



# **SAR Evaluation Report**

**IN ACCORDANCE WITH THE REQUIREMENTS OF  
FCC OET BULLETIN 65 SUPPLEMENT C  
IC RSS 102 ISSUE 2 : NOVEMBER 2005**

**FOR**

**VOIP MOBILE PHONE TERMINAL**

**MODEL: WLPS3(E)-A**

**FCC ID: EW4-WLPS3-1  
IC: 4250A-WLPS3**

**REPORT NUMBER: 07J11502-3B**

**ISSUE DATE: FEBRUARY 5, 2008**

*Prepared for*

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**NVLAP LAB CODE 200065-0**

**Revision History**

Rev.	Issued date	Revisions	Revised By
--	2-1-08	Initial issue	Hsin Fu Shih
B	2-7-08	Removed note from p. 23 and updated FCC ID on p.1	J. King

**CERTIFICATE OF COMPLIANCE (SAR EVALUATION)****DATES OF TEST:** January 31, 2008

APPLICANT: ADDRESS:	MITSUMI ELECTRIC CO., LTD 1601 SAKAI, ATSUGI-SHI, KANAGAWA, 243-8533, JAPAN
FCC ID: MODEL:	EW4-WLPS3-1 WLPS3(E)-A
DEVICE CATEGORY: EXPOSURE CATEGORY:	Portable Device General Population/Uncontrolled Exposure



VOIP MOBILE PHONE TERMINAL		
Test Sample is a:	Production unit	
Modulation type:	Direct Sequence Spread Spectrum (DSSS) for 802.11b	
Rule Parts	Frequency Range [MHz]	The Highest SAR Values [1g_mW/g]
FCC 15.247	2412 - 2462	Head Positions: 0.453 Body Positions: 1.457
<p>This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for General Population/Uncontrolled Exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC OET 65 Supplement C (Edition 01-01) and RSS 102.</p> <p>Note: The results documented in this report apply only to the tested sample, under the conditions and modes of operation as described herein. This document may not be altered or revised in any way unless done so by Compliance Certification Services and all revisions are duly noted in the revisions section. Any alteration of this document not carried out by Compliance Certification Services will constitute fraud and shall nullify the document. No part of this report may be used to claim product certification, approval, or endorsement by NVLAP, NIST, or any government agency.</p>		
Approved & Released For CCS By:	Tested By:	
		
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**1 DEVICE UNDER TEST (DUT) DESCRIPTION**

VOIP MOBILE PHONE TERMINAL	
Normal operation:	Head and body worn positions
Accessories:	Headset Jack
Duty cycle:	100%
Antenna(s)	Main Antenna: Mitsumi Electric Co., LTD. Model DCA-P09 Sub Antenna: Mitsumi Electric Co., LTD. Model DCA-P07 Note: Only the Main Antenna was used for the SAR testing.
Battery:	Manufacturer: NEC Tokin Corp. Model No.: CBG-002535-202, 3.7Vdc, 850mAh, Li-Ion Battery

## 2 FACILITIES AND ACCREDITATION

The test sites and measurement facilities used to collect data are located at 47173 Benicia Street, Fremont, CA 94538 USA. The sites are constructed in conformance with the requirements of ANSI C63.4, ANSI C63.7 and CISPR Publication 22. All receiving equipment conforms to CISPR Publication 16-1, "Radio Interference Measuring Apparatus and Measurement Methods."

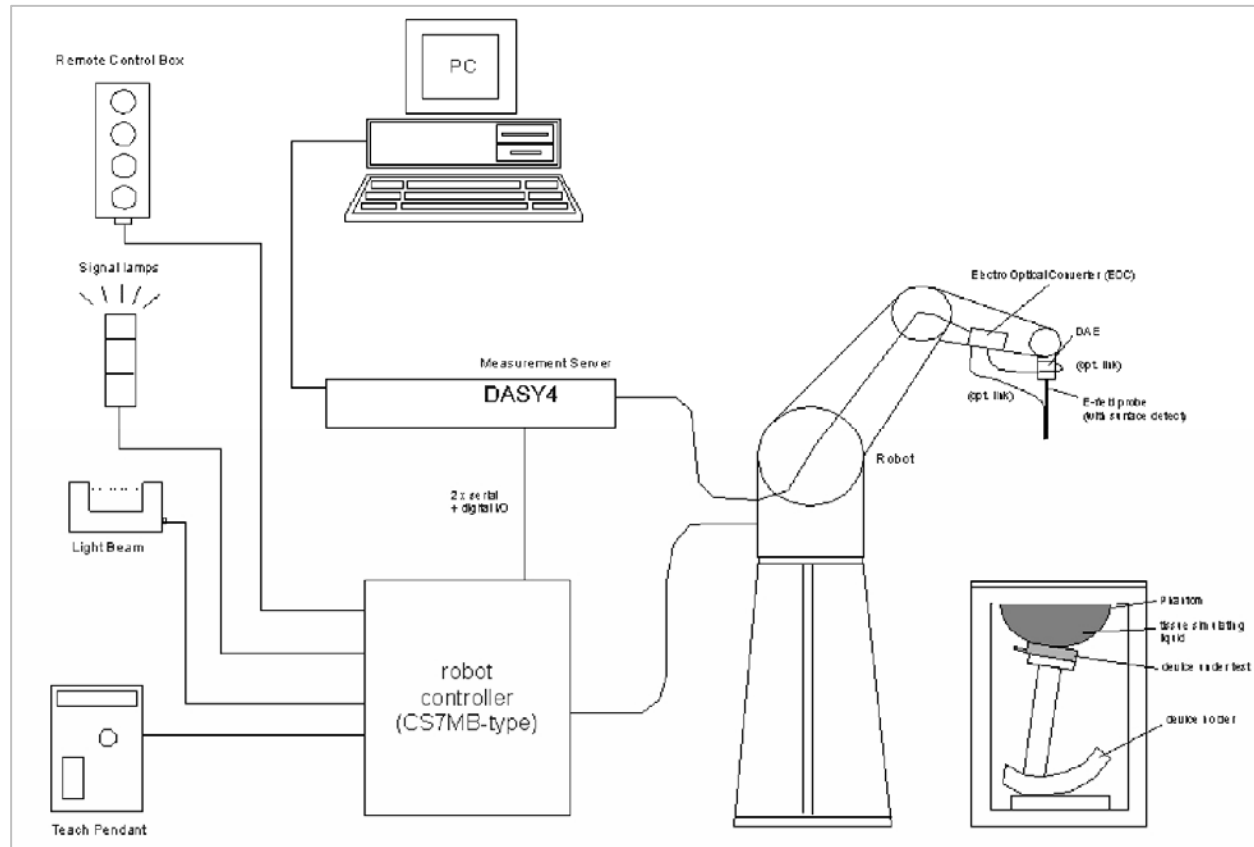


NVLAP LAB CODE 200065-0

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### 3 SYSTEM DESCRIPTION



**The DASY4 system for performing compliance tests consists of the following items:**

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows XP.
- DASY4 software.
- Remote controls with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- Validation dipole kits allowing to validate the proper functioning of the system.

### 3.1 COMPOSITION OF INGREDIENTS FOR TISSUE SIMULATING LIQUIDS

The following tissue formulations are provided for reference only as some of the parameters have not been thoroughly verified. The composition of ingredients may be modified accordingly to achieve the desired target tissue parameters required for routine SAR evaluation.

Ingredients (% by weight)	Frequency (MHz)									
	450		835		915		1900		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	38.56	51.16	41.45	52.4	41.05	56.0	54.9	40.4	62.7	73.2
Salt (NaCl)	3.95	1.49	1.45	1.4	1.35	0.76	0.18	0.5	0.5	0.04
Sugar	56.32	46.78	56.0	45.0	56.5	41.76	0.0	58.0	0.0	0.0
HEC	0.98	0.52	1.0	1.0	1.0	1.21	0.0	1.0	0.0	0.0
Bactericide	0.19	0.05	0.1	0.1	0.1	0.27	0.0	0.1	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	0.0	0.0	0.0	0.0	44.92	0.0	0.0	26.7
Dielectric Constant	43.42	58.0	42.54	56.1	42.0	56.8	39.9	54.0	39.8	52.5
Conductivity (S/m)	0.85	0.83	0.91	0.95	1.0	1.07	1.42	1.45	1.88	1.78

Salt: 99+% Pure Sodium Chloride

Sugar: 98+% Pure Sucrose

Water: De-ionized, 16 M $\Omega$ + resistivity

HEC: Hydroxyethyl Cellulose

DGBE: 99+% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]

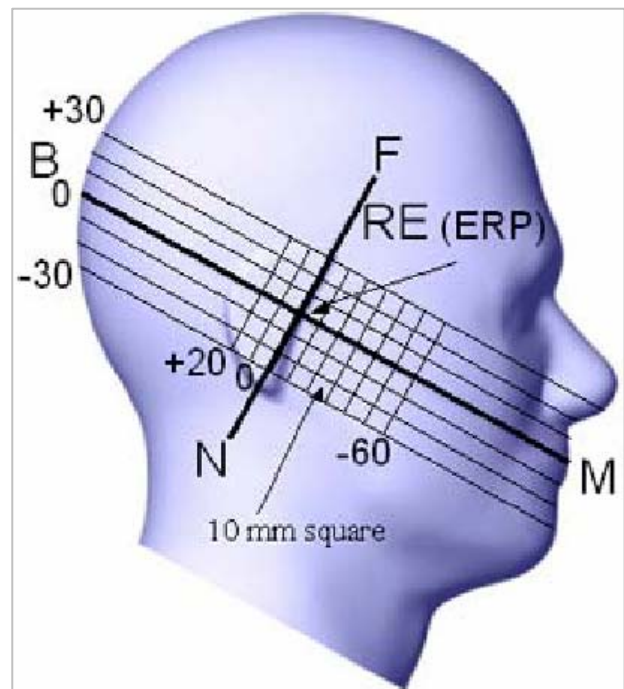
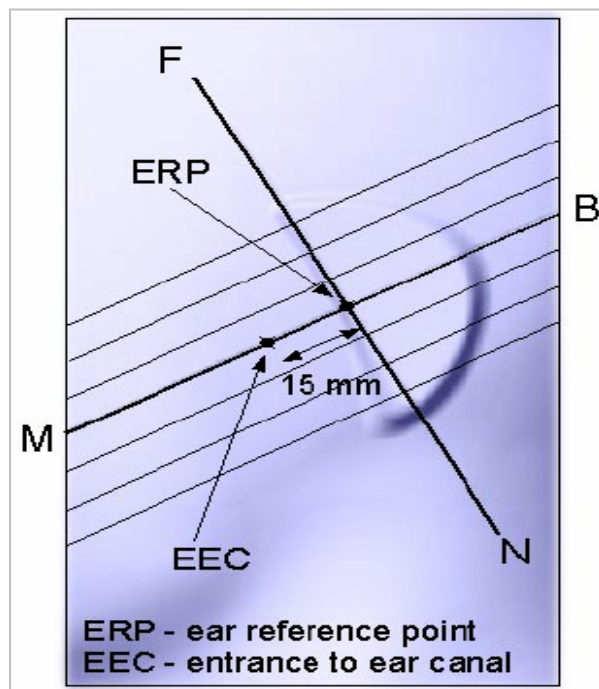
Triton X-100 (ultra pure): Polyethylene glycol mono [4-(1,1, 3, 3-tetramethylbutyl)phenyl]ether



**4 TEST POSITIONS FOR DEVICES OPERATING NEXT TO A PERSON’S EAR**

This category includes most wireless handsets with fixed, retractable or internal antennas located toward the top half of the device, with or without a foldout, sliding or similar keypad cover. The handset should have its earpiece located within the upper ¼ of the device, either along the centerline or off-centered, as perceived by its users. This type of handset should be positioned in a normal operating position with the “test device reference point” located along the “vertical centerline” on the front of the device aligned to the “ear reference point”. The “test device reference point” should be located at the same level as the center of the earpiece region. The “vertical centerline” should bisect the front surface of the handset at its top and bottom edges. A “ear reference point” is located on the outer surface of the head phantom on each ear spacer. It is located 1.5 cm above the center of the ear canal entrance in the “phantom reference plane” defined by the three lines joining the center of each “ear reference point” (left and right) and the tip of the mouth.

A handset should be initially positioned with the earpiece region pressed against the ear spacer of a head phantom. For the SCC-34/SC-2 head phantom, the device should be positioned parallel to the “N-F” line defined along the base of the ear spacer that contains the “ear reference point”. For interim head phantoms, the device should be positioned parallel to the cheek for maximum RF energy coupling. The “test device reference point” is aligned to the “ear reference point” on the head phantom and the “vertical centerline” is aligned to the “phantom reference plane”. This is called the “initial ear position”. While maintaining these three alignments, the body of the handset is gradually adjusted to each of the following positions for evaluating SAR:



#### 4.1 CHEEK/TOUCH POSITION

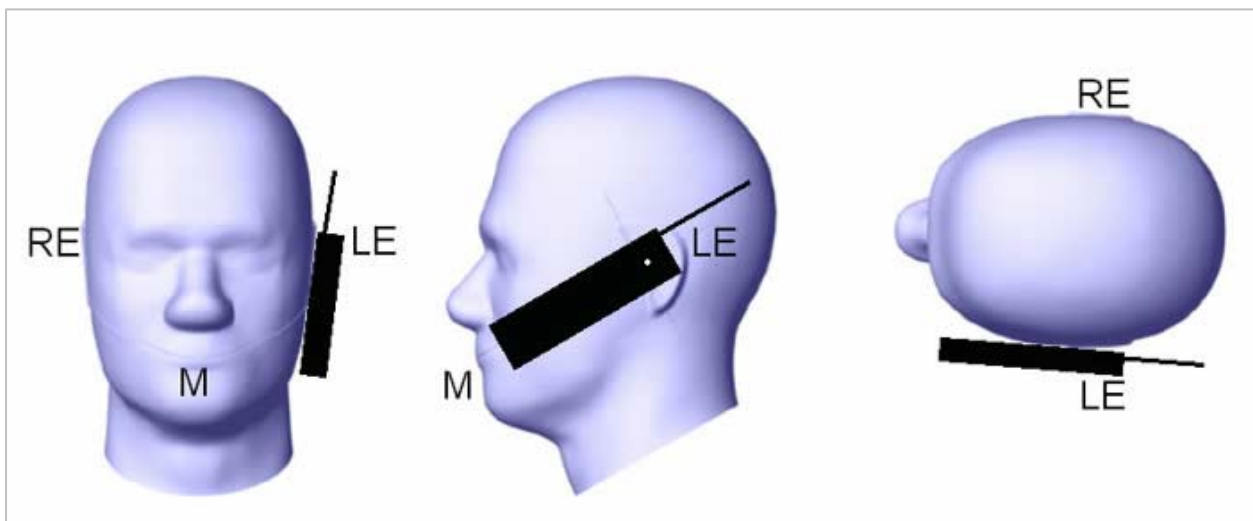
The device is brought toward the mouth of the head phantom by pivoting against the “ear reference point” or along the “N-F” line for the SCC-34/SC-2 head phantom.

This test position is established:

- i. When any point on the display, keypad or mouthpiece portions of the handset is in contact with the phantom.
- ii. (or) When any portion of a foldout, sliding or similar keypad cover opened to its intended self-adjusting normal use position is in contact with the cheek or mouth of the phantom.

For existing head phantoms – when the handset loses contact with the phantom at the pivoting point, rotation should continue until the device touches the cheek of the phantom or breaks its last contact from the ear spacer.

Cheek / Touch Position



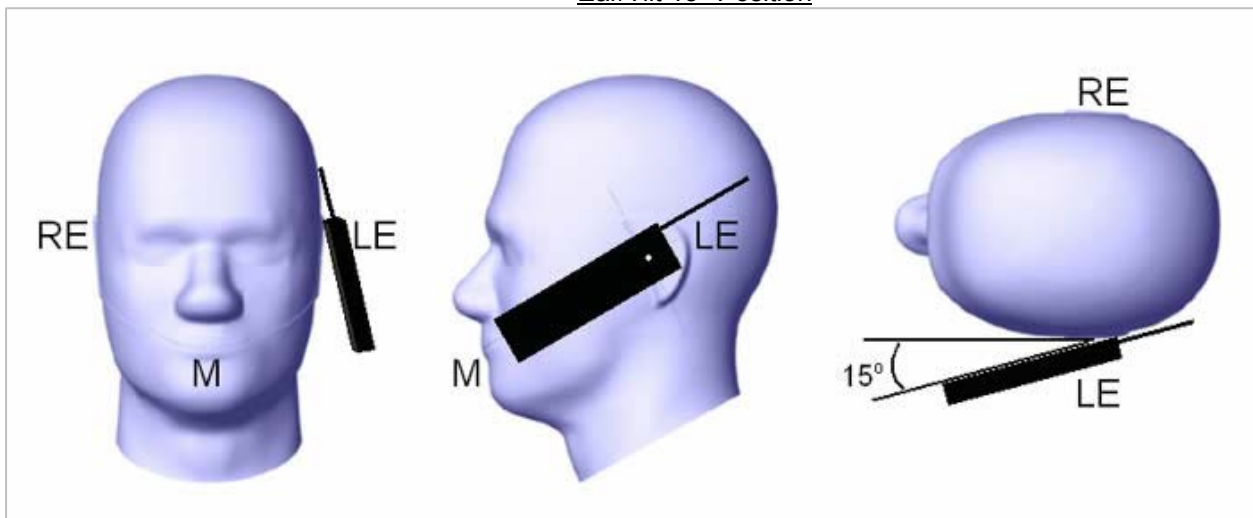
## 4.2 EAR/TILT POSITION

With the handset aligned in the “Cheek/Touch Position”:

- i. If the earpiece of the handset is not in full contact with the phantom’s ear spacer (in the “Cheek/Touch position”) and the peak SAR location for the “Cheek/Touch” position is located at the ear spacer region or corresponds to the earpiece region of the handset, the device should be returned to the “initial ear position” by rotating it away from the mouth until the earpiece is in full contact with the ear spacer.
- ii. (otherwise) The handset should be moved (translated) away from the cheek perpendicular to the line passes through both “ear reference points” (note: one of these ear reference points may not physically exist on a split head model) for approximate 2-3 cm. While it is in this position, the device handset is tilted away from the mouth with respect to the “test device reference point” until the inside angle between the vertical centerline on the front surface of the phone and the horizontal line passing through the ear reference point is by  $15^\circ$ . After the tilt, it is then moved (translated) back toward the head perpendicular to the line passes through both “ear reference points” until the device touches the phantom or the ear spacer. If the antenna touches the head first, the positioning process should be repeated with a tilt angle less than  $15^\circ$  so that the device and its antenna would touch the phantom simultaneously. This test position may require a device holder or positioner to achieve the translation and tilting with acceptable positioning repeatability.

If a device is also designed to transmit with its keypad cover closed for operating in the head position, such positions should also be considered in the SAR evaluation. The device should be tested on the left and right side of the head phantom in the “Cheek/Touch” and “Ear/Tilt” positions. When applicable, each configuration should be tested with the antenna in its fully extended and fully retracted positions. These test configurations should be tested at the high, middle and low frequency channels of each operating mode; for example, AMPS, CDMA, and TDMA. If the SAR measured at the middle channel for each test configuration (left, right, Cheek/Touch, Tilt/Ear, extended and retracted) is at least 3.0 dB lower than the SAR limit, testing at the high and low channels is optional for such test configuration(s). If the transmission band of the test device is less than 10 MHz, testing at the high and low frequency channels is optional.

Ear/Tilt  $15^\circ$  Position



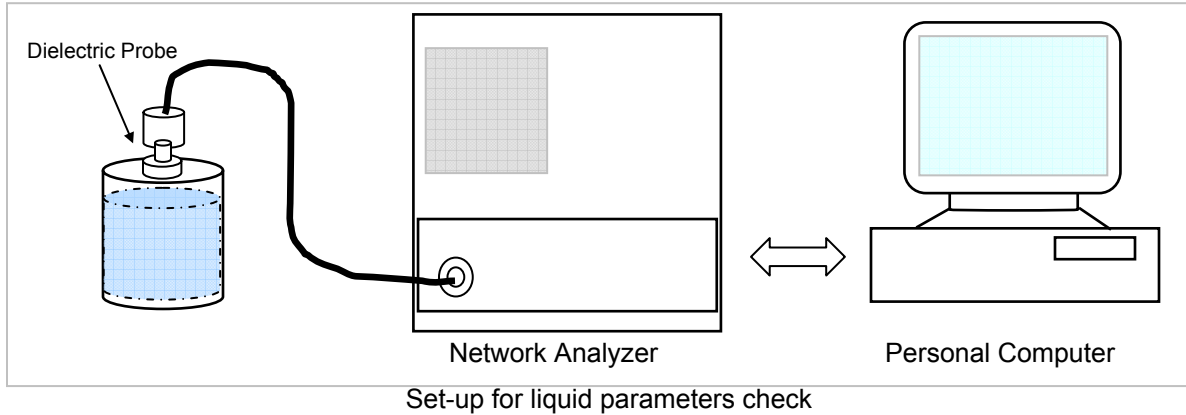
### **4.3 TEST POSITIONS FOR BODY-WORN AND OTHER SIMILAR CONFIGURATIONS**

Without the belt-clips or holsters

Body-worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances. Other separation distances may be used, but they should not exceed 2.5 cm. In these cases, the device may use body-worn accessories that provide a separation distance greater than that tested for the device provided however that the accessory contains no metallic components.

**5 SIMULATING LIQUID PARAMETERS CHECK**

The simulating liquids should be checked at the beginning of a series of SAR measurements to determine if the dielectric parameters are within the tolerances of the specified target values. The relative permittivity and conductivity of the tissue material should be within  $\pm 5\%$  of the values given in the table below.



**Reference Values of Tissue Dielectric Parameters for Head and Body Phantom (for 150 – 3000 MHz and 5800 MHz)**

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in IEEE Standard 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations and extrapolated according to the head parameters specified in IEEE Standard 1528.

Target Frequency (MHz)	Head		Body	
	$\epsilon_r$	$\sigma$ (S/m)	$\epsilon_r$	$\sigma$ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800 – 2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

( $\epsilon_r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho = 1000 \text{ kg/m}^3$ )

**5.1 SIMULATING LIQUID PARAMETER CHECK RESULT**

Simulating Liquid Dielectric Parameter Check Result @ Head 2450 MHz

Room Ambient Temperature = 23°C; Relative humidity =40%

Measured by: Jonathan King

Simulating Liquid			Parameters		Measured	Target	Deviation (%)	Limit (%)	
f (MHz)	Temp. (°C)	Depth (cm)							
2450	22	15	e'	38.1245	Relative Permittivity ( $\epsilon_r$ ):	38.1245	39.2	-2.74	± 5
			e"	13.3246	Conductivity ( $\sigma$ ):	1.81610	1.80	0.89	± 5

Liquid Check

Ambient temperature: 23 deg. C; Liquid temperature: 22 deg C

January 31, 2008 09:53 AM

Frequency	e'	e"
2400000000.	38.3522	13.1847
2405000000.	38.3163	13.1909
2410000000.	38.2937	13.2165
2415000000.	38.2701	13.2239
2420000000.	38.2452	13.2461
2425000000.	38.2260	13.2582
2430000000.	38.2179	13.2668
2435000000.	38.1949	13.2905
2440000000.	38.1854	13.3003
2445000000.	38.1580	13.3112
<b>2450000000.</b>	<b>38.1245</b>	<b>13.3246</b>
2455000000.	38.0901	13.3497
2460000000.	38.0799	13.3576
2465000000.	38.0510	13.3756
2470000000.	38.0364	13.3710
2475000000.	38.0105	13.3921
2480000000.	37.9822	13.4099
2485000000.	37.9790	13.4314
2490000000.	37.9540	13.4493
2495000000.	37.9165	13.4587
2500000000.	37.9031	13.4671

The conductivity ( $\sigma$ ) can be given as:

$$\sigma = \omega \epsilon_0 e'' = 2 \pi f \epsilon_0 e''$$

where  $f = \text{target } f * 10^6$

$$\epsilon_0 = 8.854 * 10^{-12}$$

Simulating Liquid Dielectric Parameter Check Result @ Muscle 2450 MHz

Room Ambient Temperature = 23°C; Relative humidity = 40%

Measured by: Jonathan King

Simulating Liquid			Parameters		Measured	Target	Deviation (%)	Limit (%)	
f (MHz)	Temp. (°C)	Depth (cm)							
2450	22	15	e'	54.3001	Relative Permittivity (ε <sub>r</sub> ):	54.3001	52.7	3.04	± 5
			e"	14.8217	Conductivity (σ):	2.02015	1.95	3.60	± 5

Liquid Check

Ambient temperature: 23.0 deg. C; Liquid temperature: 22.0 deg C

January 31, 2008 12:48 PM

Frequency	e'	e"
2400000000.	53.8230	14.2832
2405000000.	53.7643	14.4099
2410000000.	53.7398	14.5114
2415000000.	53.7424	14.6092
2420000000.	53.7664	14.6869
2425000000.	53.8319	14.7416
2430000000.	53.9293	14.7898
2435000000.	54.0527	14.8269
2440000000.	54.1572	14.8372
2445000000.	54.2349	14.8151
<b>2450000000.</b>	<b>54.3001</b>	<b>14.8217</b>
2455000000.	54.3500	14.7844
2460000000.	54.3736	14.7101
2465000000.	54.3893	14.6301
2470000000.	54.3246	14.5566
2475000000.	54.2903	14.4816
2480000000.	54.2355	14.4356
2485000000.	54.1650	14.4159
2490000000.	54.0672	14.4227
2495000000.	53.9662	14.4587
2500000000.	53.8236	14.5250

The conductivity (σ) can be given as:

$$\sigma = \omega \epsilon_0 e'' = 2 \pi f \epsilon_0 e''$$

where  $f = \text{target } f * 10^6$

$$\epsilon_0 = 8.854 * 10^{-12}$$

## 6 SYSTEM PERFORMANCE CHECK

The system performance check is performed prior to any usage of the system in order to guarantee reproducible results. The system performance check verifies that the system operates within its specifications of  $\pm 10\%$ .

### System Performance Check Measurement Conditions

- The measurements were performed in the flat section of the SAM twin phantom filled with Head simulating liquid of the following parameters.
- The DASY4 system with an Isotropic E-Field Probe EX3DV3-SN: 3554 was used for the measurements.
- The dipole was mounted on the small tripod so that the dipole feed point was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10 mm (above 1 GHz) and 15 mm (below 1 GHz) from dipole center to the simulating liquid surface.
- The coarse grid with a grid spacing of 15 mm was aligned with the dipole.  
For 5 GHz band - The coarse grid with a grid spacing of 10 mm was aligned with the dipole.
- Special 5 x 5 x 7 fine cube was chosen for cube integration(dx=dy=7.5mm; dz=5mm).  
For 5 GHz band - Special 8x8x8 fine cube was chosen for cube integration(dx=dy=4.3mm; dz=3mm)
- Distance between probe sensors and phantom surface was set to 4 mm.  
For 5 GHz band - Distance between probe sensors and phantom surface was set to 2.0mm
- The dipole input power (forward power) was 250 mW $\pm 3\%$ .
- The results are normalized to 1 W input power.

IEEE Standard 1528-2003 Recommended Reference Value.

Frequency (MHz)	Distance (mm)	1g SAR [W/kg]	10g SAR [W/kg]
300	15	3.0	2.0
450	15	4.9	3.3
835	15	9.5	6.2
900	15	10.8	6.9
1450	10	29.0	16.0
1800	10	38.1	19.8
1900	10	39.7	20.5
2000	10	41.1	21.1
2450	10	52.4	24.0
3000	10	63.8	25.7

Note: All SAR values normalized to 1 W forward power.



**6.1 SYSTEM PERFORMANCE CHECK RESULTS****System Validation Dipole: D2450V2 SN: 706**

Date: January 31, 2008

Ambient Temperature = 23°C; Relative humidity = 40%

Measured by: Jonathan King

Head Simulating Liquid			SAR (mW/g)	Normalized to 1 W	Target	Deviation (%)	Limit (%)	
f (MHz)	Temp. (°C)	Depth (cm)						
2450	22	15	1g	13.30	53.2	52.4	1.53	± 10
			10g	5.89	23.56	24.0	-1.83	± 10

## 7 SAR MEASUREMENT PROCEDURE

A summary of the procedure follows:

- a) A measurement of the SAR value at a fixed location is used as a reference value for assessing the power drop of the EUT. The SAR at this point is measured at the start of the test, and then again at the end of the test.
- b) The SAR distribution at the exposed flat section of the flat phantom is measured at a distance of 4 mm from the inner surface of the shell. The area covers the entire dimension of the EUT and the horizontal grid spacing is 15 mm x 15 mm. Based on this data, the area of the maximum absorption is determined by Spline interpolation. The first Area Scan covers the entire dimension of the EUT to ensure that the hotspot was correctly identified.

For 5 GHz band - The SAR distribution at the exposed flat section of the flat phantom is measured at a distance of 2.0 mm from the inner surface of the shell. The area covers the entire dimension of the EUT and the horizontal grid spacing is 10 mm x 10 mm. Based on this data, the area of the maximum absorption is determined by Spline interpolation. The first Area Scan covers the entire dimension of the EUT to ensure that the hotspot was correctly identified.

- c) Around this point, a volume of X=Y= 30 and Z=21 mm is assessed by measuring 5 x 5 x 7 mm points. On the basis of this data set, the spatial peak SAR value is evaluated with the following procedure:

For 5 GHz band - Around this point, a volume of X=Y=24 and Z=20 mm is assessed by measuring 7 x 7 x 9 mm points. On the basis of this data set, the spatial peak SAR value is evaluated with the following procedure:

- (i) The data at the surface are extrapolated, since the centre of the dipoles is 1.2 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.3 mm. The extrapolation is based on a least square algorithm. A polynomial of the fourth order is calculated through the points in z-axes. This polynomial is then used to evaluate the points between the surface and the probe tip.
- (ii) The maximum interpolated value is searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g and 10 g) are computed using the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one-dimensional splines with the "Not a knot"- condition (in x, y and z-direction). The volume is integrated with the trapezoidal – algorithm. One thousand points (10 x 10 x 10) are interpolated to calculate the averages.
- (iii) All neighbouring volumes are evaluated until no neighbouring volume with a higher average value is found.
- (iv) The SAR value at the same location as in Step (a) is again measured to evaluate the actual power drift.

## 7.1 DASY4 SAR MEASUREMENT PROCEDURE

### Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The Minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. The minimum distance of probe sensors to surface is 2.1 mm. This distance cannot be smaller than the Distance of sensor calibration points to probe tip as defined in the probe properties (for example, 1.2 mm for an EX3DV3 probe type).

### Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY4 software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE Standard 1528, EN 50361 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan). If only one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of Zoom Scans has to be increased accordingly.

### Step 3: Zoom Scan

Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The Zoom Scan measures 5 x 5 x 7 points within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1 g and 10 g and displays these values next to the job's label.

For 5 GHz band – Same as above except the Zoom Scan measures 7 x 7 x 9 points.

### Step 4: Power drift measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the last Power Reference Measurement. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

### Step 5: Z-Scan

The Z Scan measures points along a vertical straight line. The line runs along the Z-axis of a one-dimensional grid. In order to get a reasonable extrapolation, the extrapolated distance should not be larger than the step size in Z-direction.

**8 PROCEDURE USED TO ESTABLISH TEST SIGNAL**

The following procedures had been used to prepare the EUT for the SAR test.

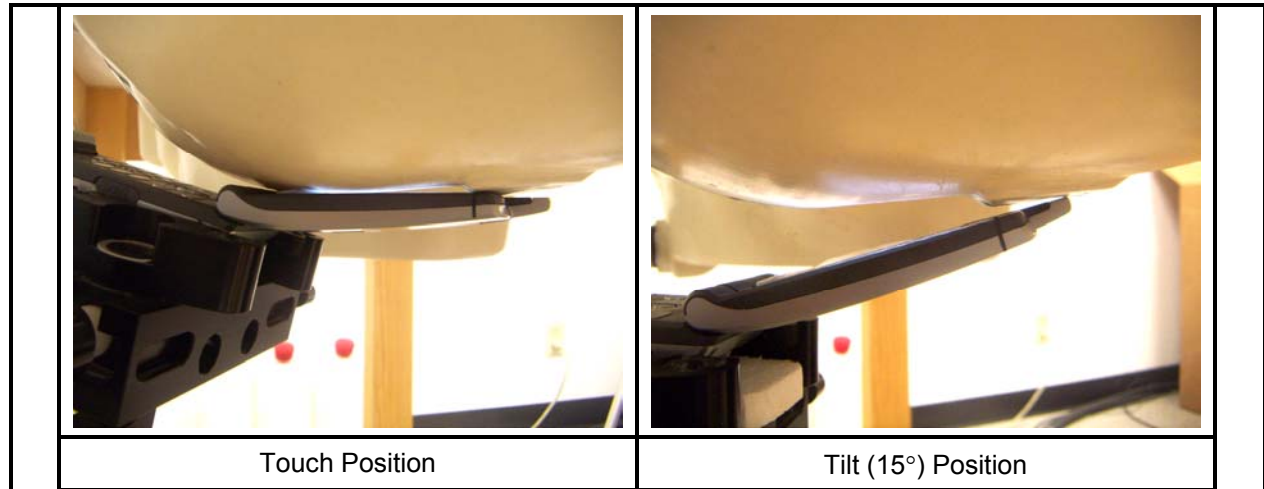
The cable assembly insertion loss of 11dB (including 10 dB attenuator and 1dB connectors) was entered as an offset in the power meter to allow for direct reading of power.

**802.11b**

Channel	Frequency (MHz)	Average Power (dBm)
Low	2412	12.1
Middle	2437	12.2
High	2462	12.3

**9 SAR MEASUREMENT RESULTS**

**9.1 HEAD POSITIONS - LEFT HAND SIDE (LHS)**





**802.11b**

Test Position	Channel	f (MHz)	Measured SAR 1g (mW/g)	Power Drift (dB)	Extrapolated <sup>1)</sup> SAR 1g (mW/g)
Touch	1	2412.0	0.394	-0.012	0.395
	6	2437.0			
	11	2462.0			
Tilt (15°)	1	2412.0	0.326	0.000	0.326
	6	2437.0			
	11	2462.0			

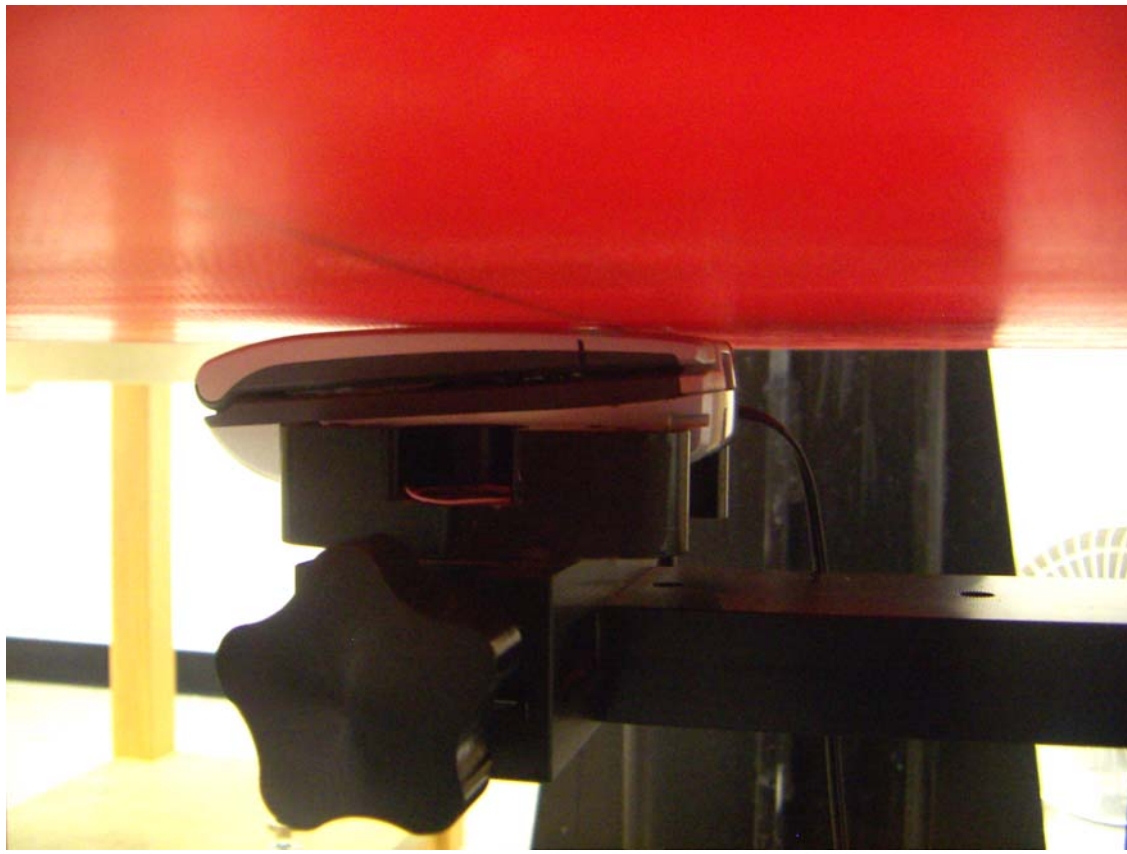
Notes:

- 1) The exact method of extrapolation is  $\text{Measured SAR} \times 10^{(-\text{drift}/10)}$ . The SAR reported at the end of the measurement process by the DASY4 system can be scaled up by the Power drift to determine the SAR at the beginning of the measurement process.
- 2) The SAR measured at the middle channel for this configuration is at least 3 dB lower (0.8 mW/g) than SAR limit (1.6 mW/g), thus testing at low & high channel is optional.
- 3) Please see attachments for the detailed measurement data and plots showing the maximum SAR location of the EUT.
- 4) The battery was fully charged in accordance with manufacture's instructions prior to SAR measurements.

**9.2 HEAD POSITIONS - RIGHT HAND SIDE (RHS)**

					
Touch Position	Tilt (15°) Position				
<b>802.11b</b>					
<b>Test Position</b>	<b>Channel</b>	<b>f (MHz)</b>	<b>Measured SAR 1g (mW/g)</b>	<b>Power Drift (dB)</b>	<b>Extrapolated<sup>1)</sup> SAR 1g (mW/g)</b>
Touch	1	2412.0	0.414	-0.028	0.417
	6	2437.0	0.417	-0.016	0.419
	<b>11</b>	<b>2462.0</b>	<b>0.452</b>	<b>-0.010</b>	<b>0.453</b>
Tilt (15°)	1	2412.0	0.340	-0.141	0.351
	6	2437.0	0.340	-0.141	0.351
	11	2462.0	0.340	-0.141	0.351
Notes:					
1) The exact method of extrapolation is Measured SAR x 10 <sup>^(-drift/10)</sup> . The SAR reported at the end of the measurement process by the DASY4 system can be scaled up by the Power drift to determine the SAR at the beginning of the measurement process.					
2) The SAR measured at the middle channel for this configuration is at least 3 dB lower (0.8 mW/g) than SAR limit (1.6 mW/g), thus testing at low & high channel is optional.					
3) Please see attachments for the detailed measurement data and plots showing the maximum SAR location of the EUT.					
4) The battery was fully charged in accordance with manufacture's instructions prior to SAR measurements.					

**9.3 BODY-WORN POSITION – NO SEPARATION**



LCD Facing Up

**802.11b**

Test Position	Channel	f (MHz)	Measured SAR 1g (mW/g)	Power Drift (dB)	Extrapolated <sup>1)</sup> SAR 1g (mW/g)
Facing Up	1	2412.0	1.240	0.000	1.240
	6	2437.0	1.280	0.000	1.280
	<b>11</b>	<b>2462.0</b>	<b>1.430</b>	<b>-0.081</b>	<b>1.457</b>

Notes:

- 1) The exact method of extrapolation is  $\text{Measured SAR} \times 10^{(-\text{drift}/10)}$ . The SAR reported at the end of the measurement process by the DASY4 system can be scaled up by the Power drift to determine the SAR at the beginning of the measurement process.
- 2) Please see attachments for the detailed measurement data and plots showing the maximum SAR location of the EUT.
- 3) The battery was fully charged in accordance with manufacture's instructions prior to SAR measurements.
- 4) LCD facing down position was skipped due to significantly lower SAR value.

**10 MEASUREMENT UNCERTAINTY**

**10.1 MEASUREMENT UNCERTAINTY FOR 300 MHz – 3000 MHz**

Uncertainty component	Tol. (±%)	Probe Dist.	Div.	Ci (1g)	Ci (10g)	Std. Unc.(±%)	
						Ui (1g)	Ui(10g)
<b>Measurement System</b>							
Probe Calibration	4.80	N	1	1	1	4.80	4.80
Axial Isotropy	4.70	R	1.732	0.707	0.707	1.92	1.92
Hemispherical Isotropy	9.60	R	1.732	0.707	0.707	3.92	3.92
Boundary Effects	1.00	R	1.732	1	1	0.58	0.58
Linearity	4.70	R	1.732	1	1	2.71	2.71
System Detection Limits	1.00	R	1.732	1	1	0.58	0.58
Readout Electronics	1.00	N	1	1	1	1.00	1.00
Response Time	0.80	R	1.732	1	1	0.46	0.46
Integration Time	2.60	R	1.732	1	1	1.50	1.50
RF Ambient Conditions - Noise	1.59	R	1.732	1	1	0.92	0.92
RF Ambient Conditions - Reflections	0.00	R	1.732	1	1	0.00	0.00
Probe Positioner Mechanical Tolerance	0.40	R	1.732	1	1	0.23	0.23
Probe Positioning With Respect to Phantom Shell	2.90	R	1.732	1	1	1.67	1.67
Extrapolation, interpolation, and integration algorithms for max. SAR evaluation	3.90	R	1.732	1	1	2.25	2.25
<b>Test sample Related</b>							
Test Sample Positioning	1.10	N	1	1	1	1.10	1.10
Device Holder Uncertainty	3.60	N	1	1	1	3.60	3.60
Power and SAR Drift Measurement	5.00	R	1.732	1	1	2.89	2.89
<b>Phantom and Tissue Parameters</b>							
Phantom Uncertainty	4.00	R	1.732	1	1	2.31	2.31
Liquid Conductivity - Target	5.00	R	1.732	0.64	0.43	1.85	1.24
Liquid Conductivity - Meas.	8.60	N	1	0.64	0.43	5.50	3.70
Liquid Permittivity - Target	5.00	R	1.732	0.6	0.49	1.73	1.41
Liquid Permittivity - Meas.	3.30	N	1	0.6	0.49	1.98	1.62
<b>Combined Standard Uncertainty</b>	RSS					11.44	10.49
<b>Expanded Uncertainty (95% Confidence Interval)</b>	K=2					22.87	20.98
Notes for table							
1. Tol. - tolerance in influence quantity							
2. N - Nomal							
3. R - Rectangular							
4. Div. - Divisor used to obtain standard uncertainty							
5. Ci - is te sensitivity coefficient							



**11 EQUIPMENT LIST AND CALIBRATION**

Name of Equipment	Manufacturer	Type/Model	Serial Number	Cal. Due date		
				MM	DD	Year
Robot - Six Axes	Stäubli	RX90BL	N/A			N/A
Robot Remote Control	Stäubli	CS7MB	3403-91535			N/A
DASY4 Measurement Server	SPEAG	SEUMS001BA	1041			N/A
Probe Alignment Unit	SPEAG	LB (V2)	261			N/A
SAM Phantom (SAM1)	SPEAG	QD000P40CA	1185			N/A
SAM Phantom (SAM2)	SPEAG	QD000P40CA	1050			N/A
Oval Flat Phantom (ELI 4.0)	SPEAG	QD OVA001 B	1003			N/A
Electronic Probe kit	HP	85070C	N/A			N/A
S-Parameter Network Analyzer	Agilent	8753ES-6	US39173569	2	14	2008
E-Field Probe	SPEAG	EX3DV4	3554	4	24	2008
Thermometer	ERTCO	639-1S	1718	8	30	2008
Data Acquisition Electronics	SPEAG	DAE3 V1	500	11	16	2008
System Validation Dipole	SPEAG	D2450V2	706	4	27	2008
Signal Generator	R&S	SMP 04	DE34210	2	16	2009
Power Meter	Giga-tronics	8651A	8651404	4	3	2008
Power Sensor	Giga-tronics	80701A	1834588	4	17	2008
Amplifier	Mini-Circuits	ZHL-42W	D072701-5			N/A
Simulating Liquid	CCS	H2450	N/A	Within 24 hrs of first test		
Simulating Liquid	CCS	M2450	N/A	Within 24 hrs of first test		

12 PHOTOS

EUT





**13 ATTACHMENTS**

<b>No.</b>	<b>Contents</b>	<b>No. Of Pages</b>
1	System Performance Check Plots	2
2	SAR Test Plots	11
3	Certificate of E-Field Probe - EX3DV4SN3554	10
4	Certificate of System Validation Dipole - D2450 SN:706	9

**END OF REPORT**