

# Test Lab Techno Corp.

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SAR EVALUATION REPORT



Test Report No.	:	0704FS11
Applicant	:	Acer Incorporated
FCC ID	:	HLZC500
Model Name	:	Travel Companion
Trade Mark	÷	Acer
Model Number	:	C500
Dates of Test	:	Mar.20-27,2007
Test Environment	:	Ambient Temperature : 22 $\pm$ 3 $^{\circ}$ C
		Relative Humidity : 40 - 70 %
Test Specification	:	Standard C95.1-1999
		IEEE Std. 1528-2003
Max. SAR	:	0.212 W/kg WLAN Body SAR(802.11b)
		0.111 W/kg WLAN Body SAR(802.11g)
FCC Rule Part(s)	:	2.1093;FCC/OET Bulletin 65 Supplement C [July 2001]
Test Lab	:	Changan Lab



results are as attached. 2. The test results are under chamber environment of A Test Lab Techno Corp. A Test Lab Techno Corp. does not assume responsibility for any conclusions and generalizations drawn from the test results with regard to other

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# 1. <u>Description of Equipment Under Test (EUT)</u>

Applicant :

Acer Incorporated

8F, 88, Sec. 1, Hsin Tai Wu Rd., Hsichih Taipei Hsien 221, Taiwan.

FCC ID	:	HLZC500
Model Name	:	Travel Companion
Trade Mark	:	Acer
Model Number	:	C500
Battery Type	:	Li-ion Battery ( 3.7V, 2600mAh)
Test Device	:	Production Unit
Tx Frequency	:	2412 -2462 MHz (WLAN )
Max. RF Conducted Power	:	0.049 W (16.86 dBm ) WLAN(802.11b)
		0.035 W (15.43 dBm ) WLAN(802.11g)
Max. SAR Measurement	:	0.212 W/kg WLAN Body SAR(802.11b)
		0.111 W/kg WLAN Body SAR(802.11g)
HW Version	:	PCB ver.E
SW Version	:	Windows Mobile v5.01
Antenna Type	:	Internal Type
Antenna Gain	:	1.16dBi
Device Category	:	Portable
RF Exposure Environment	:	General Population / Uncontrolled
Battery Option	:	Standard
Application Type	:	Certification

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment / general population exposure limits specified in Standard C95.1-1999 and had been tested in accordance with the measurement procedures specified in IEEE Std. 1528-2003.





# 2. <u>Other Accessories</u>

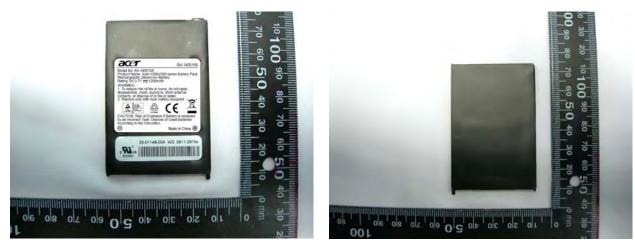


Figure 2. Lepto Battery(Li-ion 3.7V, 1250mAh)

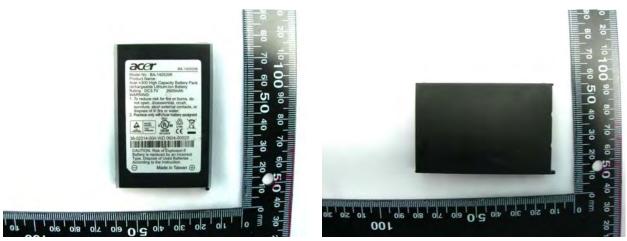


Figure 3. Thickness Battery(Li-ion 3.7V, 1250mAh)



Figure 4. Base-AC Power



# 3. <u>Introduction</u>

The A Test Lab Techno Corp. has performed measurements of the maximum potential exposure to the user of **Acer Incorporated Trade Mark : Acer Model(s) : C500**. The test procedures, as described in American National Standards, Institute C95.1 - 1999 (1), FCC/OET Bulletin 65 Supplement C [July 2001] were employed and they specify the maximum exposure limit of 1.6mW/g as averaged over any 1 gram of tissue for portable devices being used within 20cm between user and EUT in the uncontrolled environment. A description of the product and operating configuration, detailed summary of the test results, methodology and procedures used in the equipment used are included within this test report.



# 4. SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dw) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (P). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Figure 2).

$$SAR = \frac{d}{dt} \left( \frac{dw}{dm} \right) = \frac{d}{dt} \left( \frac{dw}{\rho dv} \right)$$

Figure 5. SAR Mathematical Equation

SAR is expressed in units of Watts per kilogram (W/kg)

$$SAR = \frac{\sigma E^2}{\rho}$$

Where :

 $\sigma$  = conductivity of the tissue (S/m)

 $\rho$  = mass density of the tissue (kg/m<sup>3</sup>)

*E* = RMS electric field strength (V/m)

#### \*Note :

The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane [2]



### 5. <u>SAR Measurement Setup</u>

These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9m) which positions the probes with a positional repeatability of better than  $\pm 0.025$ mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines (length = 300mm) to the data acquisition unit.

A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and remote control, is used to drive the robot motors. The Measurement Server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chipdisk and 64MB RAM. The necessary circuits for communication with either the DAE3 electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board. The PC consists of the Intel Pentium 4 2.4GHz computer with Windows2000 system and SAR Measurement Software DASY4, Post Processor SEMCAD, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection...etc. is connected to the Electro-optical converter (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the Measurement Server.

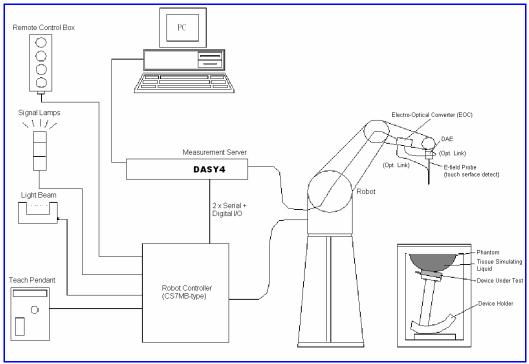


Figure 6. SAR Lab Test Measurement Setup



The DAE3 consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail in [3].



### 6. <u>System Components</u>

### 6.1 DASY4 E-Field Probe System

The SAR measurements were conducted with the dosimetric probe ET3DV6 (manufactured by SPEAG), designed in the classical triangular configuration [3] and optimized for dosimetric evaluation. The probes is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped when reaching the maximum.



### 6.1.1 EX3DV3 E-Field Probe Specification

Construction	Symmetrical design with triangular core
	Built-in optical fiber for surface detection
	System (EX3DV3 only)
	Built-in shielding against static charges
	PEEK enclosure material
	(resistant to organic solvents, e.q., glycol)
Calibration	In air from 10 MHz to 6 GHz
	In brain and muscle simulating tissue at
	frequencies of 900MHz, 1800MHz, 5200MHz
	and 5500MHz and 5800MHz (accuracy $\pm 8\%$ )
	Calibration for other liquids and frequencies upon request
Frequency	10 MHz to > 6 GHz; Linearity: $\pm 0.2 \text{ dB}$
	(30 MHz to 3 GHz)
Directivity	$\pm 0.3$ dB in brain tissue (rotation around probe axis)
	$\pm$ 0.5 dB in brain tissue (rotation normal probe axis)
Dynamic Range	10 $\mu$ W/g to > 100mW/g; Linearity: ±0.2dB
Surface Detection	$\pm 0.2$ mm repeatability in air and clear liquids
	over diffuse reflecting surface(EX3DV3 only)
Dimensions	Overall length: 330mm
	Tip length: 20mm
	Body diameter: 12mm
	Tip diameter: 2.5mm
	Distance from probe tip to dipole centers: 1.0mm
Application	General dosimetry up to 6GHz
	Compliance tests of mobile phones
	Fast automatic scanning in arbitrary phantoms



Figure 7. EX3DV3 E-field Probe



Figure 8. Probe setup on robot



### 6.1.2 EX3DV3 E-Field Probe Calibration

Each probe is calibrated according to a dosimetric assessment procedure described in [4] with accuracy better than  $\pm 10\%$ . The spherical isotropy was evaluated with the procedure described in [5] and found to be better than  $\pm 0.25$ dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1GHz, and in a wave guide above 1GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

Where :

 $\Delta t$  = Exposure time (30 seconds),

**C** = Heat capacity of tissue (head or body),

 $\Delta T$  = Temperature increase due to RF exposure.

Or 
$$SAR = \frac{|E|^2 \sigma}{\rho}$$

Where :

 $\sigma$  = Simulated tissue conductivity,

 $\rho$  = Tissue density (kg/m<sup>3</sup>).

### 6.2 Data Acquisition Electronic (DAE) System

Cell Controller	
Processor :	Intel Pentium 4
Clock Speed :	2.4GHz
Operating System :	Windows 2000 Professional
Data Converter	
Features :	Signal Amplifier, multiplexer, A/D converter, and control logic
Software :	DASY4 v4.7 (Build 53) & SEMCAD v1.8 (Build 172)
Connecting Lines :	Optical downlink for data and status info
	Optical uplink for commands and clock



### 6.3 Robot

Positioner :	Stäubli Unimation Corp. Robot Model: RX90L
Repeatability :	±0.025 mm
No. of Axis :	6

#### 6.4 Measurement Server

Processor :	PC/104 with a 166MHz low-power Pentium
I/O-board:	Link to DAE3
	16-bit A/D converter for surface detection system
	Digital I/O interface
	Serial link to robot
	Direct emergency stop output for robot

#### 6.5 Device Holder for Transmitters

In combination with the SAM Twin Phantom V4.0, the Mounting Device (POM) enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation points is the ear opening. The devices can be easily, accurately, and repeat ably positioned according to the IEEE SCC34-SC2 and CENELEC specifications. The device holder can be locked at different phantom locations (left head, right head, and flat phantom).

**\*Note**: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produced infinite number of configurations [6]. To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.

Larger DUT cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values. Therefore those devices are normally only tested at the flat part of the SAM.

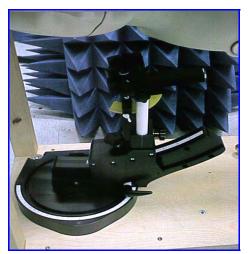


Figure 9. Device Holder



#### 6.6 Phantom - SAM v4.0

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-2003, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.



Figure 10.SAM Twin Phantom

Shell Thickness	2 ±0.2 mm		
Filling Volume	Approx. 25 liters		
Dimensions	810×1000×500 mm (H×L×W)		

Table 1. Specification of SAM v4.0

#### 6.7 Data Storage and Evaluation

#### 6.7.1 Data Storage

The DASY4 software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension .DA4. The postprocessing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.



### 6.7.2 Data Evaluation

The DASY4 post processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software :

Probe parameters :	- Sensitivity	Normi, ai0, ai1, ai2
	- Conversion factor	ConvFi
	- Diode compression point	dcpi
Device parameters :	- Frequency	f
	- Crest factor	cf
Media parameters :	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as :

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with

 $V_i$  = compensated signal of channel *i* (*i* = x, y, z)

 $U_i$  = input signal of channel *i* (*i* = x, y, z)

cf = crest factor of exciting field (DASY parameter)

*dcp*<sub>i</sub> = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated :

E-field probes :

$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$



#### H-field probes :

$$H_{i} = \sqrt{V_{i}} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^{2}}{f}$$

with 
$$V_i$$
 = compensated signal of channel *i* (*i* = x, y, z)

*Norm*<sub>i</sub> = sensor sensitivity of channel i (i = x, y, z)

 $\mu$  V/(V/m)<sup>2</sup> for E-field Probes

- ConvF = sensitivity enhancement in solution
- $a_{ij}$  = sensor sensitivity factors for H-field probes
- f = carrier frequency [GHz]
- $E_i$  = electric field strength of channel *i* in V/m
- Hi = magnetic field strength of channel *i* in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude) :

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

 $E_{tot}$  = total field strength in V/m

 $\sigma$  = conductivity in [mho/m] or [Siemens/m]

 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

**\*Note**: that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770}$$
 or  $P_{pwe} = \frac{H_{tot}^2}{37.7}$ 

with  $P_{pwe}$  = equivalent power density of a plane wave in mW/cm<sup>2</sup>

 $E_{tot}$  = total electric field strength in V/m

 $H_{tot}$  = total magnetic field strength in A/m



# 7. <u>Test Equipment List</u>

Manufacturer	Name of Equipment	Type/Model	Serial Number	Calibration	
Manaracturer		i ype/ woder	Schar Namber	Last Cal.	Due Date
SPEAG	Dosimetric E-Filed Probe	ET3DV6	1530	Sep. 21, 2006	Sep. 21, 2007
SPEAG	2450MHz System Validation Kit	D2450V2	712	Feb. 20, 2007	Feb. 20, 2008
SPEAG	Data Acquisition Electronics	DAE4	541	Oct. 16, 2006	Oct. 16, 2007
SPEAG	Device Holder	N/A	N/A	NCR	NCR
SPEAG	Phantom	SAM V4.0	1009	NCR	NCR
SPEAG	Robot	Staubli RX90L	F00/589B1/A/01	NCR	NCR
SPEAG	Software	DASY4 V4.7 Build 53	N/A	NCR	NCR
SPEAG	Software	SEMCAD V1.8 Build 172	N/A	NCR	NCR
SPEAG	Measurement Server	SE UMS 001 BA	1021	NCR	NCR
Agilent	Wireless Communication Test Set	8960(E5515C)	GB47020167	Feb. 14, 2007	Feb. 14, 2008
Agilent	S-Parameter Network Analyzer	8720ES	US39172472	Aug. 15, 2006	Aug. 15, 2007
Agilent	Dielectric Probe Kit	85070C	US99360094	NCR	NCR
Agilent	Power Meter	E4418B	GB40206143	Apr. 24, 2006	Apr. 24, 2007
Agilent	Power Sensor	8481H	3318A20779	Apr. 25, 2006	Apr. 25, 2007
Agilent	Signal Generator	8648C	3847A05201	Jul. 06, 2006	Jul. 06, 2007
Agilent	Dual Directional Coupler	778D	50334	NCR	NCR
Mini-Circuits	Power Amplifier	ZHL-42W-SMA	D111103#5	NCR	NCR
Mini-Circuits	Power Amplifier	ZVE-8G-SMA	D042005 671800514	NCR	NCR

Table 2. Test Equipment List



# 8. <u>Tissue Simulating Liquids</u>

The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue. The dielectric parameters of the liquids were verified prior to the SAR evaluation using an 85070C Dielectric Probe Kit and an 8720ES Network Analyzer.

INGREDIENT	FREQUENCY			
	HSL5G (Head)	MSL5G (Body)		
Water	64%	78%		
Mineral Oil	18%	11%		
Emulsifiers	15%	9%		
Additives and Salt	3%	2%		

Table 3. Recipes for Head & Body Tissue Simulating Liquids

#### IEEE SCC-34/SC-2 in 1528 recommended Tissue Dielectric Parameters

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in human head. Other head and body tissue parameters that have not been specified in 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equation and extrapolated according to the head parameter specified in 1528.



Target Frequency	Head		Body		
(MHz)	٤r	<b>σ</b> (S/m)	٤ <sub>r</sub>	<b>σ</b> (S/m)	
150	52.3	0.76	61.9	0.80	
300	45.3	0.87	58.2	0.92	
450	43.5	0.87	56.7	0.94	
835	41.5	0.90	55.2	0.97	
900	41.5	0.97	55.0	1.05	
915	41.5	0.98	55.0	1.06	
1450	40.5	1.20	54.0	1.30	
1610	40.3	1.29	53.8	1.40	
1800 - 2000	40.0	1.40	53.3	1.52	
2450	39.2	1.80	52.7	1.95	
3000	38.5	2.40	52.0	2.73	
5800	35.3	5.27	48.2	6.00	
( $\pmb{\epsilon}_r$ = relative permittivity, $\pmb{\sigma}$ = conductivity and $\pmb{\rho}$ = 1000 kg/m³)					

 Table 4. Tissue dielectric parameters for head and body phantoms

### 8.1 Liquid Confirmation

#### 8.1.1 Parameters

Liquid Verify								
Ambient	Temperat	ure: 22	2 ± 3 °C ;	Relativ	e Humidity	/:40 -70%		
Liquid Type	Frequency	Temp (°C)	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)	Measured Date
2450MHz	2450MHz	22.0	٤٢	52.7	51.4	-2.47%	±5%	Mar 20, 2007
Body	2430101112	22.0	σ	1.95	1.97	1.03%	±5%	Mar. 20 , 2007
2450MHz	0450MU-	22.0	٤r	52.7	51.8	-1.71%	±5%	Mar 00 0007
Body	2450MHz	22.0	σ	1.95	1.96	0.51%	±5%	Mar. 26 , 2007

 Table 5. Measured Tissue dielectric parameters for head and body phantoms



### 8.1.2 Liquid Depth

The liquid level was during measurement 15cm  $\pm$ 0.5cm.

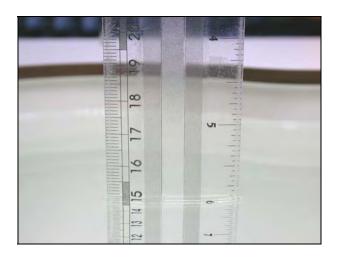


Figure 11. Head-Tissue-Simulating-Liquid

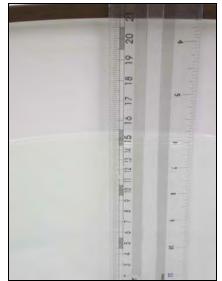


Figure 12. Body-Tissue-Simulating-Liquid



### 9. <u>Measurement Process</u>

### 9.1 Device and Test Conditions

The Test Device was provided by **Acer Incorporated** for this evaluation. The spatial peak SAR values were assessed for the lowest, middle and highest channels defined by WLAN (Ch0 = 1928.448MHz, Ch2 = 1924.992MHz, Ch4 = 1921.536MHz) systems. The antenna(s), battery and accessories shall be those specified by the manufacturer. The battery shall be fully charged before each measurement and there shall be no external connections.

Usage		rates with a built-in st mode by client	Distance between antenna axis at the joint and the liquid surface:	For Body, EL phantom,15mm		
Simulating human Head/Body	÷	Head and Body	EUT Battery	Fully-charged with Ni-MH batteries		
		Channel	Frequency MHz	Before SAR Test (dBm)	After SAR Test (dBm)	
	802.11b	Highest Channel - 1	2412	15.38	15.37	
Conducted	802.11b	Middle Channel - 6	2437	16.86	16.85	
power	802.11b Lowest Channel - 11		2462	16.23	16.22	
	802.11g Highest Channel - 1		2412	14.78	14.77	
	802.11g Middle Channel - 6		2437	15.43	15.42	
	802.11g	Lowest Channel - 11	2462	14.95	14.93	

Note: 2. The EUT has built-in test mode that used to evaluate SAR.

3. The EUT take Nickel-Metal as its power source. Each test was preceded under the condition of fully-charged EUT.



### 9.2 System Performance Check

### 9.2.1 Symmetric Dipoles for System Validation

Construction	Symmetrical dipole with I/4 balun enables measurement
	of feed point impedance with NWA matched for use near
	flat phantoms filled with head simulating solutions
	Includes distance holder and tripod adaptor Calibration
	Calibrated SAR value for specified position and input
	power at the flat phantom in head simulating solutions.
Frequency	450, 900, 1800, 2000, 2450, 5000MHz
Return Loss	> 20 dB at specified validation position
Power Capability	> 100 W (f < 1GHz); > 40 W (f > 1GHz)
Options	Dipoles for other frequencies or solutions and other
	calibration conditions are available upon request
Dimensions	D450V2 : dipole length 270 mm; overall height 330 mm
	D900V2 : dipole length 149 mm; overall height 330 mm
	D1800V2 : dipole length 72 mm; overall height 300 mm
	D2000V2 : dipole length 65 mm; overall height 300 mm
	D2450V2 : dipole length 51.5 mm; overall height 300 mm
	D5GHzV2 : dipole length 20.6 mm; overall height 450 mm



Figure 13. Validation Kit



### 9.2.2 Validation

Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of  $\pm$  7%. The validation was performed at 2450MHz.

Validat	Validation kit		SAR <sub>1g</sub> [mW/g]		SAR <sub>10g</sub> [mW/g]		Date of Calibration	
D2450V2-SN712		Head	54.4		25	.32	Feb, 20, 2007	
D2430V2	-011/12	Body	5	3.6	24.76		1 65, 20, 2007	
Frequency (MHz)	Power (dBm)	SAR <sub>1g</sub>	SAR <sub>10g</sub>	Drift (dB)	Difference percentage		Date	
(10172)	(ubili)	(mW/g)	(mW/g)	(UB)	1g	10g		
2450	250mW	13.6	6.16	-0.027	15%	-05%	Mar. 20, 2007	
(Body)	Normalize to 1 Watt	54.4	24.64	-0.027	1.5 % -0.5 %		Wai. 20, 2007	
2450	250mW	13.2	6.2	-0.065	-1.5 % 0.2 %		Mar. 26, 2007	
(Body)	Normalize to 1 Watt	52.8	24.8	-0.005	-1.5 /0	0.2 /0	Wal. 20, 2007	



### 9.3 Dosimetric Assessment Setup

#### 9.3.1 Headset Test Position – Body-Worn

#### **Body-Worn Configuration**

Body-worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a handset output should be tested with a handset connected to the device.

Body-worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances.

For this test :

The EUT is placed into the holster/belt clip and the holster is positioned against the surface of the phantom in a normal operating position.

Since this EUT doesn't supply any body-worn accessory to the end user, a distance of 15 mm was tested to confirm the necessary "minimum SAR separation distance".

(\*Note : this distance includes the 2 mm phantom shell thickness.)



#### 9.3.2 Measurement Procedures

The evaluation was performed with the following procedures :

- Surface Check : A surface check job gathers data used with optical surface detection. It determines the distance from the phantom surface where the reflection from the optical detector has its peak. Any following measurement jobs using optical surface detection will then rely on this value. The surface check performs its search a specified number of times, so that the repeatability can be verified. The probe tip distance is 1.3mm to phantom inner surface during scans.
- **Reference :** The reference job measures the field at a specified reference position, at 4 mm from the selected section's grid reference point.
- Area Scan : The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines can find the maximum locations even in relatively coarse grids. When an area scan has measured all reachable points, it computes the field maxima found in the scanned area, within a range of the global maximum. Any following zoom scan within the same procedure will then perform fine scans around these maxima. The area covered the entire dimension of the EUT and the horizontal grid spacing was 15 mm × 15 mm.
- Zoom Scan : Zoom scans are used to assess the highest averaged SAR for cubic averaging volumes with 1 g and 10 g of simulated tissue. The zoom scan measures 5 x 5 x 7 points in a 32 x 32 x 30 mm cube whose base faces are centered around the maxima returned from a preceding area scan within the same procedure.
- **Drift :** The drift job measures the field at the same location as the most recent reference job within the same procedure, with the same settings. The drift measurement gives the field difference in dB from the last reference measurement. Several drift measurements are possible for each reference measurement. This allows monitoring of the power drift of the device in the batch process. If the value changed by more than 5%, the evaluation was repeated.



### 9.4 Spatial Peak SAR Evaluation

The DASY4 software includes all numerical procedures necessary to evaluate the spatial peak SAR values. Based on the Draft: SCC-34, SC-2, WG-2 - Computational Dosimetry, IEEE P1529/D0.0 (Draft Recommended Practice for Determining the Spatial-Peak Specific Absorption Rate (SAR) Associated with the Use of Wireless Handsets - Computational Techniques), a new algorithm has been implemented. The spatial-peak SAR can be computed over any required mass.

The base for the evaluation is a "cube" measurement in a volume of (32×32×30)mm<sup>3</sup> (5×5×7 points). The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan. If the 10g cube or both cubes are not entirely inside the measured volumes, the system issues a warning regarding the evaluated spatial peak values within the Postprocessing engine (SEMCAD). This means that if the measured volume is shifted, higher values might be possible. To get the correct values you can use a finer measurement grid for the area scan. In complicated field distributions, a large grid spacing for the area scan might miss some details and give an incorrectly interpolated peak location.

The entire evaluation of the spatial peak values is performed within the Postprocessing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into three stages:

#### Interpolation and Extrapolation

The probe is calibrated at the center of the dipole sensors which is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated.

In DASY4, the choice of the coordinate system defining the location of the measurement points has no influence on the uncertainty of the interpolation, Maxima Search and SAR extrapolation routines. The interpolation, Maxima Search and extrapolation routines are all based on the modified Quadratic Shepard's method [7].



# 10. Measurement Uncertainty

Measurement uncertainties in SAR measurements are difficult to quantify due to several variables including biological, physiological, and environmental. However, we estimate the measurement uncertainties in SAR to be less than  $\pm 27 \%$  (8).

According to Std. C95.3 [9], the overall uncertainties are difficult to assess and will vary with the type of meter and usage situation. However, accuracy's of  $\pm 1$  to 3 dB can be expected in practice, with greater uncertainties in near-field situations and at higher frequencies (shorter wavelengths), or areas where large reflecting objects are present. Under optimum measurement conditions, SAR measurement uncertainties of at least  $\pm 2$ dB can be expected.

According to CENELEC [10], typical worst-case uncertainty of field measurements is  $\pm 5$  dB. For well-defined modulation characteristics the uncertainty can be reduced to  $\pm 3$  dB.



Source of Uncertainty	Uncertainty Value	Probability Distribution	Divisor	Ci	Standard Uncertainty ±1%(1-g)	V <sub>i</sub> or V <sub>eff</sub>
Туре-А	0.9 %	Normal	1	1	0.9	9
Measurement System						
Probe Calibration	7 %	Normal	2	1	3.5	$\infty$
Axial Isotropy	0.2dB	Rectangular	$\sqrt{3}$	$\sqrt{0.5}$	1.9	$\infty$
Hemispherical Isotropy	9.6 %	Rectangular	$\sqrt{3}$	$\sqrt{0.5}$	3.9	$\infty$
Spatial Resolution	0 %	Rectangular	$\sqrt{3}$	1	0	$\infty$
Boundary Effect	11.0 %	Rectangular	$\sqrt{3}$	1	6.4	$\infty$
Linearity	0.2dB	Rectangular	$\sqrt{3}$	1	2.7	$\infty$
Detection Limit	1.0 %	Rectangular	$\sqrt{3}$	1	0.6	$\infty$
Readout Electronics	1.0 %	Normal	1	1	1.0	$\infty$
RF Ambient Conditions	3.0 %	Rectangular	$\sqrt{3}$	1	1.73	$\infty$
Probe Positioner Mech. Const.	0.4 %	Rectangular	$\sqrt{3}$	1	0.2	$\infty$
Probe Positioning	0.35 %	Rectangular	$\sqrt{3}$	1	0.2	$\infty$
Extrapolation and Integration	3.9 %	Rectangular	$\sqrt{3}$	1	2.3	$\infty$
Test sample Related						
Test sample Positioning	4.7 %	Normal	1	1	4.7	5
Device Holder Uncertainty	6.1 %	Normal	1	1	6.1	5
Drift of Output Power	5.0 %	Rectangular	$\sqrt{3}$	1	2.9	$\infty$
Phantom and Setup						
Phantom Uncertainty (Including temperature effects)	4.0%	Rectangular	$\sqrt{3}$	1	2.3	$\infty$
Liquid Conductivity (target)	5.0%	Rectangular	$\sqrt{3}$	0.6	1.7	$\infty$
Liquid Conductivity (meas.)	10.0%	Rectangular	$\sqrt{3}$	0.6	3.4	$\infty$
Liquid Permittivity (target)	5.0%	Rectangular	$\sqrt{3}$	0.6	1.7	$\infty$
Liquid Permittivity (meas.)	5.0%	Rectangular	$\sqrt{3}$	0.6	1.7	$\infty$
Combined standard uncertainty		RSS			13.5	88.7
Expanded uncertainty (Coverage factor = 2)		Normal (k=2)			27	

Table 6. Uncertainty Budget of DASY



# 11. SAR Test Results Summary

### 11.1 Lepto WLAN Body SAR

### 11.1.1 802.11b

Ambient :           Temperature (°C) :         22 ± 3			<u>± 3 Rel</u>	ative HUMID		40 - 70			
Liquid : Mixture Type : MSL2450				uid Tempera	<u> </u>				
Measuremer Crest Fact		1	1 Probe S/N :				1530		
Freque	ncy	Battery	Phantom	Accessory	SAR <sub>1g</sub>	Power Drift	Ter	np.	Remark
MHz	СН	Ballery	Position	Accessory	[mW/g]	(dB)	Amb.	Liq.	Remark
2412	1	Li-ion	Flat	N/A	0.171	-0.153	20.1	22.0	-
2412	1	Li-ion	Flat	N/A	0.212	-0.006	20.3	22.0	-
2437	6	Li-ion	Flat	N/A	0.171	-0.085	20.1	22.0	-

2462	11	Li-ion	Flat	N/A	0.170	0.056	20.1	22.0	
Std. ( Uncontrolled	Spat	999 - Safety tial Peak sure/Genera				W/kg (m ged over		1	



### 11.1.2 802.11g

Ambient : Temperatu	<b>re (</b> ℃):	22 =	<u>⊦ 3</u> Rel	elative HUMIDITY (%) : 40 - 70						
			Liquid Temperature(℃): Depth of liquid (cm):					22.0 15		
Measuremen Crest Facto		1 Probe S/N :						15	30	
Frequer	ncy	Battery	Phantom	Accessory	SAR <sub>1g</sub>	Power Drift	Ter	np.	Remark	
MHz	СН	Dattery	Position	Accessory	[mW/g]	(dB)	Amb.	Liq.	Remark	
2412	1	Li-ion	Flat	N/A	0.092	-0.076	20.1	22.0	-	
2412	1	Li-ion	Flat	N/A	0.111	-0.069	20.3	22.0	-	
2437	6	Li-ion	Flat	N/A	0.092	-0.195	20.1	22.0	-	
2462	11	Li-ion	Flat	N/A	0.080	-0.110	20.1	22.0	-	
Std. ( Uncontrolle	999 - Safety ial Peak sure/Genera			6 W/kg (m liged over		1				



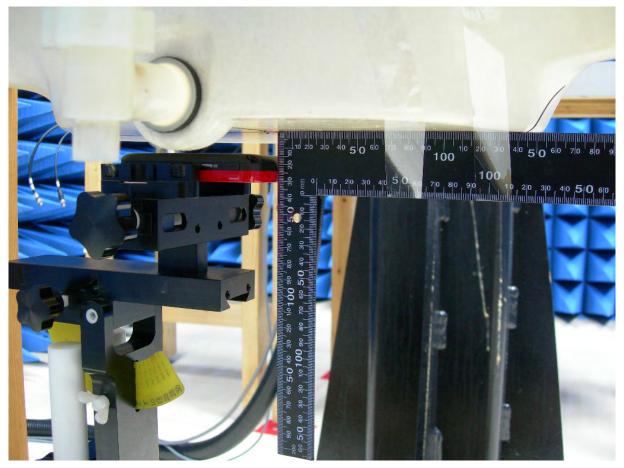


Figure 14. Body SAR Test Setup (Flat Section)\_Lepto



### 11.2 Thickness WLAN Body SAR

### 11.2.1 802.11b

	Temperature (°C) :         22 ± 3				Relative HUMIDITY (%) :				
Liquid : Mixture Ty	rpe:	MSL2450Liquid Temperature (°C) :Depth of liquid (cm) :						22	-
Measuremer Crest Fact			Probe S/N :					15	30
Freque	ncy	Pottony	Phantom	A	SAR <sub>1g</sub>	Power Drift	Ter	np.	Remark
MHz	СН	Battery	Position	Accessory	[mW/g]	(dB)	Amb.	Liq.	Remark
2412	1	Li-ion	Flat	Headset	0.087	-0.146	20.1	22.0	-
2412	1	Li-ion	Flat	Headset	0.150	-0.024	20.1	22.0	-
2437	6	Li-ion	Flat	Headset	0.083	-0.111	20.1	22.0	-

2462	11	Li-ion	Flat	Headset	0.080	0.050	20.1	22.0	-
Std. ( Uncontrolle	Spat	999 - Safety tial Peak sure/Genera				W/kg (m ged over		1	



# 11.2.2 802.11g

Ambient : Temperatu	<b>re (</b> ℃):	22	ative HUMID	DITY (%):			40-	70	
				Liquid Temperature (°C) : Depth of liquid (cm) :					2.0 5
Measurement :       Crest Factor :     1       Probe S/N :							15	30	
Frequer	ncy	Pottory	Phantom	Accessory	SAR <sub>1g</sub>	Power	Ter	np.	Remark
MHz	СН	Battery	Position	Accessory	[mW/g]	Drift (dB)	Amb.	Liq.	Remark
2412	1	Li-ion	Flat	Headset	0.091	-0.152	20.1	22.0	-
2437	6	Li-ion	Flat	Headset	0.093	-0.100	20.1	22.0	-
2437	6	Li-ion	Flat	Headset	0.103	-0.029	20.1	22.0	-
2462	11	Li-ion	Flat	Headset	0.092	-0.133	20.1	22.0	-
Std. ( Uncontrolle	Spat	999 - Safety ial Peak ure/Genera			W/kg (m ged over				



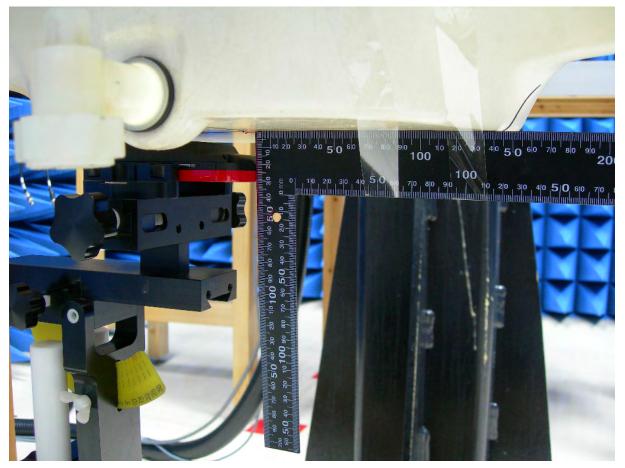


Figure 15. Body SAR Test Setup (Flat Section)\_Thickness

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Human Exposure	Population Uncontrolled Exposure ( W/kg ) or (mW/g)	Occupational Controlled Exposure ( W/kg ) or (mW/g)
Spatial Peak SAR* (head)	1.60	8.00
Spatial Peak SAR** (Whole Body)	0.08	0.40
Spatial Peak SAR*** (Partial-Body)	1.60	8.00
Spatial Peak SAR**** (Hands / Feet / Ankle / Wrist )	4.00	20.00

#### 11.3 Std. C95.1-1999 RF Exposure Limit

Table 7. Safety Limits for Partial Body Exposure

#### Notes :

- \* The Spatial Peak value of the SAR averaged over any 1 gram of tissue.
  ( defined as a tissue volume in the shape of a cube ) and over the appropriate averaging time.
- \*\* The Spatial Average value of the SAR averaged over the whole body.
- \*\*\* The Spatial Average value of the SAR averaged over the partial body.
- \*\*\*\* The Spatial Peak value of the SAR averaged over any 10 grams of tissue.(defined as a tissue volume in the shape of a cube ) and over the appropriate averaging time.

**Population / Uncontrolled Environments :** are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

**Occupational / Controlled Environments :** are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).



# 12. <u>Conclusion</u>

The SAR test values found for the portable mobile phone **Acer Incorporated Trade Mark : Acer Model (s) : C500** are below the maximum recommended level of 1.6 W/kg (mW/g).



### 13. <u>References</u>

- [1] Std. C95.1-1999, "American National Standard safety levels with respect to human exposure to radio frequency electromagnetic fields, 300KHz to 100GHz", New York.
- [2] NCRP, National Council on Radiation Protection and Measurements, "*Biological Effects and Exposure Criteria for Radio frequency Electromagnetic Fields*", NCRP report NO. 86, 1986.
- [3] T. Schmid, O. Egger, and N. Kuster, "Automatic E-field scanning system for dosimetric assessments", IEEE Transactions on Microwave Theory and Techniques, vol. 44, pp, 105-113, Jan. 1996.
- [4] K. Poković, T. Schmid, and N. Kuster, "Robust setup for precise calibration of E-field probes in tissue simulating liquids at mobile communications frequency", in ICECOM'97, Dubrovnik, October 15-17, 1997, pp.120-124.
- [5] K. Poković, T. Schmid, and N. Kuster, "*E-field probe with improved isotropy in brain simulating liquids*", in Proceedings of the ELMAR, Zadar, Croatia, 23-25 June, 1996, pp.172-175.
- [6] N. Kuster, and Q. Balzano, "Energy absorption mechanism by biological bodies in the near field of dipole antennas above 300MHz", IEEE Transaction on Vehicular Technology, vol. 41, no. 1, Feb. 1992, pp. 17-23.
- [7] Robert J. Renka, "*Multivariate Interpolation Of Large Sets Of Scattered Data*", University of North Texas ACM Transactions on Mathematical Software, vol. 14, no. 2, June 1988, pp. 139-148.
- [8] N. Kuster, R. Kastle, T. Schmid, Dosimetric evaluation of mobile communications equipment with known precision, IEEE Transaction on Communications, vol. E80-B, no. 5, May 1997, pp. 645-652.
- [9] Std. C95.3-1991, "IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave, New York: IEEE, Aug. 1992.
- [10]CENELEC CLC/SC111B, European Prestandard (prENV 50166-2), *Human Exposure to Electromagnetic Fields High-frequency*: 10KHz-300GHz, Jan. 1995.



#### Appendix A – System Performance Check

See following Attached Pages for System Performance Check.



Date/Time: 3/20/2007 11:41:20 PM

# System Performance Check at 2450MHz\_20070320\_Body

#### DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:712

Communication System: CW; Frequency: 2450 MHz;Duty Cycle: 1:1

Medium parameters used: f = 2450 MHz;  $\sigma = 1.97 \text{ mho/m}$ ;  $\varepsilon_r = 51.4$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

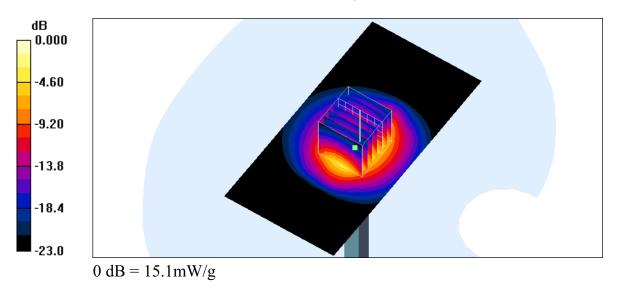
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### System Performance Check at 2450MHz/Area Scan (51x101x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 15.5 mW/g

#### System Performance Check at 2450MHz/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 90.0 V/m; Power Drift = -0.027 dB Peak SAR (extrapolated) = 32.3 W/kg **SAR(1 g) = 13.6 mW/g; SAR(10 g) = 6.16 mW/g** Maximum value of SAR (measured) = 15.1 mW/g





Date/Time: 3/26/2007 2:51:21 PM

# System Performance Check at2450MHz\_20070326\_Body

#### DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:712

Communication System: CW; Frequency: 2450 MHz;Duty Cycle: 1:1

Medium parameters used: f = 2450 MHz;  $\sigma = 1.96 \text{ mho/m}$ ;  $\varepsilon_r = 51.8$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

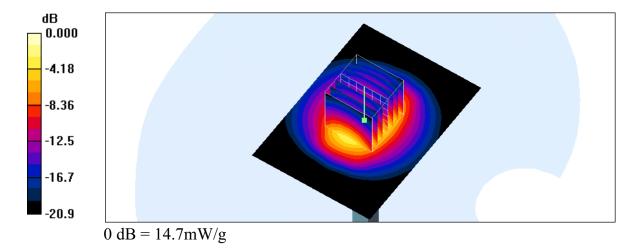
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### System Performance Check at 2450MHz/Area Scan (51x71x1):

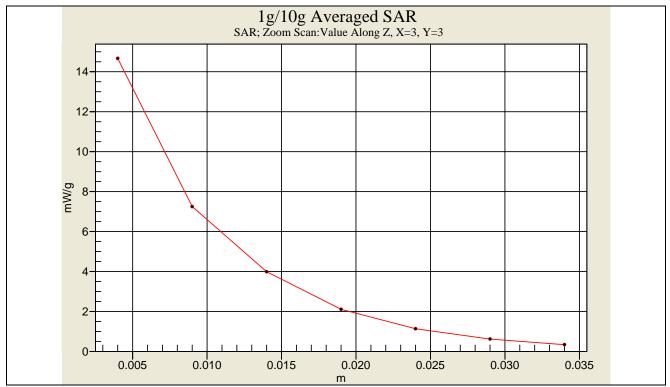
Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 17.5 mW/g

#### System Performance Check at 2450MHz/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 90.7 V/m; Power Drift = -0.065 dB Peak SAR (extrapolated) = 29.9 W/kg **SAR(1 g) = 13.2 mW/g; SAR(10 g) = 6.2 mW/g** Maximum value of SAR (measured) = 14.7 mW/g

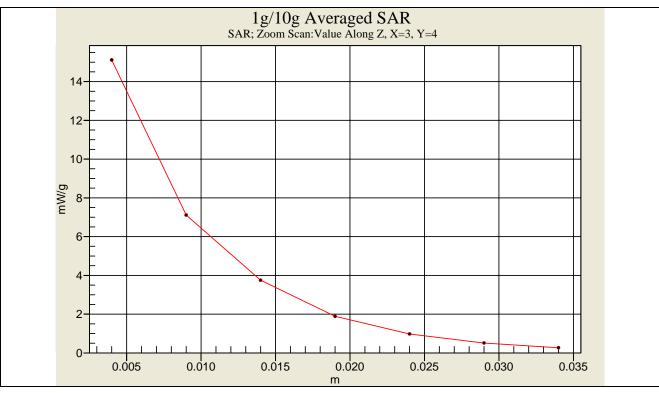






#### Z-axis Plot of System Performance Check

Head-Tissue-Simulating-Liquid 2GHz(20070320)



Head-Tissue-Simulating-Liquid 2GHz(20070326)



#### Appendix B – SAR Measurement Data

See following Attached Pages for SAR Measurement Data.



Date/Time: 3/21/2007 1:26:18 AM

# Flat\_802.11b CH1\_Lepto\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11b; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2412 MHz;  $\sigma$  = 1.96 mho/m;  $\epsilon_r$  = 51.3;  $\rho$  = 1000 kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

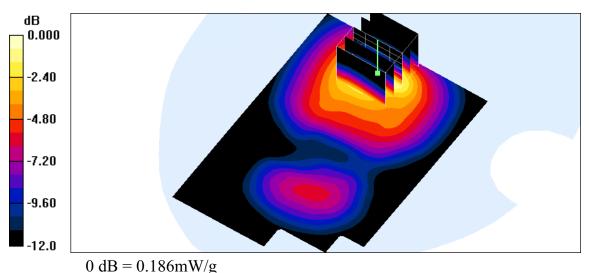
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Flat/Area Scan (71x101x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.196 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 10.1 V/m; Power Drift = -0.153 dB Peak SAR (extrapolated) = 0.363 W/kg **SAR(1 g) = 0.171 mW/g; SAR(10 g) = 0.088 mW/g** Maximum value of SAR (measured) = 0.186 mW/g





Date/Time: 3/21/2007 7:36:34 PM

# Flat\_802.11b CH1\_Lepto\_Battery\_BT ON\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11b; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2412 MHz;  $\sigma = 1.92 \text{ mho/m}$ ;  $\varepsilon_r = 52$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

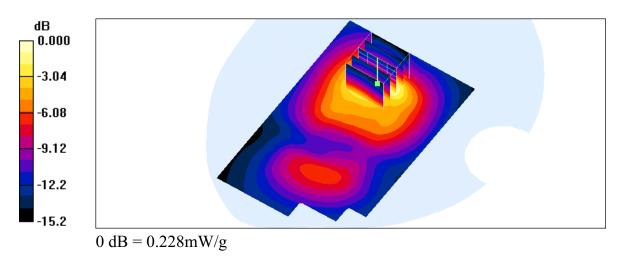
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Flat/Area Scan (71x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.246 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 11.7 V/m; Power Drift = -0.006 dB Peak SAR (extrapolated) = 0.452 W/kg **SAR(1 g) = 0.212 mW/g; SAR(10 g) = 0.111 mW/g** Maximum value of SAR (measured) = 0.228 mW/g





Date/Time: 3/21/2007 1:42:00 AM

# Flat\_802.11b CH6\_Lepto\_Battery\_Muscle\_15mm

# DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11b; Frequency: 2437 MHz;Duty Cycle: 1:1

Medium parameters used: f = 2437 MHz;  $\sigma = 1.98$  mho/m;  $\epsilon_r = 51.3$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

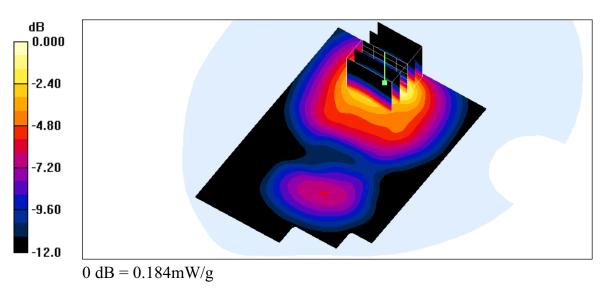
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

# Flat/Area Scan (71x101x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.192 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 9.92 V/m; Power Drift = -0.085 dB Peak SAR (extrapolated) = 0.369 W/kg **SAR(1 g) = 0.171 mW/g; SAR(10 g) = 0.088 mW/g** Maximum value of SAR (measured) = 0.184 mW/g





Date/Time: 3/21/2007 2:08:53 AM

# Flat\_802.11b CH11\_Lepto\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11b; Frequency: 2462 MHz;Duty Cycle: 1:1 Medium parameters used: f = 2462 MHz;  $\sigma = 1.98$  mho/m;  $\varepsilon_r = 51.4$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

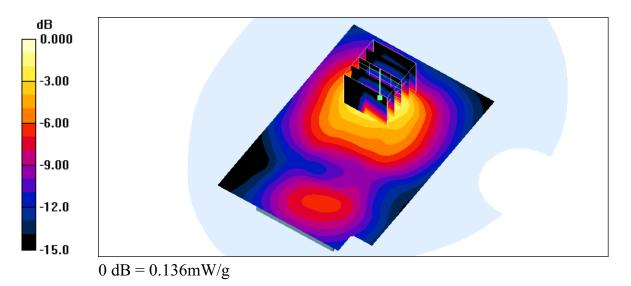
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Flat/Area Scan (71x101x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.137 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 8.71 V/m; Power Drift = 0.056 dB Peak SAR (extrapolated) = 0.585 W/kg **SAR(1 g) = 0.170 mW/g; SAR(10 g) = 0.072 mW/g Maximum value of SAR (measured) = 0.136 mW/g** 





Date/Time: 3/27/2007 2:30:22 AM

# Flat\_802.11g CH1\_Lepto\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11g; Frequency: 2412 MHz;Duty Cycle: 1:1

Medium parameters used: f = 2412 MHz;  $\sigma = 1.96$  mho/m;  $\varepsilon_r = 51.3$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

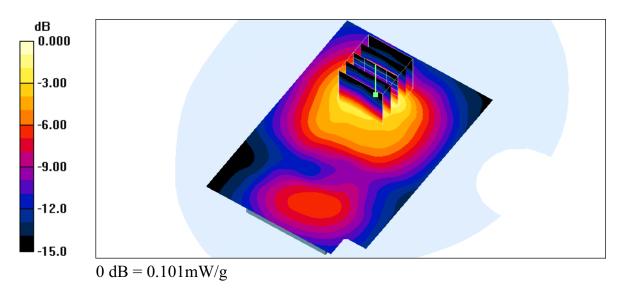
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Flat/Area Scan (71x101x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.104 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 7.39 V/m; Power Drift = -0.076 dB Peak SAR (extrapolated) = 0.195 W/kg **SAR(1 g) = 0.092 mW/g; SAR(10 g) = 0.048 mW/g** Maximum value of SAR (measured) = 0.101 mW/g





Date/Time: 3/26/2007 7:53:40 PM

# Flat\_802.11g CH1\_Lepto\_Battery\_BT ON\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11g; Frequency: 2412 MHz;Duty Cycle: 1:1 Medium parameters used: f = 2412 MHz;  $\sigma = 1.92$  mho/m;  $\epsilon_r = 52$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

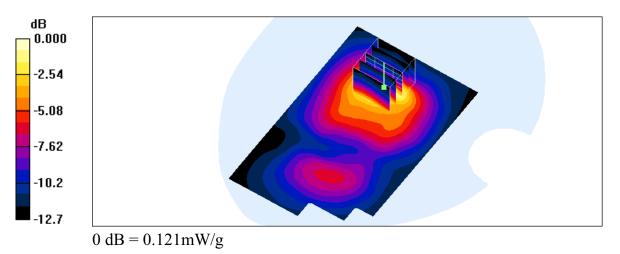
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Flat/Area Scan (71x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.130 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 8.51 V/m; Power Drift = -0.069 dB Peak SAR (extrapolated) = 0.237 W/kg **SAR(1 g) = 0.111 mW/g; SAR(10 g) = 0.059 mW/g** Maximum value of SAR (measured) = 0.121 mW/g





Date/Time: 3/27/2007 2:48:15 AM

# Flat\_802.11g CH6\_Lepto\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11g; Frequency: 2437 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2437 MHz;  $\sigma = 1.98$  mho/m;  $\varepsilon_r = 51.3$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

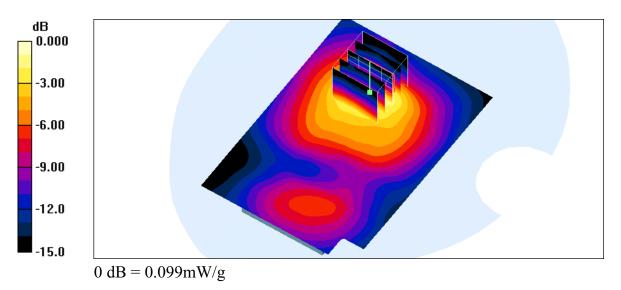
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

# Flat/Area Scan (71x101x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.098 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 7.39 V/m; Power Drift = -0.195 dB Peak SAR (extrapolated) = 0.199 W/kg SAR(1 g) = 0.092 mW/g; SAR(10 g) = 0.047 mW/g Maximum value of SAR (measured) = 0.099 mW/g





Date/Time: 3/27/2007 3:03:32 AM

# Flat\_802.11g CH11\_Lepto\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11g; Frequency: 2462 MHz;Duty Cycle: 1:1

Medium parameters used: f = 2462 MHz;  $\sigma = 1.98 \text{ mho/m}$ ;  $\varepsilon_r = 51.4$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

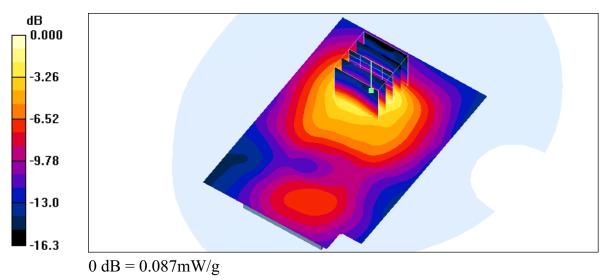
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

# Flat/Area Scan (71x101x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.088 mW/g

#### Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 6.77 V/m; Power Drift = -0.110 dB Peak SAR (extrapolated) = 0.177 W/kg **SAR(1 g) = 0.080 mW/g; SAR(10 g) = 0.041 mW/g** Maximum value of SAR (measured) = 0.087 mW/g





Date/Time: 3/21/2007 6:29:57 PM

#### Flat\_802.11b CH1\_Thickness\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11b; Frequency: 2412 MHz;Duty Cycle: 1:1

Medium parameters used: f = 2412 MHz;  $\sigma = 1.92$  mho/m;  $\varepsilon_r = 52$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

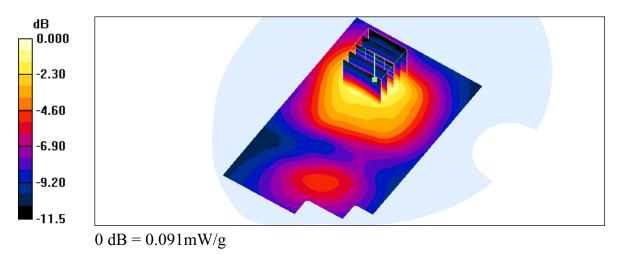
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

# Flat/Area Scan (71x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.096 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 7.05 V/m; Power Drift = -0.146 dB Peak SAR (extrapolated) = 0.164 W/kg **SAR(1 g) = 0.087 mW/g; SAR(10 g) = 0.051 mW/g** Maximum value of SAR (measured) = 0.091 mW/g





Date/Time: 3/21/2007 2:15:42 AM

# Flat\_802.11b CH1\_Thickness\_Battery\_BT ON\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11b; Frequency: 2412 MHz;Duty Cycle: 1:1

Medium parameters used: f = 2412 MHz;  $\sigma = 1.92 \text{ mho/m}$ ;  $\varepsilon_r = 52$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

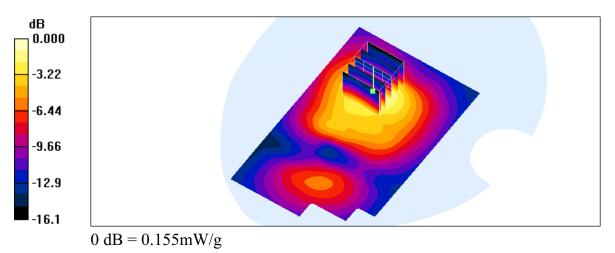
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Flat/Area Scan (71x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.159 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 9.18 V/m; Power Drift = -0.024 dB Peak SAR (extrapolated) = 0.324 W/kg **SAR(1 g) = 0.150 mW/g; SAR(10 g) = 0.078 mW/g** Maximum value of SAR (measured) = 0.155 mW/g





Date/Time: 3/21/2007 6:45:46 PM

# Flat\_802.11b CH6\_Thickness\_Battery\_Muscle\_15mm

# DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11b; Frequency: 2437 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2437 MHz;  $\sigma = 1.95$  mho/m;  $\epsilon_r = 51.9$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

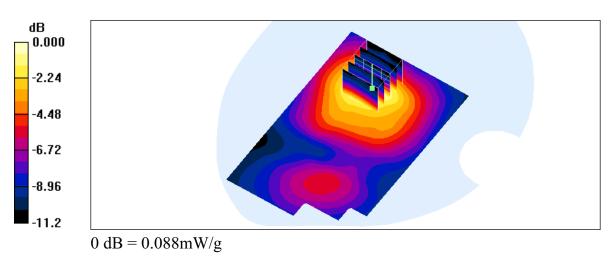
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

# Flat/Area Scan (71x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.092 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 6.80 V/m; Power Drift = -0.111 dB Peak SAR (extrapolated) = 0.159 W/kg **SAR(1 g) = 0.083 mW/g; SAR(10 g) = 0.048 mW/g Maximum value of SAR (measured) = 0.088 mW/g** 





Date/Time: 3/21/2007 7:01:09 PM

#### Flat\_802.11b CH11\_Thickness\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11b; Frequency: 2462 MHz;Duty Cycle: 1:1 Medium parameters used: f = 2462 MHz;  $\sigma = 1.98$  mho/m;  $\epsilon_r = 51.8$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

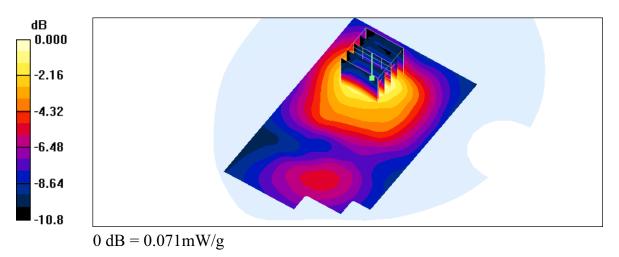
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

# Flat/Area Scan (71x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.078 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 6.18 V/m; Power Drift = 0.050 dB Peak SAR (extrapolated) = 0.203 W/kg SAR(1 g) = 0.080 mW/g; SAR(10 g) = 0.042 mW/g Maximum value of SAR (measured) = 0.071 mW/g





Date/Time: 3/27/2007 2:35:54 AM

# Flat\_802.11g CH1\_Thickness\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11g; Frequency: 2412 MHz;Duty Cycle: 1:1 Medium parameters used: f = 2412 MHz;  $\sigma = 1.92$  mho/m;  $\varepsilon_r = 52$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

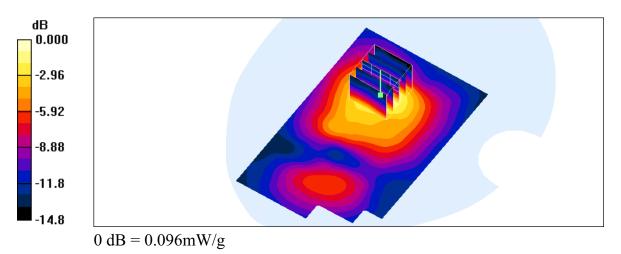
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Flat/Area Scan (71x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.096 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 6.82 V/m; Power Drift = -0.152 dB Peak SAR (extrapolated) = 0.197 W/kg **SAR(1 g) = 0.091 mW/g; SAR(10 g) = 0.048 mW/g** Maximum value of SAR (measured) = 0.096 mW/g





Date/Time: 3/27/2007 2:51:53 AM

# Flat\_802.11g CH6\_Thickness\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11g; Frequency: 2437 MHz;Duty Cycle: 1:1 Medium parameters used: f = 2437 MHz;  $\sigma = 1.95$  mho/m;  $\varepsilon_r = 51.9$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

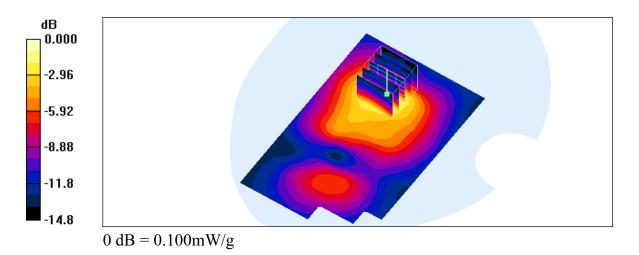
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Flat/Area Scan (71x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.099 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 7.20 V/m; Power Drift = -0.100 dB Peak SAR (extrapolated) = 0.200 W/kg **SAR(1 g) = 0.093 mW/g; SAR(10 g) = 0.049 mW/g** Maximum value of SAR (measured) = 0.100 mW/g





Date/Time: 3/27/2007 3:27:02 AM

# Flat\_802.11g CH6\_Thickness\_Battery\_BT ON\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11g; Frequency: 2437 MHz;Duty Cycle: 1:1 Medium parameters used: f = 2437 MHz;  $\sigma = 1.95$  mho/m;  $\epsilon_r = 51.9$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

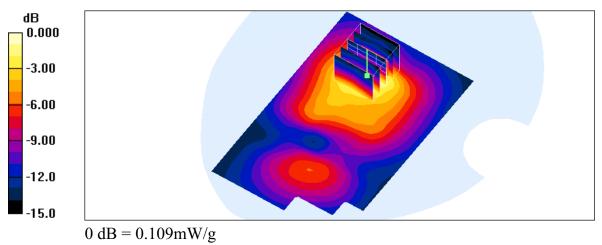
- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Flat/Area Scan (71x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.111 mW/g

# Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 7.54 V/m; Power Drift = -0.029 dB Peak SAR (extrapolated) = 0.221 W/kg **SAR(1 g) = 0.103 mW/g; SAR(10 g) = 0.054 mW/g** Maximum value of SAR (measured) = 0.109 mW/g





Date/Time: 3/27/2007 3:07:46 AM

# Flat\_802.11g CH11\_Thickness\_Battery\_Muscle\_15mm

#### DUT: C500; Type: Travel Companion; Serial: HLZC500

Communication System: IEEE 802.11g; Frequency: 2462 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2462 MHz;  $\sigma = 1.98 \text{ mho/m}$ ;  $\varepsilon_r = 51.8$ ;  $\rho = 1000 \text{ kg/m}^3$ 

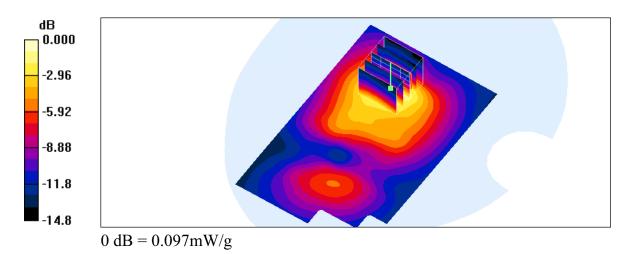
Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ET3DV6 SN1530; ConvF(3.94, 3.94, 3.94); Calibrated: 9/21/2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 10/16/2006
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

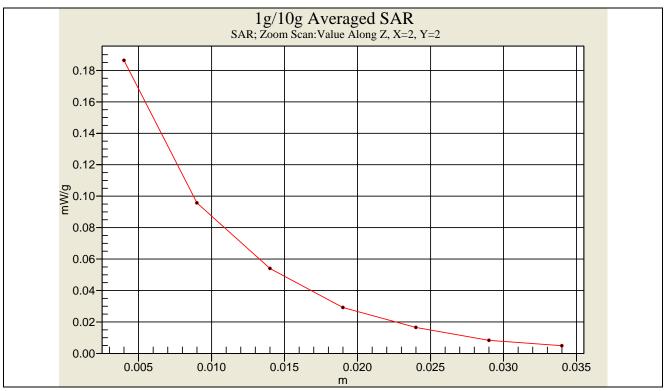
**Flat/Area Scan (71x111x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.098 mW/g

Flat/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 7.16 V/m; Power Drift = -0.133 dB Peak SAR (extrapolated) = 0.196 W/kg SAR(1 g) = 0.092 mW/g; SAR(10 g) = 0.048 mW/g Maximum value of SAR (measured) = 0.097 mW/g

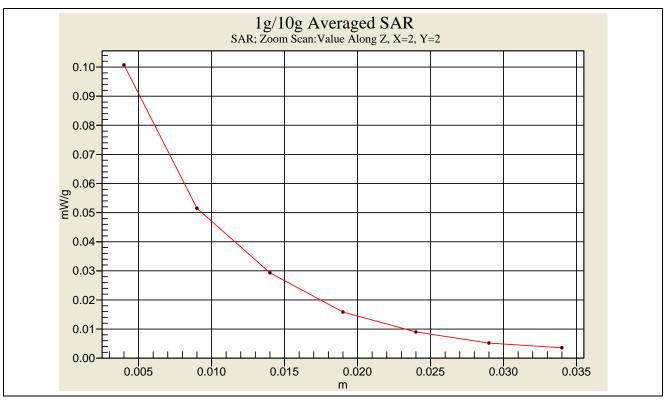




#### Z-axis Plot of SAR Measurement

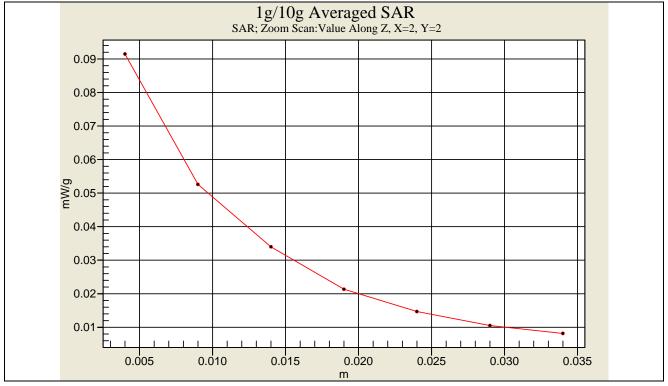


SAR Measurement \_ Flat Cheek 802.11b CH1

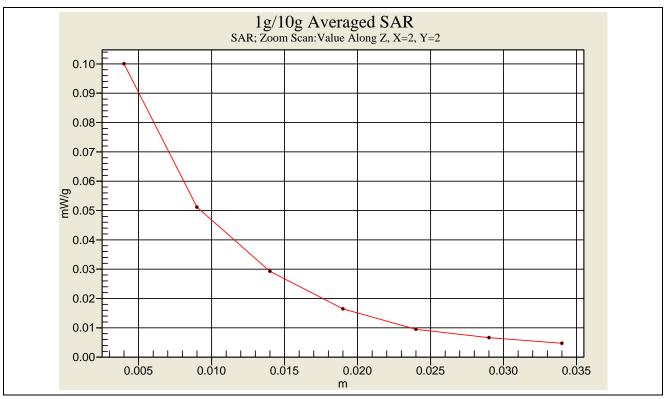


SAR Measurement \_ Flat Cheek 802.11g CH1





SAR Measurement \_ Flat 802.11b CH1



SAR Measurement \_ Flat 802.11g CH6



#### Appendix C – Calibration

All of the instruments Calibration information are listed below.

- Dipole \_ D2450V2 SN:712 Calibration No.D2450V2-712\_Feb07
- Probe \_ ET3DV6 SN:1530 Calibration No.ET3-1530\_Sep06
- DAE \_ DAE4 SN:541 Calibration No.DAE4-541\_Oct06

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





Schweizerischer Kalibrierdienst

C Service suisse d'étalonnage

Servizio svizzero di taratura

S Swiss Calibration Service

Accreditation No.: SCS 108

S

Client ATL (Auden)

Certificate No: D2450V2-712\_Feb07

# CALIBRATION CERTIFICATE

Accredited by the Swiss Federal Office of Metrology and Accreditation The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Dbject	D2450V2 - SN: 7	12	
Calibration procedure(s)	QA CAL-05.v6 Calibration proces	dure for dipole validation kits	
Calibration date:	February 20, 200	7	
Condition of the calibrated item	In Tolerance		
The measurements and the unce	rtainties with confidence pr	onal standards, which realize the physical units of obability are given on the following pages and are y facility: environment temperature (22 ± 3)°C and	part of the certificate.
Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	03-Oct-06 (METAS, No. 217-00608)	Oct-07
ower sensor HP 8481A	US37292783	03-Oct-06 (METAS, No. 217-00608)	Oct-07
eference 20 dB Attenuator	SN: 5086 (20g)	10-Aug-06 (METAS, No 217-00591)	Aug-07
leference 10 dB Attenuator	SN: 5047.2 (10r)	10-Aug-06 (METAS, No 217-00591)	Aug-07
Reference Probe ES3DV3	SN 3025	19-Oct-06 (SPEAG, No. ES3-3025_Oct06)	Oct-07
DAE4	SN 601	30-Jan-07 (SPEAG, No. DAE4-601_Jan07)	Jan-08
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (SPEAG, in house check Oct-05)	In house check: Oct-07
RF generator Agilent E4421B	MY41000675	11-May-05 (SPEAG, in house check Nov-05)	In house check: Nov-07
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (SPEAG, in house check Oct-06)	In house check: Oct-07
	Marine	Eurotion	Signature
	Name	Function	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Calibrated by:	Marcel Fehr	Laboratory Technician	Malle
Approved by:	Katja Pokovic	Technical Manager	A.M.

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S

Schweizerischer Kalibrierdienst

- Service suisse d'étalonnage
- C Servizio svizzero di taratura
- S Swiss Calibration Service

Accreditation No.: SCS 108

Accredited by the Swiss Federal Office of Metrology and Accreditation The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

#### Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

#### Additional Documentation:

d) DASY4 System Handbook

#### Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end
  of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed
  point exactly below the center marking of the flat phantom section, with the arms oriented
  parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole
  positioned under the liquid filled phantom. The impedance stated is transformed from the
  measurement at the SMA connector to the feed point. The Return Loss ensures low
  reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

#### **Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY4	V4.7
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V5.0	
Distance Dipole Center - TSL	10 mm	with Spacer
Area Scan resolution	dx, dy = 15 mm	
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	2450 MHz ± 1 MHz	

#### **Head TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	38.0 ± 6 %	1.79 mho/m ± 6 %
Head TSL temperature during test	(20.5 ± 0.2) °C		

#### SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	condition	
SAR measured	250 mW input power	13.5 mW / g
SAR normalized	normalized to 1W	54.0 mW / g
SAR for nominal Head TSL parameters 1	normalized to 1W	53.3 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	condition	
SAR measured	250 mW input power	6.30 mW / g
SAR normalized	normalized to 1W	25.2 mW / g
SAR for nominal Head TSL parameters 1	normalized to 1W	25.0 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>1</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### **Body TSL parameters**

The following parameters and calculations were applied.

le following parameter e ana e	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	51.2 ± 6 %	1.97 mho/m ± 6 %
Body TSL temperature during test	(20.9 ± 0.2) °C		

# SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	13.4 mW / g
SAR normalized	normalized to 1W	53.6 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	52.5 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	Condition	
SAR measured	250 mW input power	6.19 mW / g
SAR normalized	normalized to 1W	24.8 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	24.4 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>2</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### Appendix

#### Antenna Parameters with Head TSL

Impedance, transformed to feed point	55.6 Ω + 2.7 jΩ	
Return Loss	– 24.5 dB	

#### Antenna Parameters with Body TSL

Impedance, transformed to feed point	50.2 Ω + 6.1 jΩ	
Return Loss	– 24.3 dB	

#### General Antenna Parameters and Design

Electrical Delay (one direction)	1.147 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

#### **Additional EUT Data**

Manufactured by	SPEAG		
Manufactured on	July 02, 2006		

#### DASY4 Validation Report for Head TSL

Date/Time: 20.02.2007 15:28:53

Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN712

Communication System: CW-2450; Frequency: 2450 MHz;Duty Cycle: 1:1 Medium: HSL U10 BB; Medium parameters used: f = 2450 MHz;  $\sigma$  = 1.78 mho/m;  $\epsilon_r$  = 38.1;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

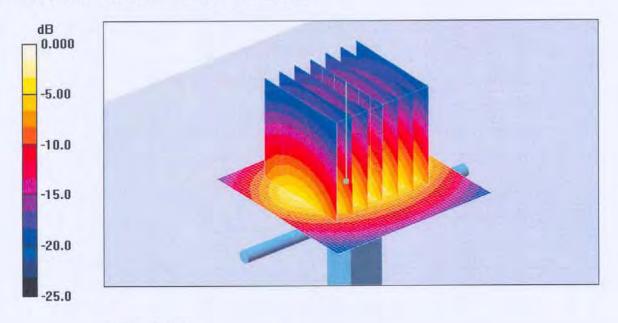
- Probe: ES3DV2 SN3025 (HF); ConvF(4.5, 4.5, 4.5); Calibrated: 19.10.2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 30.01.2007
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; ;
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Pin = 250 mW; d = 10 mm 2/Area Scan (51x51x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 16.1 mW/g

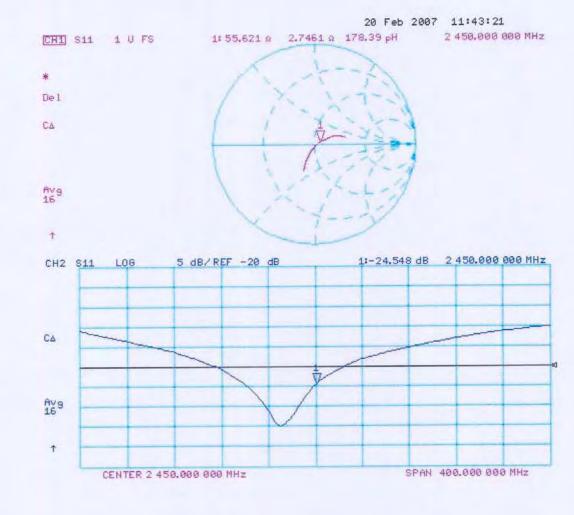
#### Pin = 250 mW; d = 10 mm 2/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 91.4 V/m; Power Drift = -0.003 dB Peak SAR (extrapolated) = 28.2 W/kg SAR(1 g) = 13.5 mW/g; SAR(10 g) = 6.3 mW/g Maximum value of SAR (measured) = 15.4 mW/g



0 dB = 15.4mW/g

Certificate No: D2450V2-712\_Feb07



#### Impedance Measurement Plot for Head TSL

#### DASY4 Validation Report for Body TSL

Date/Time: 13.02.2007 16:22:55

Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN712

Communication System: CW-2450; Frequency: 2450 MHz;Duty Cycle: 1:1 Medium: MSL U10; Medium parameters used: f = 2450 MHz;  $\sigma$  = 1.98 mho/m;  $\epsilon_r$  = 51.3;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

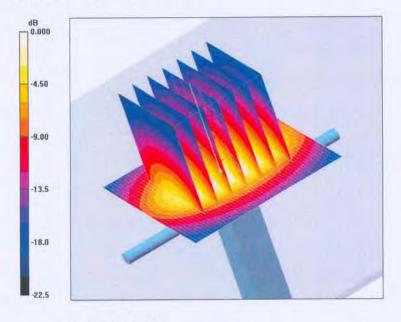
- Probe: ES3DV2 SN3025 (HF); ConvF(4.16, 4.16, 4.16); Calibrated: 19.10.2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 30.01.2007
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; ;
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Pin = 250 mW; d = 10 mm/Area Scan (51x51x1):

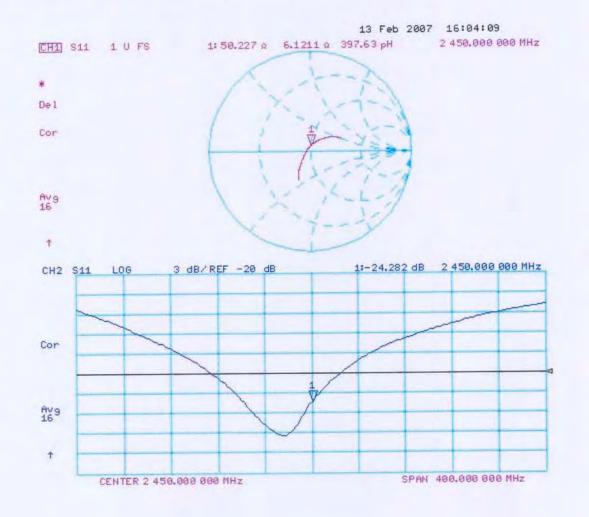
Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 16.7 mW/g

#### Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 88.3 V/m; Power Drift = -0.023 dB Peak SAR (extrapolated) = 28.1 W/kg SAR(1 g) = 13.4 mW/g; SAR(10 g) = 6.19 mW/g Maximum value of SAR (measured) = 15.3 mW/g



 $0 \, dB = 15.3 mW/g$ 



# Impedance Measurement Plot for Body TSL

#### **Calibration Laboratory of** Schmid & Partner **Engineering AG** Zeughausstrasse 43, 8004 Zurich, Switzerland





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Client ATL (Auden) Certificate No: ET3-1530\_Sep06

Accreditation No.: SCS 108

Dbject	ET3DV6 - SN:1	530	STATISTICS.
Calibration procedure(s)		and QA CAL-12.v4 edure for dosimetric E-field probes	
Calibration date:	September 21, 2	2006	
Condition of the calibrated item	In Tolerance	I'm I'm I'm I'm	A MERICAN ST
his calibration certificate documents	ents the traceability to na	tional standards, which realize the physical units of probability are given on the following pages and are	f measurements (SI).
ne measurements and the unce	riainties with confidence	probability are given on the following pages and are	s part of the continuate.
Il calibrations have been conduc	ted in the closed laborate	ory facility: environment temperature $(22 \pm 3)^{\circ}C$ and	d humidity < 70%.
Calibration Equipment used (M&T	E critical for calibration)		
Primary Standards	ID#	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
ower meter E4419B	GB41293874	5-Apr-06 (METAS, No. 251-00557)	Apr-07
ower sensor E4412A	MY41495277	5-Apr-06 (METAS, No. 251-00557)	Apr-07
ower sensor E4412A	MY41498087	5-Apr-06 (METAS, No. 251-00557)	Apr-07
eference 3 dB Attenuator	SN: S5054 (3c)	10-Aug-06 (METAS, No. 217-00592)	Aug-07
eference 20 dB Attenuator	SN: S5086 (20b)	4-Apr-06 (METAS, No. 251-00558)	Apr-07
Reference 30 dB Attenuator	SN: S5129 (30b)	10-Aug-06 (METAS, No. 217-00593)	Aug-07
Reference Probe ES3DV2	SN: 3013	2-Jan-06 (SPEAG, No. ES3-3013 Jan06)	Jan-07
DAE4	SN: 654	21-Jun-06 (SPEAG, No. DAE4-654_Jun06)	Jun-07
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (SPEAG, in house check Nov-05)	In house check: Nov-07
letwork Analyzer HP 8753E	US37390585	18-Oct-01 (SPEAG, in house check Nov-05)	In house check: Nov 06
	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	Mary Rat.
Annual but	Niels Kuster	Quality Managar	1/1t
Approved by:	NIEIS KUSTER	Quality Manager	1/1000
			0.100
			Issued: September 21, 20

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: ET3-1530\_Sep06

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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#### Glossary:

TOI	Alexies almost adding liquid
TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
Polarization $\phi$	φ rotation around probe axis
Polarization 9	$\vartheta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001

#### Methods Applied and Interpretation of Parameters:

- NORMx, y, z: Assessed for E-field polarization 9 = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx, y, z are only intermediate values, i.e., the uncertainties of NORMx, y, z does not effect the E<sup>2</sup>-field uncertainty inside TSL (see below *ConvF*).
- NORM(f)x, y, z = NORMx, y, z \* frequency\_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCPx, y, z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z* \* *ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

Certificate No: ET3-1530\_Sep06

# Probe ET3DV6

# SN:1530

Manufactured: Last calibrated: Modified: Recalibrated: July 15, 2000 September 6, 2005 September 12, 2006 September 21, 2006

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

September 21, 2006

# DASY - Parameters of Probe: ET3DV6 SN:1530

Sensitivity	in	Free	Space <sup>A</sup>	
-------------	----	------	--------------------	--

Diode Compression<sup>B</sup>

NormX	1.48 ± 10.1%	$\mu V/(V/m)^2$	DCP X	92 mV
NormY	1.58 ± 10.1%	$\mu$ V/(V/m) <sup>2</sup>	DCP Y	<b>95</b> mV
NormZ	1.38 ± 10.1%	$\mu$ V/(V/m) <sup>2</sup>	DCP Z	<b>92</b> mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

#### **Boundary Effect**

TSL	9	00 MHz	Typical SAR gradient: 5	% per mm	
	Sensor Cente	r to Phanto	om Surface Distance	3.7 mm	4.7 mm
	SAR <sub>be</sub> [%]	Withou	t Correction Algorithm	10.0	5.4
	SAR <sub>be</sub> [%]	With C	orrection Algorithm	0.1	0.2
TSL	18	10 MHz	Typical SAR gradient: 10	) % per mm	
	Sensor Cente	r to Phante	om Surface Distance	3.7 mm	4.7 mm
	SAR <sub>be</sub> [%]	Withou	t Correction Algorithm	11.8	7.0
	SAR <sub>be</sub> [%]	With C	orrection Algorithm	0.2	4.0
Sen	sor Offset				
	Probe Tip to S	Sensor Ce	nter	2.7 mm	

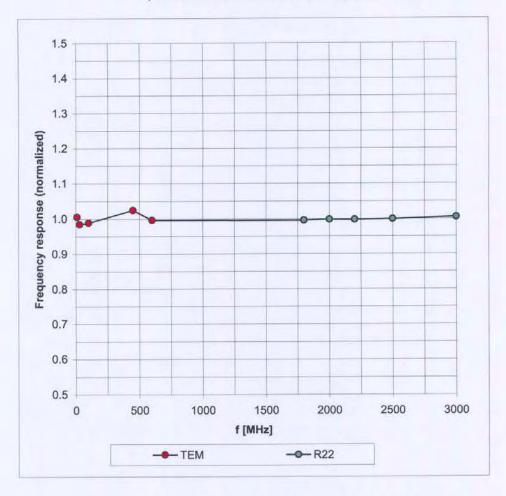
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 8).

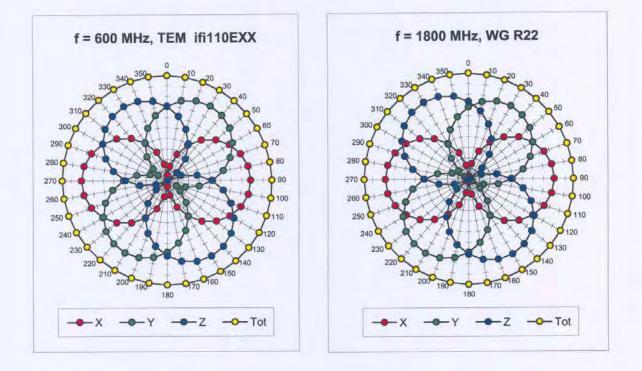
<sup>B</sup> Numerical linearization parameter: uncertainty not required.

**Frequency Response of E-Field** 

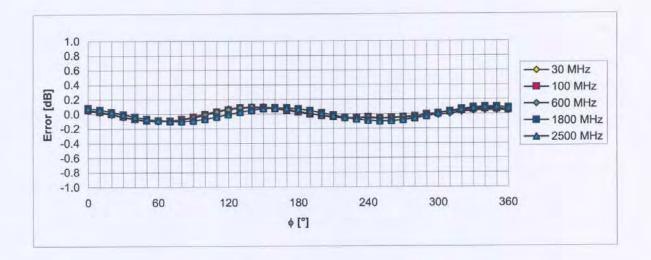
(TEM-Cell:ifi110 EXX, Waveguide: R22)



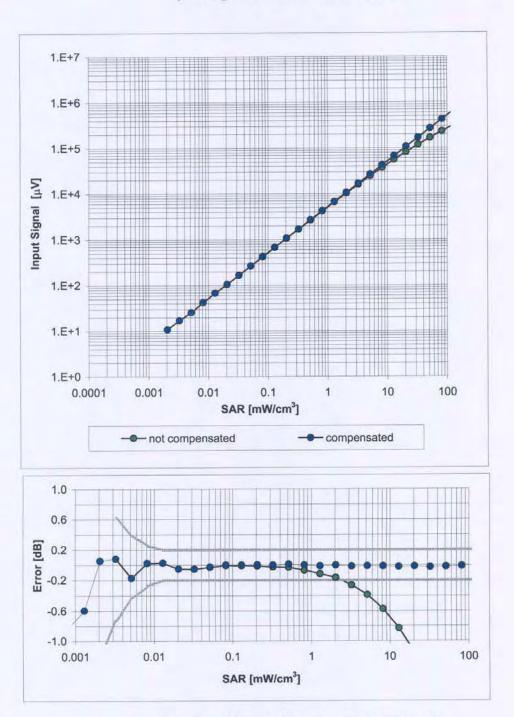
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)



# Receiving Pattern ( $\phi$ ), $\vartheta = 0^{\circ}$

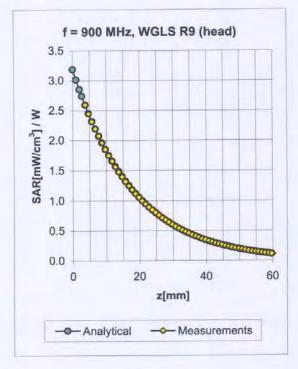


Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

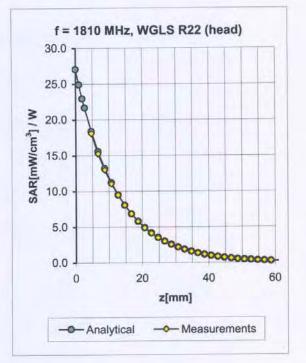


# Dynamic Range f(SAR<sub>head</sub>) (Waveguide R22, f = 1800 MHz)

Uncertainty of Linearity Assessment: ± 0.6% (k=2)



# **Conversion Factor Assessment**



Validity [MHz] <sup>C</sup>	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
± 50 / ± 100	Head	43.5 ± 5%	0.87 ± 5%	0.38	1.96	6.80 ± 13.3% (k=2)
± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.66	1.86	5.91 ± 11.0% (k=2)
± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.55	2.77	4.86 ± 11.0% (k=2)
± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.64	2.67	4.56 ± 11.0% (k=2)
± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.60	2.45	4.32 ± 11.8% (k=2)
± 50 / ± 100	Body	56.7 ± 5%	0.94 ± 5%	0.33	1.97	7.59 ± 13.3% (k=2)
± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	0.59	2.03	5.66 ± 11.0% (k=2)
± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.68	2.68	4.40 ± 11.0% (k=2)
± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.75	2.34	4.21 ± 11.0% (k=2)
± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.65	2.09	3.94 ± 11.8% (k=2)
	$\begin{array}{c} \pm 50 \ / \pm 100 \\ \pm 50 \ / \pm 100 \end{array}$	$\begin{array}{cccc} \pm 50 \ / \pm 100 & \mbox{Head} \\ \pm 50 \ / \pm 100 & \mbox{Head} \\ \pm 50 \ / \pm 100 & \mbox{Head} \\ \pm 50 \ / \pm 100 & \mbox{Head} \\ \pm 50 \ / \pm 100 & \mbox{Head} \\ \end{array}$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

<sup>c</sup> The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

-0.6

-0.8

-1.0 50

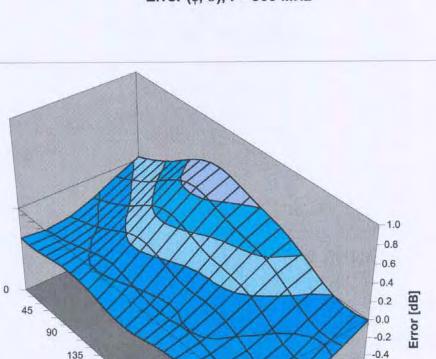
40

φ

30

20

10



135

9

180

225

270

315

# **Deviation from Isotropy in HSL** Error (\, \, \), f = 900 MHz

Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

0 ■-1.00--0.80 ■-0.80--0.60 ■-0.60--0.40 ■-0.40--0.20 ■-0.20-0.00 ■0.00-0.20 ■0.20-0.40 ■0.40-0.60 ■0.60-0.80 ■0.80-1.00

#### Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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 S Swiss Calibration Service

Accreditation No.: SCS 108

Client ATL (Auden)

Certificate No: DAE4-541\_Oct06

# CALIBRATION CERTIFICATE

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Object	DAE4 - SD 000 D	04 BA - SN: 541	
Calibration procedure(s)	QA CAL-06.v12 Calibration procee	lure for the data acquisition electr	onics (DAE)
Calibration date:	October 16, 2006		
Condition of the calibrated item	In Tolerance		
The measurements and the uncerta	ainties with confidence pro	nal standards, which realize the physical units obability are given on the following pages and facility: environment temperature (22 ± 3)°C a	are part of the certificate.
Primary Standards	ID#	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Fluke Process Calibrator Type 702 Keithley Multimeter Type 2001	SN: 6295803 SN: 0810278	13-Oct-06 (Elcal AG, No: 5492) 03-Oct-06 (Elcal AG, No: 5478)	Oct-07 Oct-07
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Calibrator Box V1.1	SE UMS 006 AB 1002	15-Jun-06 (SPEAG, in house check)	In house check Jun-07
	Name	Function	Signature
Calibrated by:	Eric Hainfeld	Technician	Grannoto Hilano F. Bankelt
Approved by:	Fin Bomholt	R&D Director	F. Banholt
		full without written approval of the laboratory.	Issued: October 16, 2006

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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# Glossary

DAE Connector angle

#### data acquisition electronics

information used in DASY system to align probe sensor X to the robot coordinate system.

#### Methods Applied and Interpretation of Parameters

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters contain technical information as a result from the performance test and require no uncertainty.
- DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
- Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
- Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
- AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
- Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
- Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
- Input resistance: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
- Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
- Power consumption: Typical value for information. Supply currents in various operating modes.

# DC Voltage Measurement

A/D - Converter Reso	olution nominal			
High Range:	1LSB =	6.1µV,	full range =	-100+300 mV
Low Range:	1LSB =	61nV ,	full range =	-1+3mV
DASY measurement	parameters: Au	to Zero Time: 3	sec; Measuring	time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.673 ± 0.1% (k=2)	404.537 ± 0.1% (k=2)	404.301 ± 0.1% (k=2)
Low Range	3.96019 ± 0.7% (k=2)	3.93060 ± 0.7% (k=2)	$3.97985 \pm 0.7\%$ (k=2)

# **Connector Angle**

Connector Angle to be used in DASY system	298 ° ± 1 °
---	-------------

#### Appendix

#### 1. DC Voltage Linearity

High Range	Input (µV)	Reading (µV)	Error (%)
Channel X + Input	200000	200000.0	0.00
Channel X + Input	20000	20002.28	0.01
Channel X - Input	20000	-19998.13	-0.01
Channel Y + Input	200000	200000.1	0.00
Channel Y + Input	20000	20002.76	0.01
Channel Y - Input	20000	-20003.58	0.02
Channel Z + Input	200000	199999.9	0.00
Channel Z + Input	20000	20001.43	0.01
Channel Z - Input	20000	-19999.11	0.00

Low Range	Input (µV)	Reading (µV)	Error (%)
Channel X + Input	2000	1999.9	0.00
Channel X + Input	200	199.98	-0.01
Channel X - Input	200	-200.61	0.31
Channel Y + Input	2000	1999.9	0.00
Channel Y + Input	200	199.23	-0.38
Channel Y - Input	200	-201.09	0.55
Channel Z + Input	2000	1999.9	0.00
Channel Z + Input	200	199.32	-0.34
Channel Z - Input	200	-201.26	0.63

2. Common mode sensitivity DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	11.13	10.40
	- 200	-9.72	-11.17
Channel Y	200	1.26	0.86
	- 200	-2.08	-2.44
Channel Z	200	0.31	0.16
	- 200	-1.51	-2.07

#### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (µV)	Channel Y (µV)	Channel Z (µV)
Channel X	200		2.52	0.49
Channel Y	200	0.49	4	4.11
Channel Z	200	-0,64	0.43	-

#### 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15930	15775
Channel Y	15757	15694
Channel Z	15947	16503

#### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec Input  $10M\Omega$ 

	Average (µV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	-0.60	-1.72	0.89	0.34
Channel Y	-0.74	-1.41	-0.01	0.29
Channel Z	-1.42	-2.84	0.19	0.40

#### 6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

#### 7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.1999	198.6
Channel Y	0.2001	201.5
Channel Z	0.2000	201.1

#### 8. Low Battery Alarm Voltage (verified during pre test)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

#### 9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9