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Specific Absorption Rate (SAR) Test Report

for

Giant Electronics Ltd.

on the

Portable UHF FRS/GMRS PTT Radio Transceiver Model Number: T8220

> Test Report: EME-040937 Date of Report: Nov. 25, 2004 Date of test: Nov. 24, 2004

Total No of Pages Contained in this Report: 71



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Accredited for testing to FCC Part 15

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Review Date: Nov. 26, 2004

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STATEMENT OF COMPLIANCE

The Giant sample device, model # T8220 was evaluated in accordance with the requirements for compliance testing defined in FCC OET Bulletin 65, Supplement C (Edition 01-01). Testing was performed at the Intertek Testing Services facility in Hsinchu, Taiwan.

The EUT was evaluated in a face-held configuration with the front of the radio placed parallel to the outer surface of the planar. A 2.5cm separation distance was maintained between the front side of the EUT and the outer surface of the planar phantom for the duration of the test.

The EUT was tested in a body-worn configuration with the rear of the radio placed parallel to outer surface of the planar phantom. The attached plastic belt-clip was touching the planar phantom. The EUT was evaluated for body-worn SAR with the microphone accessory.

For the evaluation, the dosimetric assessment system INDEXSAR SARA2 was used. The phantom employed was the box phantom of 2mm thick in one wall. The total uncertainty for the evaluation of the spatial peak SAR values averaged over a cube of 1g tissue mass had been assessed for this system to be $\pm 20.6\%$.

The device was tested at their maximum output power declared by the Giant.

The device was tested in unmodulated continuous transmit operation (Continuous Wave at 100% duty cycle) with the transmit key constantly depressed. For a push-to-talk device, the 50% duty cycle compensation reported assumes a transmit/receive cycle of equal time base.

In summary, the maximum spatial peak SAR value for the sample device averaged over 1g was found to be:

Phantom	Position	SAR_{1g} , mW/g
6mm thick box phantom wall for face-held evaluation EUT front to the phantom, 25 mm separation. 462MHz band _channel 4		0.892 mW/g.
6mm thick box phantom wall for body-worn evaluation	EUT rear to the phantom with the Belt-clip, 0 mm separation. 462MHz band _channel 4	1.191 mW/g.

In conclusion, the tested Sample device was found to be in compliance with the requirements defined in OET Bulletin 65, Supplement C (Edition 01-01) for body configurations.



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1.0 Job Description

1.1 Client Information

The T8220 has been tested at the request of:

Company: Giant Electronics Ltd.

Elite Industrial Building, 135-137 Hoi Bun Road, Kwun Tong,

Kowloon, Hong Kong

1.2 Equipment under test (EUT)

Product Descriptions:

Equipment	Two Way Radio with FRS and GMRS			
Trade Name	Giant	Model No:	T8220	
FCC ID	K7GT8220	S/N No.	Not Labeled	
Category	Portable	RF	Uncontrolled	
	Fortable	Exposure	Environment	
Frequency Band	462.5625 – 462.7125 MHz for FRS	System	F3E	
	467.5625 – 467.7125 MHz for FRS			
	462.5625 – 462.7125 MHz for GMRS			
	462.5500 – 462.7250 MHz for GMRS			

EUT Antenna Description					
Type Integral/helix Configuration Fixed					
Dimensions	73 mm length	Gain	-1.8 dBi		
Location	Embedded				

Use of Product : Walkie-Talkie

Manufacturer: Giant

Production is planned: [X] Yes, [] No

EUT receive date: Oct. 4, 2004

EUT received condition: Good operating condition prototype

Test start date: Nov. 24, 2004

Test end date: Nov. 24, 2004



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1.3 Test plan reference

FCC Rule: Part 2.1093, FCC's OET Bulletin 65, Supplement C (Edition 01-01) and IEEE 1528

1.4 System test configuration

1.4.1 System block diagram & Support equipment

Support Equipment				
Item # Equipment Brand Model No. S/N				
1	N/A	N/A	N/A	N/A





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1.4.2 Test Position

See the photographs as section 2.2

1.4.3 Test Condition

During tests the worst-case data (max RF coupling) was determined with following conditions:

Usage	Operates with a built-in test mode by client	Distance between antenna axis at the joint and the liquid surface:	For head, EUT front to phantom, 25 mm separation. For body, EUT rear with belt-clip to phantom, 0 mm separation	
Simulating human Head/ Body	Head and Body	EUT Battery	Fully-charged with 3 Nickel-Metal batteries	
E.R.P. for 462MHz Band	Channel	Frequency MHz	Before SAR Test (dBm)	After SAR Test (dBm)
	Mid Channel – 4	462.6375	31.2	31.2
E.R.P. for 467MHz Band	Channel	Frequency MHz	Before SAR Test (dBm)	After SAR Test (dBm)
	Mid Channel – 11	467.6375	26.4	26.5

The spatial peak SAR values were assessed for middle operating channels, defined by the manufacturer.

The EUT has built-in test mode that used to evaluate SAR.

The EUT was transmitted continuously during the test (Continuous Wave at 100% duty cycle). For a push-to-talk device, the 50% duty cycle compensation reported assumes a transmit/ receive cycle of equal time base.

The EUT take Nickel-Metal batteries as its power source. Each test was proceeded with fully-charged batteries.



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1.5 Modifications required for compliance

Intertek Testing Services implemented no modifications.

1.6 Additions, deviations and exclusions from standards

The phantom employed was the box phantom of 6 mm thick in vertical wall.



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2.0 SAR Evaluation

2.1 SAR Limits

The following FCC limits for SAR apply to devices operate in General Population/Uncontrolled Exposure environment:

EXPOSURE (General Population/Uncontrolled Exposure environment)	SAR (W/kg)
Average over the whole body	0.08
Spatial Peak (1g)	1.60
Spatial Peak for hands, wrists, feet and ankles (10g)	4.00



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2.2 Configuration Photographs

SAR Measurement Test Setup

Test System

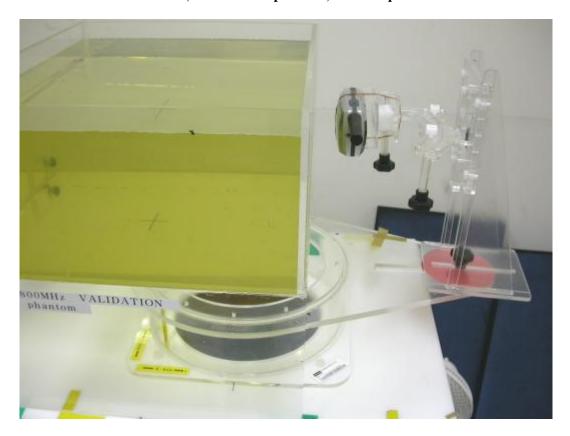




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SAR Measurement Test Setup

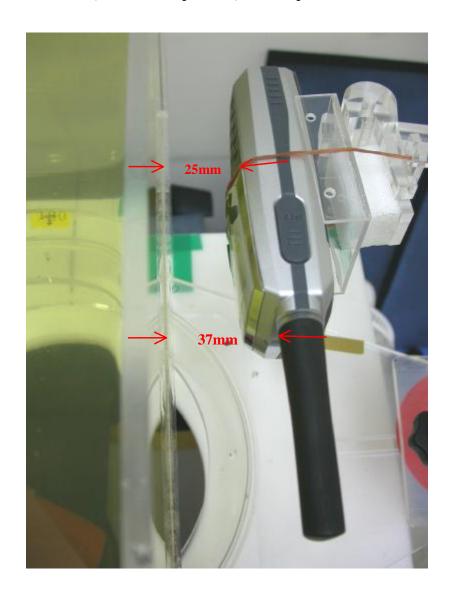
For head, EUT front to phantom, 25 mm separation





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For head, EUT front to phantom, 25 mm separation – Zoom In

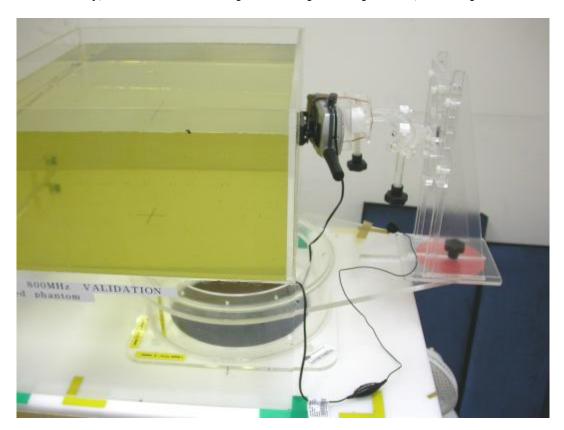




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SAR Measurement Test Setup

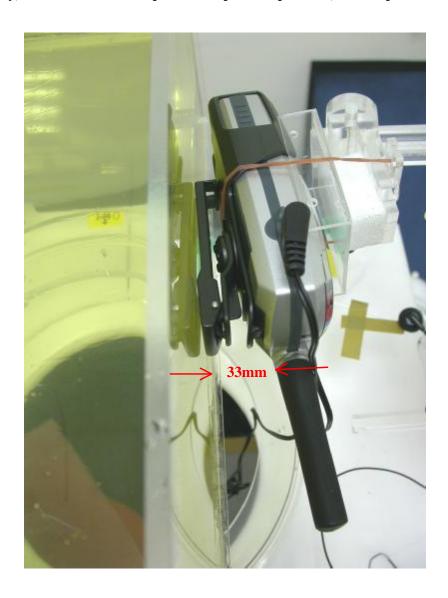
For body, EUT rear with belt-clip and microphone to phantom, 0 mm separation





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For body, EUT rear with belt-clip and microphone to phantom, 0 mm separation-Zoon In





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2.3 SAR measurement system

Robot system specification

The SAR measurement system being used is the IndexSAR SARA2 system, which consists of a Mitsubishi RV-E2 6-axis robot arm and controller, IndexSAR probe and amplifier and SAM phantom Head Shape. The robot is used to articulate the probe to programmed positions inside the phantom head to obtain the SAR readings from the DUT.

The system is controlled remotely from a PC, which contains the software to control the robot and data acquisition equipment. The software also displays the data obtained from test scans.

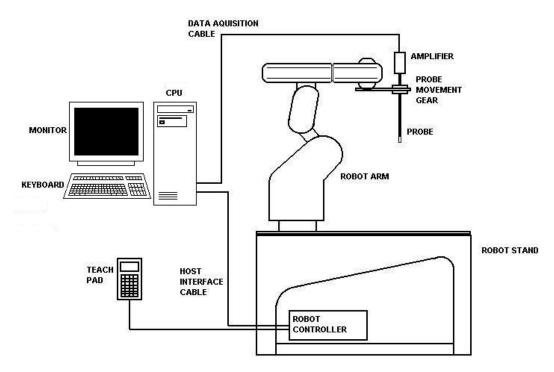


Figure 1: Schematic diagram of the SAR measurement system

The position and digitised shape of the phantom heads are made available to the software for accurate positioning of the probe and reduction of set-up time.

The SAM phantom heads are individually digitised using a Mitutoyo CMM machine to a precision of 0.02mm. The data is then converted into a shape format for the software, providing an accurate description of the phantom shell. In operation, the system first does an area (2D) scan at a fixed depth within the liquid from the inside wall of the phantom. When the maximum SAR point has been found, the system will then carry out a 3D scan centred at that point to determine volume averaged SAR level.

The first 2 measurements points in a direction perpendicular to the surface of the phantom during the zoom scan and closest to the phantom surface, were only 3.5mm and the probe is kept at greater than half a diameter from the surface.



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2.4 SAR measurement system validation

Prior to the assessment, the system was verified to the $\pm 10\%$ of the specifications by using the system validation equipments. The validation was performed at 450 MHz on the bottom side of box phantom.

Procedures

The SAR evaluation was performed with the following procedures:

- a. The SAR distribution was measured at the exposed side of the bottom of the box phantom and was measured at a distance of 8 mm from the inner surface of the shell. The feed power was 1/5 W.
- b. The dimension for this cube is 32 mm x 32 mm x 34 mm was assessed by measuring 5 x 5 x 7 points. On the basis of this data set, the spatial peak SAR value was evaluated with the following procedure:
 - i) The data at the surface were extrapolated, since the center of the dipoles is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measurement point is 5 mm. The extrapolation was based on a least square algorithm. A polynomial of the fourth order was calculated through the points in Z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
 - ii) The maximum interpolated value was searched with a straightforward algorithm. Around this maximum, the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3-D spline interpolation algorithm. The 3-D spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y and z directions). The volume was integrated with the trapezoidal algorithm. 1000 points (10 x 10 x 10) were interpolated to calculate the average.
 - iii) All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

The test scan procedure for system validation also apply to the general scan procedure except for the set-up position. For general scan, the EUT was placed at the side of phantom. For validation scan, the dipole antenna was placed at the bottom of phantom



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2.4.1 System Validation result

System Validation (450 MHz Head)				
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$				Deviation (±10%)
450	CW	4.9	4.875	-0.51%

Please see the plot below:



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2004/10/5 Date / Time:

HeadBox3-450.csv Filename: 450 system validation.txt **Phantom:**

450 system validation **Device Tested:**

450 dipole antenna Antenna:

Shape File: none.csv

bottom of phantom **Position:**

Head Rotation:

450MHz **Test Frequency: Power Level:** 23dBm

0149 **Probe:**

Cal File: SN0149_450_CW_HEAD

> \mathbf{X} \mathbf{Z} Y 365 444 414 Air **DCP** 20 20 20 .344 .344 .344 Lin

2 Amp Gain: Averaging: 1 **Batteries** Replaced:

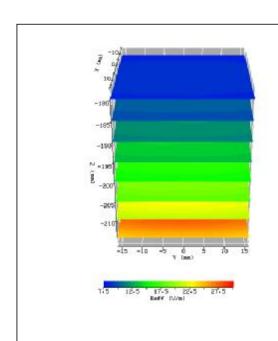
Cal Factors:

Liquid: 15.5cm

450MHz Head Type:

0.885 **Conductivity: Relative Permittivity:** 44.638 22.2 Liquid Temp (deg C): Ambient Temp (deg C): 22 Ambient RH (%): 45 1000 Density (kg/m3): 2.3VPM **Software Version:**

Crest Factor=1



ZOOM SCAN RESULTS:

Spot SAR Start Scan End Scan (W/kg): 0.207 0.205 **Change during** -0.72

Scan (%) Max E-field

(V/m):

Max SAR (W/kg)	1g	10g
wax SAK (W/Kg)	0.975	0.633

29.58

Location of Max \mathbf{X} Y 0.0 (mm): 1.3 -222.5

Normalized to an input power of 1W Averaged over 1 cm³ (1g) of tissue 4.875W/kg



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2.4.2 System Performance Check result

System performance check (450 MHz Head)				
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$				Deviation (±10%)
450	CW	4.9	4.94	0.82%

Please see the plot below:



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Date: 2004/11/23

Filename: 450performance check.txt

Device Tested: 450 performance check

Antenna: 450 MHz dipole

Shape File: none.csv

Position: Bottom of phantom box

Phantom: HeadBox3-450.csv

Head Rotation: 0 **Test Frequency:** 450 MHz

Power Level: 23 dBm

Probe: 0149

Cal File: SN0149_450_CW_HEAD

Lin

 X
 Y
 Z

 Air
 365
 444
 414

 DCP
 20
 20
 20

.344

.344

.344

Amp Gain: 2
Averaging: 1

Batteries
Replaced:

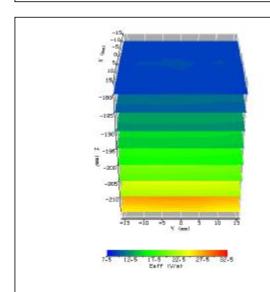
Cal Factors:

Liquid: 15.5cm

Type: 450 MHz head

Conductivity: 0.881
Relative Permittivity: 44.451
Liquid Temp (deg C): 22.5
Ambient Temp (deg C): 23
Ambient RH (%): 51
Density (kg/m3): 1000
Software Version: 2.3VPM

Crest Factor=1



ZOOM SCAN RESULTS:

Spot SAR	Start Scan	End Scan
(W/kg):	0.222	0.226

Change during 3.64

Scan (%)

Max E-field (V/m): 31.01

Max SAR (W/kg) 1g 10g 0.988 0.685

Location of Max X Y Z (mm): -1.2 -1.2 -222.5

Normalized to an input power of 1W Averaged over 1 cm³ (1g) of tissue 4.94W/kg



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2.5 Test Result

The results on the following page(s) were obtained when the device was tested in the condition described in this report. Detailed measurement data and plots, which reveal information about the location of the maximum SAR with respect to the device, are reported in Appendix A.

Measurement Results

Trade Name:	Giant		Model No.:	T8220	
Serial No.:	ial No.: Not Labled Test Engineer: Kevin Ch		Kevin Chen		
		TEST	CONDITIONS		
Ambient Temp	erature	23 °C	Relative Humidit	ty	51 %
Test Signal Sou	ırce	Test Mode (transmitted continuously)	Signal Modulation		F3E
Output Power SAR Test	Before	See page 6	Output Power Af Test	fter SAR	See page 6
Test Duration		23 min. each scan	Number of Batte	ry Change	3

Test Mode: Head evaluation

	EUT Position												
Charran	Channel Counting Court		D:-4	Measured (mW		DI - 4							
Channel (MHz)	Operating Mode	Crest Factor	Description	Distance (mm)	Duty (Plot Number							
					100%	50%							
462.6375	F3E	1	Front to phantom	25	1.784	0.892	1						
467.6375	F3E	1	Front to phantom	25	0.744	0.372	2						

Test Mode: Body evaluation with belt-clip and microphone

	EUT Position											
Charmal					Measured (mW	Plot						
Channel (MHz)	Operating Mode	Crest Factor	Description	Distance (mm)	Duty (Cycle	Number					
					100%	50%						
462.6375	F3E	1	Rear to phantom	0	2.382	1.191	3					
467.6375	F3E	1	Rear to phantom	0	1.086	0.543	4					



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3.0 Test Equipment

3.1 Equipment List

The Specific Absorption Rate (SAR) tests were performed with the INDEXSAR SARA2 SYSTEM.

The following major equipment/components were used for the SAR evaluations:

	SAR Measurement System			
EQUIPMENT	SPECIFICATIONS	S/N #	LAST CAL. DATE	
Balanced Validation dipole	450MHz	0065	10/2003	
Controller	Mitsubishi CR-E116	F1008007	N/A	
Robot	Mitsubishi RV-E2	EA009002	N/A	
	Repeatability: ± 0.04mm; Number of Axes: 6			
E-Field Probe	IXP-050	0149	05/13/2004	
	Frequency Range: Probe outer diameter: 5.2 mm; probe tip and the dipole center: 2.7 mm	Length: 350 mm;	Distance between the	
Data Acquisition	SARA2	N/A	N/A	
	Processor: Pentium 4; Clock speed: 1.5GHz; OS: Will Software: SARA2 ver. 2.3VPM	ndows XP; I/O: two	RS232;	
Phantom	6mm wall thickness box phantom	N/A	N/A	
	Shell Material: clear Perspex; Thickness: 6 ± 0.1 mm mm ³ ; Dielectric constant: less than 2.85 above 500M		33 x 170 (W x L x D)	
Device holder	Material: clear Perspex	N/A	N/A	
	Dielectric constant: less than 2.85 above 500MHz			
Simulated Tissue	Mixture	N/A	11/23/2004	
	Please see section 3.2 for details			
RF Power Meter	Boonton 4231A with 51011-EMC power sensor	79401-32482	03/21/2004	
	Frequency Range: 0.03 to 8 GHz, <24dBm			
Vector Network Analyzer	HP 8753B HP 85046A	2807J04037 2729A01958	07/04/2004	
	300k to 3GHz			
Signal Generator	R&S SMR27	100036	09/19/2004	
	10M to 27GHz, <120dBuV			
Crystal Detector	Agilent 8472B	MY42240243	N/A	
	10MHz to 18GHz			
Two Channel Digital Storage Oscilloscope	Tektronix TDS1012	C031679	08/16/2004	

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3.2 Tissue Simulating Liquid

The head and body tissue parameters should be used to test operating frequency band of transmitters. When a transmission band overlaps with one of the target frequencies, the tissue dielectric parameters of the tissue medium at the middle of a device transmission band should be within $\pm 5\%$ of the parameters specified at that target frequency.

3.2.1 Body Tissue Simulating Liquid for evaluation test

Body Ingredients Frequency (450 MHz)							
Water	51.16%						
Salt	1.49%						
Sugar	46.78%						
HEC (Hydroxyethyl Cellulose)	0.52%						
Bactericide	0.05%						

The dielectric parameters were verified prior to assessment using the HP 85046A dielectric probe kit and the HP 8753B network Analyzer. The dielectric parameters were:

Frequency (MHz)	Temp. (°C)	e r / Relati	ive Perm	ittivity	s / Condu	r *(kg/m ³)		
450	22.5	measured	target	△(±5%)	measured	target	△(±5%)	1000
430	22.3	57.497	56.7	1.41%	0.951	0.94	1.17%	1000

^{*} Worst-case assumption

3.2.2 Head Tissue Simulating Liquid for System performance Check and evaluation test

Head Ingredients Frequency (450 MHz)							
Water	38.56%						
Salt	3.95%						
Sugar	56.32%						
HEC (Hydroxyethyl Cellulose)	0.98%						
Bactericide	0.19%						

The dielectric parameters were verified prior to assessment using the HP 85046A dielectric probe kit and the HP 8753B network Analyzer. The dielectric parameters were:

Frequency (MHz)	Temp. (°C)	e r/ Relati	ive Pern	nittivity	s / Condu	$r *(kg/m^3)$		
450	22.5	measured	target	△(±5%)	measured	target	△(±5%)	1000
430	22.3	44.451	43.5	2.19%	0.881	0.87	1.26%	1000

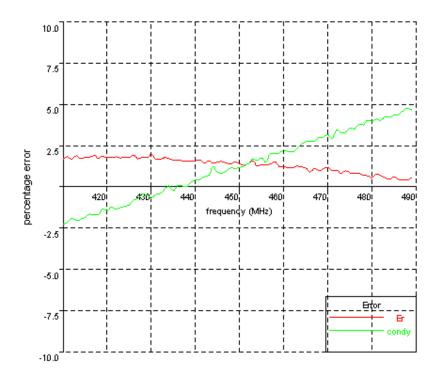
^{*} Worst-case assumption



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3.2.3 Body Liquid results

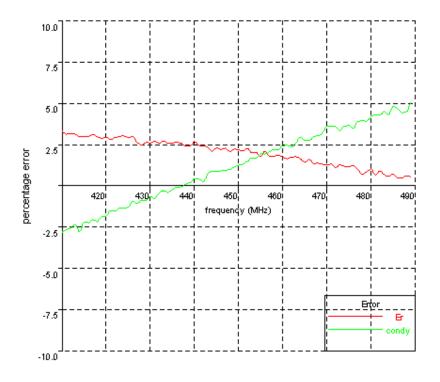
Date: 23 Nov. 2004	Temperature: 22.5 °C	Type: 450 MHz/ Body (FCC)	Tested by: Kevin
410, 58.0740491303, -0.913391 411, 58.1310161531, -0.914753 412, 58.0411826885, -0.917080 413, 58.1501410819, -0.915955 414, 58.046003524, -0.9168226 415, 58.0624567097, -0.918201 416, 58.0673946645, -0.919963 417, 58.1151747523, -0.919863 418, 58.0110998135, -0.919937 419, 58.0637720836, -0.923383 420, 58.0052047074, -0.922121 421, 58.0045704205, -0.924602 422, 58.018896996, -0.9236792 423, 57.9661502057, -0.924427 424, 57.9945582575, -0.925578 425, 57.9661397651, -0.926167 426, 58.0258204936, -0.923453 427, 57.8996217337, -0.930230 428, 57.9423342446, -0.933059 429, 57.92379334244, -0.932517 430, 58.0275962983, -0.930749 431, 57.85736405, -0.933649 432, 57.8252442236, -0.933849 433, 57.7038738405, -0.938484 435, 57.7610978879, -0.935989 436, 57.7632032799, -0.938794 437, 57.7348981561, -0.938782 438, 57.715155223, -0.938523 449, 57.503873451511, -0.944771 443, 57.6608494991, -0.9445281 444, 57.5753814232, -0.994768 446, 57.6171259174, -0.94768 446, 57.6171259174, -0.947618 447, 57.5484313914, -0.948644 448, 57.5132419527, -0.950531 449, 57.562664145, -0.9504725	2772 3002 3619 8288 976 7198 2327 523 36 0536 5585 7058 325 1359 9032 9151 576 7351 1004 7262 0626 9932 7964 2062 7964 2062 7964 2062 7964 2062 8899 8835 7959 6876 88425 6084 44283 2250 28889 0833 7041 6412 33229 6262	450, 57.4969858422, -0.9508580847 451, 57.4350124171, -0.9519439378 452, 57.4934480681, -0.9534440303 453, 57.5822565478, -0.9560914139 454, 57.4026148765, -0.9556459472 455, 57.4454119097, -0.956880173 456, 57.4363386613, -0.9546329842 457, 57.450524889, -0.9596527243 458, 57.3371699131, -0.9593836879 459, 57.3555782896, -0.9599081578 460, 57.3506999437, -0.9617617417 461, 57.3205076222, -0.9606937988 462, 57.3042544377, -0.9610885848 463, 57.353756271, -0.9628606598 464, 57.3302688769, -0.9654460933 464, 57.3302688769, -0.9654483609 465, 57.2451418139, -0.9674460933 467, 57.2607880255, -0.9675818599 468, 57.1814016236, -0.969637697 469, 57.245141513, -0.967654402 470, 57.2842031029, -0.9713675745 471, 57.1718888467, -0.9741998912 474, 57.1604344652, -0.9728240312 474, 57.1604344652, -0.9728240312 474, 57.1604344652, -0.9728432149 475, 57.0784126939, -0.977533726 476, 57.067081045, -0.9777549104 478, 56.980351239, -0.997849041 479, 56.980351239, -0.997849041 479, 56.980351239, -0.9803176341 480, 56.8921269265, -0.99777944107 481, 57.0177821188, -0.9811344017 482, 56.9659454733, -0.98803847464 483, 56.8800560747, -0.982697207 484, 56.8372023073, -0.9823238095 485, 56.81939325304, -0.9884026014 488, 56.88798258, -0.9877372034 489, 56.8377989585, -0.9877372034 489, 56.8377989585, -0.9877372034	Tested by. Kevili





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3.2.4 Head Liquid results





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3.3 E-Field Probe and 450 Balanced Dipole Antenna Calibration

Probe calibration factors and dipole antenna calibration are included in Appendix C.



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4.0 Measurement Uncertainty

The uncertainty budget has been determined for the INDEXSAR SARA2 measurement system according to IEEE P1528 documents [3] and is given in the following table. The extended uncertainty (95% confidence level) was assessed to be 20.6 % for SAR measurement, and the extended uncertainty (95% confidence level) was assessed to be 20.2 % for system performance check.

Table 1 Exposure Assessment Uncertainty

Example of measurement uncertainty assessment SAR measurement

(blue entries are site-specific)

(blue entries are site-specific)				_		T	1	1	1	1	
а	b			С	d	е		f	g	h	ı
Uncertainty Component	Sec.	T (dB)	ol. (+/-		Prob. Dist.	Divisor (descrip)	Divisor (value)	c1 (1g)	c1 (10g)	Standard Uncertainty (%) 1g	Standard Uncertainty (%) 10g
Measurement System		(GD)		(70)							
Probe Calibration	E2.1			2.5	N	1 or k	1	1	1	2.50	2.50
Axial Isotropy	E2.2	0.25	5.93	5.93	R	√3	1.73	0	0	0.00	0.00
Hemispherical Isotropy	E2.2	0.45	10.92	10.92	R	√3	1.73	1	1	6.30	6.30
Boundary effect	E2.3		4	4.00	R	√3	1.73	1	1	2.31	2.31
Linearity	E2.4	0.04	0.93	0.93	R	√3	1.73	1	1	0.53	0.53
System Detection Limits	E2.5		1	1.00	R	√3	1.73	1	1	0.58	0.58
Readout Electronics	E2.6		1	1.00	N	1 or k	1.00	1	1	1.00	1.00
Response time	E2.7		0	0.00	R	√3	1.73	1	1	0.00	0.00
Integration time	E2.8		1.4	1.40	R	√3	1.73	1	1	0.81	0.81
RF Ambient Conditions	E6.1		3	3.00	R	√3	1.73	1	1	1.73	1.73
Probe Positioner Mechanical Tolerance	E6.2		0.6	0.60	R	√3	1.73	1	1	0.35	0.35
Probe Position wrt. Phantom Shell	E6.3		3	3.00	R	√3	1.73	1	1	1.73	1.73
SAR Evaluation Algorithms	E5		8	8.00	R	√3	1.73	1	1	4.62	4.62
Test Sample Related											
Test Sample Positioning	E4.2		2	2.00	N	1	1.00	1	1	2.00	2.00
Device Holder Uncertainty	E4.1		2	2.00	N	1	1.00	1	1	2.00	2.00
Output Power Variation	6.6.2		5	5.00	R	√3	1.73	1	1	2.89	2.89
Phantom and Tissue Parameters											
Phantom Uncertainty (shape and thickness)	E3.1		4	4.00	R	√3	1.73	1	1	2.31	2.31
Liquid conductivity (Deviation from target)	E3.2		5	5.00	R	√3	1.73	0.64	0.43	1.85	1.24
Liquid conductivity (measurement uncert.)	E3.3		1.1	1.10	N	1	1.00	0.64	0.43	0.70	0.47
Liquid permittivity (Deviation from target)	E3.2		5	5.00	R	√3	1.73	0.6	0.49	1.73	1.41
Liquid permittivity (measurement uncert.)	E3.3		1.1	1.10	N	1	1.00	0.6	0.49	0.66	0.54
Combined standard uncertainty					RSS					10.5	10.3
Expanded uncertainty	(95% Confidence Level)				k=2					20.6	20.3



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Table 2 System Check (Verification)

Example of measurement uncertainty assessment for system performance check

(blue entries are site-specific)

(blue entries are site-specific)	1									1	
а	b			С	d	е		f	g	h	1
Uncertainty Component	Sec.		Tol. (+/	′-)	Prob. Dist.	Divisor (descrip)	Divisor (value)		c1 (10g)	Standard Uncertainty (%) 1g	Standard Uncertainty (%) 10g
		(dB)		(%)							
Measurement System											
Probe Calibration	E2.1			2.5	N	1 or k	1	1	1	2.50	2.50
Axial Isotropy	E2.2	0.25	5.93	5.93	R	√3	1.73	0	0	0.00	0.00
Hemispherical Isotropy	E2.2	0.45	10.92	10.92	R	√3	1.73	1	1	6.30	6.30
Boundary effect	E2.3		4	4.00	R	√3	1.73	1	1	2.31	2.31
Linearity	E2.4	0.04	0.93	0.93	R	√3	1.73	1	1	0.53	0.53
System Detection Limits	E2.5		1	1.00	R	√3	1.73	1	1	0.58	0.58
Readout Electronics	E2.6		1	1.00	N	1 or k	1.00	1	1	1.00	1.00
Response time	E2.7		0	0.00	R	√3	1.73	1	1	0.00	0.00
Integration time	E2.8		1.4	1.40	R	√3	1.73	1	1	0.81	0.81
RF Ambient Conditions	E6.1		3	3.00	R	√3	1.73	1	1	1.73	1.73
Probe Positioner Mechanical Tolerance	E6.2		0.6	0.60	R	√3	1.73	1	1	0.35	0.35
Probe Position wrt. Phantom Shell	E6.3		3	3.00	R	√3	1.73	1	1	1.73	1.73
SAR Evaluation Algorithms	E5		8	8.00	R	√3	1.73	1	1	4.62	4.62
Dipole											
Dipole axis to liquid distance	8, E4.2		2	2.00	N	1	1.00	1	1	2.00	2.00
Input power and SAR drift measurement	8, 6.6.2		5	5.00	R	√3	1.73	1	1	2.89	2.89
Phantom and Tissue Parameters											
Phantom Uncertainty (thickness)	E3.1		4	4.00	R	√3	1.73	1	1	2.31	2.31
Liquid conductivity (Deviation from target)	E3.2		5	5.00	R	√3	1.73	0.64	0.43	1.85	1.24
Liquid conductivity (measurement uncert.)	E3.3		1.1	1.10	N	1	1.00	0.64	0.43	0.70	0.47
Liquid permittivity (Deviation from target)	E3.2		5	5.00	R	√3	1.73	0.6	0.49	1.73	1.41
Liquid permittivity (measurement uncert.)	E3.3		1.1	1.10	Ν	1	1.00	0.6	0.49	0.66	0.54
Combined standard uncertainty					RSS					10.3	10.1
Expanded uncertainty	(95% Confidence Level)				k=2					20.2	19.9



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5.0 Measurement Traceability

All measurements described in this report are traceable to Chinese National Laboratory Accreditation (CNLA) standards or appropriate national standards.

6.0 Warning Label Information - USA

See user manual.



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7.0 References

[1] ANSI, ANSI/IEEE C95.1-1999: IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3kHz to 300 GHz, The Institute of electrical and Electronics Engineers, Inc., New York, NY 10017, 1999

- [2] Federal Communications Commission, "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields", Supplement C to OET Bulletin 65, Washington, D.C. 20554, 1997
- [3] IEEE Standards Coordinating Committee 34, "IEEE Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", IEEE Std 1528TM-2003



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8.0 Document History

Revision/ Job Number	Writer Initials	Date	Change
N/A	S.L.	Nov. 25, 2004	Original document



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APPENDIX A - SAR Evaluation Data

Power drift is the measurement of power drift of the device over one complete SAR scan.

To assess the drift of the power of the device under test, a SAR measurement was made in the middle of the zoom scan volume at the start of the scan and a measurement at this point was then also made after the measurement scan. The difference between the two measurements should be less than 5%.



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Plot #1(1/2)

Date: 2004/11/24

Filename: CH4(Head)041015.txt

Device Tested: T8220

Antenna: Integral (Helix) Antenna

Shape File: T8220Front.csv **Position:** Front to phantom 25mm

Phantom: HeadBox2-test.csv

Head Rotation:

Test Frequency: CH4_462.6375 MHz

Power Level: 31.2 dBm

Probe: 0149

Cal File: SN0149_450_CW_HEAD

> \mathbf{X} \mathbf{Y} \mathbf{Z} 365 444 414 Air **DCP** 20 20 20 .344 Lin .344 .344

Amp Gain: 2

Cal Factors:

Averaging: 1

Batteries 3 Replaced:

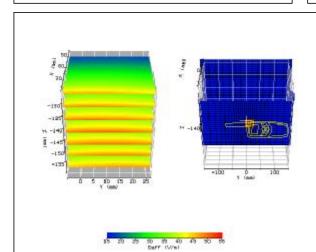
Liquid: 15.5cm

Type: 450 MHz head

Conductivity: 0.881 **Relative Permittivity:** 44.451 **Liquid Temp (deg C):** 22.6 Ambient Temp (deg C): 23 Ambient RH (%): 55 Density (kg/m3): 1000

Software Version: 2.3VPM

Crest Factor=1



ZOOM SCAN RESULTS:

Spot SAR **Start Scan End Scan** (W/kg): 0.844 0.835

Change during -3.23 **Scan** (%)

Max E-field 47.22 (V/m):

Mary CAD (W/lea)	1g	10g
Max SAR (W/kg)	1.784	1.385

Location of Max (m

Cation of Max	Λ	
nm):	78.0	

X	Y	Z
78.0	-4.9	-145.1



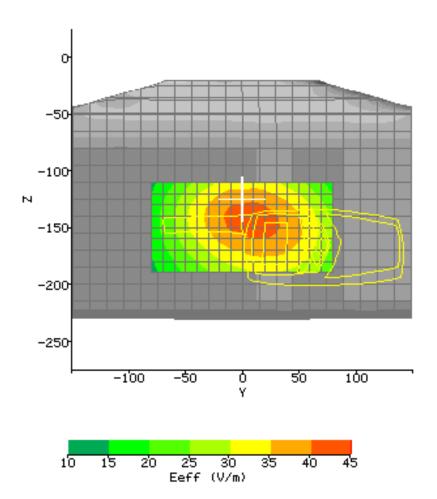
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Plot #1(2/2)

AREA SCAN:

Scan Extent:

	Min	Max	Steps
Y	-80.0	80.0	16.0
Z	-190.0	-110.0	8.0





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Plot #2(1/2)

Date: 2004/11/24

Filename: CH11(Head)041015.txt

Device Tested: T8220

Antenna: Integral (Helix) Antenna

Shape File: T8220Front.csv

Position: Front to phantom 25mm

Phantom: HeadBox2-test.csv

Head Rotation: 0

Test Frequency: 467.6375 MHz

Power Level: 26.4 dBm

Probe: 0149

Cal File: SN0149_450_CW_HEAD

 X
 Y
 Z

 Air
 365
 444
 414

 DCP
 20
 20
 20

 Lin
 .344
 .344
 .344

Amp Gain: 2

Cal Factors:

Averaging: 1

Batteries 3

Replaced:

Liquid: 15.5cm

Type: 450 MHz head

Conductivity: 0.881
Relative Permittivity: 44.451
Liquid Temp (deg C): 22.6

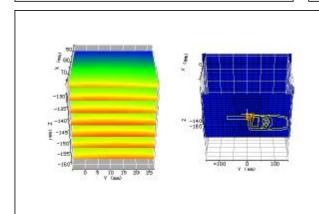
 Ambient Temp (deg C):
 23

 Ambient RH (%):
 55

 Density (kg/m3):
 1000

Software Version: 2.3VPM

Crest Factor=1



17.5 ' 22.5 ' 27.5 ' 22.5 ' 27.5 Earr (V/e)

ZOOM SCAN RESULTS:

 Spot SAR
 Start Scan
 End Scan

 (W/kg):
 0.399
 0.378

34.50

Change during Scan (%)

Max E-field

(V/m):

Max SAR (W/kg)

1g	10g
0.744	0652

Location of Max

(mm):

X	Y	Z
78.0	-4.8	-146.9



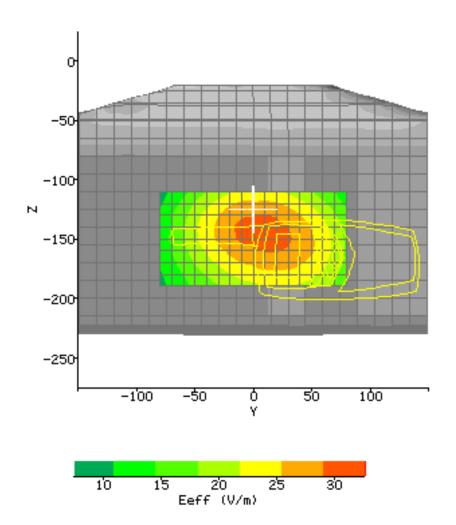
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Plot #2(2/2)

AREA SCAN:

Scan Extent:

	Min	Max	Steps
Y	-80.0	80.0	16.0
Z	-190.0	-110.0	8.0





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Plot #3(1/2)

Date: 2004/11/24

Filename: T8220-CH4_rear.txt

Device Tested: T8220

Antenna: Integral (Helix) Antenna

Shape File: T8220Rear.csv

Position: Rear to phantom with Belt Clip

Phantom: HeadBox2-test.csv

Head Rotation: 0

Test Frequency: CH4_462.6375 MHz

Power Level: 31.2 dBm

Probe: 0149

Cal File: SN0149_450_CW_BODY

 X
 Y
 Z

 Air
 365
 444
 414

 DCP
 20
 20
 20

 Lin
 .360
 .360
 .360

Amp Gain: 2

Cal Factors:

Averaging: 1

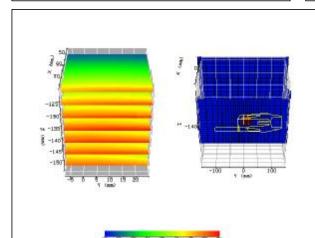
Batteries Replaced: 3

Liquid: 15.5cm

Type: 450 MHz body

Conductivity: 0.951
Relative Permittivity: 57.497
Liquid Temp (deg C): 22.2
Ambient Temp (deg C): 23
Ambient RH (%): 55
Density (kg/m3): 1000
Software Version: 2.3VPM

Crest Factor=1



ZOOM SCAN RESULTS:

 Spot SAR (W/kg):
 Start Scan
 End Scan

 1.201
 1.193

-3.51

Change during Scan (%)

Max E-field (V/m): 53.87

Max SAR (W/kg)

1g	10g
2.382	1.721

Location of Max (mm):

X	Y	Z
78.0	-6.8	-138.5



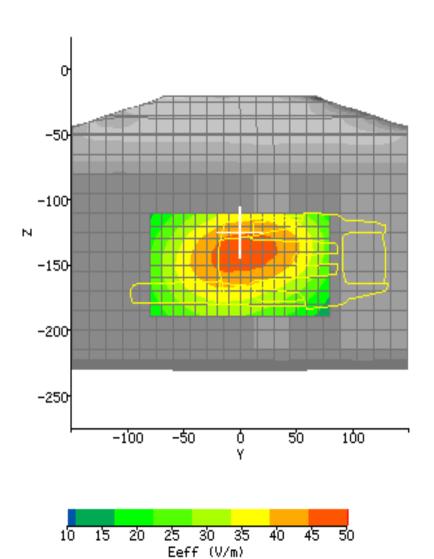
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Plot #3(2/2)

AREA SCAN:

Scan Extent:

	Min	Max	Steps
Y	-80.0	80.0	16.0
Z	-190.0	-110.0	8.0





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Plot #4(1/2)

Date: 2004/11/24

Filename: T8220-CH11_rear.txt

Device Tested: T8220

Antenna: Integral (Helix) Antenna

Shape File: T8220Rear.csv

Position: Rear to phantom with Belt Clip

Phantom: HeadBox2-test.csv

Head Rotation: 0

Test Frequency: CH11_467.6375 MHz

Power Level: 26.4 dBm

Probe: 0149

Cal File: SN0149_450_CW_BODY

 X
 Y
 Z

 Air
 365
 444
 414

 DCP
 20
 20
 20

 Lin
 .360
 .360
 .360

Amp Gain: $\overline{2}$

Cal Factors:

Averaging: 1

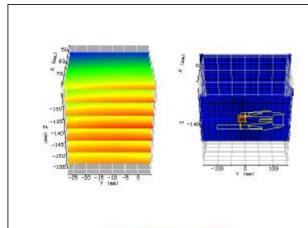
Batteries Replaced: 3

Liquid: 15.5cm

Type: 450 MHz body

Conductivity: 0.951
Relative Permittivity: 57.497
Liquid Temp (deg C): 22.2
Ambient Temp (deg C): 23
Ambient RH (%): 55
Density (kg/m3): 1000
Software Version: 2.3VPM

Crest Factor=1



ZOOM SCAN RESULTS:

 Spot SAR (W/kg):
 Start Scan
 End Scan

 0.555
 0.532

Change during Scan (%)

-2.47

Max E-field (V/m): 35.02

Max SAR (W/kg)

1g	10g
1.086	0.777

Location of Max (mm):

X	Y	Z
78.2	-26.9	-141.0



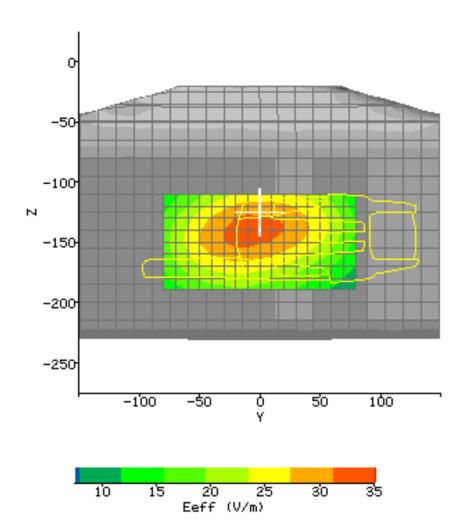
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Plot #4(2/2)

AREA SCAN:

Scan Extent:

	Min	Max	Steps
Y	-80.0	80.0	16.0
Z	-190.0	-110.0	8.0





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APPENDIX B - Photographs

(External)



(External)





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(Battery)



(Battery)





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(Belt-clip)



(Belt-clip)





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(earphone)





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APPENDIX C - E-Field Probe and 450MHz Balanced Dipole Antenna Calibration Data



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IMMERSIBLE SAR PROBE

CALIBRATION REPORT

Part Number: IXP – 050

S/N 0149

May 2004



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Oakfield House
Cudworth Lane
Newdigate
Surrey RH5 5BG

Tel: +44 (0) 1306 632 870 Fax: +44 (0) 1306 631 834 e-mail: <u>enquiries@indexsar.com</u>



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INTRODUCTION

This Report presents measured calibration data for a particular Indexsar SAR probe (S/N 0149) and describes the procedures used for characterisation and calibration.

Indexsar probes are characterised using procedures that, where applicable, follow the recommendations of CENELEC [1] and IEEE [2] standards. The procedures incorporate techniques for probe linearisation, isotropy assessment and determination of liquid factors (conversion factors). Calibrations are determined by comparing probe readings with analytical computations in canonical test geometries (waveguides) using normalised power inputs.

Each step of the calibration procedure and the equipment used is described in the sections below.

CALIBRATION PROCEDURE

1. Equipment Used

For the first part of the characterisation procedure, the probe is placed in an isotropy measurement jig as pictured in Figure 1. In this position the probe can be rotated about its axis by a non-metallic belt driven by a stepper motor.

The probe is attached via its amplifier and an optical cable to a PC. A schematic representation of the test geometry is illustrated in Figure 2.

A balanced dipole (900 MHz) is inserted horizontally into the bracket attached to a second belt (Figure 1). The dipole can also be rotated about its axis. A cable connects the dipole to a signal generator, via a directional coupler and power meter. The signal generator feeds an RF amplifier at constant power, the output of which is monitored using the power meter. The probe is positioned so that its sensors line up with the rotation center of the source dipole. By recording output voltage measurements of each channel as both the probe and the dipole are rotated, data are obtained from which the spherical isotropy of the probe can be optimised and its magnitude determined.

The calibration process requires E-field measurements to be taken in air, in 900 MHz simulated brain liquid and at other frequencies/liquids as appropriate.

2. Linearising probe output

The probe channel output signals are linearised in the manner set out in Refs [1] and [2]. The following equation is utilized for each channel:

$$U_{lin} = U_{o/p} + U_{o/p}^{2} / DCP$$
 (1)

where U_{lin} is the linearised signal, $U_{o/p}$ is the raw output signal in voltage units and DCP is the diode compression potential in similar voltage units.



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DCP is determined from fitting equation (1) to measurements of U_{lin} versus source feed power over the full dynamic range of the probe. The DCP is a characteristic of the schottky diodes used as the sensors. For the IXP-050 probes with CW signals the DCP values are typically 0.10V (or 20 in the voltage units used by Indexsar software, which are V*200).

3. Selecting channel sensitivity factors to optimise isotropic response

The basic measurements obtained using the calibration jig (Fig 1) represent the output from each diode sensor as a function of the presentation angle of the source (probe and dipole rotation angles). The directionality of the orthogonally-arranged sensors can be checked by analysing the data using dedicated Indexsar software, which displays the data in 3D format as in Figure 3. The left-hand side of this diagram shows the individual channel outputs after linearisation (see above). The program uses these data to balance the channel outputs and then applies an optimisation process, which makes fine adjustments to the channel factors for optimum isotropic response.

The next stage of the process is to calibrate the Indexsar probe to a W&G EMR300 E-field meter in air. The principal reasons for this are to obtain conversion factors applicable should the probe be used in air and to provide an overall measure of the probe sensitivity.

A multiplier is applied to factors to bring the magnitudes of the average E-field measurements as close as possible to those of the W&G probe.

The following equation is used (where linearised output voltages are in units of V*200):

$$E_{air}^{2} (V/m) = U_{linx} * Air Factor_{x} + U_{liny} * Air Factor_{y} + U_{linz} * Air Factor_{z}$$
(2)

It should be noted that the air factors are not separately used for normal SAR testing. The IXP-050 probes are optimised for use in tissue-simulating liquids and do not behave isotropically in air.

4. 900 MHz Liquid Calibration

Conversion factors for use when the probes are immersed in tissue-simulant liquids at 900 MHz are determined either using a waveguide or by comparison to a reference probe that has been calibrated by NPL. Waveguide procedures are described later. The summary sheet indicates the method used for the probe S/N 0149.

The conversion factor, referred to as the 'liquid factor' is also applied to the measurements of each channel. The following equation is used (where output voltages are in units of V*200):

$$E_{liq}^{2} (V/m) = U_{linx} * Air Factor_{x} * Liq Factor_{x} + U_{liny} * Air Factor_{y} * Liq Factor_{y} + U_{linz} * Air Factor_{z} * Liq Factor_{z}$$
(3)



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A 3D representation of the spherical isotropy for probe S/N 0149 using these factors is shown in Figure 3.

The rotational isotropy can also determined from the calibration jig measurements and is reported as the 900MHz isotropy in the summary table. Note that waveguide measurements can also be used to determine rotational isotropy (Fig. 5).

The design of the cells used for determining probe conversion factors are waveguide cells is shown in Figure 4. The cells consist of a coax to waveguide transition and an open-ended section of waveguide containing a dielectric separator. Each waveguide cell stands in the upright positition and is filled with liquid within 10 mm of the open end. The seperator provides a liquid seal and is designed for a good electrical transition from air filled guide to liquid filled guide. The choice of cell depends on the portion of the frequency band to be examined and the choice of liquid used. The depth of liquid ensures there is negligible radiation from the waveguide open top and that the probe calibration is not influenced by reflections from nearby objects. The return loss at the coaxial connector of the filled waveguide cell is measured initially using a network analyser and this information is used subsequently in the calibration procedure. The probe is positioned in the centre of the waveguide and is adjusted vertically or rotated using stepper motor arrangements. The signal generator is connected to the waveguide cell and the power is monitored with a coupler and a power meter. A fuller description of the waveguide method is given below.

The liquid dielectric parameters used for the probe calibrations are listed in the Tables below. The final calibration factors for the probe are listed in the summary chart.

WAVEGUIDE MEASUREMENT PROCEDURE

The calibration method is based on setting up a calculable specific absorption rate (SAR) in a vertically-mounted WG8 (R22) waveguide section [1]. The waveguide has an air-filled, launcher section and a liquid-filled section separated by a matching window that is designed to minimise reflections at the liquid interface. A TE₀₁ mode is launched into the waveguide by means of a N-type-to-waveguide adapter. The power delivered to the liquid section is calculated from the forward power and reflection coefficient measured at the input to the waveguide. At the centre of the cross-section of the waveguide, the local spot SAR in the liquid as a function of distance from the window is given by functions set out in IEEE1528 as below:

Because of the low cutoff frequency, the field inside the liquid nearly propagates as a TEM wave. The depth of the medium (greater than three penetration depths) ensures that reflections at the upper surface of the liquid are negligible. The power absorbed in the liquid is determined by measuring the waveguide forward and reflected power. Equation (4) shows the relationship between the SAR at the cross-sectional center of the lossy waveguide and the longitudinal distance (*z*) from the dielectric separator

$$SAR(z) = \frac{4(P_f - P_b)}{rabd}e^{-2z/d}$$
(4)



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where the density ρ is conventionally assumed to be 1000 kg/m³, ab is the cross-sectional area of the waveguide, P_f and P_b are the forward and reflected power inside the lossless section of the waveguide, respectively. The penetration depth d, which is the reciprocal of the waveguide-mode attenuation coefficient, is determined from a scan along the z-axis and compared with the theoretical value determined from Equation (5) using the measured dielectric properties of the lossy liquid.

$$d = \left[\operatorname{Re} \left\{ \sqrt{\left(p / a \right)^2 + j w m_o \left(s + j w e_o e_r \right)} \right\} \right]^{-1}.$$
 (5)

Table A.1 of [1] can be used for designing calibration waveguides with a return loss greater than 30 dB at the most important frequencies used for personal wireless communications. Values for the penetration depth for these specific fixtures and tissue-simulating mixtures are also listed in Table A.1.

According to [1], this calibration technique provides excellent accuracy, with standard uncertainty of less than 3.6% depending on the frequency and medium. The calibration itself is reduced to power measurements traceable to a standard calibration procedure. The practical limitation to the frequency band of 800 to 2500 MHz because of the waveguide size is not severe in the context of compliance testing.

CALIBRATION FACTORS MEASURED FOR PROBE S/N 0149

The probe was calibrated at 900, 1800, 1900 and 2450MHz MHz in liquid samples representing both brain liquid and body fluid at these frequencies. The calibration was for CW signals only, and the axis of the probe was parallel to the direction of propagation of the incident field i.e. end-on to the incident radiation. The axial isotropy of the probe was measured by rotating the probe about its axis in 10 degree steps through 360 degrees in this orientation.

The reference point for the calibration is in the centre of the probe's cross-section at a distance of 2.7 m from the probe tip in the direction of the probe amplifier. A value of 2.7 mm should be used for the tip to sensor offset distance in the software.

It is important that the diode compression point and air factors used in the software are the same as those quoted in the results tables, as these are used to convert the diode output voltages to a SAR value.

DIELECTRIC PROPERTIES OF LIQUIDS

The dielectric properties of the brain and body tissue-simulant liquids employed for calibration are listed in the tables below. The measurements were performed prior to each waveguide test using an Indexsar DiLine measurement kit, which uses the TEM method as recommended in [2].

AMBIENT CONDITIONS

Measurements were made in the open laboratory at 22 ± 2.0 °C. The temperature of the liquids in the waveguide used was measured using a mercury thermometer.



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RESPONSE TO MODULATED SIGNALS

To measure the response of the probe and amplifier to modulated signals, the probe is held vertically in a liquid-filled waveguide.

An RF amplifier is allowed to warm up and stabilise before use. A spectrum analyser is used to demonstrate that the peak power of the RF amplifier for the CW signals and the pulsed signals are within 0.1dB of each other when the signal generator is switched from CW to modulated output. Subsequently, the power levels recorded are read from a power meter when a CW signal is being transmitted.

The test sequence involves manually stepping the power up in regular (e.g. 2 dB) steps from the lowest power that gives a measurable reading on the SAR probe up to the maximum that the amplifiers can deliver.

At each power level, the individual channel outputs from the SAR probe are recorded at CW and then recorded again with the modulation setting. The results are entered into a spreadsheet. Using the spreadsheets, the modulated power is calculated by applying a factor to the measured CW power (e.g. for GSM, this factor is 9.03dB). This process is repeated 3 times with the response maximised for each channel sensor in turn.

The probe channel output signals are linearised in the manner set out in Section 1 above using equation (1) with the DCPs determined from the linearisation procedure. Calibration factors for the probe are used to determine the E-field values corresponding to the probe readings using equation (3). SAR is determined from the equation

SAR (W/kg) =
$$E_{lig}^{2}$$
 (V/m) * σ (S/m) / 1000 (6)

Where σ is the conductivity of the simulant liquid employed.

Using the spreadsheet data, the DCP value for linearising each of the individual channels (X, Y and Z) is assessed separately. The corresponding DCP values are listed in the summary page of the calibration factors for each probe.

Figure 7 shows the linearised probe response to GSM signals, Figure 8 the response to GPRS signals (GSM with 2 timeslots) and Figure 9 the response to CDMA IS-95A and W-CDMA signals.

Additional tests have shown that the modulation response is similar at 1800MHz and is not affected by the orientation between the source and the probe.



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VPM (Virtual Probe Miniaturisation)

SAR probes with 3 diode-sensors in an orthogonal arrangement are designed to display an isotropic response when exposed to a uniform field. However, the probes are ordinarily used for measurements in non-uniform fields and isotropy is not assured when the field gradients are significant compared to the dimensions of the tip containing the three orthogonally-arranged dipole sensors.

It becomes increasingly important to assess the effects of field gradients on SAR probe readings when higher frequencies are being used. For Indexsar IXP-050 probes, which are of 5mm tip diameter, field gradient effects are minor at GSM frequencies, but are major above 5GHz. Smaller probes are less affected by field gradients and so probes, which are significantly less than 5mm diameter, would be better for applications above 5GHz.

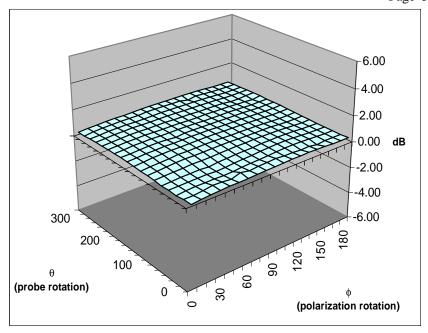
The IndexSAR report IXS0223 describes theoretical and experimental studies to evaluate the issues associated with the use of probes at arbitrary angles to surfaces and field directions. Based upon these studies, the procedures and uncertainty analyses referred to in P1528 are addressed for the full range of probe presentation angles.

In addition, generalized procedures for correcting for the finite size of immersible SAR probes are developed. Use of these procedures enables application of schemes for virtual probe miniaturization (VPM) – allowing probes of a specific size to be used where physically-smaller probes would otherwise be required.

Given the typical dimensions of 3-channel SAR probes presently available, use of the VPM technique extends the satisfactory measurement range to higher frequencies.



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Surface Isotropy diagram of IXP-050 Probe S/N 0149 at 900MHz after VPM

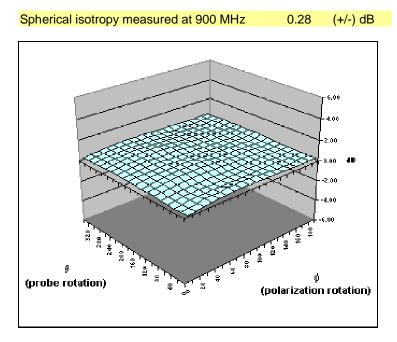
Probe tip radius	1.25
X Ch. Angle to red dot	7

	Head		Body	
Frequency	Bdy. Corrn. – f(0)	Bdy. Corrn. – d(mm)	Bdy. Corrn. – f(0)	Bdy. Corrn. – d(mm)
900	0.2	1.0	0.31	2.0
1800	0.2	2.0	0.27	1.6
1900	0.19	1.7	0.3	1.4
2450	0.24	2.0	0.72	2.0



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SUMMARY OF CALIBRATION FACTORS FOR PROBE IXP-050 S/N 0149



	Χ	Υ	Z	
Air factors	365	444	414	(V*200)
DCPs	20	20	20	(V*200)
GSM	13.4	9.6	7.9	(V*200)
CDMA	20	20	20	(V*200)

f (MHz)	Axial isotro	ру	SAR conve	rsion factors	Notes
	(+/- dB)		(liq/air)		
	BRAIN	BODY	BRAIN	BODY	
450	0.08	0.07	0.344	0.360	1,2,3
835	0.08	0.07	0.344	0.360	1,2,3
900	0.08	0.07	0.344	0.360	1,2,3
1800	0.10	0.11	0.438	0.477	1,2,3
1900	0.11	0.12	0.441	0.504	1,2,3
2450	0.11	0.11	0.504	0.561	1,2,3

Notes	
1)	Calibrations done at 22C +/- 2C
2)	Waveguide calibration
3)	Checked using box-phantom validation test

(the graph shows a simple, spreadsheet representation of surface shown in 3D in Figure 3 below)



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PROBE SPECIFICATIONS

Chemical resistance

Indexsar probe 0149, along with its calibration, is compared with CENELEC and IEEE standards recommendations (Refs [1] and [2]) in the Tables below. A listing of relevant specifications is contained in the tables below:

S/N 0149 350 10 12 5.2 2.7 S/N 0149 0.01 >35	CENELEC [1] 8 CENELEC [1] <0.02 >100	8 IEEE [2] 0.01
10 12 5.2 2.7 S/N 0149	CENELEC [1] <0.02	IEEE [2] 0.01
12 5.2 2.7 S/N 0149	CENELEC [1] <0.02	IEEE [2] 0.01
5.2 2.7 S/N 0149	CENELEC [1] <0.02	IEEE [2] 0.01
2.7 S/N 0149 0.01	CENELEC [1] <0.02	IEEE [2] 0.01
S/N 0149 0.01	[1] <0.02	0.01
0.01	[1] <0.02	0.01
0.01	[1] <0.02	0.01
0.01	[1] <0.02	0.01
	_	
>35	>100	400
		100
S/N 01/0	TOENIELEC	IEEE [2]
3/14 0 149	[1]	الالد زدا
0.125	0.50	0.25
S/N 0149	CENEL EC	IEEE [2]
0/11/01-15	[1]	
0.12 Max	0.5	0.25
(See table		
above)		
0.28	1.0	0.50
Took probo	- contains three	- arthogonal
	S/N 0149 0.12 Max (See table above) 0.28 Each probe dipole sens prism core, charges by covered at the series of	[1] 0.125 0.50 S/N 0149 CENELEC [1] 0.12 Max (See table above) [1]

used in the immersed section. Outer case materials are PEEK and heat-shrink

Tested to be resistant to glycol and alcohol containing simulant liquids but probes should be removed, cleaned and

dried when not in use.

sleeving.



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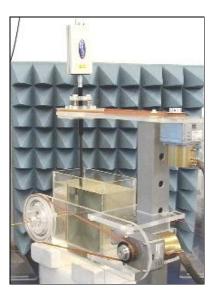
REFERENCES

[1] CENELEC, EN 50361, July 2001. Basic Standard for the measurement of specific absorption rate related to human exposure to electromagnetic fields from mobile phones.

[2] IEEE 1528, Recommended practice for determining the spatial-peak specific absorption rate (SAR) in the human body due to wireless communications devices: Experimental techniques.



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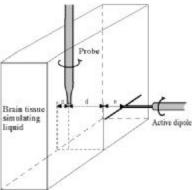


Figure 1. Spherical isotropy jig showing probe, dipole and box filled with simulated brain liquid (see Ref [2], Section A.5.2.1)

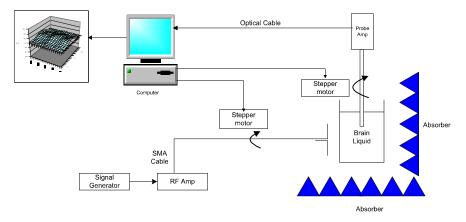


Figure 2. Schematic diagram of the test geometry used for isotropy determination



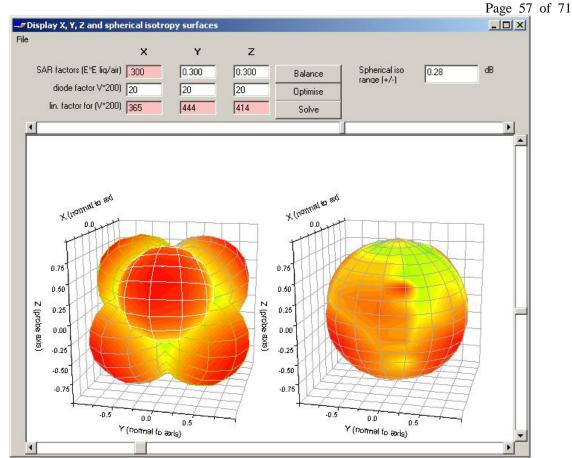


Figure 3. Graphical representation of the probe response to fields applied from each direction. The diagram on the left shows the individual response characteristics of each of the three channels and the diagram on the right shows the resulting probe sensitivity in each direction. The colour range in the figure images the lowest values as blue and the maximum values as red. For the probe S/N 0149, this range is (+/-) 0.28 dB. The probe is more sensitive to fields parallel to the axis and less sensitive to

fields normal to the probe axis.

Lossy
Liquid

Dielectric
Slab

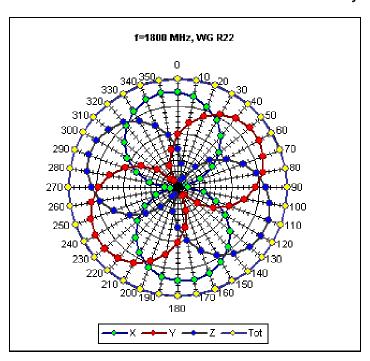
Figure 4. Geometry used for waveguide calibration (after Ref [2]. Section A.3.2.2)



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IXP-050 S/N 0149

11-May-04



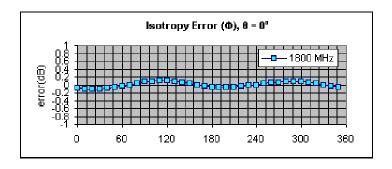
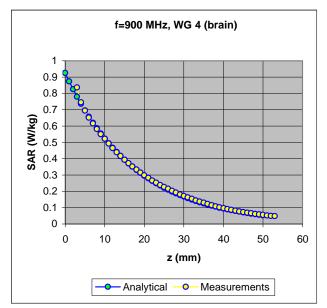


Figure 5. Example of the rotational isotropy of probe S/N 0149 obtained by rotating the probe in a liquid-filled waveguide at 1800 MHz. Similar distributions are obtained at the other test Frequencies (900 and 2450 MHz) both in brain liquids and body fluids (see summary table).



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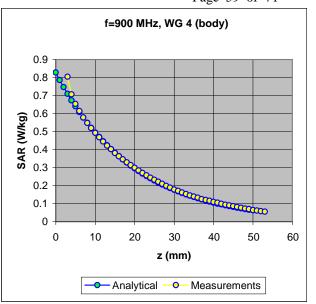
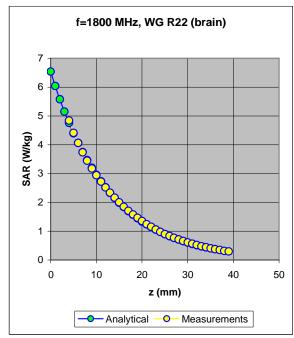
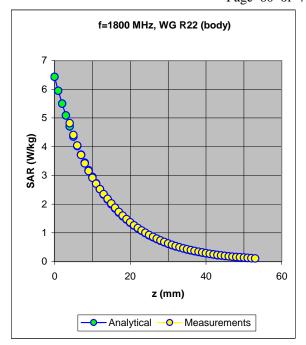


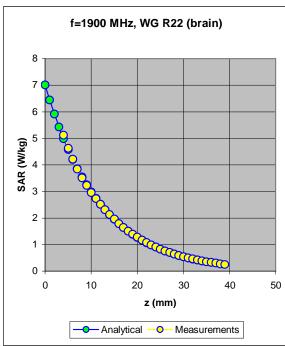
Figure 6. The measured SAR decay function along the centreline of the WG4 waveguide with conversion factors adjusted to fit to the theoretical function for the particular dimension, frequency, power and liquid properties employed.

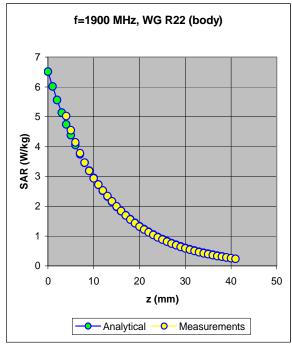


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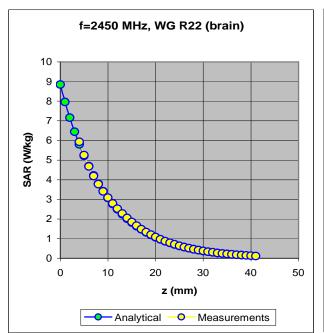








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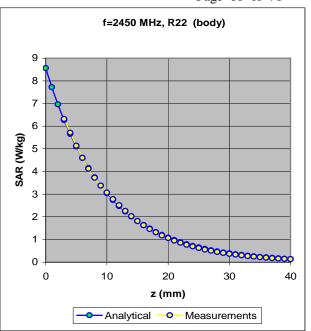


Figure 7. The measured SAR decay function along the centreline of the R22 waveguide with conversion factors adjusted to fit to the theoretical function for the particular dimension, frequency, power and liquid properties employed.



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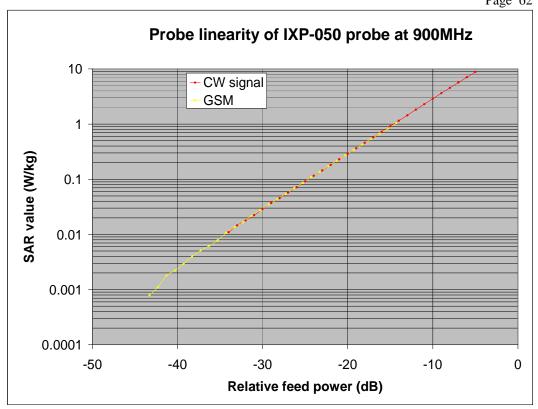


Figure 8. The GSM response of an IXP-050 probe at 900MHz

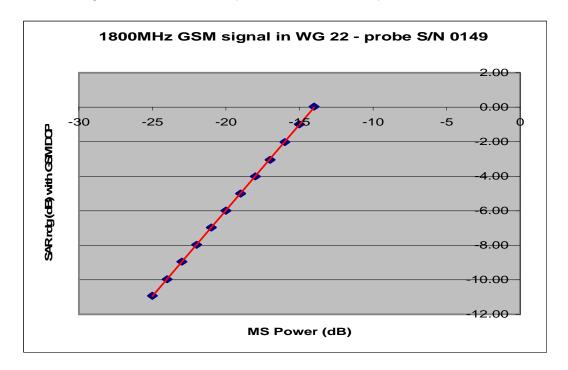


Figure 8a. The actual GSM response of IXP-050 probe S/N 0149 at 1800MHz



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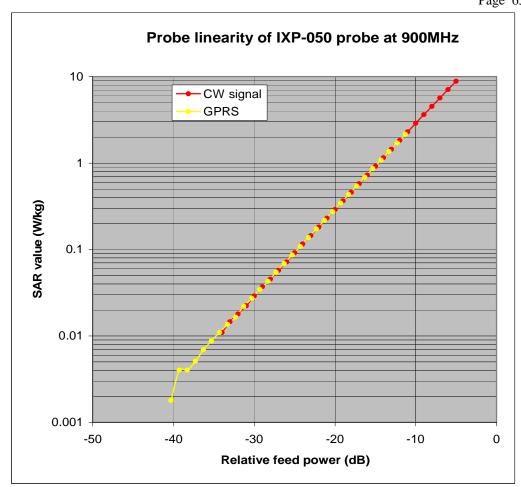
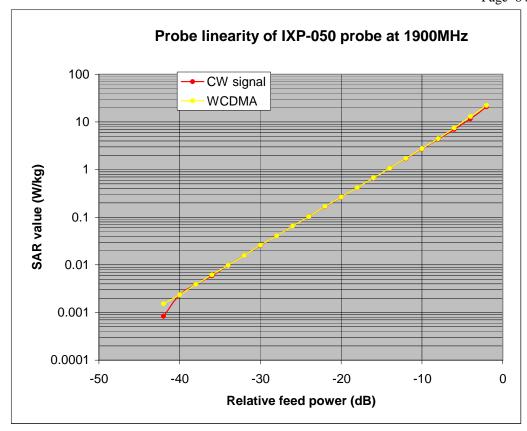


Figure 9. The GPRS response of an IXP-050 probe at 900MHz.



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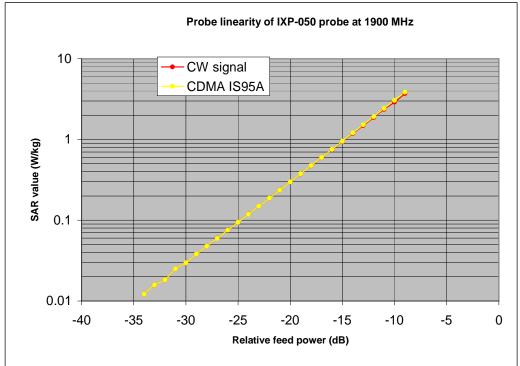


Figure 10. The CDMA response of an IXP-050 probe at 1900MHz.



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Table indicating the dielectric parameters of the liquids used for calibrations at each frequency

Liquid used	Relative permittivity (measured)	Conductivity (S/m) (measured)
900 MHz BRAIN	40.92	0.99
900 MHz BODY	57.27	1.045
1800 MHz BRAIN	40.63	1.37
1800 MHz BODY	52.89	1.53
1900 MHz BRAIN	40.33	1.47
1900 MHz BODY	52.84	1.55
2450 MHz BRAIN	40.73	1.82
2450 MHz BODY	<i>54.5</i> 6	2.04



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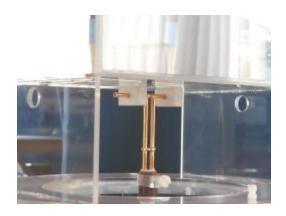


Report No. SN0065_450 October 2003

INDEXSAR 450MHz validation Dipole Type IXD-045 S/N 0065

Performance measurements

MI Manning



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e-mail: enquiries@indexsar.com





Type:

Report No.: EME-040937
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Indexsar Limited
Oakfield House
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Surrey RH5 5DR

Tel: +44 (0) 1306 631 233 Fax: +44 (0) 1306 631 834 e-mail: enquiries@indexsar.com

Calibration / Conformance statement Balanced Validation dipole

IXD-045 450MHz

Manufacturer:	IndexSAR, UK		
Serial Number:	0065		
Place of Calibration:	IndexSAR, UK		
IndexSAR Limited hereby declares that the IXD series dipole named above has been checked for conformity to the specifications given in the draft IEEE 1528 and CENELEC En 50361 standards on the date shown below.			
Date of Calibration/Check:	October 2003		
The dipole named above should be periodically re-checked using the procedures set out in the dipole calibration document. It is important that the cautions regarding handling of the dipoles (given in the calibration document) are adhered to.			
Next Calibration Date:	October 2005		
The calibration measurements were carried out using the methods described in the calibration document. Where applicable, the standards used in the calibration process are traceable to the UK's National Physical Laboratory.			
Calibrated By:	kmladley		
	M. Many		
Approved By:			



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1. Measurement Conditions

Measurements were performed using a box-shaped phantom made of PMMA with dimensions designed to meet the accuracy criteria for reasonably-sized phantoms that do not have liquid capacities substantially in excess of the volume of liquid required to fill the Indexsar upright SAM phantoms used for SAR testing of handsets against the ear.

An HP 8753B vector network analyser was used for the return loss measurements.

The dipole was placed in a special holder made of low-permittivity, low-loss materials. This holder enables the dipole to be positioned accurately in the centre of the base of the Indexsar box-phantom used for flat-surface testing and validation checks.

The validation dipoles are supplied with special spacers made from a low-permittivity, low-loss foam material. These spacers are fitted to the dipole arms to ensure that, when the dipole is offered up to the phantom surface, the spacing between the dipole and the liquid surface is accurately aligned according to the guidance in the relevant standards documentation. The spacers are rectangular with a central hole equal to the dipole arm diameter and dimensioned so that the longer side can be used to ensure a spacing of 15mm from the liquid in the phantom (for tests at 900MHz and below) and the shorter side can be used for tests at 1800MHz and above to ensure a spacing of 10mm from the liquid in the phantom. The spacers are made on a CNC milling machine with an accuracy of $1/40^{th}$ mm but they may suffer wear and tear and need to be replaced periodically. The material used is Rohacell, which has a relative permittivity of approx. 1.05 and a negligible loss tangent.

The apparatus supplied by Indexsar for dipole validation tests thus includes:

Balanced dipoles for each frequency required are dimensioned according to the guidelines given in IEEE 1528 [1]. The dipoles are made from semi-rigid 50 Ohm co-ax, which is joined by soldering and is gold-plated subsequently. The constructed dipoles are easily deformed, if mis-handled, and periodic checks need to be made of their symmetry.

Rohacell foam spacers designed for presenting the dipoles to 2mm thick PMMA box phantoms. These components also suffer wear and tear and should be replaced when the central hole is a loose-fit on the dipole arms or if the edges are too worn to ensure accurate alignment. The standard spacers are dimensioned for use with 2mm wall thickness (additional spacers are available for 4mm wall thickness).



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2. Typical SAR Measurement

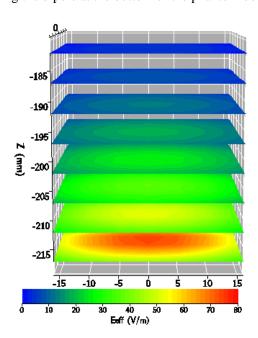
A SAR validation check is performed with the box-phantom located on the SARA2 phantom support base on the SARA2 robot system. Tests are then conducted at a feed power level of approx. 0.25W. The actual power level is recorded and used to normalise the results obtained to the standard input power conditions of 1W (forward power). The ambient temperature is $23^{\circ}C$ +/- $1^{\circ}C$ and the relative humidity is around 67% during the measurements.

The phantom is filled with a 450MHz brain liquid using a recipe from [1], which has the following electrical parameters (measured using an Indexsar DiLine kit) at 450MHz +/-10%:

Relative Permittivity 43.5 Conductivity 0.87 S/m

The SARA2 software version 0.421N is used with an Indexsar probe previously calibrated using waveguides.

The 3D measurements made using the dipole at the bottom of the phantom box is shown below:



The results, normalised to an input power of 1W (forward power) are typically:

Averaged over 1 cm3 (1g) of tissue 4.9 W/kg Averaged over 10cm3 (10g) of tissue 3.3 W/kg

These results can be compared with Table 8.1 in [1]. The agreement is within 10%.



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3. Dipole impedance and return loss

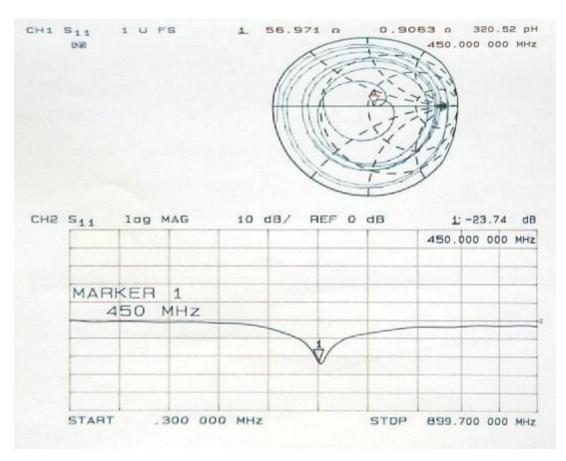
The dipoles are designed to have low return loss ONLY when presented against a lossy-phantom at the specified distance. A Vector Network Analyser (VNA) was used to perform a return loss measurement on the specific dipole when in the measurement-location against the box phantom. The distance was as specified in the standard i.e. 10mm from the liquid (for 450MHz). The Indexsar foam spacers (described above) were used to ensure this condition during measurement.

The impedance was measured at the SMA-connector with the network analyser. The following parameters were measured:

Dipole impedance at 450 MHz Re{Z} = **56.971** Ω

 $Im{Z} = 0.9063 \Omega$

Return loss at 450MHz -23.74 dB





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4. Dipole handling

The dipoles are made from standard, copper-sheathed coaxial cable. In assembly, the sections are joined using ordinary soft-soldering. This is necessary to avoid excessive heat input in manufacture, which would destroy the polythene dielectric used for the cable. The consequence of the construction material and the assembly technique is that the dipoles are fragile and can be deformed by rough handling. Conversely, they can be straightened quite easily as described in this report.

If a dipole is suspected of being deformed, a normal workshop lathe can be used as an alignment jig to restore the symmetry. To do this, the dipole is first placed in the headstock of the lathe (centred on the plastic or brass spacers) and the headstock is rotated by hand (do NOT use the motor). A marker (lathe tool or similar) is brought up close to the end of one dipole arm and then the headstock is rotated by 0.5 rev. to check the opposing arm. If they are not balanced, judicious deformation of the arms can be used to restore the symmetry.

If a dipole has a failed solder joint, the dipole can be fixed down in such a way that the arms are co-linear and the joint re-soldered with a reasonably-powerful electrical soldering iron. Do not use gas soldering irons. After such a repair, electrical tests must be performed as described below.

Please note that, because of their construction, the dipoles are short-circuited for DC signals.

5. Tuning the dipole

The dipole dimensions are based on calculations that assumed specific liquid dielectric properties. If the liquid dielectric properties are somewhat different, the dipole tuning will also vary. A pragmatic way of accounting for variations in liquid properties is to 'tune' the dipole (by applying minor variations to its effective length). For this purpose, Indexsar can supply short brass tube lengths to extend the length of the dipole and thus 'tune' the dipole. It cannot be made shorter without removing a bit from the arm. An alternative way to tune the dipole is to use copper shielding tape to extend the effective length of the dipole. Do both arms equally.

It should be possible to tune a dipole as described, whilst in place in the measurement position as long as the user has access to a VNA for determining the return loss.

6. References

- [1] Draft recommended practice for determining the peak spatial-average specific absorption rate (SAR) in the human body due to wireless communications devices: Experimental Techniques.
- [2] Calibration report on SAR probe IXP-050 S/N 0071 from National Physical Laboratory. Test Report EF07/2002/03/IndexSAR. Dated 20 February 2002.