



ANSI/IEEE Std. C95.1-1992 / RSS-102

in accordance with the requirements of
FCC Report and Order: ET Docket 93-62, and OET Bulletin 65 Supplement C

IC Report and Order: SSI/DRB-TP-D01-030



FCC/IC TEST REPORT

For

802.11abgn 1x2 MISO module

For FCC Model NO. : 512AN_MMW

For IC Model NO. : 512AN

Trade Name: Intel

Issued to

For FCC

**General Dynamics Itronix Corporation
509 North Sullivan - C441, Spokane Valley, WA 99037 USA**

For IC

**General Dynamics Itronix Corporation
1000 Sawgrass Corp. Pkwy Suite 300 Sunrise Florida 33323 United States**

Issued by

**Compliance Certification Services Inc.
No.11, Wu-Gong 6th Rd., Wugu Industrial Park,
New Taipei City 248, Taiwan (R.O.C.)**

<http://www.ccsrf.com.tw>

service@ccsrf.com

Issued Date: August 01, 2011



Testing Laboratory
1309

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Revision History

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1. CERTIFICATE OF COMPLIANCE (SAR EVALUATION)

Applicant: **For FCC**
 General Dynamics Itronix Corporation
 509 North Sullivan - C441, Spokane Valley, WA 99037 USA
For IC
 General Dynamics Itronix Corporation
 1000 Sawgrass Corp. Pkwy Suite 300 Sunrise Florida 33323
 United States

Equipment Under Test: 802.11abgn 1x2 MISO module

Trade Name: Intel

Model Number: **For FCC**
 512AN_MMW
For IC
 512AN

Date of Test: July 30 ~ August 01, 2011

Device Category: PORTABLE DEVICES

Exposure Category: GENERAL POPULATION/UNCONTROLLED EXPOSURE

APPLICABLE STANDARDS	
STANDARD	
FCC	FCC OET 65 Supplement C
IC	IC RSS-102
Deviation from Applicable Standard	
None	
TEST RESULT	
No non-compliance noted	
The device was tested by Compliance Certification Services Inc. in accordance with the measurement methods and procedures specified in OET Bulletin 65 Supplement C (Edition 01-01). The test results in this report apply only to the tested sample of the stated device/equipment. Other similar device/equipment will not necessarily produce the same results due to production tolerance and measurement uncertainties.	
The device was tested by Compliance Certification Services Inc. in accordance with the measurement methods and procedures specified in IC RSS-102. The test results in this report apply only to the tested sample of the stated device/equipment. Other similar device/equipment will not necessarily produce the same results due to production tolerance and measurement uncertainties.	

Approved by:

Rex Lai
 Section Manager
 Compliance Certification Services Inc.

Tested by:

Anson Lu
 Test Engineer
 Compliance Certification Services Inc.



2. EUT DESCRIPTION

Product	802.11abgn 1x2 MISO module
Trade Name	Intel
Model Number	For FCC: 512AN_MMW For IC: 512AN
Model Discrepancy	All the above models are identical except the model designation.
Received Date	March 19, 2011
Frequency Range	802.11a: 5180 ~ 5240 MHz / 5260 ~ 5320 MHz / 5500 ~ 5700 MHz / 5745 ~ 5825 MHz 802.11a(HT20): 5180 ~ 5240 MHz / 5260 ~ 5320 MHz / 5500 ~ 5700 MHz / 5745 ~ 5825 MHz 802.11a(HT40): 5190~5230 MHz / 5270 ~ 5310 MHz / 5510~5670 MHz / 5755~5795 MHz 802.11b: 2412 ~ 2462 MHz / 802.11g: 2412 ~ 2462 MHz 802.11n HT20: 2412 ~ 2462 MHz 802.11n HT40: 2422 ~ 2452 MHz
Max. Output Power(Avg)	802.11a: 19.18 dBm 802.11a HT20: 16.85 dBm 802.11a HT40: 17.09 dBm 802.11b: 19.64 dBm 802.11g: 17.08 dBm 802.11n HT20: 17.08 dBm 802.11n HT40: 16.62 dBm
Max. SAR (1g)	802.11b: 0.058 W/kg (Body position) 802.11g: <i>SAR test is not required, please refer to page 28.</i> 802.11n HT20: <i>SAR test is not required, please refer to page 28.</i> 802.11n HT40: <i>SAR test is not required, please refer to page 28.</i> 802.11a: 0.258 W/kg (Body position) 802.11a HT20: 0.201W/kg (Body position) 802.11a HT40: 0.265 W/kg (Body position)
Modulation Technique	802.11b: Direct Sequence Spread Spectrum (DSSS) 802.11g: Orthogonal Frequency Division Multiplexing (OFDM) 802.11a: Orthogonal Frequency Division Multiplexing (OFDM)
Antenna Specification	Antenna Type: WLAN: PIFA antenna

The sample selected for test was production product and was provided by manufacturer.



REQUIREMENTS FOR COMPLIANCE TESTING DEFINED

3.1 REQUIREMENTS FOR COMPLIANCE TESTING DEFINED BY THE FCC

The US Federal Communications Commission has released the report and order "Guidelines for Evaluating the Environmental Effects of RF Radiation", ET Docket No. 93-62 in August 1996 [1]. The order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 mW/g for an uncontrolled environment and 8.0 mW/g for an occupational/controlled environment as recommended by the ANSI/IEEE standard C95.1-1992 [6]. According to the Supplement C of OET Bulletin 65 "Evaluating Compliance with FCC Guide-lines for Human Exposure to Radio frequency Electromagnetic Fields", released on Jun 29, 2001 by the FCC, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

3.2 REQUIREMENTS FOR COMPLIANCE TESTING DEFINED BY THE IC

The US Federal Communications Commission has released the report and order "Guidelines for Evaluating the Environmental Effects of RF Radiation", ET Docket No. 93-62 in August 1996 [1]. The order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 mW/g for an uncontrolled environment and 8.0 mW/g for an occupational/controlled environment as recommended by the ANSI/IEEE standard C95.1-1992 [6]. According to the Supplement C of OET Bulletin 65 "Evaluating Compliance with FCC Guide-lines for Human Exposure to Radio frequency Electromagnetic Fields", released on Jun 29, 2001 by the FCC, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

3. DOSIMETRIC ASSESSMENT SETUP

These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9 m), which positions the probes with a positional repeatability of better than ± 0.02 mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit. The SAR measurements were conducted with the dosimetric probe EX3DV4-SN:3554 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure described in [7] with accuracy of better than $\pm 10\%$. The spherical isotropy was evaluated with the procedure described in [8] and found to be better than ± 0.25 dB. The phantom used was the SAM Twin Phantom as described in FCC supplement C, IEE P1528 and CENELEC EN50361.

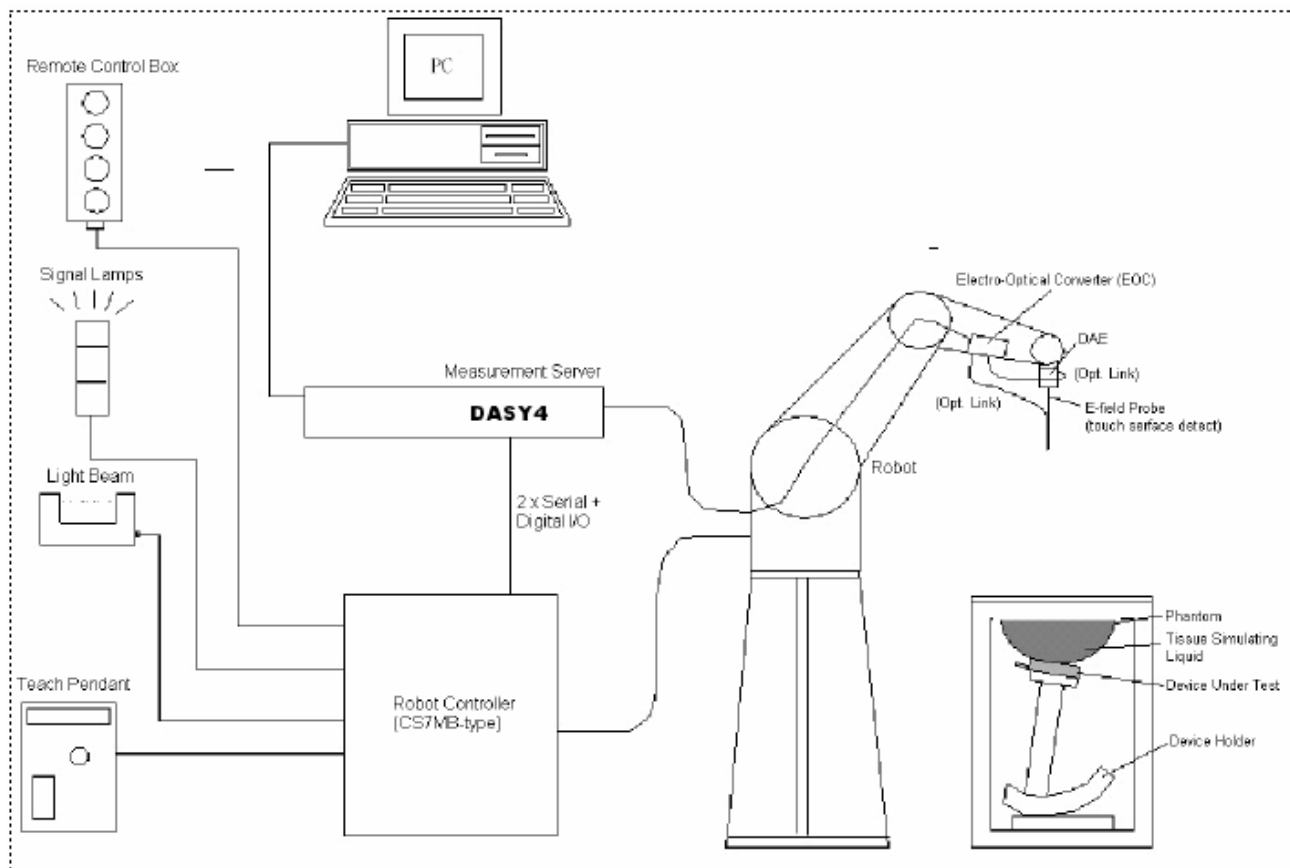
The Tissue simulation liquid used for each test is in according with the FCC OET65 supplement C as listed below.



Ingredients (% by weight)	Frequency (MHz)									
	450		835		915		1900		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	38.56	51.16	41.45	52.4	41.05	56.0	54.9	40.4	62.7	73.2
Salt (NaCl)	3.95	1.49	1.45	1.4	1.35	0.76	0.18	0.5	0.5	0.04
Sugar	56.32	46.78	56.0	45.0	56.5	41.76	0.0	58.0	0.0	0.0
HEC	0.98	0.52	1.0	1.0	1.0	1.21	0.0	1.0	0.0	0.0
Bactericide	0.19	0.05	0.1	0.1	0.1	0.27	0.0	0.1	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	0.0	0.0	0.0	0.0	44.92	0.0	0.0	26.7
Dielectric Constant	43.42	58.0	42.54	56.1	42.0	56.8	39.9	54.0	39.8	52.5
Conductivity (S/m)	0.85	0.83	0.91	0.95	1.0	1.07	1.42	1.45	1.88	1.78



3.1 MEASUREMENT SYSTEM DIAGRAM



The DASYS4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC is connected to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows XP.
- DASYS4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- Validation dipole kits allowing validating the proper functioning of the system.]



3.2 SYSTEM COMPONENTS

DASY4 Measurement Server



The DASY4 measurement server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chip disk and 64MB RAM. The necessary circuits for communication with either the DAE3 electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation.

The PC-operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with two expansion slots which are reserved for future applications. Please note that the expansion slots do not have a standardized pinout and therefore only the expansion cards provided by SPEAG can be inserted. Expansion cards from any other supplier could seriously damage the measurement server. Calibration: No calibration required.

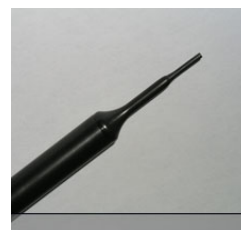
Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 box is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



EX3DV4 Isotropic E-Field Probe for Dosimetric Measurements

- Construction:** Symmetrical design with triangular core
Built-in shielding against static charges
PEEK enclosure material (resistant to organic solvents, e.g., DGBE)
- Calibration:** Basic Broad Band Calibration in air: 10-3000 MHz.
Conversion Factors (CF) for HSL 900 and HSL 1800
CF-Calibration for other liquids and frequencies upon request.
- Frequency:** 10 MHz to > 6 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)
- Directivity:** ± 0.3 dB in HSL (rotation around probe axis)
± 0.5 dB in HSL (rotation normal to probe axis)
- Dynamic Range:** 10 µW/g to > 100 mW/g; Linearity: ± 0.2 dB
(noise: typically < 1 µW/g)
- Dimensions:** Overall length: 330 mm (Tip: 20 mm)
Tip diameter: 2.5 mm (Body: 12 mm)
Distance from probe tip to dipole centers: 1 mm
- Application:** High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precision of better 30%.



Interior of probe



E-Field probe EX3DV4



SAM Phantom (V4.0)

Construction: The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-200X, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

Shell Thickness: 2 ± 0.2 mm

Filling Volume: Approx. 25 liters

Dimensions: Height: 810mm; Length: 1000mm; Width: 500mm



SAM Phantom (ELI4)

Description

Construction: Phantom for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with the latest draft of the standard IEC 62209 Part II and all known tissue simulating liquids. ELI4 has been optimized regarding its performance and can be integrated into our standard phantom tables. A cover prevents evaporation of the liquid. Reference markings on the phantom allow installation of the complete setup, including all predefined phantom positions and measurement grids, by teaching three points. The phantom is supported by software version DASY4.5 and higher and is compatible with all SPEAG dosimetric probes and dipoles



Shell Thickness: 2.0 ± 0.2 mm (sagging: <1%)

Filling Volume: Approx. 25 liters

Dimensions: Major ellipse axis: 600 mm

Minor axis: 400 mm 500mm

Device Holder for SAM Twin Phantom

Construction: In combination with the Twin SAM Phantom V4.0 or Twin SAM, the Mounting Device (made from POM) enables the rotation of the mounted transmitter in spherical coordinates, whereby the rotation point is the ear opening. The devices can be easily and accurately positioned according to IEC, IEEE, CENELEC, FCC or other specifications. The device holder can be locked at different phantom locations (left head, right head, and flat phantom).





System Validation Kits for SAM Phantom (V4.0)

Construction: Symmetrical dipole with 1/4 balun Enables measurement of feedpoint impedance with NWA Matched for use near flat phantoms filled with brain simulating solutions Includes distance holder and tripod adaptor.

Frequency: 450, 900, 1800, 2450, 5800 MHz

Return loss: > 20 dB at specified validation position

Power capability: > 100 W ($f < 1\text{GHz}$); > 40 W ($f > 1\text{GHz}$)

Dimensions: D450V2: dipole length: 270 mm; overall height: 330 mm
D835V2: dipole length: 161 mm; overall height: 340 mm
D900V2: dipole length: 148.5 mm; overall height: 340 mm
D1800V2: dipole length: 72.5 mm; overall height: 300 mm
D1900V2: dipole length: 67.7 mm; overall height: 300 mm
D1900V3: dipole length: 67.0 mm; overall height: 300 mm
D2450V2: dipole length: 51.5 mm; overall height: 290 mm
D5GHzV2: dipole length: 20.6 mm; overall height: 300 mm



System Validation Kits for ELI4 phantom

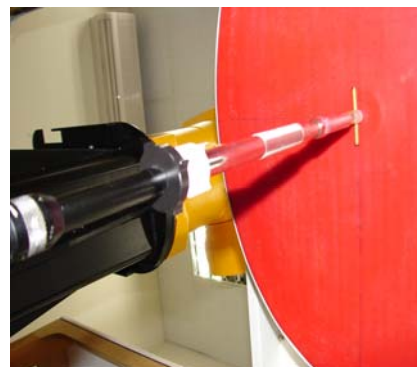
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D1900V2: dipole length: 67.7 mm; overall height: 300 mm
D1900V3: dipole length: 67.0 mm; overall height: 300 mm
D2450V2: dipole length: 51.5 mm; overall height: 290 mm
D5GHzV2: dipole length: 20.6 mm; overall height: 300 mm





4. EVALUATION PROCEDURES

DATA EVALUATION

The DASYS4 post processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	$Norm_i, a_{i0}, a_{i1}, a_{i2}$
	- Conversion factor	$ConvF_i$
	- Diode compression point	dcp_i
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or be imported into the software from the configuration files issued for the DASYS components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with	V_i	= Compensated signal of channel i	(i = x, y, z)
	U_i	= Input signal of channel i	(i = x, y, z)
	cf	= Crest factor of exciting field	(DASY parameter)
	dcp_i	= Diode compression point	(DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$\text{E-field probes: } E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

$$\text{H-field probes: } H_i = \sqrt{V_i} \cdot \frac{a_{i10} + a_{i11}f + a_{i12}f^2}{f}$$

with	V_i	= Compensated signal of channel i	(i = x, y, z)
	$Norm_i$	= Sensor sensitivity of channel i	(i = x, y, z)
		$\mu\text{V}/(\text{V/m})^2$ for E0field Probes	
	$ConvF$	= Sensitivity enhancement in solution	
	a_{ij}	= Sensor sensitivity factors for H-field probes	
	f	= Carrier frequency (GHz)	
	E_i	= Electric field strength of channel i in V/m	
	H_i	= Magnetic field strength of channel i in A/m	

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.



$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

- with SAR = local specific absorption rate in mW/g
 E_{tot} = total field strength in V/m
 σ = conductivity in [mho/m] or [Siemens/m]
 ρ = equivalent tissue density in g/cm³

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770} \quad \text{or} \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

- with P_{pwe} = Equivalent power density of a plane wave in mW/cm²
 E_{tot} = total electric field strength in V/m
 H_{tot} = total magnetic field strength in A/m



SAR EVALUATION PROCEDURES

The procedure for assessing the peak spatial-average SAR value consists of the following steps:

- **Power Reference Measurement**

The reference and drift jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method.

- **Area Scan**

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in DASY4 software can find the maximum locations even in relatively coarse grids. The scan area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom. When the area scan's property sheet is brought-up, grid was at to 15 mm by 15 mm and can be edited by a user.

- **Zoom Scan**

Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default zoom scan measures 7 x 7 x 9 points within a cube whose base faces are centered around the maximum found in a preceding area scan job within the same procedure. If the preceding Area Scan job indicates more than one maximum, the number of Zoom Scans has to be enlarged accordingly (The default number inserted is 1).

- **Power Drift measurement**

The drift job measures the field at the same location as the most recent reference job within the same procedure, and with the same settings. The drift measurement gives the field difference in dB from the reading conducted within the last reference measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. In the properties of the Drift job, the user can specify a limit for the drift and have DASY4 software stop the measurements if this limit is exceeded.



SPATIAL PEAK SAR EVALUATION

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1529 standard. It can be conducted for 1 g and 10 g.

The DASY4 system allows evaluations that combine measured data and robot positions, such as:

- maximum search
- extrapolation
- boundary correction
- peak search for averaged SAR

During a maximum search, global and local maximum searches are automatically performed in 2-D after each Area Scan measurement with at least 6 measurement points. It is based on the evaluation of the local SAR gradient calculated by the Quadratic Shepard's method. The algorithm will find the global maximum and all local maxima within -2 dB of the global maxima for all SAR distributions.

Extrapolation

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. Several measurements at different distances are necessary for the extrapolation.

Extrapolation routines require at least 10 measurement points in 3-D space. They are used in the Cube Scan to obtain SAR values between the lowest measurement points and the inner phantom surface. The routine uses the modified Quadratic Shepard's method for extrapolation. For a grid using 7x7x9 measurement points with 5mm resolution amounting to 441 measurement points, the uncertainty of the extrapolation routines is less than 1% for 1 g and 10 g cubes.

Boundary effect

For measurements in the immediate vicinity of a phantom surface, the field coupling effects between the probe and the boundary influence the probe characteristics. Boundary effect errors of different dosimetric probe types have been analyzed by measurements and using a numerical probe model. As expected, both methods showed an enhanced sensitivity in the immediate vicinity of the boundary. The effect strongly depends on the probe dimensions and disappears with increasing distance from the boundary. The sensitivity can be approximately given as:

$$S \approx S_o + S_b \exp\left(-\frac{z}{a}\right) \cos\left(\pi \frac{z}{\lambda}\right)$$

Since the decay of the boundary effect dominates for small probes ($a \ll \lambda$), the cos-term can be omitted. Factors S_b (parameter Alpha in the DASY4 software) and a (parameter Delta in the DASY4 software) are assessed during probe calibration and used for numerical compensation of the boundary effect. Several simulations and measurements have confirmed that the compensation is valid for different field and boundary configurations.

This simple compensation procedure can largely reduce the probe uncertainty near boundaries. It works well as long as:

- the boundary curvature is small
- the probe axis is angled less than 30° to the boundary normal
- the distance between probe and boundary is larger than 25% of the probe diameter
- the probe is symmetric (all sensors have the same offset from the probe tip)

Since all of these requirements are fulfilled in a DASY4 system, the correction of the probe boundary effect in the vicinity of the phantom surface is performed in a fully automated manner via the measurement data extraction during postprocessing.



5. MEASUREMENT UNCERTAINTY

UNCERTAINTY BUDGE ACCORDING TO IEEE P1528						
Error Description	Uncertainty Value $\pm\%$	Probability distribution	Divisor	C ₁ 1g	Standard unc.(1g/10g) $\pm\%$	V ₁ or V _{eff}
Measurement System						
Probe calibration	± 4.8	normal	1	1	± 4.8	∞
Axial isotropy of probe	± 4.6	rectangular	$\sqrt{3}$	$(1-C_p)^{1/2}$	± 1.9	∞
Sph. Isotropy of probe	± 9.7	rectangular	$\sqrt{3}$	$(C_p)^{1/2}$	± 3.9	∞
Probe linearity	± 4.5	rectangular	$\sqrt{3}$	1	± 2.7	∞
Detection Limit	± 0.9	rectangular	$\sqrt{3}$	1	± 0.6	∞
Boundary effects	± 8.5	rectangular	$\sqrt{3}$	1	± 4.8	∞
Readoutelectronics	± 1.0	normal	1	1	± 1.0	∞
Response time	± 0.9	rectangular	$\sqrt{3}$	1	± 0.5	∞
Integration time	± 1.2	rectangular	$\sqrt{3}$	1	± 0.8	∞
Mech Constrains of robot	± 0.5	rectangular	$\sqrt{3}$	1	± 0.2	∞
Probe positioning	± 2.7	rectangular	$\sqrt{3}$	1	± 1.7	∞
Extrap. And integration	± 4.0	rectangular	$\sqrt{3}$	1	± 2.3	∞
RF ambient conditiona	± 0.54	rectangular	$\sqrt{3}$	1	± 0.43	∞
Test Sample Related						
Device positioning	± 2.2	normal	1	1	± 2.23	11
Device holder uncertainty	± 5	normal	1	1	± 5.0	7
Power drift	± 5	rectangular	$\sqrt{3}$	1	± 2.9	∞
Phantom and Set up						
Phantom uncertainty	± 4	rectangular	$\sqrt{3}$	1	± 2.3	∞
Liquid conductivity	± 5	rectangular	$\sqrt{3}$	0.6	± 1.7	∞
Liquid conductivity	± 5	rectangular	$\sqrt{3}$	0.6	$\pm 3.5/1.7$	∞
Liquid permittivity	± 5	rectangular	$\sqrt{3}$	0.6	± 1.7	∞
Liquid permittivity	± 5	rectangular	$\sqrt{3}$	0.6	± 1.7	∞
Combined Standard Uncertainty					$\pm 12.14/11.76$	
Coverage Factor for 95%		kp=2				
Expanded Standard Uncertainty					$\pm 24.29/23.51$	

Table: Worst-case uncertainty for DASY4 assessed according to IEEE P1528.

The budge is valid for the frequency range 300 MHz to 6G Hz and represents a worst-case analysis.



6. EXPOSURE LIMIT

(A).Limits for Occupational/Controlled Exposure (W/kg)

<u>Whole-Body</u>	<u>Partial-Body</u>	<u>Hands, Wrists, Feet and Ankles</u>
0.4	8.0	2.0

(B).Limits for General Population/Uncontrolled Exposure (W/kg)

<u>Whole-Body</u>	<u>Partial-Body</u>	<u>Hands, Wrists, Feet and Ankles</u>
0.08	1.6	4.0

NOTE: **Whole-Body SAR** is averaged over the entire body, **partial-body SAR** is averaged over any 1 gram of tissue defined as a tissue volume in the shape of a cube. **SAR for hands, wrists, feet and ankles** is averaged over any 10 grams of tissue defined as a tissue volume in the shape of a cube.

Population/Uncontrolled Environments:

are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Occupational/Controlled Environments:

are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

<p style="text-align: center;">NOTE GENERAL POPULATION/UNCONTROLLED EXPOSURE PARTIAL BODY LIMIT 1.6 W/kg</p>
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7. EUT ARRANGEMENT

Please refer to IEEE P1528 illustration below.

7.1 ANTHROPOMORPHIC HEAD PHANTOM

Figure 7-1a shows the front, back and side views of SAM. The point “M” is the reference point for the center of mouth, “LE” is the left ear reference point (ERP), and “RE” is the right ERP. The ERPs are 15 mm posterior to the entrance to ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 7-1b. The plane passing through the two ear reference points and M is defined as the Reference Plane. The line N-F (Neck-Front) perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 7-1c). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines should be marked on the external phantom shell to facilitate handset positioning. Posterior to the N-F line, the thickness of the phantom shell with the shape of an ear is a flat surface 6 mm thick at the ERPs. Anterior to the N-F line, the ear is truncated as illustrated in Figure 7-1b. The ear truncation is introduced to avoid the handset from touching the ear lobe, which can cause unstable handset positioning at the cheek.

Figure 7-1a

Front, back and side view of SAM (model for the phantom shell)

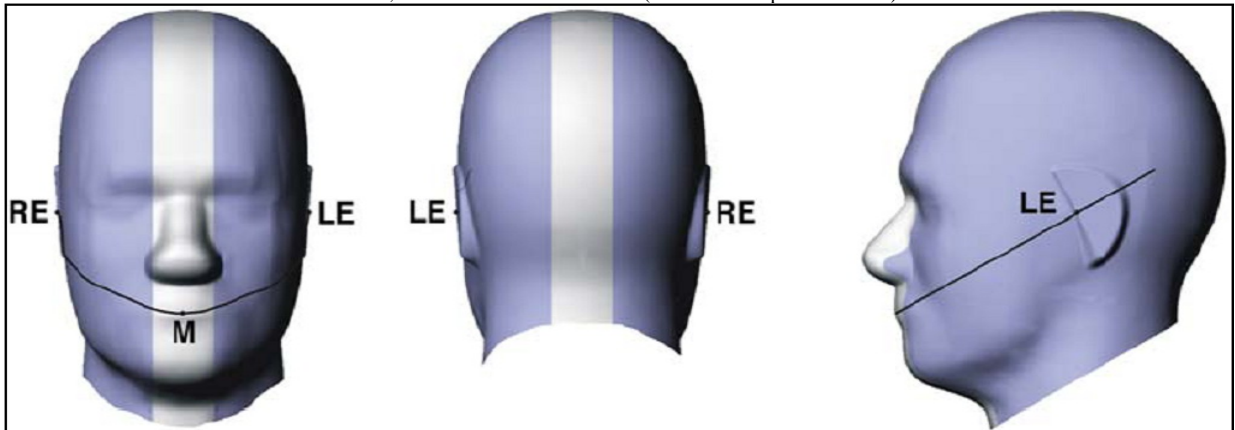


Figure 7-1b

Close up side view of phantom showing the ear region

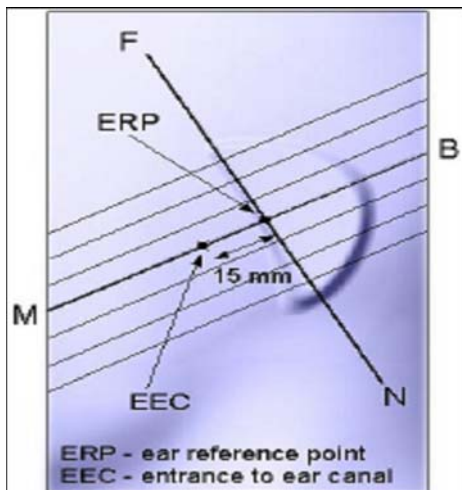


Figure 7-1b

Close up side view of phantom showing the ear region

Figure 7-1c

Side view of the phantom showing relevant markings and the 7 cross sectional plane locations

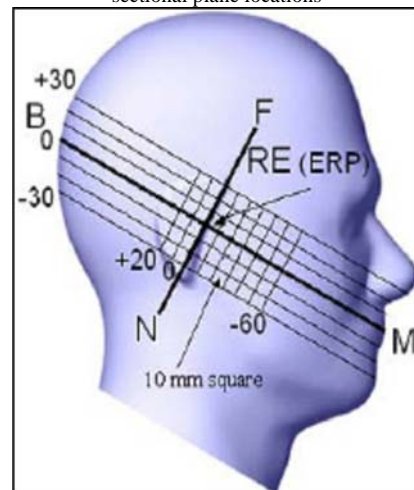


Figure 7-1c

Side view of the phantom showing relevant markings and the 7 cross-sectional plane locations



7.2 DEFINITION OF THE “CHEEK/TOUCH” POSITION

The “cheek” or “touch” position is defined as follows:

- a. Ready the handset for talk operation, if necessary. For example, for handsets with a cover piece, open the cover. (If the handset can also be used with the cover closed both configurations must be tested.)
- b. Define two imaginary lines on the handset: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width w_t of the handset at the level of the acoustic output (point A on Figures 7-2a and 7-2b), and the midpoint of the width w_b of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 7-2a). The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily parallel to the front face of the handset (see Figure 7-2b), especially for clamshell handsets, handsets with flip pieces, and other irregularly-shaped handsets.
- c. Position the handset close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 7-2c), such that the plane defined by the vertical center line and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.
- d. Translate the handset towards the phantom along the line passing through RE and LE until the handset touches the pinna.
- e. e) While maintaining the handset in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to MB-NF including the line MB (called the reference plane).
- f. Rotate the handset around the vertical centerline until the handset (horizontal line) is symmetrical with respect to the line NF.
- g. While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the handset contact with the pinna, rotate the handset about the line NF until any point on the handset is in contact with a phantom point below the pinna (cheek). See Figure 7-2c. The physical angles of rotation should be noted.

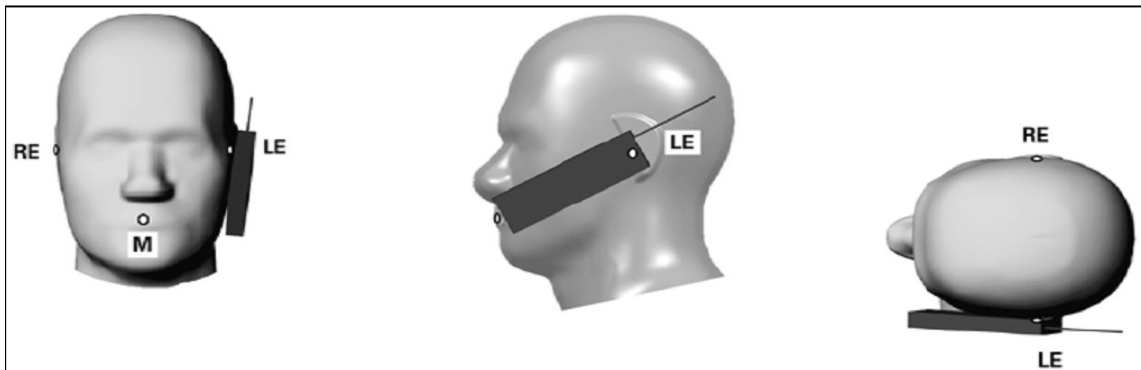


Figure 7.2c

Phone “cheek” or “touch” position. The reference points for the right ear (RE), left ear (LE) and mouth (M), which define the reference plane for handset positioning, are indicated.

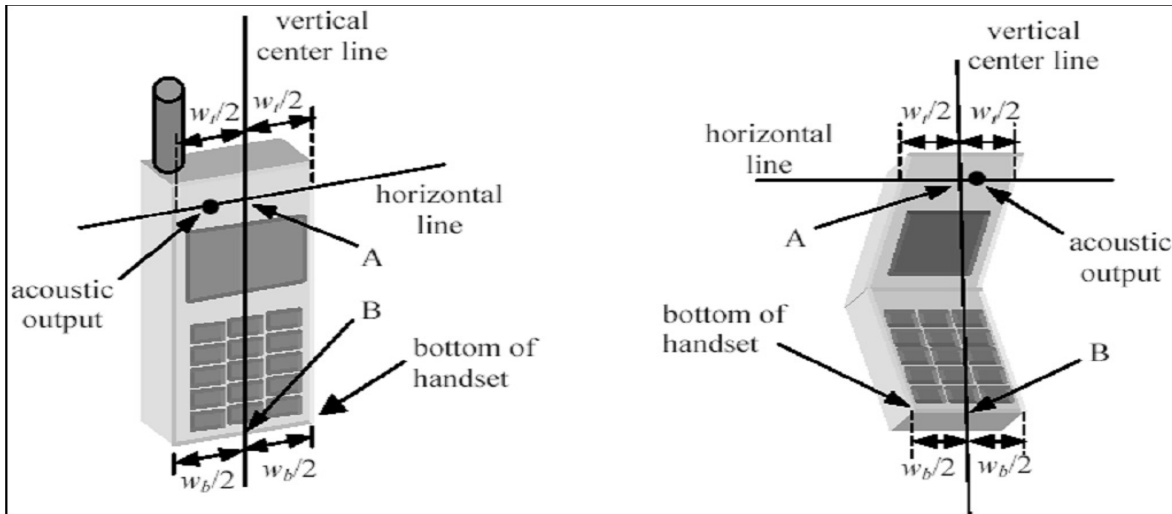


Figure 7.2a

Figure 7.2b

7.3 DEFINITION OF THE “TILTED” POSITION

The “tilted” position is defined as follows:

- a. Repeat steps (a) – (g) of 7.2 to place the device in the “cheek position.”
- b. While maintaining the orientation of the handset move the handset away from the pinna along the line passing through RE and LE in order to enable a rotation of the handset by 15 degrees.
- c. Rotate the handset around the horizontal line by 15 degrees.
- d. While maintaining the orientation of the handset, move the handset towards the phantom on a line passing through RE and LE until any part of the handset touches the ear. The tilted position is obtained when the contact is on the pinna. If the contact is at any location other than the pinna (e.g., the antenna with the back of the phantom head), the angle of the handset should be reduced. In this case, the tilted position is obtained if any part of the handset is in contact with the pinna as well as a second part of the handset is contact with the phantom (e.g., the antenna with the back of the head).

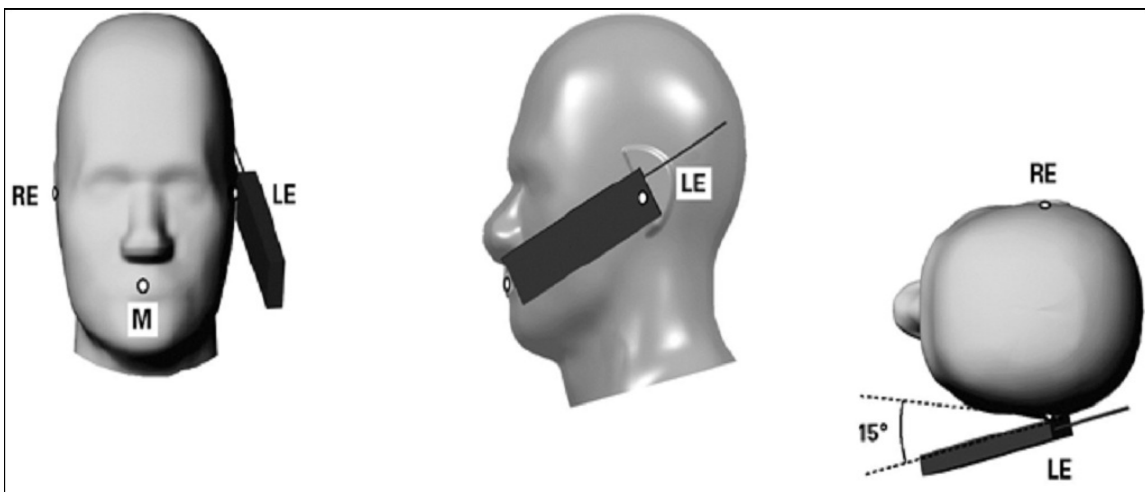


Figure 7-3

Phone “tilted” position. The reference points for the right ear (RE), left ear (LE) and mouth (M), which define the reference plane for handset positioning, are indicated.



8. MEASUREMENT RESULTS

8.1 TEST LIQUIDS CONFIRMATION

SIMULATING LIQUIDS PARAMETER CHECK

The simulating liquids should be checked at the beginning of a series of SAR measurements to determine if the dielectric parameters are within the tolerances of the specified target values

The relative permittivity and conductivity of the tissue material should be within $\pm 5\%$ of the values given in the table below. 5% may not be easily achieved at certain frequencies. Under such circumstances, 10% tolerance may be used until more precise tissue recipes are available

IEEE SCC-34/SC-2 P1528 RECOMMENDED TISSUE DIELECTRIC PARAMETERS

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in P1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations and extrapolated according to the head parameters specified in P1528

Target Frequency (MHz)	Head		Body	
	ϵ_r	σ (S/m)	ϵ_r	σ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	45.3	5.27	48.2	6.00

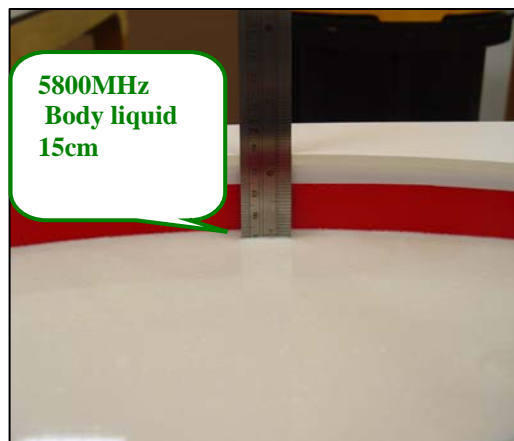
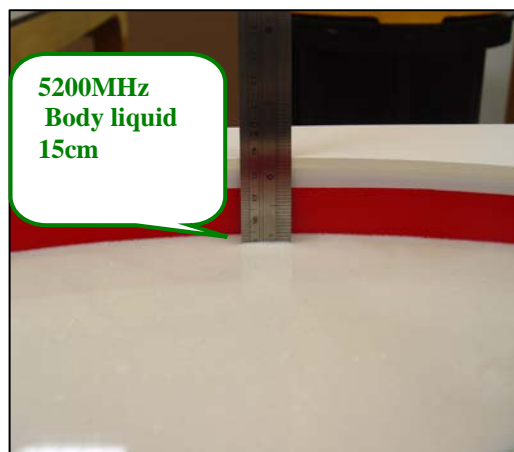
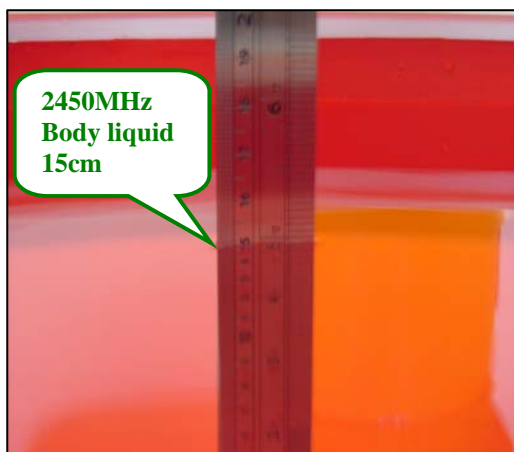
(ϵ_r = relative permittivity, σ = conductivity and $\rho = 1000 \text{ kg/m}^3$)



LIQUID MEASUREMENT RESULTS

Date: August 01, 2011 **Ambient condition:** Temperature 24.6°C; Relative humidity: 52%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f (MHz)	Temp. [°C]	Depth (cm)					
2450.00	23.60	15.00	Permittivity:	52.70	51.70	-1.90	± 5
			Conductivity:	1.95	2.00	2.56	± 5



Date: July 30, 2011 **Ambient condition:** Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f (MHz)	Temp. [°C]	Depth (cm)					
5200.00	23.60	15.00	Permittivity:	49.00	48.20	-1.63	± 5
			Conductivity:	5.30	5.38	1.51	± 5

Date: July 30, 2011 **Ambient condition:** Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f (MHz)	Temp. [°C]	Depth (cm)					
5500.00	23.60	15.00	Permittivity:	48.60	47.60	-2.06	± 5
			Conductivity:	5.65	5.83	3.19	± 5



Date: July 30, 2011 Ambient condition: Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f (MHz)	Temp. [°C]	Depth (cm)					
5800.00	23.60	15.00	Permittivity:	48.20	47.00	-2.49	± 5
			Conductivity:	6.00	6.24	4.00	± 5

Date: July 31, 2011 Ambient condition: Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f (MHz)	Temp. [°C]	Depth (cm)					
5200.00	23.60	15.00	Permittivity:	49.00	47.90	-2.24	± 5
			Conductivity:	5.30	5.33	0.57	± 5

Date: July 31, 2011 Ambient condition: Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f (MHz)	Temp. [°C]	Depth (cm)					
5500.00	23.60	15.00	Permittivity:	48.60	47.60	-2.06	± 5
			Conductivity:	5.65	5.73	1.42	± 5

Date: July 31, 2011 Ambient condition: Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f (MHz)	Temp. [°C]	Depth (cm)					
5800.00	23.60	15.00	Permittivity:	48.20	47.10	-2.28	± 5
			Conductivity:	6.00	6.26	4.33	± 5



8.2 SYSTEM PERFORMANCE CHECK

The system performance check is performed prior to any usage of the system in order to guarantee reproducible results. The system performance check verifies that the system operates within its specifications of $\pm 10\%$. The system performance check results are tabulated below. And also the corresponding SAR plot is attached as well in the SAR plots files.

IEEE P1528 Recommended Reference Value

Frequency (MHz)	1 g SAR	10 g SAR	Local SAR at surface (Above feed point)	Local SAR at surface (y=2cm offset from feed point)
300	3.0	2.0	4.4	2.1
450	4.9	3.3	7.2	3.2
835	9.5	6.2	14.1	4.9
900	10.8	6.9	16.4	5.4
1450	29.0	16.0	50.2	6.5
1800	38.1	19.8	69.5	6.8
1900	38.8	20.4	67.6	6.6
2000	41.1	21.1	74.6	6.5
2450	52.4	24.0	104.2	7.7
3000	63.8	25.7	140.2	9.5

SYSTEM PERFORMANCE CHECK MEASUREMENT CONDITIONS

- The measurements were performed in the flat section of the SAM twin phantom filled with Bodysimulating liquid of the following parameters.
- The DASY4 system with EX3DV4-SN:3554 was used for the measurements.
- The dipole was mounted on the small tripod so that the dipole feed point was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 15 mm (below 1 GHz) and 10 mm (above 1 GHz) from dipole center to the simulating liquid surface.
- The dipole input power (forward power) was 250 mW.
- The 1g and 10 g spatial average SAR values normalized to 1 W dipole input power give reference data for comparisons and it's equal to 4x(dipole forward power).



SYSTEM PERFORMANCE CHECK RESULTS

Dipole: D2450V2 SN: 735

Date: August 01, 2011 **Ambient condition:** Temperature 24.6°C; Relative humidity: 52%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f(MHz)	Temp. [°C]	Depth [cm]					
2450.00	23.60	15.00	Permittivity:	52.70	51.70	-1.90	± 5
			Conductivity:	1.95	2.00	2.56	± 5
			1g SAR:	51.20	52.00	1.56	± 5

ps. 1g SAR is equal 4x13(250mW forward power SAR value)

Dipole: D5GMHz SN:1040

Date: July 30, 2011 **Ambient condition:** Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f(MHz)	Temp. [°C]	Depth [cm]					
5200.00	23.60	15.00	Permittivity:	49.00	48.20	-1.63	± 5
			Conductivity:	5.30	5.38	1.51	± 5
			1g SAR:	76.00	75.80	-0.26	± 5

ps. 1g SAR is equal 10x7.58 (100mW forward power SAR value)

Dipole: D5GMHz SN:1040

Date: July 30, 2011 **Ambient condition:** Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f(MHz)	Temp. [°C]	Depth [cm]					
5500.00	23.60	15.00	Permittivity:	48.60	47.60	-2.06	± 5
			Conductivity:	5.65	5.83	3.19	± 5
			1g SAR:	81.70	80.30	-1.71	± 5

ps. 1g SAR is equal 10x8.03 (100mW forward power SAR value)

Dipole: D5GMHz SN:1040

Date: July 30, 2011 **Ambient condition:** Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f(MHz)	Temp. [°C]	Depth [cm]					
5800.00	23.60	15.00	Permittivity:	48.20	47.00	-2.49	± 5
			Conductivity:	6.00	6.24	4.00	± 5
			1g SAR:	75.40	73.50	-2.52	± 5

ps. 1g SAR is equal 10x7.35 (100mW forward power SAR value)



Dipole: D5GMHz SN:1040

Date: July 31, 2011

Ambient condition: Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f(MHz)	Temp. [°C]	Depth [cm]					
5200.00	23.60	15.00	Permittivity:	49.00	48.20	-1.63	± 5
			Conductivity:	5.30	5.40	1.89	± 5
			1g SAR:	76.00	77.10	1.45	± 5

ps. 1g SAR is equal 10x7.71 (100mW forward power SAR value)

Dipole: D5GMHz SN:1040

Date: July 31, 2011

Ambient condition: Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f(MHz)	Temp. [°C]	Depth [cm]					
5500.00	23.60	15.00	Permittivity:	48.60	47.70	-1.85	± 5
			Conductivity:	5.65	5.73	1.42	± 5
			1g SAR:	81.70	82.30	0.73	± 5

ps. 1g SAR is equal 10x8.23 (100mW forward power SAR value)

Dipole: D5GMHz SN:1040

Date: July 31, 2011

Ambient condition: Temperature 24.6°C; Relative humidity: 53%

Body Simulating Liquid			Parameters	Target	Measured	Deviation[%]	Limited[%]
f(MHz)	Temp. [°C]	Depth [cm]					
5800.00	23.60	15.00	Permittivity:	48.20	47.10	-2.28	± 5
			Conductivity:	6.00	6.26	4.33	± 5
			1g SAR:	75.40	77.10	2.25	± 5

ps. 1g SAR is equal 10x7.72 (100mW forward power SAR value)



8.3 EUT TUNE-UP PROCEDURES

The following procedure had been used to prepare the EUT for the SAR test.

- The client supplied a special driver to program the EUT, allowing it to continually transmit the specified maximum power and change the channel frequency.
- The output power(dBm) we measured before SAR test in different channel
- Performing the highest output power channel first
- There are three module in this EUT WLAN module and WWan module and Bluetooth module, and they can transmit simultaneously.
- This EUT screen can't rotation 180°(Primary Landscape(Top edge), disable via software), can rotation 90°(Primary Portrait(Right edge)) and 270°(Secondary Portrait(Left edge)).
- WLAN Tx antenna to Bottom(user) is 16.8cm, so NB mode configuration SAR test is required; WLAN Tx antenna to Right edge is 10cm, so Primary Portrait(Right edge) configuration SAR test is not required; WLAN Tx antenna to Left edge is 3.5cm, so Secondary Portrait(Left edge) configuration SAR test is required; WLAN Tx antenna to WWAN Tx antenna is 5.1cm.

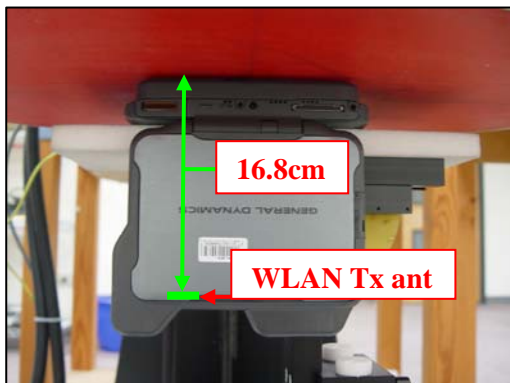
Test mode:

Secondary Portrait(Left edge)



WLAN antenna to phantom is 3.2cm

NB Bottom



WLAN antenna to phantom is 16.8cm



Screen Bottom



WLAN antenna to phantom is 3.5cm

802.11b Conducted Output Power(average):

channel	Frequency (MHz)	RF Power(dBm)
		1Mbps
1	2412	19.64
6	2437	17.26
11	2462	19.63

802.11g Conducted Output Power(average):

channel	Frequency (MHz)	RF Power(dBm)
		6Mbps
1	2412	14.61
6	2437	17.08
11	2462	14.12

802.11n HT20 Conducted Output Power(average):

channel	Frequency (MHz)	RF Power(dBm)
		6.5Mbps
1	2412	13.32
6	2437	17.08
11	2462	14.22

802.11n HT40 Conducted Output Power(average):

channel	Frequency (MHz)	RF Power(dBm)
		13.5Mbps
1	2422	10.17
4	2437	16.62
7	2452	14.32

Ps. KDB 248227 - SAR is not required for 802.11g /HT20/HT40 channels when the maximum average output power is less than 1/4 dB higher than that measured on the corresponding 802.11b channels.



802.11a 1Tx Conducted Output Power(average):

channel	Frequency (MHz)	RF Power(dBm)
		6Mbps
36	5180	16.71
40	5200	16.83
44	5220	16.61
48	5240	16.68
52	5260	16.69
56	5280	16.56
60	5300	16.73
64	5320	16.68
100	5500	19.18
104	5520	16.57
108	5540	16.46
112	5560	16.26
116	5580	16.49
120	5600	16.79
124	5620	16.56
128	5640	16.65
132	5660	16.60
136	5680	16.50
140	5700	16.72
149	5745	16.56
153	5765	16.12
157	5785	16.63
161	5805	16.59
165	5825	16.61



802.11a 1Tx HT20 Conducted Output Power(average):

channel	Frequency (MHz)	RF Power(dBm)
		6.5Mbps
36	5180	16.77
40	5200	16.64
44	5220	16.37
48	5240	16.51
52	5260	16.82
56	5280	16.62
60	5300	16.51
64	5320	16.66
100	5500	16.85
104	5520	16.53
108	5540	16.47
112	5560	16.52
116	5580	16.49
120	5600	16.57
124	5620	16.38
128	5640	16.46
132	5660	16.66
136	5680	16.58
140	5700	16.63
149	5745	16.65
153	5765	15.78
157	5785	16.63
161	5805	15.98
165	5825	16.52



802.11a 1Tx HT40 Conducted Output Power(average):

channel	Frequency (MHz)	RF Power(dBm)
		13.5Mbps
38	5190	15.31
46	5230	16.66
54	5270	16.85
62	5310	15.72
102	5510	16.36
118	5590	16.97
164	5670	17.09
151	5755	16.51
159	5795	16.61

RF Exposure:

- (1) There are three module in this EUT WLAN module and WWan module(FCC ID: N7NMC8355-L) and Bluetooth module(FCC ID: KBCIX-EYXFDC), and they can transmit simultaneously.
- (2) WLAN Tx antenna to Bottom(user) is 16.8cm,
WLAN Tx antenna to Right edge is 10cm,
WLAN Tx antenna to Left edge is 3.5cm,
WLAN Tx antenna to WWAN Tx antenna is 5.1cm,
WLAN Tx antenna to WWAN Rx antenna is 9cm
WWAN Tx antenna to WLAN Rx antenna is 11cm,
WLAN Tx antenna to BT antenna is 9.5cm,
WWAN Tx antenna to BT antenna is 9.9cm,
- (3) WLAN 802.11b maximum sar is 0.058 W/kg,
WLAN 802.11a HT40 mode maximum sar is 0.265 W/kg,
WWAN 850 band maximum sar is 0.384 W/kg,
WWAN 1900 band maximum sar is 0.285 W/kg,
WWAN 1700 band maximum sar is 0.324 W/kg,
- (4) accaording KDB616217 D03 4. a)
(WLAN maximum sar + WLAN maximum sar) / 1.6 is less than sar limit,
so simultaneous sar test is not required.



8.4 SAR MEASUREMENT RESULTS

802.11b Body position:

Test mode: 802.11b, Duty Cycle: 100%, Rate= 1M, Crest Factor: 1					Depth of liquid: 15.0 cm	
EUT Position	Antenna	Frequency		Liquid Temp_°C	SAR (1g) (W/kg)	Limit (W/kg)
		Channel	MHz			
Left Edge	PIFA	1	2412	23.6	0.058	1.6
Screen Bottom	PIFA	1	2412	23.6	0.031	
NB Bottom	PIFA	1	2412	23.6	0.028	

Notes: 1) Please refer to attachment for the result presentation in plot format.

802.11a Body position :

Test mode: 802.11a, Duty Cycle: 100%, Rate= 1M, Crest Factor: 1					Depth of liquid: 15.0 cm	
EUT Position	Antenna	Frequency		Liquid Temp_°C	SAR (1g) (W/kg)	Limit (W/kg)
		Channel	MHz			
Left Edge	PIFA	40	5200	23.6	0.205	1.6
Left Edge	PIFA	48	5240	23.6	0.138	1.6
Left Edge	PIFA	52	5260	23.6	0.144	1.6
Left Edge	PIFA	60	5300	23.6	0.177	1.6
Left Edge	PIFA	100	5500	23.6	0.220	1.6
Left Edge	PIFA	120	5600	23.6	0.138	1.6
Left Edge	PIFA	128	5640	23.6	0.2472	1.6
Left Edge	PIFA	132	5660	23.6	0.134	1.6
Left Edge	PIFA	140	5700	23.6	0.153	1.6
Left Edge	PIFA	157	5785	23.6	0.258	1.6
Screen Bottom	PIFA	100	5500	23.6	0.108	1.6
Screen Bottom	PIFA	157	5785	23.6	0.093	1.6
NB Bottom	PIFA	100	5500	23.6	0.058	1.6
NB Bottom	PIFA	157	5785	23.6	0.165	1.6

Notes: 1) Please refer to attachment for the result presentation in plot format.



802.11a HT20 Body position:

Test mode: 802.11a HT20 , Duty Cycle: 100%, Rate= 1M, Crest Factor: 1 Depth of liquid: 15.0 cm						
EUT Position	Antenna	Frequency		Liquid Temp_°C	SAR (1g) (W/kg)	Limit (W/kg)
		Channel	MHz			
Left Edge	PIFA	36	5180	23.6	0.117	1.6
Left Edge	PIFA	48	5240	23.6	0.086	1.6
Left Edge	PIFA	52	5260	23.6	0.125	1.6
Left Edge	PIFA	64	5320	23.6	0.201	1.6
Left Edge	PIFA	100	5500	23.6	0.114	1.6
Left Edge	PIFA	120	5600	23.6	0.105	1.6
Left Edge	PIFA	128	5640	23.6	0.109	1.6
Left Edge	PIFA	132	5660	23.6	0.074	1.6
Left Edge	PIFA	149	5745	23.6	0.039	1.6
Left Edge	PIFA	149	5745	23.6	0.030	1.6
Screen Bottom	PIFA	64	5320	23.6	0.129	1.6
Screen Bottom	PIFA	100	5500	23.6	0.112	1.6
NB Bottom	PIFA	64	5320	23.6	0.044	1.6
NB Bottom	PIFA	100	5500	23.6	0.117	1.6

Notes: 1) Please refer to attachment for the result presentation in plot format.



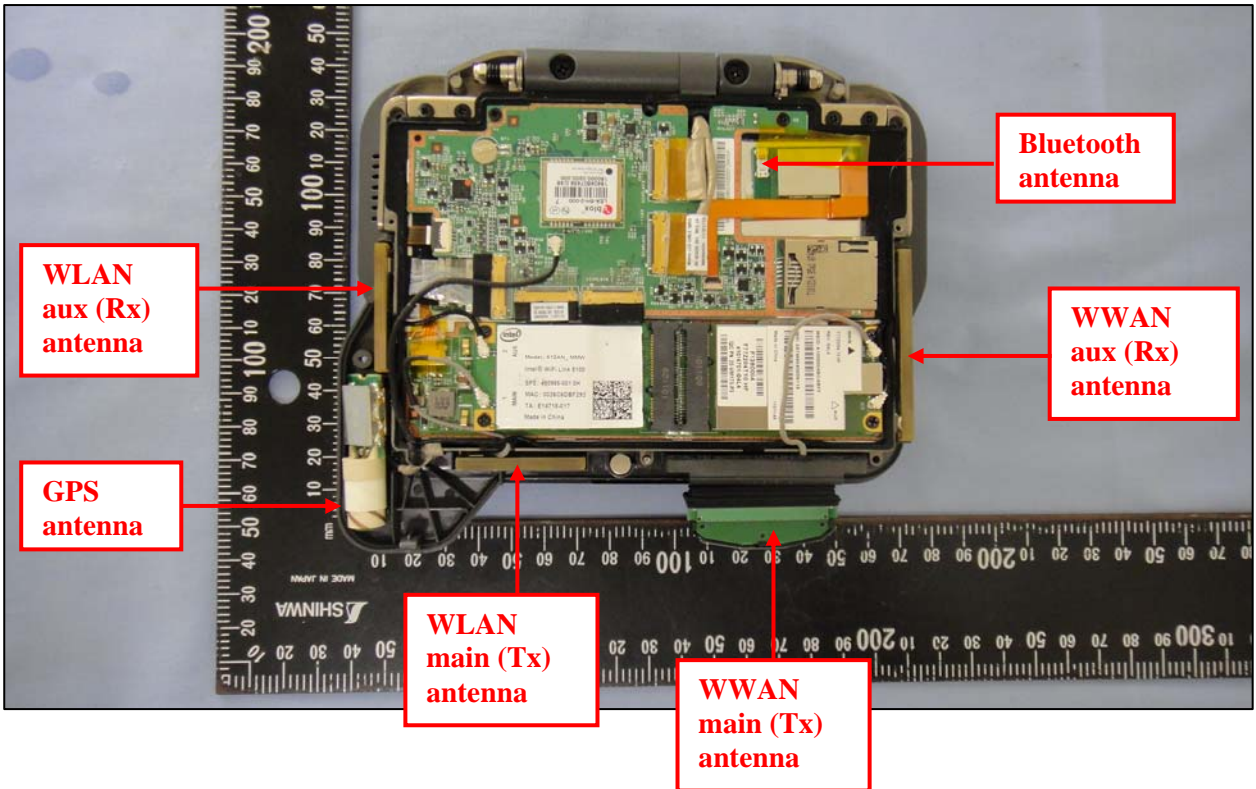
802.11a HT40 Body position:

Test mode: 802.11a HT40 , Duty Cycle: 100%, Rate= 1M, Crest Factor: 1 Depth of liquid: 15.0 cm						
EUT Position	Antenna	Frequency		Liquid Temp_°C	SAR (1g) (W/kg)	Limit (W/kg)
		Channel	MHz			
Left Edge	PIFA	38	5190	23.6	0.148	1.6
Left Edge	PIFA	46	5230	23.6	0.152	1.6
Left Edge	PIFA	54	5270	23.6	0.211	1.6
Left Edge	PIFA	62	5310	23.6	0.216	1.6
Left Edge	PIFA	102	5510	23.6	0.083	1.6
Left Edge	PIFA	118	5590	23.6	0.170	1.6
Left Edge	PIFA	134	5670	23.6	0.174	1.6
Left Edge	PIFA	151	5755	23.6	0.129	1.6
Left Edge	PIFA	159	5795	23.6	0.265	1.6
Screen Bottom	PIFA	134	5670	23.6	0.106	1.6
Screen Bottom	PIFA	159	5795	23.6	0.087	1.6
NB Bottom	PIFA	134	5670	23.6	0.105	1.6
NB Bottom	PIFA	159	5795	23.6	0.126	1.6

Notes: 1) Please refer to attachment for the result presentation in plot format.



9. EUT PHOTOS





10. EQUIPMENT LIST & CALIBRATION STATUS

Name of Equipment	Manufacturer	Type/Model	Serial Number	Calibration Cycle(days)	Calibration Due
S-Parameter Network Analyzer	Agilent	E8358A	US40260243	365	07/14/2012
Electronic Probe kit	Hewlett Packard	85070D	N/A	N/A	N/A
Spectrum Analyzer	Agilent	E4446A	MY43360131	365	11/04/2011
Power Meter	Anritsu	ML2495A	1012009	365	03/27/2012
Power Sensor	Anritsu	MA2411B	0917072	365	03/08/2012
Data Acquisition Electronics (DAE)	SPEAG	DAE4	588	365	07/13/2011
Dosimetric E-Field Probe	SPEAG	EX3DV4	3554	365	09/21/2011
2450 MHz System Validation Dipole	SPEAG	D2450V2	735	730	06/21/2012
D5GHz System Validation Dipole	SPEAG	D5GHzV2	1040	730	06/20/2012
Probe Alignment Unit	SPEAG	LB (V2)	348	N/A	N/A
Robot	Staubli	RX90B L	F02/5T69A1/A/01	N/A	N/A
SAM Twin Phantom V4.0	SPEAG	N/A	N/A	N/A	N/A
Devices Holder	SPEAG	N/A	N/A	N/A	N/A
Head/ Muscle 2450 MHz	CCS	H/M 2450A	N/A	N/A	N/A
Head/ Muscle 5800 MHz	CCS	H/M 5800A	N/A	N/A	N/A



11. FACILITIES

All measurement facilities used to collect the measurement data are located at

- No.81-1, Lane 210, Bade 2nd Rd., Lujhu Township, Taoyuan County 33841, TAIWAN, R.O.C.
- No.11, Wu-Gong 6th Rd., Wugu Industrial Park, New Taipei City 248, Taiwan (R.O.C.)
- No. 199, Chunghsen Road, Hsintien City, Taipei Hsien, Taiwan, R.O.C.

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13. ATTACHMENTS

Exhibit	Content
1	System Performance Check Plots
2	SAR Test Plots
3	Probe_EX3DV4_sn3554_20100922c
4	Dipole_D2450v2_sn735_20110622c
5	Dipole_D5GHz_sn1040_20110621c

END OF REPORT