




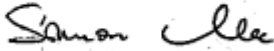
# SAR EVALUATION REPORT

For

## Lectrosonics Inc.

581 Laser Road NE  
Rio Rancho, NM 87124, USA

**FCC ID: DBZSMWBA1**

<b>Report Type:</b> Original Report	<b>Product Type:</b> Wireless Microphone Transmitter
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<b>Report Number:</b> R1704196-SAR	
<b>Report Date:</b> 2017-08-11	
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Note: This test report is prepared for the customer shown above and for the device described herein. It may not be duplicated or used in part without prior written consent from Bay Area Compliance Laboratories Corp. This report must not be used by the customer to claim product certification, approval, or endorsement by A2LA\* or any agency of the Federal Government. \* This report may contain data that are not covered by the A2LA accreditation and are marked with an asterisk "\*" (Rev. 3)

<b>Summary of Test Results</b>			
Rule Part(s):	FCC §2.1093		
Test Procedure(s):	IEEE 1528: 2013, KDB 447498, IEC 62209-2:2010		
Device Category: Exposure Category:	Portable Device General Population/Uncontrolled Exposure		
Device Type:	Portable Device		
Modulation Type:	FM		
Frequency Range:	470.1-537.575 MHz		
Maximum Conducted Power Tested:	20.12 dBm		
Antenna Type(s) Tested:	External Antenna		
Body-Worn Accessories:	Microphone		
Face-Head Accessories:	-		
Battery Type (s) Tested:	SMWB-A1: 1 DC 1.5V battery. SMDWB-A1: 2 DC 1.5V batteries.		
Max. SAR Level (s) Measured:	<b>Level (W/Kg)</b>	<b>Position</b>	<b>Operational Mode</b>
	0.694	Back Touch	470.1 – 537.575 MHz

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**DOCUMENT REVISION HISTORY**

<b>Revision Number</b>	<b>Report Number</b>	<b>Description of Revision</b>	<b>Date of Revision</b>
0	R1704196-SAR	Original Report	2017-06-27
1	R1704196-SAR	Updated page 2, EUT photos, and page 33	2017-08-01
2	R1704196-SAR	Update Page 2, 6, and 24	2017-08-11

## 1 General Description

### 1.1 Product Description for Equipment under Test (EUT)

This test and measurement report has been compiled on behalf of Lectrosonics, Inc. and their product model: *SMWB-A1 & SMDWB-A1, FCC ID: DBZSMWBA1*, which henceforth is referred to as the EUT (Equipment Under Test). The EUT is a Wireless Microphone Transmitter. The EUT operates in the frequency range 470.1MHz – 537.575MHz.

### 1.2 EUT Technical Specification

Item	Description
Modulation	FM
Frequency Range	470.1-537.575 MHz
Maximum Conducted Power Tested:	20.12 dBm
Power Source	SMWB-A1: 1 DC 1.5V battery. SMDWB-A1: 2 DC 1.5V batteries.
Normal Operation	Body-worn with accessories

### 1.3 Test Facility Registrations

*BACL's test facilities that are used to perform Radiated and Conducted Emissions tests are currently recognized by the Federal Communications Commission as Accredited with NIST Designation Number US1129.*

*BACL's test facilities that are used to perform Radiated and Conducted Emissions tests are currently registered with Industry Canada under Registration Numbers: 3062A-1, 3062A-2, and 3062A-3.*

BACL is a Chinese Taipei Bureau of Standards Metrology and Inspection (BSMI) validated Conformity Assessment Body (CAB), under Appendix B, Phase I Procedures of the APEC Mutual Recognition Arrangement (MRA). BACL's BSMI Lab Code Number is: SL2-IN-E-1002R

*BACL's test facilities that are used to perform AC Line Conducted Emissions, Telecommunications Line Conducted Emissions, Radiated Emissions from 30 MHz to 1 GHz, and Radiated Emissions from 1 GHz to 6 GHz are currently recognized as Accredited in accordance with the Voluntary Control Council for Interference [VCCI] Article 15 procedures under Registration Number A-0027.*

## 1.4 Test Facility Accreditations

Bay Area Compliance Laboratories Corp. (BACL) is:

**A- An independent, 3<sup>rd</sup>-Party, Commercial Test Laboratory accredited to ISO/IEC 17025:2005 by A2LA (Test Laboratory Accreditation Certificate Number 3279.02)**, in the fields of: Electromagnetic Compatibility and Telecommunications. Unless noted by an Asterisk (\*) in the Compliance Matrix (See Section 3 of this Test Report), BACL's ISO/IEC 17025:2005 Scope of Accreditation includes all of the Test Method Standards and/or the Product Family Standards detailed in this Test Report..

BACL's ISO/IEC 17025:2005 Scope of Accreditation includes a comprehensive suite of EMC Emissions, EMC Immunity, Radio, RF Exposure, Safety and wireline Telecommunications test methods applicable to a wide range of product categories. These product categories include Central Office Telecommunications Equipment [including NEBS - Network Equipment Building Systems], Unlicensed and Licensed Wireless and RF devices, Information Technology Equipment (ITE); Telecommunications Terminal Equipment (TTE); Medical Electrical Equipment; Industrial, Scientific and Medical Test Equipment; Professional Audio and Video Equipment; Industrial and Scientific Instruments and Laboratory Apparatus; Cable Distribution Systems, and Energy Efficient Lighting.

**B- A Product Certification Body accredited to ISO/IEC 17065:2012 by A2LA (Product Certification Body**

- - For the USA (Federal Communications Commission):

- 1- All Unlicensed radio frequency devices within FCC Scopes A1, A2, A3, and A4;
- 2- All Licensed radio frequency devices within FCC Scopes B1, B2, B3, and B4;
- 3- All Telephone Terminal Equipment within FCC Scope C.

- For the Canada (Industry Canada):

- 1- All Scope 1-Licence-Exempt Radio Frequency Devices;
- 2- All Scope 2-Licensed Personal Mobile Radio Services;
- 3- All Scope 3-Licensed General Mobile & Fixed Radio Services;
- 4- All Scope 4-Licensed Maritime & Aviation Radio Services;
- 5- All Scope 5-Licensed Fixed Microwave Radio Services
- 6- All Broadcasting Technical Standards (BETS) in the Category I Equipment Standards List.

For Singapore (Info-Communications Development Authority (IDA)):

- 1 All Line Terminal Equipment: All Technical Specifications for Line Terminal Equipment – Table 1 of IDA MRA Recognition Scheme: 2011, Annex 2
2. All Radio-Communication Equipment: All Technical Specifications for Radio-Communication Equipment – Table 2 of IDA MRA Recognition Scheme: 2011, Annex 2

- For the Hong Kong Special Administrative Region:

- 1 All Radio Equipment, per KHCA 10XX-series Specifications;
- 2 All GMDSS Marine Radio Equipment, per HKCA 12XX-series Specifications;
- 3 All Fixed Network Equipment, per HKCA 20XX-series Specifications.

- For Japan:

- 1 MIC Telecommunication Business Law (Terminal Equipment):
  - All Scope A1 - Terminal Equipment for the Purpose of Calls;
  - All Scope A2 - Other Terminal Equipment
- 2 Radio Law (Radio Equipment):
  - All Scope B1 - Specified Radio Equipment specified in Article 38-2-2, paragraph 1, item 1 of the Radio Law
  - All Scope B2 - Specified Radio Equipment specified in Article 38-2-2, paragraph 1, item 2 of the Radio Law
  - All Scope B3 - Specified Radio Equipment specified in Article 38-2-2, paragraph 1, item 3 of the Radio Law

**C- A Product Certification Body accredited to ISO/IEC 17065:2012 by A2LA (Product Certification Body Accreditation Certificate Number 3279.01)** to certify Products to USA's Environmental Protection Agency (EPA) ENERGY STAR Product Specifications for:

- 1 Electronics and Office Equipment:
  - for Telephony (ver. 3.0)

- for Audio/Video (ver. 3.0)
- for Battery Charging Systems (ver. 1.1)
- for Set-top Boxes & Cable Boxes (ver. 4.1)
- for Televisions (ver. 6.1)
- for Computers (ver. 6.0)
- for Displays (ver. 6.0)
- for Imaging Equipment (ver. 2.0)
- for Computer Servers (ver. 2.0)
- 2 Commercial Food Service Equipment
  - for Commercial Dishwashers (ver. 2.0)
  - for Commercial Ice Machines (ver. 2.0)
  - for Commercial Ovens (ver. 2.1)
  - for Commercial Refrigerators and Freezers
- 3 Lighting Products
  - For Decorative Light Strings (ver. 1.5)
  - For Luminaires (including sub-components) and Lamps (ver. 1.2)
  - For Compact Fluorescent Lamps (CFLs) (ver. 4.3)
  - For Integral LED Lamps (ver. 1.4)
- 4 Heating, Ventilation, and AC Products
  - for Residential Ceiling Fans (ver. 3.0)
  - for Residential Ventilating Fans (ver. 3.2)
- 5 Other
  - For Water Coolers (ver. 3.0)

**D. A NIST Designated Phase-I and Phase-II Conformity Assessment Body (CAB) for the following economies and regulatory authorities under the terms of the stated MRAs/Treaties:**

- Australia: ACMA (Australian Communication and Media Authority) – APEC Tel MRA -Phase I;
- Canada: (Industry Canada - IC) Foreign Certification Body – FCB – APEC Tel MRA -Phase I & Phase II;
- Chinese Taipei (Republic of China – Taiwan):
  - o BSMI (Bureau of Standards, Metrology and Inspection) APEC Tel MRA -Phase I;
  - o NCC (National Communications Commission) APEC Tel MRA -Phase I;
- European Union:
  - o EMC Directive 2014/30/EU US-EU EMC & Telecom MRA CAB (NB)
  - o Radio & Teleterminal Equipment (R&TTE) Directive 1995/5/EC US -EU EMC & Telecom MRA CAB (NB)
  - o Radio Equipment (RE) Directive 2014/53/EU US-EU EMC & Telecom MRA CAB (NB)
  - o Low Voltage Directive (LVD) 2014/35/EU
- Hong Kong Special Administrative Region: (Office of the Telecommunications Authority – OFTA) APEC Tel MRA -Phase I & Phase II
- Israel – US-Israel MRA Phase I
- Republic of Korea (Ministry of Communications - Radio Research Laboratory) APEC Tel MRA -Phase I
- Singapore: (Infocomm Development Authority - IDA) APEC Tel MRA -Phase I & Phase II;
- Japan: VCCI - Voluntary Control Council for Interference US-Japan Telecom Treaty VCCI Side Letter
- USA:
  - o ENERGY STAR Recognized Test Laboratory – US EPA
  - o Telecommunications Certification Body (TCB) – US FCC;
  - o Nationally Recognized Test Laboratory (NRTL) – US OSHA
- Vietnam: APEC Tel MRA -Phase I;

## 2 Reference, Standards and Guidelines

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### **FCC:**

The Report and Order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 mW/g as recommended by the ANSI/IEEE standard C95.1-1992 [6] for an uncontrolled environment (Paragraph 65). According to the Supplement C of OET Bulletin 65 "Evaluating Compliance with FCC Guide-lines for Human Exposure to Radio frequency Electromagnetic Fields", released on Jun 29, 2001 by the FCC, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

This report describes the methodology and results of experiments performed on wireless data terminal. The objective was to determine if there is RF radiation and if radiation is found, what is the extent of radiation with respect to safety limits. SAR (Specific Absorption Rate) is the measure of RF exposure determined by the amount of RF energy absorbed by human body (or its parts) – to determine how the RF energy couples to the body or head which is a primary health concern for body worn devices. The limit below which the exposure to RF is considered safe by regulatory bodies in North America is 1.6 mW/g average over 1 gram of tissue mass.

### **CE:**

The CE requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 2 mW/g as recommended by the EN50360 for an uncontrolled environment. According to the Standard, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

This report describes the methodology and results of experiments performed on wireless data terminal. The objective was to determine if there is RF radiation and if radiation is found, what is the extent of radiation with respect to safety limits? SAR (Specific Absorption Rate) is the measure of RF exposure determined by the amount of RF energy absorbed by human body (or its parts) – to determine how the RF energy couples to the body or head which is a primary health concern for body worn devices. The limit below which the exposure to RF is considered safe by regulatory bodies in Europe is 2 mW/g average over 10 gram of tissue mass.

The test configurations were laid out on a specially designed test fixture to ensure the reproducibility of measurements. Each configuration was scanned for SAR. Analysis of each scan was carried out to characterize the above effects in the device.



## 2.1 SAR Limits

### FCC/IC Limit

EXPOSURE LIMITS	SAR (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)
Spatial Average (averaged over the whole body)	0.08	0.4
Spatial Peak (averaged over any 1 g of tissue)	1.60	8.0
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

### CE Limit

EXPOSURE LIMITS	SAR (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)
Spatial Average (averaged over the whole body)	0.08	0.4
Spatial Peak (averaged over any 10 g of tissue)	2.0	10
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

Population/Uncontrolled Environments are defined as locations where there is the exposure of individual who have no knowledge or control of their exposure.

Occupational/Controlled Environments are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure (i.e. as a result of employment or occupation).

General Population/Uncontrolled environments Spatial Peak limit 1.6 W/kg (FCC) & 2 W/kg (CE) applied to the EUT.

### 3 Equipment List and Calibration

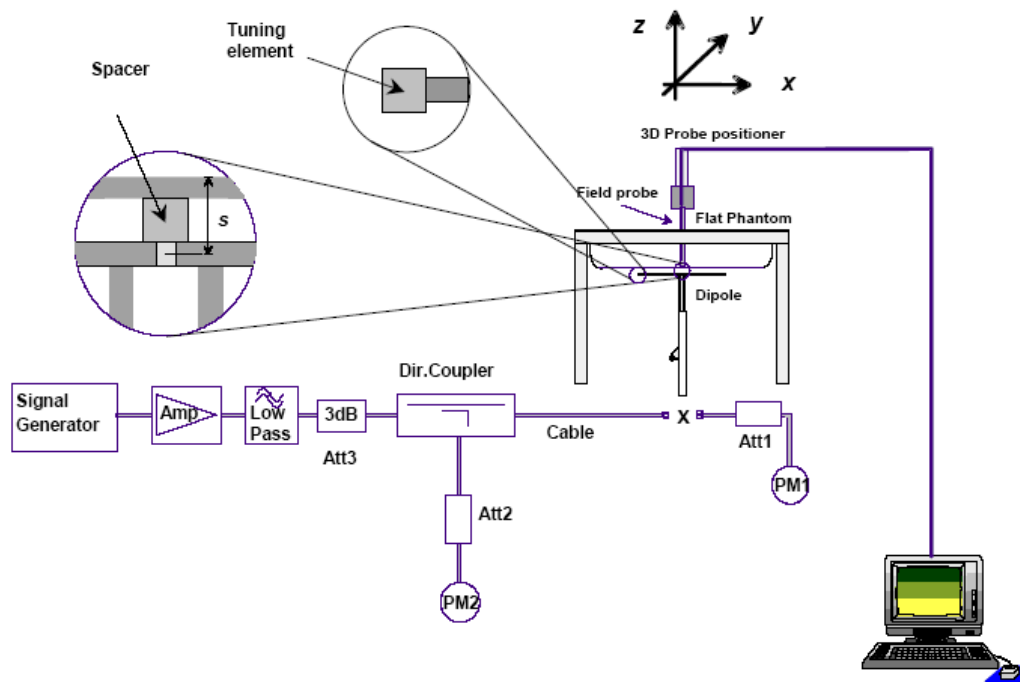
Type/Model	Cal. Due Date	S/N
DASY4 Professional Dosimetric System	N/A	N/A
Robot RX90B.L	N/A	599328-02
Robot Controller	N/A	3403-90092
HP Compoq 8000	N/A	CZC048171C
SPEAG EDC3	N/A	N/A
SPEAG DAE4	2017-09-21	530
DASY4 Measurement Server	N/A	1155
SPEAG E-Field Probe EX3DV4	2017-09-23	3619
Antenna, Dipole D600V3	2019-02-11	1010
SPEAG Twin SAM Phantom	N/A	TP-1032
Muscle Equivalent Matter (600 MHz)	Each Time	N/A
Agilent, Spectrum Analyzer E4440A	2018-02-24	US45303156
Mini Circuits, AMPLIFIER ZHL-42	2017-11-03	QA1326001
Power Sensor Agilent E9304A	2017-08-31	MY54280008
Power Sensor Agilent E9304A	2017-08-31	MY54280006
Dielectric Probe Kit HP85070A	N/A	US99360201
Power Meter Amplifier Research	2017-09-01	PM2002
HP, Signal Generator, 83650B	2017-09-09	3614A00276
Mini Circuits, AMPLIFIER ZVE-8G+	2017-11-03	N605601404

## 4 SAR Measurement System Verification

### 4.1 System Accuracy Verification

SAR system verification is required to confirm measurement accuracy. The system verification must be performed for each frequency band. A system verification must be performed before each series of SAR measurements.

### 4.2 SAR System Verification Setup and procedure



#### Procedure:

- 1) The SAR system verification measurements were performed in the flat section of TWIN SAM or flat phantom with shell thickness of  $2 \pm 0.2$  mm filled with head or body liquid.
- 2) The depth of liquid in phantom must be  $\geq 15$  cm for SAR measurement less than 3 GHz and  $\geq 10$  cm for SAR measurement above 3 GHz.
- 3) The dipole was mounted below the center of flat phantom, and oriented parallel to the Y-Axis. The standard measurement distance is 15mm (below 1 GHz) and 10mm (above 1 GHz) from dipole center to the liquid surface.
- 4) The dipole input power was 250 mW or 100 mW.
- 5) The SAR results are normalized to 1 Watt input power.
- 6) Compared the normalized the SAR results to the dipole calibration results.

### 4.3 Liquid and System Validation

Date	Simulant	Freq. [MHz]	Parameters	Liquid Temp [°C]	Target Value	Measured Value	Deviation [%]	Limits [%]
2017-06-02	Body	600	$\epsilon_r$	23	56.12	56.8	1.21	$\pm 5$
			$\sigma$	23	0.951	0.97	2.00	$\pm 5$
			1g SAR	23	6.66	6.32	-5.11	$\pm 10$

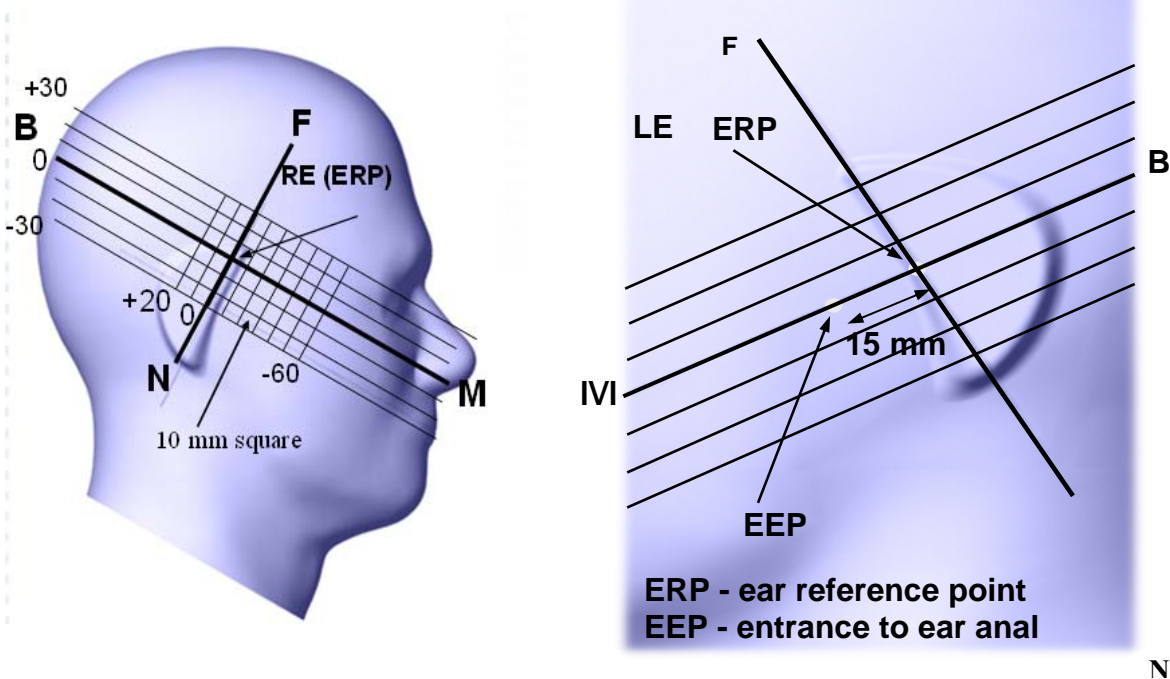
$\epsilon_r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho=1000 \text{ kg/m}^3$

## 5 EUT Test Strategy and Methodology

### 5.1 Test Positions for Device Operating Next to a Person's Ear

This category includes most wireless handsets with fixed, retractable or internal antennas located toward the top half of the device, with or without a foldout, sliding or similar keypad cover. The handset should have its earpiece located within the upper ¼ of the device, either along the centerline or off-centered, as perceived by its users. This type of handset should be positioned in a normal operating position with the “test device reference point” located along the “vertical centerline” on the front of the device aligned to the “ear reference point”. The “test device reference point” should be located at the same level as the center of the earpiece region. The “vertical centerline” should bisect the front surface of the handset at its top and bottom edges. An “ear reference point” is located on the outer surface of the head phantom on each ear spacer. It is located 1.5 cm above the center of the ear canal entrance in the “phantom reference plane” defined by the three lines joining the center of each “ear reference point” (left and right) and the tip of the mouth.

A handset should be initially positioned with the earpiece region pressed against the ear spacer of a head phantom. For the SCC-34/SC-2 head phantom, the device should be positioned parallel to the “N-F” line defined along the base of the ear spacer that contains the “ear reference point”. For interim head phantoms, the device should be positioned parallel to the cheek for maximum RF energy coupling. The “test device reference point” is aligned to the “ear reference point” on the head phantom and the “vertical centerline” is aligned to the “phantom reference plane”. This is called the “initial ear position”. While maintaining these three alignments, the body of the handset is gradually adjusted to each of the following positions for evaluating SAR:



## 5.2 Cheek/Touch Position

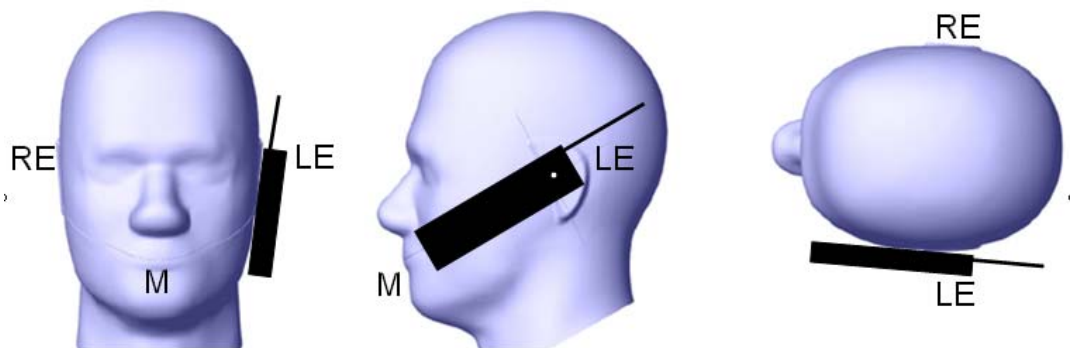
The device is brought toward the mouth of the head phantom by pivoting against the “ear reference point” or along the “N-F” line for the SCC-34/SC-2 head phantom.

This test position is established:

- When any point on the display, keypad or mouthpiece portions of the handset is in contact with the phantom.
- (or) When any portion of a foldout, sliding or similar keypad cover opened to its intended self-adjusting normal use position is in contact with the cheek or mouth of the phantom.

For existing head phantoms – when the handset loses contact with the phantom at the pivoting point, rotation should continue until the device touches the cheek of the phantom or breaks its last contact from the ear spacer.

### Cheek /Touch Position



## 5.3 Ear/Tilt Position

With the handset aligned in the “Cheek/Touch Position”:

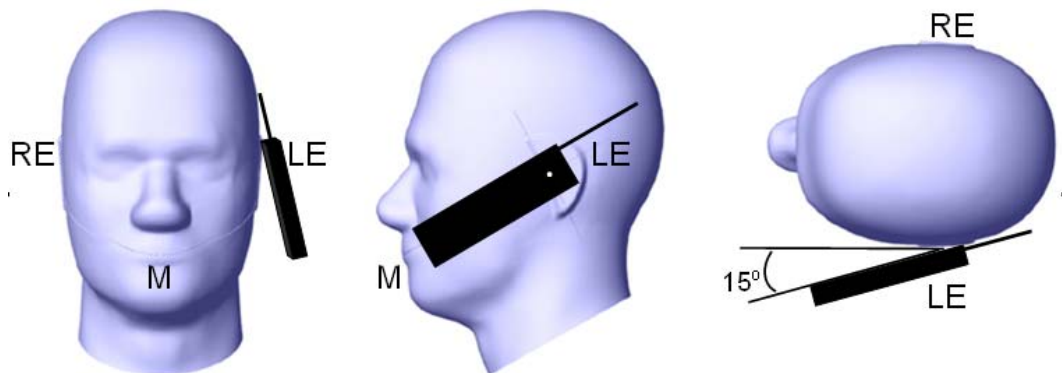
- 1) If the earpiece of the handset is not in full contact with the phantom’s ear spacer (in the “Cheek/Touch position”) and the peak SAR location for the “Cheek/Touch” position is located at the ear spacer region or corresponds to the earpiece region of the handset, the device should be returned to the “initial ear position” by rotating it away from the mouth until the earpiece is in full contact with the ear spacer.
- 2) (otherwise) The handset should be moved (translated) away from the cheek perpendicular to the line passes through both “ear reference points” (note: one of these ear reference points may not physically exist on a split head model) for approximate 2-3 cm. While it is in this position, the device handset is tilted away from the mouth with respect to the “test device reference point” until the inside angle between the vertical centerline on the front surface of the phone and the horizontal line passing through the ear reference point is by 15 80°. After the tilt, it is then moved (translated) back toward the head perpendicular to the line passes through both “ear reference points” until the device touches the phantom or the ear spacer. If the antenna touches the head first, the positioning process should be repeated with a tilt angle less than 15 80° so that the device and its antenna would touch the phantom simultaneously. This test position may require a device holder or positioner to achieve the translation and tilting with acceptable positioning repeatability.

If a device is also designed to transmit with its keypad cover closed for operating in the head position, such positions should also be considered in the SAR evaluation. The device should be tested on the left and right

side of the head phantom in the “Cheek/Touch” and “Ear/Tilt” positions. When applicable, each configuration should be tested with the antenna in its fully extended and fully retracted positions. These test configurations should be tested at the high, middle and low frequency channels of each operating mode; for example, AMPS, CDMA, and TDMA. If the SAR measured at the middle channel

for each test configuration (left, right, Cheek/Touch, Tile/Ear, extended and retracted) is at least 2.0 dB lower than the SAR limit, testing at the high and low channels is optional for such test configuration(s). If the transmission band of the test device is less than 10 MHz, testing at the high and low frequency channels is optional.

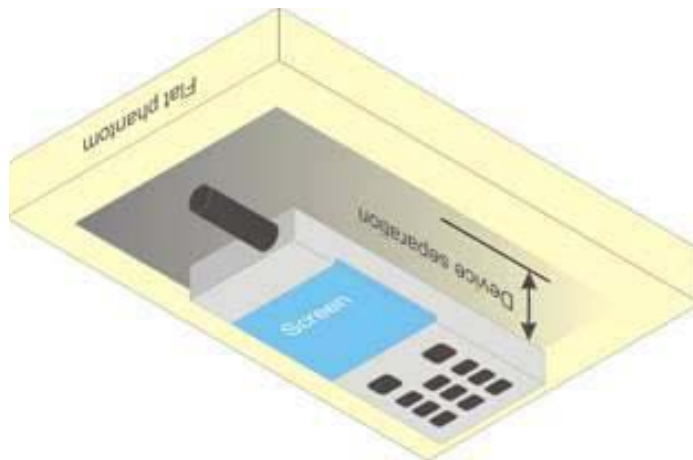
### **Ear /Tilt 15° Position**



## 5.4 Test positions for body-worn and other configurations

Body-worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a headset output should be tested with a headset connected to the device. When multiple accessories that do not contain metallic components are supplied with the device, the device may be tested with only the accessory that dictates the closest spacing to the body. When multiple accessories that contain metallic components are supplied with the device, the device must be tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (e.g., the same metallic belt-clip used with different holsters with no other metallic components), only the accessory that dictates the closest spacing to the body must be tested.

Body-worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances. Other separation distances may be used, but they should not exceed 2.5 cm. In these cases, the device may use body-worn accessories that provide a separation distance greater than that tested for the device provided however that the accessory contains no metallic components.



## 5.5 SAR Evaluation Procedure

The evaluation was performed with the following procedure:

**Step 1:** Measurement of the SAR value at a fixed location above the ear point or central position was used as a reference value for assessing the power drop. The SAR at this point is measured at the start of the test and then again at the end of the testing.

**Step 2:** The SAR distribution at the exposed side of the head was measured at a distance of 4 mm from the inner surface of the shell. The area covered the entire dimension of the head or EUT and the horizontal grid spacing was 15 mm x 15 mm. Based on these data, the area of the maximum absorption was determined by line interpolation. The first Area Scan covers the entire dimension of the EUT to ensure that the hotspot was correctly identified.



**Step 3:** Around this point, a volume of 30 mm x 30 mm x 21 mm was assessed by measuring 5 x 5 x 7 points. On the basis of this data set, the spatial peak SAR value was evaluated under the following procedure:

1. The data at the surface were extrapolated, since the center of the dipoles is 1.2 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.3 mm. The extrapolation was based on a least square algorithm. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
2. The maximum interpolated value was searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g or 10 g) were computed by the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one dimensional splines with the "Not a knot"-condition (in x, y and z-directions). The volume was integrated with the trapezoidal-algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the averages.
3. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

**Step 4:** Re-measurement of the SAR value at the same location as in Step 1. If the value changed by more than 5%, the evaluation was repeated.

## 5.6 Test Methodology

- KDB 447498 D01 (General SAR Guidance)

## 6 DASYS4 SAR Evaluation Procedure

### 6.1 Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method. The Minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. By default, the Minimum distance of probe sensors to surface is 4mm. This distance can be modified by the user, but cannot be smaller than the Distance of sensor calibration points to probe tip as defined in the probe properties (for example, 2.7mm for an ET3DV6 probe type).

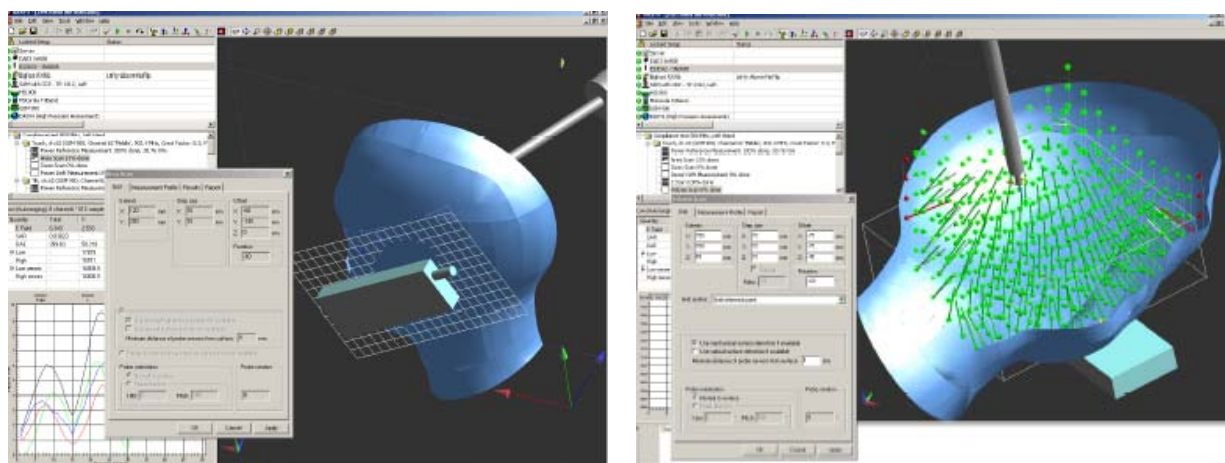
### 6.2 Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in DASYS4 software can find the maximum locations even in relatively coarse grids.

The scanning area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom. When the Area Scan's property sheet is brought-up, grid settings can be edited by a user.

When an Area Scan has measured all reachable points, it computes the field maxima found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE 1528-2003, EN 50361 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan). If only one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of Zoom Scans has to be increased accordingly.

After measurement is completed, all maxima and their coordinates are listed in the Results property page. The maximum selected in the list is highlighted in the 3-D view. For the secondary maxima returned from an Area Scan, the user can specify a lower limit (peak SAR value), in addition to the Find secondary maxima within x dB condition. Only the primary maximum and any secondary maxima within x dB from the primary maximum and above this limit will be measured.



### 6.3 Zoom Scan

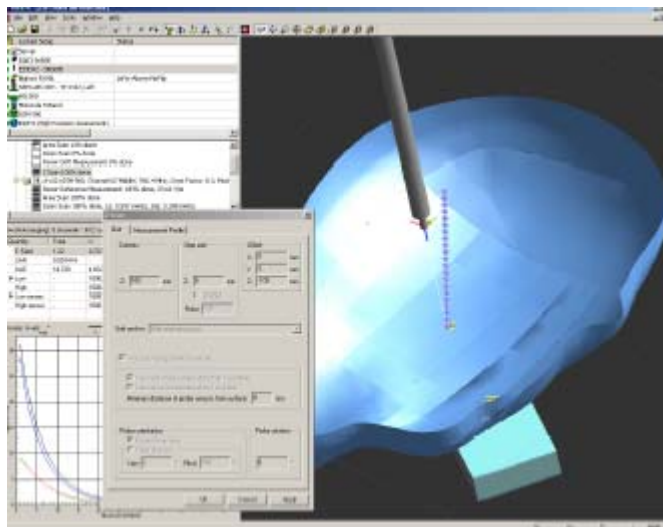
Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default Zoom Scan measures 5 x 5 x 7 points within a cube whose base faces are centered around the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1 g and 10 g and displays these values next to the job's label.

### 6.4 Power drift measurement

The Power Drift Measurement job measures the field at the same location as the most recent power reference measurement job within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the last Power Reference Measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

### 6.5 Z-Scan

The Z Scan job measures points along a vertical straight line. The line runs along the Z axis of a one-dimensional grid. A user can anchor the grid to the section reference point, to any defined user point or to the current probe location. As with any other grids, the local Z axis of the anchor location establishes the Z axis of the grid.



## 7 Description of Test System

These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG) which is the fourth generation of the system shown in the figure hereinafter:



The system is based on a high precision robot (working range greater than 0.9m), which positions the probes with a positional repeatability of better than  $\pm 0.02\text{mm}$ . Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit.

The SAR measurements were conducted with the dosimetric probe ET3DV6 SN: 1604 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure with accuracy of better than  $\pm 10\%$ . The spherical isotropy was evaluated with the procedure and found to be better than  $\pm 0.25\text{dB}$ .

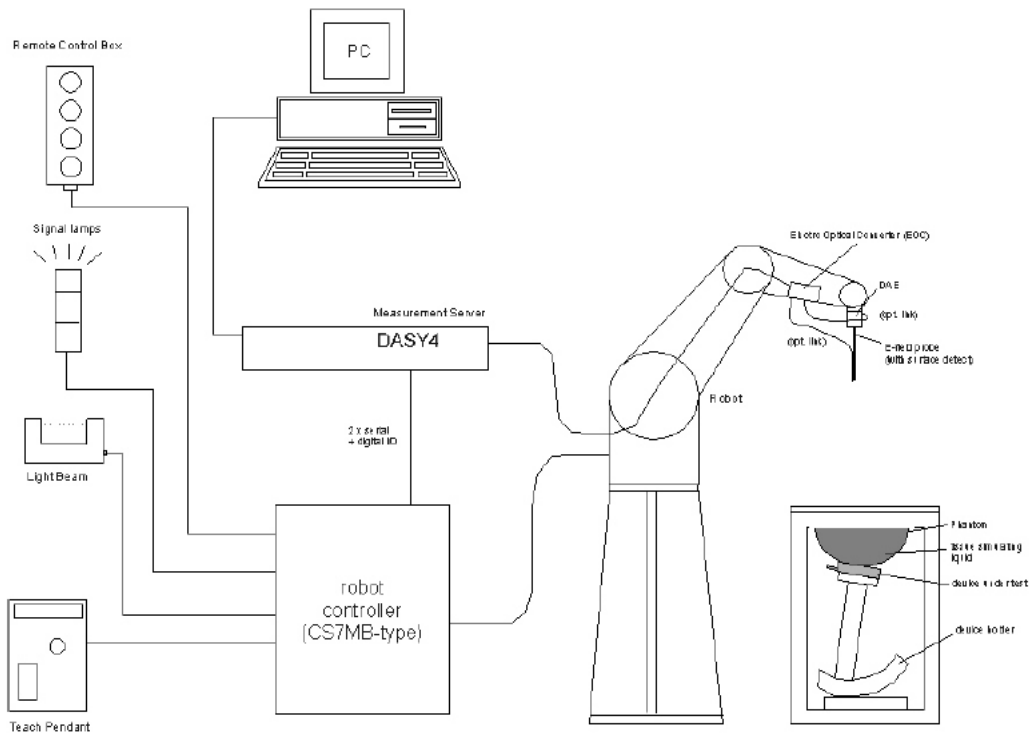
## 7.1 IEEE SCC-34/SC-2 P1528 Recommended Tissue Dielectric Parameters

Frequency (MHz)	Head Tissue		Body Tissue	
	$\epsilon_r$	$\sigma$ (S/m)	$\epsilon_r$	$\sigma$ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

## 7.2 DASY4 user's Manual Recommended Tissue Dielectric Parameters

Frequency (MHz)	Head Tissue		Body Tissue	
	$\epsilon_r$	$\sigma$ (S/m)	$\epsilon_r$	$\sigma$ (S/m)
2450	39.2	1.8	52.7	1.95
5200	36.0	4.66	49.0	5.30
5500	35.6	4.96	48.6	5.65
5800	35.3	5.27	48.2	6.00

### 7.3 Measurement System Diagram



The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC is connected to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows XP.
- DASY4 software.

- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- Validation dipole kits allowing system validation.

## 7.4 System Components

- DASY4 Measurement Server
- Data Acquisition Electronics
- Probes
- Light Beam Unit
- Medium
- SAM Twin Phantom
- Device Holder for SAM Twin Phantom
- System Validation Kits
- Robot

### DASY4 Measurement Server

The DASY4 measurement server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chip disk and 64MB RAM. The necessary circuits for communication with either the DAE4 (or DAE3) electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board.



The measurement server performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. The PC-operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with two expansion slots which are reserved for future applications. Please note that the expansion slots do not have a standardized pin out and therefore only the expansion cards provided by SPEAG can be inserted. Expansion cards from any other supplier could seriously damage the measurement server.



## Data Acquisition Electronics

The data acquisition electronics DAE3 consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.



## Probes

The DASY system can support many different probe types.

**Dosimetric Probes:** These probes are specially designed and calibrated for use in liquids with high permittivities. They should not be used in air, since the spherical isotropy in air is poor ( $\pm 2$  dB). The dosimetric probes have special calibrations in various liquids at different frequencies.

**Free Space Probes:** These are electric and magnetic field probes specially designed for measurements in free space. The z-sensor is aligned to the probe axis and the rotation angle of the x-sensor is specified. This allows the DASY system to automatically align the probe to the measurement grid for field component measurement. The free space probes are generally not calibrated in liquid. (The H-field probes can be used in liquids without any change of parameters.)

**Temperature Probes:** Small and sensitive temperature probes for general use. They use a completely different parameter set and different evaluation procedures. Temperature rise features allow direct SAR evaluations with these probes.

## ET3DV6 Probe Specification

Construction Symmetrical design with triangular core  
 Built-in optical fiber for surface detection System  
 Built-in shielding against static charges  
 Calibration In air from 10 MHz to 2.5 GHz  
 In brain and muscle simulating tissue at  
 Frequencies of 450 MHz, 900 MHz and  
 1.8 GHz (accuracy  $\pm 8\%$ )  
 Frequency 10 MHz to  $> 6$  GHz; Linearity:  $\pm 0.2$  dB  
 (30 MHz to 3 GHz)  
 Directivity  $\pm 0.2$  dB in brain tissue (rotation around  
 probe axis)  
 $\pm 0.4$  dB in brain tissue (rotation normal probe axis)  
 Dynamic 5 mW/g to  $> 100$  mW/g;  
 Range Linearity:  $\pm 0.2$  dB  
 Surface  $\pm 0.2$  mm repeatability in air and clear liquids  
 Detection over diffuse reflecting surfaces.  
 Dimensions Overall length: 330 mm  
 Tip length: 16 mm



**Photograph of the probe**

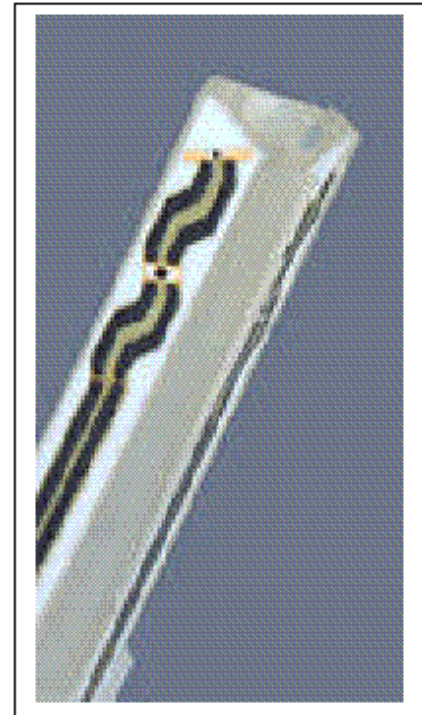


Body diameter: 12 mm  
Tip diameter: 6.8 mm  
Distance from probe tip to dipole centers: 2.7 mm  
Application General dosimetric up to 3 GHz  
Compliance tests of mobile phones  
Fast automatic scanning in arbitrary phantoms

The SAR measurements were conducted with the dosimetric probe ET3DV6 designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY3 software reads the reflection

#### **Inside view of**

during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped when reaching the maximum.



**ET3DV6 E-field Probe**

### **E-Field Probe Calibration Process**

Each probe is calibrated according to a dosimetric assessment procedure described in [6] with accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure described in [7] and found to be better than +/-0.25dB. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies below 1 GHz, and in a waveguide above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

## Data Evaluation

The DASY4 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Norm<sub>i</sub>, ai0, ai1, ai2  
 - Conversion factor ConvFi  
 - Diode compression point dcp<sub>i</sub>

Device parameters: - Frequency f  
 - Crest factor cf

Media parameters: - Conductivity  $\sigma$   
 - Density  $\rho$

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

With  $V_i$  = compensated signal of channel i (i =x, y, z)  
 $U_i$  = input signal of channel i (i =x, y, z)  
 cf = crest factor of exciting field (DASY parameter)  
 dcp<sub>i</sub> = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$\text{E - fieldprobes : } E_i = \sqrt{\frac{V_i}{\text{Norm}_i \cdot \text{ConvF}}}$$

$$\text{H - fieldprobes : } H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

With  $V_i$  = compensated signal of channel i (i =x, y, z)  
 Norm<sub>i</sub> = sensor sensitivity of channel i (i =x, y, z)  
 $\mu\text{V}/(\text{V}/\text{m})^2$  for E-field probes  
 ConF = sensitivity enhancement in solution  
 a<sub>ij</sub> = sensor sensitivity factors for H-field probes  
 f = carrier frequency [GHz]  
 E<sub>i</sub> = electric field strenggy of channel i in V/m  
 H<sub>i</sub> = diode compression point (DASY parameter)

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1'000}$$

With SAR = local specific absorption rate in mW/g  
 $E_{tot}$  = total field strength in V/m  
 $\sigma$  = conductivity in [mho/meter] or [Siemens/meter]  
 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

Note that the density is normally set to 1, to account for actual brain density rather than the density of the simulation liquid.

### Light Beam Unit

The light beam switch allows automatic “tooling” of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, so that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.

### Medium

#### Parameters

The parameters of the tissue simulating liquid strongly influence the SAR in the liquid. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE 1528-2003).

#### Parameter measurements

Several measurement systems are available for measuring the dielectric parameters of liquids:

- The open coax test method (e.g., HP85070 dielectric probe kit) is easy to use, but has only moderate accuracy. It is calibrated with open, short, and deionized water and the calibrations a critical process.
- The transmission line method (e.g., model 1500T from DAMASKOS, INC.) measures the transmission and reflection in a liquid filled high precision line. It needs standard two port calibration and is probably more accurate than the open coax method.
- The reflection line method measures the reflection in a liquid filled shorted precision lined. The method is not suitable for these liquids because of its low sensitivity.

- The slotted line method scans the field magnitude and phase along a liquid filled line. The evaluation is straight forward and only needs a simple response calibration. The method is very accurate, but can only be used in high loss liquids and at frequencies above 100 to 200MHz. Cleaning the line can be tedious.

### **SAM Twin Phantom**

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left hand
- Right hand
- Flat phantom

The phantom table comes in two sizes: A 100 x 50 x 85 cm (L x W x H) table for use with free standing robots (DASY4 professional system option) or as a second phantom and a 100 x 75 x 85 cm(L x W x H) table with reinforcements for table mounted robots (DASY4 compact system option) .

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids) A white cover is provided to tap the phantom during o<sub>-</sub>periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.



The phantom can be used with the following tissue simulating liquids:

- Water-sugar based liquids can be left permanently in the phantom. Always cover the liquid if the system is not used, otherwise the parameters will change due to water evaporation.
- Glycol based liquids should be used with care. As glycol is a softener for most plastics, the liquid should be taken out of the phantom and the phantom should be dried when the system is not used (desirable at least once a week).
- Do not use other organic solvents without previously testing the phantom's compatibility.

### **Device Holder for SAM Twin Phantom**

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source in 5mm distance, a positioning uncertainty of  $\pm 0.5$ mm would produce a SAR uncertainty of  $\pm 20\%$ . An accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions, in which the devices must be measured, are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the

ear reference points). The rotation center for both scales is the ear reference point ERP). Thus the device needs no repositioning when changing the angles.



The DASy device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\epsilon_r=3$  and loss tangent  $\tan \delta=0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

### System Validation Kits

Each DASy system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASy software, enable the user to conduct the system performance check and system validation. For that purpose a well defined SAR distribution in the flat section of the SAM twin phantom is produced.

System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder. Dipoles are available for the variety of frequencies between 300MHz and 6 GHz (dipoles for other frequencies or media and other calibration conditions are available upon request).

The dipoles are highly symmetric and matched at the center frequency for the specified liquid and distance to the flat phantom (or flat section of the SAM-twin phantom). The accurate distance between the liquid surface and the dipole center is achieved with a distance holder that snaps on the dipole.

## Robot

The DASY4 system uses the high precision industrial robots RX60L, RX90 and RX90L, as well as the RX60BL and RX90BL types out of the newer series from Stäubli SA (France). The RX robot series offers many features that are important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance-free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchronous motors; no stepper motors)
- Low ELF interference (the closed metallic construction shields against motor control fields)

For the newly delivered DASY4 systems as well as for the older DASY3 systems delivered since 1999, the CS7MB robot controller version from Stäubli is used. Previously delivered systems have either a CS7 or CS7M controller; the differences to the CS7MB are mainly in the hardware, but some procedures in the robot software from Stäubli are also not completely the same. The following descriptions about robot hard- and software correspond to CS7MB controller with software version 13.1 (edit S5). The actual commands, procedures and configurations, also including details in hardware, might differ if an older robot controller is in use. In this case please also refer to the Stäubli manuals for further information.

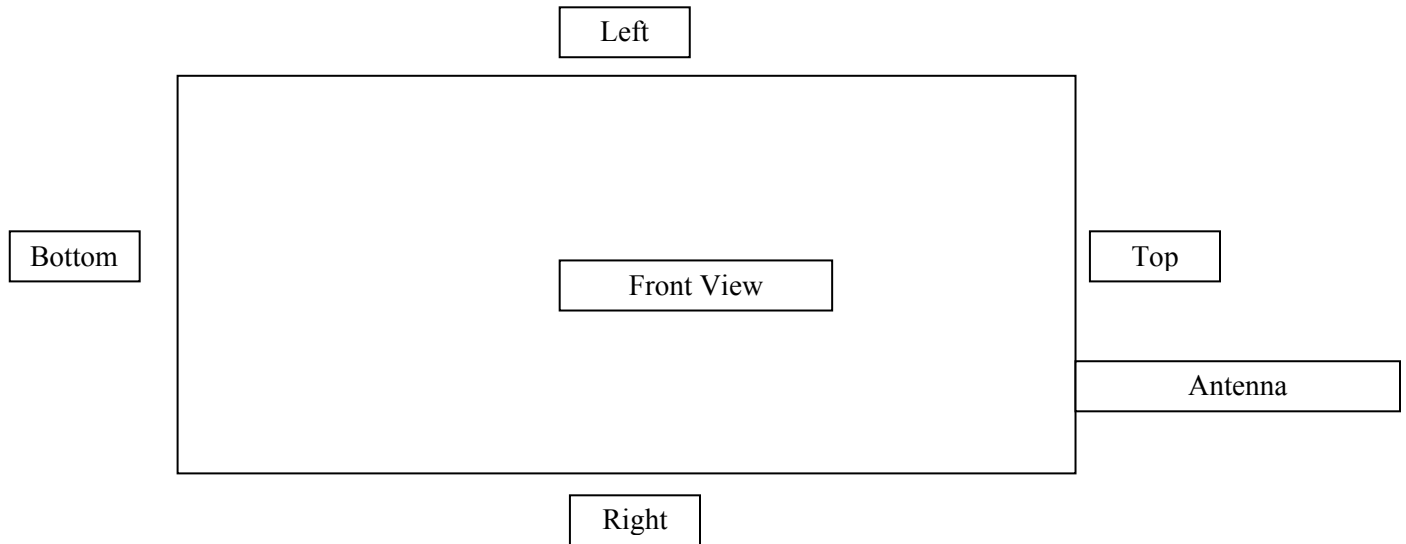


## 8 SAR Measurement Consideration and Reduction

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### 8.1 SAR Reductions

#### EUT Antennas Location



Note1: One position was chosen for SAR testing, rear side touch to human body for normal operation.

## 9 SAR Measurement Results

This page summarizes the results of the performed SAR evaluation. The plots with the corresponding SAR distributions, which reveal information about the location of the maximum SAR with respect to the device, could be found in Appendix E.

### 9.1 Test Environmental Conditions

<b>Temperature:</b>	23° C
<b>Relative Humidity:</b>	42 %
<b>ATM Pressure:</b>	102 kPa

Testing was performed by Jin Yang in SAR chamber from 2017-06-02.

### 9.2 Standalone SAR Results

Please refer to the following tables.

SMWB-A1									
EUT Position	Frequency (MHz)	Test Type	Output Power (dBm)		Scale Factor	Measured (W/kg)	Scaled (W/kg)	Limit (W/kg)	Plot #
			Measured	Target					
Rear Side Touch (Middle CH)	503.8	Body	20.12	20	1.000	0.555	0.555	1.6	-
SMDWB-A1									
EUT Position	Frequency (MHz)	Test Type	Output Power (dBm)		Scale Factor	Measured (W/kg)	Scaled (W/kg)	Limit (W/kg)	Plot #
			Measured	Target					
Rear Side Touch (Middle CH)	503.8	Body	19.98	20	1.004	0.691	0.694	1.6	1

Note: According to KDB 447498 D01, in each wireless mode and frequency band, when the reported 1-g SAR for the mid-band or highest output power channel is  $\leq 0.8$  W/kg, testing of other required channels are not required.



## 10 Appendix A – Measurement Uncertainty

The uncertainty budget has been determined for the DASY4 measurement system and is given in the following Table.

### Below 3 GHz

DASY4 Uncertainty Budget According to IEC 62209-2								
Error Description	Uncertainty Value	Prob. Dist.	Div.	(c i) 1g	(c i) 10g	Std. Unc. (1g)	Std. Unc. (10g)	(v i) veff
<b>Measurement System</b>								
Probe Calibration (600 MHz)	± 6.65 %	N	1	1	1	± 6.65 %	± 6.65 %	∞
Isotropy	± 0.94 %	R	$\sqrt{3}$	1	1	± 0.54 %	± 0.54 %	∞
Linearity	± 0.3 %	R	$\sqrt{3}$	1	1	± 0.17 %	± 0.17 %	∞
Modulation Response	± 1.65 %	R	$\sqrt{3}$	1	1	± 0.95 %	± 0.95 %	∞
System Detection Limits	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	∞
Boundary Effects	± 0.5 %	R	$\sqrt{3}$	1	1	± 0.29 %	± 0.29 %	∞
Readout Electronics	± 0.3 %	N	1	1	1	± 0.3 %	± 0.3 %	∞
Response Time	± 0.8 %	R	$\sqrt{3}$	1	1	± 0.5 %	± 0.5 %	∞
Integration Time	± 2.6 %	R	$\sqrt{3}$	1	1	± 1.5 %	± 1.5 %	∞
RF Ambient Noise	± 0.0 %	R	$\sqrt{3}$	1	1	± 0.0 %	± 0.0 %	∞
RF Ambient Reflections	± 3.0 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	∞
Probe Positioner	± 0.4 %	R	$\sqrt{3}$	1	1	± 0.2 %	± 0.2 %	∞
Probe Positioning	± 2.9 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	∞
Post-processing	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	∞
<b>Test Sample Related</b>								
Device Holder	± 3.6 %	N	1	1	1	± 3.6 %	± 2.6 %	5
Device Positioning	± 2.9 %	N	1	1	1	± 2.9 %	± 2.9 %	145
SAR Scaling	± 0.0 %	R	$\sqrt{3}$	1	1	± 0.0 %	± 0.0 %	∞
Power Drift	± 5.0 %	R	$\sqrt{3}$	1	1	± 2.9 %	± 2.9 %	∞
<b>Phantom and Setup</b>								
Phantom Uncertainty	± 4.0 %	R	$\sqrt{3}$	1	1	± 2.3 %	± 2.3 %	∞
SAR Correction	± 0.0 %	N	1	1	1	± 0.0 %	± 0.0 %	∞
Liquid Conductivity (Target)	± 5.0 %	R	$\sqrt{3}$	0.64	0.43	± 1.8 %	± 1.2 %	∞
Liquid Conductivity (meas.)	± 2.5 %	N	1	0.64	0.43	± 1.6 %	± 1.1 %	∞
Liquid Permittivity (Target)	± 5.0 %	R	$\sqrt{3}$	0.6	0.49	± 1.7 %	± 1.4 %	∞
Liquid Permittivity (meas.)	± 2.5 %	N	1	0.6	0.49	± 1.5 %	± 1.2 %	∞
Combined Std. Uncertainty	-	RSS	-	-	-	± 9.32 %	± 9.23 %	330
Expanded STD Uncertainty	-	2	-	-	-	± 18.6 %	± 18.5 %	-

## 11 Appendix B - Probe Calibration Certificates

**Calibration Laboratory of  
Schmid & Partner  
Engineering AG**  
Zeughausstrasse 43, 8004 Zurich, Switzerland



**S** Schweizerischer Kalibrierdienst  
**C** Service suisse d'étalonnage  
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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Client **BACL**

Certificate No: **EX3-3619\_Sep16**

### CALIBRATION CERTIFICATE

Object **EX3DV4 - SN:3619**

Calibration procedure(s) **QA CAL-01.v9, QA CAL-12.v9, QA CAL-14.v4, QA CAL-23.v5,  
QA CAL-25.v6  
Calibration procedure for dosimetric E-field probes**

Calibration date: **September 23, 2016**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature ( $22 \pm 3$ )°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	06-Apr-16 (No. 217-02288/02289)	Apr-17
Power sensor NRP-Z91	SN: 103244	06-Apr-16 (No. 217-02288)	Apr-17
Power sensor NRP-Z91	SN: 103245	06-Apr-16 (No. 217-02289)	Apr-17
Reference 20 dB Attenuator	SN: S5277 (20x)	05-Apr-16 (No. 217-02293)	Apr-17
Reference Probe ES3DV2	SN: 3013	31-Dec-15 (No. ES3-3013_Dec15)	Dec-16
DAE4	SN: 660	23-Dec-15 (No. DAE4-660_Dec15)	Dec-16
Secondary Standards	ID	Check Date (in house)	Scheduled Check
Power meter E4419B	SN: GB41293874	06-Apr-16 (in house check Jun-16)	In house check: Jun-18
Power sensor E4412A	SN: MY41498087	06-Apr-16 (in house check Jun-16)	In house check: Jun-18
Power sensor E4412A	SN: 000110210	06-Apr-16 (in house check Jun-16)	In house check: Jun-18
RF generator HP 8648C	SN: US3642U01700	04-Aug-99 (in house check Jun-16)	In house check: Jun-18
Network Analyzer HP 8753E	SN: US37390585	18-Oct-01 (in house check Oct-15)	In house check: Oct-16

	Name	Function	Signature
Calibrated by:	Michael Weber	Laboratory Technician	
Approved by:	Katja Pokovic	Technical Manager	

Issued: September 28, 2016

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

**Calibration Laboratory of  
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Zeughausstrasse 43, 8004 Zurich, Switzerland



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Accreditation No.: **SCS 0108**

### Glossary:

TSL	tissue simulating liquid
NORM <sub>x,y,z</sub>	sensitivity in free space
ConvF	sensitivity in TSL / NORM <sub>x,y,z</sub>
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization $\varphi$	$\varphi$ rotation around probe axis
Polarization $\vartheta$	$\vartheta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

### Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

### Methods Applied and Interpretation of Parameters:

- NORM<sub>x,y,z</sub>**: Assessed for E-field polarization  $\vartheta = 0$  ( $f \leq 900$  MHz in TEM-cell;  $f > 1800$  MHz: R22 waveguide). NORM<sub>x,y,z</sub> are only intermediate values, i.e., the uncertainties of NORM<sub>x,y,z</sub> does not affect the  $E^2$ -field uncertainty inside TSL (see below ConvF).
- NORM(f)<sub>x,y,z</sub> = NORM<sub>x,y,z</sub> \* frequency\_response** (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP<sub>x,y,z</sub>**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR**: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- A<sub>x,y,z</sub>; B<sub>x,y,z</sub>; C<sub>x,y,z</sub>; D<sub>x,y,z</sub>; VR<sub>x,y,z</sub>**: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters**: Assessed in flat phantom using E-field (or Temperature Transfer Standard for  $f \leq 800$  MHz) and inside waveguide using analytical field distributions based on power measurements for  $f > 800$  MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM<sub>x,y,z</sub> \* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from  $\pm 50$  MHz to  $\pm 100$  MHz.
- Spherical isotropy (3D deviation from isotropy)**: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the NORM<sub>x</sub> (no uncertainty required).

EX3DV4 – SN:3619

September 23, 2016

# Probe EX3DV4

## SN:3619

Manufactured: July 3, 2007  
Calibrated: September 23, 2016

Calibrated for DASY/EASY Systems  
(Note: non-compatible with DASY2 system!)



EX3DV4- SN:3619

September 23, 2016

**DASY/EASY - Parameters of Probe: EX3DV4 - SN:3619****Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ( $\mu\text{V}/(\text{V}/\text{m})^2$ ) <sup>A</sup>	0.44	0.36	0.39	$\pm 10.1\%$
DCP (mV) <sup>B</sup>	101.0	98.1	99.9	

**Modulation Calibration Parameters**

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Unc <sup>E</sup> (k=2)
0	CW	X	0.0	0.0	1.0	0.00	176.2	$\pm 3.3\%$
		Y	0.0	0.0	1.0		178.2	
		Z	0.0	0.0	1.0		177.1	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of Norm X,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Pages 5 and 6).

<sup>B</sup> Numerical linearization parameter; uncertainty not required.

<sup>E</sup> Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

EX3DV4- SN:3619

September 23, 2016

**DASY/EASY - Parameters of Probe: EX3DV4 - SN:3619****Calibration Parameter Determined in Head Tissue Simulating Media**

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha <sup>G</sup>	Depth <sup>G</sup> (mm)	Unc (k=2)
450	43.5	0.87	9.60	9.60	9.60	0.17	1.15	± 13.3 %
600	42.7	0.88	8.83	8.83	8.83	0.14	1.15	± 13.3 %
750	41.9	0.89	9.88	9.88	9.88	0.64	0.80	± 12.0 %
835	41.5	0.90	9.28	9.28	9.28	0.54	0.80	± 12.0 %
1750	40.1	1.37	7.56	7.56	7.56	0.30	0.80	± 12.0 %
1900	40.0	1.40	7.21	7.21	7.21	0.34	0.87	± 12.0 %
2450	39.2	1.80	6.64	6.64	6.64	0.34	0.85	± 12.0 %
2600	39.0	1.96	6.59	6.59	6.59	0.32	0.97	± 12.0 %
5250	35.9	4.71	4.52	4.52	4.52	0.40	1.80	± 13.1 %
5600	35.5	5.07	4.00	4.00	4.00	0.50	1.80	± 13.1 %
5800	35.3	5.27	4.05	4.05	4.05	0.50	1.80	± 13.1 %

<sup>C</sup> Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

<sup>G</sup> Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

EX3DV4- SN:3619

September 23, 2016

## DASY/EASY - Parameters of Probe: EX3DV4 - SN:3619

### Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha <sup>G</sup>	Depth (mm) <sup>G</sup>	Unc (k=2)
450	56.7	0.94	10.05	10.05	10.05	0.08	1.15	± 13.3 %
600	56.1	0.95	9.19	9.19	9.19	0.12	1.15	± 13.3 %
750	55.5	0.96	8.36	8.36	8.36	0.45	0.80	± 12.0 %
835	55.2	0.97	8.20	8.20	8.20	0.44	0.80	± 12.0 %
1750	53.4	1.49	7.26	7.26	7.26	0.27	1.05	± 12.0 %
1900	53.3	1.52	7.00	7.00	7.00	0.39	0.84	± 12.0 %
2450	52.7	1.95	6.69	6.69	6.69	0.35	0.85	± 12.0 %
2600	52.5	2.16	6.54	6.54	6.54	0.26	0.95	± 12.0 %
5250	48.9	5.36	4.05	4.05	4.05	0.50	1.90	± 13.1 %
5600	48.5	5.77	3.39	3.39	3.39	0.60	1.90	± 13.1 %
5800	48.2	6.00	3.68	3.68	3.68	0.60	1.90	± 13.1 %

<sup>C</sup> Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

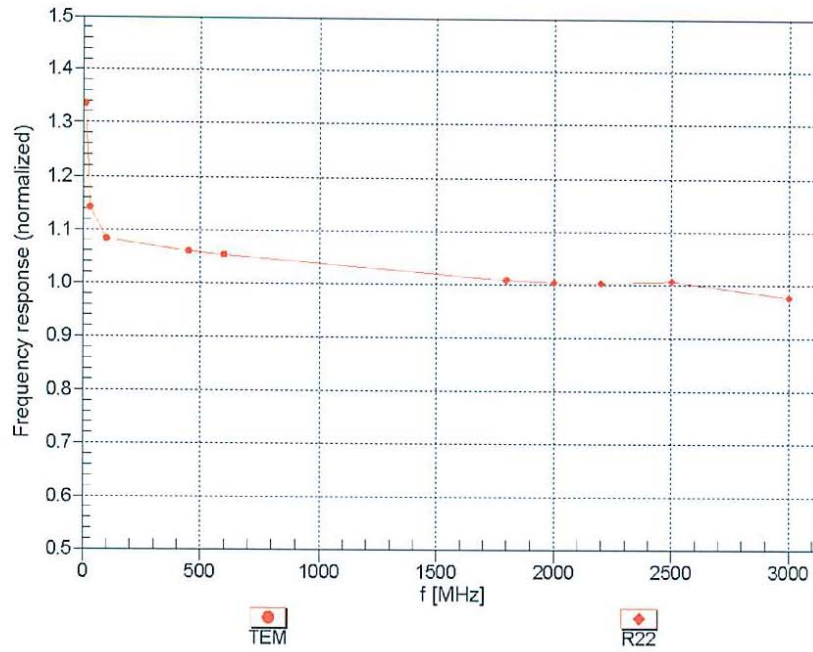
<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

<sup>G</sup> Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

EX3DV4- SN:3619

September 23, 2016

### Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



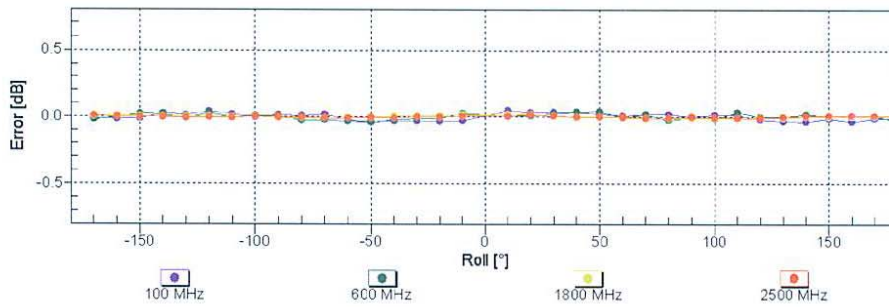
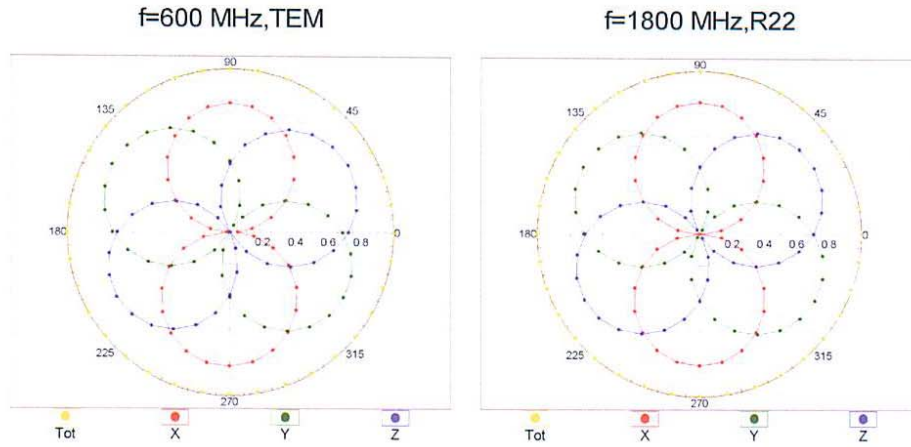
Uncertainty of Frequency Response of E-field:  $\pm 6.3\%$  (k=2)



EX3DV4- SN:3619

September 23, 2016

### Receiving Pattern ( $\phi$ ), $\theta = 0^\circ$

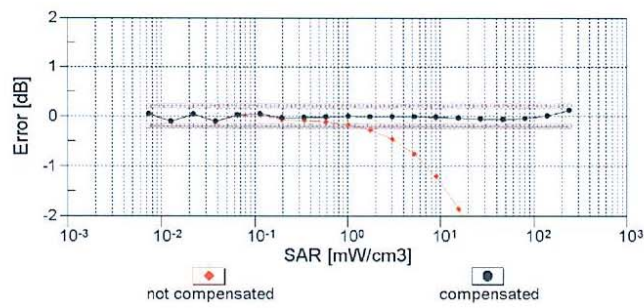
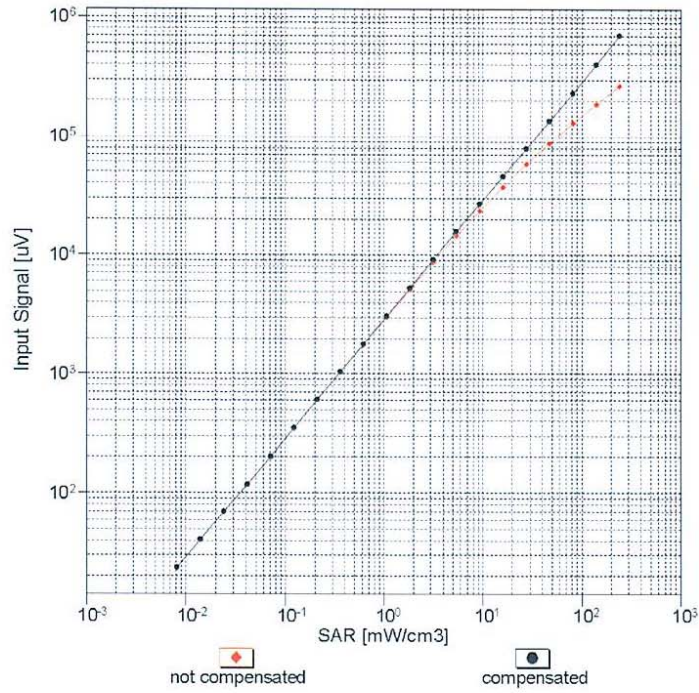


Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  ( $k=2$ )

EX3DV4- SN:3619

September 23, 2016

### Dynamic Range $f(\text{SAR}_{\text{head}})$ (TEM cell , $f_{\text{eval}}= 1900 \text{ MHz}$ )

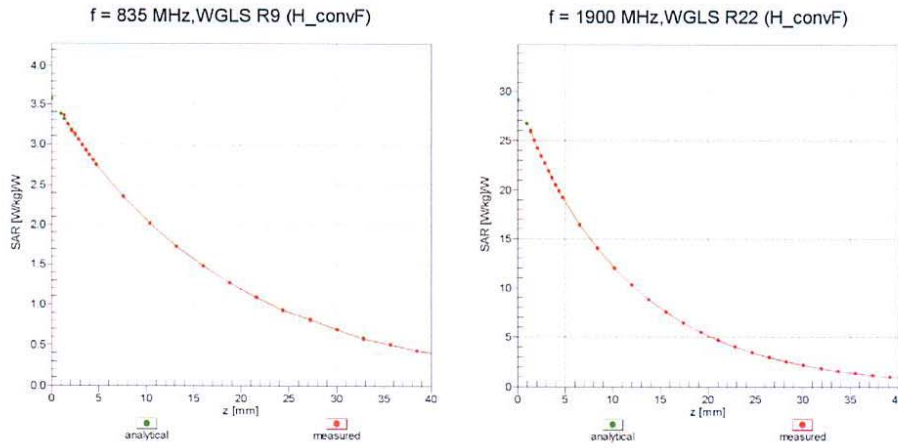


Uncertainty of Linearity Assessment:  $\pm 0.6\%$  ( $k=2$ )

EX3DV4- SN:3619

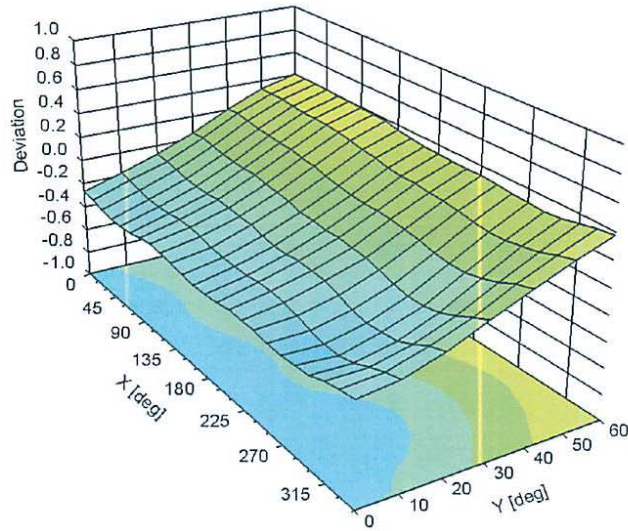
September 23, 2016

### Conversion Factor Assessment



### Deviation from Isotropy in Liquid

Error ( $\phi, \theta$ ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment:  $\pm 2.6\%$  (k=2)

EX3DV4– SN:3619

September 23, 2016

**DASY/EASY - Parameters of Probe: EX3DV4 - SN:3619****Other Probe Parameters**

Sensor Arrangement	Triangular
Connector Angle (°)	30
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	1.4 mm



## 12 Appendix C – Dipole Calibration Certificates

**Calibration Laboratory of  
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Zeughausstrasse 43, 8004 Zurich, Switzerland



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Accreditation No.: **SCS 0108**

Client **BACL**

Certificate No: **D600V3-1010\_Feb16**

CALIBRATION CERTIFICATE	
Object	D600V3 - SN: 1010
Calibration procedure(s)	QA CAL-15.v8 Calibration procedure for dipole validation kits below 700 MHz <b>Post Repair/Re-Calibration Verification</b>
Calibration date:	February 11, 2016 Date Received Back <u>2/22/2016</u> Cal Cert/Sticker Date OK? <input checked="" type="checkbox"/> Date <u>2/24/2016</u> Functional Verification OK? <input checked="" type="checkbox"/> Date <u>2/24/2016</u> Verifications By: <u>Rudy Sun</u>
This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.	
All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.	
Calibration Equipment used (M&TE critical for calibration)	
<b>Primary Standards</b>	<b>ID #</b> <b>Cal Date (Certificate No.)</b> <b>Scheduled Calibration</b>
Power meter E4419B	GB41293874      01-Apr-15 (No. 217-02128)      Mar-16
Power sensor E4412A	MY41498087      01-Apr-15 (No. 217-02128)      Mar-16
Reference 3 dB Attenuator	SN: S5054 (3c)      01-Apr-15 (No. 217-02129)      Mar-16
Reference 20 dB Attenuator	SN: S5058 (20k)      01-Apr-15 (No. 217-02131)      Mar-16
Type-N mismatch combination	SN: 5047.2 / 06327      01-Apr-15 (No. 217-02134)      Mar-16
Reference Probe ET3DV6	SN: 1507      31-Dec-15 (No. ET3-1507_Dec15)      Dec-16
DAE4	SN: 654      08-Jul-15 (No. DAE4-654_Jul15)      Jul-16
<b>Secondary Standards</b>	<b>ID #</b> <b>Check Date (in house)</b> <b>Scheduled Check</b>
RF generator HP 8648C	US3642U01700      04-Aug-99 (in house check Apr-13)      In house check: Apr-16
Network Analyzer HP 8753E	US37390585 S4206      18-Oct-01 (in house check Oct-15)      In house check: Oct-16
Calibrated by:	Name: <b>Jeton Kastrati</b> Function: <b>Laboratory Technician</b> Signature:
Approved by:	Name: <b>Katja Pokovic</b> Function: <b>Technical Manager</b> Signature:
Issued: February 11, 2016	
This calibration certificate shall not be reproduced except in full without written approval of the laboratory.	

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Accreditation No.: **SCS 0108**

#### Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

#### Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

#### Additional Documentation:

- DASY4/5 System Handbook

#### Methods Applied and Interpretation of Parameters:

- Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL:** The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss:** These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay:** One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured:** SAR measured at the stated antenna input power.
- SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor  $k=2$ , which for a normal distribution corresponds to a coverage probability of approximately 95%.

**Measurement Conditions**

DASY system configuration, as far as not given on page 1.

<b>DASY Version</b>	DASY5	V52.8.8
<b>Extrapolation</b>	Advanced Extrapolation	
<b>Phantom</b>	ELI4 Flat Phantom	Shell thickness: $2 \pm 0.2$ mm
<b>Distance Dipole Center - TSL</b>	15 mm	with Spacer
<b>Zoom Scan Resolution</b>	dx, dy, dz = 5 mm	
<b>Frequency</b>	600 MHz $\pm$ 1 MHz	

**Head TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
<b>Nominal Head TSL parameters</b>	22.0 °C	42.7	0.88 mho/m
<b>Measured Head TSL parameters</b>	(22.0 $\pm$ 0.2) °C	42.7 $\pm$ 6 %	0.86 mho/m $\pm$ 6 %
<b>Head TSL temperature change during test</b>	< 0.5 °C	----	----

**SAR result with Head TSL**

<b>SAR averaged over 1 cm<sup>3</sup> (1 g) of Head TSL</b>	Condition	
SAR measured	250 mW input power	1.59 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	<b>6.47 W/kg <math>\pm</math> 18.1 % (k=2)</b>

<b>SAR averaged over 10 cm<sup>3</sup> (10 g) of Head TSL</b>	condition	
SAR measured	250 mW input power	1.04 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	<b>4.22 W/kg <math>\pm</math> 17.6 % (k=2)</b>

**Body TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
<b>Nominal Body TSL parameters</b>	22.0 °C	56.1	0.95 mho/m
<b>Measured Body TSL parameters</b>	(22.0 $\pm$ 0.2) °C	55.8 $\pm$ 6 %	0.93 mho/m $\pm$ 6 %
<b>Body TSL temperature change during test</b>	< 0.5 °C	----	----

**SAR result with Body TSL**

<b>SAR averaged over 1 cm<sup>3</sup> (1 g) of Body TSL</b>	Condition	
SAR measured	250 mW input power	1.64 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	<b>6.66 W/kg <math>\pm</math> 18.1 % (k=2)</b>

<b>SAR averaged over 10 cm<sup>3</sup> (10 g) of Body TSL</b>	condition	
SAR measured	250 mW input power	1.07 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	<b>4.34 W/kg <math>\pm</math> 17.6 % (k=2)</b>

**Appendix (Additional assessments outside the scope of SCS 0108)****Antenna Parameters with Head TSL**

Impedance, transformed to feed point	56.9 $\Omega$ - 4.0 j $\Omega$
Return Loss	- 22.5 dB

**Antenna Parameters with Body TSL**

Impedance, transformed to feed point	52.5 $\Omega$ - 7.5 j $\Omega$
Return Loss	- 22.3 dB

**General Antenna Parameters and Design**

Electrical Delay (one direction)	1.151 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

**Additional EUT Data**

Manufactured by	SPEAG
Manufactured on	December 22, 2015



**DASY5 Validation Report for Head TSL**

Date: 11.02.2016

Test Laboratory: SPEAG, Zurich, Switzerland

**DUT: Dipole 600 MHz; Type: D600V3; Serial: D600V3 - SN: 1010**

Communication System: UID 0 - CW; Frequency: 600 MHz

Medium parameters used:  $f = 600$  MHz;  $\sigma = 0.86$  S/m;  $\epsilon_r = 42.7$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: ET3DV6 - SN1507; ConvF(6.54, 6.54, 6.54); Calibrated: 31.12.2015;
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn654; Calibrated: 08.07.2015
- Phantom: ELI v4.0; Type: QDOVA001BB; Serial: TP:1003
- DASY52 52.8.8(1258); SEMCAD X 14.6.10(7372)

**Dipole Calibration for Head Tissue/Pin=250 mW, d=15mm/Zoom Scan (7x7x7)/Cube 0:**

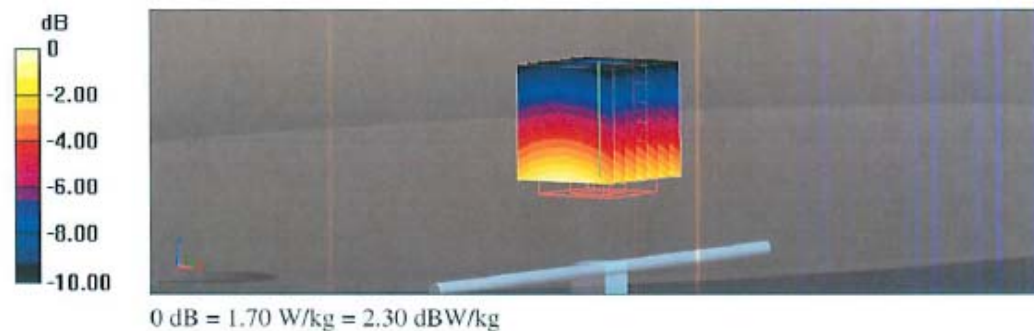
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 45.65 V/m; Power Drift = -0.01 dB

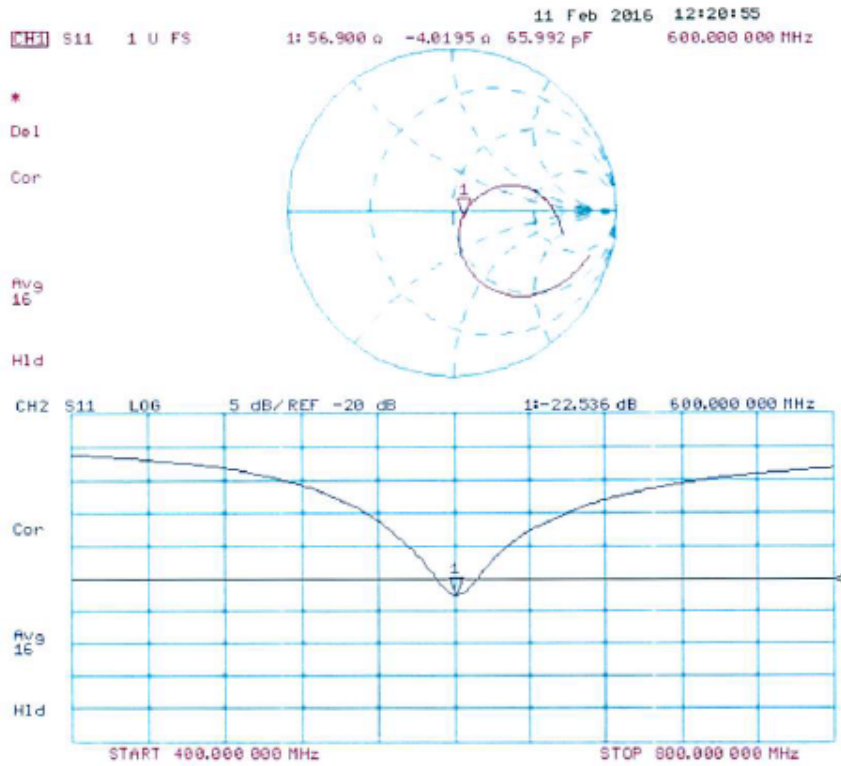
Peak SAR (extrapolated) = 2.53 W/kg

**SAR(1 g) = 1.59 W/kg; SAR(10 g) = 1.04 W/kg**

Maximum value of SAR (measured) = 1.70 W/kg



### Impedance Measurement Plot for Head TSL



**DASY5 Validation Report for Body TSL**

Date: 11.02.2016

Test Laboratory: SPEAG, Zurich, Switzerland

**DUT: Dipole 600 MHz; Type: D600V3; Serial: D600V3 - SN: 1010**

Communication System: UID 0 - CW; Frequency: 600 MHz

Medium parameters used:  $f = 600$  MHz;  $\sigma = 0.93$  S/m;  $\epsilon_r = 55.8$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: ET3DV6 - SN1507; ConvF(6.5, 6.5, 6.5); Calibrated: 31.12.2015;
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn654; Calibrated: 08.07.2015
- Phantom: ELI v4.0; Type: QDOVA001BB; Serial: TP:1003
- DASY52 52.8.8(1258); SEMCAD X 14.6.10(7372)

**Dipole Calibration for Body Tissue/Pin=250 mW, d=15mm/Zoom Scan (7x7x7)/Cube 0:**

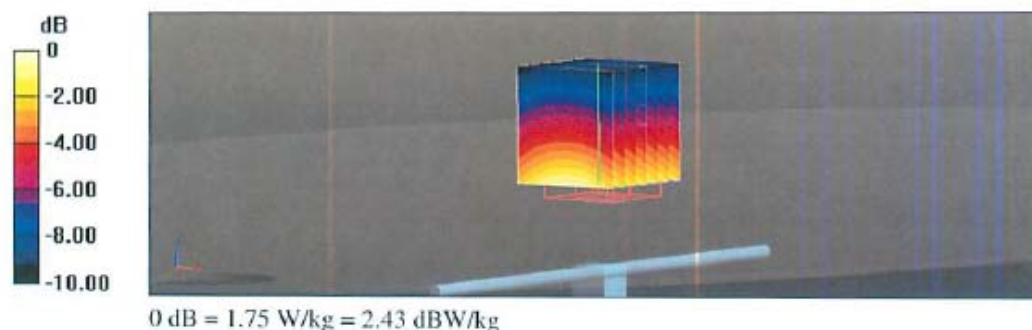
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 44.43 V/m; Power Drift = -0.03 dB

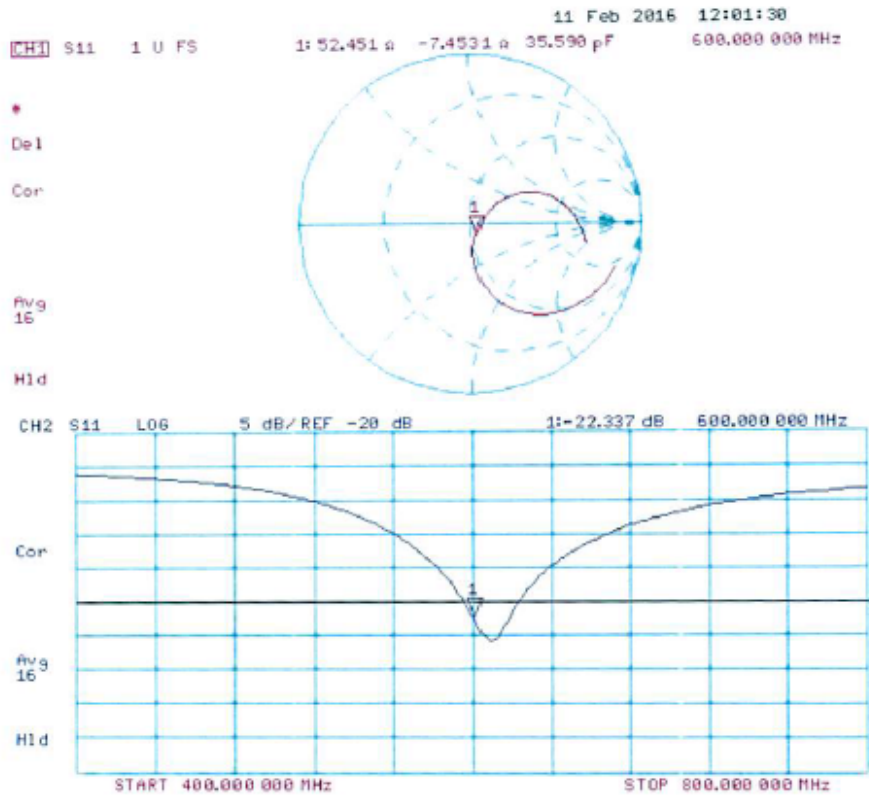
Peak SAR (extrapolated) = 2.61 W/kg

**SAR(1 g) = 1.64 W/kg; SAR(10 g) = 1.07 W/kg**

Maximum value of SAR (measured) = 1.75 W/kg



### Impedance Measurement Plot for Body TSL



## 13 Appendix D - Test System Verifications Scans

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

### 600 MHz Body System Validation

**DUT: Dipole 600 MHz; Type: D600V3; Serial: 1010**

Communication System: CW; Frequency: 600 MHz; Duty Cycle: 1:1

Medium parameters used:  $f = 600$  MHz;  $\sigma = 0.97$  mho/m;  $\epsilon_r = 56.8$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASYS4 (High Precision Assessment)

DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(9.19, 9.19, 9.19); Calibrated: 9/23/2016
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn530; Calibrated: 9/21/2016
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASYS4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 186

**d =15 mm, Pin = 20 dBm/Area Scan (91x201x1):** Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.682 mW/g

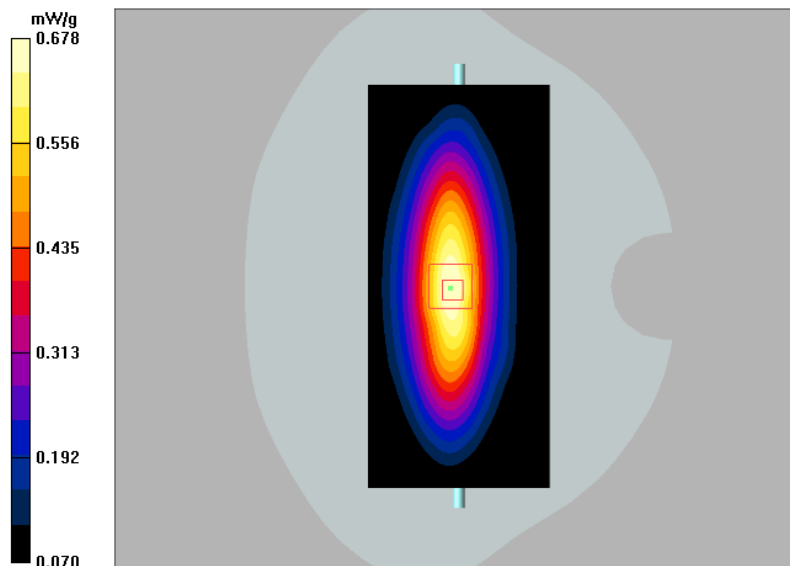
**d =15 mm, Pin = 20 dBm/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 26.4 V/m; Power Drift = 0.021 dB

Peak SAR (extrapolated) = 0.964 W/kg

**SAR(1 g) = 0.632 mW/g; SAR(10 g) = 0.418 mW/g**

Maximum value of SAR (measured) = 0.678 mW/g



## 14 Appendix E - EUT Scan Results

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

**Rear Side Touch SMDWB-A1 Mid 503.8 MHz**

**DUT: Lectrosonics; Type: Wireless Microphone Transmitter; Serial: 1**

Communication System: CW; Frequency: 503.8 MHz; Duty Cycle: 1:1

Medium parameters used:  $f = 503.8$  MHz;  $\sigma = 0.96$  mho/m;  $\epsilon_r = 57.9$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(10.05, 10.05, 10.05); Calibrated: 9/23/2016
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn530; Calibrated: 9/21/2016
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 186

**Back Touch Mid CH/Area Scan (71x171x1):** Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.756 mW/g

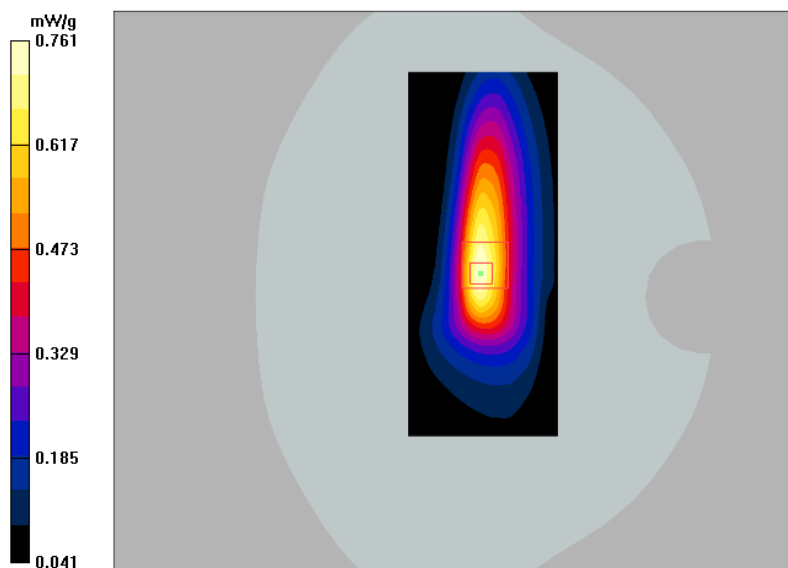
**Back Touch Mid CH/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 16.8 V/m; Power Drift = 0.058 dB

Peak SAR (extrapolated) = 1.28 W/kg

**SAR(1 g) = 0.691 mW/g; SAR(10 g) = 0.403 mW/g**

Maximum value of SAR (measured) = 0.761 mW/g



#1

## 15 Appendix F- RF Output Power Measurement

### RF Output Power Measurement Results

Channel	Frequency (MHz)	Conducted Output Power (dBm)	Target Power (dBm)	Rated Power (mW/dBm)
<b>SMWB-A1</b>				
Middle	503.8	20.12	20	100/20
Low	470.1	20.06	20	100/20
High	537.5	19.96	20	100/20
<b>SMDWB-A1</b>				
Middle	503.8	19.98	20	100/20
Low	470.1	19.92	20	100/20
High	537.5	19.84	20	100/20

## 16 Appendix J - Informative References

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