

A Test Lab Techno Corp.

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SAR EVALUATION REPORT





Test Report No. : 1112FS14

Applicant : VTech Telecommunications Ltd.

EUT Type : 1.9GHz DECT 6.0 Cordless Phone

FCC ID : EW780-8535-00

Trade Name : VTech

Model Number : CS6529

Dates of Receive : Dec. 05, 2011

Dates of Test : Dec. 06, 2011

Date of Issued : Dec. 12, 2011

Test Environment : Ambient Temperature : $22 \pm 2 \degree C$

Relative Humidity: 40 - 70 %

Test Specification : Standard C95.1-1992

IEEE Std. 1528-2003

2.1093;FCC/OET Bulletin 65 Supplement C [July 2001]

Max. SAR : 0.032 W/kg UPCS Head SAR

Test Lab Location : Chang-an Lab



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1. Description of Equipment under Test (EUT)

| Applicant | : | VTech Telecommunications Ltd. |
|-------------------------|---|--|
| Applicant Address | : | 23/F, Tai Ping Industrial Centre, Block 1, 57 Ting Kok Road, |
| Applicant Address | • | Tai Po, Hong Kong. |
| | | |
| Manufacturer | : | VTech (Dongguan) Telecommunications Limited |
| Manufacturer Address | : | VTech Science Park, Xia Ling Bei Management Zone, |
| | | Liaobu, Dongguan, Guangdong, China |
| EUT Type | : | 1.9GHz DECT 6.0 Cordless Phone |
| FCC ID | : | EW780-8535-00 |
| Trade Name | : | VTech |
| Model Number | : | CS6529 |
| Battery Type | : | Ni-MH battery (2.4V, 300mAh) |
| Test Device | : | Production Unit |
| Tx Frequency | : | 1921.536 -1928.448 MHz (UPCS) |
| Max. RF Conducted Power | : | 0.106 W (20.26 dBm) UPCS |
| Max. SAR Measurement | : | 0.032 W/kg UPCS Head SAR |
| Antenna Type | : | Fixed Type |
| Antenna Gain | : | 0dBi |
| Device Category | : | Portable |
| RF Exposure Environment | : | General Population / Uncontrolled |
| Battery Option | : | Standard |
| Application Type | : | Certification |

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment / general population exposure limits specified in Standard C95.1-1992 and had been tested in accordance with the measurement procedures specified in IEEE Std. 1528-2003.

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2. Introduction

The A Test Lab Techno Corp. has performed measurements of the maximum potential exposure to the user of VTech Telecommunications Ltd. Trade Name: VTech Model(s): CS6529. The test procedures, as described in American National Standards, Institute C95.1 - 1992 [1], FCC/OET Bulletin 65 Supplement C [July 2001] were employed and they specify the maximum exposure limit of 1.6mW/g as averaged over any 1 gram of tissue for portable devices being used within 20cm between user and EUT in the uncontrolled environment. A description of the product and operating configuration, detailed summary of the test results, methodology and procedures used in the equipment used are included within this test report.

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3. SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dw) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Figure 2).

SAR =
$$\frac{d}{dt} \left(\frac{dw}{dm} \right) = \frac{d}{dt} \left(\frac{dw}{\rho dv} \right)$$

Figure 2. SAR Mathematical Equation

SAR is expressed in units of Watts per kilogram (W/kg)

$$SAR = \frac{\sigma E^2}{\rho}$$

Where:

 σ = conductivity of the tissue (S/m)

 ρ = mass density of the tissue (kg/m³)

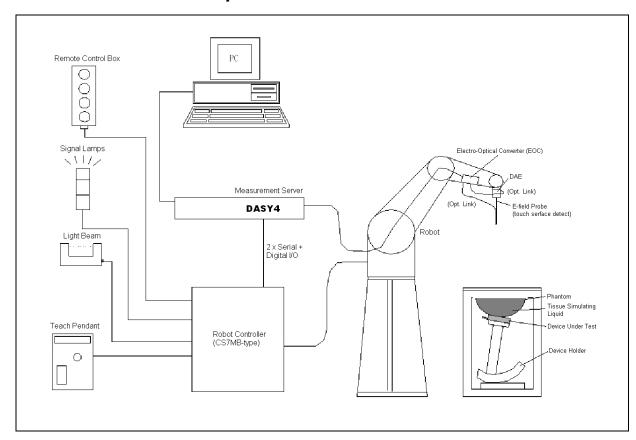
E = RMS electric field strength (V/m)

*Note:

The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane (2)



4. SAR Measurement Setup



These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9m) which positions the probes with a positional repeatability of better than \pm 0.02mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines (length = 300mm) to the data acquisition unit.

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A cell controller system contains the power supply, robot controller, teaches pendant (Joystick) and remote control, and is used to drive the robot motors. The Measurement Server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chipdisk and 64MB RAM. The necessary circuits for communication with either the DAE4 (or DAE3) electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board. The PC consists of the Intel Pentium 4 2.4GHz computer with Windows XP system and SAR Measurement Software DASY4, Post Processor SEMCAD, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection...etc. is connected to the Electro-optical converter (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the Measurement Server.

The DAE4 (or DAE3) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail in $\{3\}$.

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5. System Components

5.1 DASY4 E-Field Probe System

The SAR measurements were conducted with the dosimetric probe ES3DV3 (manufactured by SPEAG), designed in the classical triangular configuration [3] and optimized for dosimetric evaluation. The probes is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped when reaching the maximum.

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5.1.1 E-Field Probe Specification

Construction Symmetrical design with triangular core

Built-in optical fiber for surface detection System

Built-in shielding against static charges

PEEK enclosure material (resistant to organic solvents, e.q., glycol)

Calibration In air from 10 MHz to 6 GHz

In brain and muscle simulating tissue at frequencies of 1950MHz (accuracy ±8%)

Calibration for other liquids and frequencies upon request

Frequency ± 0.2 dB (30 MHz to 6 GHz) for EX3DV4

 ± 0.2 dB (30 MHz to 4 GHz) for ES3DV3

Directivity ± 0.3 dB in brain tissue (rotation around probe axis)

±0.5 dB in brain tissue (rotation normal probe axis)

Dynamic Range 10 μ W/g to > 100mW/g; Linearity: \pm 0.2dB

Dimensions Overall length: 337mm

Tip length: 20mm

Body diameter: 12mm

Tip diameter: 2.5mm for EX3DV4, 3.9mm for ES3DV3

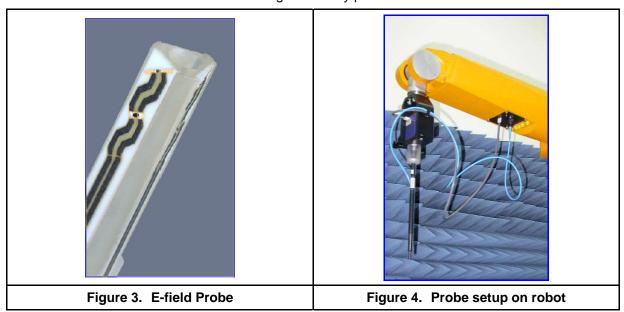
Distance from probe tip to dipole centers: 1.0mm for EX3DV4, 2.0mm for

ES3DV3

Application General dosimetry up to 6GHz

Compliance tests of mobile phones

Fast automatic scanning in arbitrary phantoms





5.1.2 E-Field Probe Calibration

Each probe is calibrated according to a dosimetric assessment procedure described in (4) with accuracy better than $\pm 10\%$. The spherical isotropy was evaluated with the procedure described in (5) and found to be better than ± 0.25 dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1GHz, and in a wave guide above 1GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

Where:

 Δt = Exposure time (30 seconds),

C = Heat capacity of tissue (head or body),

Δ T = Temperature increase due to RF exposure.

Or SAR =
$$\frac{|E|^2 \sigma}{\rho}$$

Where:

σ = Simulated tissue conductivity,

 ρ = Tissue density (kg/m³).



5.2 Data Acquisition Electronic (DAE) System

Cell Controller

Processor: Intel Pentium 4

Clock Speed: 2.4GHz

Operating System: Windows XP Professional

Data Converter

Features: Signal Amplifier, multiplexer, A/D converter, and control logic Software: DASY4 v4.7 (Build 80) & SEMCAD X Version 1.8 Build 186

Connecting Lines: Optical downlink for data and status info

Optical uplink for commands and clock

5.3 Robot

Positioner: Stäubli Unimation Corp. Robot Model: TX90XL

Repeatability: ±0.02 mm

No. of Axis: 6

5.4 Measurement Server

Processor: PC/104 with a 400MHz intel ULV Celeron

I/O-board: Link to DAE4(or DAE3)

16-bit A/D converter for surface detection system

Digital I/O interface Serial link to robot

Direct emergency stop output for robot

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5.5 Device Holder for Transmitters

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity ε =3 and loss tangent δ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

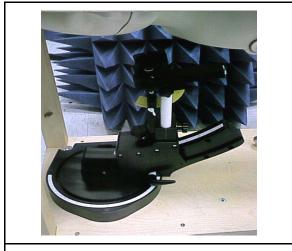


Figure 5. Device Holder

5.6 Phantom - SAM v4.0

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

| Dimensions | 1000×500 mm (LxW) |
|-----------------|-------------------|
| Filling Volume | Approx. 25 liters |
| Shell Thickness | 2 ±0.2 mm |



Figure 6. SAM Twin Phantom



5.7 Data Storage and Evaluation

5.7.1 Data Storage

The DASY4 software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension .DA4. The post processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

5.7.2 Data Evaluation

The DASY4 post processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Normi, ai0, ai1, ai2

- Conversion factor ConvFi

- Diode compression point dcpi

Device parameters: - Frequency

- Crest factor cf

Media parameters : - Conductivity σ

- Density ho

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

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The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with V_i = compensated signal of channel i (i = x, y, z)

 U_i = input signal of channel i (i = x, y, z)

cf = crest factor of exciting field (DASY parameter)

 dcp_i = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes :
$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

H-field probes :
$$H_{i} = \sqrt{V_{i}} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^{2}}{f}$$

with V_i = compensated signal of channel i (i = x, y, z)

 $Norm_i$ = sensor sensitivity of channel i (i = x, y, z)

 $\mu V/(V/m)^2$ for E-field Probes

ConvF = sensitivity enhancement in solution

 a_{ii} = sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

 E_i = electric field strength of channel i in V/m

Hi = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$



The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

 E_{tot} = total field strength in V/m

 σ = conductivity in [mho/m] or [Siemens/m]

 ρ = equivalent tissue density in g/cm³

*Note: That the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770}$$
 or $P_{pwe} = \frac{H_{tot}^2}{37.7}$

with P_{pwe} = equivalent power density of a plane wave in mW/cm²

 E_{tot} = total electric field strength in V/m

 H_{tot} = total magnetic field strength in A/m



6. Test Equipment List

| Manufacturer | Name of Equipment | Type/Model | Serial Number | Calibration | | | |
|---------------|----------------------------------|----------------------------|----------------------|---------------|---------------|--|--|
| Manufacturer | Ivaine of Equipment | Турелиодеі | Serial Number | Last Cal. | Due Date | | |
| SPEAG | Dosimetric E-Field Probe | ES3DV3 | 3150 | Jan. 19. 2011 | Jan. 19. 2012 | | |
| SPEAG | 1950MHz System Validation Kit | D1950V3 | 1117 | Feb. 24, 2011 | Feb. 24, 2012 | | |
| SPEAG | Data Acquisition Electronics | DAE4 | 541 | Jul. 21, 2011 | Jul. 21, 2012 | | |
| SPEAG | Device Holder | N/A | N/A | NCR | NCR | | |
| SPEAG | Phantom | SAM V4.0 | TP-1009 | NCR | NCR | | |
| SPEAG | Robot | Staubli TX90XL | F07/564ZA1/C/01 | NCR | NCR | | |
| SPEAG | Software | DASY4 V4.7 Build 80 | N/A | NCR | NCR | | |
| SPEAG | Software | SEMCAD X V1.8 Build 186 | N/A | NCR | NCR | | |
| SPEAG | Measurement Server | SE UMS 011 AA | 1025 | NCR | NCR | | |
| Agilent | ENA Series Network Analyzer | E5071B | MY42402996 | Jan. 04, 2011 | Jan. 04, 2013 | | |
| Agilent | Dielectric Probe Kit | 85070C | US99360094 | NCR | NCR | | |
| R&S | Power Sensor | NRP-Z22 | 100179 | May 27, 2011 | May 27, 2012 | | |
| Agilent | MXG Vector Signal Generator | N5182A | MY47420962 | May 16, 2011 | May 16, 2012 | | |
| Agilent | Dual Directional Coupler | 778D | 50334 | NCR | NCR | | |
| Mini-Circuits | Power Amplifier | ZHL-42W-SMA | D111103#5 | NCR | NCR | | |
| Mini-Circuits | Power Amplifier | ZVE-8G-SMA | D042005 671800514 | NCR | NCR | | |

Table 2. Test Equipment List

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7. Tissue Simulating Liquids

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The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue. The dielectric parameters of the liquids were verified prior to the SAR evaluation using an 85070C Dielectric Probe Kit and an E5071B Network Analyzer.

IEEE SCC-34/SC-2 in 1528 recommended Tissue Dielectric Parameters

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in human head. Other head and body tissue parameters that have not been specified in 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equation and extrapolated according to the head parameter specified in 1528.

| € | He | ad | Body | | |
|-------------|--------------------------|-----------------------------|------------------|---------|--|
| (MHz) | εr | σ (S/m) | εr | σ (S/m) | |
| 150 | 52.3 | 0.76 | 61.9 | 0.80 | |
| 300 | 45.3 | 0.87 | 58.2 | 0.92 | |
| 450 | 43.5 | 0.87 | 56.7 | 0.94 | |
| 835 | 41.5 | 0.90 | 55.2 | 0.97 | |
| 900 | 41.5 | 0.97 | 55.0 | 1.05 | |
| 915 | 41.5 | 0.98 | 55.0 | 1.06 | |
| 1450 | 40.5 | 1.20 | 54.0 | 1.30 | |
| 1610 | 40.3 | 1.29 | 53.8 | 1.40 | |
| 1800 - 2000 | 40.0 | 1.40 | 53.3 | 1.52 | |
| 2450 | 39.2 | 1.80 | 52.7 | 1.95 | |
| 3000 | 38.5 | 2.40 | 52.0 | 2.73 | |
| 5800 | 35.3 | 5.27 | 48.2 | 6.00 | |
| (εr | = relative permittivity, | σ = conductivity and | ρ = 1000 kg/m3) | | |

Table 3. Tissue dielectric parameters for head and body phantoms



7.1 Ingredients

The following ingredients are used:

- Water: deionized water (pure H_20), resistivity \geq 16 M Ω -as basis for the liquid
- Sugar: refied white sugar (typically 99.7 % sucrose, available as crystal sugar in food shops) to reduce relative permittivity
- Salt: pure NaCl -to increase conductivity
- Cellulose: Hydroxyethyl-cellulose, medium viscosity (75-125 mPa.s, 2% in water, 20°C), CAS # 54290 -to increase viscosity and to keep sugar in solution.
- Preservative: Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS # 55965-84-9 -to prevent the spread of bacteria and molds
- DGBE: Diethylenglycol-monobuthyl ether (DGBE), Fluka Chemie GmbH, CAS # 112-34-5 -to reduce relative permittivity

7.2 Recipes

The following tables give the recipes for tissue simulating liquids to be used in different frequency bands.

Note: The goal dielectric parameters (at 22 $^{\circ}$ C) must be achieved within a tolerance of ±5% for ϵ and ±5% for σ .

| Liquid type | HSL 1950-B | | | | |
|----------------------------|------------|------------|--|--|--|
| Ingredient | Weight (g) | Weight (%) | | | |
| Water | 554.12 | 55.41 | | | |
| DGBE | 445.08 | 44.51 | | | |
| Salt | 0.80 | 0.08 | | | |
| Total amount | 1,000.00 | 100.00 | | | |
| Goal dielectric parameters | | | | | |
| Frequency [MHz] | 1800-2000 | | | | |
| Relative Permittivity | 40.0 | | | | |
| Conductivity [S/m] | 1.4 | 40 | | | |

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7.3 Liquid Confirmation

7.3.1 Parameters

| Liquid Verify | | | | | | | | | |
|--|--------------------|--------------|------------|-----------------|-------------------|---------------|--------------|------------------|---------------|
| Ambient Temperature: 22 ± 2 °C; Relative Humidity: 40 -70% | | | | | | | | | |
| Liquid Type | Frequency | Temp (°C) | Parameters | Target Value | Measured Value | Deviation (%) | Limit (%) | Measured Date | |
| | 1920MHz 1950MHz | 1020MH- | 22.0 | ٤r | 40.00 | 38.90 | -2.75 % | ±5% | Dec. 06, 2011 |
| | | 22.0 | σ | 1.40 | 1.38 | -1.43 % | ±5% | Dec. 00, 2011 | |
| 1950MHz | | 22.0 | ٤r | 40.00 | 38.94 | -2.65 % | ±5% | Dec. 06, 2011 | |
| Head | | 22.0 | σ | 1.40 | 1.42 | 1.43 % | ±5% | Dec. 00, 2011 | |
| | 1978MHz | 22.0 | ٤r | 40.00 | 38.90 | -2.75 % | ±5% | Dec. 06. 2011 | |
| | | 22.0 | σ | 1.40 | 1.46 | 4.29 % | ±5% | Dec. 00, 2011 | |

Table 4. Measured Tissue dielectric parameters for head phantoms

7.3.2 Liquid Depth

The liquid level was during measurement 15cm \pm 0.5cm.

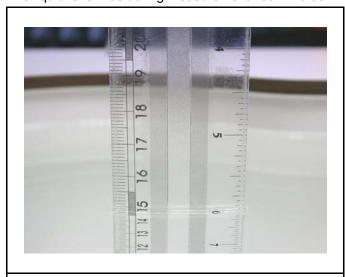


Figure 7. Head-Tissue-Simulating-Liquid

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8. Measurement Process

8.1 Device and Test Conditions

The Test Device was provided by **VTech Telecommunications Ltd.** for this evaluation. The spatial peak SAR values were assessed for the middle channels defined by UPCS (Ch2 = 1924.992MHz) systems. The antenna(s), battery and accessories shall be those specified by the manufacturer. The battery shall be fully charged before each measurement and there shall be no external connections.

| Usage | Operates with normal mode by client | | | | | | |
|--|---|--------------------|--------------------------|-------------------------|--|--|--|
| Distance between antenna axis at the joint and the liquid surface: | For head, EUT left head, right head, to phantom 0mm separation. | | | | | | |
| Simulating human Head/Body | Head | | | | | | |
| EUT Battery | Fully-charged with | Ni-MH batteries. | | | | | |
| Conducted power | Channel | Frequency (MHz) | Before SAR Test (dBm) | After SAR Test (dBm) | | | |
| | Middle Ch 2 | 1924.992 | 20.26 | 20.21 | | | |

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8.2 System Performance Check

8.2.1 Symmetric Dipoles for System Validation

Construction Symmetrical dipole with I/4 balun enables measurement of feed point impedance

with NWA matched for use near flat phantoms filled with head simulating solutions Includes distance holder and tripod adaptor Calibration Calibrated SAR value for specified position and input power at the flat phantom in head simulating solutions.

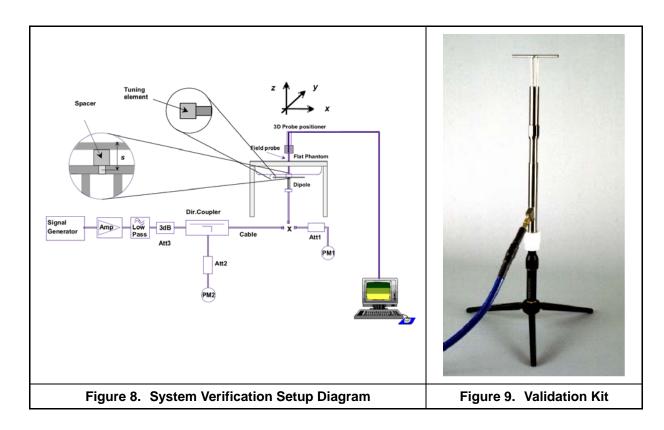
Frequency 1950 MHz

Return Loss > 20 dB at specified validation position Power Capability > 100 W (f < 1GHz); > 40 W (f > 1GHz)

Options Dipoles for other frequencies or solutions and other calibration conditions are

available upon request

Dimensions D1950V3: dipole length 67.5 mm; overall height 300 mm



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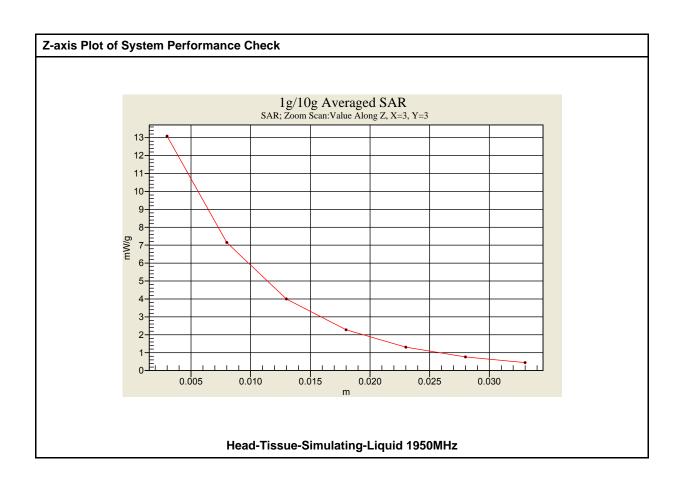


8.2.2 Validation

Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of \pm 7%. The validation was performed at 1950MHz.

| Validat | ion kit | Mixture Type | SAR₁g [mW/g] | | SAR _{10g} [mW/g] | | Date of Calibration |
|--------------------|------------------------|-----------------------------|------------------------------|---------------|------------------------------|-----------------------|------------------------|
| D1950V3 | - SN1117 | Head | 42.00 | | 21.60 | | Feb. 24, 2011 |
| Frequency (MHz) | Power | SAR _{1g} (mW/g) | SAR _{10g} (mW/g) | Drift (dB) | _ | rence ntage 10g | Validation Date |
| 1950 | 250mW | 10.2 | 5.22 | 0.046 | 2.0.0/ | 2.2.0/ | D 00 0044 |
| (Head) | Normalize to 1 Watt | 40.8 | 20.88 | -0.016 | -2.9 % | -3.3 % | Dec. 06, 2011 |

Detail results see Appendix A.



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8.3 Dosimetric Assessment Setup

8.3.1 Body Test Position

Body - Worn Configuration

Body - Worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a headset output should be tested with a headset connected to the device.

Body - Worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 15 mm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances.

For this test :

| The EUT is placed into the holster/belt clip and the holster is positioned against the surface of the phantom in a normal operating position. |
|---|
| Belt clip sold with the product is not available. Therefore for SAR measurement, 0mm separation |
| between the product and phantom is done for worst-case compliance. |

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8.3.2 Measurement Procedures

The evaluation was performed with the following procedures:

Surface Check:

A surface checks job gathers data used with optical surface detection. It determines the distance from the phantom surface where the reflection from the optical detector has its peak. Any following measurement jobs using optical surface detection will then rely on this value. The surface check performs its search a specified number of times, so that the repeatability can be verified. The probe tip distance is 1.3mm to phantom inner surface during scans.

Reference:

The reference job measures the field at a specified reference position, at 4 mm from the selected section's grid reference point.

Area Scan:

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines can find the maximum locations even in relatively coarse grids. When an area scan has measured all reachable points, it computes the field maxima found in the scanned area, within a range of the global maximum. Any following zoom scan within the same procedure will then perform fine scans around these maxima. The area covered the entire dimension of the EUT and the horizontal grid spacing was $15 \text{ mm} \times 15 \text{ mm}$.

Zoom Scan:

Zoom scans are used to assess the highest averaged SAR for cubic averaging volumes with 1 g and 10 g of simulated tissue. The zoom scan measures $7 \times 7 \times 9$ points in a 30 x 30 x 24 mm cube whose base faces are centered around the maxima returned from a preceding area scan within the same procedure.

Drift:

The drift job measures the field at the same location as the most recent reference job within the same procedure, with the same settings. The drift measurement gives the field difference in dB from the last reference measurement. Several drift measurements are possible for each reference measurement. This allows monitoring of the power drift of the device in the batch process. If the value changed by more than 5%, the evaluation was repeated.

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8.4 Spatial Peak SAR Evaluation

The DASY4 software includes all numerical procedures necessary to evaluate the spatial peak SAR values. Based on the Draft: SCC-34, SC-2, WG-2 - Computational Dosimetry, IEEE P1529/D0.0 (Draft Recommended Practice for Determining the Spatial-Peak Specific Absorption Rate (SAR) Associated with the Use of Wireless Handsets - Computational Techniques), a new algorithm has been implemented. The spatial-peak SAR can be computed over any required mass.

The base for the evaluation is a "cube" measurement in a volume of ($30 \times 30 \times 24 \text{ mm}^3$) ($7 \times 7 \times 9 \text{ points}$). The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan. If the 10g cube or both cubes are not entirely inside the measured volumes, the system issues a warning regarding the evaluated spatial peak values within the Postprocessing engine (SEMCAD). This means that if the measured volume is shifted, higher values might be possible. To get the correct values you can use a finer measurement grid for the area scan. In complicated field distributions, a large grid spacing for the area scan might miss some details and give an incorrectly interpolated peak location.

The entire evaluation of the spatial peak values is performed within the Postprocessing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into three stages:

Interpolation and Extrapolation

The probe is calibrated at the center of the dipole sensors which is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated.

In DASY4, the choice of the coordinate system defining the location of the measurement points has no influence on the uncertainty of the interpolation, Maxima Search and SAR extrapolation routines. The interpolation, Maxima Search and extrapolation routines are all based on the modified Quadratic Shepard's method [7].

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9. Measurement Uncertainty

Measurement uncertainties in SAR measurements are difficult to quantify due to several variables including biological, physiological, and environmental. However, we estimate the measurement uncertainties in SAR to be less than $\pm 20.10 \%$ [8].

According to Std. C95.3[9], the overall uncertainties are difficult to assess and will vary with the type of meter and usage situation. However, accuracy's of ± 1 to 3 dB can be expected in practice, with greater uncertainties in near-field situations and at higher frequencies (shorter wavelengths), or areas where large reflecting objects are present. Under optimum measurement conditions, SAR measurement uncertainties of at least ± 2 dB can be expected.

According to CENELEC (10), typical worst-case uncertainty of field measurements is ± 5 dB. For well-defined modulation characteristics the uncertainty can be reduced to ± 3 dB.

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| Uncertainty Component | Uncertainty Value | Probability Distribution | Divisor | <i>c_i</i> (1g) | c _i (10g) | Standard Uncertainty ±1% (1-g) | Standard Uncertainty ±1% (10-g) | V _i or V _{eff} |
|--|----------------------|-----------------------------|------------|---------------------------|-------------------------|---|--|--|
| Measurement System | | _ | _ | <u>-</u> . | <u>-</u> | | _ | |
| Probe Calibration (k=1) | ±5.5% | Normal | 1 | 1 | 1 | ±5.5% | ±5.5% | 8 |
| Probe Isotropy | ±7.6% | Rectangular | $\sqrt{3}$ | 0.7 | 0.7 | ±3.1% | ±3.1% | 8 |
| Boundary Effect | ±1.0% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.6% | ±0.6% | 8 |
| Linearity | ±4.7% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±2.7% | ±2.7% | 8 |
| System Detection Limit | ±1.0% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.58% | ±0.58% | 8 |
| Readout Electronics | ±0.3% | Normal | 1 | 1 | 1 | ±0.3% | ±0.3% | 8 |
| Response Time | ±0.8% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.5% | ±0.5% | 8 |
| Integration Time | ±2.6% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±1.5% | ±1.5% | 8 |
| RF Ambient Conditions | ±0% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0% | ±0% | 8 |
| RF Ambient Reflections | ±0% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0% | ±0% | 8 |
| Probe Positioner Mechanical Tolerance | ±0.4% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.2% | ±0.2% | 8 |
| Probe Positioning with respect to Phantom Shell | ±2.9% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±1.7% | ±1.7% | 8 |
| Extrapolation, interpolation and integration Algorithms for Max. SAR | ±1.0% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.6% | ±0.6% | 8 |
| Test sample Related | | | | | | | | |
| Test sample Positioning | ±3.6% | Normal | 1 | 1 | 1 | ±3.6% | ±3.6% | 89 |
| Device Holder Uncertainty | ±3.5% | Normal | 1 | 1 | 1 | ±3.5% | ±3.5% | 5 |
| Output Power Variation - SAR drift measurement | ±5.0% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±2.9% | ±2.9% | 8 |
| Phantom and Tissue Parameters | | _ | _ | | <u>-</u> | | _ | |
| Phantom Uncertainty (shape and thickness tolerances) | ±4.0% | Rectangular | $\sqrt{3}$ | 1 | 1 | ±2.3% | ±2.3% | 8 |
| Liquid Conductivity - deviation from target values | ±5.0% | Rectangular | $\sqrt{3}$ | 0.64 | 0.43 | ±1.8% | ±1.2% | 8 |
| Liquid Conductivity - measurement uncertainty | ±1.93% | Normal | 1 | 0.64 | 0.43 | ±1.24% | ±0.83% | 69 |
| Liquid Permittivity - deviation from target values | ±5.0 | Rectangular | $\sqrt{3}$ | 0.6 | 0.49 | ±1.7% | ±1.4% | 8 |
| Liquid Permittivity - measurement uncertainty | ±1.4% | Normal | 1 | 0.6 | 0.49 | ±0.84% | ±0.69% | 69 |
| Combined standard uncer | tainty | RSS | | | | ±10.05% | ±9.85% | 313 |
| Expanded uncertainty (95% CONFIDENCE LEV | k=2 | | | | ±20.10% | ±19.70% | | |

Table 5. System uncertainty: 300MHz -3000MHz

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| Uncertainty Component | Uncertainty Value | Probability Distribution | Divisor | <i>c_i</i> (1g) | <i>c_i</i> (10g) | Standard Uncertainty ±1% (1-g) | Standard Uncertainty ±1% (10-g) | $egin{array}{c} oldsymbol{V_i} \ oldsymbol{Or} \ oldsymbol{V_{\mathit{eff}}} \end{array}$ |
|-----------------------------|----------------------|-----------------------------|------------|---------------------------|----------------------------|---|--|---|
| Measurement System | | _ | _ | _ | | _ | | |
| Probe Calibration | ±6.55 % | Normal | 1 | 1 | 1 | ±6.55 % | ±6.55 % | 8 |
| Axial Isotropy | ±4.7 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±2.7 % | ±2.7 % | 8 |
| Hemispherical Isotropy | ±9.6 % | Rectangular | $\sqrt{3}$ | 0 | 0 | ±0 % | ±0 % | 8 |
| Boundary Effects | ±1.0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.6% | ±0.6 % | 8 |
| Linearity | ±4.7 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±2.7 % | ±2.7 % | 8 |
| System Detection Limits | ±1.0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.6 % | ±0.6 % | 8 |
| Modulation Response | ±0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0 % | ±0 % | 8 |
| Readout Electronics | ±0.3 % | Normal | 1 | 1 | 1 | ±0.3 % | ±0.3 % | 8 |
| Response Time | ±0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0 % | ±0 % | 8 |
| Integration Time | ±0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0 % | ±0 % | 8 |
| RF Ambient Noise | ±1.0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.6 % | ±0.6 % | 8 |
| RF Ambient Reflections | ±1.0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.6 % | ±0.6 % | 8 |
| Probe Positioner | ±0.8 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±0.5 % | ±0.5 % | 8 |
| Probe Positioning | ±6.7 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±3.9 % | ±3.9 % | 8 |
| Max. SAR Eval. | ±2.0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±1.2 % | ±1.2 % | 8 |
| Dipole Related | | | | - | | | | |
| Deviation of exp. dipole | ±5.5 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±3.2 % | ±3.2 % | 8 |
| Dipole Axis to Liquid Dist. | ±2.0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±1.2 % | ±1.2 % | 8 |
| Input power & SAR drift | ±3.4 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±2.0 % | ±2.0 % | 8 |
| Phantom and Setup | | | | | | | | |
| Phantom Uncertainty | ±4.0 % | Rectangular | $\sqrt{3}$ | 1 | 1 | ±2.3 % | ±2.3 % | 8 |
| SAR correction | ±1.9 % | Rectangular | $\sqrt{3}$ | 1 | 0.84 | ±1.1 % | ±0.9 % | 8 |
| Liquid Conductivity (meas.) | ±2.5 % | Normal | 1 | 0.78 | 0.71 | ±2.0 % | ±1.8 % | 8 |
| Liquid Permittivity (meas.) | ±2.5 % | Normal | 1 | 0.26 | 0.26 | ±0.7 % | ±0.7 % | 8 |
| Temp. uncConductivity | ±1.7 % | Rectangular | $\sqrt{3}$ | 0.78 | 0.71 | ±0.8 % | ±0.7 % | 8 |
| Temp. uncPermittivity | ±0.3 % | Rectangular | $\sqrt{3}$ | 0.23 | 0.26 | ±0.0 % | ±0.0 % | 8 |
| Combined standard uncerta | ainty | RSS | | | | ±10.1% | ±10.1 % | |
| Expanded uncertainty | | k=2 | | | | ±20.2 | ±20.1 % | |

Table 6. Uncertainty Budget for System Validation for the 0.3 -6 GHz range

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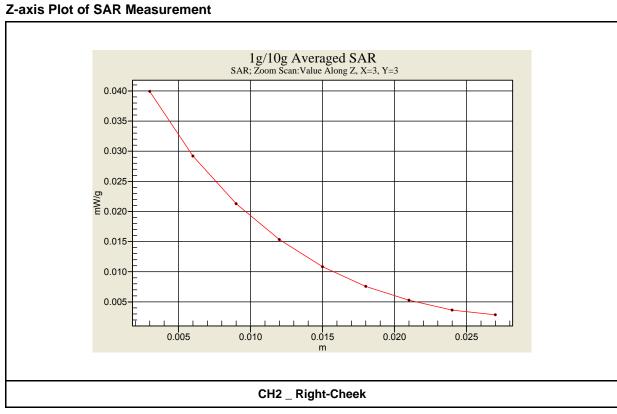


SAR Test Results Summary *10.*

10.1 **Head SAR**

| Measurement Results | | | | | | | | | |
|---|-----------|----------|---------|---------------------|-----------|---|----------------|-------------|--------|
| Band | Frequency | | Battery | Phantom Position | Accessory | SAR _{1g} [mW/g] | Power Drift | Amb Temp | Remark |
| | СН | MHz | | Position | | [IIIVV/9] | (dB) | Temp | |
| UPCS | 2 | 1924.992 | Ni-MH | Right-Cheek | N/A | 0.032 | 0.005 | 22.0 | |
| | 2 | 1924.992 | Ni-MH | Right-Tilted | N/A | 0.020 | -0.055 | 22.0 | |
| | 2 | 1924.992 | Ni-MH | Left-Cheek | N/A | 0.031 | 0.016 | 22.0 | |
| | 2 | 1924.992 | Ni-MH | Left-Tilted | N/A | 0.021 | 0.031 | 22.0 | |
| Std. C95.1-1992 - Safety Limit Spatial Peak Uncontrolled Exposure/General Population | | | | | | 1.6 W/kg (mW/g) Averaged over 1 gram | | | |

Detail results see Appendix B.



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10.2 Std. C95.1-1992 RF Exposure Limit

| | Population | Occupational | | |
|---------------------------------|--------------------|--------------------|--|--|
| Human Exposure | Uncontrolled | Controlled | | |
| Tiuman Exposure | Exposure | Exposure | | |
| | (W/kg) or (mW/g) | (W/kg) or (mW/g) | | |
| Spatial Peak SAR* | 1.60 | 8.00 | | |
| (head) | 1.00 | 0.00 | | |
| Spatial Peak SAR** | 0.08 | 0.40 | | |
| (Whole Body) | 0.00 | 0.40 | | |
| Spatial Peak SAR*** | 1.60 | 8.00 | | |
| (Partial-Body) | 1.00 | 0.00 | | |
| Spatial Peak SAR**** | 4.00 | 20.00 | | |
| (Hands / Feet / Ankle / Wrist) | 4.00 | | | |

Table 7. Safety Limits for Partial Body Exposure

Notes:

- * The Spatial Peak value of the SAR averaged over any 1 gram of tissue.(defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.
- ** The Spatial Average value of the SAR averaged over the whole body.
- *** The Spatial Average value of the SAR averaged over the partial body.
- **** The Spatial Peak value of the SAR averaged over any 10 grams of tissue.

 (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Population / **Uncontrolled Environments**: are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Occupational / Controlled Environments: are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

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11. Conclusion

The SAR test values found for the portable mobile phone **VTech Telecommunications Ltd. Trade Name: VTech Model(s): CS6529** is below the maximum recommended level of 1.6 W/kg (mW/g).

12. References

- [1] Std. C95.1-1992, "American National Standard safety levels with respect to human exposure to radio frequency electromagnetic fields, 300KHz to 100GHz", New York.
- [2] NCRP, National Council on Radiation Protection and Measurements, "Biological Effects and Exposure Criteria for Radio frequency Electromagnetic Fields", NCRP report NO. 86, 1986.
- [3] T. Schmid, O. Egger, and N. Kuster, "Automatic E-field scanning system for dosimetric assessments", IEEE Transactions on Microwave Theory and Techniques, vol. 44, pp, 105-113, Jan. 1996.
- [4] K. Poković, T. Schmid, and N. Kuster, "Robust setup for precise calibration of E-field probes in tissue simulating liquids at mobile communications frequency", in ICECOM'97, Dubrovnik, October 15-17, 1997, pp.120-124.
- [5] K. Poković, T. Schmid, and N. Kuster, "*E-field probe with improved isotropy in brain simulating liquids*", in Proceedings of the ELMAR, Zadar, Croatia, 23-25 June, 1996, pp.172-175.
- [6] N. Kuster, and Q. Balzano, "Energy absorption mechanism by biological bodies in the near field of dipole antennas above 300MHz", IEEE Transaction on Vehicular Technology, vol. 41, no. 1, Feb. 1992, pp. 17-23.
- [7] Robert J. Renka, "Multivariate Interpolation Of Large Sets Of Scattered Data", University of North Texas ACM Transactions on Mathematical Software, vol. 14, no. 2, June 1988, pp. 139-148.
- [8] N. Kuster, R. Kastle, T. Schmid, *Dosimetric evaluation of mobile communications equipment with known precision*, IEEE Transaction on Communications, vol. E80-B, no. 5, May 1997, pp. 645-652.
- [9] Std. C95.3-1991, "IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields RF and Microwave, New York: IEEE, Aug. 1992.
- [10] CENELEC CLC/SC111B, European Prestandard (prENV 50166-2), *Human Exposure to Electromagnetic Fields High-frequency*: 10KHz-300GHz, Jan. 1995.



Appendix A - System Performance Check

Test Laboratory: A Test Lab Techno Corp.

Date/Time: 2011/12/6 PM 12:06:19

System Performance Check at 1950MHz_20111206_Head

DUT: Dipole 1950 MHz; Type: D1950V3; Serial: D1950V3 - SN:1117

Communication System: CW; Frequency: 1950 MHz; Duty Cycle: 1:1

Medium parameters used: f = 1950 MHz; $\sigma = 1.42 \text{ mho/m}$; $\varepsilon_r = 38.9$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: ES3DV3 SN3150; ConvF(5.18, 5.18, 5.18); Calibrated: 2011/1/19
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 2011/7/21
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 80;Postprocessing SW: SEMCAD, V1.8 Build 186

System Performance Check at 1950MHz/Area Scan (61x61x1):

Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 13.4 mW/g

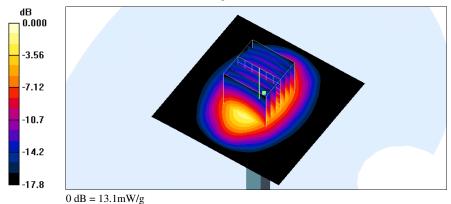
System Performance Check at 1950MHz/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 98.2 V/m; Power Drift = -0.016 dB

Peak SAR (extrapolated) = 18.8 W/kg

SAR(1 g) = 10.2 mW/g; SAR(10 g) = 5.22 mW/g Maximum value of SAR (measured) = 13.1 mW/g



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Appendix B - SAR Measurement Data

Test Laboratory: A Test Lab Techno Corp.

Date/Time: 2011/12/6 PM 03:45:02

RC_DECT CH2

DUT: CS6529; Type: 1.9GHz DECT 6.0 Cordless Phone; FCC ID: EW780-8535-00

Communication System: DECT; Frequency: 1924.992 MHz; Duty Cycle: 1:24

Medium parameters used: f = 1924.992 MHz; $\sigma = 1.38 \text{ mho/m}$; $\varepsilon_r = 38.9$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Right Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: ES3DV3 SN3150; ConvF(5.18, 5.18, 5.18); Calibrated: 2011/1/19
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 2011/7/21
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 80;Postprocessing SW: SEMCAD, V1.8 Build 186

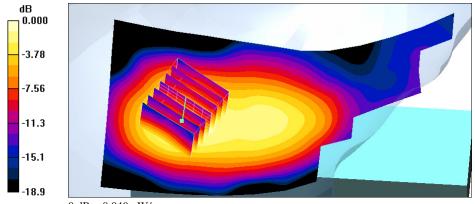
Right Cheek/Area Scan (61x121x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.041 mW/g

Right Cheek/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 4.86 V/m; Power Drift = 0.005 dB Peak SAR (extrapolated) = 0.052 W/kg SAP(10g) = 0.032 mW/g; SAP(10g) = 0.018 mW/g

SAR(1 g) = 0.032 mW/g; SAR(10 g) = 0.018 mW/gMaximum value of SAR (measured) = 0.040 mW/g



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Test Laboratory: A Test Lab Techno Corp.

Date/Time: 2011/12/6 PM 04:13:57

RT_DECT CH2

DUT: CS6529; Type: 1.9GHz DECT 6.0 Cordless Phone; FCC ID: EW780-8535-00

Communication System: DECT; Frequency: 1924.992 MHz; Duty Cycle: 1:24

Medium parameters used: f = 1924.992 MHz; $\sigma = 1.38 \text{ mho/m}$; $\varepsilon_r = 38.9$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Right Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

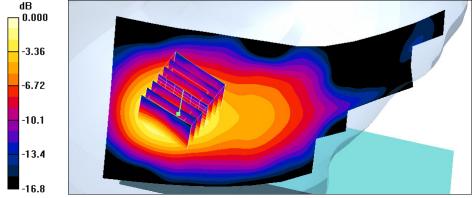
- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: ES3DV3 SN3150; ConvF(5.18, 5.18, 5.18); Calibrated: 2011/1/19
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 2011/7/21
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 80;Postprocessing SW: SEMCAD, V1.8 Build 186

Right Tilted/Area Scan (61x121x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = $0.025 \ mW/g$

Right Tilted/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 4.23 V/m; Power Drift = -0.055 dB Peak SAR (extrapolated) = 0.034 W/kg SAR(1 g) = 0.020 mW/g; SAR(10 g) = 0.011 mW/g Maximum value of SAR (measured) = 0.025 mW/g



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Test Laboratory: A Test Lab Techno Corp.

Date/Time: 2011/12/6 PM 04:42:12

LC_DECT CH2

DUT: CS6529; Type: 1.9GHz DECT 6.0 Cordless Phone; FCC ID: EW780-8535-00

Communication System: DECT; Frequency: 1924.992 MHz; Duty Cycle: 1:24

Medium parameters used: f = 1924.992 MHz; $\sigma = 1.38 \text{ mho/m}$; $\varepsilon_r = 38.9$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Left Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

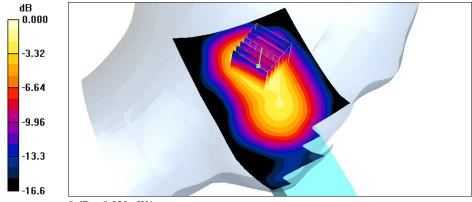
- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: ES3DV3 SN3150; ConvF(5.18, 5.18, 5.18); Calibrated: 2011/1/19
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 2011/7/21
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 80;Postprocessing SW: SEMCAD, V1.8 Build 186

Left Cheek/Area Scan (61x121x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.041 mW/g

Left Cheek/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 4.66 V/m; Power Drift = 0.016 dB Peak SAR (extrapolated) = 0.051 W/kg SAR(1 g) = 0.031 mW/g; SAR(10 g) = 0.017 mW/g Maximum value of SAR (measured) = 0.039 mW/g



0 dB = 0.039 mW/g

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Test Laboratory: A Test Lab Techno Corp.

Date/Time: 2011/12/6 PM 05:07:27

LT_DECT CH2

DUT: CS6529; Type: 1.9GHz DECT 6.0 Cordless Phone; FCC ID: EW780-8535-00

Communication System: DECT; Frequency: 1924.992 MHz; Duty Cycle: 1:24

Medium parameters used: f = 1924.992 MHz; $\sigma = 1.38 \text{ mho/m}$; $\varepsilon_r = 38.9$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Left Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

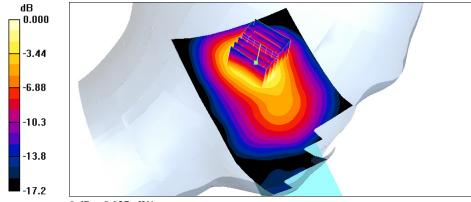
- Area Scan setting Find Secondary Maximum Within: 2.0dB and with a peak SAR value greater than 0.5 W/Kg
- Probe: ES3DV3 SN3150; ConvF(5.18, 5.18, 5.18); Calibrated: 2011/1/19
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn541; Calibrated: 2011/7/21
- Phantom: SAM 12; Type: SAM v4.0; Serial: TP:1009
- Measurement SW: DASY4, V4.7 Build 80;Postprocessing SW: SEMCAD, V1.8 Build 186

Left Tilted/Area Scan (61x121x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.028 mW/g

Left Tilted/Zoom Scan (7x7x9)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=3mm Reference Value = 4.35 V/m; Power Drift = 0.031 dB Peak SAR (extrapolated) = 0.034 W/kg SAR(1 g) = 0.021 mW/g; SAR(10 g) = 0.012 mW/g Maximum value of SAR (measured) = 0.027 mW/g



0 dB = 0.027 mW/g

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Appendix C - Calibration

All of the instruments Calibration information are listed below.

- Dipole _ D1950V3 SN:1117 Calibration No.D1950V3-1117_Feb11
- Probe _ ES3DV3 SN:3150 Calibration No.ES3-3150_Jan11
- DAE _ DAE4 SN:541 Calibration No.DAE4-541_ Jul11

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Client ATL (Auden) Certificate No: D1950V3-1117_Feb11 CALIBRATION CERTIFICATE Object D1950V3 - SN: 1117 Calibration procedure(s) QA CAL-05.v8 Calibration procedure for dipole validation kits Calibration date: February 24, 2011 This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%. Calibration Equipment used (M&TE critical for calibration) Primary Standards ID# Cal Date (Certificate No.) Scheduled Calibration Power meter EPM-442A GB37480704 06-Oct-10 (No. 217-01266) Oct-11 Power sensor HP 8481A US37292783 06-Oct-10 (No. 217-01266) Oct-11 Reference 20 dB Attenuator SN: 5086 (20g) 30-Mar-10 (No. 217-01158) Mar-11 Type-N mismatch combination SN: 5047.2 / 06327 30-Mar-10 (No. 217-01162) Mar-11 Reference Probe ES3DV3 SN: 3205 30-Apr-10 (No. ES3-3205_Apr10) Apr-11 DAE4 SN: 601 10-Jun-10 (No. DAE4-601_Jun10) Jun-11 Secondary Standards ID# Check Date (in house) Scheduled Check Power sensor HP 8481A MY41092317 18-Oct-02 (in house check Oct-09) In house check: Oct-11 RF generator R&S SMT-06 100005 4-Aug-99 (in house check Oct-09) In house check: Oct-11 Network Analyzer HP 8753E US37390585 S4206 18-Oct-01 (in house check Oct-10) In house check: Oct-11 Name Function Signature Calibrated by: Dimce Iliev Laboratory Technician Katja Pokovic Approved by: Technical Manager Issued: February 24, 2011

Certificate No: D1950V3-1117_Feb11

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Report Number: 1112FS14



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Glossary:

TSL

tissue simulating liquid

ConvF

sensitivity in TSL / NORM x,y,z

N/A not applicable or not measured

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

Additional Documentation:

d) DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end
 of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed
 point exactly below the center marking of the flat phantom section, with the arms oriented
 parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole
 positioned under the liquid filled phantom. The impedance stated is transformed from the
 measurement at the SMA connector to the feed point. The Return Loss ensures low
 reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point.
 No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

Certificate No: D1950V3-1117_Feb11 Page 2 of 9



Measurement Conditions

DASY system configuration, as far as not given on page 1.

| DASY Version | DASY5 | V52.6 |
|------------------------------|---------------------------|-------------|
| Extrapolation | Advanced Extrapolation | |
| Phantom | Modular Flat Phantom V5.0 | |
| Distance Dipole Center - TSL | 10 mm | with Spacer |
| Zoom Scan Resolution | dx, dy, dz = 5 mm | |
| Frequency | 1950 MHz ± 1 MHz | |

Head TSL parameters

The following parameters and calculations were applied.

| | Temperature | Permittivity | Conductivity |
|----------------------------------|-----------------|--------------|------------------|
| Nominal Head TSL parameters | 22.0 °C | 40.0 | 1.40 mho/m |
| Measured Head TSL parameters | (22.0 ± 0.2) °C | 40.8 ± 6 % | 1.35 mho/m ± 6 % |
| Head TSL temperature during test | (21.0 ± 0.2) °C | 22207 | 1444 |

SAR result with Head TSL

| SAR averaged over 1 cm ³ (1 g) of Head TSL | Condition | |
|---|--------------------|---------------------------|
| SAR measured | 250 mW input power | 10.3 mW / g |
| SAR normalized | normalized to 1W | 41.2 mW / g |
| SAR for nominal Head TSL parameters | normalized to 1W | 42.0 mW /g ± 17.0 % (k=2) |

| SAR averaged over 10 cm ³ (10 g) of Head TSL | condition | |
|---|--------------------|---------------------------|
| SAR measured | 250 mW input power | 5.36 mW / g |
| SAR normalized | normalized to 1W | 21.4 mW / g |
| SAR for nominal Head TSL parameters | normalized to 1W | 21.6 mW /g ± 16.5 % (k=2) |



Body TSL parameters
The following parameters and calculations were applied.

| - Les CALID. | Temperature | Permittivity | Conductivity |
|----------------------------------|-----------------|--------------|------------------|
| Nominal Body TSL parameters | 22.0 °C | 53.3 | 1.52 mho/m |
| Measured Body TSL parameters | (22.0 ± 0.2) °C | 53.8 ± 6 % | 1.49 mho/m ± 6 % |
| Body TSL temperature during test | (21.5 ± 0.2) °C | | **** |

SAR result with Body TSL

| SAR averaged over 1 cm ³ (1 g) of Body TSL | Condition | |
|---|--------------------|----------------------------|
| SAR measured | 250 mW input power | 9.76 mW / g |
| SAR normalized | normalized to 1W | 39.0 mW / g |
| SAR for nominal Body TSL parameters | normalized to 1W | 39.5 mW / g ± 17.0 % (k=2) |

| SAR averaged over 10 cm ³ (10 g) of Body TSL | condition | |
|---|--------------------|----------------------------|
| SAR measured | 250 mW input power | 5.16 mW / g |
| SAR normalized | normalized to 1W | 20.6 mW / g |
| SAR for nominal Body TSL parameters | normalized to 1W | 20.7 mW / g ± 16.5 % (k=2) |

Report Number: 1112FS14



Appendix

Antenna Parameters with Head TSL

| Impedance, transformed to feed point | 50.2 Ω - 1.5 jΩ | |
|--------------------------------------|-----------------|--|
| Return Loss | - 36.2 dB | |

Antenna Parameters with Body TSL

| Impedance, transformed to feed point | 46.2 Ω - 1.2 jΩ | |
|--------------------------------------|-----------------|--|
| Return Loss | - 27.6 dB | |

General Antenna Parameters and Design

| Electrical Delay (one direction) | 1.198 ns | |
|----------------------------------|----------|--|
|----------------------------------|----------|--|

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

| Manufactured by | SPEAG | |
|-----------------|------------------|--|
| Manufactured on | October 20, 2006 | |

Certificate No: D1950V3-1117_Feb11

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DASY5 Validation Report for Head TSL

Date/Time: 21.02.2011 12:25:12

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 1950 MHz; Type: D1950V3; Serial: D1950V3 - SN:1117

Communication System: CW; Frequency: 1950 MHz; Duty Cycle: 1:1

Medium: HSL BB1.9

Medium parameters used: f = 1950 MHz; $\sigma = 1.37 \text{ mho/m}$; $\varepsilon_r = 40.8$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

Probe: ES3DV3 - SN3205; ConvF(4.96, 4.96, 4.96); Calibrated: 30.04.2010

· Sensor-Surface: 3mm (Mechanical Surface Detection)

Electronics: DAE4 Sn601; Calibrated: 10.06.2010

Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001

Measurement SW: DASY52, V52.6 Build (401)

Postprocessing SW: SEMCAD X, V14.4.2 Build (2595)

Pin=250 mW /d=10mm, dist=3.0mm (ES-Probe)/Zoom Scan (7x7x7) /Cube 0: Measurement

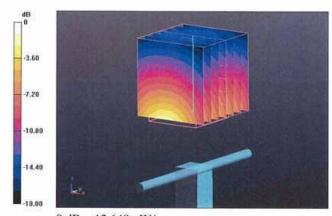
grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 99.080 V/m; Power Drift = 0.07 dB

Peak SAR (extrapolated) = 18.691 W/kg

SAR(1 g) = 10.3 mW/g; SAR(10 g) = 5.36 mW/g

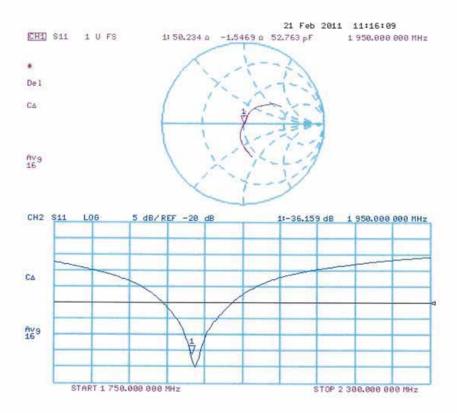
Maximum value of SAR (measured) = 12.637 mW/g



0 dB = 12.640 mW/g



Impedance Measurement Plot for Head TSL





DASY5 Validation Report for Body TSL

Date/Time: 24.02.2011 11:27:10

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 1950 MHz; Type: D1950V3; Serial: D1950V3 - SN:1117

Communication System: CW; Frequency: 1950 MHz; Duty Cycle: 1:1

Medium: MSL BB1.9

Medium parameters used: f = 1950 MHz; $\sigma = 1.5$ mho/m; $\varepsilon_r = 53.8$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

Probe: ES3DV3 - SN3205; ConvF(4.7, 4.7, 4.7); Calibrated: 30.04.2010

Sensor-Surface: 3mm (Mechanical Surface Detection)

Electronics: DAE4 Sn601; Calibrated: 10.06.2010

Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; Serial: 1002

Measurement SW: DASY52, V52.6 Build (401)

Postprocessing SW: SEMCAD X, V14.4.2 Build (2595)

Pin=250 mW /d=10mm, dist=3.0mm (ES-Probe)/Zoom Scan (7x7x7) /Cube 0: Measurement

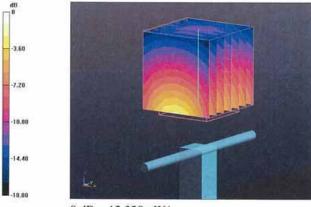
grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 95.673 V/m; Power Drift = 0.0072 dB

Peak SAR (extrapolated) = 16.521 W/kg

SAR(1 g) = 9.76 mW/g; SAR(10 g) = 5.16 mW/g

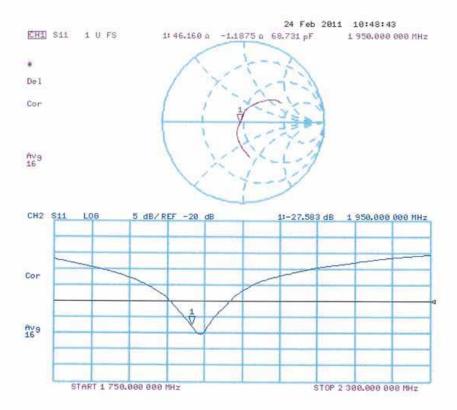
Maximum value of SAR (measured) = 12.318 mW/g



0 dB = 12.320 mW/g



Impedance Measurement Plot for Body TSL





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Client ATL (Auden)

Certificate No: ES3-3150_Jan11

Accreditation No.: SCS 108

CALIBRATION CERTIFICATE

Object ES3DV3 - SN:3150

Calibration procedure(s) QA CAL-01.v7, QA CAL-23.v4 and QA CAL-25.v3

Calibration procedure for dosimetric E-field probes

Calibration date: January 19, 2011

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).

The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID# | Cal Date (Certificate No.) | Scheduled Calibration |
|----------------------------|-----------------|-----------------------------------|------------------------|
| Power meter E4419B | GB41293874 | 1-Apr-10 (No. 217-01136) | Apr-11 |
| Power sensor E4412A | MY41495277 | 1-Apr-10 (No. 217-01136) | Apr-11 |
| Power sensor E4412A | MY41498087 | 1-Apr-10 (No. 217-01136) | Apr-11 |
| Reference 3 dB Attenuator | SN: S5054 (3c) | 30-Mar-10 (No. 217-01159) | Mar-11 |
| Reference 20 dB Attenuator | SN: S5086 (20b) | 30-Mar-10 (No. 217-01161) | Mar-11 |
| Reference 30 dB Attenuator | SN: S5129 (30b) | 30-Mar-10 (No. 217-01160) | Mar-11 |
| Reference Probe ES3DV2 | SN: 3013 | 29-Dec-10 (No. ES3-3013_Dec10) | Dec-11 |
| DAE4 | SN: 660 | 20-Apr-10 (No. DAE4-660_Apr10) | Apr-11 |
| Secondary Standards | ID# | Check Date (in house) | Scheduled Check |
| RF generator HP 8648C | US3642U01700 | 4-Aug-99 (in house check Oct-09) | In house check: Oct-11 |
| Network Analyzer HP 8753E | US37390585 | 18-Oct-01 (in house check Oct-10) | In house check: Oct-11 |
| | Name | Function | Signature |
| Calibrated by: | Marcel Fehr | Laboratory Technician | Miller |
| Approved by: | Katja Pokovic | Technical Manager | 20 KS |

Issued: January 20, 2011

Certificate No: ES3-3150_Jan11

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Glossary:

TSL tissue simulating liquid
NORMx,y,z sensitivity in free space
ConvF sensitivity in TSL / NORMx,y,z
DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal A, B, C modulation dependent linearization parameters

Polarization φ rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., 9 = 0 is normal to probe axis

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- EC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization 9 = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
 NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z * frequency_response (see Frequency Response Chart). This linearization is
 implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included
 in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C are numerical linearization parameters assessed based on the data of
 power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the
 maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

Certificate No: ES3-3150_Jan11 Page 2 of 10



Probe ES3DV3

SN:3150

Manufactured:

June 12, 2007 January 27, 2010

Last calibrated: Recalibrated:

January 19, 2011

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

Certificate No: ES3-3150_Jan11

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DASY/EASY - Parameters of Probe: ES3DV3 SN:3150

Basic Calibration Parameters

| | Sensor X | Sensor Y | Sensor Z | Unc (k=2) |
|-------------------------------|----------|----------|----------|-----------|
| Norm (μV/(V/m)²) ^A | 1.25 | 1.24 | 1.23 | ± 10.1% |
| DCP (mV) ^B | 102.3 | 100.4 | 101.1 | |

Modulation Calibration Parameters

| UID | Communication System Name | PAR | | A dB | B dBuV | С | VR mV | Unc ^E (k=2) |
|-------|---------------------------|------|---|---------|-----------|------|----------|---------------------------|
| 10000 | cw | 0.00 | X | 0.00 | 0.00 | 1.00 | 149.9 | ± 2.4 % |
| | | | Υ | 0.00 | 0.00 | 1.00 | 149.5 | |
| | | | Z | 0.00 | 0.00 | 1.00 | 149.1 | |

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Certificate No: ES3-3150_Jan11

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A The uncertainties of NormX,Y,Z do not affect the E-field uncertainty inside TSL (see Pages 5 and 6).

Numerical linearization parameter: uncertainty not required.

E Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.



DASY/EASY - Parameters of Probe: ES3DV3 SN:3150

Calibration Parameter Determined in Head Tissue Simulating Media

| f [MHz] | Validity [MHz] ^C | Permittivity | Conductivity | ConvF X C | onvF Y | ConvF Z | Alpha | Depth Unc (k=2) |
|---------|-----------------------------|----------------|----------------|-----------|--------|---------|-------|-----------------|
| 835 | \pm 50 / \pm 100 | $41.5 \pm 5\%$ | $0.90 \pm 5\%$ | 6.15 | 6.15 | 6.15 | 0.77 | 1.14 ± 11.0% |
| 1810 | ± 50 / ± 100 | $40.0\pm5\%$ | 1.40 ± 5% | 5.28 | 5.28 | 5.28 | 0.49 | 1.53 ± 11.0% |
| 1900 | $\pm 50 / \pm 100$ | $40.0 \pm 5\%$ | $1.40 \pm 5\%$ | 5.18 | 5.18 | 5.18 | 0.42 | 1.65 ± 11.0% |

^c The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

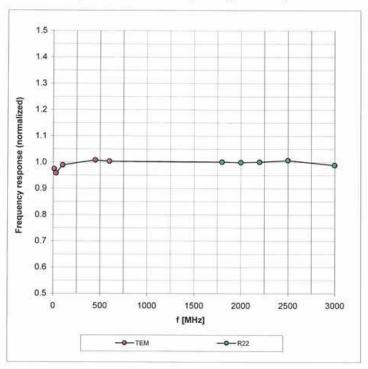
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Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)



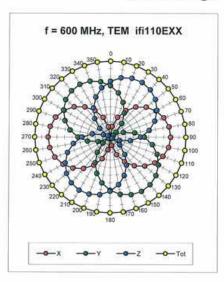
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

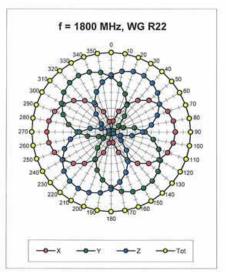
Certificate No: ES3-3150_Jan11

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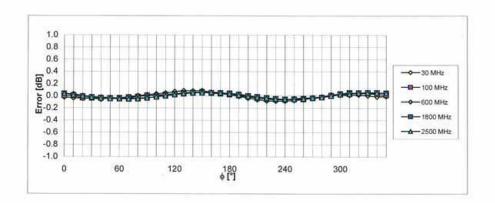


Receiving Pattern (ϕ), ϑ = 0°





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Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

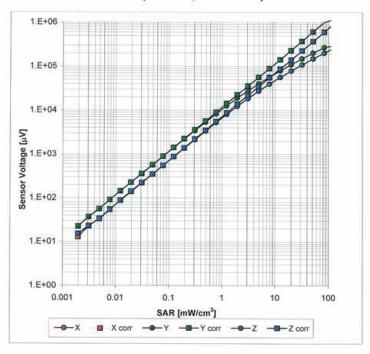
Certificate No: ES3-3150_Jan11

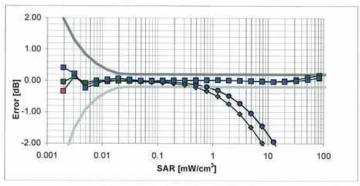
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Dynamic Range f(SAR_{head})

(TEM cell, f = 900 MHz)





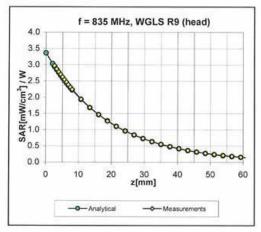
Uncertainty of Linearity Assessment: ± 0.6% (k=2)

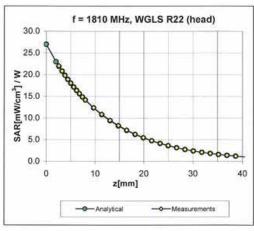
Certificate No: ES3-3150_Jan11

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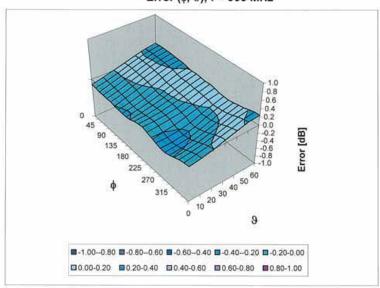
Conversion Factor Assessment





Deviation from Isotropy in HSL

Error (φ, θ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Certificate No: ES3-3150_Jan11

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Other Probe Parameters

| Sensor Arrangement | Triangular |
|---|----------------|
| Connector Angle (°) | Not applicable |
| Mechanical Surface Detection Mode | enabled |
| Optical Surface Detection Mode | disabled |
| Probe Overall Length | 337 mm |
| Probe Body Diameter | 10 mm |
| Tip Length | 10 mm |
| Tip Diameter | 4 mm |
| Probe Tip to Sensor X Calibration Point | 2 mm |
| Probe Tip to Sensor Y Calibration Point | 2 mm |
| Probe Tip to Sensor Z Calibration Point | 2 mm |
| Recommended Measurement Distance from Surface | 3 mm |

Certificate No: ES3-3150_Jan11

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Accreditation No.: SCS 108

| ATL (Auden) | | Cer | rtificate No: DAE4-541_Jul11 |
|---------------------------------------|--------------------------------------|---|--|
| CALIBRATION C | ERTIFICATE | | |
| Object | DAE4 - SD 000 D | 04 BJ - SN: 541 | |
| Calibration procedure(s) | QA CAL-06.v23 Calibration proceed | dure for the data acquisit | ion electronics (DAE) |
| Calibration date: | July 21, 2011 | | |
| | rtainties with confidence pro | obability are given on the following | ohysical units of measurements (SI). g pages and are part of the certificate. e (22 ± 3)°C and humidity < 70%. |
| Primary Standards | ID# | Cal Date (Certificate No.) | Scheduled Calibration |
| Keithley Multimeter Type 2001 | SN: 0810278 | 28-Sep-10 (No:10376) | Sep-11 |
| Secondary Standards | ID# | Check Date (in house) | Scheduled Check |
| Calibrator Box V1.1 | SE UMS 006 AB 1004 | 08-Jun-11 (in house check) | In house check: Jun-12 |
| | | | |
| | Name | Function | Signature |
| Calibrated by: | Andrea Guntli | Technician | f title |
| Approved by: | Fin Bomholt | R&D Director | J. J. B. Remov |
| This calibration certificate shall no | t he senseduced average in | ull without without pages 1 of the second | Issued: July 21, 2011 |

Certificate No: DAE4-541_Jul11

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Calibration Laboratory of Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage

S Servizio svizzero di taratura
S Swiss Calibration Service

Accreditation No.: SCS 108

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA

Multilateral Agreement for the recognition of calibration certificates

Glossary

DAE data acquisition electronics

Connector angle information used in DASY system to align probe sensor X to the robot

coordinate system.

Methods Applied and Interpretation of Parameters

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
 - Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
 - AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
 - Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
 - Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - Input resistance: Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
 - Power consumption: Typical value for information. Supply currents in various operating modes.

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DC Voltage Measurement A/D - Converter Resolution nominal

High Range: 1LSB = 6.1μV , 61nV , full range = -100...+300 mV full range = -1.....+3mV Low Range: 1LSB = DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| Calibration Factors | х | Υ | Z |
|---------------------|----------------------|----------------------|----------------------|
| High Range | 404.582 ± 0.1% (k=2) | 404.459 ± 0.1% (k=2) | 404.224 ± 0.1% (k=2) |
| Low Range | 3.96870 ± 0.7% (k=2) | 3.93611 ± 0.7% (k=2) | 3.97524 ± 0.7% (k=2) |

Connector Angle

| Connector Angle to be used in DASY system | 289.5 ° ± 1 ° |
|---|---------------|
| | 200.0 2 1 |

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Report Number: 1112FS14



Appendix

1. DC Voltage Linearity

| High Range | Reading (μV) | Difference (μV) | Error (%) |
|-------------------|--------------|-----------------|-----------|
| Channel X + Input | 200008.1 | -0.88 | -0.00 |
| Channel X + Input | 20002.50 | 3.10 | 0.02 |
| Channel X - Input | -19996.27 | 4.53 | -0.02 |
| Channel Y + Input | 199996.8 | -1.55 | -0.00 |
| Channel Y + Input | 19997.00 | -2.30 | -0.01 |
| Channel Y - Input | -19998.95 | 1.65 | -0.01 |
| Channel Z + Input | 199999.3 | 1.60 | 0.00 |
| Channel Z + Input | 20001.15 | 1.75 | 0.01 |
| Channel Z - Input | -19996.29 | 3.21 | -0.02 |

| Low Range | Reading (μV) | Difference (μV) | Error (%) |
|-------------------|--------------|-----------------|-----------|
| Channel X + Input | 2000.5 | 0.58 | 0.03 |
| Channel X + Input | 200.06 | -0.04 | -0.02 |
| Channel X - Input | -200.23 | -0.23 | 0.11 |
| Channel Y + Input | 2000.2 | 0.25 | 0.01 |
| Channel Y + Input | 199.49 | -0.51 | -0.25 |
| Channel Y - Input | -200.76 | -0.76 | 0.38 |
| Channel Z + Input | 2000.0 | -0.07 | -0.00 |
| Channel Z + Input | 198.95 | -0.95 | -0.47 |
| Channel Z - Input | -200.96 | -0.76 | 0.38 |
| | | | |

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | Common mode Input Voltage (mV) | High Range Average Reading (μV) | Low Range Average Reading (μV) |
|-----------|-----------------------------------|------------------------------------|-----------------------------------|
| Channel X | 200 | 12.21 | 10.17 |
| | - 200 | -8.92 | -10.93 |
| Channel Y | 200 | 1.33 | 1.31 |
| | - 200 | -3.20 | -2.56 |
| Channel Z | 200 | 1.32 | 0.71 |
| | - 200 | -1.57 | -2.26 |

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | Input Voltage (mV) | Channel X (μV) | Channel Y (μV) | Channel Z (μV) |
|-----------|--------------------|----------------|----------------|----------------|
| Channel X | 200 | | 2.77 | -0.01 |
| Channel Y | 200 | 1.35 | P46 | 4.90 |
| Channel Z | 200 | 0.02 | 0.12 | - |

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4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | High Range (LSB) | Low Range (LSB) |
|-----------|------------------|-----------------|
| Channel X | 16012 | 16048 |
| Channel Y | 15790 | 15279 |
| Channel Z | 15978 | 16594 |

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10MΩ

| | Average (μV) | min. Offset (μV) | max. Offset (μV) | Std. Deviation (µV) |
|-----------|--------------|------------------|------------------|---------------------|
| Channel X | -0.14 | -1.06 | 0.50 | 0.27 |
| Channel Y | -0.69 | -2.35 | 0.18 | 0.36 |
| Channel Z | -0.84 | -1.32 | -0.29 | 0.23 |

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

| | Zeroing (kOhm) | Measuring (MOhm) |
|-----------|----------------|------------------|
| Channel X | 200 | 200 |
| Channel Y | 200 | 200 |
| Channel Z | 200 | 200 |

8. Low Battery Alarm Voltage (Typical values for information)

| Typical values | Alarm Level (VDC) | |
|----------------|-------------------|--|
| Supply (+ Vcc) | +7.9 | |
| Supply (- Vcc) | -7.6 | |

9. Power Consumption (Typical values for information)

| Typical values | Switched off (mA) | Stand by (mA) | Transmitting (mA) |
|----------------|-------------------|---------------|-------------------|
| Supply (+ Vcc) | +0.01 | +6 | +14 |
| Supply (- Vcc) | -0.01 | -8 | -9 |