SAR Test Report

Report No.: AGC01628180407FH07

FCC ID	:	BRWDX6R
APPLICATION PURPOSE	:	Original Equipment
PRODUCT DESIGNATION	:	DX6R
BRAND NAME	:	Spektrum
MODEL NAME	:	DX6R
CLIENT	:	Horizon Hobby, LLC
DATE OF ISSUE	:	July 30,2018
STANDARD(S)	:	IEEE Std. 1528:2013 FCC 47CFR § 2.1093 IEEE/ANSI C95.1:2005
REPORT VERSION	:	V1.2

Attestation of Global Compliance(Shenzhen) Co., Ltd.

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Report Revise Record

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	/	June 06,2018	Invalid	Initial Release
V1.1	1st	July 18,2018	Invalid	Updated page 22, page 27-29, page 30, page 34
V1.2	2nd	July 30,2018	Valid	Modify Tune-up Power on page 30.

Test Report Certification

Applicant Name	Horizon Hobby, LLC
Applicant Address	4105 Fieldstone Road, Champaign, IL 61822, USA
Manufacturer Name	Horizon Hobby, LLC
Manufacturer Address	4105 Fieldstone Road, Champaign, IL 61822, USA
Product Designation	DX6R
Brand Name	Spektrum
Model Name	DX6R
Different Description	N/A
EUT Voltage	DC 3.6V
Applicable Standard	IEEE Std. 1528:2013 FCC 47CFR § 2.1093 IEEE/ANSI C95.1:2005
Test Date	May 21,2018
Report Template	AGCRT-US-2.4G/SAR (2018-01-01)

Note: The results of testing in this report apply to the product/system which was tested only.

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Tested By

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1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Frequency Band	Highest Reported 10g-SAR(W/Kg)	Highest Reported 1g-SAR(W/Kg)	SAR Test Result
	Body (with 0mm separation)	Body (with 10mm separation)	
WIFI 2.4GHz	0.130	0.110	Pass
SAR Test Limit (W/Kg)	4.0	1.6	

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits specified in IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE/ANSI C95.1:2005 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v06
- KDB 648474 D04 Handset SAR v01r03
- KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04
- KDB 248227 D01 802 11 Wi-Fi SAR v02r02
- KDB 941225 D07 UMPC Mini Tablet v01r02

2. GENERAL INFORMATION

2.1. EUT Description

General Information	
Product Designation	DX6R
Test Model	SPM6400
Hardware Version	UH1-SOM-DX12-REV03
Software Version	2.02.06.
Device Category	Portable
RF Exposure Environment	Uncontrolled
Antenna Type	Internal
Bluetooth	
Bluetooth Version	☐V2.0 ☐V2.1 ☐V2.1+EDR ☐V3.0 ☐V3.0+HS ☒V4.0 ☐V4.1
Operation Frequency	2402~2480MHz
Type of modulation	☒GFSK ☐π/4-DQPSK ☐8-DPSK
Output Power	7.414dBm
Antenna Gain	1.5dBi
WIFI	
WIFI Specification	☐802.11a ☒802.11b ☒802.11g ☒802.11n(20) ☐802.11n(40)
Operation Frequency	2412~2462MHz
Output Power	11b:15.61dBm,11g:10.57dBm,11n(20):10.44dBm
Antenna Gain	1.5dBi
Accessories	
Battery	Voltage and Capacitance: 3.6 V & 4000mAh

Note: 1. The sample used for testing is end product.

Product	Type	
	☒ Production unit	☐ Identical Prototype

2.2. Test Procedure

1	Setup the EUT and Install the test software in PC.
2	Turn on the power of all equipment.
3	Make EUT in continuous emission test at fixed frequency through software control.

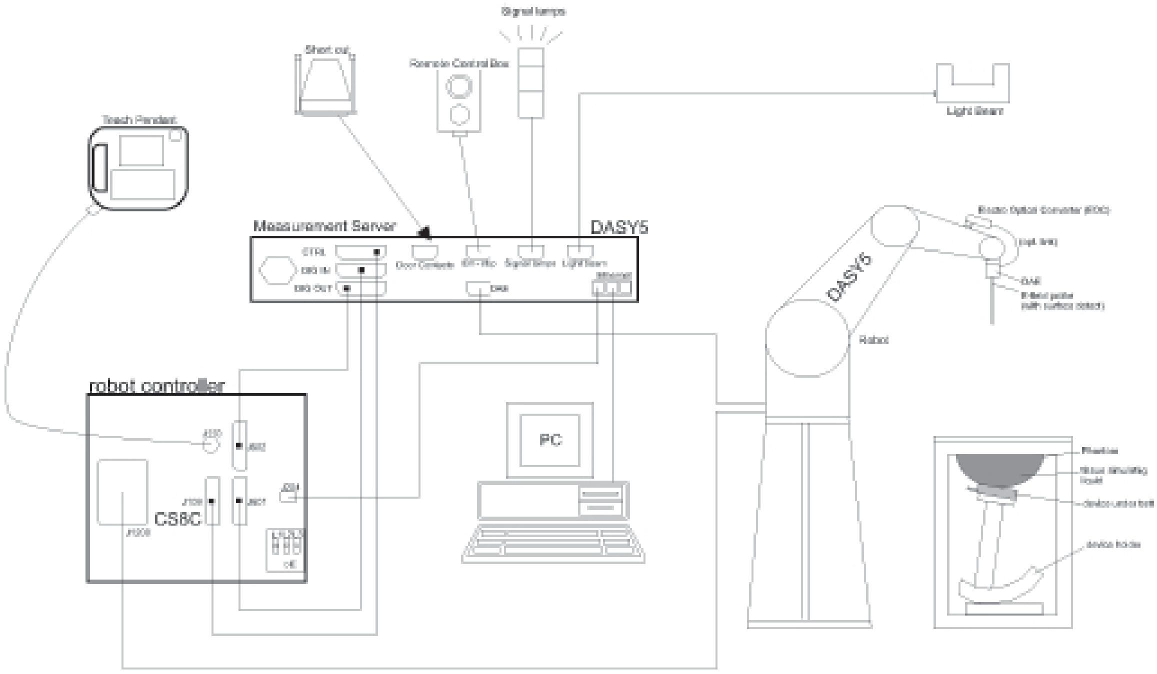
2.3. Test Environment

Ambient conditions in the laboratory:

Items	Required	Actual
Temperature (°C)	18-25	21± 2
Humidity (%RH)	30-70	55± 2

3. SAR MEASUREMENT SYSTEM

3.1. The DASY5 system used for performing compliance tests consists of following items



- A standard high precision 6-axis robot with controller, teach pendant and software.
- Data acquisition electronics (DAE) which attached to the robot arm extension. The DAE consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock
- A dosimetric probe equipped with an optical surface detector system.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital Communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- A Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- Phantoms, device holders and other accessories according to the targeted measurement.

3.2. DASY5 E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SPEAG. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE Std. 1528:2013 etc.)Under ISO17025.The calibration data are in Appendix D.

Isotropic E-Field Probe Specification

Model	EX3DV4	
Manufacture	SPEAG	
frequency	0.45GHz-6 GHz Linearity:±0.9%(k=2)(450MHz-6 GHz)	
Dynamic Range	0.01W/Kg-100W/Kg Linearity:±0.9%(k=2)	
Dimensions	Overall length:337mm Tip diameter:2.5mm Typical distance from probe tip to dipole centers:1mm	
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precision of better 30%.	

3.3. Data Acquisition Electronics description

The data acquisition electronics (DAE) consist if a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converte and a command decoder with a control logic unit. Transmission to the measurement sever is accomplished through an optical downlink fir data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

DAE4

Input Impedance	200MOhm	
The Inputs	Symmetrical and floating	
Common mode rejection	above 80 dB	

3.4. Robot

The DASY system uses the high precision robots (DASY5:TX60) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from is used.
The XL robot series have many features that are important for our application:
- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller

3.5. Light Beam Unit

The light beam switch allows automatic “tooling” of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.
The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned prob.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position. e, the same position will be reached with another aligned probe within 0

3.6. Device Holder

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR). Thus the device needs no repositioning when changing the angles. The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity ε=3 and loss tangent δ = 0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.	

3.7. Measurement Server

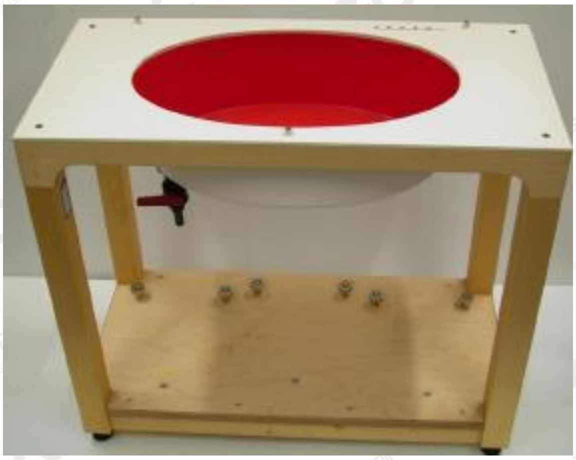
The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chip-disk (DASY5: 128MB), RAM (DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DAYS I/O board, which is directly connected to the PC/104 bus of the CPU board. The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.	

3.8. PHANTOM
SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas: □ Left head □ Right head □ Flat phantom	

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

ELI4 Phantom

□ Flat phantom a fiberglass shell flat phantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom	

4. SAR MEASUREMENT PROCEDURE

4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element(dv) of given mass density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt}\left(\frac{dW}{dm}\right) = \frac{d}{dt}\left(\frac{dW}{\rho dV}\right)$$

SAR is expressed in units of Watts per kilogram (W/Kg)
SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \left.\frac{dT}{dt}\right|_{t=0}$$

Where

SAR	is the specific absorption rate in watts per kilogram;
E	is the r.m.s. value of the electric field strength in the tissue in volts per meter;
σ	is the conductivity of the tissue in siemens per metre;
ρ	is the density of the tissue in kilograms per cubic metre;
c_h	is the heat capacity of the tissue in joules per kilogram and Kelvin;
$\frac{dT}{dt} \mid t = 0$	is the initial time derivative of temperature in the tissue in kelvins per second

4.2. SAR Measurement Procedure

Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance os sensor calibration points to probe tip as `defined in the probe properties,

Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 ± 1 mm	½·δ·ln(2) ± 0.5 mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30° ± 1°	20° ± 1°
Maximum area scan spatial resolution: Δx_{Area}, Δy_{Area}	≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm
	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g abd 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

Maximum zoom scan spatial resolution: Δx_{Zoom}, Δy_{Zoom}			≤ 2 GHz: ≤ 8 mm 2 – 3 GHz: ≤ 5 mm*	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$		≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
	graded grid	$\Delta z_{Zoom}(1)$: between 1st two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
		$\Delta z_{Zoom}(n>1)$: between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$	
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm
Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details. * When zoom scan is required and the *reported* SAR from the *area scan based 1-g SAR estimation* procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.				

Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

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4.3. RF Exposure Conditions

Test Configuration and setting:

The EUT is a DSMR Vehicle system. The device has three modules, first is 2.4GHz transmitter, second is 2.4GHz receiver, the third module is 2.4GHz BT/WIFI module.

In this report, SAR only test the third 2.4GHz BT/WIFI module, and 2.4GHz transmitter SAR test refer to the report AGC01628180407FH01

All the BT/WIFI modules were controlled by software during test.

Antenna Location:

BT/WIFI Antenna
Located : beollow the
screen

5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm.The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 5.2

5.1. The composition of the tissue simulating liquid

Ingredient (% Weight) / Frequency (MHz)	Water	Nacl	Polysorbate 20	DGBE	1,2 Propanediol	Triton X-100
2450 Body	70	1	0.0	9	0.0	20

5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in IEEE 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in IEEE 1528.

Target Frequency (MHz)	head		body	
	εr	σ (S/m)	εr	σ (S/m)
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	1.01	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800 – 2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	**52.7**	**1.95**
3000	38.5	2.40	52.0	2.73

(εr = relative permittivity, σ = conductivity and ρ = 1000 kg/m3)

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5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using DASY 5 Dielectric Probe Kit and R&S Network Analyzer ZVL6.

Tissue Stimulant Measurement for 2450MHz					
	Fr. (MHz)	Dielectric Parameters (±5%)		Tissue Temp [°C]	Test time
		εr52.7(50.065-55.335)	δ[s/m]1.95(1.8525-2.0475)		
Body	2412	54.53	1.87	21.5	May 21,2018
	2437	53.98	1.89		
	2450	53.26	1.91		
	2462	52.74	1.92		

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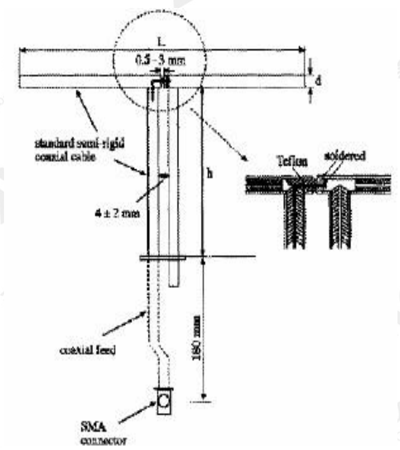
6. SAR SYSTEM CHECK PROCEDURE

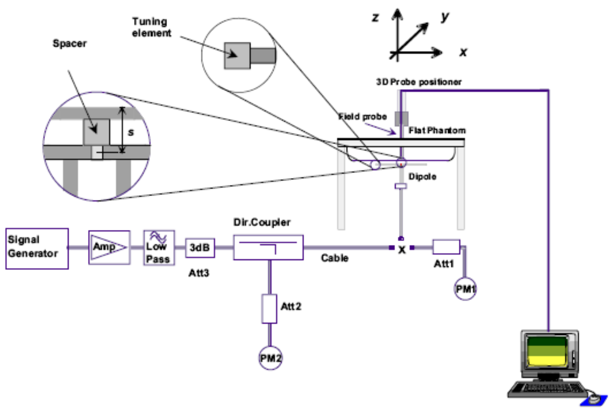
6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

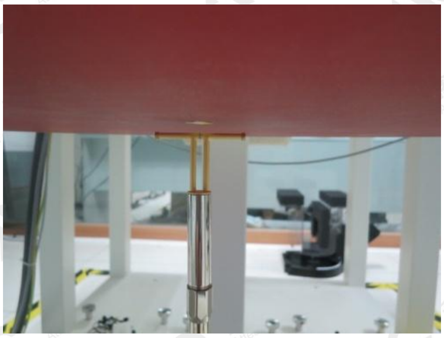
Each DASY system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

The system check verifies that the system operates within its specifications. It’s performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.





6.2. SAR System Check
6.2.1. Dipoles



The dipole used are based on the IEEE-1528 standard, the table below provides details for the mechanical and electrical specifications for the dipole.

Frequency	L (mm)	h (mm)	d (mm)
2450MHz	51.5	30.4	3.6

6.2.2. System Check Result

System Performance Check at 835 MHz &1900MHz & 2450MHz for Body								
Validation Kit: D2450V2-SN:968								
Frequency [MHz]	Target Value(W/Kg)		Reference Result (± 10%)		Tested Value(W/Kg)		Tissue Temp. [°C]	Test time
	1g	10g	1g	10g	1g	10g		
2450	51.7	24.3	46.53-56.87	21.87-26.73	51.67	23.61	21.5	May 21,2018

Note:

(1) We use a CW signal of 18dBm for system check, and then all SAR values are normalized to 1W forward power. The result must be within ±10% of target value.

(2) Tested normalized SAR (W/kg) = Tested SAR (W/kg) ×[1000/ 10^1.8]

7. EUT TEST POSITION

This EUT was tested in **all surfaces and side edges.**

7.1. Body Worn Position

(1) To position the EUT parallel to the phantom surface.

(2) To adjust the EUT parallel to the flat phantom.

(3) To adjust the distance between the EUT surface and the flat phantom to 0mm for 10-g-SAR and 10mm for 1g-SAR.

The SAR test procedure has been defined by FCC via KDB.

Surfaces and side edges with BT/WIFI antenna.

TEST POSITION	
(Position 1)	(Position 2)
	
(Position 3)	(Position 4)
	
(Position 5)	
	

8. SAR EXPOSURE LIMITS

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit (W/kg)
Spatial Peak SAR (1g cube tissue for brain or body)	1.60
Spatial Average SAR (Whole body)	0.08
Spatial Peak SAR (Limbs)	4.0

9. TEST FACILITY

Test Site	Attestation of Global Compliance (Shenzhen) Co., Ltd
Location	1-2F., Bldg.2, No.1-4, Chaxi Sanwei Technical Industrial Park, Gushu, Xixiang, Bao'an District B112-B113, Shenzhen 518012
NVLAP Lab Code	600153-0
Designation Number	CN5028
Test Firm Registration Number	682566
Description	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by National Voluntary Laboratory Accreditation program, NVLAP Code 600153-0

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10. TEST EQUIPMENT LIST

Equipment description	Manufacturer/ Model	Identification No.	Current calibration date	Next calibration date
Stäubli Robot	Stäubli-TX60	F13/5Q2UD1/A/01	N/A	N/A
Robot Controller	Stäubli-CS8	139522	N/A	N/A
E-Field Probe	Speag- EX3DV4	SN:3953	Aug. 31,2017	Aug. 30,2018
SAM Twin Phantom	Speag-SAM	1790	N/A	N/A
Device Holder	Speag-SD 000 H01 KA	SD 000 H01 KA	N/A	N/A
DAE4	Speag-SD 000 D04 BM	1398	Feb. 08,2018	Feb. 07,2019
SAR Software	Speag-DASY5	DASY52.8	N/A	N/A
Liquid	SATIMO	-	N/A	N/A
Dipole	D2450V2	SN:968	Jun. 12,2015	Jun. 11,2018
Comm Tester	Agilent-8960	GB46310822	Mar. 01,2018	Feb. 28,2019
Signal Generator	Agilent-E4438C	US41461365	Mar. 01,2018	Feb. 28,2019
Vector Analyzer	Agilent / E4440A	US41421290	Mar. 01,2018	Feb. 28,2019
Network Analyzer	Rhode & Schwarz ZVL6	SN100132	Mar. 01,2018	Feb. 28,2019
Attenuator	Warison /WATT-6SR1211	N/A	N/A	N/A
Attenuator	Mini-circuits / VAT-10+	N/A	N/A	N/A
Amplifier	EM30180	SN060552	Mar. 01,2018	Feb. 28,2019
Directional Couple	Werlatone/ C5571-10	SN99463	June 20,2017	June 19,2018
Directional Couple	Werlatone/ C6026-10	SN99482	June 20,2017	June 19,2018
Power Sensor	NRP-Z21	1137.6000.02	Oct. 12,2017	Oct. 11,2018
Power Sensor	NRP-Z23	US38261498	Mar. 01,2018	Feb. 28,2019
Power Viewer	R&S	V2.3.1.0	N/A	N/A

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:
1. There is no physical damage on the dipole;
2. System validation with specific dipole is within 10% of calibrated value;
3. Return-loss is within 20% of calibrated measurement;
4. Impedance is within 5Ω of calibrated measurement.

11. MEASUREMENT UNCERTAINTY

Measurement uncertainty for Dipole averaged over 1 gram / 10 gram.									
a	b	c	d	e f(d,k)	f	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System									
Probe calibration	E.2.1	5.831	N	1	1	1	5.83	5.83	∞
Axial Isotropy	E.2.2	0.695	R	√3	√0.5	√0.5	0.28	0.28	∞
Hemispherical Isotropy	E.2.2	1.045	R	√3	√0.5	√0.5	0.43	0.43	∞
Boundary effect	E.2.3	1.0	R	√3	1	1	0.58	0.58	∞
Linearity	E.2.4	0.685	R	√3	1	1	0.40	0.40	∞
System detection limits	E.2.4	1.0	R	√3	1	1	0.58	0.58	∞
Modulation response	E2.5	3.0	R	√3	1	1	1.73	1.73	∞
Readout Electronics	E.2.6	0.021	N	1	1	1	0.021	0.021	∞
Response Time	E.2.7	0	R	√3	1	1	0	0	∞
Integration Time	E.2.8	1.4	R	√3	1	1	0.81	0.81	∞
RF ambient conditions-Noise	E.6.1	3.0	R	√3	1	1	1.73	1.73	∞
RF ambient conditions-reflections	E.6.1	3.0	R	√3	1	1	1.73	1.73	∞
Probe positioner mechanical tolerance	E.6.2	1.4	R	√3	1	1	0.81	0.81	∞
Probe positioning with respect to phantom shell	E.6.3	1.4	R	√3	1	1	0.81	0.81	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	1	1	1.33	1.33	∞
Test sample Related									
Test sample positioning	E.4.2	2.6	N	1	1	1	2.6	2.6	∞
Device holder uncertainty	E.4.1	3	N	1	1	1	3	3	∞
Output power variation—SAR drift measurement	E.2.9	5	R	√3	1	1	2.89	2.89	∞
SAR scaling	E.6.5	5	R	√3	1	1	2.89	2.89	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	√3	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	∞
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	M
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS				9.79	9.59	
Expanded Uncertainty (95% Confidence interval)			K=2				19.58	19.18	

System check uncertainty for Dipole averaged over 1 gram / 10 gram.									
a	b	c	d	e f(d,k)	f	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System									
Probe calibration drift	E.2.1.3	0.5	N	1	1	1	0.50	0.50	∞
Axial Isotropy	E.2.2	0.695	R	√3	0	0	0.00	0.00	∞
Hemispherical Isotropy	E.2.2	1.045	R	√3	0	0	0.00	0.00	∞
Boundary effect	E.2.3	1.0	R	√3	0	0	0.00	0.00	∞
Linearity	E.2.4	0.685	R	√3	0	0	0.00	0.00	∞
System detection limits	E.2.4	1.0	R	√3	0	0	0.00	0.00	∞
Modulation response	E2.5	3.0	R	√3	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.021	N	1	0	0	0.00	0.00	∞
Response Time	E.2.7	0	R	√3	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.4	R	√3	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R	√3	0	0	0.00	0.00	∞
RF ambient conditions-reflections	E.6.1	3.0	R	√3	0	0	0.00	0.00	∞
Probe positioner mechanical tolerance	E.6.2	1.4	R	√3	1	1	0.81	0.81	∞
Probe positioning with respect to phantom shell	E.6.3	1.4	R	√3	1	1	0.81	0.81	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	0	0	0.00	0.00	∞
System check source (dipole)									
Deviation of experimental dipoles	E.6.4	2	N	1	1	1	2	2	∞
Input power and SAR drift measurement	8,6.6.4	5	R	√3	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2	R	√3	1	1	1.15	1.15	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	√3	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	∞
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	M
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS				5.564	5.205	
Expanded Uncertainty (95% Confidence interval)			K=2				11.128	10.410	

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System Validation uncertainty for Dipole averaged over 1 gram / 10 gram.									
a	b	c	d	e f(d,k)	f	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (±%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System									
Probe calibration	E.2.1	5.831	N	1	1	1	5.83	5.83	∞
Axial Isotropy	E.2.2	0.695	R	$\sqrt{3}$	1	1	0.40	0.40	∞
Hemispherical Isotropy	E.2.2	1.045	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Linearity	E.2.4	0.685	R	$\sqrt{3}$	1	1	0.40	0.40	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Modulation response	E2.5	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.021	N	1	1	1	0.021	0.021	∞
Response Time	E.2.7	0.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.4	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
Probe positioner mechanical tolerance	E.6.2	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Probe positioning with respect to phantom shell	E.6.3	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	$\sqrt{3}$	1	1	1.33	1.33	∞
System check source (dipole)									
Deviation of experimental dipole from numerical dipole	E.6.4	5.0	N	1	1	1	5.00	5.00	∞
Input power and SAR drift measurement	8,6.6.4	5.0	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4.0	R	$\sqrt{3}$	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	∞
Liquid conductivity measurement	E.3.3	4.0	N	1	0.78	0.71	3.12	2.84	M
Liquid permittivity measurement	E.3.3	5.0	N	1	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS				9.718	9.517	
Expanded Uncertainty (95% Confidence interval)			K=2				19.437	19.035	

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12. CONDUCTED POWER MEASUREMENT

WIFI 2.4GHz

Mode	Data Rate (Mbps)	Channel	Frequency(MHz)	Max. Tune-up Power (dBm)	Average Power (dBm)
802.11b	1	01	2412	15.70	15.24
		06	2437	15.70	**15.61**
		11	2462	15.70	15.22
802.11g	6	01	2412	10.60	10.31
		06	2437	10.60	10.57
		11	2462	10.60	10.16
802.11n(20)	6.5	01	2412	10.50	10.44
		06	2437	10.50	10.26
		11	2462	10.50	10.37

Bluetooth_V4.0(BLE)

Modulation	Channel	Frequency(MHz)	Peak Power (dBm)
GFSK	0	2402	6.131
	19	2440	**7.414**
	39	2480	6.643

13. TEST RESULTS

13.1. SAR Test Results Summary

13.1.1. Test position and configuration

1. The EUT is a DSMR Vehicle system;
2. Per FCC Response: We used the test procedures in KDB 941225 D07 and test all surfaces and side edges with a transmitting antenna located at ≤ 25 mm from that surface or edge.
3. Test procedure:
   (1). Using a Flat phantom flied with body tissue simulating liquid for test;
   (2). Using a separation distance of 0mm for 10-g-SAR and 10mm for 1g-SAR test;
4. For SAR testing, the device was controlled by software to test at reference fixed frequency points.

13.1.2. Operation Mode

1. Per KDB 447498 D01 v06 ,for each exposure position, if the highest 1-g SAR is ≤ 0.8 W/kg, testing for low and high channel is optional.
2. Per KDB 865664 D01 v01r04,for each frequency band, if the measured SAR is ≥0.8W/Kg, testing for repeated SAR measurement is required , that the highest measured SAR is only to be tested. When the SAR results are near the limit, the following procedures are required for each device to verify these types of SAR measurement related variation concerns by repeating the highest measured SAR configuration in each frequency band.
   (1) When the original highest measured SAR is ≥0.8W/Kg, repeat that measurement once.
   (2) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is >1.20 or when the original or repeated measurement is ≥1.45 W/Kg.
   (3) Perform a third repeated measurement only if the original, first and second repeated measurement is ≥1.5 W/Kg and ratio of largest to smallest SAR for the original, first and second measurement is ≥ 1.20.
3. Per KDB 248227D01v01r02, For WiFi 2.4GHz, highest average RF output power channel for the lowest data rate of 802.11b mode was selected for SAR evalutation. SAR test at higher data rates and higher order modulations (including 802.11g/n) were not required since the maximum average output power for each of these configurations is not more than 1/4dB higher than the tested channel for the lowest data rate of 802.11b mode.
4. Per KDB 941225 D07 v01r02, UMPC mini-tablet devices must be tested for 1-g SAR on all surfaces and side edges with a transmitting antenna located at ≤ 25 mm from that surface or edge. Depending on the device form factor, antenna locations, operating configurations and exposure conditions, a test separation distance up to 10 mm may be considered for some devices; for example, certain game controllers and dual display smart phones. Under such circumstances, 10-g extremity SAR must also be measured at zero test separation for all measured 1-g (10 mm) SAR configurations to address hand exposure.

5. Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:
   Maximum Scaling SAR =tested SAR (Max.) ×[maximum turn-up power (mw)/ maximum measurement output power(mw)]

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13.1.3. Test Result

SAR MEASUREMENT									
Depth of Liquid (cm):>15					Relative Humidity (%): 48.2				
Product: DX6R									
Test Mode:2.4GHz WIFI									
Position	**Mode**	**Ch.**	**Fr. (MHz)**	**Power Drift (<±0.2dB)**	**10(g)-Extremity SAR (W/kg)**	**Max. Tune-up Power (dBm)**	**Meas. output Power (dBm)**	**Scaled SAR (W/Kg)**	**Limit (W/kg)**
Position 1	DTS	6	2437	0.01	0.067	15.70	15.61	0.068	4.0
Position 2	DTS	6	2437	0.16	0.048	15.70	15.61	0.049	4.0
Position 3	DTS	6	2437	0.13	0.033	15.70	15.61	0.034	4.0
Position 4	DTS	6	2437	-0.19	**0.127**	15.70	15.61	**0.130**	4.0
Position 5	DTS	6	2437	0.12	0.021	15.70	15.61	0.021	4.0

Note:
·The separation distance of 0mm for 10-g extremity SAR.
·Plots are only shown for the bold markered worst case SAR results
·The meaning of the above "Position 1/2/3/4/5", see section 7.

SAR MEASUREMENT									
Depth of Liquid (cm):>15					Relative Humidity (%): 48.2				
Product: DX6R									
Test Mode:2.4GHz WIFI									
Position	**Mode**	**Ch.**	**Fr. (MHz)**	**Power Drift (<±0.2dB)**	**SAR (1g) (W/kg)**	**Max. Tune-up Power (dBm)**	**Meas. output Power (dBm)**	**Scaled SAR (W/Kg)**	**Limit (W/kg)**
Position 1	DTS	6	2437	0.03	0.063	15.70	15.61	0.064	1.6
Position 2	DTS	6	2437	-0.10	0.038	15.70	15.61	0.039	1.6
Position 3	DTS	6	2437	-0.08	0.029	15.70	15.61	0.030	1.6
Position 4	DTS	6	2437	-0.13	**0.108**	15.70	15.61	**0.110**	1.6
Position 5	DTS	6	2437	0.11	0.014	15.70	15.61	0.014	1.6

Note:
·The separation distance of 10mm for 1-g-SAR.
·Plots are only shown for the bold markered worst case SAR results
·The meaning of the above "Position 1/2/3/4/5", see section 7.

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Estimated SAR		Max Power including Tune-up Tolerance		Separation Distance (mm)	Estimated SAR (W/kg)
		dBm	mW		
BT	Body	8	6.310	0	0.263
		8	6.310	10	0.131

Note:WIFI and BT share the same antenna, and cannot transmit simultaneously.

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APPENDIX A. SAR SYSTEM CHECK DATA

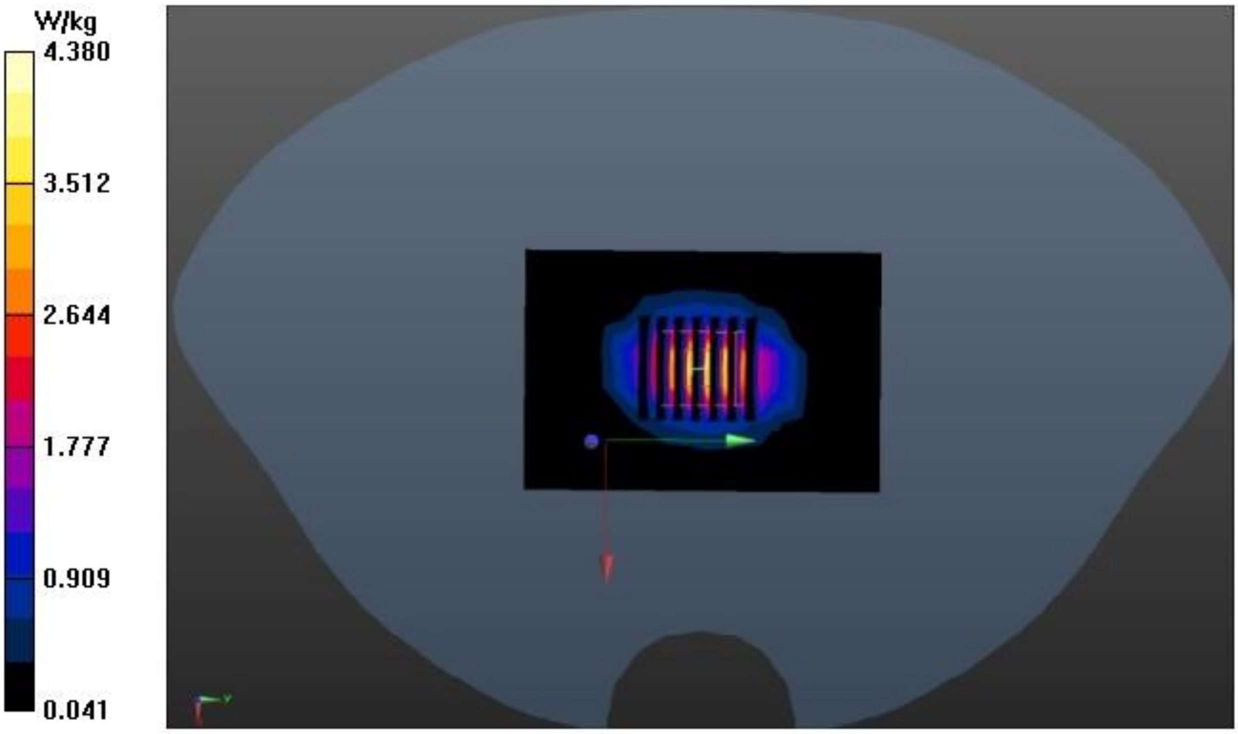
Test Laboratory: AGC Lab **Date: May 21,2018**
System Check Body 2450 MHz
DUT: Dipole 2450 MHz Type: SID 2450

Communication System CW; Communication System Band: D2450 (2450.0 MHz); Duty Cycle: 1:1;
Frequency: 2450 MHz; Medium parameters used: f = 2450 MHz; σ=1.91 mho/m; εr =53.26; ρ= 1000 kg/m³ ;
Phantom section: Flat Section; Input Power=18dBm
Ambient temperature (℃):22.0, Liquid temperature (℃): 21.5

DASY Configuration:
- EX3DV4 – SN:3953; ConvF(7.73, 7.73, 7.73); Calibrated:Aug. 31,2017;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 31.0
- Electronics: DAE4 SN1398; Calibrated: Feb. 08,2018
- Phantom: SAM (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

Configuration/System Check Body 2450MHz /Area Scan (7x12x1): Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (measured) = 4.23 W/kg

Configuration/System Check Body 2450MHz /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 33.359 V/m; Power Drift = -0.12 dB
Peak SAR (extrapolated) = 7.11 W/kg
SAR(1 g) = 3.26 W/kg; SAR(10 g) = 1.49 W/kg
Maximum value of SAR (measured) = 4.38 W/kg



APPENDIX B. SAR MEASUREMENT DATA

2.4GHz WIFI for 10-g-SAR:

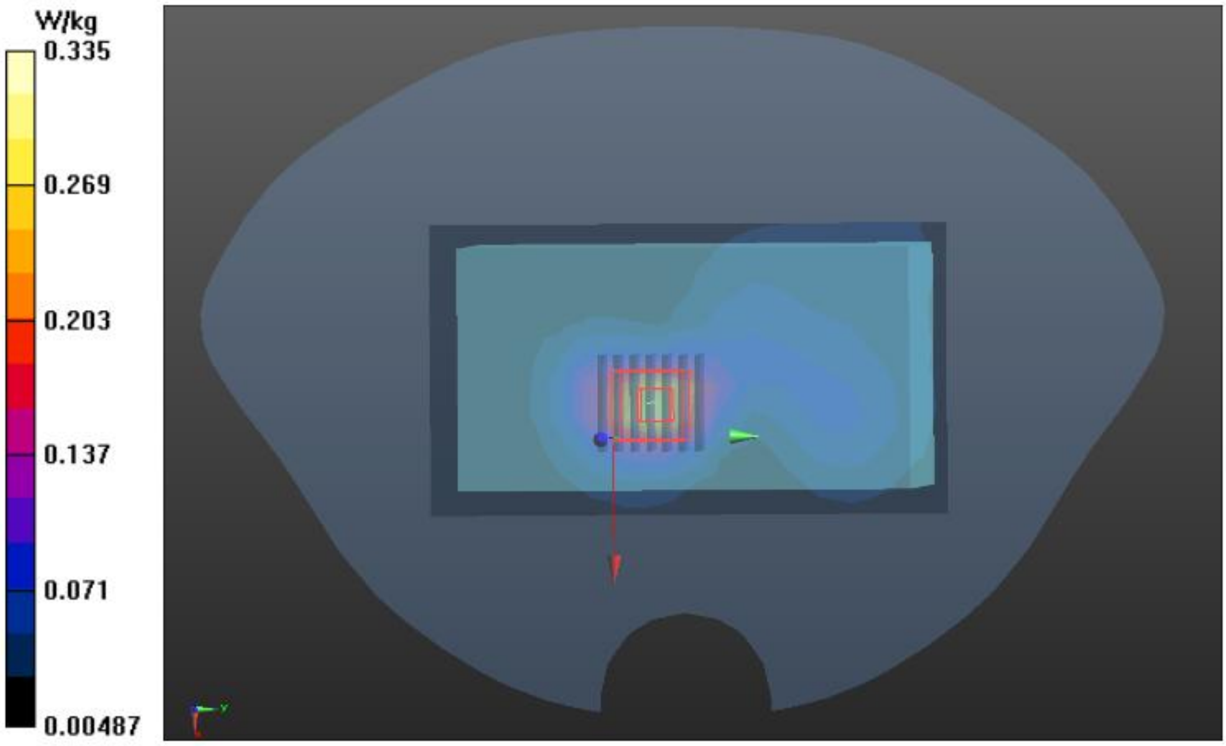
Test Laboratory: AGC Lab **Date: May 21,2018**
802.11b Mid- Position 4 (DTS)
DUT: DX6R; Type: SPM6400

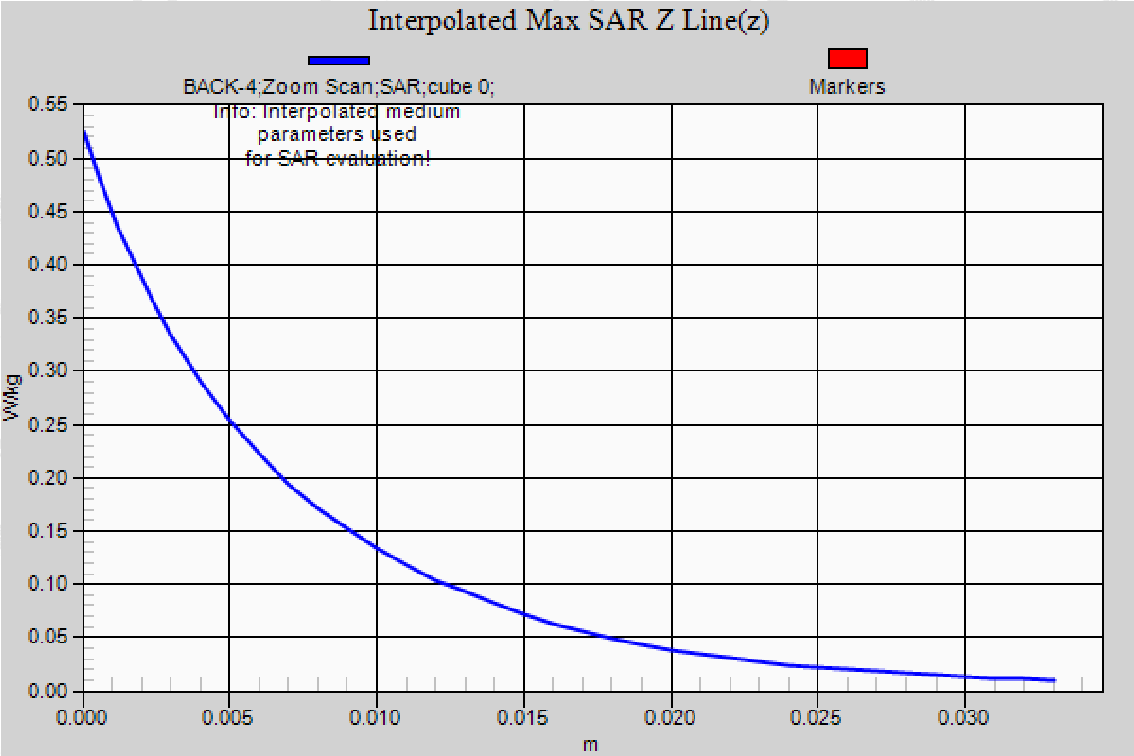
Communication System: Wi-Fi; Communication System Band: 802.11b; Duty Cycle: 1:1;
Frequency: 2437 MHz; Medium parameters used: f = 2450 MHz; σ=1.89 mho/m; εr =53.98; ρ= 1000 kg/m³ ;
Phantom section: Flat Section
Ambient temperature (℃): 22.0, Liquid temperature (℃): 21.5

DASY Configuration:
- EX3DV4 – SN:3953; ConvF(7.73, 7.73, 7.73); Calibrated:Aug. 31,2017;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0, 31.0
- Electronics: DAE4 SN1398; Calibrated: Feb. 08,2018
- Phantom: SAM (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BODY 4/BACK-4/Area Scan (10x17x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (measured) = 0.298 W/kg

BODY 4/BACK-4/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 9.306 V/m; Power Drift = -0.19 dB
Peak SAR (extrapolated) = 0.526 W/kg
SAR(1 g) = 0.259 W/kg; SAR(10 g) = 0.127 W/kg
Maximum value of SAR (measured) = 0.335 W/kg




Interpolated Max SAR Z Line(z)
BACK-4;Zoom Scan;SAR;cube 0;
Markers
Info: Interpolated medium
parameters used
for SAR evaluation!
W/kg
0.55
0.50
0.45
0.40
0.35
0.30
0.25
0.20
0.15
0.10
0.05
0.00
0.000
0.005
0.010
0.015
0.020
0.025
0.030
m

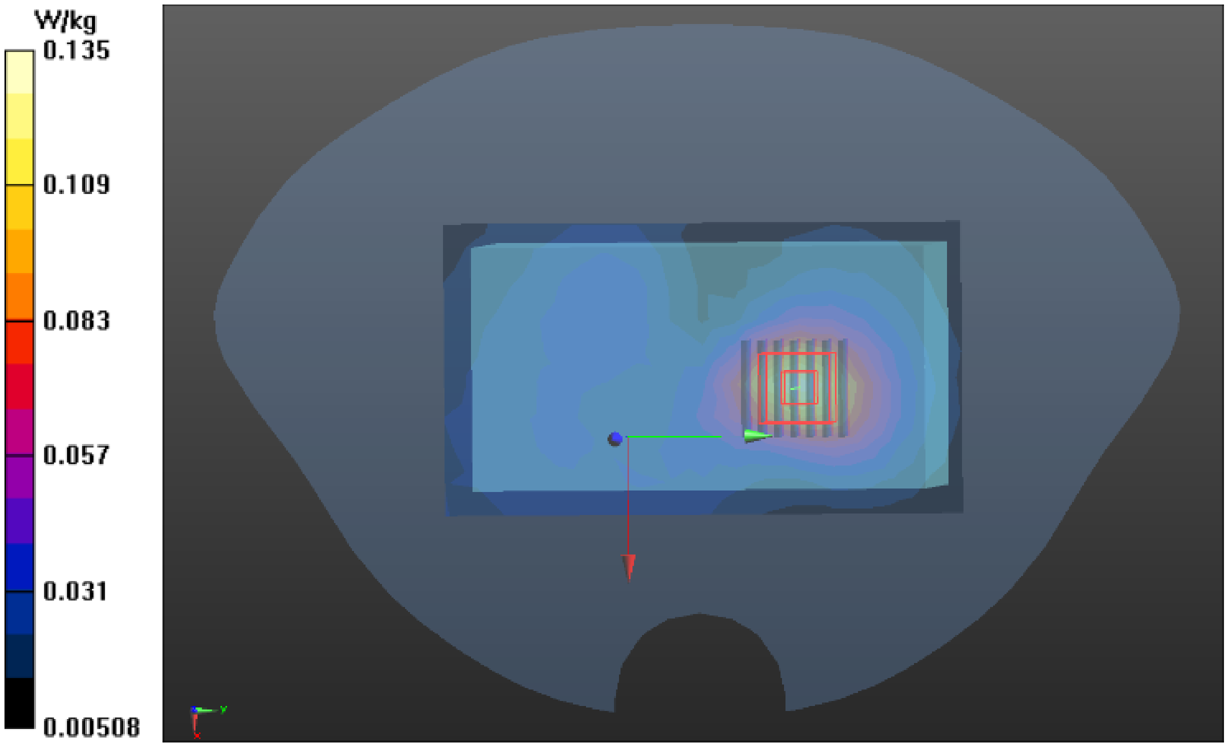
2.4GHz WIFI for 1-g-SAR:
Test Laboratory: AGC Lab **Date: May 21,2018**
802.11b Mid- Position 4 (DTS)
DUT: DX6R; Type: SPM6400

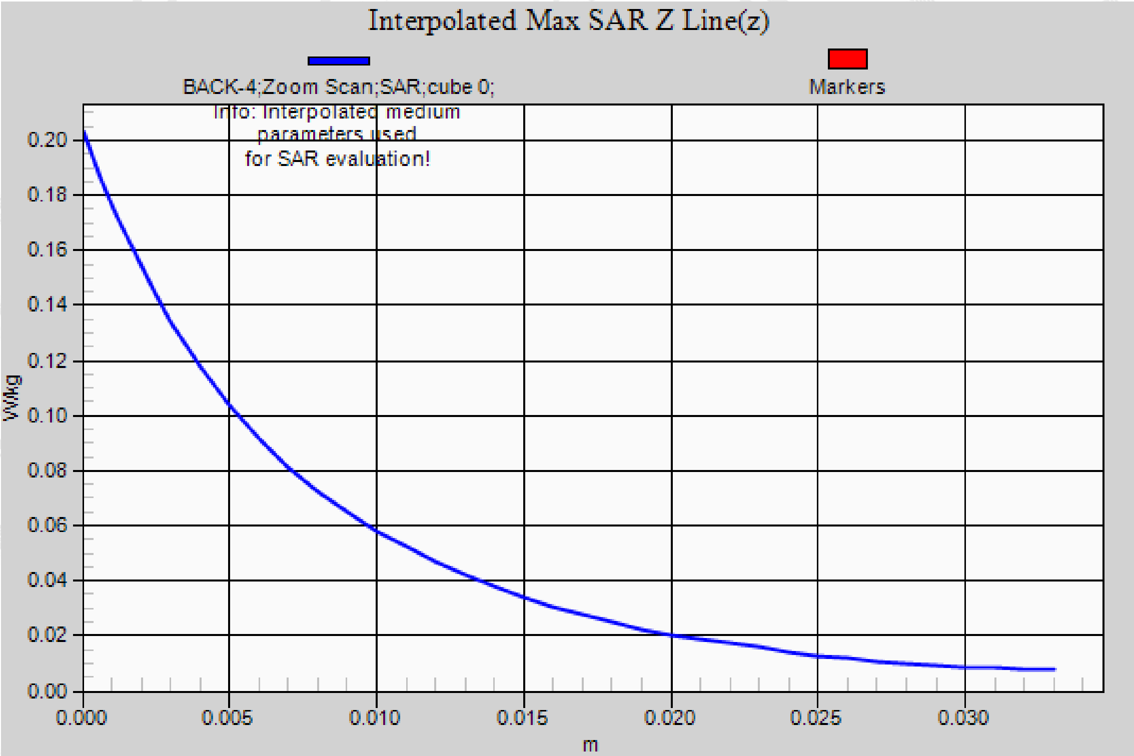
Communication System: Wi-Fi; Communication System Band: 802.11b; Duty Cycle: 1:1;
Frequency: 2437 MHz; Medium parameters used: f = 2450 MHz; σ=1.89 mho/m; εr =53.98; ρ= 1000 kg/m³ ;
Phantom section: Flat Section
Ambient temperature (℃): 22.0, Liquid temperature (℃): 21.5

DASY Configuration:
- EX3DV4 – SN:3953; ConvF(7.73, 7.73, 7.73); Calibrated:Aug. 31,2017;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0, 31.0
- Electronics: DAE4 SN1398; Calibrated: Feb. 08,2018
- Phantom: SAM (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BODY 4/BACK-4/Area Scan (10x17x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (measured) = 0.131 W/kg

BODY 4/BACK-4/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 4.032 V/m; Power Drift = -0.13 dB
Peak SAR (extrapolated) = 0.203 W/kg
SAR(1 g) = 0.108 W/kg; SAR(10 g) = 0.060 W/kg




Interpolated Max SAR Z Line(z)
BACK-4;Zoom Scan;SAR;cube 0;
Info: Interpolated medium parameters used for SAR evaluation!
Markers
W/kg
0.20
0.18
0.16
0.14
0.12
0.10
0.08
0.06
0.04
0.02
0.00
0.000
0.005
0.010
0.015
0.020
0.025
0.030
m

APPENDIX C. TEST SETUP PHOTOGRAPHS

Position 1 of 0mm

Position 2 of 0mm

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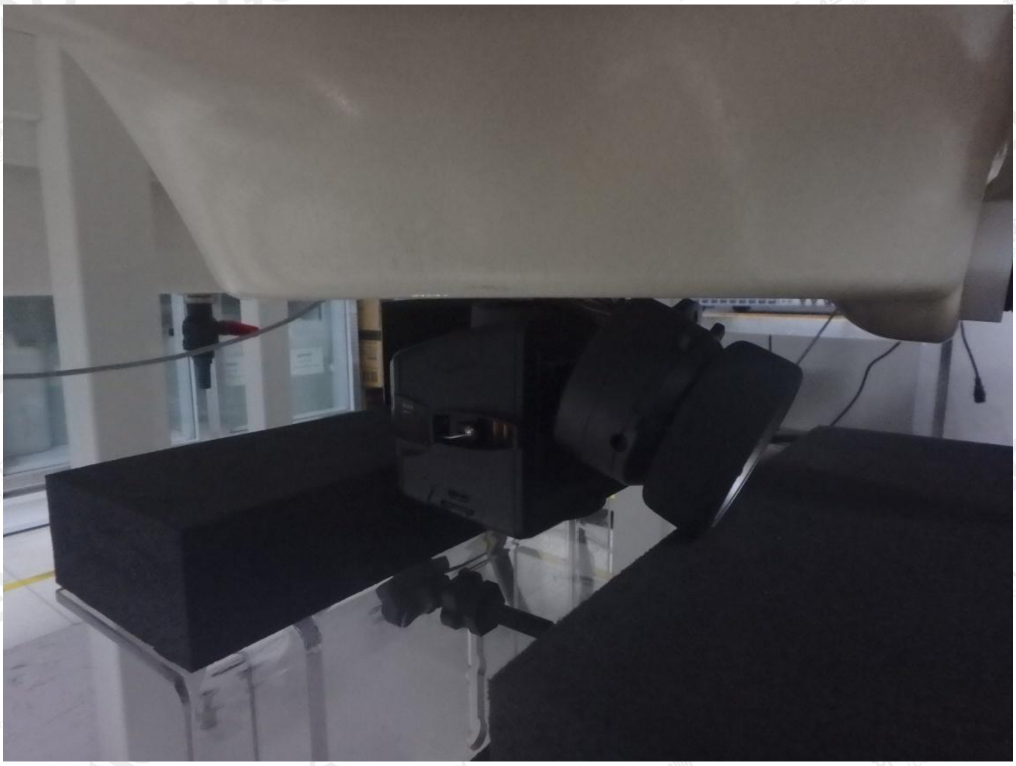
Position 3 of 0mm



Position 4 of 0mm

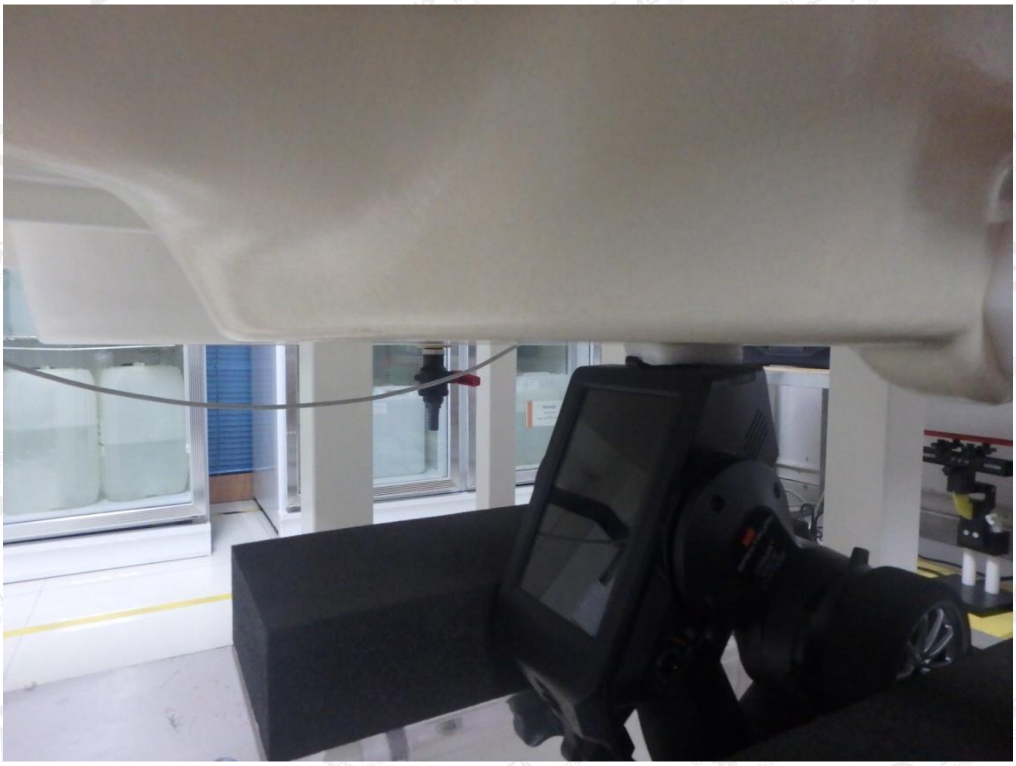
Attestation of Global Compliance
Tel: +86-755 2908 1955 Fax: +86-755 2600 8484 E-mail: agc@agc-cert.com 400 089 2118
Add: 2/F. , Building 2, No.1-4,Chaxi Sanwei Technical Industrial Park,Gushu, Xixiang, Baoan District, Shenzhen, Guangdong China

Position 5 of 0mm

Tel: +86-755 2908 1955 Fax: +86-755 2600 8484 E-mail: agc@agc-cert.com 400 089 2118
Add: 2/F. , Building 2, No.1-4,Chaxi Sanwei Technical Industrial Park,Gushu, Xixiang, Baoan District, Shenzhen, Guangdong China

Position 1 of 10mm

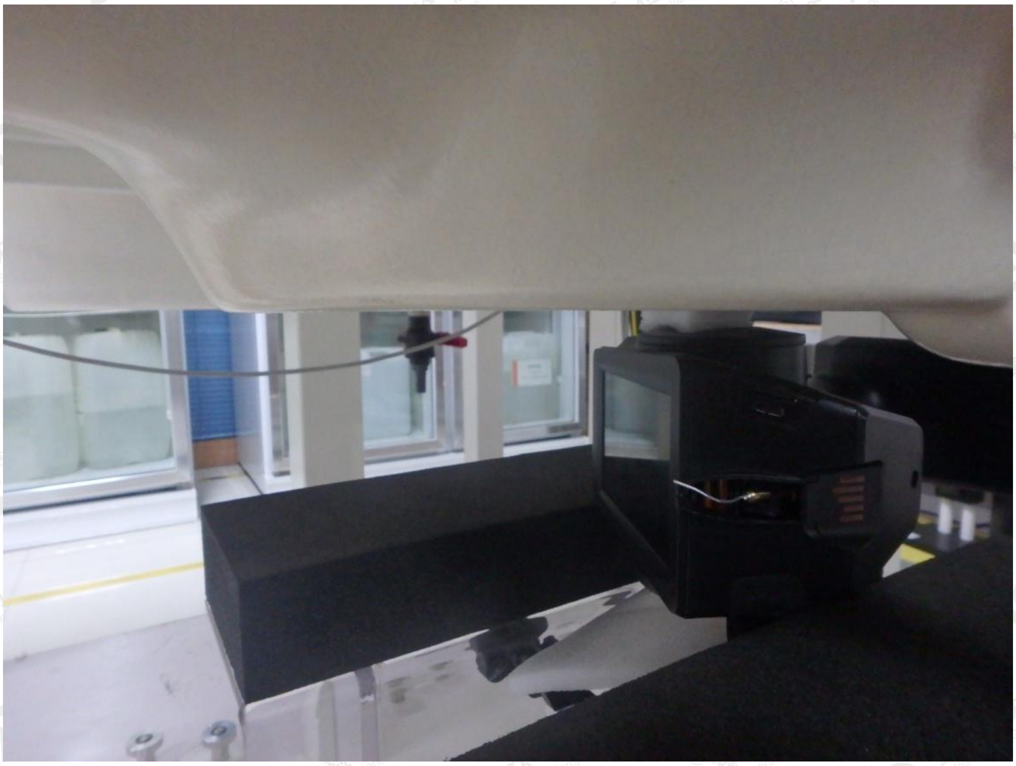
Position 2 of 10mm



Tel: +86-755 2908 1955 Fax: +86-755 2600 8484 E-mail: agc@agc-cert.com 400 089 2118
Add: 2/F. , Building 2, No.1-4,Chaxi Sanwei Technical Industrial Park,Gushu, Xixiang, Baoan District, Shenzhen, Guangdong China

Position 3 of 10mm

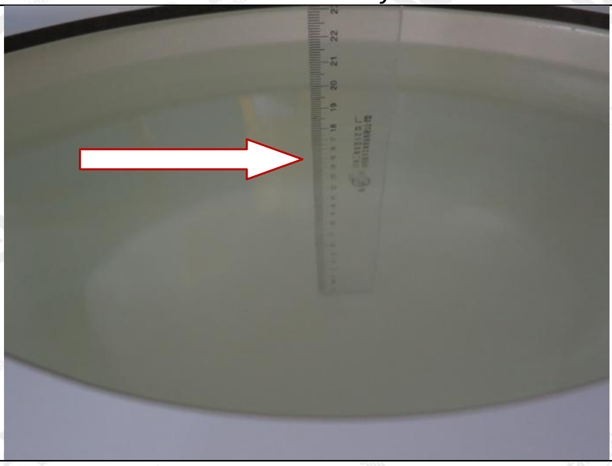
Position 4 of 10mm



Position 5 of 10mm

DEPTH OF THE LIQUID IN THE PHANTOM—ZOOM IN

Note：The position used in the measurement were according to IEEE 1528-2013

2450MHz body


Tel: +86-755 2908 1955 Fax: +86-755 2600 8484 E-mail: agc@agc-cert.com 400 089 2118
Add: 2/F. , Building 2, No.1-4,Chaxi Sanwei Technical Industrial Park,Gushu, Xixiang, Baoan District, Shenzhen, Guangdong China

APPENDIX D. CALIBRATION DATA

Refer to Attached files.