# Specific Absorption Rate (SAR) Test Report for 

 MICRO-STAR INTL Co., LTD.on the
Wireless LAN Card

| Report No. | $:$ | FA872111A |
| :--- | :---: | :--- |
| Trade Name | $:$ | MSI |
| Model Name | $:$ | MS-6877 |
| FCC ID | $:$ | I4L-MS6877 |
| Date of Testing | $:$ | Aug. 09~26, 2008 |
| Date of Report | $:$ | Sep. 03, 2008 |
| Date of Review | $:$ | Sep. 03, 2008 |

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## SPORTON International Inc.

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## 1. Statement of Compliance

The Specific Absorption Rate (SAR) maximum result found during testing for the MICRO-STAR INTL Co., LTD. Wireless LAN Card MSI MS-6877 on the laptop host ECS / J10ILY (Y=0~9, A~Z) is $0.03 \mathrm{~W} / \mathrm{Kg}$ on $802.11 \mathrm{~b} / \mathrm{g}$ body SAR with expanded uncertainty $21.9 \%$. It is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1999 and had been tested in accordance with the measurement methods and procedures specified in OET Bulletin 65 Supplement C (Edition 01-01).

Approved by


## 2. Administration Data

### 2.1 Testing Laboratory

Company Name : Sporton International Inc.
Address : No.52, Hwa-Ya $1^{\text {st }}$ RD., Hwa Ya Technology Park, Kwei-Shan Hsiang, TaoYuan Hsien, Taiwan, R.O.C.
Telephone Number : 886-3-327-3456
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### 2.2 Detail of Applicant

Company Name : MICRO-STAR INTL Co., LTD.<br>Address : No. 69, Li-De St., Jung-He City, Taipei Hsien, Taiwan, R.O.C.

### 2.3 Detail of Manufacturer

Company Name : MICRO-STAR INTL Co., LTD.
Address: No. 69, Li-De St., Jung-He City, Taipei Hsien, Taiwan, R.O.C.

### 2.4 Application Details

Date of reception of application: Jul. 21, 2008
Start of test :
Aug. 09, 2008
End of test :
Aug. 26, 2008

## 3. General Information

### 3.1 Description of Device Under Test (DUT)

| Product Feature \& Specification |  |
| :--- | :--- |
| DUT Type : | Wireless LAN Card |
| Trade Name : | MSI |
| Model Name : | MS-6877 |
| FCC ID : | I4L-MS6877 |
| Frequency Range : | $2400 \mathrm{MHz} \sim 2483.5 \mathrm{MHz}$ |
| Channel Spacing : | 5 MHz |
| Carrier Frequency of Each Channel : | $2412+(\mathrm{n}-1) * 5 \mathrm{MHz} ; \mathrm{n}=1 \sim 11$ |
| Maximum Output Power to Antenna : | $802.11 \mathrm{~b}: 18.20 \mathrm{dBm}$ |
| $802.11 \mathrm{~g}: 15.27 \mathrm{dBm}$ |  |
| Type of Modulation : | $802.11 \mathrm{~b}:$ DSSS |
| $802.11 \mathrm{~g}:$ OFDM |  |
| DUT Stage : | Production Unit |

### 3.2 Description of Host

| Product Feature \& Specification |  |
| :--- | :--- |
| DUT Type : | Laptop Computer |
| Trade Name : | ECS |
| Model Name : | J10ILY (Y=0~9, A~Z) |
| Type of Antenna Connector : | I-PEX |
| Antenna Type : | PIFA Antenna |
| CPU : | ATOM 1.6G 533/512K SLB73 |
| LCD : | CPT, CLAA102NA0ACW LED (10.2" WVGA) |
| HDD : | Toshiba, MK1646GSX ( 160GB 5400RPM SATA) |
| WLAN Module : | MSI, MS-6877 |
| Touch Pad : | TOUCHPAD KGDFC0011B ALPS LF |
| Battery : | J10-3S2200-G1B1 (3 cell 2200mAh) |
| Web Cam : | Camera Module 1.3M CNF8111 CHICONY |
| Modem : | CASTLENE ML3054-LV |
| Power Adapter : | Delta, ADP-40MH AD |
| RAM : | LI SHIN, 0225C2040 |
| Resolution (Max.) : | Pqi, MECDR421LA0111 (DDR2 667 1GB*1) |

### 3.3 Product Photos

Please refer to Appendix D

### 3.4 Applied Standards

The Specific Absorption Rate (SAR) testing specification, method and procedure for this Wireless LAN Card is in accordance with the following standards:

47 CFR Part 2 (2.1093),
IEEE C95.1-1999,
IEEE C95.3-2002,
IEEE P1528-2003, and
OET Bulletin 65 Supplement C (Edition 01-01)
KDB 248227 r1.2 SAR Measurement Procedures for 802.11abg Transmitters
KDB 616217 D01 v01 SAR for Laptop with Screen Ant

### 3.5 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is $1.6 \mathrm{~W} / \mathrm{kg}$ as averaged over any 1 gram of tissue.

### 3.6 Test Conditions

### 3.6.1 Ambient Condition

| Date | Aug. 09, 2008 | Aug. 26, 2008 |
| :--- | :---: | :---: |
| Item | MSL_2450 | MSL_2450 |
| Ambient Temperature $\left({ }^{\circ} \mathbf{C}\right)$ | $20 \sim 24^{\circ} \mathrm{C}$ | $20 \sim 24^{\circ} \mathrm{C}$ |
| Tissue simulating liquid <br> temperature $\left({ }^{\circ} \mathbf{C}\right)$ | $21.4^{\circ} \mathrm{C}$ | $21.5^{\circ} \mathrm{C}$ |
| Humidity $(\%)$ | $<60 \%$ | $<60 \%$ |

### 3.6.2 Test Configuration

For WLAN link mode, engineering testing software installed on the EUT can provide continuous transmitting RF signal. This RF signal utilized in SAR measurement has almost $100 \%$ duty cycle and its crest factor is 1 . Measurements were performed on the lowest, middle, and highest channel for each testing position. However, measurements were performed only on the middle channel if the SAR is below 3 dB of limit for body SAR testing.

The data rates for WLAN SAR testing were set in 11 Mbps for 802.11 b and 54 Mbps for 802.11 g due to the highest RF output power.

## 4. Specific Absorption Rate (SAR)

### 4.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The FCC recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

### 4.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density. $\rho$ ). The equation description is as below:

$$
\mathbf{S A R}=\frac{d}{d t}\left(\frac{d W}{d m}\right)=\frac{d}{d t}\left(\frac{d W}{\rho d v}\right)
$$

## SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$
\mathbf{S A R}=C \frac{\delta T}{\delta t}
$$

, where C is the specific head capacity, $\delta T$ is the temperature rise and $\delta t$ the exposure duration, or related to the electrical field in the tissue by

$$
\mathbf{S A R}=\frac{\sigma|E|^{2}}{\rho}
$$

, where $\sigma$ is the conductivity of the tissue, $\rho$ is the mass density of the tissue and $\boldsymbol{E}$ is the rms electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

## 5. SAR Measurement Setup



Fig. 5.1 DASY5 System
The DASY5 system for performance compliance tests is illustrated above graphically. This system consists of the following items:
$>$ A standard high precision 6-axis robot with controller, a teach pendant and software
$>$ A data acquisition electronic (DAE) attached to the robot arm extension
$>$ A dosimetric probe equipped with an optical surface detector system
$>$ The electro-optical converter (ECO) performs the conversion between optical and electrical signals
> A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
$>$ A probe alignment unit which improves the accuracy of the probe positioning
> A computer operating Windows XP
> DASY5 software
> Remove control with teach pendant and additional circuitry for robot safety such as warming lamps, etc.
> The SAM twin phantom
$>$ A device holder
> Tissue simulating liquid
$>$ Dipole for evaluating the proper functioning of the system
Some of the components are described in details in the following sub-sections.
spoorion Lae. FCC SAR Test Report

### 5.1 DASY5 E-Field Probe System

The SAR measurement is conducted with the dosimetric probe ET3DV6 (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.


### 5.1.2 ET3DV6 E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than $\pm 10 \%$. The spherical isotropy shall be evaluated and within $\pm 0.25 \mathrm{~dB}$. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data are as below:
$>$ ET3DV6 sn1788

| Sensitivity | X axis : $1.72 \mu \mathrm{~V}$ |  | Y axis : $1.66 \mu \mathrm{~V}$ | Z axis : $1.70 \mu \mathrm{~V}$ |
| :---: | :---: | :---: | :---: | :---: |
| Diode compression point | X axis : 91 mV |  | Y axis : 93 mV | Z axis : 94 mV |
| Conversion factor (Head / Body) | Frequency (MHz) | X axis | Y axis | Z axis |
|  | 2350~2550 | 4.58 / 4.17 | 4.58 / 4.17 | 4.58 / 4.17 |
| Boundary effect (Head / Body) | Frequency (MHz) | Alpha | Depth |  |
|  | 2350~2550 | 0.61 / 0.61 | 2.39 / 2.58 |  |

NOTE: The probe parameters have been calibrated by the SPEAG.

### 5.2 DATA Acquisition Electronics (DAE)

The data acquisition electronics (DAE4) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE4 is 200M Ohm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB .

### 5.3 Robot

The DASY5 system uses the high precision robots TX90 XL type out of the newer series from Stäubli SA (France). For the 6 -axis controller DASY5 system, the CS8C robot controller version from Stäubli is used. The XL robot series have many features that are important for our application:
$>$ High precision (repeatability 0.02 mm )
$>$ High reliability (industrial design)
$>$ Jerk-free straight movements
$>$ Low ELF interference (the closed metallic construction shields against motor control fields)
> 6-axis controller

### 5.4 Measurement Server

The DASY5 measurement server is based on a PC/104 CPU board with 400 MHz CPU
128 MB chipdisk and 128 MB RAM.

Communication with the DAE4 electronic box the 16 -bit AD-converter system for optical detection and digital I/O interface.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.

### 5.5 SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2 mm shell thickness (except the ear region where shell thickness increases to 6 mm ). It has three measurement areas:
$>$ Left head
$>$ Right head
$>$ Flat phantom
The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

The phantom can be used with the following tissue simulating liquids:
*Water-sugar based liquid
*Glycol based liquids


Fig. 5.3 Top View of Twin Phantom


Fig. 5.4 Bottom View of Twin Phantom

### 5.6 Device Holder for SAM Twin Phantom

The SAR in the Phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source in 5 mm distance, a positioning uncertainty of $\pm 0.5 \mathrm{~mm}$ would produce a SAR uncertainty of $\pm 20 \%$. An accurate device position is therefore crucial for accurate and repeatable measurement. The position in which the devices must be measured, are defined by the standards.

The DASY5 device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).
Thus the device needs no repositioning when changing the angles.
The DASY5 device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\varepsilon_{\mathrm{r}}=3$ and loss tangent $\delta=0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.


Fig. 5.5 Device Holder

### 5.7 Data Storage and Evaluation

### 5.7.1 Data Storage

The DASY5 software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension .DA5. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., $[\mathrm{V} / \mathrm{m}],[\mathrm{A} / \mathrm{m}],[\mathrm{mW} / \mathrm{g}]$ ). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-louse media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

### 5.7.2 Data Evaluation

The DASY5 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software :

| Probe parameters: | - Sensitivity | $\operatorname{Norm}_{i}, \mathrm{a}_{i} 0, \mathrm{a}_{i} 1, \mathrm{a}_{i 2}$ |
| :--- | :--- | :--- |
|  | - Conversion factor | $\operatorname{ConvF}_{i}$ |
|  | - Diode compression point | $\mathrm{dcp} \mathrm{p}_{i}$ |
| Device parameters : | - Frequency | f |
|  | - Crest factor | cf |
| Media parameters: | - Conductivity | $\sigma$ |
|  | - Density | $\rho$ |

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY5 components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.
The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power.

The formula for each channel can be given as :

$$
V i=U_{i}+U_{i}^{2} \cdot \frac{c f}{d c p_{i}}
$$

with $\quad V_{i}=$ compensated signal of channel $i(i=x, y, z)$
$U_{i}=$ input signal of channel $i(i=x, y, z)$
cf = crest factor of exciting field (DASY parameter)
dcp $\boldsymbol{p}_{\boldsymbol{i}}=$ diode compression point (DASY parameter)
From the compensated input signals, the primary field data for each channel can be evaluated :
E-field probes: $E_{i}=\sqrt{\frac{V_{i}}{N o r m_{i} \operatorname{ConvF}}}$
H-field probes: $H_{i}=\sqrt{V_{i} \frac{a_{i 0}+a_{i 1} f+a_{i 2} f^{2}}{f}}$
with $\quad \boldsymbol{V}_{\boldsymbol{i}}=$ compensated signal of channel $i(i=\mathrm{x}, \mathrm{y}, \mathrm{z})$
Norm $_{i}=$ sensor sensitivity of channel $\mathrm{i}(\mathrm{i}=\mathrm{x}, \mathrm{y}, \mathrm{z})$ $\mu \mathrm{V} /(\mathrm{V} / \mathrm{m}) 2$ for E-field Probes
ConvF $=$ sensitivity enhancement in solution
$\boldsymbol{a}_{i j}=$ sensor sensitivity factors for H -field probes
$\boldsymbol{f}=$ carrier frequency $[\mathrm{GHz}]$
$\boldsymbol{E}_{\boldsymbol{i}}=$ electric field strength of channel $i$ in $\mathrm{V} / \mathrm{m}$
$\boldsymbol{H}_{i}=$ magnetic field strength of channel $i$ in $\mathrm{A} / \mathrm{m}$
The RSS value of the field components gives the total field strength (Hermitian magnitude) :

$$
E_{t o t}=\sqrt{E_{X}^{2}+E_{Y}^{2}+E_{Z}^{2}}
$$

The primary field data are used to calculate the derived field units.

$$
\mathrm{SAR}=E_{\text {tot }}^{2} \cdot \frac{\sigma}{\rho \cdot 1000}
$$

with $\quad \boldsymbol{S A R}=$ local specific absorption rate in $\mathrm{mW} / \mathrm{g}$
$\boldsymbol{E t o t}=$ total field strength in V/m
$\sigma=$ conductivity in [mho/m] or [Siemens $/ \mathrm{m}$ ]
$\rho=$ equivalent tissue density in $\mathrm{g} / \mathrm{cm}^{3}$

* Note that the density is set to 1 , to account for actual head tissue density rather than the density of the tissue simulating liquid.

The power flow density is calculated assuming the excitation field to be a free space field.

$$
P_{p w e}=\frac{E_{\text {tot }}^{2}}{3770} \quad \text { or } \quad P_{p w e}=H_{\text {tot }}^{2} \cdot 37.7
$$

with $\quad \boldsymbol{P}_{\boldsymbol{p} \text { we }}=$ equivalent power density of a plane wave in $\mathrm{mW} / \mathrm{cm}^{2}$
$\boldsymbol{E}_{\text {tot }}=$ total electric field strength in V/m
$H_{\text {tot }}=$ total magnetic field strength in $\mathrm{A} / \mathrm{m}$

### 5.8 Test Equipment List

| Manufacturer | Name of Equipment | Type/Model | Serial Number | Calibration |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | Last Cal. | Due Date |
| SPEAG | Dosimetric E-Filed Probe | ET3DV6 | 1788 | Sep. 26, 2007 | Sep. 25, 2008 |
| SPEAG | 2450MHz System Validation Kit | D2450V2 | 736 | Jul. 12, 2007 | Jul. 11, 2009 |
| SPEAG | Data Acquisition Electronics | DAE3 | 577 | Nov. 16, 2007 | Nov. 15, 2008 |
| SPEAG | Device Holder | N/A | N/A | NCR | NCR |
| SPEAG | SAM Phantom | QD 000 P40 C | TP-1303 | NCR | NCR |
| SPEAG | SAM Phantom | QD 000 P40 C | TP-1446 | NCR | NCR |
| SPEAG | SAM Phantom | QD 000 P40 C | TP-1383 | NCR | NCR |
| SPEAG | ELI4 Phantom | QD 0VA 001 BB | 1029 | NCR | NCR |
| SPEAG | Robot | Staubli RX90BL | F03/5W15A1/A/01 | NCR | NCR |
| SPEAG | Software | $\begin{gathered} \text { DASY5 } \\ \text { V5.0 Build } 91 \end{gathered}$ | N/A | NCR | NCR |
| SPEAG | Software | $\begin{gathered} \text { SEMCAD X } \\ \text { V12.4 Build } 52 \end{gathered}$ | N/A | NCR | NCR |
| SPEAG | Measurement Server | SE UMS 011 AA | 1014 | NCR | NCR |
| Agilent | PNA Series Network Analyzer | E8358A | US40260131 | Apr. 02, 2008 | Apr. 01, 2009 |
| Agilent | Wireless Communication Test Set | E5515C | GB46311322 | Dec. 22, 2006 | Dec. 21, 2008 |
| R\&S | Universal Radio Communication Tester | CMU200 | 103937 | Oct. 19, 2007 | Oct. 18, 2008 |
| Agilent | Dielectric Probe Kit | 85070D | US01440205 | NCR | NCR |
| Agilent | Dual Directional Coupler | 778D | 50422 | NCR | NCR |
| AR | Power Amplifier | 5S1G4M2 | 0328767 | NCR | NCR |
| R\&S | Power Meter | NRVD | 101394 | Oct. 31, 2007 | Oct. 30, 2008 |
| R\&S | Power Sensor | NRV-Z1 | 100130 | Oct. 31, 2007 | Oct. 30, 2008 |

Table 5.1 Test Equipment List

## 6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY5, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. The liquid height from the bottom of the phantom body is 15.2 centimeters, which is shown in Fig. 6.1.

The following ingredients for tissue simulating liquid are used:
> Water: deionized water (pure $\mathrm{H}_{2} 0$ ), resistivity $\geqq 16 \mathrm{M} \Omega$ - as basis for the liquid
$>$ Sugar: refined sugar in crystals, as available in food shops - to reduce relative permittyvity
> Salt: pure NaCl - to increase conductivity
> Cellulose: Hydroxyethyl-cellulose, medium viscosity ( $75-125 \mathrm{mPa} . \mathrm{s}, 2 \%$ in water, $20^{\circ} \mathrm{C}$ ), CAS\#54290-to increase viscosity and to keep sugar in solution.
> Preservative: Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS\#55965-84-9- to prevent the spread of bacteria and molds.
> DGMBE: Deithlenglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH, CAS\#112-34-5 - to reduce relative permittivity.

Table 6.1 gives the recipes for one liter of tissue simulating liquid for frequency band 2450 MHz .

| Ingredient | MSL-2450 |
| :--- | :--- |
| Water | 698.3 ml |
| DGMBE | 301.7 ml |
| Total amount | 1 liter $(1.0 \mathrm{~kg})$ |
| Dielectric Parameters at $\mathbf{2 2}^{\circ}$ | $\mathrm{f}=2450 \mathrm{MHz}$ <br> $\varepsilon_{\mathrm{r}}=52.7 \pm 5 \%, \quad \sigma=1.95 \pm 5 \% \mathrm{~S} / \mathrm{m}$ |

Table 6.1 Recipes of tissue Simulating Liquid
The dielectric parameters of the liquids were verified prior to the SAR evaluation using an Agilent 85070D Dielectric Probe Kit and an Agilent Network Analyzer.

Table 6.2 shows the measuring results for muscle simulating liquid.

| Band | Frequency <br> $(\mathbf{M H z})$ | Conductivity <br> $(\boldsymbol{\sigma})$ | Permittivity <br> $\left(\boldsymbol{\varepsilon}_{\mathbf{r}}\right)$ | Measurement <br> date |
| :---: | :---: | :---: | :---: | :---: |
| $802.11 \mathrm{~b} / \mathrm{g}$ | 2412 | 1.89 | 54.0 |  |
|  | 2437 | 1.92 | 53.9 | Aug. 09,2008 |
|  | 2462 | 1.95 | 53.8 |  |
| $802.11 \mathrm{~b} / \mathrm{g}$ | 2412 | 1.92 | 53.4 | Aug. 26, 2008 |
|  | 2437 | 1.95 | 53.3 |  |
|  | 2462 | 1.98 | 53.2 |  |

Table 6.2 Measuring Results for Muscle Simulating Liquid
The measuring data are consistent with $\varepsilon_{\mathrm{r}}=52.7 \pm 5 \%$ and $\sigma=1.95 \pm 5 \%$.


Fig 6.1 Liquid Height from the Bottom of the Phantom Body is 15.2 Centimeters

## 7. Uncertainty Assessment

The component of uncertainly may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainly by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table 7.1

| Uncertainty <br> Distributions | Normal | Rectangular | Triangular | U-shape |
| :---: | :---: | :---: | :---: | :---: |
| Multiplying factor ${ }^{(\mathrm{a})}$ | $1 / \mathrm{k}$ (b) | $1 / \sqrt{ } 3$ | $1 / \sqrt{ } 6$ | $1 / \sqrt{ } 2$ |

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity
(b) $\kappa$ is the coverage factor

## Table 7.1 Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3 . Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about $95 \%$. The DASY5 uncertainty Budget is showed in Table 7.2.

| Error Description | Uncertainty <br> Value $\pm \%$ | Probability Distribution | Divisor | $\begin{gathered} \mathbf{C i} \\ (\mathbf{1 g}) \end{gathered}$ | Standard Unc. (1g) | $\begin{gathered} \text { vi } \\ \text { or } \\ \text { Veff } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Measurement Equipment |  |  |  |  |  |  |
| Probe Calibration | $\pm 5.9$ \% | Normal | 1 | 1 | $\pm 5.9$ \% | $\infty$ |
| Axial Isotropy | $\pm 4.7$ \% | Rectangular | $\sqrt{3}$ | 0.7 | $\pm 1.9$ \% | $\infty$ |
| Hemispherical Isotropy | $\pm 9.6$ \% | Rectangular | $\sqrt{3}$ | 0.7 | $\pm 3.9$ \% | $\infty$ |
| Boundary Effects | $\pm 1.0$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 0.6$ \% | $\infty$ |
| Linearity | $\pm 4.7$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 2.7$ \% | $\infty$ |
| System Detection Limits | $\pm 1.0$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 0.6$ \% | $\infty$ |
| Readout Electronics | $\pm 0.3$ \% | Normal | 1 | 1 | $\pm 0.3$ \% | $\infty$ |
| Response Time | $\pm 0.8$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 0.5$ \% | $\infty$ |
| Integration Time | $\pm 2.6$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 1.5$ \% | $\infty$ |
| RF Ambient Noise | $\pm 3.0$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 1.7$ \% | $\infty$ |
| RF Ambient Reflections | $\pm 3.0$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 1.7$ \% | $\infty$ |
| Probe Positioner | $\pm 0.4$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 0.2$ \% | $\infty$ |
| Probe Positioning | $\pm 2.9$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 1.7$ \% | $\infty$ |
| Max. SAR Eval. | $\pm 1.0$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 0.6$ \% | $\infty$ |
| Test Sample Related |  |  |  |  |  |  |
| Device Positioning | $\pm 2.9$ \% | Normal | 1 | 1 | $\pm 2.9$ | 145 |
| Device Holder | $\pm 3.6$ \% | Normal | 1 | 1 | $\pm 3.6$ | 5 |
| Power Drift | $\pm 5.0$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 2.9$ | $\infty$ |
| Phantom and Setup |  |  |  |  |  |  |
| Phantom Uncertainty | $\pm 4.0$ \% | Rectangular | $\sqrt{3}$ | 1 | $\pm 2.3$ | $\infty$ |
| Liquid Conductivity (target) | $\pm 5.0$ \% | Rectangular | $\sqrt{3}$ | 0.64 | $\pm 1.8$ | $\infty$ |
| Liquid Conductivity (meas.) | $\pm 2.5$ \% | Normal | 1 | 0.64 | $\pm 1.6$ | $\infty$ |
| Liquid Permittivity (target) | $\pm 5.0$ \% | Rectangular | $\sqrt{3}$ | 0.6 | $\pm 1.7$ | $\infty$ |
| Liquid Permittivity (meas.) | $\pm 2.5$ \% | Normal | 1 | 0.6 | $\pm 1.5$ | $\infty$ |
| Combined Standard Uncertainty |  |  |  |  | $\pm 10.9$ | 387 |
| Coverage Factor for $95 \%$ |  | $\mathrm{K}=2$ |  |  |  |  |
| Expanded uncertainty (Coverage factor $=2$ ) |  |  |  |  | $\pm 21.9$ |  |

Table 7.2 Uncertainty Budget of DASY5

## 8. SAR Measurement Evaluation

Each DASY5 system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY5 software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

### 8.1 Purpose of System Performance Check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

### 8.2 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave which comes from a signal generator at frequency 2450 MHz . The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:


Fig. 8.1 System Setup for System Evaluation

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. 2450 MHz Dipole

The output power on dipole port must be calibrated to $100 \mathrm{~mW}(20 \mathrm{dBm})$ before dipole is connected.


Fig 8.2 Dipole Setup

### 8.3 Validation Results

Comparing to the original SAR value provided by SPEAG, the validation data should within its specification of $10 \%$. Table 8.1 shows the target SAR and measured SAR after normalized to 1 W input power.

| Frequency | SAR | Target <br> $(\mathbf{W} / \mathbf{k g})$ | Measurement data <br> $(\mathbf{W} / \mathbf{k g})$ | Variation | Measurement <br> date |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 2450 MHz | SAR (1g) | 52.5 | 51.1 | $-2.7 \%$ | Aug. 08,2008 |
|  | SAR $(10 \mathrm{~g})$ | 24.4 | 24.6 | $0.8 \%$ |  |
| 2450 MHz | SAR $(1 \mathrm{~g})$ | 52.5 | 54.7 | $4.2 \%$ | Aug. 26, 2008 |
|  | SAR $(10 \mathrm{~g})$ | 24.4 | 26.1 | $7.0 \%$ |  |

Table 8.1 Target and Measured SAR after Normalized
The table above indicates the system performance check can meet the variation criterion.

## 9. Description for DUT Testing Position

This DUT was tested in one position. It is "Laptop Bottom with 0cm Gap".
Remark: Please refer to Appendix E for the test setup photos.

## 10. Measurement Procedures

The measurement procedures are as follows:
> Using engineering software to transmit RF power continuously (continuous Tx)
$>$ Placing the DUT in the positions described in the last section
$>$ Setting scan area, grid size and other setting on the DASY5 software
> Taking data for the low channel
$>$ Repeat the previous steps for the middle and high channels.
According to the IEEE P1528 draft standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:
$>$ Power reference measurement
$>$ Area scan
> Zoom scan
$>$ Power reference measurement

### 10.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1528-2003 standard. It can be conducted for 1 g and 10 g , as well as for user-specific masses. The DASY5 software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

Base on the Draft: SCC-34, SC-2, WG-2-Computational Dosimetry, P1528/D1.2 (Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques), a new algorithm has been implemented. The spatial-peak SAR can be computed over any required mass.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1 g and 10 g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1 g and 10 g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- extraction of the measured data (grid and values) from the Zoom Scan
- calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- generation of a high-resolution mesh within the measured volume
- interpolation of all measured values form the measurement grid to the high-resolution grid
- extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- calculation of the averaged SAR within masses of 1 g and 10 g


### 10.2 Scan Procedures

First Area Scan is used to locate the approximate location(s) of the local peak SAR value(s). The measurement grid within an Area Scan is defined by the grid extent, grid step size and grid offset. Next, in order to determine the EM field distribution in a three-dimensional spatial extension, Zoom Scan is required. The Zoom Scan measures $5 \times 5 \times 7$ points with step size 8,8 and 5 mm . The Zoom Scan is performed around the highest E-field value to determine the averaged SAR-distribution over 1 g .

### 10.3 SAR Averaged Methods

In DASY5, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within $1 \%$ for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm .

## 11.SAR Test Results

### 11.1 Conducted Power

<802.11b>

| Channel | Frequency <br> (MHz) | Conducted Power <br> (dBm) |
| :---: | :---: | :---: |
| CH 01 | 2412 MHz | 16.74 dBm |
| CH 06 | 2437 MHz | 17.79 dBm |
| CH 11 | 2462 MHz | 18.20 dBm |

$<802.11 \mathrm{~g}>$

| Channel | Frequency <br> (MHz) | Conducted Power <br> (dBm) |
| :---: | :---: | :---: |
| CH 01 | 2412 MHz | 13.94 dBm |
| CH 06 | 2437 MHz | 14.88 dBm |
| CH 11 | 2462 MHz | 15.27 dBm |

### 11.2 Laptop Bottom with 0cm Gap

| Antenna | Band | Chan. | Frequency (MHz) | Modulation Type | $\begin{gathered} \hline \text { Measured } \\ \text { 1g SAR } \\ \text { (W/kg) } \end{gathered}$ | Power Drift | Limit (W/kg) | Result |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Main | 802.11 b | 6 | 2437 | CCK | 0.025 | 0.000557 | 1.6 | Pass |
|  | 802.11 g | 6 | 2437 | OFDM | 0.017 | -0.00903 | 1.6 | Pass |
|  | 802.11b | 1 | 2412 | CCK | 0.03 | 0.124 | 1.6 | Pass |
|  | 802.11 b | 11 | 2462 | CCK | 0.028 | 0.133 | 1.6 | Pass |
| Aux. | 802.11 b | 6 | 2437 | CCK | 0.012 | 0.102 | 1.6 | Pass |
|  | 802.11 g | 6 | 2437 | OFDM | 0.014 | 0.131 | 1.6 | Pass |
|  | 802.11 g | 1 | 2412 | OFDM | 0.012 | 0.124 | 1.6 | Pass |
|  | 802.11 g | 11 | 2462 | OFDM | 0.013 | 0.12 | 1.6 | Pass |

Test Engineer : $\underline{\text { A-Rod Chen }}$

## 12. Reference

[1] FCC 47 CFR Part 2 "Frequency Allocations and Radio Treaty Matters; General Rules and Regulations"
[2] IEEE Std. P1528-2003, "Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", April 21, 2003.
[3] Supplement C (Edition 01-01) to OET Bulletin 65 (Edition 97-01), "Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to RF Emissions", June 2001
[4] IEEE Std. C95.3-2002, "IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields-RF and Microwave", 2002
[5] IEEE Std. C95.1-1999, "IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz", 1999
[6] Robert J. Renka, "Multivariate Interpolation Of Large Sets Of Scattered Data", University of North Texas ACM Transactions on Mathematical Software, vol. 14, no. 2, June 1988, pp. 139-148
[7] KDB 248227 r1.2, "SAR Measurement Procedures for 802.11abg Transmitters"
[8] KDB 616217 D01 v01, "SAR for Laptop with Screen Ant"
[9] DASY5 System Handbook

## Appendix A - System Performance Check Data

Test Laboratory: Sporton International Inc. SAR/HAC Testing Lab
Date: 2008/8/8
System Check_Body_2450MHz

## DUT: Dipole 2450 MHz

Communication System: CW; Frequency: 2450 MHz ;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: $\mathrm{f}=2450 \mathrm{MHz} ; \sigma=1.93 \mathrm{mho} / \mathrm{m} ; \varepsilon_{\mathrm{r}}=53.8 ; \rho=1000 \mathrm{~kg} / \mathrm{m}^{3}$ Ambient Temperature : $22.5^{\circ} \mathrm{C}$; Liquid Temperature : $21.4^{\circ} \mathrm{C}$

DASY5 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.17, 4.17, 4.17); Calibrated: 2007/9/26
- Sensor-Surface: 4 mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2007/11/16
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1029
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

Pin $=100 \mathrm{~mW} /$ Area Scan ( 91 x 91 x 1 ): Measurement grid: $\mathrm{dx}=10 \mathrm{~mm}, \mathrm{dy}=10 \mathrm{~mm}$ Maximum value of SAR (interpolated) $=5.95 \mathrm{~mW} / \mathrm{g}$

Pin $=100 \mathrm{~mW} /$ Zoom Scan ( $7 \times 7 \times 7$ )/Cube 0: Measurement grid: $\mathrm{dx}=5 \mathrm{~mm}, \mathrm{dy}=5 \mathrm{~mm}, \mathrm{dz}=5 \mathrm{~mm}$ Reference Value $=57.5 \mathrm{~V} / \mathrm{m}$; Power Drift $=0.00664 \mathrm{~dB}$ Peak SAR $($ extrapolated $)=10.2 \mathrm{~W} / \mathrm{kg}$ $\operatorname{SAR}(1 \mathrm{~g})=5.11 \mathrm{~mW} / \mathrm{g} ; \operatorname{SAR}(10 \mathrm{~g})=2.46 \mathrm{~mW} / \mathrm{g}$ Maximum value of SAR (measured) $=5.82 \mathrm{~mW} / \mathrm{g}$


Test Laboratory: Sporton International Inc. SAR/HAC Testing Lab
Date: 2008/8/26

System Check_Body_2450MHz

## DUT: Dipole 2450 MHz

Communication System: CW; Frequency: 2450 MHz ;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: $\mathrm{f}=2450 \mathrm{MHz} ; \sigma=1.97 \mathrm{mho} / \mathrm{m} ; \varepsilon_{\mathrm{r}}=53.2 ; \rho=1000 \mathrm{~kg} / \mathrm{m}^{3}$
Ambient Temperature : $22.4^{\circ} \mathrm{C}$; Liquid Temperature : $21.5^{\circ} \mathrm{C}$

DASY4 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.17, 4.17, 4.17); Calibrated: 2007/9/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2007/11/16
- Phantom: ELI 4.0_Front; Type: QDOVA001BB; Serial: 1026
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

Pin=100mWIArea Scan (91x91x1): Measurement grid: $d x=10 \mathrm{~mm}, d y=10 \mathrm{~mm}$ Maximum value of SAR (interpolated) $=6.41 \mathrm{~mW} / \mathrm{g}$

Pin=100mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $\mathrm{dx}=5 \mathrm{~mm}, \mathrm{dy}=5 \mathrm{~mm}, \mathrm{dz}=5 \mathrm{~mm}$
Reference Value $=57.1 \mathrm{~V} / \mathrm{m}$; Power Drift $=0.088 \mathrm{~dB}$
Peak SAR (extrapolated) $=11.0 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=5.47 \mathrm{~mW} / \mathrm{g} ; \operatorname{SAR}(\mathbf{1 0} \mathrm{g})=2.61 \mathrm{~mW} / \mathrm{g}$
Maximum value of SAR $($ measured $)=6.22 \mathrm{~mW} / \mathrm{g}$


## Appendix B - SAR Measurement Data

Test Laboratory: Sporton International Inc. SAR/HAC Testing Lab
Body_802.11b Chl_Bottom with 0cm Gap_MS-6877
DUT: 872111
Communication System: 802.11 b ; Frequency: 2412 MHz ;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: $\mathrm{f}=2412 \mathrm{MHz} ; \sigma=1.89 \mathrm{mho} / \mathrm{m} ; \varepsilon_{\mathrm{r}}=54 ; \rho=1000 \mathrm{~kg} / \mathrm{m}^{3}$ Ambient Temperature : $22.5^{\circ} \mathrm{C}$; Liquid Temperature : $21.4^{\circ} \mathrm{C}$

DASY5 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.17, 4.17, 4.17); Calibrated: 2007/9/26
- Sensor-Surface: 4 mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2007/11/16
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1029
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

Ch1/Area Scan (101x91x1): Measurement grid: $\mathrm{dx}=15 \mathrm{~mm}, \mathrm{dy}=15 \mathrm{~mm}$
Maximum value of SAR (interpolated) $=0.039 \mathrm{~mW} / \mathrm{g}$
Ch1/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $\mathrm{dx}=8 \mathrm{~mm}, \mathrm{dy}=8 \mathrm{~mm}, \mathrm{dz}=5 \mathrm{~mm}$
Reference Value $=2.41 \mathrm{~V} / \mathrm{m}$; Power Drift $=0.124 \mathrm{~dB}$
Peak SAR (extrapolated) $=0.051 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=0.030 \mathrm{~mW} / \mathrm{g} ; \operatorname{SAR}(10 \mathrm{~g})=0.018 \mathrm{~mW} / \mathrm{g}$
Maximum value of SAR (measured) $=0.048 \mathrm{~mW} / \mathrm{g}$
Ch1/Zoom Scan (5x5x7)/Cube 1: Measurement grid: $\mathrm{dx}=8 \mathrm{~mm}, \mathrm{dy}=8 \mathrm{~mm}, \mathrm{dz}=5 \mathrm{~mm}$
Reference Value $=2.41 \mathrm{~V} / \mathrm{m}$; Power Drift $=0.124 \mathrm{~dB}$
Peak SAR (extrapolated) $=0.038 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=0.028 \mathrm{~mW} / \mathrm{g} ; \operatorname{SAR}(10 \mathrm{~g})=0.021 \mathrm{~mW} / \mathrm{g}$
Maximum value of SAR (measured) $=0.030 \mathrm{~mW} / \mathrm{g}$


Body_802.11b Chl_Bottom with 0cm Gap_MS-6877_2D
DUT: 872111
Communication System: 802.11 b ; Frequency: 2412 MHz ;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: $\mathrm{f}=2412 \mathrm{MHz} ; \sigma=1.89 \mathrm{mho} / \mathrm{m} ; \varepsilon_{\mathrm{r}}=54 ; \rho=1000 \mathrm{~kg} / \mathrm{m}^{3}$ Ambient Temperature : $22.5^{\circ} \mathrm{C}$; Liquid Temperature : $21.4^{\circ} \mathrm{C}$

DASY5 Configuration:

- Probe: ET3DV6 - SN1788; ConvF(4.17, 4.17, 4.17); Calibrated: 2007/9/26
- Sensor-Surface: 4 mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 2007/11/16
- Phantom: ELI 4.0; Type: QDOVA001BA; Serial: 1029
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

Ch1/Area Scan (101x91x1): Measurement grid: $\mathrm{dx}=15 \mathrm{~mm}, \mathrm{dy}=15 \mathrm{~mm}$
Maximum value of SAR (interpolated) $=0.039 \mathrm{~mW} / \mathrm{g}$
Ch1/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $\mathrm{dx}=8 \mathrm{~mm}, \mathrm{dy}=8 \mathrm{~mm}, \mathrm{dz}=5 \mathrm{~mm}$
Reference Value $=2.41 \mathrm{~V} / \mathrm{m}$; Power Drift $=0.124 \mathrm{~dB}$
Peak SAR (extrapolated) $=0.051 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=0.030 \mathrm{~mW} / \mathrm{g} ; \operatorname{SAR}(10 \mathrm{~g})=0.018 \mathrm{~mW} / \mathrm{g}$
Maximum value of SAR (measured) $=0.048 \mathrm{~mW} / \mathrm{g}$
Ch1/Zoom Scan (5x5x7)/Cube 1: Measurement grid: $\mathrm{dx}=8 \mathrm{~mm}, \mathrm{dy}=8 \mathrm{~mm}, \mathrm{dz}=5 \mathrm{~mm}$
Reference Value $=2.41 \mathrm{~V} / \mathrm{m}$; Power Drift $=0.124 \mathrm{~dB}$
Peak SAR (extrapolated) $=0.038 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=0.028 \mathrm{~mW} / \mathrm{g} ; \operatorname{SAR}(10 \mathrm{~g})=0.021 \mathrm{~mW} / \mathrm{g}$
Maximum value of SAR (measured) $=0.030 \mathrm{~mW} / \mathrm{g}$


## Appendix C - Calibration Data

## Calibration Laboratory of

Schmid \& Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland


\section*{Calibration Laboratory of <br> Schmid \& Partner <br> Engineering AG <br> Zeughausstrasse 43, 8004 Zurich, Switzerland <br>  <br> S Schweizerischer Kalibrierdienst <br> C Service suisse d'étalonnage <br> C Servizio svizzero di taratur <br> S Swiss Calibration Service <br> Accredited by the Swiss Federal Office of Metrology and Accreditation <br> Glossary: <br> | TSL | tissue simulating liquid |
| :--- | :--- |
| ConvF | sensitivity in TSL / NORM $x, y, z$ | <br> N/A not applicable or not measured}

Calibration is Performed According to the Following Standards:
a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak SpatialAveraged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz ), February 2005
c) Federal Communications Commission Office of Engineering \& Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

## Additional Documentation:

d) DASY4 System Handbook

## Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.


## Measurement Conditions

DASY system configuration, as far as not given on page 1.

| DASY Version | DASY4 | V4.7 |
| :--- | :---: | :---: |
| Extrapolation | Advanced Extrapolation |  |
| Phantom | Modular Flat Phantom V5.0 |  |
| Distance Dipole Center - TSL | 10 mm | with Spacer |
| Zoom Scan Resolution | $\mathrm{dx}, \mathrm{dy}, \mathrm{dz}=5 \mathrm{~mm}$ |  |
| Frequency | $2450 \mathrm{MHz} \pm 1 \mathrm{MHz}$ |  |

## Head TSL parameters

The following parameters and calculations were applied

|  | Temperature | Permittivity | Conductivity |
| :--- | :---: | :---: | :---: |
| Nominal Head TSL parameters | $22.0^{\circ} \mathrm{C}$ | 39.2 | $1.80 \mathrm{mho} / \mathrm{m}$ |
| Measured Head TSL parameters | $(22.0 \pm 0.2)^{\circ} \mathrm{C}$ | $38.6 \pm 6 \%$ | $1.81 \mathrm{mho} / \mathrm{m} \pm 6 \%$ |
| Head TSL temperature during test | $(22.0 \pm 0.2)^{\circ} \mathrm{C}$ | - | -- |

SAR result with Head TSL

| SAR averaged over $\mathbf{1} \mathbf{~ c m}^{\mathbf{3}} \mathbf{( 1 \mathbf { g } ) \text { of Head TSL }}$ | condition |  |
| :--- | :---: | :---: |
| SAR measured | 250 mW input power | $13.3 \mathrm{~mW} / \mathrm{g}$ |
| SAR normalized | normalized to 1W | $53.2 \mathrm{~mW} / \mathrm{g}$ |
| SAR for nominal Head TSL parameters ${ }^{1}$ | normalized to 1 W | $\mathbf{5 2 . 7} \mathbf{~ m W} / \mathrm{g} \pm \mathbf{1 7 . 0} \%(\mathbf{k}=\mathbf{2})$ |


| SAR averaged over $\left.\mathbf{1 0} \mathbf{c m}^{\mathbf{3}} \mathbf{( 1 0 ~ g}\right)$ of Head TSL | condition |  |
| :--- | :---: | :---: |
| SAR measured | 250 mW input power | $6.17 \mathrm{~mW} / \mathrm{g}$ |
| SAR normalized | normalized to 1 W | $24.7 \mathrm{~mW} / \mathrm{g}$ |
| SAR for nominal Head TSL parameters ${ }^{1}$ | normalized to 1 W | $\mathbf{2 4 . 5 \mathrm { mW } / \mathbf { g } \pm \mathbf { 1 6 . 5 } \% ( \mathbf { k } = \mathbf { 2 } )}$ |

[^0]Body TSL parameters
The following parameters and calculations were applied.

|  | Temperature | Permittivity | Conductivity |
| :--- | :---: | :---: | :---: |
| Nominal Body TSL parameters | $22.0^{\circ} \mathrm{C}$ | 52.7 | $1.95 \mathrm{mho} / \mathrm{m}$ |
| Measured Body TSL parameters | $(22.0 \pm 0.2)^{\circ} \mathrm{C}$ | $53.5 \pm 6 \%$ | $1.94 \mathrm{mho} / \mathrm{m} \pm 6 \%$ |
| Body TSL temperature during test | $(22.0 \pm 0.2)^{\circ} \mathrm{C}$ | --- | -- |

## SAR result with Body TSL

| SAR averaged over $\mathbf{1} \mathrm{cm}^{\mathbf{3}} \mathbf{( 1 \mathbf { g } ) \text { of Body TSL }}$ | Condition |  |
| :--- | :---: | :---: |
| SAR measured | 250 mW input power | $13.0 \mathrm{~mW} / \mathrm{g}$ |
| SAR normalized | normalized to 1 W | $52.0 \mathrm{~mW} / \mathrm{g}$ |
| SAR for nominal Body TSL parameters ${ }^{2}$ | normalized to 1 W | $\mathbf{5 2 . 5} \mathbf{~ m W} / \mathrm{g} \pm \mathbf{1 7 . 0} \%(\mathbf{k}=\mathbf{2})$ |


| SAR averaged over $10 \mathrm{~cm}^{\mathbf{3}}(\mathbf{1 0} \mathrm{g})$ of Body TSL | Condition |  |
| :--- | :---: | :---: |
| SAR measured | 250 mW input power | $6.05 \mathrm{~mW} / \mathrm{g}$ |
| SAR normalized | normalized to 1 W | $24.2 \mathrm{~mW} / \mathrm{g}$ |
| SAR for nominal Body TSL parameters $^{2}$ | normalized to 1 W | $\mathbf{2 4 . 4} \mathbf{~ m W} / \mathrm{g} \pm \mathbf{1 6 . 5} \%$ (k=2) |

[^1]
## Appendix

## Antenna Parameters with Head TSL

| Impedance, transformed to feed point | $53.1 \Omega+3.0 \mathrm{j} \Omega$ |
| :--- | :---: |
| Return Loss | -27.6 dB |

## Antenna Parameters with Body TSL

| Impedance, transformed to feed point | $48.7 \Omega+4.6 \mathrm{j} \Omega$ |
| :--- | :---: |
| Return Loss | -26.3 dB |

## General Antenna Parameters and Design

| Electrical Delay (one direction) | 1.158 ns |
| :--- | :--- |

After long term use with 100 W radiated power, only a slight warming of the dipole near the feedpoint can be measured.
The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.
No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

## Additional EUT Data

| Manufactured by | SPEAG |
| :--- | :---: |
| Manufactured on | August 26, 2003 |

## DASY4 Validation Report for Head TSL

## Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz ; Type: D2450V2; Serial: D2450V2 - SN736
Communication System: CW-2450; Frequency: 2450 MHz ; Duty Cycle: 1:1
Medium: HSL U10 BB;
Medium parameters used: $\mathrm{f}=2450 \mathrm{MHz} ; \sigma=1.81 \mathrm{mho} / \mathrm{m} ; \varepsilon_{\mathrm{r}}=38.6 ; \rho=1000 \mathrm{~kg} / \mathrm{m}^{3}$
Phantom section: Flat Section
Measurement Standard: DASY4 (High Precision Assessment)
DASY4 Configuration:

- Probe: ES3DV2 - SN3025 (HF); ConvF(4.5, 4.5, 4.5); Calibrated: 19.10.2006
- Sensor-Surface: 4 mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 30.01.2007
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Pin $=\mathbf{2 5 0} \mathbf{m W} ; \mathbf{d}=\mathbf{1 0} \mathbf{m m} /$ Zoom Scan ( $7 \times 7 \times 7$ )/Cube 0:
Measurement grid: $\mathrm{dx}=5 \mathrm{~mm}, \mathrm{dy}=5 \mathrm{~mm}, \mathrm{dz}=5 \mathrm{~mm}$
Reference Value $=93.0 \mathrm{~V} / \mathrm{m}$; Power Drift $=-0.004 \mathrm{~dB}$
Peak SAR (extrapolated) $=28.1 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=13.3 \mathrm{~mW} / \mathrm{g} ; \operatorname{SAR}(10 \mathrm{~g})=6.17 \mathrm{~mW} / \mathrm{g}$
Maximum value of SAR (measured) $=15.0 \mathrm{~mW} / \mathrm{g}$


## Impedance Measurement Plot for Head TSL



## DASY4 Validation Report for Body TSL

Date/Time: 12.07.2007 12:28:49
Test Laboratory: SPEAG, Zurich, Switzerland
DUT: Dipole 2450 MHz ; Type: D2450V2; Serial: D2450V2 - SN736
Communication System: CW-2450; Frequency: 2450 MHz ; Duty Cycle: 1:1
Medium: MSL U10 BB;
Medium parameters used: $\mathrm{f}=2450 \mathrm{MHz} ; \sigma=1.94 \mathrm{mho} / \mathrm{m} ; \varepsilon_{\mathrm{r}}=53.5 ; \rho=1000 \mathrm{~kg} / \mathrm{m}^{3}$
Phantom section: Flat Section
Measurement Standard: DASY4 (High Precision Assessment)
DASY4 Configuration:

- Probe: ES3DV2 - SN3025 (HF); ConvF(4. 16, 4.16, 4.16); Calibrated: 19.10.2006
- Sensor-Surface: 4 mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 30.01.2007
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Pin $=250 \mathrm{~mW} ; \mathbf{d}=10 \mathrm{~mm} /$ Zoom Scan ( $7 \times 7 \times 7$ )/Cube 0:
Measurement grid: $\mathrm{dx}=5 \mathrm{~mm}, \mathrm{dy}=5 \mathrm{~mm}, \mathrm{dz}=5 \mathrm{~mm}$
Reference Value $=88.6 \mathrm{~V} / \mathrm{m}$; Power Drift $=0.005 \mathrm{~dB}$
Peak SAR $($ extrapolated $)=27.0 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=13 \mathrm{~mW} / \mathrm{g} ; \operatorname{SAR}(10 \mathrm{~g})=6.05 \mathrm{~mW} / \mathrm{g}$
Maximum value of SAR (measured) $=14.8 \mathrm{~mW} / \mathrm{g}$


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## Impedance Measurement Plot for Body TSL



## Calibration Laboratory of <br> Schmid \& Partner <br> Engineering AG <br> Zeughausstrasse 43, 8004 Zurich, Switzerland


S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage Servizio svizzero di taratura S Swiss Calibration Service

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Accreditation No.: SCS 108
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates
Client Sporton (Auden) Certificate No: DAE3-577_Nov07

## CALIBRATION CERTIFICATE

| Object | DAE3 - SD 000 D03 AA - SN: 577 |  |  |
| :---: | :---: | :---: | :---: |
| Calibration procedure(s) | QA CAL-06.v12 <br> Calibration procedure for the data acquisition electronics (DAE) |  |  |
| Calibration date: | November 16, 2007 |  |  |
| Condition of the calibrated itern | In Tolerance |  |  |
| This caibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. |  |  |  |
| All calicrations have been conducted in the closed laboratory facility: environment temperature ( $22 \pm 3)^{\circ} \mathrm{C}$ and humidity $<70 \%$. |  |  |  |
| Calibration Equipment used (M\&TE critical for calibraton) |  |  |  |
| Primary Standards | ID \# | Cal Date (Callibrated by, Certificate No.) | Scheduled Calibration |
| Fluke Process Calibrator Type 702 | SN: 6295803 | 04-Oct-07 (Elcal AG, No: 6467) | Oct-08 |
| Keithley Multimeter Type 2001 | SN: 0810278 | 03-Oct-07 (Elcal AG, No: 6465) | Oct-08 |
| Secondary Standards | 10\# | Check Date (in house) | Scheduled Check |
| Calibrator Box V1.1 | SE UMS 006 AB 1004 | 25-Jun-07 (SPEAG, in house check) | In house check Jun-08 |



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## Glossary

DAE
Connector angle
data acquisition electronics information used in DASY system to align probe sensor X to the robot coordinate system.

## Methods Applied and Interpretation of Parameters

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
- DC Voltage Measurement Linearity: Verification of the Linearity at $+10 \%$ and $-10 \%$ of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
- Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
- Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
- AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
- Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
- Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
- Input resistance: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
- Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
- Power consumption: Typical value for information. Supply currents in various operating modes.


## DC Voltage Measurement

A/D - Converter Resolution nominal

| High Range: | $1 \mathrm{LSB}=$ | $6.1 \mu \mathrm{~V}$, | full range $=$ |
| :--- | :--- | :--- | :--- |
| Low Range: | $1 \mathrm{LSB}=$ | 61 nV, | full range $=$ |
|  | $-1 \ldots \ldots+300 \mathrm{mV}$ |  |  |
|  | $1 \ldots \mathrm{mV}$ |  |  |

DASY measurement parameters: Auto Zero Time: 3 sec ; Measuring time: 3 sec

| Calibration Factors | $\mathbf{X}$ | $\mathbf{Y}$ | $\mathbf{Z}$ |
| :--- | :---: | :---: | :---: |
| High Range | $404.432 \pm 0.1 \%(\mathrm{k}=2)$ | $403.884 \pm 0.1 \%(\mathrm{k}=2)$ | $404.331 \pm 0.1 \%(\mathrm{k}=2)$ |
| Low Range | $3.94218 \pm 0.7 \%(\mathrm{k}=2)$ | $3.94771 \pm 0.7 \%(\mathrm{k}=2)$ | $3.94526 \pm 0.7 \%(\mathrm{k}=2)$ |

## Connector Angle

| Connector Angle to be used in DASY system | $268^{\circ} \pm 1^{\circ}$ |
| :--- | :---: |

## Appendix

1. DC Voltage Linearity

| High Range | Input $(\mu \mathbf{V})$ | Reading $(\mu \mathbf{V})$ | Error (\%) |  |
| :--- | :--- | :---: | :---: | :---: |
| Channel X | + Input | 200000 | 199999.3 | 0.00 |
| Channel X | + Input | 20000 | 20005.75 | 0.03 |
| Channel X | - Input | 20000 | -19997.67 | -0.01 |
| Channel Y | + Input | 200000 | 199999.5 | 0.00 |
| Channel Y | + Input | 20000 | 20002.82 | 0.01 |
| Channel Y | - Input | 20000 | -20004.40 | 0.02 |
| Channel Z | + Input | 200000 | 199999.6 | 0.00 |
| Channel Z | + Input | 20000 | 20005.54 | 0.03 |
| Channel Z | - Input | 20000 | -20001.11 | 0.01 |


| Low Range | Input $(\mu \mathbf{V})$ | Reading $(\mu \mathbf{V})$ | Error (\%) |  |
| :--- | :--- | :---: | :---: | :---: |
| Channel X | + Input | 2000 | 2000.1 | 0.00 |
| Channel X | + Input | 200 | 199.12 | -0.44 |
| Channel X | - Input | 200 | -200.64 | 0.32 |
| Channel Y | + Input | 2000 | 2000 | 0.00 |
| Channel Y | + Input | 200 | 199.96 | -0.02 |
| Channel Y | - Input | 200 | -201.00 | 0.50 |
| Channel Z | + Input | 2000 | 1999.9 | 0.00 |
| Channel Z | + Input | 200 | 199.05 | -0.47 |
| Channel Z | - Input | 200 | -201.08 | 0.54 |

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec ; Measuring time: 3 sec

|  | Common mode <br> Input Voltage $(\mathrm{mV})$ | High Range <br> Average Reading $(\mu \mathrm{V})$ | Low Range <br> Average Reading $(\mu \mathrm{V})$ |
| :--- | :---: | :---: | :---: |
| Channel X | 200 | 13.88 | 12.97 |
|  | -200 | -12.40 | -14.29 |
| Channel $\mathbf{Y}$ | 200 | -6.32 | -6.22 |
|  | -200 | 5.34 | 5.31 |
| Channel Z | 200 | 1.08 | 0.59 |
|  | -200 | -1.42 | -1.66 |

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec ; Measuring time: 3 sec

|  | Input Voltage $(\mathbf{m V})$ | Channel $\mathbf{X}(\mu \mathbf{V})$ | Channel $\mathbf{Y}(\mu \mathbf{V})$ | Channel $\mathbf{Z}(\mu \mathbf{V})$ |
| :--- | :---: | :---: | :---: | :---: |
| Channel X | 200 | - | 1.14 | 0.16 |
| Channel $\mathbf{Y}$ | 200 | 1.52 | - | 3.87 |
| Channel Z | 200 | 0.23 | 0.75 | - |

## 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

|  | High Range (LSB) | Low Range (LSB) |
| :--- | :---: | :---: |
| Channel X | 15969 | 16269 |
| Channel Y | 15848 | 16148 |
| Channel Z | 16203 | 16661 |

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec ; Measuring time: 3 sec

| Input $10 \mathrm{M} \Omega$ | Average $(\mu \mathrm{V})$ | min. Offset $(\mu \mathrm{V})$ | max. Offset $(\mu \mathrm{V})$ | Std. Deviation <br> $(\mu \mathrm{V})$ |
| :--- | :---: | :---: | :---: | :---: |
| Channel X | 0.12 | -1.70 | 1.72 | 0.50 |
| Channel Y | -2.46 | -3.42 | -1.39 | 0.44 |
| Channel $Z$ | -0.78 | -2.16 | 0.00 | 0.29 |

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA
7. Input Resistance

|  | Zeroing (MOhm) | Measuring (MOhm) |
| :--- | :---: | :---: |
| Channel X | 0.2000 | 199.3 |
| Channel Y | 0.2001 | 199.9 |
| Channel Z | 0.1999 | 199.4 |

8. Low Battery Alarm Voltage (verified during pre test)

| Typical values | Alarm Level (VDC) |  |
| :--- | :---: | :---: |
| Supply (+ Vcc) |  | +7.9 |
| Supply (- Vcc) |  | -7.6 |

9. Power Consumption (verified during pre test)

| Typical values | Switched off (mA) | Stand by (mA) | Transmitting (mA) |
| :--- | :---: | :---: | :---: |
| Supply (+ Vcc) | +0.0 | +6 | +14 |
| Supply (- Vcc) | -0.01 | -8 | -9 |



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Client Sporton (Auden) Certificate No: ET3-1788_Sep07

## CALIBRATION CERTIFICATE



[^2]Page 1 of 9


## Glossary:

TSL tissue simulating liquid
NORMx,y,z sensitivity in free space
ConF sensitivity in TSL / NORMx,y,z
DCP diode compression point
Polarization $\varphi \quad \varphi$ rotation around probe axis
Polarization $\vartheta \quad \vartheta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta=0$ is normal to probe axis

## Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak SpatialAveraged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz )", February 2005

## Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization $\vartheta=0$ ( $f \leq 900 \mathrm{MHz}$ in TEM-cell; $f>1800 \mathrm{MHz}$ : R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORM $x, y, z$ does not effect the $E^{2}$-field uncertainty inside TSL (see below ConvF).
- $\operatorname{NORM}(f) x, y, z=N O R M x, y, z *$ frequency_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $\mathrm{f} \leq 800 \mathrm{MHz}$ ) and inside waveguide using analytical field distributions based on power measurements for $f>800 \mathrm{MHz}$. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from $\pm 50 \mathrm{MHz}$ to $\pm 100 \mathrm{MHz}$.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.


# Probe ET3DV6 

## SN:1788

| Manufactured: | May 28,2003 |
| :--- | :--- |
| Last calibrated: | September 19, 2006 |
| Modified: | September 24, 2007 |
| Recalibrated: | September 26, 2007 |

Calibrated for DASY Systems
(Note: non-compatible with DASY2 system!)

## DASY - Parameters of Probe: ET3DV6 SN:1788

| Sensitivity in Free Space ${ }^{\text {A }}$ |  |  |  | Diode Compression ${ }^{\text {B }}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | NormX | $1.72 \pm 10.1 \%$ | $\mu \mathrm{V} /(\mathrm{V} / \mathrm{m})^{2}$ | DCP X | 91 mV |
|  | NormY | $1.66 \pm 10.1 \%$ | $\mu \mathrm{V} /(\mathrm{V} / \mathrm{m})^{2}$ | DCP Y | 93 mV |
|  | NormZ | $1.70 \pm 10.1 \%$ | $\mu \mathrm{V} /(\mathrm{V} / \mathrm{m})^{2}$ | DCP Z | 94 mV |
| Sensitivity in Tissue Simulating Liquid (Conversion Factors) |  |  |  |  |  |
| Please see Page 8. |  |  |  |  |  |
| Boundary Effect |  |  |  |  |  |
| TSL | 900 MHz Typical SAR gradient: $5 \%$ per mm |  |  |  |  |
|  | Sensor Center to Phantom Surface Distance |  |  | 3.7 mm 4.7 mm |  |
|  | SAR ${ }_{\text {be }}[\%]$ | Without Correction Algorithm |  | 6.2 | 3.3 |
|  | SAR $\mathrm{bb}^{\text {a }}$ [\%] | With Correction Algorithm |  | 0.4 | 1.0 |
| TSL | 1810 MHz Typical S |  | gradient: 10 |  |  |
|  | Sensor Center to Phantom Surface Distance |  |  | 3.7 mm | 4.7 mm |
|  | SAR ${ }_{\text {bg }}[\%]$$S A R_{\text {bg }}[\%]$ | Without Correction Algorithm |  | 12.0 | 8.1 |
|  |  | With Correction Algorithm |  | 0.2 | 0.1 |
| Sensor Offset |  |  |  |  |  |
| Probe Tip to Sensor Center |  |  | 2.7 mm |  |  |

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $\mathbf{k}=2$, which for a normal distribution corresponds to a coverage probability of approximately $95 \%$.

[^3]
## Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)


Receiving Pattern $(\phi), \vartheta=\mathbf{0}^{\circ}$




Uncertainty of Axial Isotropy Assessment: $\pm 0.5 \%(k=2)$

## Dynamic Range $f\left(S_{\text {head }}\right)$ <br> (Waveguide R22, $\mathrm{f}=1800 \mathrm{MHz}$ )




Uncertainty of Linearity Assessment: $\mathbf{\pm 0 . 6 \%}$ ( $\mathbf{k}=\mathbf{2}$ )

## Conversion Factor Assessment




| $f[\mathrm{MHz}]$ | ${\text { Validity }[\mathrm{MHz}]^{\mathrm{C}}}$ | TSL | Permittivity | Conductivity | Alpha | Depth | ConvF Uncertainty |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 900 | $\pm 50 / \pm 100$ | Head | $41.5 \pm 5 \%$ | $0.97 \pm 5 \%$ | 0.22 | 3.28 | $6.54 \pm 11.0 \%(\mathrm{k}=2)$ |
| 1810 | $\pm 50 / \pm 100$ | Head | $40.0 \pm 5 \%$ | $1.40 \pm 5 \%$ | 0.59 | 2.15 | $5.28 \pm 11.0 \%(\mathrm{k}=2)$ |
| 2000 | $\pm 50 / \pm 100$ | Head | $40.0 \pm 5 \%$ | $1.40 \pm 5 \%$ | 0.60 | 2.23 | $4.87 \pm 11.0 \%(\mathrm{k}=2)$ |
| 2450 | $\pm 50 / \pm 100$ | Head | $39.2 \pm 5 \%$ | $1.80 \pm 5 \%$ | 0.61 | 2.39 | $4.58 \pm 11.8 \%(\mathrm{k}=2)$ |


| 900 | $\pm 50 / \pm 100$ | Body | $55.0 \pm 5 \%$ | $1.05 \pm 5 \%$ | 0.28 | 2.94 | $6.37 \pm 11.0 \%(\mathrm{k}=2)$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 1810 | $\pm 50 / \pm 100$ | Body | $53.3 \pm 5 \%$ | $1.52 \pm 5 \%$ | 0.63 | 2.39 | $4.75 \pm 11.0 \%(\mathrm{k}=2)$ |
| 2000 | $\pm 50 / \pm 100$ | Body | $53.3 \pm 5 \%$ | $1.52 \pm 5 \%$ | 0.63 | 2.33 | $4.36 \pm 11.0 \%(\mathrm{k}=2)$ |
| 2450 | $\pm 50 / \pm 100$ | Body | $52.7 \pm 5 \%$ | $1.95 \pm 5 \%$ | 0.61 | 2.58 | $4.17 \pm 11.8 \%(\mathrm{k}=2)$ |

${ }^{\mathrm{c}}$ The validity of $\pm 100 \mathrm{MHz}$ only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

# Deviation from Isotropy in HSL 

Error $(\phi, \vartheta), \mathbf{f}=\mathbf{9 0 0} \mathbf{~ M H z}$


Uncertainty of Spherical Isotropy Assessment: $\pm \mathbf{2 . 6 \%}(\mathbf{k}=\mathbf{2})$
spoaton las. FCC SAR Test Report

## Appendix D-Product Photos

<WLAN Module>


## <Laptop Computer>


spoomon Las. FCC SAR Test Report

## Appendix E-Test Setup Photo



Laptop Bottom with 0cm Gap


[^0]:    ${ }^{1}$ Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

[^1]:    ${ }^{2}$ Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

[^2]:    Certificate No: ET3-1788_Sep07

[^3]:    ${ }^{\text {A }}$ The uncertainties of Norm $X, Y, Z$ do not affect the $E^{2}$-field uncertainty inside TSL (see Page 8)
    ${ }^{8}$ Numerical linearization parameter: uncertainty not required

