

# A Test Lab Techno Corp.

Changan Lab: No. 140 -1, Changan Street, Bade City, Taoyuan County, Taiwan R.O.C.

Tel: 886-3-271-0188 / Fax: 886-3-271-0190

### SAR EVALUATION REPORT





Test Report No. : 1201FS13

Applicant : Giant Electronics Limited

Product Name : Two Way Radio with GMRS and FRS

Trade Mark : MOTOROLA

Model Number : MD200

Date of Received : Jan. 03, 2012

Date of Test : Jan.  $04 \sim 05$ , 2012

Issued Date : Jan. 16, 2012

Test Environment : Ambient Temperature : 22  $\pm$  2  $^{\circ}$ C

Relative Humidity: 40 - 70 %

Test Specification : Standard C95.1-1992

IEEE Std. 1528-2003

2.1093;FCC/OET Bulletin 65 Supplement C [July 2001]

Max. SAR : 0.025 W/kg FRS Brain SAR \_15mm (50% Duty Cycle)

0.908 W/kg GMRS Brain SAR \_15mm (50% Duty Cycle)

0.025 W/kg FRS Muscle SAR With Headset\_15mm(50% Duty Cycle)

1.303 W/kg GMRS Muscle SAR With Headset\_15mm (50% Duty Cycle)

0.003 W/kg FRS Muscle SAR With Headset\_Belt Clip\_15mm(50% Duty Cycle)

0.743 W/kg GMRS Muscle SAR With Headset\_Belt Clip\_15mm (50% Duty Cycle)

(Condition: 50% Duty Cycle and positive power drift)

Test Lab : Changan Lab.



1. The test operations have to be performed with cautious behavior, the test results are as attached.

The test results are under chamber environment of A Test Lab Techno Corp. A Test Lab Techno Corp. does not assume responsibility for any conclusions and generalizations drawn from the test results with regard to other specimens or samples.

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Approved By

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(Bill Hu)



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# 1. Description of Equipment under Test (EUT)

Applicant	:	Giant Electronics Limited
Applicant Address	:	33/F., Two Landmark East, 100 How Ming Road, Kwun Tong, Kowloon,
		Hong Kong
Manufacturer	:	DONGGUAN WISETRONICS TELECOM EQUIPMENT CO. LTD
Manufacturer Address	:	Elite Industrial City, Melin District, Dailing Mount Town, Dongguan,
		Guangdong, PRC
Product Name	:	Two Way Radio with GMRS and FRS
Trade Mark	:	MOTOROLA
Model Number	:	MD200
FCC ID	:	K7GMDBJJ
Battery Type	:	Ni-MH Battery (3.6 VDC, 650 mA)
		ALKALINE Battery(1.5 V AA Battery x 3PCS)
TX Frequency	:	467.5625 - 467.7125 MHz ( FRS CH8 - CH 14)
		462.5500 - 462.7250 MHz ( GMRS CH1 - CH 7, CH15 - CH 22)
Max. RF Output Power	:	0.200 W ERP (23.00 dBm) FRS
		0.562 W ERP (27.50 dBm) GMRS
Max. SAR Measurement	:	0.025 W/kg FRS Brain SAR _15mm (50% Duty Cycle)
		0.908 W/kg GMRS Brain SAR _15mm (50% Duty Cycle)
		0.025 W/kg FRS Muscle SAR With Headset_15mm (50% Duty Cycle)
		1.303 W/kg GMRS Muscle SAR With Headset_15mm (50% Duty Cycle)
		0.003 W/kg FRS Muscle SAR With Headset_Belt Clip_15mm (50% Duty Cycle)
		0.743 W/kg GMRS Muscle SAR With Headset_Belt Clip_15mm (50% Duty Cycle)
		(Condition: 50% Duty Cycle and positive power drift)
Antenna Type	:	Fixed Type
Antenna Gain	:	0dBi
Device Category	:	Portable
RF Exposure Environment	:	General Population / Uncontrolled
Application Type	:	Certification

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment / general population exposure limits specified in Standard C95.1-1992 and had been tested in accordance with the measurement procedures specified in IEEE Std. 1528-2003.

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### 2. Introduction

The A Test Lab Techno Corp. RF Testing Laboratory has performed measurements of the maximum potential exposure to the user of **Giant Electronics Limited Trade Mark**: **MOTOROLA Model(s)**: **MD200**. The test procedures, as described in American National Standards, Institute C95.1 - 1992 [1], FCC/OET Bulletin 65 Supplement C [July 2001] were employed and they specify the maximum exposure limit of 1.6mW/g as averaged over any 1 gram of tissue for portable devices being used within 20cm between user and EUT in the uncontrolled environment. A description of the product and operating configuration, detailed summary of the test results, methodology and procedures used in the equipment used are included within this test report.

### 3. SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dw) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (P). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Figure 9).

SAR = 
$$\frac{d}{dt} \left( \frac{dw}{dm} \right) = \frac{d}{dt} \left( \frac{dw}{\rho dv} \right)$$

Figure 1. SAR Mathematical Equation

SAR is expressed in units of Watts per kilogram (W/kg)

$$SAR = \frac{\sigma E^2}{\rho}$$

Where:

 $\sigma$  = conductivity of the tissue (S/m)

 $\rho$  = mass density of the tissue (kg/m<sup>3</sup>)

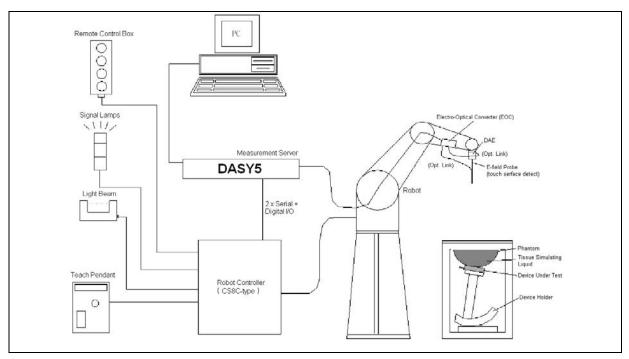
E = RMS electric field strength (V/m)

#### \*Note:

The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane [2]



## 4. SAR Measurement Setup



The DASY5 system for performing compliance tests consists of the following items:

- 1. A standard high precision 6-axis robot (Stäubli TX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- 2. A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- 4. The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- 5. A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- 6. A computer operating Windows 2000 or Windows XP.
- 7. DASY5 software.
- 8. Remote controls with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- 9. The SAM twin phantom enabling testing left-hand and right-hand usage.
- 10. The device holder for handheld mobile phones.
- 11. Tissue simulating liquid mixed according to the given recipes.
- 12. Validation dipole kits allowing validating the proper functioning of the system.

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### 5. System Components

### 5.1 DASY 5 E-Field Probe System

The SAR measurements were conducted with the dosimetric probe EX3DV4 (manufactured by SPEAG), designed in the classical triangular configuration [3] and optimized for dosimetric evaluation. The probes is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY5 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped when reaching the maximum.

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### 5.1.1 E-Field Probe Specification

Construction Symmetrical design with triangular core

Built-in optical fiber for surface detection System

Built-in shielding against static charges

PEEK enclosure material (resistant to organic solvents, e.q., glycol)

Calibration In air from 10 MHz to 6 GHz

In brain and muscle simulating tissue at frequencies of 450MHz (accuracy ±8%)

Calibration for other liquids and frequencies upon request

Frequency  $\pm 0.2$  dB (30 MHz to 6 GHz) for EX3DV4

Directivity  $\pm 0.3$  dB in brain tissue (rotation around probe axis)

±0.5 dB in brain tissue (rotation normal probe axis)

Dynamic Range 10  $\mu$  W/g to > 100mW/g; Linearity:  $\pm$ 0.2dB

Dimensions Overall length: 337mm

Tip length: 20mm

Body diameter: 12mm

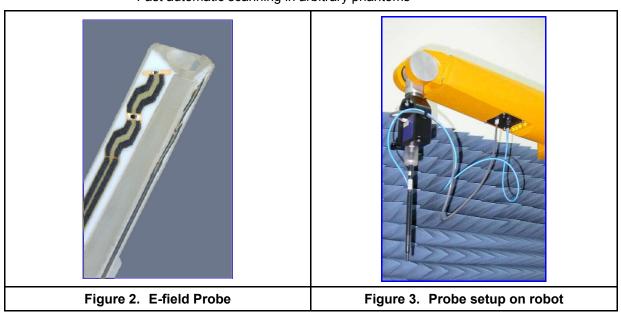
Tip diameter: 2.5mm for EX3DV4

Distance from probe tip to dipole centers: 1.0mm for EX3DV4,

Application General dosimetry up to 6GHz

Compliance tests of mobile phones

Fast automatic scanning in arbitrary phantoms





#### 5.1.2 E-Field Probe Calibration

Each probe is calibrated according to a dosimetric assessment procedure described in (4) with accuracy better than ±10%. The spherical isotropy was evaluated with the procedure described in (5) and found to be better than ±0.25dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1GHz, and in a wave guide above 1GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

Where:

 $\Delta t$  = Exposure time (30 seconds),

**C** = Heat capacity of tissue (head or body),

**Δ T** = Temperature increase due to RF exposure.

Or 
$$SAR = \frac{|E|^2 \sigma}{\rho}$$

Where:

**σ** = Simulated tissue conductivity,

 $\rho$  = Tissue density (kg/m<sup>3</sup>).



### 5.2 Data Acquisition Electronic (DAE) System

**Cell Controller** 

Processor: Intel Core(TM)2 CPU

Clock Speed: @ 1.86GHz

Operating System: Windows XP Professional

**Data Converter** 

Features: Signal Amplifier, multiplexer, A/D converter, and control logic Software: DASY5 v5.0 (Build 125) & SEMCAD X Version 13.4 Build 125

Connecting Lines: Optical downlink for data and status info

Optical uplink for commands and clock

5.3 Robot

Positioner: Stäubli Unimation Corp. Robot Model: TX90XL

Repeatability: ±0.02 mm

No. of Axis: 6

### 5.4 Measurement Server

Processor: PC/104 with a 400MHz intel ULV Celeron

I/O-board: Link to DAE4(or DAE3)

16-bit A/D converter for surface detection system

Digital I/O interface Serial link to robot

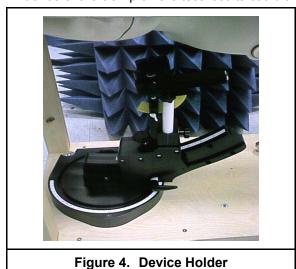
Direct emergency stop output for robot

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### 5.5 Device Holder for Transmitters

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon$ =3 and loss tangent  $\delta$ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



### 5.6 Phantom - SAM v4.0

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

Dimensions	1000x500 mm (LxW) fication of SAM v4.0
Filling Volume	Approx. 25 liters
Shell Thickness	2 ±0.2 mm



Figure 5. SAM Twin Phantom



### 5.7 Data Storage and Evaluation

### 5.7.1 Data Storage

The DASY5 software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension DA5 The post processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

#### 5.7.2 Data Evaluation

The DASY5 post processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Normi, ai0, ai1, ai2

- Conversion factor ConvFi

- Diode compression point dcpi

**Device parameters**: - Frequency f

- Crest factor cf

**Media parameters** : - Conductivity  $\sigma$ 

- Density ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

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The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with  $V_i$  = compensated signal of channel i (i = x, y, z)

 $U_i$  = input signal of channel i (i = x, y, z)

cf = crest factor of exciting field (DASY parameter)

 $dcp_i$  = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes :  $E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$ 

 $H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$ 

H-field probes:

with  $V_i$  = compensated signal of channel i (i = x, y, z)

 $Norm_i$  = sensor sensitivity of channel i (i = x, y, z)

 $\mu \text{ V/(V/m)}^2$  for E-field Probes

ConvF = sensitivity enhancement in solution

 $a_{ij}$  = sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

 $E_i$  = electric field strength of channel i in V/m

Hi = magnetic field strength of channel i in A/m



The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with *SAR* = local specific absorption rate in mW/g

 $E_{tot}$  = total field strength in V/m

 $\sigma$  = conductivity in [mho/m] or [Siemens/m]

 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

\*Note: that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770}$$
 or  $P_{pwe} = \frac{H_{tot}^2}{37.7}$ 

With  $P_{nwe}$  = equivalent power density of a plane wave in mW/cm<sup>2</sup>

 $E_{tot}$  = total electric field strength in V/m

 $H_{tot}$  = total magnetic field strength in A/m



# 6. Test Equipment List

Manufacturer	Name of Equipment	Type/Model	Serial Number	Calib	ration
Manufacturer	Name of Equipment	Турелиоцеі	Serial Number	Last Cal.	Due Date
SPEAG	Dosimetric E-Field Probe	EX3DV4	3632	Jan. 19. 2011	Jan. 19. 2012
SPEAG	450MHz System Validation Kit	D450V2	1021	Feb. 16, 2011	Feb. 16, 2012
SPEAG	Data Acquisition Electronics	DAE4	779	Jan. 31, 2011	Jan. 31, 2012
SPEAG	Measurement Server	SE UMS 011 AA	1025	NO	CR
SPEAG	Device Holder	N/A	N/A	NO	CR
SPEAG	Phantom	SAM V4.0	TP-1150	NO	CR
SPEAG	Robot	Staubli TX90XL	F07/564ZA1/C/01	NO	CR
SPEAG	Software	DASY5 V5.0 Build 125	N/A	NO	CR
SPEAG	Software	SEMCAD V13.4 Build 125	N/A	NO	CR
Agilent	ENA Series Network Analyzer	E5071B	MY42402996	Jan. 04, 2011	Jan. 04, 2013
Agilent	Dielectric Probe Kit	85070C	US99360094	NO	CR
R&S	Power Sensor	NRP-Z22	100179	May 27, 2011	May 27, 2012
Agilent	MXG Vector Signal Generator	N5182A	MY47420962	May 16, 2011	May 16, 2012
Agilent	Dual Directional Coupler	778D	50334	NCR	
Mini-Circuits	Power Amplifier	ZHL-42W-SMA	D111103#5	NO	CR
Mini-Circuits	Power Amplifier	ZVE-8G-SMA	D042005 671800514	NO	CR

Remark: (1) Calibration period 1 year. (2) Calibration period 2 years.

NOTE: N.C.R. = No Calibration Request.

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## 7. Tissue Simulating Liquids

The Head and body mixtures consist of a viscous gel using hydroxethylcellullouse (HEC) gelling agent and saline solution. Preservation with a bactericide is added and visual inspection is made to ensure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue.

The dielectric parameters of the liquids were verified prior to the SAR evaluation using an 85070C Dielectric Probe Kit and an E5071B Network Analyzer.

#### IEEE SCC-34/SC-2 in 1528 recommended Tissue Dielectric Parameters

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in human head. Other head and body tissue parameters that have not been specified in 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equation and extrapolated according to the head parameter specified in 1528.

Target Frequency	He	ad	Во	dy						
(MHz)	٤ <sub>r</sub>	<b>σ</b> (S/m)	٤r	<b>σ</b> (S/m)						
150	52.3	0.76	61.9	0.80						
300	45.3	0.87	58.2	0.92						
450	43.5	0.87	56.7	0.94						
835	41.5	0.90	55.2	0.97						
900	41.5	0.97	55.0	1.05						
915	41.5	0.98	55.0	1.06						
1450	40.5	1.20	54.0	1.30						
1610	40.3	1.29	53.8	1.40						
1800 - 2000	40.0	1.40	53.3	1.52						
2450	39.2	1.80	52.7	1.95						
3000	38.5	2.40	52.0	2.73						
5800	35.3	5.27	48.2	6.00						
( ε <sub>r</sub> = 1	( $\varepsilon_{\rm r}$ = relative permittivity, $\sigma$ = conductivity and $\rho$ = 1000 kg/m <sup>3</sup> )									

Table 2. Tissue dielectric parameters for head and body phantoms

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### 7.1 Ingredients

The following ingredients are used:

- Water: deionized water (pure  $H_20$ ), resistivity  $\geq$  16 M  $\Omega$  -as basis for the liquid
- Sugar: refied white sugar (typically 99.7 % sucrose, available as crystal sugar in food shops)
- to reduce relative permittivity
- Salt: pure NaCl -to increase conductivity
- Cellulose: Hydroxyethyl-cellulose, medium viscosity (75-125 mPa.s, 2% in water, 20°C), CAS # 54290 -to increase viscosity and to keep sugar in solution.
- Preservative: Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS # 55965-84-9 -to prevent the spread of bacteria and molds
- DGBE: Diethylenglycol-monobuthyl ether (DGBE), Fluka Chemie GmbH, CAS # 112-34-5 -to reduce relative permittivity

### 7.2 Recipes

The following tables give the recipes for tissue simulating liquids to be used in different frequency bands.

Note: The goal dielectric parameters (at 22  $^{\circ}$ C) must be achieved within a tolerance of ±5% for  $\epsilon$  and ±5% for  $\sigma$ .

Liquid type	HSL 450 - A				
Ingredient	Weight (g)	Weight (%)			
Water	522.94	38.91			
Sugar	765.09	56.93			
Cellulose	3.39	0.25			
Salt	50.94	3.79			
Preventol	1.63	0.12			
Total amount	1'344.00	100.00			
Goal dielectric parameters					
Frequency [MHz]	45	50			
Relative Permittivity	43.5				
Conductivity [S/m]	3.0	37			

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Liquid type	MSL 450 - B				
Ingredient	Weight (g)	Weight (%)			
Water	590.62	46.21			
Sugar	654.00	51.17			
Cellulose	2.36	0.18			
Salt	29.96	2.34			
Preventol	1.06	0.08			
Total amount	1'278.00	100.00			
Goal dielectric parameters					
Frequency [MHz]	45	50			
Relative Permittivity	56.7				
Conductivity [S/m]	0.94				

# 7.3 Liquid Confirmation

### 7.3.1 Parameters

Liquid Verify										
Ambient	Ambient Temperature : 22 $\pm$ 2 $^{\circ}\mathrm{C}$ ; Relative Humidity : 40-70 $^{\circ}\mathrm{M}$									
Liquid Type	- Fred I -		Parameters	Target Value			Deviation Limit (%)			
450MHz	450MHz	22.0	٤r	43.50	44.38	2.02%	± 5	01/04/2012		
Head		VITZ 22.0	ъ	0.870	0.876	0.69%	± 5	01/04/2012		
450MHz	450MHz	22.0	εr	56.70	55.71	-1.75%	± 5	01/05/2012		
Body	450MHZ	22.0	σ	0.940	0.934	-0.64%	± 5	01/03/2012		

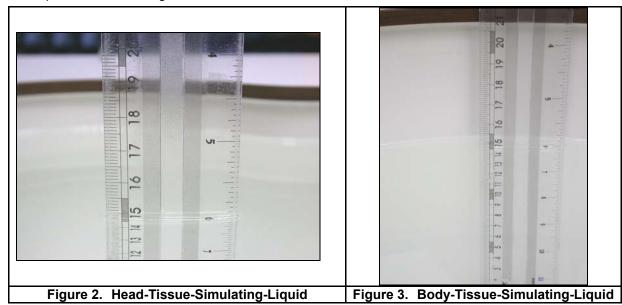
Table 3. Measured Tissue dielectric parameters for head and body phantoms

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## 7.3.2 Liquid Depth

The liquid level was during measurement 15cm  $\pm 0.5$ cm.





### 8. Measurement Process

### 8.1 Device and Test Conditions

The Test Device was provided by Giant Electronics Limited for this evaluation. The spatial peak SAR values were assessed for the middle channel defined by FRS (Ch11 = 467.6375MHz) and GMRS (Ch4 = 462.6375MHz) systems. Battery and accessories shall be those specified by the manufacturer. The battery shall be fully charged before each measurement and there shall be no external connections.

Usage				Operates with a built-in test mode by client			
Distance betwee and the liquid su		axis at the	joint	For Body, EUT front to phantom, 15mm separation. EUT back to phantom, 15mm separation. EUT back to phantom, to attach belt clip.			
Simulating huma	n Head/Bo	ody		Head / Body			
EUT Battery				Fully-charged with Ni-MH Battery and Alkaline Battery.			
	Channel			Frequency	Before	After	
Output Power		MHz	MHz	dBm	dBm		
(ERP)	FRS	Middle	- 11	467.6375	23.00	22.91	
	GMRS	Middle	- 04	462.6375	27.50	27.42	

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### 8.2 System Performance Check

### 8.2.1 Symmetric Dipoles for System Validation

Construction Symmetrical dipole with I/4 balun enables measurement of feed point impedance

with NWA matched for use near flat phantoms filled with head simulating solutions Includes distance holder and tripod adaptor Calibration Calibrated SAR value for specified position and input power at the flat phantom in head simulating solutions.

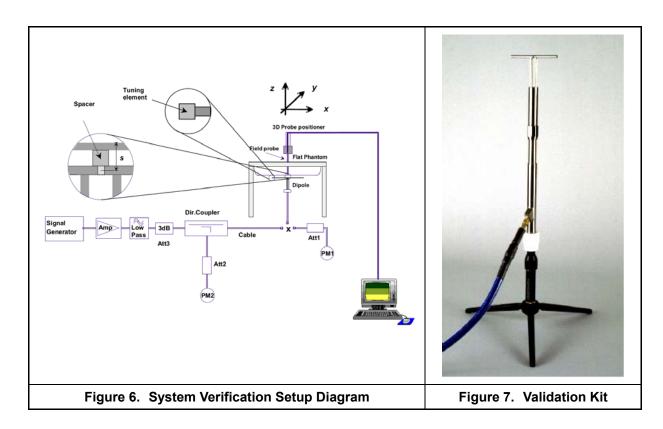
Frequency 450 MHz

Return Loss > 20 dB at specified validation position Power Capability > 100 W (f < 1GHz); > 40 W (f > 1GHz)

Options Dipoles for other frequencies or solutions and other calibration conditions are

available upon request

Dimensions D450V2: dipole length 270 mm; overall height 330 mm





### 8.2.2 Validation

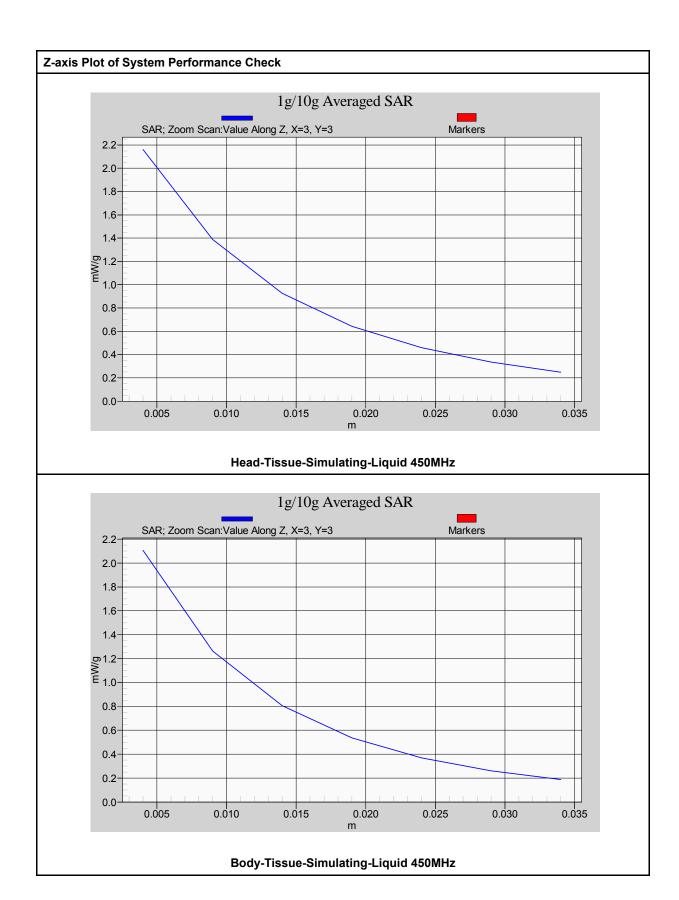
Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of  $\pm$  10%. The validation was performed at 450 MHz.

Valida	tion kit	Mixture Type	SAR <sub>1g</sub> [mW/g]	SAR <sub>10g</sub> [mW/g]	Cal.	Date	Due Date	
D450\/2	SN1021	Head	4.93	3.27	Fab. 46, 0044		Feb 16 2012	
D450V2-SN1021		Body	4.68	3.11	Feb. 16, 2011		Feb. 16, 2012	
Frequency (MHz)	Power	SAR <sub>1g</sub> (mW/g)	SAR <sub>10g</sub> (mW/g)	Drift (dB)		rence entage	Date	
(		(IIIV/g)	(IIIVV/g)	(==)	1g	10g		
450	398mW	1.99	1.27	-0.101	1.4 %	-2.4 %	Jan. 04, 2012	
(Head)	Normalize to 1 Watt	5.00	3.19	-0.101	1.4 /0	-2.4 /0	Jan. 04, 2012	
450	398mW	1.95	1.2	-0.022	4.7 %	-3.1 %	Jan. 05, 2012	
(Body)	Normalize to 1 Watt	4.90	3.02	-0.022	4.7 /0	-3.1 /0	Jan. 03, 2012	

Detail results see Appendix A.

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### 8.3 Dosimetric Assessment Setup

### 8.3.1 Body Test Position

Body - Worn Configuration

Body - Worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a headset output should be tested with a headset connected to the device.

Body - Worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 15 mm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances.

For this test:

- The EUT is placed into the holster/belt clip and the holster is positioned against the surface of the phantom in a normal operating position.
- Belt clip sold with the product is not available. Therefore for SAR measurement, 0mm separation between the product and phantom is done for worst-case compliance.

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#### 8.3.2 **Measurement Procedures**

The evaluation was performed with the following procedures:

Surface Check: A surface checks job gathers data used with optical surface detection. It determines the distance from the phantom surface where the reflection from the optical detector has its peak. Any following measurement jobs using optical surface detection will then rely on this value. The surface check performs its search a specified number of times, so that the repeatability can be verified. The probe tip distance is 1.3mm to phantom inner surface during scans.

Reference:

The reference job measures the field at a specified reference position, at 4 mm from the selected section's grid reference point.

Area Scan:

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines can find the maximum locations even in relatively coarse grids. When an area scan has measured all reachable points, it computes the field maxima found in the scanned area, within a range of the global maximum. Any following zoom scan within the same procedure will then perform fine scans around these maxima. The area covered the entire dimension of the EUT and the horizontal grid spacing was 15 mm × 15 mm.

Zoom Scan:

Zoom scans are used to assess the highest averaged SAR for cubic averaging volumes with 1 g and 10 g of simulated tissue. The zoom scan measures 7 x 7 x 9 points in a 30 x 30 x 24 mm cube whose base faces are centered around the maxima returned from a preceding area scan within the same procedure.

Drift:

The drift job measures the field at the same location as the most recent reference job within the same procedure, with the same settings. The drift measurement gives the field difference in dB from the last reference measurement. Several drift measurements are possible for each reference measurement. This allows monitoring of the power drift of the device in the batch process. If the value changed by more than 5%, the evaluation was repeated.

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### 8.4 Spatial Peak SAR Evaluation

The DASY5 software includes all numerical procedures necessary to evaluate the spatial peak SAR values. Based on the Draft: SCC-34, SC-2, WG-2 - Computational Dosimetry, IEEE P1529/D0.0 (Draft Recommended Practice for Determining the Spatial-Peak Specific Absorption Rate (SAR) Associated with the Use of Wireless Handsets - Computational Techniques), a new algorithm has been implemented. The spatial-peak SAR can be computed over any required mass.

The base for the evaluation is a "cube" measurement in a volume of (30×30×24)mm3 (7×7×9 points). The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan. If the 10g cube or both cubes are not entirely inside the measured volumes, the system issues a warning regarding the evaluated spatial peak values within the Postprocessing engine (SEMCAD). This means that if the measured volume is shifted, higher values might be possible. To get the correct values you can use a finer measurement grid for the area scan. In complicated field distributions, a large grid spacing for the area scan might miss some details and give an incorrectly interpolated peak location.

The entire evaluation of the spatial peak values is performed within the Postprocessing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into three stages:

#### Interpolation and Extrapolation

The probe is calibrated at the center of the dipole sensors which is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated.

In DASY5, the choice of the coordinate system defining the location of the measurement points has no influence on the uncertainty of the interpolation, Maxima Search and SAR extrapolation routines. The interpolation, Maxima Search and extrapolation routines are all based on the modified Quadratic Shepard's method [7].

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## 9. Measurement Uncertainty

Measurement uncertainties in SAR measurements are difficult to quantify due to several variables including biological, physiological, and environmental. However, we estimate the measurement uncertainties in SAR to be less than  $\pm 20.10 \%$  (8).

According to Std. C95.3[9], the overall uncertainties are difficult to assess and will vary with the type of meter and usage situation. However, accuracy's of  $\pm 1$  to 3 dB can be expected in practice, with greater uncertainties in near-field situations and at higher frequencies (shorter wavelengths), or areas where large reflecting objects are present. Under optimum measurement conditions, SAR measurement uncertainties of at least  $\pm 2$ dB can be expected.

According to CENELEC (10), typical worst-case uncertainty of field measurements is  $\pm$  5 dB. For well-defined modulation characteristics the uncertainty can be reduced to  $\pm$  3 dB.

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Uncertainty Component	Uncertainty Value	Probability Distribution	Divisor	<i>c<sub>i</sub></i> (1g)	<i>c<sub>i</sub></i> (10g)	Standard Uncertainty ±1% ( 1-g )	Standard Uncertainty ±1% ( 10-g )	$V_i$ or $V_{\it eff}$
Measurement System								
Probe Calibration (k=1)	±5.5%	Normal	1	1	1	±5.5%	±5.5%	8
Probe Isotropy	±7.6%	Rectangular	$\sqrt{3}$	0.7	0.7	±3.1%	±3.1%	8
Boundary Effect	±1.0%	Rectangular	$\sqrt{3}$	1	1	±0.6%	±0.6%	8
Linearity	±4.7%	Rectangular	$\sqrt{3}$	1	1	±2.7%	±2.7%	8
System Detection Limit	±1.0%	Rectangular	$\sqrt{3}$	1	1	±0.58%	±0.58%	8
Readout Electronics	±0.3%	Normal	1	1	1	±0.3%	±0.3%	8
Response Time	±0.8%	Rectangular	$\sqrt{3}$	1	1	±0.5%	±0.5%	8
Integration Time	±2.6%	Rectangular	$\sqrt{3}$	1	1	±1.5%	±1.5%	8
RF Ambient Conditions	±0%	Rectangular	$\sqrt{3}$	1	1	±0%	±0%	8
RF Ambient Reflections	±0%	Rectangular	$\sqrt{3}$	1	1	±0%	±0%	8
Probe Positioner Mechanical Tolerance	±0.4%	Rectangular	$\sqrt{3}$	1	1	±0.2%	±0.2%	8
Probe Positioning with respect to Phantom Shell	±2.9%	Rectangular	$\sqrt{3}$	1	1	±1.7%	±1.7%	8
Extrapolation, interpolation and integration Algorithms for Max. SAR	±1.0%	Rectangular	$\sqrt{3}$	1	1	±0.6%	±0.6%	8
Test sample Related								
Test sample Positioning	±3.6%	Normal	1	1	1	±3.6%	±3.6%	89
Device Holder Uncertainty	±3.5%	Normal	1	1	1	±3.5%	±3.5%	5
Output Power Variation - SAR drift measurement	±5.0%	Rectangular	$\sqrt{3}$	1	1	±2.9%	±2.9%	8
Phantom and Tissue Parameters								
Phantom Uncertainty ( shape and thickness tolerances)	±4.0%	Rectangular	$\sqrt{3}$	1	1	±2.3%	±2.3%	8
Liquid Conductivity - deviation from target values	±5.0%	Rectangular	$\sqrt{3}$	0.64	0.43	±1.8%	±1.2%	8
Liquid Conductivity - measurement uncertainty	±1.93%	Normal	1	0.64	0.43	±1.24%	±0.83%	69
Liquid Permittivity - deviation from target values	±5.0	Rectangular	$\sqrt{3}$	0.6	0.49	±1.7%	±1.4%	8
Liquid Permittivity - measurement uncertainty			1	0.6	0.49	±0.84%	±0.69%	69
Combined standard uncer	tainty	RSS				±10.05%	±9.85%	313
	Expanded uncertainty (95% CONFIDENCE LEVEL)					±20.10%	±19.70%	

Table 4. System uncertainty: 300MHz -3000MHz

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Uncertainty Component	Uncertainty Value	Probability Distribution	Divisor	c <sub>i</sub> (1g)	<i>c<sub>i</sub></i> (10g)	Standard Uncertainty ±1% ( 1-g )	Standard Uncertainty ±1% ( 10-g )	V <sub>i</sub> or V <sub>eff</sub>
Measurement System								
Probe Calibration	±6.55 %	Normal	1	1	1	±6.55 %	±6.55 %	8
Axial Isotropy	±4.7 %	Rectangular	$\sqrt{3}$	1	1	±2.7 %	±2.7 %	8
Hemispherical Isotropy	±9.6 %	Rectangular	$\sqrt{3}$	0	0	±0 %	±0 %	8
Boundary Effects	±1.0 %	Rectangular	$\sqrt{3}$	1	1	±0.6%	±0.6 %	8
Linearity	±4.7 %	Rectangular	$\sqrt{3}$	1	1	±2.7 %	±2.7 %	8
System Detection Limits	±1.0 %	Rectangular	$\sqrt{3}$	1	1	±0.6 %	±0.6 %	8
Modulation Response	±0 %	Rectangular	$\sqrt{3}$	1	1	±0 %	±0 %	8
Readout Electronics	±0.3 %	Normal	1	1	1	±0.3 %	±0.3 %	8
Response Time	±0 %	Rectangular	$\sqrt{3}$	1	1	±0 %	±0 %	8
Integration Time	±0 %	Rectangular	$\sqrt{3}$	1	1	±0 %	±0 %	8
RF Ambient Noise	±1.0 %	Rectangular	$\sqrt{3}$	1	1	±0.6 %	±0.6 %	8
RF Ambient Reflections	±1.0 %	Rectangular	$\sqrt{3}$	1	1	±0.6 %	±0.6 %	8
Probe Positioner	±0.8 %	Rectangular	$\sqrt{3}$	1	1	±0.5 %	±0.5 %	8
Probe Positioning	±6.7 %	Rectangular	$\sqrt{3}$	1	1	±3.9 %	±3.9 %	8
Max. SAR Eval.	±2.0 %	Rectangular	$\sqrt{3}$	1	1	±1.2 %	±1.2 %	8
Dipole Related								
Deviation of exp. dipole	±5.5 %	Rectangular	$\sqrt{3}$	1	1	±3.2 %	±3.2 %	8
Dipole Axis to Liquid Dist.	±2.0 %	Rectangular	$\sqrt{3}$	1	1	±1.2 %	±1.2 %	8
Input power & SAR drift	±3.4 %	Rectangular	$\sqrt{3}$	1	1	±2.0 %	±2.0 %	8
Phantom and Setup								
Phantom Uncertainty	±4.0 %	Rectangular	$\sqrt{3}$	1	1	±2.3 %	±2.3 %	8
SAR correction	±1.9 %	Rectangular	$\sqrt{3}$	1	0.84	±1.1 %	±0.9 %	8
Liquid Conductivity (meas.)	±2.5 %	Normal	1	0.78	0.71	±2.0 %	±1.8 %	8
Liquid Permittivity (meas.)	±2.5 %	Normal	1	0.26	0.26	±0.7 %	±0.7 %	8
Temp. uncConductivity	±1.7 %	Rectangular	$\sqrt{3}$	0.78	0.71	±0.8 %	±0.7 %	8
Temp. uncPermittivity	±0.3 %	Rectangular	$\sqrt{3}$	0.23	0.26	±0.0 %	±0.0 %	8
Combined standard uncer	tainty	RSS				±10.1%	±10.1 %	
Expanded uncertaint	/	k=2				±20.2	±20.1 %	

Table 5. Uncertainty Budget for System Validation for the 0.3 -6 GHz range

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# 10. SAR Test Results Summary

### 10.1 Brain SAR

	Measurement Results_ EUT Front surface to phantom 15mm											
	Fre	equency	<b>-</b>	Phantom		SAR <sub>1g</sub> [mW/g]		SAR <sub>1g</sub> [mW/g]		Power	Amb	
Band	СН	MHz	Battery	Position	Accessory	Duty 100%	Cycle 50%	Drift (dB)	Temp	Remark		
FRS	11	467.6375	Ni-MH	Flat	N/A	0.009	0.004	-0.032	22.0			
110	11	467.6375	ALKALINE	Flat	N/A	0.049	0.025	-0.069	22.0			
GMRS	4	462.6375	Ni-MH	Flat	N/A	1.790	0.895	-0.061	22.0			
GIVIING	4	462.6375	ALKALINE	Flat	N/A	1.140	0.570	-0.183	22.0			
Std. C95.1-1992 - Safety Limit Spatial Peak Uncontrolled Exposure/General Population							1.6 W/kg (mW/g) Averaged over 1 gram					

Detail results see Appendix B.

### ◆ SAR values are scaled for the power drift

Frequency		equency		SAR <sub>1g</sub> [mW/g]		power drift	+ power drift 10^(dB/10)	SAR <sub>1g</sub> [mW/g] (include +power drift)		Remark
Band			Battery	Duty Cycle		(dB)				
	Ch.	MHz	100% 50%			100%	50%			
FRS	11	467.6375	Ni-MH	0.009	0.004	-0.032	1.007	0.009	0.005	
FRO	11	467.6375	ALKALINE	0.049	0.025	-0.069	1.016	0.050	0.025	
GMRS	4	467.6375	Ni-MH	1.790	0.895	-0.061	1.014	1.815	0.908	
GIVIRS	4	467.6375	ALKALINE	1.140	0.570	-0.183	1.043	1.189	0.595	

SAR is basically proportional to average transmit power and duty cycle

(i.e. SAR = P x T where P is the average transmit power and T is the transmit duty cycle).

SAR(unknown) = SAR(know) x (PxTx/P(known) T(known))

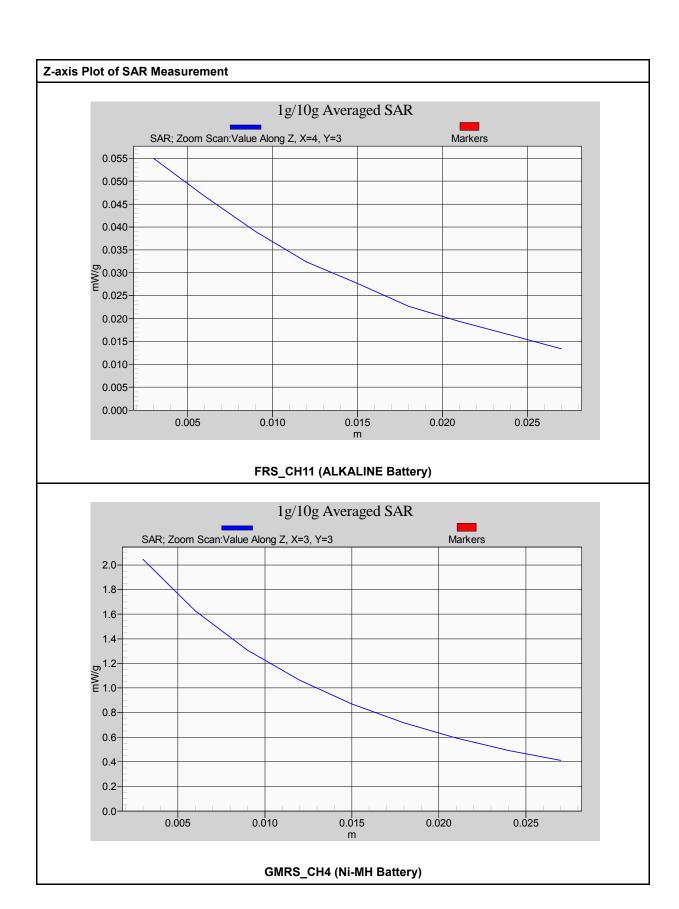
Where Px is the unknown power (i.e. the power at the highest drift)

Tx is the transmit duty cycle used at that unknown power.

If transmitter duty cycle is the same then it should be a relationship of Px/Pknown)

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### 10.2 Muscle SAR

	Measurement Results _ EUT Back surface to phantom 15mm											
	Fre	equency		Phantom		SAR <sub>1g</sub> [mW/g]		SAR <sub>1g</sub> [mW/g]		Power	Amb	,
Band	СН	MHz	Battery	Position	Accessory	Duty 100%	Cycle 50%	Drift (dB)	Temp	Remark		
FRS	11	467.6375	Ni-MH	Flat	Headset	0.028	0.014	-0.021	22.0			
110	11	467.6375	ALKALINE	Flat	Headset	0.050	0.025	0.068	22.0			
GMRS	4	462.6375	Ni-MH	Flat	Headset	2.580	1.290	0.043	22.0			
GIVITO	4	462.6375	ALKALINE	Flat	Headset	0.999	0.500	-0.106	22.0			
	Std. C95.1-1992 - Safety Limit Spatial Peak Uncontrolled Exposure/General Population							.6 W/kg (n raged ove		n		

Detail results see Appendix B.

### ◆ SAR values are scaled for the power drift

	Frequency			SAR <sub>1g</sub> [mW/g]		power drift	+ power drift 10^(dB/10)	(include	[mW/g] +power ift)	
Band			Battery	Duty Cycle		(dB)				Remark
	Ch. MHz	MHz		100%	50%			100%	50%	
FRS	11	467.6375	Ni-MH	0.028	0.014	-0.021	1.005	0.028	0.014	
FRO	11	467.6375	ALKALINE	0.050	0.025	0.068	1.016	0.051	0.025	
CMDS	4	467.6375	Ni-MH	2.580	1.290	0.043	1.010	2.606	1.303	
GMRS	4	467.6375	ALKALINE	0.999	0.500	-0.106	1.025	1.024	0.512	

SAR is basically proportional to average transmit power and duty cycle

(i.e. SAR = P x T where P is the average transmit power and T is the transmit duty cycle).

 $SAR(unknown) = SAR(know) \times (PxTx/P(known) T(known))$ 

Where Px is the unknown power (i.e. the power at the highest drift)

Tx is the transmit duty cycle used at that unknown power.

If transmitter duty cycle is the same then it should be a relationship of Px/Pknown)

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Measurement Results _ EUT Back surface to phantom 0mm										
	Frequency		<b>-</b>	Phantom		SAR <sub>1g</sub> [mW/g]		Power	Amb	
Band	СН	MHz	Battery	Position	Accessory	Duty Cycle 100% 50%		Drift (dB)	Temp	Remark
FRS	11	467.6375	Ni-MH	Flat	Headset & Belt clip	0.005	0.003	-0.172	22.0	
GMRS	4	462.6375	Ni-MH	Headset &		1.470	0.735	-0.046	22.0	
Std. C95.1-1992 - Safety Limit Spatial Peak Uncontrolled Exposure/General Population								.6 W/kg (n raged ove		n

Detail results see Appendix B.

### ◆ SAR values are scaled for the power drift

	Frequency Band			SAR <sub>1g</sub> [mW/g]  Duty Cycle		power drift	+ power drift	SAR <sub>1g</sub> [mW/g] (include +power drift)		Remark
Band			Battery			(dB)	10^(dB/10)			
	Ch.	MHz		100%	50%			100%	50%	
FRS	11	467.6375	Ni-MH	0.005	0.003	-0.172	1.040	0.005	0.003	
GMRS	4	467.6375	Ni-MH	1.470	0.735	-0.046	1.011	1.486	0.743	

SAR is basically proportional to average transmit power and duty cycle

(i.e. SAR = P x T where P is the average transmit power and T is the transmit duty cycle).

SAR(unknown) = SAR(know) x (PxTx/P(known) T(known))

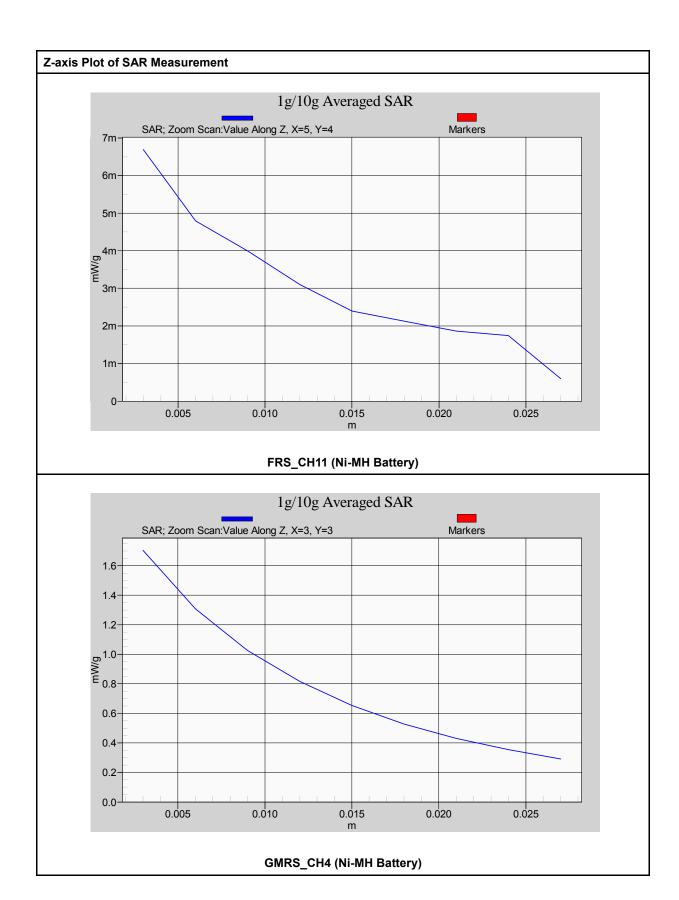
Where Px is the unknown power (i.e. the power at the highest drift)

Tx is the transmit duty cycle used at that unknown power.

If transmitter duty cycle is the same then it should be a relationship of Px/Pknown)

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### 10.3 Std. C95.1-1992 RF Exposure Limit

Human Exposure	Population Uncontrolled Exposure ( W/kg ) or (mW/g)	Occupational Controlled Exposure ( W/kg ) or (mW/g)		
Spatial Peak SAR* (head)	1.60	8.00		
Spatial Peak SAR** (Whole Body)	0.08	0.40		
Spatial Peak SAR*** (Partial-Body)	1.60	8.00		
Spatial Peak SAR**** (Hands / Feet / Ankle / Wrist)	4.00	20.00		

Table 6. Safety Limits for Partial Body Exposure

#### Notes:

- \* The Spatial Peak value of the SAR averaged over any 1 gram of tissue.

  ( defined as a tissue volume in the shape of a cube ) and over the appropriate averaging time.
- \*\* The Spatial Average value of the SAR averaged over the whole body.
- \*\*\* The Spatial Average value of the SAR averaged over the partial body.
- \*\*\*\* The Spatial Peak value of the SAR averaged over any 10 grams of tissue.

( defined as a tissue volume in the shape of a cube ) and over the appropriate averaging time.

**Population** / **Uncontrolled Environments**: are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

**Occupational / Controlled Environments:** are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

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### 11. Conclusion

The SAR test values found for the portable mobile phone **Giant Electronics Limited Trade Mark: MOTOROLA Model(s): MD200** are below the maximum recommended level of 1.6 W/kg (mW/g).

### 12. References

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- [7] Robert J. Renka, "Multivariate Interpolation Of Large Sets Of Scattered Data", University of North Texas ACM Transactions on Mathematical Software, vol. 14, no. 2, June 1988, pp. 139-148.
- [8] N. Kuster, R. Kastle, T. Schmid, *Dosimetric evaluation of mobile communications equipment with known precision*, IEEE Transaction on Communications, vol. E80-B, no. 5, May 1997, pp. 645-652.
- [9] Std. C95.3-1991, "IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields RF and Microwave, New York: IEEE, Aug. 1992.
- [10] CENELEC CLC/SC111B, European Prestandard (prENV 50166-2), *Human Exposure to Electromagnetic Fields High-frequency*: 10KHz-300GHz, Jan. 1995.

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### Appendix A - System Performance Check

Test Laboratory: A Test Lab Techno Corp.

Date/Time: 1/4/2012 8:21:54 PM

System Performance Check at 450 MHz 20120104 Head

DUT: Dipole 450MHz; Type: D450V2; Serial: D450V2 SN:1021

Communication System: CW; Frequency: 450 MHz; Duty Cycle: 1:1

Medium parameters used: f = 450 MHz;  $\sigma = 0.876 \text{ mho/m}$ ;  $\varepsilon_r = 44.4$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(9.4, 9.4, 9.4); Calibrated: 1/19/2011
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### System Performance Check at 450 MHz/Area Scan (61x201x1):

Measurement grid:

dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 2.11 mW/g

### System Performance Check at 450 MHz/Zoom Scan (7x7x7)/Cube 0:

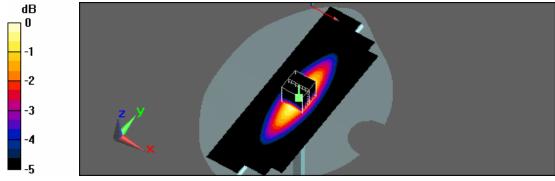
Measurement grid:

dx=5mm, dy=5mm, dz=5mm

Reference Value = 50.4 V/m; Power Drift = -0.101 dB

Peak SAR (extrapolated) = 3.13 W/kg

SAR(1 g) = 1.99 mW/g; SAR(10 g) = 1.27 mW/gMaximum value of SAR (measured) = 2.16 mW/g



0 dB = 2.16 mW/g

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Date/Time: 1/5/2012 5:19:13 PM

#### System Performance Check at 450 MHz 20120105 Body

### DUT: Dipole 450MHz; Type: D450V2; Serial: D450V2 SN:1021

Communication System: CW; Frequency: 450 MHz; Duty Cycle: 1:1

Medium parameters used: f = 450 MHz;  $\sigma = 0.934 \text{ mho/m}$ ;  $\varepsilon_r = 55.7$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(10.05, 10.05, 10.05); Calibrated: 1/19/2011
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### System Performance Check at 450 MHz/Area Scan (61x201x1):

Measurement grid:

dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 2.1 mW/g

### System Performance Check at 450 MHz/Zoom Scan (7x7x7)/Cube 0:

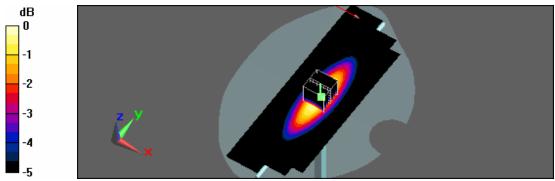
Measurement grid:

dx=5mm, dy=5mm, dz=5mm

Reference Value = 47.6 V/m; Power Drift = -0.022 dB

Peak SAR (extrapolated) = 3.35 W/kg

SAR(1 g) = 1.95 mW/g; SAR(10 g) = 1.2 mW/gMaximum value of SAR (measured) = 2.11 mW/g



0 dB = 2.11 mW/g

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### Appendix B - SAR Measurement Data

Test Laboratory: A Test Lab Techno Corp.

Date/Time: 1/5/2012 7:41:21 AM

### Flat\_GMRS CH4\_Front surface to phantom 15mm

### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: GMRS; Frequency: 462.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 462.6375 MHz;  $\sigma = 0.884 \text{ mho/m}$ ;  $\varepsilon_r = 44.1$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

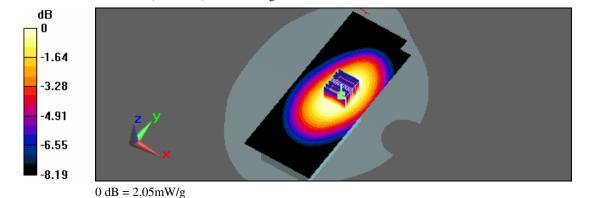
- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(9.4, 9.4, 9.4); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### Flat/Area Scan (61x151x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 2.55 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 56.4 V/m; Power Drift = -0.061 dB Peak SAR (extrapolated) = 2.6 W/kgSAR(1 g) = 1.79 mW/g; SAR(10 g) = 1.22 mW/gMaximum value of SAR (measured) = 2.05 mW/g



Report Number: 1201FS13 Page 39 of 74



Date/Time: 1/5/2012 10:45:04 AM

### Flat GMRS CH4 Front surface to phantom 15mm Alkaline

#### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: GMRS; Frequency: 462.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 462.6375 MHz;  $\sigma = 0.884 \text{ mho/m}$ ;  $\varepsilon_r = 44.1$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(9.4, 9.4, 9.4); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### Flat/Area Scan (61x151x1):

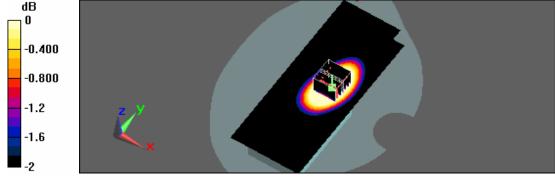
Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 1.71 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 48.4 V/m; Power Drift = -0.183 dB Peak SAR (extrapolated) = 1.53 W/kg

SAR(1 g) = 1.14 mW/g; SAR(10 g) = 0.804 mW/gMaximum value of SAR (measured) = 1.3 mW/g



0 dB = 1.3 mW/g

Report Number: 1201FS13 Page 40 of 74



Date/Time: 1/5/2012 7:03:24 PM

### Flat\_GMRS CH4\_Back surface to phantom 15mm\_headset

### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: GMRS; Frequency: 462.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 462.6375 MHz;  $\sigma = 0.946$  mho/m;  $\varepsilon_r = 55.5$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

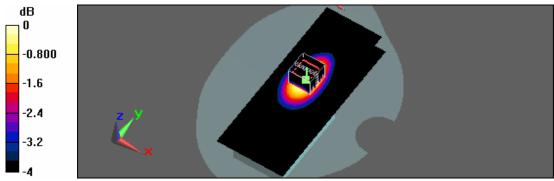
- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(10.05, 10.05, 10.05); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### Flat/Area Scan (61x151x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 3.28 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 56.3 V/m; Power Drift = 0.043 dB Peak SAR (extrapolated) = 4.58 W/kgSAR(1 g) = 2.58 mW/g; SAR(10 g) = 1.62 mW/gMaximum value of SAR (measured) = 3.04 mW/g



0 dB = 3.04 mW/g



Date/Time: 1/5/2012 10:45:32 PM

#### Flat\_GMRS CH4\_Back surface to phantom 15mm\_headset\_Alkaline

### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: GMRS; Frequency: 462.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 462.6375 MHz;  $\sigma = 0.946$  mho/m;  $\varepsilon_r = 55.5$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(10.05, 10.05, 10.05); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

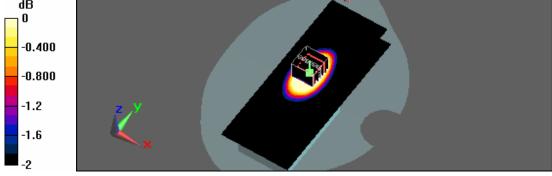
### Flat/Area Scan (61x151x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 1.54 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 45.6 V/m; Power Drift = -0.106 dB Peak SAR (extrapolated) = 1.56 W/kgSAR(1 g) = 0.999 mW/g; SAR(10 g) = 0.666 mW/g

Maximum value of SAR (measured) = 1.16 mW/g



0 dB = 1.16 mW/g

Report Number: 1201FS13 Page 42 of 74



Date/Time: 1/5/2012 8:53:57 PM

### Flat\_GMRS CH4\_Back surface to phantom 0mm\_belt clip\_headset

### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: GMRS; Frequency: 462.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 462.6375 MHz;  $\sigma = 0.946$  mho/m;  $\varepsilon_r = 55.5$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(10.05, 10.05, 10.05); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### Flat/Area Scan (61x151x1):

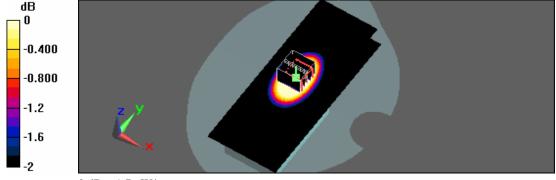
Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 2.25 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 55.1 V/m; Power Drift = -0.046 dB Peak SAR (extrapolated) = 2.28 W/kg

SAR(1 g) = 1.47 mW/g; SAR(10 g) = 0.987 mW/gMaximum value of SAR (measured) = 1.7 mW/g



0 dB = 1.7 mW/g

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Date/Time: 1/5/2012 4:22:56 AM

#### Flat FRS CH11\_Front surface to phantom 15mm

#### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: FRS; Frequency: 467.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 467.6375 MHz;  $\sigma = 0.887$  mho/m;  $\varepsilon_r = 44$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(9.4, 9.4, 9.4); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### Flat/Area Scan (61x151x1):

Measurement grid: dx=15mm, dy=15mm

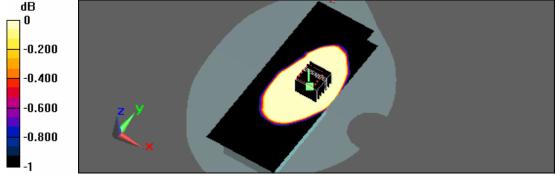
Maximum value of SAR (interpolated) = 0.029 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 6.44 V/m; Power Drift = -0.032 dB Peak SAR (extrapolated) = 0.014 W/kg

### SAR(1 g) = 0.00895 mW/g; SAR(10 g) = 0.00624 mW/g

Maximum value of SAR (measured) = 0.011 mW/g



0 dB = 0.011 mW/g

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Date/Time: 1/5/2012 3:18:09 AM

#### Flat\_FRS CH11\_Front surface to phantom 15mm\_Alkaline

### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: FRS; Frequency: 467.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 467.6375 MHz;  $\sigma = 0.887 \text{ mho/m}$ ;  $\varepsilon_r = 44$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(9.4, 9.4, 9.4); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### Flat/Area Scan (61x151x1):

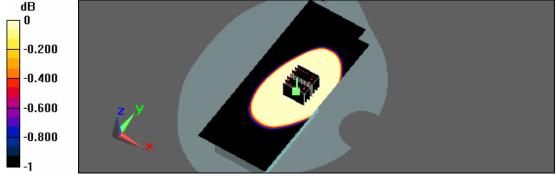
Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.144 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 14.8 V/m; Power Drift = -0.069 dB Peak SAR (extrapolated) = 0.062 W/kg SAR(1 g) = 0.049 mW/g; SAR(10 g) = 0.035 mW/g

Maximum value of SAR (measured) = 0.055 mW/g



0 dB = 0.055 mW/g

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Date/Time: 1/6/2012 12:13:54 AM

### Flat FRS CH11 Back surface to phantom 15mm headset

#### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: FRS; Frequency: 467.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 467.6375 MHz;  $\sigma = 0.951$  mho/m;  $\varepsilon_r = 55.4$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(10.05, 10.05, 10.05); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### Flat/Area Scan (61x151x1):

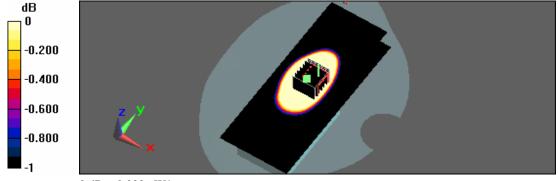
Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.053 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 7.94 V/m; Power Drift = -0.021 dB Peak SAR (extrapolated) = 0.040 W/kg

SAR(1 g) = 0.028 mW/g; SAR(10 g) = 0.020 mW/gMaximum value of SAR (measured) = 0.032 mW/g



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Date/Time: 1/6/2012 1:05:11 AM

### Flat\_FRS CH11\_Back surface to phantom 15mm\_headset\_Alkaline

### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: FRS; Frequency: 467.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 467.6375 MHz;  $\sigma = 0.951$  mho/m;  $\varepsilon_r = 55.4$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(10.05, 10.05, 10.05); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

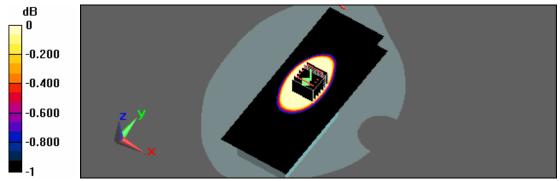
### Flat/Area Scan (61x151x1):

Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.088 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 10.2 V/m; Power Drift = 0.068 dB Peak SAR (extrapolated) = 0.069 W/kg SAR(1 g) = 0.050 mW/g; SAR(10 g) = 0.035 mW/gMaximum value of SAR (measured) = 0.056 mW/g



0 dB = 0.056 mW/g

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Date/Time: 1/5/2012 11:19:51 PM

### Flat FRS CH11 Back surface to phantom 0mm belt clip headset

#### DUT: MD200; Type: Two Way Radio with GMRS and FRS; FCC ID: K7GMDBJJ

Communication System: FRS; Frequency: 467.6375 MHz; Duty Cycle: 1:1

Medium parameters used: f = 467.6375 MHz;  $\sigma = 0.951$  mho/m;  $\varepsilon_r = 55.4$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC)

### DASY5 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: EX3DV4 SN3632; ConvF(10.05, 10.05, 10.05); Calibrated: 1/19/2011
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 1/31/2011
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 125;SEMCAD X Version 13.4 Build 125

### Flat/Area Scan (61x151x1):

Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.019 mW/g

### Flat/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 4.67 V/m; Power Drift = -0.172 dB Peak SAR (extrapolated) = 0.00987 W/kg

SAR(1 g) = 0.00523 mW/g; SAR(10 g) = 0.0033 mW/gMaximum value of SAR (measured) = 0.00669 mW/g



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### Appendix C - Calibration

All of the instruments Calibration information are listed below.

- Dipole \_ D450V2 SN:1021 Calibration No.D450V2-1021\_Feb11
- Probe \_ EX3DV4 SN:3632 Calibration No.EX3-3632\_Jan11
- DAE \_ DAE4 SN:779 Calibration No.DAE4-779\_Jan11

Report Number: 1201FS13 Page 49 of 74



## Calibration Laboratory of

Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA

Multilateral Agreement for the recognition of calibration certificates

Client ATL (Auden)

Accreditation No.: SCS 108

Certificate No: D450V2-1021\_Feb11

### CALIBRATION CERTIFICATE

Object

D450V2 - SN: 1021

Calibration procedure(s)

QA CAL-15.v5

Calibration Procedure for dipole validation kits below 800 MHz

Calibration date:

February 16, 2011

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID#	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	1-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41495277	1-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41498087	1-Apr-10 (No. 217-01136)	Apr-11
Reference 3 dB Altenustor	SN: S5054 (3c)	30-Mar-10 (No. 217-01159)	Mar-11
Reference 20 dB Attenuator	SN: S5085 (20b)	30-Mar-10 (No. 217-01161)	Mar-11
Type-N mismatch combination	SN: E047.3 / 06327	30-Mar-10 (No. 217-01162)	Mar-11
Reference Probe ET3DV6	SN: 1507	30-Apr-10 (No. ET3-1507_Apr10)	Apr-11
DAE4	SN: 654	23-Apr-10 (No. DAE4-654_Apr10)	Apr-11
Secondary Standards	ID#	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	04-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (in house check Oct-10)	In house check: Oct-11
	Name	Function	Signature
Calibrated by:	Jeton Kastrati	Laboratory Technician	f= (C
Approved by:	Kalja Pokovic	Technical Manager	0010

Issued: February 16, 2011

Certificate No: D450V2-1021\_Feb11

Page 1 of 9

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



### Calibration Laboratory of

Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kallbrierdienst
C Service suisse d'étalonnage
Servizio svizzero di taratura
Swiss Calibration Service

Accreditation No.: SCS 108

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA

Multilateral Agreement for the recognition of calibration certificates

#### Glossary:

TSL tissue simulating liquid

ConF sensitivity in TSL / NORM x,y,z N/A not applicable or not measured

### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

### Additional Documentation:

d) DASY4/5 System Handbook

### Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end
  of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed
  point exactly below the center marking of the flat phantom section, with the arms oriented
  parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole
  positioned under the liquid filled phantom. The impedance stated is transformed from the
  measurement at the SMA connector to the feed point. The Return Loss ensures low
  reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point.
   No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

Certificate No: D450V2-1021\_Feb11 Page 2 of 9



### Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.6
Extrapolation	Advanced Extrapolation	
Phantom	Flat Phantom V4.4	Shell thickness: 6 ± 0.2 mm
Distance Dipole Center - TSL	15 mm	with Spacer
Area Scan Resolution	dx, dy = 15 mm	
Zoom Scan Resolution	dx, $dy$ , $dz = 5 mm$	
Frequency	450 MHz ± 1 MHz	

Head TSL parameters
The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	43.5	0.87 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	43.6 ± 6 %	0.83 mho/m ± 6 %
Head TSL temperature during test	(22.0 ± 0.2) °C	****	****

### SAR result with Head TSL

SAR averaged over 1 cm3 (1 g) of Head TSL	condition	
SAR measured	398 mW input power	1.89 mW / g
SAR normalized	normalized to 1W	4.75 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	4.93 mW / g ± 18.1 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	condition	
SAR measured	398 mW input power	1.26 mW / g
SAR normalized	normalized to 1W	3.17 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	3.27 mW / g ± 17.6 % (k=2)



Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	56.7	0.94 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	53.9 ± 6 %	0.90 mho/m ± 6 %
Body TSL temperature during test	(22.0 ± 0.2) °C	****	

### SAR result with Body TSL

SAR averaged over 1 cm3 (1 g) of Body TSL	condition	
SAR measured	398 mW input power	1.82 mW / g
SAR normalized	normalized to 1W	4.57 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	4.68 mW / g ± 18.1 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	candition	
SAR measured	398 mW input power	1.21 mW / g
SAR normalized	normalized to 1W	3.04 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	3.11 mW / g ± 17.6 % (k=2)



### Appendix

### Antenna Parameters with Head TSL

Impedance, transformed to feed point	57.6 Ω - 4.5 jΩ	
Return Loss	- 21.7 dB	

### Antenna Parameters with Body TSL

Impedance, transformed to feed point	54.6 Ω - 8.5 jΩ	
Return Lass	- 20.7 dB	

### General Antenna Parameters and Design

Electrical Delay (one direction)	1.352 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

### Additional EUT Data

Manufactured by	SPEAG
Manufactured on	February 04, 2004

Certificate No: D450V2-1021\_Feb11



### DASY5 Validation Report for Head TSL

Date/Time: 16.02.2011 10:51:29

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 450 MHz; Type: D450V2; Serial: D450V2 - SN:1021

Communication System: CW; Frequency: 450 MHz; Duty Cycle: 1:1

Medium: HSL450

Medium parameters used: f = 450 MHz;  $\sigma = 0.83 \text{ mho/m}$ ;  $\varepsilon_r = 43.6$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

### DASY5 Configuration:

Probe: ET3DV6 - SN1507; ConvF(6.62, 6.62, 6.62); Calibrated: 30.04.2010

Sensor-Surface: 4mm (Mechanical Surface Detection)

Electronics: DAE4 Sn654; Calibrated: 23.04.2010

Phantom: Flat Phantom 4.4; Type: Flat Phantom 4.4; Serial: 1002

Measurement SW: DASY52, V52.6.1 Build (408)

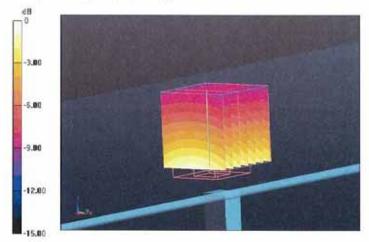
Postprocessing SW: SEMCAD X, V14.4.2 Build (2595)

# Pin=398mW /d=15mm, /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 50.454 V/m; Power Drift = -0.03 dB

Peak SAR (extrapolated) = 2.903 W/kg

SAR(1 g) = 1.89 mW/g; SAR(10 g) = 1.26 mW/gMaximum value of SAR (measured) = 2.023 mW/g



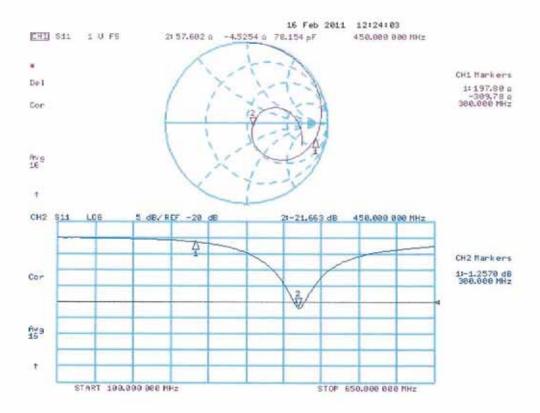
0 dB = 2.020 mW/g

Certificate No: D450V2-1021\_Feb11

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### Impedance Measurement Plot for Head TSL



Certificate No: D450V2-1021\_Feb11

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### DASY5 Validation Report for Body TSL

Date/Time: 15.02.2011 16:16:45

Test Laboratory: SPEAG, Zurich, Switzerland

### DUT: Dipole 450 MHz; Type: D450V2; Serial: D450V2 - SN:1021

Communication System: CW; Frequency: 450 MHz; Duty Cycle: 1:1

Medium: MSL450

Medium parameters used: f = 450 MHz;  $\sigma = 0.9 \text{ mho/m}$ ;  $\epsilon_r = 53.9$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

#### DASY5 Configuration:

Probe: ET3DV6 - SN1507; ConvP(7.2, 7.2, 7.2); Calibrated: 30.04,2010

Sensor-Surface: 4mm (Mechanical Surface Detection)

Electronics: DAB4 Sn654; Calibrated: 23.04.2010

Phantom: Flat Phantom 4.4; Type: Flat Phantom 4.4; Serial: 1002

Measurement SW: DASY52, V52.6.1 Build (408)

Postprocessing SW; SEMCAD X, V14.4.2 Build (2595)

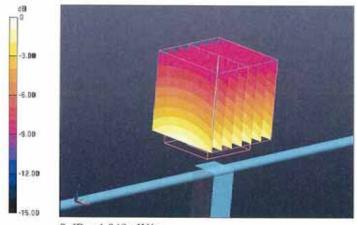
### Pin=398mW /d=15mm /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 46.922 V/m; Power Drift = -0.02 dB

Peak SAR (extrapolated) = 2.856 W/kg

SAR(1 g) = 1.82 mW/g; SAR(10 g) = 1.21 mW/gMaximum value of SAR (measured) = 1.939 mW/g

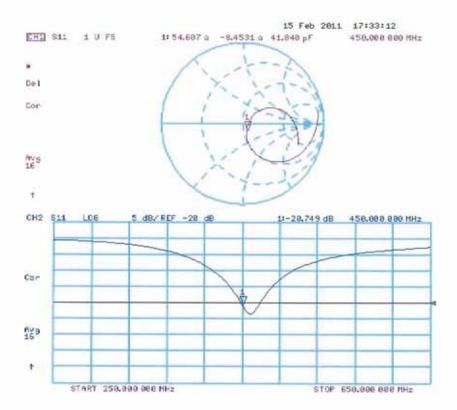


0 dB = 1.940 mW/g

Certificate No: D450V2-1021\_Feb11



### Impedance Measurement Plot for Body TSL



Certificate No: D450V2-1021\_Feb11

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Client

ATL (Auden)

Accreditation No.: SCS 108

Certificate No: EX3-3632\_Jan11

C

CALIBRATION CERTIFICATE

EX3DV4 - SN:3632 Object

QA CAL-01.v7, QA CAL-12.v6, QA CAL-23.v4 and QA CAL-25.v3 Calibration procedure(s)

Calibration procedure for dosimetric E-field probes

Calibration date: January 19, 2011

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The messurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	10#	Cal Date (Certificate No.)	Scheduled Calibration
Power mater E4419B	GB41293874	1-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41495277	1-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41498087	1-Apr-10 (No. 217-01136)	Apr-11
Reference 3 dB Attenuator	SN: S5054 (3c)	30-Mar-10 (No. 217-01159)	Mar-11
Reference 20 dB Attenuator	SN: S5086 (20b)	30-Mar-10 (No. 217-01161)	Mar-11
Reference 30 dB Attenuator	SN; S5129 (30b)	30-Mar-10 (No. 217-01160)	Mar-11
Reference Probe ES3DV2	SN: 3013	29-Dec-10 (No. ES3-3013_Dec10)	Dec-11
DAE4	SN: 660	20-Apr-10 (No. DAE4-660_Apr10)	Apr-11
Secondary Standards	ID#	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-10)	In house check: Oct-11
	Name	Function	Signature
Calibrated by	Jeton Kastrati	Laboratory Technician	7-12
Approved by:	Katja Pokovic	Technical Manager	THE.

Certificate No. EX3-3632\_Jan11

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Accreditation No.: SCS 108

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#### Glossary:

TSL tissue simulating liquid
NORMx,y,z sensitivity in free space
ConvF sensitivity in TSL / NORMx,y,z
DCP diode compression point

CF crest factor (1/duty\_cycle) of the RF signal A, B, C modulation dependent linearization parameters

Polarization φ rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., 9 = 0 is normal to probe axis

### Calibration is Performed According to the Following Standards:

- EEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- Techniques", December 2003
  b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

#### Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization 9 = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
   NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z \* frequency\_response (see Frequency Response Chart). This linearization is
  implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included
  in the stated uncertainty of ConvF.
- DCPx,y,z, DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- Ax.y.z; Bx.y.z; Cx.y.z, VRx.y.z: A, B, C are numerical linearization parameters assessed based on the data of
  power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the
  maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z \* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset. The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

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# Probe EX3DV4

SN:3632

Manufactured: November 1, 2007 Last calibrated: January 26, 2010 Recalibrated: January 19, 2011

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

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Report Number: 1201FS13 Page 61 of 74



### DASY/EASY - Parameters of Probe: EX3DV4 SN:3632

### **Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (μV/(V/m) <sup>2</sup> ) <sup>A</sup>	0.46	0.44	0.39	± 10.1%
DCP (mV) <sup>B</sup>	97.4	94.9	97.4	

### **Modulation Calibration Parameters**

UID	Communication System Name	PAR		A dB	B dBuV	С	VR mV	Unc <sup>E</sup> (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	133.3	± 3.4 %
			Υ	0.00	0.00	1.00	110.0	
			Z	0.00	0.00	1.00	125.1	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

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<sup>\*</sup> The uncertainties of NormX Y.Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Pages 5 and 6).

<sup>8</sup> Numerical inearization parameter; uncertainty not required.

E Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.



### DASY/EASY - Parameters of Probe: EX3DV4 SN:3632

### Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz]	Validity [MHz] <sup>C</sup>	Permittivity	Conductivity	ConvF X Co	nvFY C	onvF Z	Alpha	Depth Unc (k=2)
450	± 50 / ± 100	$43.5\pm5\%$	$0.87 \pm 5\%$	9.40	9.40	9.40	0.12	2.85 ± 13.3%
750	±50/±100	41.9 ± 5%	0.89 ± 5%	9.51	9.51	9.51	0.67	0.64 ± 11.0%
835	± 50 / ± 100	41.5 ± 5%	$0.90 \pm 5\%$	9.09	9.09	9.09	0.66	0.64 ± 11.0%
1810	± 50 / ± 100	40.0 ± 5%	$1.40 \pm 5\%$	8.16	8.16	8.16	0.51	0.74 ± 11.0%
1900	± 50 / ± 100	40.0 ± 5%	$1.40 \pm 5\%$	8.02	8.02	8.02	0.58	0.68 ± 11.0%
2450	± 50 / ± 100	39.2 ± 5%	$1.80 \pm 5\%$	7.28	7.28	7.28	0.33	0.91 ± 11.0%

E The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

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### DASY/EASY - Parameters of Probe: EX3DV4 SN:3632

### Calibration Parameter Determined in Body Tissue Simulating Media

f [MHz]	Validity [MHz] <sup>C</sup>	Permittivity	Conductivity	ConvF X C	ConvF Y	ConvF Z	Alpha	Depth Unc (k=2)
450	$\pm 50 / \pm 100$	$56.7 \pm 5\%$	$0.94 \pm 5\%$	10.05	10.05	10.05	0.05	1.80 ± 13.3%
750	±50/±100	$55.5\pm5\%$	$0.96 \pm 5\%$	9.33	9.33	9.33	0.78	0.63 ± 11.0%
835	±50/±100	55.2 ± 5%	$0.97 \pm 5\%$	9.28	9.28	9.28	0.73	0.66 ± 11.0%
1810	±50/±100	$53.3 \pm 5\%$	1.52 ± 5%	7.57	7.57	7.57	0.83	0.60 ± 11.0%
1900	± 50 / ± 100	$53.3 \pm 5\%$	1.52 ± 5%	7.39	7.39	7.39	0.67	0.65 ± 11.0%
2450	± 50 / ± 100	52.7 ± 5%	1.95 ± 5%	7.23	7.23	7.23	0.28	1.07 ± 11.0%

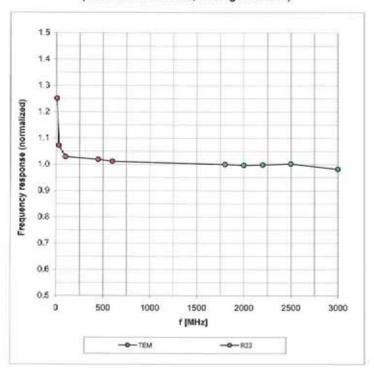
<sup>&</sup>lt;sup>2</sup> The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

Certificate No: EX3-3632\_Jan11



### Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)



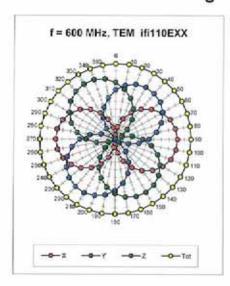
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

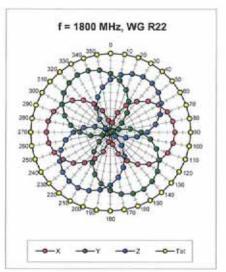
Certificate No: EX3-3632\_Jan11

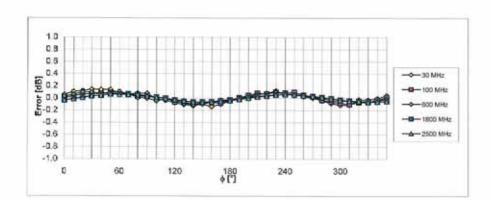
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# Receiving Pattern ( $\phi$ ), $\vartheta = 0^{\circ}$







Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

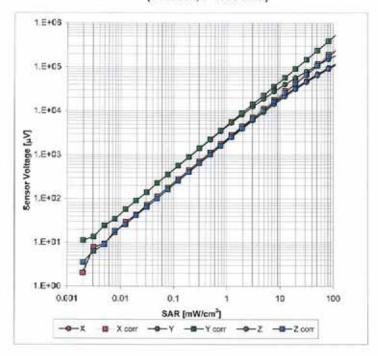
Certificate No: EX3-3632\_Jan11

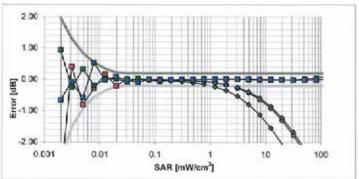
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### Dynamic Range f(SAR<sub>head</sub>)

(TEM cell, f = 900 MHz)





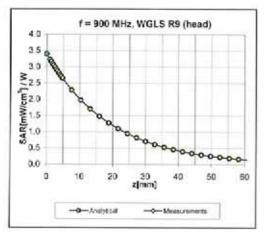
Uncertainty of Linearity Assessment: ± 0.6% (k=2)

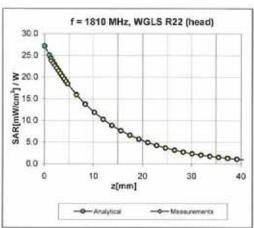
Certificate No: EX3-3632\_Jan11

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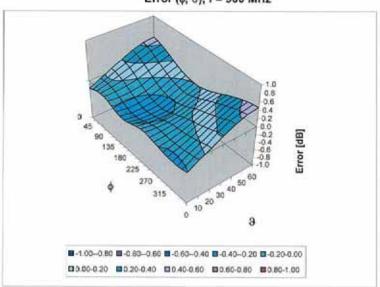
### Conversion Factor Assessment





### Deviation from Isotropy in HSL

Error (φ, θ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Certificate No: EX3-3632\_Jan11

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### Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (*)	Not applicable
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	2 mm

Certificate No: EX3-3632\_Jan11

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Accreditation No.: SCS 108

DAE4 - SD 000 D04 BJ - SN; 779  Calibration procedure(s)  Calibration procedure(s)  Calibration procedure for the data acquisition electronics (DAE)  Calibration certificate documents life traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.   All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.   Calibration Equipment used (M&TE critical for calibration)  Primary Standards  ID # Cal Date (Certificate No.) Scheduled Celibration Secondary Standards  ID # Check Date (in house) Scheduled Celibration Secondary Standards  ID # Check Date (in house) Scheduled Check Calibrator Box V1.1 SE UMS 006 AB 1004 07-Jun-10 (in house check) In house check: Jun-11  Page Calibrator Box V1.1 SE UMS 006 AB 1004 07-Jun-10 (in house check)  Name Function Signature  Ancrea Guntil Technician	lient ATL (Auden)		Ce	rtificate No: DAE4-779_Jan11
Calibration procedure(s)  QA CAL-06.v22 Calibration procedure for the data acquisition electronics (DAE)  allibration date:  January 31, 2011  his calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI), he measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.  It calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.  It calibrations Equipment used (M&TE critical for calibration)  In all bration Equipment used (M&TE critical for calibration)  Scheduled Calibration eithery Multimeter Type 2001  SN: 0810278  28-Sep-10 (No:10376)  Sep-11  Scheduled Calibration  Scheduled Check  Diff Check Date (in house)  Scheduled Check  In house check: Jun-11  Name  Function  Signature  Andrea Guntili  Technician	ALIBRATION O	CERTIFICATE		ALTERNATION VIOLENT
Calibration procedure for the data acquisition electronics (DAE)  alibration date:  January 31, 2011  his calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI), the measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.  It calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.  all tration Equipment used (M&TE critical for calibration)  himary Standards  ID # Cal Date (Certificate No.) Scheduled Calibration eithley Multimeter Typa 2001 SN: 0810278 28-Sep-10 (No:10376) Sep-11  secondary Standards  ID # Check Date (in house) Scheduled Check allbrator Box V1.1 SE UMS 006 AB 1004 07-Jun-10 (in house check) In house check: Jun-11  Name Function Signature  Andrea Suntil Technician	<b>b</b> ject	DAE4 - SD 000 D	04 BJ - SN; 779	
his calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.  If calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.  If calibrations is a calibration of the certificate of t	Calibration procedure(s)		dure for the data acquisi	tion electronics (DAE)
the measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.  If calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.  It is calibration Equipment used (M&TE critical for calibration)  It is calibrated by:  ID # Cal Date (Certificate No.) Scheduled Calibration  Septimary Standards  ID # Check Date (in house) Scheduled Check  In house check: Jun-11  In house check: Jun-11  Name Function Signature  Andrea Guntil Technician  Name Function  Fin Bemholt R&D Director  Fin Bemholt R&D Director	fallbration date:	January 31, 2011		
Ceithley Multimeter Type 2001 SN: 0810278 28-Sep-10 (No:10376) Sep-11 Secondary Standards ID # Check Date (in house) Scheduled Check Calibrator Box V1.1 SE UMS 006 AB 1004 07-Jun-10 (in house check) In house check: Jun-11  Name Function Signature Calibrated by: Anchea Guntil Technician	The measurements and the unce All calibrations have been conduct Calibration Equipment used (M&T	rtainties with confidence protected in the closed laboratory	obability are given on the following facility: environment temperature	g pages and are part of the certificate. e (22 ± 3)°C and humidity < 70%.
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				Issued: January 31, 2011

Certificate No: DAE4-779\_Jan11

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Glossary

DAE data acquisition electronics

Connector angle information used in DASY system to align probe sensor X to the robot

coordinate system.

### Methods Applied and Interpretation of Parameters

 DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.

- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
  - Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
  - AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
  - Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
  - Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - Input resistance: Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
  - Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
  - Power consumption: Typical value for information. Supply currents in various operating modes.

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### DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB =  $6.1\mu V$ , full range = -100...+300 mVLow Range: 1LSB = 61nV, full range = -1......+3mVDASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	x	Y	Z
High Range	404.517 ± 0.1% (k=2)	403.748 ± 0.1% (k=2)	403.972 ± 0.1% (k=2)
Low Range	3.96927 ± 0.7% (k=2)	3.98585 ± 0.7% (k=2)	3.99915 ± 0.7% (k=2)

### Connector Angle

Connector Angle to be used in DASY system 155.5 ° ± 1 °
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### Appendix

1. DC Voltage Linearity

High Range	Reading (µV)	Difference (μV)	Error (%)	
Channel X + Input	200001.8	6.19	0.00	
Channel X + Input	20003.75	4.25	0.02	
Channel X - Input	-19996.56	3.04	-0.02	
Channel Y + Input	200005.0	0.90	0.00	
Channel Y + Input	20000.78	1.38	0.01	
Channel Y - Input	-19996.43	2.97	-0.01	
Channel Z + Input	200002.2	-1.15	-0.00	
Channel Z + Input	19999.59	0.19	0.00	
Channel Z - Input	-19995.05	4.35	-0.02	

Low Range	Reading (μV)	Difference (µV)	Error (%)
Channel X + Input	2000.4	0.25	0.01
Channel X + Input	200.27	0.37	0.18
Channel X - Input	-199.08	1.12	-0.56
Channel Y + Input	2000.1	0.19	0.01
Channel Y + Input	199.01	-0.89	-0.45
Channel Y - Input	-199.30	0.50	-0.25
Channel Z + Input	1999.6	-0.40	-0.02
Channel Z + Input	199.22	-0.88	-0.44
Channel Z - Input	-200.27	-0.37	0.19

2. Common mode sensitivity
DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	-3.66	-5.39
	- 200	5.82	4.90
Channel Y	200	13.39	13,58
	- 200	-14.98	-15.16
Channel Z	200	2.20	2.53
	- 200	-4.84	-4.61

### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (µV)	Channel Y (µV)	Channel Z (μV)
Channel X	200	· ·	1.33	-0.57
Channel Y	200	1.97		3.29
Channel Z	200	1.19	-0.28	

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### 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15613	15134
Channel Y	15831	16218
Channel Z	16150	17743

### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec Input  $10 M\Omega$ 

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (µV)
Channel X	-0.26	-1.03	0.79	0.42
Channel Y	0.52	-1.04	2.07	0.58
Channel Z	-2.22	-3.25	-0.85	0.44

### 6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)	
Supply (+ Vcc)	+7.9	
Supply (- Vcc)	-7.6	

9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9

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