SAR TEST REPORT

REPORT NO.: SA931125H02
MODEL NO.: USR5411
RECEIVED: Nov. 25, 2004
TESTED: Nov. 30, 2004

APPLICANT: UNIVERSAL SCIENTIFIC INDUSTRIAL CO., LTD.

ADDRESS: 141, Lane 351, Taiping Road, Sec. 1, Tsao Tuen, Nan-Tou, Taiwan, R.O.C.

ISSUED BY: Advance Data Technology Corporation

LAB ADDRESS: No. 47, 14th Ling, Chia Pau Tsuen, Lin Kou Hsiang 244, Taipei Hsien, Taiwan, R.O.C.

TEST LOCATION: No. 19, Hwa Ya 2nd Rd., Wen Hwa Tsuen, Kwei Shan Hsiang, Taoyuan Hsien 333, Taiwan, R.O.C.

No. 2177-01

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1. CERTIFICATION

PRODUCT :	U.S. Robotics Wireless Maxg PC Card
MODEL NO. :	USR5411
BRAND :	USR
APPLICANT :	UNIVERSAL SCIENTIFIC INDUSTRIAL CO., LTD.
TESTED :	Nov. 30, 2004
TEST SAMPLE :	R&D SAMPLE
STANDARDS :	FCC Part 2 (Section 2.1093), FCC OET Bulletin 65, Supplement C (01-01), RSS-102

The above equipment has been tested by **Advance Data Technology Corporation**, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample's EMC characteristics under the conditions specified in this report.

PREPARED BY : Candice Chen, **DATE:** Dec. 01, 2004
(Candice Chen)

TECHNICAL ACCEPTANCE Responsible for RF : Ansen Lei, **DATE:** Dec. 01, 2004
(Ansen Lei)

APPROVED BY : Cody Chang for, **DATE:** Dec. 01, 2004
(Cody Chang, Deputy Manager)

2. GENERAL INFORMATION

2.1 GENERAL DESCRIPTION OF EUT

PRODUCT	U.S. Robotics Wireless Maxg PC Card
MODEL NO.	USR5411
POWER SUPPLY	3.3Vdc from host equipment
CLASSIFICATION	Portable device, production unit
MODULATION TYPE	CCK, DQPSK, DBPSK for DSSS 64QAM, 16QAM, QPSK, BPSK for OFDM
RADIO TECHNOLOGY	DSSS / OFDM
TRANSFER RATE	1/2/5.5/6/9/11/12/18/24/36/48/54Mbps
FREQUENCY RANGE	2412MHz ~ 2462MHz
NUMBER OF CHANNEL	11
CONDUCTED OUTPUT POWER (FOR CCK)	72.444mW
CONDUCTED OUTPUT POWER (FOR OFDM)	65.313mW
ANTENNA TYPE	Printed antenna with 0.97dBi gain
AVERAGE SAR(1g) (FOR CCK)	0.131W/kg
AVERAGE SAR(1g) (FOR OFDM)	0.075W/kg
DATA CABLE	NA
I/O PORTS	NA
ASSOCIATED DEVICES	NA

NOTE

1. Normal operating condition of the EUT shall be plugged into the laptop PC. Then the property of the EUT shall be complied with the portable device according to the FCC 2.1093.
2. The above EUT information was declared by manufacturer and for more detailed features description, please refer to the manufacturer's specifications or User's Manual.

2.2 GENERAL DESCRIPTION OF APPLIED STANDARDS

According to the specifications of the manufacturer, this product must comply with the requirements of the following standards:

FCC 47 CFR Part 2 (2.1093)
FCC OET Bulletin 65, Supplement C (01- 01)
RSS-102
IEEE 1528-2003

All test items have been performed and recorded as per the above standards.

2.3 GENERAL INOFRMATION OF THE SAR SYSTEM

DASY4 (software 4.4 Build 3) consists of high precision robot, probe alignment sensor, phantom, robot controller, controlled measurement server and near-field probe. The robot includes six axes that can move to the precision position of the DASY4 software defined. The DASY4 software can define the area that is detected by the probe. The robot is connected to controlled box. Controlled measurement server is connected to the controlled robot box. The DAE includes amplifier, signal multiplexing, AD converter, offset measurement and surface detection. It is connected to the Electro-optical coupler (ECO). The ECO performs the conversion form the optical into digital electric signal of the DAE and transfers data to the PC.

ET3DV6 ISOTROPIC E-FIELD PROBE

Construction	Symmetrical design with triangular core. Built-in optical fiber for surface detection system. Built-in shielding against static charges. PEEK enclosure material (resistant to organic solvents, e.g., glycolether).
Calibration	Basic Broad Band Calibration in air: 10-2500 MHz Conversion Factors (CF) for HSL 900, HSL 1800, HSL2450, MSL 900, MSL 1800 and MSL2450. CF-Calibration for other liquids and frequencies upon request
Frequency	10 MHz to 3 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)
Directivity	± 0.2 dB in HSL (rotation around probe axis) ± 0.4 db in HSL (rotation normal to probe axis)
Dynamic Range	5 µW/g to > 100 mW/g; Linearity: ± 0.2 dB
Optical Surface Detection	± 0.2 mm repeatability in air and clear liquids over diffuse reflecting surfaces

Dimensions
Overall length: 330 mm (Tip Length: 16 mm)
Tip diameter: 6.8 mm (Body diameter: 12 mm)
Distance from probe tip to dipole centers: 2.7 mm

Application
General dosimetric measurements up to 3 GHz
Compliance tests of mobile phones
Fast automatic scanning in arbitrary phantoms (ET3DV6)

Sensitivity
X axis :1.74 μV ; Y axis : 1.69 μV ; Z axis : 1.76 μV

Diode compression point
X axis : 96 mV ; Y axis : 96 mV ; Z axis : 96mV

Conversion Factor

Frequency range (MHz)	X axis	Y axis	Z axis
800~950 (Head)	6.34	6.34	6.34
800~950 (Body)	6.06	6.06	6.06
1700~1910 (Head)	5.16	5.16	5.16
1700~1910 (Body)	4.54	4.54	4.54
2400~2500 (Head)	4.41	4.41	4.41
2400~2500 (Body)	4.23	4.23	4.23

Boundary effect

Frequency range (MHz)	Alpha	Depth
800~950 (Head)	0.48	2.13
800~950 (Body)	0.40	2.57
1700~1910 (Head)	0.49	2.70
1700~1910 (Body)	0.54	2.76
2400~2500 (Head)	1.00	1.89
2400~2500 (Body)	1.21	1.59

NOTE

1. The Probe parameters have been calibrated by the SPEAG. Please reference "APPENDIX D" for the Calibration Certification Report.
2. For frequencies above 800 MHz, calibration in a rectangular wave-guide is used, because wave-guide size is manageable.
3. For frequencies below 800 MHz, temperature transfer calibration is used because the wave-guide size becomes relatively large.

TWIN SAM V4.0

Construction	The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-2003, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.
Shell Thickness	2 ± 0.2 mm
Filling Volume	Approx. 25 liters
Dimensions	Height: 810 mm; Length: 1000 mm; Width: 500 mm

SYSTEM VALIDATION KITS: D900V2 – D2450V2

Construction	Symmetrical dipole with l/4 balun enables measurement of feedpoint impedance with NWA matched for use near flat phantoms filled with brain simulating solutions. Includes distance holder and tripod adaptor
Calibration	Calibrated SAR value for specified position and input power at the flat phantom in brain simulating solutions
Frequency	900, 1800, 1900, 2450 MHz
Return Loss	> 20 dB at specified validation position
Power Capability	> 100 W (f < 1GHz); > 40 W (f > 1GHz)
Options	Dipoles for other frequencies or solutions and other calibration conditions upon request
Dimensions	D900V2: dipole length: 149 mm; overall height: 83.3mm D1800V2: dipole length: 72 mm; overall height: 41.2 mm D1900V2: dipole length: 68 mm; overall height: 39.5 mm D2450V2: dipole length: 51.5 mm; overall height: 30.6 mm

Construction

The device holder for the mobile phone device is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles. The holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity ε =3 and loss tangent δ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered. The device holder for the portable device makes up of the polyethylene foam. The dielectric parameters of material close to the dielectric parameters of the air. The holder of the portable device could support the EUT in the specific testing position.

DATA ACQUISITION ELECTRONICS

Construction

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplex, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe is mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 box is 200Mohm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.

2.4 GENERAL DESCRIPTION OF THE SPATIAL PEAK SAR EVALUATION

The DASY4 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the micro-volt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	$Norm_i$, a_{i0}, a_{i1}, a_{i2}
	- Conversion factor	$ConvF_i$
	- Diode compression point	dcp_i
Device parameters:	- Frequency	F
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \bullet \frac{cf}{dcp_i}$$

V_i	=compensated signal of channel i	(i = x, y, z)
U_i	=input signal of channel I	(i = x, y, z)
cf	=crest factor of exciting field	(DASY parameter)
dcp_i	=diode compression point	(DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-fieldprobes :

$$E_i = \sqrt{\frac{V_1}{Norm_i \cdot ConvF}}$$

H-fieldprobes :

$$H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1} f + a_{i2} f^2}{f}$$

V_i	=compensated signal of channel I	(i = x, y, z)
$Norm_i$	=sensor sensitivity of channel i μV/(V/m)2 for E-field Probes	(i = x, y, z)
ConvF	= sensitivity enhancement in solution	
a_{ij}	= sensor sensitivity factors for H-field probes	
F	= carrier frequency [GHz]	
E_i	= electric field strength of channel i in V/m	
H_i	= magnetic field strength of channel i in A/m	

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{o}{p \cdot 1'000}$$

SAR = local specific absorption rate in mW/g
E_{tot} = total field strength in V/m
o = conductivity in [mho/m] or [Siemens/m]
p = equivalent tissue density in g/cm3

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid. The entire evaluation of the spatial peak values is performed within the Post-processing engine (SEMCAD). The system always gives the maximum values for the 1 g and 10 g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

1. The extraction of the measured data (grid and values) from the Zoom Scan
2. The calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
3. The generation of a high-resolution mesh within the measured volume
4. The interpolation of all measured values from the measurement grid to the high-resolution grid
5. The extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
6. The calculation of the averaged SAR within masses of 1g and 10g.

The probe is calibrated at the center of the dipole sensors that is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated. The angle between the probe axis and the surface normal line is less than 30 degree.

In the Area Scan, the gradient of the interpolation function is evaluated to find all the extreme of the SAR distribution. The uncertainty on the locations of the extreme is less than 1/20 of the grid size. Only local maximum within –2 dB of the global maximum are searched and passed for the Cube Scan measurement. In the Cube Scan, the interpolation function is used to extrapolate the Peak SAR from the lowest measurement points to the inner phantom surface (the extrapolation distance). The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5mm.

The maximum search is automatically performed after each area scan measurement. It is based on splines in two or three dimensions. The procedure can find the maximum for most SAR distributions even with relatively large grid spacing. After the area scanning measurement, the probe is automatically moved to a position at the interpolated maximum. The following scan can directly use this position for reference, e.g., for a finer resolution grid or the cube evaluations. The 1g and 10g peak evaluations are only available for the predefined cube 7x7x7 scans. The routines are verified and optimized for the grid dimensions used in these cube measurements. The measured volume of 30x30x30mm contains about 30g of tissue. The first procedure is an extrapolation (incl. Boundary correction) to get the points between the lowest measured plane and the surface. The next step uses 3D interpolation to get all points within the measured volume in a 1mm grid (42875 points). In the last step, a 1g cube is placed numerically into the volume and its averaged SAR is calculated. This cube is the moved around until the highest averaged SAR is found. If the highest SAR is found at the edge of the measured volume, the system will issue a warning: higher SAR values might be found outside of the measured volume. In that case the cube measurement can be repeated, using the new interpolated maximum as the center.

3. DESCRIPTION OF TEST MODES AND CONFIGURATIONS

CARRIER MODULATION UNDER TEST	CCK, OFDM
CREST FACTOR	1.0
CHANNEL FREQUENCIES UNDER TEST AND ITS CONDUCTED OUTPUT POWER	71.285mW / Ch1: 2412MHz For CCK 72.444mW / Ch6: 2437MHz For CCK 69.984mW / Ch11: 2462MHz For CCK 63.096mW / Ch1: 2412MHz For OFDM 65.313mW / Ch6: 2437MHz For OFDM 63.973mW / Ch11: 2462MHz For OFDM
ANTENNA CONFIGURATION	Printed antenna with 0.97dBi gain
ANTENNA POSTITON	Inside the front cover, near the top
EUT POWER SOURCE	From Host Notebook
HOST POWER SOURCE	Fully Charged Battery

The following test configurations have been applied in this test report:

Mode 1: The EUT is plugged in the PCMCIA slot of the notebook, the bottom of the notebook contacted the bottom of the flat phantom with 0mm separation distance. Therefore the bottom of the EUT face to the phantom and the separation distance is 16mm. The area scan size is 7 x 9 points.(CCK modulation)

Mode 2: The EUT is plugged in the PCMCIA slot of the notebook, the bottom of the notebook contacted the bottom of the flat phantom with 0mm separation distance. Therefore the bottom of the EUT face to the phantom and the separation distance is 16mm. The area scan size is 7 x 9 points.(OFDM modulation)

NOTE: 1. Please reference “APPENDIX A” for the photos of test configuration.
2. All test modes have been complied with the body worn configuration.
3. The notebook has been installed the controlling software (provided by manufacturer) that could control the EUT transmitted channel and power. But that software is just for test software, not for normal user.
4.Pre-scan has been conducted, 11Mbps with CCK technique and 6Mbps with OFDM technique, the worse case were chose for final test.

4. DESCRIPTION OF SUPPORT UNITS

The EUT has been tested as an independent unit together with other necessary accessories or support units. The following support units or accessories were used to form a representative test configuration during the tests.

NO.	PRODUCT	BRAND	MODEL NO.	SERIAL NO.	FCC ID
1	NOTEBOOK COMPUTER	DELL	PP05L	9954115984	E2K24CLNS

NO.	SIGNAL CABLE DESCRIPTION OF THE ABOVE SUPPORT UNITS
1	NA

5. TEST RESULTS

5.1 TEST PROCEDURES

The EUT (U.S. Robotics Wireless Maxg PC Card) plugged into the notebook. Use the software to control the EUT channel and transmission power. Then record the conducted power before the testing. Place the EUT to the specific test location. After the testing, must writing down the conducted power of the EUT into the report. The SAR value was calculated via the 3D spline interpolation algorithm that has been implemented in the software of DASY4 SAR measurement system manufactured and calibrated by SPEAG. According to the IEEE P1528 draft standards, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- Power reference measurement
- Area scan
- Zoom scan
- Power reference measurement

The area scan with 15mm x 15mm grid was performed for the highest spatial SAR location. Consist of 7 x 9 points while the scan size is the 90mm x 120mm. The zoom scan with 30mm x 30mm x 30mm volume was performed for SAR value averaged over 1g and 10g spatial volumes.

In the zoon scan, the distance between the measurement point at the probe sensor location (geometric center behind the probe tip) and the phantom surface is 4.0 mm and maintained at a constant distance of ±1.0 mm during a zoon scan to determine peak SAR locations. The distance is 4mm between the first measurement point and the bottom surface of the phantom. The secondary measurement point to the bottom surface of the phantom is with 9mm separation distance. The cube size is 7 x 7 x 7points consist of 343 points and the grid space is 5mm.

The measurement time is 0.5 s at each point of the zoon scan. The probe boundary effect compensation shall be applied during the SAR test. Because of the tip of the probe to the Phantom surface separated distances are longer than half a tip probe diameter.

In the area scan, the separation distance is 4mm between the each measurement point and the phantom surface. The scan size shall be included the transmission portion of the EUT. The measurement time is the same as the zoon scan. At last the reference power drift shall be less than ±5%.

5.2 MEASURED SAR RESULT

EUT	U.S. Robotics Wireless Maxg PC Card	MODEL	USR5411
ENVIRONMENTAL CONDITION	Air Temperature：22.0°C, Liquid Temperature：21.0°C Humidity：54%RH		
TESTED BY	Johan Kuo		

Chan.	Freq. (MHz)	Modulate type	Conducted Power (dBm)		Power Drift (%)	Device Use Power	Device Test Position Mode	Antenna Position	Measured 1g SAR (W/kg)
			Begin Test	After Test					
1	2412 (Low)	CCK	18.53	18.68	3.51	Standard Battery from host	1	Internal Fixed	**0.131**
6	2437 (Mid.)	CCK	18.60	18.40	-4.50	Standard Battery from host	1	Internal Fixed	0.118
11	2462 (High)	CCK	18.45	18.28	-3.84	Standard Battery from host	1	Internal Fixed	0.103

NOTE:
1. Test configuration of each mode is described in section 3.
2. In this testing, the limit for General Population Spatial Peak averaged over 1g, **1.6 W/kg**, is applied.
3. Please see the Appendix A for the photo of the test configuration and also the data.
4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%

EUT	U.S. Robotics Wireless Maxg PC Card			**MODEL**		USR5411		
ENVIRONMENTAL CONDITION	Air Temperature：22.0°C, Liquid Temperature：21.0°C Humidity：54%RH							
TESTED BY	Johan Kuo							

Chan.	**Freq. (MHz)**	**Modulate type**	**Conducted Power (dBm)**		**Power Drift (%)**	**Device Use Power**	**Device Test Position Mode**	**Antenna Position**	**Measured 1g SAR (W/kg)**
			Begin Test	**After Test**					
1	**2412 (Low)**	**OFDM**	18.00	18.15	3.51	Standard Battery from host	2	Internal Fixed	**0.075**
6	**2437 (Mid.)**	**OFDM**	18.15	18.00	-3.39	Standard Battery from host	2	Internal Fixed	0.061
11	**2462 (High)**	**OFDM**	18.06	18.24	4.23	Standard Battery from host	2	Internal Fixed	0.064

NOTE:

1. Test configuration of each mode is described in section 3.
2. In this testing, the limit for General Population Spatial Peak averaged over 1g, **1.6 W/kg**, is applied.
3. Please see the Appendix A for the photo of the test configuration and also the data.
4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%

5.3 SAR LIMITS

HUMAN EXPOSURE	SAR (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / controlled Exposure Environment)
Spatial Average (whole body)	0.08	0.4
Spatial Peak (averaged over 1 g)	**1.6**	8.0
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

NOTE

1. This limits accord to ANSI/IEEE C95.1 1992 – Safety Limit.
2. The EUT property been complied with the partial body exposure limit under the general population environment.

5.4 RECIPES FOR TISSUE SIMULATING LIQUIDS

For the measurement of the field distribution inside the SAM phantom, the phantom must be filled with 25 litters of tissue simulation liquid.

The following ingredients are used：

- Water- Deionized water (pure H20), resistivity _16 M - as basis for the liquid
- Sugar- Refined sugar in crystals, as available in food shops - to reduce relative permittivity
- Salt- Pure NaCl - to increase conductivity
- Cellulose- Hydroxyethyl-cellulose, medium viscosity (75-125 mPa.s, 2% in water, 20_C),CAS # 54290 - to increase viscosity and to keep sugar in solution
- Preservative- Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS # 55965-84-9 - to prevent the spread of bacteria and molds
- DGMBE- Diethylenglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH, CAS # 112-34-5 - to reduce relative permittivity

The Recipes For 2450MHz Simulating Liquid Table

Ingredient	Head Simulating Liquid 2450MHz(HSL-2450)	Muscle Simulating Liquid 2450MHz(MSL-2450)
Water	45%	69.83%
DGMBE	55%	30.17%
Salt	NA	NA
Dielectric Parameters at 22℃	f=2450MHz e=39.2±5% s= 1.80±5% S/m	f=2450MHz e=52.7±5% s= 1.95±5% S/m

The liquid tested by Agilent Network Analyzer E8358A and Agilent Dielectric Probe Kit 85070D.Here are the procedure.

1. Turn Network Analyzer on and allow at least 30 min. warm up.
2. Mount dielectric probe kit so that interconnecting cable to Network Analyzer will not be moved during measurements or calibration.
3. Pour de-ionized water and measure water temperature (±1°).
4. Set water temperature in Agilent-Software (Calibration Setup).
5. Perform calibration.
6. Validate calibration with dielectric material of known properties (e.g. polished ceramic slab with >8mm thickness e'=10.0, e''=0.0). If measured parameters do not fit within tolerance, repeat calibration (±0.2 for e': ±0.1 for e'').
7. Conductivity can be calculated from e'' by s = ? e_0 e'' =e'' f [GHz] / 18.
8. Measure liquid shortly after calibration. Repeat calibration every hour.
9. Stir the liquid to be measured. Take a sample (~50ml) with a syringe from the center of the liquid container.
10. Pour the liquid into a small glass flask. Hold the syringe at the bottom of the flask to avoid air bubbles.
11. Put the dielectric probe in the glass flask. Check that there are no air bubbles in front of the opening in the dielectric probe kit.
12. Perform measurements.
13. Adjust medium parameters in DASY4 for the frequencies necessary for the measurements (‘ Setup Config’ , select medium (e.g. Brain 900 MHz) and press ‘ Option’ -button.
14. Select the current medium for the frequency of the validation (e.g. Setup Medium Brain 900 MHz).

For 802.11g Band Simulating Liquid

Liquid Type		HSL-2450		MSL-2450	
Simulating Liquid Temp.		NA		21°C	
Test Date		NA		2004 / 11 / 30	
Tested By		NA		Johan Kuo	
Freq. (MHz)	Liquid Parameter	Standard Value	Measurement Value	Standard Value	Measurement Value
2412	Permitivity (ε)	NA	NA	52.7507	51.1121
2437		NA	NA	52.7173	51.0521
2450		NA	NA	52.7000	51.0147
2462		NA	NA	52.6847	50.9657
2412	Conductivity (σ) S/m	NA	NA	1.9137	1.9822
2437		NA	NA	1.9376	2.0165
2450		NA	NA	1.9500	2.0336
2462		NA	NA	1.9670	2.0489
Dielectric Parameters Required at 22℃					

5.5 TEST EQUIPMENT FOR TISSUE PROPERTY

Item	Name	Band	Type	Series No.	Calibrated Until
1	Network Analyzer	Agilent	E8358A	US41480538	Mar. 24, 2005
2	Dielectric Probe	Agilent	85070D	US01440176	NA

NOTE

1. Before starting, all test equipment shall be warmed up for 30min.
2. The tolerance (k=1) specified by Agilent for general dielectric measurements, deriving from inaccuracies in the calibration data, analyzer drift, and random errors, are usually ±2.5% and ±5% for measured permittivity and conductivity, respectively. However, the tolerances for the conductivity is smaller for material with large loss tangents, i.e., less than ±2.5% (k=1) . It can be substantially smaller if more accurate methods are applied.

6. SYSTEM VALIDATION

The system validation was performed in the flat phantom with equipment listed in the following table. Since the SAR value is calculated from the measured electric field, dielectric constant and conductivity of the body tissue, and the SAR is proportional to the square of the electric field. So, the SAR value will be also proportional to the RF power input to the system validation dipole under the same test environment. In our system validation test, 100mW RF input power was used instead of 250mW used by Schmid & Partner, the measured SAR will be linearly extrapolated to that of 250mW RF power.

6.1 TEST EQUIPMENT

Item	Name	Band	Type	Series No.	Calibrated Until
1	SAM Phantom	S & P	QD000 P40 CA	PT-1150	NA
2	Signal Generator	R & S	SMP04	10001	May 05, 2005
3	E-Field Probe	S & P	ET3DV6	1687	Aug. 25, 2005
4	DAE	S & P	DAE3 V1	510	Aug. 16, 2005
5	Robot Positioner	Staubli Unimation	NA	NA	NA
6	Validation Dipole	S & P	D2450V2	716	Aug. 22, 2005

NOTE: Before starting the measurement, all test equipment shall be warmed up for 30min.

6.2 TEST PROCEDURE

Before the system performance check, we need only to tell the system which components (probe, medium, and device) are used for the system performance check; the system will take care of all parameters. The dipole must be placed beneath the flat section of the SAM Twin Phantom with the correct distance holder in place. The distance holder should touch the phantom surface with a light pressure at the reference marking (little cross) and be oriented parallel to the long side of the phantom. Accurate positioning is not necessary, since the system will search for the peak SAR location, except that the dipole arms should be parallel to the surface. The device holder for mobile phones can be left in place but should be rotated away from the dipole.

1.The "Power Reference Measurement" and "Power Drift Measurement" jobs are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the amplifier output power. If it is too high (above ±0.1 dB), the system performance check should be repeated; some amplifiers have very high drift during warm-up. A stable amplifier gives drift results in the DASY system below ±0.02 dB.

2.The "Surface Check" job tests the optical surface detection system of the DASY system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above ±0.1mm). In that case it is better to abort the system performance check and stir the liquid. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within ±30^{o}.) However, varying breaking indices of different liquid compositions might also influence the distance. If the indicated difference varies from the actual setting, the probe parameter "optical surface

3. The "Area Scan" job measures the SAR above the dipole on a plane parallel to the surface. It is used to locate the approximate location of the peak SAR. The proposed scan uses large grid spacing for faster measurement; due to the symmetric field, the peak detection is reliable. If a finer graphic is desired, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result.

4. The "Zoom Scan" job measures the field in a volume around the peak SAR value assessed in the previous "Area Scan" job (for more information see the application note on SAR evaluation).

About the validation dipole positioning uncertainty, the constant and low loss dielectric spacer is used to establish the correct distance between the top surface of the dipole and the bottom surface of the phantom, the error component introduced by the uncertainty of the distance between the liquid (i.e., phantom shell) and the validation dipole in the DASY4 system is less than ±0.1mm.

$$SAR_{tolerance}[\%] = 100 \times (\frac{(a+d)^2}{a^2} - 1)$$

As the closest distance is 10mm, the resulting tolerance $SAR_{tolerance}$[%] is <2%.

6.3 VALIDATION RESULT

ENVIRONMENTAL CONDITION	Temperature：22.0°C, Humidity：54%RH		
TESTED BY	Johan Kuo		
TEST DATE	2004/11/30		
2450MHz System Validation Test in the Muscle Simulating Liquid			
Required SAR (mW/g)	**Measured SAR (mW/g)**	**Deviation (%)**	**Separation Distance**
12.20 (1g)	12.70	4.10	10mm
5.64 (10g)	5.99	6.21	10mm

NOTE: Please see Appendix for the photo of system validation test.

6.4 SYSTEM VALIDATION UNCERTAINTIES

In the table below, the system validation uncertainty with respect to the analytically assessed SAR value of a dipole source as given in the P1528 standard is given. This uncertainty is smaller than the expected uncertainty for mobile phone measurements due to the simplified setup and the symmetric field distribution.

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(C_i)		Standard Uncertainty (±%)		(v_i)
				(1g)	(10g)	(1g)	(10g)	
Measurement System								
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	∞
Axial Isotropy	4.7	Rectangular	$\sqrt{3}$	1	1	2.7	2.7	∞
Hemispherical Isotropy	0	Rectangular	$\sqrt{3}$	1	1	0	0	∞
Boundary effect	1.0	Rectangular	$\sqrt{3}$	1	1	0.6	0.6	∞
Linearity	4.7	Rectangular	$\sqrt{3}$	1	1	2.7	2.7	∞
System Detection Limit	1.0	Rectangular	$\sqrt{3}$	1	1	0.6	0.6	∞
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	∞
Response Time	0	Rectangular	$\sqrt{3}$	1	1	0	0	∞
Integration Time	0	Rectangular	$\sqrt{3}$	1	1	0	0	∞
RF Ambient Conditions	3.0	Rectangular	$\sqrt{3}$	1	1	1.7	1.7	∞
Probe Positioner	0.4	Rectangular	$\sqrt{3}$	1	1	0.2	0.2	∞
Probe positioning	2.9	Rectangular	$\sqrt{3}$	1	1	1.7	1.7	∞
Algorithms for Max. SAR Evaluation	1.0	Rectangular	$\sqrt{3}$	1	1	0.6	0.6	∞
Dipole								
Dipole Axis to Liquid Distance	2.0	Rectangular	$\sqrt{3}$	1	1	1.2	1.2	∞
Input power and SAR drift measurement	4.7	Rectangular	$\sqrt{3}$	1	1	2.7	2.7	∞
Phantom and Tissue Parameters								
Phantom Uncertainty	4.0	Rectangular	$\sqrt{3}$	1	1	2.3	2.3	∞
Liquid Conductivity (target)	5.0	Rectangular	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	∞
Liquid Permittivity (target)	5.0	Rectangular	$\sqrt{3}$	0.6	0.49	1.7	1.4	∞
Liquid Permittivity (measurement)	2.5	Normal	1	0.6	0.49	1.5	1.2	∞
Combined Standard Uncertainty						8.4	8.1	∞
Coverage Factor for 95%						kp=2		
Expanded Uncertainty (K=2)						16.8	16.2	

NOTE: About the system validation uncertainty assessment, please reference the section 7.

7. MEASUREMENT SAR PROCEDURE UNCERTAINTIES

The assessment of spatial peak SAR of the hand handheld devices is according to IEEE 1528. All testing situation shall be met below these requirement.

- The system is used by an experienced engineer who follows the manual and the guidelines taught during the training provided by SPEAG.
- The probe has been calibrated within the requested period and the stated uncertainty for the relevant frequency bands does not exceed 4.8% (k=1).
- The validation dipole has been calibrated within the requested period and the system performance check has been successful.
- The DAE unit has been calibrated within the within the requested period.
- The minimum distance between the probe sensor and inner phantom shell is selected to be between 4 and 5mm.
- The operational mode of the DUT is CW, CDMA, FDMA or TDMA (GSM, DCS, PCS, IS136 and PDC) and the measurement/integration time per point is >500 ms.
- The dielectric parameters of the liquid have been assessed using Agilent 85070D dielectric probe kit or a more accurate method.
- The dielectric parameters are within 5% of the target values.
- The DUT has been positioned as described in section 3.

7.1 PROBE CALIBRATION UNCERTAINTY

SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN50361, IEC 62209, etc.) under ISO17025. The uncertainties are stated on the calibration certificate. For the most relevant frequency bands, these values do not exceed 4.8% (k=1). If evaluations of other bands are performed for which the uncertainty exceeds these values, the uncertainty tables given in the summary have to be revised accordingly.

7.2 ISOTROPY UNCERTAINTY

The axial isotropy tolerance accounts for probe rotation around its axis while the hemispherical isotropy error includes all probe orientations and field polarizations. These parameters are assessed by SPEAG during initial calibration. In 2001, SPEAG further tightened its quality controls and warrants that the maximal deviation from axial isotropy is ±0.20 dB, while the maximum deviation of hemispherical isotropy is ±0.40 dB, corresponding to ±4.7% and ±9.6%, respectively. A weighting factor of cp equal to 0.5 can be applied, since the axis of the probe deviates less than 30 degrees from the normal surface orientation.

7.3 BOUNDARY EFFECT UNCERTAINTY

The effect can be estimated according to the following error approximation formula

$$SAR_{tolerance}[\%] = SAR_{be}[\%] \times \frac{(d_{be} + d_{step})^2}{2d_{step}} \frac{e^{-\frac{d_{be}}{\delta/2}}}{\delta/2}$$

$$d_{be} + d_{step} < 10mm$$

The parameter d_{be} is the distance in mm between the surface and the closest measurement point used in the averaging process; d_{step} is the separation distance in mm between the first and second measurement points; d is the minimum penetration depth in mm within the head tissue equivalent liquids (i.e., d= 13.95 mm at 3GHz); SAR_{be} is the deviation between the measured SAR value at the distance d_{be} from the boundary and the wave-guide analytical value SAR_{ref}.DASY4 applies a boundary effect compensation algorithm according to IEEE 1528, which is possible since the axis of the probe never deviates more than 30 degrees from the normal surface orientation. SAR_{be}[%] is assessed during the calibration process and SPEAG warrants that the uncertainty at distances larger than 4mm is always less than 1%.In summary, the worst case boundary effect SAR tolerance[%] for scanning distances larger than 4mm is < ± 0.8%.

7.4 PROBE LINEARITY UNCERTAINTY

Field probe linearity uncertainty includes errors from the assessment and compensation of the diode compression effects for CW and pulsed signals with known duty cycles. This error is assessed using the procedure described in IEEE 1528. For SPEAG field probes, the measured difference between CW and pulsed signals, with pulse frequencies between 10 Hz and 1 kHz and duty cycles between 1 and 100, is < ±0.20 dB (< ±4.7%).

7.5 READOUT ELECTRONICS UNCERTAINTY

All uncertainties related to the probe readout electronics (DAE unit), including the gain and linearity of the instrumentation amplifier, its loading effect on the probe, and accuracy of the signal conversion algorithm, have been assessed accordingly to IEEE 1528.The combination (root-sum-square RSS method) of these components results in an overall maximum error of ±1.0%.

7.6 RESPONSE TIME UNCERTAINTY

The time response of the field probes is assessed by exposing the probe to a well-controlled electric field producing SAR larger than 2.0 W/kg at the tissue medium surface. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/of switch of the power source. Analytically, it can be expressed as:

$$SAR_{tolerance}[\%] = 100 \times \left(\frac{T_m}{T_m + \tau e^{-T_m/\tau} - \tau} - 1 \right)$$

where Tm is 500 ms, i.e., the time between measurement samples, and τ the time constant. The response time τ of SPEAG's probes is <5 ms. In the current implementation, DASY4 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.

7.7 INTEGRATION TIME UNCERTAINTY

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization and can be assessed as follows

$$SAR_{tolerance}[\%] = 100 \times \sum_{allsub-frames} \frac{t_{frame}}{t_{integration}} \frac{slot_{idle}}{slot_{total}}$$

The tolerances for the different systems are given in Table 7.1, whereby the worst-case $SAR_{tolerance}$ is 2.6%.

System	$SAR_{tolerance}$ %
CW	0
CDMA*	0
WCDMA*	0
FDMA	0
IS-136	2.6
PDC	2.6
GSM/DCS/PCS	1.7
DECT	1.9
Worst-Case	2.6

Table 7.1

7.8 PROBE POSITIONER MECHANICAL TOLERANCE

The mechanical tolerance of the field probe positioner can introduce probe positioning uncertainties. The resulting SAR uncertainty is assessed by comparing the SAR obtained according to the specifications of the probe positioner with respect to the actual position defined by the geometric enter of the probe sensors. The tolerance is determined as:

$$SAR_{tolerance}[\%] = 100 \times \frac{d_{ss}}{\delta/2}$$

The specified repeatability of the RX robot family used in DASY4 systems is ±25 µm. The absolute accuracy for short distance movements is better than ±0.1mm, i.e., the $SAR_{tolerance}$[%] is better than 1.5% (rectangular).

7.9 PROBE POSITIONING

The probe positioning procedures affect the tolerance of the separation distance between the probe tip and the phantom surface as:

$$SAR_{tolerance}[\%] = 100 \times \frac{d_{ph}}{\delta/2}$$

where d_{ph} is the maximum deviation of the distance between the probe tip and the phantom surface. The optical surface detection has a precision of better than 0.2 mm, resulting in an $SAR_{tolerance}[\%]$ of <2.9% (rectangular distribution). Since the mechanical detection provides better accuracy, 2.9% is a worst-case figure for DASY4 system.

7.10 PHANTOM UNCERTAINTY

The SAR measurement uncertainty due to SPEAG phantom shell production tolerances has been evaluated using

$$SAR_{tolerance}[\%] \cong 100 \times \frac{2d}{a}, \qquad d << a$$

For a maximum deviation d of the inner and outer shell of the phantom from that specified in the CAD file of ±0.2 mm, and a 10mm spacing a between source and tissue liquid, the calculated phantom uncertainty is ±4.0%.

7.11 DASY4 UNCERTAINTY BUDGET

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(C_i) (1g)	(C_i) (10g)	Standard Uncertainty (±%) (1g)	Standard Uncertainty (±%) (10g)	(v_i)
Measurement System								
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	∞
Axial Isotropy	4.7	Rectangular	$\sqrt{3}$	1	1	1.9	1.9	∞
Hemispherical Isotropy	9.6	Rectangular	$\sqrt{3}$	1	1	3.9	3.9	∞
Boundary effect	1.0	Rectangular	$\sqrt{3}$	1	1	0.6	0.6	∞
Linearity	4.7	Rectangular	$\sqrt{3}$	1	1	2.7	2.7	∞
System Detection Limit	1.0	Rectangular	$\sqrt{3}$	1	1	0.6	0.6	∞
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	∞
Response Time	0.8	Rectangular	$\sqrt{3}$	1	1	0.5	0.5	∞
Integration Time	2.6	Rectangular	$\sqrt{3}$	1	1	1.5	1.5	∞
RF Ambient Conditions	3.0	Rectangular	$\sqrt{3}$	1	1	1.7	1.7	∞
Probe Positioner	0.4	Rectangular	$\sqrt{3}$	1	1	0.2	0.2	∞
Probe positioning	2.9	Rectangular	$\sqrt{3}$	1	1	1.7	1.7	∞
Algorithms for Max. SAR Evaluation	1.0	Rectangular	$\sqrt{3}$	1	1	0.6	0.6	∞
Test EUT Related								
Device Positioning	2.9	Normal	1	1	1	2.9	2.9	875
Device Holder	3.6	Normal	1	1	1	3.6	3.6	5
Power Drift	5	Rectangular	$\sqrt{3}$	1	1	2.9	2.9	∞
Phantom and Tissue Parameters								
Phantom Uncertainty	4.0	Rectangular	$\sqrt{3}$	1	1	2.3	2.3	∞
Liquid Conductivity (target)	5.0	Rectangular	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	∞
Liquid Permittivity (target)	5.0	Rectangular	$\sqrt{3}$	0.6	0.49	1.7	1.4	∞
Liquid Permittivity (measurement)	2.5	Normal	1	0.6	0.49	1.5	1.2	∞
Combined Standard Uncertainty						**10.3**	**10**	331
Coverage Factor for 95%						**kp=2**		
Expanded Uncertainty (K=2)						20.6	20.1	

Table 7.2

The table 7.2: Worst-Case uncertainty budget for DASY4 assessed according to IEEE P1528. The budget is valid for the frequency range 300MHz ~ 3 GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.

8. INFORMATION ON THE TESTING LABORATORIES

We, ADT Corp., were founded in 1988 to provide our best service in EMC, Radio, Telecom and Safety consultation. Our laboratories are accredited and approved by the following approval agencies according to ISO/IEC 17025.

USA	FCC, NVLAP, UL, A2LA
Germany	TUV Rheinland
Japan	VCCI
Norway	NEMKO
Canada	INDUSTRY CANADA , CSA
R.O.C.	CNLA, BSMI, DGT
Netherlands	Telefication
Singapore	PSB , GOST-ASIA(MOU)
Russia	CERTIS(MOU)

Copies of accreditation certificates of our laboratories obtained from approval agencies can be downloaded from our web site: www.adt.com.tw/index.5/phtml. If you have any comments, please feel free to contact us at the following:

Linko EMC/RF Lab:
Tel: 886-2-26052180
Fax: 886-2-26052943

Hsin Chu EMC/RF Lab:
Tel: 886-3-5935343
Fax: 886-3-5935342

Hwa Ya EMC/RF/Safety/Telecom Lab:
Tel: 886-3-3183232
Fax: 886-3-3185050

Linko RF Lab.
Tel: 886-3-3270910
Fax: 886-3-3270892

Email: service@adt.com.tw
Web Site: www.adt.com.tw

The address and road map of all our labs can be found in our web site also.

Report Format Version 1.5

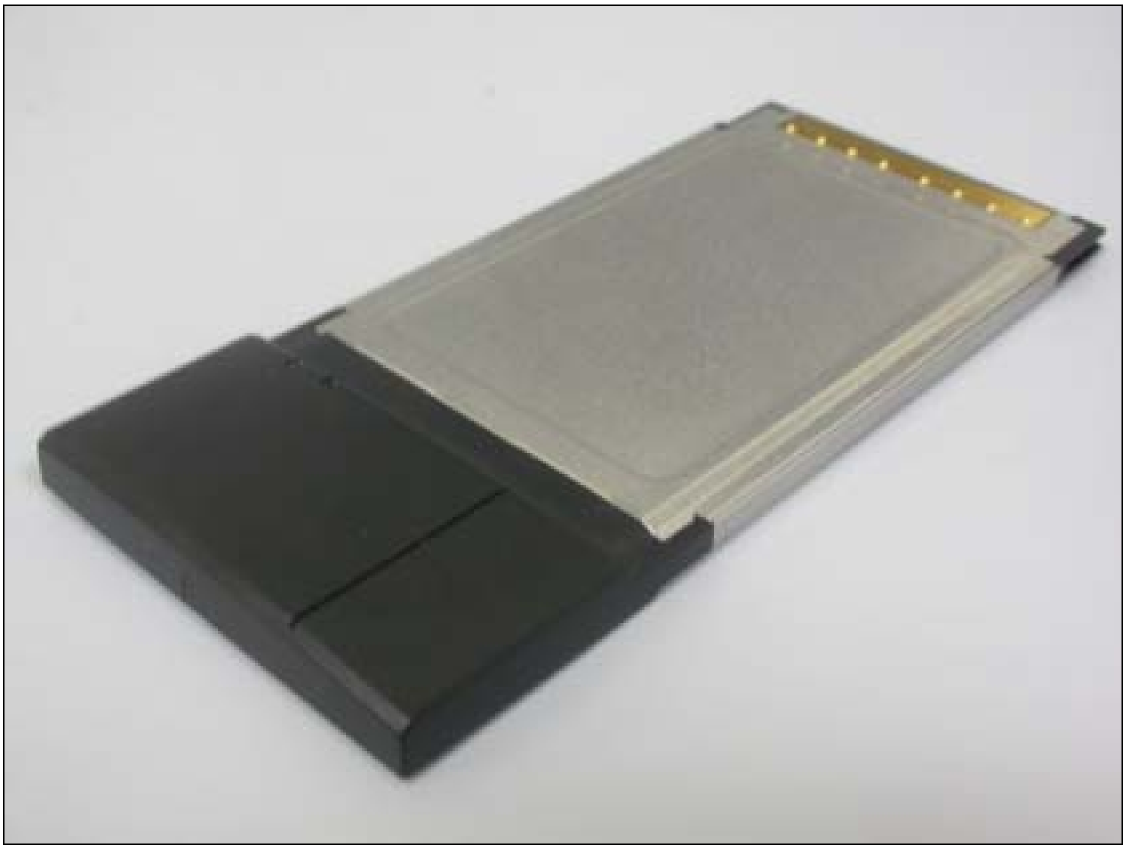
APPENDIX A: TEST CONFIGURATIONS AND TEST DATA

A1: TEST CONFIGURATION

Test Position: Bottom Position

The bottom of the EUT to the flat phantom distance 16 mm

EUT Photo



Liquid Level Photo

MSL 2450MHz D=155mm

Date/Time: 11/30/04 14:56:44

Test Laboratory: Advance Data Technology

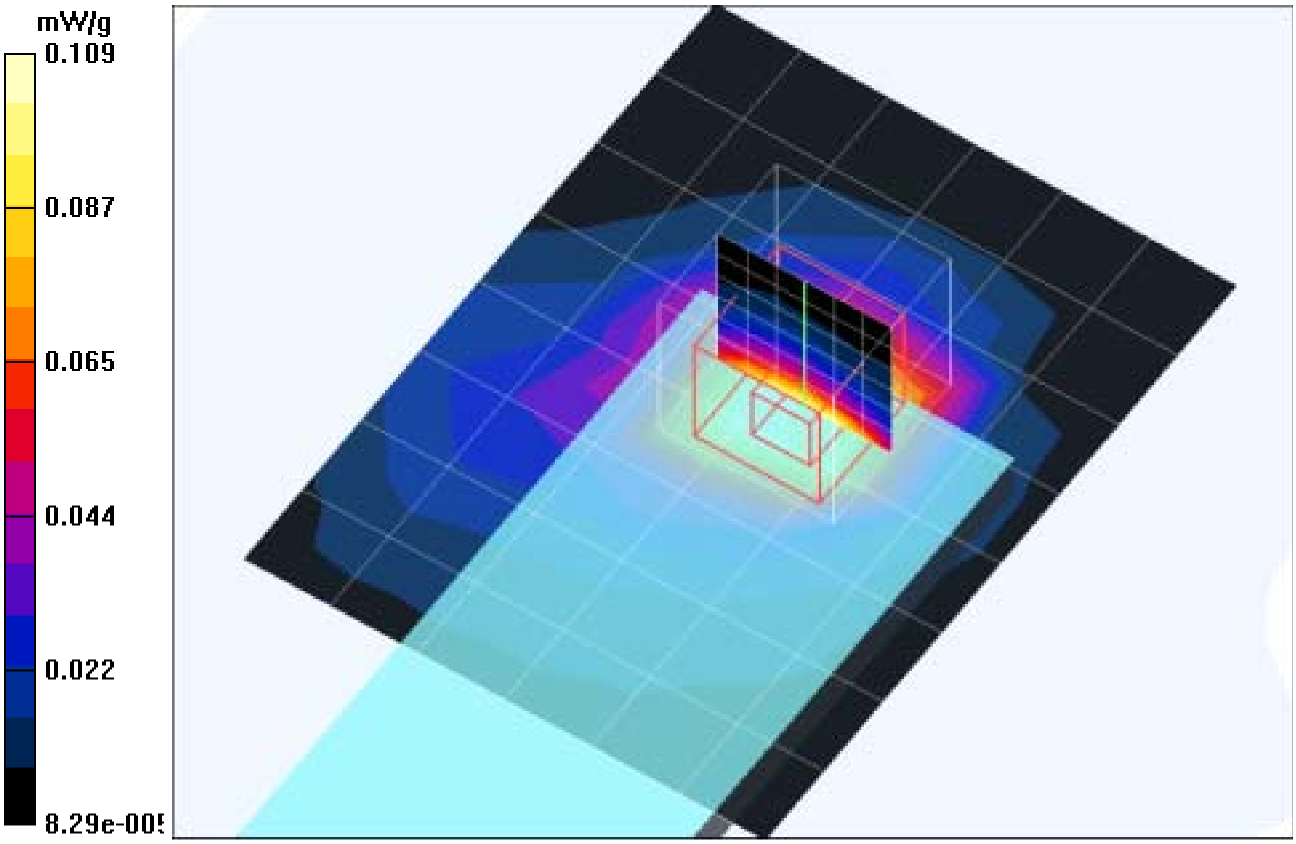
USR5411 11b Bottom Mode 1 Ch 1

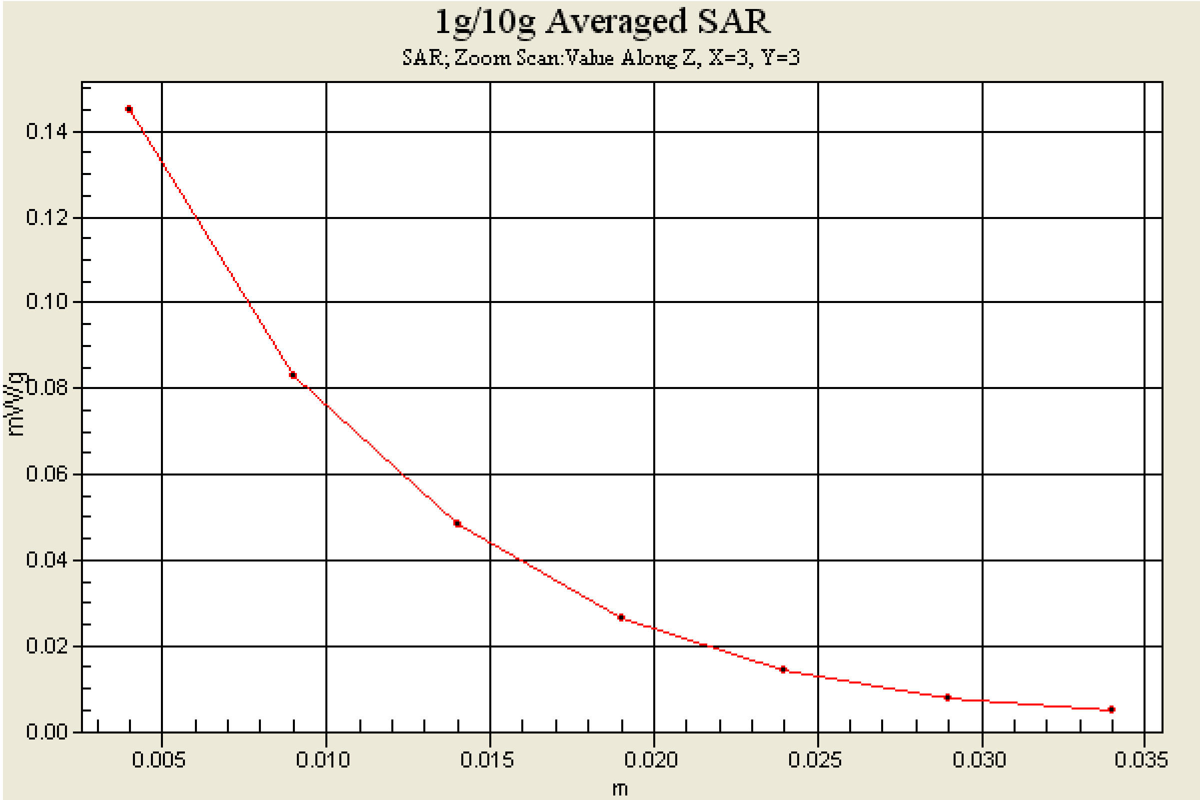
DUT: U.S. Robotics Wireless Maxg PC Card ; Type: USR5411 ; Test Channel Frequency: 2412 MHz

Communication System: 802.11b ; Frequency: 2412 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 Medium parameters used: f = 2412 MHz; σ = 1.98 mho/m; ε_r = 51.1; ρ = 1000 kg/m^3 ; Liquid level : 155 mm
Phantom section: Flat Section ; Separation distance : 16 mm (The bottom side of the EUT to the Phantom)
Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees
DASY4 Configuration:
- Probe: ET3DV6 - SN1687 ; ConvF(4.23, 4.23, 4.23) ; Calibrated: 2004/8/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510 ; Calibrated: 2004/8/17
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.4 Build 3 ; Postprocessing SW: SEMCAD, V1.8 Build 130

Low Channel/Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (measured) = 0.109 mW/g

Low Channel/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 3.87 V/m; Power Drift = 0.2 dB
Peak SAR (extrapolated) = 0.247 W/kg
SAR(1 g) = 0.131 mW/g; SAR(10 g) = 0.068 mW/g
Maximum value of SAR (measured) = 0.145 mW/g




1g/10g Averaged SAR
SAR; Zoom Scan:Value Along Z, X=3, Y=3
mW/g
0.14
0.12
0.10
0.08
0.06
0.04
0.02
0.00
0.005
0.010
0.015
0.020
0.025
0.030
0.035
m

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Test Laboratory: Advance Data Technology

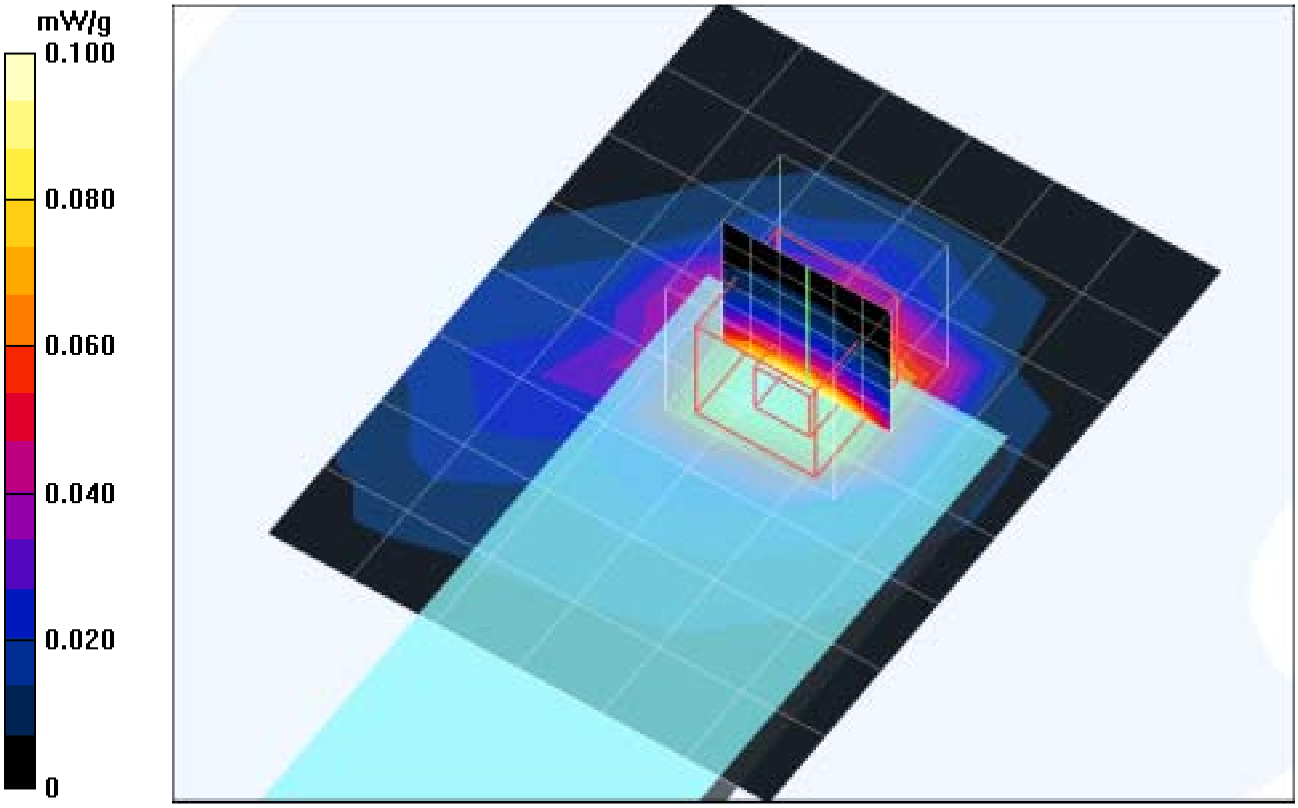
USR5411 11b Bottom Mode 1 Ch 6

DUT: U.S. Robotics Wireless Maxg PC Card ; Type: USR5411 ; Test Channel Frequency: 2437 MHz

Communication System: 802.11b ; Frequency: 2437 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 Medium parameters used: f = 2437 MHz; σ = 2.02 mho/m; ε_r = 51.1; ρ = 1000 kg/m^3 ; Liquid level : 155 mm
Phantom section: Flat Section ; Separation distance : 16 mm (The bottom side of the EUT to the Phantom)
Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees
DASY4 Configuration:
- Probe: ET3DV6 - SN1687 ; ConvF(4.23, 4.23, 4.23) ; Calibrated: 2004/8/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510 ; Calibrated: 2004/8/17
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.4 Build 3 ; Postprocessing SW: SEMCAD, V1.8 Build 130

Middle Channel/Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (measured) = 0.100 mW/g

Middle Channel/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 3.88 V/m; Power Drift = -0.2 dB
Peak SAR (extrapolated) = 0.219 W/kg
SAR(1 g) = 0.118 mW/g; SAR(10 g) = 0.062 mW/g
Maximum value of SAR (measured) = 0.129 mW/g



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Test Laboratory: Advance Data Technology

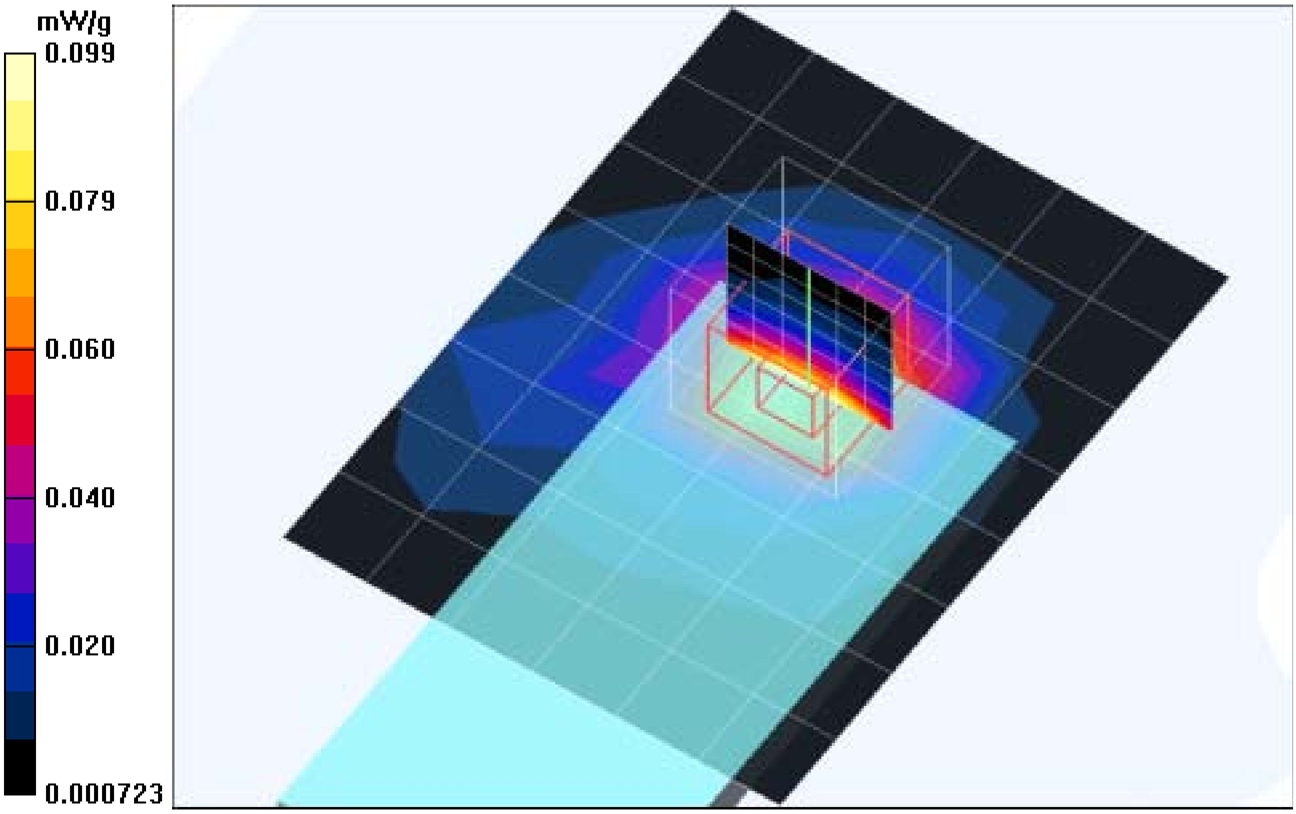
USR5411 11b Bottom Mode 1 Ch 11

DUT: U.S. Robotics Wireless Maxg PC Card ; Type: USR5411 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11b ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: CCK
Medium: MSL2450 Medium parameters used: f = 2462 MHz; σ = 2.05 mho/m; ε_r = 51; ρ = 1000 kg/m^3 ; Liquid level : 155 mm
Phantom section: Flat Section ; Separation distance : 16 mm (The bottom side of the EUT to the Phantom)
Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees
DASY4 Configuration:
- Probe: ET3DV6 - SN1687 ; ConvF(4.23, 4.23, 4.23) ; Calibrated: 2004/8/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510 ; Calibrated: 2004/8/17
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.4 Build 3 ; Postprocessing SW: SEMCAD, V1.8 Build 130

High Channel/Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (measured) = 0.099 mW/g

High Channel/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 3.78 V/m; Power Drift = -0.2 dB
Peak SAR (extrapolated) = 0.183 W/kg
SAR(1 g) = 0.103 mW/g; SAR(10 g) = 0.054 mW/g
Maximum value of SAR (measured) = 0.112 mW/g



Date/Time: 11/30/04 16:05:27

Test Laboratory: Advance Data Technology

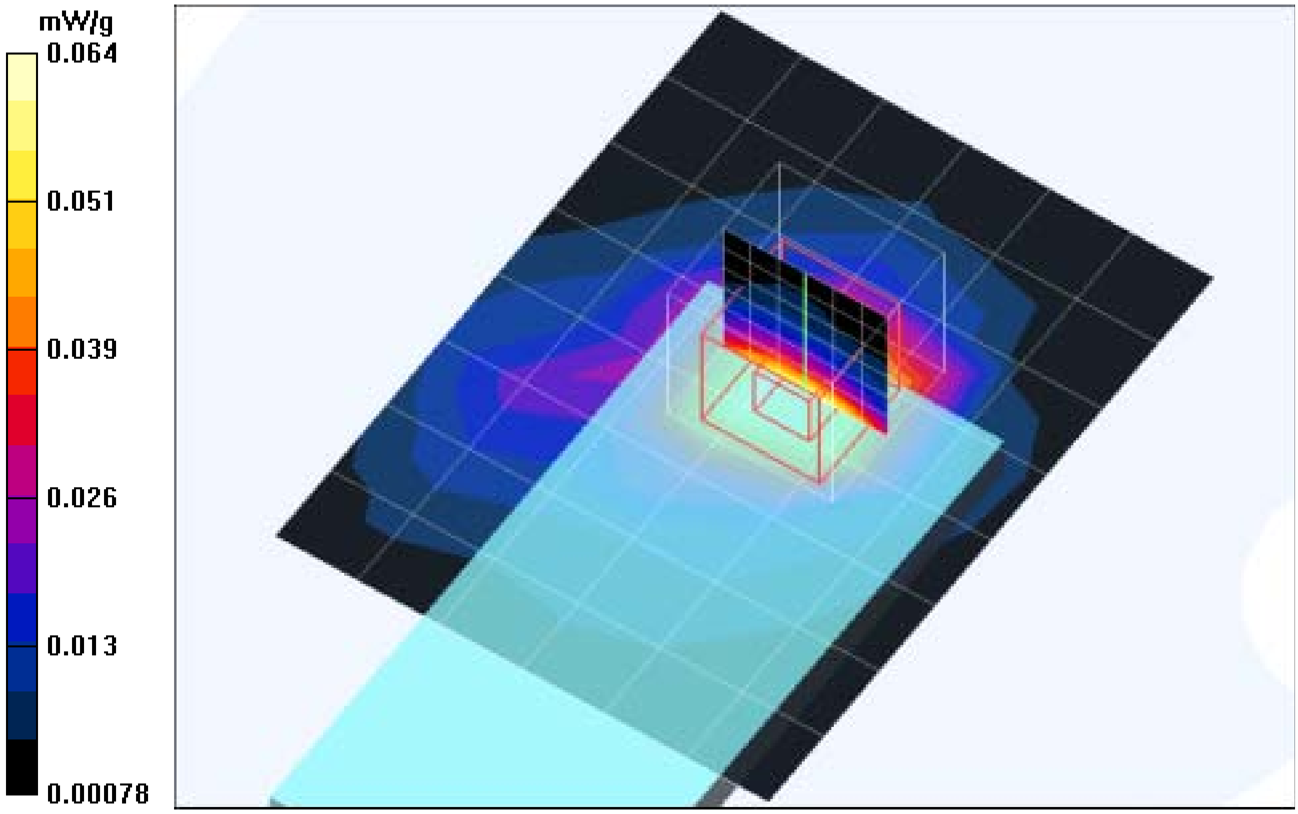
USR5411 11g Bottom Mode 2 Ch 1

DUT: U.S. Robotics Wireless Maxg PC Card ; Type: USR5411 ; Test Channel Frequency: 2412 MHz

Communication System: 802.11g ; Frequency: 2412 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM
Medium: MSL2450 Medium parameters used: f = 2412 MHz; σ = 1.98 mho/m; ε_r = 51.1; ρ = 1000 kg/m^3 ; Liquid level : 155 mm
Phantom section: Flat Section ; Separation distance : 16 mm (The bottom side of the EUT to the Phantom)
Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees
DASY4 Configuration:
- Probe: ET3DV6 - SN1687 ; ConvF(4.23, 4.23, 4.23) ; Calibrated: 2004/8/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510 ; Calibrated: 2004/8/17
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.4 Build 3 ; Postprocessing SW: SEMCAD, V1.8 Build 130

Low Channel/Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (measured) = 0.064 mW/g

Low Channel/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 2.82 V/m; Power Drift = 0.2 dB
Peak SAR (extrapolated) = 0.147 W/kg
SAR(1 g) = 0.075 mW/g; SAR(10 g) = 0.038 mW/g
Maximum value of SAR (measured) = 0.083 mW/g



Date/Time: 11/30/04 16:24:10

Test Laboratory: Advance Data Technology

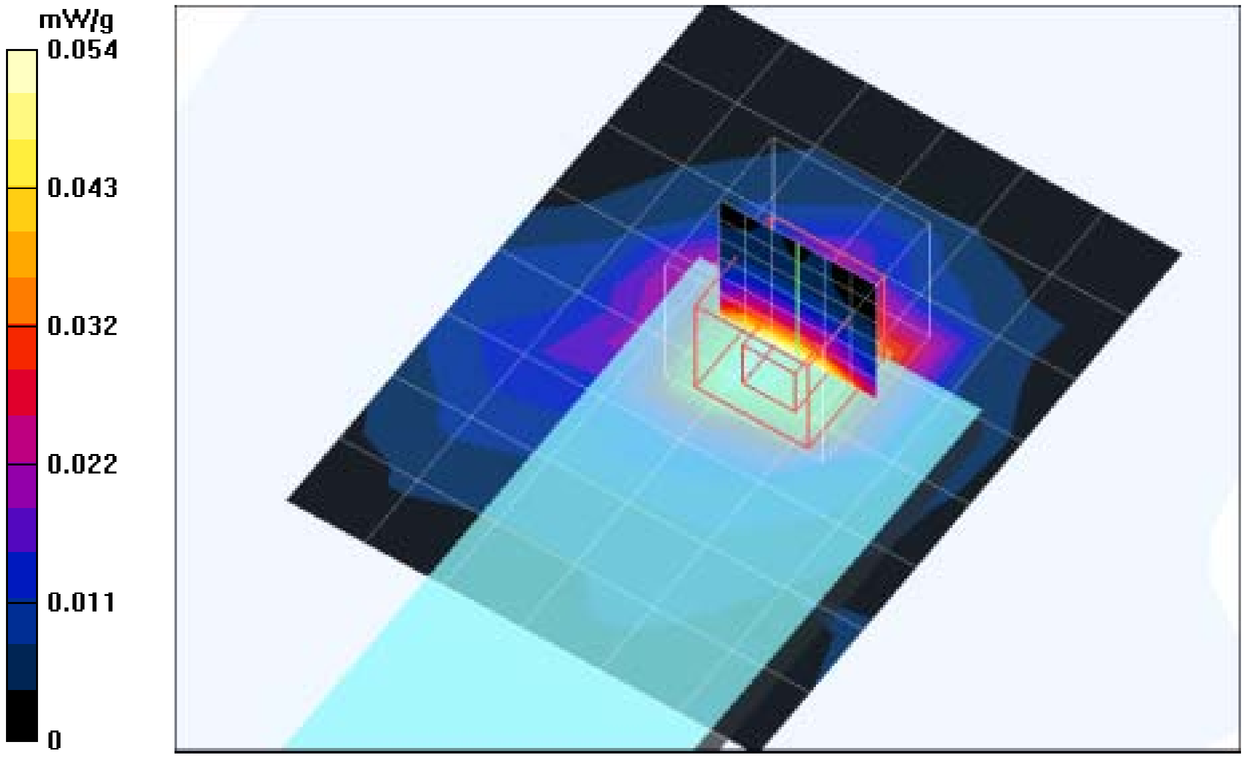
USR5411 11g Bottom Mode 2 Ch 6

DUT: U.S. Robotics Wireless Maxg PC Card ; Type: USR5411 ; Test Channel Frequency: 2437 MHz

Communication System: 802.11g ; Frequency: 2437 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM
Medium: MSL2450 Medium parameters used: f = 2437 MHz; σ = 2.02 mho/m; ε_r = 51.1; ρ = 1000 kg/m^3 ; Liquid level : 155 mm
Phantom section: Flat Section ; Separation distance : 16 mm (The bottom side of the EUT to the Phantom)
Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees
DASY4 Configuration:
- Probe: ET3DV6 - SN1687 ; ConvF(4.23, 4.23, 4.23) ; Calibrated: 2004/8/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510 ; Calibrated: 2004/8/17
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.4 Build 3 ; Postprocessing SW: SEMCAD, V1.8 Build 130

Middle Channel/Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (measured) = 0.054 mW/g

Middle Channel/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 2.84 V/m; Power Drift = -0.2 dB
Peak SAR (extrapolated) = 0.113 W/kg
SAR(1 g) = 0.061 mW/g; SAR(10 g) = 0.032 mW/g
Maximum value of SAR (measured) = 0.067 mW/g



Date/Time: 11/30/04 16:45:02

Test Laboratory: Advance Data Technology

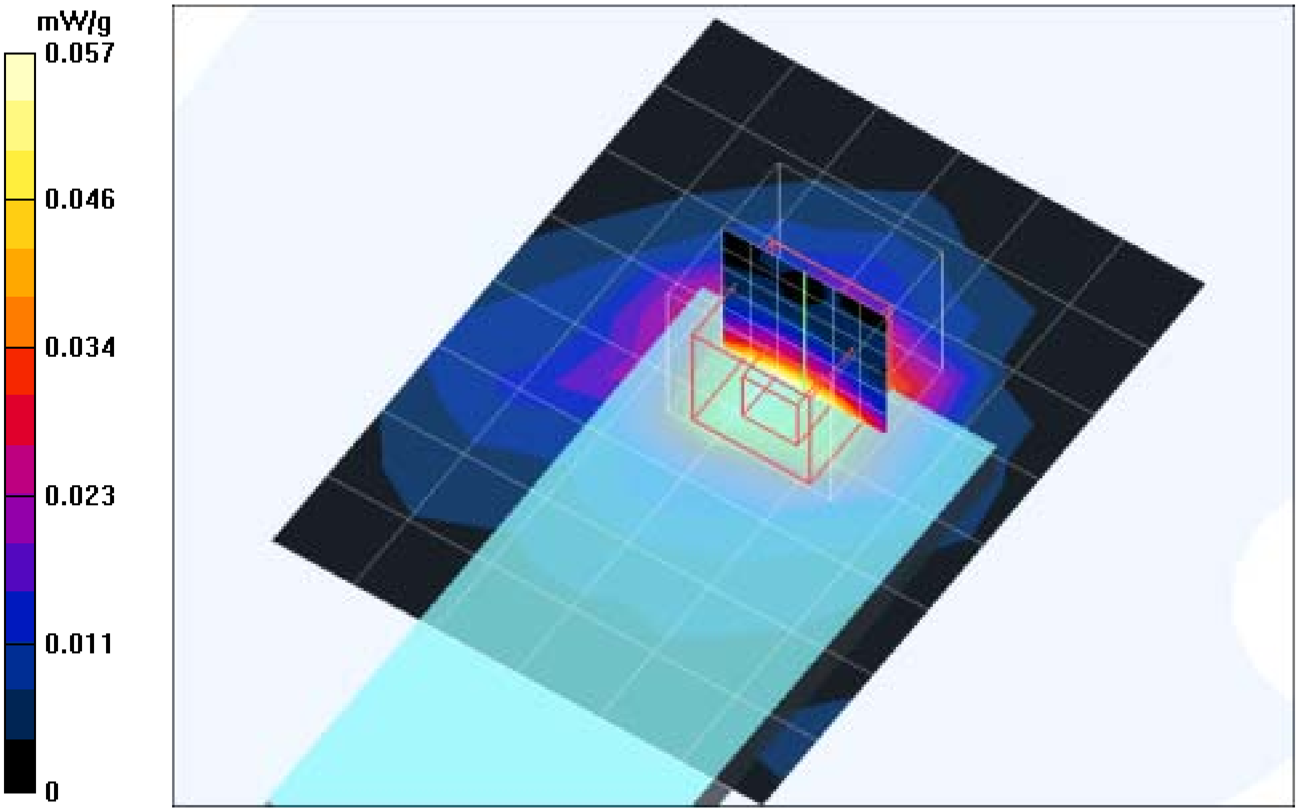
USR5411 11g Bottom Mode 2 Ch 11

DUT: U.S. Robotics Wireless Maxg PC Card ; Type: USR5411 ; Test Channel Frequency: 2462 MHz

Communication System: 802.11g ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: OFDM
Medium: MSL2450 Medium parameters used: f = 2462 MHz; σ = 2.05 mho/m; ε_r = 51; ρ = 1000 kg/m^3 ; Liquid level : 155 mm
Phantom section: Flat Section ; Separation distance : 16 mm (The bottom side of the EUT to the Phantom)
Antenna type : Internal Antenna ; Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees
DASY4 Configuration:
- Probe: ET3DV6 - SN1687 ; ConvF(4.23, 4.23, 4.23) ; Calibrated: 2004/8/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510 ; Calibrated: 2004/8/17
- Phantom: SAM 12 ; Type: SAM V4.0 ; Serial: TP 1202
- Measurement SW: DASY4, V4.4 Build 3 ; Postprocessing SW: SEMCAD, V1.8 Build 130

High Channel/Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (measured) = 0.057 mW/g

High Channel/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 2.71 V/m; Power Drift = 0.2 dB
Peak SAR (extrapolated) = 0.124 W/kg
SAR(1 g) = 0.064 mW/g; SAR(10 g) = 0.032 mW/g
Maximum value of SAR (measured) = 0.069 mW/g



A3 : SYSTEM VALIDATION

Date/Time: 11/30/04 10:33:20

Test Laboratory: Advance Data Technology

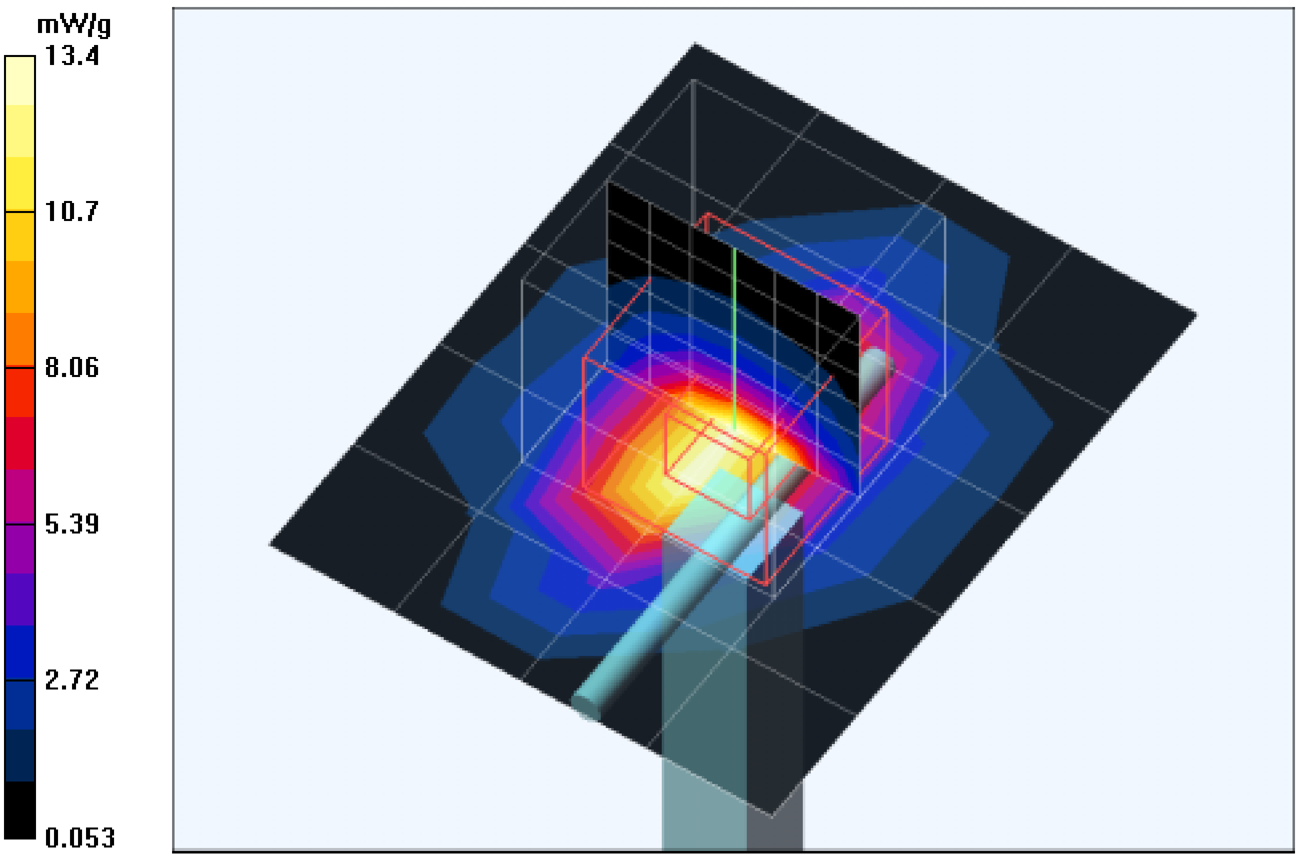
System Validation Check-MSL 2450MHz

DUT: Dipole 2450 MHz ; Type: D2450V2 ; Serial: 716 ; Test Channel Frequency: 2450 MHz

Communication System: CW ; Frequency: 2450 MHz; Duty Cycle: 1:1; Modulation type: CW
Medium: MSL2450;Medium parameters used: f = 2450 MHz; σ = 2.03 mho/m; ε_r = 51; ρ = 1000 kg/m^3 ; Liquid level : 155mm
Phantom section: Flat Section ; Separation distance : 10 mm (The feetpoint of the dipole to the Phantom)Air temp. : 22.0 degrees ; Liquid temp. : 21.0 degrees
DASY4 Configuration:
- Probe: ET3DV6 - SN1687 ; ConvF(4.23, 4.23, 4.23) ; Calibrated: 2004/8/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2004/8/17
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

d=10mm, Pin=250mW/Area Scan (5x6x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (measured) = 13.4 mW/g

d=10mm, Pin=250mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 88.3 V/m; Power Drift = -0.2 dB
Peak SAR (extrapolated) = 25.7 W/kg
SAR(1 g) = 12.7 mW/g; SAR(10 g) = 5.99 mW/g
Maximum value of SAR (measured) = 14.4 mW/g



APPENDIX B : ADT SAR MEASUREMENT SYSTEM

APPENDIX C: PHOTOGRAPHS OF SYSTEM VALIDATION

APPENDIX D: SYSTEM CERTIFICATE & CALIBRATION

D1: SAM PHANTOM

Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland, Phone +41 1 245 97 00, Fax +41 1 245 97 79

Certificate of conformity / First Article Inspection

Item	SAM Twin Phantom V4.0
Type No	QD 000 P40 CA
Series No	TP-1150 and higher
Manufacturer / Origin	Untersee Composites Hauptstr. 69 CH-8559 Fruthwilen Switzerland

Tests

The series production process used allows the limitation to test of first articles.
Complete tests were made on the pre-series Type No. QD 000 P40 AA, Serial No. TP-1001 and on the series first article Type No. QD 000 P40 BA, Serial No. TP-1006. Certain parameters have been retested using further series units (called samples).

Test	Requirement	Details	Units tested
Shape	Compliance with the geometry according to the CAD model.	IT'IS CAD File (*)	First article, Samples
Material thickness	Compliant with the requirements according to the standards	2mm +/- 0.2mm in specific areas	First article, Samples
Material parameters	Dielectric parameters for required frequencies	200 MHz – 3 GHz Relative permittivity < 5 Loss tangent < 0.05.	Material sample TP 104-5
Material resistivity	The material has been tested to be compatible with the liquids defined in the standards	Liquid type HSL 1800 and others according to the standard.	Pre-series, First article

Standards

[1] CENELEC EN 50361
[2] IEEE P1528-200x draft 6.5
[3] IEC PT 62209 draft 0.9
(*) The IT'IS CAD file is derived from [2] and is also within the tolerance requirements of the shapes of [1] and [3].

Conformity

Based on the sample tests above, we certify that this item is in compliance with the uncertainty requirements of SAR measurements specified in standard [1] and draft standards [2] and [3].

Date 28.02.2002

Signature / Stamp

Schmid & Partner Engineering AG
Zeughausstrasse 43, CH-8004 Zurich
Tel. +41 1 245 97 00, Fax +41 1 245 97 79

F. Bomholt

D2: DOSIMETRIC E-FIELD PROBE

Schmid & Partner Engineering AG

s p e a g

Zeughausstrasse 43, 8004 Zurich, Switzerland
Phone +41 1 245 9700, Fax +41 1 245 9779
info@speag.com, http://www.speag.com

IMPORTANT NOTICE

USAGE OF PROBES IN ORGANIC SOLVENTS

Diethylene Gycol Monobuthy Ether (the basis for liquids above 1 GHz), as many other organic solvents, is a very effective softener for synthetic materials. These solvents can cause irreparable damage to certain SPEAG products. except those which are explicitly declared as compliant with organic solvents.

Compatible Probes:
- ET3DV6
- ET3DV6R
- ES3DV2
- ER3DV6
- H3DV6

Important Note for ET3DV6 Probes:
The ET3DV6 probes shall not be exposed to solvents longer than necessary for the measurements and shall be cleaned daily after use with warm water and stored dry.

s p e a g

Schmid & Partner Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland
Phone +41 1 245 9700, Fax +41 1 245 9779
info@speag.com, http://www.speag.com

Schmid & Partner Engineering AG

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

Client ADT (Auden)

CALIBRATION CERTIFICATE

Object(s)	ET3DV6 - SN:1687
Calibration procedure(s)	QA CAL-01.v2 Calibration procedure for dosimetric E-field probes
Calibration date:	August 26, 2004
Condition of the calibrated item	In Tolerance (according to the specific calibration document)

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature 22 +/- 2 degrees Celsius and humidity < 75%.

Calibration Equipment used (M&TE critical for calibration)

Model Type	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter EPM E4419B	GB41293874	5-May-04 (METAS, No 251-00388)	May-05
Power sensor E4412A	MY41495277	5-May-04 (METAS, No 251-00388)	May-05
Reference 20 dB Attenuator	SN 5086 (20b)	3-May-04 (METAS, No 251-00389)	May-05
Fluke Process Calibrator Type 702	SN 6295803	8-Sep-03 (Sintrel SCS No. E-030020)	Sep-04
Power sensor HP 8481A	MY41092180	18-Sep-02 (SPEAG, in house check Oct03)	In house check: Oct 05
RF generator HP 8684C	US3642U01700	4-Aug-99 (SPEAG, in house check Aug02)	In house check: Aug05
Network Analyzer HP 8753E	US37390585	18-Oct-01 (SPEAG, in house check Oct03)	In house check: Oct 05

	Name	Function	Signature
Calibrated by:	Nico Vetterli	Technician	
Approved by:	Katja Pokovic	Laboratory Director	

Date issued: August 26, 2004

This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.

Probe ET3DV6

SN:1687

Manufactured:	May 28, 2002
Last calibrated:	November 24, 2003
Recalibrated:	August 26, 2004

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

DASY - Parameters of Probe: ET3DV6 SN:1687

Sensitivity in Free Space

NormX	**1.87** µV/(V/m)^2	
NormY	**1.84** µV/(V/m)^2	
NormZ	**1.64** µV/(V/m)^2	

Diode Compression[A]

DCP X	**95**	mV
DCP Y	**95**	mV
DCP Z	**95**	mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Plese see Page 7.

Boundary Effect

Head **900 MHz** **Typical SAR gradient: 5 % per mm**

Sensor Center to Phantom Surface Distance		**3.7 mm**	**4.7 mm**
SAR_{be} [%]	Without Correction Algorithm	10.4	6.1
SAR_{be} [%]	With Correction Algorithm	0.3	0.5

Head **1800 MHz** **Typical SAR gradient: 10 % per mm**

Sensor Center to Phantom Surface Distance		**3.7 mm**	**4.7 mm**
SAR_{be} [%]	Without Correction Algorithm	13.0	8.9
SAR_{be} [%]	With Correction Algorithm	0.2	0.1

Sensor Offset

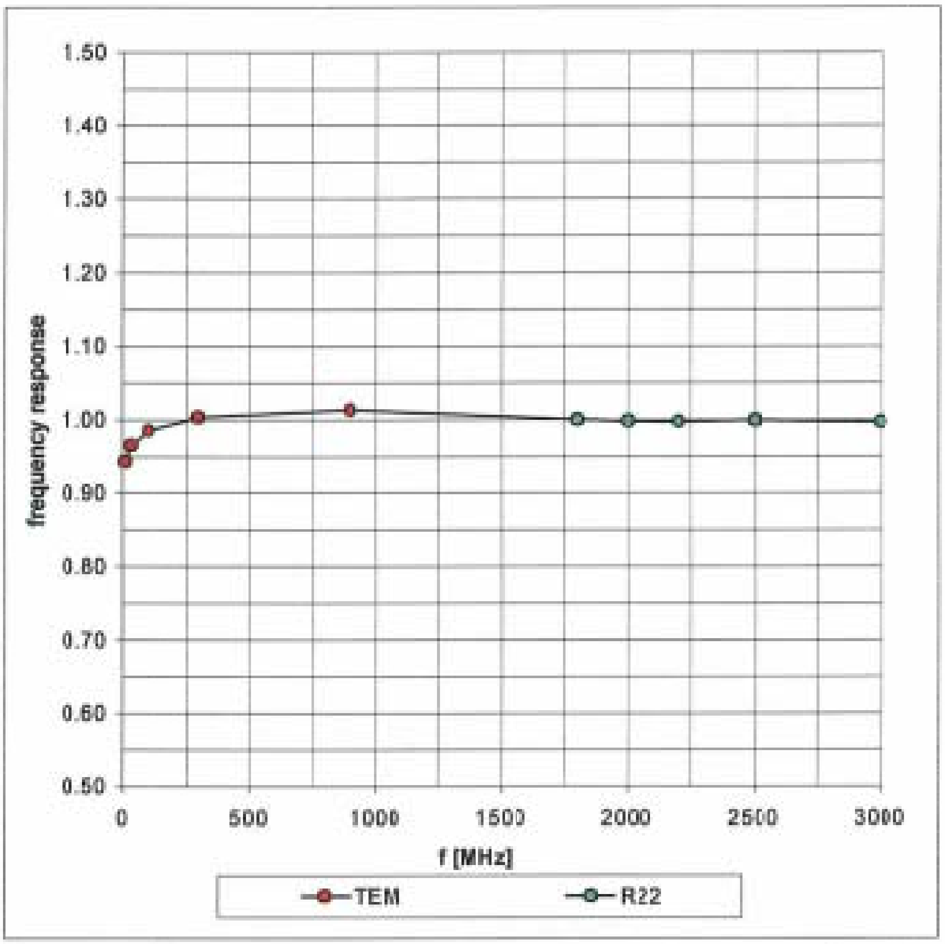
Probe Tip to Sensor Center	**2.7**	mm
Optical Surface Detection	**in tolerance**	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

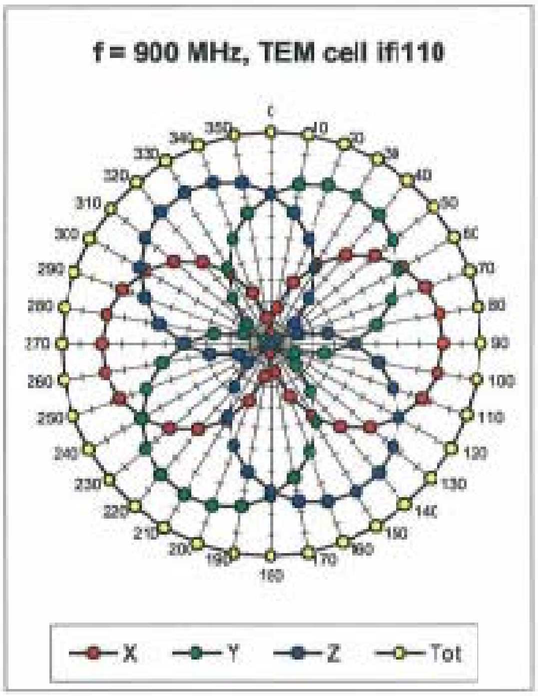
[A] numerical linearization parameter: uncertainty not required

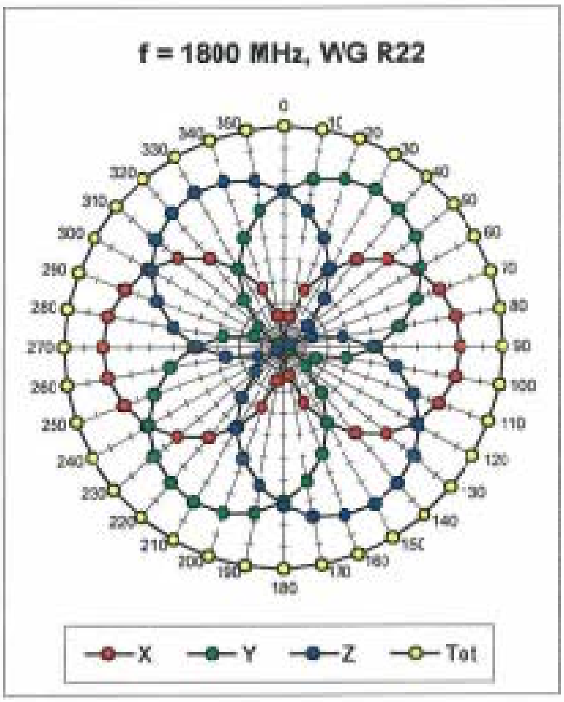
Frequency Response of E-Field

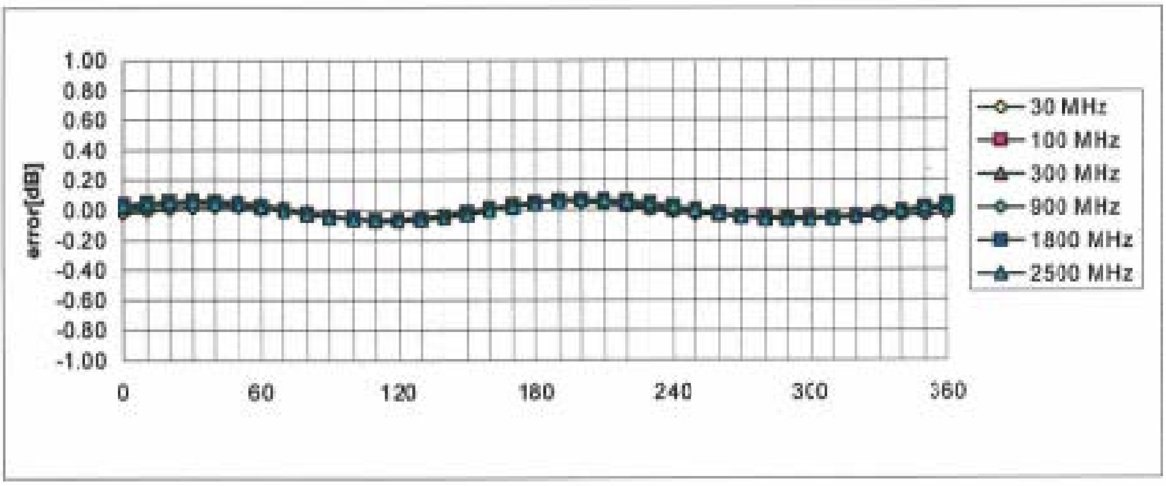
(TEM-Cell:ifi110, Waveguide R22)



Receiving Pattern (ϕ), θ = 0°



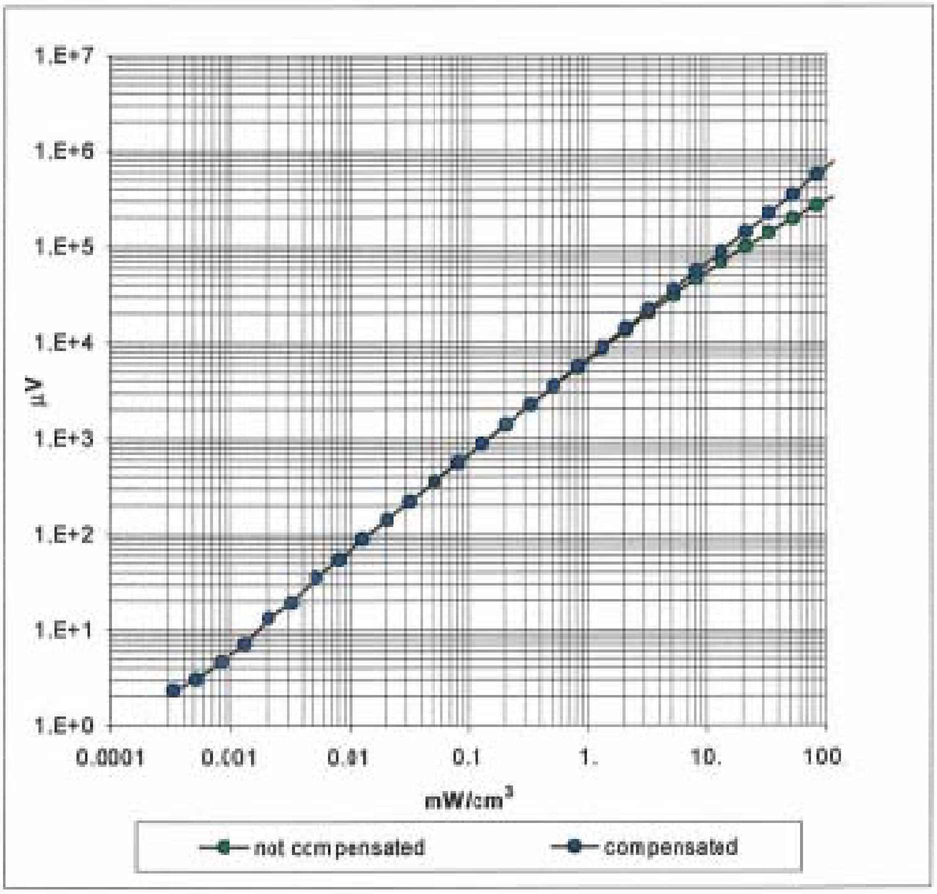


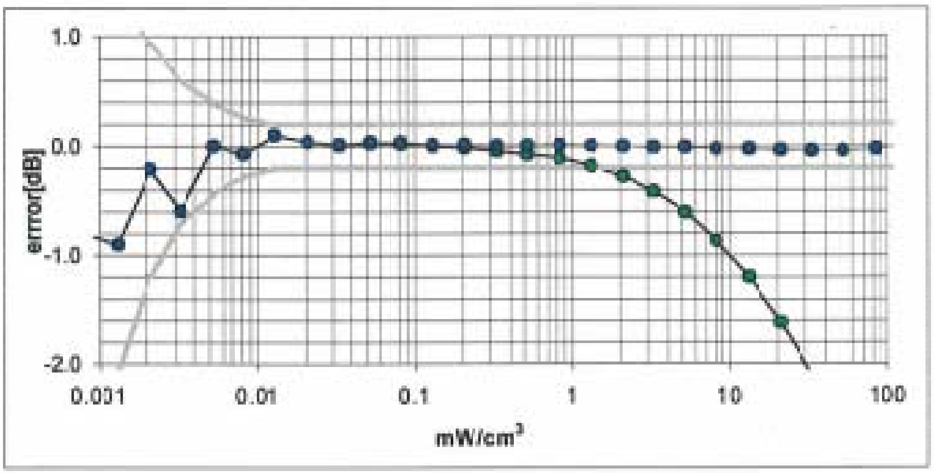


Axial Isotropy Error < ± 0.2 dB

Dynamic Range f(SAR_{head})

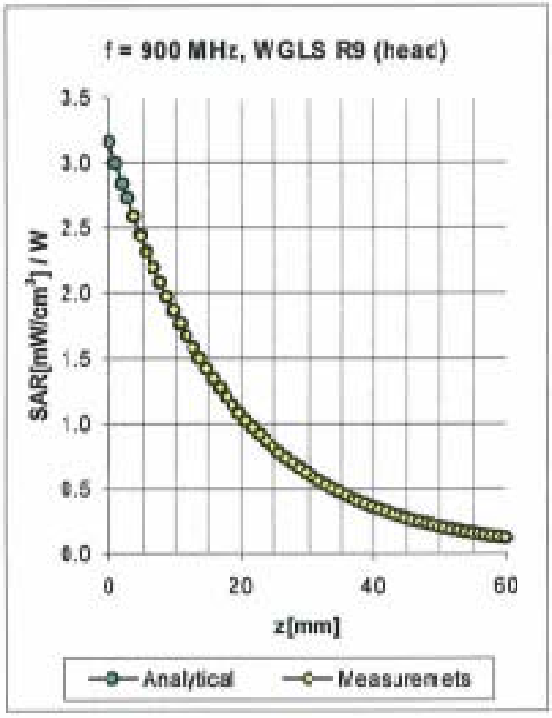
(Waveguide R22)

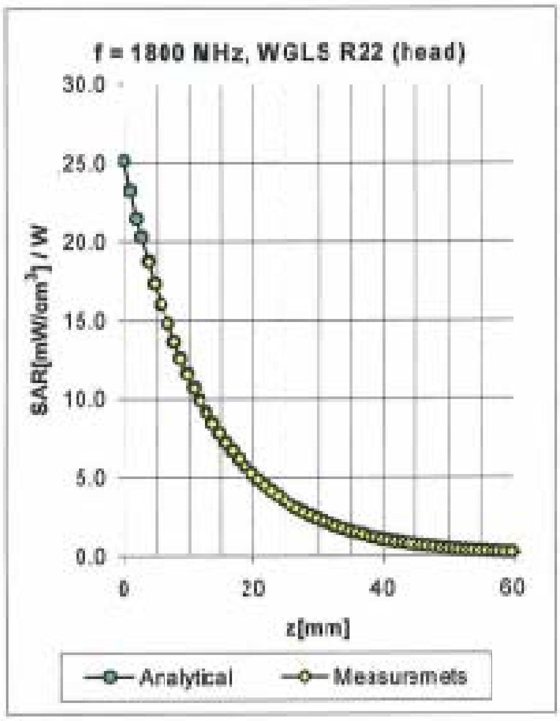




Probe Linearity Error < ± 0.2 dB

Conversion Factor Assessment



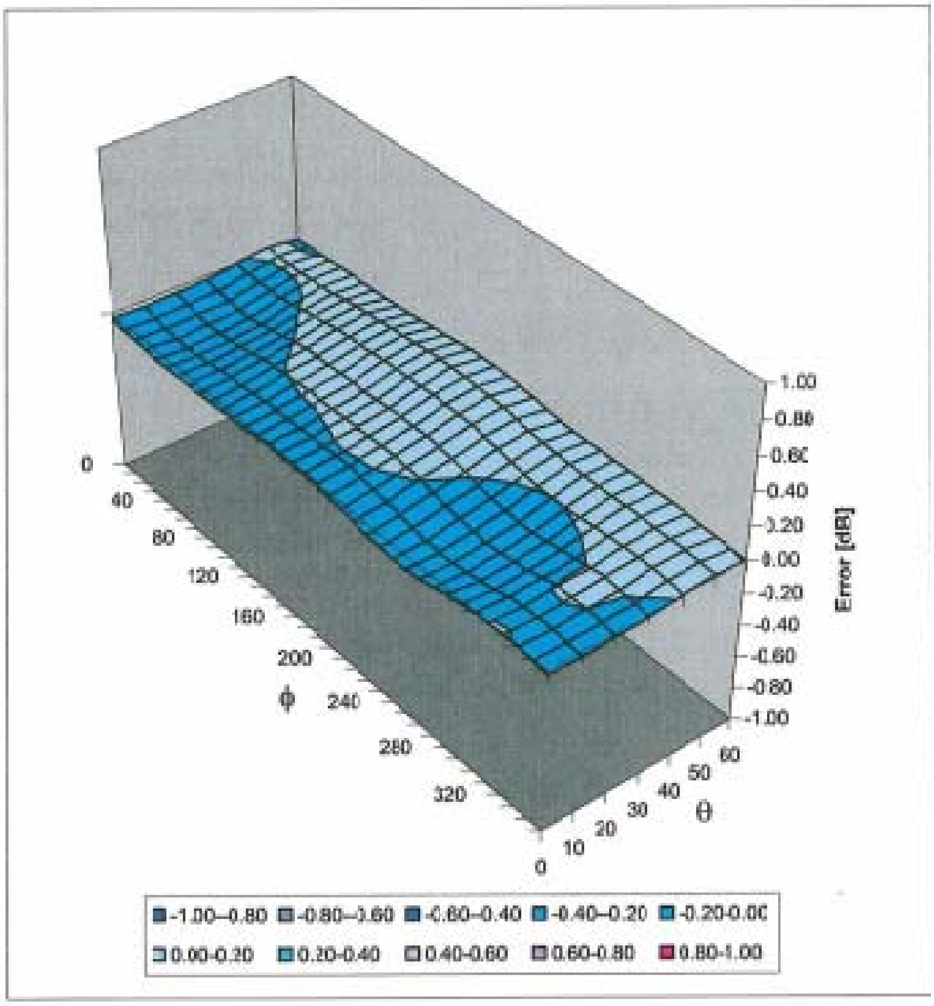


f [MHz]	Validity [MHz][8]	Tissue	Permittivity	Conductivity	Alpha	Depth	ConvF	Uncertainty
900	800-1000	Head	41.5 ± 5%	0.97 ± 5%	0.38	2.58	6.54	± 11.3% (k=2)
1800	1710-1910	Head	40.0 ± 5%	1.40 ± 5%	0.46	2.71	5.16	± 11.7% (k=2)
2450	2400-2500	Head	39.2 ± 5%	1.80 ± 5%	0.90	1.93	4.41	± 9.7% (k=2)
900	800-1000	Body	55.0 ± 5%	1.05 ± 5%	0.52	2.10	6.06	± 11.3% (k=2)
1800	1710-1910	Body	53.3 ± 5%	1.52 ± 5%	0.52	2.88	4.54	± 11.7% (k=2)
2450	2400-2500	Body	52.7 ± 5%	1.95 ± 5%	1.04	1.62	4.23	± 9.7% (k=2)

[8] The total standard uncertainty is calculated as root-sum-square of standard uncertainty of the Conversion Factor at calibration frequency and the standard uncertainty for the indicated frequency band.

Deviation from Isotropy in HSL

Error (θ, φ), f = 900 MHz



Spherical Isotropy Error < ± 0.4 dB

D3: DAE

Zeughausstrasse 43, 8004 Zurich, Switzerland
Phone +41 1 245 9700, Fax +41 1 245 9779
info@speag.com, http://www.speag.com

IMPORTANT NOTICE

USAGE OF THE DAE 3

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

Battery Exchange: The battery cover of the DAE3 unit is connected to a fragile 3-pin battery connector. Customer is responsible to apply outmost caution not to bend or damage the connector when changing batteries.

Shipping of the DAE: Before shipping the DAE to SPEAG for calibration Customer shall remove the batteries and pack the DAE in an antistatic bag. The packaging shall protect the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

E-Stop Failures: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, Customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

Repair: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

Important Note:
Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.

Important Note:
Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the E-stop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

Schmid & Partner Engineering

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

Client **Auden ADT**

CALIBRATION CERTIFICATE

Object(s)	DAE3 - SD 000 D03 AA - SN: 510
Calibration procedure(s)	QA CAL-06.v7 Calibration procedure for the data acquisition unit (DAE)
Calibration date:	17.08.2004
Condition of the calibrated item	In Tolerance (according to the specific calibration document)

This calibration statement documents traceability of M&TE used in the calibration procedures and conformity of the procedures with the ISO/IEC 17025 international standard.

All calibrations have been conducted in the closed laboratory facility: environment temperature 22 +/- 2 degrees Celsius and humidity < 75%.

Calibration Equipment used (M&TE critical for calibration)

Model Type	ID #	Cal Date	Scheduled Calibration
Fluke Process Calibrator Type 702	SN: 6295803	8-Sep-03	Sep-04

	Name	Function	Signature
Calibrated by:	Philipp Storchenegger	Technician	
Approved by:	Fin Bomholt	R&D Director	i.V.

Date issued: 17.08.2004

This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.

1. DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1µV , full range = -100...+300 mV

Low Range: 1LSB = 61nV , full range = -1.......+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time 3 sec

Calibration Factors	X	Y	Z
High Range	403.405	403.470	403.344
Low Range	3.95588	3.93301	3.95923
Connector Angle to be used	in DASY System	43 °	

High Range	Input (µV)	Reading (µV)	Error (%)
Channel X + Input	200000	199999.5	0.00
Channel X + Input	20000	20004.1	0.02
Channel X - Input	20000	-19988.8	-0.06
Channel Y + Input	200000	199999.9	0.00
Channel Y + Input	20000	19999.3	0.00
Channel Y - Input	20000	-19993.8	-0.03
Channel Z + Input	200000	199999.6	0.00
Channel Z + Input	20000	20005.6	0.03
Channel Z - Input	20000	-19995.4	-0.02

Low Range	Input (µV)	Reading (µV)	Error (%)
Channel X + Input	2000	1999.96	0.00
Channel X + Input	200	200.00	0.00
Channel X - Input	200	-200.34	0.17
Channel Y + Input	2000	2000.03	0.00
Channel Y + Input	200	199.39	-0.31
Channel Y - Input	200	-200.81	0.41
Channel Z + Input	2000	2000.07	0.00
Channel Z + Input	200	199.29	-0.36
Channel Z - Input	200	-201.07	0.53

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Reading (µV)	Low Range Reading (µV)
Channel X	200	17.42	16.88
	- 200	-17.00	-17.10
Channel Y	200	14.86	14.26
	- 200	-15.53	-16.14
Channel Z	200	-8.63	-8.44
	- 200	7.15	7.51

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (µV)	Channel Y (µV)	Channel Z (µV)
Channel X	200	-	2.45	1.22
Channel Y	200	0.25	-	4.38
Channel Z	200	-1.29	0.37	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15983	16854
Channel Y	16210	16793
Channel Z	16173	16131

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10MΩ

	Average (µV)	min. Offset (µV)	max. Offset (µV)	Std. Deviation (µV)
Channel X	0.46	-0.28	1.02	0.27
Channel Y	-1.06	-1.87	-0.38	0.25
Channel Z	-0.15	-1.01	0.88	0.36

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.2001	201.3
Channel Y	0.2001	199.6
Channel Z	0.2001	200.7

8. Low Battery Alarm Voltage

typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption

typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9

D4: 2450MHz SYSTEM VALIDATION DIPOLE

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

Client **ADT (Auden)**

CALIBRATION CERTIFICATE

Object(s)	D2450V2 - SN:716
Calibration procedure(s)	QA CAL-05.v2 Calibration procedure for dipole validation kits
Calibration date:	August 23, 2004
Condition of the calibrated item	In Tolerance (according to the specific calibration document)

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature 22 +/- 2 degrees Celsus and humidity < 75%

Calibration Equipment used (M&TE critical for calibration)

Model Type	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter EPM E442	GB37480704	6-Nov-03 (METAS, No. 252-0254)	Nov-04
Power sensor HP 8481A	US37292783	6-Nov-03 (METAS, No. 252-0254)	Nov-04
Power sensor HP 8481A	MY41092317	18-Oct-02 (Agilent, No. 20021018)	Oct-04
RF generator R&S SML-03	100698	27-Mar-2002 (R&S, No. 20-92389)	In house check: Mar-05
Network Analyzer HP 8753E	US37390585	18-Oct-01 (SPEAG, in house check Nov-03)	In house check: Oct 05

	Name	Function	Signature
Calibrated by:	Judith Mueller	Technician	
Approved by:	Katja Pokovic	Laboratory Director	

Date issued: August 26, 2004

This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.

Schmid & Partner Engineering AG

s p e a g

Zeughausstrasse 43, 8004 Zurich, Switzerland
Phone +41 1 245 9700, Fax +41 1 245 9779
info@speag.com, http://www.speag.com

DASY

Dipole Validation Kit

Type: D2450V2

Serial: 716

Manufactured: September 10, 2002
Calibrated: August 23, 2004

1. Measurement Conditions

The measurements were performed in the quarter size flat phantom filled with **head simulating solution** of the following electrical parameters at 2450 MHz:

Relative Dielectricity	**38.3**	± 5%
Conductivity	**1.86 mho/m**	± 5%

The DASY4 System with a dosimetric E-field probe ES3DV2 (SN:3025, Conversion factor 4.55 at 2450 MHz) was used for the measurements.

The dipole was mounted on the small tripod so that the dipole feedpoint was positioned below the center marking of the quarter size flat phantom and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10mm from dipole center to the solution surface. Lossless spacer was used during measurements for accurate distance positioning.

The coarse grid with a grid spacing of 15mm was aligned with the dipole. The 7x7x7 fine cube was chosen for cube integration.
The dipole input power (forward power) was 250mW ± 3 %. The results are normalized to 1W input power.

2. SAR Measurement with DASY4 System

Standard SAR-measurements were performed according to the measurement conditions described in section 1. The results (see figure supplied) have been normalized to a dipole input power of 1W (forward power). The resulting averaged SAR-values measured with the dosimetric probe ES3DV2 SN:3025 and applying the advanced extrapolation are:

averaged over 1 cm^3 (1 g) of tissue:	**52.4 mW/g** ± 16.8 % (k=2)[1]
averaged over 10 cm^3 (10 g) of tissue:	**23.8 mW/g** ± 16.2 % (k=2)[1]

[1] validation uncertainty

3. Dipole Impedance and Return Loss

The impedance was measured at the SMA-connector with a network analyzer and numerically transformed to the dipole feedpoint. The transformation parameters from the SMA-connector to the dipole feedpoint are:

Electrical delay:	**1.147 ns**	(one direction)
Transmission factor:	**0.983**	(voltage transmission, one direction)

The dipole was positioned at the flat phantom sections according to section 1 and the distance spacer was in place during impedance measurements.

Feedpoint impedance at 2450 MHz:	Re{Z} = **54.7 Ω**
	Im {Z} = **2.7 Ω**
Return Loss at 2450 MHz	**-26.1 dB**

4. Measurement Conditions

The measurements were performed in the quarter size flat phantom filled with **body simulating solution** of the following electrical parameters at 2450 MHz:

Relative Dielectricity	**51.7**	± 5%
Conductivity	**1.96 mho/m**	± 5%

The DASY4 System with a dosimetric E-field probe ES3DV2 (SN:3025, Conversion factor 4.22 at 2450 MHz) was used for the measurements.

The dipole was mounted on the small tripod so that the dipole feedpoint was positioned below the center marking of the quarter size flat phantom and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10mm from dipole center to the solution surface. Lossless spacer was used during measurements for accurate distance positioning.

The coarse grid with a grid spacing of 15mm was aligned with the dipole. The 7x7x7 fine cube was chosen for cube integration.
The dipole input power (forward power) was 250mW ± 3 %. The results are normalized to 1W input power.

5. SAR Measurement with DASY4 System

Standard SAR-measurements were performed according to the measurement conditions described in section 4. The results (see figure supplied) have been normalized to a dipole input power of 1W (forward power). The resulting averaged SAR-values measured with the dosimetric probe ES3DV2 SN:3025 and applying the advanced extrapolation are:

averaged over 1 cm^3 (1 g) of tissue:	**48.8 mW/g** ± 16.8 % (k=2)[2]
averaged over 10 cm^3 (10 g) of tissue:	**22.6 mW/g** ± 16.2 % (k=2)[2]

6. Dipole Impedance and Return Loss

The dipole was positioned at the flat phantom sections according to section 4 and the distance spacer was in place during impedance measurements.

Feedpoint impedance at 2450 MHz:	Re{Z} = **50.8 Ω**
	Im {Z} = **4.1 Ω**
Return Loss at 2450 MHz	**-27.7 dB**

7. Handling

Do not apply excessive force to the dipole arms, because they might bend. Bending of the dipole arms stresses the soldered connections near the feedpoint leading to a damage of the dipole.

8. Design

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

Small end caps have been added to the dipole arms in order to improve matching when loaded according to the position as explained in Sections 1and 4. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

9. Power Test

After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

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[2] validation uncertainty

Date/Time: 08/20/04 14:48:41

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN716

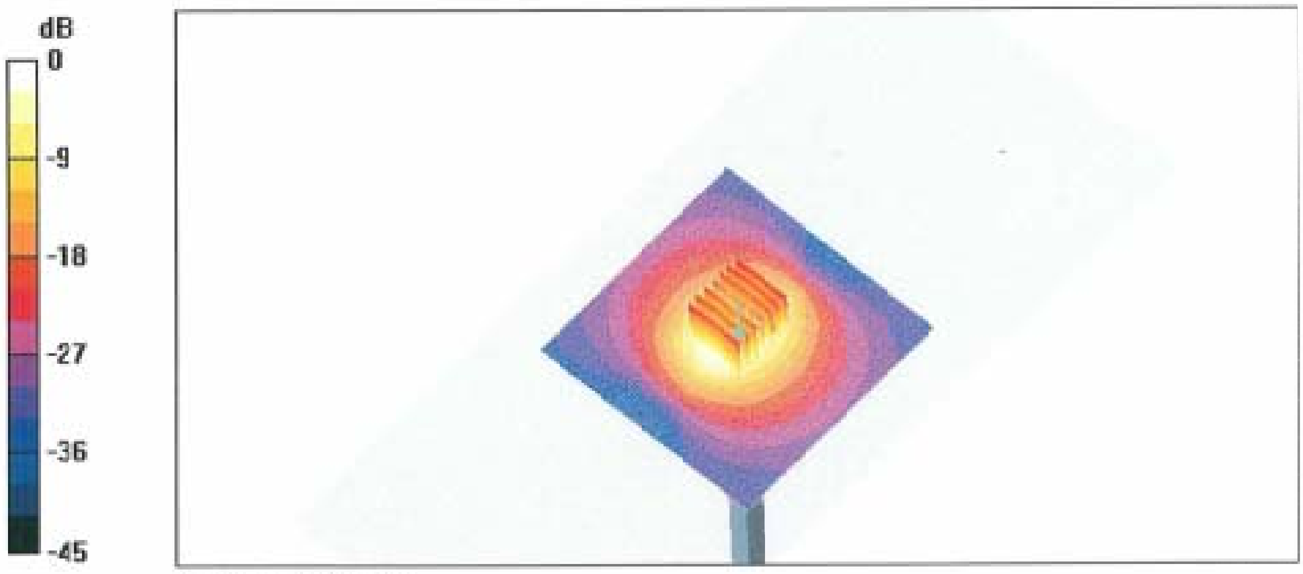
Communication System: CW-2450; Frequency: 2450 MHz;Duty Cycle: 1:1
Medium: HSL 2450 MHz;
Medium parameters used: f = 2450 MHz; σ = 1.86 mho/m; ε_r = 38.3; ρ = 1000 kg/m^3
Phantom section: Flat Section
Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV2 - SN3025; ConvF(4.55, 4.55, 4.55); Calibrated: 9/29/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 7/22/2004
- Phantom: Flat Phantom quarter size; Type: QD000P50AA; Serial: SN:1001;
- Measurement SW: DASY4, V4.3 Build 16; Postprocessing SW: SEMCAD, V1.8 Build 123

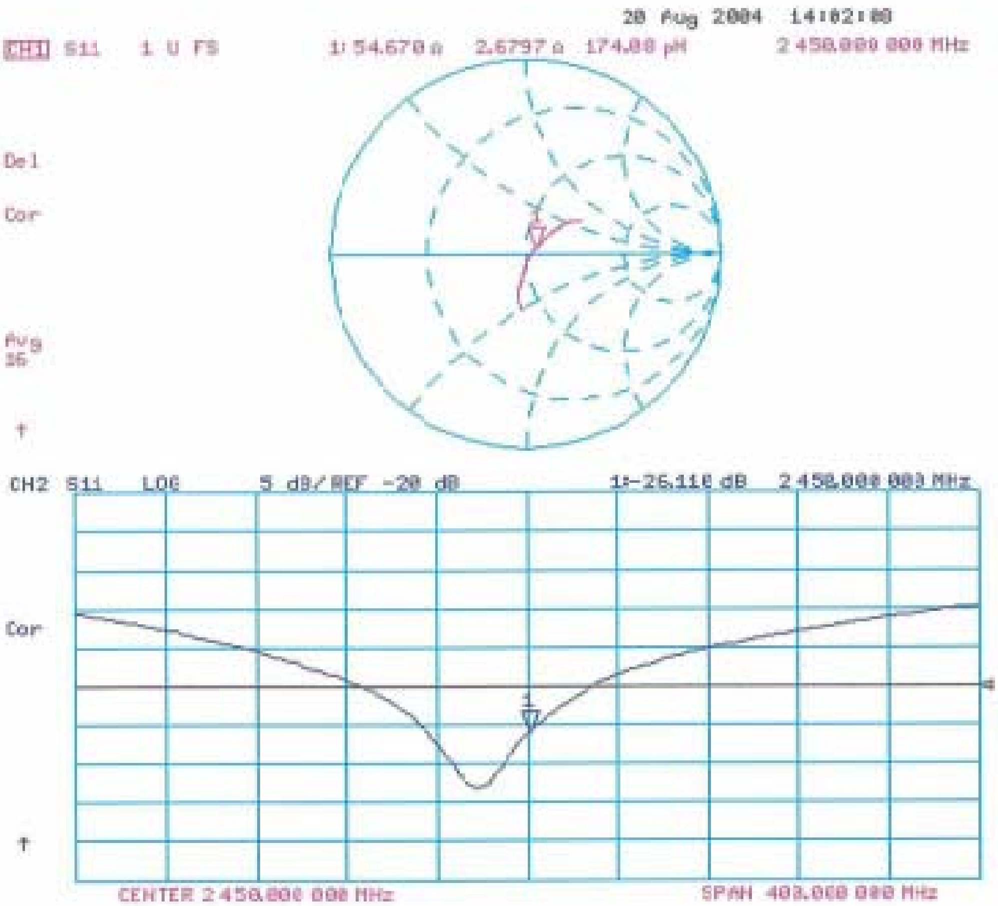
Pin = 250 mW; d = 10 mm/Area Scan (81x81x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 14.9 mW/g

Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 91.1 V/m; Power Drift = 0.1 dB
Peak SAR (extrapolated) = 27.6 W/kg
SAR(1 g) = 13.1 mW/g; SAR(10 g) = 5.95 mW/g
Maximum value of SAR (measured) = 14.8 mW/g



0 dB = 14.8mW/g

716
Head


20 Aug 2004 14:02:00
CH1 S11 1 U FS
1: 54.670 Ω 2.6797 Ω 174.08 pH
2 450.000 000 MHz
Del
Cor
Avg
16
CH2 S11 LOG
5 dB/ REF -20 dB
1:-26.110 dB 2 450.000 000 MHz
Cor
CENTER 2 450.000 000 MHz
SPAN 400.000 000 MHz

Date/Time: 08/23/04 11:02:14

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN716

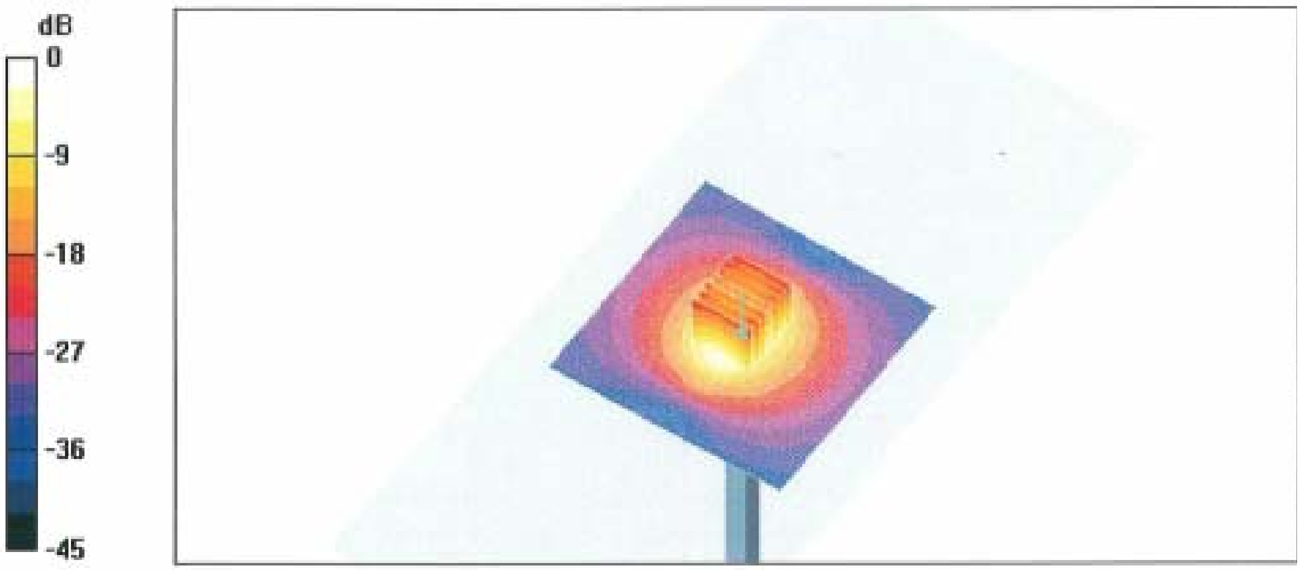
Communication System: CW-2450; Frequency: 2450 MHz;Duty Cycle: 1:1
Medium: Muscle 2450 MHz;
Medium parameters used: f = 2450 MHz; σ = 1.96 mho/m; ε_r = 51.7; ρ = 1000 kg/m^3
Phantom section: Flat Section
Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV2 - SN3025; ConvF(4.22, 4.22, 4.22); Calibrated: 9/29/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 7/22/2004
- Phantom: Flat Phantom quarter size; Type: QD000P50AA; Serial: SN:1001;
- Measurement SW: DASY4, V4.3 Build 17; Postprocessing SW: SEMCAD, V1.8 Build 124

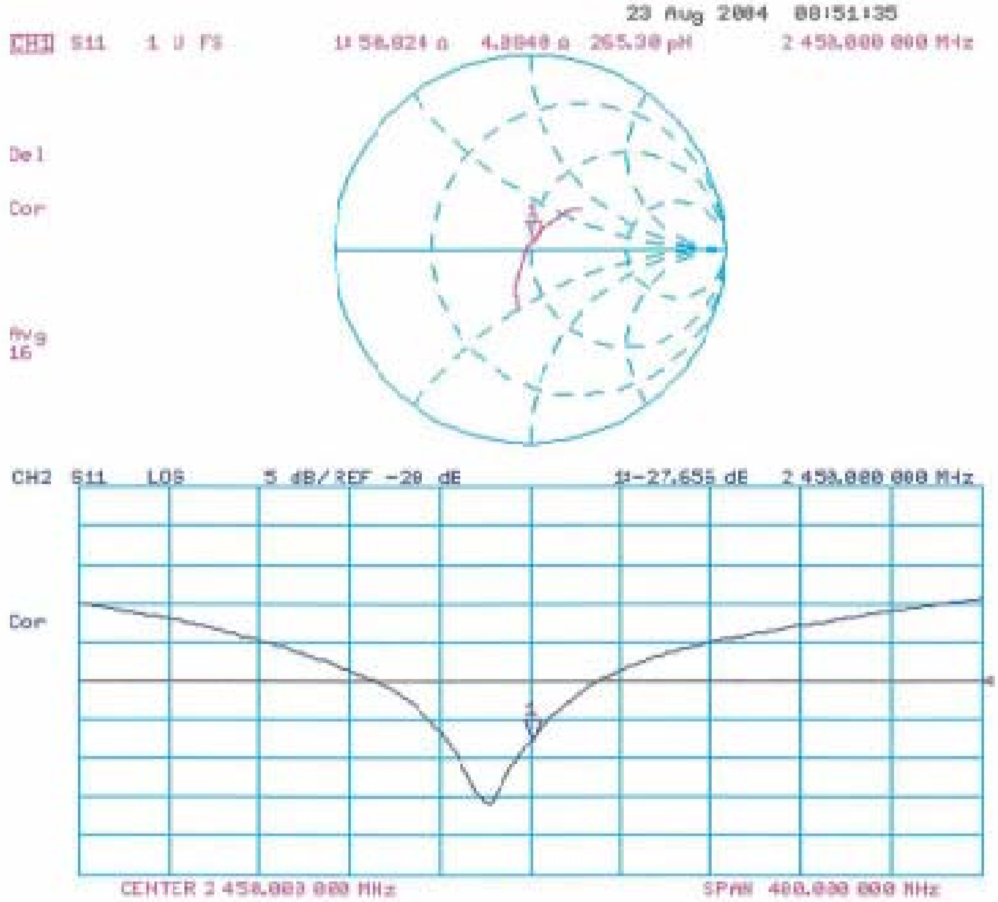
Pin = 250 mW; d = 10 mm/Area Scan (81x81x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 14.2 mW/g

Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 85.8 V/m; Power Drift = 0.0 dB
Peak SAR (extrapolated) = 24.9 W/kg
SAR(1 g) = 12.2 mW/g; SAR(10 g) = 5.64 mW/g
Maximum value of SAR (measured) = 14.1 mW/g



0 dB = 14.1mW/g

716
Body



23 Aug 2004 08:51:35
CH1 S11 1 U FS 1: 58.024 Ω 4.0040 Ω 265.30 pH 2 450.000 000 MHz
Del
Cor
Avg
16
CH2 S11 LOG 5 dB/REF -20 dB 1: -27.655 dB 2 450.000 000 MHz
Cor
CENTER 2 450.000 000 MHz
SPAN 400.000 000 MHz