

EUROFINS PRODUCT SERVICE GMBH

# SAR Test - Report

**SAR Compliance Test Report** 

Test report no.:

G5M209010002-S-8

Eurofins Product Service GmbH Storkower Str. 38c, 15526 Reichenwalde, Germany

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# 1 General Information

#### 1.1 Notes

The purpose of conformity testing is to increase the probability of adherence to the essential requirements or conformity specifications, as appropriate.

The complexity of the technical specifications, however, means that full and thorough testing is impractical for both technical and economic reasons.

Furthermore, there is no guarantee that a test sample which has passed all the relevant tests conforms to a specification.

The existence of the tests nevertheless provides the confidence that the test sample possesses the qualities as maintained and that is performance generally conforms to representative cases of communications equipment.

The test results of this test report relate exclusively to the item tested as specified in 1.5.

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I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualification of all persons taking them.

## **Operator:**

05.03.2009

Date

B. Pudell

Name

T. Jahn

Name

Signature

#### Technical responsibility for area of testing:

Eurofins

Eurofins -Lab.

05.03.2009

Signature



#### 1.2 Testing laboratory

#### 1.2.1 Location

EUROFINS PRODUCT SERVICE GMBH Storkower Straße 38c D-15526 Reichenwalde b. Berlin Germany Telephone : +49 33631 888 00 Fax : +49 33631 888 660

#### **1.2.2** Details of accreditation status

#### DAR ACCREDITED TESTING LABORATORY

DAR-REGISTRATION NUMBER: DAT-P-268/08

#### **RECOGNIZED NOTIFIED BODY EMC** REGISTRATION NUMBER: BNetzA-bS EMV-07/61

#### RECOGNIZED NOTIFIED BODY R&TTE REGISTRATION NUMBER: BNetzA-bS-02/51-53

# FCC FILED TEST LABORATORY

REG.-NO. 96970

# A2LA ACCREDITED TESTING LABORATORY

CERTIFICATE NO. 1983.01

# BLUETOOTH QUALIFICATION TEST FACILITY (BQTF)

ACCREDITED BY BLUETOOTH QUALIFICATION REVIEW BOARD

## INDUSTRY CANADA FILED TEST LABORATORY

REG. NO. IC 3470

**Statement:** The tests documented within this report are carried out in accordance with the scope of accreditation of test laboratory Eurofins Product Service GmbH.

#### 1.3 Details of approval holder

Name	: Pantech Co., Ltd.
Street	: Pantech Bldg, I-2 DMC, Sangam-dong
Town	: Mapo-gu, Seoul
Country	: Korea
Telephone	: +82-2-2030-1320
Fax	: +82-2-2030-2519
Contact	: Mr. B.W. Kim
E-Mail	: bwkim@pantech.com
	. DWRITI@partcon.com



## **1.4** Manufacturer: (if applicable)

Name	:
Street	:
Town	:
Country	:

# 1.5 Application details

Date of receipt of application	: 20.01.2009
Date of receipt of test item	: 20.01.2009
Date of test	: 26.02.2009 - 28.02.2009

#### 1.6 Test item

FCC ID	: JYCC570	
Description of test item	: GSM phone	
Type identification	: C570	Brand Name:Kate
Serial number	: without; Identical proto	type
Device category	: PCE ( Licensed Portal	ble Transmitter held to ear)

#### Technical data

<u>GSM / PCS / EGPRS</u> Frequency range	: <u>GSM 850 / EGPRS</u>	PCS 1900 / / EGPRS	
TX Frequency range	: 824.2 - 848.8 MHz	1850.2 - 1909.9 MHz	
RX Frequency range	: 869.2 - 893.8 MHz	1930.2 - 1989.8 MHz	
Max. Cond GSM RF output power	: 33,21 dBm (2,09 W)	30,14 dBm (1,03 W)	
Max. Cond Edge RF output power	: 32,97 dBm (1,98 W)	29,72 dBm (0,94 W)	
Power supply	: 3.8 V DC rechargeable battery		
Antenna Tx	: integral		
Antenna RX	: integral		
Additional information	: Tx and Rx. antenna are the same. This test sample was tested according FCC OET Bulletin Supplement C, Edition 01-01 on the used Frequency band		

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65,



#### 1.7 Test Results

Max. SAR Measurement GSM (Head)	: 0,778 W/kg (averaged over 1 gram)
Max. SAR Measurement GSM (Body)	: 0,921 W/kg (averaged over 1 gram)
Max. SAR Measurement PCS (Head)	: 0,400 W/kg (averaged over 1 gram)
Max. SAR Measurement PCS (Body)	: 1,02 W/kg (averaged over 1 gram)
Max. SAR Measurement GPRS 850 (Body)	: 1,23 W/kg (averaged over 1 gram)
Max. SAR Measurement GPRS 1900 (Body)	: 1,23 W/kg (averaged over 1 gram)
Max. SAR Measurement EGPRS 850 (Body)	: 0,935 W/kg (averaged over 1 gram)
Max. SAR Measurement EGPRS 1900 (Body)	: 1,00 W/kg (averaged over 1 gram)

This EUT has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC/OET Bulletin 65 Supplement C (2001) and IEEE Std. 1528-2003, December 2003.

#### 1.8 Test standards

Standards	: -	IEEE Std. 1528-2003, December 2003
FCC Rule Part(s)	: -	FCC OET Bulletin 65, Supplement C, Edition 01-01



#### 2 Technical test

#### 2.1 Summary of test results

#### **Applicable Configuration**

Handset (Head)	Х
Handset (Body)	Х
Headset (Head)	
Body Worn Equipment	

EUT complies with the RF radiation exposure limits of the FCC as shown by the SAR measurement results. These measurements are taken to simulate the RF effects exposure under worst-case conditions. The EUT complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease). Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables. [1]

In case of multiple hotspots the secondary hotspots within 2 dB of the maximum SAR value will be recorded and displayed in the measurement plots. The secondary hotspots with a peak SAR value below 0.5 W/kg will not be measured by the system, due to the high margin to the limits.

#### 2.2 Test environment

Room temperature	: 22.	1 - 22	.6 ° C
Liquid temperature	: 22.0	) - 22	.3 ° C
Relative humidity content	: 20		75 %
Air pressure	: 86		103 kPa
Details of power supply	: 3.8	V DC	



## 2.3 Test equipment utilized

No. Measurement device:		Туре:	Manufacturer:	
ETS 0449	Stäubli Robot	RX90B L	Stäubli	
ETS 0450	Stäubli Robot Controller	CS/MBs&p	Stäubli	
ETS 0451 DASY 4 Measurement Server			Schmid & Partner	
ETS 0452	Control Pendant		Stäubli	
ETS 0453	Compaq Computer	Pentium IV, 2 GHz,	Schmid & Partner	
ETS 0454	Dabu Acquisition Electronics	DAE3V1	Schmid & Partner	
ETS 0455	Dummy Probe		Schmid & Partner	
ETS 0456	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner	
ETS 0457	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner	
ETS 0458	Dosimetric H-Field Probe	H3DV6	Schmid & Partner	
ETS 0479	System Validation Kit	D300V3	Schmid & Partner	
ETS 0480	System Validation Kit	D450V3	Schmid & Partner	
ETS 0459	System Validation Kit	D900V2	Schmid & Partner	
ETS 0460	System Validation Kit	D1800V2	Schmid & Partner	
ETS 0461	System Validation Kit	D1900V2	Schmid & Partner	
ETS 0462	System Validation Kit	D2450V2	Schmid & Partner	
ETS 0463	Probe Alignment Unit	LBV2	Schmid & Partner	
ETS 0464	SAM Twin phantom	V 4.0	Schmid & Partner	
ETS 0513	Flat phantom	V 4.4	Schmid & Partner	
ETS 0467	Oval flat phantom	ELI 4	Schmid & Partner	
ETS 0465	Mounting Device	V 3.1	Schmid & Partner	
ETS 0224a	Millivoltmeter	URV 5	Rohde & Schwarz	
ETS 0219	Power sensor	NRV-Z2	Rohde & Schwarz	
ETS 0268	RF signal generator	SMP 02	Rohde & Schwarz	
ETS 0322	Insertion unit	URV5-Z4	Rohde & Schwarz	
ETS 0466	Directional Coupler	HP 87300B	HP	
ETS 0231	Radio Communication Tester	CMD65	Rohde & Schwarz	
ETS 0484	Universal Radio Communication Tester	CMU 200	Rohde & Schwarz	
ETS 0468	Network Analyzer 300 kHz to 3 GHz	8753C	Agilent	
ETS 0469	Dielectric Probe Kit	85070C	Agilent	



#### 2.4 Definitions

#### 2.4.1 SAR

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy (*dW*) absorbed by (dissipated in) an incremental mass (*dm*) contained in a volume element (*dV*) of a given density ( $\rho_t$ ), expressed in watts per kilogram (W/kg).

SAR = 
$$\frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho_t dV} \right) = \frac{\sigma}{\rho_1} |E_t|^2$$

where:

$$\frac{dW}{dt} = \int_{V} E \cdot J \, dV = \int_{V} \sigma E^2 dV$$

#### 2.4.2 Uncontrolled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category, and the general population/uncontrolled exposure limits apply to these devices. [2].

#### 2.4.3 Controlled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on methods to minimize such exposure risks. [2].



#### 2.5 Measurement System Description

#### 2.5.1 System Setup

Measurements are performed using the DASY4 automated dosimetric assessment system (figure 1) made by Schmid & Partner Engineering AG (SPEAG)in Zurich, Switzerland.



Figure 1

The DASY4 system for performing compliance tests consists of the following items:

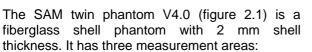
- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, ADconversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- An unit to operate the optical surface detector which is connected to the EOC.
- The Electro-optical converter (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the measurement server.
- The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows NT.
- DASY4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes (see Application Notes).
- System validation dipoles allowing to validate the proper functioning of the system.



#### 2.5.2 Phantom Description



(Figure 2.1)



- Left hand
- Right hand
- Flat phantom

The phantom is integrated in a wooden table.

The bottom plate of the table contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids).

A cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible.

On the phantom top, three reference markers are provided to identify the phantom positions with respect to the robot.



(Figure 2.2)

The Oval flat phantom (ELI 4) (figure 2.3) is a fiberglass shell phantom with 2 mm thickness.



# 2.5.3 Tissue Simulating Liquids

The parameters of the tissue simulating liquid strongly influence the SAR. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE P1528-2003.)

Tissue dielectric properties

	Head		Bo	ody
Frequency (MHz)	Relative Dielectric Constant (ε <sub>r</sub> )	Conductivity (σ) (S/m)	Relative Dielectric Constant (ε <sub>r</sub> )	Conductivity (σ) (S/m)
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
1450	40.5	1.20	54.0	1.30
1800	40.0	1.40	53.3	1.52
1900	40.0	1.40	53.3	1.52
2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73



#### 2.5.4 Device Holder

The DASY device holder (figure 3.1 and 3.2) is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The rotation centers for both scales is the ear opening. Thus the device needs no repositioning when changing the angles.



Figure 3.1

Figure 3.2

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



#### 2.5.5 Probes

The SAR measurements were conducted with the dosimetric probe ET3DV6 (figure 4), designed in the classical triangular configuration and optimized for dosimetric evaluation. [3] The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2<sup>nd</sup> order fitting. The approach is stopped at reaching the maximum.



Figure 4

#### Probe Specifications

Calibration:	In air from 10 MHz to 2.5 GHz In brain and muscle simulating tissue at Frequencies of 835 MHz, 900 MHz, 1800 MHz, 1900 MHz and 2450 MHz Calibration certificates please find attached.
Frequency:	10 MHz to > 3 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)
Directivity:	$\pm$ 0.2 dB in HSL (rotation around probe axis) $\pm$ 0.4 dB in HSL (rotation normal probe axis)
Dynamic Range:	5 μW/g to > 100 mW/g;
Linearity:	± 0.2 dB
Dimensions:	Overall length: 330 m Tip length: 16 mm Body diameter: 12 mm Tip diameter: 6.8 mm Distance from probe tip to dipole centers: 2.7 mm
Application:	General dosimetry up to 3 GHz Compliance tests of mobile phones Fast automatic scanning in arbitrary phantoms



Thickness:

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## 2.6 Test System Specification

Positioner Robot: Repeatability: No. of axis:	Stäubli Animation Corp. Robot Model: RX90B L 0.02 mm 6
Data Acquisition Electronic (DAE) S Cell Controller Processor: Clock Speed: Operating System: Data Card: Data Converter Features: Software: Connecting Lines:	System Pentium IV 2.0 GHz Windows 2000 DASY4 PC-Board Signal Amplifier, multiplexer, A/D converter, & control logic DASY4 software Optical downlink for data and status info. Optical uplink for commands and clock
<b>PC Interface Card</b> Function:	24 bit (64 MHz) DSP for real time processing Link to DAE3 16 bit A/D converter for surface detection system serial link to robot direct emergency stop output for robot
E-Field Probes Model: Construction: Frequency: Linearity:	ET3DV6 SN1711 Triangular core fiber optic detection system 10 MHz to 6 GHz ± 0.2 dB (30MHz to 3 GHz)
Phantom Phantom 1: Shell Material: Thickness: Phantom 2:	Oval flat phantom (ELI 4) Fiberglass $2.0 \pm 0.2 \text{ mm}$ Flat Phantom (V4.4)
Phantom 2: Shell Material: Thickness:	Flat Phantom (V4.4) Fiberglass $6.0 \pm 0.2 \text{ mm}$
Phantom 3: Shell Material:	SAM Twin Phantom (V4.0) Fiberglass

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 $2.0\pm0.2\ mm$ 



#### 2.7 Measurement Procedure

The evaluation was performed using the following procedure:

- 1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing. This fixed location point was measured and used as a reference value.
- 2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9 mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 10 mm x 10 mm.
- 3. Based on the area scan data, the area of the maximum absorption was determined by spline interpolation. Around this point, a volume of 30 mm x 30 mm x 30 mm (fine resolution volume scan, zoom scan) was assessed by measuring 5 x 5 x 5 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure:
  - a. The data at the surface was extrapolated, since the center of the dipoles is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2 mm. The extrapolation was based on a least square algorithm [4]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
  - b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g or 10 g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y, and z directions) [4] [5]. The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
  - c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
- 4. The SAR reference value, at the same location as procedure # 1, was re-measured. If the value changed by more than 5 %, the evaluation is repeated.



#### 2.8 Reference Points

#### 2.8.1 Ear Reference Points

Figure 5.1 shows the front, back and side vies of SAM. The point "M" is the reference point for the center of mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15 mm posterior to the entrance to ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 5.2. The plane passing through the two ear reference points and M is defined as the Reference Plane. The line N-F (Neck-Front) perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 5.3). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines should be marked on the external phantom shell to facilitate handset positioning. Posterior to the N-F line, the thickness of the N-F line, the ear is truncated as illustrated in Figure 5.2. The ear truncation is introduced to avoid the handset from touching the ear lobe, which can cause unstable handset positioning at the cheek. [6]

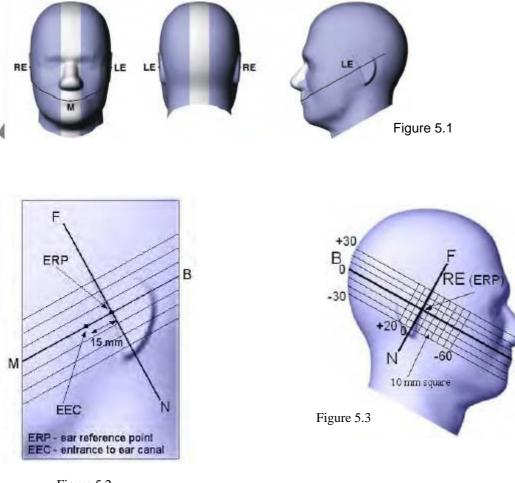
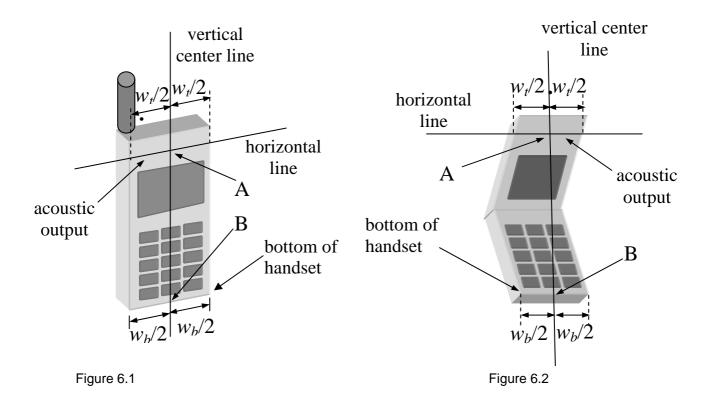


Figure 5.2



#### 2.8.2 Handset Reference Points

Two imaginary lines on the handset were defined: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width *wt* of the handset at the level of the acoustic output (point A on Figures 6.1 and 6.2), and the midpoint of the width *wb* of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 6.1). The two lines intersect at point A. For many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. The vertical centerline is not necessarily parallel to the front face of the handset (see Figure 6.2), especially for clamshell handsets, handsets with flip pieces, and other irregularly-shaped handsets. [6]





#### 2.9 Test Positions

#### 2.9.1 "Cheek" / "Touch" Position

The EUT was positioned close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 7), such that the plane defined by the vertical center line and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.

The EUT was translated towards the phantom along the line passing through RE and LE until the handset touches the pinna.

While maintaining the handset in this plane, the EUT was rotated it around the LE-RE line until the vertical centerline was in the plane normal to MB-NF including the line MB (called the reference plane).

The EUT was rotated around the vertical centerline until the handset (horizontal line) was symmetrical with respect to the line NF.

While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the handset contact with the pinna, the EUT was rotated about the line NF until any point on the handset was in contact with a phantom point below the pinna (cheek). [6] See Figure 7.



Figure 7



#### 2.9.2 "Tilted" Position

The EUT was in "cheek position".

While maintaining the orientation of the handset move the handset away from the pinna along the line passing through RE and LE in order to enable a rotation of the handset by 15 degrees.

The EUT was rotated around the horizontal line by 15 degrees.

While maintaining the orientation of the handset, the EUT was moved towards the phantom on a line passing through RE and LE until any part of the handset touched the ear. The tilted position is obtained when the contact is on the pinna. If the contact was at any location other than the pinna (e.g., the antenna with the back of the phantom head), the angle of the handset would be reduced. In this case, the tilted position is obtained if any part of the handset was in contact with the pinna as well as a second part of the handset was in contact with the back of the head). [6] See Figure 8.



Figure 8



## 2.9.3 Belt Clip/Holster Configuration

Test configurations for body-worn operated EUTs are carried out while the belt-clip and/or holster is attached to the EUT and placed against a flat phantom in a regular configuration (see Figure 9). An EUT with a headset output is tested with a headset connected to the device.

Body dielectric parameters are used.

There are two categories for accessories for body-worn operation configurations:

- 1. accessories not containing metallic components
- 2. accessories containing metallic components.

When the EUT is equipped with accessories not containing metallic components the tests are done with the accessory that dictates the closest spacing to the body. For accessories containing metallic parts a test with each one is implemented. If the multiple accessories share an identical metallic component (e.g. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that has the closest spacing to the body is tested.

In case that a EUT authorized to be body-worn is not supplied or has no options to be operated with any accessories, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented.

Transmitters operating in front of a person's face (e.g. push-to-talk configurations) are tested for SAR compliance with the front of the device positioned to face the flat platform. SAR Compliance tests for shoulder, waist or chest-worn transmitters are carried out with the accessories including headsets and microphones attached to the device and placed against a flat phantom in a regular configuration.

The SAR measurements are performed to investigate the worst-case positioning. This is documented and used to perform Body SAR testing. [2].



Figure 9



### 2.9.4 Headset Configuration

Headsets which have their radiating structure in close proximity to the head are measured according to the following conditions.

- Head tissue liquid is used.
- The EUT is positioned on the surface of the head of phantom according the picture below. Right and left position is tested according to the normal use (see figure 10).
- Additional metallic parts like clips or others are subject of testing, too.



Figure 10

Headsets which have their radiating structure in close proximity to the body are tested as body worn equipment.



#### 2.10 Measurement uncertainty

The uncertainty budget has been determined for the DASY4 system performance check according to IEEE Std. 1528-2003 December 2003.

	Tol.	Prob.	Div.	( <sup>c</sup> i) <sup>1</sup>	Std. unc.	( <sup>v</sup> i) <sup>2</sup>
Error Description	(± %)	dist.		(1 g)	(1 g) (± %)	•
Measurement System						
Probe Calibration	4.8	N	1	1	4.8	$\infty$
Axial Isotropy	4.7	R	<sup>∨</sup> З	0.7	1.9	$\infty$
Hemispherical Isotropy	9.6	R	<sup>∨</sup> З	0.7	3.9	$\infty$
Boundary Effects	1.0	R	<sup>∨</sup> З	1	0.6	$\infty$
Linearity	4.7	R	<sup>∨</sup> З	1	2.7	$\infty$
System Detection Limit	1.0	R	<sup>v</sup> 3	1	0.6	$\infty$
Readout Electronics	1.0	N	1	1	1.0	$\infty$
Response Time	0.8	R	<sup>∨</sup> З	1	0.5	$\infty$
Integration Time	2.6	R	<sup>v</sup> 3	1	1.5	$\infty$
RF Ambient Conditions	3.0	R	<sup>∨</sup> 3	1	1.7	$\infty$
Probe Positioner	0.4	R	<sup>v</sup> 3	1	0.2	$\infty$
Probe Positioning	2.9	R	<sup>∨</sup> 3	1	1.7	$\infty$
Algorithms for Max. SAR Eval.	1.0	R	<sup>∨</sup> З	1	0.6	$\infty$
Test Sample Related						
Device Positioning	2.9	N	1	1	2.9	145
Device Holder	3.6	N	1	1	3.6	5
Power Drift	5.0	R	<sup>∨</sup> 3	1	2.9	$\infty$
Phantom and Setup						
Phantom Uncertainty	4.0	R	<sup>√</sup> 3	1	2.3	$\infty$
Liquid Conductivity (target)	5.0	R.	<sup>∨</sup> 3	0.64	1.8	$\infty$
Liquid Conductivity (meas.)	2.6	Ν	1	0.64	1.7	$\infty$
Liquid Permittivity (target)	5.0	R	<sup>∨</sup> 3	0.6	1.7	$\infty$
Liquid Permittivity (meas.)	3.8	Ν	1	0.6	2.3	$\infty$
Combined Standard Uncertainty					10.4	330
Expanded Uncertainty kp = 2						
Coverage Factor for 95 %					20.8	

The budget is valid for the frequency range 300 MHz - 3 GHz and represent a worst case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



#### 3 Tissue and System Verification

#### 3.1 Tissue Verification

Dielectric parameters of the simulating liquids were verified using a Dielectric Probe Kit Agilent 85070D to a tolerance of  $\pm$  5 %.

#### Room Temperature: 22.1 - 22.6 ° C

		Measured Tissue Parameters				
	900 M	Hz Head	1900 MH	Iz Head		
	Target	Target Measured		Measured		
Date:		27.02.2009		26.02.2009		
Liquid Temperature: °C		22,1		22,0		
Dielectric Constant: ε	41,5	40,5	40,0	39,9		
Conductivity: σ	0,97	0.944	1,40	1,42		

Room Temperature: 22.1 - 22.6 ° C

		Measured Tissue Parameters				
	900 MH	z Muscle	1900 MHz	z Muscle		
	Target Measured		Target	Measured		
Date:		28.02.2009		27.02.2009		
Liquid Temperature: ° C		22,1		22,1		
Dielectric Constant: ε	55,0	54,1	53,3	51,9		
Conductivity: σ	1,05	1,01	1,52	1,58		



## 3.2 System Verification

Prior to the assessment, the system was verified by using a 1900 MHz validation dipole. Power level of 250 mW was supplied to the dipole antenna placed under the flat section of SAM Phantom. This system validation is valid for a frequency range of 1900  $\pm$  100 MHz.

The system was verified to a tolerance of  $\pm$  10 %.

Liquid Temperature:	22.0 - 22.3 ° C
Room Temperature:	22.1 - 22.6 ° C
Liquid Depth:	>15.5 cm

System Dipole Validation Target & Measurement						
Date	System Validation Kit:	Liquid	Targeted SAR 1 g (mW/g)	Measured SAR 1 g (mW/g)	Deviation (%)	
27.02.2009	D900V2 SN164	900 MHz Head	10,2	10,92	7,05	
28.02.2009	D900V2 SN164	900 MHz Muscle	11,2	10,76	-3,92	
26.02.2009	D1900V2 SN5d025	1900 MHz Head	40,4	42,40	4,95	
27.02.2009	D1900V2 SN5d025	1900 MHz Muscle	45,6	46,00	0,87	

Comment: Please find attached the measurement plots.



#### 4 Test Results

#### Procedures Used To Establish Test Signal

The EUT was placed into simulated call mode (e.g. AMPS, Cellular CDMA & PCS CDMA modes) using manufacturers test codes. Such test signals offer a consistent means for testing SAR and are recommended for evaluating SAR [2]. The actual transmission is activated through a base station simulator or similar when test modes are not available or inappropriate for testing the EUT.

The EUT is rechargeable battery operated. The battery used for the SAR measurements was completely charged. The device was tested at full power verified by implementing conducted output power measurements. For confirming of the output power it was tested before and after each SAR measurement. The test was repeated if a conducted power deviation of more than 5 % occurred.

Frequency band:	GSM 850
Mixture Type:	900 MHz Head
Date:	27.02.2009
Liquid Temperature:	22.0 - 22.3 ° C

Room Temperature: 22.1 - 22.6 °C

	Frequency		Power Drift	Antenna	Phantom	Test Position	SAR
MHz	Channel	Modulation	dBm	Pos.	Section		(W/kg)
	128	GSM	-0.033	Integral	Right Ear	Cheek	0.615
836,4	189	GSM	-0.128	Integral	Right Ear	Cheek	0.675
836,4	189	GSM	-0.101	Integral	Right Ear	Tilted	0.384
848,8	251	GSM	-0.079	Integral	Right Ear	Cheek	0.778
836,4	189	GSM	-0.032	Integral	Left Ear	Cheek	0.672
836,4	189	GSM	-0.139	Integral	Left Ear	Tilted	0.355

Mixture	Type:
Date:	

900 MHz Muscle 28.02.2009

Frequency				Phantom	Test Position	SAR	
MHz	Channel	Modulation	dBm	Pos.	Section	10 mm	(W/kg)
836,4	189	GSM	-0.142	Integral	Flat	Front	0.749
836,4	189	GSM	-0.037	Integral	Flat	Back	0.921



Frequency band:	PCS 1900
Mixture Type:	1900 MHz Head
Date:	26.02.2009
Liquid Temperature:	22.0 - 22.3 ° C

Room Temperature: 22.1 - 22.6 °C

Frequency		Power Drift	Antenna	Phantom	Test Position	SAR (W/kg)	
MHz	Channel	Modulation	dBm	Pos.	Section		(W/kg)
1850,2	512	GSM	0.055	Integral	Right Ear	Cheek	0.347
1880,0	661	GSM	-0.102	Integral	Right Ear	Cheek	0.400
1880,0	661	GSM	-0.029	Integral	Right Ear	Tilted	0.085
1909,8	810	GSM	-0.059	Integral	Right Ear	Cheek	0.397
1880,0	661	GSM	-0.149	Integral	Left Ear	Cheek	0.325
1880,0	661	GSM	-0.195	Integral	Left ear	Tilted	0.118

Note: Upper and lower frequencies were measured at the worst position.

Mixture	Type:
Date:	

1900 MHz Muscle 27.02.2009

Frequency		Power Drift Antenna		Phantom	Test Position	SAR	
MHz	Channel	Modulation	dBm	Pos.	Section	10 mm	(W/kg)
1880,0	661	GSM	-0.048	Integral	Flat	Front	0.376
1880,0	661	GSM	-0.001	Integral	Flat	Back	1.02

Note: Upper and lower frequencies were measured at the worst position.



Frequency band: Mixture Type: Date: GPRS 850 900 MHz Muscle 28.02.2009

Frequency		Power Drift	Antenna Phantom	Test Position	SAR		
MHz	Channel	Modulation	dBm	Pos.	Section	10 mm	(W/kg)
824,2	128	GPRS	0,098	Integral	Flat	Back	1.23
836,4	189	GPRS	-0.043	Integral	Flat	Back	1.11
848,8	251	GPRS	-0.147	Integral	Flat	Back	0.977

Frequency band: Mixture Type: Date: GPRS 1900 1900 MHz Muscle 27.02.2009

Frequency		Power Drift Antenna		Phantom	Test Position	SAR	
MHz	Channel	Modulation	dBm	Pos.	Section	10 mm	(W/kg)
1850,2	512	GPRS	-0.018	Integral	Flat	Back	0.920
1880.0	661	GPRS	-0.121	Integral	Flat	Back	1.17
1909.8	810	GPRS	-0.034	Integral	Flat	Back	1.23

Frequency band: Mixture Type: Date: EGPRS 850 900 MHz Muscle 28.02.2009

Frequency		Power Drift Antenna		Phantom	Test Position	SAR	
MHz	Channel	Modulation	dBm	Pos.	Section	10 mm	(W/kg)
836,4	189	EGPRS	-0.100	Integral	Flat	Back	0.935

Frequency band: Mixture Type: Date: EGPRS 1900 1900 MHz Muscle 27.02.2009

Frequency		Power Drift Antenna		Phantom	Test Position	SAR	
MHz	Channel	Modulation	dBm	Pos.	Section	10 mm	(W/kg)
1880.0	661	EGPRS	0,021	Integral	Flat	Back	1.00



Limits:

	SAR (W/kg)						
Exposure Limits	Uncontrolled Exposure/General Population Environment			Controlled Exposure/Occupational Environment			
Region	Australia	US	EU	Australia	US	EU	
Spatial Average SAR (averaged over the whole body)	0.08	0.08	0.08	0.40	0.40	0.40	
Spatial Peak SAR (averaged over any 1 g of tissue)	2.00	1.60	2.00	10.0	8.00	10.0	
Spatial Peak SAR (Hands, Feet, Ankles, Wrist) (averaged over any 10 g of tissue)	4.00	4.00	4.00	20.0	20.0	20.0	

Notes:

- 1. Test data represent the worst case SAR value and test procedure used are according to OET Bulletin 65, Supplement C (01-01).
- 2. All modes of operation were investigated.



#### 5 References

- [1] ANSI/IEEE C95.3 1991, IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic fields, 300 kHz to 100 GHz, New York: IEEE, Aug. 1992
- [2] Federal Communications Commission, OET Bulletin 65 (Edition 97-01), Supplement C (Edition 01-01), Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields, July 2001.
- [3] T. Schmid, O. Egger, N. Kuster, *Automated E-field scanning system for dosimetric assessments,* IEEE Transaction on Microwave Theory and Techniques, vol. 44, Jan. 1996, pp. 105-113.
- [4] W. Gander, *Computer mathematics*, Birkhaeuser, Basel, 1992.
- [5] W.H. Press, S.A. Teukolsky, W.T. Vetterling, and B.P. Flannery, *Numerical Recipes in C*, The Art of Scientific Computing, Second edition, Cambridge University Press, 1992.
- [6] IEEE Standards Coordinating Committee 34 IEEE Std. 1528-2003, December 2003 Recommended Practice for Determining the Peak Spatial-Average Absorption Rate (SAR in the Human Body Due to Wireless Communications Devices: Experimental Techniques.
- [7] DASY4 *Dosimetric Assessment System Manual*; Draft; September 6, 2002; Schmid & Partner Engineering AG



6	Annex		
1.	Annex A	Calibration Certificate	D1900V2 SN5d025 D900V2 SN164 ET3DV6 SN1711 DAE3V1-522
2.	Annex B	Measurement Plots	
3.	Annex C	Pictures	



Annex A

### **Calibration Certificate**

Note:

The calibration cycle for SAR field probes and related equipment is determined to one year. According to Eurofins's internal quality management instruction based on EN 17025 the calibration cycle for other test equipment is determined to 2 years. Additionally, Eurofins has prolonged the calibration interval for SPEAG System Validation Dipoles by two additional years. These QM procedures are acknowledged by the accreditation bodies mentioned on page 3 of this report during several accreditation audits.

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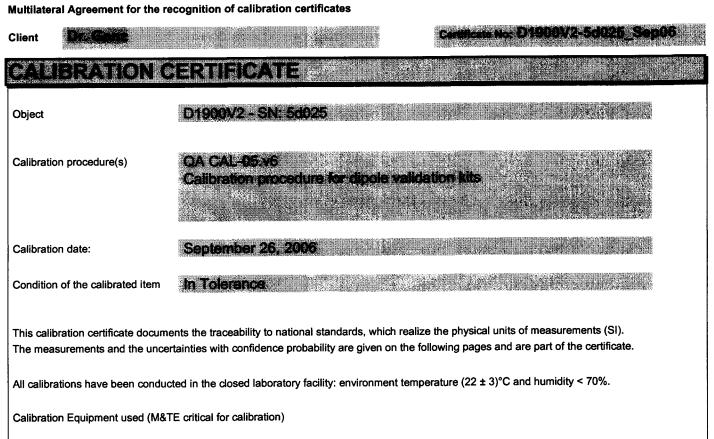
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S



	l		Scheduled Calibration
Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	
Power meter EPM-442A	GB37480704	04-Oct-05 (METAS, No. 251-00516)	Oct-06
Power sensor HP 8481A	US37292783	04-Oct-05 (METAS, No. 251-00516)	Oct-06
Reference 20 dB Attenuator	SN: 5086 (20g)	10-Aug-06 (METAS, No 217-00591)	Aug-07
Reference 10 dB Attenuator	SN: 5047.2 (10r)	10-Aug-06 (METAS, No 217-00591)	Aug-07
Reference Probe ET3DV6	SN: 1507	28-Oct-05 (SPEAG, No. ET3-1507_Oct05)	Oct-06
Reference Probe ES3DV3	SN: 3025	28-Oct-05 (SPEAG, No. ES3-3025_Oct05)	Oct-06
DAE4	SN: 601	15-Dec-Q5 (SPEAG, No. DAE4-601_Dec05)	Dec-06
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (SPEAG, in house check Oct-05)	In house check: Oct-07
RF generator Agilent E4421B	MY41000675	11-May-05 (SPEAG, in house check Nov-05)	In house check: Nov-07
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (SPEAG, in house check Nov-05)	In house check: Nov-06
	Name	Function	Signature
Calibrated by:	Marcel Fehr	Laboratory Technician	II Alex
			VI-par
Approved by:	Katta Pokovic	. Technical Manager	the ships
			Issued: September 27, 2006
This calibration certificate shall n	ot be reproduced except in	full without written approval of the laboratory.	

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#### **Glossary**:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

## Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

#### **Additional Documentation:**

d) DASY4 System Handbook

#### Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed • point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole • positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point. • No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna • connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the • nominal SAR result.

#### **Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY4	V4.7
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V5.0	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	1900 MHz ± 1 MHz	

## Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	40.0	1.40 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	38.6 ± 6 %	1.41 mho/m ± 6 %
Head TSL temperature during test	(21.6 ± 0.2) °C		

## SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	condition	
SAR measured	250 mW input power	9.65 mW / g
SAR normalized	normalized to 1W	38.6 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	37.7 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	5.11 mW / g
SAR normalized	normalized to 1W	20.4 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	20.1 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>1</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

# **Body TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	53.3	1.52 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	52.7 ± 6 %	1.56 mho/m ± 6 %
Body TSL temperature during test	(22.4 ± 0.2) °C		

# SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	10.2 mW / g
SAR normalized	normalized to 1W	40.8 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	39.9 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	condition	
SAR measured	250 mW input power	5.40 mW / g
SAR normalized	normalized to 1W	21.6 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	21.3 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>2</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

### Appendix

### **Antenna Parameters with Head TSL**

Impedance, transformed to feed point	53.8 Ω + 4.5 jΩ
Return Loss	- 24.9 dB

### Antenna Parameters with Body TSL

Impedance, transformed to feed point	47.3 Ω + 3.9 jΩ
Return Loss	- 26.3 dB

### **General Antenna Parameters and Design**

Electrical Delay (one direction)	1.198 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

### Additional EUT Data

Manufactured by	SPEAG	
Manufactured on	July 29, 2002	

### **DASY4 Validation Report for Head TSL**

Date/Time: 26.09.2006 13:01:39

Test Laboratory: SPEAG, Zurich, Switzerland

### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d025

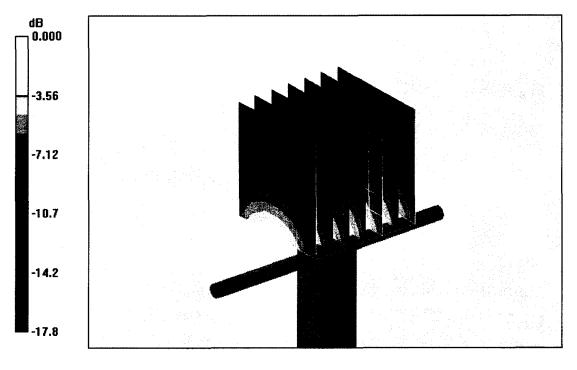
Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1 Medium: HSL U10 BB; Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.41 mho/m;  $\epsilon_r$  = 38.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

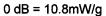
DASY4 Configuration:

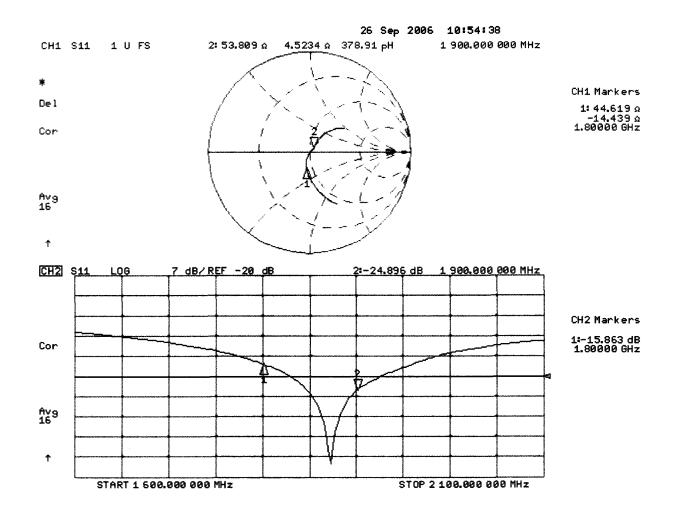
- Probe: ET3DV6 SN1507 (HF); ConvF(4.74, 4.74, 4.74); Calibrated: 28.10.2005
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 15.12.2005
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; ;
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

### Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 93.1 V/m; Power Drift = 0.007 dB Peak SAR (extrapolated) = 16.4 W/kg SAR(1 g) = 9.65 mW/g; SAR(10 g) = 5.11 mW/g Maximum value of SAR (measured) = 10.8 mW/g







### Impedance Measurement Plot for Head TSL

### **DASY4 Validation Report for Body TSL**

Date/Time: 20.09.2006 11:37:46

Test Laboratory: SPEAG, Zurich, Switzerland

### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d025

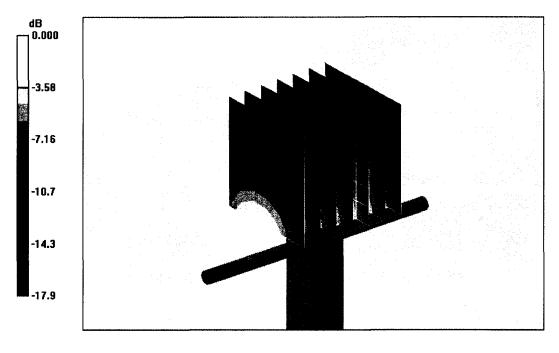
Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1 Medium: MSL U10; Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.56 mho/m;  $\epsilon_r$  = 52.7;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

### DASY4 Configuration:

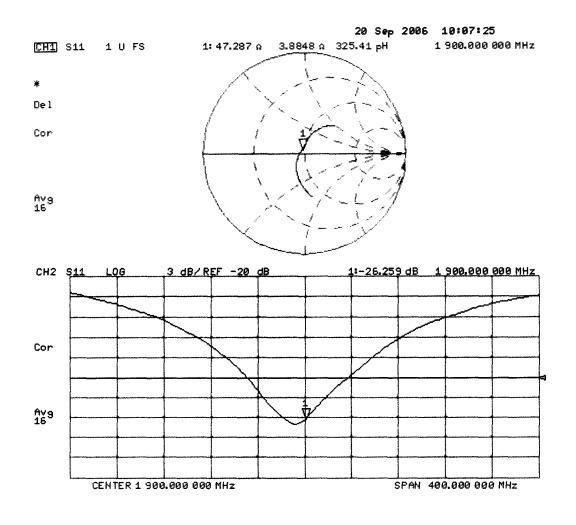
- Probe: ES3DV2 SN3025 (HF); ConvF(4.38, 4.38, 4.38); Calibrated: 28.10.2005
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 15.12.2005
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; ;
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

### Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 86.5 V/m; Power Drift = 0.034 dB Peak SAR (extrapolated) = 16.8 W/kg SAR(1 g) = 10.2 mW/g; SAR(10 g) = 5.4 mW/g Maximum value of SAR (measured) = 11.3 mW/g



 $0 \, dB = 11.3 mW/g$ 



### Impedance Measurement Plot for Body TSL

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Swiss Calibration Service

Accreditation	No.:	SCS	108
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Certificate No: D900V2-764\_Jul06

S

С

S

Client ETS Dr. Genz

	HRTH LOW I		
Object	D900V2 - SN: 16	4	
Calibration procedure(s)	QA CAL-05.v6 Calibration proce	dure for dipole validation kits	
Calibration date:	July 28, 2006		
Condition of the calibrated item	In Tolerance		
The measurements and the uncer	rtainties with confidence pr	onal standards, which realize the physical units of robability are given on the following pages and are	e part of the certificate.
		ry facility: environment temperature (22 ± 3)°C and	humiaity < 70%.
Calibration Equipment used (M&T	E critical for calibration)		
Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	04-Oct-05 (METAS, No. 251-00516)	Oct-06
Power sensor HP 8481A	US37292783	04-Oct-05 (METAS, No. 251-00516)	Oct-06
Reference 20 dB Attenuator	SN: 5086 (20g)	11-Aug-05 (METAS, No 251-00498)	Aug-06
Reference 10 dB Attenuator	SN: 5047.2 (10r)	11-Aug-05 (METAS, No 251-00498)	Aug-06
Reference Probe ET3DV6 (HF)	SN 1507	28-Oct-05 (SPEAG, No. ET3-1507_Oct05)	Oct-06
DAE4	SN 601	15-Dec-05 (SPEAG, No. DAE4-601_Dec05)	Dec-06
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (SPEAG, in house check Oct-05)	In house check: Oct-07
RF generator Agilent E4421B	MY41000675	11-May-05 (SPEAG, in house check Nov-05)	In house check: Nov-07
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (SPEAG, in house check Nov-05)	In house check: Nov-06
	Name	Function	Signature
Calibrated by:	Claudio Leubler	Laboratory Technician	
Approved by:	Fin Bomholf	Technics! Director 7.6	and and and the
This calibration certificate shall no	ot be reproduced except in	full without written approval of the laboratory.	Issued: August 3, 2006

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ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361. "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

### **Additional Documentation:**

d) DASY4 System Handbook

### Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. • No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

### **Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY4	V4.7
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V4.9	
Distance Dipole Center - TSL	15 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	900 MHz ± 1 MHz	

### **Head TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	41.5	0.97 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	39.9 ± 6 %	0.95 mho/m ± 6 %
Head TSL temperature during test	(23.2 ± 0.2) °C		

### SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	2.75 mW / g
SAR normalized	normalized to 1W	11.0 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	10.9 mW /g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	condition	
SAR measured	250 mW input power	1.76 mW / g
SAR normalized	normalized to 1W	7.04 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	6.96 mW /g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>1</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

### **Body TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	55.0	1.05 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	54.2 ± 6 %	1.06 mho/m ± 6 %
Body TSL temperature during test	(23.5 ± 0.2) °C		

### SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	condition	
SAR measured	250 mW input power	2.71 mW / g
SAR normalized	normalized to 1W	10.8 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	10.7 mW /g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	condition	
SAR measured	250 mW input power	1.76 mW / g
SAR normalized	normalized to 1W	7.04 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	6.96 mW /g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>2</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

### Appendix

### **Antenna Parameters with Head TSL**

Impedance, transformed to feed point	49.1 Ω - 6.9 jΩ
Return Loss	- 23.0 dB

### Antenna Parameters with Body TSL

Impedance, transformed to feed point	44.9 Ω - 9.2 jΩ
Return Loss	- 19.1 dB

### **General Antenna Parameters and Design**

Electrical Delay (one direction)	1.407 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

### **Additional EUT Data**

Manufactured by	SPEAG
Manufactured on	May 16, 2002

### **DASY4 Validation Report for Head TSL**

Date/Time: 28.07.2006 11:17:39

Test Laboratory: SPEAG, Zurich, Switzerland

### DUT: Dipole 900 MHz; Type: D900V2; Serial: D900V2 - SN:164

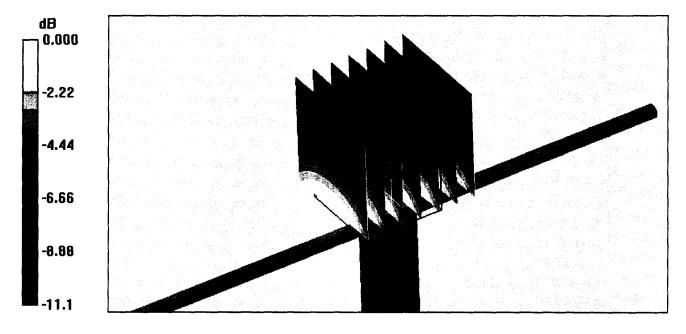
Communication System: CW; Frequency: 900 MHz;Duty Cycle: 1:1 Medium: HSL 900 MHz; Medium parameters used: f = 900 MHz;  $\sigma$  = 0.953 mho/m;  $\epsilon_r$  = 40.3;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

### **DASY4** Configuration:

- Probe: ET3DV6 SN1507 (HF); ConvF(5.8, 5.8, 5.8); Calibrated: 28.10.2005
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 15.12.2005
- Phantom: Flat Phantom 4.9L; Type: QD000P49AA; ;
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

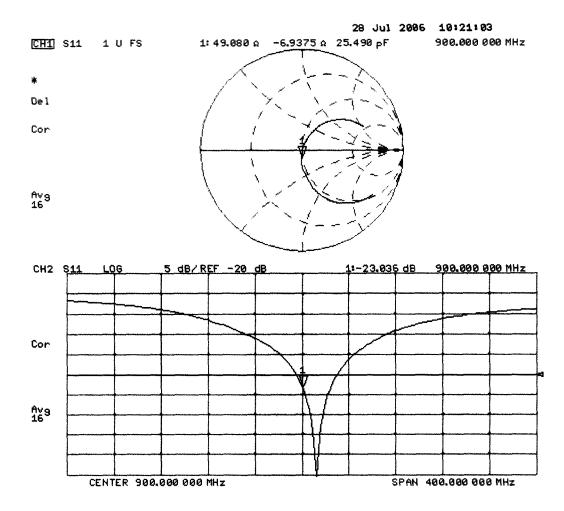
# **Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 57.7 V/m; Power Drift = 0.026 dB Peak SAR (extrapolated) = 4.16 W/kg SAR(1 g) = 2.75 mW/g; SAR(10 g) = 1.76 mW/g Maximum value of SAR (measured) = 2.98 mW/g





### Impedance Measurement Plot for Head TSL



### **DASY4 Validation Report for Body TSL**

Date/Time: 28.07.2006 13:09:12

Test Laboratory: SPEAG, Zurich, Switzerland

### DUT: Dipole 900 MHz; Type: D900V2; Serial: D900V2 - SN:164

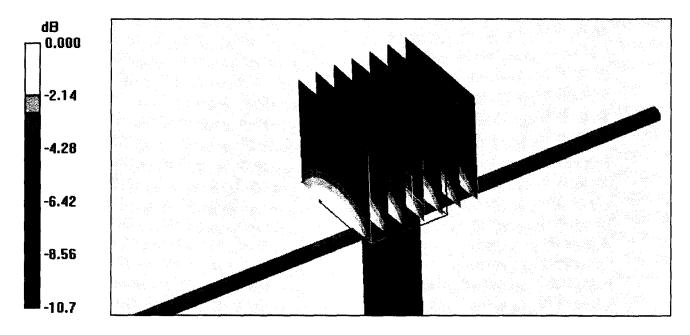
Communication System: CW-900; Frequency: 900 MHz;Duty Cycle: 1:1 Medium: MSL 900; Medium parameters used: f = 900 MHz;  $\sigma$  = 1.05 mho/m;  $\epsilon_r$  = 53.2;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

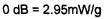
### **DASY4** Configuration:

- Probe: ET3DV6 SN1507 (HF); ConvF(5.76, 5.76, 5.76); Calibrated: 28.10.2005
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 15.12.2005
- Phantom: Flat Phantom 4.9L; Type: QD000P49AA; ;
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

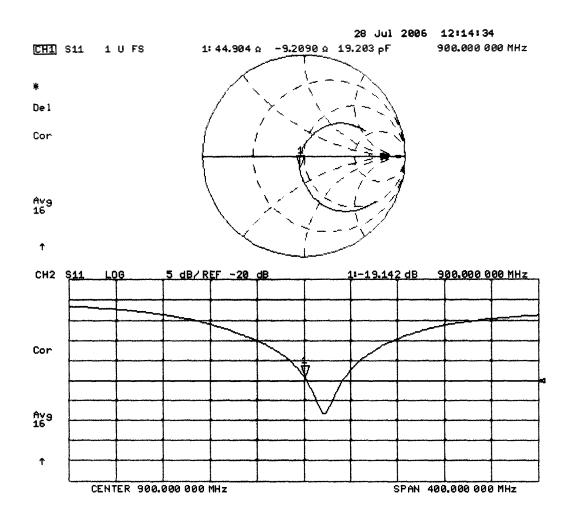
### Pin = 250 mW; d = 15 mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 55.2 V/m; Power Drift = -0.020 dB Peak SAR (extrapolated) = 3.97 W/kg SAR(1 g) = 2.71 mW/g; SAR(10 g) = 1.76 mW/g Maximum value of SAR (measured) = 2.95 mW/g





### Impedance Measurement Plot for Body TSL



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Certificate No: ET3-1711 Sep08 Client Eurofins **CALIBRATION CERTIFICATE** Object ET3DV6 - SN:1711 Calibration procedure(s) QA CAL-01.v6, QA CAL-12.v5 and QA CAL-23.v3 Calibration procedure for dosimetric E-field probes Calibration date: September 17, 2008 Condition of the calibrated item In Tolerance This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%. Calibration Equipment used (M&TE critical for calibration) ID # **Primary Standards** Cal Date (Certificate No.) Scheduled Calibration Power meter F4419B GB41293874 1-Apr-08 (No. 217-00788) Apr-09 Power sensor E4412A 1-Apr-08 (No. 217-00788) Apr-09 MY41495277 Power sensor E4412A MY41498087 1-Apr-08 (No. 217-00788) Apr-09 Reference 3 dB Attenuator SN: S5054 (3c) 1-Jul-08 (No. 217-00865) Jul-09 Reference 20 dB Attenuator SN: S5086 (20b) 31-Mar-08 (No. 217-00787) Apr-09 Reference 30 dB Attenuator SN: S5129 (30b) 1-Jul-08 (No. 217-00866) Jul-09 Reference Probe ES3DV2 SN: 3013 2-Jan-08 (No. ES3-3013\_Jan08) Jan-09 DAE4 SN: 660 9-Sep-08 (No. DAE4-660\_Sep08) Sep-09 Secondary Standards ID # Check Date (in house) Scheduled Check US3642U01700 RF generator HP 8648C 4-Aug-99 (in house check Oct-07) In house check: Oct-09 Network Analyzer HP 8753E US37390585 18-Oct-01 (in house check Oct-07) In house check: Oct-08 Name Function Signature Calibrated by: Katja Pokovic **Technical Manager** Niels Kuster Approved by: **Quality Manager** Issued: September 17, 2008 This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: ET3-1711 Sep08

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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### Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConvF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
Polarization φ	φ rotation around probe axis
Polarization 9	9 rotation around an axis that is in the plane normal to probe axis (at
	measurement center), i.e., $\vartheta = 0$ is normal to probe axis

### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

### Methods Applied and Interpretation of Parameters:

- NORMx, y, z: Assessed for E-field polarization θ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx, y, z are only intermediate values, i.e., the uncertainties of NORMx, y, z does not effect the E<sup>2</sup>-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z \* frequency\_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z* \* *ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

# Probe ET3DV6

# SN:1711

Manufactured: Last calibrated: Recalibrated: August 7, 2002 September 19, 2007 September 17, 2008

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

### DASY - Parameters of Probe: ET3DV6 SN:1711

Sensitivity in Free	Diode C	ompression <sup>B</sup>		
NormX	1.92 ± 10.1%	$\mu$ V/(V/m) <sup>2</sup>	DCP X	90 mV
NormY	1.86 ± 10.1%	$\mu$ V/(V/m) <sup>2</sup>	DCP Y	<b>93</b> mV
NormZ	2.04 ± 10.1%	$\mu$ V/(V/m) <sup>2</sup>	DCP Z	<b>92</b> mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

### **Boundary Effect**

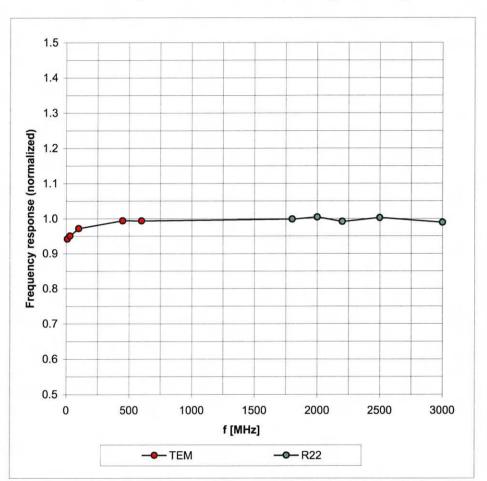
TSL	900	) MHz	Typical SAR gradient: 5 %	per mm	
	Sensor Center t	o Phanto	om Surface Distance	3.7 mm	4.7 mm
	SAR <sub>be</sub> [%]	Withou	t Correction Algorithm	9.8	5.8
	SAR <sub>be</sub> [%]	With C	orrection Algorithm	0.9	0.2
TSL	1810	MHz	Typical SAR gradient: 10 %	per mm	
	Sensor Center t	o Phanto	om Surface Distance	3.7 mm	4.7 mm
	SAR <sub>be</sub> [%]	Without Correction Algorithm		10.4	6.5
	SAR <sub>be</sub> [%]	With Correction Algorithm		0.8	0.4
Sens	or Offset				
	Probe Tip to Sei	nsor Cer	iter	2.7 mm	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 8).

<sup>B</sup> Numerical linearization parameter: uncertainty not required.

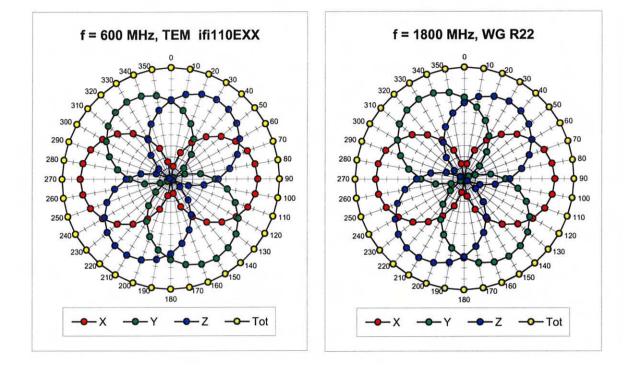
### ET3DV6 SN:1711



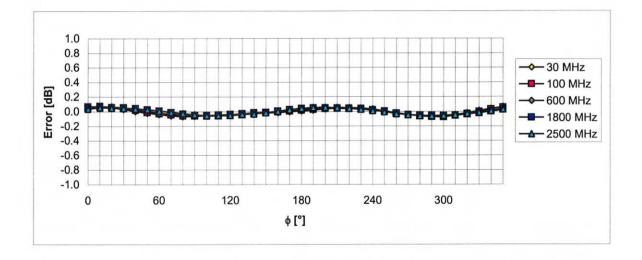
### **Frequency Response of E-Field**

(TEM-Cell:ifi110 EXX, Waveguide: R22)

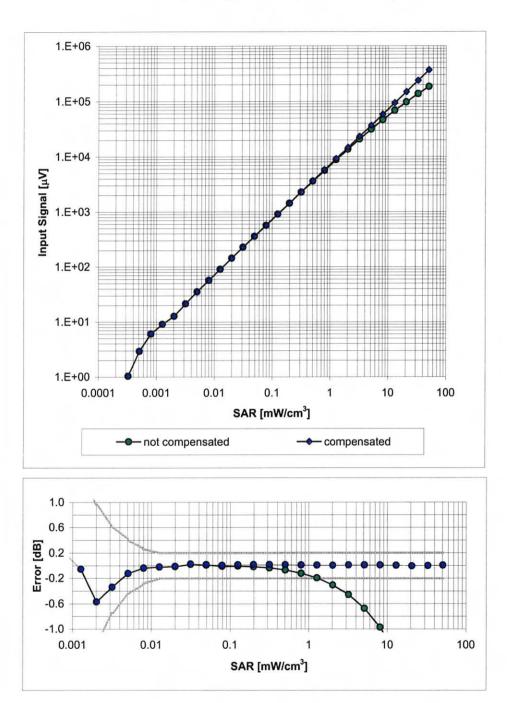
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)



### Receiving Pattern ( $\phi$ ), $\vartheta = 0^{\circ}$



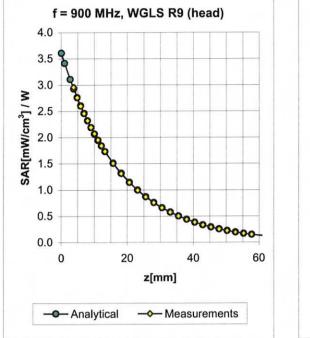
Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)



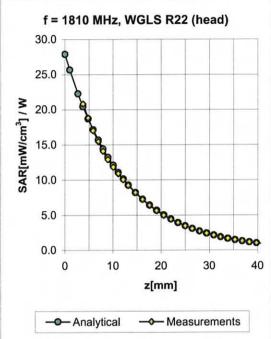
### Dynamic Range f(SAR<sub>head</sub>)

(Waveguide R22, f = 1800 MHz)

Uncertainty of Linearity Assessment: ± 0.6% (k=2)



### **Conversion Factor Assessment**



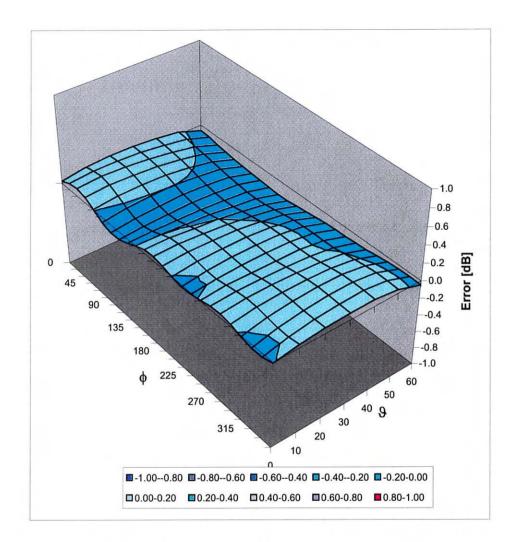
f [MHz]	Validity [MHz] <sup>C</sup>	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
450	± 50 / ± 100	Head	43.5 ± 5%	0.87 ± 5%	0.34	1.75	7.42 ± 13.3% (k=2)
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.30	2.88	6.17 ± 11.0% (k=2)
1810	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.67	1.95	5.17 ± 11.0% (k=2)
1950	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.79	1.69	4.96 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.85	1.50	4.55 ± 11.0% (k=2)
450	± 50 / ± 100	Body	56.7 ± 5%	0.94 ± 5%	0.28	1.82	7.91 ± 13.3% (k=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	0.38	2.65	6.01 ± 11.0% (k=2)
1810	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.70	2.03	4.57 ± 11.0% (k=2)
1950	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.76	1.82	4.51 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.85	1.55	3.81 ± 11.0% (k=2)

<sup>c</sup> The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

### ET3DV6 SN:1711

# **Deviation from Isotropy in HSL**

Error (φ, ϑ), f = 900 MHz



#### Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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Certificate No: DAE3-522\_Sep08

### **CALIBRATION CERTIFICATE**

Object	DAE3 - SD 000 D	03 AA - SN: 522	
Calibration procedure(s)	QA CAL-06.v12 Calibration procec	lure for the data acquisition	electronics (DAE)
Calibration date:	September 16, 20	08	
Condition of the calibrated item	In Tolerance		
The measurements and the uncerta	ainties with confidence pro	nal standards, which realize the physic obability are given on the following page facility: environment temperature (22 :	es and are part of the certificate.
Primary Standards	ID#	Cal Date (Certificate No.)	Scheduled Calibration
Fluke Process Calibrator Type 702 Keithley Multimeter Type 2001	SN: 6295803 SN: 0810278	04-Oct-07 (No: 6467) 03-Oct-07 (No: 6465)	Oct-08 Oct-08
Secondary Standards	ID#	Check Date (in house)	Scheduled Check
Calibrator Box V1.1	SE UMS 006 AB 1004	06-Jun-08 (in house check)	In house check: Jun-09
	Name	Function	Signature
Calibrated by:	Andrea Guntli	Technician	A.
Approved by:	Fin Bomholt	R&D Director	i.N. B. Luner
This collibration contificate chall act	he reproduced event in f	ull without written approval of the labor	Issued: September 16, 2008

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### Glossarv

DAE Connector angle data acquisition electronics

information used in DASY system to align probe sensor X to the robot coordinate system.

### Methods Applied and Interpretation of Parameters

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of • the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
  - Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
  - AD Converter Values with inputs shorted: Values on the internal AD converter . corresponding to zero input voltage
  - Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
  - Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - Input resistance: DAE input resistance at the connector, during internal auto-zeroing . and during measurement.
  - Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
  - Power consumption: Typical value for information. Supply currents in various operating modes.

## DC Voltage Measurement A/D - Converter Resolution nominal

High Range:	1LSB =	6.1μV ,		-100…+300 mV
Low Range:	1LSB =	61nV ,		-1+3mV
DASY measurement p	parameters: Aut	o Zero Time: 3	sec; Measuring	time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.296 ± 0.1% (k=2)	403.979 ± 0.1% (k=2)	$404.799 \pm 0.1\%$ (k=2)
Low Range	3.96483 ± 0.7% (k=2)	3.94724 ± 0.7% (k=2)	$3.95304 \pm 0.7\%$ (k=2)

### **Connector Angle**

Connector Angle to be used in DASY system	59 ° ± 1 °
---	------------

### Appendix

### 1. DC Voltage Linearity

High Range	Input (μV)	Reading (µV)	Error (%)
Channel X + Input	200000	200000.1	0.00
Channel X + Input	20000	20004.65	0.02
Channel X - Input	20000	-19997.96	-0.01
Channel Y + Input	200000	200000.2	0.00
Channel Y + Input	20000	20002.06	0.01
Channel Y - Input	20000	-20002.21	0.01
Channel Z + Input	200000	199999.5	0.00
Channel Z + Input	20000	20000.45	0.00
Channel Z - Input	20000	-20000.24	0.00

Low Range	Input (μV)	Reading (µV)	Error (%)
Channel X + Input	2000	2000	0.00
Channel X + Input	200	199.52	-0.24
Channel X - Input	200	-199.25	-0.38
Channel Y + Input	2000	2000	0.00
Channel Y + Input	200	199.61	-0.19
Channel Y - Input	200	-199.68	-0.16
Channel Z + Input	2000	2000.1	0.00
Channel Z + Input	200	198.97	-0.51
Channel Z - Input	200	-200.89	0.44

### 2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	-4.55	-4.98
	- 200	5.39	5.72
Channel Y	200	-1.09	-1.66
	- 200	-0.37	-0.36
Channel Z	200	16.19	16.11
	- 200	-17.75	-17.97

### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (µV)	Channel Z (μV)
Channel X	200	-	3.70	0.32
Channel Y	200	0.80	-	3.59
Channel Z	200	-3.13	-0.50	-

### 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15722	15373
Channel Y	15735	14486
Channel Z	16044	16908

### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec Input  $10M\Omega$ 

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (µV)
Channel X	0.98	-0.32	2.54	0.62
Channel Y	-1.57	-3.53	-0.17	0.62
Channel Z	-0.13	-1.30	1.18	0.51

### 6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

#### 7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.2000	198.1
Channel Y	0.2001	199.4
Channel Z	0.2001	196.4

### 8. Low Battery Alarm Voltage (verified during pre test)

Typical values	Alarm Level (VDC)	
Supply (+ Vcc)	+7.9	
Supply (- Vcc)	-7.6	

### 9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9



**Eurofins Product Service** 

Annex B

**Measurement Plots** 

Test Report No.: G5M209010002-S-8

### Dipol Valid.900 (h)\_250mW 27.02.2009

### DUT: Dipole 900 MHz; Type: D900V2; Serial: 164

Communication System: CW; Frequency: 900 MHz;Duty Cycle: 1:1 Medium: Head 900 MHz Medium parameters used: f = 900 MHz;  $\sigma$  = 0.944 mho/m;  $\epsilon_r$  = 40.5;  $\rho$  =

1000 kg/m<sup>3</sup> Phantom section: Flat Section

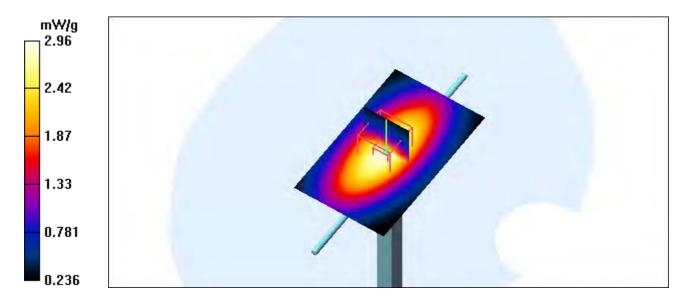
### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.17, 6.17, 6.17); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Dipol 900 (250mW)/Area Scan (61x101x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 2.94 mW/g

**Dipol 900 (250mW)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 58.3 V/m; Power Drift = -0.036 dBPeak SAR (extrapolated) = 4.02 W/kgSAR(1 g) = 2.73 mW/g; SAR(10 g) = 1.76 mW/gMaximum value of SAR (measured) = 2.96 mW/g



### Dipol Valid 900 (m)\_250mW 28.02.2009

### DUT: Dipole 900 MHz; Type: D900V2; Serial: 164

Communication System: CW; Frequency: 900 MHz;Duty Cycle: 1:1

Medium: Muscle 900 MHz Medium parameters used: f = 900 MHz;  $\sigma = 1.01$  mho/m;  $\varepsilon_r = 54.1$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

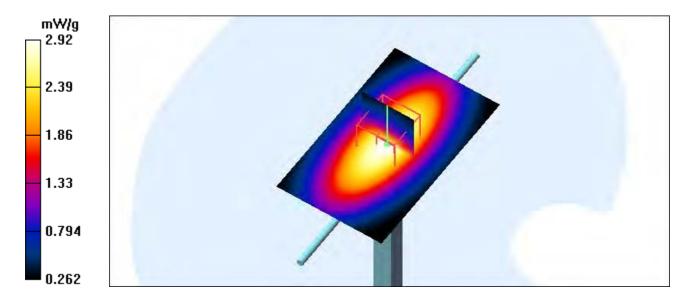
### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Dipol 900 (250mW)/Area Scan (61x101x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 2.96 mW/g

**Dipol 900 (250mW)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 56.2 V/m; Power Drift = -0.046 dBPeak SAR (extrapolated) = 3.85 W/kg**SAR(1 g) = 2.69 \text{ mW/g}; SAR(10 g) = 1.76 \text{ mW/g}** Maximum value of SAR (measured) = 2.92 mW/g



### Dipol Valid.1900 (h)\_250mW 26.02.2009

### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: 5d025

Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1 Medium: Head 1900 MHz Medium parameters used: f = 1900 MHz;  $\sigma = 1.42$  mho/m;  $\varepsilon_r = 39.9$ ;  $\rho =$ 

1000 kg/m<sup>3</sup> Phantom section: Flat Section

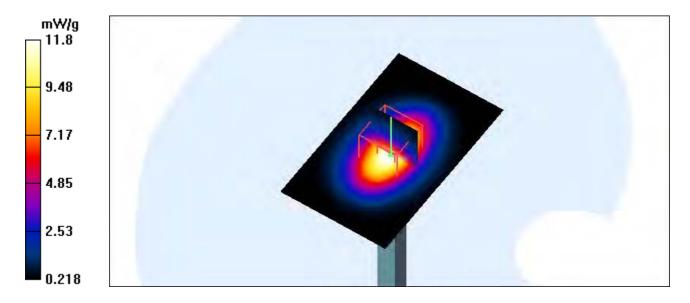
DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.17, 5.17, 5.17); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Dipol 1900 (250mW)/Area Scan (61x101x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 12.1 mW/g

**Dipol 1900 (250mW)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 96.7 V/m; Power Drift = -0.028 dBPeak SAR (extrapolated) = 18.9 W/kg SAR(1 g) = 10.6 mW/g; SAR(10 g) = 5.57 mW/g Maximum value of SAR (measured) = 11.8 mW/g



### Dipol Valid 1900 (m)\_250mW 27.02.2009

### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: 5d025

Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1

Medium: Muscle 1900 MHz Medium parameters used: f = 1900 MHz;  $\sigma = 1.58$  mho/m;  $\epsilon_r = 51.9$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

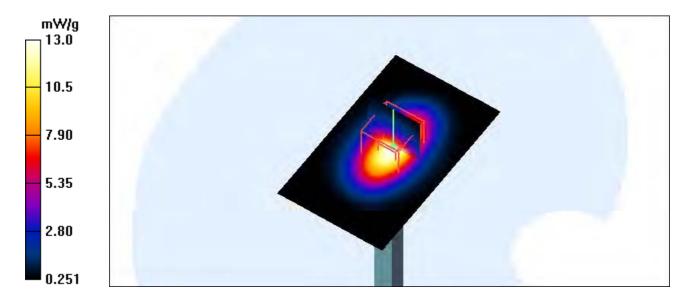
### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.57, 4.57, 4.57); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Dipol 1900 (250mW)/Area Scan (61x101x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 13.2 mW/g

**Dipol 1900 (250mW)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 94.2 V/m; Power Drift = -0.021 dBPeak SAR (extrapolated) = 21.2 W/kgSAR(1 g) = 11.5 mW/g; SAR(10 g) = 5.95 mW/g Maximum value of SAR (measured) = 13.0 mW/g



### GSM\_850\_ch128\_right\_cheek

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 824.2 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 824.2 MHz;  $\sigma = 0.927$  mho/m;  $\epsilon_r = 54.9$ ;  $\rho$ 

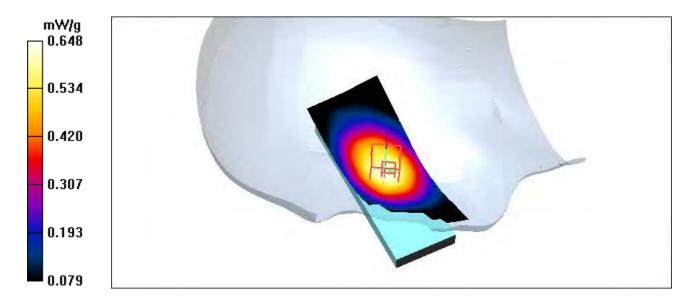
= 1000 kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.637 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 11.7 V/m; Power Drift = -0.033 dB Peak SAR (extrapolated) = 0.790 W/kg SAR(1 g) = 0.615 mW/g; SAR(10 g) = 0.453 mW/g Maximum value of SAR (measured) = 0.648 mW/g



### GSM\_850\_ch189\_right\_cheek

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\epsilon_r = 54.8$ ;  $\rho$ 

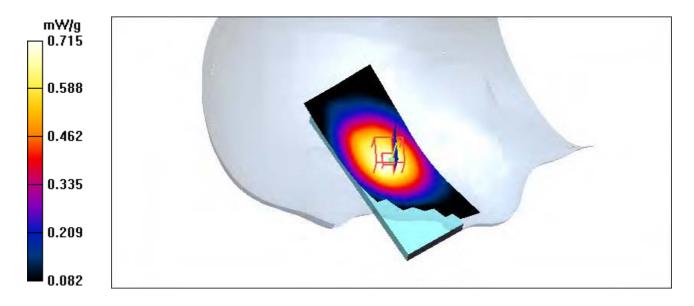
= 1000 kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.717 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 12.4 V/m; Power Drift = -0.128 dB Peak SAR (extrapolated) = 0.854 W/kg SAR(1 g) = 0.675 mW/g; SAR(10 g) = 0.498 mW/g Maximum value of SAR (measured) = 0.715 mW/g



### GSM\_850\_ch189\_right\_tilted

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\epsilon_r = 54.8$ ;  $\rho$ 

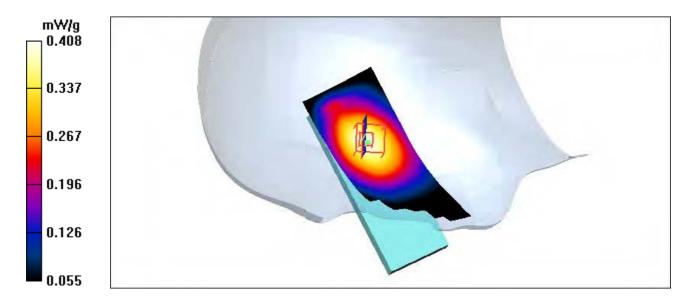
= 1000 kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.405 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 14.8 V/m; Power Drift = -0.101 dB Peak SAR (extrapolated) = 0.475 W/kg SAR(1 g) = 0.384 mW/g; SAR(10 g) = 0.283 mW/g Maximum value of SAR (measured) = 0.408 mW/g



# GSM\_850\_ch251\_right\_cheek

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 848.8 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 848.8 MHz;  $\sigma = 0.944$  mho/m;  $\epsilon_r = 54.7$ ;  $\rho$ 

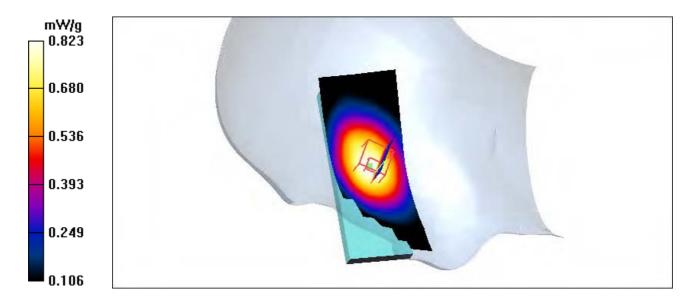
= 1000 kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.842 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 11.0 V/m; Power Drift = -0.079 dB Peak SAR (extrapolated) = 0.977 W/kg SAR(1 g) = 0.778 mW/g; SAR(10 g) = 0.572 mW/g Maximum value of SAR (measured) = 0.823 mW/g



# GSM\_850\_ch189\_left\_cheek

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\epsilon_r = 54.8$ ;  $\rho$ 

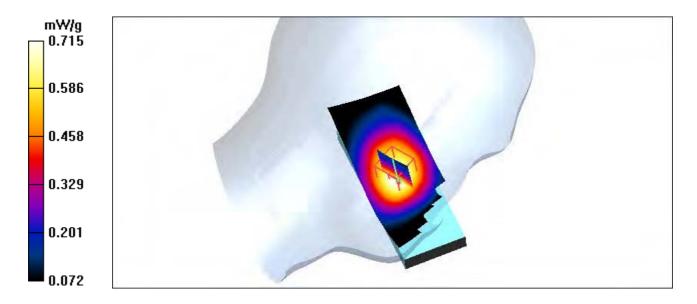
 $= 1000 \text{ kg/m}^3$ Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.726 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 12.2 V/m; Power Drift = -0.032 dB Peak SAR (extrapolated) = 0.868 W/kg SAR(1 g) = 0.672 mW/g; SAR(10 g) = 0.484 mW/g Maximum value of SAR (measured) = 0.715 mW/g



# GSM\_850\_ch189\_left\_tilted

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\epsilon_r = 54.8$ ;  $\rho$ 

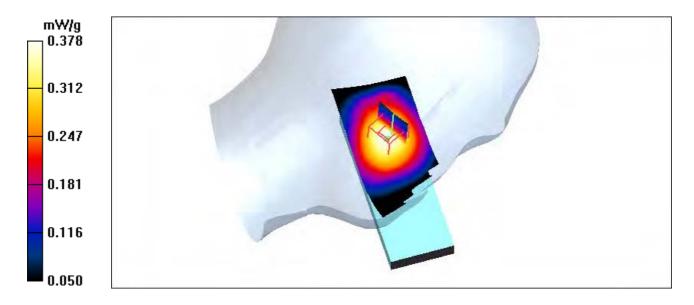
= 1000 kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.384 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 14.7 V/m; Power Drift = -0.139 dB Peak SAR (extrapolated) = 0.446 W/kgSAR(1 g) = 0.355 mW/g; SAR(10 g) = 0.260 mW/gMaximum value of SAR (measured) = 0.378 mW/g



# GSM\_850\_ch189\_flat\_front\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\epsilon_r = 54.8$ ;  $\rho$ 

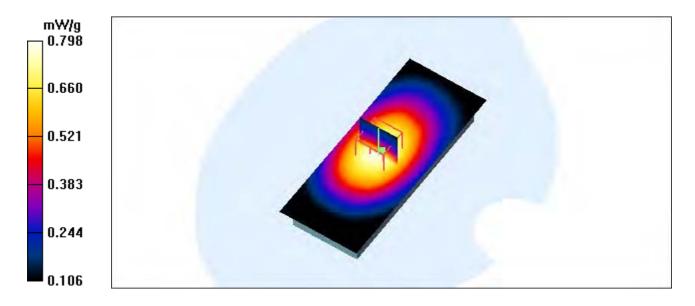
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.798 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 30.6 V/m; Power Drift = -0.142 dB Peak SAR (extrapolated) = 0.946 W/kg SAR(1 g) = 0.749 mW/g; SAR(10 g) = 0.548 mW/g Maximum value of SAR (measured) = 0.798 mW/g



# GSM\_850\_ch189\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\epsilon_r = 54.8$ ;  $\rho$ 

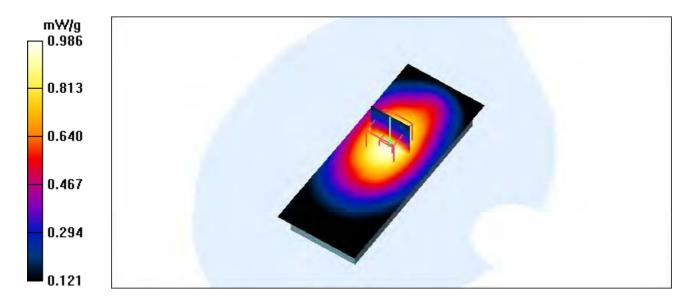
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.985 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 31.9 V/m; Power Drift = -0.037 dB Peak SAR (extrapolated) = 1.18 W/kg SAR(1 g) = 0.921 mW/g; SAR(10 g) = 0.661 mW/g Maximum value of SAR (measured) = 0.986 mW/g



# GSM\_1900\_ch512\_right\_cheek

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1850.2 MHz;  $\sigma = 1.37$  mho/m;  $\epsilon_r = 39.9$ ;  $\rho$ 

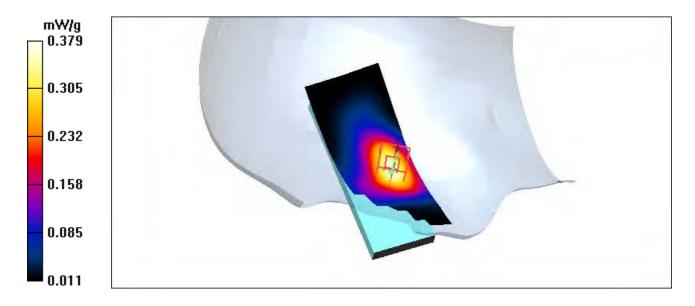
= 1000 kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.17, 5.17, 5.17); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

C570/Area Scan (61x151x1): Measurement grid: dx=10mm, dy=10mmMaximum value of SAR (interpolated) = 0.374 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 3.70 V/m; Power Drift = 0.055 dB Peak SAR (extrapolated) = 0.529 W/kg SAR(1 g) = 0.347 mW/g; SAR(10 g) = 0.216 mW/g Maximum value of SAR (measured) = 0.379 mW/g



# GSM\_1900\_ch661\_right\_cheek

#### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma$  = 1.4 mho/m;  $\epsilon_r$  = 39.9;  $\rho$  =

1000 kg/m<sup>3</sup> Phantom section: Right Section

#### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.17, 5.17, 5.17); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.433 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 4.09 V/m; Power Drift = -0.102 dB Peak SAR (extrapolated) = 0.594 W/kg SAR(1 g) = 0.400 mW/g; SAR(10 g) = 0.249 mW/g Maximum value of SAR (measured) = 0.442 mW/g



# GSM\_1900\_ch661\_right\_tilted

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma$  = 1.4 mho/m;  $\epsilon_r$  = 39.9;  $\rho$  =

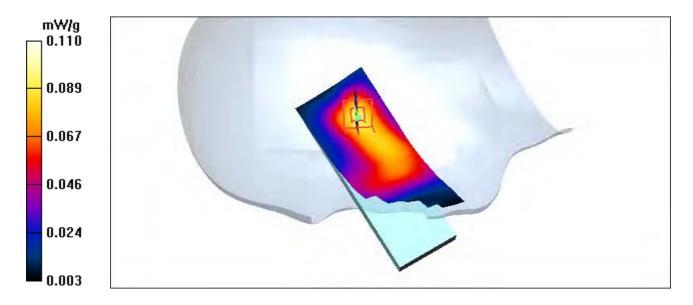
1000 kg/m<sup>3</sup> Phantom section: Right Section

#### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.17, 5.17, 5.17); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.095 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 6.25 V/m; Power Drift = -0.029 dB Peak SAR (extrapolated) = 0.125 W/kg SAR(1 g) = 0.085 mW/g; SAR(10 g) = 0.054 mW/g Maximum value of SAR (measured) = 0.092 mW/g



# GSM\_1900\_ch810\_right\_cheek

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1909.8 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1909.8 MHz;  $\sigma = 1.43$  mho/m;  $\varepsilon_r = 39.8$ ;  $\rho$ 

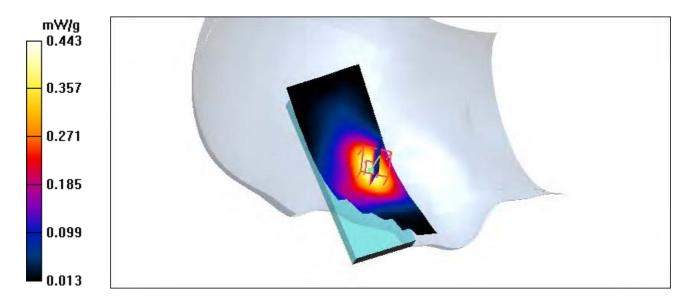
= 1000 kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.17, 5.17, 5.17); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.428 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 4.25 V/m; Power Drift = -0.059 dB Peak SAR (extrapolated) = 0.598 W/kg SAR(1 g) = 0.397 mW/g; SAR(10 g) = 0.244 mW/g Maximum value of SAR (measured) = 0.443 mW/g



# GSM\_1900\_ch661\_left\_cheek

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma = 1.4$  mho/m;  $\epsilon_r = 39.9$ ;  $\rho =$ 

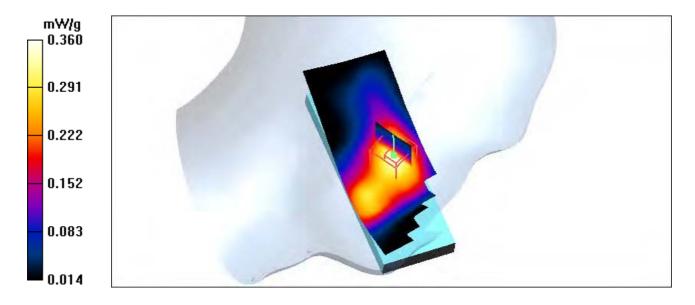
1000 kg/m<sup>3</sup> Phantom section: Left Section

### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.17, 5.17, 5.17); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.354 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 5.63 V/m; Power Drift = -0.149 dB Peak SAR (extrapolated) = 0.486 W/kg SAR(1 g) = 0.325 mW/g; SAR(10 g) = 0.204 mW/g Maximum value of SAR (measured) = 0.360 mW/g



# GSM\_1900\_ch661\_left\_tilted

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma = 1.4$  mho/m;  $\epsilon_r = 39.9$ ;  $\rho =$ 

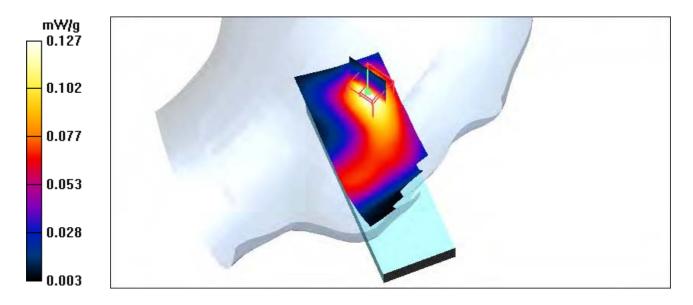
1000 kg/m<sup>3</sup> Phantom section: Left Section

#### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.17, 5.17, 5.17); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.127 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 7.27 V/m; Power Drift = -0.195 dB Peak SAR (extrapolated) = 0.178 W/kg SAR(1 g) = 0.118 mW/g; SAR(10 g) = 0.073 mW/g Maximum value of SAR (measured) = 0.127 mW/g



# GSM\_1900\_ch661\_flat\_front\_10mm

#### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3 Medium: Muscle 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma = 1.55$  mho/m;  $\epsilon_r = 51.9$ ;  $\rho$ 

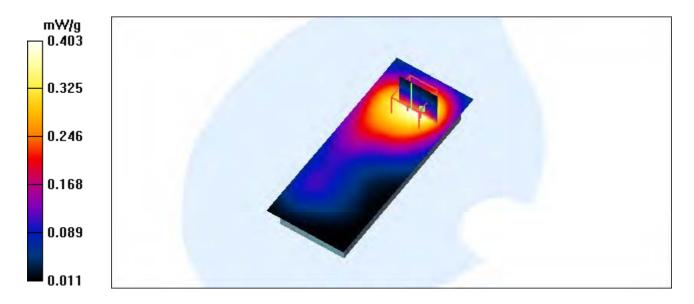
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.57, 4.57, 4.57); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.410 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 8.48 V/m; Power Drift = -0.048 dB Peak SAR (extrapolated) = 0.644 W/kg SAR(1 g) = 0.376 mW/g; SAR(10 g) = 0.227 mW/g Maximum value of SAR (measured) = 0.403 mW/g



# GSM\_1900\_ch661\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3 Medium: Muscle 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma = 1.55$  mho/m;  $\epsilon_r = 51.9$ ;  $\rho$ 

= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.57, 4.57, 4.57); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x151x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 1.15 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 14.8 V/m; Power Drift = -0.001 dB Peak SAR (extrapolated) = 1.85 W/kgSAR(1 g) = 1.02 mW/g; SAR(10 g) = 0.554 mW/gMaximum value of SAR (measured) = 1.12 mW/g

C570/Zoom Scan (7x7x7)/Cube 1: Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 14.8 V/m; Power Drift = -0.001 dB Peak SAR (extrapolated) = 1.91 W/kg SAR(1 g) = 0.950 mW/g; SAR(10 g) = 0.517 mW/g Maximum value of SAR (measured) = 1.10 mW/g



# GPRS\_850\_ch128\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 824.2 MHz;Duty Cycle: 1:4.15 Medium: Muscle 900 MHz Medium parameters used: f = 824.2 MHz;  $\sigma = 0.927$  mho/m;  $\epsilon_r = 54.9$ ;  $\rho$ 

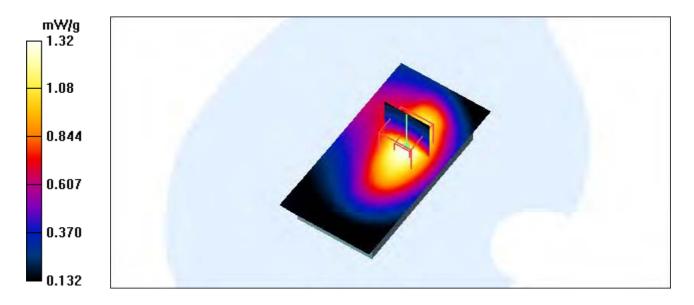
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 1.32 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 35.5 V/m; Power Drift = 0.098 dB Peak SAR (extrapolated) = 1.68 W/kg SAR(1 g) = 1.23 mW/g; SAR(10 g) = 0.841 mW/g Maximum value of SAR (measured) = 1.32 mW/g



# GPRS\_850\_ch189\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:4.15 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\epsilon_r = 54.8$ ;  $\rho$ 

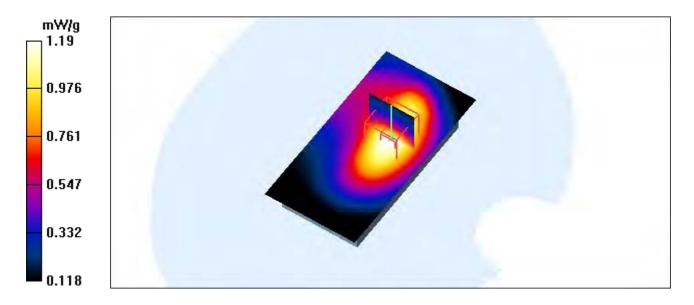
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 1.21 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 33.7 V/m; Power Drift = -0.043 dB Peak SAR (extrapolated) = 1.53 W/kg SAR(1 g) = 1.11 mW/g; SAR(10 g) = 0.756 mW/g Maximum value of SAR (measured) = 1.19 mW/g



# GPRS\_850\_ch251\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 848.8 MHz;Duty Cycle: 1:4.15 Medium: Muscle 900 MHz Medium parameters used: f = 848.8 MHz;  $\sigma = 0.944$  mho/m;  $\epsilon_r = 54.7$ ;  $\rho$ 

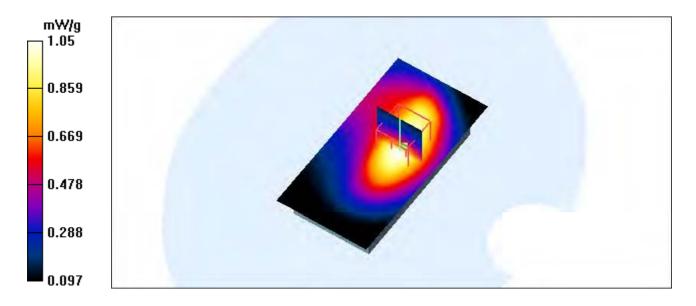
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 1.07 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 31.8 V/m; Power Drift = -0.147 dB Peak SAR (extrapolated) = 1.35 W/kg SAR(1 g) = 0.977 mW/g; SAR(10 g) = 0.663 mW/g Maximum value of SAR (measured) = 1.05 mW/g



# GPRS\_1900\_ch512\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:4.15 Medium: Muscle 1900 MHz Medium parameters used: f = 1850.2 MHz;  $\sigma = 1.51$  mho/m;  $\varepsilon_r = 52$ ;  $\rho$ 

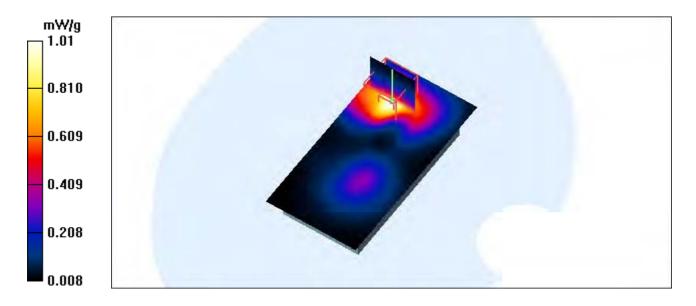
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.57, 4.57, 4.57); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 1.03 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 8.82 V/m; Power Drift = -0.018 dB Peak SAR (extrapolated) = 1.96 W/kg SAR(1 g) = 0.920 mW/g; SAR(10 g) = 0.456 mW/g Maximum value of SAR (measured) = 1.01 mW/g



# GPRS\_1900\_ch661\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:4.15 Medium: Muscle 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma = 1.55$  mho/m;  $\varepsilon_r = 51.9$ ;  $\rho$ 

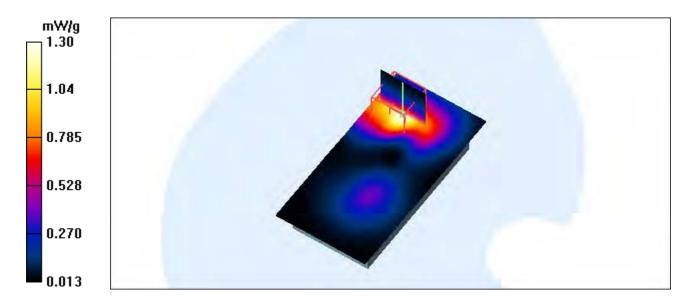
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.57, 4.57, 4.57); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 1.31 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 8.82 V/m; Power Drift = -0.121 dB Peak SAR (extrapolated) = 2.52 W/kg SAR(1 g) = 1.17 mW/g; SAR(10 g) = 0.582 mW/g Maximum value of SAR (measured) = 1.30 mW/g



# GPRS\_1900\_ch810\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1909.8 MHz;Duty Cycle: 1:4.15 Medium: Muscle 1900 MHz Medium parameters used: f = 1909.8 MHz;  $\sigma = 1.59$  mho/m;  $\varepsilon_r = 51.9$ ;

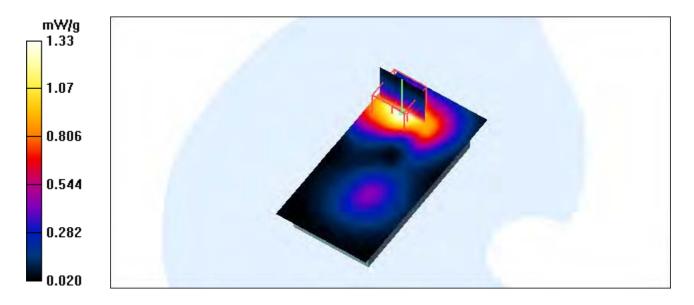
 $\rho = 1000 \text{ kg/m}^3$ Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.57, 4.57, 4.57); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 1.36 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 9.42 V/m; Power Drift = -0.034 dB Peak SAR (extrapolated) = 2.40 W/kg SAR(1 g) = 1.23 mW/g; SAR(10 g) = 0.647 mW/g Maximum value of SAR (measured) = 1.33 mW/g



# EGPRS\_850\_ch189\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:4.15 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\epsilon_r = 54.8$ ;  $\rho$ 

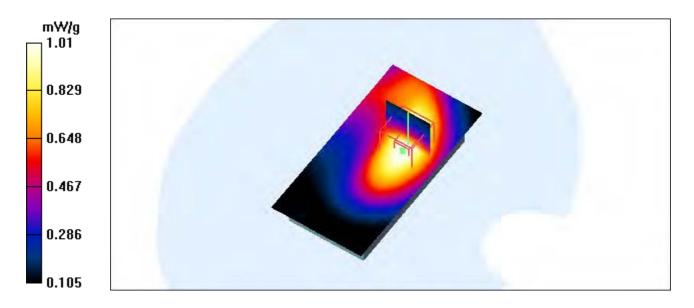
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 1.03 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 29.1 V/m; Power Drift = -0.100 dBPeak SAR (extrapolated) = 1.29 W/kgSAR(1 g) = 0.935 mW/g; SAR(10 g) = 0.636 mW/gMaximum value of SAR (measured) = 1.01 mW/g



## EGPRS\_1900\_ch661\_flat\_back\_10mm

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:4.15 Medium: Muscle 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma = 1.55$  mho/m;  $\varepsilon_r = 51.9$ ;  $\rho$ 

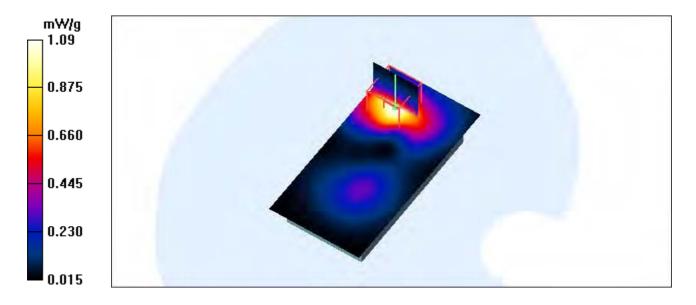
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.57, 4.57, 4.57); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 1.13 mW/g

C570/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 8.14 V/m; Power Drift = 0.021 dB Peak SAR (extrapolated) = 1.98 W/kg SAR(1 g) = 1 mW/g; SAR(10 g) = 0.519 mW/g Maximum value of SAR (measured) = 1.09 mW/g



# Z - axis scan

### DUT: C570; Type: GSM phone; Serial: # Proto

Communication System: GSM 850; Frequency: 824.2 MHz;Duty Cycle: 1:4.15 Medium: Muscle 900 MHz Medium parameters used: f = 824.2 MHz;  $\sigma = 0.927$  mho/m;  $\epsilon_r = 54.9$ ;  $\rho$ 

= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.01, 6.01, 6.01); Calibrated: 9/17/2008
- Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**C570/Z Scan (1x1x16):** Measurement grid: dx=20mm, dy=20mm, dz=20mm Maximum value of SAR (interpolated) = 0.758 mW/g

