# FUNCTIONAL SPECIFICATION FOR MONTY - KENSINGTON GRAVIS 

PREPARED BY: H.Y. LEUNG
DATE: March 3, 2000
REVISION: 2

## Revision History

Revision<br>1<br>2<br>Description<br>First release to KGT<br>CRC2 includes battery status P<br>Defined operands for CRC1, CRC2<br>Defined switches and battery status bits polarity

## Introduction

PDE was requested by Gravis to design a RF trackball code named Monty. PDE has generated this functional specification for PI Engineering as a tool to migrate their existing USB-PS2 firmware to accommodate the serial data stream from the receiver electronics. This functional specification will cover the following aspects:

- An overview of the system
- Communication Protocol
- Electrical Signals
- System Specifications
- Appendix 1 - CRC Table


## System Overview

The input status of the trackball is monitored by a microcontroller on the Transmitter board. Whenever the microcontroller sees a change in the status, it sends a stream of data to the microcontroller on the Receiver board through an RF link. The receiver microcontroller will extract the information carried in the data stream and report to the PC by the PS2 or USB connection. There is a channel selection mechanism on both Transmitter and Receiver to avoid jamming by another user in the same frequency channel. The RF carrier is FSK modulated by a stream of Miller Code base band signal.


## Communication Protocol

## The Data Packet

The transmitter remains in idle mode most of the time and transmits only if it sees a change in the trackball status. Before any packet is transmitted after the transmitter wakes up from the idle state, the Preamble and the Device ID are sent. The Preamble allows the receiver and detection circuitry to stabilize before the data packet is received. The Device ID identifies the transmitter to the receiver. After the Device ID, the Report Frames follow. The Report Frames will be sent as long as there is trackball status change.
The IFI, Inter-Frame Idle, acts as a delimiter. It terminates a frame and separates it from the next one. If there is no transition received after any timer longer than two IFI, the receiver should assume the transmitter has returned to Idle mode.
"Start of Frames", SOF, are provided for the Device ID and Report Frame for transition synchronization as well as frame identification. Also, SOF for the Device ID helps to identify the product type. SOF for the Device ID is ' 01 XX ' where XX is equal to ' 00 ' for Monty. SOF for Report Frames are '0001'. However, the receiver firmware should recognize the SOF of the Report Frames as one of these patterns '0001'or '001' with a leading IFI.

| TX IDLE | PREAMBLE | IFI | DEVICE ID | IFI | REPORT FRAME | IFI | REPORT FRAME |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| IFI |  |  |  |  |  |  |  |

DATA PACKET

## The Device ID

| Bit \# | Length | Description |
| :--- | :--- | :--- |
| $0-3$ | 4 | Start of Frame Identifier b0b1b2b3 $=01 X X$ where $X X=00$ for Monty |
| $4-7$ | 4 | 4-bit ID |

The Device ID is sent once only after the Preamble.

## The Report Frame

Each bit in the report Frame is defined as followings:

| Bit \# | Length | Description |
| :--- | :--- | :--- |
| $0-3$ | 4 | Start of Frame Identifier b0b1b2b3 = 0001 |
| $4-5$ | 2 | Frame Number - Identifies the frame being sent |
| $6-16$ | 11 | State of Button $1-11$, with ' 1 ' represents closed of the switch |
| $17-19$ | 3 | Z - Value of Vertical Scroll Axis, signed - DOWN scrolling is positive |
| $20-26$ | 7 | Value of $\mathrm{X}-$ movement, signed - RIGHT is positive |


| $27-33$ | 7 | Value of Y - movement, signed - DOWN is positive |
| :--- | :--- | :--- |
| 34 | 1 | P - Transmitter Battery Status, with '1' represents low battery condition |
| $35-38$ | 4 | CRC1 including the frame \#, buttons \& Z |
| $39-42$ | 4 | CRC2 including X , Y \& P |

Total number of bits: 43
Symbol Period: 0.4 ms
Inter-Frame Idle time: 2.8 ms
The same trackball status can be sent up to 4 times. The receiver should ignore any report Frame with Frame number larger than zero if a valid report frame with smaller frame number was received.


REPORT FRAME FORMAT

## Bit Ordering

The low significant bit is sent first and the most significant bit is sent last.

## Error Checking

The validity of the packet is ensured by two 4-bit CRC checksums. The following describes the CRC checksum provided by KGT.

The checksum is generated based on 16 bits of data with polynomial $x^{4}+x^{2}+x^{1}+1$. In the KGT documents, "gripcrc.inc" \& "crcgen.inc", a table driven CRC algorithm which involve a 256-entry table (included in Appendix 1) are introduced:

1. Append ' 0 ' to the LSB to make it a 16 bit data if data is less than 16 bits.
2. Look up the CRC table indexed by the MSB of the 16 bit data.
3. XOR the result with the LSB of the 16 bit data.
4. Look up the CRC table indexed by the result in step 3.
5. The higher 4 bits is taken as the CRC for the 16 -bit data.

There is no error recovery scheme provided. The receiver should drop any error packet and keep looking for the good packets.

## Operands for CRC1 and CRC2 Evaluation

Operands for CRC1 is defined below:

|  | b 7 | b 6 | b 5 | b 4 | b 3 | b 2 | b 1 | b 0 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Higher Order | sw 6 | sw 5 | sw 4 | sw 3 | sw 2 | sw 1 | fm 1 | fm 0 |
| Lower Order | z 2 | z 1 | z 0 | sw11 | sw10 | sw 9 | sw 8 | sw 7 |

Operands for CRC2 is defined below:

|  | b 7 | b 6 | b 5 | b 4 | b 3 | b 2 | b 1 | b 0 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Higher Order | y 0 | x 6 | x 5 | x 4 | x 3 | x 2 | x 1 | x 0 |
| Lower Order | 0 | P | y 6 | y 5 | y 4 | y 3 | y 2 | y 1 |

Where:
$\mathrm{fm} 0, \mathrm{fm} 1$ are bits for Frame Number.
sw1 to sw 11 are switch status.
x 0 to x 6 are x -axis offset.
y 0 to y 6 are y -axis offset.
z 0 to z 2 are z -axis offset.
$P$ is the battery status

## Electrical Signals

## Preamble

The preamble is a series of four 'hi and 'lo' pairs. The preamble is provided to condition the receiver and detection circuit before receiving any data. Only one preamble is sent after the transmitter wakes up. The absolute level of the Preamble may be inverted.


The PREAMBLE

## Inter-Frame Idle - 2.8ms

The IFI or Inter-Frame Idle time is the period at which there is no transition. The level can be high or low. If there is another Report Frame following the IFI, the level toggles after the IFI for the receiver firmware to synchronize the symbols. However, the level will or will not toggle if there is no other Report Frame after the IFI.

## Miller Code Modulation

The Data in the Report Frame is encoded by Miller Code. The rules for the encoding scheme are:

1. "One" is represented by a signal transition at the midpoint of the symbol period.
2. "Zero" is represented by no transition unless 3 .
3. For "Zero" followed by another "Zero", a transition is placed at the end of the symbol period of the first symbol.


The advantages of Miller Code modulation are:

1. The bandwidth is only $1 / 2$ of the bit rate.
2. No D.C. component.
3. The absolute polarity of the signal level is not important

However, the receiver firmware must be able to deduce the transition timing relative to the beginning of a symbol period.

## System Specifications

## RF Specification

A simple data transmitter/receiver pair operating in the "Radio Control" Band at 27 MHz
Channels:
26.995MHz - Channel 1 27.195MHz - Channel 2

Bandwidth: 8 kHz
Modulation: FSK
Deviation: $+/-2 \mathrm{kHz}$
Data Rate: $\quad 2.5 \mathrm{kbps}$
Max. Modulation Frequency: $1 / 2$ data rate $=1.25 \mathrm{kHz}$ (square wave)
Min. Modulation Frequency: $1 / 4$ data rate $=625 \mathrm{~Hz}$ (square wave)
Transmitter Output Power: $\quad-5 \mathrm{dBm}$ into antenna approx.
Oscillation Stability: $\quad$ transmitter \& receiver crystal controlled $+/-100 \mathrm{ppm}$
Channel Switching: by mechanical switch

## Power Source

- Transmitter - 2 AAA Alkaline Battery (1100mAh)
- Battery Life - T.B.D.
- Low Battery Threshold Voltage - T.B.D.
- Low Battery Shutdown Voltage - 2V


## Input Devices

- 2 - axes quadrature encoder for $\mathrm{X}-\mathrm{Y}$ position encoding
- 1 - axes quadrature scroller for Z position encoding
- 11 - input buttons

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## Appendix

## 1. CRC Table

| Data | CRC | Data | CRC | Data | CRC | Data | CRC | Data | CRC | Data | CRC | Data | CRC | Data | CRC |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 00h | 32 | 40h | 64 | 80h | 96 | cOh | 128 | 70h | 160 | 30h | 192 | f0h | 224 | bOh |
| 1 | 70h | 33 | 30h | 65 | f0h | 97 | bOh | 129 | 00h | 161 | 40h | 193 | 80h | 225 | c0h |
| 2 | e0h | 34 | aOh | 66 | 60h | 98 | 20h | 130 | 90h | 162 | dOh | 194 | 10h | 226 | 50h |
| 3 | 90h | 35 | d0h | 67 | 10h | 99 | 50h | 131 | e0h | 163 | a0h | 195 | 60h | 227 | 20h |
| 4 | bOh | 36 | f0h | 68 | 30h | 100 | 70h | 132 | cOh | 164 | 80h | 196 | 40h | 228 | 00h |
| 5 | cOh | 37 | 80h | 69 | 40h | 101 | 00h | 133 | b0h | 165 | f0h | 197 | 30h | 229 | 70h |
| 6 | 50h | 38 | 10h | 70 | d0h | 102 | 90h | 134 | 20h | 166 | 60h | 198 | aOh | 230 | eOh |
| 7 | 20h | 39 | 60h | 71 | a0h | 103 | e0h | 135 | 50h | 167 | 10h | 199 | d0h | 231 | 90h |
| 8 | 10h | 40 | 50h | 72 | 90h | 104 | d0h | 136 | 60h | 168 | 20h | 200 | e0h | 232 | a0h |
| 9 | 60h | 41 | 20h | 73 | e0h | 105 | a0h | 137 | 10h | 169 | 50h | 201 | 90h | 233 | d0h |
| 10 | f0h | 42 | bOh | 74 | 70h | 106 | 30h | 138 | 80h | 170 | coh | 202 | 00h | 234 | 40h |
| 11 | 80h | 43 | cOh | 75 | 00h | 107 | 40h | 139 | f0h | 171 | bOh | 203 | 70h | 235 | 30h |
| 12 | a0h | 44 | eOh | 76 | 20h | 108 | 60h | 140 | dOh | 172 | 90h | 204 | 50h | 236 | 10h |
| 13 | d0h | 45 | 90h | 77 | 50h | 109 | 10h | 141 | a0h | 173 | e0h | 205 | 20 h | 237 | 60h |
| 14 | 40h | 46 | 00h | 78 | cOh | 110 | 80h | 142 | 30h | 174 | 70h | 206 | bOh | 238 | foh |
| 15 | 30h | 47 | 70h | 79 | bOh | 111 | f0h | 143 | 40h | 175 | 00h | 207 | c0h | 239 | 80h |
| 16 | 20h | 48 | 60h | 80 | a0h | 112 | e0h | 144 | 50h | 176 | 10h | 208 | dOh | 240 | 90h |
| 17 | 50h | 49 | 10h | 81 | d0h | 113 | 90h | 145 | 20h | 177 | 60h | 209 | aOh | 241 | eOh |
| 18 | cOh | 50 | 80h | 82 | 40h | 114 | 00h | 146 | b0h | 178 | f0h | 210 | 30h | 242 | 70h |
| 19 | bOh | 51 | f0h | 83 | 30h | 115 | 70h | 147 | c0h | 179 | 80h | 211 | 40h | 243 | 00h |
| 20 | 90h | 52 | d0h | 84 | 10h | 116 | 50h | 148 | e0h | 180 | a0h | 212 | 60h | 244 | 20h |
| 21 | e0h | 53 | a0h | 85 | 60h | 11 | 20h | 149 | 90h | 181 | d0h | 213 | 10h | 245 | 50h |
| 22 | 70h | 54 | 30h | 86 | f0h | 118 | bOh | 150 | 00h | 182 | 40h | 214 | 80h | 246 | coh |
| 23 | 00h | 55 | 40h | 87 | 80h | 119 | cOh | 151 | 70h | 183 | 30h | 215 | f0h | 247 | bOh |
| 24 | 30h | 56 | 70h | 88 | bOh | 120 | f0h | 152 | 40h | 184 | 00h | 216 | coh | 248 | 80h |
| 25 | 40h | 57 | 00h | 89 | coh | 121 | 80h | 153 | 30h | 185 | 70h | 217 | bOh | 249 | f0h |
| 26 | d0h | 58 | 90h | 90 | 50h | 122 | 10h | 154 | aOh | 186 | eOh | 218 | 20h | 250 | 60h |
| 27 | a0h | 59 | e0h | 91 | 20h | 123 | 60h | 155 | d0h | 187 | 90h | 219 | 50h | 251 | 10h |
| 28 | 80h | 60 | cOh | 92 | 00h | 124 | 40h | 156 | f0h | 188 | bOh | 220 | 70h | 252 | 30h |
| 29 | f0h | 61 | bOh | 93 | 70h | 125 | 30h | 157 | 80h | 189 | c0h | 221 | 00h | 253 | 40h |
| 30 | 60h | 62 | 20h | 94 | e0h | 126 | a0h | 158 | 10h | 190 | 50h | 222 | 90h | 254 | dOh |
| 31 | 10h | 63 | 50h | 95 | 90h | 127 | d0h | 159 | 60h | 191 | 20h | 223 | eOh | 255 | aOh |

