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ILAC MRA

**Specific Absorption Rate (SAR) Test Report**  
for  
**Universal Scientific Industrial Co., Ltd.**  
on the  
**U.S. Robotics Wireless Maxg USB Adapter**

**Report No.** : FA521613-1-2-01  
**Trade Name** : USR  
**Model Name** : USR5421  
**FCC ID** : IXM-USGBR01  
**Date of Testing** : Feb. 22, 2005  
**Date of Report** : Feb. 25, 2005  
**Date of Review** : Feb. 28, 2005

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***SPORTON International Inc.***

6F, No.106, Sec. 1, Hsin Tai Wu Rd., Hsi Chih, Taipei Hsien, Taiwan, R.O.C.



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**Appendix A – System Performance Check Data**

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**Appendix C – Calibration Data**

## 1. Statement of Compliance

The Specific Absorption Rate (SAR) maximum result found during testing for the **Universal Scientific Industrial Co., Ltd. U.S. Robotics Wireless Maxg USB Adapter USR5421** is **1.28 W/Kg** on the **WLAN body SAR** with expanded uncertainty 20.6%. The co-location of GPRS, WLAN and BT were also checked. It is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1999 and had been tested in accordance with the measurement methods and procedures specified in OET Bulletin 65 Supplement C (Edition 01-01).

Tested by

Approved by



Nilson She  
Test Engineer

 3/2/2005

Dr. C.H. Daniel Lee  
SAR Lab. Manager



## **2. Administration Data**

### **2.1. Testing Laboratory**

**Company Name :** Sporton International Inc.  
**Department :** Antenna Design/SAR  
**Address :** No.52, Hwa-Ya 1<sup>st</sup> RD., Hwa Ya Technology Park, Kwei-Shan Hsiang,  
TaoYuan Hsien, Taiwan, R.O.C.  
**Telephone Number :** 886-3-327-3456  
**Fax Number :** 886-3-327-0973

### **2.2. Detail of Applicant**

**Company Name :** Universal Scientific Industrial Co., Ltd.  
**Address :** 141, Lane 351, Taiping Road, Sec. 1, Tsao Tuen, Nan-Tou, Taiwan  
**Telephone Number :** 886-4-9232-5876  
**Fax Number :** 886-4-92352872  
**Contact Person :** marvin@ms.usi.com.tw

### **2.3. Detail of Manufacturer**

**Company Name :** Universal Scientific Industrial Co., Ltd.  
**Address :** 141, Lane 351, Taiping Road, Sec. 1, Tsao Tuen, Nan-Tou, Taiwan

### **2.4. Application Detail**

**Date of reception of application:** Feb. 16, 2005  
**Start of test :** Feb. 22, 2005  
**End of test :** Feb. 22, 2005



### 3. Scope

#### 3.1. Description of Device Under Test (DUT)

<b>DUT Type :</b>	U.S. Robotics Wireless Maxg USB Adapter
<b>Trade Name :</b>	USR
<b>Model Name :</b>	USR5421
<b>FCC ID :</b>	IXM-USGBR01
<b>Type of Modulation :</b>	802.11b: CCK/11Mbps 802.11g: OFDM/54Mbps
<b>Frequency Range :</b>	2400~2483.5 MHz
<b>Antenna Connector :</b>	N/A
<b>Antenna Type :</b>	On board printed antenna
<b>Antenna Gain :</b>	-1 dBi
<b>Maximum Output Power to Antenna (Average) :</b>	802.11b: 21.4 dBm 802.11g: 21.9 dBm
<b>Power Rating (DC/AC Voltage) :</b>	DC 5V
<b>DUT Stage :</b>	Production Unit
<b>Application Type :</b>	Certification



3.2. Product Photo



Top View



Bottom View



**3.3. Applied Standards:**

The Specific Absorption Rate (SAR) testing specification, method and procedure for this **U.S. Robotics Wireless Maxg USB Adapter** is in accordance with the following standards:

47 CFR Part 2 ( 2.1093),  
IEEE C95.1-1999,  
IEEE C95.3-2002,  
IEEE P1528 -2003, and  
OET Bulletin 65 Supplement C (Edition 01-01)





**3.4. Device Category and SAR Limits**

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user.

Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue.

**3.5. Test Conditons**

**3.5.1. Ambient Condition:**

Item	802.11b/802.11g
Ambient Temperature (°C)	20 ~ 24°C
Tissue simulating liquid temperature (°C)	22.3°C
Humidity (%)	< 60%

**3.5.2. Test Configuration:**

Engineering testing software installed on the Notebook can provide continuous transmitting RF signal. This RF signal utilized in SAR measurement has almost 100% duty cycle and its crest factor is 1. The measurements were performed on the lowest, middle, and highest channel, i.e. channel 1, channel 6, and channel 11 for each testing position.



#### 4. Specific Absorption Rate (SAR)

##### 4.1. Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The FCC recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

##### 4.2. SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density ( $\rho$ ). The equation description is as below:

$$\mathbf{SAR} = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dv} \right)$$

*SAR is expressed in units of Watts per kilogram (W/kg)*

SAR measurement can be either related to the temperature elevation in tissue by

$$\mathbf{SAR} = C \frac{\delta T}{\delta t}$$

, where C is the specific heat capacity,  $\delta T$  is the temperature rise and  $\delta t$  the exposure duration,

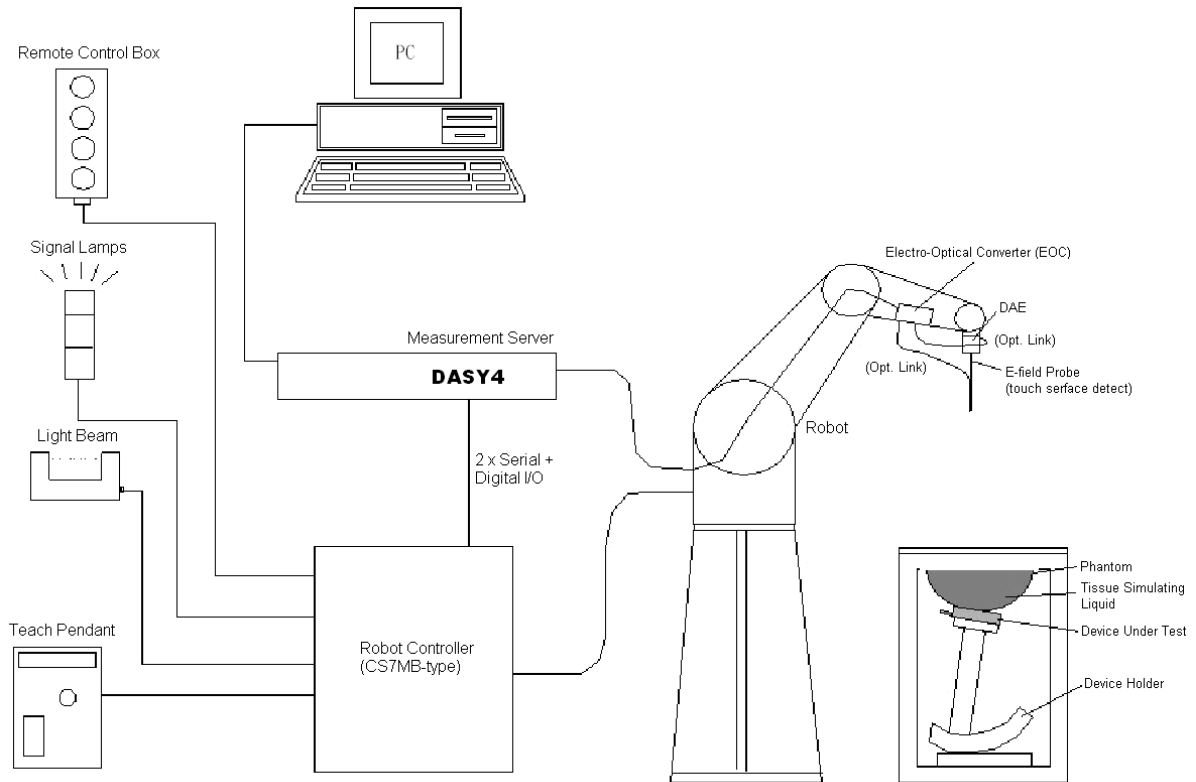
or related to the electrical field in the tissue by

$$\mathbf{SAR} = \frac{\sigma |E|^2}{\rho}$$

, where  $\sigma$  is the conductivity of the tissue,  $\rho$  is the mass density of the tissue and  $E$  is the rms electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

## 5. SAR Measurement Setup



**Fig. 5.1 DASY4 system**



The DASY4 system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (ECO) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY4 software
- Remove control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom
- A device holder
- Tissue simulating liquid
- Dipole for evaluating the proper functioning of the system

Some of the components are described in details in the following sub-sections.

### **5.1. DASY4 E-Field Probe System**

The SAR measurement is conducted with the dosimetric probe ET3DV6 (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

5.1.1. ET3DV6 E-Field Probe Specification

<b>Construction</b>	Symmetrical design with triangular core Built-in optical fiber for surface detection system Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents)
<b>Calibration</b>	Simulating tissue at frequencies of 900MHz, 1.8GHz and 2.45GHz for brain and muscle (accuracy $\pm 8\%$ )
<b>Frequency</b>	10 MHz to > 3 GHz
<b>Directivity</b>	$\pm 0.2$ dB in brain tissue (rotation around probe axis) $\pm 0.4$ dB in brain tissue (rotation perpendicular to probe axis)
<b>Dynamic Range</b>	5 $\mu$ W/g to > 100mW/g; Linearity: $\pm 0.2$ dB
<b>Surface Detection</b>	$\pm 0.2$ mm repeatability in air and clear liquids on reflecting surface
<b>Dimensions</b>	Overall length: 330mm Tip length: 16mm Body diameter: 12mm  Tip diameter: 6.8mm Distance from probe tip to dipole centers: 2.7mm
<b>Application</b>	General dosimetry up to 3GHz Compliance tests for mobile phones and Wireless LAN Fast automatic scanning in arbitrary phantoms



**Fig. 5.2 Probe setup on robot**

5.1.2. ET3DV6 E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than  $\pm 10\%$ . The spherical isotropy shall be evaluated and within  $\pm 0.25$ dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data are as below:



<b>Sensitivity</b>	X axis : 1.68 $\mu$ V	Y axis : 1.70 $\mu$ V	Z axis : 1.74 $\mu$ V	
<b>Diode compression point</b>	X axis : 94 mV	Y axis : 94 mV	Z axis : 94 mV	
<b>Conversion factor (Head / Body)</b>	<b>Frequency (MHz)</b>	<b>X axis</b>	<b>Y axis</b>	<b>Z axis</b>
	2350~2550	4.56 / 4.26	4.56 / 4.26	4.56 / 4.26
<b>Boundary effect (Head / Body)</b>	<b>Frequency (MHz)</b>	<b>Alpha</b>	<b>Depth</b>	
	2350~2550	0.65 / 0.72	2.22 / 2.00	

NOTE:

1. The probe parameters have been calibrated by the SPEAG.
2. For the detailed calibration data is shown in Appendix C.

5.2. DATA Acquisition Electronics (DAE)

The data acquisition electronics (DAE4) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE4 is 200M Ohm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.

Calibration data is attached in Appendix C.



### 5.3. Robot

The DASY4 system uses the high precision robots RX90BL type out of the newer series from Stäubli SA (France). For the 6-axis controller DASYS system, the CS7MB robot controller version from Stäubli is used. The RX robot series have many features that are important for our application:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller

### 5.4. Measurement Server

The DASY4 measurement server is based on a PC/104 CPU board with  
166 MHz CPU  
32 MB chipset and  
64 MB RAM.

Communication with  
the DAE4 electronic box  
the 16-bit AD-converter system for optical detection and digital I/O interface.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.

### 5.5. SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left head
- Right head
- Flat phantom

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections.

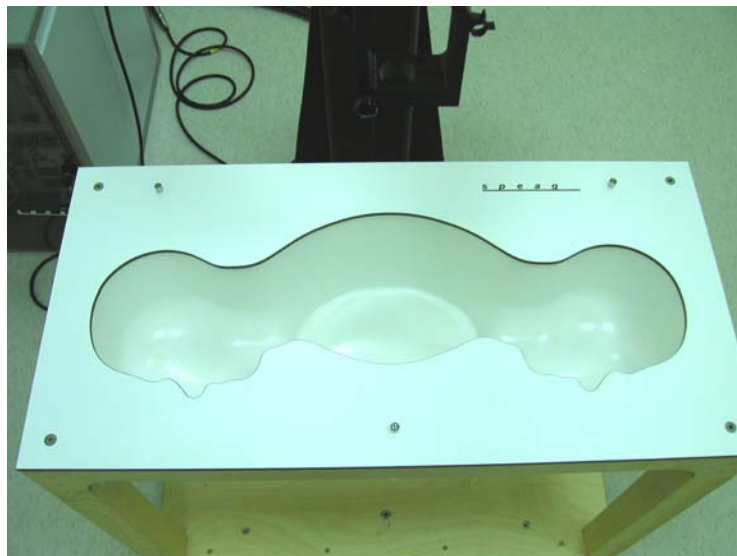
A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters.

On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

The phantom can be used with the following tissue simulating liquids:

\*Water-sugar based liquid

\*Glycol based liquids



**Fig. 5.3 Top view of twin phantom**



**Fig. 5.4 Bottom view of twin phantom**





5.6. Data Storage and Evaluation

5.6.1. Data Storage

The DASY4 software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension .DA4. The postprocessing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a loseless media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

5.6.2. Data Evaluation

The DASY4 postprocessing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software :

<b>Probe parameters :</b>	- Sensitivity	Norm <sub>i</sub> , a <sub>i0</sub> , a <sub>i1</sub> , a <sub>i2</sub>
	- Conversion factor	ConvF <sub>i</sub>
	- Diode compression point	dcp <sub>i</sub>
<b>Device parameters :</b>	- Frequency	f
	- Crest factor	cf
<b>Media parameters :</b>	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used. The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel



can be given as :

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with  $V_i$  = compensated signal of channel  $i$  ( $i = x, y, z$ )  
 $U_i$  = input signal of channel  $i$  ( $i = x, y, z$ )  
 $cf$  = crest factor of exciting field (DASY parameter)  
 $dcp_i$  = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated :

E-field probes :  $E_i = \sqrt{\frac{V_i}{Norm_i ConvF}}$

H-field probes :  $H_i = \sqrt{V_i} \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$

with  $V_i$  = compensated signal of channel  $i$  ( $i = x, y, z$ )  
 $Norm_i$  = sensor sensitivity of channel  $i$  ( $i = x, y, z$ )  
 $\mu V/(V/m)^2$  for E-field Probes  
 $ConvF$  = sensitivity enhancement in solution  
 $a_{ij}$  = sensor sensitivity factors for H-field probes  
 $f$  = carrier frequency [GHz]  
 $E_i$  = electric field strength of channel  $i$  in V/m  
 $H_i$  = magnetic field strength of channel  $i$  in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude) :

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with  $SAR$  = local specific absorption rate in mW/g  
 $E_{tot}$  = total field strength in V/m  
 $\sigma$  = conductivity in [mho/m] or [Siemens/m]  
 $\rho$  = equivalent tissue density in g/ cm<sup>3</sup>



\* Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770} \quad \text{or} \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

with  $P_{pwe}$  = equivalent power density of a plane wave in mW/cm<sup>2</sup>  
 $E_{tot}$  = total electric field strength in V/m  
 $H_{tot}$  = total magnetic field strength in A/m



5.7. Test Equipment List

Manufacture	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	Due Date
SPEAG	Dosimetric E-Filed Probe	ET3DV6	1788	Sep. 30, 2004	Sep. 30, 2005
SPEAG	835MHz System Validation Kit	D835V2	499	Feb. 12, 2004	Feb. 12, 2006
SPEAG	900MHz System Validation Kit	D900V2	190	July 17, 2003	July 17, 2005
SPEAG	1800MHz System Validation Kit	D1800V2	2d076	July 16, 2003	July 16, 2005
SPEAG	1900MHz System Validation Kit	D1900V2	5d041	Feb. 17, 2004	Feb. 17, 2006
SPEAG	2450MHz System Validation Kit	D2450V2	736	Aug. 26, 2003	Aug. 26, 2005
SPEAG	Data Acquisition Electronics	DAE3	577	Nov. 17, 2004	Nov. 17, 2005
SPEAG	Device Holder	N/A	N/A	NCR	NCR
SPEAG	Phantom	QD 000 P40 C	TP-1150	NCR	NCR
SPEAG	Robot	Staubli RX90BL	F03/5W15A1/A/01	NCR	NCR
SPEAG	Software	DASY4 V4.4 Build 3	N/A	NCR	NCR
SPEAG	Software	SEMCAD V1.8 Build 130	N/A	NCR	NCR
SPEAG	Measurement Server	SE UMS 001 BA	1021	NCR	NCR
Agilent	S-Parameter Network Analyzer (PNA)	E8358A	US40260131	Nov. 24,2004	Nov. 24, 2005
Agilent	Dielectric Probe Kit	85070D	US01440205	NCR	NCR
Agilent	Dual Directional Coupler	778D	50422	NCR	NCR
Agilent	Power Amplifier	8449B	3008A01917	NCR	NCR
R & S	Radio Communication Tester	CMU200	105934	Aug. 24, 2004	Aug 24, 2005
Agilent	Power Meter	E4416A	GB41292344	Jan. 21, 2005	Jan. 21, 2006
Agilent	Signal Generator	E8247C	MY43320596	Feb. 10, 2004	Feb. 10, 2006
Agilent	Base Station Emulator	E5515C	GB43460754	Jan. 12, 2004	Jan. 12, 2006

**Table 5.1 Test Equipment List**



6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY4, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. The liquid height from the bottom of the phantom body is 15.2 centimeters, which is shown in Fig. 6.1.

The following ingredients for tissue simulating liquid are used:

- **Water:** deionized water (pure H<sub>2</sub>O), resistivity  $\geq 16M\Omega$  - as basis for the liquid
- **Sugar:** refined sugar in crystals, as available in food shops – to reduce relative permittivity
- **Salt:** pure NaCl – to increase conductivity
- **Cellulose:** Hydroxyethyl-cellulose, medium viscosity (75-125 mPa.s, 2% in water, 20°C), CAS#54290-to increase viscosity and to keep sugar in solution.
- **Preservative:** Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS#55965-84-9- to prevent the spread of bacteria and molds.
- **DGMBE:** Deithlenglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH, CAS#112-34-5 – to reduce relative permittivity.

Table 6.1 gives the recipes for one liter of tissue simulating liquid for frequency band 2450 MHz.

Ingredient	MSL-2450
Water	698.3 ml
DGMBE	301.7 ml
Total amount	1 liter (1.0 kg)
Dielectric Parameters at 22°	f = 2450MHz $\epsilon_r = 52.5 \pm 5\%$ , $\sigma = 2.00 \pm 5\%$ S/m

Table 6.1

The dielectric parameters of the liquids were verified prior to the SAR evaluation using an Agilent 85070D Dielectric Probe Kit and an Agilent E8358A Network Analyzer.



Table 6.2 shows the measuring results for muscle simulating liquid.

Bands	Frequency(MHz)	Permittivity ( $\epsilon_r$ )	Conductivity ( $\sigma$ )	Measurement date
2450 MHz	2412	51.4	1.94	Feb. 22, 2005
	2437	51.6	2	
	2462	51.6	2.02	

Table 6.2

The measuring data are consistent with  $\epsilon_r = 52.5 \pm 5\%$  and  $\sigma = 2.00 \pm 5\%$ .



Fig. 6.1



### 7. Uncertainty Assessment

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and knowledge of the behavior and properties of relevant materials and instruments, manufacture’s specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table 7.1

Uncertainty Distributions	Normal	Rectangular	Triangular	U-shape
Multiplying factor <sup>(a)</sup>	1/k <sup>(b)</sup>	1/√3	1/√6	1/√2

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b) *k* is the coverage factor

**Table 7.1**

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual “root-sum-squares” (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY4 uncertainty Budget is showed in Table 7.2.



Error Description	Uncertainty Value $\pm$ %	Probability Distribution	Divisor	$C_i$ $1g$	Standard Unc. (1-g)	$v_i$ or $V_{eff}$
<b>Measurement System</b>						
Probe Calibration	$\pm 4.8$	Normal	1	1	$\pm 4.8$	$\infty$
Axial Isotropy	$\pm 4.7$	Rectangular	$\sqrt{3}$	0.7	$\pm 1.9$	$\infty$
Hemispherical Isotropy	$\pm 9.6$	Rectangular	$\sqrt{3}$	0.7	$\pm 3.9$	$\infty$
Boundary Effect	$\pm 1.0$	Rectangular	$\sqrt{3}$	1	$\pm 0.6$	$\infty$
Linearity	$\pm 4.7$	Rectangular	$\sqrt{3}$	1	$\pm 2.7$	$\infty$
System Detection Limit	$\pm 1.0$	Rectangular	$\sqrt{3}$	1	$\pm 0.6$	$\infty$
Readout Electronics	$\pm 1.0$	Normal	1	1	$\pm 1.0$	$\infty$
Response Time	$\pm 0.8$	Rectangular	$\sqrt{3}$	1	$\pm 0.5$	$\infty$
Integration time	$\pm 2.6$	Rectangular	$\sqrt{3}$	1	$\pm 1.5$	$\infty$
RF Ambient Conditions	$\pm 3.0$	Rectangular	$\sqrt{3}$	1	$\pm 1.7$	$\infty$
Probe Positioner Mech. Tolerance	$\pm 0.4$	Rectangular	$\sqrt{3}$	1	$\pm 0.2$	$\infty$
Probe Positioning with respect to Phantom Shell	$\pm 2.9$	Rectangular	$\sqrt{3}$	1	$\pm 1.7$	$\infty$
Extrapolation and Interpolation Algorithms for Max. SAR Evaluation	$\pm 1.0$	Rectangular	$\sqrt{3}$	1	$\pm 0.6$	$\infty$
<b>Test sample Related</b>						
Test sample Positioning	$\pm 2.9$	Normal	1	1	$\pm 2.9$	145
Device Holder Uncertainty	$\pm 3.6$	Normal	1	1	$\pm 3.6$	5
Output Power Variation-SAR drift measurement	$\pm 5.0$	Rectangular	$\sqrt{3}$	1	$\pm 2.9$	$\infty$
<b>Phantom and Setup</b>						
Phantom uncertainty(Including shape and thickness tolerances)	$\pm 4.0$	Rectangular	$\sqrt{3}$	1	$\pm 2.3$	$\infty$
Liquid Conductivity Target tolerance	$\pm 5.0$	Rectangular	$\sqrt{3}$	0.64	$\pm 1.8$	$\infty$
Liquid Conductivity measurement uncertainty	$\pm 2.5$	Normal	1	0.64	$\pm 1.6$	$\infty$
Liquid Permittivity Target tolerance	$\pm 5.0$	Rectangular	$\sqrt{3}$	0.6	$\pm 1.7$	$\infty$
Liquid Permittivity measurement uncertainty	$\pm 2.5$	Normal	1	0.6	$\pm 1.5$	$\infty$
Combined standard uncertainty					$\pm 10.3$	330
<b>Coverage Factor for 95 %</b>		<b><math>K=2</math></b>				
<b>Expanded uncertainty (Coverage factor = 2)</b>			<b>Normal (k=2) 27</b>		<b><math>\pm 20.6</math></b>	

Table 7.2. Uncertainty Budget of DASYS



## 8. SAR Measurement Evaluation

Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

### 8.1. Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

### 8.2. System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave which comes from a signal generator at frequency 2450 MHz. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

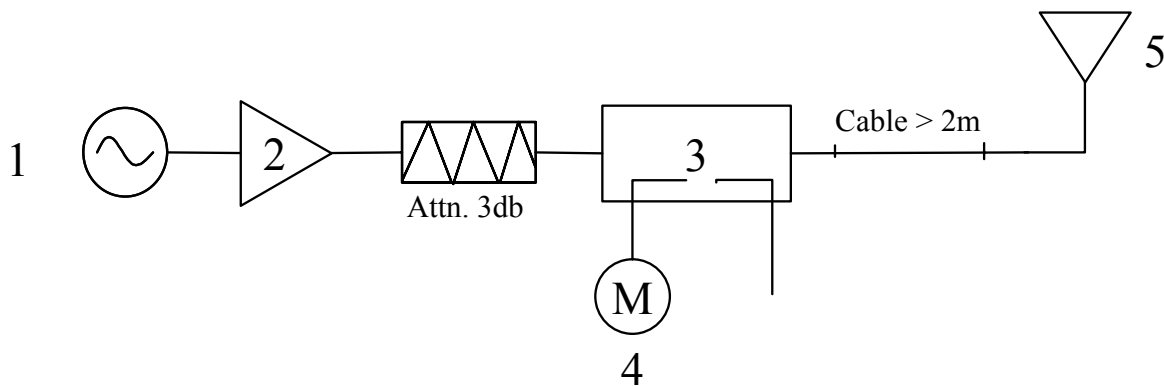


Fig. 8.1



1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. 2450 MHz Dipole

The output power on dipole port must be calibrated to 100 mW (20 dBm) before dipole is connected.

**8.3. Validation Results**

Comparing to the original SAR value provided by Speag, the validation data should within its specification of 10 %. Table 8.1 shows the target SAR and measured SAR after normalized to 1W input power.

		Target (W/kg)	Measurement data (W/kg)	Variation	Measurement date
ISM band (2450 MHz)	SAR (1g)	56	56.6	1.1 %	Feb. 22, 2005
	SAR (10g)	25.8	25.9	0.4 %	

**Table 8.1**

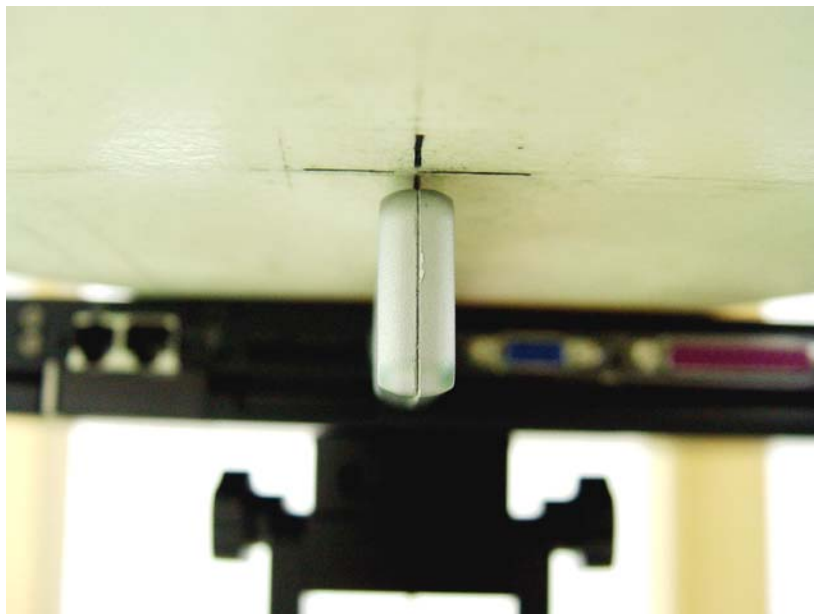
The table above indicates the system performance check can meet the variation criterion.

### **9. Description for DUT Testing Position**

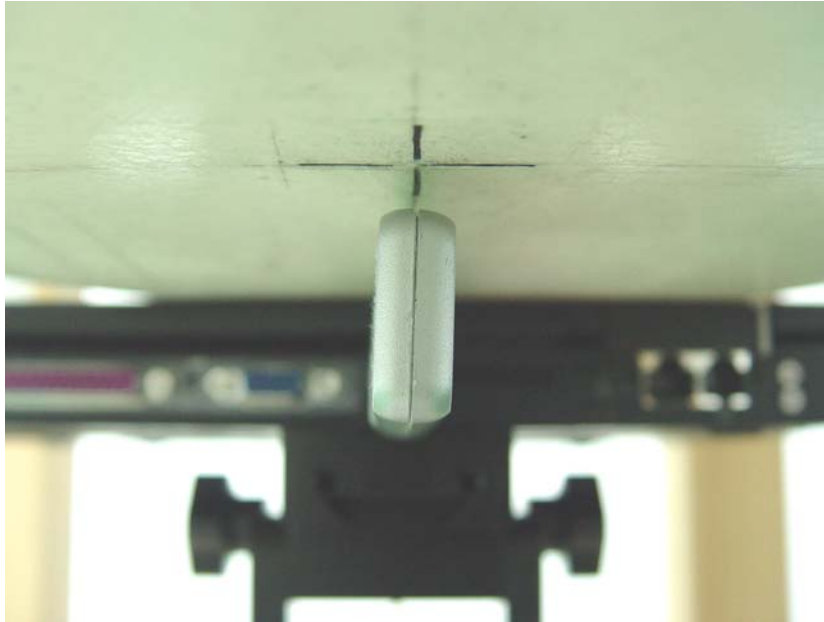
This DUT was tested in 3 different positions. The first one is “Notebook Bottom Touch” shown in Fig. 9.1, the second one is “Turn Right” shown in Fig. 9.2, and the third one is “Turn Left” shown in Fig.9.3.



**Fig. 9.1 Notebook Bottom Touch**



**Fig. 9.2 Turn Right**



**Fig. 9.3 Turn Left**



## **10. Measurement Procedures**

The measurement procedures are as follows:

- Plugging DUT into the notebook
- Using engineering software to transmit RF power continuously (continuous Tx) in the low channel
- Placing the DUT in the positions described in the last section
- Setting scan area, grid size and other setting on the DASY4 software
- Taking data for the low channel
- Repeat the previous steps for the middle and high channels.

According to the IEEE P1528 draft standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- Power reference measurement
- Area scan
- Zoom scan
- Power reference measurement

### **10.1. Spatial Peak SAR Evaluation**

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1528-2003 standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY4 software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

Base on the Draft: SCC-34, SC-2, WG-2-Computational Dosimetry, P1528/D1.2 (Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques), a new algorithm has been implemented. The spatial-peak SAR can be computed over any required mass.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.



The entire evaluation of the spatial peak values is performed within the postprocessing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- extraction of the measured data (grid and values) from the Zoom Scan
- calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- generation of a high-resolution mesh within the measured volume
- interpolation of all measured values from the measurement grid to the high-resolution grid
- extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- calculation of the averaged SAR within masses of 1g and 10g

### 10.2. Scan Procedures

First **Area Scan** is used to locate the approximate location(s) of the local peak SAR value(s). The measurement grid within an **Area Scan** is defined by the grid extent, grid step size and grid offset. Next, in order to determine the EM field distribution in a three-dimensional spatial extension, **Zoom Scan** is required. The **Zoom Scan** measures 7x7x7 points with step size 5, 5 and 5 mm. The **Zoom Scan** is performed around the highest E-field value to determine the averaged SAR-distribution over 1 g.

### 10.3. SAR Averaged Methods

In DASY4, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.



**11. SAR Test Results**

**11.1. Notebook Bottom Touch**

Mode	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
802.11b	1	2412(Low)	CCK	21.4	-	-	-	-
	6	2437(Mid)	CCK	21.4	-0.1	0.525	1.6	Pass
	11	2462(High)	CCK	21.4	-	-	-	-
802.11g	1	2412(Low)	OFDM	21.2	-	-	-	-
	6	2437(Mid)	OFDM	21.9	0.006	0.28	1.6	Pass
	11	2462(High)	OFDM	21.6	-	-	-	-

**11.2. Turn Right**

Mode	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
802.11b	1	2412(Low)	CCK	21.4	-	-	-	-
	6	2437(Mid)	CCK	21.4	0.2	0.68	1.6	Pass
	11	2462(High)	CCK	21.4	-	-	-	-
802.11g	1	2412(Low)	OFDM	21.2	-	-	-	-
	6	2437(Mid)	OFDM	21.9	0.1	0.377	1.6	Pass
	11	2462(High)	OFDM	21.6	-	-	-	-

**11.3. Turn Left**

Mode	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
802.11b	1	2412(Low)	CCK	21.4	0.1	1.08	1.6	Pass
	6	2437(Mid)	CCK	21.4	-0.1	1.28	1.6	Pass
	11	2462(High)	CCK	21.4	0	1.15	1.6	Pass
802.11g	1	2412(Low)	OFDM	21.2	0	0.618	1.6	Pass
	6	2437(Mid)	OFDM	21.9	-0.1	0.617	1.6	Pass
	11	2462(High)	OFDM	21.6	0	0.558	1.6	Pass



## **12. References**

- [1] FCC 47 CFR Part 2 “Frequency Allocations and Radio Treaty Matters; General Rules and Regulations”
- [2] IEEE Std. P1528-2003, “Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques”, April 21,2003.
- [3] Supplement C (Edition 01-01) to OET Bulletin 65 (Edition 97-01), “Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to RF Emissions”, June 2001
- [4] IEEE Std. C95.3-2002, “IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields-RF and Microwave”, 2002
- [5] IEEE Std. C95.1-1999, “IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz”, 1999
- [6] Robert J. Renka, “Multivariate Interpolation Of Large Sets Of Scattered Data”, University of North Texas ACM Transactions on Mathematical Software, vol. 14, no. 2, June 1988, pp. 139-148
- [7] DAYS4 System Handbook





### Appendix A - System Performance Check Data

Test Laboratory: Sporton International Inc. SAR Testing Lab

Date/Time: 02/22/05 15:59:22

#### System Check\_Body\_2450MHz\_20050222

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:736

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: MSL\_2450 Medium parameters used: f = 2450 MHz;  $\sigma = 2.02$  mho/m;  $\epsilon_r = 51.6$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 21.8 °C; Liquid Temperature : 22.1 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.26, 4.26, 4.26); Calibrated: 9/30/2004
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection) Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/17/2004
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

Pin=100mW/Area Scan (91x91x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 6.64 mW/g

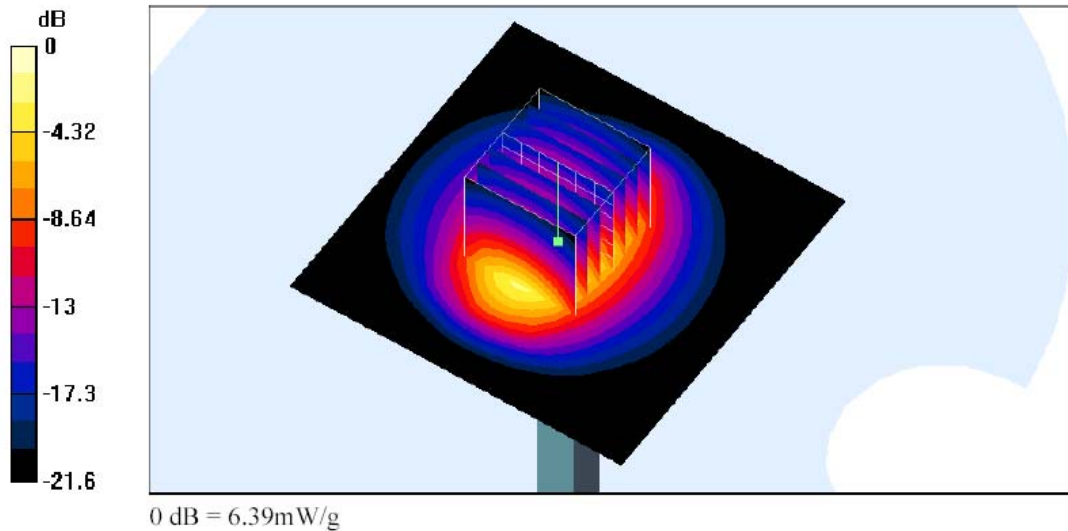
Pin=100mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 58.1 V/m; Power Drift = -0.0 dB

Peak SAR (extrapolated) = 12.8 W/kg

SAR(1 g) = 5.66 mW/g; SAR(10 g) = 2.59 mW/g

Maximum value of SAR (measured) = 6.39 mW/g





### Appendix B - SAR Measurement Data

Test Laboratory: Sporton International Inc. SAR Testing Lab

Date/Time: 02/22/05 10:59:23

#### Body\_802.11b Ch6\_NB BTM Touch \_20050222

**DUT: USR5421; Type: U.S. Robotics Wireless Maxg USB Adapter**

Communication System: 802.11b ; Frequency: 2437 MHz;Duty Cycle: 1:1

Medium: MSL\_2450 Medium parameters used:  $f = 2437$  MHz;  $\sigma = 2$  mho/m;  $\epsilon_r = 51.6$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 20.8 °C ; Liquid Temperature : 21.3 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.26, 4.26, 4.26); Calibrated: 9/30/2004
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/17/2004
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

**Ch6/Area Scan (41x81x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.539 mW/g

**Ch6/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 9.64 V/m; Power Drift = -0.1 dB

Peak SAR (extrapolated) = 1.05 W/kg

**SAR(1 g) = 0.525 mW/g; SAR(10 g) = 0.273 mW/g**

Maximum value of SAR (measured) = 0.572 mW/g

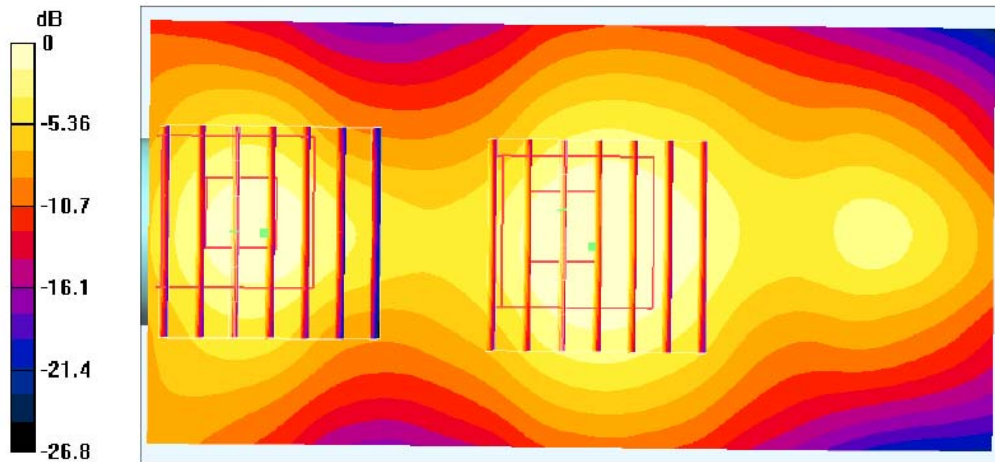
**Ch6/Zoom Scan (7x7x7)/Cube 1:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 9.64 V/m; Power Drift = -0.1 dB

Peak SAR (extrapolated) = 0.814 W/kg

**SAR(1 g) = 0.376 mW/g; SAR(10 g) = 0.178 mW/g**

Maximum value of SAR (measured) = 0.407 mW/g



0 dB = 0.407mW/g



Test Laboratory: Sporton International Inc. SAR Testing Lab

Date/Time: 02/22/05 20:26:33

Body\_802.11g Ch6\_NB BTM Touch\_20050222

DUT: USR5421; Type: U.S. Robotics Wireless Maxg USB Adapter

Communication System: 802.11g; Frequency: 2437 MHz; Duty Cycle: 1:1

Medium: MSL\_2450 Medium parameters used: f = 2437 MHz; sigma = 2 mho/m; epsilon\_r = 51.6; rho = 1000 kg/m^3

Ambient Temperature : 21.9 °C; Liquid Temperature : 22.2 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.26, 4.26, 4.26); Calibrated: 9/30/2004
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/17/2004
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

Ch6/Area Scan (41x81x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.332 mW/g

Ch6/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 8.22 V/m; Power Drift = 0.006 dB

Peak SAR (extrapolated) = 0.578 W/kg

SAR(1 g) = 0.280 mW/g; SAR(10 g) = 0.144 mW/g

Maximum value of SAR (measured) = 0.295 mW/g

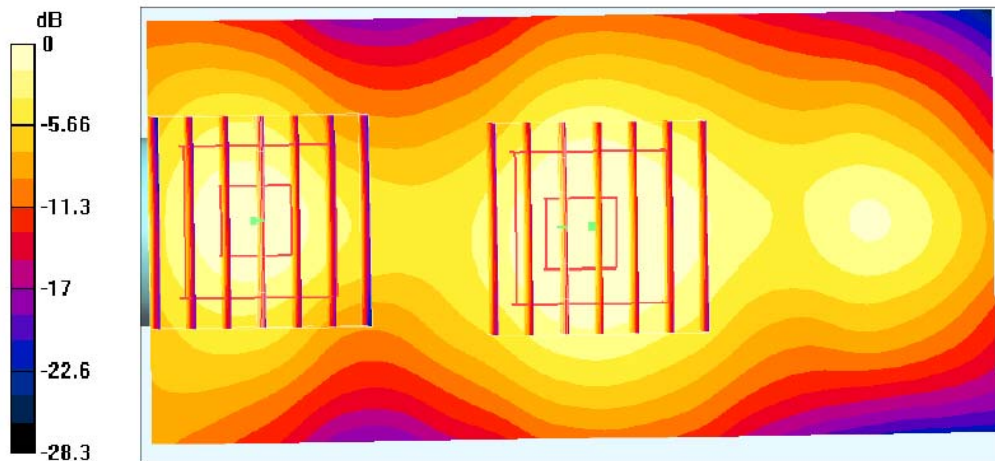
Ch6/Zoom Scan (7x7x7)/Cube 1: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 8.22 V/m; Power Drift = 0.006 dB

Peak SAR (extrapolated) = 0.452 W/kg

SAR(1 g) = 0.212 mW/g; SAR(10 g) = 0.100 mW/g

Maximum value of SAR (measured) = 0.239 mW/g





Test Laboratory: Sporton International Inc. SAR Testing Lab

Date/Time: 02/22/05 16:20:26

**Body\_802.11b Ch6\_NB BTM Touch\_20050222\_Turn Right**

**DUT: USR5421; Type: U.S. Robotics Wireless Maxg USB Adapter**

Communication System: 802.11b ; Frequency: 2437 MHz;Duty Cycle: 1:1

Medium: MSL\_2450 Medium parameters used:  $f = 2437$  MHz;  $\sigma = 2$  mho/m;  $\epsilon_r = 51.6$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 21.1 °C ; Liquid Temperature : 21.4 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.26, 4.26, 4.26); Calibrated: 9/30/2004
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/17/2004
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

**Ch6/Area Scan (31x81x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.864 mW/g

**Ch6/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 12.3 V/m; Power Drift = 0.2 dB

Peak SAR (extrapolated) = 1.57 W/kg

**SAR(1 g) = 0.680 mW/g; SAR(10 g) = 0.311 mW/g**

Maximum value of SAR (measured) = 0.756 mW/g

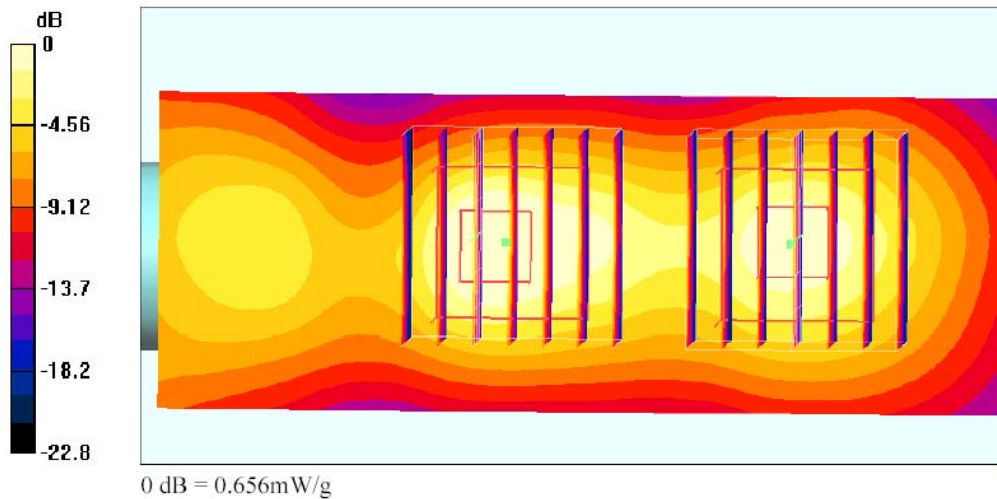
**Ch6/Zoom Scan (7x7x7)/Cube 1:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 12.3 V/m; Power Drift = 0.2 dB

Peak SAR (extrapolated) = 1.43 W/kg

**SAR(1 g) = 0.578 mW/g; SAR(10 g) = 0.253 mW/g**

Maximum value of SAR (measured) = 0.656 mW/g







Test Laboratory: Sporton International Inc. SAR Testing Lab

Date/Time: 02/22/05 20:59:01

**Body\_802.11g Ch6\_NB BTM Touch \_20050222\_Turn Right**

**DUT: USR5421; Type: U.S. Robotics Wireless Maxg USB Adapter**

Communication System: 802.11g; Frequency: 2437 MHz; Duty Cycle: 1:1

Medium: MSL\_2450 Medium parameters used:  $f = 2437$  MHz;  $\sigma = 2$  mho/m;  $\epsilon_r = 51.6$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 21.6 °C; Liquid Temperature : 21.9 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.26, 4.26, 4.26); Calibrated: 9/30/2004
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/17/2004
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

**Ch6/Area Scan (31x81x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.465 mW/g

**Ch6/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 8.68 V/m; Power Drift = 0.1 dB

Peak SAR (extrapolated) = 0.870 W/kg

**SAR(1 g) = 0.377 mW/g; SAR(10 g) = 0.171 mW/g**

Maximum value of SAR (measured) = 0.414 mW/g

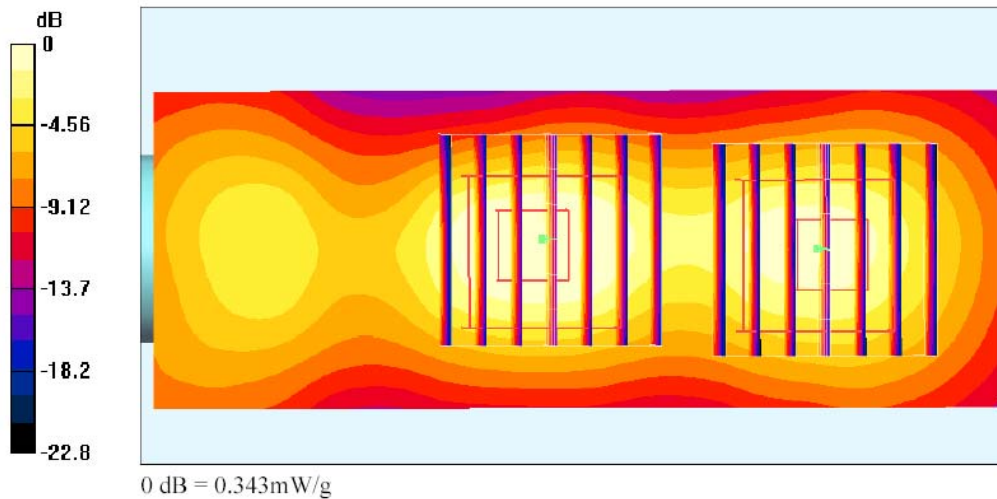
**Ch6/Zoom Scan (7x7x7)/Cube 1:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 8.68 V/m; Power Drift = 0.1 dB

Peak SAR (extrapolated) = 0.723 W/kg

**SAR(1 g) = 0.286 mW/g; SAR(10 g) = 0.127 mW/g**

Maximum value of SAR (measured) = 0.343 mW/g





Test Laboratory: Sporton International Inc. SAR Testing Lab

Date/Time: 02/22/05 18:19:02

**Body\_802.11b Ch6\_NB BTM Touch\_20050222\_Turn Left**

**DUT: USR5421; Type: U.S. Robotics Wireless Maxg USB Adapter**

Communication System: 802.11b ; Frequency: 2437 MHz;Duty Cycle: 1:1

Medium: MSL\_2450 Medium parameters used:  $f = 2437$  MHz;  $\sigma = 2$  mho/m;  $\epsilon_r = 51.6$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 21.2 °C ; Liquid Temperature : 21.5 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.26, 4.26, 4.26); Calibrated: 9/30/2004
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/17/2004
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

**Ch6/Area Scan (31x81x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 1.57 mW/g

**Ch6/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 11.2 V/m; Power Drift = -0.1 dB

Peak SAR (extrapolated) = 3.63 W/kg

**SAR(1 g) = 1.28 mW/g; SAR(10 g) = 0.518 mW/g**

Maximum value of SAR (measured) = 1.45 mW/g

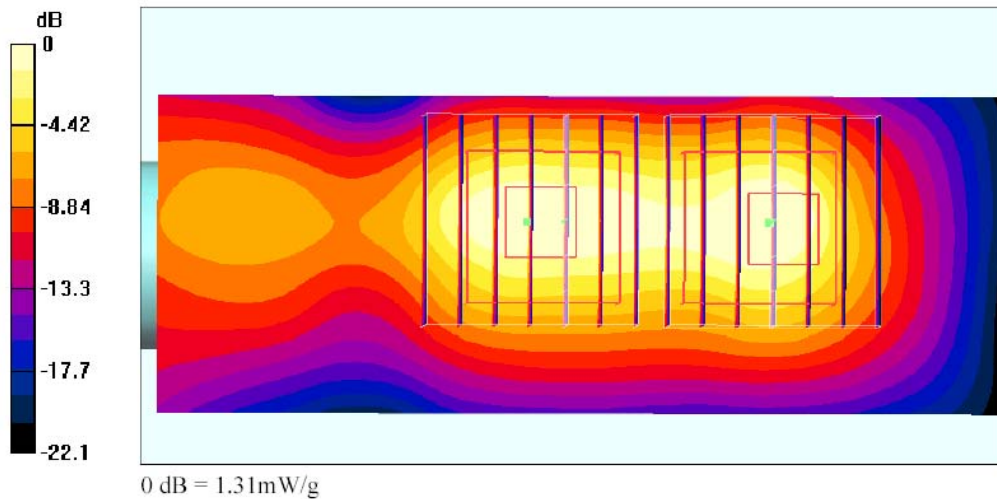
**Ch6/Zoom Scan (7x7x7)/Cube 1:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 11.2 V/m; Power Drift = -0.1 dB

Peak SAR (extrapolated) = 2.85 W/kg

**SAR(1 g) = 1.15 mW/g; SAR(10 g) = 0.517 mW/g**

Maximum value of SAR (measured) = 1.31 mW/g





Test Laboratory: Sporton International Inc. SAR Testing Lab

Date/Time: 02/22/05 21:57:51

**Body\_802.11g Ch1\_NB BTM Touch \_20050222\_Turn Left**

**DUT: USR5421; Type: U.S. Robotics Wireless Maxg USB Adapter**

Communication System: 802.11g; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium: MSL\_2450 Medium parameters used:  $f = 2412$  MHz;  $\sigma = 1.94$  mho/m;  $\epsilon_r = 51.4$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 22.1 °C; Liquid Temperature : 22.4 °C

DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.26, 4.26, 4.26); Calibrated: 9/30/2004
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/17/2004
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

**Ch1/Area Scan (31x81x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.715 mW/g

**Ch1/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 7.61 V/m; Power Drift = -0.0 dB

Peak SAR (extrapolated) = 1.47 W/kg

**SAR(1 g) = 0.618 mW/g; SAR(10 g) = 0.281 mW/g**

Maximum value of SAR (measured) = 0.705 mW/g

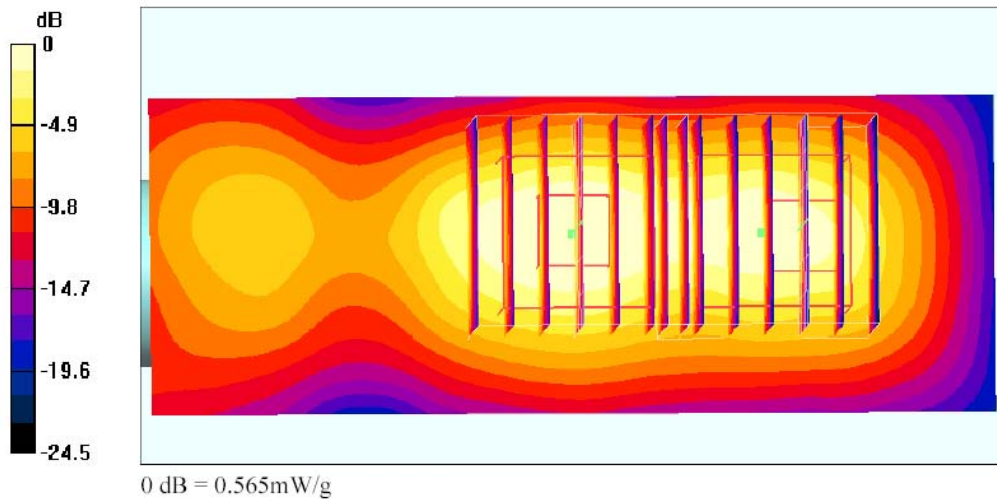
**Ch1/Zoom Scan (7x7x7)/Cube 1:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 7.61 V/m; Power Drift = -0.0 dB

Peak SAR (extrapolated) = 1.34 W/kg

**SAR(1 g) = 0.502 mW/g; SAR(10 g) = 0.215 mW/g**

Maximum value of SAR (measured) = 0.565 mW/g





Test Laboratory: Sporton International Inc. SAR Testing Lab

Date/Time: 02/22/05 18:19:02

Body\_802.11b Ch6\_NB BTM Touch\_20050222\_Turn Left

DUT: USR5421; Type: U.S. Robotics Wireless Maxg USB Adapter

Communication System: 802.11b ; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium: MSL\_2450 Medium parameters used: f = 2437 MHz; sigma = 2 mho/m; epsilon = 51.6; rho = 1000 kg/m^3
Ambient Temperature : 21.2 C; Liquid Temperature : 21.5 C

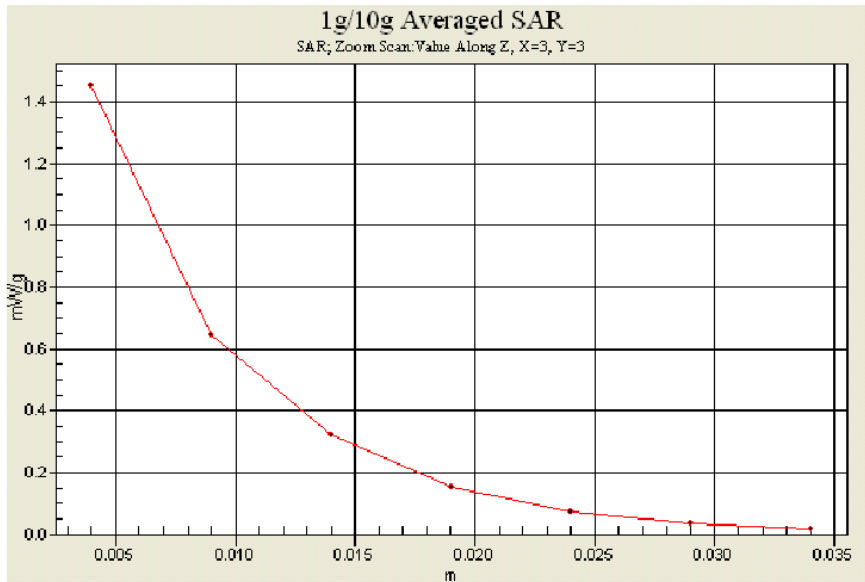
DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.26, 4.26, 4.26); Calibrated: 9/30/2004
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/17/2004
- Phantom: SAM I2; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

Ch6/Area Scan (31x81x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 1.57 mW/g

Ch6/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 11.2 V/m; Power Drift = -0.1 dB
Peak SAR (extrapolated) = 3.63 W/kg
SAR(1 g) = 1.28 mW/g; SAR(10 g) = 0.518 mW/g
Maximum value of SAR (measured) = 1.45 mW/g

Ch6/Zoom Scan (7x7x7)/Cube 1: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 11.2 V/m; Power Drift = -0.1 dB
Peak SAR (extrapolated) = 2.85 W/kg
SAR(1 g) = 1.15 mW/g; SAR(10 g) = 0.517 mW/g
Maximum value of SAR (measured) = 1.31 mW/g







Test Laboratory: Sporton International Inc. SAR Testing Lab

Date/Time: 02/22/05 21:57:51

Body\_802.11g Ch1\_NB BTM Touch\_20050222\_Turn Left

DUT: USR5421; Type: U.S. Robotics Wireless Maxg USB Adapter

Communication System: 802.11g; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium: MSL\_2450 Medium parameters used: f = 2412 MHz; sigma = 1.94 mho/m; epsilon\_r = 51.4; rho = 1000 kg/m^3

Ambient Temperature : 22.1 C; Liquid Temperature : 22.4 C

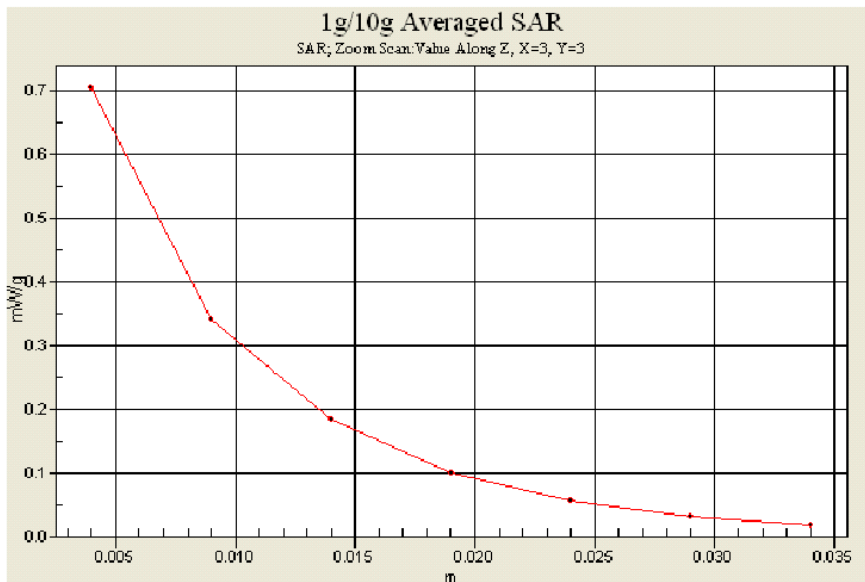
DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.26, 4.26, 4.26); Calibrated: 9/30/2004
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/17/2004
- Phantom: SAM I2; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

Ch1/Area Scan (31x81x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 0.715 mW/g

Ch1/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 7.61 V/m; Power Drift = -0.0 dB
Peak SAR (extrapolated) = 1.47 W/kg
SAR(1 g) = 0.618 mW/g; SAR(10 g) = 0.281 mW/g
Maximum value of SAR (measured) = 0.705 mW/g

Ch1/Zoom Scan (7x7x7)/Cube 1: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 7.61 V/m; Power Drift = -0.0 dB
Peak SAR (extrapolated) = 1.34 W/kg
SAR(1 g) = 0.502 mW/g; SAR(10 g) = 0.215 mW/g
Maximum value of SAR (measured) = 0.565 mW/g





Appendix C – Calibration Data

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

Client Auden > Sporton Int. Inc.

CALIBRATION CERTIFICATE
Object(s) D2450V2 - SN:736
Calibration procedure(s) QA CAL-05.v2
Calibration date: August 27, 2003
Condition of the calibrated item In-Tolerance (according to the specific calibration document)
This calibration statement documents traceability of M&TE used in the calibration procedures and conformity of the procedures with the ISO/IEC 17025 international standard.
All calibrations have been conducted in the closed laboratory facility: environment temperature 22 +/- 2 degrees Celsius and humidity < 75%.
Calibration Equipment used (M&TE critical for calibration)
Table with columns: Model Type, ID #, Cal Date (Calibrated by, Certificate No.), Scheduled Calibration
Calibrated by: Judith Mueller, Technician
Approved by: Katja Pokovic, Laboratory Director
Date issued: August 28, 2003
This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.



Schmid & Partner Engineering AG

**s p e a g**

Zeughausstrasse 43, 8004 Zurich, Switzerland  
Phone +41 1 245 9700, Fax +41 1 245 9779  
info@speag.com, <http://www.speag.com>

# DASY

## Dipole Validation Kit

Type: D2450V2

Serial: 736

Manufactured: August 26, 2003

Calibrated: August 27, 2003



**1. Measurement Conditions**

The measurements were performed in the flat section of the SAM twin phantom filled with head simulating solution of the following electrical parameters at 2450 MHz:

Relative Dielectricity	<b>38.2</b>	$\pm 5\%$
Conductivity	<b>1.89 mho/m</b>	$\pm 5\%$

The DASY4 System with a dosimetric E-field probe ES3DV2 (SN:3013, Conversion factor 4.8 at 2450 MHz) was used for the measurements.

The dipole was mounted on the small tripod so that the dipole feedpoint was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10mm from dipole center to the solution surface. Lossless spacer was used during measurements for accurate distance positioning.

The coarse grid with a grid spacing of 15mm was aligned with the dipole. The 7x7x7 fine cube was chosen for cube integration.

The dipole input power (forward power) was 250mW  $\pm 3\%$ . The results are normalized to 1W input power.

**2. SAR Measurement with DASY4 System**

Standard SAR-measurements were performed according to the measurement conditions described in section I. The results (see figure supplied) have been normalized to a dipole input power of 1W (forward power). The resulting averaged SAR-values measured with the dosimetric probe ES3DV2 SN:3013 and applying the advanced extrapolation are:

averaged over 1 cm <sup>3</sup> (1 g) of tissue:	<b>55.6 mW/g <math>\pm 16.8\%</math> (k=2)<sup>1</sup></b>
averaged over 10 cm <sup>3</sup> (10 g) of tissue:	<b>25.0 mW/g <math>\pm 16.2\%</math> (k=2)<sup>1</sup></b>

<sup>1</sup> validation uncertainty



### 3. Dipole Impedance and Return Loss

The impedance was measured at the SMA-connector with a network analyzer and numerically transformed to the dipole feedpoint. The transformation parameters from the SMA-connector to the dipole feedpoint are:

Electrical delay: **1.158 ns** (one direction)  
Transmission factor: **0.983** (voltage transmission, one direction)

The dipole was positioned at the flat phantom sections according to section 1 and the distance spacer was in place during impedance measurements.

Feedpoint impedance at 2450 MHz:  $\text{Re}\{Z\} = 52.5 \Omega$   
 $\text{Im}\{Z\} = 3.6 \Omega$   
Return Loss at 2450 MHz **-27.5 dB**

### 4. Measurement Conditions

The measurements were performed in the flat section of the SAM twin phantom filled with **body simulating solution** of the following electrical parameters at 2450 MHz:

Relative Dielectricity **50.8**  $\pm 5\%$   
Conductivity **2.03 mho/m**  $\pm 5\%$

The DASY4 System with a dosimetric E-field probe ES3DV2 (SN:3013, Conversion factor 4.2 at 2450 MHz) was used for the measurements.

The dipole was mounted on the small tripod so that the dipole feedpoint was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10mm from dipole center to the solution surface. Lossless spacer was used during measurements for accurate distance positioning.

The coarse grid with a grid spacing of 15mm was aligned with the dipole. The 7x7x7 fine cube was chosen for cube integration.

The dipole input power (forward power) was 250mW  $\pm 3\%$ . The results are normalized to 1W input power.





**5. SAR Measurement with DASY4 System**

Standard SAR-measurements were performed according to the measurement conditions described in section 4. The results (see figure supplied) have been normalized to a dipole input power of 1W (forward power). The resulting averaged SAR-values measured with the dosimetric probe ES3DV2 SN:3013 and applying the advanced extrapolation are:

averaged over 1 cm <sup>3</sup> (1 g) of tissue:	<b>56.0 mW/g ± 16.8 % (k=2)<sup>2</sup></b>
averaged over 10 cm <sup>3</sup> (10 g) of tissue:	<b>25.8 mW/g ± 16.2 % (k=2)<sup>2</sup></b>

**6. Dipole Impedance and Return Loss**

The dipole was positioned at the flat phantom sections according to section 4 and the distance spacer was in place during impedance measurements.

Feedpoint impedance at 2450 MHz:	Re{Z} = <b>48.7 Ω</b>
	Im {Z} = <b>4.8 Ω</b>
Return Loss at 2450 MHz	<b>-25.8 dB</b>

**7. Handling**

Do not apply excessive force to the dipole arms, because they might bend. Bending of the dipole arms stresses the soldered connections near the feedpoint leading to a damage of the dipole.

**8. Design**

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

Small end caps have been added to the dipole arms in order to improve matching when loaded according to the position as explained in Sections 1 and 4. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

**9. Power Test**

After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

<sup>2</sup> validation uncertainty



Test Laboratory: SPEAG, Zurich, Switzerland  
File Name: SN736\_SN3013\_M2450\_270803.da4

**DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN736**  
**Program: Dipole Calibration**

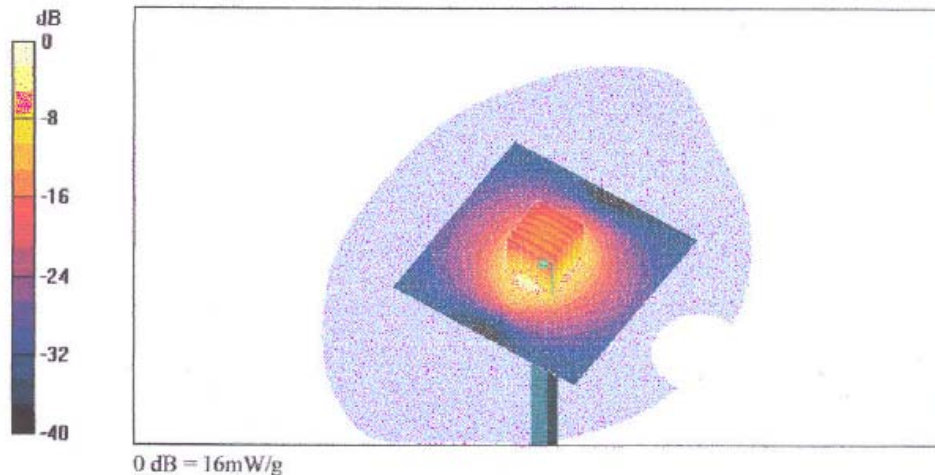
Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1  
Medium: Muscle 2450 MHz ( $\sigma = 2.03 \text{ mho/m}$ ,  $\epsilon_r = 50.75$ ,  $\rho = 1000 \text{ kg/m}^3$ )  
Phantom section: Flat Section  
Measurement Standard: DASy4 (High Precision Assessment)

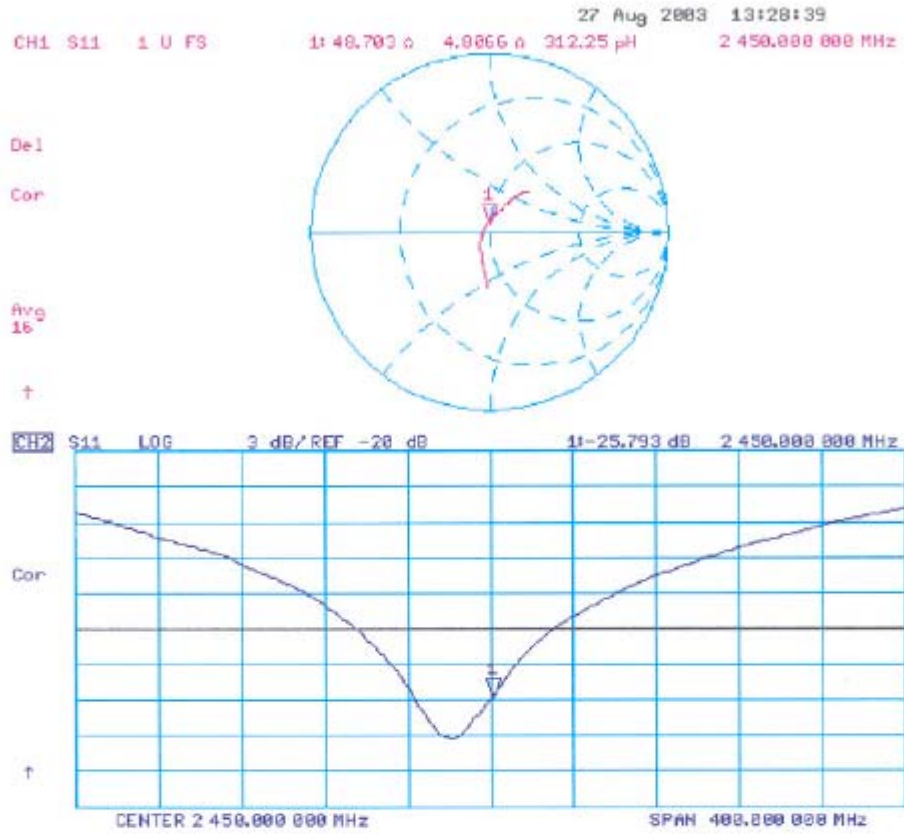
DASy4 Configuration:

- Probe: ES3DV2 - SN3013; ConvF(4.2, 4.2, 4.2); Calibrated: 1/19/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 - SN411; Calibrated: 1/16/2003
- Phantom: SAM with CRP - TP1006; Type: SAM 4.0; Serial: TP:1006
- Measurement SW: DASy4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**Pin = 250 mW; d = 10 mm/Area Scan (81x81x1):** Measurement grid: dx=15mm, dy=15mm  
Reference Value = 91 V/m  
Power Drift = -0.02 dB  
Maximum value of SAR = 15.7 mW/g

**Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm  
Peak SAR (extrapolated) = 27.8 W/kg  
SAR(1 g) = 14 mW/g; SAR(10 g) = 6.46 mW/g  
Reference Value = 91 V/m  
Power Drift = -0.02 dB  
Maximum value of SAR = 16 mW/g









Test Laboratory: SPEAG, Zurich, Switzerland  
File Name: SN736\_SN3013\_HSL2450\_270803\_da4

**DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN736**  
**Program: Dipole Calibration**

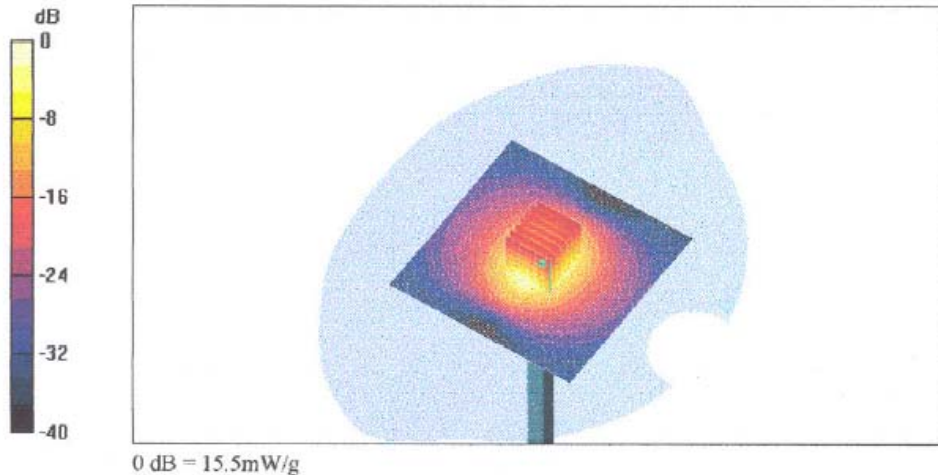
Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1  
Medium: HSL 2450 MHz ( $\sigma = 1.89$  mho/m,  $\epsilon_r = 38.19$ ,  $\rho = 1000$  kg/m<sup>3</sup>)  
Phantom section: Flat Section  
Measurement Standard: DASy4 (High Precision Assessment)

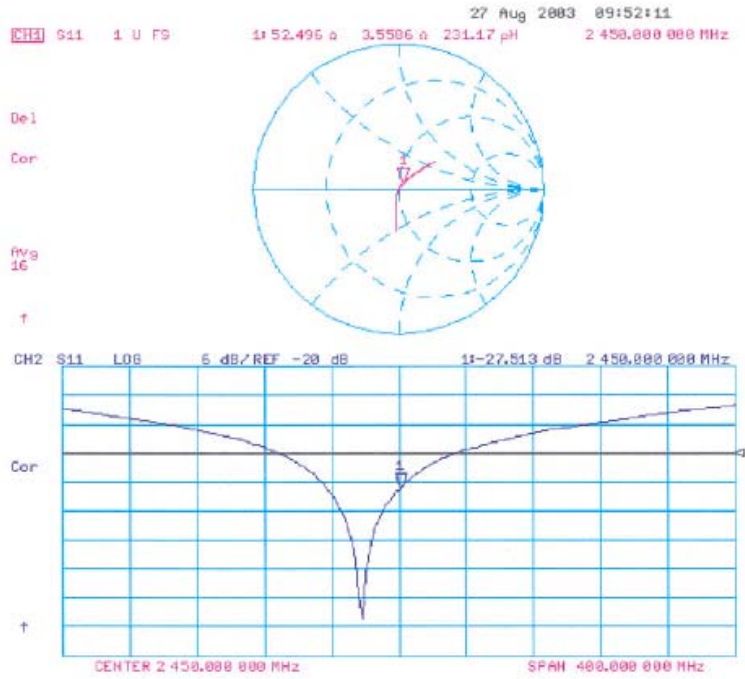
DASy4 Configuration:

- Probe: ES3DV2 - SN3013; ConvF(4.8, 4.8, 4.8); Calibrated: 1/19/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 - SN411; Calibrated: 1/16/2003
- Phantom: SAM with CRP - TP1006; Type: SAM 4.0; Serial: TP:1006
- Measurement SW: DASy4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**Pin = 250 mW; d = 10 mm/Area Scan (81x81x1):** Measurement grid: dx=15mm, dy=15mm  
Reference Value = 91.5 V/m  
Power Drift = -0.04 dB  
Maximum value of SAR = 15.3 mW/g

**Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm  
Peak SAR (extrapolated) = 30.2 W/kg  
SAR(1 g) = 13.9 mW/g; SAR(10 g) = 6.25 mW/g  
Reference Value = 91.5 V/m  
Power Drift = -0.04 dB  
Maximum value of SAR = 15.5 mW/g







Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland



S Schweizerischer Kalibrierdienst
C Service suisse d'etalonnage
S Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Federal Office of Metrology and Accreditation
The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client Sporton (Auden)

Certificate No: ET3-1788\_Sep04

CALIBRATION CERTIFICATE

Object ET3DV6 - SN:1788
Calibration procedure(s) QA CAL-01.v5
Calibration procedure for dosimetric E-field probes
Calibration date: September 30, 2004
Condition of the calibrated item In Tolerance

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Table with 4 columns: Primary Standards, ID #, Cal Date (Calibrated by, Certificate No.), Scheduled Calibration. Lists equipment like Power meter E4419B, Reference 3 dB Attenuator, etc.

Table with 4 columns: Secondary Standards, ID #, Check Date (in house), Scheduled Check. Lists equipment like Power sensor HP 8481A, RF generator HP 8648C, etc.

Calibrated by: Nico Vetterli, Laboratory Technician
Approved by: Katja Pokovic, Technical Manager

Issued: October 1, 2004

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.