

ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH

# **TEST - REPORT**

**SAR Compliance Test Report** 

Test report no.:

G5M206020032-S-8





ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH STORKOWER STRASSE 38C, PHONE +49-33631-888 00 D-15526 REICHENWALDE B. BERLIN FAX +49-33631-888 660

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### **1** General Information

#### 1.1 Notes

The purpose of conformity testing is to increase the probability of adherence to the essential requirements or conformity specifications, as appropriate.

The complexity of the technical specifications, however, means that full and thorough testing is impractical for both technical and economic reasons.

Furthermore, there is no guarantee that a test sample which has passed all the relevant tests conforms to a specification.

The existence of the tests nevertheless provides the confidence that the test sample possesses the qualities as maintained and that is performance generally conforms to representative cases of communications equipment.

The test results of this test report relate exclusively to the item tested as specified in 1.5.

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I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualification of all persons taking them.

#### **Tester:**

18.04.2006

M. Cersovsky

i.s. Thur &

Date

ETS-Lab. Name

Signature

#### Technical responsibility for area of testing:

Unbert Kaspar 18.04.2006 N. Kaspar ETS Signature Date Name



#### **1.2** Testing laboratory

#### 1.2.1 Location

ELECTRONIC TECHNOLOGY SYSTEM DR. GENZ GMBH (ETS) Storkower Straße 38c D-15526 Reichenwalde b. Berlin Germany Telephone : +49 33631 888 00 Fax : +49 33631 888 660

#### **1.2.2** Details of accreditation status

ACCREDITED TESTING LABORATORY DAR-registration number: DAT-P-201/96

FCC FILED TEST LABORATORY REG. NO. 96970

#### **BLUETOOTH QUALIFICATION TEST FACILITY (BQTF)**

ACCREDITED BY BLUETOOTH QUALIFICATION REVIEW BOARD

#### **INDUSTRY CANADA FILED TEST LABORATORY REG.** No. IC 3470

A2LA ACCREDITED Certificate Number 1983-01

#### **1.3** Details of approval holder

Name	: Pantech Co., Ltd.
Street	: Shinsong Center Bldg. 8th Fl., 25-12, Yeouido-dong
Town	: Yeoungdeungpo-gu, Seoul
Country	: Korea
Telephone	: +82-2-3660-5862
Fax	: +82-2-3660-5990
Contact	: Mr. B.W. Kim
E-Mail	: bwkim@pantech.co.kr

## **1.4 Manufacturer**: (if applicable)

Name	:
Street	:
Town	:
Country	:



#### **1.5** Application details

Date of receipt of application	: 03.03.2006
Date of receipt of test item	: 03.03.2006
Date of test	: 14.03.2006 - 15.03.2006

#### 1.6 Test item

FCC ID	: JYCPG-3700		
Description of test item	: Triple Band GSM 900 (E-GSM)/DCS 1800 /PCS 1900 (with WAP & GPRS)		
Type identification	: PG-3700		
Serial number	: without; Identical prototype		
Device category	: PCB (Licensed Base Station)		
Technical data			
TX Frequency range	: 1850,2 - 1909,8 MHz		
RX Frequency range	: 1930,2 - 1989,8 MHz		
Max. Conducted RF output power	: PCS 1900 / 30,26 dBm (1061,7 mW)		
Power supply	: 3,8 V DC rechargeable battery		
Antenna Tx	: integral		
Antenna RX	: integral		
Additional information	<ul> <li>Tx and Rx. antenna are the same.</li> <li>This procedure is requested by customer. This device conta 900 MHz and 1800 MHz GSM functions not operational U. S. Territories. This filing is only applicable for 1900 M PCS operations.</li> </ul>	in	

#### **1.7** Test Results

Max. SAR Measurement (Head)	: 1.15 W/kg (averaged over 1 gram)
Max. SAR Measurement (Body	: 1.15 W/kg (averaged over 1 gram)

This EUT has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC/OET Bulletin 65 Supplement C (2001) and IEEE Std. 1528-2003, December 2003.



#### **1.8** Test standards

Standards	:	-	IEEE Std. 1528-2003, December 2003
FCC Rule Part(s)	:	-	FCC OET Bulletin 65, Supplement C, Edition 01-01

#### 2 Technical test

#### 2.1 Summary of test results

#### **Applicable Configuration**

Handset (Head)	X
Handset (Body)	X
Headset (Head)	
Body Worn Equipment	

EUT complies with the RF radiation exposure limits of the FCC as shown by the SAR measurement results. These measurements are taken to simulate the RF effects exposure under worst-case conditions. The EUT complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease). Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables. [1]

In case of multiple hotspots the secondary hotspots within 2dB of the maximum SAR value will be recorded and displayed in the measurement plots. The secondary hotspots with a peak SAR value below 0.5 W/kg will not be measured by the system, due to the high margin to the limits.

#### 2.2 Test environment

Room temperature	: 22,1 -22,6 ° C
Liquid temperature	: 22,0 -22,3 ° C
Relative humidity content	: 20 75 %
Air pressure	: 86 103 k P a
Details of power supply	: 3,8 V DC



# 2.3 Test equipment utilized

No.	Measurement device:	Type:	Manufacturer:
ETS 0449	Stäubli Robot	RX90B L	Stäubli
ETS 0450	Stäubli Robot Controller	CS/MBs&p	Stäubli
ETS 0451	DASY 4 Measurement Server		Schmid & Partner
ETS 0452	Control Pendant		Stäubli
ETS 0453	Compaq Computer	Pentium IV, 2 GHz,	Schmid & Partner
ETS 0454	Dabu Acquisition Electronics	DAE3V1	Schmid & Partner
ETS 0455	Dummy Probe		Schmid & Partner
ETS 0456	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner
ETS 0457	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner
ETS 0458	Dosimetric H-Field Probe	H3DV6	Schmid & Partner
ETS 0459	System Validation Kit	D900V2	Schmid & Partner
ETS 0460	System Validation Kit	D1800V2	Schmid & Partner
ETS 0461	System Validation Kit	D1900V2	Schmid & Partner
ETS 0462	System Validation Kit	D2450V2	Schmid & Partner
ETS 0463	Probe Alignment Unit	LBV2	Schmid & Partner
ETS 0464	SAM Twin phantom	V 4.0	Schmid & Partner
ETS 0465	Mounting Device	V 3.1	Schmid & Partner
ETS 0224a	Millivoltmeter	URV 5	Rohde & Schwarz
ETS 0219	Power sensor	NRV-Z2	Rohde & Schwarz
ETS 0268	RF signal generator	SMP 02	Rohde & Schwarz
ETS 0322	Insertion unit	URV5-Z4	Rohde & Schwarz
ETS 0466	Directional Coupler	HP 87300B	HP
ETS0231	Radio Communication Tester	CMD65	Rohde & Schwarz
ETS 0467	Universal Radio Communication Tester	CMU 200	Rohde & Schwarz
ETS 0468	Network Analyzer 300 kHz to 3 GHz	8753C	Agilent
ETS 0469	Dielectric Probe Kit	85070C	Agilent



#### 2.4 Definitions

#### 2.4.1 SAR

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density ( $\rho_t$ ), expressed in watts per kilogram (W/kg)

SAR = 
$$\frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho_t dV} \right) = \frac{\sigma}{\rho_1} \left| E_t \right|^2$$

where:

$$\frac{dW}{dt} = \int_{V} E \cdot J \, dV = \int_{V} \sigma E^2 dV$$

#### 2.4.2 Uncontrolled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category, and the general population/uncontrolled exposure limits apply to these devices. [2]

#### 2.4.3 Controlled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on the risk of potential exposure risks. [2]



#### 2.5 Measurement System Description

#### 2.5.1 System Setup

Measurements are performed using the DASY4 automated dosimetric assessment system (figure 1) made by Schmid & Partner Engineering AG (SPEAG)in Zurich, Switzerland.

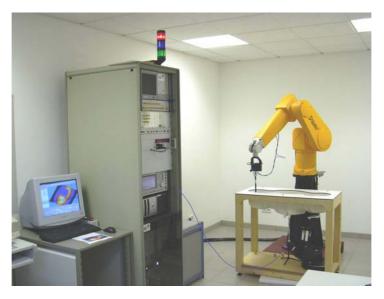


Figure 1

The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- An unit to operate the optical surface detector which is connected to the EOC.
- The Electro-optical converter (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the measurement server.
- The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows NT.
- DASY4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes (see Application Notes).
- System validation dipoles allowing to validate the proper functioning of the system.



#### 2.5.2 Phantom Description



Figure 2

The SAM twin phantom V4.0 (figure 2) is a fiberglass shell phantom with 2 mm shell thickness. It has three measurement areas:

- Left hand
- Right hand
- Flat phantom

The phantom is integrated in a wooden table.

The bottom plate of the table contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids).

A cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible.

On the phantom top, three reference markers are provided to identify the phantom positions with respect to the robot.

#### 2.5.3 Tissue Simulating Liquids

The parameters of the tissue simulating liquid strongly influence the SAR. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE P1528-2003, December 2003).

Head			Body		
Frequency (MHz)	Relative Dielectric Constant (ε <sub>r</sub> )	Conductivity (σ) (S/m)	Relative Dielectric Constant (ε <sub>r</sub> )	Conductivity (σ) (S/m)	
300	45.3	0.87	58.2	0.92	
450	43.5	0.87	56.7	0.94	
835	41.5	0.90	55.2	0.97	
900	41.5	0.97	55.0	1.05	
1450	40.5	1.20	54.0	1.30	
1800	40.0	1.40	53.3	1.52	
1900	40.0	1.40	53.3	1.52	
2000	40.0	1.40	53.3	1.52	
2450	39.2	1.80	52.7	1.95	
3000	38.5	2.40	52.0	2.73	

Tissue dielectric properties



#### 2.5.4 Device Holder

The DASY device holder (figure 3.1 and 3.2) is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The rotation centers for both scales is the ear opening. Thus the device needs no repositioning when changing the angles.



Figure 3.1

Figure 3.2

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

#### 2.5.5 Probes

The SAR measurements were conducted with the dosimetric probe ET3DV6 (figure 4), designed in the classical triangular configuration and optimized for dosimetric evaluation. [3] The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2<sup>nd</sup> order fitting. The approach is stopped at reaching the maximum.



Figure 4



## Probe Specifications

Calibration:	In air from 10 MHz to 2.5 GHz In brain and muscle simulating tissue at Frequencies of 835 MHz, 900 MHz, 1800 MHz, 1900 MHz and 2450 MHz Calibration certificates please find attached.
Frequency:	10 MHz to $>$ 3 GHz; Linearity: $\pm$ 0.2 dB (30 MHz to 3 GHz)
Directivity:	$\pm$ 0.2 dB in HSL (rotation around probe axis) $\pm$ 0.4 dB in HSL (rotation normal probe axis)
Dynamic Range:	5 $\mu$ W/g to > 100 mW/g;
Linearity:	$\pm 0.2 \text{ dB}$
Dimensions:	Overall length: 330 m Tip length: 16 mm Body diameter: 12 mm Tip diameter: 6.8 mm Distance from probe tip to dipole centers: 2.7 mm
Application:	General dosimetry up to 3 GHz Compliance tests of mobile phones Fast automatic scanning in arbitrary phantoms

## 2.6 Test System Specification

Positioner	
Robot:	Stäubli Animation Corp. Robot Model: RX90B L
Repeatability:	0.02 mm
No. of axis:	6

#### Data Acquisition Electronic (DAE) System Cell Controller

Pentium IV
2.0 GHz
Windows 2000
DASY4 PC-Board
Signal Amplifier, multiplexer, A/D converter, & control logic
DASY4 software
Optical downlink for data and status info.
Optical uplink for commands and clock
24 bit (64 MHz) DSP for real time processing
Link to DAE3
16 bit A/D converter for surface detection system
serial link to robot
direct emergency stop output for robot



#### **E-Field Probes**

Model: Construction: Frequency: Linearity:

Phantom

Phantom: Shell Material: Thickness: ET3DV6 SN1711 Triangular core fiber optic detection system 10 MHz to 6 GHz ± 0.2 dB (30MHz to 3 GHz)

SAM Twin Phantom (V4.0) Fiberglass  $2.0 \pm 0.2 \text{ mm}$ 

#### 2.7 Measurement Procedure

The evaluation was performed using the following procedure:

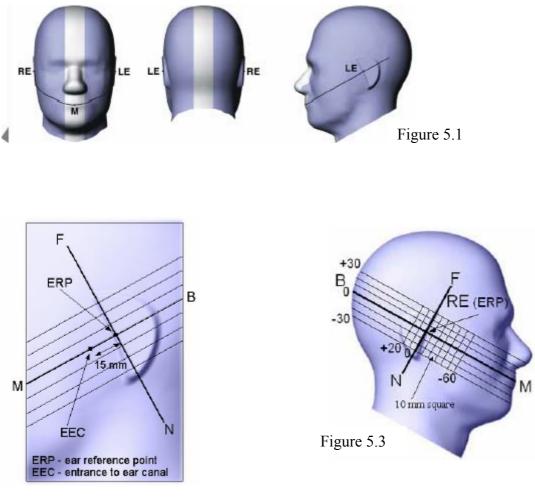
- 1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing. This fixed location point was measured and used as a reference value.
- 2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 10mm x 10mm.
- 3. Based on the area scan data, the area of the maximum absorption was determined by spline interpolation. Around this point, a volume of 30mm x 30mm x 30mm (fine resolution volume scan, zoom scan) was assessed by measuring 5 x 5 x 5 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure:
  - a. The data at the surface was extrapolated, since the center of the dipoles is 2.7mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2mm. The extrapolation was based on a least square algorithm [4]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
  - b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y, and z directions) [4] [5]. The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
  - c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
- 4. The SAR reference value, at the same location as procedure #1, was re-measured. If the value changed by more than 5%, the evaluation is repeated.



#### **2.8** Reference Points

#### **2.8.1** Ear Reference Points

Figure 5.1 shows the front, back and side vies of SAM. The point "M" is the reference point for the center of mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15 mm posterior to the entrance to ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 5.2. The plane passing through the two ear reference points and M is defined as the Reference Plane. The line N-F (Neck-Front) perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 5.3). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines should be marked on the external phantom shell to facilitate handset positioning. Posterior to the N-F line, the thickness of the N-F line, the ear is truncated as illustrated in Figure 5.2. The ear truncation is introduced to avoid the handset from touching the ear lobe, which can cause unstable handset positioning at the cheek. [6]

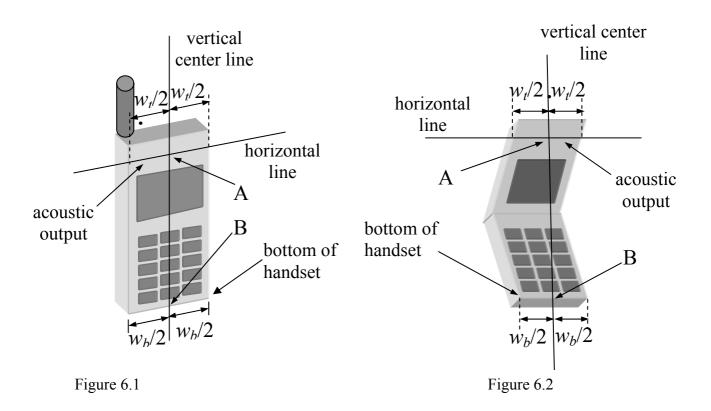






#### 2.8.2 Handset Reference Points

Two imaginary lines on the handset were defined: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width  $w_t$  of the handset at the level of the acoustic output (point A on Figures 6.1 and 6.2), and the midpoint of the width wb of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 6.1). The two lines intersect at point A. For many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. The vertical centerline is not necessarily parallel to the front face of the handset (see Figure 6.2), especially for clamshell handsets, handsets with flip pieces, and other irregularly-shaped handsets. [6]





#### 2.9 Test Positions

#### 2.9.1 "Cheek" / "Touch" Position

The EUT was positioned close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 7), such that the plane defined by the vertical center line and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.

The EUT was translated towards the phantom along the line passing through RE and LE until the handset touches the pinna.

While maintaining the handset in this plane, the EUT was rotated it around the LE-RE line until the vertical centerline was in the plane normal to MB-NF including the line MB (called the reference plane).

The EUT was rotated around the vertical centerline until the handset (horizontal line) was symmetrical with respect to the line NF.

While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the handset contact with the pinna, the EUT was rotated about the line NF until any point on the handset was in contact with a phantom point below the pinna (cheek). [6] See Figure 7.



Figure 7

# EIS

#### 2.9.2 "Tilted" Position

#### The EUT was in "cheek position".

While maintaining the orientation of the handset move the handset away from the pinna along the line passing through RE and LE in order to enable a rotation of the handset by 15 degrees.

The EUT was rotated around the horizontal line by 15 degrees.

While maintaining the orientation of the handset, the EUT was moved towards the phantom on a line passing through RE and LE until any part of the handset touched the ear. The tilted position is obtained when the contact is on the pinna. If the contact was at any location other than the pinna (e.g., the antenna with the back of the phantom head), the angle of the handset would be reduced. In this case, the tilted position is obtained if any part of the handset was in contact with the pinna as well as a second part of the handset was in contact with the pinna as well as a second part of the handset was in contact with the back of the head). [6] See Figure 8.



Figure 8



#### 2.9.3 Belt Clip/Holster Configuration

Test configurations for body-worn operated EUTs are carried out while the belt-clip and/or holster is attached to the EUT and placed against a flat phantom in a regular configuration (see Figure 9). An EUT with a headset output is tested with a headset connected to the device.

Body dielectric parameters are used.

There are two categories for accessories for body-worn operation configurations:

- 1. accessories not containing metallic components
- 2. accessories containing metallic components.

When the EUT is equipped with accessories not containing metallic components the tests are done with the accessory that dictates the closest spacing to the body. For accessories containing metallic parts a test with each one is implemented. If the multiple accessories share an identical metallic component (e.g. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that has the closest spacing to the body is tested.

In case that a EUT authorized to be body-worn is not supplied or has no options to be operated with any accessories, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented.

Transmitters operating in front of a person's face (e.g. push-to-talk configurations) are tested for SAR compliance with the front of the device positioned to face the flat platform. SAR Compliance tests for shoulder, waist or chest-worn transmitters are carried out with the accessories including headsets and microphones attached to the device and placed against a flat phantom in a regular configuration.

The SAR measurements are performed to investigate the worst-case positioning. This is documented and used to perform Body SAR testing. [2].



Figure 9



#### 2.9.4 Headset Configuration

Headsets which have their radiating structure in close proximity to the head are measured according to the following conditions.

- Head tissue liquid is used.
- The EUT is positioned on the surface of the head of phantom according the picture below. Right and left position is tested according to the normal use (see figure 10).
- Additional metallic parts like clips or others are subject of testing, too.



Figure 10

Headsets which have their radiating structure in close proximity to the body are tested as body worn equipment.

# EIS

#### 2.10 Measurement uncertainty

The uncertainty budget has been determined for the DASY4 system performance check according to IEEE Std. 1528-2003, December 2003.

	Tol.	Prob.	Div.	$({}^{c}i)^{1}$	Std. unc.	$(v_i)^2$
Error Description	(±%)	dist.		(1g)	$(1g) (\pm \%)$	
Measurement System						
Probe Calibration	4.8	N	1	1	4.8	$\infty$
Axial Isotropy	4.7	R	<sup>√</sup> 3	0.7	1.9	$\infty$
Hemispherical Isotropy	9.6	R	<sup>√</sup> 3	0.7	3.9	$\infty$
Boundary Effects	1.0	R	√3	1	0.6	$\infty$
Linearity	4.7	R	√3	1	2.7	$\infty$
System Detection Limit	1.0	R	<sup>√</sup> 3	1	0.6	$\infty$
Readout Electronics	1.0	N	1	1	1.0	$\infty$
Response Time	0.8	R	√3	1	0.5	$\infty$
Integration Time	2.6	R	<sup>√</sup> 3	1	1.5	$\infty$
RF Ambient Conditions	3.0	R	<sup>√</sup> 3	1	1.7	$\infty$
Probe Positioner	0.4	R	√3	1	0.2	$\infty$
Probe Positioning	2.9	R	√3	1	1.7	$\infty$
Algorithms for Max. SAR Eval.	1.0	R	<sup>√</sup> 3	1	0.6	$\infty$
Test Sample Related						
Device Positioning	2.9	N	1	1	2.9	145
Device Holder	3.6	N	1	1	3.6	5
Power Drift	5.0	R	<sup>√</sup> 3	1	2.9	$\infty$
Phantom and Setup						
Phantom Uncertainty	4.0	R	<sup>√</sup> 3	1	2.3	$\infty$
Liquid Conductivity (target)	5.0	R.	<sup>√</sup> 3	0.64	1.8	$\infty$
Liquid Conductivity (meas.)	2.6	Ν	1	0.64	1.7	$\infty$
Liquid Permittivity (target)	5.0	R	<sup>√</sup> 3	0.6	1.7	$\infty$
Liquid Permittivity (meas.)	3.8	N	1	0.6	2.3	$\infty$
Combined Standard Uncertainty					10.4	330
Expanded Uncertainty kp=2						
Coverage Factor for 95%					20.8	

The budget is valid for the frequency range 300 MHz - 3 GHz and represent a worst case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



## **3** Tissue and System Verification

#### **3.1** Tissue Verification

Dielectric parameters of the simulating liquids were verified using a Dielectric Probe Kit Agilent 85070D to a tolerance of  $\pm$  5 %.

**Room Temperature:** 22,1 -22,6 ° C

	Measured Tissue Parameters		
	<b>1900 MHz Brain</b>		
	Target	Measured	
Date		14.03.2006	
Liquid Temperature: ° C		22,1	
Dielectric Constant: ε	40,0	39,9	
Conductivity: σ	1,40	1,42	

**Room Temperature:** 22,1 -22,6 °C

	Measured Tissue Parameters 1900 MHz Muscle			
	Target Measured			
Date		13.02.2006		
Liquid Temperature: °C		22,1		
Dielectric Constant: ε	53,3	51,9		
Conductivity: σ	1,52	1,58		

#### 3.2 System Verification

Prior to the assessment, the system was verified by using a 1900 MHz validation dipole. Power level of 250 mW was supplied to the dipole antenna placed under the flat section of SAM Phantom. This system validation is valid for a frequency range of  $900 \pm 100$  MHz.

The system was verified to a tolerance of  $\pm$  10 %.

Liquid Temperature:	22,0 -22,3 ° C
<b>Room Temperature:</b>	22,1 -22,6 ° C
Liquid Depth:	>15.5 cm

System Dipole Validation Target & Measurement						
Date	System Validation Kit:	Liquid	Targeted SAR 1g (mW/g)	Measured SAR 1g (mW/g)	Deviation (%)	
14.03.2006	D1900V2 SN5d025	1900 MHz Head	40,4	41,6	2,97	
15.03.2006	D1900V2 SN5d025	1900 MHz Muscle	45,6	44,8	-1,75	

Comment: Please find attached the measurement plots.



#### 4 Test Results

Procedures Used To Establish Test Signal

The EUT was placed into simulated call mode (e.g. AMPS, Cellular CDMA & PCS CDMA modes) using manufacturers test codes. Such test signals offer a consistent means for testing SAR and are recommended for evaluating SAR [2]. The actual transmission is activated through a base station simulator or similar when test modes are not available or inappropriate for testing the EUT.

The EUT is rechargeable battery operated. The battery used for the SAR measurements was completely charged. The device was tested at full power verified by implementing conducted output power measurements. For confirming of the output power it was tested before and after each SAR measurement. The test was repeated if a conducted power deviation of more than 5 % occurred.

 Mixture Type:
 1900 MHz Head

 Date:
 14.03.2006

 Liquid Temperature:
 22,0 -22,3 ° C

Room Temperature: 22,1 -22,6 ° C

	Frequency	7	Power Drift	Antenna Pos.	Phantom	Test	SAR
MHz	Channel	Modulation	dBm		Section	Position	(W/kg)
1850,2	512	GSM	-0,034	Integral ant1	Right Ear	Cheek	1,15
1880,0	661	GSM	-0,009	Integral ant1	Right Ear	Cheek	1,03
1880,0	661	GSM	-0,086	Integral ant1	Right Ear	Tilt	0,636
1909,8	810	GSM	-0,003	Integral ant1	Right Ear	Cheek	0,801
1850,2	512	GSM	-0,070	Integral ant1	Left Ear	Cheek	1,02
1880,0	661	GSM	-0,056	Integral ant1	Left Ear	Cheek	0,902
1880,0	661	GSM	-0,084	Integral ant1	Left Ear	Tilt	0,552
1909,8	810	GSM	-0,031	Integral ant1	Left Ear	Cheek	0,715

Mixture Type:	1900 MHz Muscle
Date:	15.03.2006
Liquid Temperature:	22,0 -22,3 ° C

Room Temperature: 22,1 -22,6 ° C

	Frequency	,	Power Drift	Antenna Pos.	Phantom	Test	SAR
MHz	Channel	Modulation	dBm		Section	Position -5 mm	(W/kg)
1850,2	512	GSM	-0,011	Integral	Flat	Back	1,15
1880,0	661	GSM	0,028	Integral	Flat	Front	0,493
1880,0	661	GSM	-0,041	Integral	Flat	Back	0,956
1909,8	810	GSM	0,019	Integral	Flat	Back	0,887

Note: Device positioning: spacing from flat phantom was adjusted at 1.5 cm.



Limits:

	SAR (W/kg)			
Exposure Limits	Uncontrolled Exposure/General Population Environment	Controlled Exposure/Occupational Environment		
Spatial Average SAR (averaged over the whole body)	0.08	0.40		
Spatial Peak SAR (averaged over any 1g of tissue)	1.60	8.00		
Spatial Peak SAR (Hands, Feet, Ankles, Wrist) (averaged over any 10g of tissue)	4.00	20.00		

Notes:

- 1. Test data represent the worst case SAR value and test procedure used are according to OET Bulletin 65, Supplement C (01-01).
- 2. All modes of operation were investigated.



#### 5 References

[1] ANSI/IEEE C95.3 – 1991, *IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic fields, 300 kHz to 100 GHz,* New York: IEEE, Aug. 1992

[2] Federal Communications Commission, OET Bulletin 65 (Edition 97-01), Supplement C (Edition 01-01), *Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields*, July 2001.

[3] T. Schmid, O. Egger, N. Kuster, *Automated E-field scanning system for dosimetric assessments*, IEEE Transaction on Microwave Theory and Techniques, vol. 44, Jan. 1996, pp. 105-113.

[4] W. Gander, *Computermathematics*, Birkhaeuser, Basel, 1992.

[5] W.H. Press, S.A. Teukolsky, W.T. Vetterling, and B.P. Flannery, *Numerical Recipes in C*, The Art of Scientific Computing, Second edition, Cambridge University Press, 1992.

[6] IEEE Standards Coordinating Committee 34 – IEEE Std. 1528-2003, December 2003, *Recommended Practice for Determining the Peak Spatial-Average Absorption Rate (SAR in the Human Body Due to Wireless Communications Devices: Experimental Techniques.* 

[7] DASY4 *Dosimetric Assessment System Manual*; Draft; September 6, 2002; Schmid & Partner Engineering AG



## 6 Appendix

- 1.
   Appendix A
   Calibration Certificate
   D1900V2 SN5d025

   ET3DV6 SN1711
   DAE3V1-522
- 2. Appendix B Measurement Plots
- 3. Appendix C Pictures



#### Appendix A

#### **Calibration Certificate**

Note:

ETS Dr. Genz GmbH has extended the calibration interval for SPEAG System Validation Dipoles up to two years above the two years recommended by manufacturer. The determination of individual calibrations interval is covered and defined by ETS internal quality management procedures according EN 17025. This QM procedures are acknowledged by accreditation bodies mentioned on page 3 of this test report.

## Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland, Phone +41 1 245 97 00, Fax +41 1 245 97 79

# **Calibration Certificate**

1900 MHz System Validation Dipole

Туре:	D1900V2
Serial Number:	50025
Place of Calibration:	Zurich
Date of Calibration:	October 14, 2002
Calibration Interval:	24 months

Schmid & Partner Engineering AG hereby certifies, that this device has been calibrated on the date indicated above. The calibration was performed in accordance with specifications and procedures of Schmid & Partner Engineering AG.

Wherever applicable, the standards used in the calibration process are traceable to international standards. In all other cases the standards of the Laboratory for EMF and Microwave Electronics at the Swiss Federal Institute of Technology (ETH) in Zurich, Switzerland have been applied.

Calibrated by:

D.Vellan Blait Kofz

Approved by:

# Schmid & Partner **Engineering AG**

Zeughausstrasse 43, 8004 Zurich, Switzerland, Phone +41 1 245 97 00, Fax +41 1 245 97 79

# DASY

# **Dipole Validation Kit**

# Type: D1900V2

# Serial: 5d025

Manufactured:

July 29, 2002 Calibrated: October 14, 2002

#### 1. Measurement Conditions

The measurements were performed in the flat section of the new SAM twin phantom filled with head simulating glycol solution of the following electrical parameters at 1900 MHz:

Relative Dielectricity	38.7	± 5%
Conductivity	1.45 mho/m	± 5%

The DASY4 System with a dosimetric E-field probe ET3DV6 (SN:1507, Conversion factor 5.2 at 1900 MHz) was used for the measurements.

The dipole was mounted on the small tripod so that the dipole feedpoint was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was <u>10mm</u> from dipole center to the solution surface. The included distance holder was used during measurements for accurate distance positioning.

The coarse grid with a grid spacing of 15mm was aligned with the dipole. The 7x7x7 fine cube was chosen for cube integration.

The dipole input power (forward power) was  $250 \text{mW} \pm 3 \%$ . The results are normalized to 1W input power.

#### 2 SAR Measurement with DASY4 System

Standard SAR-measurements were performed according to the measurement conditions described in section 1. The results (see figure supplied) have been normalized to a dipole input power of 1W (forward power). The resulting averaged SAR-values measured with the dosimetric probe ET3DV6 SN:1507 and applying the <u>advanced extrapolation</u> are:

averaged over  $1 \text{ cm}^3$  (1 g) of tissue:40.4 mW/gaveraged over  $10 \text{ cm}^3$  (10 g) of tissue:20.6 mW/g

#### 3. Dipole Impedance and Return Loss

The impedance was measured at the SMA-connector with a network analyzer and numerically transformed to the dipole feedpoint. The transformation parameters from the SMA-connector to the dipole feedpoint are:

Electrical delay:	1.196 ns	(one direction)
Transmission factor:	0.997	(voltage transmission, one direction)

The dipole was positioned at the flat phantom sections according to section 1 and the distance holder was in place during impedance measurements.

Feedpoint impedance at 1900 MHz:	$\operatorname{Re}\{Z\}=51.6\Omega$		
	$\operatorname{Im} \{Z\} = 4.7 \Omega$		
Return Loss at 1900 MHz	-26.3 dB		

#### 4. Handling

Do not apply excessive force to the dipole arms, because they might bend. Bending of the dipole arms stresses the soldered connections near the feedpoint leading to a damage of the dipole.

#### 5. Design

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

#### 6. Power Test

After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

Test Laboratory: SPEAG, Zurich, Switzerland File Name: SN5d025\_SN1507\_HSL1900\_141002.da4

#### DUT: Dipole 1900 MHz Type & Serial Number: D1900V2 - SN5d025 Program: Dipole Calibration; Pin = 250 mW; d = 10 mm

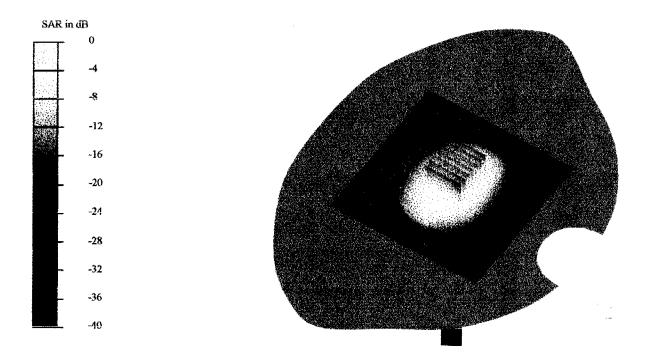
Communication System: CW-1900; Frequency: 1900 MHz; Duty Cycle: 1:1 Medium: HSL 1900 MHz ( $\sigma$  = 1.45 mho/m,  $\epsilon$  = 38.7,  $\rho$  = 1000 kg/m3) Phantom section: FlatSection

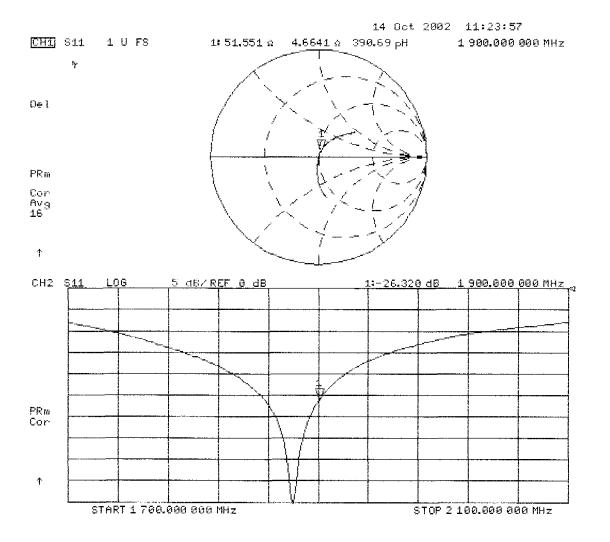
DASY4 Configuration:

- Probe: ET3DV6 SN1507; ConvF(5.2, 5.2, 5.2); Calibrated: 1/24/2002
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 SN410; Calibrated: 7/18/2002
- Phantom: SAM 4.0 TP:1006

- Software: DASY4, V4.0 Build 35

Area Scan (81x81x1): Measurement grid: dx=15mm, dy=15mmZoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mmReference Value = 93 V/m Peak SAR = 18.3 mW/g SAR(1 g) = 10.1 mW/g; SAR(10 g) = 5.16 mW/g Power Drift = -0.0005 dB





s p e a g

Zeughausstrasse 43, 8004 Zurich, Switzerland Phone +41 1 245 9700, Fax +41 1 245 9779 info@speag.com, http://www.speag.com

# Probe ET3DV6

# SN:1711

Manufactured: Last calibration: Recalibrated: August 7, 2002 November 26, 2002 December 16, 2003

Calibrated for DASY Systems

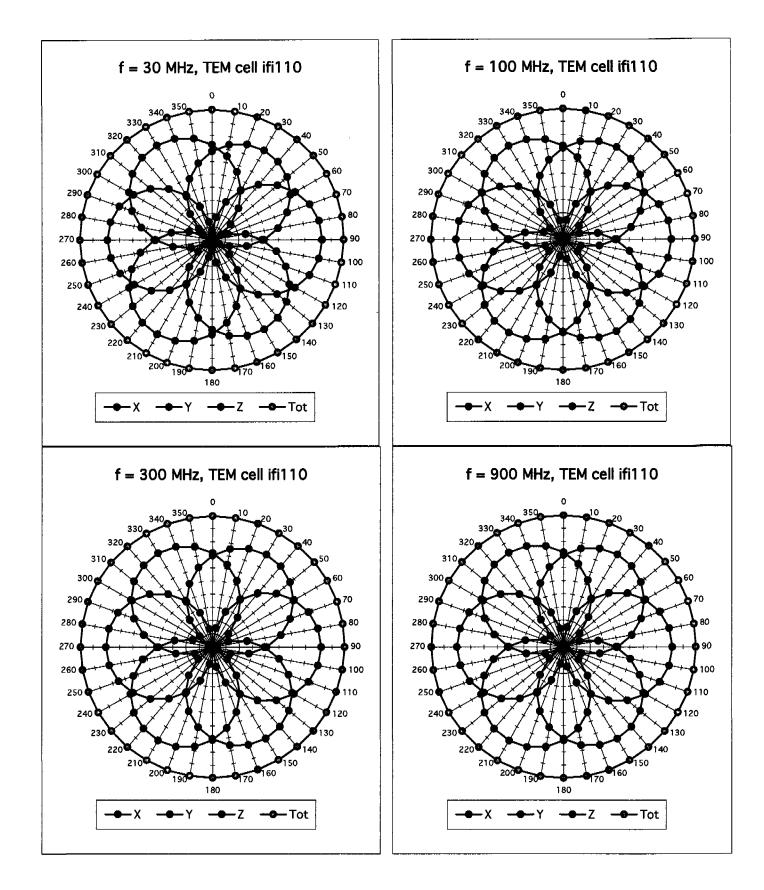
(Note: non-compatible with DASY2 system!)

#### ET3DV6 SN:1711

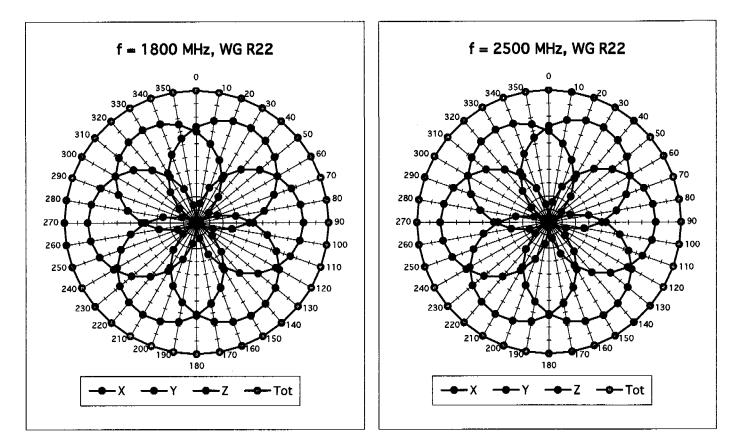
# DASY - Parameters of Probe: ET3DV6 SN:1711

Sensitivity in Free Space				Diode Compression			
	NormX	1.4	<b>41</b> μV/(V/m) <sup>2</sup>		DCP X	97	mV
	NormY		<b>62</b> μV/(V/m)²		DCP Y	97	mV
	NormZ		<b>56</b> μV/(V/m) <sup>2</sup>		DCP Z	97	mV
Sensitiv	rity in Tissue	e Simulati	ing Liquid				
Head	90	0 MHz	ε <sub>r</sub> = 41.5 ±	:5% σ	= 0.97 ± 5%	mho/m	
Valid for f=	800-1000 MHz v	with Head Tis:	sue Simulating Liquid acc	ording to EN 5036	61, P1 528-200	x	
	ConvF X	6	<b>.2</b> ± 9.5% (k=2)		Boundary ef	fect:	
	ConvF Y	6	<b>.2</b> ± 9.5% (k=2)		Alpha	0.31	
	ConvF Z	6	.2 ± 9.5% (k=2)		Depth	2.87	
Head	180	0 MHz	$\varepsilon_r = 40.0 \pm$	: <b>5% </b> σ	= 1.40 ± 5%	mho/m	
Valid for f=	1710-1910 MHz	with Head Ti	ssue Simulating Liquid ad	cording to EN 503	861, P1 528-20	ОХ	
	ConvF X	5	.2 ± 9.5% (k=2)		Boundary et	fect:	
	ConvF Y	5	.2 ± 9.5% (k=2)		Alpha	0.50	
	ConvF Z	5	<b>.2</b> ± 9.5% (k=2)		Depth	2.62	
Bounda	ary Effect						
Head	90	0 MHz	Typical SAR gradie	ent: 5 % per mm			
	Probe Tip to	Boundary			1 mm	2 mm	
	SAR <sub>be</sub> [%]	Without C	orrection Algorithm		9.9	5.8	
	SAR <sub>be</sub> [%]	With Corre	ection Algorithm		0.4	0.6	
Head	180	0 MHz	Typical SAR gradie	ent: 10 % per mm			
	Probe Tip to	Boundary			1 mm	2 mm	
	SAR <sub>be</sub> [%]	•	orrection Algorithm		13.6	9.2	
	SAR <sub>be</sub> [%]	With Corre	ection Algorithm		0.2	0.1	
Sensor	Offset						
Probe Tip to Sensor Center		2.7		mm			
	Optical Surface Detection			1.1 ± 0.2		mm	

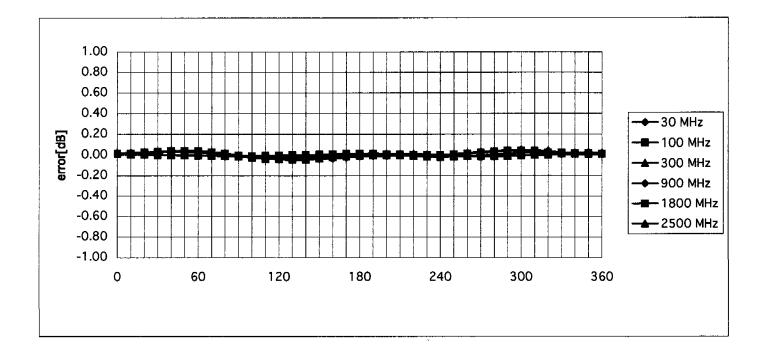
December 16, 2003



# **Receiving Pattern (** $\phi$ **),** $\theta$ = 0°

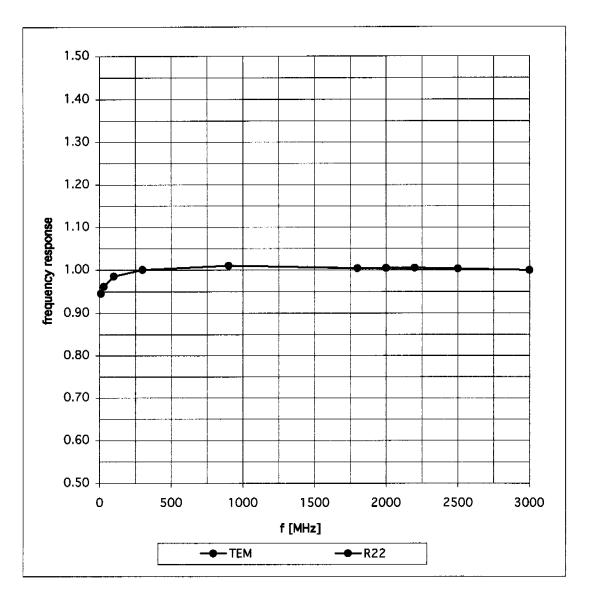


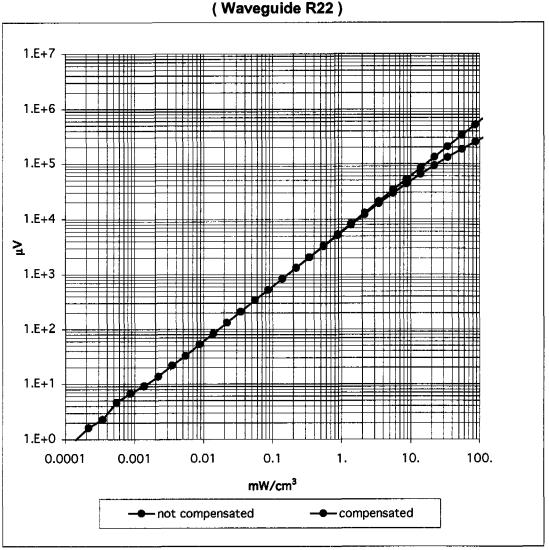
Isotropy Error ( $\phi$ ),  $\theta = 0^{\circ}$ 



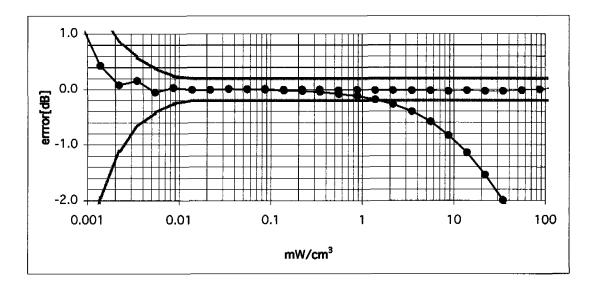
# **Frequency Response of E-Field**

(TEM-Cell:ifi110, Waveguide R22)

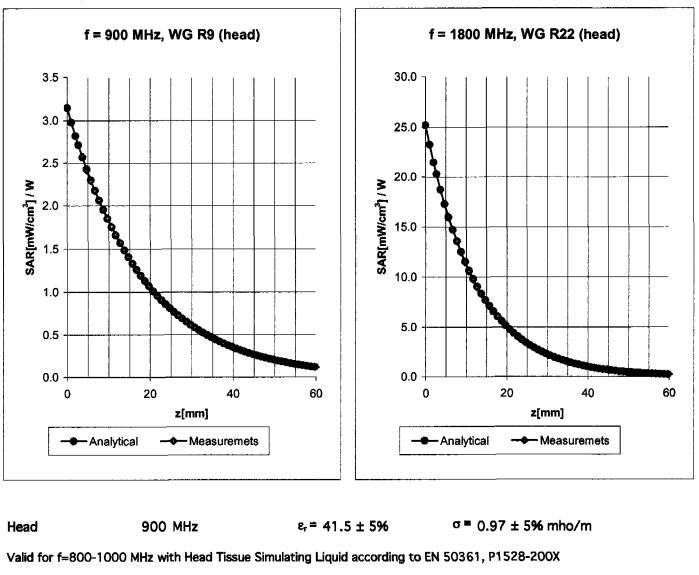




# **Dynamic Range f(SARhead)**



(Waveguide R22)

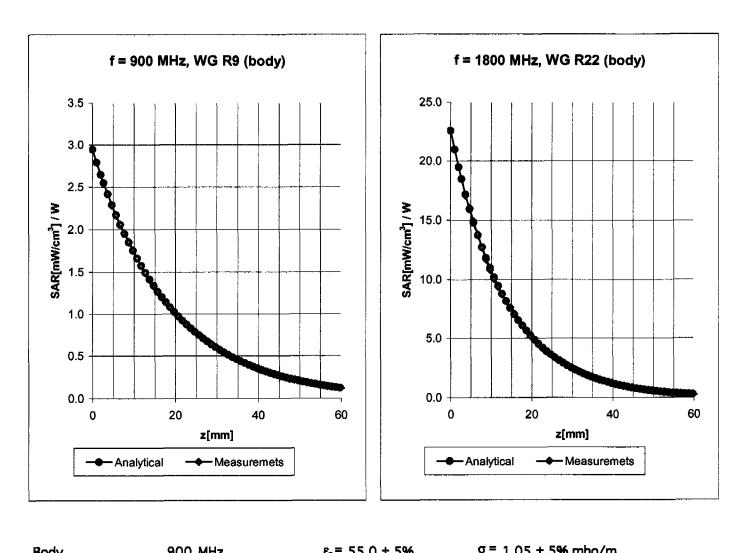


# **Conversion Factor Assessment**

ConvF X	6.2 ± 9.5% (k=2)	Boundary effect:	
ConvF Y	6.2 ± 9.5% (k=2)	Alpha	0.31
ConvF Z	6.2 ± 9.5% (k=2)	Depth	2.87

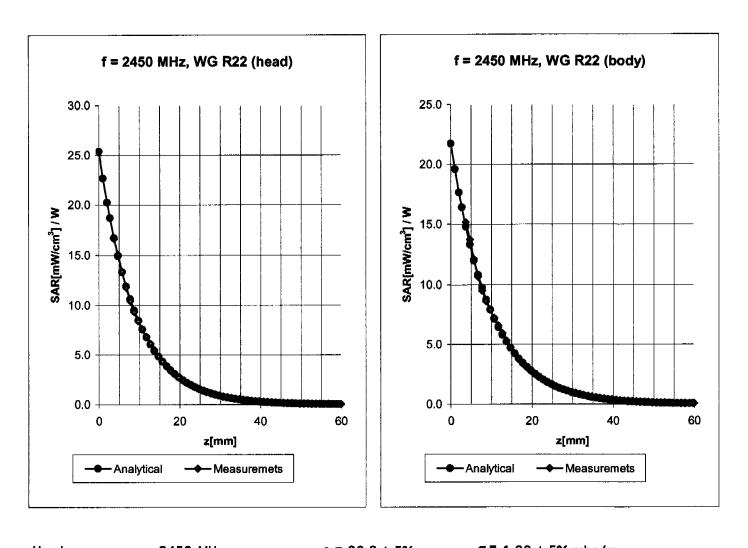
Head	1800 MHz	$\varepsilon_r$ = 40.0 ± 5%	$\sigma$ = 1.40 ± 5% mho/m	
Valid for f=1	710-1910 MHz with He	ad Tissue Simulating Liquid according to EN	1 50361, P1528-200X	
	ConvF X	<b>5.2</b> ± 9.5% (k=2)	Boundary effect:	
	ConvF Y	<b>5.2</b> ± 9.5% (k=2)	Alpha 0.5	0
	ConvF Z	<b>5.2</b> ± 9.5% (k=2)	Depth 2.6	2

,



# **Conversion Factor Assessment**

Body	900 MHz	$\epsilon_{\rm r} = 55.0 \pm 5\%$	0-	1.05 ± 5%	mno/m
Valid for f=800-1000 MH	lz with Body Tissue S	imulating Liquid accordir	ng to OET 65 S	uppl. C	
ConvF X	6.0 ±	: 9.5% (k=2)		Boundary ef	fect:
ConvF Y	6.0 ±	9.5% (k=2)		Alpha	0.38
ConvF Z	6.0 ±	:9.5% (k=2)		Depth	2.52
Body 18	300 MHz	$\varepsilon_r$ = 53.3 ± 5%	σ=	1.52 ± 5%	mho/m
Valid for f=1710-1910 M	IHz with Body Tissue	Simulating Liquid accord	ling to OET 65	Suppl. C	
ConvF X	<b>4.6</b> ±	: 9.5% (k=2)		Boundary ef	fect:
ConvF Y	4.6 ±	: 9.5% (k=2)		Alpha	0.56
ConvF Z	4.6 ±	9.5% (k=2)		Depth	2.67

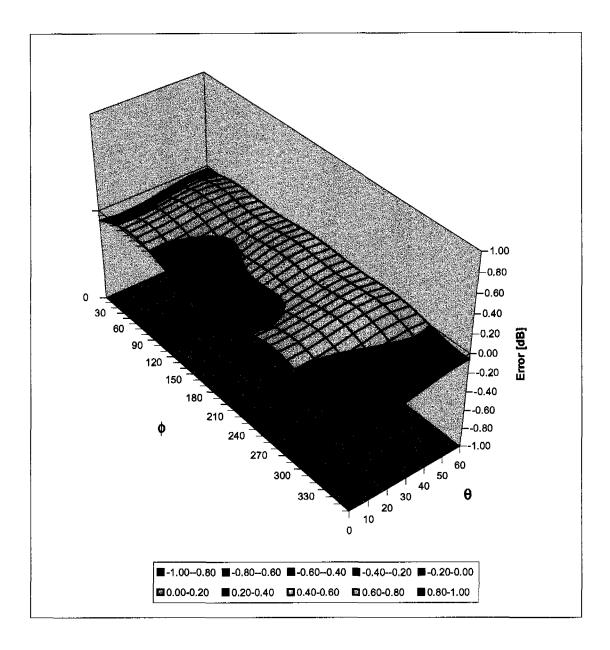


# **Conversion Factor Assessment**

Head	2450 MHz	$\epsilon_{\rm r}$ = 39.2 ± 5%	σ =	1.80 ± 5% mho/	m
Valid for f=2400-2500	) MHz with Head Tissu	e Simulating Liquid accordi	ing to EN 5036	51, P1528-200X	
ConvF X	4.6	± 9.5% (k=2)		Boundary effect:	
ConvF Y	ý 4.6	± 9.5% (k=2)		Alpha	1.07
ConvF Z	4.6	± 9.5% (k=2)		Depth	1.79
Body	2450 MHz	ε <sub>r</sub> = 52.7 ± 5%	σ=	1.95 ± 5% mho/	m
Valid for f=2400-2500	MHz with Body Tissu	e Simulating Liquid accordi	ing to OET 65	Suppl. C	
ConvF X	4.1	± 9.5% (k=2)		Boundary effect:	
ConvF Y	<sup>,</sup> 4.1	± 9.5% (k=2)		Alpha	1.11
ConvF Z	<b>4.</b> 1	± 9.5% (k=2)		Depth	1.56

# **Deviation from Isotropy in HSL**

Error  $(\theta, \phi)$ , f = 900 MHz



Client ETS Dr. Genz

CALIBRATION	eerna(gane		
Object(s)	DAE3 - SD 000 D03 A	A - SN:522	
Calibration procedure(s)	QA CAL-06.v5a Calibration procedure I	for the data acquisitio	on unit (DAE)
Calibration date:	16.12.2003		
Condition of the calibrated item	In Tolerance (accordin	g to the specific calib	pration document)
This calibration statement docume 17025 international standard.	ents traceability of M&TE used in the	calibration procedures and cor	nformity of the procedures with the ISO/IEC
All calibrations have been conduc	ted in the closed laboratory facility: e	nvironment temperature 22 +/-	2 degrees Celsius and humidlty < 75%.
Calibration Equipment used (M&T	E critical for calibration)		
Model Type Fluke Process Calibrator Type 70	ID # 2 SN: 6295803	Cal Date 8-Sep-03	Scheduled Calibration Sep-04
	Name	Function	Sighature
Calibrated by:	Philipp Storchenegger	Technician	1:Aur
Approved by:	Fin Bomholt	R&D Director	F. Soulidt
			Date issued: 16.12.2003
This calibration certificate is issue Calibration Laboratory of Schmid		1 1	on ISO/IEC 17025 International Standard) for

Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland Phone +41 1 245 9700, Fax +41 1 245 9779 info@speag.com, http://www.speag.com

# **IMPORTANT NOTICE**

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#### **USAGE OF THE DAE**

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

Battery Exchange: The battery cover of the DAE3 unit is connected to a fragile 3-pin battery connector. Customer is responsible to apply outmost caution not to bend or damage the connector when changing batteries.

Shipping of the DAE: Before shipping the DAE to SPEAG for calibration Customer shall remove the batteries and pack the DAE in an antistatic bag. The packaging shall protect the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

**E-Stop Failures**: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, Customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

**Repair**: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

#### Important Note: Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.

#### Important Note: Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the Estop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

#### <u>speag</u>

Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland Phone +41 1 245 9700, Fax +41 1 245 9779 info@speag.com, http://www.speag.com

Schmid & Partner Engineering AG

# 1. Cal Lab. Incoming Inspection & Pre Test

Modification Status	Note Status here $\rightarrow \rightarrow \rightarrow \rightarrow$	BC	
Visual Inspection	Note anomalies	None	
Pre Test	Indication	Yes/No	
Probe Touch	Function	Yes	
Probe Collision	Function	Yes	
Probe Touch&Collision	Function	Yes	

# 2. DC Voltage Measurement

A/D - Converter Resolution nominal

High Range:	1LSB =	6.1µV ,	full range =	400 mV
Low Range:	1LSB =	61nV ,	full range =	4 mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	403.721	403.496	403.817
Low Range	3.90669	3.92578	3.92595
Connector Angle to be used	in DASY System	44 °	

High Range	Input	Reading in µV	% Error
Channel X + Input	200mV	199999.4	0.00
	20mV	19996.3	-0.02
Channel X - Input	20mV	-19993.6	-0.03
Channel Y + Input	200mV	199999.5	0.00
	20mV	19995.9	-0.02
Channel Y - Input	20mV	-19994.4	-0.03
Channel Z + Input	200mV	200000.7	0.00
	20mV	19994.2	-0.03
Channel Z - Input	20mV	-19995.6	-0.02

Low Range	Input	Reading in µV	% Error
Channel X + Input	2mV	1999.97	0.00
	0.2mV	200.58	0.29
Channel X - Input	0.2mV	-200.30	0.15
Channel Y + Input	2mV	1999.98	0.00
	0.2mV	199.72	-0.14
Channel Y - Input	0.2mV	-200.64	0.32
Channel Z + Input	2mV	2000.02	0.00
	0.2mV	199.41	-0.30
Channel Z - Input	0.2mV	-201.21	0.61

Page 2 of 4

## 3. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec,

Measuring time: 3 sec

High/Low Range

in μV	Common mode Input Voltage	High Range Reading	Low Range Reading
Channel X	200mV	-0.71	-1.13
	- 200mV	2.36	-0.91
Channel Y	200mV	-0.87	-0.14
	- 200mV	-0.34	-1.27
Channel Z	200mV	-7.73	-6.96
	- 200mV	5.49	6.16

# 4. Channel separation

DASY measurement parameters:

Auto Zero Time: 3 sec, Measuring time: 3 sec

High Range

in μV	Input Voltage	Channel X	Channel Y	Channel Z
Channel X	200mV		1.45	0.18
Channel Y	200mV	-0.88	-	4.83
Channel Z	200mV	-1.60	0.24	-

## 5.1 AD-Converter Values with Input Voltage set to 2.0 mVDC

in Zero Low	Low Range Max - Min	Max.	Min
Channel X	10	16531	16521
Channel Y	5	16003	15998
Channel Z	13	16439	16426

### 5.2 AD-Converter Values with inputs shorted

in LSB	Low Range	High Range
Channel X	16555	15364
Channel Y	16020	15473
Channel Z	16437	15486

### 6. Input Offset Measurement

DASY measurement parameters:	
Auto Zero Time: 3 sec,	N
Number of measurements:	10

Measuring time: 3 sec 100, Low Range

Input 10MΩ

in μV	Average	min. Offset	max. Offset	Std. Deviation
Channel X	1.48	0.57	2.44	0.40
Channel Y	-1.16	-1.66	-0.62	0.23
Channel Z	0.05	-0.52	1.00	0.23

Input shorted

in μV	Average	min. Offset	max. Offset	Std. Deviation
Channel X	0.15	-0.68	0.94	0.31
Channel Y	-0.50	-1.87	-0.10	0.25
Channel Z	-0.86	-1.70	-0.19	0.23

## 7. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

## 8. Input Resistance

In MOhm	Calibrating	Measuring
Channel X	0.2000	199.5
Channel Y	0.2000	199.0
Channel Z	0.1999	199.5

## 9. Low Battery Alarm Voltage

in V	Alarm Level
Supply (+ Vcc)	7.88
Supply (- Vcc)	-7.65

### **10.** Power Consumption

in mA	Switched off	Stand by	Transmitting
Supply (+ Vcc)	0.00	5.70	13.9
Supply (- Vcc)	-0.01	-8.03	-9.22