Accredited testing laboratory

DAR registration number: DAT-P-176/94-D1

Federal Motor Transport Authority (KBA)
DAR registration number: KBA-P 00070-97

Test report no. : 4-2089-01-03/06-A
Type identification: BW900 HS
Test specification : EN 50360 (07-2001)

Table of Contents

1 General Information

1.1 Notes

The test results of this test report relate exclusively to the test item specified in 1.5. The CETECOM ICT Services GmbH does not assume responsibility for any conclusions and generalisations drawn from the test results with regard to other specimens or samples of the type of the equipment represented by the test item. The test report may only be reproduced or published in full. Reproduction or publication of extracts from the report requires the prior written approval of the CETECOM ICT Services GmbH.

1.1.1 Statement of Compliance

The SAR values found for the BW900 HS Bluetooth headset are below the maximum recommended levels of 2 W/Kg as averaged over any 10 g tissue according to the EN standards listed in chapter 1.6. The measurement together with the test system set-up is described in chapter 2.3 of this test report. A detailed description of the equipment under test can be found in chapter 1.5.

Test engineer:

2006-05-22	**Oleksandr Hnatovskiy**	
Date	Name	Signature

Technical responsibility for area of testing:

2006-05-22	**Fabien Coulet**	
Date	Name	Signature

1.2 Testing laboratory

CETECOM ICT Services GmbH
Untertuerkheimer Straße 6-10,
66117 Saarbruecken
Germany
Telephone: + 49 681 598 - 0
Fax: + 49 681 598 - 8475

e-mail: info@ict.cetecom.de
Internet: http://www.cetecom-ict.de

State of accreditation: The Test laboratory (area of testing) is accredited according to DIN EN ISO/IEC 17025. DAR registration number: DAT-P-176/94-D1

Test location, if different from CETECOM ICT Services GmbH

Name: ---
Street: ---
Town: ---
Country: ---
Phone: ---
Fax: ---

1.3 Details of applicant

Name: Sennheiser Communications A/S

Street: 6 Langager
Town: 2680 Solrod Strand
Country: Denmark

Contact: Mr. Stefan Heise
Telephone: (+45) 56 18 00 27

1.4 Application details

Date of receipt of application:	2005-06-22
Date of receipt of test item:	2006-05-09
Start/Date of test:	2006-05-09
End of test:	2006-05-09
Person(s) present during the test:	Mr. Per Hillersborg

1.5 Test item

Description of the test item:	Bluetooth headset
Type identification:	BW900 HS
Serial number:	235
Manufacturer:	
Name:	Sennheiser Communications A/S
Street:	6 Langager
Town:	2680 Solrod Strand
Country:	Denmark

additional information on the DUT:

additional information on the DUT:	
device type :	Bluetooth headset
device category :	portable device
BD Address:	0004ABDCAFE
test device production information:	identical prototype
exposure category:	uncontrolled environment / general population
device operating configurations :	
operating mode(s):	Bluetooth
modulation:	GFSK
spread spectrum:	FHSS
operating frequency range:	2402 MHz (channel 0) - 2472 MHz (channel 70)
power class	1 (100 mW; 20 dBm)
antenna type:	External antenna

1.6 Test specification(s)

- EN 50360 (07-2001)

Product standard to demonstrate the compliance of mobile phones with the basic restrictions related to human exposure to electromagnetic fields (300 MHz - 3 GHz)

-EN 50361 (07-2001)

Basic standard for the measurement of SAR related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz)

- European Council Recommendation 1999/519/EEC (07-1999)

Council Recommendation 1999/519/EEC of 12 July 1999 on the limitation of exposure of the general public to electromagnetic fields (0 Hz to 300 GHz) (Official Journal L 197 of 30 July 1999)

1.6.1 RF exposure limits (according to ECR 1999/519/EC)

Human Exposure	Basic restrictions for electric, magnetic and electromagnetic fields
Spatial Peak SAR* (Head and Trunk)	**2.00 mW/g**
Spatial Average SAR** (Whole Body)	0.08 mW/g
Spatial Peak SAR*** (Limbs)	4.00 mW/g

Table 1: RF exposure limits

The limit applied in this test report is shown in **bold** letters

Notes:

* The Spatial Peak value of the SAR averaged over any 10 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time

** The Spatial Average value of the SAR averaged over the whole body.

*** The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

2 Technical test

2.1 Summary of test results

No deviations from the technical specification(s) were ascertained in the course of the tests performed.	☒
The deviations as specified in 2.5 were ascertained in the course of the tests performed.	☐

2.2 Test environment

General Environment conditions in the test area are as follows:

Ambient temperature:	20°C – 24°C
Tissue simulating liquid:	20°C – 24°C
Humidity:	40% – 50%

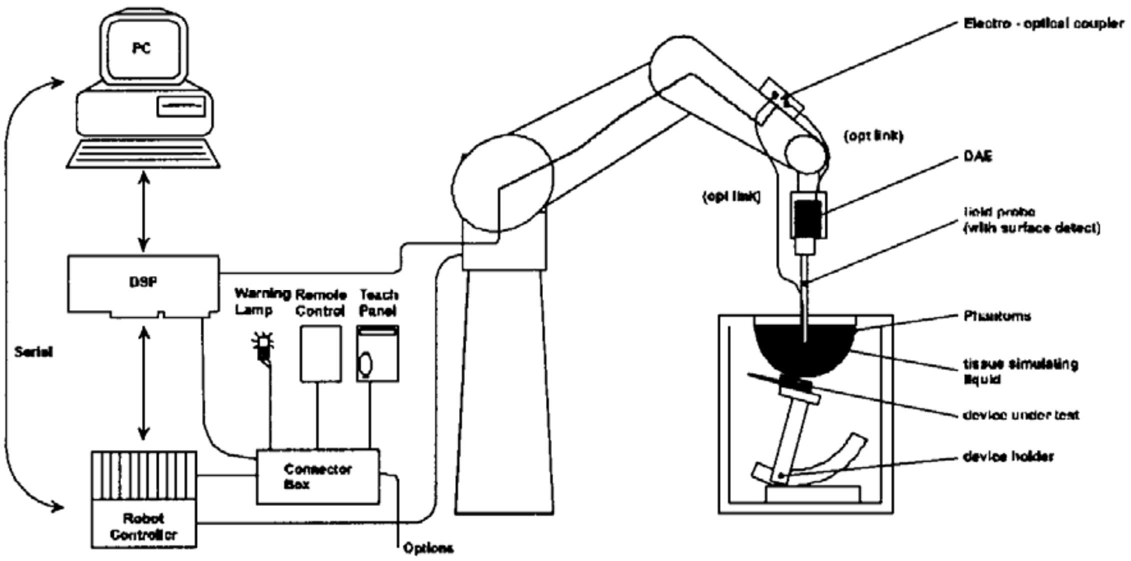
2.3 Measurement and test set-up

The measurement system is described in chapter 2.4.

A description of positioning and test signal control can be found in chapter 2.5 together with the test results.

2.4 Measurement system

2.4.1 System Description



The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).

- A dosimetric probe, i.e. an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.

- A data acquisition electronic (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- A unit to operate the optical surface detector which is connected to the EOC.
- The Electro-Optical Coupler (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the DASY4 measurement server.
- The DASY4 measurement server, which performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. A computer operating Windows 2000
- DASY4 software and SEMCAD data evaluation software.
- Remote control with teach panel and additional circuitry for robot safety such as warning lamps, etc.
- The generic twin phantom enabling the testing of left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- System validation dipoles allowing to validate the proper functioning of the system.

2.4.2 Test environment

The DASY4 measurement system is placed at the head end of a room with dimensions:
5 x 2.5 x 3 m³, the SAM phantom is placed in a distance of 75 cm from the side walls and 1.1m from the rear wall. Above the test system a 1.5 x 1.5 m² array of pyramid absorbers is installed to reduce reflections from the ceiling.
Picture 1 of the photo documentation shows a complete view of the test environment.
The system allows the measurement of SAR values larger than 0.005 mW/g.

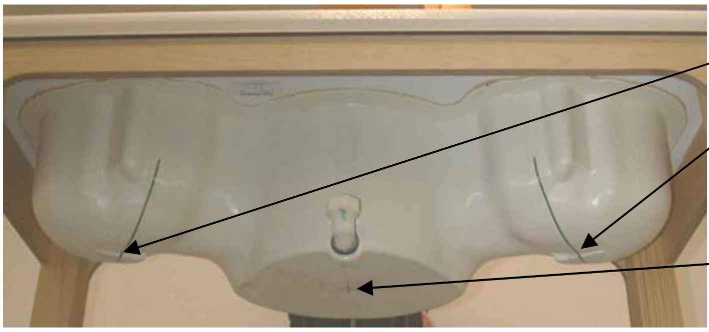
2.4.3 Probe description

Isotropic E-Field Probe ET3DV6 for Dosimetric Measurements

Technical data according to manufacturer information	
Construction	Symmetrical design with triangular core Built-in optical fiber for surface detection system Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycolether)
Calibration	In air from 10 MHz to 2.5 GHz In head tissue simulating liquid (HSL) at 900 (800-1000) MHz and 1.8 GHz (1700-1910 MHz) (accuracy ± 9.5%; k=2) Calibration for other liquids and frequencies upon request
Frequency	10 MHz to 3 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 3 GHz)
Directivity	± 0.2 dB in HSL (rotation around probe axis) ± 0.4 dB in HSL (rotation normal to probe axis)
Dynamic range	5 µW/g to > 100 mW/g; Linearity: ± 0.2 dB
Optical Surface Detection	± 0.2 mm repeatability in air and clear liquids over diffuse reflecting surfaces (ET3DV6 only)
Dimensions	Overall length: 330 mm Tip length: 16 mm Body diameter: 12 mm Tip diameter: 6.8 mm Distance from probe tip to dipole centers: 2.7 mm
Application	General dosimetry up to 3 GHz Compliance tests of mobile phones Fast automatic scanning in arbitrary phantoms (ET3DV6)

2.4.4 Phantom description

The used SAM Phantom meets the requirements specified in Edition 01-01 of Supplement C to OET Bulletin 65 for Specific Absorption Rate (SAR) measurements.
The phantom consists of a fibreglass shell integrated in a wooden table. It allows left-hand and right-hand head as well as body-worn measurements with a maximum liquid depth of 18 mm in head position and 22 mm in planar position (body measurements). The thickness of the Phantom shell is 2 mm +/- 0.1 mm.



2.4.5 Device holder description

The DASY4 device holder has two scales for device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The plane between the ear openings and the mouth tip has a rotation angle of 65°. The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. This device holder is used for standard mobile phones or PDA's only. If necessary an additional support of polystyrene material is used.

Larger DUT's (e.g. notebooks) cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values .
Therefore those devices are normally only tested at the flat part of the SAM.

2.4.6 Scanning procedure

The DASY4 installation includes predefined files with recommended procedures for measurements and validation. They are read-only document files and destined as fully defined but unmeasured masks. All test positions (head or body-worn) are tested with the same configuration of test steps differing only in the grid definition for the different test positions.

- The „reference“ and „drift“ measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the DUT’s output power and should vary max. +/- 5 %.

- The „surface check“ measurement tests the optical surface detection system of the DASY4 system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above ± 0.1mm). To prevent wrong results tests are only executed when the liquid is free of air bubbles. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within ± 30°.)

- The „area scan“ measures the SAR above the DUT or verification dipole on a parallel plane to the surface. It is used to locate the approximate location of the peak SAR with 2D spline interpolation. The robot performs a stepped movement along one grid axis while the local electrical field strenth is measured by the probe. The probe is touching the surface of the SAM during acquisition of measurement values. The standard scan uses large grid spacing for faster measurement. Standard grid spacing for head measurements is 15 mm in x- and y- dimension. If a finer resolution is needed, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result. For special applications where the standard scan method does not find the peak SAR within the grid, e.g. mobile phones with flip cover, the grid can be adapted in orientation.
  Results of this coarse scan are shown in annex 2.

- A „7x7x7 zoom scan” measures the field in a volume around the 2D peak SAR value acquired in the previous „coarse“ scan. This is a fine 7x7 grid where the robot additionally moves the probe in 7 steps along the z-axis away from the bottom of the Phantom. Grid spacing for the cube measurement is 5 mm in x and y-direction and 5 mm in z-direction. DASY4 is also able to perform repeated zoom scans if more than 1 peak is found during area scan. Test results relevant for the specified standard (see chapter 1.6.) are shown in table form in chapter 2.5.

2.4.7 Spatial Peak SAR Evaluation

The spatial peak SAR - value for 1 and 10 g is evaluated after the Cube measurements have been done. The basis of the evaluation are the SAR values measured at the points of the fine cube grid consisting of 7 x 7 x 7 points. The algorithm that finds the maximal averaged volume is separated into three different stages.

- The data between the dipole center of the probe and the surface of the phantom are extrapolated. This data cannot be measured since the center of the dipole is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is about 1 mm (see probe calibration sheet). The extrapolated data from a cube measurement can be visualized by selecting 'Graph Evaluated'.

- The maximum interpolated value is searched with a straight-forward algorithm. Around this maximum the SAR - values averaged over the spatial volumes (1g or 10 g) are computed using the 3d-spline interpolation algorithm. If the volume cannot be evaluated (i.e., if a part of the grid was cut off by the boundary of the measurement area) the evaluation will be started on the corners of the bottom plane of the cube.

- All neighboring volumes are evaluated until no neighboring volume with a higher average value is found.

Extrapolation

The extrapolation is based on a least square algorithm [W. Gander, Computermathematik, p.168-180]. Through the points in the first 3 cm along the z-axis, polynomials of order four are calculated. These polynomials are then used to evaluate the points between the surface and the probe tip. The points, calculated from the surface, have a distance of 1 mm from each other.

Interpolation

The interpolation of the points is done with a 3d-Spline. The 3d-Spline is composed of three one-dimensional splines with the "Not a knot"-condition [W. Gander, Computermathematik, p.141-150] (x, y and z -direction) [Numerical Recipes in C, Second Edition, p.123ff].

Volume Averaging

At First the size of the cube is calculated. Then the volume is integrated with the trapezoidal algorithm. 8000 points (20x20x20) are interpolated to calculate the average.

Advanced Extrapolation

DASY4 uses the advanced extrapolation option which is able to compansate boundary effects on E-field probes.

2.4.8 Data Storage and Evaluation

Data Storage

The DASY4 software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension ".DA4". The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm²], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation by SEMCAD

The SEMCAD software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	$Norm_i$, a_{i0}, a_{i1}, a_{i2}
	- Conversion factor	$ConvF_i$
	- Diode compression point	Dcpi
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY4 components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics.

If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot cf/dcp_i$$

with	V_i	= compensated signal of channel i	(i = x, y, z)
	U_i	= input signal of channel i	(i = x, y, z)
	cf	= crest factor of exciting field	(DASY parameter)
	dcp_i	= diode compression point	(DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: $$E_i = (V_i / Norm_i \cdot ConvF)^{1/2}$$

H-field probes: $$H_i = (V_i)^{1/2} \cdot (a_{i0} + a_{i1}f + a_{i2}f^2)/f$$

with	V_i	= compensated signal of channel i	(i = x, y, z)
	$Norm_i$	= sensor sensitivity of channel i [mV/(V/m)^2] for E-field Probes	(i = x, y, z)
	ConvF	= sensitivity enhancement in solution	
	a_{ij}	= sensor sensitivity factors for H-field probes	
	f	= carrier frequency [GHz]	
	E_i	= electric field strength of channel i in V/m	
	H_i	= magnetic field strength of channel i in A/m	

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = (E_x^2 + E_Y^2 + E_z^2)^{1/2}$$

The primary field data are used to calculate the derived field units.

$$SAR = (E_{tot}^2 \cdot \sigma) / (\rho \cdot 1000)$$

with	SAR	= local specific absorption rate in mW/g
	E_{tot}	= total field strength in V/m
	σ	= conductivity in [mho/m] or [Siemens/m]
	ρ	= equivalent tissue density in g/cm^3

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid. The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = E_{tot}^2 / 3770 \quad \text{or} \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

with	P_{pwe}	= equivalent power density of a plane wave in mW/cm^2
	E_{tot}	= total electric field strength in V/m
	H_{tot}	= total magnetic field strength in A/m

2.4.9 Test equipment utilized

This table gives a complete overview of the SAR measurement equipment

Devices used during the test described in chapter 2.5. are marked ☒

	Manufacturer	Device	Type	Serial number	Date of last calibration
☒	Schmid & Partner Engineering AG	Dosimetric E-Field Probe	ET3DV6	1558	September 6, 2005
☐	Schmid & Partner Engineering AG	Dosimetric E-Field Probe	ET3DV6	1559	January 19, 2006
☐	Schmid & Partner Engineering AG	900 MHz System Validation Dipole	D900V2	102	August 31, 2005
☐	Schmid & Partner Engineering AG	1800 MHz System Validation Dipole	D1800V2	287	September 1, 2005
☐	Schmid & Partner Engineering AG	1900 MHz System Validation Dipole	D1900V2	5d009	August 30, 2005
☒	Schmid & Partner Engineering AG	2450 MHz System Validation Dipole	D2450V2	710	August 23, 2005
☒	Schmid & Partner Engineering AG	Data acquisition electronics	DAE3V1	413	January 12, 2006
☒	Schmid & Partner Engineering AG	Software	DASY 4 V4.5	---	N/A
☒	Schmid & Partner Engineering AG	Phantom	SAM	---	N/A
☒	Rohde & Schwarz	Universal Radio Communication Tester	CMU 200	832221/0055	January 12, 2006
☐	Agilent)*	Network Analyser 300 kHz to 3 GHz	8753C	2936A00872	July 15, 2004
☐	Agilent)*	Dielectric Probe Kit	85070C	US99360146	N/A
☐	Agilent	Peak Power Analyzer	8990A	3128A00169	August 23, 2005
☐	Agilent	Peak Power Sensor	84813A	3125A00111	August 25, 2005
☒	Agilent	Signal Generator	8665A	2833A00112	November 08, 2005
☒	Amplifier Reasearch	Amplifier	25S1G4 (25 Watt)	20452	N/A
☒	Agilent	Power Meter	438A	2804U01006	February 4, 2006
☒	Agilent	Power Meter Sensor	8482A	2703A03025	February 4, 2006

)* : Network analyzer probe calibration against air, destilled water and a 50 Ohm resistor performed before measuring liquid parameters.

2.4.10 Tissue simulating liquids: dielectric properties

The following materials are used for producing the tissue-equivalent materials.

(liquids used for tests described in chapter 2.5. are marked with ☒) :

Ingredients (% of weight)	**Frequency (MHz)**					
frequency band	☐ 450	☐ 835	☐ 900	☐ 1800	☐ 1900	☒ 2450
Tissue Type	Head	Head	Head	Head	Head	Head
Water	38.56	41.45	40.92	52.64	54.9	62.7
Salt (NaCl)	3.95	1.45	1.48	0.36	0.18	0.5
Sugar	56.32	56.0	56.5	0.0	0.0	0.0
HEC	0.98	1.0	1.0	0.0	0.0	0.0
Bactericide	0.19	0.1	0.1	0.0	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	36.8
DGBE	0.0	0.0	0.0	47.0	44.92	0.0

Table 2: Head tissue dielectric properties

Salt: 99+% Pure Sodium Chloride
Sugar: 98+% Pure Sucrose
Water: De-ionized, 16MΩ+ resistivity
HEC: Hydroxyethyl Cellulose
DGBE: 99+% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]
Triton X-100(ultra pure): Polyethylene glycol mono [4-(1,1,3,3-tetramethylbutyl)phenyl]ether

2.4.11 Tissue simulating liquids: parameters

Used Target Frequency	**Target Head Tissue**		**Measured Head Tissue**		**Measured Date**
[MHz]	Permittivity	Conductivity [S/m]	Permittivity	Conductivity [S/m]	
2450	39.0	1.84	37.6	1.92	2006-05-09

Table 3: Parameter of the head tissue simulating liquid

Note: The dielectric properties have been measured using the contact probe method at 22°C.

2.4.12 Measurement uncertainty evaluation for SAR test

The overall combined measurement uncertainty of the measurement system is ± 10,3% (K=1).
The expanded uncertainty(k=2) is assessed to be ± 20.6%
This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

Error Sources	Uncertainty Value	Probability Distribution	Divi-sor	c_i 1g	c_i 10g	Standard Uncertainty 1g	Standard Uncertainty 10g	v_i^2 or v_{eff}
Measurement System								
Probe calibration	± 4.8%	Normal	1	1	1	± 4.8%	± 4.8%	∞
Axial isotropy	± 4.7%	Rectangular	√3	0.7	0.7	± 1.9%	± 1.9%	∞
Hemispherical isotropy	± 9.6%	Rectangular	√3	0.7	0.7	± 3.9%	± 3.9%	∞
Spatial resolution	± 0.0%	Rectangular	√3	1	1	± 0.0%	± 0.0%	∞
Boundary effects	± 1.0%	Rectangular	√3	1	1	± 0.6%	± 0.6%	∞
Probe linearity	± 4.7%	Rectangular	√3	1	1	± 2.7%	± 2.7%	∞
System detection limits	± 1.0%	Rectangular	√3	1	1	± 0.6%	± 0.6%	∞
Readout electronics	± 1.0%	Normal	1	1	1	± 1.0%	± 1.0%	∞
Response time	± 0.8%	Rectangular	√3	1	1	± 0.5%	± 0.5%	∞
Integration time	± 2.6%	Rectangular	√3	1	1	± 1.5%	± 1.5%	∞
RF ambient conditions	± 3.0%	Rectangular	√3	1	1	± 1.7%	± 1.7%	∞
Probe positioner	± 0.4%	Rectangular	√3	1	1	± 0.2%	± 0.2%	∞
Probe positioning	± 2.9%	Rectangular	√3	1	1	± 1.7%	± 1.7%	∞
Max. SAR evaluation	± 1.0%	Rectangular	√3	1	1	± 0.6%	± 0.6%	∞
Test Sample Related								
Device positioning	± 2.9%	Normal	1	1	1	± 2.9%	± 2.9%	145
Device holder uncertainty	± 3.6%	Normal	1	1	1	± 3.6%	± 3.6%	5
Power drift	± 5.0%	Rectangular	√3	1	1	± 2.9%	± 2.9%	∞
Phantom and Set-up								
Phantom uncertainty	± 4.0%	Rectangular	√3	1	1	± 2.3%	± 2.3%	∞
Liquid conductivity (target)	± 5.0%	Rectangular	√3	0.64	0.43	± 1.8%	± 1.2%	∞
Liquid conductivity (meas.)	± 2.5%	Normal	1	0.64	0.43	± 1.6%	± 1.1%	∞
Liquid permittivity (target)	± 5.0%	Rectangular	√3	0.6	0.49	± 1.7%	± 1.4%	∞
Liquid permittivity (meas.)	± 2.5%	Normal	1	0.6	0.49	± 1.5%	± 1.2%	∞
Combined Uncertainty						± 10.3%	± 10.0%	330
Expanded Std. Uncertainty						**± 20.6%**	**± 20.1%**	

Table 4: Measurement uncertainties

2.4.13 Measurement uncertainty evaluation for system validation

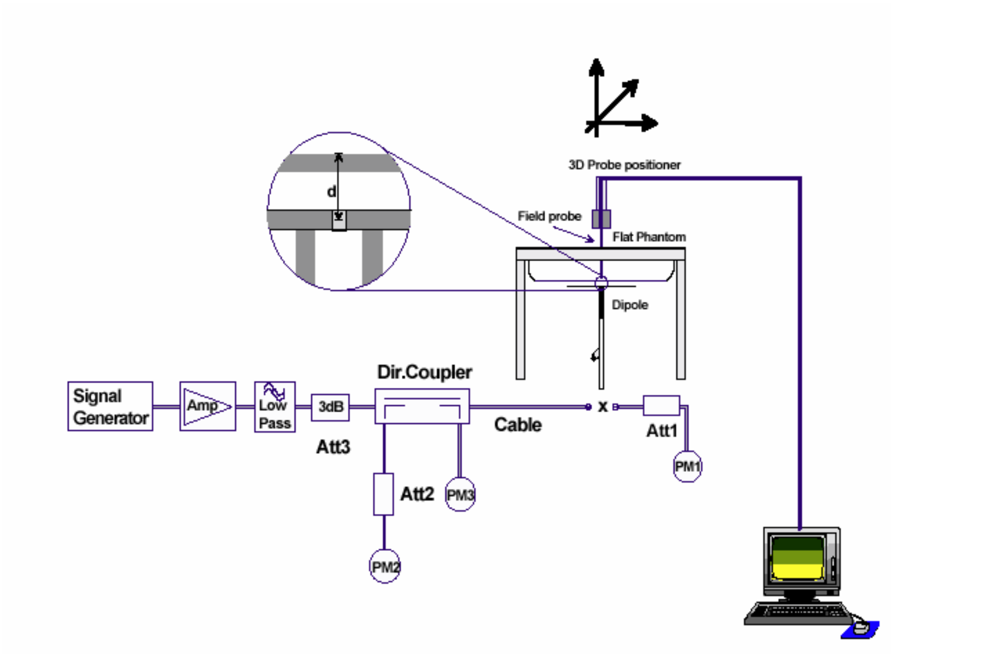
The overall combined measurement uncertainty of the measurement system is ± 8.4% (K=1).
The expanded uncertainty(k=2) is assessed to be ± 16.8%
This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

Error Sources	Uncertainty Value	Probability Distribution	Divi-sor	c_i 1g	c_i 10g	Standard Uncertainty 1g	Standard Uncertainty 10g	v_i^2 or v_{eff}
Measurement System								
Probe calibration	± 4.8%	Normal	1	1	1	± 4.8%	± 4.8%	∞
Axial isotropy	± 4.7%	Rectangular	√3	0.7	0.7	± 1.9%	± 1.9%	∞
Hemispherical isotropy	± 0.0%	Rectangular	√3	0.7	0.7	± 0.0%	± 3.9%	∞
Boundary effects	± 1.0%	Rectangular	√3	1	1	± 0.6%	± 0.6%	∞
Probe linearity	± 4.7%	Rectangular	√3	1	1	± 2.7%	± 2.7%	∞
System detection limits	± 1.0%	Rectangular	√3	1	1	± 0.6%	± 0.6%	∞
Readout electronics	± 1.0%	Normal	1	1	1	± 1.0%	± 1.0%	∞
Response time	± 0.0%	Rectangular	√3	1	1	± 0.0%	± 0.0%	∞
Integration time	± 0.0%	Rectangular	√3	1	1	± 0.0%	± 0.0%	∞
RF ambient conditions	± 3.0%	Rectangular	√3	1	1	± 1.7%	± 1.7%	∞
Probe positioner	± 0.4%	Rectangular	√3	1	1	± 0.2%	± 0.2%	∞
Probe positioning	± 2.9%	Rectangular	√3	1	1	± 1.7%	± 1.7%	∞
Max. SAR evaluation	± 1.0%	Rectangular	√3	1	1	± 0.6%	± 0.6%	∞
Test Sample Related								
Dipole axis to liquid distance	± 2.0%	Normal	1	1	1	± 1.2%	± 1.2%	∞
Power drift	± 4.7%	Rectangular	√3	1	1	± 2.7%	± 2.7%	∞
Phantom and Set-up								
Phantom uncertainty	± 4.0%	Rectangular	√3	1	1	± 2.3%	± 2.3%	∞
Liquid conductivity (target)	± 5.0%	Rectangular	√3	0.64	0.43	± 1.8%	± 1.2%	∞
Liquid conductivity (meas.)	± 2.5%	Normal	1	0.64	0.43	± 1.6%	± 1.1%	∞
Liquid permittivity (target)	± 5.0%	Rectangular	√3	0.6	0.49	± 1.7%	± 1.4%	∞
Liquid permittivity (meas.)	± 2.5%	Normal	1	0.6	0.49	± 1.5%	± 1.2%	∞
Combined Uncertainty						**± 8.4%**	**± 8.1%**	
Expanded Std. Uncertainty						**± 16.8%**	**± 16.2%**	

Table 5: Measurement uncertainties

2.4.14 System validation

System validation is performed by using a validation dipole which is positioned parallel to the planar part of the SAM phantom at the reference point. The distance of the dipole to the SAM phantom is determined by a plexiglass spacer. The dipole is connected to the signal source consisting of signal generator and amplifier via a directional coupler, N-connector cable and adaption to SMA. It is fed with a power of 1000 mW. To adjust this power a power meter is used. The power sensor is connected to the cable before the validation to measure the power at this point and do adjustments at the signal generator. At the outputs of the directional coupler both return loss as well as forward power are controlled during the validation to make sure that emitted power at the dipole is kept constant. This can also be checked by the power drift measurement after the test.
Validation results have to be equal or near the values determined during dipole calibration with the relevant liquids and test system (+/- 10 %).
System validation is performed regularly on all frequency bands where tests are performed with the DASY 4 system. Results are stored to have a long time overview of system performance and are shown in EN test reports at request.



2.5 Test results (Head SAR)

The table contains the measured SAR values averaged over a mass of 10 g				
Channel / frequency	Position	Left hand position	Right hand position	Limit
39 / 2441 MHz	cheek	0.146 W/kg	0.221 W/kg	2 W/kg
0 / 2402 MHz	cheek	not necessary	0.220 W/kg	2 W/kg
78 / 2482 MHz	cheek	not necessary	0.221 W/kg	2 W/kg

Table 6: Test results (Head SAR)

Note: Upper and lower frequencies were measured at the worst position.

2.5.1 General description of test procedures

The DUT is tested using a CMU 200 communications tester as controller unit to set test channels and maximum output power to the DUT, as well as for measuring the conducted peak power.
Test positions as described in the tables above are in accordance with the specified test standard.
Tests in head position are performed in voice mode with:

Slave Sig.1:	
Test mode Type:	Loopback Tests
Hopping Scheme:	RX/TX single freq.
Pattern Type:	Static PRBS
Packet Type:	DH1
Len. Test Seq.:	27 byte

(see chapter 1.5 for details).
Conducted output power was measured using an integrated RF connector and attached RF cable.

Annex 1 Measurement results (printout from DASY ™)

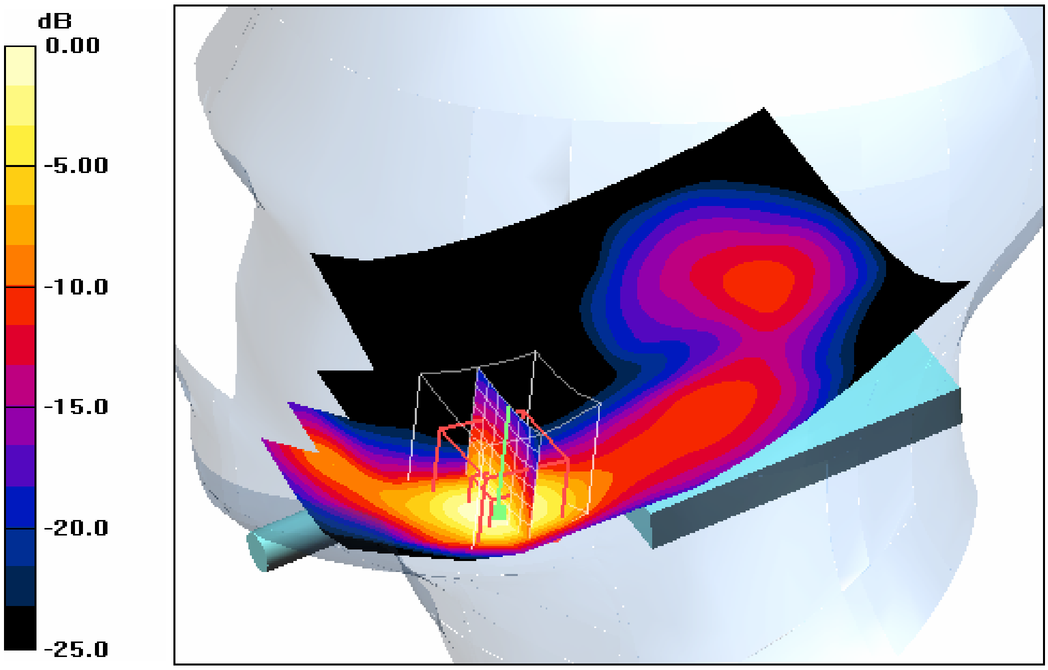
Date/Time: 2006-05-09 15:37:25Date/Time: 2006-05-09 15:56:57

2.5.2 P1528_OET65_EN50361-RightHandSide-BT-headset

DUT: Sennheiser; Type: BW900 HS; Serial: 235
Communication System: Bluetooth; Frequency: 2441 MHz; Duty Cycle: 1:3.42
Medium: HSL2450 Medium parameters used: f = 2441 MHz; σ = 1.92 mho/m; ε_r = 37.6; ρ = 1000 kg/m^3
Phantom section: Right Section
DASY4 Configuration:
- Probe: ET3DV6 - SN1558; ConvF(4.34, 4.34, 4.34); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Touch position - Middle/Area Scan (71x111x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 0.630 mW/g

Touch position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 15.2 V/m; Power Drift = 0.194 dB
Peak SAR (extrapolated) = 1.30 W/kg
SAR(1 g) = 0.540 mW/g; SAR(10 g) = 0.221 mW/g
Maximum value of SAR (measured) = 0.634 mW/g



0 dB = 0.634mW/g

Additional information:
position or distance of DUT to SAM (if not standard head positions) :
ambient temperature: 22.7°C; liquid temperature: 21.5°C

Annex 2 Photo documentation

Picture no. 1

Measurement System DASY 4

Picture no. 2

DUT - top view

Picture no. 3

DUT - side view

Picture no. 4

Test position left hand side touched

Picture no. 5

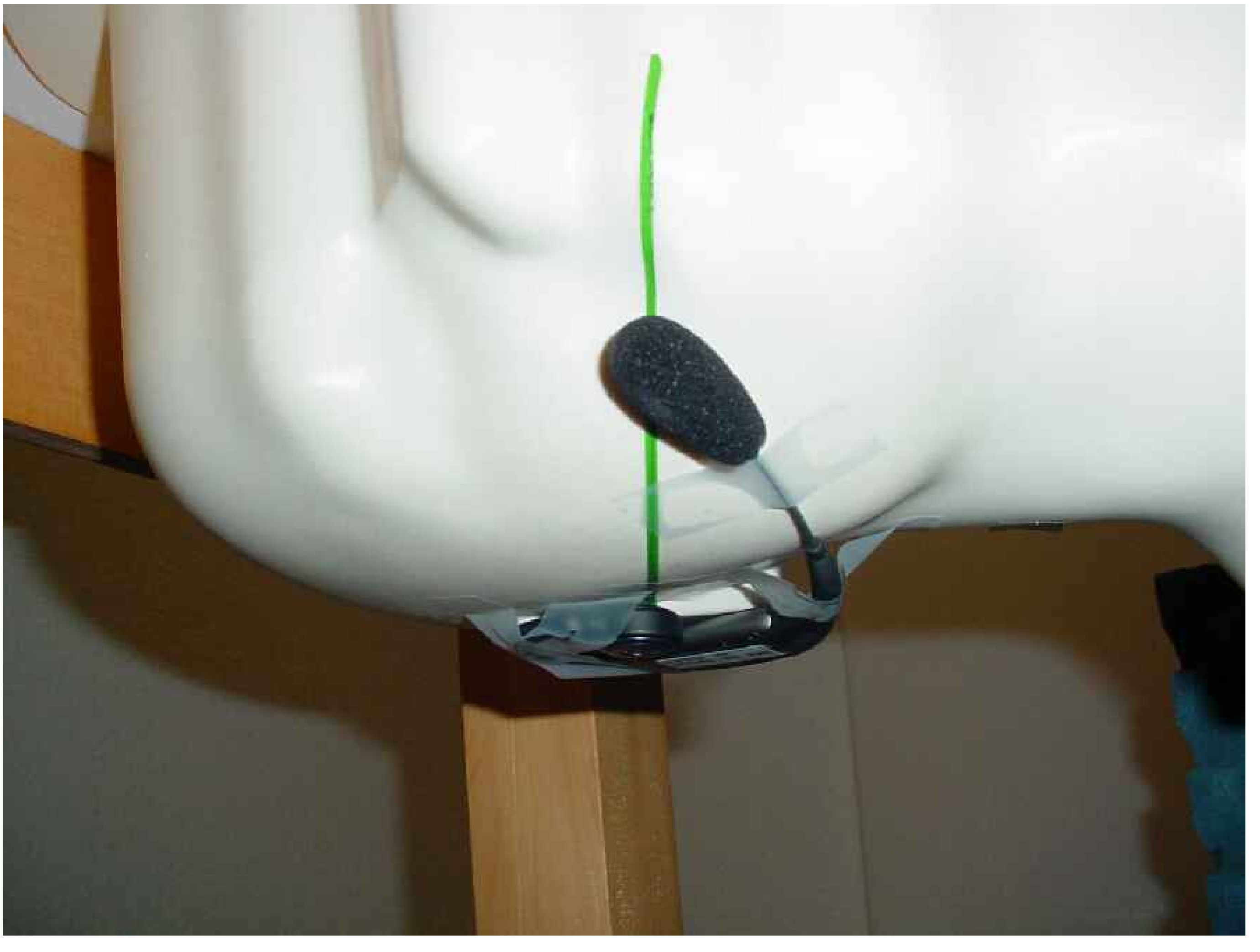
Test position left hand side touched

Picture no. 6

Test position left hand side touched

Picture no. 7

Test position right hand side touched



Picture no. 8

Test position right hand side touched

Picture no. 9

Test position right hand side touched

Picture no. 10

Bluetooth signal duty cycle