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Report On

Emergency Beacons Limited Testing of the
McMurdo Limited
uBlox NEO - 6M (G5 Smartfind Plus)

Document 75911555 Report 04 Issue 1 March 2011

Product Service

TÜV SÜD Product Service Ltd, Octagon House, Concorde Way, Segensworth North,
Fareham, Hampshire, United Kingdom, PO15 5RL
Tel: +44 (0) 1489 558100. Website: www.tuvps.co.uk

REPORT ON

Emergency Beacons Limited Testing of the
McMurdo Limited
uBlox NEO - 6M (G5 Smartfind Plus)

Document 75911555 Report 04 Issue 1

March 2011

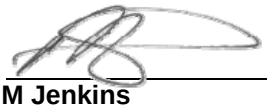
PREPARED FOR

McMurdo Limited
Silver Point
Airport Service Road
Portsmouth
PO3 5PB

PREPARED BY

R Hampton
Test Engineer

APPROVED BY



M Jenkins
Authorised Signatory

DATED 22 March 2011

Product Service

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SECTION 1

REPORT SUMMARY

Emergency Beacons Limited Testing of the
McMurdo Limited
uBlox NEO - 6M (G5 Smartfind Plus)

1.1 INTRODUCTION

The information contained in this report is intended to show verification of the Emergency Beacons Testing of the uBlox NEO - 6M (McMurdo Limited G5 Smartfind Plus) to the requirements of IEC 61108-1.

Objective	To perform GPS Testing to determine the Equipment Under Test's (EUT's) compliance with the Test Specification, for the series of tests carried out.
Manufacturer	McMurdo Limited
Model Number(s)	uBlox NEO - 6M (G5 Smartfind Plus)
Serial Number(s)	Not serialised TÜV Reference Number: 75911555-TSR0004
Number of Samples Tested	One
Test Specification/Issue/Date	IEC 61108-1: 2003
Order Number Date	PC0004329 29 October 2010
Start of Test	29 November 2010
Finish of Test	09 March 2011
Name of Engineer(s)	R Hampton
Related Documents	EN 61162-1: 2008

1.2 DECLARATION OF BUILD STATUS

MAIN EUT	
MANUFACTURING DESCRIPTION	Emergency Positioning Indicating Radio Beacon (EPIRB)
MANUFACTURER	McMurdo Ltd
TYPE	EPIRB
PART NUMBER	G5/E5 Smartfind
SERIAL NUMBER	1
HARDWARE VERSION	Issue 1
SOFTWARE VERSION	1.3.220
TRANSMITTER OPERATING RANGE	406.040MHz & 121.5MHz
RECEIVER OPERATING RANGE	N/A
INTERMEDIATE FREQUENCIES	N/A
EMISSION DESIGNATOR(S): (i.e. G1D, GXW)	3K20A3X & 16K0G1D
MODULATION TYPES: (i.e. GMSK, QPSK)	121.5MHz = AM (Swept tone) & 406.040MHz = Phase Modulation
HIGHEST INTERNALLY GENERATED FREQUENCY	406.040MHz
HIGHEST INTERNALLY GENERATED FREQUENCY IN RECEIVE IDLE MODE	N/A
OUTPUT POWER (W or dBm)	121.5MHz = 16dBm 406.040MHz = 37dBm
TECHNICAL DESCRIPTION (a brief description of the intended use and operation)	Emergency Positioning Indicating Radio Beacon (EPIRB) for last resort safeguard against life threatening incidents that may occur anywhere in the world at sea.
If unit is SRD being tested to ETS 301 489-3 please state Class of Equipment as defined in Section 6.1	
BATTERY/POWER SUPPLY	
MANUFACTURING DESCRIPTION	Lithium Battery Pack
MANUFACTURER	Varta/Panasonic
TYPE	Lithium Manganese Dioxide
PART NUMBER	CR 2/3 AH
VOLTAGE	9V
SERIAL NUMBER	N/A

Signature

Date 15 March 2011

D of B S Serial No 75911555/01

Note: This document has been prepared to enable manufacturers with no mechanism for producing their own Declaration of Build Status, to declare the build state of the equipment submitted for test.

No responsibility will be accepted by TÜV SÜD Product Service as to the accuracy of the information declared in this document by the manufacturer.

1.3 PRODUCT INFORMATION

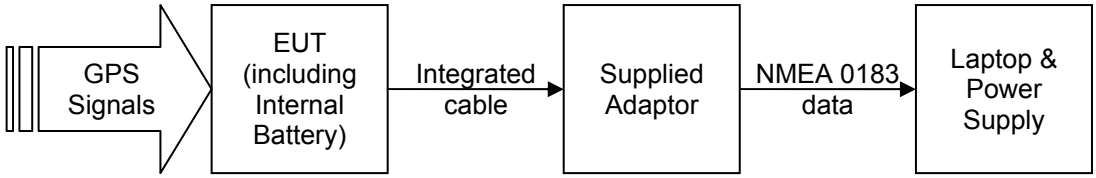
1.3.1 Technical Description

The Equipment Under Test (EUT) was a McMurdo Limited uBlox NEO - 6M (G5 Smartfind Plus) as shown in the photograph below. A full technical description can be found in the manufacturer's documentation.

Equipment Under Test

1.3.2 Physical Test Configuration

The EUT was configured so that the RF transmitters were disabled and module data output (normally to EUT internal systems) was output to a remote (integral) adaptor. The Equipment Under Test (EUT) was operated using an internal battery and the NMEA 0183 serial output connected to an external laptop (test equipment) running logging/monitoring software "VisualGPS".



1.3.3 Modes of Operation

Modes of operation of the EUT during testing were as follows:

Operating:

- Physical configuration as above, EUT entered operational mode upon activation of its main switch
- Low intensity Green LEDs flashing at ~2 Hz initially to indicate activation
- High Intensity white LEDs (strobe lights) flashing at ~0.4 Hz
- NMEA 0183 serial data outputting to Test Equipment

Off/Idle:

- Main switch moved to “OFF” position

Isolated:

- Battery disconnected.

1.4 MODIFICATIONS

The table below details modifications made to the EUT during the test programme. The modifications incorporated during each test are recorded on the appropriate test pages.

Modification State	Description of Modification still fitted to EUT	Modification Fitted By	Date Modification Fitted
0	As supplied by the customer	Not Applicable	Not Applicable
1	To allow enable constant power to the GPS module (to facilitate testing to IEC 61108) the PCB pads 1 & 4 for device Q10 (FET FDC638p) were shorted together to provide a constant 3v3 voltage drive to the uBlox NEO-6M GNSS module.	Neil Jordan, McMurdo Limited	07 February 2011

1.5 REPORT MODIFICATION RECORD

Issue 1 – First Issue

Product Service

SECTION 2

TEST DETAILS

Emergency Beacons Limited Testing of the
McMurdo Limited
uBlox NEO - 6M (G5 Smartfind Plus)

2.1 PERFORMANCE MONITORING

2.1.1 Performance Checks

IEC 61108-1, Clause 5.3 Standard test signals:

"A "performance check" is defined as a shortened version of the static accuracy test described in 5.6.4.1, i.e. a minimum of 100 position measurements shall be taken over a period of not <5 min and not >10 min, discarding any measurements with HDOP ≥4. The position of the antenna of the EUT shall not be in error compared with the known position by >100 m 95 % using WGS 84 as the reference datum."

Clause 4.3.3.1 Static Accuracy:

"(M.112/A3.4*) The GPS receiver equipment* shall have *static accuracy such that the horizontal position of the antenna is determined to within 100 m (95 %) with horizontal dilution of precision (HDOP) ≤4 (or PDOP ≤ 6)*. Since Selective Availability has been set to zero, the static accuracy has been determined to be within 13 m (95 %) as specified by the GPS SPS Performance Standards of October 2001."

Performance Check Procedure:

For every Performance Check, the following actions were completed:

Action	Reported
EUT provided with GPS signals	Signal Type (Live or Simulated)
EUT powered 'ON'	EUT started simultaneously (Y or N) Note: for Live GPS Signals this is N/A
EUT allowed to acquire valid position	Time to acquire valid position
>100 position measurements recorded (NMEA output)	Measurement duration
Measurement duration noted	Total number of measurements
Measurements with HDOP≥4 discarded	Number of measurements with HDOP ≥ 4 (and PDOP ≥ 6)
Haversine position error calculated for each measurement	N/A
Proportion within tolerance calculated	Measurements with position error ≤ (13) m

[1] The term 'valid position' (also referenced as 'position lock' or 'lock' within this report) is defined as when the NMEA data GGA sentence reports "Position Quality" as any value between 1 and 8. EN 61162:2008 states that "*All GPS quality indicators in headings 1 through 8 are considered "valid". The heading "0" is the only "invalid" indicator.*"

[2] Earth's radius taken as 6367 km

2.2 STATIC ACCURACY (GPS)

2.2.1 Specification Reference

IEC 61108-1, Clause 5.6.4.1.1

2.2.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

2.2.3 Date of Test and Modification State

10 to 11 February 2011 – Modification State 1

2.2.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.2.5 Test Setup

Test Set-up

2.2.6 Environmental Conditions

	10 February 2011	11 February 2011
Ambient Temperature:	8.1°C	7.9°C
Relative Humidity:	84%	92%

2.2.7 Test Results

Static Test Site, Clause 5.5.2

"The antenna shall be mounted according to the manufacturer's instructions at a height of between 1 m and 1,5 m above the electrical ground in an area providing clear line of sight to the satellites from zenith through to an angle of +5° above horizontal. The position of the antenna shall be known, with reference to WGS 84 to an accuracy of better than 0,1 m in (x, y, z). Maximum cable lengths as specified by the manufacturer shall be used during testing.

All static tests shall utilize actual GPS signals."

Test Method, Clause 5.6.4.1.1

"Position fix measurements shall be taken over a period of not <24 h. The absolute horizontal position accuracy shall be within 13 m (95 %), having discarded measurements taken in conditions of HDOP ≥ 4 and PDOP ≥6."

Procedure/Results:

EUT was placed on the static test site on a non-conductive platform. It was operated and monitored continuously for the period of measurement as below. Results were as follows:

Test Parameter	Units	Result	Limit
Signal Type	Live/Simulated	Live	-
EUT started simultaneously	Y/N	N/A	-
Time to acquire valid position	s	29	-
Total number of measurements	-	89477	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	89477	> 100
Measurement duration	h	24.85	> 24
Measurements with position error ≤ 13 m	%	100	≥ 95

Limits Clause 4.3.3.1

"(M.112/A3.4) *The GPS receiver equipment* shall *have static accuracy such that the horizontal position of the antenna is determined to within 100 m (95 %) with horizontal dilution of precision (HDOP) ≤4 (or PDOP ≤ 6).* Since Selective Availability has been set to zero, the static accuracy has been determined to be within 13 m (95 %) as specified by the GPS SPS Performance Standards of October 2001."

2.3 ANGULAR MOVEMENT OF THE ANTENNA

2.3.1 Specification Reference

IEC 61108-1, Clause 5.6.4.2

2.3.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

2.3.3 Date of Test and Modification State

09 and 10 February 2011 - Modification State 1

2.3.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.3.5 Test Setup

Test Set-up (Two images showing EUT in positive and negative stages of oscillation)

2.3.6 Environmental Conditions

	09 February 2011	10 February 2011
Ambient Temperature:	7.1°C	8.1°C
Relative Humidity:	73%	84%

2.3.7 Test Results

Test Method Clause 5.6.4.2:

"The static tests specified in 5.6.4.1.1 and 5.6.4.1.2 shall be repeated with the antenna performing an angular displacement of ±22,5° (simulating roll) in a period of about 8 s (see IEC 60721-3-6) during the duration of the tests.

The results shall be as in 5.6.4.1.1 and 5.6.4.1.2."

Procedure/Results:

EUT was placed on the static test site on a non-conductive platform oscillating ±22.5° from the vertical with a period of approximately 8 seconds. It was operated and monitored continuously for the period of measurement as below. Results were as follows:

Test Parameter	Units	Result	Limit
Signal Type	Live/Simulated	Live	-
EUT started simultaneously	Y/N	N/A	-
Time to acquire valid position	s	43	-
Total number of measurements	-	90975	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	90975	> 100
Measurement duration	h	26.25	> 24
Measurements with position error ≤ 13 m	%	100	≥ 95

Limits Clause 4.3.3.1

"(M.112/A3.4) *The GPS receiver equipment* shall *have static accuracy such that the horizontal position of the antenna is determined to within 100 m (95 %) with horizontal dilution of precision (HDOP) ≤4 (or PDOP ≤ 6).* Since Selective Availability has been set to zero, the static accuracy has been determined to be within 13 m (95 %) as specified by the GPS SPS Performance Standards of October 2001."

2.4 DYNAMIC ACCURACY (GPS)

2.4.1 Specification Reference

IEC 61108-1, Clause 5.6.4.3.1

2.4.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

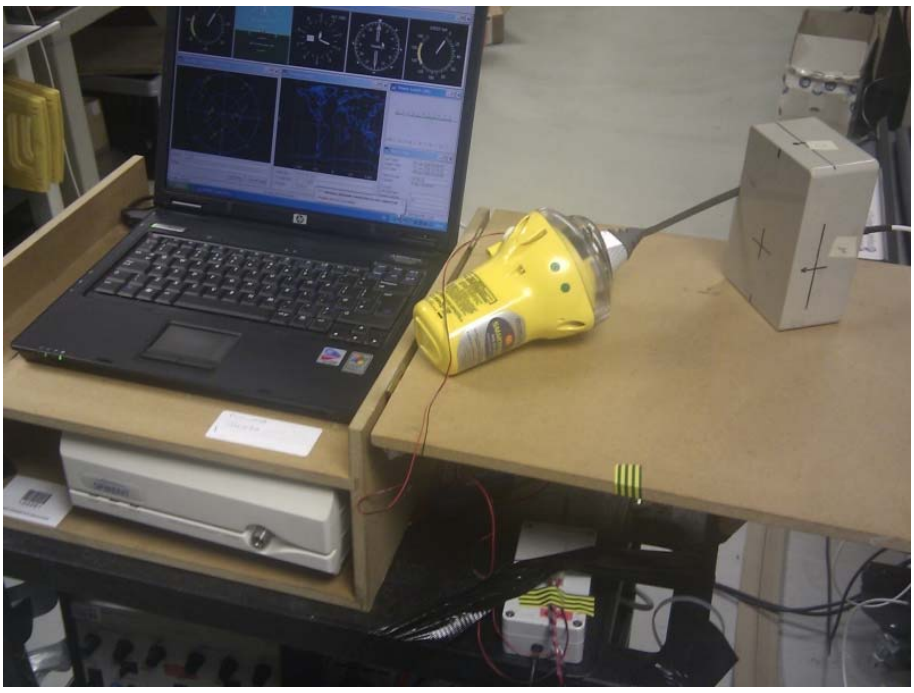
2.4.3 Date of Test and Modification State

28 February 2011 – Modification State 1

2.4.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.4.5 Test Setup



Test Set-up

2.4.6 Environmental Conditions

Ambient Temperature:	22.2°C
Relative Humidity:	30%

2.4.7 Test Results

Test Method Clause 5.6.4.3.1:

"The tests for dynamic accuracy are a practical interpretation of the conditions set out in IEC 60721-3-6, Table V, item e), X – direction (surge) and Y – direction (sway). These are stated as surge 5 m/s^2 and sway 6 m/s^2 for all classes of environment. When using a simulator, the simulator characteristics shall accurately represent the signals required.

The results of the test performed by simulation facilities shall be identical with those in a) and b) below. *[…]*

a) a fully locked and settled EUT travelling in a straight line at 48 knots ± 2 knots for a minimum of 1,2 min which is reduced to 0 knots in the same straight line in 5 s […]

b) a fully locked and settled EUT travelling at least 100 m at 24 knots ± 1 knot in a straight line then subjected, for at least 2 min, to smooth deviations either side of the straight line of approximately 2 m at a period of 11 s to 12 s[…]"

Procedure/Results - Dynamic Accuracy A:

EUT and GPS simulator were started simultaneously and the EUT acquired a position lock after the acquisition time stated in the table below; the simulator ran a dynamic position travelling at 48 knots in a straight line for 10 minutes before decelerating to 0 knots in 5 seconds (in the same straight line). The position output 10 seconds after coming to rest was determined from the NMEA 0183 output. A Performance Check was then performed for information.

Test Parameter	Units	Result	Limit
Initial Acquisition Time	s	18	-
Position Error 10 s after coming to rest	m	3.96	< 13
Performance Check			
Signal Type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	Y	-
Time to acquire valid position	s	N/A	-
Total number of measurements	-	302	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	302	> 100
Measurement duration	min	5.02	> 5 and < 10
Measurements with position error ≤ 13 m	%	100	≥ 95

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Procedure/Results - Dynamic Accuracy B:

EUT and GPS simulator were started simultaneously and the EUT acquired a position lock after the acquisition time stated in the table below; the simulator ran a dynamic position travelling at 24 knots in a straight line for 10 minutes before starting to oscillate smoothly ±2 m either side of the original path for a further 20 minutes.

EUT position output error compared to the simulated dynamic position was determined from the EUT NMEA output.

A Performance Check was conducted during the 20-minute oscillation period in order to determine that the position error was not outside of the ±30 m 'lane' of tolerance.

Test Parameter	Units	Result	Limit
Initial Acquisition Time	s	19	-
Performance Check			
Signal Type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	Y	-
Time to acquire valid position	s	N/A	-
Total number of measurements	-	317	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	317	> 100
Measurement duration	min	5.27	> 5 and < 10
Measurements with position error ≤ **30 m**	%	100	≥ 95

Limits Clause 5.6.4.3.1 (Test Method Clause)

"a) […] shall not indicate a positional offset >±13 m from the final position 10 s after coming to rest;

b) […] shall remain in lock and follow the actual position to within a lane of 30 m wide centred on the mean direction of motion."

2.5 ACQUISITION - CONDITION A - INITIALIZATION

2.5.1 Specification Reference

IEC 61108-1, Clause 5.6.5.1

2.5.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

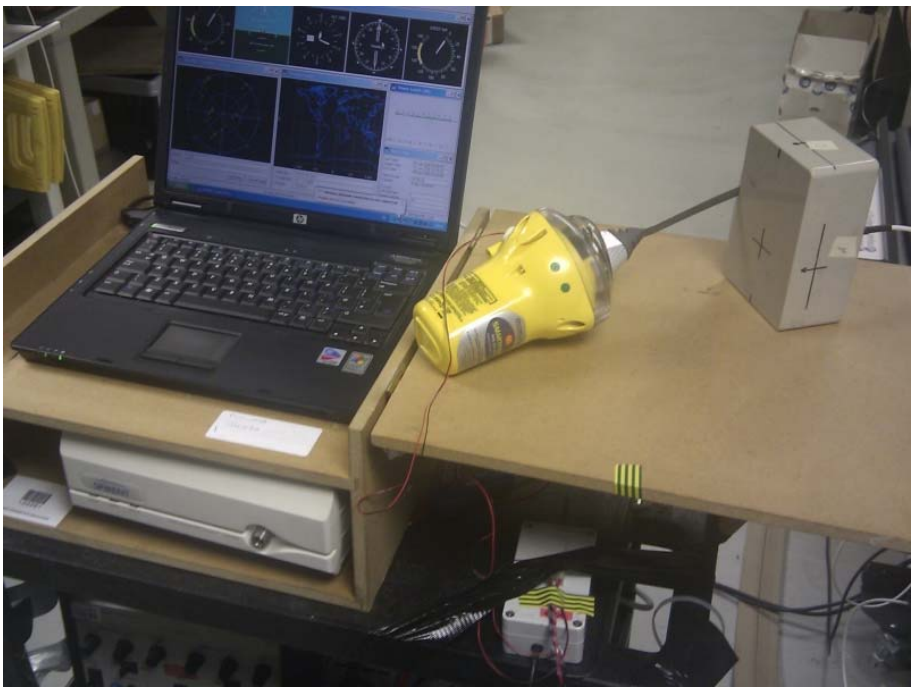
2.5.3 Date of Test and Modification State

28 February 2011 - Modification State 1

2.5.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.5.5 Test Setup



Test Set-up

2.5.6 Environmental Conditions

Ambient Temperature:	22.2°C
Relative Humidity:	30%

2.5.7 Test Results

Test Method Clause 5.6.5.1

"The EUT shall be either:

a) initialized to a false position at least 1 000 km and not greater than 10 000 km from the test position, or alternatively, by deletion of the current almanac; or

b) isolated from a power source for >7 days.

A performance check shall be carried out after the time limit contained in Table 1."

Procedure/Results:

EUT was previously isolated from its power supply for >7 days (approx 14 days).

The GPS simulator scenario was started followed by the EUT, the time to position lock was measured. A Performance Check was started once position lock was obtained.

Test Parameter	Units	Result	Limit
Power isolation period	days	14	> 7
Performance Check			
Signal Type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	N	-
Time to acquire valid position	min	0.417	30
Total number of measurements	-	508	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	508	> 100
Measurement duration	min	8.87	> 5 and < 10
Measurements with position error ≤ 13 m	%	100	≥ 95

Limits Clause 4.3.4

"(M.112/A3.8) *The GPS receiver equipment* shall *be capable of acquiring position to the required accuracy, within 30 min, when there is no valid almanac data.*"

2.6 ACQUISITION - CONDITION B - POWER OUTAGE

2.6.1 Specification Reference

IEC 61108-1, Clause 5.6.5.2

2.6.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

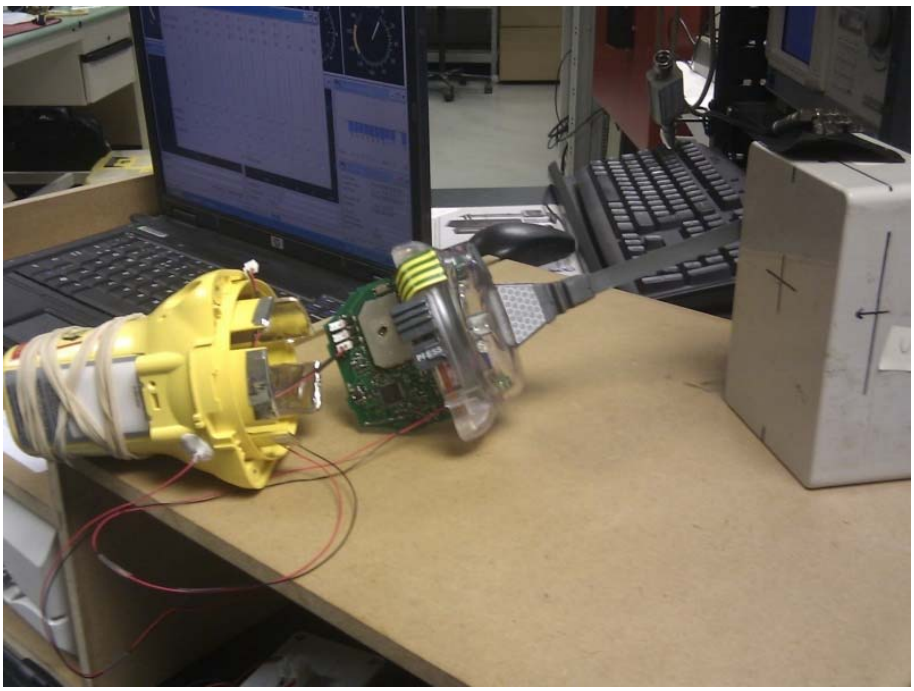
2.6.3 Date of Test and Modification State

28 February to 01 March 2011 - Modification State 1

2.6.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.6.5 Test Setup



Test Set-up

Note: EUT is configured to operate with 3 battery packs in parallel, throughout the test only one battery pack was connected, this was sufficient to operate the EUT and also ensured that Power On/Off times were accurate as only one battery need be connected/disconnected.

2.6.6 Environmental Conditions

	28 February 2011	01 March 2011
Ambient Temperature:	22.2°C	22.9°C
Relative Humidity:	30%	20%RH

2.6.7 Test Results

Test Method Clause 5.6.5.2

"The EUT shall be isolated from the power source for a period within 24 h to 25 h. At the end of the period, a performance check shall be carried out after the time limit contained in Table 1."

Procedure/Results:

EUT was locked and stable and the power was removed for the "power isolation period", as below, then re-applied. A Performance Check was then completed:

Test Parameter	Units	Result	Limit
Power isolation period	h	24.25	> 24 and < 25
Performance Check			
Signal Type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	N	-
Time to acquire valid position	min	0.317	5
Total number of measurements	-	508	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	508	> 100
Measurement duration	Min	5.02	> 5 and < 10
Measurements with position error ≤ 13 m	%	100	≥ 95

Limits Clause 4.3.4

"(M.112/A3.9) *The GPS receiver equipment* shall *be capable of acquiring position to the required accuracy, within 5 min, when there is valid almanac data.*"

2.7 ACQUISITION - CONDITION C - INTERRUPTION OF GPS SIGNALS

2.7.1 Specification Reference

IEC 61108-1, Clause 5.6.5.3

2.7.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

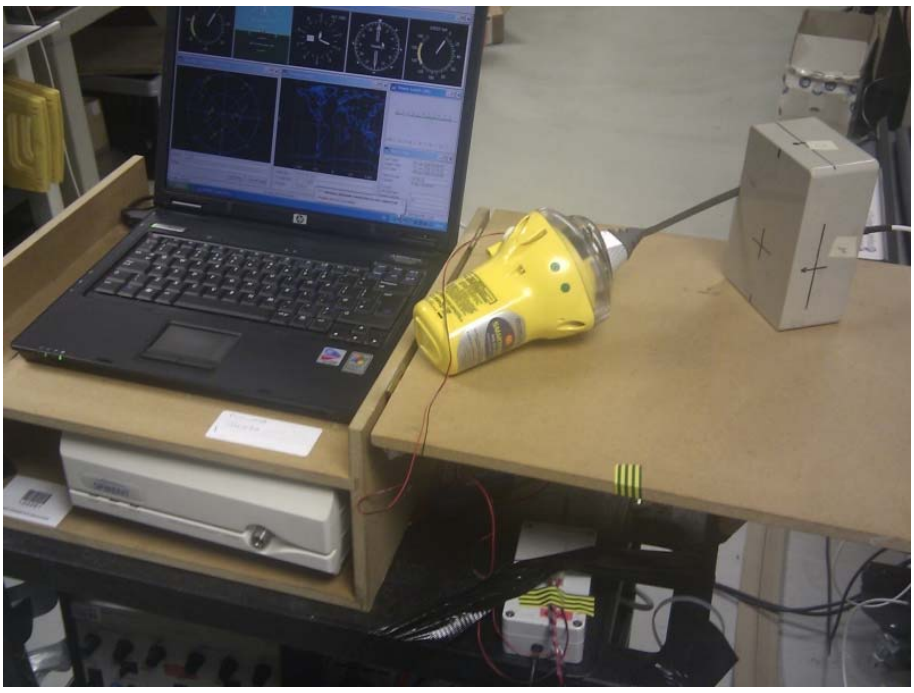
2.7.3 Date of Test and Modification State

01 to 02 March 2011 - Modification State 1

2.7.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.7.5 Test Setup



Test Set-up

2.7.6 Environmental Conditions

	01 March 2011	02 March 2011
Ambient Temperature:	22.9°C	20.8°C
Relative Humidity:	20%	26%

2.7.7 Test Results

Test Method Clause 5.6.5.3

"During normal operation of the EUT, the antenna shall be completely masked for a period between 24 h and 25 h.

At the end of the period, a performance check shall be carried out after the time limit contained in Table 1."

Procedure/Results:

The EUT was locked and settled in 'normal operation', the GPS Signals were then removed (but the scenario kept running) for the "GPS signal isolation period" as below. The GPS signals were re-applied and a Performance Check was then completed.

Test Parameter	Units	Result	Limit
GPS signal isolation period	h	24.25	> 24 and < 25
Performance Check			
Signal Type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	N	-
Time to acquire valid position	min	0.583	5
Total number of measurements	-	339	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	339	> 100
Measurement duration	min	5.63	> 5 and < 10
Measurements with position error ≤ 13 m	%	100	≥ 95

Limits Clause 4.3.4

"(M.112/A3.10) *The GPS receiver equipment* shall *be capable of re-acquiring position to the required accuracy, within 5 min, when the GPS signals are interrupted for a period of at least 24 h, but there is no loss of power.*"

2.8 ACQUISITION - CONDITION D - BRIEF INTERRUPTION OF POWER

2.8.1 Specification Reference

IEC 61108-1, Clause 5.6.5.4

2.8.2 Equipment Under Test

Error! Reference source not found., S/N: 75911555-TSR0004

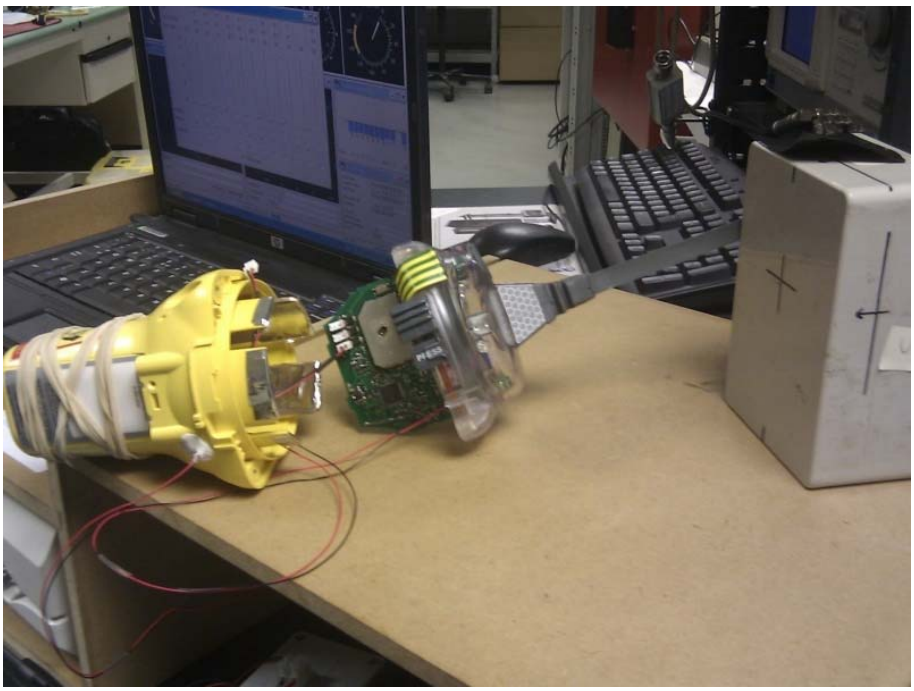
2.8.3 Date of Test and Modification State

28 February 2011 - Modification State 1

2.8.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.8.5 Test Setup



Test Set-up

Note: EUT is configured to operate with 3 battery packs in parallel, throughout the test only one battery pack was connected, this was sufficient to operate the EUT and also ensured that Power On/Off times were accurate as only one battery need be connected/disconnected.

2.8.6 Environmental Conditions

Ambient Temperature:	21.3 °C
Relative Humidity:	32%

2.8.7 Test Results

Test Method Clause 5.6.5.4

"During normal operation of the EUT, the power shall be removed for a period of 60 s. At the end of this period, the power shall be restored.

A performance check shall be carried out after the time limit contained in Table 1."

Procedure/Results:

The EUT was locked and settled in 'normal operation'; power was then removed for the "power isolation period", as below, then re-applied. A Performance Check was then completed.

Test Parameter	Units	Result	Limit
Power isolation period	s	60	60
Performance Check			
Signal Type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	N/A	-
Time to acquire valid position	min	0.367	2
Total number of measurements	-	388	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	388	> 100
Measurement duration	min	6.45	> 5 and < 10
Measurements with position error ≤ 13 m	%	100	≥ 95

Limits Clause 4.3.4

"(M.112/A3.11) *The GPS receiver equipment* shall *be capable of re-acquiring position to the required accuracy, within 2 min, when subjected to a power interruption of 60 s."*

2.9 PROTECTION – ANTENNA AND INPUT/OUTPUT CONNECTIONS

2.9.1 Specification Reference

IEC 61108-1, Clause 5.6.6.1

2.9.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

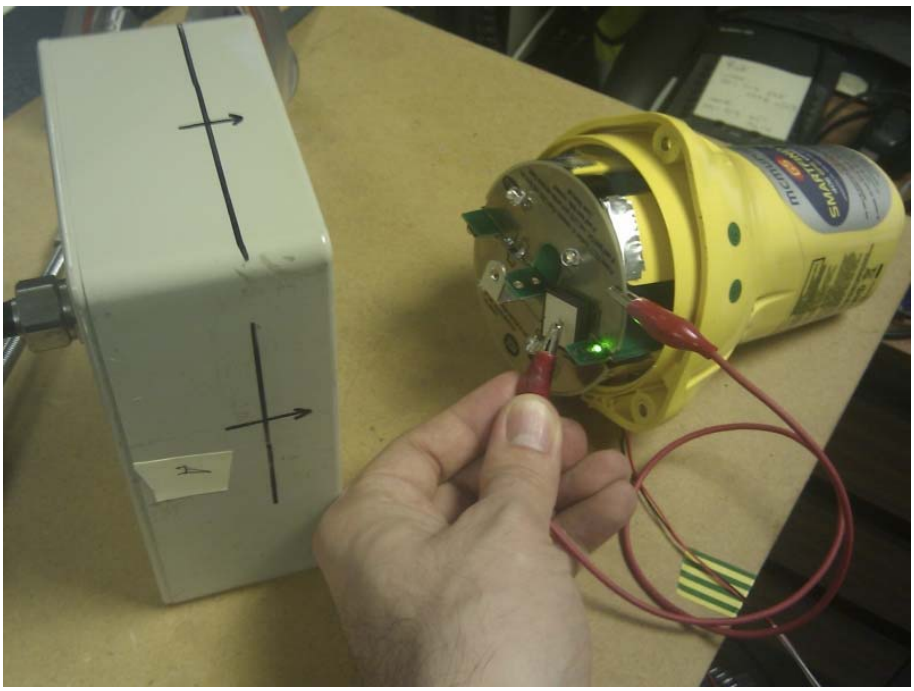
2.9.3 Date of Test and Modification State

09 March 2011 - Modification State 1

2.9.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.9.5 Test Setup



Test Set-up

2.9.6 Environmental Conditions

Ambient Temperature:	22.8 °C
Relative Humidity:	27 %RH

2.9.7 Test Results

Test Method Clause 5.6.6.1

"The antenna input of the receiver, if provided, shall be connected to ground for 5 min. After completion of the test and reset of the EUT, if required, the antenna or input/output connections shall be connected normally, and a performance check shall be carried out to ensure that no permanent damage has resulted."

Procedure/Results:

As per customer instructions, EUT case was opened and main transmitting antenna disconnected in order to gain access to the GPS patch antenna (see setup photo).

The EUT was allowed to lock and settle on a GPS position. An electrical connection was made between the centre pin and the PCB ground plane for 5 min. After removal of the electrical connection, the EUT was allowed to re-acquire a position. A Performance Check was then carried out.

Note: Although the EUT lost its position lock at the beginning of the grounded period, it re-acquired a position before the 5-minute period was complete. Removal of the electrical connection at the end of the grounded period did not result in another loss of position only an increase in reported signal to noise ratio. Hence, the performance check was started as soon as the electrical connection was removed.

Test Parameter	Units	Result	Limit
Time antenna was grounded	min	5	5
Performance Check			
Signal Type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	N/A	-
Time to acquire valid position	Min	N/A	-
Total number of measurements	-	311	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	311	> 100
Measurement duration	min	5.17	> 5 and < 10
Measurements with position error ≤ 13 m	%	100	≥ 95

Limits Clause 4.3.5.1

"(M.112/A4) *Precautions* shall *be taken to ensure that no permanent damage can result from an accidental short circuit or grounding of the antenna or any of its input or output connections or any of the GPS receiver equipment inputs or outputs for a duration of 5 min.*"

2.10 SENSITIVITY AND DYNAMIC RANGE – ACQUISITION

2.10.1 Specification Reference

IEC 61108-1, Clause 5.6.8.1

2.10.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

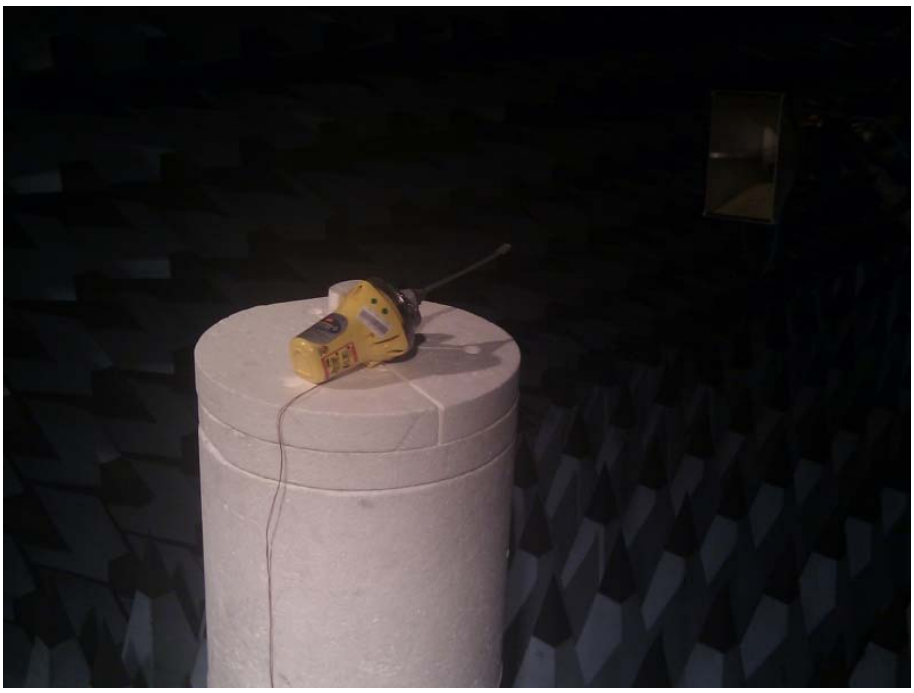
2.10.3 Date of Test and Modification State

29 November 2010 – Modification State 0

2.10.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.10.5 Test Setup



EUT with internal GPS patch antenna facing GPS transmitting antenna (right)

Note: GPS Signal Transmitting Antenna is a linearly polarised Double Ridged wave-Guide (DRG). EUT antenna is a patch antenna (neither helical-form nor circularly polarised). Hence, the linear transmitting antenna was deemed 'suitable' as per the test clause. No 3 dB correction factor was applied.

Product Service

Field Calibration

Field strength was ascertained by the following process.

1) “System Loss” taken from calibrated chamber ‘Transducer Factor’. This is the loss from the (normally) transmitting EUT, over the 1 m air gap to the receiving antenna (including antenna gain) and trough the connecting cables bulkhead and interlock system. This is normally used to adjust the received power outside the chamber into an EIRP. In this case, however, the transmission path is in reverse but this makes no difference to the loss. The system is calibrated at 1.5 GHz and 1.6 GHz and the value for 1.57542 GHz was interpolated as follows:

Frequency (x)	System Loss (y)	Comments
1.5 GHz	30.190	Calibrated (a)
1.57542 GHz	30.73	Interpolated as below
1.6 GHz	30.912	Calibrated (b)

The Interpolant, y (System Loss at 1.575GHz) is given by the equation:

$$y = y_a + (x - x_a)\frac{(y_b - y_a)}{(x_b - x_a)}$$

$$y = 30.190 + \left((1.57542 - 1.5) \times \frac{30.912 - 30.190}{1.6 - 1.5}\right)$$

$$y = 30.73$$

Where x, y, a and b are indicated in parenthesis in the above table.

2) Additional Attenuation was calibrated using a Power Meter zeroed (i.e. Relative Measurement) on the output of a Signal Generator at 1.57542 GHz. This Additional Attenuation was required to drop the GPS Simulator output from the measurable range into the required range. This was measured as 34.60 dB.

3) GPS Simulator output (1 satellite) measured on a spectrum analyser using the following settings:

Parameter	Setting	Comments
Centre Frequency	1.57542 GHz	GPS L1 Band
Span	10 MHz	
Reference Level	-50 dBm	
Reference Attenuation	10dB	Automatic
Resolution Bandwidth	1 MHz	
Video Bandwidth	1 MHz	Automatic
Sweep Time	5 ms	Automatic
Trace Type	Peak (200)	Peak of 200 samples
Sweep Count	200	
Marker Frequency	1.57542 GHz	GPS L1 Band

Note: Investigation prior to this test programme indicated that using a Peak Trace Type gives a power level approximately 13dB higher than average and so the field strength would be effectively this much lower.

GPS Simulator software was adjusted to achieve a power output of -59.67 dBm.

4) Final Calculation:

Component	Value & Units
GPS Simulator output, P_{GPS}	-59.67 dBm
Additional Attenuation, L_A	34.60 dB
System Loss, L_S	30.73 dB
Signal Power, $P_S = P_{GPS} – L_A – L_S$	-125.00 dBm

2.10.6 Environmental Conditions

Ambient Temperature: 21.3 °C
Relative Humidity: 21 %

2.10.7 Test Results

Test Method Clause 5.6.8.1:

"a) Transmit the simulator signal over a suitable antenna.
b) Adjust the signal power by use of a calibrated test receiver to -125 dBm ± 5 dBm.
c) Replace the antenna of the calibrated test receiver by the receiving unit of the EUT.
d) A performance check shall be carried out."

Procedure/Results:

EUT was placed in the test chamber on a non-conductive platform. GPS simulator was started and the field strength calibrated as per the above procedure.

The EUT was powered up and the acquisition time noted in the following table; a Performance Check was then performed.

Test Parameter	Units	Result	Limit
Field Strength	dBm	-125.00	-125 dBm ± 5 dBm
Initial Acquisition Time	s	35	-
Performance Check			
Signal Type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	N/A	-
Time to acquire valid position	s	N/A	-
Total number of measurements	-	358	-
Number of measurements with HDOP ≥ 4 and PDOP ≥6	-	358	> 100
Measurement duration	min	5.95	> 5 and < 10
Measurements with position error ≤ 13 m	%	100	≥ 95

Limits Clause 4.3.7

"(M.112/A3.7) *The GPS receiver equipment* shall *be capable of acquiring satellite signals with input signals having carrier levels in the range of -130 dBm to -120 dBm* as measured at the output of a 3 dBi linear polarized receiving antenna. *Once the satellite signals have been acquired the equipment shall continue to operate satisfactorily with satellite signals having carrier levels down to -133 dBm* as measured at the output of a 3 dBi linear polarized receiving antenna."

Limits Clause 5.6.8.1

"The EUT shall meet the requirements of this check, within this signal range."

2.11 SENSITIVITY AND DYNAMIC RANGE – TRACKING

2.11.1 Specification Reference

IEC 61108-1, Clause 5.6.8.2

2.11.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

2.11.3 Date of Test and Modification State

29 November 2010 – Modification State 1

2.11.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.11.5 Test Setup

As per Section 2.10.5, Sensitivity and Dynamic Range – Acquisition

2.11.6 Environmental Conditions

Ambient Temperature: 21.3°C
Relative Humidity: 21 %

2.11.7 Test Results

Test Method Clause 5.6.8.2

"[As per Clause 5.6.8.1 except:]

d) After the start of transmission and tracking with the nominal transmission level condition, gradually reduce transmission level down to −133 dBm."

Procedure/Results:

EUT remained operational after the Sensitivity and Dynamic Range – Acquisition test in "Normal Operation"; locked and settled having just passed a Performance Check. GPS Signal power was then reduced gradually in 0.5dB steps over 1.5 minutes to -133 dBm.

The EUT continued to track enough satellites to maintain a position fix. The NMEA 0183 'GSV' sentence, the 'GGA' sentence gave the number of satellites used from the position solution as 10 or 11 out of a possible 11 throughout a 3-minute period of observation.

Limits Clause 4.3.7

"(M.112/A3.7) *The GPS receiver equipment* shall *be capable of acquiring satellite signals with input signals having carrier levels in the range of -130 dBm to -120 dBm* as measured at the output of a 3 dBi linear polarized receiving antenna. *Once the satellite signals have been acquired the equipment shall continue to operate satisfactorily with satellite signals having carrier levels down to -133 dBm* as measured at the output of a 3 dBi linear polarized receiving antenna."

Limits Clause 5.6.8.1

"The EUT shall continue tracking at least one satellite."

2.12 SLOW SPEED UPDATE RATE

2.12.1 Specification Reference

IEC 61108-1, Clause 5.6.10.1

2.12.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

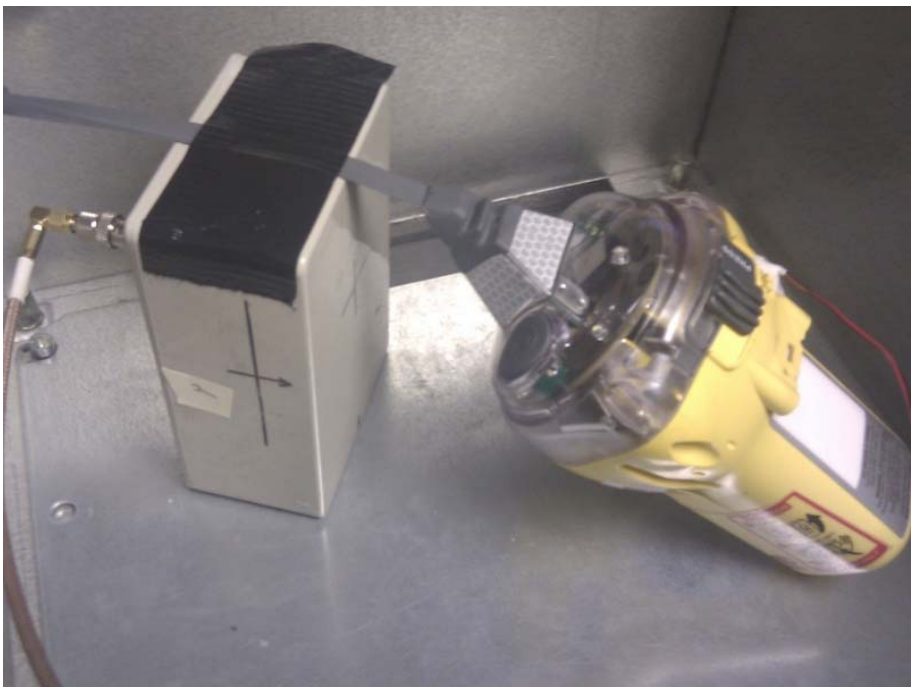
2.12.3 Date of Test and Modification State

08 March 2011 – Modification State 1

2.12.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.12.5 Test Setup



Test Set-up

2.12.6 Environmental Conditions

Ambient Temperature:	22.0 °C
Relative Humidity:	27 %RH

2.12.7 Test Results

EUT was locked and settled on a static simulated position; the simulated scenario then began a period of motion at 5 knots ±1 knot. During a 10-minute period of observation, the time between position output messages and time between position updates was checked. Maximum values are recorded in the table below.

To confirm the minimum resolution of position, the GGA sentence of the NMEA 0183 output was inspected for the Latitude and Longitude field values (see table below), in the format *DDMM.X* and *DDDMM.X* respectively. Where *D* is degrees, *M* is minutes and *X* is decimal places of minutes.

A Performance Check was carried out during the 10-minute observation period to confirm that the received positions complied with the simulated position.

Test Parameter	Units	Result	Limit
Maximum position output interval	s	1	≤ 1
Maximum position update interval	s	1	≤ 10
Sample latitude field value	Min	5051.01672	Resolution must be to 0.001
Sample longitude field value	Min	00107.40478	Resolution must be to 0.001
Performance Check			
Signal type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	Y	-
Time to acquire valid position	s	N/A	-
Total number of measurements	-	599	-
Number of measurements with HDOP ≥ 4 and PDOP ≥ 6	-	599	> 100
Measurement duration	min	10.00	> 5 and < 10
Measurements with position error ≤ 13 m *	%	100	≥ 95

* Position error relative to the instantaneous position

2.13 HIGH SPEED UPDATE RATE

2.13.1 Specification Reference

IEC 61108-1, Clause 5.6.10.2

2.13.2 Equipment Under Test

uBlox NEO - 6M (G5 Smartfind Plus), S/N: 75911555-TSR0004

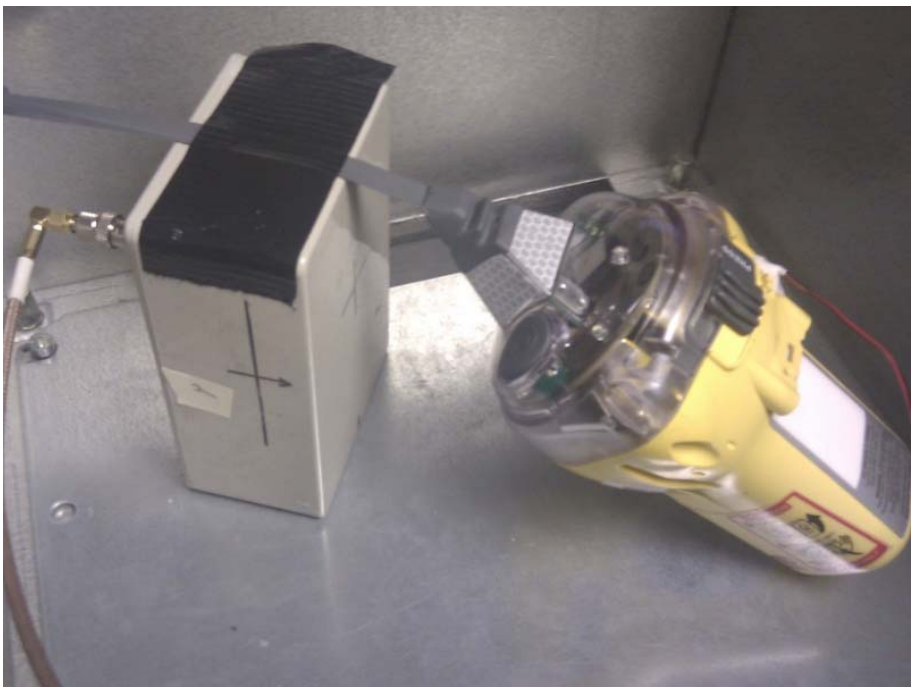
2.13.3 Date of Test and Modification State

08 March 2011 – Modification State 1

2.13.4 Test Equipment Used

The major items of test equipment used for the above tests are identified in Section 3.1.

2.13.5 Test Setup



Test Set-up

2.13.6 Environmental Conditions

Ambient Temperature:	22.6 °C
Relative Humidity:	28 %RH

2.13.7 Test Results

Deviation from the Test Method Clause

A simulator was used to perform this test; however, EUT output was at 1-second intervals, not 0.5 s as required (or "recommended" as per Clause 4.3.9).

Results

EUT was locked and settled on a scenario simulating motion at 70 knots. During a 10-minute period of observation, the time between position output messages and time between position updates was checked. Maximum values are recorded in the table below.

To confirm the minimum resolution of position, the GGA sentence of the NMEA 0183 output was inspected for the Latitude and Longitude field values (see table below), in the format *DDMM.X* and *DDDMM.X* respectively. Where *D* is degrees, *M* is minutes and *X* is decimal places of minutes.

A Performance Check was carried out during the 10-minute observation period to confirm that the received positions complied with the simulated position.

Test Parameter	Units	Result	Limit
Maximum position output interval	s	1	≤ 1
Maximum position update interval	s	1	≤ 1
Sample latitude field value	min	5052.99614	Resolution must be to 0.001
Sample longitude field value	min	00102.79923	Resolution must be to 0.001
Performance Check			
Signal type	Live/Simulated	Simulated	-
EUT started simultaneously	Y/N	Y	-
Time to acquire valid position	s	N/A	-
Total number of measurements	-	601	-
Number of measurements with HDOP ≥ 4 and PDOP ≥ 6	-	601	> 100
Measurement duration	min	10.00	> 5 and < 10
Measurements with position error ≤ 13 m *	%	100	≥ 95

SECTION 3

TEST EQUIPMENT USED

3.1 TEST EQUIPMENT

List of absolute measuring and other principal items of test equipment.

Instrument	Manufacturer	Type No.	TE No.	Calibration Period (months)	Calibration Due
Section 2.2 Beacons - GPS Static Accuracy					
Power Supply Unit	Farnell	LT-30-2	41	-	O/P Mon
Multimeter	Iso-tech	IDM101	2421	12	26-Oct-2011
Stop Clock	R.S Components	RS328 061	2674	-	TU
Inclinometer	FISCO	EN 17	3223	12	24-Dec-2011
Humidity and Temperature Meter	R.S Components	1361C	3844	12	7-Feb-2012
Section 2.3 Beacons - GPS Angular Movement of the Antenna					
Power Supply Unit	Farnell	LT-30-2	41	-	O/P Mon
Multimeter	Iso-tech	IDM101	2421	12	26-Oct-2011
Stop Clock	R.S Components	RS328 061	2674	-	TU
Inclinometer	FISCO	EN 17	3223	12	24-Dec-2011
Humidity and Temperature Meter	R.S Components	1361C	3844	12	7-Feb-2012
Section 2.4 Beacons - GPS Dynamic Accuracy					
Power Supply Unit	Farnell	LT-30-2	41	-	O/P Mon
Multimeter	Iso-tech	IDM101	2421	12	26-Oct-2011
Stop Clock	R.S Components	RS328 061	2674	-	TU
GPS/SBAS Simulator	Spirent	STR4500	3056	-	TU
Sections 2.5, 2.6, 2.7 and 2.8 Beacons - GPS Acquisition (Power Conditions)					
Power Supply Unit	Farnell	LT-30-2	41	-	O/P Mon
Multimeter	Iso-tech	IDM101	2421	12	26-Oct-2011
Stop Clock	R.S Components	RS328 061	2674	-	TU
GPS/SBAS Simulator	Spirent	STR4500	3056	-	TU
Hygrometer	Rotronic	I-1000	3068	12	10-Jul-2011
Timer	Radio Spares	427-590	3282	-	TU
Sections 2.10 and 2.11 Beacons - GPS Position Update and 2.9 Beacons - GPS Protection					
Power Supply Unit	Farnell	LT-30-2	41	-	O/P Mon
RF Shielded Enclosure	Rittal	AE1380	162	-	TU
Multimeter	Iso-tech	IDM101	2421	12	26-Oct-2011
Stop Clock	R.S Components	RS328 061	2674	-	TU
GPS/SBAS Simulator	Spirent	STR4500	3056	-	TU
Hygrometer	Rotronic	I-1000	3068	12	10-Jul-2011
Timer	Radio Spares	427-590	3282	-	TU
Section 2.12 and 2.13 Beacons – Slow and High Speed Update Rate					
Power Supply Unit	Farnell	LT-30-2	41	-	O/P Mon
RF Shielded Enclosure	Rittal	AE1380	162	-	TU
Multimeter	Iso-tech	IDM101	2421	12	26-Oct-2011
Stop Clock	R.S Components	RS328 061	2674	-	TU
GPS/SBAS Simulator	Spirent	STR4500	3056	-	TU
Hygrometer	Rotronic	I-1000	3068	12	10-Jul-2011
Timer	Radio Spares	427-590	3282	-	TU

TU – Traceability Unscheduled
O/P MON – Output Monitored with Calibrated Equipment

SECTION 4

DISCLAIMERS AND COPYRIGHT

4.1 DISCLAIMERS AND COPYRIGHT

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ANNEX A

CUSTOMER SUPPLIED INFORMATION: GPS MODULE DATASHEET

GPS

NEO-6

u-blox 6 GPS Modules

Data Sheet

locate, communicate, accelerate

Objective Specification

Abstract

Technical data sheet describing the cost effective, high-performance u-blox 6 based NEO-6 series of GPS modules, that brings the high performance of the u-blox 6 positioning engine to the miniature NEO form factor.

These receivers combine a high level of integration capability with flexible connectivity options in a small package. This makes them perfectly suited for mass-market end products with strict size and cost requirements.

16.0 x 12.2mm

www.u-blox.com

Document Information	
Title	NEO-6
Subtitle	u-blox 6 GPS Modules
Document type	Data Sheet
Document number	GPS.G6-HW-09005
Document status	Objective Specification This document contains target or goal specification for product development.

This document applies to the following products:

Name	Type number	ROM/FLASH version	PCN reference
NEO-6Q		6.01	
NEO-6M		6.01	

Objective Specification

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Objective Specification

1 Functional description

1.1 Overview

The NEO-6 module series is a family of stand-alone GPS receivers featuring the high performance u-blox 6 positioning engine. These flexible and cost effective receivers offer numerous connectivity options in a miniature 16 x 12.2 x 2.4mm package. Their compact architecture and power and memory options make NEO-6 modules ideal for battery operated mobile devices with very strict cost and space constraints.

The 50-channel u-blox 6 positioning engine boasts a Time-To-First-Fix (TTFF) of under 1 second. The dedicated acquisition engine, with 2 million correlators, is capable of massive parallel time/frequency space searches, enabling it to find satellites instantly. Innovative design and technology suppresses jamming sources and mitigates multipath effects, giving NEO-6 GPS receivers excellent navigation performance even in the most challenging environments.

1.2 Product features

Series	Power	Memory	Function					Antenna		Input / Output					
	Voltage range [V]	Programmable (Flash) FW update	Power Save mode	Capture & Process	TCXO	Dead Reckoning	Raw data	Precision Timing	Antenna supply	Antenna supervisor	UART	USB	SPI	DDC (I²C compliant)	Reset input	Configuration pin
NEO-6M	2.7 - 3.6		•								1	1		1		1
NEO-6Q	2.7 - 3.6		•		•						1	1		1		3

Table 1: Features of the NEO-6 Series

Objective Specification

1.3 GPS performance

Parameter	Specification		
Receiver type	50 Channels GPS L1 frequency, C/A Code GALILEO Open Service L1 frequency		
Time-To-First-Fix[1]		NEO-6Q	NEO-6M
	Cold Start (Autonomous)	29 s	32s
	Warm Start (Autonomous)	29 s	32s
	Hot Start (Autonomous)	<1 s	<1s
	Aided Starts[2]	<1 s	<3s
Sensitivity[3]		NEO-6Q	NEO-6M
	Tracking & Navigation	-160 dBm	-160 dBm
	Reacquisition	-160 dBm	-160 dBm
	Cold Start (Autonomous)	-147 dBm	-146 dBm
Horizontal position accuracy[4]	Autonomous	< 2.5 m	
	SBAS	< 2.0 m	
Accuracy of Timepulse signal	RMS 99% Time Pulse	30 ns <60 ns Configurable f = 0.25 Hz ... 1 kHz	
Max navigation update rate		up to 5 Hz	
Velocity accuracy[5]		0.1m/s	
Heading accuracy[6]		0.5 degrees	
Dynamics		≤ 4 g	
Operational limits[7]	Altitude	50000 m	
	Velocity	500 m/s	

Table 2: NEO-6 GPS performance

Objective Specification

[1] All satellites at -130 dBm
[2] Dependent on aiding data connection speed and latency
[3] Demonstrated with a good active antenna
[4] CEP, 50%, 24 hours static, -130dBm, SEP: <3.5m
[5] 50% @ 30 m/s
[6] 50% @ 30 m/s
[7] Assuming Airborne <4g platform

1.4 Block diagram

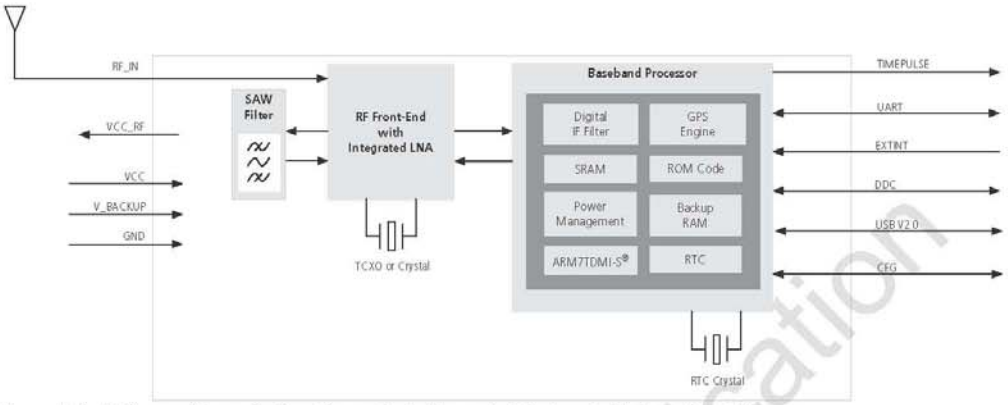


Figure 1: Block diagram (For available options refer to the product features table in section 1.2).

1.5 Assisted GPS (A-GPS)

Supply of aiding information like ephemeris, almanac, rough last position and time and satellite status and an optional time synchronization signal will reduce time to first fix significantly and improve the acquisition sensitivity. All NEO-6 modules support the u-blox AssistNow Online and AssistNow Offline A-GPS services[8] and are OMA SUPL compliant.

1.6 SuperSense Indoor GPS

All NEO-6 modules come with SuperSense, providing ultra-fast acquisition/reacquisition and exceptional tracking sensitivity. SuperSense enables best-in-class tracking and navigation in difficult signal environments such as urban canyons or indoor locations.

1.7 KickStart / Oscillators

An available feature is KickStart. This functionality uses a TCXO to accelerate weak signal acquisition, enabling faster start and reacquisition times. KickStart is available with the NEO-6Q.

1.8 Protocols and interfaces

Protocol	Type
NMEA	Input/output, ASCII, 0183, 2.3 (compatible to 3.0)
UBX	Input/output, binary, u-blox proprietary

Table 3: Available protocols

Both protocols are available on UART, USB, and DDC. For specification of the various protocols see the *u-blox 5 & u-blox 6 Receiver Description Including Protocol Specification* [2].

NEO-6 modules support a number of peripheral interfaces for serial communication. The embedded firmware uses these interfaces according to their respective protocol specifications. For specific applications, the firmware also supports the connection of peripheral devices, such as external memories, to some of the interfaces.

[8] Requires external memory.

Objective Specification

1.8.1 UART

NEO-6 modules include one configurable UART interface for serial communication (for information about configuration see section 1.11).

1.8.2 USB

NEO-6 modules provide a USB version 2.0 FS (Full Speed, 12Mbit/s) interface as an alternative to the UART. The pull-up resistor on USB_DP is integrated to signal a full-speed device to the host. The VDD_USB pin supplies the USB interface, independently from the VDD_IO pin.

1.8.3 Display Data Channel (DDC)

The I^2C compatible DDC interface can be used either to access external devices with a serial interface (e.g. EEPROM or A/D converters) or to interface with a host CPU. It is capable of master and slave operation.

☞ The maximum bandwidth is 100kBit/s.

Objective Specification

1.9 Antenna

NEO-6 modules are designed for use with passive and active[9] antennas.

Parameter	Specification	
Antenna Type		Passive and active antenna
Active Antenna Recommendations	Minimum gain	15 - 20 dB (to compensate signal loss in RF cable)
	Maximum noise figure	1.5 dB
	Maximum gain	50 dB

Table 4: Antenna Specifications for all NEO-6 modules

1.10 Power management

For more information about power management strategies, see the *u-blox 5 & u-blox 6 Receiver Description Including Protocol Specification* [2].

1.10.1 Operating modes

NEO-6 modules have 2 continuous operating modes (Maximum Performance and Eco) and 1 intermittent operating mode (Power Save). Maximum Performance mode freely uses the acquisition engine, resulting in the best possible TTFF, while Eco mode optimizes the use of the acquisition engine to deliver lower current consumption. At medium to strong signals, there is almost no difference for acquisition and tracking performance in these modes.

1.10.2 Maximum Performance mode

In Maximum Performance mode, u-blox 6 receivers use the acquisition engine at full performance to search for all possible satellites until the Almanac is completely downloaded.

As a consequence, tracking current consumption level will be achieved when:

- A valid GPS position is fixed
- Almanac is entirely downloaded
- Ephemeris for all satellites in view are valid

1.10.3 Eco mode

In Eco mode, u-blox 6 receivers use the acquisition engine to search for new satellites *only when needed* for navigation:

- In cold starts, u-blox 6 searches for enough satellites to navigate and optimizes use of the acquisition engine to download their ephemeris.
- In non-cold starts, u-blox 6 focuses on searching for visible satellites whose orbits are known from the Almanac.

In Eco mode, the u-blox 6 acquisition engine limits use of its searching resources to minimize power consumption. As a consequence the time to find some satellites at weakest signal level might be slightly increased in comparison to the Max. Performance mode.

[9] For information on using active antennas with NEO-6 modules, see the *LEA-6/NEO-6 Hardware Integration Manual* [1].

Objective Specification

u-blox 6 deactivates the acquisition engine as soon as a position is fixed and a sufficient number (at least 4) of satellites are being tracked. The tracking engine continues to search and track new satellites without orbit information.

1.10.4 Power Save mode

NEO-6 modules include intelligent power management that allows reducing the average tracking current consumption by periodically switching off parts of or the complete GPS receiver and waking it up at configurable intervals from one second to one week. This can be done by using a hardware interrupt or by sending a serial command.

1.11 Configuration

1.11.1 Boot-time configuration

NEO-6 modules provide configuration pins for boot-time configuration. These become effective immediately after start-up. Once the module has started, the configuration settings may be modified with UBX configuration messages. The modified settings remain effective until power-down or reset. If these settings have been stored in battery-backup RAM, then the modified configuration will be retained, as long as the backup battery supply is not interrupted.

All NEO-6 modules include a **CFG_COM0** pin, which can be configured as seen in Table 5. Default settings in bold.

CFG_COM0	Protocol	Messages	UART Baud rate	USB Power
1	**NMEA**	**GSV, RMC, GSA, GGA, GLL, VTG, TXT**	**9600**	**BUS Powered**
0	NMEA	GSV, RMC, GSA, GGA, GLL, VTG, TXT	38400	Self Powered

Table 5: Supported CFG_COM0 settings

NEO-6Q includes both **CFG_COM0** and **CFG_COM1** pins and can be configured as seen in Table 6. Default settings in bold.

CFG_COM1	CFG_COM0	Protocol	Messages	UART Baud rate	USB power
1	**1**	**NMEA**	**GSV, RMC, GSA, GGA, GLL, VTG, TXT**	**9600**	**BUS Powered**
1	0	NMEA	GSV, RMC, GSA, GGA, GLL, VTG, TXT	38400	Self Powered
0	1	NMEA	GSV, RMC, GSA, GGA, VTG, TXT	4800	BUS Powered
0	0	UBX	NAV-SOL, NAV-STATUS, NAV-SVINFO, NAV-CLOCK, INF, MON-EXCEPT	57600	BUS Powered

Table 6: Supported COM settings (NEO-6Q)

NEO-6Q includes a **CFG_GPS0** pin, which enables the boot-time configuration of the power mode. These settings are described in Table 7. Default settings in bold.

CFG_GPS0	Power Mode
0	Eco Mode
1	**Maximum Performance Mode**

Table 7: Supported CFG_GPS0 settings (NEO-6Q)

1.12 External serial EEPROM

NEO-6 modules allow an optional external serial EEPROM to be connected to the DDC interface.

☞ For more information see the *LEA-6/NEO-6 Hardware Integration Manual* [1].

Objective Specification

2 Mechanical specifications

Parameter	Specification	
A	16.0 +0.6/-0.1mm	[628.8 +24/-4mil]
B	12.2 ±0.1mm	[479.5 ±4mil]
C	2.4 ±0.2mm	[94.3 ±8mil]
D	1.0 +0.3/-0.1mm	[39.3 +18/-4mil]
E	1.1 ±0.1mm	[43.2 ±4mil]
F	3.0 ±0.1mm	[117.9 ±4mil]
G	1.1 ±0.1mm	[43.2 ±4mil]
Weight	1.6 g	

Table 8: Dimensions

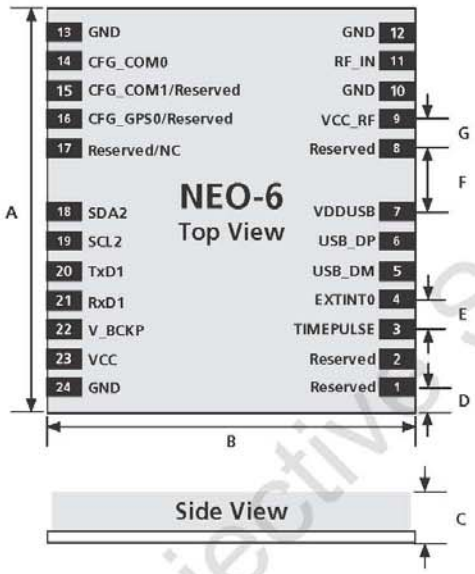


Figure 2: Dimensions (see Table 9 for specification)

☞ For information regarding the Paste Mask and Footprint see the *LEA-6/NEO-6 Hardware Integration Manual* [1].

Objective Specification

2.1 Pin assignment

No	Module	Name	I/O	Description
1	All	Reserved	I	Reserved
2	All	Reserved	I	Reserved
3	All	TIMEPULSE	O	Time pulse (1PPS)
4	All	EXTINT0	I	External Interrupt Pin
5	All	USB_DM	I/O	USB Data
6	All	USB_DP	I/O	USB Data
7	All	VDDUSB	I	USB Supply
8	All	Reserved		See Hardware Integration Manual Pin 8 and 9 must be connected together.
9	All	VCC_RF	O	Output Voltage RF section Pin 8 and 9 must be connected together.
10	All	GND	I	Ground
11	All	RF_IN	I	GPS signal input
12	All	GND	I	Ground
13	All	GND	I	Ground
14	All	CFG_COM0	I	Configuration Pin
15	NEO-6Q	CFG_COM1	I	Configuration Pin. Leave open if not used.
	NEO-6M	Reserved	I	Reserved
16	NEO-6Q	CFG_GPS0	I	Power Mode Configuration Pin
	NEO-6M	Reserved	I	Reserved
17	NEO-6Q	Reserved	I	Reserved
	NEO-6M	NC	I	Not Connected
18	All	SDA2	I/O	DDC Data
19	All	SCL2	I/O	DDC Clock
20	All	TxD1	O	Serial Port 1
21	All	RxD1	I	Serial Port 1
22	All	V_BCKP	I	Backup voltage supply
23	All	VCC	I	Supply voltage
24	All	GND	I	Ground

Table 9: Pinout

Pins designated Reserved should only be used with caution. For more information about Pinouts see the *LEA-6/NEO-6 Hardware Integration Manual* [1].

Objective Specification

3 Electrical specifications

3.1 Absolute maximum ratings

Parameter	Symbol		Condition	Min	Max	Units
Power supply voltage (VCC)	Vcc	All		-0.5	3.6	V
Backup battery voltage (V_BCKP)	Vbckp	All		-0.5	3.6	V
USB supply voltage (VDDUSB)	Vddusb	All			3.6	V
Input pin voltage	Vin	All		-0.5	3.6	V
	Vin_usb	All		-0.5	Vddusb	V
VCC_RF output current	Iccrf	All			100	mA
Input power at RF_IN	Prfin	All	source impedance = 50 Ω, continuous wave		-5	dBm
Storage temperature	Tstg	All		-40	85	°C

Table 10: Absolute maximum ratings

GPS receivers are Electrostatic Sensitive Devices (ESD) and require special precautions when handling. For more information see the *LEA-6/NEO-6 Hardware Integration Manual* [1].

Stressing the device beyond the "Absolute Maximum Ratings" may cause permanent damage. These are stress ratings only. The product is not protected against overvoltage or reversed voltages. If necessary, voltage spikes exceeding the power supply voltage specification, given in table above, must be limited to values within the specified boundaries by using appropriate protection diodes.

Objective Specification

3.2 Operating conditions

All specifications are at an ambient temperature of 25°C.

Parameter	Symbol	Module	Min	Typ	Max	Units	Condition
Power supply voltage (VCC)	Vcc	All	2.7	3.0	3.6	V	
Peak supply current [10]	Iccp	All			150	mA	Vcc = 3.6V
Sustained supply current [11]	Icc Acquisition	All		49 [12]		mA	Vcc = 3.0V
	Icc Tracking (Max Performance mode)	NEO-6Q		42 [13]		mA	Vcc = 3.0V
		NEO-6M		40 [13]		mA	Vcc = 3.0V
	Icc Tracking (Eco mode)	NEO-6Q		40 [13]		mA	Vcc = 3.0V
		NEO-6M		38 [13]		mA	Vcc = 3.0V
	Icc Tracking (Power Save mode / 1 Hz)	NEO-6Q		17 [13]		mA	Vcc = 3.0V
		NEO-6M		16 [13]		mA	Vcc = 3.0V
Backup battery voltage	Vbckp		1.4		3.6	V	
Backup battery current	Ibckp			25		µA	Vbckp = 1.8V
Input pin voltage range	Vin				3.6	V	
Input pin low voltage	Vin_low_1				0.2x Vcc	V	
Input pin high voltage	Vin_high_1		0.7x Vcc			V	
Input pin low voltage for EXTINT0 and RxD1	Vin_low_2				0.22	V	
Input pin high voltage for EXTINT0 and RxD1	Vin_high_2		0.91			V	
Output pin low voltage	Vout_low				0.4	V	Iout = 4 mA
Output pin high voltage	Vout_high	All	Vcc – 0.4			V	Iout = -4 mA
VDDUSB (Pin 24) for USB operation	Vddusb1	All	3.0 [14]		3.6	V	
USB_DM, USB_DP	VinU	All	Compatible with USB with 27 Ohms series resistance				
Antenna gain	Gant	All			50	dB	
Receiver Chain Noise Figure	NFtot			2.5		dB	
VCC_RF voltage	Vccrf	All		Vcc-0.1		V	
VCC_RF output current	Iccrf	All			50	mA	
Operating temperature	Topr	All	-40		85	°C	

Table 11: Operating conditions

Operation beyond the specified operating conditions can affect device reliability.

4 Design-in

In order to obtain the necessary information to conduct a proper design-in, u-blox strongly recommends consulting the *LEA-6/NEO-6 Hardware Integration Manual* [1].

[10] Use this figure to dimension maximum current capability of power supply
[11] Use this figure to determine required battery capacity.
[12] ROM 6.00, >8 SVs in view, CNo >40 dBHz, current average of 30 sec after cold start
[13] ROM 6.00, with strong signals, all orbits available. For Cold Starts typical 12 min after First Fix. For Hot Starts typical 15 sec after First Fix.
[14] If USB not used connect to GND

Objective Specification

5 Reliability tests and approvals

5.1 Reliability tests

The u-blox 6 product family is qualified according to the ISO 16750 standard: "Road vehicles - Environmental conditions and testing for electrical and electronic equipment".

5.2 Approvals

Products marked with this lead-free symbol on the product label comply with the "Directive 2002/95/EC of the European Parliament and the Council on the Restriction of Use of certain Hazardous Substances in Electrical and Electronic Equipment" (RoHS).

All u-blox 6 GPS modules are RoHS compliant.

Objective Specification

6 Product handling

6.1 Packaging

NEO-6 modules are delivered as hermetically sealed, reeled tapes in order to enable efficient production, production lot set-up and tear-down.

Figure 3: Reeled u-blox 6 modules

6.1.1 Reels

NEO-6 GPS modules are deliverable in quantities of 250pcs on a reel. The dimensions of the reel are shown in Figure 4.

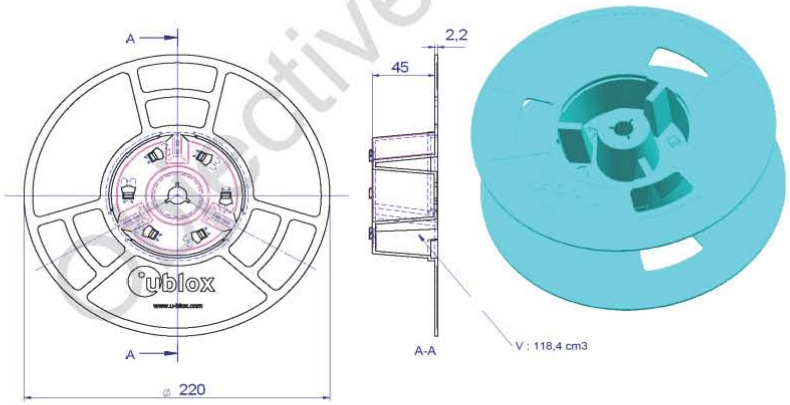


Figure 4: Dimension of reel for 250 pieces (dimensions unless otherwise specified in mm)

Objective Specification

6.1.2 Tapes

The dimensions and orientations of the tapes for NEO-6 modules are specified in Figure 5.

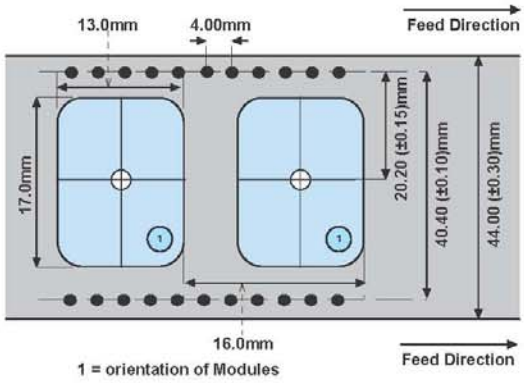


Figure 5: Dimensions and orientation for NEO-6 modules on tape

6.2 Shipment, storage and handling

NEO modules are designed and packaged to be processed in an automatic assembly line, and are shipped in Tape-and-Reel.

NEO-6 modules are Moisture Sensitive Devices (MSD) in accordance to the IPC/JEDEC specification. Appropriate MSD handling instructions and precautions are summarized in Sections 6.2.1 to 6.2.3. Read them carefully to prevent permanent damage due to moisture intake.

GPS receivers contain highly sensitive electronic circuitry and are Electrostatic Sensitive Devices (ESD). Handling NEO-6 modules without proper ESD protection may destroy or damage them permanently. See Section 6.2.6 for ESD handling instructions.

6.2.1 Moisture Sensitivity Levels

The Moisture Sensitivity Level (MSL) relates to the packaging and handling precautions required. NEO-6 modules are rated at MSL level 4.

For MSL standard see IPC/JEDEC J-STD-020, which can be downloaded from www.jedec.org.

Objective Specification

6.2.2 Shipment

Table 12 summarizes the dry pack requirements for different MSL levels in the IPC/JDEC specification.

MSL Level	Dry Pack Requirement
1	Optional
2	Required
2a	Required
3	Required
4	Required

Table 12: JEDEC specification of dry pack requirements

According to IPC/JEDEC specification J-STD-020, if a device passes MSL level 1, it is classified as not moisture sensitive and does not require dry pack. If a device fails level 1 but passes a higher numerical level, it is classified as moisture sensitive and must be dry packed in accordance with J-STD-033.

NEO-6 modules are delivered on Tape-and-Reels in a hermetically sealed package ("dry bag") to prevent moisture intake and protect against electrostatic discharge. For protection from physical damage, the reels are individually packed in cartons.

Carrier materials such as trays, tubes, reels, etc., that are placed in the Moisture Barrier Bag (MBB) can affect the moisture level within the MBB. Therefore, the effect of these materials is compensated by adding additional desiccant in the MBB to ensure the shelf life of the SMD packages.

The dry bag provides an IPC/JEDEC compliant MSD label describing the handling requirements to prevent humidity intake. IPC/JEDEC specifications require that MSD sensitive devices be packaged together with a Humidity Indicator Card (HIC) and desiccant to absorb humidity. If no moisture has been absorbed, the three fields in the HIC indicate blue color. Figure 6 shows examples of an MSD label and HIC.

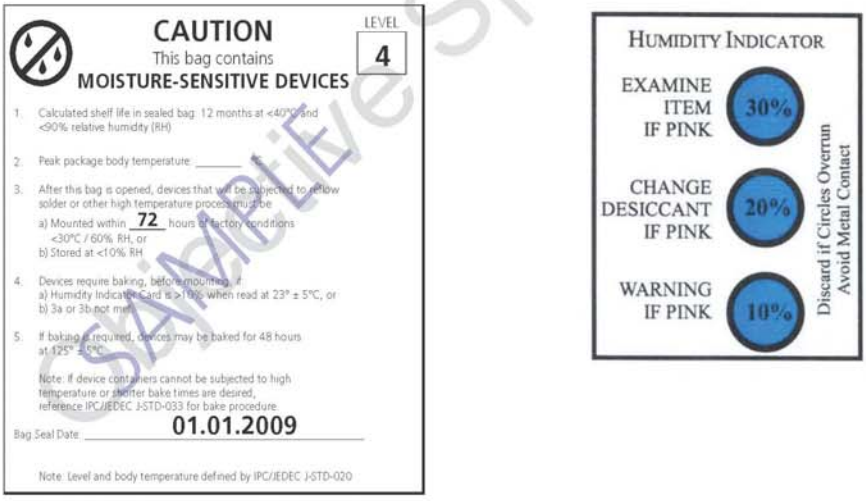


Figure 6: Examples of MSD label and Humidity Indicator Card

Objective Specification

6.2.3 Storage and floor life

The calculated shelf life for dry packed SMD packages is a minimum of 12 months from the bag seal date, when stored in a noncondensing atmospheric environment of <40°C/90% RH.

Table 13 lists floor life for different MSL levels in the IPC/JEDEC specification.

MSL level	Floor life (out of bag) at factory ambient ≤30°C/60% RH or as stated
1	Unlimited at ≤30°C/85% RH
2	1 year
2a	4 weeks
3	168 hours
4	72 hours

Table 13: JEDEC specification of floor life

The parts must be processed and soldered within the time specified for the MSL level. If this time is exceeded, or the humidity indicator card in the sealed package indicates that they have been exposed to moisture, the devices need to be pre-baked before the reflow solder process.

6.2.4 Drying

Both encapsulant and substrate materials absorb moisture. IPC/JEDEC specification J-STD-020 must be observed to prevent cracking and delamination associated with the "popcorn" effect during reflow soldering. The popcorn effect can be described as miniature explosions of evaporating moisture. Baking before processing is required in the following cases:

- Humidity indicator card: At least one circular indicator is no longer blue
- Floor life or environmental requirements after opening the seal have been exceeded, e.g. exposure to excessive seasonal humidity.

Refer to Section 4 of IPC/JEDEC J-STD-033 for recommended baking procedures. Table 4-1 of the specification lists the required bake times and conditions for drying. For example, a module that has exceeded its floor life by >72 hours shall be baked at 125°C for 9 hours. (Floor life begins counting at time = 0 after bake).

⚠ **Do not attempt to bake NEO-6 modules while contained in tape and rolled up in reels. For baking, place parts individually onto oven tray.**

⚠ **Oxidation Risk: Baking SMD packages may cause oxidation and/or intermetallic growth of the terminations, which if excessive can result in solderability problems during board assembly. The temperature and time for baking SMD packages are therefore limited by solderability considerations. The cumulative bake time at a temperature greater than 90°C and up to 125°C shall not exceed 96 hours. If the bake temperature is not greater than 90°C, there is no limit on bake time. Bake temperatures higher than 125°C are not allowed.**

6.2.5 Reflow soldering

Reflow profiles are to be selected according to IPC/JEDEC J-STD-020.

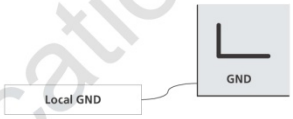
Objective Specification

6.2.6 ESD handling precautions

NEO-6 modules are Electrostatic Sensitive Devices (ESD). Observe precautions for handling! Failure to observe these precautions can result in severe damage to the GPS receiver!

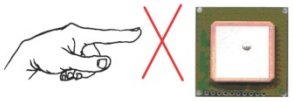
GPS receivers are Electrostatic Sensitive Devices (ESD) and require special precautions when handling. Particular care must be exercised when handling patch antennas, due to the risk of electrostatic charges. In addition to standard ESD safety practices, the following measures should be taken into account whenever handling the receiver:

- Unless there is a galvanic coupling between the local GND (i.e. the work table) and the PCB GND, then the first point of contact when handling the PCB shall always be between the local GND and PCB GND.



- Before mounting an antenna patch, connect ground of the device
- When handling the RF pin, do not come into contact with any charged capacitors and be careful when contacting materials that can develop charges (e.g. patch antenna ~10pF, coax cable ~50-80pF/m, soldering iron, …)

- To prevent electrostatic discharge through the RF input do not touch the mounted patch antenna.



- When soldering RF connectors and patch antennas to the receiver's RF pin, make sure to use an ESD safe soldering iron (tip).

Objective Specification

7 Default settings

Interface	Settings
Serial Port 1 Output	9600 Baud, 8 bits, no parity bit, 1 stop bit Configured to transmit both NMEA and UBX protocols, but only following NMEA and no UBX messages have been activated at start-up: **GGA, GLL, GSA, GSV, RMC, VTG, TXT**
USB Output	Configured to transmit both NMEA and UBX protocols, but only following NMEA and no UBX messages have been activated at start-up: **GGA, GLL, GSA, GSV, RMC, VTG, TXT** USB Power Mode: Bus-Powered
Serial Port 1 Input	9600 Baud, 8 bits, no parity bit, 1 stop bit Automatically accepts following protocols without need of explicit configuration: **UBX, NMEA** The GPS receiver supports interleaved UBX and NMEA messages.
USB Input	Automatically accepts following protocols without need of explicit configuration: **UBX, NMEA** The GPS receiver supports interleaved UBX and NMEA messages. USB Power Mode: Bus-Powered
TIMEPULSE (1Hz Nav)	1 pulse per second, synchronized at rising edge, pulse length 100ms
Power Mode	Maximum Performance mode

Table 14: Available protocols

Refer to the *LEA-6/NEO-6 Hardware Integration Manual* [1] for information about further settings.

Objective Specification

8 Labeling and ordering information

8.1 Product labeling

The labeling of u-blox 6 GPS modules includes important product information. The location of the product type number is shown in Figure 7.

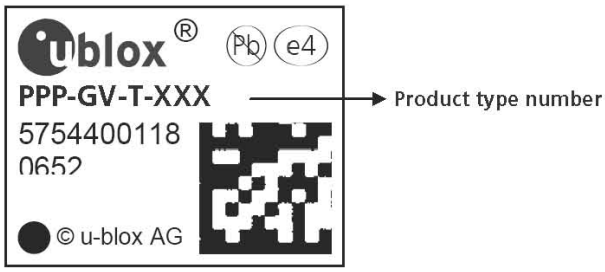


Figure 7: Location of product type number on u-blox 6 module label

8.2 Explanation of codes

3 different product code formats are used. The **Product Name** is used in documentation such as this data sheet and identifies all u-blox 6 products, independent of packaging and quality grade. The **Ordering Code** includes options and quality, while the **Type Number** includes the hardware and firmware versions. Table 15 below details these 3 different formats:

Format	Structure
Product Name	PPP-GV
Ordering Code	PPP-GV-T
Type Number	PPP-GV-T-XXX

Table 15: Product Code Formats

The parts of the product code are explained in Table 16.

Code	Meaning	Example
PPP	Product Family	NEO
G	Product Generation	6 = u-blox6
V	Variant	T = Timing, R = DR, etc.
T	Option / Quality Grade	Describes standardized functional element or quality grade such as Flash size, automotive grade etc.
XXX	Product Detail	Describes product details or options such as hard- and software revision, cable length, etc.

Table 16: part identification code

8.3 Ordering information

Ordering No.	Product
NEO-6M-0	ROM-based u-blox 6 GPS Module, 12x16mm, 250 pcs/reel
NEO-6Q-0	ROM-based u-blox 6 GPS Module with TCXO, 12x16mm, 250 pcs/reel

Table 17: Product Ordering Codes

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Product changes affecting form, fit or function are documented by u-blox. For a list of Product Change Notifications (PCNs) see our website at: http://www.u-blox.com/customersupport/pcn/ublox5.html.

Related documents

[1] LEA-6/NEO-6 Hardware Integration Manual , Docu. No GPS.G6-HW-09007

[2] u-blox 5 & u-blox 6 Receiver Description Including Protocol Specification, Docu. No GPS-X-07036

All these documents are available on our homepage (http://www.u-blox.com).

For regular updates to u-blox documentation and to receive product change notifications please register on our homepage.

Revision history

Revision	Date	Name	Status / Comments
	31/08/2009	tgri	Initial Version

Objective Specification

Contact

For complete contact information visit us at www.u-blox.com

Headquarters

u-blox AG
Zuercherstrasse 68
CH-8800 Thalwil
Switzerland

Phone: +41 44 722 74 44
Fax: +41 44 722 74 47
E-mail: info@u-blox.com

Offices

North, Central and South America

u-blox America, Inc.
Phone: +1 (703) 483 3180
E-mail: info_us@u-blox.com

Regional Office West Coast:
Phone: +1 (703) 483 3184
E-mail: info_us@u-blox.com

Technical Support:
Phone: +1 (703) 483 3185
E-mail: support_us@u-blox.com

Europe, Middle East, Africa

u-blox AG
Phone: +41 44 722 74 44
E-mail: info@u-blox.com

Technical Support:
Phone: +41 44 722 74 44
E-mail: info@u-blox.com

Asia, Australia, Pacific

u-blox Singapore Pte. Ltd.
Phone: +65 6734 3811
E-mail: info_ap@u-blox.com
Support: support_ap@u-blox.com

Regional Office China:
Phone: +86 10 68 133 545
E-mail: info_cn@u-blox.com
Support: support_cn@u-blox.com

Regional Office Japan:
Phone: +81 3 5775 3850
E-mail: info_jp@u-blox.com
Support: support_jp@u-blox.com

Regional Office Korea:
Phone: +82 2 542 0861
E-mail: info_kr@u-blox.com
Support: support_kr@u-blox.com

Regional Office Taiwan:
Phone: +886 2 2657 1090
E-mail: info_tw@u-blox.com
Support: support_tw@u-blox.com

Objective Specification