$ 0.60.49 $\pm$ 1.7 % $\pm$ 1.4 % $\infty$ Liquid permittivity (meas.) $\pm$ 5.0 %Rectangular $\sqrt{3}$ 0.60.49 $\pm$ 1.7 % $\pm$ 1.4 % $\infty$ Combined Std.  | Liquid conductivity (target) | ± 5.0 %        | Rectangular  | √ 3                      | 0.64    | 0.43    | ± 1.8 %    | ± 1.2 %       | ∞                |  |  |  |  |  |
| Liquid permittivity (target) $\pm$ 5.0       %       Rectangular $\sqrt{3}$ 0.6       0.49 $\pm$ 1.7       % $\pm$ 1.4       % $\infty$ Liquid permittivity (meas.) $\pm$ 5.0       %       Rectangular $\sqrt{3}$ 0.6       0.49 $\pm$ 1.7       % $\pm$ 1.4       % $\infty$ Combined Std. $\pm$ 1.1       % $\pm$ 10.8       %       387   | Liquid conductivity (meas.)  | ± 5.0 %        | Rectangular  | √ 3                      | 0.64    | 0.43    | ± 1.8 %    | ± 1.2 %       | ∞                |  |  |  |  |  |
| Combined Std.         ± 11.1 %         ± 10.8 %         387   | Liquid permittivity (target) | ± 5.0 %        |              | √ 3                      | 0.6     | 0.49    | ± 1.7 %    | ± 1.4 %       | ∞                |  |  |  |  |  |
| Combined Std.         ± 11.1 %         ± 10.8 %         387   | Liquid permittivity (meas.)  | ± 5.0 %        | Rectangular  | √ 3                      | 0.6     | 0.49    | ± 1.7 %    |               | ∞                |  |  |  |  |  |
| Expanded Std.         ± 22.1 %         ± 21.6 %   | Combined Std.                |                |              |                          |         |         | ± 11.1 %   | ± 10.8 %      | 387              |  |  |  |  |  |
|   | Expanded Std.                |                |              |                          |         |         | ± 22.1 %   | ± 21.6 %      |                  |  |  |  |  |  |

Table 4: Measurement uncertainties

Worst-Case uncertainty budget for DASY5 assessed according to IEEE 1528/2003.

The budget is valid for 2G and 3G communication signals and frequency range 300MHz - 3 GHz. For these conditions it represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



| Relative                    | DAS    | Y5 Und     | ertainty Bu  | udget f  | for S/   | AR Te    | sts | i        |       |           |                  |
|-----------------------------|--------|------------|--------------|----------|----------|----------|-----|----------|-------|-----------|------------------|
| According to IEE            | E 152  | 28/2013 a  | and IEC62209 | /2011 fc | or the ( | 0.3 - 30 | GHz | range    |       |           |                  |
|                             | lcerta | ainty Valu | Probability  | Divisor  | Ci       | Ci       | ç   | Standard | d Uno | certainty | $v_i^2$ or       |
| Error Description           | =      | ± %        | Distribution |          | (1g)     | (10g)    | ± 2 | %, (1g)  | ± %   | %, (10g)  | V <sub>eff</sub> |
| Measurement System          |        |            |              |          |          |          |     |          |       |           |                  |
| Probe calibration           | ±      | 6.0 %      | Normal       | 1        | 1        | 1        | ±   | 6.0 %    | ±     | 6.0 %     | 8                |
| Axial isotropy              | ±      | 4.7 %      | Rectangular  | √ 3      | 0.7      | 0.7      | +I  | 1.9 %    | ±     | 1.9 %     | 8                |
| Hemispherical isotropy      | ±      | 9.6 %      | Rectangular  | √ 3      | 0.7      | 0.7      | +I  | 3.9 %    | ±     | 3.9 %     | 8                |
| Boundary effects            | ±      | 1.0 %      | Rectangular  | √ 3      | 1        | 1        | +   | 0.6 %    | +     | 0.6 %     | 8                |
| Probe linearity             | ±      | 4.7 %      | Rectangular  | √ 3      | 1        | 1        | +I  | 2.7 %    | ±     | 2.7 %     | 8                |
| System detection limits     | ±      | 1.0 %      | Rectangular  | √ 3      | 1        | 1        | ÷   | 0.6 %    | ±     | 0.6 %     | 8                |
| Modulation Response         | ±      | 2.4 %      | Rectangular  | √ 3      | 1        | 1        | ÷   | 1.4 %    | ±     | 1.4 %     | 8                |
| Readout electronics         | ±      | 0.3 %      | Normal       | 1        | 1        | 1        | ±   | 0.3 %    | ±     | 0.3 %     | 8                |
| Response time               | ±      | 0.8 %      | Rectangular  | √ 3      | 1        | 1        | ±   | 0.5 %    | ±     | 0.5 %     | 8                |
| Integration time            | ±      | 2.6 %      | Rectangular  | √ 3      | 1        | 1        | ÷   | 1.5 %    | ±     | 1.5 %     | 8                |
| RF ambient noise            | ±      | 3.0 %      | Rectangular  | √ 3      | 1        | 1        | ±   | 1.7 %    | ±     | 1.7 %     | 8                |
| RF ambient reflections      | ±      | 3.0 %      | Rectangular  | √ 3      | 1        | 1        | ±   | 1.7 %    | ±     | 1.7 %     | 8                |
| Probe positioner            | ±      | 0.4 %      | Rectangular  | √ 3      | 1        | 1        | ±   | 0.2 %    | ±     | 0.2 %     | 8                |
| Probe positioning           | ±      | 2.9 %      | Rectangular  | √ 3      | 1        | 1        | ±   | 1.7 %    | ±     | 1.7 %     | 8                |
| Max. SAR evaluation         | ±      | 2.0 %      | Rectangular  | √ 3      | 1        | 1        | ±   | 1.2 %    | ±     | 1.2 %     | 8                |
| Test Sample Related         |        |            |              |          |          |          |     |          |       |           |                  |
| Device positioning          | ±      | 2.9 %      | Normal       | 1        | 1        | 1        | ÷   | 2.9 %    | ±     | 2.9 %     | 145              |
| Device holder uncertainty   | +      | 3.6 %      | Normal       | 1        | 1        | 1        | ±   | 3.6 %    | ±     | 3.6 %     | 5                |
| Power drift                 | ±      | 5.0 %      | Rectangular  | √ 3      | 1        | 1        | ±   | 2.9 %    | ±     | 2.9 %     | 8                |
| Phantom and Set-up          |        |            |              |          |          |          |     |          |       |           |                  |
| Phantom uncertainty         | ±      | 6.1 %      | Rectangular  | √ 3      | 1        | 1        | +   | 3.5 %    | ŧ     | 3.5 %     | 8                |
| SAR correction              | ±      | 1.9 %      | Rectangular  | √ 3      | 1        | 0.84     | ±   | 1.1 %    | ±     | 0.9 %     | 8                |
| Liquid conductivity (meas.) | ±      | 5.0 %      | Rectangular  | √ 3      | 0.78     | 0.71     | ±   | 2.3 %    | ±     | 2.0 %     | 8                |
| Liquid permittivity (meas.) | ±      | 5.0 %      | Rectangular  | √ 3      | 0.26     | 0.26     | +   | 0.8 %    | ±     | 0.8 %     | 8                |
| Temp. Unc Conductivity      |        | 3.4 %      | Rectangular  | √ 3      | 0.78     | 0.71     | +   | 1.5 %    | ±     | 1.4 %     | 8                |
| Temp. Unc Permittivity      | ±      | 0.4 %      | Rectangular  | √ 3      | 0.23     | 0.26     | ±   | 0.1 %    | ±     | 0.1 %     | 8                |
| Combined Uncertainty        |        |            |              |          |          |          | ±   | 11.3 %   | ±     | 11.3 %    | 330              |
| Expanded Std.               |        |            |              |          |          |          |     |          |       |           |                  |
| Uncertainty                 |        |            |              |          |          |          | ±   | 22.7 %   | ±     | 22.5 %    |                  |
|                             |        |            |              |          |          |          | _   |          |       |           |                  |

Table 5: Measurement uncertainties

Worst-Case uncertainty budget for DASY5 assessed according to IEEE 1528/2013 and IEC 62209-1/2011 standards. The budget is valid for the frequency range 300MHz -3 GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



|                             | DASY5         | Uncertainty    | Budg    | et     |        |                 |                  |                  |
|-----------------------------|---------------|----------------|---------|--------|--------|-----------------|------------------|------------------|
| According                   | to IEC 62209- | 2/2010 for the | e 300 M | Hz - 6 | GHz ra | ange            |                  |                  |
| Source of                   | Uncertainty   | Probability    | Divisor | Ci     | Ci     | Standard        | d Uncertainty    | $v_i^2$ or       |
| uncertainty                 | Value         | Distribution   |         | (1g)   | (10g)  | ± %, (1g)       | ± %, (10g)       | V <sub>eff</sub> |
| Measurement System          |               |                |         |        |        |                 |                  |                  |
| Probe calibration           | ± 6.6 %       | Normal         | 1       | 1      | 1      | ± 6.6 %         | ± 6.6 %          | ∞                |
| Axial isotropy              | ± 4.7 %       | Rectangular    | √ 3     | 0.7    | 0.7    | ± 1.9 %         | ± 1.9 %          | ∞                |
| Hemispherical isotropy      | ± 9.6 %       | Rectangular    | √ 3     | 0.7    | 0.7    | ± 3.9 %         | ± 3.9 %          | ∞                |
| Boundary effects            | ± 2.0 %       | Rectangular    | √ 3     | 1      | 1      | ± 1.2 %         | ± 1.2 %          | ∞                |
| Probe linearity             | ± 4.7 %       | Rectangular    | √ 3     | 1      | 1      | ± 2.7 %         | ± 2.7 %          | ∞                |
| System detection limits     | ± 1.0 %       | Rectangular    | √ 3     | 1      | 1      | ± 0.6 %         | ± 0.6 %          | ∞                |
| Modulation Response         | ± 2.4 %       | Rectangular    | √ 3     | 1      | 1      | ± 1.4 %         | ± 1.4 %          | ∞                |
| Readout electronics         | ± 0.3 %       | Normal         | 1       | 1      | 1      | ± 0.3 %         | ± 0.3 %          | ∞                |
| Response time               | ± 0.8 %       | Rectangular    | √ 3     | 1      | 1      | ± 0.5 %         | ± 0.5 %          | 8                |
| Integration time            | ± 2.6 %       | Rectangular    | √ 3     | 1      | 1      | ± 1.5 %         | ± 1.5 %          | 8                |
| RF ambient noise            | ± 3.0 %       | Rectangular    | √ 3     | 1      | 1      | ± 1.7 %         | ± 1.7 %          | 8                |
| RF ambient reflections      | ± 3.0 %       | Rectangular    | √ 3     | 1      | 1      | ± 1.7 %         | ± 1.7 %          | 8                |
| Probe positioner            | ± 0.8 %       | Rectangular    | √ 3     | 1      | 1      | ± 0.5 %         | ± 0.5 %          | ∞                |
| Probe positioning           | ± 6.7 %       | Rectangular    | √ 3     | 1      | 1      | ± 3.9 %         | ± 3.9 %          | 8                |
| Post-processing             | ± 4.0 %       | Rectangular    | √ 3     | 1      | 1      | ± 2.3 %         | ± 2.3 %          | ∞                |
| Test Sample Related         |               |                |         |        |        |                 |                  |                  |
| Device positioning          | ± 2.9 %       | Normal         | 1       | 1      | 1      | ± 2.9 %         | ± 2.9 %          | 145              |
| Device holder uncertainty   | ± 3.6 %       | Normal         | 1       | 1      | 1      | ± 3.6 %         | ± 3.6 %          | 5                |
| Power drift                 | ± 5.0 %       | Rectangular    | √ 3     | 1      | 1      | ± 2.9 %         | ± 2.9 %          | ∞                |
| Phantom and Set-up          |               |                |         |        |        |                 |                  |                  |
| Phantom uncertainty         | ± 7.9 %       | Rectangular    | √ 3     | 1      | 1      | ± 4.6 %         | ± 4.6 %          | ∞                |
| SAR correction              | ± 1.9 %       | Rectangular    | √ 3     | 1      | 0.84   | ± 1.1 %         | ± 0.9 %          | ∞                |
| Liquid conductivity (meas.) | ± 5.0 %       | Rectangular    | √ 3     | 0.78   | 0.71   | ± 2.3 %         | ± 2.0 %          | ∞                |
| Liquid permittivity (meas.) | ± 5.0 %       | Rectangular    | √ 3     | 0.26   | 0.26   | ± 0.8 %         | ± 0.8 %          | ∞                |
| Temp. Unc Conductivity      | ± 3.4 %       | Rectangular    | √ 3     | 0.78   | 0.71   | ± 1.5 %         | ± 1.4 %          | ∞                |
| Temp. Unc Permittivity      | ± 0.4 %       | Rectangular    | √ 3     | 0.23   | 0.26   | ± 0.1 %         | ± 0.1 %          | ∞                |
| Combined Uncertainty        |               |                |         |        |        | ± 12.7 %        | ± 12.6 %         | 330              |
| Expanded Std.               |               |                |         |        |        | ± 25.4 %        | ± 25.3 %         |                  |
| Uncertainty                 |               |                |         |        |        | ± <b>23.</b> 70 | ± <b>20.0</b> /0 |                  |

Table 6: Measurement uncertainties.

Worst-Case uncertainty budget for DASY5 assessed according to according to IEC 62209-2/2010 standard. The budget is valid for the frequency range 300MHz - 6 GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.

## 6.1.12 Measurement uncertainty evaluation for System Check

| Uncertainty of              | of a | -         |              |              |      | with  | DA | SY5 S   | yst | tem      |                                |
|-----------------------------|------|-----------|--------------|--------------|------|-------|----|---------|-----|----------|--------------------------------|
|                             | 1    | for       | the 0.3 - 3  | <u>GHz</u> r | ange |       | 1  |         |     |          |                                |
| Source of                   | Und  | certainty | Probability  | Divisor      | Ci   | Ci    | St | andard  | Unc | ertainty | v <sub>i</sub> <sup>2</sup> or |
| uncertainty                 | `    | Value     | Distribution |              | (1g) | (10g) | ±  | %, (1g) | ±°  | %, (10g) | V <sub>eff</sub>               |
| Measurement System          |      |           |              |              |      |       |    |         |     |          |                                |
| Probe calibration           | ±    | 6.0 %     | Normal       | 1            | 1    | 1     | ±  | 6.0 %   | ±   | 6.0 %    | 8                              |
| Axial isotropy              | ±    | 4.7 %     | Rectangular  | √ 3          | 0.7  | 0.7   | ±  | 1.9 %   | ±   | 1.9 %    | 8                              |
| Hemispherical isotropy      | +    | 0.0 %     | Rectangular  | √ 3          | 0.7  | 0.7   | ±  | 0.0 %   | ±   | 0.0 %    | 8                              |
| Boundary effects            | +    | 1.0 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 0.6 %   | ±   | 0.6 %    | 8                              |
| Probe linearity             | +I   | 4.7 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 2.7 %   | ±   | 2.7 %    | 8                              |
| System detection limits     | +I   | 1.0 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 0.6 %   | ±   | 0.6 %    | 8                              |
| Readout electronics         | +    | 0.3 %     | Normal       | 1            | 1    | 1     | ±  | 0.3 %   | ±   | 0.3 %    | 8                              |
| Response time               | ±    | 0.0 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 0.0 %   | ±   | 0.0 %    | 8                              |
| Integration time            | ±    | 0.0 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 0.0 %   | ±   | 0.0 %    | 8                              |
| RF ambient conditions       | ±    | 3.0 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 1.7 %   | ±   | 1.7 %    | 8                              |
| Probe positioner            | ±    | 0.4 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 0.2 %   | ±   | 0.2 %    | 8                              |
| Probe positioning           | ±    | 2.9 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 1.7 %   | ±   | 1.7 %    | 8                              |
| Max. SAR evaluation         | ±    | 1.0 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 0.6 %   | ±   | 0.6 %    | 8                              |
| Test Sample Related         |      |           |              |              |      |       |    |         |     |          |                                |
| Dev. of experimental dipole | ±    | 0.0 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 0.0 %   | ±   | 0.0 %    | 8                              |
| Source to liquid distance   | ±    | 2.0 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 1.2 %   | ±   | 1.2 %    | 8                              |
| Power drift                 | ±    | 3.4 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 2.0 %   | ±   | 2.0 %    | 8                              |
| Phantom and Set-up          |      |           |              |              |      |       |    |         |     |          |                                |
| Phantom uncertainty         | +    | 4.0 %     | Rectangular  | √ 3          | 1    | 1     | ±  | 2.3 %   | ±   | 2.3 %    | 8                              |
| SAR correction              | ±    | 1.9 %     | Rectangular  | √ 3          | 1    | 0.84  | ±  | 1.1 %   | ±   | 0.9 %    | 8                              |
| Liquid conductivity (meas.) | ±    | 5.0 %     | Normal       | 1            | 0.78 | 0.71  | ±  | 3.9 %   | ±   | 3.6 %    | 8                              |
| Liquid permittivity (meas.) | ŧ    | 5.0 %     | Normal       | 1            | 0.26 | 0.26  | ±  | 1.3 %   |     | 1.3 %    | 8                              |
| Temp. unc Conductivity      | +I   | 1.7 %     | Rectangular  | √ 3          | 0.78 | 0.71  | ±  | 0.8 %   | ±   | 0.7 %    | 8                              |
| Temp. unc Permittivity      | ±    | 0.3 %     | Rectangular  | √ 3          | 0.23 | 0.26  | ±  | 0.0 %   | ±   | 0.0 %    | 8                              |
| Combined Uncertainty        |      |           |              |              |      |       | ±  | 9.1 %   | ±   | 8.9 %    | 330                            |
| Expanded Std.               |      |           |              |              |      |       |    | 10 0 0/ |     | 47 0 0/  |                                |
| Uncertainty                 |      |           |              |              |      |       | ±  | 18.2 %  | ±   | 17.9 %   |                                |

Table 7: Measurement uncertainties of the System Check with DASY5 (0.3-3GHz)

Note: Worst case probe calibration uncertainty has been applied for all probes used during the measurements.



## 6.1.13 System check

The system check is performed for verifying the accuracy of the complete measurement system and performance of the software. The system check is performed with tissue equivalent material according to IEEE 1528. The following table shows system check results for all frequency bands and tissue liquids used during the tests (plot(s) see annex A).

|                             | System performence check (1000 mW) |   |  |   |                           |  |                            |                  |  |  |  |  |  |
|-----------------------------|------------------------------------|---|--|---|---------------------------|--|----------------------------|------------------|--|--|--|--|--|
| System<br>validation<br>Kit | Frequency                          | Target<br>SAR <sub>1g</sub><br>/mW/g (+/-<br>10%) | Target<br>SAR <sub>10g</sub><br>/mW/g (+/-<br>10%) | Measured<br>SAR <sub>1g</sub> /<br>mW/g | SAR <sub>1g</sub><br>dev. | Measured<br>SAR <sub>10g</sub> /<br>mW/g | SAR <sub>10g</sub><br>dev. | Measured<br>date |  |  |  |  |  |
| D2450V2<br>S/N: 710         | 2450 MHz<br>MSL                    | 51.10   | 24.20  | 48.10                                   | -5.9%                     | 22.30                                    | -7.9%                      | 2018-01-05       |  |  |  |  |  |

Table 8: Results system check

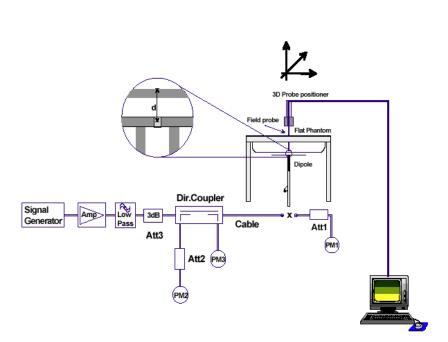


#### 6.1.14 System check procedure

The system check is performed by using a validation dipole which is positioned parallel to the planar part of the SAM phantom at the reference point. The distance of the dipole to the SAM phantom is determined by a plexiglass spacer. The dipole is connected to the signal source consisting of signal generator and amplifier via a directional coupler, N-connector cable and adaption to SMA. It is fed with a power of 1000 mW for frequencies below 2 GHz or 100 mW for frequencies above 2 GHz. To adjust this power a power meter is used. The power sensor is connected to the cable before the system check to measure the power at this point and do adjustments at the signal generator. At the outputs of the directional coupler both return loss as well as forward power are controlled during the validation to make sure that emitted power at the dipole is kept constant. This can also be checked by the power drift measurement after the test (result on plot).

System check results have to be equal or near the values determined during dipole calibration (target SAR in table above) with the relevant liquids and test system.







### 6.1.15 System validation

The system validation is performed in a similar way as a system check. It needs to be performed once a SAR measurement system has been established and allows an evaluation of the system accuracy with all components used together with the specified system. It has to be repeated at least once a year or when new system components are used (DAE, probe, phantom, dipole, liquid type).

In addition to the procedure used during system check a system validation also includes checks of probe isotropy, probe modulation factor and RF signal.

The following table lists the system validations relevant for this test report:

| Frequency<br>(MHz) | DASY<br>SW | Dipole Type<br>/SN | Probe Type<br>/ SN | Calibrated<br>signal<br>type(s) | DAE unit<br>Type / SN | body<br>validation |
|--------------------|------------|--------------------|--------------------|---------------------------------|-----------------------|--------------------|
| 2450               | V52.8.7    | D2450V2 /<br>710   | ES3DV3 /<br>3326   | CW                              | DAE4 /<br>1387        | 2017-10-13         |



# 7 Detailed Test Results

# 7.1 Conducted power measurements

Bluetooth: duty cycle 46%

| Modulation | Maximum average output power conducted [dBm] |          |          |  |
|------------|--|----------|----------|--|
| Frequency  | 2402 MHz                                     | 2441 MHz | 2480 MHz |  |
| GFSK       | -0.6   | -0.1     | -1.4     |  |
| Pi/4 DQPSK | -1.5   | -1.1     | -2.4     |  |
| 8 DPSK     | -1.0   | -0.6     | -1.9     |  |

Proprietary roger: duty cycle:100%

| Modulation | Maximum average output power conducted [dBm] |          |          |  |
|------------|--|----------|----------|--|
| Frequency  | 2402 MHz                                     | 2441 MHz | 2480 MHz |  |
| CW         | 15.9   | 16.0     | 15.0     |  |



#### 7.2 SAR test results

#### 7.2.1 General description of test procedures

- The DUT is tested using a software provided by the manufacturer to activate a testing signal transmitting from the DUT without any other auxiliary needed. Test channels and maximum output power were set to the highest possible output power level.
- Test positions as described in the tables above are in accordance with the specified test standard.
- According to IEEE 1528 the SAR test shall be performed at middle channel. Testing of top and bottom channel is optional.
- According to KDB 447498 D01 testing of other required channels within the operating mode of a frequency band is not required when the reported 1-g or 10-g SAR for the mid-band or highest output power channel is:
  - $\leq 0.8$  W/kg or 2.0 W/kg, for 1-g or 10-g respectively, when the transmission band is  $\leq 100$  MHz
  - ≤ 0.6 W/kg or 1.5 W/kg, for 1-g or 10-g respectively, when the transmission band is between 100 MHz and 200 MHz
  - $\leq 0.4$  W/kg or 1.0 W/kg, for 1-g or 10-g respectively, when the transmission band is  $\geq 200$  MHz
- IEEE 1528-2013 requires the middle channel to be tested first. This generally applies to wireless
  devices that are designed to operate in technologies with tight tolerances for maximum output power
  variations across channels in the band. When the maximum output power variation across the required
  test channels is > ½ dB, instead of the middle channel, the highest output power channel must be
  used.

#### 7.2.2 Results overview

|              | measured / extrapolated SAR numbers - Body worn |                  |          |                                 |       |              |         |               |         |                |        |       |
|--------------|---|------------------|----------|---------------------------------|-------|--------------|---------|---------------|---------|----------------|--------|-------|
| Ch. Freq.    |   | test cond.       | Position | cond. P <sub>max</sub><br>(dBm) |       | SAR1g (W/kg) |         | SAR10g (W/kg) |         | power<br>drift | liquid | dist. |
|              | (MHz)   |                  |          | decl.**                         | meas. | meas.        | extrap. | meas.         | extrap. | (dB)           | (°C)   | (mm)  |
|              |   |                  |          |                                 | Roger | Tx           |         |               |         |                |        |       |
| 0            | 2402  | proprietary (CW) | bottom   | 16.5                            | 15.9  | 1.040        | 1.194   | 0.483         | 0.555   | 0.10           | 22.9   | 0     |
| 1            | 2440  | proprietary (CW) | bottom   | 16.5                            | 16.0  | 1.070        | 1.201   | 0.498         | 0.559   | 0.11           | 22.9   | 0     |
| 2            | 2480  | proprietary (CW) | bottom   | 16.5                            | 15.0  | 0.995        | 1.405   | 0.433         | 0.612   | -0.11          | 22.9   | 0     |
| 1            | 2440  | proprietary (CW) | bottom   | 16.5                            | 16.0  | 1.150        | 1.290   | 0.509         | 0.571   | -0.06          | 22.9   | 0     |
| Bluetooth Tx |   |                  |          |                                 |       |              |         |               |         |                |        |       |
| 0            | 2402  | 1Mbit/s          | bottom   | 1.0                             | -0.6  | 0.135        | 0.195   | 0.060         | 0.087   | 0.01           | 22.9   | 0     |
| 1            | 2440  | 1Mbit/s          | bottom   | 1.0                             | -0.1  | 0.154        | 0.198   | 0.067         | 0.086   | -0.08          | 22.9   | 0     |
| 2            | 2480  | 1Mbit/s          | bottom   | 1.0                             | -1.4  | 0.175        | 0.304   | 0.075         | 0.131   | -0.09          | 22.9   | 0     |

Table 9: Test results body worn SAR for Roger Tx proprietary and Bluetooth 2450 MHz

\* - repeated at the highest SAR measurement according to the FCC KDB 865664

\*\* - maximum possible output power declared by manufacturer.



## 8 Test equipment and ancillaries used for tests

To simplify the identification of the test equipment and/or ancillaries which were used, the reporting of the relevant test cases only refer to the test item number as specified in the table below.

| Equipment                            | Туре                | Manufacturer                       | Serial No. | Last Calibration | Frequency<br>(months) |
|--------------------------------------|---------------------|------------------------------------|------------|------------------|-----------------------|
| Dosimetric E-Field Probe             | ES3DV3              | Schmid & Partner<br>Engineering AG | 3326       | August 11, 2017  | 12                    |
| 2450 MHz System Validation<br>Dipole | D2450V2             | Schmid & Partner<br>Engineering AG | 710        | August 15, 2016  | 36                    |
| Data acquisition electronics         | DAE4                | Schmid & Partner<br>Engineering AG | 1387       | August 07, 2017  | 12                    |
| Software                             | DASY52<br>52.8.7    | Schmid & Partner<br>Engineering AG |            | N/A              |                       |
| Triple Modular Flat Phantom V5.1     | QD 000<br>P51 C     | Schmid & Partner<br>Engineering AG | 1154       | N/A              |                       |
| Network Analyser<br>300 kHz to 6 GHz | 8753ES              | Hewlett Packard)*                  | US39174436 | January 28, 2016 | 24                    |
| Dielectric Probe Kit                 | 85070C              | Hewlett Packard                    | US99360146 | N/A              | 12                    |
| Signal Generator                     | 8671B               | Hewlett Packard                    | 2823A00656 | January 31, 2017 | 24                    |
| Amplifier                            | 25S1G4<br>(25 Watt) | Amplifier<br>Reasearch             | 20452      | N/A              |                       |
| Power Meter                          | NRP                 | Rohde & Schwarz                    | 101367     | January 31, 2017 | 24                    |
| Power Meter Sensor                   | NRP Z22             | Rohde & Schwarz                    | 100227     | January 31, 2017 | 12                    |
| Power Meter Sensor                   | NRP Z22             | Rohde & Schwarz                    | 100234     | January 31, 2017 | 12                    |
| Directional Coupler                  | 778D                | Hewlett Packard                    | 19171      | January 31, 2017 | 12                    |

)\* : Network analyzer probe calibration against air, distilled water and a shorting block performed before measuring liquid parameters.

#### 9 Observations

No observations exceeding those reported with the single test cases have been made.



Date/Time: 1/5/2018 11:57:46 AM

## Annex A: System performance check

## SystemPerformanceCheck-D2450 MSL 2018-01-05

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 710

Communication System: UID 0, CW (0); Communication System Band: D2450 (2450.0 MHz); Frequency: 2450 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 2450 MHz;  $\sigma$  = 1.976 S/m;  $\epsilon$ r = 50.886;  $\rho$  = 1000 kg/m<sup>3</sup>

Phantom section: Center Section

Measurement Standard: DASY5

**DASY5** Configuration:

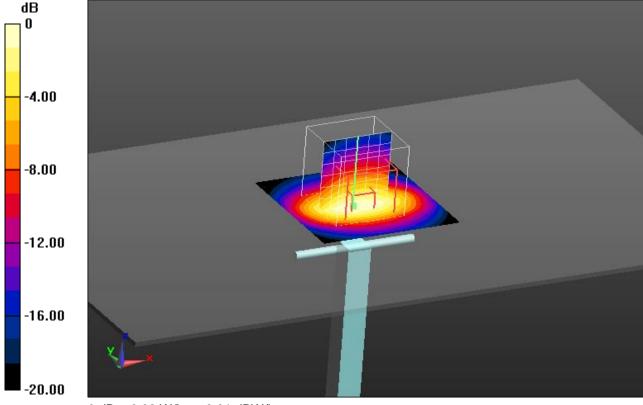
- Probe: ES3DV3 SN3326; ConvF(4.59, 4.59, 4.59); Calibrated: 8/11/2017;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 2.0, 32.0
- Electronics: DAE4 Sn1387; Calibrated: 8/7/2017
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1154
- DASY52 52.10.0(1446); SEMCAD X 14.6.10(7417)

# MSL2450/d=10mm, Pin=100 mW, dist=3mm/Area Scan (61x61x1): Interpolated

grid: dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 6.58 W/kg

# MSL2450/d=10mm, Pin=100 mW, dist=3mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 58.31 V/m; Power Drift = -0.04 dB Peak SAR (extrapolated) = 9.79 W/kg SAR(1 g) = 4.81 W/kg; SAR(10 g) = 2.23 W/kg Maximum value of SAR (measured) = 6.32 W/kg



0 dB = 6.32 W/kg = 8.01 dBW/kg



ambient temperature: 23.4°C; liquid temperature: 22.9°C



### Annex B: DASY5 measurement results

SAR plots for **the highest measured SAR** in each exposure configuration, wireless mode and frequency band combination according to FCC KDB 865664 D02

## Annex B.1: Roger proprietary TX 2450 MHz

Date/Time: 1/5/2018 10:55:36 AM

# FCC\_EN62209-2 RogerTX\_2450 body worn

DUT: Phonak; Type: Roger Select; Serial: 1749CY001

Communication System: UID 0, ROGER TX; Communication System Band: 2.4 GHz; Frequency: 2440 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 2440 MHz;  $\sigma$  = 1.964 S/m;  $\epsilon$ r = 50.894;  $\rho$  = 1000 kg/m<sup>3</sup>

Phantom section: Center Section

Measurement Standard: DASY5

DASY5 Configuration:

- Probe: ES3DV3 - SN3326; ConvF(4.59, 4.59, 4.59); Calibrated: 8/11/2017;

- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 2.0, 27.0

- Electronics: DAE4 Sn1387; Calibrated: 8/7/2017

- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1154

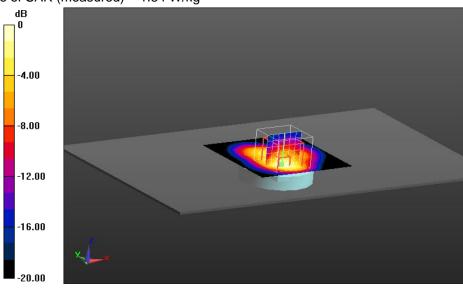
- DASY52 52.10.0(1446); SEMCAD X 14.6.10(7417)

# MSL2450/Bottom Middle 0mm (WC)/Area Scan (81x81x1): Interpolated grid:

dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 1.62 W/kg

# MSL2450/Bottom Middle 0mm (WC)/Zoom Scan (7x7x7)/Cube 0: Measurement

grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 28.49 V/m; Power Drift = -0.06 dB Peak SAR (extrapolated) = 2.64 W/kg SAR(1 g) = 1.15 W/kg; SAR(10 g) = 0.509 W/kg Maximum value of SAR (measured) = 1.54 W/kg



0 dB = 1.54 W/kg = 1.88 dBW/kg

#### Additional information:

position or distance of DUT to the phantom: 0 mm ambient temperature: 23.4°C; liquid temperature: 22.9°C



Date/Time: 1/5/2018 9:26:54 AM

# FCC\_EN62209-2 RogerTX\_2450 body worn

DUT: Phonak; Type: Roger Select; Serial: 1749CY001

Communication System: UID 0, Roger Tx (0); Communication System Band: 2450 MHz propietary;

Frequency: 2480 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 2480 MHz;  $\sigma$  = 2.011 S/m;  $\epsilon$ r = 50.807;  $\rho$  = 1000 kg/m<sup>3</sup>

Phantom section: Center Section

Measurement Standard: DASY5

DASY5 Configuration:

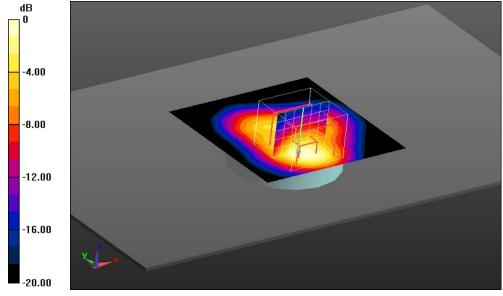
- Probe: ES3DV3 SN3326; ConvF(4.59, 4.59, 4.59); Calibrated: 8/11/2017;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 2.0, 27.0
- Electronics: DAE4 Sn1387; Calibrated: 8/7/2017
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1154
- DASY52 52.10.0(1446); SEMCAD X 14.6.10(7417)

# MSL2450/Bottom High 0mm/Area Scan (81x81x1): Interpolated grid: dx=1.000 mm,

dy=1.000 mm Maximum value of SAR (interpolated) = 1.40 W/kg

# MSL2450/Bottom High 0mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid:

dx=5mm, dy=5mm, dz=5mm Reference Value = 26.58 V/m; Power Drift = -0.11 dB Peak SAR (extrapolated) = 2.33 W/kg SAR(1 g) = 0.995 W/kg; SAR(10 g) = 0.433 W/kg Maximum value of SAR (measured) = 1.36 W/kg



0 dB = 1.36 W/kg = 1.34 dBW/kg

#### Additional information:

position or distance of DUT to the phantom: 0 mm ambient temperature: 23.4°C; liquid temperature: 22.9°C



## Annex B.2: Bluetooth 2450 MHz

Date/Time: 1/5/2018 10:37:08 AM

# FCC\_EN62209-2 BT2450 body worn

DUT: Phonak; Type: Roger Select; Serial: 1749CY001

Communication System: UID 0, Bluetooth (46%) (0); Communication System Band: BT (GFSK-DH5-46%); Frequency: 2480 MHz; Communication System PAR: 3.3 dB; PMF: 1.46218

Medium parameters used: f = 2480 MHz;  $\sigma = 2.011 \text{ S/m}$ ;  $\epsilon_r = 50.807$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Center Section

Measurement Standard: DASY5

DASY5 Configuration:

- Probe: ES3DV3 - SN3326; ConvF(4.59, 4.59, 4.59); Calibrated: 8/11/2017;

- Sensor-Surface: 3mm (Mechanical Surface Detection (Locations From Previous Scan Used)), Sensor-

Surface: 3mm (Mechanical Surface Detection), z = 2.0, 27.0

- Electronics: DAE4 Sn1387; Calibrated: 8/7/2017

- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1154

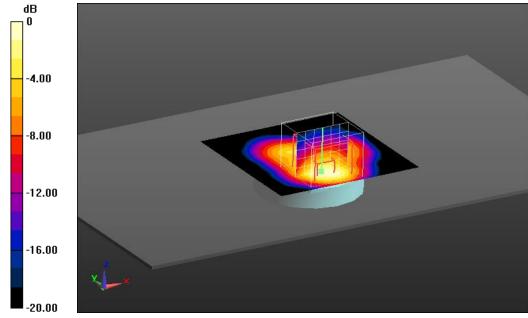
- DASY52 52.10.0(1446); SEMCAD X 14.6.10(7417)

## MSL2450/Bottom High 0mm/Area Scan (81x81x1): Interpolated grid: dx=1.000 mm,

dy=1.000 mm Maximum value of SAR (interpolated) = 0.243 W/kg

## MSL2450/Bottom High 0mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid:

dx=5mm, dy=5mm, dz=5mm Reference Value = 10.81 V/m; Power Drift = -0.09 dB Peak SAR (extrapolated) = 0.411 W/kg SAR(1 g) = 0.175 W/kg; SAR(10 g) = 0.075 W/kg Maximum value of SAR (measured) = 0.237 W/kg



0 dB = 0.237 W/kg = -6.25 dBW/kg

Additional information:

position or distance of DUT to the phantom: 0 mm ambient temperature: 23.4°C; liquid temperature: 22.9°C



# Annex B.3: Liquid depth

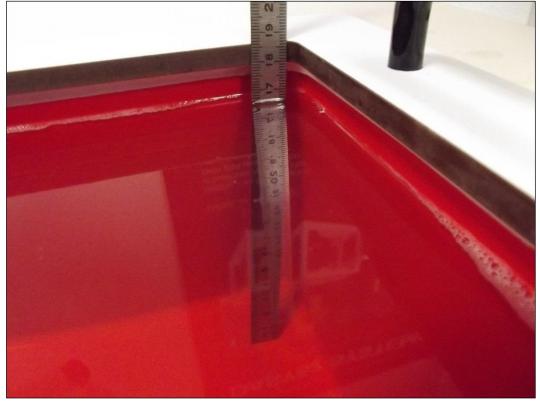


Photo 1: Liquid depth 2450 MHz body simulating liquid



Photo 2: DUT - Top side view









Photo 4: DUT - Rear side view





Photo 5: DUT - Front side view



Photo 6: DUT - Bottom side view (Label)

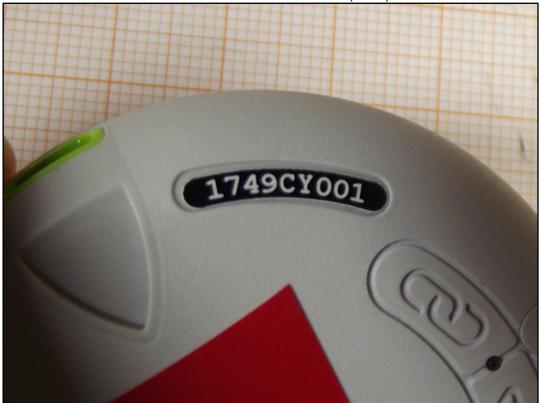






Photo 7: Measurement position - Bottom side with 0mm distance



#### Annex D: Calibration parameters

Calibration parameters are described in the additional document:

# Appendix to test report no. 1-5466/17-01-04 Calibration data, Phantom certificate and detail information of the DASY5 System

### Annex E: RSS-102 Annex A and B

ICRF documents are described in the additional document:

# Appendix to test report no. 1-5466/17-01-04\_ICRF RF Technical Brief Cover Sheet acc. To RSS-102 Annex A and Declaration of RX Exposure Compliance Annex B



# Annex F: Document History

| Version | Applied Changes | Date of Release |  |
|---------|-----------------|-----------------|--|
|         | Initial Release | 2018-01-05      |  |
|         |                 |                 |  |

# Annex G: Further Information

#### <u>Glossary</u>

| BW       | - | Bandwidth                                      |
|----------|---|--|
| DTS      | - | Distributed Transmission System                |
| DUT      | - | Device under Test                              |
| EUT      | - | Equipment under Test                           |
| FCC      | - | Federal Communication Commission               |
| FCC ID   | - | Company Identifier at FCC                      |
| HW       | - | Hardware                                       |
| IC       | - | Industry Canada                                |
| Inv. No. | - | Inventory number                               |
| LTE      | - | Long Term Evolution                            |
| N/A      | - | not applicable                                 |
| PCE      | - | Personal Consumption Expenditure               |
| OET      | - | Office of Engineering and Technology           |
| RB       | - | resource block(s)                              |
| SAR      | - | Specific Absorption Rate                       |
| S/N      | - | Serial Number                                  |
| SPLSRi   | - | SAR-to-(peak-locations spacing) ratio          |
| SW       | - | Software                                       |
| UNII     | - | Unlicensed National Information Infrastructure |