

# A Test Lab Techno Corp.

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# SAR EVALUATION REPORT



Test Report No.	•	0804FS15	
Applicant	:	VTech Telecommunications Ltd	
FCC ID	:	EW780-5681-00	
Trade Name	:	AT&T	
Model Name	:	TL76108	
Battery Type	:	Ni-MH Battery (3.6V <sup>,</sup> 800mAh)	
EUT Type	:	5.8GHz Frequency Hopping Spread Spectrum Cordless Phone	
Dates of Test	:	Apr. 16 ~ Apr. 21, 2008	
Test Environment	:	Ambient Temperature : 22 $\pm$ 2 $^{\circ}$ C	
		Relative Humidity:40-70 %	
<b>Test Specification</b>	:	Standard C95.1-1999	
		IEEE Std. 1528-2003	
		2.1093;FCC/OET Bulletin 65 Supplement C [July 2001]	
		SAR Measurement Requirements For 3-6GHz:FCC	
Max. SAR	:	0.065 W/kg Head SAR	
		0.085 W/kg Body SAR	
Test Lab.	:	Changan Lab.	



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**Testing Engineer** 

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- Appendix B SAR Measurement Data
- Appendix C Calibration



# 1. <u>Description of Equipment Under Test (EUT)</u>

Applicant :

**VTech Telecommunications Ltd** 23/F., Tai Ping Industrial Centre, Block 1, 57 Ting Kok Road, Tai Po, HK.

Manufacturer	:	Dongguan VTech Electronics Telecommunication industries
Manufacturer Address	:	VTech Science Park, Xia Ling Bei Management Zone, Liaobu, Dongguan, Guangdong, China.
EUT Type	:	5.8GHz Frequency Hopping Spread Spectrum Cordless Phone
FCC ID	:	EW780-5681-00
Trade Name	:	AT&T
Model Name	:	TL76108
Battery Type	:	Ni-MH Battery (3.6V , 800mAh)
Test Device	:	Production Unit
Tx Frequency	:	5744.736 -5825.952 MHz ( EDCT)
Max. RF Conducted Power	:	0.318 W (25.02 dBm )
Max. SAR Measurement	:	0.065 W/kg Head SAR
		0.085 W/kg Body SAR
HW Version	:	NA
SW Version	:	NA
Antenna Type	:	Internal Type
Antenna Gain	:	0dBi
Device Category	:	Portable
RF Exposure Environment	:	General Population / Uncontrolled
Battery Option	:	Standard
Application Type	:	Certification

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment / general population exposure limits specified in Standard C95.1-1999 and had been tested in accordance with the measurement procedures specified in IEEE Std. 1528-2003.







2. <u>Other Accessories</u>



Figure 2. Headset



Figure 3. Belt-Clip



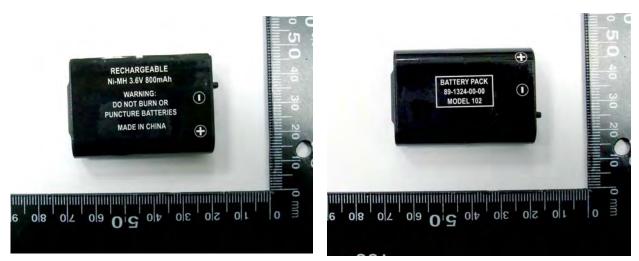


Figure 4. Battery (Ni-MH 3.6V , 800mAh)



Figure 5. Charger



Figure 6. Charger - AC Power



# 3. <u>Introduction</u>

The A Test Lab Techno Corp. has performed measurements of the maximum potential exposure to the user of **VTech Telecommunications Ltd Trade Name: AT&T Model(s): TL76108**. The test procedures, as described in American National Standards, Institute C95.1 - 1999 [1], FCC/OET Bulletin 65 Supplement C [July 2001] were employed and they specify the maximum exposure limit of 1.6mW/g as averaged over any 1 gram of tissue for portable devices being used within 20cm between user and EUT in the uncontrolled environment. A description of the product and operating configuration, detailed summary of the test results, methodology and procedures used in the equipment used are included within this test report.



# 4. SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dw) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (P). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Figure 7).

SAR = 
$$\frac{d}{dt}\left(\frac{dw}{dm}\right) = \frac{d}{dt}\left(\frac{dw}{\rho dv}\right)$$

Figure 7. SAR Mathematical Equation

SAR is expressed in units of Watts per kilogram (W/kg)

$$SAR = \frac{\sigma E^2}{\rho}$$

Where :

 $\sigma$  = conductivity of the tissue (S/m)

 $\rho$  = mass density of the tissue (kg/m<sup>3</sup>)

E = RMS electric field strength (V/m)

#### \*Note :

The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane [2]



# 5. <u>SAR Measurement Setup</u>

These measurements were performed with the automated near-field scanning system DASY5 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9m) which positions the probes with a positional repeatability of better than  $\pm 0.02$ mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines (length = 300mm) to the data acquisition unit.

A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and remote control, is used to drive the robot motors. The Measurement Server is based on a PC/104 CPU board with a 400MHz intel ULV Celeron, 128MB chipdisk and 128MB RAM. The necessary circuits for communication with either the DAE4 (or DAE3) electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY5 I/O-board, which is directly connected to the PC/104 bus of the CPU board. The PC consists of the Intel Core(TM)2 CPU @1.86GHz computer with Windows XP system and SAR Measurement Software DASY5, Post Processor SEMCAD, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection...etc. is connected to the Electro-optical converter (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the Measurement Server.



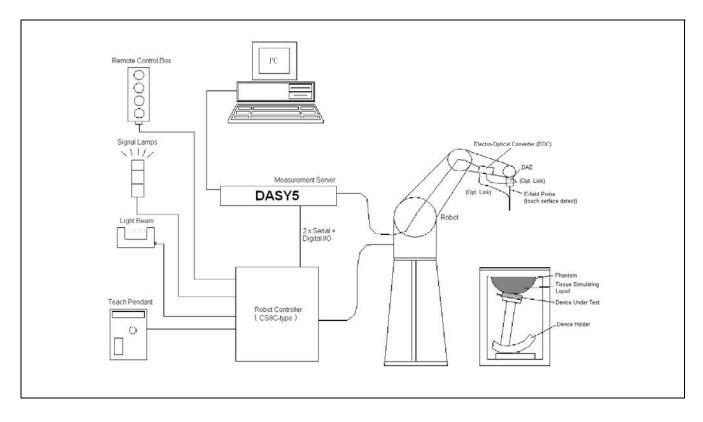


Figure 8. SAR Lab Test Measurement Setup

The DAE4 (or DAE3) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail in [3].



# 6. <u>System Components</u>

#### 6.1 DASY5 E-Field Probe System

The SAR measurements were conducted with the dosimetric probe EX3DV3 (manufactured by SPEAG), designed in the classical triangular configuration [3] and optimized for dosimetric evaluation. The probes is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface reflectivity and largely independent of the surface to probe angle. The DASY5 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped when reaching the maximum.



### 6.1.1 E-Field Probe Specification

Construction	Symmetrical design with triangular core
	Built-in optical fiber for surface detection
	System
	Built-in shielding against static charges
	PEEK enclosure material
	(resistant to organic solvents, e.q., glycol)
Calibration	In air from 10 MHz to 6 GHz
	In brain and muscle simulating tissue at
	frequencies of 900MHz, 1800MHz, 2000MHz, 2300MHz,
	2450MHz, 2600MHz, 3500MHz, 5200MHz, 5500MHz
	and 5800MHz (accuracy $\pm 8\%$ )
	Calibration for other liquids and frequencies upon request
Frequency	10 MHz to $>$ 6 GHz; Linearity: ±0.2 dB
	(30 MHz to 3 GHz)
Directivity	$\pm 0.3$ dB in brain tissue (rotation around probe axis)
	$\pm 0.5$ dB in brain tissue (rotation normal probe axis)
Dynamic Range	10 $\mu$ W/g to > 100mW/g; Linearity: ±0.2dB
Surface Detection	$\pm 0.2$ mm repeatability in air and clear liquids
	over diffuse reflecting surface
Dimensions	Overall length: 330mm
	Tip length: 20mm
	Body diameter: 12mm
	Tip diameter: 2.5mm
	Distance from probe tip to dipole centers: 1.0mm
Application	General dosimetry up to 6GHz
	Compliance tests of mobile phones
Fast automatic scanr	ing in arbitrary phantoms



Figure 9. E-field Probe



Figure 10. Probe setup on robot



#### 6.1.2 E-Field Probe Calibration

Each probe is calibrated according to a dosimetric assessment procedure described in [4] with accuracy better than ±10%. The spherical isotropy was evaluated with the procedure described in [5] and found to be better than ±0.25dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1GHz, and in a wave guide above 1GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$\mathsf{SAR} = \mathsf{C}\frac{\Delta T}{\Delta t}$$

Where :

 $\Delta t$  = Exposure time (30 seconds),

**C** = Heat capacity of tissue (head or body),

 $\Delta T$  = Temperature increase due to RF exposure.

$$\mathsf{SAR} = \frac{|\mathbf{E}|^2 \, \sigma}{\rho}$$

Where :

 $\sigma$  = Simulated tissue conductivity,

Or

 $\boldsymbol{\rho}$  = Tissue density (kg/m<sup>3</sup>).



# 6.2 Data Acquisition Electronic (DAE) System

Cell Controller	
Processor :	Intel Core(TM)2 CPU
Clock Speed :	@ 1.86GHz
Operating System :	Windows XP Professional
Data Converter	
Features :	Signal Amplifier, multiplexer, A/D converter, and control logic
Software :	DASY5 v5.0 (Build 91) & SEMCAD X Version 12.4 Build 52
Connecting Lines :	Optical downlink for data and status info
	Optical uplink for commands and clock

# 6.3 Robot

Positioner :	Stäubli Unimation Corp. Robot Model: TX90XL
Repeatability :	±0.02 mm
No. of Axis :	6

# 6.4 Measurement Server

Processor :	PC/104 with a 400MHz intel ULV Celeron
I/O-board :	Link to DAE3(or DAE4)
	16-bit A/D converter for surface detection system
	Digital I/O interface
	Serial link to robot
	Direct emergency stop output for robot



#### 6.5 Device Holder for Transmitters

In combination with the SAM Twin Phantom V4.0, the Mounting Device (POM) enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation points is the ear opening. The devices can be easily, accurately, and repeat ably positioned according to the IEEE SCC34-SC2 and CENELEC specifications. The device holder can be locked at different phantom locations (left head, right head, and flat phantom). **\*Note :** A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produced infinite number of configurations [6]. To produce the worst-case condition (the hand

Larger DUT cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values. Therefore those devices are normally only tested at the flat part of the SAM.

absorbs antenna output power), the hand is omitted during the tests.



Figure 11. Device Holder



#### 6.6 Phantom - SAM v4.0

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-2003, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.



Figure 12.SAM Twin Phantom

Shell Thickness	2 ±0.2 mm		
Filling Volume	Approx. 25 liters		
Dimensions	810×1000×500 mm (H×L×W)		

Table 1. Specification of SAM v4.0

#### 6.7 Data Storage and Evaluation

#### 6.7.1 Data Storage

The DASY5 software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension .DA5. The postprocessing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.



#### 6.7.2 Data Evaluation

The DASY5 post processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software :

Probe parameters :	- Sensitivity	Normi, ai0, ai1, ai2
	- Conversion factor	ConvFi
	- Diode compression point	dcpi
Device parameters :	- Frequency	f
	- Crest factor	cf
Media parameters :	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as :

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with

 $V_i$  = compensated signal of channel *i* (*i* = x, y, z)

 $U_i$  = input signal of channel *i* (*i* = x, y, z)

cf = crest factor of exciting field (DASY parameter)

*dcp*<sub>i</sub> = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated :

E-field probes : 
$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$



H-field probes :

$$H_{i} = \sqrt{V_{i}} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^{2}}{f}$$

with  $V_i$  = compensated signal of channel *i* (*i* = x, y, z) *Norm*<sub>*i*</sub> = sensor sensitivity of channel i (*i* = x, y, z)  $\mu V/(V/m)^2$  for E-field Probes

*ConvF* = sensitivity enhancement in solution

- $a_{ij}$  = sensor sensitivity factors for H-field probes
- f = carrier frequency [GHz]
- $E_i$  = electric field strength of channel *i* in V/m
- Hi = magnetic field strength of channel *i* in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude) :

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

 $E_{tot}$  = total field strength in V/m

 $\sigma$  = conductivity in [mho/m] or [Siemens/m]

 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

**\*Note**: that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770}$$
 or  $P_{pwe} = \frac{H_{tot}^2}{37.7}$ 

with  $P_{pwe}$  = equivalent power density of a plane wave in mW/cm<sup>2</sup>

 $E_{tot}$  = total electric field strength in V/m

 $H_{tot}$  = total magnetic field strength in A/m



# 7. <u>Test Equipment List</u>

Manufacturer Name of Equipment		Type/Model	Serial Number	Calibration		
				Last Cal.	Due Date	
SPEAG	Dosimetric E-Filed Probe	EX3DV3	3519	Mar. 21, 2008	Mar. 21, 2009	
SPEAG	5800MHz System Validation Kit	D5GHzV2	1021	Mar. 11, 2008	Mar. 11, 2009	
SPEAG	Data Acquisition Electronics	DAE4	SN:779	Nov. 30, 2007	Nov. 30, 2008	
SPEAG	Device Holder	N/A	N/A	NCR	NCR	
SPEAG	Phantom	SAM V4.0	TP-1150	NCR	NCR	
SPEAG	Robot	Staubli TX90XL	F07/564ZA1/A/01	NCR	NCR	
SPEAG	Software	DASY5 V5.0 Build 91	N/A	NCR	NCR	
SPEAG	Software	SEMCAD V12.4 Build 52	N/A	NCR	NCR	
SPEAG	Measurement Server	SE UMS 011 AA	1025	NCR	NCR	
R & S	Wireless Communication Test Set	CMU200	109369	Oct. 24, 2007	Oct. 24, 2008	
Agilent	ENA Series Network Analyzer	E5071B	MY42404650	Feb. 18, 2008	Feb. 18, 2009	
Agilent	Dielectric Probe Kit	85070C	US99360094	NCR	NCR	
Agilent	Power Meter	E4418B	GB40206143	May. 23, 2007	May. 23, 2008	
Agilent	Power Sensor	8481H	3318A20779	May. 28, 2007	May. 28, 2008	
Agilent	Signal Generator	8648C	3847A05201	May. 28, 2007	May. 28, 2008	
Agilent	Dual Directional Coupler	778D	50334	NCR	NCR	
Mini-Circuits	Power Amplifier	ZHL-42W-SMA	D111103#5	NCR	NCR	
Mini-Circuits	Power Amplifier	ZVE-8G-SMA	D042005 671800514	NCR	NCR	

 Table 2.
 Test Equipment List



# 8. <u>Tissue Simulating Liquids</u>

The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue. The dielectric parameters of the liquids were verified prior to the SAR evaluation using an 85070E Dielectric Probe Kit and an 8720ES Network Analyzer.

INGREDIENT	FREQUENCY			
	HSL5G (Head)	MSL5G (Body)		
Water	64%	78%		
Mineral Oil	18%	11%		
Emulsifiers	15%	9%		
Additives and Salt	3%	2%		

Table 3. Recipes for Head & Body Tissue Simulating Liquids

#### IEEE SCC-34/SC-2 in 1528 recommended Tissue Dielectric Parameters

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in human head. Other head and body tissue parameters that have not been specified in 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equation and extrapolated according to the head parameter specified in 1528.



Target Frequency	Head		Body		
(MHz)	٤r	<b>σ</b> (S/m)	٤r	<b>σ</b> (S/m)	
150	52.3	0.76	61.9	0.80	
300	45.3	0.87	58.2	0.92	
450	43.5	0.87	56.7	0.94	
835	41.5	0.90	55.2	0.97	
900	41.5	0.97	55.0	1.05	
915	41.5	0.98	55.0	1.06	
1450	40.5	1.20	54.0	1.30	
1610	40.3	1.29	53.8	1.40	
1800 - 2000	40.0	1.40	53.3	1.52	
2450	39.2	1.80	52.7	1.95	
3000	38.5	2.40	52.0	2.73	
5800	35.3	5.27	48.2	6.00	
( $\pmb{\epsilon}_r$ = relative permittivity, $\pmb{\sigma}$ = conductivity and $\pmb{\rho}$ = 1000 kg/m^3)					

Table 4. Tissue dielectric parameters for head and body phantoms

# 8.1 Liquid Confirmation

#### 8.1.1 Parameters

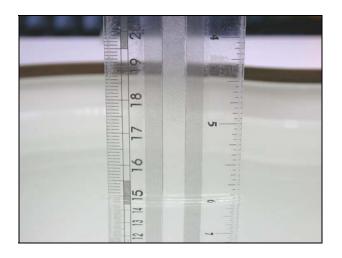
Liquid Verify																		
Ambient T	Ambient Temperature : 22 $\pm$ 2 °C ; Relative Humidity : 40 -70%																	
Liquid Type	Frequency	Temp (°C)	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)	Measured Date										
5800MHz	5800MHz	5000N411	50001411	50000411	50000411	50001411	5000N/U -	5000141	5000NU -	5000N/III-	5000MU-	22.0	٤r	35.30	35.5	0.57	±5%	Apr. 24, 2000
Head		22.0	22.0	σ	5.27	5.34	1.33	±5%	Apr. 21, 2008									
5800MHz		5000MU-	FROOMUL		22.0	٤٢	48.20	47.8	-0.83	±5%	Apr 16 2008							
Body	5800MHz	22.0	σ	6.00	5.8	-3.33	±5%	Apr. 16 , 2008										

Table 5. Measured Tissue dielectric parameters for head and body phantoms



# 8.1.2 Liquid Depth

The liquid level was during measurement 15cm  $\pm$ 0.5cm, measured from the ear reference point.



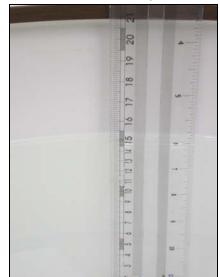


Figure 13. Head-Tissue-Simulating-Liquid

Figure 14. Body-Tissue-Simulating-Liquid



# 9. <u>Measurement Process</u>

### 9.1 Device and Test Conditions

The Test Device was provided by **VTech Telecommunications Ltd** for this evaluation. The spatial peak SAR values were assessed for the lowest, middle and highest channels defined by EDCT (Ch0 = 5744.736MHz, Ch47 = 5785.344MHz, Ch94 = 5825.952MHz) systems. The antenna(s), battery and accessories shall be those specified by the manufacturer. The battery shall be fully charged before each measurement and there shall be no external connections.

Usage		Operates with a built-in test mode by client						
	pint and the liquid	For head, EUT left head, right head, to phantom, 0mm separation. For Body, EUT back to phantom, to attach belt clip.						
Simulating I	numan Head/Body	Head and Body						
EUT Battery	,	Fully-charged with Ni-MH batteries.						
Conducted	Channel	Frequency MHz		Before SAR Test (dBm)	After SAR Test (dBm)			
power	Lowest Channel -	00	5744.736	25.02	25.01			
	Middle Channel -	47	5785.344	24.87	24.85			
	Highest Channel -	81	5825.952	24.56	24.55			

Note: The EUT take Ni-MH battery as its power source. Each test was preceded under the condition of fully-charged EUT.



# 9.2 System Performance Check

### 9.2.1 Symmetric Dipoles for System Validation

Construction	Symmetrical dipole with I/4 balun enables measurement of feed point impedance with NWA matched for use near flat phantoms filled with head simulating solutions
	Includes distance holder and tripod adaptor Calibration
	Calibrated SAR value for specified position and input
	power at the flat phantom in head simulating solutions.
Frequency	5200, 5600, 5800MHz
Return Loss	> 20 dB at specified validation position
Power Capability	> 100 W (f < 1GHz); > 40 W (f > 1GHz)
Options	Dipoles for other frequencies or solutions and other
	calibration conditions are available upon request
Dimensions	D5GHzV2: dipole length 20.6 mm; overall height 450 mm



Figure 15. Validation Kit

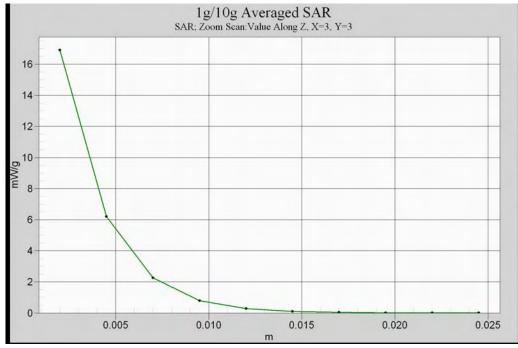


## 9.2.2 Validation

Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of  $\pm$  7%. The validation was performed at 5800MHz.

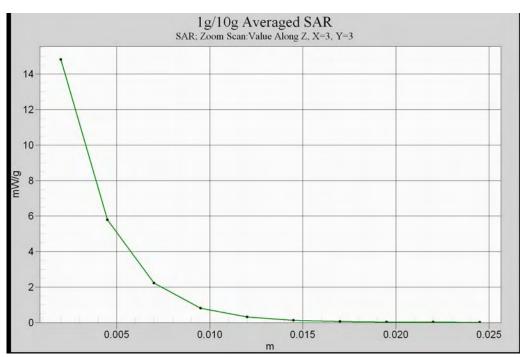
Validation kit		Mixture Type	SAR <sub>1g</sub> [mW/g]			R <sub>10g</sub> V/g]	Date of Calibration	
D5GHzV2-SN1021		Head	33.80		9.44		Mar. 11, 2008	
		Body	31.28		8.72		Mai. 11, 2000	
Frequency Power			SAR <sub>10g</sub>	Drift	Difference percentage		Date	
(MHz)		(mW/g)	/g) (mW/g)	(dB)	1g	10g		
5800	250mW	8.38	2.36	0.171	-0.8 %	0.0 %	Apr. 21, 2008	
(Head)	Normalize to 1 Watt	33.52	9.44	0.171	-0.0 %	0.0 %	Apr. 21, 2006	
5800	250mW	7.45	2.24	-0.015	-4.7 %	2.8 %	Apr. 16, 2008	
(Body)	Normalize to 1 Watt	29.8	8.96	-0.015	-4.7 /0	2.0 /0	Αρι. 10, 2000	





#### Z-axis Plot of System Performance Check

Head-Tissue-Simulating-Liquid 5.8GHz



Body-Tissue-Simulating-Liquid 5.8GHz



## 9.3 Dosimetric Assessment Setup

#### 9.3.1 Headset Test Position - Body-Worn

Body-Worn Configuration

Body-worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a handset output should be tested with a handset connected to the device.

Body-worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances. For this test :

- The EUT is placed into the holster/belt clip and the holster is positioned against the surface of the phantom in a normal operating position.
- Since this EUT doesn't supply any body-worn accessory to the end user, a distance of 15 mm was tested to confirm the necessary "minimum SAR separation distance".
   (\*Note : This distance includes the 2 mm phantom shell thickness.)



#### 9.3.2 Measurement Procedures

#### The evaluation was performed with the following procedures :

- Surface Check : A surface check job gathers data used with optical surface detection. It determines the distance from the phantom surface where the reflection from the optical detector has its peak. Any following measurement jobs using optical surface detection will then rely on this value. The surface check performs its search a specified number of times, so that the repeatability can be verified. The probe tip distance is 1.3mm to phantom inner surface during scans.
- **Reference :** The reference job measures the field at a specified reference position, at 4 mm from the selected section's grid reference point.
- Area Scan :The area scan is used as a fast scan in two dimensions to find the area of high field values,<br/>before doing a finer measurement around the hot spot. The sophisticated interpolation<br/>routines can find the maximum locations even in relatively coarse grids. When an area<br/>scan has measured all reachable points, it computes the field maxima found in the scanned<br/>area, within a range of the global maximum. Any following zoom scan within the same<br/>procedure will then perform fine scans around these maxima. The area covered the entire<br/>dimension of the EUT and the horizontal grid spacing was 10 mm × 10 mm.<br/>Area scan measurements are made at a constant distance from the phantom surface, ≤ 3.5<br/>mm below 4.5 GHz and ≤ 2.5 mm at or above 4.5 GHz, with ≤ ± 0.5 mm variation.
- Zoom Scan : Zoom scans are used to assess the highest averaged SAR for cubic averaging volumes with 1 g and 10 g of simulated tissue. The zoom scan measures 4 x 4 x 2.5 points in a 24 x 24 x 20 mm cube whose base faces are centered around the maxima returned from a preceding area scan within the same procedure.
- **Drift :** The drift job measures the field at the same location as the most recent reference job within the same procedure, with the same settings. The drift measurement gives the field difference in dB from the last reference measurement. Several drift measurements are possible for each reference measurement. This allows monitoring of the power drift of the device in the batch process. If the value changed by more than 5%, the evaluation was repeated.



#### 9.4 Spatial Peak SAR Evaluation

The DASY5 software includes all numerical procedures necessary to evaluate the spatial peak SAR values. Based on the Draft: SCC-34, SC-2, WG-2 - Computational Dosimetry, IEEE P1529/D0.0 (Draft Recommended Practice for Determining the Spatial-Peak Specific Absorption Rate (SAR) Associated with the Use of Wireless Handsets - Computational Techniques), a new algorithm has been implemented. The spatial-peak SAR can be computed over any required mass.

The base for the evaluation is a "cube" measurement in a volume of (24×24×20)mm<sup>3</sup> (8×8×9 points). The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan. If the 10g cube or both cubes are not entirely inside the measured volumes, the system issues a warning regarding the evaluated spatial peak values within the Postprocessing engine (SEMCAD). This means that if the measured volume is shifted, higher values might be possible. To get the correct values you can use a finer measurement grid for the area scan. In complicated field distributions, a large grid spacing for the area scan might miss some details and give an incorrectly interpolated peak location.

The entire evaluation of the spatial peak values is performed within the Postprocessing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into three stages:

#### Interpolation and Extrapolation

The probe is calibrated at the center of the dipole sensors which is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated.

In DASY5, the choice of the coordinate system defining the location of the measurement points has no influence on the uncertainty of the interpolation, Maxima Search and SAR extrapolation routines. The interpolation, Maxima Search and extrapolation routines are all based on the modified Quadratic Shepard's method [7].



# 10. Measurement Uncertainty

Measurement uncertainties in SAR measurements are difficult to quantify due to several variables including biological, physiological, and environmental. However, we estimate the measurement uncertainties in SAR to be less than  $\pm 21.9 \%$  [8].

According to Std. C95.3 [9], the overall uncertainties are difficult to assess and will vary with the type of meter and usage situation. However, accuracy's of  $\pm 1$  to 3 dB can be expected in practice, with greater uncertainties in near-field situations and at higher frequencies (shorter wavelengths), or areas where large reflecting objects are present. Under optimum measurement conditions, SAR measurement uncertainties of at least  $\pm 2$ dB can be expected.

According to CENELEC [10], typical worst-case uncertainty of field measurements is  $\pm 5$  dB. For well-defined modulation characteristics the uncertainty can be reduced to  $\pm 3$  dB.



Error Description	Uncertainty value	Prob. Dist.	Div.	( <i>ci</i> ) 1g	( <i>ci</i> ) 10g	Std. Unc. (1g)	Std. Unc. (10g)	(vi) veff
Measurement System								
Probe Calibration	± 5.9 %	Ν	1	1	1	± 5.9 %	± 5.9 %	
Axial Isotropy	± 4.7 %	R		0.7	0.7	± 1.9 %	± 1.9 %	$\infty$
Hemispherical Isotropy	± 9.6 %	R	$\sqrt{3}$	0.7	0.7	± 3.9 %	± 3.9 %	8
Boundary Effects	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	8
Linearity	± 4.7 %	R	$\sqrt{3}$	1	1	± 2.7 %	± 2.7 %	$\infty$
System Detection Limits	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	$\infty$
Readout Electronics	± 0.3 %	N	1	1	1	± 0.3 %	± 0.3 %	$\infty$
Response Time	± 0.8 %	R	$\sqrt{3}$	1	1	± 0.5 %	± 0.5 %	$\infty$
Integration Time	± 2.6 %	R	$\sqrt{3}$	1	1	± 1.5 %	± 1.5 %	$\infty$
RF Ambient Noise	± 3.0 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	$\infty$
RF Ambient Reflections	± 3.0 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	$\infty$
Probe Positioner	± 0.4 %	R	$\sqrt{3}$	1	1	± 0.2 %	± 0.2 %	$\infty$
Probe Positioning	± 2.9 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	$\infty$
Max. SAR Eval.	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	$\infty$
Test Sample Related				•			•	
Device Positioning	± 2.9 %	Ν	1	1	1	± 2.9 %	± 2.9 %	145
Device Holder	± 3.6 %	Ν	1	1	1	± 3.6 %	± 3.6 %	5
Power Drift	± 5.0 %	R	$\sqrt{3}$	1	1	± 2.9 %	± 2.9 %	$\infty$
Phantom and Setup					•			
Phantom Uncertainty	± 4.0 %	R	$\sqrt{3}$	1	1	± 2.3 %	2.3 %	$\infty$
Liquid Conductivity (target)	± 5.0 %	R	$\sqrt{3}$	0.64	0.43	± 1.8 %	1.2 %	$\infty$
Liquid Conductivity (meas.)	± 2.5 %	N	1	0.64	0.43	± 1.6 %	1.1 %	$\infty$
Liquid Permittivity (target)	± 5.0 %	R	$\sqrt{3}$	0.6	0.49	± 1.7 %	1.4 %	$\infty$
Liquid Permittivity (meas.)	± 2.5 %	N	1	0.6	0.49	± 1.5 %	1.2 %	$\infty$
Combined Std. Uncertainty					± 10.9 %	± 10.7 %	387	1
Expanded STD Uncertainty					± 21.9 %	± 21.4 %		

Table 6. Uncertainty Budget of DASY



# 11. SAR Test Results Summary

### 11.1 Head SAR

#### Ambient :

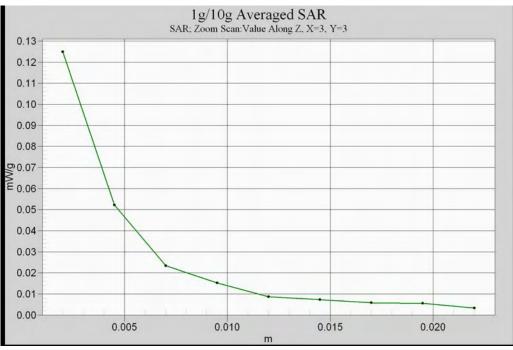
Temperature (°C) :	22 ± 2	Relative HUMIDITY (%) :	40 - 70
Liquid :			
Mixture Type :	HSL5800	Liquid Temperature (°C) :	22.0
		Depth of liquid (cm) :	15
Measurement :			
Crest Factor :	1	Probe S/N :	3519

Frequen	су	Pottony	Phantom	Accessory	SAR <sub>1g</sub>	Power Drift	Ter	np.	Remark
MHz	СН	Battery	Position Access		[mW/g]	(dB)	Amb.	Liq.	Reillark
5744.736	00	Ni-MH	Right-Cheek	N/A	0.035	0.133	22.0	22.0	-
5785.344	47	Ni-MH	Right-Cheek	N/A	0.028	-0.161	22.0	22.0	-
5825.952	94	Ni-MH	Right-Cheek	N/A	0.023	0.011	22.0	22.0	-
5744.736	00	Ni-MH	<b>Right-Tilted</b>	N/A	0.065	-0.066	22.0	22.0	-
5785.344	47	Ni-MH	Right-Tilted	N/A	0.051	-0.194	22.0	22.0	-
5825.952	94	Ni-MH	<b>Right-Tilted</b>	N/A	0.041	0.120	22.0	22.0	-
5744.736	00	Ni-MH	Left-Cheek	N/A	0.030	-0.162	22.0	22.0	-
5785.344	47	Ni-MH	Left-Cheek	N/A	0.029	0.104	22.0	22.0	-
5825.952	94	Ni-MH	Left-Cheek	N/A	0.027	0.173	22.0	22.0	-
5744.736	00	Ni-MH	Left-Tilted	N/A	0.062	-0.156	22.0	22.0	-
5785.344	47	Ni-MH	Left-Tilted	N/A	0.046	-0.124	22.0	22.0	-
5825.952	94	Ni-MH	Left-Tilted	N/A	0.039	-0.136	22.0	22.0	-
	Std. C95.1-1999 - Safety Limit Spatial Peak Uncontrolled Exposure/General Population					1.6 W/kg (mW/g) Averaged over 1 gram			

Detail results see Appendix B.



#### **Z-axis Plot of SAR Measurement**



SAR Measurement (Right-Tilted Section) CH00

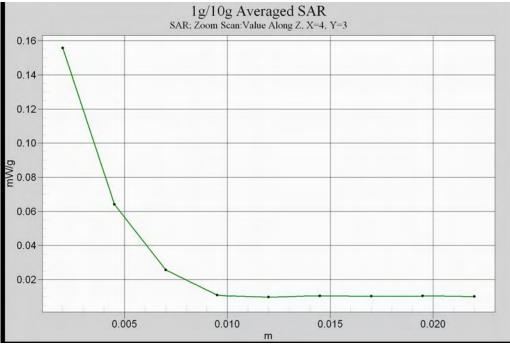


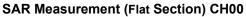
## 11.2 Body SAR\_ Belt clip

Ambient :           Temperature (°C) :         22 ± 2			_	Relative		40-70					
Liquid : Mixture Type : MSL			MSL5800	Liquid Temperature ( $^{\circ}C$ ) : Depth of liquid (cm) :					22.0 15		
Measurement : Crest Factor :			1	Probe S/N :					3519		
Frequer	псу	Battery	Phantom	Accessory	, SAR <sub>1g</sub> [mW/g]	Power Drift	Ter	np.	Remark		
MHz	СН	Ballery	Position	ACCESSOLY		(dB)	Amb.	Liq.	Remark		
5744.736	00	Ni-MH	Flat	Belt Clip & Headset	0.085	0.095	21.5	22.0	-		
5785.344	47	Ni-MH	Flat	Belt Clip & Headset	0.066	0.171	21.5	22.0	-		
5825.952	5825.952 94 Ni-MH		Flat	Belt Clip & Headset	0.037	-0.029	21.5	22.0	-		
	Std. C95.1-1999 - Safety Limit Spatial Peak Uncontrolled Exposure/General Population					1.6 W/kg (mW/g) Averaged over 1 gram					

Detail results see Appendix B.

#### **Z-axis Plot of SAR Measurement**





Test Report No : 0804FS15 ©2008 A Test Lab Techno Corp.



### 11.3 Setup photo



Figure 16. Right Head SAR Test Setup (Cheek)

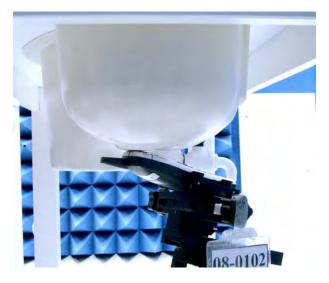


Figure 17. Right Head SAR Test Setup (Tilted)

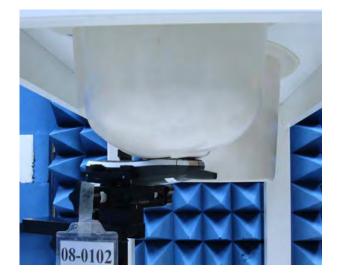


Figure 18. Left Head SAR Test Setup (Cheek)



Figure 19. Left Head SAR Test Setup (Tilted)





Figure 20. Body SAR Test Setup(Flat Section) with belt clip and Headset



# 11.4 Std. C95.1-1999 RF Exposure Limit

Human Exposure	Population Uncontrolled Exposure ( W/kg ) or (mW/g)	Occupational Controlled Exposure ( W/kg ) or (mW/g)
Spatial Peak SAR* (head)	1.60	8.00
Spatial Peak SAR** (Whole Body)	0.08	0.40
Spatial Peak SAR*** (Partial-Body)	1.60	8.00
<b>Spatial Peak SAR****</b> (Hands / Feet / Ankle / Wrist )	4.00	20.00

 Table 7.
 Safety Limits for Partial Body Exposure

# Notes :

- \* The Spatial Peak value of the SAR averaged over any 1 gram of tissue.
  ( defined as a tissue volume in the shape of a cube ) and over the appropriate averaging time.
- \*\* The Spatial Average value of the SAR averaged over the whole body.
- \*\*\* The Spatial Average value of the SAR averaged over the partial body.
- \*\*\*\* The Spatial Peak value of the SAR averaged over any 10 grams of tissue.( defined as a tissue volume in the shape of a cube ) and over the appropriate averaging time.

**Population / Uncontrolled Environments :** are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

*Occupational / Controlled Environments :* are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).



# 12. <u>Conclusion</u>

The SAR test values found for the portable mobile phone **VTech Telecommunications Ltd Trade Name : AT&T Model(s) : TL76108** are below the maximum recommended level of 1.6 W/kg ( mW/g ).



# 13. <u>References</u>

- [1] Std. C95.1-1999, "American National Standard safety levels with respect to human exposure to radio frequency electromagnetic fields, 300KHz to 100GHz", New York.
- [2] NCRP, National Council on Radiation Protection and Measurements, "*Biological Effects and Exposure Criteria for Radio frequency Electromagnetic Fields*", NCRP report NO. 86, 1986.
- [3] T. Schmid, O. Egger, and N. Kuster, "Automatic E-field scanning system for dosimetric assessments", IEEE Transactions on Microwave Theory and Techniques, vol. 44, pp, 105-113, Jan. 1996.
- [4] K. Poković, T. Schmid, and N. Kuster, "Robust setup for precise calibration of E-field probes in tissue simulating liquids at mobile communications frequency", in ICECOM'97, Dubrovnik, October 15-17, 1997, pp.120-124.
- [5] K. Poković, T. Schmid, and N. Kuster, "*E-field probe with improved isotropy in brain simulating liquids*", in Proceedings of the ELMAR, Zadar, Croatia, 23-25 June, 1996, pp.172-175.
- [6] N. Kuster, and Q. Balzano, "Energy absorption mechanism by biological bodies in the near field of dipole antennas above 300MHz", IEEE Transaction on Vehicular Technology, vol. 41, no. 1, Feb. 1992, pp. 17-23.
- [7] Robert J. Renka, "*Multivariate Interpolation Of Large Sets Of Scattered Data*", University of North Texas ACM Transactions on Mathematical Software, vol. 14, no. 2, June 1988, pp. 139-148.
- [8] N. Kuster, R. Kastle, T. Schmid, Dosimetric evaluation of mobile communications equipment with known precision, IEEE Transaction on Communications, vol. E80-B, no. 5, May 1997, pp. 645-652.
- [9] Std. C95.3-1991, "IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields - RF and Microwave, New York: IEEE, Aug. 1992.
- [10] CENELEC CLC/SC111B, European Prestandard (prENV 50166-2), *Human Exposure to Electromagnetic Fields High-frequency*: 10KHz-300GHz, Jan. 1995.



# Appendix A - System Performance Check

See following Attached Pages for System Performance Check.



Date/Time: 4/21/2008 12:07:42 PM

# System Performance Check at 5.8GHz\_20080421\_Head

# DUT: Dipole 5800 MHz - SN:1021; Type: D5GHzV2; Serial: D5GHzV2-SN:1021

Communication System: CW; Frequency: 5800 MHz;Duty Cycle: 1:1 Medium parameters used: f = 5800 MHz;  $\sigma$  = 5.34 mho/m;  $\varepsilon_r$  = 35.5;  $\rho$  = 1000 kg/m<sup>3</sup>

Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

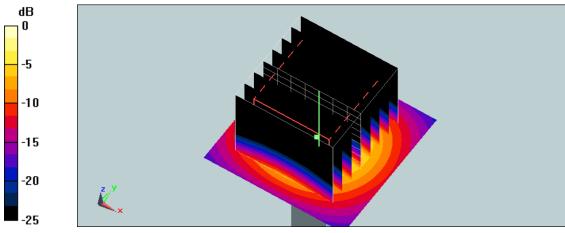
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

# System Performance Check at 5.8GHz/Area Scan (41x41x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 17.6 mW/g

## System Performance Check at 5.8GHz/Zoom Scan (8x8x10)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mmReference Value = 54.6 V/m; Power Drift = 0.171 dB Peak SAR (extrapolated) = 40.7 W/kg SAR(1 g) = 8.38 mW/g; SAR(10 g) = 2.36 mW/g Maximum value of SAR (measured) = 16.9 mW/g



 $0 \, dB = 16.9 \, mW/g$ 



Date/Time: 4/16/2008 2:00:10 AM

# System Performance Check at 5.8GHz\_20080415\_Body

# DUT: Dipole 5800 MHz - SN:1021; Type: D5GHzV2; Serial: D5GHzV2-SN:1021

Communication System: CW; Frequency: 5800 MHz;Duty Cycle: 1:1 Medium parameters used: f = 5800 MHz;  $\sigma = 5.8$  mho/m;  $\varepsilon_r = 47.8$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

**DASY5** Configuration:

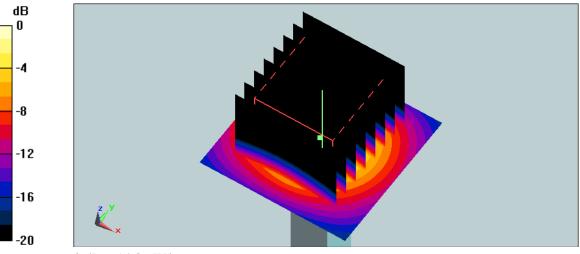
- Probe: EX3DV3 SN3519; ConvF(3.88, 3.88, 3.88); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

# System Performance Check at 5.8GHz/Area Scan (41x41x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 15.8 mW/g

# System Performance Check at 5.8GHz/Zoom Scan (8x8x10)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mmReference Value = 50.3 V/m; Power Drift = -0.015 dB Peak SAR (extrapolated) = 35.9 W/kg SAR(1 g) = 7.45 mW/g; SAR(10 g) = 2.24 mW/g Maximum value of SAR (measured) = 14.8 mW/g



0 dB = 14.8 mW/g



# Appendix B - SAR Measurement Data

See following Attached Pages for SAR Measurement Data.



Date/Time: 4/21/2008 4:09:12 PM

## RC\_Dect 5.8G CH0

#### DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5744.736 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5744.736 MHz;  $\sigma = 5.17$  mho/m;  $\varepsilon_r = 35.3$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

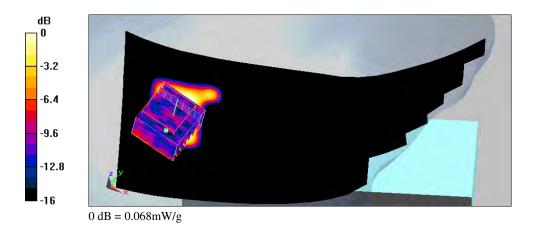
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### Right Cheek/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.131 mW/g

## **Right Cheek/Zoom Scan (8x8x9)/Cube 0:**

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 2 V/m; Power Drift = 0.133 dB Peak SAR (extrapolated) = 0.121 W/kg SAR(1 g) = 0.035 mW/g; SAR(10 g) = 0.015 mW/g Maximum value of SAR (measured) = 0.068 mW/g





Date/Time: 4/21/2008 3:18:45 PM

## RC\_Dect 5.8G CH47

#### DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5785.344 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5785.344 MHz;  $\sigma$  = 5.29 mho/m;  $\varepsilon_r$  = 35.5;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

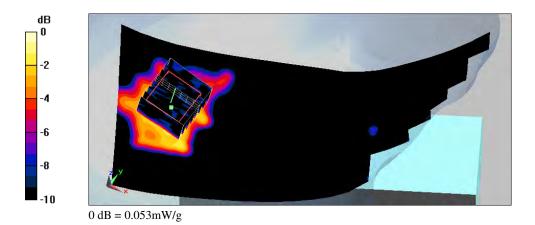
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### Right Cheek/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.054 mW/g

## Right Cheek/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.2 V/m; Power Drift = -0.161 dB Peak SAR (extrapolated) = 0.102 W/kg SAR(1 g) = 0.028 mW/g; SAR(10 g) = 0.012 mW/g Maximum value of SAR (measured) = 0.053 mW/g





Date/Time: 4/21/2008 4:53:37 PM

## RC\_Dect 5.8G CH94

#### DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5825.952 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5825.952 MHz;  $\sigma$  = 5.39 mho/m;  $\varepsilon_r$  = 35.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

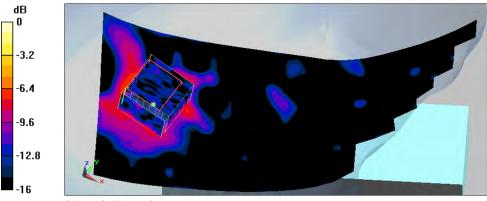
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### Right Cheek/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.047 mW/g

## Right Cheek/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.5 V/m; Power Drift = 0.011 dB Peak SAR (extrapolated) = 0.252 W/kg SAR(1 g) = 0.023 mW/g; SAR(10 g) = 0.011 mW/g Maximum value of SAR (measured) = 0.125 mW/g



0 dB = 0.125 mW/g



Date/Time: 4/21/2008 7:41:24 PM

## RT\_Dect 5.8G CH0

## DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5744.736 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5744.736 MHz;  $\sigma = 5.17$  mho/m;  $\varepsilon_r = 35.3$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

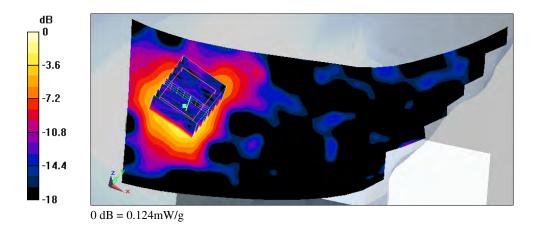
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### **Right Tilted/Area Scan (91x211x1):**

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.124 mW/g

## Right Tilted/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.4 V/m; Power Drift = -0.066 dB Peak SAR (extrapolated) = 0.288 W/kg SAR(1 g) = 0.065 mW/g; SAR(10 g) = 0.025 mW/g Maximum value of SAR (measured) = 0.124 mW/g





Date/Time: 4/21/2008 6:55:14 PM

## RT\_Dect 5.8G CH47

## DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5785.344 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5785.344 MHz;  $\sigma$  = 5.29 mho/m;  $\varepsilon_r$  = 35.5;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

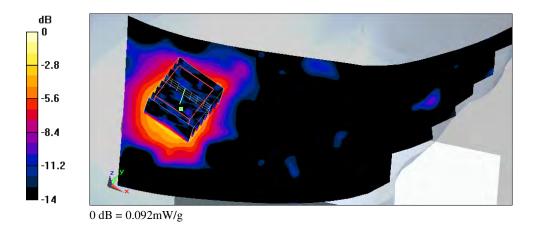
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### **Right Tilted/Area Scan (91x211x1):**

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.094 mW/g

## Right Tilted/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mmReference Value = 1.02 V/m; Power Drift = -0.194 dB Peak SAR (extrapolated) = 0.22 W/kg SAR(1 g) = 0.051 mW/g; SAR(10 g) = 0.018 mW/g Maximum value of SAR (measured) = 0.092 mW/g





Date/Time: 4/21/2008 5:40:11 PM

## RT\_Dect 5.8G CH94

#### DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5825.952 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5825.952 MHz;  $\sigma$  = 5.39 mho/m;  $\varepsilon_r$  = 35.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

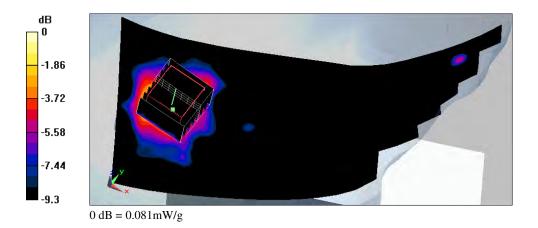
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### **Right Tilted/Area Scan (91x211x1):**

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.076 mW/g

## Right Tilted/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.05 V/m; Power Drift = 0.12 dB Peak SAR (extrapolated) = 0.207 W/kg SAR(1 g) = 0.041 mW/g; SAR(10 g) = 0.017 mW/g Maximum value of SAR (measured) = 0.081 mW/g





Date/Time: 4/21/2008 8:23:14 PM

## LC\_Dect 5.8G CH0

## DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5744.736 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5744.736 MHz;  $\sigma$  = 5.17 mho/m;  $\varepsilon_r$  = 35.3;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

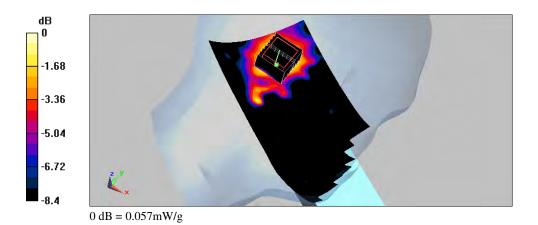
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### Left Cheek/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.067 mW/g

## Left Cheek/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.6 V/m; Power Drift = -0.162 dB Peak SAR (extrapolated) = 0.151 W/kg SAR(1 g) = 0.03 mW/g; SAR(10 g) = 0.014 mW/g Maximum value of SAR (measured) = 0.057 mW/g





Date/Time: 4/21/2008 9:11:23 PM

## LC\_Dect 5.8G CH47

#### DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5785.344 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5785.344 MHz;  $\sigma$  = 5.29 mho/m;  $\varepsilon_r$  = 35.5;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

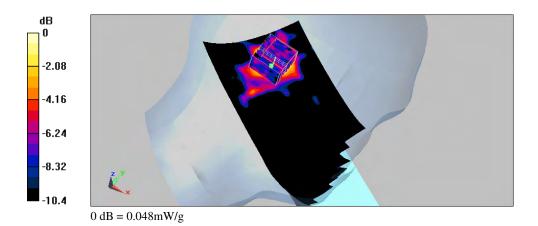
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### Left Cheek/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.051 mW/g

## Left Cheek/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.67 V/m; Power Drift = 0.104 dB Peak SAR (extrapolated) = 0.197 W/kg SAR(1 g) = 0.029 mW/g; SAR(10 g) = 0.014 mW/g Maximum value of SAR (measured) = 0.048 mW/g





Date/Time: 4/21/2008 9:53:51 PM

## LC\_Dect 5.8G CH94

## DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

## FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5825.952 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5825.952 MHz;  $\sigma$  = 5.39 mho/m;  $\varepsilon_r$  = 35.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

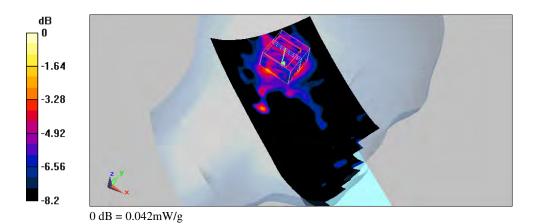
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### Left Cheek/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.042 mW/g

## Left Cheek/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.65 V/m; Power Drift = 0.173 dB Peak SAR (extrapolated) = 0.125 W/kg SAR(1 g) = 0.027 mW/g; SAR(10 g) = 0.016 mW/g Maximum value of SAR (measured) = 0.042 mW/g





Date/Time: 4/21/2008 11:50:12 PM

## LT\_Dect 5.8G CH0

## DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5744.736 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5744.736 MHz;  $\sigma = 5.17$  mho/m;  $\varepsilon_r = 35.3$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

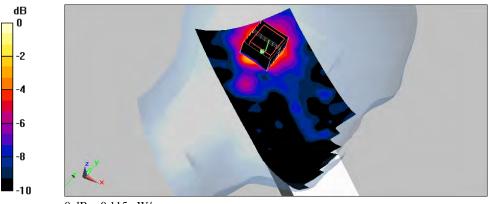
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### Left Tilted/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.122 mW/g

## Left Tilted/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.95 V/m; Power Drift = -0.156 dB Peak SAR (extrapolated) = 0.249 W/kg **SAR(1 g) = 0.062 mW/g; SAR(10 g) = 0.029 mW/g Maximum value of SAR (measured) = 0.115 mW/g** 





Date/Time: 4/21/2008 11:12:11 PM

## LT\_Dect 5.8G CH47

## DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

## FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5785.344 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5785.344 MHz;  $\sigma$  = 5.29 mho/m;  $\varepsilon_r$  = 35.5;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

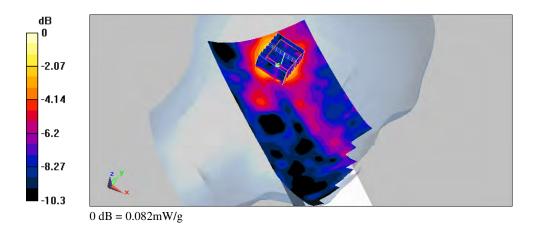
- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### Left Tilted/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.093 mW/g

## Left Tilted/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.95 V/m; Power Drift = -0.124 dB Peak SAR (extrapolated) = 0.192 W/kg **SAR(1 g) = 0.046 mW/g; SAR(10 g) = 0.020 mW/g Maximum value of SAR (measured) = 0.082 mW/g** 





Date/Time: 4/21/2008 10:26:33 PM

## LT\_Dect 5.8G CH94

#### DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

#### FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5825.952 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5825.952 MHz;  $\sigma$  = 5.39 mho/m;  $\varepsilon_r$  = 35.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

- Probe: EX3DV3 SN3519; ConvF(4.46, 4.46, 4.46); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### Left Tilted/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.071 mW/g

## Left Tilted/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.58 V/m; Power Drift = -0.136 dB Peak SAR (extrapolated) = 0.180 W/kg SAR(1 g) = 0.039 mW/g; SAR(10 g) = 0.022 mW/g Maximum value of SAR (measured) = 0.067 mW/g





Date/Time: 4/16/2008 2:59:20 AM

# Flat\_Dect 5.8G CH0\_Headset\_Belt Clip\_Close Body

# DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

## FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5744.736 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5744.736 MHz;  $\sigma$  = 5.81 mho/m;  $\epsilon_r$  = 47.8;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

**DASY5** Configuration:

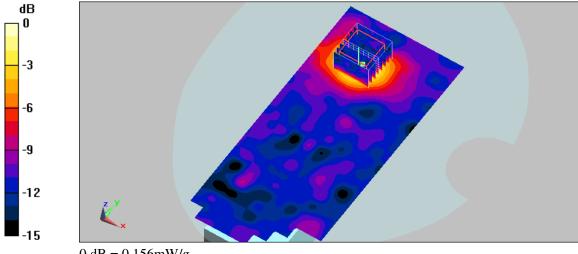
- Probe: EX3DV3 SN3519; ConvF(3.88, 3.88, 3.88); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

# Flat/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.168 mW/g

# Flat/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mmReference Value = 1.66 V/m; Power Drift = 0.095 dB Peak SAR (extrapolated) = 0.378 W/kg **SAR(1 g) = 0.085 mW/g; SAR(10 g) = 0.037 mW/g** Maximum value of SAR (measured) = 0.156 mW/g



 $0 \, dB = 0.156 \, mW/g$ 



Date/Time: 4/16/2008 3:36:47 AM

# Flat\_Dect 5.8G CH47\_Headset\_Belt Clip\_Close Body

# DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

# FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5785.344 MHz;Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5785.344 MHz;  $\sigma$  = 5.8 mho/m;  $\varepsilon_r$  = 47.8;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

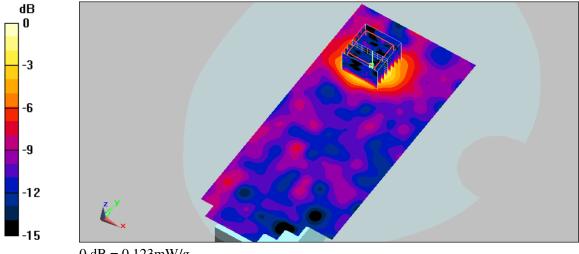
- Probe: EX3DV3 SN3519; ConvF(3.88, 3.88, 3.88); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

# Flat/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.130 mW/g

# Flat/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mmReference Value = 1.64 V/m; Power Drift = 0.171 dB Peak SAR (extrapolated) = 0.264 W/kg **SAR(1 g) = 0.066 mW/g; SAR(10 g) = 0.028 mW/g** Maximum value of SAR (measured) = 0.123 mW/g



 $0 \, dB = 0.123 \, mW/g$ 



Date/Time: 4/16/2008 4:22:25 AM

# Flat\_Dect 5.8G CH94\_Headset\_Belt Clip\_Close Body

# DUT: TL76108; Type: 5.8GHz Frequency Hopping Spread Spectrum Cordless Phone;

# FCC ID: EW780-5681-00

Communication System: DECT\_5.8G; Frequency: 5825.952 MHz; Duty Cycle: 1:1 Medium parameters used (interpolated): f = 5825.952 MHz;  $\sigma$  = 5.84 mho/m;  $\varepsilon_r$  = 47.9;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

**DASY5** Configuration:

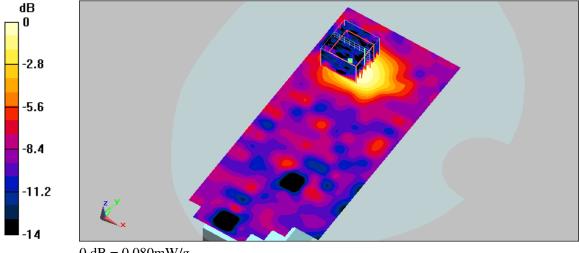
- Probe: EX3DV3 SN3519; ConvF(3.88, 3.88, 3.88); Calibrated: 3/21/2008
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

# Flat/Area Scan (91x211x1):

Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.081 mW/g

# Flat/Zoom Scan (8x8x9)/Cube 0:

Measurement grid: dx=4mm, dy=4mm, dz=2.5mm Reference Value = 1.9 V/m; Power Drift = -0.029 dBPeak SAR (extrapolated) = 0.156 W/kg SAR(1 g) = 0.037 mW/g; SAR(10 g) = 0.015 mW/g Maximum value of SAR (measured) = 0.080 mW/g



 $0 \, dB = 0.080 \, mW/g$ 



# Appendix C - Calibration

All of the instruments Calibration information are listed below.

- Dipole \_ D5GHzV2 SN:1021 Calibration No.D5GHzV2-1021\_Mar08
- Probe \_ EX3DV3 SN:3519 Calibration No.EX3-3519\_Mar08
- DAE \_ DAE4 SN:779 Calibration No.DAE4-779\_Nov07