

## APPENDIX D (PROBE CALIBRATION DATA)

Calibration Laboratory of  
Schmid & Partner  
Engineering AG  
Zeughausstrasse 43, 8004 Zurich, Switzerland



S Schweizerischer Kalibrierdienst  
C Service suisse d'étalonnage  
S Servizio svizzero di taratura  
S Swiss Calibration Service

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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client **Pantech (Dymstec)**

Certificate No: ER3-2242\_Sep10

**CALIBRATION CERTIFICATE**

Object: ER3DV6R - SN:2242

Calibration procedure(s): QA CAL-02.v5 and QA CAL-25.v2  
Calibration procedure for E-field probes optimized for close near field evaluations in air

Calibration date: September 20, 2010

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	1-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41495277	1-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41498087	1-Apr-10 (No. 217-01136)	Apr-11
Reference 3 dB Attenuator	SN: S5054 (3c)	30-Mar-10 (No. 217-01159)	Mar-11
Reference 20 dB Attenuator	SN: S5086 (20b)	30-Mar-10 (No. 217-01161)	Mar-11
Reference 30 dB Attenuator	SN: S5129 (30b)	30-Mar-10 (No. 217-01160)	Mar-11
Reference Probe ER3DV6	SN: 2328	3-Oct-09 (No. ER3-2328_Oct09)	Oct-10
DAE4	SN: 789	31-Aug-10 (No. DAE4-789_Aug10)	Aug-11
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10

Calibrated by: Name: Katja Pokovic, Function: Technical Manager, Signature: *[Signature]*

Approved by: Name: Fin Bomholt, Function: R&D Director, Signature: *[Signature]*

Issued: September 20, 2010

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Accreditation No.: **SCS 108**

**Glossary:**

NORM <sub>x,y,z</sub>	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization $\phi$	$\phi$ rotation around probe axis
Polarization $\vartheta$	$\vartheta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

**Calibration is Performed According to the Following Standards:**

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

**Methods Applied and Interpretation of Parameters:**

- NORM<sub>x,y,z</sub>*: Assessed for E-field polarization  $\vartheta = 0$  for XY sensors and  $\vartheta = 90$  for Z sensor ( $f \leq 900$  MHz in TEM-cell;  $f > 1800$  MHz: R22 waveguide).
- NORM(f)<sub>x,y,z</sub>* = *NORM<sub>x,y,z</sub>* \* *frequency\_response* (see Frequency Response Chart).
- DCP<sub>x,y,z</sub>*: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- A<sub>x,y,z</sub>; B<sub>x,y,z</sub>; C<sub>x,y,z</sub>; VR<sub>x,y,z</sub>*: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle*: The angle is assessed using the information gained by determining the *NORM<sub>x</sub>* (no uncertainty required).

ER3DV6R SN:2242

September 20, 2010

# Probe ER3DV6R

## SN:2242

Manufactured:	November 24, 1999
Last calibrated:	November 23, 2009
Recalibrated:	September 20, 2010

Calibrated for DASYS/EASY Systems

(Note: non-compatible with DASYS2 system!)

ER3DV6R SN:2242

September 20, 2010

**DASY/EASY - Parameters of Probe: ER3DV6R SN:2242**
**Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ( $\mu\text{V}/(\text{V}/\text{m})^2$ )	3.72	3.55	5.45	$\pm 10.1\%$
DCP (mV) <sup>A</sup>	95.3	95.9	98.0	

**Modulation Calibration Parameters**

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc <sup>E</sup> (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	$\pm 1.5\%$
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> numerical linearization parameter: uncertainty not required

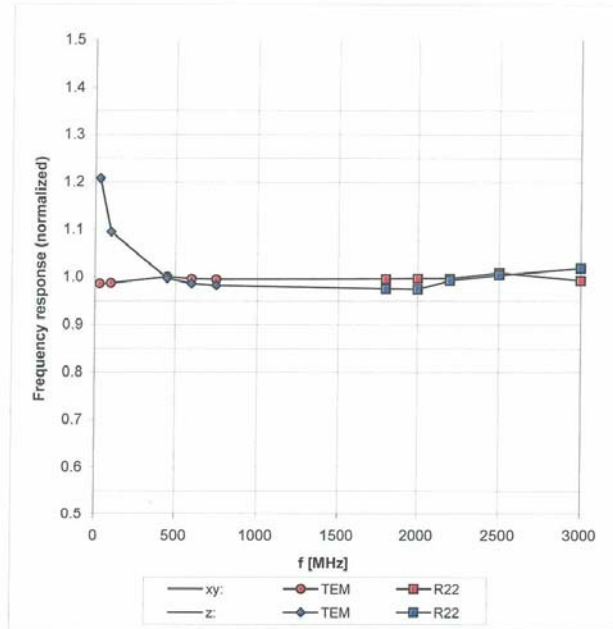
<sup>E</sup> Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

ER3DV6R SN:2242

September 20, 2010

### Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)

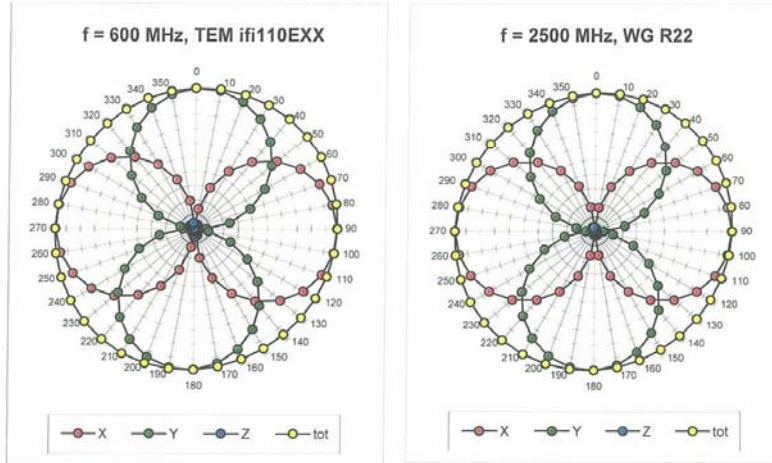


Uncertainty of Frequency Response of E-field:  $\pm 6.3\%$  (k=2)

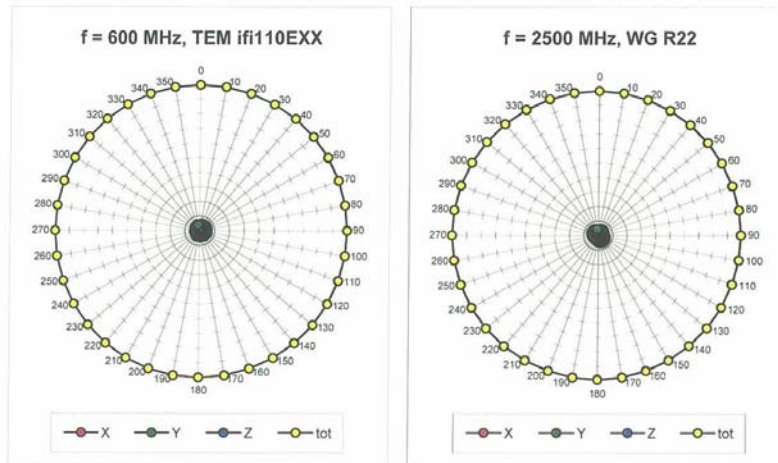
ER3DV6R SN:2242

September 20, 2010

**Receiving Pattern ( $\phi$ ),  $\vartheta = 0^\circ$**



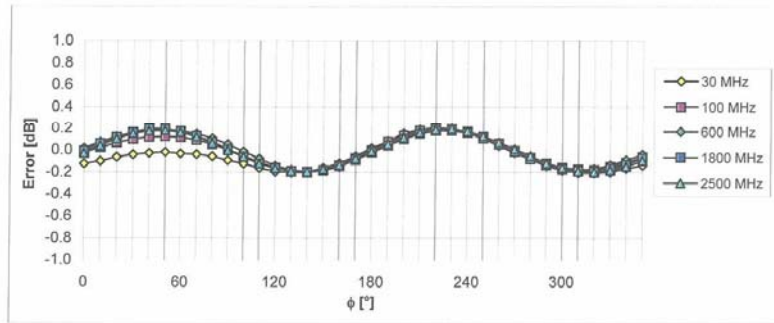
**Receiving Pattern ( $\phi$ ),  $\vartheta = 90^\circ$**



ER3DV6R SN:2242

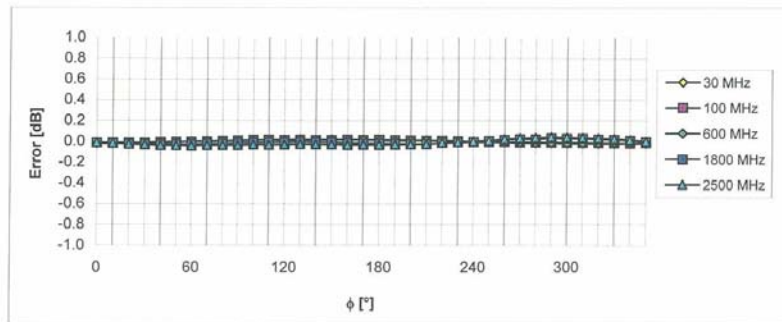
September 20, 2010

**Receiving Pattern ( $\phi$ ),  $\vartheta = 0^\circ$**



Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  (k=2)

**Receiving Pattern ( $\phi$ ),  $\vartheta = 90^\circ$**



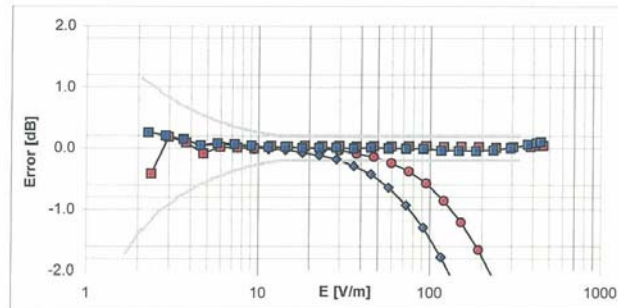
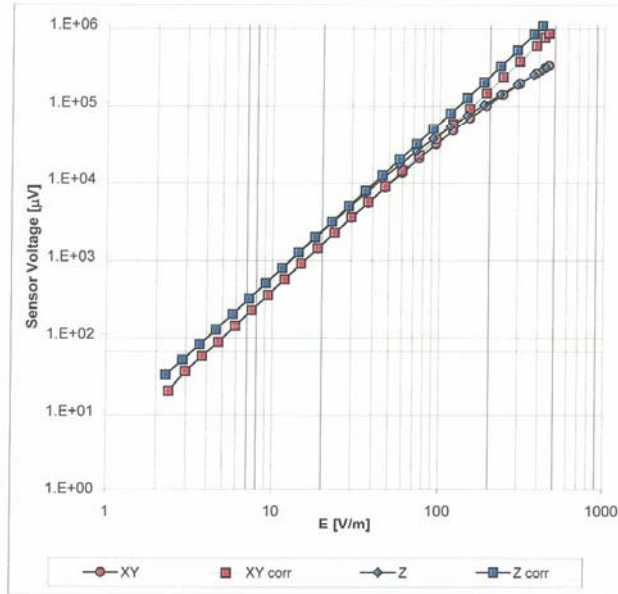
Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  (k=2)



ER3DV6R SN:2242

September 20, 2010

**Dynamic Range f(E-field)**  
(Waveguide R22, f = 1800 MHz)

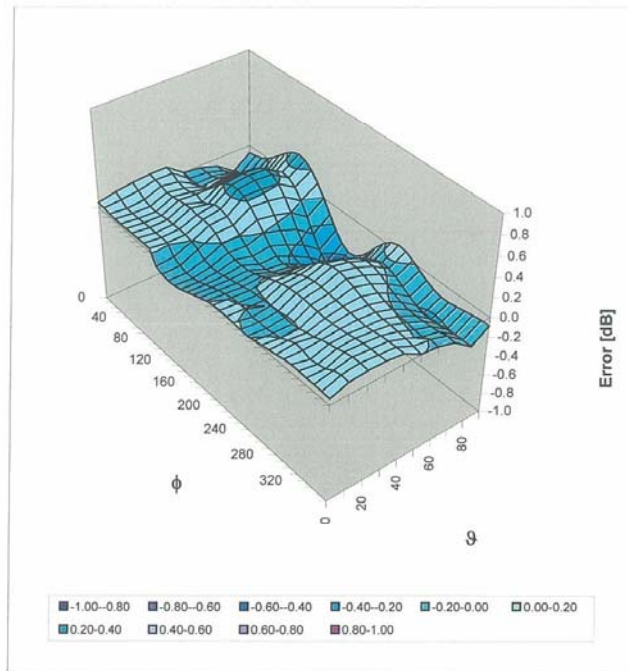


Uncertainty of Linearity Assessment:  $\pm 0.6\%$  (k=2)

ER3DV6R SN:2242

September 20, 2010

Deviation from Isotropy in Air  
Error ( $\phi, \vartheta$ ),  $f = 900$  MHz



Uncertainty of Spherical Isotropy Assessment:  $\pm 2.6\%$  ( $k=2$ )

ER3DV6R SN:2242

September 20, 2010

**Other Probe Parameters**

Sensor Arrangement	Rectangular
Connector Angle (°)	-292.4
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8.0 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

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Accreditation No.: **SCS 108**

Client **Pantech (Dymstec)**

Certificate No: **H3-6051\_Sep10**

**CALIBRATION CERTIFICATE**

Object: **H3DV6 - SN:6051**

Calibration procedure(s): **QA CAL-03.v5 and QA CAL-25.v2  
Calibration procedure for H-field probes optimized for close near field  
evaluations in air**

Calibration date: **September 20, 2010**

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The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
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Power sensor E4412A	MY41498087	1-Apr-10 (No. 217-01136)	Apr-11
Reference 3 dB Attenuator	SN: S5054 (3c)	30-Mar-10 (No. 217-01159)	Mar-11
Reference 20 dB Attenuator	SN: S5086 (20b)	30-Mar-10 (No. 217-01161)	Mar-11
Reference 30 dB Attenuator	SN: S5129 (30b)	30-Mar-10 (No. 217-01160)	Mar-11
Reference Probe H3DV6	SN: 6182	3-Oct-09 (No. H3-6182_Oct09)	Oct-10
DAE4	SN: 789	31-Aug-10 (No. DAE4-789_Aug10)	Aug-11
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	
Approved by:	Fin Bomholt	R&D Director	

Issued: September 20, 2010

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Accreditation No.: **SCS 108**

#### Glossary:

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DCP	diode compression point
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A, B, C	modulation dependent linearization parameters
Polarization $\phi$	$\phi$ rotation around probe axis
Polarization $\vartheta$	$\vartheta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

#### Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

#### Methods Applied and Interpretation of Parameters:

- NORM<sub>x,y,z</sub>*: Assessed for E-field polarization  $\vartheta = 0$  for XY sensors and  $\vartheta = 90$  for Z sensor ( $f \leq 900$  MHz in TEM-cell;  $f > 1800$  MHz: R22 waveguide).
- X, Y, Z(f)\_a0a1a2* = *X, Y, Z\_a0a1a2* \* *frequency\_response* (see Frequency Response Chart).
- DCP<sub>x,y,z</sub>*: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- A<sub>x,y,z</sub>; B<sub>x,y,z</sub>; C<sub>x,y,z</sub>; VR<sub>x,y,z</sub>*: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle*: The angle is assessed using the information gained by determining the *X\_a0a1a2* (no uncertainty required).

H3DV6 SN:6051

September 20, 2010

# Probe H3DV6

## SN:6051

Manufactured:	November 3, 1999
Last calibrated:	November 23, 2009
Recalibrated:	September 20, 2010

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

H3DV6 SN:6051

September 20, 2010

**DASY/EASY - Parameters of Probe: H3DV6 SN:6051**

**Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)	
Norm (A/m / $\sqrt{\mu V}$ )	a0	2.83E-3	2.61E-3	2.98E-3	± 5.1%
Norm (A/m / $\sqrt{\mu V}$ )	a1	-2.52E-4	-1.91E-4	-6.62E-4	± 5.1%
Norm (A/m / $\sqrt{\mu V}$ )	a2	6.03E-5	5.33E-5	2.20E-4	± 5.1%
DCP (mV) <sup>A</sup>	89.9	83.1	82.7		

**Modulation Calibration Parameters**

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc <sup>E</sup> (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	± 1.5 %
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> numerical linearization parameter: uncertainty not required

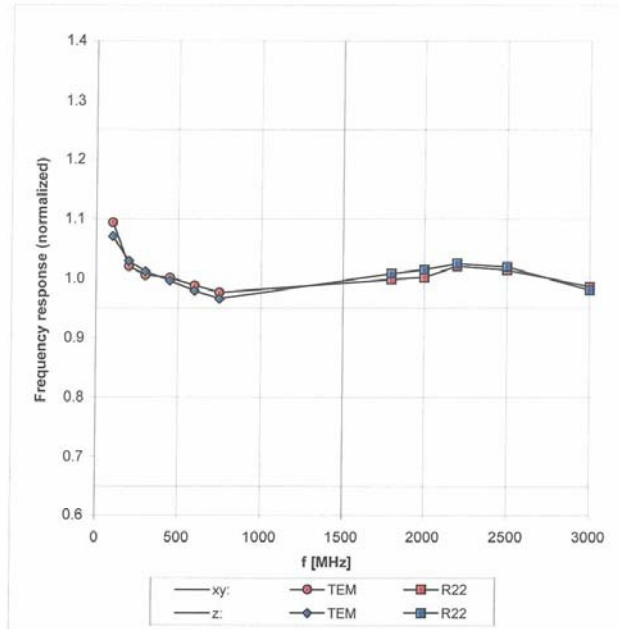
<sup>E</sup> Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

H3DV6 SN:6051

September 20, 2010

### Frequency Response of H-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)



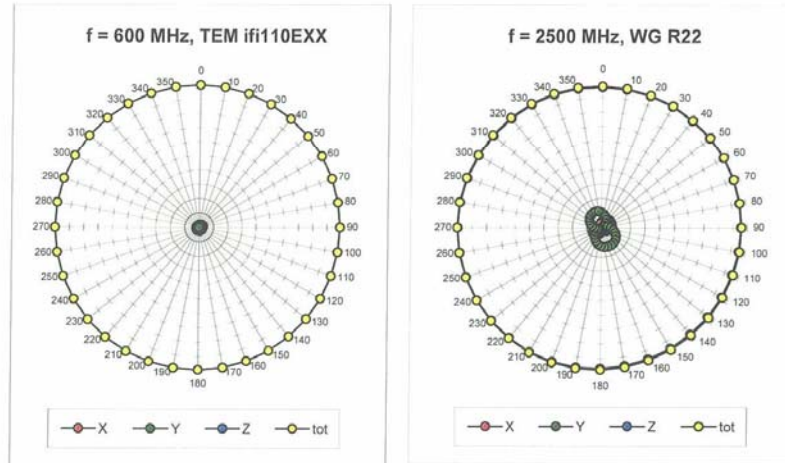
Uncertainty of Frequency Response of H-field:  $\pm 6.3\%$  (k=2)



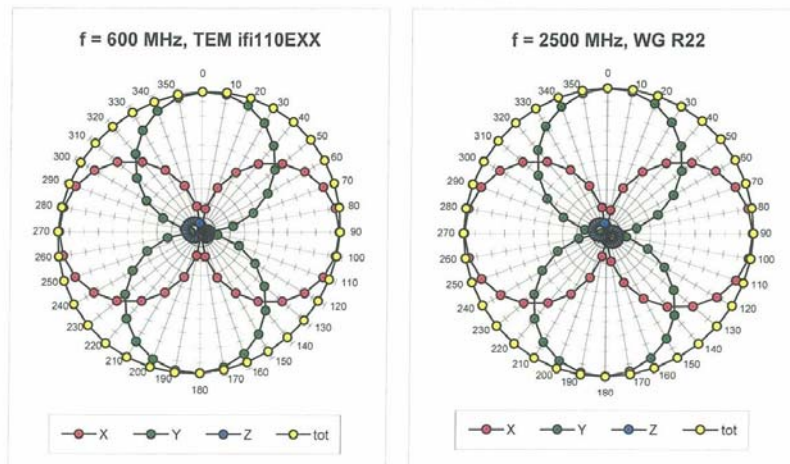
H3DV6 SN:6051

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**Receiving Pattern ( $\phi$ ),  $\vartheta = 90^\circ$**



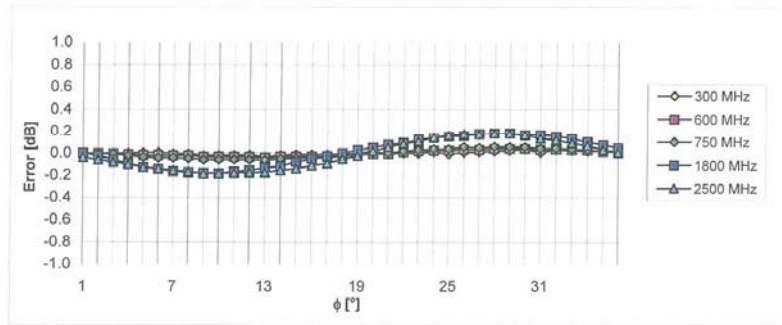
**Receiving Pattern ( $\phi$ ),  $\vartheta = 0^\circ$**



H3DV6 SN:6051

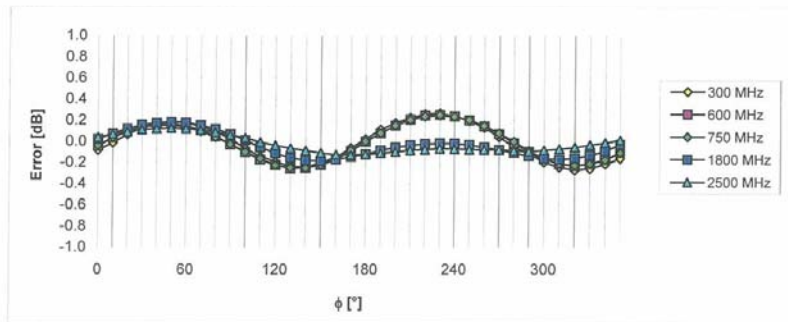
September 20, 2010

### Receiving Pattern ( $\phi$ ), $\vartheta = 90^\circ$



Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  ( $k=2$ )

### Receiving Pattern ( $\phi$ ), $\vartheta = 0^\circ$

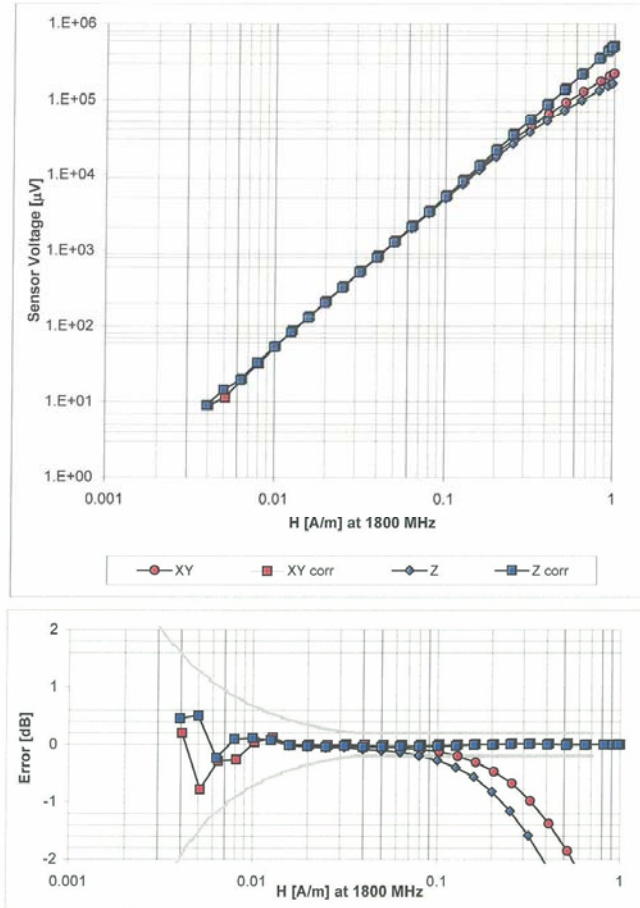


Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  ( $k=2$ )

H3DV6 SN:6051

September 20, 2010

**Dynamic Range f(H-field)**  
(Waveguide R22, f = 1800 MHz)

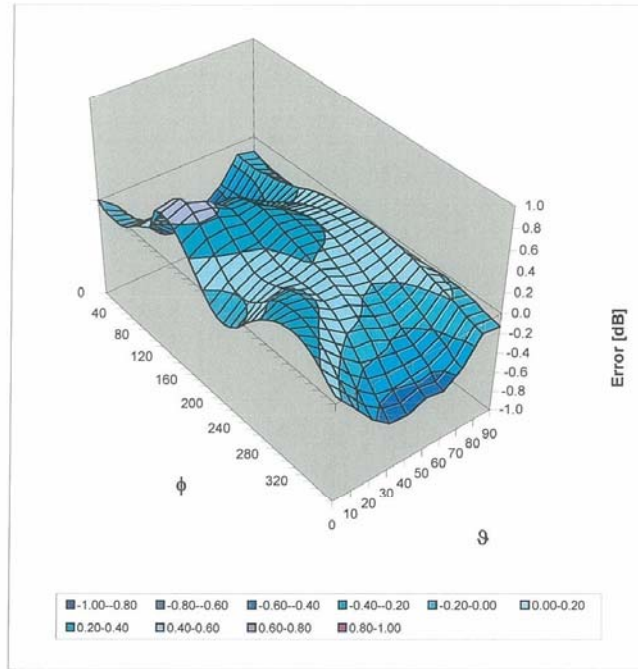


Uncertainty of Linearity Assessment:  $\pm 0.6\%$  (k=2)

H3DV6 SN:6051

September 20, 2010

### Deviation from Isotropy in Air Error ( $\phi, \theta$ ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment:  $\pm 2.6\%$  ( $k=2$ )

H3DV6 SN:6051

September 20, 2010

**Other Probe Parameters**

Sensor Arrangement	Rectangular
Connector Angle (°)	-213.8
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6.0 mm
Probe Tip to Sensor X Calibration Point	3 mm
Probe Tip to Sensor Y Calibration Point	3 mm
Probe Tip to Sensor Z Calibration Point	3 mm