

XT6360 User Guide

Version 1.0



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Document Change History

Revision	Date	Changes
1.0	4/24/2015	Initial Release (NB)



XIRGO TECHNOLOGIES

Hardware Specification:

Cellular Wireless Technology:

2G/GSM/GPRS/EGPRS: 850/900/1800/1900 Bands - Models: XT6360 / XT6355

3G (UMTS): 850/1900 Bands (Bands V, II) - **Models: XT6360**

CDMA (1xRTT): 850/1900 Bands - Models: XT6360

Parameter	Spec
GPS Specification	
Receiver	56 channels
Receiver tracking sensitivity	-162 dBm
Receiver Cold Start	-148dBm
CEP Accuracy	+/- 2.5m
TTF	
- Cold Start	<29 sec
- Hot Start	< 1 sec
HW Options:	
3-axis Accel.	
BT/BTLE	
Last Gasp Back-up Battery	Internal 250 mAh rechargeable Li-Ion
Power Requirements	
D.C. Power	9-32V
Physical Connection	
Data Connector	24-pin Molex Main 14-pin Molex OBD/J-Bus
Antenna: Cellular/GPS /BT	Internal
SIM Access (2G/3G)	N/A
Programming	Serial Xirgo Device Manager (XDMI)
Mechanical	
Case Material	PC2407, Black
Dimension	3.05" x 3.08" x 0.8"
Weight	3 oz.
Operating Temperature	-30C to +75C
Certifications	
Product	(CDMA) FCC ID: GKM-XT6360 (3G): FCC ID: GKM-XT6360 IC: 10281A-XT6360
Carrier	Verizon, ATT

Notes:

TTF: All satellites at -130 dBm ; Accuracy: CEP, 50%, 24 hours static, -130 dBm, > 6 SVs

Connectors IO Interface:

Main 24-pin Molex Connector (IO Interface):

Pin No.	Pin Name	Comments
1	12/24 Volt Power	
2	LED+12V	w/5K limiting resistor (panic LED)
3	Ground	Main Battery GND
4	Ign Out	Buzzer +12V/24V with 560 ohm
5	IN0	Ignition Sense
6	IN1	
7	IN2	
8	IN3	Panic: pin3 on panic 4-pin Molex
9	IN4	
10	OUT0	Buzzer GND
11	OUT1	
12	OUT2	Panic: pin4 (LED) on panic 4-pin Molex
13	Garmin PWR	12V/2A Switched
14	Serial Port-1 TX	Garmin FMI Tx
15	Serial Port-1 RX	Garmin FMI Rx
16	Serial Port-1 GND	Garmin FMI GND
17	Serial Port-2 TX	
18	Serial Port-2 RX	
19	Serial Port-2 GND	
20	1-Wire Serial Main	iButton Data (default)
21	1-Wire Serial Sec.	
22	Ext. ADC	
23	Spare GND	Panic GND
24	Spare GND	

OBD 14-pin Molex connector (OBD2/JBUS/SWC):

J1962 OBD2 Pin No.	XT6360 Pins	XT6360 Pin Description	9 Pin J-Bus	6 Pin J-Bus
6	1	CAN_HS_H	C	
	2	J1708_RXD	G	B
	3	J1708_TXD	F	A
15	4	L_LINE		
10	5	J1850_NEG		
2	6	J1850_POS		
	7			
14	8	CAN_HS_L	D	
3	9	CAN_MS_H		
11	10	CAN_MS_L		
1	11	SWC_BUS		
7	12	K_LINE		
5&4	13	GND	A	E
16	14	Vehicle Power (VBAT)	B	C

Cable Harness Specification:

- 24-pin Microfit: Molex 43025-2400
- Panic SW/LED Button Conn. Molex 43020-0401 (4 pin 2 row female shell)
- I-Button Conn.: Molex 43640-0201 (2 pin Female Shell)
- Buzzer Conn.: Molex 43640-0301 (3 pin Female Shell)
- Garmin Conn. Molex 43020-1001 (10 pin 2 row female shell)
- Garmin pins 2 and 4 looped-in (black wire, 26 AWG)
- Molex male pins: 43031-0002
- Total length: 5 ft.
- Pins 1, 3, and 5 are 18 AWG, All others are 24 AWG.
- Fuse: 3A in line with pins with pins 1 (red) and 5 (white), 7 in. from wire end
- Wires 1, 3, and 5 to be jacketed up to the fuse

24-pin No.	Color	Length	AWG	Pin function	Comments	I-Button	Buzz.	Panic SW LED	Garmin
1	Red	60 in.	18	VBAT	3A fuse, 7 in. from end				
2	Orange	7 in.	20	LED+12V				3	
3	Black	60 in.	18	Ground					
4	White	7 in.	20	Ign Out			1		
5	White	60 in.	18	IN0	3A fuse, 7 in. from end				
6	Gray	60 in.	20	IN1					
7	Brown	60 in.	20	IN2					
8	Blue	7 in.	20	IN3				1	
9	Red	60 in.	20	IN4					
10	Brown	7 in.	20	OUT0	Buzzer GND		2		
11	Orange	60 in.	20	OUT1					
12	Yellow	7 in.	20	OUT2				4	
13	Red	7 in.	20	Garmin PWR	12V/2A Switched				5
14	White/Brown	7 in.	20	Serial Port-1 TX	Garmin FMI Tx				1
15	Green	7 in.	20	Serial Port-1 RX	Garmin FMI Rx				6
16	Orange/Brown	7 in.	20	Serial Port-1 GND	Garmin FMI GND				4
17	Yellow	7 in.	20	Serial Port-2 TX					
18	Green	7 in.	20	Serial Port-2 RX					
19	Black	7 in.	20	Serial Port-2 GND					
20	Gray	7 in.	20	1-Wire Serial Main	i-Button	1			



21	White	60 in.	20	OWB2					
22	Purple	60 in.	20	Ext. ADC					
23	Black	7 in.	20	Spare GND	Panic GND			2	
24	Blue/Green	7 in.	20	Spare GND		2			

LED Definition

BASE UNIT	LED	Description	Status
	Cellular (Amber)	Searching for Cellular Network	LED OFF
		Cellular Carrier Lock	Solid
	GPS (Green)	Searching for satellite	Solid
		GPS Lock	Blinking
Optional	Bluetooth (Blue)	TBD	TBD

Current Consumption

OPERATING MODE	CURRENT CONSUMPTION
Deep Sleep (non-functional mode)	3 mA
Standby	10 mA
Active Receive	65 mA

Device Mounting:

The XT6360 device must be securely installed. The accelerometer will not calibrate if unit is loose when vehicle is in motion. When mounting the device, use a tie strap to secure the device as noted below.



PC Device Configuration:

- a. A RS-232 to USB TTL converter cable is required to connect an XT6360 device to a computer for local configuration. Serial Port # 2 is used for configuration. Connect the XT6360 Tx wire to the TTL converter cable Rx wire. Connect the XT6360 Rx wire to the TTL converter cable Tx wire. Connect the XT6360 ground wire to the ground wire of the TTL converter cable. Use a terminal application to connect to the COM port associated with the TTL converter cable. Use the following settings:
 - A. Terminal Application Settings:
 - a. Bits per second: 115200
 - b. Data bits: 8
 - c. Parity: None
 - d. Stop bits: 1
 - e. Flow control: None
 - B. Load Script File with the following command
 - a. :grscr x 2
 - C. Load Parameter File with the following command
 - a. :uyscr x 2
 - D. Save the configuration
 - a. :vycfg

Feature Matrix:

Technology	1XRTT
Feature Highlight	XT-4550
Locate	X
Idle	X
Vehicle Disable	X
5 Digital IO	X
2 - 1 Wire Bus	X
Ignition On/Off	X
Mileage	X
Periodic Reporting	X
Speed	X
Direction Change	X
Battery Voltage	X
Battery Disconnect	X
Tow Alerts	X
Movement Start/Stop	X
Acceleration/Deceleration	X

Park Time	X
Virtual Odometer	X
Quick Fence	X
Device Diagnostics	X
Motion	X
Accelerometer	X
Geo-Zones	50 Circular
Back Up Battery	250mAh
Communication Protocol	TCP, UDP, UDPwACK
Firmware Download	FTP

Device Configuration

The XT6360 is a full-feature device based on a platform that allows rapid customization by market and application requirements. The XT6360 series offers highly configurable firmware which allows full control of device reporting behavior. The customizable messages provides only the data required to support unique and evolving business needs. The XT6360 configuration is accomplished by loading 2 files:

Script File

Parameter File

The **Script File** is the file that triggers the alerts and actions of the XT6360 .

The **Parameter File** specifies values used to configure hardware peripherals, network behavior, and inputs to core functionality of the XT6360 .

Script File

A Script file can contain an unlimited number of Triggers. When scripting the Triggers are group into individual Trigger blocks. A trigger block is comprised of the following sections:

Trigger
 Conditional Actions - optional
 Actions

EXAMPLE:

```
trigger when Eq(InputState(0), 1) [Debounce(0, 0)]
  conduct always
  actions
    run BuildAndSendMsg(0, 2, 0, 0)
```

DESCRIPTION:

When ignition goes high a message is sent to the server.

Important notes on Scripting:

1. Each Trigger Block has one Trigger.
2. The Trigger must test true for an action to occur.
3. A test is usually made of one comparison. See Comparison table.
4. Each Trigger Block can contain unlimited Conditional Action Blocks.
5. Trigger Blocks and Conditional Action block will use the following when building a script:
 - a. System Values
 - b. Events
 - c. Special Functions
 - d. Numbers
6. Each Conditional Action Block may optionally contain one Conditional Action Block Test.
7. A Conditional Action Block Test may contain up to 5 comparisons (Using same “any” or “all” logic as described for Trigger Block Test).
8. Each Conditional Action Block must contain one Action Block.

How Trigger Block Tests Work

Each Trigger Block is entered when the Trigger Block Test becomes true. Note that the Trigger Block is NOT entered WHILE the Test IS true, only the moment it becomes true. For example if you want to trigger actions when vehicle speed goes above 80 km/hr:

```
trigger when Gt(GPSSpeed, 80) [Debounce(0, 0)]
```

The interpreter will enter the trigger block at the moment the vehicle speed increases above 80 km/hr. It will not continue to enter the trigger block during subsequent evaluations where the speed remains above 80 km/hr. Once the speed drops below 80 (for at least one evaluation), then the trigger block will be entered again next time the speed increases above 80 km/hr.

Note that if the speed oscillates between 80.0 and 80.1 km/hr it is possible to cause the actions to be executed as frequently as the speed oscillates. In order to avoid this, make use of the debounce specifiers.

How Conditional Action Block Tests Work

Unlike Trigger Block Tests, Conditional Action Block Tests allow the action to be performed WHILE the test is true. Continuing with the example above, let's say we want to further limit our actions to only execute the moment speed goes above 80 km/hr AND only when the vehicle heading is within 10 degrees of North:

```
trigger when Gt(GPSSpeed, 80) [Debounce(0, 0)]
contact any          InRange(GPSHeading, 3500, 3600) [Debounce(0, 0)]
                    InRange(GPSHeading, 0, 100) [Debounce(0, 0)]
actions
```

All Conditional Action blocks are independent. One is not dependent on the other.

- | | |
|-----------------------|---|
| Contact Always | This means the actions inside a Conditional Action Block will ALWAYS run when the trigger Block's test(s) are true. |
| Contact When | When only one comparison is used |
| Contact Any | The test is true when ANY of the comparisons is true. |
| Contact All - | ALL comparisons must be true for test to be true. |

COMPARISONS TABLE:

COMPARISON	DESCRIPTION
InRange(<a>, , <c>)	True when argument a is between argument b and argument c (inclusive)
NotInRange(<a>, , <c>)	True when a is less than b or a is greater than c. b must be less than c.
Eq(<a>,)	True when a equals b.
NotEq(<a>,)	True when a is not equal to b.
Gt(<a>,)	True when a is greater than b.
Lt(<a>,)	True when a is less than b.
GtEq(<a>,)	True when a is greater than/equal to b.
LtEq(<a>,)	True when a is less than/equal to b.

Test items (<a>, , <c> above) should be one of:

- System Value
- Event
- Special Function
- Numbers (constants)

Note:

See Appendices for Complete Tables

Debounce

Debounce(<hi>, <lo>) - where *hi* and *lo* are specified in seconds (max: 15). The 'Debounce Specify' is only used following certain tests (see below). When a debounce is specified, it means that a test is true only AFTER the comparison is true for *hi* seconds, and it is false only AFTER the comparison is false for *lo* seconds.

A test debounce MUST be specified any time the first argument in the test is either:

- System value
- Special function.

Parameter File

The parameter file is the setting for all of the XT6360 hardware peripherals, network behavior, and inputs to core functionality of the XT6360. The following table contains all the parameters that can be configured in a XT6360:

Acceleration event thresholds	Accelerometer report correction	APNs (GSM only)
Crash event params	Debounce settings	Destination
ECU_Thresholds	Flag save mask	Garmin Blacklist
Geofence	Input default polarity	Ignition sense
MIP/SIP Control (<i>TBD</i>)	Motion sensitivity	NMEA stream output
Odom Ign Off accum	Packet Creation Append	Packet Creation Recipe
Packet Retry	Serial port settings	Timer duration
OBD RPM and Speed	OBD Accel and Decel	Variable save mask

See Appendix C for Parameter settings.

Creating a Parameter File:

1. The parameter settings are written and saved as a .txt file.
2. Use **:wycfg** in front of the parameter your are configuring.
3. To load the parameter file you can use XDMI or load the file over Serial Port 2.
 - a. Load via Serial port use the following commands
 - i. **:uyscr x 2** load the file
 - ii. **:wycfg** Save the parameter file

Below is an example of a parameter file.

```

:wycfg pdo 0 1
:wycfg dst[0] "71.24.53.116" 65534
:wycfg dst[9] "none" 65535
:wycfg pcr[0] "00080104030607080b17"
:wycfg pcr[1] "01050103070809"
:wycfg pcr[2] "02140104535455565758595a5b5c5d5e5f6061622c2e"
:wycfg pcr[3] "030701040305060708"
:wycfg pcr[4] "040701040305060708"
:wycfg pcr[5] "050701040305060708"
:wycfg pcr[6] "06080104030607080b17"
:wycfg pcr[7] "07080104030607080b17"
:wycfg pcr[8] "08040104060c"
:wycfg tmr[0] 90 1
:wycfg tmr[1] 90 1
:wycfg aet[0] 0 1000 1000 205

```

Messages

How to create a Message

The XT6360 custom message allows users to select what fields of data to be sent in a message when triggered. A message can contain up to 40 data fields and you can have up to 128 different messages.

Refer to Appendix F - Message Field Table

When defining a Message use the following syntax:

```
pcr[<slot_index>] "<recipe_hex_string>"
```

- where:
 - <slot_index> is in the range 0 - 127
 - "<recipe_hex_string>" is a quoted string of hexadecimal bytes (represented by two ascii characters) The **Message Field Table** in Appendix F contains the **Hex** values for the individual fields that can be selected to create the Packet.
 - String format: "<recipe_id><num_fields><field_0><field_1>...<field_N>"

EXAMPLES

- **pcr[0] "0003010306"**
 - pcr slot 0 will contain a Recipe string with 3 fields: PacketID, DeviceID, and GpsSpeed
 - recipe_hex_string - "000301030b"

▪ RecipeID	00 (Hex)
▪ Number of fields	03 (Hex)
▪ Field 0 is Packet ID	01 (Hex)
▪ Field 1 is DeviceID	03 (Hex)
▪ Field 2 is GpsSpeed	0b (Hex)

Notes:

- The device can store and use 128 pcr (messages)
 - :wycfg pcr[0] :wycfg pcr[127]
 - RecipeID is always in Hex.
- **pcr[1] "14050103070809"**
 - pcr slot 1 will contain a Recipe string with 5 fields : PacketID, DeviceID, Latitude, Longitude, and Altitude
 - recipe_hex_string - "14050103070809"

• RecipeID	01
• Number of fields	05
• Field 0 is Packet ID	01
• Field 1 is DeviceID	03
• Field 2 is Latitude	07
• Field 3 is Longitude	08
• Field 4 is Altitude	09

pcr Breakdown

A pcr is a list of fields that will be used to create a message to be sent from the XT6360 to the server.

- Each packet recipe can contain up to 40 fields
- The device can store 128 packet recipes

pcr[<slot_index>] "<recipe_hex_string>"

<slot_index> is in the range 0 - 127

"<recipe_hex_string>" is a quoted string of hexadecimal bytes (represented by two ascii characters)

String format: "<packet_id><num_fields><field_0><field_1>...<field_N>"

Example:

pcr 1 will contain a 5 fields : PacketID, DeviceID, Latitude, Longitude, and Altitude

```
pcr[1] "01050103070809"
```

RecipeID	01
Number of fields	05
Field 0 is Packet ID	01
Field 1 is DeviceID	03
Field 2 is Latitude	07
Field 3 is Longitude	08
Field 4 is Altitude	09

Below is an example of a packet recipe that is partially decoded.

EXAMPLE:

```
pcr[1] "010E01040305060708090a0b12131415"
```

(all values below are in Hex)

Recipe ID	01			
Number of fields	0E			
Field	HEX ID	Value	Parsed	Comment
PacketID	01	01	01	
ReasonCode	04	03	03	(IGN. OFF MESSAGE)
Serial #	03	088c1c72	143400050	Unit Serial Number
PacketSerialNum	05	205a	8282	
Etc..				

DATA FROM DEVICE CONVERTED FROM BINARY TO HEX USED IN TABLE ABOVE

datagram: 4 from 75.255.159.0:3000 (size: 31 bytes)

HEX-----

01 03 08 8c 1c 72 20 5a 54 81 be e1 01 f7 fb dd

fa 3a 18 7a 07 0c 0a 1e 01 1c 04 00 15 ff ff

Acknowledgements

Currently the XT6360 supports a simple acknowledgement consisting of four bytes (88-88-xx-xx) where xx-xx is the packet serial number. You will want to send the 88-88 header and return the serial number of the packet sent to you, in the third and fourth byte. Therefore, the XIRGO unit will only accept an acknowledgement payload of 88-88-01-04 for a packet sent with packet serial number 260 (hex 01-04).



Appendix A

SYSTEM VALUES

VALUE	DESCRIPTION
UnixTime	Seconds since midnight Jan 1, 1970.
GPSLat	Degrees of latitude (unit 0.000001 degree)
GPSLon	Degrees of longitude (unit 0.000001 degree)
GPSAlt	Height above sea level (unit 0.1 meter)
GPSHeading	Heading of travel (unit 0.1 degree)
GPSSpeed	2D speed in km/hr.
Inputs	User Input states
Outputs	User Output states
DriverId1	Most recent Driver ID detected on 1 wire bus channel 1
DriverId2	Most recent Driver ID detected on 1 wire bus channel 2
OdomDelta	Current value of Trip odometer 1 (in meters)
GPSHDOP	GPS Horizontal dilution of precision (unit 0.1)
GPSNumSats	Number of GPS satellites used for navigation solution.
GPSOdom	Virtual odometer in meters
OdomDiff	TBD
BattVoltage	Device External voltage (vehicle system voltage, unit 0.1V)
InternVoltage	Device Internal voltage (unit 0.1V)
MotionState	1 when vehicle is moving (as reported by ECU), otherwise 0.
EngineState	1 when engine has RPM (as reported by ECU), otherwise 0.
WakeReason	Bit mask value representing the reason for waking from sleep: 0x00 = Woke on SMS or UDP message received 0x01 = Woke on Wired Ignition 0x02 = Woke on Input 1 0x04 = Woke on Input 2 0x08 = Woke on Input 3 0x10 = Woke on Input 4 0x20 = Woke periodic 0x40 = Woke on vibration detected 0x80 = Woke on supply voltage > 13.2V

Appendix B

EVENT TABLE

EVENT	DESCRIPTION	INDEX RANGE
TimerExpired(<index>)	Evaluates to 1 when timer is expired, otherwise 0	index is in the range 0 - 31
UserEventIsActive(<index>)	Evaluates to 1 when a user event has been injected into interpreter, otherwise 0	index is in the range 0 - 255.
	Use :xrmsg <index> to inject a message into interpreter. (Must be caught in interpreter script with this event function)	
AccelEventIsActive(<index>)	Evaluates to 1 when an accelerometer event is detected, otherwise 0	index is in the range 0 - 3.
GarminResponseReceived(<index>)	Evaluates to 1 when a non-blacklisted Garmin response is received (and Garmin is active), otherwise 0	index is in the range 0 - 5. 0 = Ack (or Nak) packet (only triggered when specified in SendGarminMsg()) 1 = Unit ID (a.k.a. Garmin ESN) response 2 = Product ID response 3 = Throttle Message response 4 = Ping response 5 = Generic response; any response that isn't listed above and isn't blacklisted
GarminUserPayloadReceived(<index>)	Evaluates to 1 when a payload (destined for garmin device) has been received, otherwise 0	index can only be 0. This signals that a payload has been sent to the device by a user/server. Typically this would be used to trigger a SendGarminMsg() action.
DriverIdRead(<index>)	Evaluates to 1 when driver id is detected on 1-wire channel <index>, otherwise 0	index is in the range 0 - 1
SystemEventIsActive(<index>)	Evaluates to 1 when system event <index> is active, otherwise 0.	index is in the range 0 - 17. 0 = Reset 1 = Wakeup 2 = BootloaderUpgrade (TBD) 3 = FWUpgrade 4 = ScriptUpgrade 5 = ParamSetUpgrade 6 = OverlayUpgrade 7 = ManualConfigChange 8 = CellRegistrationChange 9 = IPChange 10 = SMSReceived 11 = SMSSendOK 12 = SMSSendFailure 13 = UDPReceived 14 = UDPSendOK 15 = UDPSendFailure 16 = PacketStorageEmpty 17 = PacketStorageFull



Appendix C SPECIAL FUNCTION TABLE

Special Function	Description	Index Range
UserVar8(<index>)	Evaluates to value stored in user variable	index is in the range 0 - 15
UserVar16(<index>)	Evaluates to value stored in user variable	index is in the range 0 - 7
UserVar32(<index>)	Evaluates to value stored in user variable	index is in the range 0 - 7
FlagsSet(<index>)	Evaluates to 1 when flag is set, otherwise 0	index is in the range 0 - 31
GeofenceState(<index>)	Evaluates to: -1=<index> is not configured 0=outside fence 1=inside fence	index is in the range 0 - 49
InputState(<index>)	Evaluates to 1 when input is high/when condition is true, otherwise 0	index is in the range 0 - 6. 0 = Ignition 1 = Input 1 2 = Input 2 3 = Input 3 4 = Input 4 5 = Device in motion (via GPS) 6 = Vehicle Battery > Threshold 7 = Accelerometer reorientation validity
SystemState(<index>)	Evaluates to 1 when true, otherwise 0	index is in the range 0 - 16. 0 = Valid Registration 1 = Valid IP 2 = Valid GPS 3 = Valid Script 4 = DM Session Active 5 = Accel Oriented 6 = Bluetooth Discoverable(TBD) 7 = Bluetooth Paired(TBD) 8 = Bluetooth Authenticated(TBD) 9 = Bluetooth Connected(TBD) 10 = Bluetooth Powered(TBD) 11 = Cellular Powered 12 = GPS Powered 13 = Garmin Powered 14 = Motion Via Accel 15 = Motion Via GPS 16 = External Power



Appendix D

ACTIONS TABLE

Action	Syntax
Reset Device	ResetDevice()
Reset Modem	ResetModem()
Reset GPS	ResetGPS()
Turn Off GPS	TurnOffGPS()
Turn On GPS	TurnOnGPS()
Set User Variable	<p>SetUserVar(<type>, <index>, <value>)</p> <p>type is in the range 0 - 2 where: 0 = 8bit variable 1 = 16bit variable 2 = 32bit variable</p> <p>index is in the range: 0 - 15 for 8bit variables 0 - 7 for 16bit variables 0 - 7 for 32bit variables</p> <p>value is in the range: -128 to 127 for 8bit variables -32768 to 32767 for 16bit variables -2147483648 to 2147483647 for 32 bit variables</p>
Adjust User Variable	<p>AdjustUserVar(<type>, <index>, <adjust_amount>)</p> <p>type is in the range 0 - 2 where: 0 = 8bit variable 1 = 16bit variable 2 = 32bit variable</p> <p>index is in the range: 0 - 15 for 8bit variables 0 - 7 for 16bit variables 0 - 7 for 32bit variables</p> <p>adjust_amount is in the range: -128 to 127 for 8bit variables -32768 to 32767 for 16bit variables -2147483648 to 2147483647 for 32 bit variables</p>
Set Flag	<p>SetFlag(<flag_index>)</p> <p>index is in the range 0 - 31.</p>
Clear Flag	<p>ClearFlag<flag_index>)</p> <p>index is in the range 0 - 31.</p>
Start Timer	<p>StartTimer(<timer_index>)</p> <p>index is in the range 0 - 31.</p>
Stop Timer	<p>StopTimer<timer_index>)</p> <p>index is in the range 0 - 31.</p>
Rest Timer	<p>ResetTimer(<timer_index>)</p> <p>index is in the range 0 - 31.</p>



ACTION	SYNTAX
Build And Send Msg	<p><packet_id>, <reason_code>, <destination_id>, <ack>)</p> <p>packet_id is in the range 0 – 255. reason_code is in the range 0 - 255. destination_id is in the range 0 - 9. One of the destinations servers dst[x] ack is in the range 0 - 1 0 = No Acknowledgement needed 1 = Resend until acknowledged</p>
Clear Log	TBD
Enter Deep Sleep	<p>EnterDeepSleep(<wake_mask>, <wake_minutes>)</p> <p>wake_mask is in the range 0x00 - 0xFF where: 0x01 = Wake on Wired Ignition 0x02 = Wake on Input 1 0x04 = Wake on Input 2 0x08 = Wake on Input 3 0x10 = Wake on Input 4 0x20 = Wake after wake_minutes 0x40 = Wake on vibration detected 0x80 = Wake on supply voltage > 13.2V</p>
Enter Sleep	<p>EnterSleep(<wake_mask>, <wake_minutes>)</p> <p>wake_mask is in the range 0x00 - 0xFF where: 0x00 = Wake on SMS or UDP message received 0x01 = Wake on Wired Ignition 0x02 = Wake on Input 1 0x04 = Wake on Input 2 0x08 = Wake on Input 3 0x10 = Wake on Input 4 0x20 = Wake after wake_minutes 0x40 = Wake on vibration detected 0x80 = Wake on supply voltage > 13.2V</p>
Set Garmin Power	<p>SetGarminPower(<power_state>)</p> <p>power_state is in the range 0 - 1 where: 0 = Off 1 = On</p>
Send Garmin Msg	TBD
Clear Trip Odom	<p>ClearTripOdom(<odom_index>)</p> <p>index is in the range 0 - 1.</p>
Set Output	<p>SetOutput(<output_index>)</p> <p>index is in the range 0 - 3</p>
Clear Output	<p>ClearOutput(<output_index>)</p> <p>index is in the range 0 - 3.</p>
Pulse Output	<p>PulseOutput(<output_index>, <seconds_on>)</p> <p>index is in the range 0 - 3. seconds_on is in the range 1 - 65535.</p>



Flash Output	FlashOutput(<output_index>, <blink_rate>) index is in the range 0 - 3. blink_rate is in the range 1 - 65535Hz.
Clear Driver Ids	ClearDriverIds()
Device Check In	CheckInNow()



Appendix E

PARAMTER TABLE

Acceleration event thresholds	8	aet	4	<direction (adlr)> <start_duration> <end_duration> <mg_thresh>
Accelerometer report correction	1	arc	1	<correction_factor>
APNs	4	apn	3	"<apn_name>" "<username>" "<password>"
Crash event params	1	cep	3	<mg_thresh> <poll_freq> <hist_depth>
Debounce settings	6	idb	2	<on_sec> <off_sec>
Destination	10	dst	2	"<ip> <hostname>" <port> <serial_port_id>
ECU_Thresholds	1	vth	4	<brake_thresh> <accel_thresh> <speed_limit> <rpm_limit>
Flag save mask	1	fsm	1	<32bit_mask>
Garmin Blacklist	16	gbl	5	<flags> <pid> <size> <byte0> <byte1> <i>(see example below)</i>
Geofence	50	gfn	3	<lat> <lon> <radius>
Input default polarity	4	idp	1	<pullup_disable> <i>(0=active_low,1=active_high)</i>
Ignition sense	1	ign	3	<source mask> <ign on sec> <ign off sec>
MIP/SIP Control <i>(TBD)</i>	1	mip	1	<value>
Motion sensitivity	1	mst	1	<motion_sensitivity_value>
NMEA stream output	4	nso	1	<8bit_mask> <i>(see NMEA mask below. One param for each of the 4 serial outputs)</i>
Odom Ign Off accum	2	oio	1	<accum>
Packet Creation Append	16	pca	1	"<append_hex_string>"
Packet Creation Recipe	128	pcr	1	"<recipe_hex_string>"
Packet Retry	2	prt	1	<sec>
Serial port settings	2	sps	2	<baudrate> "<dps>"
Timer duration	32	tmr	2	<sec> <auto_start>
OBD RPM and Speed	2	ors	2	<rpm threshold> <rpm time sec> <mph threshold> <mph time sec>
OBD Accel and Decel	2	oad	1	<obd accel> <obd decel> (1mph/sec, 1mph increments)
Variable save mask	1	vsm	1	<32bit_mask>

NMEA mask

One bit for each of the available NMEA sentences. Values can be added to stream more than one sentence type. Set mask to zero to stop streaming.

GPGGA 0x01
 GPGLL 0x02
 GPGSA 0x04
 GPGSV 0x08
 GPRMC 0x10



Appendix F MESSAGE FIELDS TABLE

ID	ID Hex	Field	Size	Units	resolution	Range	Notes
1	0x01	PacketID	1	N/A	1	0 to 255	packet recipes can be labelled from 0-255, but there are only 128 recipe slots"
2	0x02	FmCustomHeader	1	N/A	1	0 to 255	value TBD (currently zero)
3	0x03	DeviceId/ Unit Serial #	4	N/A	1	100000000 to 999999999	Unsigned integer representing numeric ESN
4	0x04	ReasonCode	1		1	0 to 255	Unsigned integer
5	0x05	PacketSerialNum	2		1	0 to 65535	Unsigned integer
6	0x06	UnixTime	4		1	0x0 to 0xffffffff	Unsigned integer representing number of seconds since Unix Epoch
7	0x07	Latitude	4	degrees	1.00E-06	-2147.483648 to 2147.483647	Signed integer decimal value of 4byte hex string divided by 1000000 (useful range -180.0 to 180.0)
8	0x08	Longitude	4	degrees	1.00E-06	-2147.483648 to 2147.483647	Signed integer decimal value of 4byte hex string divided by 1000000 (useful range -90.0 to 90.0)
9	0x09	Altitude	2	m	0.1	-2147.483648 to 2147.483647	Signed integer
10	0x0a	Heading	2	degrees	1.00E-01	-3276.8 to 3276.7	Signed integer (useful range 0.0 to 360.0)
11	0x0b	GpsSpeed	1	km/hr	1	0 to 255	Unsigned integer
12	0x0c	InputStates	1	N/A	1	0x0 to 0x1f	bitfield: for example - LSB (bit:0) represents INPUT0
13	0x0d	OutputStates	1	N/A	1	0x0 to 0x7	bitfield: for example - LSB (bit:0) represents OUTPUT0



14	0x0e	DriverIdCode1	4	N/A	1	0 to 4294967295	Unsigned integer represent unique iButton ID
15	0x0f	DriverIdCode2	4	N/A	1	0 to 4294967295	Unsigned integer represent unique iButton ID
16	0x10	OdometerDelta	4	m	1	0 to 4294967295	
17	0x11	Flags	4		1	0 to 4294967295	bitfield
18	0x12	Hdop	1	DOP	0.1	0.0 to 25.5	Unsigned integer
19	0x13	NumSats	1	N/A	1	0 to 255	
20	0x14	ReceiverSigStr	1	dBm	1.23	-113 to -75	
21	0x15	CellularCarrierId	2		1	0x0 to 0xffff	
22	0x16	InternalBattVolts	1	V	0.1	0.0 to 25.5	Possibly using a 2 byte unsigned integer representing mV (0 to 65535)
23	0x17	VehicleBattVolts	1	V	0.1	0.0 to 25.5	Possibly using a 2 byte unsigned integer representing mV (0 to 65535)
24	0x18	LifetimeOdometer	4	m	1	0 to 4294967295	Unsigned integer
25	0x19	AccelStartDateTime	4		1	0x0 to 0xffffffff	Unsigned integer representing number of seconds from Unix Epoch
26	0x1a	AccelStartLat	4	degrees	1.00E-06	-2147.483648 to 2147.483647	Signed integer decimal value of 4byte hex string divided by 1000000 (useful range -180.0 to 180.0)
27	0x1b	AccelStartLong	4	degrees	1.00E-06	-2147.483648 to 2147.483647	Signed integer decimal value of 4byte hex string divided by 1000000 (useful range -90.0 to 90.0)
28	0x1c	AccelStartSpeed	1	km/hr	1	0 to 255	
29	0x1d	AccelStartHeading	2	degrees	0.1	0 to 3599	
30	0x1e	MaxAccel	2	mG	1	0 to 32767	



31	0x1f	AccelEventDuration	1	seconds	0.1	0 to 255	
32	0x20	AccelEndDateTime	4		1	0x0 to 0xffffffff	Unsigned integer representing number of seconds from Unix Epoch
33	0x21	AccelEndLat	4	degrees	1.00E-06	-2147.483648 to 2147.483647	Signed integer decimal value of 4byte hex string divided by 1000000 (useful range -180.0 to 180.0)
34	0x22	AccelEndLong	4	degrees	1.00E-06	-2147.483648 to 2147.483647	Signed integer decimal value of 4byte hex string divided by 1000000 (useful range -90.0 to 90.0)
35	0x23	AccelEndSpeed	1	km/hr	1	0 to 255	
36	0x24	AccelEndHeading	2	degrees	0.1	0 to 3599	
37	0x25	GeofenceId	1	N/A		0 to 49	
84	0x54	ObdOdometer	4	m	1	0 to 4294967295	32-bit unsigned integer
85	0x55	ObdTotFuelUsed	4	liters	1	0 to 4294967295	32-bit unsigned integer
86	0x56	ObdTotEngHours	4	hours	1	0 to 4294967295	32-bit unsigned integer
87	0x57	ObdVehicleSpeed	2	kph	0.1	0 to 2550	16-bit unsigned integer
88	0x58	ObdEngRpm	2	rpm	1	0 to 65535	16-bit unsigned integer
89	0x59	ObdEngCoolantTemp	2	Celsius	1	-40 to 215	16-bit signed integer
90	0x5a	ObdFuelLevelPct	2	%	0.1	0 to 1000	16-bit unsigned integer
91	0x5b	ObdTotDrivingSec	4	s	1	0 to 4294967295	32-bit unsigned integer
92	0x5c	ObdTotCruiseSec	4	s	1	0 to 4294967295	32-bit unsigned integer
93	0x5d	ObdTotIdleSec	4	s	1	0 to 4294967295	32-bit unsigned integer
94	0x5e	ObdTotIdleFuel	4	liters	1	0 to 4294967295	32-bit unsigned integer



95	0x5f	ObdHarshBreakTotCnt	4		1	0 to 4294967295	32-bit unsigned integer
96	0x60	ObdSpeedExceedTotTime	4		1	0 to 4294967295	32-bit unsigned integer
97	0x61	ObdRPMExceedTotTime	4		1	0 to 4294967295	32-bit unsigned integer
98	0x62	ObdHarchAccelTotTime	4		1	0 to 4294967295	32-bit unsigned integer
101	0x65	ObdVIN	17	ascii			

Regulatory Statements:

FCC ID:

Model: XT6360

FCC ID: GKM-XT6360

This product contains FCC ID: XPYSARAU260

FCC Information to User:

The XT6360 does not contain any user serviceable components and is to be used with approved antennas only. Any product changes or modifications will invalidate all applicable regulatory certifications and approvals.

FCC Guidelines for Human Exposure:

The XT6360 complies with FCC radiation exposure limits set forth for an uncontrolled environment. This equipment should be installed and operated with minimum distance of 20 cm between the radiator and your body.

This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

FCC Declaration of Conformity:

The XT6360 complies with Part 15 Subpart B of FCC CFR47 Rules. Operation is subject to the following two conditions:

1. This device may not cause harmful interference, and
2. This device must accept any interference received, including interference that may cause undesired operation.

FCC Radio Frequency Interference Warnings & Instructions:

The XT6360 has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following methods:

1. Reorient or relocate the receiving antenna.
2. Increase the separation between the equipment and the receiver.
3. Connect the equipment into an electrical outlet on a circuit different from that which the radio receiver is connected.
4. Consult the dealer or an experienced radio/TV technician for help.

Industry Canada (IC):

IC: 10281A-XT6360

This product contains IC: 8595A-SARAU260

This device complies with Industry Canada licence-exempt RSS standard(s). Operation is subject to the following two conditions:

- (1) this device may not cause interference, and
- (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio

exempts de licence. L'exploitation est autorisée aux deux conditions suivantes :

- (1) l'appareil ne doit pas produire de brouillage, et
- (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication.

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante.

This radio transmitter (IC: 10281A-XT6360 , Model Number: XT6360) has been approved by Industry Canada to operate with the antenna types listed below with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Cet émetteur radio (identifier le périphérique par numéro de certification, ou le numéro de modèle si Catégorie II) a été approuvé par Industrie Canada pour fonctionner avec les types d'antennes énumérées ci-dessous avec le gain maximal admissible et l'impédance d'antenne requise pour chaque antenne type indiqué. Types d'antennes ne figurent pas dans cette liste, ayant un gain supérieur au maximum gagné indiqué pour ce type, sont strictement interdites pour une utilisation avec cet appareil..