

### **PCTEST**

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## **HEARING AID COMPATIBILITY**

Applicant Name: Microsoft Corporation One Microsoft Way Redmond, WA 98052 United States Date of Testing: 9/20/2021 - 9/24/2021 Test Site/Location: PCTEST, Columbia, MD, USA Test Report Serial No.: 1M2109130107-02.C3K Date of Issue: 10/7/2021

FCC ID: C3K1995

APPLICANT: MICROSOFT CORPORATION

Scope of Test: RF Emissions Testing
Application Type: Class II Permissive Change

FCC Rule Part(s): CFR §20.19(b)
HAC Standard: ANSI C63.19-2011

285076 D01 HAC Guidance v05

285076 D02 T-Coil testing for CMRS IP v03

**DUT Type:** Portable Handset

**Model:** 1995

**Test Device Serial No.:** Pre-Production Sample [S/N: 22545] **Class II Permissive Change(s):** See FCC Change Document

Original Grant Date: 9/17/2021

C63.19-2011 HAC Category: M3 (RF EMISSIONS CATEGORY)

The Worst-case configuration from the original certification report (Report S/N: 1M2105060048-18.C3K) for the associated portable handset was evaluated with the WPT Sleeve. Hearing-Aid Compatibility is based on the assumption that all production units will be designed electrically identical to the device tested in this report. Test results reported herein relate only to the item(s) tested. North America bands only.

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them.







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### 1. INTRODUCTION

On July 10, 2003, the Federal Communications Commission (FCC) adopted new rules requiring wireless manufacturers and service providers to provide digital wireless phones that are compatible with hearing aids. The FCC has modified the exemption for wireless phones under the Hearing Aid Compatibility Act of 1998 (HAC Act) in WT Docket 01-309 RM-8658¹ to extend the benefits of wireless telecommunications to individuals with hearing disabilities. These benefits encompass business, social and emergency communications, which increase the value of the wireless network for everyone. An estimated more than 10% of the population in the United States show signs of hearing impairment and of that fraction, almost 80% use hearing aids. Approximately 500 million people worldwide suffer from hearing loss.

### **Compatibility Tests Involved:**

The standard calls for wireless communications devices to be measured for:

- RF Electric-field emissions
- T-coil mode, magnetic-signal strength in the audio band
- T-coil mode, magnetic-signal frequency response through the audio band
- T-coil mode, magnetic-signal and noise articulation index

The hearing aid must be measured for:

- RF immunity in microphone mode
- RF immunity in T-coil mode

In the following tests and results, this report includes the evaluation for a wireless communications device.



Figure 1-1 Hearing Aid in-vitu

<sup>&</sup>lt;sup>1</sup> FCC Rule & Order, WT Docket 01-309 RM-8658

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# 2. DUT DESCRIPTION



FCC ID: C3K1995

Manufacturer: Microsoft Corporation

One Microsoft Way Redmond, WA 98052

**United States** 

Model: 1995 Serial Number: 22545

Antenna Configurations: Internal Antenna
DUT Type: Portable Handset

### I. Device Configuration Testing

This device supports held to ear scenarios in both flip and flat postures. All tested modes for this device were fully evaluated in both postures.

### **II. Accessory Testing**

This device was evaluated with the WPT Sleeve. Since this accessory has no additional transmitters, only the overall worst-case standalone configuration from the Original Certification Test Report was evaluated.

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### **Table 2-1** C3K1995 HAC Air Interfaces

			00.1.000	TIAC All IIILEITACES	
Air-Interface	Band (MHz)	Type Transport	HAC Tested	Simultaneous But Not Tested	Name of Voice Service
	850		1		0.486.4
GSM	1900	VO	No <sup>1</sup>	Yes: WIFI or BT	CMRS Voice
	GPRS/EDGE	VD	No <sup>1</sup>	Yes: WIFI or BT	Google Duo
	850	VD	No <sup>1</sup>	Yes: WIFI or BT	CMRS Voice
UMTS	1900	VD	INU	res. Wiri Oi Bi	CIVINS VOICE
	HSPA	VD	No <sup>1</sup>	Yes: WIFI or BT	Google Duo
	680 (B71)		No <sup>1</sup>		
	700 (B12)				
	780 (B13)				
	790 (B14)				
	850 (B5)				
LTE (FDD)	850 (B26)	VD	No <sup>1</sup>	Yes: NR, WIFI or BT	VoLTE, Google Duo
1700 (B4)	1700 (B4)	VD		res. NN, WIFI OI BI	
	1700 (B66)				
	1900 (B2)				
	1900 (B25)				
2300 (B3	2300 (B30)				
	2500 (B7)				
LTE (TDD)	2600 (B41)	VD	No <sup>1</sup>	Vest ND WIFL or DT	ValTE Caarla Dua
LTE (TDD)	3600 (B48)	VD	NO.	Yes: NR, WIFI or BT	VoLTE, Google Duo
	680 (n71)		No <sup>1</sup>		
	850 (n5)				
NR (FDD)	1700 (n66)	VD	No1	Yes: LTE, WIFI or BT	Google Duo
	1900 (n2)		No <sup>1</sup>		
	1900 (n25)				
	2600 (n41)		Yes <sup>1</sup>		Coordo Duo
ND (TDD)	3700 (n77)	VD		Yes: LTE, WIFI or BT	
NR (TDD)	28000 (n261)	νυ	No <sup>1</sup>		Google Duo
	39000 (n260)				
	2450				
	5200 (U-NII 1)				
WIFI	5300 (U-NII 2A)	VD	No <sup>1</sup>	Yes: GSM, UMTS, LTE, or NR	VoWIFI, Google Duo
	5500 (U-NII 2C)	İ			
	5800 (U-NII 3)				
ВТ	2450	DT	No	Yes: GSM, UMTS, LTE, or NR	N/A
-				only pertains only to the evaluation of NR n41 w riginal certification report (Report S/N: 1M210506	•

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# 3. ANSI/IEEE C63.19 PERFORMANCE CATEGORIES

### I. RF EMISSIONS

The ANSI Standard presents performance requirements for acceptable interoperability of hearing aids with wireless communications devices. When these parameters are met, a hearing aid operates acceptably in close proximity to a wireless communications device.

Category	Telephone RF Parameters		
Near field Category	E-field emissions CW dB(V/m)		
	f < 960 MHz		
M1	50 to 55		
M2	45 to 50		
М3	40 to 45		
M4	< 40		
	f > 960 MHz		
M1	40 to 45		
M2	35 to 40		
М3	30 to 35		
M4	< 30		
Table 3-1 WD near-field categories as defined in ANSI C63.19-2011			

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# 4. SYSTEM SPECIFICATIONS

#### **EF3DV3 E-Field Probe Description**

Construction: One dipole parallel, two dipoles normal to probe axis

Built-in shielding against static charges

Calibration: In air from 30 MHz to 6.0 GHz

(absolute accuracy ±5.1%, k=2)

Frequency: 30 MHz to > 6 GHz;

Linearity: ± 0.2 dB (30 MHz to 6 GHz)

Directivity  $\pm 0.2 \text{ dB}$  in air (rotation around probe axis)

± 0.4 dB in air (rotation normal to probe axis)

Dynamic Range 2 V/m to > 1000 V/m

(M3 or better device readings fall well below diode

compression point)

Linearity: ± 0.2 dB

Dimensions Overall length: 337 mm (Tip: 20 mm)

Tip diameter: 4.0 mm (Body: 12 mm)

Distance from probe tip to dipole centers: 1.5 mm



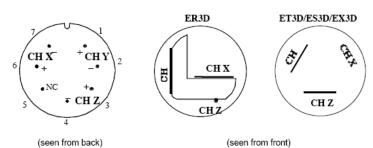
Figure 4-1
E-field Free-space
Probe

#### **Probe Tip Description**

HAC field measurements take place in the close near field with high gradients. Increasing the measuring distance from the source will generally decrease the measured field values (in case of the validation dipole approx. 10% per mm).

The electric field probes have an irregular internal geometry because it is physically not possible to have the 3 orthogonal sensors situated with the same center. The effect of the different sensor centers is accounted for in the HAC uncertainty budget ("sensor displacement").

#### Connector Plan



The antistatic shielding inside the probe is connected to the probe connector case.

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#### **Equation 1**

### Conversion of Connector Voltage u, to E-Field E,

$$E_i = \sqrt{\frac{u_i + (u_i^2 \cdot CF)/(DCP)}{Norm_i \cdot ConvF}}$$

whereby

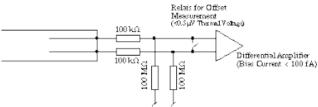
E<sub>i</sub>: electric field in V/m

 $u_i$ : voltage of channel i at the connector in  $\mu V$ Norm<sub>i</sub>: sensitivity of channel i in  $\mu V/(V/m)^2$ enhancement factor in liquid (ConvF=1 for Air)

DCP: diode compression point in  $\mu V$ 

CF: signal crest factor (peak power/average power)

#### Conditions of Calibration



Please note:

- a lower input impedance of the amplifier will result in different sensitivity factors Norm, and DCP
- · larger bias currents will cause higher offset

#### **Probe Response to Frequency**

The E-field sensors have inherently a very flat frequency response. They are calibrated with a number of frequencies resulting in a common calibration factor, with the frequency behavior documented in the calibration certificate (See also below).

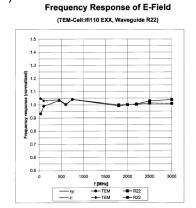


Figure 4-2 E-Field Probe Frequency Response

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#### **SPEAG Robotic System**

E-field measurements are performed using the DASY5 automated dosimetric assessment system. The DASY5 is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, Intel CORE i7 computer, near-field probe, probe alignment sensor, and the HAC phantom. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF).



**Figure 4-3** SPEAG Robotic System

#### **System Hardware**

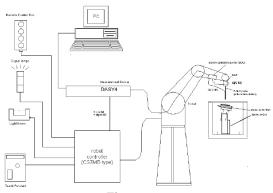
A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and a remote control used to drive the robot motors. The PC consists of the computer with operating system and RF Measurement Software DASY5 v52.8 (with HAC Extension), A/D interface card, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

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#### **System Electronics**

The DAE consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.



**Figure 4-4**SPEAG Robotic System Diagram

#### **DASY5 Instrumentation Chain**

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$\begin{aligned} V_i &= U_i + U_i^2 \cdot \frac{cf}{dcp_i} \\ \text{with} \quad &V_i &= \text{compensated signal of channel i} & (i = x, y, z) \\ &U_i &= \text{input signal of channel i} & (i = x, y, z) \\ &cf &= \text{crest factor of exciting field} & (\text{DASY parameter}) \\ &dcp_i &= \text{diode compression point} & (\text{DASY parameter}) \end{aligned}$$

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From the compensated input signals the primary field data for each channel can be evaluated:

E – field  
probes : 
$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

with  $V_i$  = compensated signal of channel i (i = x, y, z)  $Norm_i$  = sensor sensitivity of channel i (i = x, y, z)

 $\mu V/(V/m)^2$  for E-field Probes

ConvF = sensitivity enhancement in solution

 $E_i$  = electric field strength of channel i in V/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

The measurement/integration time per point, as specified by the system manufacturer is >500ms.

The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/off switch of the power source with an integration time of 500ms and a probe response time of <5 ms. In the current implementation, DASY5 waits longer than 100ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization. The tolerances for the different systems had the worst-case of 2.6%.

#### **Environmental Conditions**

Environmental conditions such as temperature and relative humidity are monitored to ensure there are no impacts on system specifications. Proper voltage and power line frequency conditions are maintained with three phase power sources. Environmental noise and reflections are monitored through system checks.

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# 5. TEST PROCEDURE

#### I. RF EMISSIONS

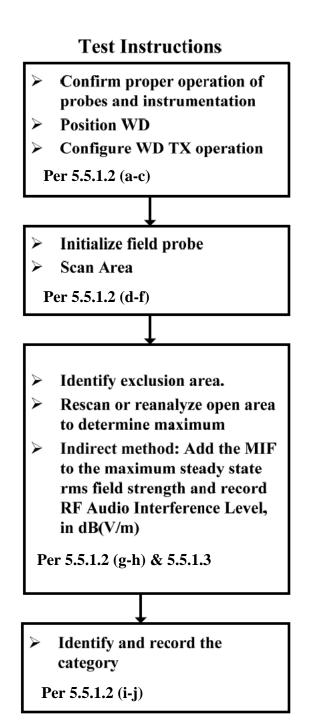


Figure 5-1 RF Emissions Flow Chart

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### **Test Setup**

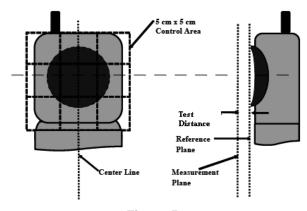


Figure 5-2
E-Field Emissions Test Setup Diagram (See Test Photographs for actual WD scan grid overlay)

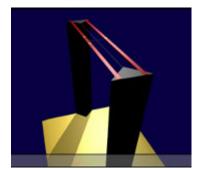


Figure 5-3 HAC Phantom

#### **RF Emissions Test Procedure:**

The following illustrate a typical RF emissions test scan over a wireless communications device:

- 1. Proper operation of the field probe, probe measurement system, other instrumentation, and the positioning system was confirmed.
- 2. WD is positioned in its intended test position, acoustic output point of the device perpendicular to the field probe.
- 3. The WD operation for maximum rated RF output power was configured and confirmed with the base station simulator, at the test channel and other normal operating parameters as intended for the test. The battery was ensured to be fully charged before each test.
- 4. The center sub-grid was centered over the center of the acoustic output (also audio band magnetic output, if applicable). The WD audio output was positioned tangent (as physically possible) to the measurement plane.
- 5. A surface calibration was performed before each setup change to ensure repeatable spacing and proper maintenance of the measurement plane using the HAC Phantom.
- 6. The measurement system measured the field strength at the reference location.
- 7. Measurements at 2mm or 5mm increments in the 5 x 5 cm region were performed at a distance 15 mm from the center point of the probe measurement element to the WD. Of the 9 subgrids (see Figure 5-2), 3 contiguous subgrids may be excluded from the measurement in order to account for localized areas of higher field intensities. The center subgrid containing the acoustic output or audio band magnetic output may not excluded. A 360° rotation about the azimuth axis at the maximum interpolated position was measured. For the worst-case condition, the peak reading from this rotation was used in re-evaluating the HAC category.
- 8. The system performed a drift evaluation by measuring the field at the reference location. If the power drift deviated by more than 5%, the HAC test and drift measurements were repeated.

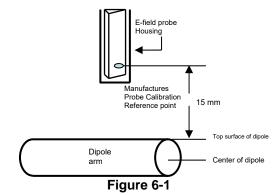
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#### SYSTEM CHECK 6.

#### I. System Check Parameters

The input signal was an un-modulated continuous wave. The following points were taken into consideration in performing this check:

- Average Input Power P = 100mW RMS (20dBm RMS) after adjustment for return loss
- The test fixture must meet the 2 wavelength separation criterion
- The proper measurement of the 15 mm probe to dipole separation, which is measured from top surface of the dipole to the calibration reference point of the sensor, defined by the probe manufacturer is shown in the following diagram:



Separation Distance from Dipole to Field Probe

RF power was recorded using both an average reading meter and a peak reading meter. Readings of the probe are provided by the measurement system.

To assure proper operation of the near-field measurement probe the input power to the dipole shall be commensurate with the full rated output power of the wireless device [e.g. - for a cellular phone wireless device the average peak antenna input power will be on the order of 100mW (20dBm) RMS] after adjustment for any mismatch.

#### II. **Validation Procedure**

A dipole antenna meeting the requirements given in C63.19 was placed in the position normally occupied by the WD.

The length of the dipole was scanned, and the average peak value was recorded.

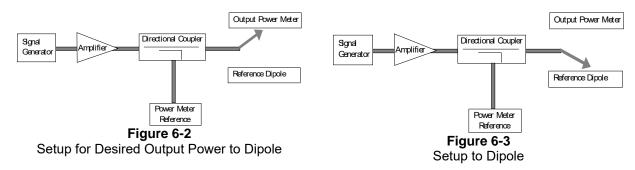
#### Measurement of CW

Using the near-field measurement system, scan the antenna over the radiating dipole and record the greatest field reading observed. Due to the nature of E-fields about free-space dipoles, the two E-field peaks measured over the dipole are averaged to compensate for non-parallelity of the setup (see manufacturer method on dipole calibration certificates, page 2). Field strength measurements shall be made only when the probe is stationary.

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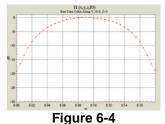
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RF power was recorded using both an average and a peak power reading meter.



Using this setup configuration, the signal generator was adjusted for the desired output power (100mW) at a specified frequency. The reference power from the coupled port of the directional coupler is recorded. Next, the output cable is connected to the reference dipole, as shown in Figure 6-3.

The input signal level was adjusted until the reference power from the coupled port of the directional coupler was the same as previously recorded, to compensate for the impedance mismatch between the output cable and the reference dipole. To assure proper operation of the near-field measurement probe the input power to the reference dipole was verified to the full rated output power of the wireless device. The dipole was secured in a holder in a manner to meet the 20 dB reflection. The near-field measurement probe was positioned over the dipole. The antenna was scanned over the appropriate sized area to cover the dipole from end to end. SPEAG uses 2D interpolation algorithms between the measured points. Please see below two dimensional plots showing that the interpolated values interpolate smoothly between 5mm steps for a free-space RF dipole:



2-D Raw Data from scan along dipole axis

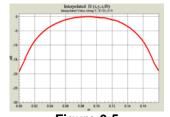
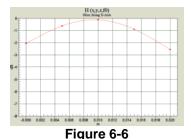


Figure 6-5
2-D Interpolated points from scan along dipole axis



2-D Raw Data from scan along transverse axis



2-D Interpolated points from scan along transverse axis

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# III. System Check Results

### **Validation Results**

Date	Frequency (MHz)	Probe S/N	DAE S/N	Dipole S/N	Input Power (dBm)	E-field Result (V/m)	Target Field (V/m)	% Deviation
9/20/2021	2600	4035	1530	1012	20.0	86.7	86.5	0.2%

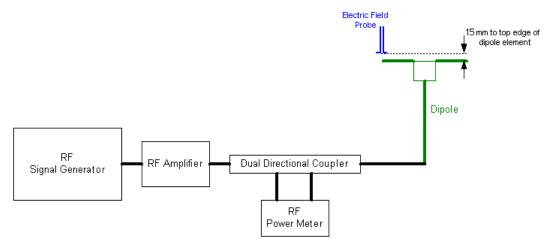


Figure 6-8 System Check Setup

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# 7. MODULATION INTERFERENCE FACTOR

# I. Measuring Modulation Interference Factors

For any specific fixed and repeatable modulated signal, a modulation interference factor (MIF, expressed in dB) may be determined that relates its interference potential to its steady-state RMS signal level or average power level. This factor is a function only of the audio-frequency amplitude modulation characteristics of the signal and is the same for field-strength and conducted power measurements. The MIF is valid only for a specific repeatable audio-frequency amplitude modulation characteristic; any change in modulation characteristic requires determination and application of a new MIF.

The MIF may be determined using a radiated RF field or a conducted RF signal:

- a. Using RF illumination or conducted coupling, apply the specific modulated signal in question to the measurement system at a level within its confirmed operating dynamic range.
- b. Measure the steady-state RMS level at the output of the fast probe or sensor.
- c. Measure the steady-state average level at the weighting output.
- d. Without changing the square-law detector or weighting system, and using RF illumination or conducted coupling, substitute for the specific modulated signal a 1 kHz, 80% amplitude modulated carrier at the same frequency and adjust its strength until the level at the weighting output equals the step c) measurement.
- e. Without changing the carrier level from step d), remove the 1 kHz modulation and again measure the steady-state RMS level indicated at the output of the fast probe or sensor.
- f. The MIF for the specific modulation characteristic is provided by the ratio of the step e) measurement to the step b) measurement, expressed in dB (20 × log[(step e)/(step b)]).

The following procedure was used to measure the MIF using the SPEAG Audio Interference Analyzer (AIA), Type No: SE UMS 170 CB, Serial No.: 1010:

- 1. The device was placed into a simulated call using a base station simulator or set to transmit using test software for a given mode.
- 2. The device was then set to continuously transmit at maximum power.
- 3. Using a coupler if needed, the device output signal was connected to the RF In port of the AIA, which was connected to a desktop computer. Alternatively, a radiated RF signal may be used with the AIA's built-in antenna.
- 4. The MIF measurement procedure in the DASY software was run, and the resulting MIF value was recorded.
- 5. Steps 1-4 were repeated for all CMRS air interfaces, frequency bands, and modulations.

The modulation interference factors obtained were applied to readings taken of the actual wireless device in order to obtain an accurate audio interference level reading using the formula:

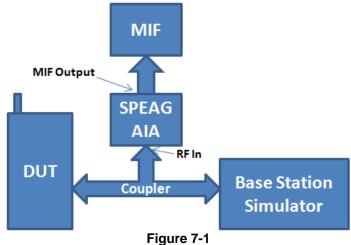
#### Audio Interference Level [dB(V/m)] = 20 \* log[Raw Field Value (V/m)] + MIF (dB)

Because the MIF value is output power independent, MIF values for a given mode should be constant across all devices; however, per C63.19-2011 §D.7, MIF values should be measured for each device being evaluated. The applicable modes for this device have been investigated in this section of the report.

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# II. MIF Measurement Block Diagram



MIF Measurement Setup for licensed modes

### **III.** Measured Modulation Interference Factors:

**Table 7-1**NR TDD n41 Modulation Interference Factors<sup>1</sup>

	1417 100 1141 Modulation Interference Lactors							
NR Band	Frequency [MHz]	Channel	Bandwidth [MHz]	Waveform	Modulation	RB Size	RB Offset	MIF [dB]
n41	2593.0	518598	20	DFT-s-OFDM	π/2-BPSK	1	1	-1.23
n41	2593.0	518598	20	DFT-s-OFDM	QPSK	1	1	-1.26
n41	2593.0	518598	20	DFT-s-OFDM	16QAM	1	1	-1.25
n41	2593.0	518598	20	DFT-s-OFDM	64QAM	1	1	-1.26
n41	2593.0	518598	20	CP-OFDM	QPSK	1	1	-1.30
n41	2593.0	518598	20	CP-OFDM	16QAM	1	1	-1.31
n41	2593.0	518598	20	CP-OFDM	64QAM	1	1	-1.36
n41	2593.0	518598	100	DFT-s-OFDM	256QAM	1	137	-1.22
n41	2593.0	518598	100	DFT-s-OFDM	256QAM	1	271	-1.20
n41	2593.0	518598	100	DFT-s-OFDM	256QAM	135	0	-1.28
n41	2593.0	518598	100	DFT-s-OFDM	256QAM	270	0	-1.25
n41	2593.0	518598	90	DFT-s-OFDM	256QAM	1	243	-1.20
n41	2593.0	518598	80	DFT-s-OFDM	256QAM	1	215	-1.21
n41	2593.0	518598	60	DFT-s-OFDM	256QAM	1	160	-1.20
n41	2593.0	518598	50	DFT-s-OFDM	256QAM	1	131	-1.21
n41	2593.0	518598	40	DFT-s-OFDM	256QAM	1	104	-1.20
n41	2593.0	518598	30	DFT-s-OFDM	256QAM	1	76	-1.19
n41	2593.0	518598	20	DFT-s-OFDM	256QAM	1	49	-1.21
n41	2511.0	502200	30	DFT-s-OFDM	256QAM	1	76	-1.20
n41	2552.0	510402	30	DFT-s-OFDM	256QAM	1	76	-1.21
n41	2634.0	526800	30	DFT-s-OFDM	256QAM	1	76	-1.21
n41	2675.0	534996	30	DFT-s-OFDM	256QAM	1	76	-1.21

<sup>&</sup>lt;sup>1</sup> Note: Measured MIF values may be lower than sample MIF values provided in ANSI C63.19-2011 Annex D.7 Table D.5 due to manufacturing variations for each device, however per Annex D.7, the sample MIF values of Table D.5 are not intended to substitute for measurements of actual devices under test and their respective operating modes.

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# 8. CONDUCTED POWER CONFIGURATIONS AND TARGETS

# I. Procedures Used to Establish RF Signal for HAC Testing

The handset was configured to transmit the required air interface in a shielded chamber. Measurements were taken with a fully charged battery.

### II. HAC Target Powers

All applicable modes supported by the device have their held-to-ear conducted power targets listed below and were used for the individual mode evaluations in Section 9. All licensed modes conducted power targets have a tolerance of +1.0dB and -1.5dB unless otherwise noted.

### III. RF Conducted Power Measurement Setup and Conditions

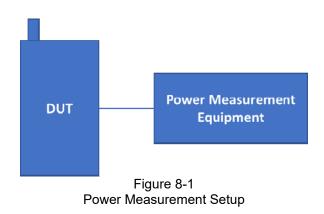
#### **Output Power Verification**

Maximum output power is verified for all applicable test channels for all air interfaces which require test scans. See Table 8-1 for air interface specific settings of transmit power parameters. See Table 9-1 for more information regarding which modes required test scans and had conducted power measurements taken.

Table 8-1
Power Control Parameters and Settings by Air Interface

Air Interface:	Parameter Name:	Parameter Set To:
NR	PLS	Mfr Specified

The general setup for conducted powers included in Section 11 is shown in Figure 8-1 below. The power measurement equipment could be a base station simulator, signal analyzer, or power meter depending on the applicable air interface.



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# IV. NR TDD Target Powers

Table 8-2 NR TDD Conducted Power Targets

Band	Modulated Average Output Power (in dBm)
NR Band n41 PC3	22.5

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# 9. JUSTIFICATION OF HELD TO EAR MODES TESTED

### I. Analysis of RF Air Interface Technologies

An analysis was performed, following the guidance of §4.3 and §4.4 of the ANSI standard, of the RF air interface technologies being evaluated. The factors that will affect the RF interference potential were evaluated, and the worst-case operating modes were identified and used in the evaluation. A WD's interference potential is a function both of the WD's average near-field field strength and of the signal's audio-frequency amplitude modulation characteristics. Per §4.4, RF air interface technologies that have low power have been found to produce sufficiently low RF interference potential, so it is possible to exempt them from the product testing specified in Clause 5 of the ANSI standard. An RF air interface technology of a device is exempt from testing when its average antenna input power plus its MIF is ≤17dBm for all of its operating modes. RF air interface technologies exempted from testing in this manner are automatically assigned an M4 rating to be used in determining the overall rating for the WD.

The worst-case MIF plus the worst-case average antenna input power for all modes are investigated below to determine the testing requirements for this device.

### II. Individual Mode Evaluations

Table 9-1
Max Power + MIF calculations for Low Power Exemptions

		o. = , ( o o		
Air Interface	Maximum Average Power (dBm)	Worst Case MIF (dB)	Total (Power + MIF, dB)	C63.19 Testing Required
NR TDD - n41	20.49*	-1.19	19.30	Yes
1417 100 - 1141	20.70	- 1.13	15.50	103

<sup>\*</sup> Note: ANSI C63.19-2011 Sec. 4.4 Footnote 20 indicates the use of a long averaging time for measuring the antenna input power when using this method of exclusion. Therefore, the frame averaged power was calculated for these modes in this investigation.

#### III. Low-Power Exemption Conclusions

Per ANSI C63.19-2011, RF Emissions testing for this device is required for NR TDD data mode and was evaluated with the WPT sleeve.

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# 10. OVERALL MEASUREMENT SUMMARY

FCC ID:	C3K1995
S/N:	22545

### I. E-FIELD EMISSIONS:

#### **Table 10-1**

HAC Data Summary for NR TDD n41 E-field (North Antenna, Flip Posture)

		IIAC	Dala	Summe	ary ic	או וע	17 1	רוו טט		ciu (iv		,,,re,,,	ıa, ı ıı	ргоз	iui <del>c</del> j		
Mode / Band	Bandwidth (MHz)	Channel	Accessory	Waveform	Mod.	RB Size	RB Offset	Scan Center	Conducted Power at BS (dBm)	Time Avg. Field (V/m)	Time Avg. Field [dB(V/m)]	MIF (dB)	Audio Interference Level [dB(V/m)]	FCC Limit (dBV/m)	FCC Margin (dB)	Result	Excl Blocks per 5.5
E-Field Emission	ons																
NR TDD / n41	30	526800	WPT Sleeve	DFT-s-OFDM	π/2-BPSK	1	1	Acoustic	22.56	50.45	34.06	-1.21	32.85	35.00	-2.15	M3	none
NK 1007 1141	30	526800	WPT Sleeve	DFT-s-OFDM	π/2-BPSK	1	1	T-Coil	22.56	49.95	33.97	-1.21	32.76	35.00	-2.24	M3	none

#### **Table 10-2**

HAC Data Summary for NR TDD n41 E-field (North Antenna, Flat Posture)

Mode / Band	Bandwidth (MHz)	Channel	Accessory	Waveform	Mod.	RB Size	RB Offset	Scan Center	Conducted Power at BS (dBm)	Time Avg. Field (V/m)	Time Avg. Field [dB(V/m)]	MIF (dB)	Audio Interference Level [dB(V/m)]	FCC Limit (dBV/m)	FCC Margin (dB)	Result	Excl Blocks per 5.5
E-Field Emission	E-Field Emissions																
NR TDD / n41	30	526800	WPT Sleeve	DFT-s-OFDM	π/2-BPSK	1	1	Acoustic	22.56	47.47	33.53	-1.21	32.32	35.00	-2.68	M3	none

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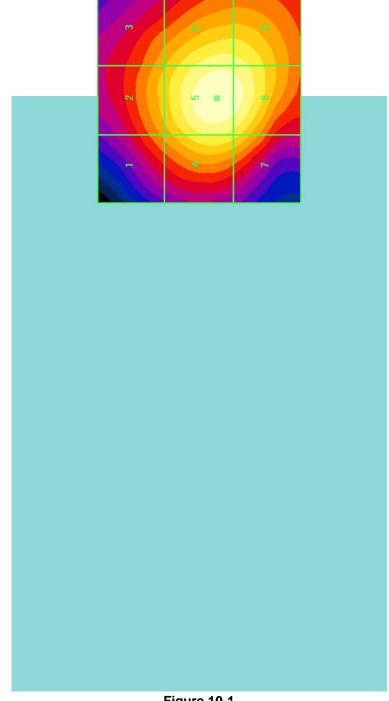


Figure 10-1 Sample E-field Scan Overlay (See Test Setup Photographs for actual WD overlay)

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# II. Worst-case Configuration Evaluation

Table 10-3
Peak Reading 360° Probe Rotation at Azimuth axis (North Antenna, Flip Posture)

Mode	Bandwidth (MHz)	Channel	Accessory	Waveform	Mod.	RB Size	RB Offset	Scan Center	Time Avg. Field (V/m)	Time Avg. Field [dB(V/m)]	MIF (dB)	Audio Interference Level [dB(V/m)]	FCC Limit (dBV/m)	FCC Margin (dB)	Result	Excl Blocks per 5.5
Probe Rotation	Probe Rotation at Worst-Case															
NR TDD / n41	30	526800	WPT Sleeve	DFT-s-OFDM	π/2-BPSK	1	1	Acoustic	52.35	34.38	-1.21	33.17	35.00	-1.83	М3	none

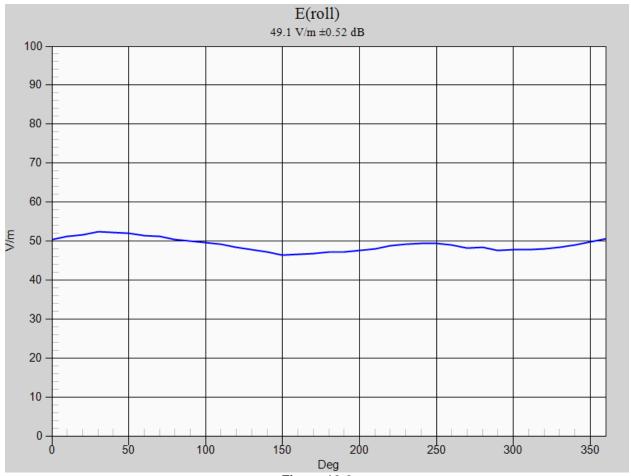


Figure 10-2
Worst-Case Probe Rotation about Azimuth axis

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<sup>\*</sup> Note: Locations of probe rotation (with and without exclusions) are shown in Figure 10-1 denoted by the green square markers.

#### 11. **EQUIPMENT LIST**

**Table 11-1 Equipment List** 

Manufacturer	Model	Description	Cal Date	Cal Interval	Cal Due	Serial Number
Agilent	E4438C	ESG Vector Signal Generator	12/14/2020	Biennial	12/14/2022	MY42082385
Agilent	E4432B	ESG-D Series Signal Generator	2/24/2021	Annual	2/24/2022	US40053896
Agilent	N5182A	MXG Vector Signal Generator	12/1/2020	Annual	12/1/2021	MY47420837
Amplifier Research	15S1G6	Amplifier	N/A	CBT*	N/A	433978
Anritsu	ML2496A	Power Meter	4/21/2021	Annual	4/21/2022	1351001
Anritsu	MA2411B	Pulse Power Sensor	3/8/2021	Annual	3/8/2022	1339007
Anritsu	MA2411B	Pulse Power Sensor	3/9/2021	Annual	3/9/2022	1207470
Anritsu	MA24106A	USB Power Sensor	3/3/2021	Annual	3/3/2022	1344556
Anritsu	MA24106A	USB Power Sensor	5/3/2021	Annual	5/3/2022	1349514
Mini-Circuits	NLP-2950+	Low Pass Filter DC to 2700 MHz	N/A	CBT*	N/A	N/A
Mini-Circuits	BW-N20W5	Power Attenuator	N/A	CBT*	N/A	1226
Pasternack	PE2237-20	Directional Coupler	N/A	CBT*	N/A	N/A
Pasternack	NC-100	Torque Wrench	8/4/2020	Biennial	8/4/2022	N/A
Rohde & Schwarz	CMW500	Wideband Radio Communication Tester	3/22/2021	Annual	3/22/2022	162125
Rohde & Schwarz	CMW500	Wideband Radio Communication Tester	2/10/2021	Annual	2/10/2022	161662
SPEAG	AIA	Audio Interference Analzyer	N/A	CBT*	N/A	1010
SPEAG	CD2600V3	Freespace 2600MHz Dipole	1/14/2021	Biennial	1/14/2023	1012
SPEAG	EF3DV3	Freespace E-field Probe	2/15/2021	Biennial	2/15/2023	4035
SPEAG	DAE4	Dasy Data Acquisition Electronics	1/13/2021	Annual	1/13/2022	1530

Calibration traceable to the National Institute of Standards and Technology (NIST).

\*Note: CBT (Calibrated Before Testing). Prior to testing, the measurement paths containing a cable, attenuator, coupler or filter were connected to a calibrated source (i.e. a signal generator) to determine the losses of the measurement path. The power meter offset was then adjusted to compensate for the measurement system losses. This level offset is stored within the power meter before measurements are made. This calibration verification procedure applies to the system verification and output power measurements. The calibrated reading is then taken directly from the power meter after compensation of the losses for all final power measurements.

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#### 12. **MEASUREMENT UNCERTAINTY**

#### **Table 12-1 Uncertainty Estimation Table**

Wireless Communications Device Near-Field Measurement							
			tainty Estima				
Uncertainty Component	Data (dB)	Data Type	Prob. Dist.	Divisor	Ci (E)	Unc. (dB)	Notes/Comments
Measurement System						•	
RF System Reflections	0.50	Tolerance	N	1.00	1	0.50	* Refl. < -20 dB
Field Probe Calibration	0.21	Tolerance	N	1.00	1	0.21	
Field Probe Isotropy	0.01	Tolerance	N	1.00	1	0.01	
Field Probe Frequency Response	0.135	Tolerance	N	1.00	1	0.14	
Field Probe Linearity	0.013	Tolerance	N	1.00	1	0.01	
Modulation Interference Factor	0.20	Tolerance	R	1.73	1	0.12	Applicable for M-rating testing
Boundary Effects	0.105	Accuracy	R	1.73	1	0.06	*
Probe Positioning Accuracy	0.20	Accuracy	R	1.73	1	0.12	*
Probe Positioner	0.050	Accuracy	R	1.73	1	0.03	*
Extrapolation/Interpolation	0.045	Tolerance	R	1.73	1	0.03	*
Resolution to 2mm error	0.21	Tolerance	N	1.00	1	0.21	
System Detection Limit	0.05	Tolerance	R	1.73	1	0.03	*
Readout Electronics	0.015	Tolerance	N	1.00	1	0.02	*
Integration Time	0.11	Tolerance	R	1.73	1	0.06	*
Response Time	0.033	Tolerance	R	1.73	1	0.02	*
Phantom Thickness	0.10	Tolerance	R	1.73	1	0.06	*
System Repeatability (Field x 2=power)	0.17	Tolerance	N	1.00	1	0.17	*
Test Sample Related							
Device Positioning Vertical	0.2	Tolerance	R	1.73	1	0.12	*
Device Positioning Lateral	0.045	Tolerance	R	1.73	1	0.03	*
Device Holder and Phantom	0.1	Tolerance	R	1.73	1	0.06	*
Power Drift	0.21	Tolerance	R	1.73	1	0.12	
Combined Standard Uncertainty (k=1)						0.66	16.3%
Expanded Uncertainty [95% confidence]						1.31	32.6%
Expanded Uncertainty [95% confidence]	on Field					0.66	16.3%

#### Notes:

- Test equipments are calibrated according to techniques outlined in NIS81, NIS3003 and NIST Tech Note 1297, All equipments have traceability according to NIST. Measurement Uncertainties are defined in further detail in NIS 81 and NIST Tech Note 1297 and UKAS M3003.
- \* Uncertainty specifications from Schmidt & Partner Engineering AG (not site specific) 2.

Measurement uncertainty reflects the quality and accuracy of a measured result as compared to the true value. Such statements are generally required when stating results of measurements so that it is clear to the intended audience that the results may differ when reproduced by different facilities. Measurement results vary due to the measurement uncertainty of the instrumentation, measurement technique, and test engineer. Most uncertainties are calculated using the tolerances of the instrumentation used in the measurement, the measurement setup variability, and the technique used in performing the test. While not generally included, the variability of the equipment under test also figures into the overall measurement uncertainty. Another component of the overall uncertainty is based on the variability of repeated measurements (so-called Type A uncertainty). This may mean that the Hearing Aid immunity tests may have to be repeated by taking down the test setup and resetting it up so that there are a statistically significant number of repeat measurements to identify the measurement uncertainty. By combining the repeat measurement results with that of the instrumentation chain using the technique contained in NIS 81 and NIS 3003, the overall measurement uncertainty was estimated.

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# 13. TEST DATA

See following Attached Pages for Test Data.

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#### DUT: CD2600V3 - SN1012

Type: CD2600V3 Serial: 1012

#### Communication System: CW; Frequency: 2600 MHz;

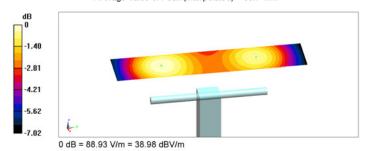
Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

#### DASY5 Configuration:

- Probe: EF3DV3 SN4035; Calibrated: 2/15/2021
- Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE4 Sn1530; Calibrated: 1/13/2021
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA;
- Measurement SW: DASY52, Version 52.10 (4);

#### 2600 MHz / 100mW HAC Dipole Validation at 15mm/Hearing Aid Compatibility Test (41x181x1):

Interpolated grid: dx=0.5000 mm, dy=0.5000 mm Device Reference Point: 0, 0, -6.3 mm Reference Value = 66.45 V/m; Power Drift = 0.05 dB Applied MIF = 0.00 dB Average Value of Peak (interpolated) = 86.7 V/m



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#### **DUT: C3K1995**

Type: Portable Handset Serial: 22545 Backlight off Duty Cycle: 1:2

#### Communication System: n41; Frequency: 2634 MHz;

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

#### DASY5 Configuration:

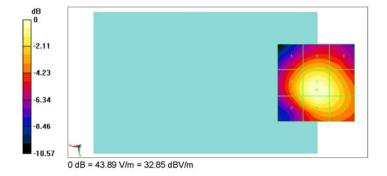
- Probe: EF3DV3 SN4035; Calibrated: 2/15/2021
- Sensor-Surface: (Fix Surface)
- Electronics: DAE4 Sn1530; Calibrated: 1/13/2021
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA;
- Measurement SW: DASY52, Version 52.10 (4);

# NR n41 Mid High Channel, 30MHz, DFT-s-OFDM, π/2-BPSK, 1RB, 1RB Offset, North Antenna, Flip Posture, Accessory:

MHz, DFT-s-OFDM, π/2-BPSK, 1RB, 1RB Offset, North Ante
WPT Sleeve / Hearing Aid Compatibility Test (101x101x1):
Interpolated grid: dx=0.5000 mm, dy=0.5000 mm
Device Reference Point: 0, 0, -6.3 mm
Reference Value = 81.00 V/m; Power Drift = 0.04 dB
Applied MIF = -1.21 dB
RF audio interference level = 32.85 dBV/m Emission category: M3

#### MIF scaled E-field

Grid 1 M4	Grid 2 M3	Grid 3 M4
29.56 dBV/m	30.45 dBV/m	29.94 dBV/m
Grid 4 M3	Grid 5 M3	Grid 6 M3
31.49 dBV/m	32.85 dBV/m	31.98 dBV/m
Grid 7 M3	Grid 8 M3	Grid 9 M3
31.07 dBV/m	32.57 dBV/m	31.87 dBV/m



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# 14. CALIBRATION CERTIFICATES

The following pages include the probe calibration used to evaluate HAC for the DUT.

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Accreditation No.: SCS 0108

Client

Certificate No: EF3 4035 Feb21

### **CALIBRATION CERTIFICATE**

Object

EF3DV3- SN:4035

Calibration procedure(s)

PC Test

QA CAL-02.v9, QA CAL-25.v7

Calibration procedure for E-field probes optimized for close near field

evaluations in air

Calibration date:

February 15, 2021

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature  $(22 \pm 3)^{\circ}$ C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	01-Apr-20 (No. 217-03100/03101)	Apr-21
Power sensor NRP-Z91	SN: 103244	01-Apr-20 (No. 217-03100)	Apr-21
Power sensor NRP-Z91	SN: 103245	01-Apr-20 (No. 217-03101)	Apr-21
Reference 20 dB Attenuator	SN: CC2552 (20x)	31-Mar-20 (No. 217-03106)	Apr-21
DAE4	SN: 789	23-Dec-20 (No. DAE4-789 Dec20)	Dec-21
Reference Probe ER3DV6	SN: 2328	05-Oct-20 (No. ER3-2328_Oct20)	Oct-21
Secondary Standards	ID	Check Date (in house)	Scheduled Check
Power meter E4419B	SN: GB41293874	06-Apr-16 (in house check Jun-20)	In house check: Jun-22
Power sensor E4412A	SN: MY41498087	06-Apr-16 (in house check Jun-20)	In house check: Jun-22
Power sensor E4412A	SN: 000110210	06-Apr-16 (in house check Jun-20)	In house check: Jun-22
RF generator HP 8648C	SN: US3642U01700	04-Aug-99 (in house check Jun-20)	In house check: Jun-22
Network Analyzer E8358A	SN: US41080477	31-Mar-14 (in house check Oct-20)	In house check: Oct-21

	Name	Function	Signature	
Calibrated by:	Michael Weber	Laboratory Technician	MHESET	
Approved by:	Katja Pokovic	Technical Manager	MA	_

Issued: February 16, 2021

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Glossary:

NORMx,y,z sensitivity in free space DCP diode compression point

CF crest factor (1/duty\_cycle) of the RF signal A, B, C, D modulation dependent linearization parameters

En incident E-field orientation parallel to probe axis

Ep incident E-field orientation parallel to probe axis

Polarization  $\phi$   $\phi$  rotation around probe axis

Polarization  $\vartheta$   $\vartheta$  rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e.,  $\vartheta = 0$  is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

#### Calibration is Performed According to the Following Standards:

 IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005

b) CTIA Test Plan for Hearing Aid Compatibility, Rev 3.1.1, May 2017

#### Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization θ = 0 for XY sensors and θ = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- NORM(f)x,y,z = NORMx,y,z \* frequency\_response (see Frequency Response Chart).
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z; Dx,y,z; VRx,y,z: A, B, C, D are numerical linearization parameters assessed based on
  the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor
  media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

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# DASY/EASY - Parameters of Probe: EF3DV3 - SN:4035

#### **Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm $(\mu V/(V/m)^2)$	0.90	0.73	1.19	± 10.1 %
DCP (mV) <sup>B</sup>	96.3	101.2	98.2	

Calibration results for Frequency Response (30 MHz - 6 GHz)

Frequency MHz	Target E-Field V/m	Measured E-field (En) V/m	Deviation E-normal in %	Measured E-field (Ep) V/m	Deviation E-normal in %	Unc (k=2) %
30	77.1	77.0	-0.2%	77.2	0.1%	± 5.1 %
100	77.2	78.3	1.4%	77.8	0.7%	± 5.1 %
450	77.2	78.4	1.6%	77.9	1.0%	± 5.1 %
600	77.1	77.9	1.1%	77.4	0.5%	± 5.1 %
750	77.1	77.8	0.9%	77.3	0.3%	± 5.1 %
1800	143.1	139.0	-2.8%	139.4	-2.6%	± 5.1 %
2000	135.1	131.3	-2.7%	131.5	-2.6%	± 5.1 %
2200	127.7	123.4	-3.3%	124.5	-2.5%	± 5.1 %
2500	125.5	122.4	-2.5%	123.5	-1.6%	± 5.1 %
3000	79.4	75.6	-4.7%	76.7	-3.3%	± 5.1 %
3500	256.9	246.8	-3.9%	243.9	-4.8%	± 5.1 %
3700	251.2	240.8	-4.2%	237.9	-5.0%	± 5.1 %
5200	50.8	51.4	1.3%	51.7	1.9%	± 5.1 %
5500	47.0	46.8	-0.5%	48.2	2.7%	± 5.1 %
5800	48.8	48.6	-0.6%	47.1	-3.6%	± 5.1 %

Calibration Results for Modulation Response

UID	Communication System Name		A dB	B dB√μV	С	D dB	VR mV	Max dev.	Unc <sup>E</sup> (k=2)
0	CW	X	0.0	0.0	1.0	0.00	141.8	± 3.8 %	± 4.7 %
		Y	0.0	0.0	1.0		172.6		
		Z	0.0	0.0	1.0		171.7		

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

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B Numerical linearization parameter: uncertainty not required.

© Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

# DASY/EASY - Parameters of Probe: EF3DV3 - SN:4035

#### **Sensor Frequency Model Parameters**

	Sensor X	Sensor Y	Sensor Z
Frequency Corr. (LF)	0.22	0.19	5.72
Frequency Corr. (HF)	2.82	2.82	2.82

#### Other Probe Parameters

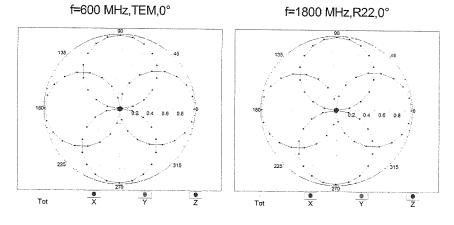
Sensor Arrangement	Rectangular
Connector Angle (°)	-126.8
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	12 mm
Tip Length	25 mm
Tip Diameter	4 mm
Probe Tip to Sensor X Calibration Point	1.5 mm
Probe Tip to Sensor Y Calibration Point	1.5 mm
Probe Tip to Sensor Z Calibration Point	1.5 mm

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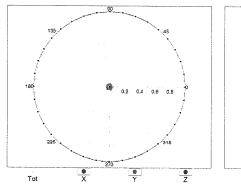
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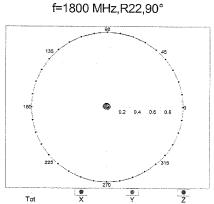
# Receiving Pattern ( $\phi$ ), $\vartheta = 0^{\circ}$



# Receiving Pattern ( $\phi$ ), $\vartheta = 90^{\circ}$



f=600 MHz,TEM,90°



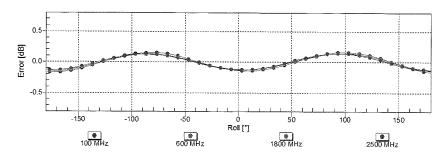
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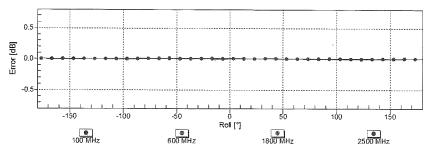
EF3DV3 – SN:4035 February 15, 2021

# Receiving Pattern ( $\phi$ ), $\vartheta = 0^{\circ}$



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

# Receiving Pattern ( $\phi$ ), $\vartheta = 90^{\circ}$



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

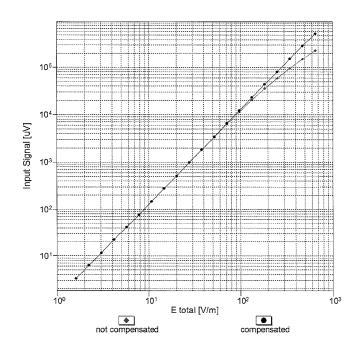
Certificate No: EF3\_4035\_Feb21

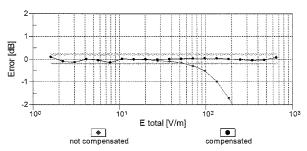
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# Dynamic Range f(E-field) (TEM cell, f = 900 MHz)





Uncertainty of Linearity Assessment: ± 0.6% (k=2)

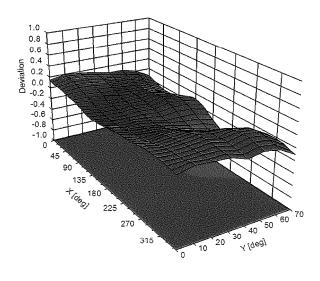
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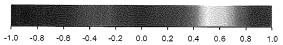
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EF3DV3 - SN:4035 February 15, 2021

# Deviation from Isotropy in Air Error $(\phi, \vartheta)$ , f = 900 MHz





Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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PC Test

Certificate No: CD2600V3-1012\_Jan21

10 <b>7</b> 1000	CD2600V3 - SN:	1012	
Calibration procedure(s)	QA CAL-20.v7 Calibration Proce	dure for Validation Sources in ai	r
Calibration date:	January 14, 2021		
		onal standards, which realize the physical uni	24 N 188 N 18 N 18 N 18 N 18 N 18 N 18 N
he measurements and the uncer	tainties with confidence pr	robability are given on the following pages an	d are part of the certificate.
All calibrations have been conduct	ed in the closed laborator	y facility: environment temperature (22 ± 3)°C	C and humidity < 70%.
Calibration Equipment used (M&T	E critical for calibration)		3/30/20
Primary Standards	ID#	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	01-Apr-20 (No. 217-03100/03101)	Apr-21
Power sensor NRP-Z91	SN: 103244	01-Apr-20 (No. 217-03100)	Apr-21
Power sensor NRP-Z91	SN: 103245	01-Apr-20 (No. 217-03101)	Apr-21
Reference 20 dB Attenuator	SN: BH9394 (20k)	31-Mar-20 (No. 217-03106)	Apr-21
Type-N mismatch combination	SN: 310982 / 06327	31-Mar-20 (No. 217-03104)	Apr-21
Probe EF3DV3	SN: 4013	28-Dec-20 (No. EF3-4013_Dec20)	Dec-21
DAE4	SN: 781	23-Dec-20 (No. DAE4-781_Dec20)	Dec-21
Secondary Standards	ID#	Check Date (in house)	Scheduled Check
Power meter Agilent 4419B	SN: GB42420191	09-Oct-09 (in house check Oct-20)	In house check: Oct-23
Power sensor HP E4412A	SN: US38485102	05-Jan-10 (in house check Oct-20)	In house check: Oct-23
Power sensor HP 8482A	SN: US37295597	09-Oct-09 (in house check Oct-20)	In house check: Oct-23
RF generator R&S SMT-06	SN: 837633/005	10-Jan-19 (in house check Oct-20)	In house check: Oct-23
	SN: US41080477	31-Mar-14 (in house check Oct-20)	In house check: Oct-21
Network Analyzer Agilent E8358A			
	Name	Function	Signature
Network Analyzer Agilent E8358A Calibrated by:	Name Leif Klysner	Function Laboratory Technician	Sed The

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#### References

[1] ANSI-C63.19-2011 American National Standard, Methods of Measurement of Compatibility between Wireless Communications Devices and Hearing Aids.

#### Methods Applied and Interpretation of Parameters:

- Coordinate System: y-axis is in the direction of the dipole arms. z-axis is from the basis of the antenna
  (mounted on the table) towards its feed point between the two dipole arms. x-axis is normal to the other axes.
   In coincidence with the standards [1], the measurement planes (probe sensor center) are selected to be at a
  distance of 15 mm above the top metal edge of the dipole arms.
- Measurement Conditions: Further details are available from the hardcopies at the end of the certificate. All
  figures stated in the certificate are valid at the frequency indicated. The forward power to the dipole connector
  is set with a calibrated power meter connected and monitored with an auxiliary power meter connected to a
  directional coupler. While the dipole under test is connected, the forward power is adjusted to the same level.
- Antenna Positioning: The dipole is mounted on a HAC Test Arch phantom using the matching dipole positioner with the arms horizontal and the feeding cable coming from the floor. The measurements are performed in a shielded room with absorbers around the setup to reduce the reflections. It is verified before the mounting of the dipole under the Test Arch phantom, that its arms are perfectly in a line. It is installed on the HAC dipole positioner with its arms parallel below the dielectric reference wire and able to move elastically in vertical direction without changing its relative position to the top center of the Test Arch phantom. The vertical distance to the probe is adjusted after dipole mounting with a DASY5 Surface Check job. Before the measurement, the distance between phantom surface and probe tip is verified. The proper measurement distance is selected by choosing the matching section of the HAC Test Arch phantom with the proper device reference point (upper surface of the dipole) and the matching grid reference point (tip of the probe) considering the probe sensor offset. The vertical distance to the probe is essential for the accuracy.
- Feed Point Impedance and Return Loss: These parameters are measured using a Vector Network Analyzer.
   The impedance is specified at the SMA connector of the dipole. The influence of reflections was eliminating by applying the averaging function while moving the dipole in the air, at least 70cm away from any obstacles.
- E-field distribution: E field is measured in the x-y-plane with an isotropic E-field probe with 100 mW forward power to the antenna feed point. In accordance with [1], the scan area is 20mm wide, its length exceeds the dipole arm length (180 or 90mm). The sensor center is 15 mm (in z) above the metal top of the dipole arms. Two 3D maxima are available near the end of the dipole arms. Assuming the dipole arms are perfectly in one line, the average of these two maxima (in subgrid 2 and subgrid 8) is determined to compensate for any non-parallelity to the measurement plane as well as the sensor displacement. The E-field value stated as calibration value represents the maximum of the interpolated 3D-E-field, in the plane above the dipole surface.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

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HAC (RF EMISSIONS) TEST REPORT

Microsoft

Approved by:
Quality Manager

Filename:

1M2109130107-02.C3K

9/20/2021 - 9/24/2021

Portable Handset

#### **Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.10.4
Phantom	HAC Test Arch	
Distance Dipole Top - Probe Center	15 mm	
Scan resolution	dx, dy = 5 mm	
Frequency	2600 MHz ± 1 MHz	
Input power drift	< 0.05 dB	

#### Maximum Field values at 2600 MHz

E-field 15 mm above dipole surface	condition	Interpolated maximum
Maximum measured above high end	100 mW input power	86.8 V/m = 38.77 dBV/m
Maximum measured above low end	100 mW input power	86.3 V/m = 38.72 dBV/m
Averaged maximum above arm	100 mW input power	86.5 V/m ± 12.8 % (k=2)

#### Appendix (Additional assessments outside the scope of SCS 0108)

#### **Antenna Parameters**

Frequency	Return Loss	Impedance 43.7 Ω - 5.7 jΩ		
2450 MHz	20.9 dB			
2550 MHz	32.2 dB	48.5 Ω + 1.9 jΩ		
2600 MHz	35.0 dB	51.4 Ω + 1.1 jΩ		
2650 MHz	31.6 dB	52.4 Ω - 1.2 jΩ		
2750 MHz	22.3 dB	48.4 Ω - 7.4 jΩ		

#### 3.2 Antenna Design and Handling

The calibration dipole has a symmetric geometry with a built-in two stub matching network, which leads to the enhanced bandwidth.

The dipole is built of standard semirigid coaxial cable. The internal matching line is open ended. The antenna is therefore open for DC signals.

Do not apply force to dipole arms, as they are liable to bend. The soldered connections near the feedpoint may be damaged. After excessive mechanical stress or overheating, check the impedance characteristics to ensure that the internal matching network is not affected.

After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

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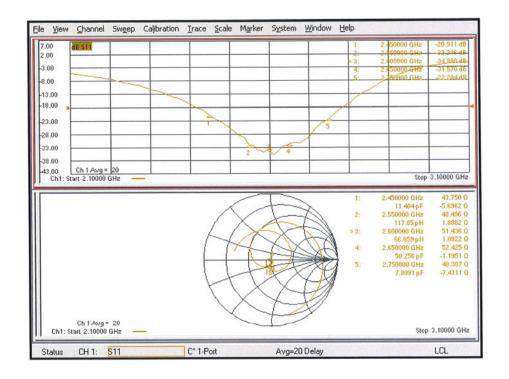
Filename:

1M2109130107-02.C3K

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#### **Impedance Measurement Plot**



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#### **DASY5 E-field Result**

Date: 14.01.2021

Test Laboratory: SPEAG Lab2

### DUT: HAC Dipole 2600 MHz; Type: CD2600V3; Serial: CD2600V3 - SN: 1012

Communication System: UID 0 - CW; Frequency: 2600 MHz Medium parameters used:  $\sigma$  = 0 S/m,  $\epsilon_r$  = 1;  $\rho$  = 0 kg/m<sup>3</sup> Phantom section: RF Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

#### DASY52 Configuration:

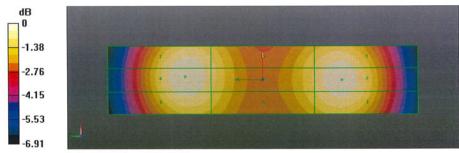
- Probe: EF3DV3 SN4013; ConvF(1, 1, 1) @ 2600 MHz; Calibrated: 28.12.2020
- Sensor-Surface: (Fix Surface)
- Electronics: DAE4 Sn781; Calibrated: 23.12.2020
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA; Serial: 1070
- DASY52 52.10.4(1527); SEMCAD X 14.6.14(7483)

### Dipole E-Field measurement @ 2600MHz/E-Scan - 2600MHz d=15mm/Hearing Aid Compatibility Test (41x181x1):

Interpolated grid: dx=0.5000 mm, dy=0.5000 mm Device Reference Point: 0, 0, -6.3 mm Reference Value = 67.09 V/m; Power Drift = -0.03 dB Applied MIF = 0.00 dB RF audio interference level = 38.77 dBV/m Emission category: M2

MIF scaled E-field

Grid 1 M2	Grid 2 <b>M2</b>	Grid 3 M2
38.56 dBV/m	38.72 dBV/m	38.5 dBV/m
Grid 4 M2	Grid 5 M2	Grid 6 M2
38.08 dBV/m	38.12 dBV/m	37.92 dBV/m
Grid 7 M2	Grid 8 M2	Grid 9 M2
38.69 dBV/m	38.77 dBV/m	38.5 dBV/m



0 dB = 86.78 V/m = 38.77 dBV/m

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# 15. CONCLUSION

The measurements indicate that the referenced wireless communications device, when used with the accessory, complies with the HAC limits specified in accordance with the ANSI C63.19 Standard and FCC WT Docket No. 01-309 RM-8658. Precise laboratory measures were taken to assure repeatability of the tests. The tested device complies with the requirements in respect to all parameters specific to the test. The test results and statements relate only to the item(s) tested.

Please note that the M-rating for this equipment only represents the field interference possible against a hypothetical and typical hearing aid. The measurement system and techniques presented in this evaluation are proposed in the ANSI standard as a means of best approximating wireless device compatibility with a hearing-aid. The literature is under continual re-construction.

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