

SAR TEST REPORT

REPORT NO.: SA980812L01-1

MODEL NO.: PoMMeS

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APPLICANT: Thomson Inc

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1. CERTIFICATION

PRODUCT: WiFi Photo Frame

MODEL: PoMMeS

BRAND: THOMSON

APPLICANT: Thomson Inc.

TESTED: Jan. 06, 2010

TEST SAMPLE: ENGINEERING SAMPLE

STANDARDS: FCC Part 2 (Section 2.1093)

FCC OET Bulletin 65, Supplement C (01-01)

RSS-102

The above equipment (model: PoMMeS) has been tested by **Bureau Veritas Consumer** Products Services (H.K.) Ltd., Taoyuan Branch, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample's EMC characteristics under the conditions specified in this report.

___ **, DATE :** ___ Jan. 08, 2010 PREPARED BY

Joanna Wang / Senior Specialist

TECHNICAL

Mason Chang / Engineer, , DATE: Jan. 08, 2010 ACCEPTANCE

Responsible for RF

APPROVED BY



2. GENERAL INFORMATION

2.1 GENERAL DESCRIPTION OF EUT

| EUT | WiFi Photo Frame | | |
|---------------------------------|---|--------------------------------|--|
| MODEL NO. | PoMMeS | | |
| FCC ID | G95TWTG001 | | |
| POWER SUPPLY | 15Vdc (Adapter) | | |
| POWER SUPPLY | 3.7Vdc (Battery) | | |
| MODULATION TYPE | CCK, DQPSK, DBPSK for DS | SSS | |
| MODULATION TYPE | 64QAM, 16QAM, QPSK, BPS | K for OFDM | |
| MODULATION TECHNOLOGY | DSSS, OFDM | | |
| TRANSFER RATE | 802.11b:11.0/ 5.5/ 2.0/ 1.0Mb | ps | |
| TRANSFER RATE | 802.11g: 54.0/ 48.0/ 36.0/ 24.0/ 18.0/ 12.0/ 9.0/ 6.0Mbps | | |
| FREQUENCY RANGE | 2412 ~ 2462MHz | | |
| NUMBER OF CHANNEL | 11 | | |
| | ANT 1 | ANT 2 | |
| CHANNEL FREQUENCIES | 802.11b: | 802.11b: | |
| UNDER TEST AND ITS | 17.5dBm / Ch11: 2462MHz | 17.4dBm / Ch11: 2462MHz | |
| CONDUCTED OUTPUT POWER | 802.11g: | 802.11g: | |
| | 22.0dBm / Ch11: 2462MHz | 21.9dBm / Ch11: 2462MHz | |
| MAXIMUM SAR (1g) 0.4W/kg | | 21.90DIII / CITT. 2402WII | |
| MAXIMUM SAR (1g) | | 21.90Biii / Citti. 2402ivii iz | |
| , | | | |
| MAXIMUM SAR (1g) ANTENNA TYPE | 0.4W/kg |).81dBi gain | |
| | 0.4W/kg ANT 1: Printed antenna with (|).81dBi gain | |
| ANTENNA TYPE | 0.4W/kg ANT 1: Printed antenna with 0 ANT 2: Wire antenna with -0.3 |).81dBi gain | |
| ANTENNA TYPE ANTENNA CONNECTOR | 0.4W/kg ANT 1: Printed antenna with (ANT 2: Wire antenna with -0.3 |).81dBi gain | |

NOTE:

1. The EUT was powered by the following adapter and battery.

| ADAPTER | | | | |
|----------------------------------|--------------------------------------|--|--|--|
| BRAND: | OEM | | | |
| MODEL: | MODEL: ADS18B-W 150120 | | | |
| INPUT: 100-240Vac, 50-60Hz, 0.5A | | | | |
| OUTPUT: 15Vdc, 1.2A | | | | |
| POWER LINE: | 2.0m non-shielded cable without core | | | |



| BATTERY | | |
|---------|-------------------------|--|
| BRAND: | H605590H | |
| RATING: | 3.7Vdc, 3900mAh, 14.4Wh | |

- 2. The USB port is for external disk access and cannot establish link with PC.
- 3. The EUT, operates in the 2.4GHz frequency range, lets you connect IEEE 802.11g or IEEE 802.11b devices to the network. With its high-speed data transmissions of up to 54Mbps.
- 4. The above EUT information was declared by manufacturer and for more detailed features description, please refer to the manufacturer's specifications or user's manual.

2.2 GENERAL DESCRIPTION OF APPLIED STANDARDS

According to the specifications of the manufacturer, this product must comply with the requirements of the following standards:

FCC Part 2 (2.1093)
FCC OET Bulletin 65, Supplement C (01- 01)
RSS-102
IEEE 1528-2003

All test items have been performed and recorded as per the above standards.



2.3 GENERAL INOFRMATION OF THE SAR SYSTEM

DASY5 (**Software 5.2 Build 157**) consists of high precision robot, probe alignment sensor, phantom, robot controller, controlled measurement server and near-field probe. The robot includes six axes that can move to the precision position of the DASY5 software defined. The DASY5 software can define the area that is detected by the probe. The robot is connected to controlled box. Controlled measurement server is connected to the controlled robot box. The DAE includes amplifier, signal multiplexing, AD converter, offset measurement and surface detection. It is connected to the Electro-optical coupler (ECO). The ECO performs the conversion form the optical into digital electric signal of the DAE and transfers data to the PC.

EX3DV4 ISOTROPIC E-FIELD PROBE

CONSTRUCTIONSymmetrical design with triangular core
Built-in shielding against static charges

PEEK enclosure material (resistant to organic solvents, e.g., DGBE)

FREQUENCY 10 MHz to > 6 GHz

Linearity: ± 0.2 dB (30 MHz to 6 GHz)

DIRECTIVITY ± 0.3 dB in HSL (rotation around probe axis)

± 0.5 dB in tissue material (rotation normal to probe axis)

DYNAMIC RANGE 10 μ W/g to > 100 mW/g

Linearity: \pm 0.2 dB (noise: typically < 1 μ W/g)

DIMENSIONSOverall length: 330 mm (Tip: 20 mm)
Tip diameter: 2.5 mm (Body: 12 mm)

Typical distance from probe tip to dipole centers: 1 mm

APPLICATION High precision dosimetric measurements in any exposure scenario

(e.g., very strong gradient fields). Only probe which enables

compliance testing for frequencies up to 6 GHz with precision of better

30%.

NOTE

- 1. The Probe parameters have been calibrated by the SPEAG. Please reference "APPENDIX D" for the Calibration Certification Report.
- 2. For frequencies above 800MHz, calibration in a rectangular wave-guide is used, because wave-guide size is manageable.
- 3. For frequencies below 800MHz, temperature transfer calibration is used because the wave-guide size becomes relatively large.



TWIN SAM V4.0

CONSTRUCTION The shell corresponds to the specifications of the Specific

Anthropomorphic Mannequin (SAM) phantom defined in IEEE

1528-2003, EN 62209-1 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually

teaching three points with the robot.

SHELL THICKNESS 2 ± 0.2mm

FILLING VOLUME Approx. 25liters

DIMENSIONS Height: 810mm; Length: 1000mm; Width: 500mm

SYSTEM VALIDATION KITS:

CONSTRUCTION Symmetrical dipole with I/4 balun enables measurement of

feedpoint impedance with NWA matched for use near flat

phantoms filled with brain simulating solutions. Includes distance holder and tripod adaptor

CALIBRATION Calibrated SAR value for specified position and input power at

the flat phantom in brain simulating solutions

FREQUENCY 2450MHz

RETURN LOSS > 20dB at specified validation position

POWER CAPABILITY > 100W (f < 1GHz); > 40W (f > 1GHz)

OPTIONS Dipoles for other frequencies or solutions and other calibration

conditions upon request



DEVICE HOLDER FOR SAM TWIN PHANTOM

CONSTRUCTION

The device holder for the mobile phone device is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles. The holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity ε =3 and loss tangent δ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered. The device holder for the portable device makes up of the polyethylene foam. The dielectric parameters of material close to the dielectric parameters of the air.

DATA ACQUISITION ELECTRONICS

CONSTRUCTION

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplex, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe is mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 box is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



2.4 TEST EQUIPMENT

FOR SAR MEASURENENT

| ITEM | NAME | BRAND | TYPE | SERIES NO. | DATE OF CALIBRATION | DUE DATE OF CALIBRATION |
|------|----------------------|----------------------|--------------|------------|---------------------|-------------------------|
| 1 | SAM Phantom | S&P | QD000 P40 CA | TP-1150 | NA | NA |
| 2 | Signal Generator | Agilent | 68247B | 984703 | May 21, 2009 | May 20, 2010 |
| 3 | E-Field Probe | S&P | EX3DV4 | 3590 | Apr. 28, 2009 | Apr. 27, 2010 |
| 4 | DAE | S&P | DAE3 | 510 | Dec. 16, 2009 | Dec. 15, 2010 |
| 5 | Robot Positioner | Staubli Unimation | NA | NA | NA | NA |
| 6 | Validation Dipole | S&P | D2450V2 | 716 | Mar. 17, 2009 | Mar. 16, 2010 |

NOTE: Before starting, all test equipment shall be warmed up for 30min.

FOR TISSUE PROPERTY

| ITEM | NAME | BRAND | TYPE | SERIES NO. | DATE OF CALIBRATION | DUE DATE OF CALIBRATION |
|------|---------------------|---------|--------|------------|---------------------|-------------------------|
| 1 | Network Analyzer | Agilent | E5071C | MY46104190 | Apr. 10, 2009 | Apr. 09, 2010 |
| 2 | Dielectric Probe | Agilent | 85070D | US01440176 | NA | NA |

NOTE:

- 1. Before starting, all test equipment shall be warmed up for 30min.
- 2. The tolerance (k=1) specified by Agilent for general dielectric measurements, deriving from inaccuracies in the calibration data, analyzer drift, and random errors, are usually ±2.5% and ±5% for measured permittivity and conductivity, respectively. However, the tolerances for the conductivity is smaller for material with large loss tangents, i.e., less than ±2.5% (k=1). It can be substantially smaller if more accurate methods are applied



2.5 GENERAL DESCRIPTION OF THE SPATIAL PEAK SAR EVALUATION

The DASY5 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the micro-volt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Norm_i, a_{i0}, a_{i1}, a_{i2}

- Conversion factor ConvF_i

- Diode compression point dcpi

Device parameters: - Frequency F

- Crest factor Cf

Media parameters: - Conductivity σ

- Density ρ

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \bullet \frac{cf}{dcp_i}$$

 V_i = compensated signal of channel i (i = x, y, z) U_i = input signal of channel I (i = x, y, z)

Cf =crest factor of exciting field (DASY parameter)

dcp_i =diode compression point (DASY parameter)



From the compensated input signals the primary field data for each channel can be evaluated:

E-fieldprobes:
$$E_i = \sqrt{\frac{V_1}{Norm_i \cdot ConvF}}$$

H-fieldprobes:
$$H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

 V_i =compensated signal of channel I (i = x, y, z)

Norm_i =sensor sensitivity of channel i $\mu V/(V/m)2$ for (i = x, y, z)

E-field Probes

ConvF = sensitivity enhancement in solution

a_{ii} = sensor sensitivity factors for H-field probes

F = carrier frequency [GHz]

E_i = electric field strength of channel i in V/m H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{S}{r \cdot 1'000}$$

SAR = local specific absorption rate in mW/g

 E_{tot} = total field strength in V/m

 σ = conductivity in [mho/m] or [Siemens/m]

 ρ = equivalent tissue density in g/cm3



Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid. The entire evaluation of the spatial peak values is performed within the Post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- 1. The extraction of the measured data (grid and values) from the Zoom Scan
- 2. The calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- 3. The generation of a high-resolution mesh within the measured volume
- 4. The interpolation of all measured values from the measurement grid to the high-resolution grid
- 5. The extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- 6. The calculation of the averaged SAR within masses of 1g and 10g.

The probe is calibrated at the center of the dipole sensors that is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated. The angle between the probe axis and the surface normal line is less than 30 degree.



The maximum search is automatically performed after each area scan measurement. It is based on splines in two or three dimensions. The procedure can find the maximum for most SAR distributions even with relatively large grid spacing. After the area scanning measurement, the probe is automatically moved to a position at the interpolated maximum. The following scan can directly use this position for reference, e.g., for a finer resolution grid or the cube evaluations. The 1g and 10g peak evaluations are only available for the predefined cube 7 x 7 x 7 scans. The routines are verified and optimized for the grid dimensions used in these cube measurements. The measured volume of 30 x 30 x 30mm contains about 30g of tissue. The first procedure is an extrapolation (incl. boundary correction) to get the points between the lowest measured plane and the surface. The next step uses 3D interpolation to get all points within the measured volume in a 1mm grid (42875 points). In the last step, a 1g cube is placed numerically into the volume and its averaged SAR is calculated. This cube is the moved around until the highest averaged SAR is found. If the highest SAR is found at the edge of the measured volume, the system will issue a warning: higher SAR values might be found outside of the measured volume. In that case the cube measurement can be repeated, using the new interpolated maximum as the center

3. DESCRIPTION OF SUPPORT UNITS

The EUT has been tested as an independent unit.



4. DESCRIPTION OF TEST MODES AND CONFIGURATIONS

4.1. DESCRIPTION OF TEST CONDITION

| TEST DATE | TEST ITEM | TEMPERATURE(°C) | | HUMIDITY(%RH) | TESTED BY |
|---------------|-----------|-----------------|--------|--------------------|-------------|
| ILSI DAIL | TEST TIEW | AMBIENT | LIQUID | TIOWIDIT I (70KII) | ILSILDBI |
| Jan. 06, 2010 | 1 ~ 8 | 23.1 | 22.7 | 62 | Aaron Liang |

4.2. ENHANCED ENERGY COUPLING AT INCREASED SEPARATION DISTANCES

INITIAL POSITION:

The probe tip is positioned at the peak SAR location of in test mode 2, 6, at a distance of one half the probe tip diameter from the phantom surface. Under this condition to get a single sar value.

5mm INCREMENTS FROM INITIAL POSITION:

With the probe fixed at this location, the device is moved away from the phantom in 5 mm increments from the initial touching or minimum separation position. A single point SAR is measured for each of these device positions until the SAR is less than 50% of that measured at the initial position.

| CHANNEL | FREQUENCY (MHZ) | TEST MODE | INITIAL POSITION MEASURED 1g SAR (W/kg) | 5 mm INCREMENTS FROM INITIAL POSITION MEASURED 1g SAR (W/kg) |
|---------|--------------------|-----------|---|---|
| 6 | 2437 | 2 | 0.6650 | 0.3127 |
| 11 | 2462 | 6 | 0.1437 | 0.0708 |

RESULT: No Enhancement Energy Coupling observed.



4.3. DESCRIPTION OF TEST MODE

Test Tool:

Test tool is DutApiUDP83xxp provided by client. It can control EUT to transmit continuously at specific channel, output power level, data rates and 100 % duty signal.

Test Date Rate:

"Per KDB 248277, for each frequency band, testing at higher data rates and higher order modulations is not required when the maximum average output power for each of these configurations is less than ¼ dB higher than those measured at the lowest data rate." Comparing output power of all modulations and data rates of each mode can find the lowest data rates has max output power. Therefore, EUT will set under lowest data rates to test.

Test Channel:

"Per KDB 447498, when the SAR procedures require multiple channels to be tested and the 1-g SAR for the highest output channel is less than 0.8 W/kg and peak SAR is less than 1.6 W/kg, where the transmission band corresponding to all channels is ≤ 100 MHz, testing for the other channels is not required."

According to test data from table of section 4.4, SAR value of highest output power channel is less than 0.8 W/kg and Peak SAR values are less than 1.6W/kg. Therefore, testing for other channels is not required.

Test Position:

There are 2 test positions in the report.

- 2 Body / Tip
- 2 Body / Bottom



Test Mode Table:

| ITEM | TEST MODE | MODULATION | ASSESSMENT POSTITION | TESTED CHANNEL | REMARK |
|------|-----------|------------|----------------------|-------------------|--------|
| 1 | 802.11b | DBPSK | | 11 | ANT 1 |
| 2 | 802.11g | BPSK | Body / Tip | 11 | ANT 1 |
| 3 | 802.11b | DBPSK | воду / Пр | 11 | ANT 2 |
| 4 | 802.11g | BPSK | | 11 | ANT 2 |
| 5 | 802.11b | DBPSK | | 11 | ANT 1 |
| 6 | 802.11g | BPSK | Body / Bottom | 11 | ANT 1 |
| 7 | 802.11b | DBPSK | Body / Bolloili | 11 | ANT 2 |
| 8 | 802.11g | BPSK | | 11 | ANT 2 |

NOTE: Please refer to the test set up photo.

4.4. SUMMARY OF TEST RESULTS

| 17 | ГЕМ | 1 | 2 | 3 | 4 |
|-------|----------------|----------------------------------|---------|---------|---------|
| TEST | MODE | 802.11b | 802.11g | 802.11b | 802.11g |
| CHAN. | FREQ. (MHz) | MEASURED VALUE OF 1g SAR (W/kg) | | | |
| 11 | 2462 (High) | 0.265 | 0.368 | 0.101 | 0.132 |

| רו | ГЕМ | 5 | 6 | 7 | 8 |
|-------|----------------|----------------------------------|---------|---------|---------|
| TEST | MODE | 802.11b | 802.11g | 802.11b | 802.11g |
| CHAN. | FREQ. (MHz) | MEASURED VALUE OF 1g SAR (W/kg) | | | |
| 11 | 2462 (High) | 0.053 | 0.088 | 0.015 | 0.023 |

NOTE: The worst value has been marked by boldface.



5. TEST RESULTS

5.1 TEST PROCEDURES

Use the software to control the EUT channel and transmission power. Then record the conducted power before the testing. Place the EUT to the specific test location. After the testing, must writing down the conducted power of the EUT into the report. The SAR value was calculated via the 3D spline interpolation algorithm that has been implemented in the software of DASY4 SAR measurement system manufactured and calibrated by SPEAG. According to the IEEE 1528 standards, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- Power reference measurement
- Verification of the power reference measurement
- Area scan
- Zoom scan
- Power reference measurement

The area scan was performed for the highest spatial SAR location. The zoom scan with 30mm x 30mm x 30mm volume was performed for SAR value averaged over 1g and 10g spatial volumes.

In the zoom scan, the distance between the measurement point at the probe sensor location (geometric center behind the probe tip) and the phantom surface is 3mm and maintained at a constant distance of ± 0.5 mm during a zoom scan to determine peak SAR locations. The distance is 3mm between the first measurement point and the bottom surface of the phantom. The secondary measurement point to the bottom surface of the phantom is with 8mm separation distance. The cube size is 7 x 7 x 7 points consists of 343 points and the grid space is 5mm.



The measurement time is 0.5s at each point of the zoom scan. The probe boundary effect compensation shall be applied during the SAR test. Because of the tip of the probe to the Phantom surface separated distances are longer than half a tip probe diameter.

In the area scan, the separation distance is 3mm between the each measurement point and the phantom surface. The scan size shall be included the transmission portion of the EUT. The measurement time is the same as the zoom scan. At last the reference power drift shall be less than $\pm 5\%$.

5.2 SAR LIMITS

| | SAR (W/kg) | | |
|-------------------------------------|--|--|--|
| HUMAN EXPOSURE | (GENERAL POPULATION / UNCONTROLLED EXPOSURE ENVIRONMENT) | (OCCUPATIONAL / CONTROLLED EXPOSURE ENVIRONMENT) | |
| Spatial Peak (averaged over 1 g) | 1.6 | 8.0 | |

NOTE:

- 1. This limits accord to 47 CFR 2.1093 Safety Limit.
- 2. The EUT property been complied with the partial body exposure limit under the general population environment.



5.3 MEASURED SAR RESULTS

| TEST MODE | CHAN. | FREQ. (MHz) | MODULATION | TEST POSITION | POWER (dBm) POWER 1g SA | | MEASURED 1g SAR (W/kg) |
|--------------|-------|-------------|------------|---------------|-------------------------|--------|------------------------------|
| 1 | 11 | 2462 | 802.11b | Body / Tip | 17.5 | -0.056 | 0.265 |
| 2 | 11 | 2462 | 802.11g | Body / Tip | 22.0 | 0.051 | 0.368 |
| 3 | 11 | 2462 | 802.11b | Body / Tip | 17.4 | 0.068 | 0.101 |
| 4 | 11 | 2462 | 802.11g | Body / Tip | 21.9 | 0.069 | 0.132 |
| 5 | 11 | 2462 | 802.11b | Body / Bottom | 17.5 | -0.087 | 0.053 |
| 6 | 11 | 2462 | 802.11g | Body / Bottom | 22.0 | -0.019 | 0.088 |
| 7 | 11 | 2462 | 802.11b | Body / Bottom | 17.4 | -0.096 | 0.015 |
| 8 | 11 | 2462 | 802.11g | Body / Bottom | 21.9 | -0.013 | 0.023 |

NOTE:

- 1. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6 W/kg, is applied
- 2. Please see the Appendix A for the data.
- 3. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



5.4 RECIPES FOR TISSUE SIMULATING LIQUIDS

For the measurement of the field distribution inside the SAM phantom, the phantom must be filled with 25 litters of tissue simulation liquid.

The following ingredients are used:

• WATER- Deionized water (pure H20), resistivity _16 M - as basis for the liquid

• **DGMBE-** Diethylenglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH,

CAS # 112-34-5 - to reduce relative permittivity

THE RECIPES FOR 2450MHz SIMULATING LIQUID TABLE

| INGREDIENT | HEAD SIMULATING LIQUID 2450MHz (HSL-2450) | MUSCLE SIMULATING LIQUID 2450MHz (MSL-2450) | | | |
|-------------------------------------|--|--|--|--|--|
| Water | 45% | 69.83% | | | |
| DGMBE | 55% | 30.17% | | | |
| Dielectric Parameters at 22°C | f= 2450MHz ε= 39.2 ± 5% σ = 1.80 ± 5% S/m | f= 2450MHz ε= 52.7 ± 5% σ= 1.95 ± 5% S/m | | | |



Testing the liquids using the Agilent Network Analyzer E5071C and Agilent Dielectric Probe Kit 85070D. The testing procedure is following as

- 1. Turn Network Analyzer on and allow at least 30min. warm up.
- 2. Mount dielectric probe kit so that interconnecting cable to Network Analyzer will not be moved during measurements or calibration.
- 3. Pour de-ionized water and measure water temperature (±1°).
- 4. Set water temperature in Agilent-Software (Calibration Setup).
- 5. Perform calibration.
- 6. Validate calibration with dielectric material of known properties (e.g. polished ceramic slab with >8mm thickness ϵ '=10.0, ϵ "=0.0). If measured parameters do not fit within tolerance, repeat calibration (±0.2 for ϵ ': ±0.1 for ϵ ").
- 7. Conductivity can be calculated from ε'' by $\sigma = \omega \varepsilon_0 \varepsilon'' = \varepsilon'' f [GHz] / 18.$
- 8. Measure liquid shortly after calibration. Repeat calibration every hour.
- 9. Stir the liquid to be measured. Take a sample (~ 50ml) with a syringe from the center of the liquid container.
- 10. Pour the liquid into a small glass flask. Hold the syringe at the bottom of the flask to avoid air bubbles.
- 11. Put the dielectric probe in the glass flask. Check that there are no air bubbles in front of the opening in the dielectric probe kit.
- 12. Perform measurements.
- 13. Adjust medium parameters in DASY5 for the frequencies necessary for the measurements ('Setup Config', select medium (e.g. Brain 900MHz) and press 'Option'-button.
- 14. Select the current medium for the frequency of the validation (e.g. Setup Medium Brain 900MHz).



FOR 2.4GHz BAND SIMULATING LIQUID

| LIQUID T | /PE | MSL-2450 | | | | | | |
|----------------|---------------------|-------------------|----------------------|----------------------------|------------|--|--|--|
| SIMULATI | NG LIQUID TEMP. | 22.7 | | | | | | |
| TEST DAT | ΓE | | Jan. 06, 2010 | | | | | |
| TESTED E | зү | | Aaron Liang | | | | | |
| FREQ. (MHz) | LIQUID PARAMETER | STANDARD VALUE | MEASUREMENT VALUE | ERROR PERCENTAGE (%) | LIMIT(%) | | | |
| 2450.0 | Permitivity | 52.70 | 53.10 | 0.76 | | | | |
| 2462.0 | (ε) | 52.70 | 53.00 | 0.57 | ±5 | | | |
| 2450.0 | Conductivity | 1.95 | 1.97 | 1.03 | ± 0 | | | |
| 2462.0 | (σ) S/m | 1.97 | 2.01 | 2.03 | | | | |



6. SYSTEM VALIDATION

The system validation was performed in the flat phantom with equipment listed in the following table. Since the SAR value is calculated from the measured electric field, dielectric constant and conductivity of the body tissue and the SAR is proportional to the square of the electric field. So, the SAR value will be also proportional to the RF power input to the system validation dipole under the same test environment. In our system validation test, 250mW RF input power was used.

6.1 TEST PROCEDURE

Before the system performance check, we need only to tell the system which components (probe, medium, and device) are used for the system performance check; the system will take care of all parameters. The dipole must be placed beneath the flat section of the SAM Twin Phantom with the correct distance holder in place. The distance holder should touch the phantom surface with a light pressure at the reference marking (little cross) and be oriented parallel to the long side of the phantom. Accurate positioning is not necessary, since the system will search for the peak SAR location, except that the dipole arms should be parallel to the surface. The device holder for mobile phones can be left in place but should be rotated away from the dipole.

- 1. The "Power Reference Measurement" and "Power Drift Measurement" jobs are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the amplifier output power. If it is too high (above ±0.1 dB), the system performance check should be repeated; some amplifiers have very high drift during warm-up. A stable amplifier gives drift results in the DASY system below ±0.02dB.
- 2. The "Surface Check" job tests the optical surface detection system of the DASY system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above ±0.1mm). In that case it is better to abort the system performance check and stir the liquid.



- 3. The "Area Scan" job measures the SAR above the dipole on a plane parallel to the surface. It is used to locate the approximate location of the peak SAR. The proposed scan uses large grid spacing for faster measurement; due to the symmetric field, the peak detection is reliable. If a finer graphic is desired, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result.
- 4. The "Zoom Scan" job measures the field in a volume around the peak SAR value assessed in the previous "Area Scan" job (for more information see the application note on SAR evaluation).

About the validation dipole positioning uncertainty, the constant and low loss dielectric spacer is used to establish the correct distance between the top surface of the dipole and the bottom surface of the phantom, the error component introduced by the uncertainty of the distance between the liquid (i.e., phantom shell) and the validation dipole in the DASY5 system is less than ±0.1mm.

$$SAR_{tolerance}[\%] = 100 \times (\frac{(a+d)^2}{a^2} - 1)$$

As the closest distance is 10mm, the resulting tolerance SAR $_{tolerance}$ [%] is <2%.



6.2 VALIDATION RESULTS

| SYSTEM VALIDATION TEST OF SIMULATING LIQUID | | | | | | | | |
|---|-------------|------------------------|------------------|------------------------|---------------|--|--|--|
| FREQUENCY REQUIRED SAR (mW/g) | | MEASURED SAR (mW/g) | DEVIATION (%) | SEPARATION DISTANCE | TESTED DATE | | | |
| MSL2450 | 13.3 (1g) | 13.0 | -2.26 | 10mm | Jan. 06, 2010 | | | |
| TESTED BY | Aaron Liang | | | | | | | |

NOTE: Please see Appendix for the photo of system validation test.



6.3 SYSTEM VALIDATION UNCERTAINTIES

In the table below, the system validation uncertainty with respect to the analytically assessed SAR value of a dipole source as given in the IEEE 1528 standard is given. This uncertainty is smaller than the expected uncertainty for mobile phone measurements due to the simplified setup and the symmetric field distribution.

| Error Description | Tolerance (±%) | Probability Distribution | Divisor | (C _i) | | Standard Uncertainty (±%) | | (v _i) |
|-----------------------------------|-------------------|-----------------------------|------------|-------------------|-------|---------------------------------|-------|-------------------|
| | | | | (1g) | (10g) | (1g) | (10g) | |
| Measurement System | | | | | | | | |
| Probe Calibration | 5.50 | Normal | 1 | 1 | 1 | 5.50 | 5.50 | ∞ |
| Axial Isotropy | 4.70 | Rectangular | √3 | 0.7 | 0.7 | 1.90 | 1.90 | ∞ |
| Hemispherical Isotropy | 9.60 | Rectangular | √3 | 0.7 | 0.7 | 3.88 | 3.88 | ∞ |
| Boundary effects | 1.00 | Rectangular | √3 | 1 | 1 | 0.58 | 0.58 | ∞ |
| Linearity | 4.70 | Rectangular | √3 | 1 | 1 | 2.71 | 2.71 | ∞ |
| System Detection Limits | 1.00 | Rectangular | √3 | 1 | 1 | 0.58 | 0.58 | ∞ |
| Readout Electronics | 0.30 | Normal | 1 | 1 | 1 | 0.30 | 0.30 | ~ |
| Response Time | 0.80 | Rectangular | √3 | 1 | 1 | 0.46 | 0.46 | 8 |
| Integration Time | 0.00 | Rectangular | √3 | 1 | 1 | 0.00 | 0.00 | 8 |
| RF Ambient Noise | 3.00 | Rectangular | √3 | 1 | 1 | 1.73 | 1.73 | 8 |
| RF Ambient Reflections | 3.00 | Rectangular | √3 | 1 | 1 | 1.73 | 1.73 | ∞ |
| Probe Positioner | 0.40 | Rectangular | √3 | 1 | 1 | 0.23 | 0.23 | ∞ |
| Probe Positioning | 2.90 | Rectangular | √3 | 1 | 1 | 1.67 | 1.67 | ∞ |
| Max. SAR Eval. | 1.00 | Rectangular | √3 | 1 | 1 | 0.58 | 0.58 | ∞ |
| | | Dipole Re | elated | | | | | |
| Dipole Axis to Liquid Distance | 2.00 | Rectangular | √3 | 1 | 1 | 1.15 | 1.15 | 145 |
| Input Power Drift | 5.00 | Rectangular | √3 | 1 | 1 | 2.89 | 2.89 | 8 |
| | | Phantom and Tiss | ue paramet | ers | | | | |
| Phantom Uncertainty | 4.00 | Rectangular | √3 | 1 | 1 | 2.31 | 2.31 | ∞ |
| Liquid Conductivity (target) | 5.00 | Rectangular | √3 | 0.64 | 0.43 | 1.85 | 1.24 | 8 |
| Liquid Conductivity (measurement) | 2.86 | Normal | 1 | 0.64 | 0.43 | 1.83 | 1.23 | 8 |
| Liquid Permittivity (target) | 5.00 | Rectangular | √3 | 0.6 | 0.49 | 1.73 | 1.41 | 8 |
| Liquid Permittivity (measurement) | 2.16 | Normal | 1 | 0.6 | 0.49 | 1.30 | 1.06 | ∞ |
| Combined Standard Uncertainty | | | | | | 9.64 | 9.36 | |
| Coverage Factor for 95% | | | | | | Kp=2 | | |
| Expanded Uncertainty (K=2) | | | | | | 19.27 | 18.72 | |



7. MEASUREMENT SAR PROCEDURE UNCERTAINTIES

The assessment of spatial peak SAR of the hand handheld devices is according to IEEE 1528 / EN 62209-1. All testing situation shall be met below these requirements.

- The system is used by an experienced engineer who follows the manual and the guidelines taught during the training provided by SPEAG.
- The probe has been calibrated within the requested period and the stated uncertainty for the relevant frequency bands does not exceed 4.8% (k=1).
- The validation dipole has been calibrated within the requested period and the system performance check has been successful.
- The DAE unit has been calibrated within the requested period.
- The minimum distance between the probe sensor and inner phantom shell is selected to be 3mm.
- The operational mode of the DUT is 802.11b/g and the measurement/integration time per point is >500 ms.
- The dielectric parameters of the liquid have been assessed using Agilent 85070D dielectric probe kit.
- The dielectric parameters are within 5% of the target values.
- The DUT has been positioned as described in section 3.

7.1. PROBE CALIBRATION UNCERTAINTY

SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN 62209-1, IEC 62209, etc.) under ISO17025. The uncertainties are stated on the calibration certificate. For the most relevant frequency bands, these values do not exceed 4.8% (k=1). If evaluations of other bands are performed for which the uncertainty exceeds these values, the uncertainty tables given in the summary have to be revised accordingly.



7.2. ISOTROPY UNCERTAINTY

The axial isotropy tolerance accounts for probe rotation around its axis while the hemispherical isotropy error includes all probe orientations and field polarizations. These parameters are assessed by SPEAG during initial calibration. In 2001, SPEAG further tightened its quality controls and warrants that the maximal deviation from axial isotropy is ± 0.20 dB, while the maximum deviation of hemispherical isotropy is ± 0.40 dB, corresponding to $\pm 4.7\%$ and $\pm 9.6\%$, respectively. A weighting factor of cp equal to 0.5 can be applied, since the axis of the probe deviates less than 30 degrees from the normal surface orientation.

7.3. BOUNDARY EFFECT UNCERTAINTY

The effect can be estimated according to the following error approximation formula

$$SAR_{tolerance}[\%] = SAR_{be}[\%] \times \frac{(d_{be} + d_{step})^2}{2d_{step}} \frac{e^{-\frac{d_{be}}{d/2}}}{d/2}$$

$$d_{be} + d_{step} < 10mm$$

The parameter d_{be} is the distance in mm between the surface and the closest measurement point used in the averaging process; d_{step} is the separation distance in mm between the first and second measurement points; δ is the minimum penetration depth in mm within the head tissue equivalent liquids (i.e., δ = 13.95mm at 3GHz); SAR_{be} is the deviation between the measured SAR value at the distance d_{be} from the boundary and the wave-guide analytical value SAR_{ref}.DASY5 applies a boundary effect compensation algorithm according to IEEE 1528, which is possible since the axis of the probe never deviates more than 30 degrees from the normal surface orientation. SAR_{be}[%] is assessed during the calibration process and SPEAG warrants that the uncertainty at distances larger than 4mm is always less than 1%.In summary, the worst case boundary effect SAR tolerance[%] for scanning distances larger than 4mm is < \pm 0.8%.



7.4. PROBE LINEARITY UNCERTAINTY

Field probe linearity uncertainty includes errors from the assessment and compensation of the diode compression effects for CW and pulsed signals with known duty cycles. This error is assessed using the procedure described in IEEE 1528 / EN 62209-1. For SPEAG field probes, the measured difference between CW and pulsed signals, with pulse frequencies between 10Hz and 1kHz and duty cycles between 1 and 100, is $< \pm 0.20$ dB ($< \pm 4.7\%$).

7.5. READOUT ELECTRONICS UNCERTAINTY

All uncertainties related to the probe readout electronics (DAE unit), including the gain and linearity of the instrumentation amplifier, its loading effect on the probe, and accuracy of the signal conversion algorithm, have been assessed accordingly to IEEE 1528 / EN 62209-1. The combination (root-sum-square RSS method) of these components results in an overall maximum error of $\pm 1.0\%$.

7.6. RESPONSE TIME UNCERTAINTY

The time response of the field probes is assessed by exposing the probe to a well-controlled electric field producing SAR larger than 2.0W/kg at the tissue medium surface. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/of switch of the power source. Analytically, it can be expressed as:

$$SAR_{tolerance} [\%] = 100 \times (\frac{T_m}{T_m + te^{-T_m/t} - t} - 1)$$

where Tm is 500 ms, i.e., the time between measurement samples, and $_{\rm T}$ the time constant. The response time $_{\rm T}$ of SPEAG's probes is <5ms. In the current implementation, DASY5 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.



7.7. INTEGRATION TIME UNCERTAINTY

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization and can be assessed as follows

$$SAR_{tolerance}$$
 [%] = $100 \times \sum_{allsub-frames} \frac{t_{frame}}{t_{int\ egration}} \frac{slot_{idle}}{slot_{total}}$

The EUT transmit 100 % duty cycle test signal under SAR test. Therefore, the Integration Time Uncertainty is 0.



7.8. PROBE POSITIONER MECHANICAL TOLERANCE

The mechanical tolerance of the field probe positioner can introduce probe positioning uncertainties. The resulting SAR uncertainty is assessed by comparing the SAR obtained according to the specifications of the probe positioner with respect to the actual position defined by the geometric enter of the probe sensors. The tolerance is determined as:

$$SAR_{tolerance}[\%] = 100 \times \frac{d_{ph}}{d/2}$$

The specified repeatability of the RX robot family used in DASY5 systems is $\pm 25\mu m$. The absolute accuracy for short distance movements is better than $\pm 0.1 mm$, i.e., the SAR_{tolerance}[%] is better than 1.5% (rectangular).

7.9. PROBE POSITIONING

The probe positioning procedures affect the tolerance of the separation distance between the probe tip and the phantom surface as:

$$SAR_{tolerance}[\%] = 100 \times \frac{d_{ph}}{d/2}$$

where d_{ph} is the maximum deviation of the distance between the probe tip and the phantom surface. The optical surface detection has a precision of better than 0.2mm, resulting in an SAR_{tolerance}[%] of <2.9% (rectangular distribution). Since the mechanical detection provides better accuracy, 2.9% is a worst-case figure for DASY5 system.



7.10. PHANTOM UNCERTAINTY

The SAR measurement uncertainty due to SPEAG phantom shell production tolerances has been evaluated using

$$SAR_{tolerance}[\%] \cong 100 \times \frac{2d}{a},$$
 $d \ll a$

For a maximum deviation d of the inner and outer shell of the phantom from that specified in the CAD file of ± 0.2 mm, and a 10mm spacing a between source and tissue liquid, the calculated phantom uncertainty is $\pm 4.0\%$.



7.11. DASY5 UNCERTAINTY BUDGET

| Error Description | Tolerance (±%) | Probability Distribution | Divisor | (C _i) | | Standard Uncertainty (±%) | | (v _i) | |
|-----------------------------------|----------------|-----------------------------|-------------|-------------------|-------|---------------------------------|-------|-------------------|--|
| | | | | (1g) | (10g) | (1g) | (10g) | | |
| Measurement Equipment | | | | | | | | | |
| Probe Calibration | 5.50 | Normal | 1 | 1 | 1 | 5.50 | 5.50 | ∞ | |
| Axial Isotropy | 4.70 | Rectangular | √3 | 0.7 | 0.7 | 1.90 | 1.90 | ∞ | |
| Hemispherical Isotropy | 9.60 | Rectangular | √3 | 0.7 | 0.7 | 3.88 | 3.88 | ∞ | |
| Boundary effects | 1.00 | Rectangular | √3 | 1 | 1 | 0.58 | 0.58 | ∞ | |
| Linearity | 4.70 | Rectangular | √3 | 1 | 1 | 2.71 | 2.71 | ∞ | |
| System Detection Limits | 1.00 | Rectangular | √3 | 1 | 1 | 0.58 | 0.58 | ∞ | |
| Readout Electronics | 0.30 | Normal | 1 | 1 | 1 | 0.30 | 0.30 | ∞ | |
| Response Time | 0.80 | Rectangular | √3 | 1 | 1 | 0.46 | 0.46 | ∞ | |
| Integration Time | 2.60 | Rectangular | √3 | 1 | 1 | 1.50 | 1.50 | ~ | |
| RF Ambient Noise | 3.00 | Rectangular | √3 | 1 | 1 | 1.73 | 1.73 | ∞ | |
| RF Ambient Reflections | 3.00 | Rectangular | √3 | 1 | 1 | 1.73 | 1.73 | ∞ | |
| Probe Positioner | 0.40 | Rectangular | √3 | 1 | 1 | 0.23 | 0.23 | ∞ | |
| Probe Positioning | 2.90 | Rectangular | √3 | 1 | 1 | 1.67 | 1.67 | ~ | |
| Max. SAR Eval. | 1.00 | Rectangular | √3 | 1 | 1 | 0.58 | 0.58 | ∞ | |
| | | Test Sample | Related | | | | | | |
| Device Positioning | 0.89 | Normal | 1 | 1 | 1 | 0.89 | 0.89 | 9 | |
| Device Holder | 3.60 | Normal | 1 | 1 | 1 | 3.60 | 3.60 | 5 | |
| Power Drift | 5.00 | Rectangular | √3 | 1 | 1 | 2.89 | 2.89 | 8 | |
| | F | Phantom and Tisso | ue parameto | ers | | | | | |
| Phantom Uncertainty | 4.00 | Rectangular | √3 | 1 | 1 | 2.31 | 2.31 | ~ | |
| Liquid Conductivity (target) | 5.00 | Rectangular | √3 | 0.64 | 0.43 | 1.85 | 1.24 | 8 | |
| Liquid Conductivity (measurement) | 2.86 | Normal | 1 | 0.64 | 0.43 | 1.83 | 1.23 | ∞ | |
| Liquid Permittivity (target) | 5.00 | Rectangular | √3 | 0.6 | 0.49 | 1.73 | 1.41 | ∞ | |
| Liquid Permittivity (measurement) | 2.16 | Normal | 1 | 0.6 | 0.49 | 1.30 | 1.06 | 8 | |
| Combined Standard Uncertainty | | | | | | 10.37 | 10.11 | | |
| Coverage Factor for 95% | | | | | | Kp=2 | | | |
| Expanded Uncertainty (K=2) | | | | | | 20.74 | 20.23 | | |

TABLE 7.2



8. INFORMATION ON THE TESTING LABORATORIES

We, Bureau Veritas Consumer Products Services (H.K.) Ltd., Taoyuan Branch, were founded in 1988 to provide our best service in EMC, Radio, Telecom and Safety consultation. Our laboratories are accredited and approved according to ISO/IEC 17025.

Copies of accreditation certificates of our laboratories obtained from approval agencies can be downloaded from our web site: www.adt.com.tw/index.5/phtml. If you have any comments, please feel free to contact us at the following:

Linko EMC/RF Lab: Hsin Chu EMC/RF Lab:

Tel: 886-2-26052180 Tel: 886-3-5935343 Fax: 886-2-26051924 Fax: 886-3-5935342

Hwa Ya EMC/RF/Safety/Telecom Lab:

Tel: 886-3-3183232 Fax: 886-3-3185050

Web Site: www.adt.com.tw

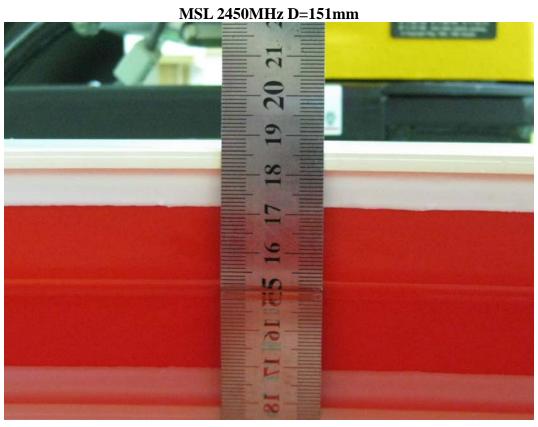
The address and road map of all our labs can be found in our web site also.

---END---



APPENDIX A: TEST DATA

Liquid Level Photo





Date/Time: 2010/1/6 10:30:47

Test Laboratory: Bureau Veritas ADT

M01-ANT 1-Body-Tip-11B-Ch 11

DUT: WiFi Photo Frame ; Type: PoMMeS

Communication System: 802.11B; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: DBPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz; $\sigma = 2.01$ mho/m; $\epsilon_r = 53$; $\rho = 1000$ kg/m³ Phantom section: Flat Section; Separation distance: 0 mm (The Tip side of the EUT to the Phantom)

DASY5 Configuration:

- Probe: EX3DV4 SN3590; ConvF(7.96, 7.96, 7.96); Calibrated: 2009/4/28
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2009/12/16
- Phantom: ELI 4.0; Type: QDOVA001BB; Serial: 1043
- Measurement SW: DASY5, V5.2 Build 157; SEMCAD X Version 14.0 Build 57

High Channel /Area Scan (11x21x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 0.372 mW/g

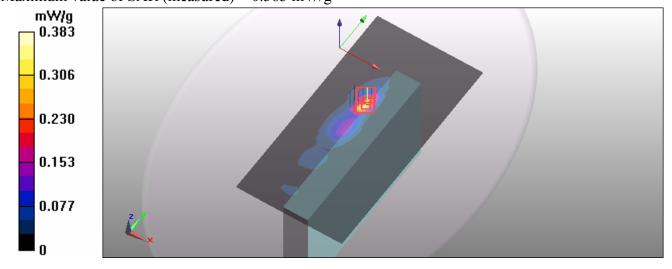
High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 7.76 V/m; Power Drift = -0.056 dB

Peak SAR (extrapolated) = 0.721 W/kg

$SAR(1 g) = \frac{0.265}{0.265} mW/g; SAR(10 g) = 0.095 mW/g$

Maximum value of SAR (measured) = 0.383 mW/g





Date/Time: 2010/1/6 11:30:06

Test Laboratory: Bureau Veritas ADT

M02-ANT 1-Body-Tip-11G-Ch 11

DUT: WiFi Photo Frame ; Type: PoMMeS

Communication System: 802.11G; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: BPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz; $\sigma = 2.01$ mho/m; $\epsilon_r = 53$; $\rho = 1000$ kg/m³ Phantom section: Flat Section; Separation distance: 0 mm (The Tip side of the EUT to the Phantom)

DASY5 Configuration:

- Probe: EX3DV4 SN3590; ConvF(7.96, 7.96, 7.96); Calibrated: 2009/4/28
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2009/12/16
- Phantom: ELI 4.0; Type: QDOVA001BB; Serial: 1043
- Measurement SW: DASY5, V5.2 Build 157; SEMCAD X Version 14.0 Build 57

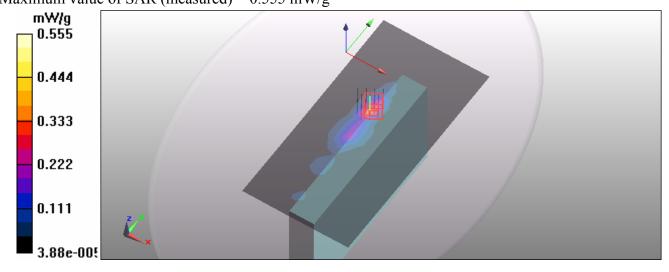
High Channel /Area Scan (11x21x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.407 mW/g

High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

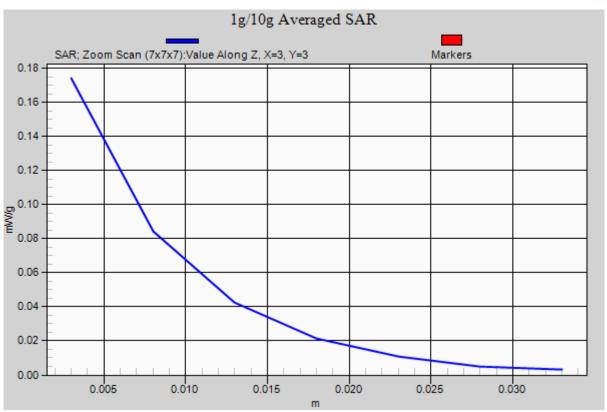
Reference Value = 7.91 V/m; Power Drift = 0.051 dB

Peak SAR (extrapolated) = 0.996 W/kg

SAR(1 g) = 0.368 mW/g; SAR(10 g) = 0.132 mW/gMaximum value of SAR (measured) = 0.555 mW/g









Date/Time: 2010/1/6 14:00:03

Test Laboratory: Bureau Veritas ADT

M03-ANT 2-Body-Tip-11B-Ch 11

DUT: WiFi Photo Frame ; Type: PoMMeS

Communication System: 802.11B ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: DBPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz; $\sigma = 2.01$ mho/m; $\epsilon_r = 53$; $\rho = 1000$ kg/m³ Phantom section: Flat Section ; Separation distance : 0 mm (The Tip side of the EUT to the Phantom)

DASY5 Configuration:

- Probe: EX3DV4 SN3590; ConvF(7.96, 7.96, 7.96); Calibrated: 2009/4/28
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2009/12/16
- Phantom: ELI 4.0; Type: QDOVA001BB; Serial: 1043
- Measurement SW: DASY5, V5.2 Build 157; SEMCAD X Version 14.0 Build 57

High Channel /Area Scan (11x21x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 0.118 mW/g

High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.57 V/m; Power Drift = 0.068 dB

Peak SAR (extrapolated) = 0.209 W/kg

SAR(1 g) = 0.101 mW/g; SAR(10 g) = 0.048 mW/g

Maximum value of SAR (measured) = 0.132 mW/g

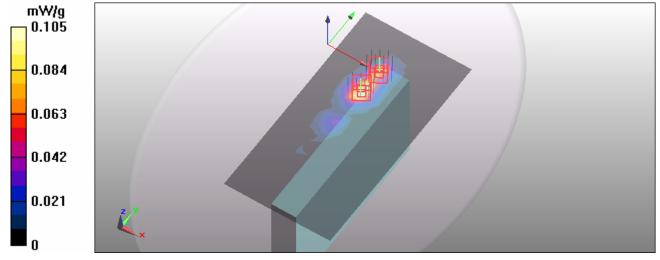
High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 1: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.57 V/m; Power Drift = 0.068 dB

Peak SAR (extrapolated) = 0.175 W/kg

SAR(1 g) = 0.077 mW/g; SAR(10 g) = 0.033 mW/g

Maximum value of SAR (measured) = 0.105 mW/g





Date/Time: 2010/1/6 16:00:24

Test Laboratory: Bureau Veritas ADT

M04-ANT 2-Body-Tip-11G-Ch 11

DUT: WiFi Photo Frame ; Type: PoMMeS

Communication System: 802.11G; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: BPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz; $\sigma = 2.01$ mho/m; $\epsilon_r = 53$; $\rho = 1000$ kg/m³ Phantom section: Flat Section; Separation distance: 0 mm (The Tip side of the EUT to the Phantom)

DASY5 Configuration:

- Probe: EX3DV4 SN3590; ConvF(7.96, 7.96, 7.96); Calibrated: 2009/4/28
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2009/12/16
- Phantom: ELI 4.0; Type: QDOVA001BB; Serial: 1043
- Measurement SW: DASY5, V5.2 Build 157; SEMCAD X Version 14.0 Build 57

High Channel /Area Scan (11x21x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.155 mW/g

High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 1.73 V/m; Power Drift = 0.069 dB

Peak SAR (extrapolated) = 0.277 W/kg

SAR(1 g) = 0.132 mW/g; SAR(10 g) = 0.062 mW/g

Maximum value of SAR (measured) = 0.174 mW/g

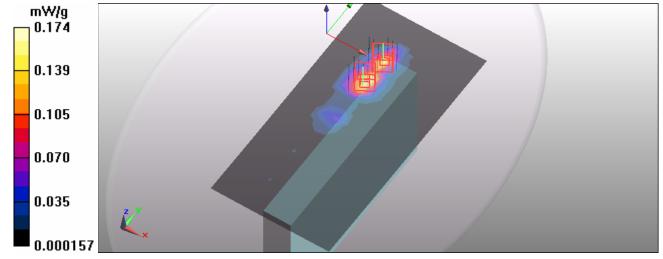
High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 1: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 1.73 V/m; Power Drift = 0.069 dB

Peak SAR (extrapolated) = 0.249 W/kg

SAR(1 g) = 0.107 mW/g; SAR(10 g) = 0.046 mW/g

Maximum value of SAR (measured) = 0.144 mW/g





Date/Time: 2010/1/6 17:00:34

Test Laboratory: Bureau Veritas ADT

M05-ANT 1 Body-Bottom-11B-Ch 11

DUT: WiFi Photo Frame ; Type: PoMMeS

Communication System: 802.11B; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: DBPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz; $\sigma = 2.01$ mho/m; $\epsilon_r = 53$; $\rho = 1000$ kg/m³ Phantom section: Flat Section; Separation distance: 0 mm (The bottom side of the EUT to the Phantom)

DASY5 Configuration:

- Probe: EX3DV4 SN3590; ConvF(7.96, 7.96, 7.96); Calibrated: 2009/4/28
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2009/12/16
- Phantom: ELI 4.0; Type: QDOVA001BB; Serial: 1043
- Measurement SW: DASY5, V5.2 Build 157; SEMCAD X Version 14.0 Build 57

High Channel /Area Scan (14x21x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 0.059 mW/g

High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

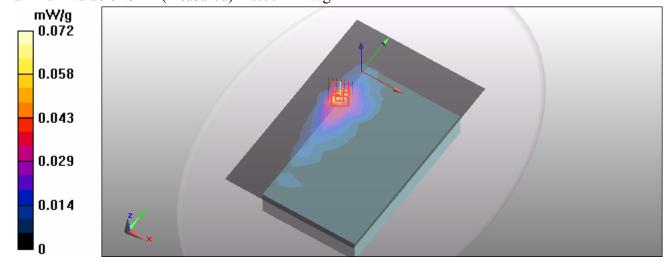
dz=5mm

Reference Value = 0.531 V/m; Power Drift = -0.087 dB

Peak SAR (extrapolated) = 0.119 W/kg

$SAR(1 g) = \frac{0.053}{0.053} mW/g; SAR(10 g) = 0.023 mW/g$

Maximum value of SAR (measured) = 0.072 mW/g





Date/Time: 2010/1/6 18:00:58

Test Laboratory: Bureau Veritas ADT

M06-ANT 1-Body-Bottom-11G-Ch 11

DUT: WiFi Photo Frame ; Type: PoMMeS

Communication System: 802.11G; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: BPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz; $\sigma = 2.01$ mho/m; $\varepsilon_r = 53$; $\rho = 1000$ kg/m³ Phantom section: Flat Section; Separation distance: 0 mm (The bottom side of the EUT to the Phantom)

DASY5 Configuration:

- Probe: EX3DV4 SN3590; ConvF(7.96, 7.96, 7.96); Calibrated: 2009/4/28
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2009/12/16
- Phantom: ELI 4.0; Type: QDOVA001BB; Serial: 1043
- Measurement SW: DASY5, V5.2 Build 157; SEMCAD X Version 14.0 Build 57

High Channel /Area Scan (14x21x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.100 mW/g

High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 0.472 V/m; Power Drift = -0.019 dB

Peak SAR (extrapolated) = 0.305 W/kg

SAR(1 g) = 0.067 mW/g; SAR(10 g) = 0.024 mW/g

Maximum value of SAR (measured) = 0.096 mW/g

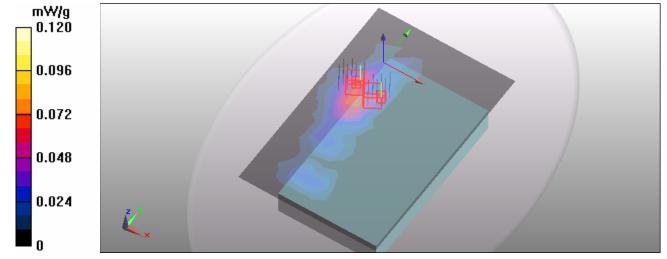
High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 1: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 0.472 V/m; Power Drift = -0.019 dB

Peak SAR (extrapolated) = 0.183 W/kg

SAR(1 g) = 0.088 mW/g; SAR(10 g) = 0.043 mW/g

Maximum value of SAR (measured) = 0.120 mW/g





Date/Time: 2010/1/6 19:00:15

Test Laboratory: Bureau Veritas ADT

M07-ANT 2-Body-Bottom-11B-Ch 11

DUT: WiFi Photo Frame ; Type: PoMMeS

Communication System: 802.11B; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: DBPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz; $\sigma = 2.01$ mho/m; $\epsilon_r = 53$; $\rho = 1000$ kg/m³ Phantom section: Flat Section; Separation distance: 0 mm (The bottom side of the EUT to the Phantom)

DASY5 Configuration:

- Probe: EX3DV4 SN3590; ConvF(7.96, 7.96, 7.96); Calibrated: 2009/4/28
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2009/12/16
- Phantom: ELI 4.0; Type: QDOVA001BB; Serial: 1043
- Measurement SW: DASY5, V5.2 Build 157; SEMCAD X Version 14.0 Build 57

High Channel /Area Scan (14x21x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.013 mW/g

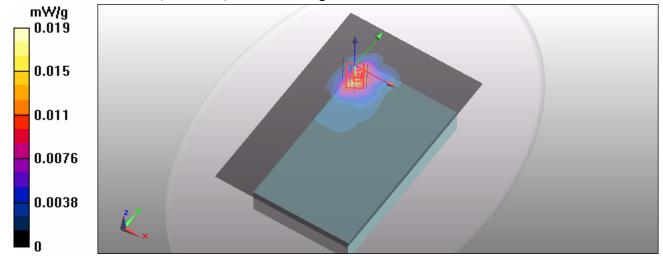
High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 0.727 V/m; Power Drift = -0.096 dB

Peak SAR (extrapolated) = 0.030 W/kg

SAR(1 g) = 0.015 mW/g; SAR(10 g) = 0.00762 mW/g

Maximum value of SAR (measured) = 0.019 mW/g





Date/Time: 2010/1/6 20:00:11

Test Laboratory: Bureau Veritas ADT

M08-ANT 2-Body-Bottom-11G-Ch 11

DUT: WiFi Photo Frame ; Type: PoMMeS

Communication System: 802.11G; Frequency: 2462 MHz; Duty Cycle: 1:1; Modulation type: BPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz; $\sigma = 2.01$ mho/m; $\epsilon_r = 53$; $\rho = 1000$ kg/m³ Phantom section: Flat Section; Separation distance: 0 mm (The bottom side of the EUT to the Phantom)

DASY5 Configuration:

- Probe: EX3DV4 SN3590; ConvF(7.96, 7.96, 7.96); Calibrated: 2009/4/28
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2009/12/16
- Phantom: ELI 4.0; Type: QDOVA001BB; Serial: 1043
- Measurement SW: DASY5, V5.2 Build 157; SEMCAD X Version 14.0 Build 57

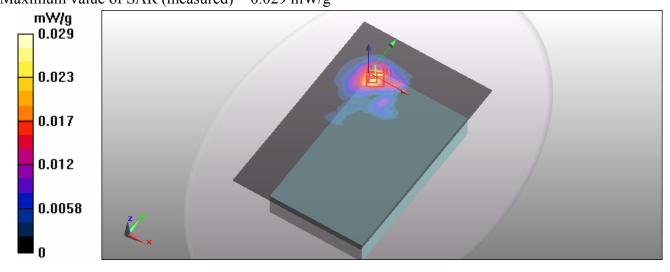
High Channel /Area Scan (14x21x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.026 mW/g

High Channel /Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 0 V/m; Power Drift = -0.013 dB

Peak SAR (extrapolated) = 0.043 W/kg

SAR(1 g) = 0.023 mW/g; SAR(10 g) = 0.011 mW/gMaximum value of SAR (measured) = 0.029 mW/g





Date/Time: 2010/1/6 09:30:07

Test Laboratory: Bureau Veritas ADT

System Validation MSL2450MHz

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 716; Test Frequency: 2450 MHz

Communication System: CW ; Frequency: 2450 MHz; Duty Cycle: 1:1; Modulation type: CW Medium: MSL2450;Medium parameters used: f = 2450 MHz; σ = 1.97 mho/m; ϵ_r = 53.1; ρ = 1000 kg/m³ ; Liquid level : 151 mm

Phantom section: Flat Section; Separation distance: 10 mm (The feetpoint of the dipole to the Phantom) Air temp.: 23.1 degrees; Liquid temp.: 22.7 degrees

DASY5 Configuration:

- Probe: EX3DV4 SN3590; ConvF(7.96, 7.96, 7.96); Calibrated: 2009/4/28
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510 ; Calibrated: 2009/12/16
- Phantom: ELI 4.0; Type: QDOVA001BB; Serial: 1043
- Measurement SW: DASY5, V5.2 Build 157; SEMCAD X Version 14.0 Build 57

d=10mm, Pin=250mW/Area Scan (5x7x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 17.3 mW/g

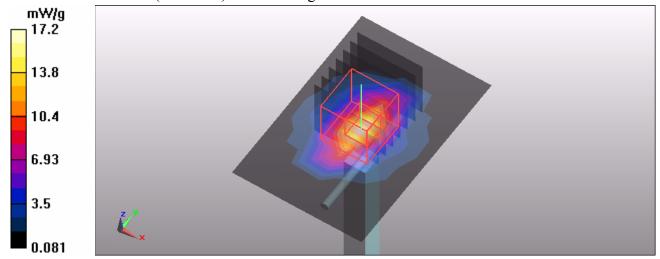
d=10mm, Pin=250mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 94.3 V/m; Power Drift = -0.079 dB

Peak SAR (extrapolated) = 26.7 W/kg

 $SAR(1 g) = \frac{13}{10} mW/g; SAR(10 g) = 5.91 mW/g$

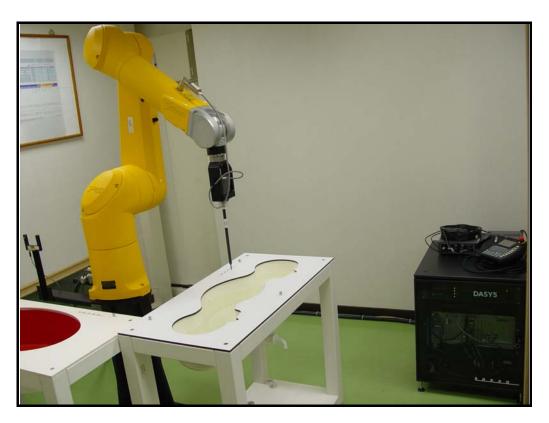
Maximum value of SAR (measured) = 17.2 mW/g





APPENDIX B: BV ADT SAR MEASUREMENT SYSTEM







APPENDIX C: PHOTOGRAPHS OF SYSTEM VALIDATION





APPENDIX D: SYSTEM CERTIFICATE & CALIBRATION

D1: PHANTOM



Zeughausstrasse 43, 8004 Zurich, Switzerland Phone ±41 1 245 9700 Fav ±41 1 245 9779 info@speag.com, http://www.speag.com

Certificate of Conformity / First Article Inspection

| Item | SAM Twin Phantom V4.0 | |
|--------------|-----------------------|--|
| Type No | QD 000 P40 C | |
| Series No | TP-1150 and higher | |
| Manufacturer | SPEAG | |
| | Zeughausstrasse 43 | |
| | CH-8004 Zürich | |
| | Switzerland | |

Tests

The series production process used allows the limitation to test of first articles.

Complete tests were made on the pre-series Type No. QD 000 P40 AA, Serial No. TP-1001 and on the series first article Type No. QD 000 P40 BA, Serial No. TP-1006. Certain parameters have been retested using further series items (called samples) or are tested at each item.

| Test | Requirement | Details | Units tested |
|----------------------|---|----------------------------|----------------|
| Dimensions | Compliant with the geometry | IT'IS CAD File (*) | First article, |
| | according to the CAD model. | | Samples |
| Material thickness | Compliant with the requirements | 2mm +/- 0.2mm in flat | First article, |
| of shell | according to the standards | and specific areas of | Samples, |
| | | head section | TP-1314 ff. |
| Material thickness | Compliant with the requirements | 6mm +/- 0.2mm at ERP | First article, |
| at ERP | according to the standards | | All items |
| Material | Dielectric parameters for required | 300 MHz – 6 GHz: | Material |
| parameters | frequencies | Relative permittivity < 5, | samples |
| | | Loss tangent < 0.05 | |
| Material resistivity | The material has been tested to be | DEGMBE based | Pre-series, |
| | compatible with the liquids defined in | simulating liquids | First article, |
| | the standards if handled and cleaned | | Material |
| | according to the instructions. | | samples |
| | Observe technical Note for material | | |
| | compatibility. | | |
| Sagging | Compliant with the requirements | < 1% typical < 0.8% if | Prototypes, |
| | according to the standards. | filled with 155mm of | Sample |
| | Sagging of the flat section when filled | HSL900 and without | testing |
| | with tissue simulating liquid. | DUT below | |

Standards

- [1] CENELEC EN 50361
- [2] IEEE Std 1528-2003
- [3] IEC 62209 Part I
- [4] FCC OET Bulletin 65, Supplement C, Edition 01-01
- (*) The IT'IS CAD file is derived from [2] and is also within the tolerance requirements of the shapes of the other documents.

Conformity

Based on the sample tests above, we certify that this item is in compliance with the uncertainty requirements of SAR measurements specified in standards [1] to [4].

Date

07.07.2005

Signature / Stamp