

APPENDIX D (PROBE CALIBRATION DATA)

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland



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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client **Pantech (Dymstec)**

Certificate No: ER3-2242_Sep10

CALIBRATION CERTIFICATE

Object: ER3DV6R - SN:2242

Calibration procedure(s): QA CAL-02.v5 and QA CAL-25.v2
Calibration procedure for E-field probes optimized for close near field evaluations in air

Calibration date: September 20, 2010

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	1-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41495277	1-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41498087	1-Apr-10 (No. 217-01136)	Apr-11
Reference 3 dB Attenuator	SN: S5054 (3c)	30-Mar-10 (No. 217-01159)	Mar-11
Reference 20 dB Attenuator	SN: S5086 (20b)	30-Mar-10 (No. 217-01161)	Mar-11
Reference 30 dB Attenuator	SN: S5129 (30b)	30-Mar-10 (No. 217-01160)	Mar-11
Reference Probe ER3DV6	SN: 2328	3-Oct-09 (No. ER3-2328_Oct09)	Oct-10
DAE4	SN: 789	31-Aug-10 (No. DAE4-789_Aug10)	Aug-11
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10

Calibrated by:	Name	Function	Signature
	Katja Pokovic	Technical Manager	
Approved by:	Fin Bomholt	R&D Director	

Issued: September 20, 2010

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Accreditation No.: **SCS 108**

Glossary:

NORM_{x,y,z} sensitivity in free space
DCP diode compression point
CF crest factor (1/duty_cycle) of the RF signal
A, B, C modulation dependent linearization parameters
Polarization ϕ ϕ rotation around probe axis
Polarization ϑ ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center),
i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- **NORM_{x,y,z}**: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- **NORM(f)_{x,y,z} = NORM_{x,y,z} * frequency_response** (see Frequency Response Chart).
- **DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- **A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}**: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- **Spherical isotropy (3D deviation from isotropy)**: in a locally homogeneous field realized using an open waveguide setup.
- **Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- **Connector Angle**: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).

ER3DV6R SN:2242

September 20, 2010

Probe ER3DV6R

SN:2242

Manufactured:	November 24, 1999
Last calibrated:	November 23, 2009
Recalibrated:	September 20, 2010

Calibrated for DASYS/EASY Systems

(Note: non-compatible with DASYS2 system!)

ER3DV6R SN:2242

September 20, 2010

DASY/EASY - Parameters of Probe: ER3DV6R SN:2242

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu V/(V/m)^2$)	3.72	3.55	5.45	$\pm 10.1\%$
DCP (mV) ^A	95.3	95.9	98.0	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc ^E (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	$\pm 1.5\%$
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A numerical linearization parameter; uncertainty not required

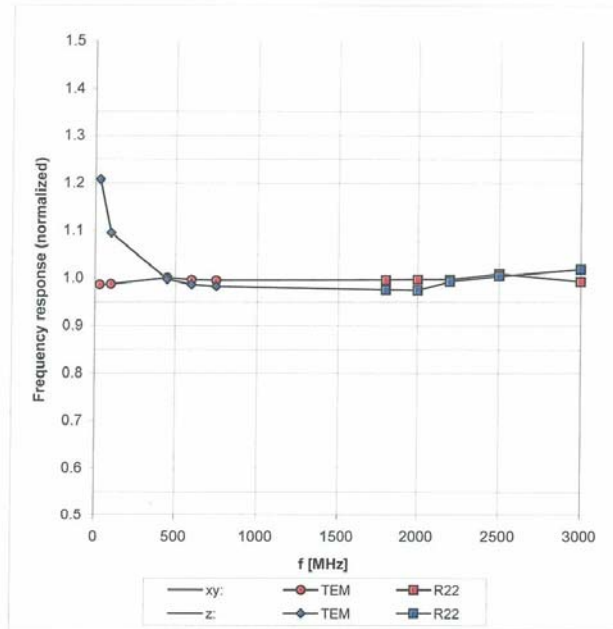
^E Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

ER3DV6R SN:2242

September 20, 2010

Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)

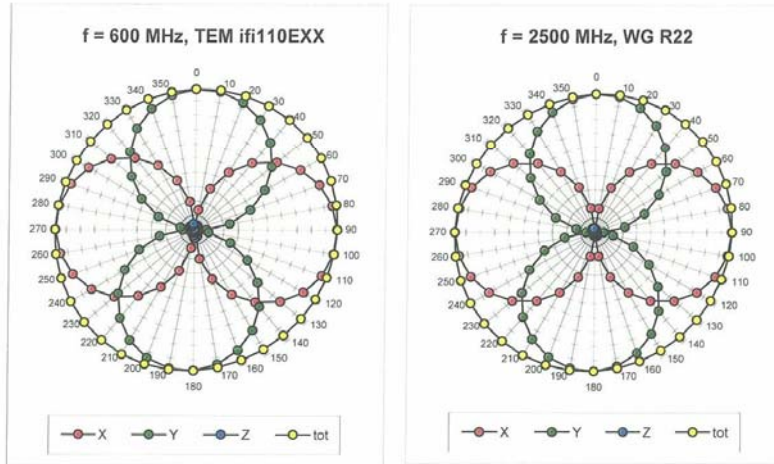


Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

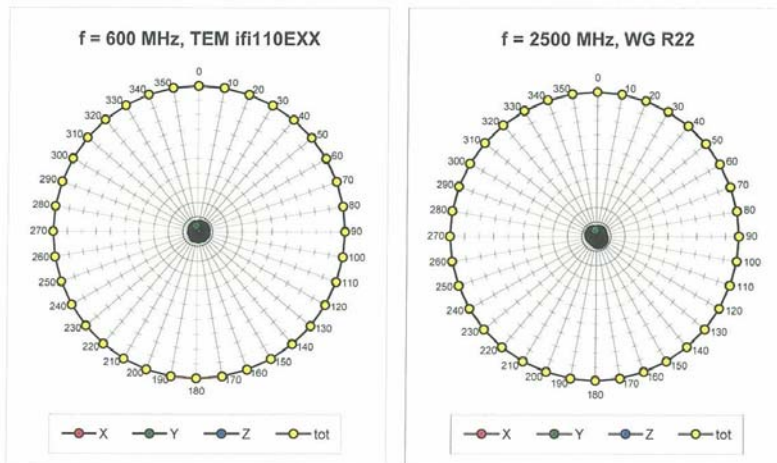
ER3DV6R SN:2242

September 20, 2010

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



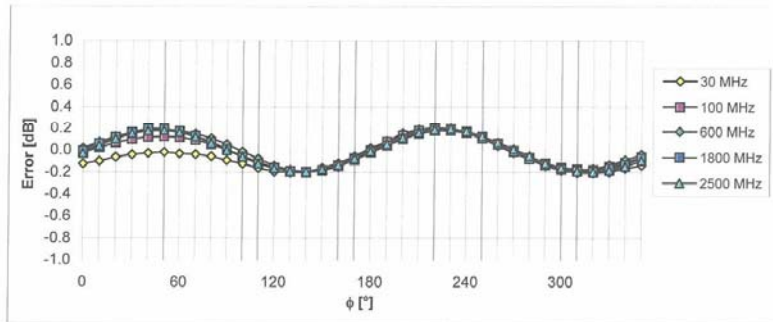
Receiving Pattern (ϕ), $\vartheta = 90^\circ$



ER3DV6R SN:2242

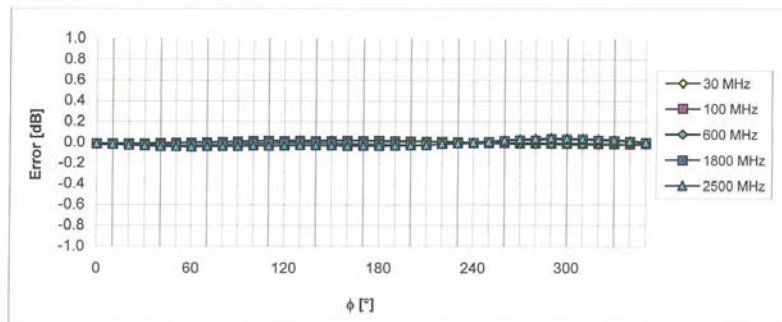
September 20, 2010

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ (k=2)

Receiving Pattern (ϕ), $\vartheta = 90^\circ$



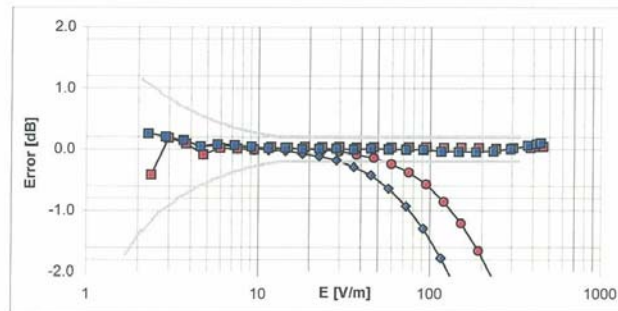
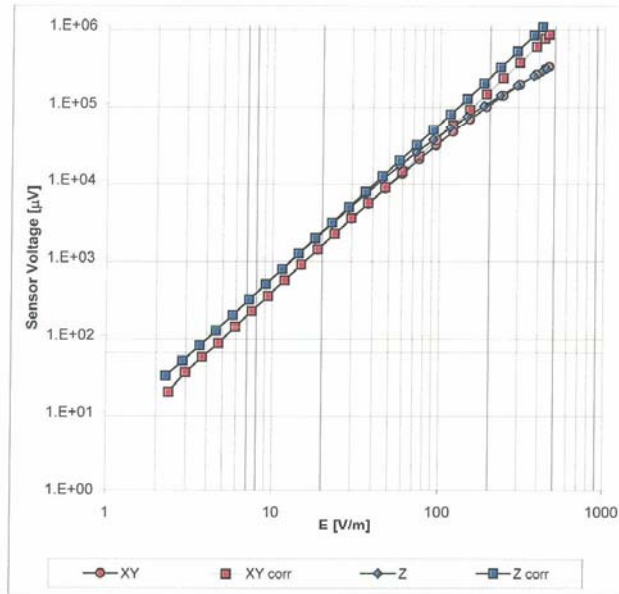
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ (k=2)

ER3DV6R SN:2242

September 20, 2010

Dynamic Range f(E-field)

(Waveguide R22, f = 1800 MHz)

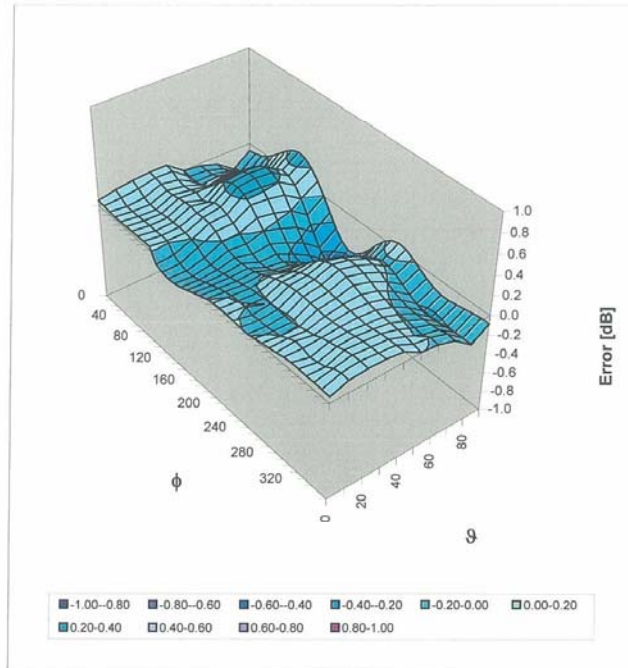


Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

ER3DV6R SN:2242

September 20, 2010

Deviation from Isotropy in Air
Error (ϕ, ϑ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

ER3DV6R SN:2242

September 20, 2010

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-292.4
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8.0 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

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Accreditation No.: **SCS 108**

Client **Pantech (Dymstec)**

Certificate No: **H3-6051_Sep10**

CALIBRATION CERTIFICATE

Object: **H3DV6 - SN:6051**

Calibration procedure(s): **QA CAL-03.v5 and QA CAL-25.v2
Calibration procedure for H-field probes optimized for close near field
evaluations in air**

Calibration date: **September 20, 2010**

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The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

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Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
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Reference 3 dB Attenuator	SN: S5054 (3c)	30-Mar-10 (No. 217-01159)	Mar-11
Reference 20 dB Attenuator	SN: S5086 (20b)	30-Mar-10 (No. 217-01161)	Mar-11
Reference 30 dB Attenuator	SN: S5129 (30b)	30-Mar-10 (No. 217-01160)	Mar-11
Reference Probe H3DV6	SN: 6182	3-Oct-09 (No. H3-6182_Oct09)	Oct-10
DAE4	SN: 789	31-Aug-10 (No. DAE4-789_Aug10)	Aug-11
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	
Approved by:	Fin Bornholt	R&D Director	

Issued: September 20, 2010

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DCP diode compression point
CF crest factor (1/duty_cycle) of the RF signal
A, B, C modulation dependent linearization parameters
Polarization φ φ rotation around probe axis
Polarization ϑ ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center),
i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- **NORM_{x,y,z}**: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- **X, Y, Z(f) $a_0 a_1 a_2 = X, Y, Z_{a_0 a_1 a_2} \cdot \text{frequency_response}$** (see Frequency Response Chart).
- **DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- **A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}; A, B, C** are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- **Spherical isotropy (3D deviation from isotropy)**: in a locally homogeneous field realized using an open waveguide setup.
- **Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- **Connector Angle**: The angle is assessed using the information gained by determining the **X_{a_0 a_1 a_2}** (no uncertainty required).

H3DV6 SN:6051

September 20, 2010

Probe H3DV6

SN:6051

Manufactured:	November 3, 1999
Last calibrated:	November 23, 2009
Recalibrated:	September 20, 2010

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

H3DV6 SN:6051

September 20, 2010

DASY/EASY - Parameters of Probe: H3DV6 SN:6051

Basic Calibration Parameters

		Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (A/m / $\sqrt{\mu V}$)	a0	2.83E-3	2.61E-3	2.98E-3	$\pm 5.1\%$
Norm (A/m / $\sqrt{\mu V}$)	a1	-2.52E-4	-1.91E-4	-6.62E-4	$\pm 5.1\%$
Norm (A/m / $\sqrt{\mu V}$)	a2	6.03E-5	5.33E-5	2.20E-4	$\pm 5.1\%$
DCP (mV) ^A		89.9	83.1	82.7	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc ^E (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	$\pm 1.5\%$
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A numerical linearization parameter: uncertainty not required

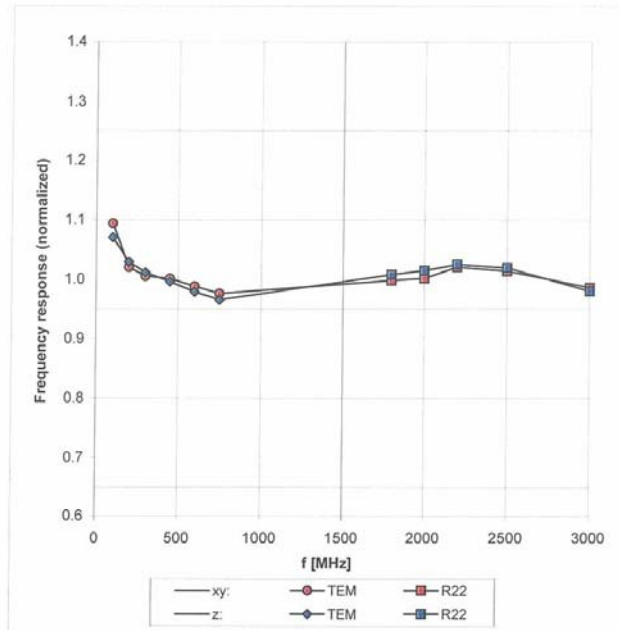
^E Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

H3DV6 SN:6051

September 20, 2010

Frequency Response of H-Field

(TEM-Cell: ifi110 EXX, Waveguide R22)

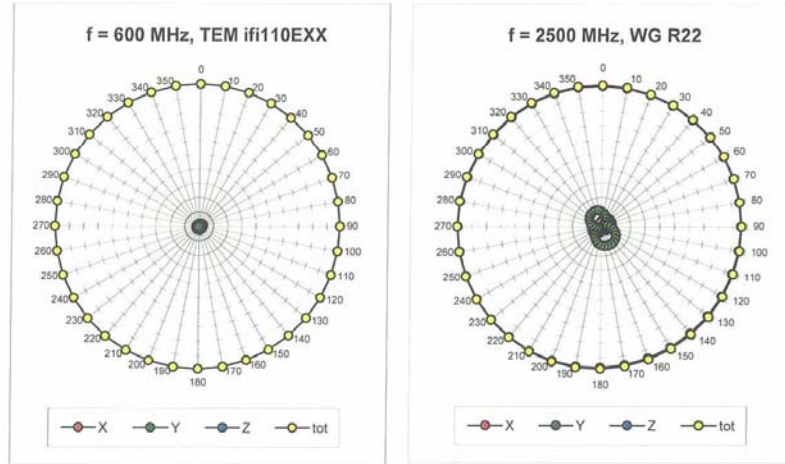


Uncertainty of Frequency Response of H-field: $\pm 6.3\%$ (k=2)

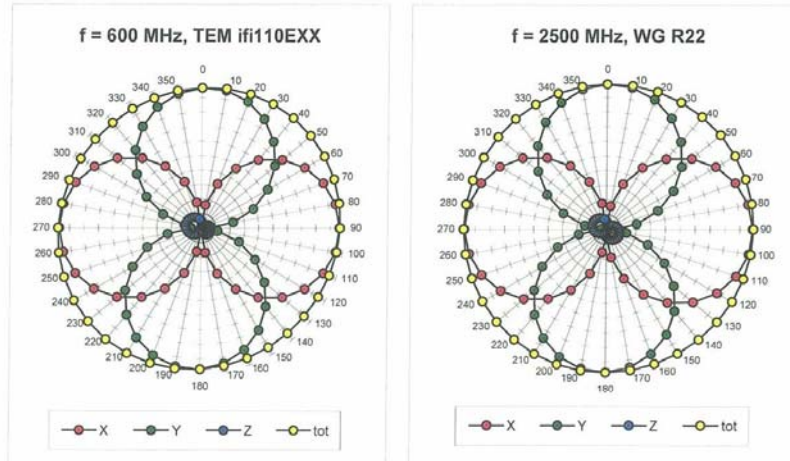
H3DV6 SN:6051

September 20, 2010

Receiving Pattern (ϕ), $\vartheta = 90^\circ$



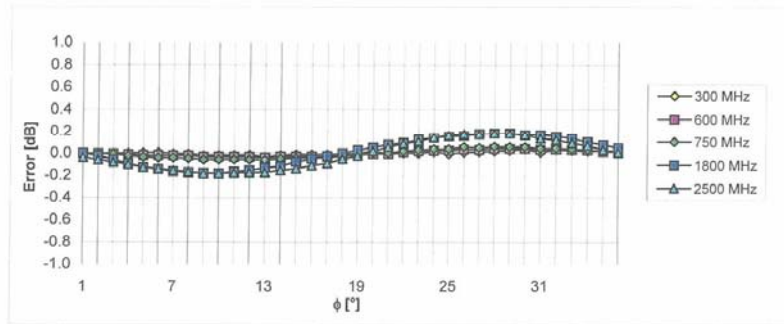
Receiving Pattern (ϕ), $\vartheta = 0^\circ$



H3DV6 SN:6051

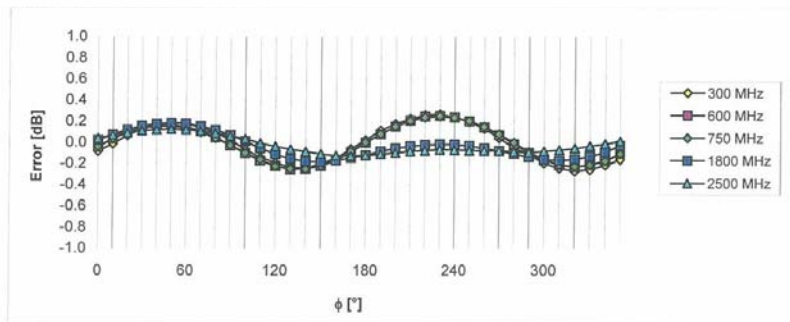
September 20, 2010

Receiving Pattern (ϕ), $\vartheta = 90^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



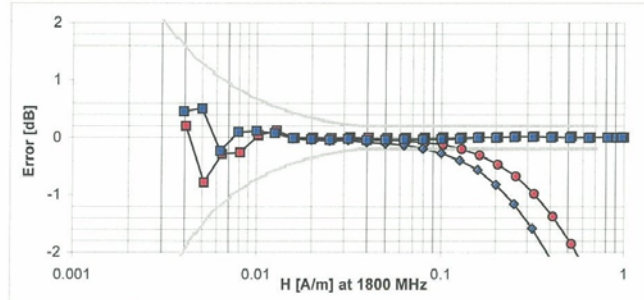
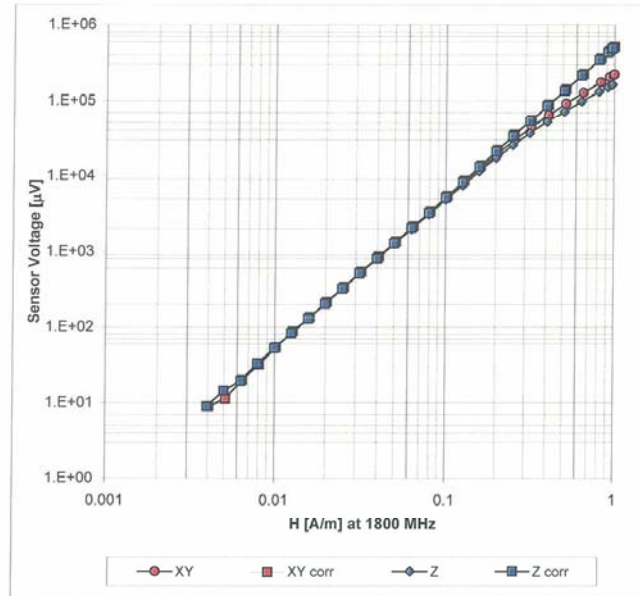
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

H3DV6 SN:6051

September 20, 2010

Dynamic Range f(H-field)

(Waveguide R22, f = 1800 MHz)

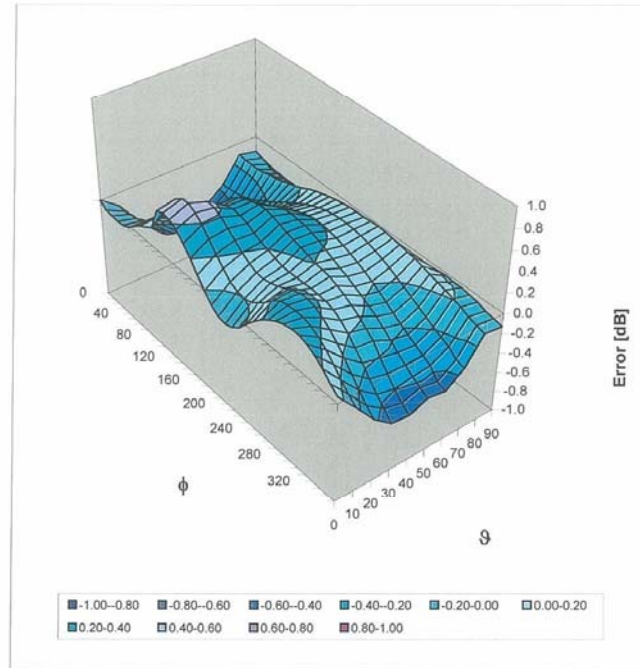


Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

H3DV6 SN:6051

September 20, 2010

Deviation from Isotropy in Air Error (ϕ, ϑ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

H3DV6 SN:6051

September 20, 2010

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-213.8
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6.0 mm
Probe Tip to Sensor X Calibration Point	3 mm
Probe Tip to Sensor Y Calibration Point	3 mm
Probe Tip to Sensor Z Calibration Point	3 mm

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Accreditation No.: **SCS 108**

Client **HCT (Dymstec)**

Certificate No: **ER3-2343_May11**

CALIBRATION CERTIFICATE

Object: **ER3DV6 - SN:2343**

Calibration procedure(s): **QA CAL-02.v6, QA CAL-25.v3
Calibration procedure for E-field probes optimized for close near field evaluations in air**

Calibration date: **May 16, 2011**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	31-Mar-11 (No. 217-01372)	Apr-12
Power sensor E4412A	MY41498087	31-Mar-11 (No. 217-01372)	Apr-12
Reference 3 dB Attenuator	SN: S5054 (3c)	29-Mar-11 (No. 217-01369)	Apr-12
Reference 20 dB Attenuator	SN: S5086 (20b)	29-Mar-11 (No. 217-01367)	Apr-12
Reference 30 dB Attenuator	SN: S5129 (30b)	29-Mar-11 (No. 217-01370)	Apr-12
Reference Probe ER3DV6	SN: 2328	4-Oct-10 (No. ER3-2328_Oct10)	Oct-11
DAE4	SN: 789	6-Apr-11 (No. DAE4-789_Apr11)	Apr-12
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-10)	In house check: Oct-11

Calibrated by: **Claudio Leubler** Name: Claudio Leubler Function: Laboratory Technician Signature: *[Signature]*

Approved by: **Katja Pokovic** Name: Katja Pokovic Function: Technical Manager Signature: *[Signature]*

Issued: May 16, 2011

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Glossary:

NORM _{x,y,z}	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., θ = 0 is normal to probe axis
Connector Angle	information used in DASYS system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- *NORM_{x,y,z}*: Assessed for E-field polarization θ = 0 for XY sensors and θ = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- *NORM(f)_{x,y,z}* = *NORM_{x,y,z}* * *frequency_response* (see Frequency Response Chart).
- *DCP_{x,y,z}*: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}*: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- *Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle*: The angle is assessed using the information gained by determining the *NORM_x* (no uncertainty required).

ER3DV6 – SN:2343

May 16, 2011

Probe ER3DV6

SN:2343

Manufactured: December 14, 2004
Calibrated: May 16, 2011

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

ER3DV6- SN:2343

May 16, 2011

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2343

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu\text{V}/(\text{V}/\text{m})^2$)	1.65	1.61	1.62	$\pm 10.1 \%$
DCP (mV) ^B	96.8	100.4	98.7	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc ^E (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	120.8	$\pm 2.7 \%$
			Y	0.00	0.00	1.00	112.2	
			Z	0.00	0.00	1.00	100.8	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

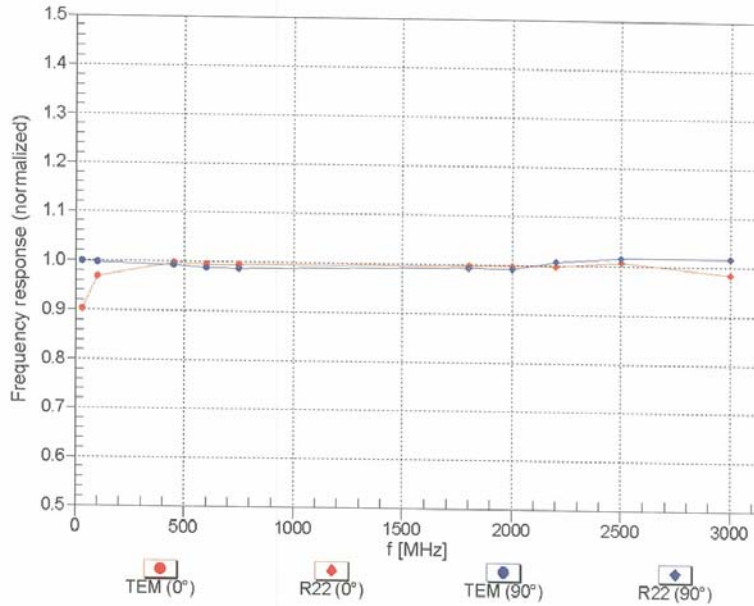
^B Numerical linearization parameter; uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

ER3DV6-SN:2343

May 16, 2011

Frequency Response of E-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



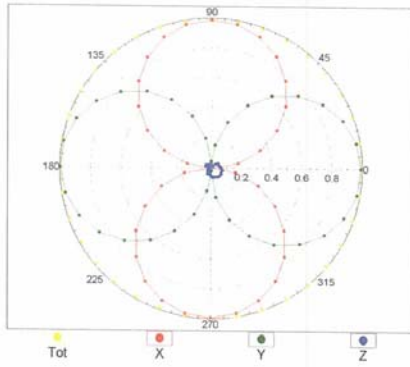
Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ (k=2)

ER3DV6- SN:2343

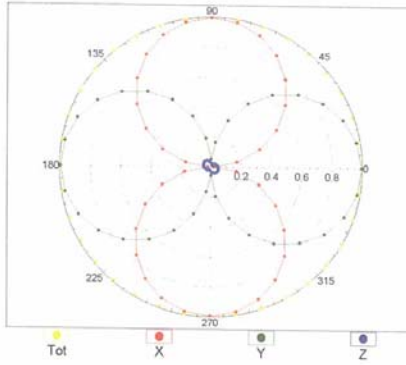
May 16, 2011

Receiving Pattern (ϕ), $\vartheta = 0^\circ$

f=600 MHz,TEM,0°

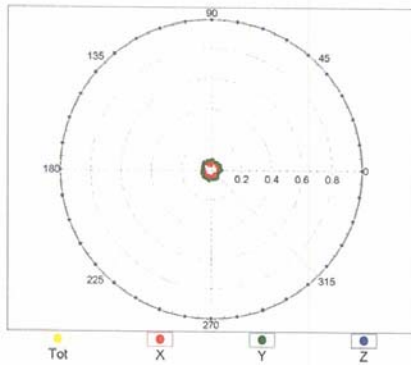


f=2500 MHz,R22,0°

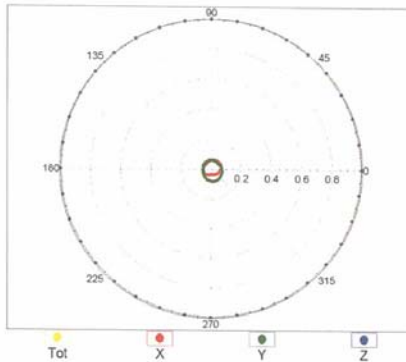


Receiving Pattern (ϕ), $\vartheta = 90^\circ$

f=600 MHz,TEM,90°



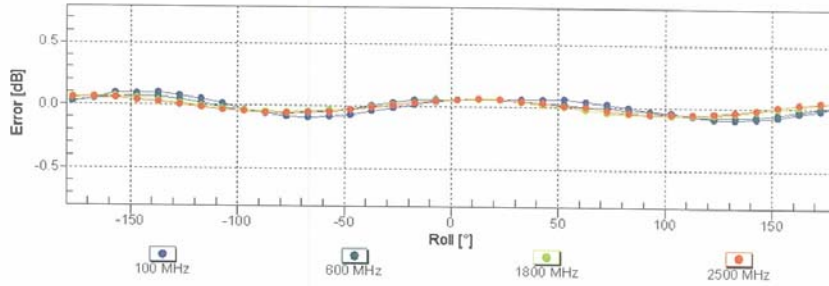
f=2500 MHz,R22,90°



ER3DV6-SN:2343

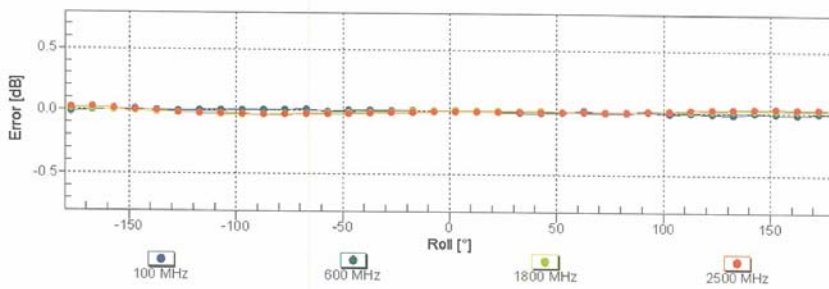
May 16, 2011

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\vartheta = 90^\circ$

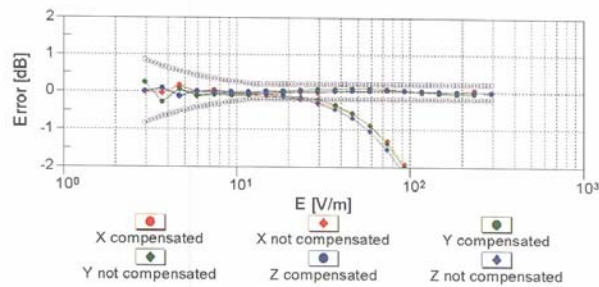
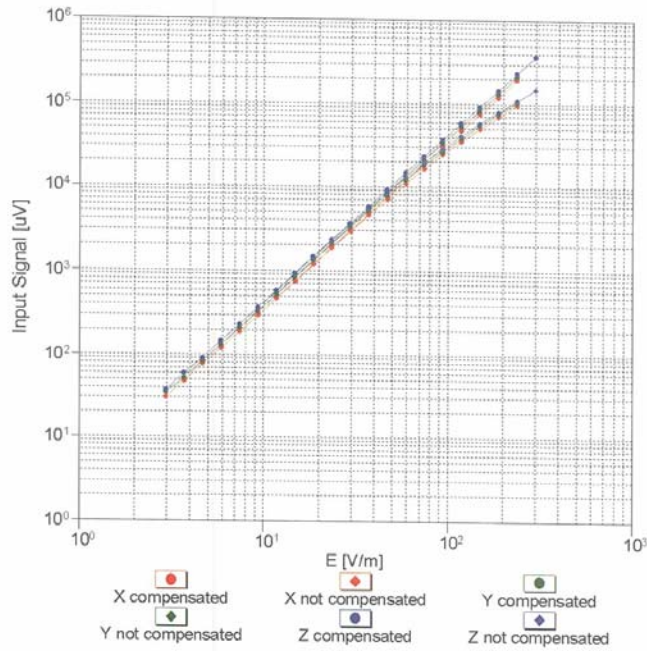


Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

ER3DV6- SN:2343

May 16, 2011

Dynamic Range f(E-field) (TEM cell , f = 900 MHz)

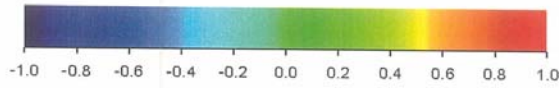
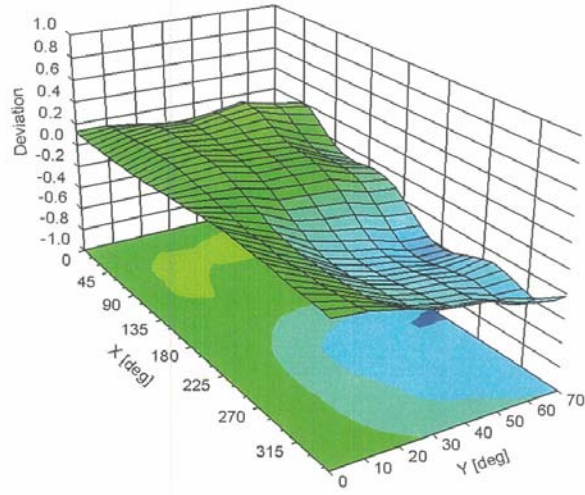


Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

ER3DV6- SN:2343

May 16, 2011

Deviation from Isotropy in Air Error (ϕ, θ), $f = 900$ MHz

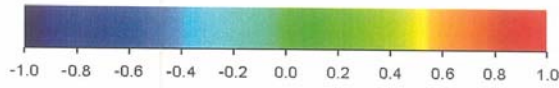
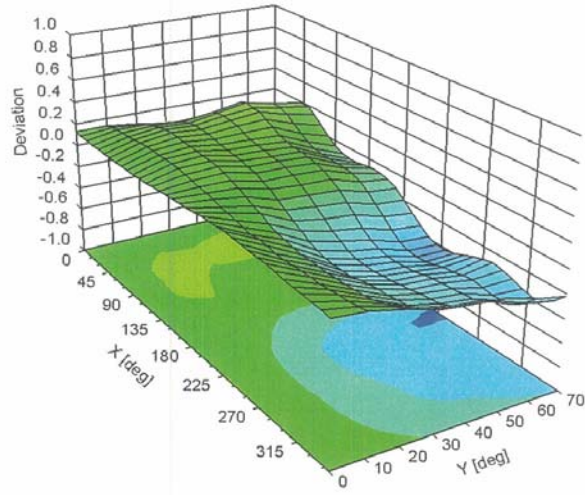


Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ (k=2)

ER3DV6- SN:2343

May 16, 2011

Deviation from Isotropy in Air Error (ϕ, θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

ER3DV6- SN:2343

May 16, 2011

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2343**Other Probe Parameters**

Sensor Arrangement	Rectangular
Connector Angle (°)	62.8
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

**Calibration Laboratory of
Schmid & Partner
Engineering AG**
Zeughausstrasse 43, 8004 Zurich, Switzerland



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The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Client **HCT (Dymstec)**

Certificate No: **H3-6101_May11**

CALIBRATION CERTIFICATE

Object: **H3DV6 - SN:6101**

Calibration procedure(s): **QA CAL-03.v6, QA CAL-25.v3
Calibration procedure for H-field probes optimized for close near field
evaluations in air**

Calibration date: **May 18, 2011**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	31-Mar-11 (No. 217-01372)	Apr-12
Power sensor E4412A	MY41498087	31-Mar-11 (No. 217-01372)	Apr-12
Reference 3 dB Attenuator	SN: S5054 (3c)	29-Mar-11 (No. 217-01369)	Apr-12
Reference 20 dB Attenuator	SN: S5086 (20b)	29-Mar-11 (No. 217-01367)	Apr-12
Reference 30 dB Attenuator	SN: S5129 (30b)	29-Mar-11 (No. 217-01370)	Apr-12
Reference Probe H3DV6	SN: 6182	4-Oct-10 (No. H3-6182 Oct10)	Oct-11
DAE4	SN: 789	6-Apr-11 (No. DAE4-789 Apr11)	Apr-12
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-10)	In house check: Oct-11

Calibrated by:	Name Claudio Leubler	Function Laboratory Technician	Signature
Approved by:	Name Katja Pokovic	Function Technical Manager	Signature

Issued: May 19, 2011

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Accreditation No.: **SCS 108**

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Glossary:

NORM _{x,y,z}	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1309-2005, " IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- *NORM_{x,y,z}*: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- *X, Y, Z(f)_a0a1a2 = X, Y, Z_a0a1a2* frequency_response* (see Frequency Response Chart).
- *DCP_{x,y,z}*: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}; A, B, C* are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. *VR* is the maximum calibration range expressed in RMS voltage across the diode.
- *Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle*: The angle is assessed using the information gained by determining the *X_a0a1a2* (no uncertainty required).

H3DV6 – SN:6101

May 18, 2011

Probe H3DV6

SN:6101

Manufactured: December 10, 2001
Calibrated: May 18, 2011

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

H3DV6- SN:6101

May 18, 2011

DASY/EASY - Parameters of Probe: H3DV6 - SN:6101

Basic Calibration Parameters

		Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (A/m / $\sqrt{\text{mV}}$)	a0	2.97E-003	2.96E-003	3.16E-003	$\pm 5.1 \%$
Norm (A/m / $\sqrt{\text{mV}}$)	a1	-8.75E-005	-1.29E-004	-1.54E-004	$\pm 5.1 \%$
Norm (A/m / $\sqrt{\text{mV}}$)	a2	-6.62E-005	-8.39E-005	-8.33E-006	$\pm 5.1 \%$
DCP (mV) ^D		93.3	91.4	90.4	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc (k=2) ^E
10000	CW	0.00	X	0.00	0.00	1.00	121.8	$\pm 3.0 \%$
			Y	0.00	0.00	1.00	123.4	
			Z	0.00	0.00	1.00	125.9	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

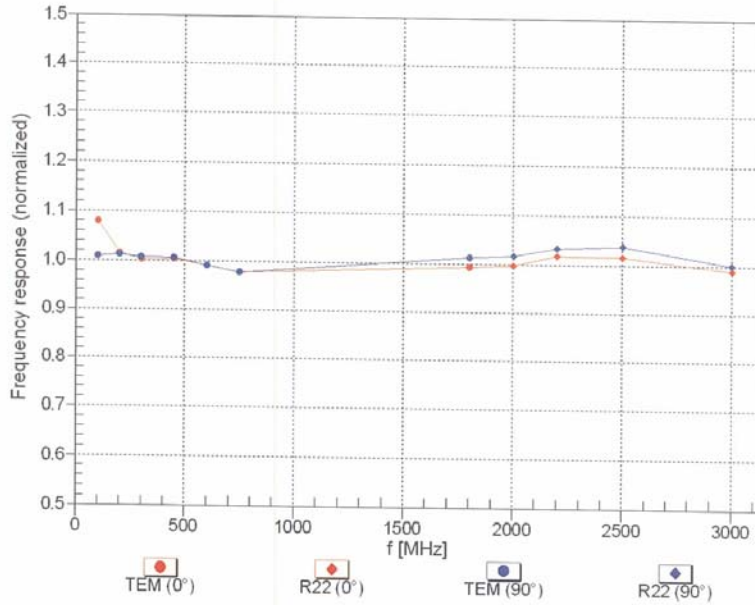
^D Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

H3DV6- SN:6101

May 18, 2011

Frequency Response of H-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



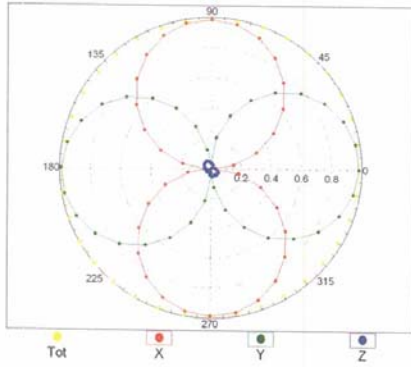
Uncertainty of Frequency Response of H-field: $\pm 6.3\%$ (k=2)

H3DV6- SN:6101

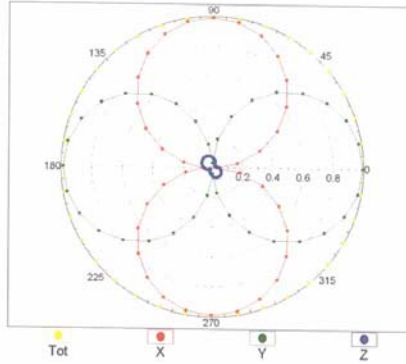
May 18, 2011

Receiving Pattern (ϕ), $\vartheta = 0^\circ$

f=600 MHz,TEM,0°

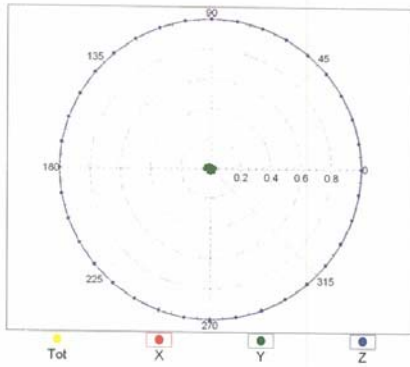


f=2500 MHz,R22,0°

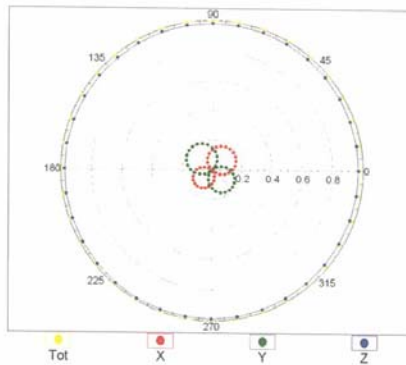


Receiving Pattern (ϕ), $\vartheta = 90^\circ$

f=600 MHz,TEM,90°



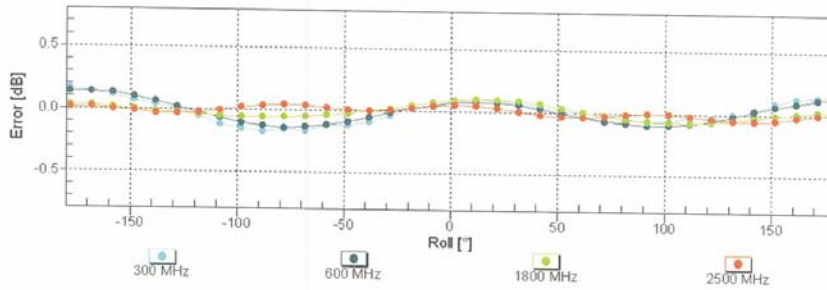
f=2500 MHz,R22,90°



H3DV6-SN:6101

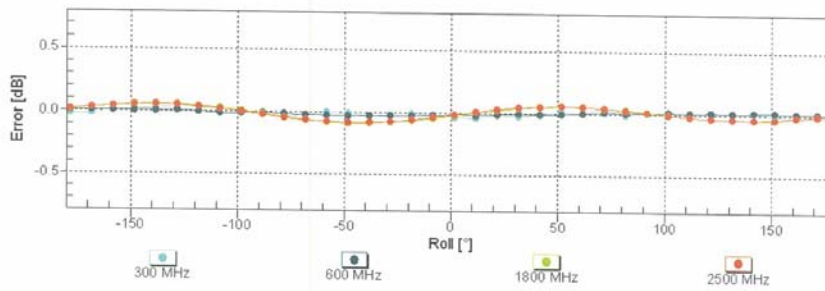
May 18, 2011

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\vartheta = 90^\circ$

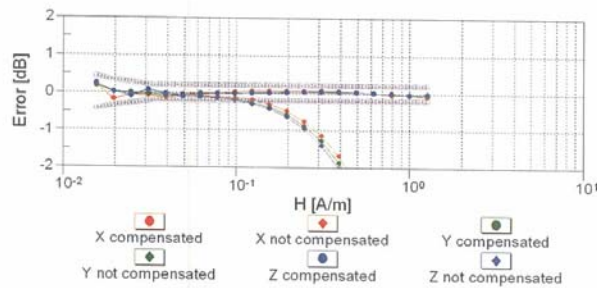
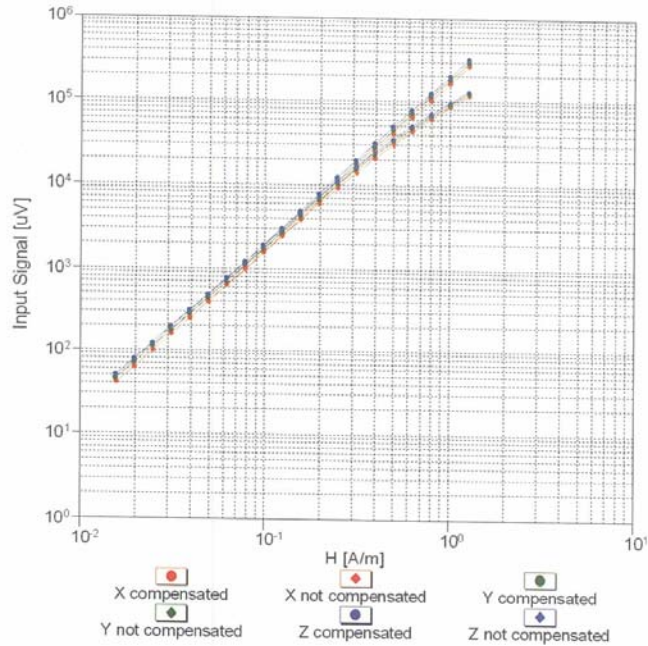


Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

H3DV6-SN:6101

May 18, 2011

Dynamic Range f(H-field) (TEM cell, f = 900 MHz)



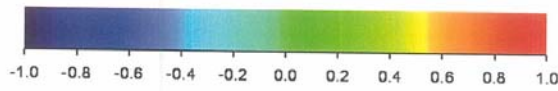
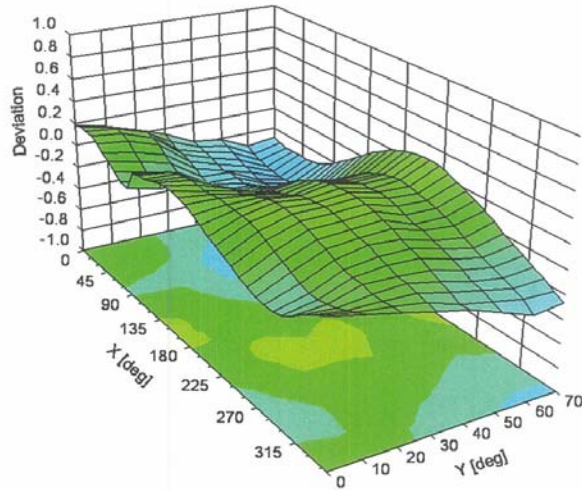
Uncertainty of Linearity Assessment: ± 0.6% (k=2)

H3DV6- SN:6101

May 18, 2011

Deviation from Isotropy in Air

Error (ϕ, θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

H3DV6- SN:6101

May 18, 2011

DASY/EASY - Parameters of Probe: H3DV6 - SN:6101**Other Probe Parameters**

Sensor Arrangement	Rectangular
Connector Angle (°)	-38.4
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6 mm
Probe Tip to Sensor X Calibration Point	3 mm
Probe Tip to Sensor Y Calibration Point	3 mm
Probe Tip to Sensor Z Calibration Point	3 mm