

# **SAR Evaluation Report**

IN ACCORDANCE WITH THE REQUIREMENTS OF FCC REPORT AND ORDER: ET DOCKET 93-62, AND OET BULLETIN 65 SUPPLEMENT C

FOR

802.11b/g Compact Flash Card Installed in CN2B Handheld Scanner

Model: 2610CF

FCC ID: EHA2610CF

REPORT NUMBER: 05U3845-1C

ISSUE DATE: December 15, 2005

Prepared for Intermec Technologies Corporation 6001 36<sup>th</sup> Avenue West Everett, Washington 98203-9280 United States

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## **Revision History**

Rev.	Issued date	Revisions	Revised By
Α	November 29, 2005	Initial Issue	HS
В	November 30, 2005	Corrected typo on page 3 of 26	HS
С	December 15, 2005	Corrected some typo and added AS/NZS compliance (10g SAR)	HS

#### **CERTIFICATE OF COMPLIANCE (SAR EVALUATION)**

DATES OF TEST: November 28, 2005

APPLICANT:	Intermec Technologies Corporation
ADDRESS:	6001 36th Avenue West,Everett, Washington 98203-9280, USA
FCC ID:	EHA2610CF
MODEL:	2610CF
DEVICE CATEGORY:	Portable Device
EXPOSURE CATEGORY:	General Population/Uncontrolled Exposure

802.11b/g transceiver is Installed in CN2B Handheld Scanner, including co-location with EHABTM210 Bluetooth radio

Test Sample is a:	Production unit						
Modulation type:	Direct Sequence Spread Spectrum (DSSS) for 802.11b Orthogonal Frequency Division Multiplexing (OFDM) for 802.11g						
FCC Rule Parts	Frequency Range [MHz]	The Highest SAR Values					
47 CFR 15.247	2412 - 2462	The highest reported SAR values are: 1g - Body-worn: 0.333 W/kg; collocation: 0.442 W/kg. 10g - Body-worn: 0.154 W/kg; collocation: 0.201W/kg. 1g - Face-held: 0.035 W/kg; collocation: 0.079 W/kg. 10g - Face-held: 0.020 W/kg; collocation: 0.043 W/kg.					

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for General Population/Uncontrolled Exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC OET 65 Supplement C (Edition 01-01). And RSS-102 Issue 1 (Provisional) September 25, 1999.

And also shown to be capable of compliance for localized specific absorption rate (SAR) for General Population limits specified in the "Australian Radiation Protection and Nuclear Safety Agency (ARPANSA)" standard, and New Zealand Standard "NZS 2772: Part 1: 1999". And had been tested in accordance with the measurement procedures specified in Australian Communications Authority (ACA) standard "Radio communications (Electromagnetic Radiation-Human Exposure) Standard 2003", Schedule 2.

Note: The results documented in this report apply only to the tested sample, under the conditions and modes of operation as described herein. This document may not be altered or revised in any way unless done so by Compliance Certification Services and all revisions are duly noted in the revisions section. Any alteration of this document not carried out by Compliance Certification Services will constitute fraud and shall nullify the document. No part of this report may be used to claim product certification, approval, or endorsement by NVLAP, NIST, or any government agency.

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## 1 Equipment Under Test (EUT) Description

The EHA2610CF 802.11b/g radio can operate simultaneously with the EHABTM210 Bluetooth radio in the CN2B unit.

Normal operation:	Worn on body, held to face and hand held							
Body worn accessory:	074490 Holster with belt-clip							
Earphone/Headset Jack:	N/A							
Duty cycle:	100% for both 802.11b/g and Bluetooth							
Battery:	3.7 V Lithium Ion Battery							

#### 2 Facilities And Accreditation

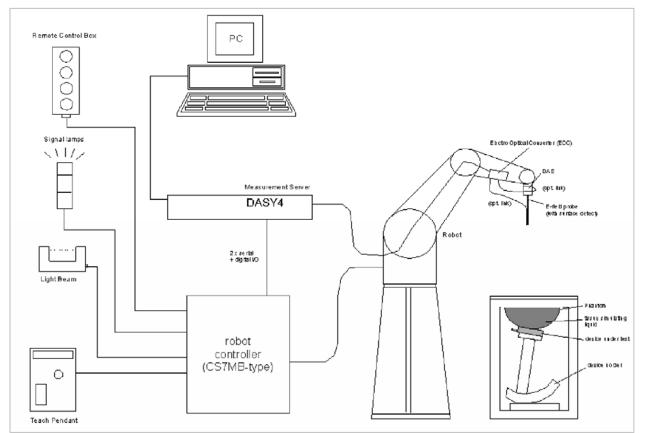
The test sites and measurement facilities used to collect data are located at 561F Monterey Road, Morgan Hill, California, USA. The sites are constructed in conformance with the requirements of ANSI C63.4, ANSI C63.7 and CISPR Publication 22. All receiving equipment conforms to CISPR Publication 16-1, "Radio Interference Measuring Apparatus and Measurement Methods."



CCS is accredited by NVLAP, Laboratory Code 200065-0. The full scope of accreditation can be viewed at http://www.ccsemc.com.

No part of this report may be used to claim product certification, approval, or endorsement by NVLAP, NIST, or any government agency.

#### 3 System Description



## The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, ADconversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows XP.
- DASY4 software.
- Remote controls with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- Validation dipole kits allowing to validate the proper functioning of the system.

#### 4 System Component

#### 4.1 DASY4 MEASUREMENT SERVER



The DASY4 measurement server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chip disk and 64MB RAM. The necessary circuits for communication with either the DAE3 electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. The PC-operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with two expansion slots which are reserved for future applications. Please note that the expansion slots do not have a standardized pinout and therefore only the expansion cards provided by SPEAG can be inserted. Expansion cards from any other supplier could seriously damage the measurement server. Calibration: No calibration required.

## 4.2 DATA ACQUISITION ELECTRONICS (DAE)

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and



probe collision detection. The input impedance of the DAE3 box is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.

## 4.3 EX3DV3 ISOTROPIC E-FIELD PROBE FOR DOSIMETRIC MEASUREMENTS

Construction:	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)
Frequency:	10 MHz to > 6 GHz; Linearity: $\pm$ 0.2 dB (30 MHz to 3 GHz)
Directivity:	± 0.3 dB in HSL (rotation around probe axis);
-	± 0.5 dB in tissue material (rotation normal to probe axis)
Dynamic Range:	10 $\mu$ W/g to > 100 mW/g; Linearity: ± 0.2 dB (noise:
	typically < 1 µW/g)
Dimensions:	Overall length: 330 mm (Tip: 20 mm)
	Tip diameter: 2.5 mm (Body: 12 mm)
	Typical distance from probe tip to dipole centers: 1 mm
Application:	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe
	which enables compliance testing for frequencies up to 6 GHz with precision of better 30%.



#### 4.4 LIGHT BEAM UNIT

The light beam switch allows automatic "tooling" of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, so that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.



## 4.5 SAM PHANTOM (V4.0)

**Construction:** The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-200X, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

Shell Thickness:2 ±0.2 mmFilling Volume:Approx. 25 litersDimensions:Height: 810mm; Length: 1000mm; Width: 500mm



#### 4.6 DEVICE HOLDER FOR SAM TWIN PHANTOM

**Construction:** In combination with the Twin SAM Phantom V4.0 or Twin SAM, the Mounting Device (made from POM) enables the rotation of the mounted transmitter in spherical coordinates, whereby the rotation point is the ear opening. The devices can be easily and accurately positioned according to IEC, IEEE, CENELEC, FCC or other specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).



## 4.7 SYSTEM VALIDATION KITS

Construction:	Symmetrical dipole with I/4 balun Enables measurement of feedpoint impedance with NWA Matched for use near flat phantoms filled with brain simulating solutions Includes distance holder and tripod adaptor.
Frequency:	450, 900, 1800, 2450, 5800 MHz
Return loss:	> 20 dB at specified validation position
Power capability:	> 100 W (f < 1GHz); > 40 W (f > 1GHz)
Dimensions:	450V2: dipole length: 270 mm; overall height: 330 mm
	D900V2: dipole length: 149 mm; overall height: 330 mm
	D1800V2: dipole length: 72 mm; overall height: 300 mm
	D835V2: dipole length: 161; overall height: 330
	D1900V2: dipole length: 68; overall height: 300
	D2450V2: dipole length: 51.5 mm; overall height: 300 mm D5GHzV2: dipole length:
	25.5 mm; overall height: 290 mm

## 4.8 COMPOSITION OF INGREDIENTS FOR TISSUE SIMULATING LIQUID

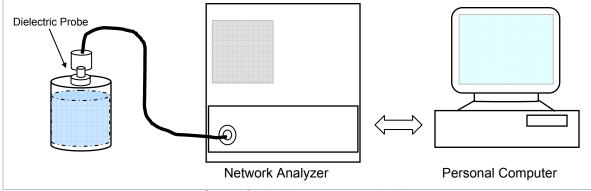
The following tissue formulations are provided for reference only as some of the parameters have not been thoroughly verified. The composition of ingredients may be modified accordingly to achieve the desired target tissue parameters required for routine SAR evaluation.

Ingredients		Frequency (MHz)									
(% by weight)	45	50	83		· 9′			1900		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body	
Water	38.56	51.16	41.45	52.4	41.05	56.0	54.9	40.4	62.7	73.2	
Salt (NaCl)	3.95	1.49	1.45	1.4	1.35	0.76	0.18	0.5	0.5	0.04	
Sugar	56.32	46.78	56.0	45.0	56.5	41.76	0.0	58.0	0.0	0.0	
HEC	0.98	0.52	1.0	1.0	1.0	1.21	0.0	1.0	0.0	0.0	
Bactericide	0.19	0.05	0.1	0.1	0.1	0.27	0.0	0.1	0.0	0.0	
Triton X-100	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	36.8	0.0	
DGBE	0.0	0.0	0.0	0.0	0.0	0.0	44.92	0.0	0.0	26.7	
Dielectric Constant	43.42	58.0	42.54	56.1	42.0	56.8	39.9	54.0	39.8	52.5	
Conductivity (S/m)	0.85	0.83	0.91	0.95	1.0	1.07	1.42	1.45	1.88	1.78	

Salt: 99+% Pure Sodium ChlorideSugar: 98+% Pure SucroseWater: De-ionized, 16 MΩ+ resistivityHEC: Hydroxyethyl CelluloseDGBE: 99+% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]Triton X-100 (ultra pure): Polyethylene glycol mono [4-(1,1,3,3-tetramethylbutyl)phenyl]ether

## 5 Simulating Liquid Parameters Check

The simulating liquids should be checked at the beginning of a series of SAR measurements to determine of the dielectric parameters are within the tolerances of the specified target values. The relative permittivity and conductivity of the tissue material should be within  $\pm$  5% of the values given in the table below.



Set-up for liquid parameters check

## Reference Values of Tissue Dielectric Parameters for Head and Body Phantom

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in IEEE Standard 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations and extrapolated according to the head parameters specified in IEEE Standard 1528.

Target Frequency (MHz)	He	ad	Bo	ody
raiget requeitcy (Mirz)	ε <sub>r</sub>	σ (S/m)	ε <sub>r</sub>	σ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800 – 2000	40.0	1.40	53.3	1.52
2450	<mark>39.2</mark>	<mark>1.80</mark>	<mark>52.7</mark>	<mark>1.95</mark>
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

( $\varepsilon_r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho$  = 1000 kg/m<sup>3</sup>)

## 5.1 SIMULATING LIQUID PARAMETER CHECK RESULT

Simulating Liquid Dielectric Parameter Check Result @ Muscle 2450 MHz

Room Ambient Temperature =23°C; Relative humidity = 34%

Measured by: Ninous Davoudi

Simulating Liquid f (MHz)  Temp. (蚓) Depth (cm)			Parameters	Target	Measured	Deviation (%)	Limit (%)	
2450	21.8	15	e"	Relative Permittivity (e'):	52.7	51.8276	-1.66	?5
2400	21.0	10	14.9235	Conductivity (σ):	1.95	2.03402	4.31	? 5
Liquid Check Ambient temperature: 23.0 deg. C; Liquid temperature: 21.8 deg C November 28, 2005 09:35 AM								
Frequency	,	e'		e"				
240000000		52.0 <sup>-</sup>	126	14.7004				
241000000	00.	51.98	353	14.7421				
24200000	00.	51.93	356	14.7858				
24300000	00.	51.9 <sup>-</sup>	124	14.8463				
24400000	00.	51.87	732	14.8596				
24500000	00.	51.82	276	14.9235				
24600000	00.	51.80	)31	14.9461				
24700000	00.	51.76	606	15.0038				
24800000	00.	51.72	289	15.0332				
24900000	00.	51.68	348	15.0871				
250000000	00.	51.64	159	15.1350				
The condu	ctivity (σ)	can be giv	en as:					
$\sigma = \omega \varepsilon_0 e''$	'= 2 π f ε <sub>0</sub>	e"						
where $f = \epsilon_0 =$	target f * 8.854 * 1	10 <sup>6</sup> 0 <sup>-12</sup>						

#### Simulating Liquid Parameter Check Result @ Head 2450 MHz

Ambient Temperature = 23°C; Relative humidity = 34%

Measured by: Ninous Davoudi

Simulating Liquid				Parameters	Target	Measured	Deviation (%)	Limit (%)	
f (MHz)	Temp. (蚓)	Depth (cm)							
2450	22	15	e"	Relative Permittivity (e'):	39.2	38.4392	-1.94	?5	
			13.7656	Conductivity (o):	1.80	1.876	4.23	? 5	
Liquid Check Ambient temperature: 23.0 deg. C; Liquid temperature: 22 deg C November 28, 2005 01:45 PM									
Frequency	/	e'		e"					
24000000		38.64	489	13.6144					
24100000		38.59							
24200000	00.	38.5	582	82 13.6762					
24300000	00.	38.53	326 13.7107						
24400000	00.	38.49	975 13.7394						
<mark>24500000</mark>	00.	38.43	392	13.7656					
24600000	00.	38.4	199	13.8010					
24700000	00.	38.3	583	13.8112					
24800000	00.	38.32	258	13.8417					
24900000	00.	38.29	908	13.8716					
25000000	00.	38.24	440	13.9092					
The condu	uctivity (σ)	can be giv	en as:						
$\sigma = \omega \varepsilon_0 e^{t}$	"= 2 π f ε <sub>0</sub>	e″							
where f ε <sub>0</sub> =	= target f * = 8.854 * 1	<sup>6</sup> 10 <sup>6</sup> 10 <sup>-12</sup>							

## 6 System Performance Check

The system performance check is performed prior to any usage of the system in order to guarantee reproducible results. The system performance check verifies that the system operates within its specifications of  $\pm 10\%$ .

#### System Performance Check Measurement Conditions

- The measurements were performed in the flat section of the SAM twin phantom filled with Body simulating liquid of the following parameters.
- The DASY4 system with an Isotropic E-Field Probe EX3DV3-SN: 3531 was used for the measurements.
- The dipole was mounted on the small tripod so that the dipole feed point was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10 mm (above 1 GHz) and 15 mm (below 1 GHz) from dipole center to the simulating liquid surface.
- The coarse grid with a grid spacing of 15 mm was aligned with the dipole. (For 5 GHz band - The coarse grid with a grid spacing of 10 mm was aligned with the dipole.)
- Special 5 x 5 x 7 fine cube was chosen for cube integration(dx=dy=7.5mm; dz=5mm). (For 5 GHz band - Special 7 x 7 x 8 fine cube was chosen for cube integration (dx=dy=4.3mm; dz=3mm))
- Distance between probe sensors and phantom surface was set to 2.5 mm.
  (For 5 GHz band Distance between probe sensors and phantom surface was set to 2.0 mm
- The dipole input power (forward power) was 250 mW±3%.
- The results are normalized to 1 W input power.

## Reference SAR Values for body-tissue

In the table below, the numerical reference SAR values of a SPEAG validation dipoles placed below the flat phantom filled with body-tissue simulating liquid are given. The reference SAR values were calculated using the finite-difference time-domain method and the geometry parameters.

Dipole Type	Distance (mm)	Frequency (MHz)	SAR (1g) [W/kg]	SAR (10g) [W/kg]	SAR (peak) [W/kg]
D450V2	15	450	5.01	3.36	7.22
D835V2	15	850	9.71	6.38	14.1
D900V2	15	900	11.1	7.17	16.3
D1450V2	10	1450	29.6	16.6	49.8
D1800V2	10	1800	38.5	20.3	67.5
D1900V2	10	1900	39.8	20.8	69.6
D2000V2	10	2000	40.9	21.2	71.5
D2450V2	10	2450	<mark>51.2</mark>	<mark>23.7</mark>	97.6

Note: All SAR values normalized to 1 W forward power.

## System Performance Check Results

## System Validation Dipole: D2450V2 SN: 748

Date: November 28, 2005

#### Ambient Temperature = $23.0^{\circ}$ C, Relative humidity = 34%

#### Measured by: Ninous Davoudi

Body Simulating Liquid			Mrasured		Target 1g	Deviation[%]	Limit [%]	
f(MHz)	Temp.[°C]	Depth [cm]	1 g	Normalized to 1 W		Deviation[%]		
			12.4	49.6	51.2	-3.13	± 10	
2450 21.8	15	1 g	Normalized to 1 W	Target 10g	Deviation[%]	Limit [%]		
			5.64	22.56	23.7	-4.81	± 10	

#### 7 SAR Measurement Procedure

A summary of the procedure follows:

- a) A measurement of the SAR value at a fixed location is used as a reference value for assessing the power drop of the EUT. The SAR at this point is measured at the start of the test, and then again at the end of the test.
- b) The SAR distribution at the exposed flat section of the flat phantom is measured at a distance of 2.5 mm from the inner surface of the shell. The area covers the entire dimension of the EUT and the horizontal grid spacing is 15 mm x 15 mm. Based on this data, the area of the maximum absorption is determined by Spline interpolation. The first Area Scan covers the entire dimension of the EUT to ensure that the hotspot was correctly identified.
- c) Around this point, a volume of X=Y=Z=30 mm is assessed by measuring 5 x 5 x 7 mm points. On the basis of this data set, the spatial peak SAR value is evaluated with the following procedure:
  - (i) The data at the surface are extrapolated, since the centre of the dipoles is 1.2 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.3 mm. The extrapolation is based on a least square algorithm. A polynomial of the fourth order is calculated through the points in z-axes. This polynomial is then used to evaluate the points between the surface and the probe tip.
  - (ii) The maximum interpolated value is searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g and 10 g) are computed using the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one-dimensional splines with the "Not a knot"- condition (in x, y and z-direction). The volume is integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) are interpolated to calculate the averages.
  - (iii) All neighbouring volumes are evaluated until no neighbouring volume with a higher average value is found.
  - (iv) The SAR value at the same location as in Step (a) is again measured to evaluate the actual power drift.

#### DASY4 SAR MEASUREMENT PROCEDURE

#### **Step 1: Power Reference Measurement**

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The Minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. The minimum distance of probe sensors to surface is 2.1 mm. This distance cannot be smaller than the Distance of sensor calibration points to probe tip as defined in the probe properties (for example, 1.2 mm for an EX3DV3 probe type).

#### Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY4 software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE Standard 1528, EN 50361 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan). If only one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of Zoom Scans has to be increased accordingly.

#### Step 3: Zoom Scan

Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The Zoom Scan measures 5 x 5 x 7 mm points within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1 g and 10 g and displays these values next to the job's label.

#### Step 4: Power drift measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the last Power Reference Measurement. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

#### Step 5: Z-Scan

The Z Scan measures points along a vertical straight line. The line runs along the Z-axis of a onedimensional grid. In order to get a reasonable extrapolation, the extrapolated distance should not be larger than the step size in Z-direction.

## 8 Procedures Used to Establish Test Signal

The client supplied a special driving program to program the EUT to continually transmit the specified maximum power.

The insertion loss of 10.2 dB (including 9.7 dB pad and 0.5 dB cable) was entered as an offset in the power meter to allow for direct reading of power.

Mode	Data rate	Channel	f (MHz)	Peak Conducted Output		
woue	(Mbps)	Channel	1 (IVII 12)	Power (dBm)	Power (mW)	
802.11b	1	1	2412	16.9	48.97	
		6	2437	16.6	45.70	
		11	2462	16.2	41.68	
802.11g	6	1	2412	17.8	60.25	
		6	2437	17.4	54.95	
		11	2462	17.2	52.48	

#### 9 SAR Test Summary

#### 9.1 BODY WORN



		Measured	Power Drift	Extrapolated	3 dB			
Channel	f (MHz)	1g (mW/g)	(dB)	1g (mW/g)	Limit (mW/g)	Limit (mW/g)		
1	2412	0.333	0.000	0.333	0.80	1.6		
6	2437	0.280	0.000	0.280	0.80	1.6		
11	2462	0.297	0.000	0.297	0.80	1.6		
1 <sup>3)</sup>	2412	0.438	-0.040	0.442	0.80	1.6		
802.11g (6 Mbps)	802.11g (6 Mbps)							
		Measured	Power Drift	Extrapolated	3 dB			
Channel	f (MHz)	1g (mW/g)	(dB)	1g (mW/g)	Limit (mW/g)	Limit (mW/g)		
1	2412							
6	2437	0.109	0.000	0.109	0.80	1.6		
11	2462							

Notes:

1) The exact method of extrapolation is measured SAR x 10<sup>(-drift/10)</sup>. The SAR reported at the end of the measurement process by the DASY4 measurement system can be scaled up by the measured drift to determine the SAR at the beginning of the measurement process.

2) The SAR measured at the middle channel for this configuration is at least 3 dB lower than SAR limit, thus testing at low & high channel is optional.

3) Co-location with Bluetooth radio FCC ID: EHABTM210

## 9.2 FACE HELD

25 mm	25 mm

#### 802.11b (1Mbps)

		Measured	Power Drift	Extrapolated	3 dB					
Channel	f (MHz)	1g (mW/g)	(dBm)	1g (mW/g)	Limit (mW/g)	Limit (mW/g)				
1	2412									
6	2437	0.035	0.000	0.035	0.80	1.6				
11	2462									
6 <sup>3)</sup>	2437	0.079	0.000	0.079	0.80	1.6				

Notes:

- 1) The exact method of extrapolation is *measured SAR x 10<sup>(-drift/10)*</sup>. The SAR reported at the end of the measurement process by the DASY4 measurement system can be scaled up by the measured drift to determine the SAR at the beginning of the measurement process.
- 2) The SAR measured at the middle channel for this configuration is at least 3 dB lower than SAR limit, thus testing at low & high channel is optional.
- 3) Co-location with Bluetooth radio FCC ID: EHABTM210

#### 10 Measurement Uncertainty

Uncortainty component		Probe	Div.	$Ci(1\sigma)$	C: (10m)	Std. Unc.(±%)	
Uncertainty component	Tol. (±%)	Dist.	Div.	Ci (1g)	Ci (10g)	Ui (1g)	Ui(10g)
Measurement System							
Probe Calibration	4.80	Ν	1	1	1	4.80	4.80
Axial Isotropy	4.70	R	1.732	0.707	0.707	1.92	1.92
Hemispherical Isotropy	9.60	R	1.732	0.707	0.707	3.92	3.92
Boundary Effects	1.00	R	1.732	1	1	0.58	0.58
Linearity	4.70	R	1.732	1	1	2.71	2.71
System Detection Limits	1.00	R	1.732	1	1	0.58	0.58
Readout Electronics	1.00	Ν	1	1	1	1.00	1.00
Response Time	0.80	R	1.732	1	1	0.46	0.46
Integration Time	2.60	R	1.732	1	1	1.50	1.50
RF Ambient Conditions - Noise	1.59	R	1.732	1	1	0.92	0.92
RF Ambient Conditions - Reflections	0.00	R	1.732	1	1	0.00	0.00
Probe Positioner Mechnical Tolerance	0.40	R	1.732	1	1	0.23	0.23
Probe Positioning With Respect to Phantom Shell	2.90	R	1.732	1	1	1.67	1.67
Extrapolation, interpolation, and integration algorithms for							
max. SAR evaluation	3.90	R	1.732	1	1	2.25	2.25
Test sample Related							
Test Sample Positioning	1.10	Ν	1	1	1	1.10	1.10
Device Holder Uncertainty	3.60	Ν	1	1	1	3.60	3.60
Power and SAR Drift Measurement	5.00	R	1.732	1	1	2.89	2.89
Phantom and Tissue Parameters							
Phantom Uncertainty	4.00	R	1.732	1	1	2.31	2.31
Liquid Conductivity - Target	5.00	R	1.732	0.64	0.43	1.85	1.24
Liquid Conductivity - Meas.	8.60	Ν	1	0.64	0.43	5.50	3.70
Liquid Permittivity - Target	5.00	R	1.732	0.6	0.49	1.73	1.41
Liquid Permittivity - Meas.	3.30	Ν	1	0.6	0.49	1.98	1.62
Combined Standard Uncertainty			RSS			11.44	10.49
Expanded Uncertainty (95% Confidence Interval)			K=2			22.87	20.98
Notesfor table							
1. Tol tolerance in influence quaitity							
2. N - Nomal							
3 R - Rectangular							

3. R - Rectangular

4. Div. - Divisor used to obtain standard uncertainty

5. Ci - is te sensitivity coefficient

# 11 Equipment List

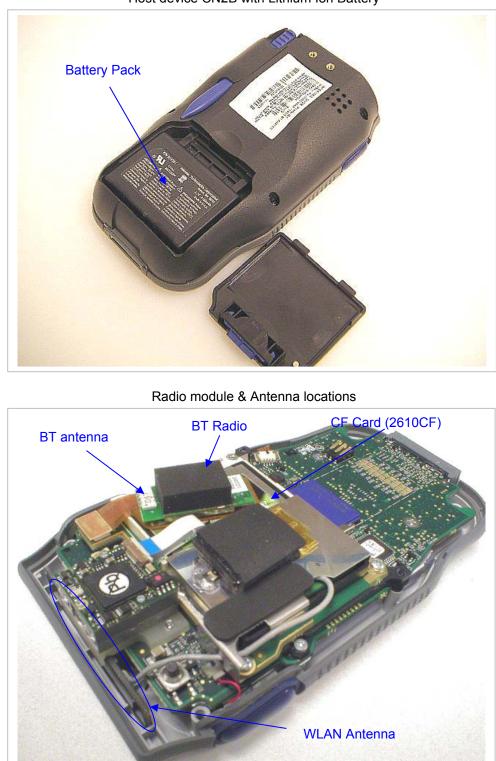
Name of Equipment	Manufacturer	Type/Model	Serial Number	Cal. Due date
Robot - Six Axes	Stäubli	RX90BL	N/A	N/A
Robot Remote Control	Stäubli	CS7MB	3403-91535	N/A
DASY4 Measurement Server	SPEAG	SEUMS001B	A1041	N/A
Probe Alignment Unit	SPEAG	LB (V2)	261	N/A
S-Parameter Network Analyzer	Agilent	8753ES-6	US39173569	2/9/07
Electronic Probe kit	Hewlett Packard	85070C	N/A	N/A
E-Field Probe	SPEAG	EX3DV3	3531	7/21/06
SAM Phantom (SAM1)	SPEAG	TP-1185	QD000P40CA	N/A
SAM Phantom (SAM2)	SPEAG	TP-1015	N/A	N/A
Data Acquisition Electronics	SPEAG	DAE3 V1	500	2/7/06
System Validation Dipole	SPEAG	D2450V2	748	5/14/06
Signal General	R&H	SMP 04	DE34210	6/2/06
Power Meter	Giga-tronics	8651A	8651404	12/27/06
Power Sensor	Giga-tronics	80701A	1834588	12/27/07
Amplifier	Mini-Circuits	ZVE-8G	0360	N/A
Amplifier	Mini-Circuits	ZHL-42W	D072701-5	N/A
Radio Communication Tester	Rohde & Schwa	rz CMU 200	838114/032	12/17/06
Simulating Liquid	CCS	H2450	N/A	Within 24 hrs of first test
Simulating Liquid	CCS	M2450	N/A	Within 24 hrs of first test

## 12 Photo





074490 Holster with host device CN2B



802.11b/g Compact Flash Card (2610CF)





#### 13 Attachment

No.	Contents	No. of page (s)
1	System Performance Check Plot	2
2	SAR Test Plot	10
3	Certificate of E-filed Probe EX3DV4 SN 3531	10
4	Certificate of System Validation Dipole D2450V2 SN 748	9

END OF REPORT