

KDB 865664 D01 SAR Measurement 100MHz to 6GHz FCC 47 CFR part 2 (2.1093)

# SAR EVALUATION REPORT For Siri Remote with Bluetooth Radio

# Model: A2854 FCC ID: BCG-A2854

# REPORT NUMBER UL-SAR-RP14247018JD41A V2.0 ISSUE DATE: 07 OCT 2022

Prepared for

APPLE INC. ONE APPLE PARK WAY CUPERTINO CA 95014-2084, USA

Prepared by

UL INTERNATIONAL (UK) LTD UNIT 1-3 HORIZON, WADE ROAD, KINGSLAND BUSINESS PARK, BASINGSTOKE, HAMPSHIRE, RG24 8AH, UK TEL: +44 (0) 1256 312 100 FAX: +44 (0) 1256 312 001



### **REVISION HISTORY**

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# TABLE OF CONTENTS

1. Attestation of Test Results	4
<ul> <li>2. Test Specification, Methods and Procedures</li> <li>2.1. Test Specification</li> <li>2.2. Methods and Procedures Reference Documentation</li> <li>2.3. Definition of Measurement Equipment</li> </ul>	5 5 5 5
3. Facilities and Accreditation	6
<ul> <li>4. SAR Measurement System &amp; Test Equipment</li></ul>	<b>7</b> 7 8 10
	<b>12</b> 13 14
6.2. Wireless Technologies	<b>15</b> 15 16 17
5	<b>18</b> 18 18
8. Conducted output power measurements	<b>19</b> 19
9.2. System Check 9.3. Numerical SAR Target Values	<b>20</b> 20 22 22 23
	<b>24</b> 24 25
11.1. Highest Standalone Reported SAR	<b>26</b> 26 26
12.1. Photos and Ports Location212.2. System Check Plots212.3. SAR Distribution Plots212.4. Calibration Certificate for E-Field Probe212.5. Calibration Certificate for Dipole2	27 40 44 47 48 49

# **1. Attestation of Test Results**

Applicant Name:	Apple Inc.									
Model:	A2854									
Test Device is	A representative	A representative test sample								
Device category	Portable	Portable								
Date Tested	12 August 2022	12 August 2022 to 20 September 2022								
FCC 47 CFR (2.1093) Limits for SAR Exposure Characteristics		General Population – Localised SAR (Body-worn) – 1g-SAR limit 1.6 W/kg General Population – Localised SAR (Limbs) –10g SAR limit 4.0 W/kg								
The highest reported		Openalitiense		Equipme	ent Class					
SAR values for Localized SAR	RF Exposure	Conditions	Licensed	DTS	U-NII	DSS				
	Standalone	Body-worn	N/A	N/A	N/A	<mark>0.53</mark> W/kg				
	Standalone	Limbs	N/A	N/A	N/A	<mark>0.11</mark> W/kg				
Applicable Standards	FCC 47 CFR par KDB publications									
Test Results	Pass									
UL International (UK) Ltd. tested the above equipment in accordance with the requirements set forth in the above standards. All indications of Pass/Fail in this report are opinions expressed by UL International (UK) Ltd. based on interpretations and/or observations of test results. Measurement Uncertainties are in accordance with the above standard and are published for informational purposes only. The test results show that the equipment tested is capable of demonstrating compliance with the requirements as documented in this report. <b>Note:</b> The results documented in this report apply only to the tested sample(s), under the conditions and modes of operation as described herein. This document may not be altered or revised in any way unless done so by UL International (UK) Ltd. and all revisions are duly noted in the revisions section. Any alteration of this document not carried out by UL International (UK) Ltd. will constitute fraud and shall nullify the document. This report must										
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M. Mascen	familie
Naseer Mirza	Harmohan Sahota
Operations Leader	Senior Test Engineer
UL	UL

Page 4 of 49

# **2.Test Specification, Methods and Procedures**

### 2.1.Test Specification

Reference:	KDB Publication Number: 865664 D01 SAR Measurement 100 MHz to 6 GHz					
Title:	SAR Measurement Requirements for 100 MHz to 6 GHz					
Introduction:	The SAR Measurement procedures for 100MHz to 6GHz are described in this document. Field probes, tissue dielectric properties, SAR scans, measurement accuracy and variability of the measured results are discussed. The field probe and SAR scan requirements are derived from criteria considered in standard IEEE 1528-2013. The wireless product and technology specific procedures in applicable KDB publications are required to be used unless further guidance has been approved by the FCC.					
Purpose of Test:	To determine if the Equipment Under Test complies with the Specific Absorption Rate for general population/uncontrolled exposure limit of 1.6 W/kg as specified in FCC 47 CFR part 2 (2.1093).					

## 2.2. Methods and Procedures Reference Documentation

The methods and procedures used were as detailed in:

### IEC/IEEE 62209-1528:2020

Measurement procedure for the assessment of specific absorption rate of human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices.

#### FCC KDB Publication:

KDB 447498 D04 Interim General RF Exposure Guidance v01 KDB 447498 D03 Supplement C Cross-Reference v01 KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz v01r04 KDB 865664 D02 RF Exposure Reporting v01r02

## 2.3. Definition of Measurement Equipment

The measurement equipment used complied with the requirements of the standards referenced in the methods & procedures section above. Section 4.3 contains a list of the test equipment used.

Page 5 of 49

# **3.Facilities and Accreditation**

The measurement facilities used to collect data are located at

Horizon Unit 1-3, Wade Road, Kingsland Business Park, Basingstoke, Hampshire, RG24 8AH, UK	Facility Type
SAR Lab 59	Controlled Environment Chamber

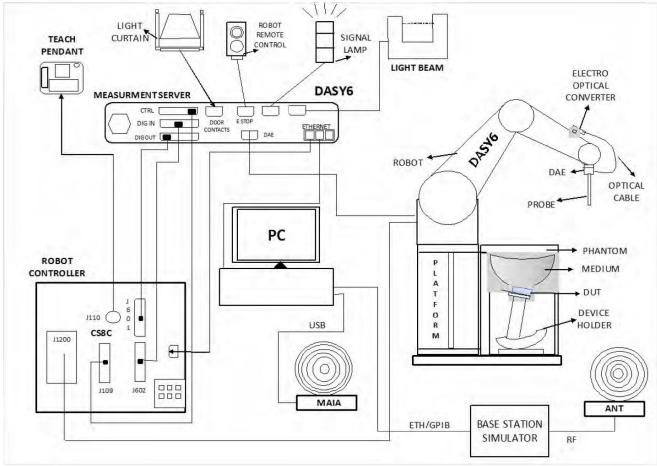
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Page 6 of 49

# 4. SAR Measurement System & Test Equipment

# 4.1. SAR Measurement System

The DASY test systems used for performing compliance tests consists of the following items:



- A standard high precision 6-axis robot with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic Field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, ADconversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running Win10 with DASY software installed.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

#### 4.2. SAR Measurement Procedure

#### 4.2.1. Normal SAR Measurement Procedure

The following procedure shall be performed for each of the test conditions

- a) Measure the local SAR at a test point within 8 mm of the phantom inner surface that is closest to the DUT.
- b) Measure the two-dimensional SAR distribution within the phantom (area scan procedure). The boundary of the measurement area shall not be closer than 20 mm from the phantom side walls. The distance between the measurement points should enable the detection of the location of local maximum with an accuracy of better than half the linear dimension of the tissue cube after interpolation. A maximum grid spacing of 20 mm for frequencies below 3 GHz and (60/f [GHz]) mm for frequencies of 3 GHz and greater is recommended. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and  $\delta \ln(2)/2$  mm for frequencies of 3 GHz and greater, where  $\delta$  is the plane wave skin depth and  $\ln(x)$  is the natural logarithm. The maximum variation of the sensor-phantom surface distance shall be ± 1 mm for frequencies below 3 GHz and ± 0,5 mm for frequencies of 3 GHz and greater. At all measurement points the angle of the probe with respect to the line normal to the surface should be less than 5°. If this cannot be achieved for a measurement distance to the phantom inner surface shorter than the probe diameter, additional uncertainty evaluation is needed.
- c) From the scanned SAR distribution, identify the position of the maximum SAR value, in addition identify the positions of any local maxima with SAR values within 2 dB of the maximum value that will not be within the zoom scan of other peaks; additional peaks shall be measured only when the primary peak is within 2 dB of the SAR compliance limit (e.g., 1 W/kg for 1,6 W /kg 1 g limit, or 1,26 W/kg for 2 W /kg, 10 g limit).
- d) Measure the three-dimensional SAR distribution at the local maxima locations identified in step c) (zoom For frequencies at or below 3 GHz, the following procedure shall be applied: The horizontal grid step shall be 8 mm or less. The grid step in the vertical direction shall be 5 mm or less if uniform spacing is used. If variable spacing is used in the vertical direction, the maximum spacing between the two closest measured points to the phantom shell (M1 and M2) shall be 4 mm or less and the spacing between farther points shall increase by a factor of 1,5 or less. The minimum size of the zoom scan volume shall be 30 mm by 30 mm

For frequencies above 3 GHz, the minimum size of the zoom scan volume may be reduced to 22 mm by 22 mm by 22 mm. The horizontal grid step shall be (24/f [GHz]) mm or less. If uniform spacing in the vertical direction is used, the grid step in the vertical direction shall be (10/(f [GHz] - 1)) mm or less. If variable spacing is used in the vertical direction, the maximum spacing between the two measured points closest to the phantom shell shall be (12/f [GHz]) mm or less and the spacing between further points shall increase by a factor of 1,5 or less. For other parameters, see Zoom Scan Parameters table.

When the highest 1 g or 10 g cube is touching the boundary of a zoom-scan volume, the entire zoom scan shall be repeated with the new centre located at the maximum psSAR location indicated by the preceding zoom scan measurement. If the zoom scan measured as defined above complies with both of the following criteria, or if the peak spatial-average SAR is below 0,1 W/kg, no additional measurements are needed:

1) the smallest horizontal distance from the local SAR peaks to all points 3 dB below the SAR peak shall be larger than the horizontal grid steps in both *x* and *y* directions ( $\Delta x$ ,  $\Delta y$ ). This shall be checked for the measured zoom scan plane conformal to the phantom at the distance *z*M1. The minimum distance shall be recorded in the SAR test report;

2) the ratio of the SAR at the second measured point (M2) to the SAR at the closest measured point (M1) at the *x-y* location of the measured maximum SAR value shall be at least 30 %. This ratio (in %) shall be recorded in the SAR test report.

If one or both of the above criteria are not met, the zoom scan measurement shall be repeated using a finer resolution while keeping the other zoom scan parameters compatible with Zoom Scan Parameters table. New horizontal and vertical grid steps shall be determined from the measured SAR distribution so that the above criteria are met. Compliance with the above two criteria shall be demonstrated for the new measured zoom scan. The size of the higher resolution zoom scan and other parameters of Zoom Scan Parameters table shall apply. The closest point to the phantom shell shall be 2 mm or less for graded grids and the grading factor shall be 1,5 or less.

Page 8 of 49

Uncertainties due to field distortion between the media boundary and the dielectric enclosure of the probe should also be minimized, which is achieved if the distance between the phantom surface and physical tip of the probe is larger than the probe tip diameter. Other methods may utilize correction procedures to compensate for boundary effects that enable high precision measurements closer than half the probe diameter. For all measurement points, the angle of the probe normal to the flat phantom surface shall be less than 5°.

Parameter	DUT transmit frequency being tested				
	f ≤ 3 GHz	3 GHz < <i>f</i> ≤ 6 GHz			
Maximum distance between the closest measured points and the phantom surface ( $z_{\rm M1}$ in Figure 14 and Table 2, in mm)	5	δ In(2)/2 ª			
Maximum angle between the probe axis and the flat phantom surface normal ( $\alpha$ in Figure 14)	5°	5°			
Maximum spacing between measured points in the x- and y-directions ( $\Delta x$ and $\Delta y$ , in mm)	8	24/f <sup>b,c</sup>			
For uniform grids:	5	10/(f - 1)			
Maximum spacing between measured points in the direction normal to the phantom shell ( $\Delta z_1$ in Figure 14, in mm)					
For graded grids:	4	12/f			
Maximum spacing between the two closest measured points in the direction normal to the phantom shell ( $\Delta z_1$ in Figure 14, in mm)					
For graded grids:	1,5	1,5			
Maximum incremental increase in the spacing between measured points in the direction normal to the phantom shell ( $R_z = \Delta z_2 / \Delta z_1$ in Figure 14)					
Minimum edge length of the zoom scan volume in the x- and y-directions ( $L_z$ in 7.2.5.3, in mm)	30	22			
Minimum edge length of the zoom scan volume in the direction normal to the phantom shell $(L_h \text{ in } 7.2.5.3, \text{ in mm})$	30	22			
Tolerance in the probe angle	1°	1°			
<sup>a</sup> $\mathcal{S}$ is the penetration depth for a plane-wave inc	ident normally on a plana	r half-space.			
<sup>b</sup> This is the maximum spacing allowed, which m	nay not work for all circum	istances.			
c f is the frequency in GHz.					

#### **Zoom Scan Parameters**

- e) Use post processing (e.g. interpolation and extrapolation) procedures to determine the local SAR values at the spatial resolution needed for mass averaging.
- f) The local SAR should be measured at the same location as in Step a). SAR drift is assessed and reported in the uncertainty budget.

In the event that the evaluation of measurement drift exceeds the 5 % tolerance, it is required that SAR be reassessed following guidelines contained within this standard.

If the drift is larger than 5 %, then the measurement drift shall be considered a bias, not an uncertainty. A correction shall be applied to the measured SAR value. It is not necessary to record the drift in the uncertainty budget (i.e. ui = 0 %). The uncertainty budget reported in a measurement report should correspond to the highest SAR value reported (after correction, if applicable). Alternatively, the uncertainty budget reported should cover all measurements, i.e., it should report a conservative value.

# 4.3. Test Equipment

Measuring equipment used to perform the tests is documented in this report and has been calibrated in accordance with UKAS' recommendations and is traceable to recognized national standards.

UL Asset No.	Instrument Name	Manufacturer	Туре	Serial No.	Date Last Calibrated	Cal. Interval (Months)
134153	E-Field Probe	SPEAG	ES3DV3	3341	21 Oct 2021	12
134031	Data Acquisition Equipment	SPEAG	DAE4	1435	18 Feb 2022	12
PRE0191239	Phantom	SPEAG	Twin Sam V8	1927	Cal. as part of system	-
130029	Dipole Antenna	SPEAG	D2450V2	725	22 Oct 2021	12
180463	POWERSOURCE1	SPEAG	SE UMS 160 BA	4012	20 Jun 2022	12
133919	RS Hygrometer	<b>RS</b> Components	408-6109	D10Q61	23 Feb 2022	12
PRE0134804	Body Handset Positioner	SPEAG	MD4HACV5	None	Cal. not required	-
PRE0134824	Head Handset Positioner	SPEAG	MD4HHTV5	None	Cal. not required	-
PRE0135027	Measurement Server	SPEAG	SE UMS 011 EA	1423	Cal. not required	-
PRE0141347	Phantom Support Structure	SPEAG	Phantom Table	-	Cal. not required	-
PRE0135134	Robot Arm	Staubli	TX60 L	F13/5SC6F1/A/01	Cal. not required	-
PRE0135131	Robot Power Supply	SPEAG	CS8C	F13/5SC6F1/C/01	Cal. not required	-
166282	Power Sensor	Rohde & Schwarz	NRP-Z51	103031-NV	31 Mar 2022	12
133453	Power Sensor	Agilent	U8481A	MY53040008	23 Mar 2022	12
174120	Thermometer (Fluid)	Testo	720	3327513	02 Mar 2022	12
147741	Vector Network Analyser	Rohde & Schwarz	ZND 132.5170K92	100151	01 Apr 2022	12
PRE0145189	DAK 3.5 Fluid Probe	SPEAG	SM DAK 040 CA	1089	Cal. before use	-
169654	Spectrum Analyser	Aeroflex	IFR 3252	l1601K011	18 Mar 2022	12
PRE0135306	Digital Camera	Nikon	S3600	41010357	Cal. not required	-

Page 10 of 49

# 4.3.1. SAR System Specifications

Robot System	
Positioner:	Stäubli Unimation Corp. Robot Model: TX60L
Repeatability:	±0.030 mm
No. of Axis:	6
Serial Number:	F13/5SC6F1/A/01
Reach:	800 mm
Payload:	2.0 kg
Control Unit:	CS8C
Programming Language:	V+
Data Acquisition Electronic (DAE) System	
Serial Number:	DAE4 SN: 1435
PC Controller	
PC:	HP EliteDesk800
Operating System:	Windows 10
Data Card:	DASY Measurement Server
Data Converter	
Features:	Signal Amplifier, multiplexer, A/D converted and control logic.
Software:	DASY6 PRO Software
Connecting Lines:	Optical downlink for data and status info. Optical uplink for commands and clock.
PC Interface Card	
Function:	24 bit (64 MHz) DSP for real time processing Link to DAE4 16 bit A/D converter for surface detection system serial link to robot direct emergency stop output for robot.
Phantom	
Phantom:	SAM Phantom
Shell Material:	Fibreglass
Thickness:	2.0 ±0.1 mm
E-Field Probe	
Model:	EX3DV3
Serial No:	3341
Construction:	Triangular core
Frequency:	10 MHz to > 4 GHz
Linearity:	±0.2 dB (30 MHz to 4 GHz)
Probe Length (mm):	337
Probe Diameter (mm):	10
Tip Length (mm):	10
Tip Diameter (mm):	4
Sensor X Offset (mm):	2
Sensor Y Offset (mm):	2
Sensor Z Offset (mm):	2

 Page 11 of 49

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# 5. Measurement Uncertainty

No measurement or test can ever be perfect, and the imperfections give rise to error of measurement in the results. Consequently, the result of a measurement is only an approximation to the value of the measurand (the specific quantity subject to measurement) and is only complete when accompanied by a statement of the uncertainty of the approximation.

The expression of uncertainty of a measurement result allows realistic comparison of results with reference values and limits given in specifications and standards.

The uncertainty of the result may need to be taken into account when interpreting the measurement results.

The reported expanded uncertainties below are based on a standard uncertainty multiplied by an appropriate coverage factor, such that a confidence level of approximately 95% is maintained. For the purposes of this document "approximately" is interpreted as meaning "effectively" or "for most practical purposes".

Test Name	Confidence Level	Calculated Uncertainty
Uncertainty- Freq. < 3 GHz 1g	95%	±25.42%
Uncertainty- Freq. < 3 GHz 10g	95%	±25.33%

The methods used to calculate the above uncertainties are in line with those recommended within the various measurement specifications. Where measurement specifications do not include guidelines for the evaluation of measurement uncertainty, the published guidance of the appropriate accreditation body is followed.

Page 12 of 49

 $\infty$ 

90

25.42

25.42

5.1. Ur	5.1. Uncertainty – Freq. < 3 GHz 1g									
Туре	Source of uncertainty	+ Value	- Value	Probability	Divisor	6		dard rtainty		
туре		+ value	- value	Distribution	DIVISOI	<b>C</b> <sub>i (1g)</sub>	+ u (%)	- u (%)		
В	Probe calibration	12.000	12.000	normal (k=2)	2.0000	1.0000	6.000	6.000		
В	Probe calibration drift	1.700	1.700	Rectangular	1.7321	1.0000	0.981	0.981		
В	Probe Linearity and Detection Limits	4.700	4.700	Rectangular	1.7321	1.0000	2.714	2.714		
В	Broadband Signal	3.000	3.000	Rectangular	1.7321	1.0000	1.732	1.732		
В	Probe Isotropy	7.600	7.600	Rectangular	1.7321	1.0000	4.388	4.388		
В	Data Acquisition	0.300	0.300	normal (k=1)	1.0000	1.0000	0.300	0.300		
В	RF Ambient conditions	0.260	0.260	normal (k=1)	1.0000	1.0000	0.260	0.260		
В	Probe Positioning	0.700	0.700	normal (k=1)	1.0000	0.1400	0.098	0.098		
В	Data Processing Errors	4.000	4.000	Rectangular	1.7321	1.0000	2.309	2.309		
В	Uncertainty in SAR correction for deviations in permittivity and conductivity	1.900	1.900	normal (k=1)	1.0000	1.0000	1.900	1.900		
В	Liquid Conductivity (measured value)	5.288	5.288	normal (k=2)	2.0000	0.0000	0.000	0.000		
В	Liquid Permittivity (measured value)	2.500	2.500	normal (k=2)	2.0000	0.0000	0.000	0.000		
В	Liquid Conductivity (temperature uncertainty)	1.430	1.430	Rectangular	1.7321	0.7800	0.644	0.644		
В	Liquid Permittivity (temperature uncertainty)	0.310	0.310	Rectangular	1.7321	0.7800	0.140	0.140		
В	Phantom Shell Permittivity	14.000	14.000	Rectangular	1.7321	0.2500	2.021	2.021		
В	Distance DUT - TSL	2.000	2.000	normal (k=1)	1.0000	2.0000	4.000	4.000		
А	Test Sample Positioning	4.240	4.240	normal (k=1)	1.0000	1.0000	4.240	4.240		
А	Device Holder uncertainty	6.090	6.090	normal (k=1)	1.0000	1.0000	6.090	6.090		
В	DUT Modulation	2.400	2.400	Rectangular	1.7321	1.0000	1.386	1.386		
В	Drift of output power	5.000	5.000	Rectangular	1.7321	1.0000	2.887	2.887		
	Combined standard uncertainty			t-distribution			12.71	12.71		

k = 2

## 5.1. Uncertainty – Freq. < 3 GHz 1g

Expanded uncertainty

# 5.2. Uncertainty – Freq. < 3 GHz 10g

_				Probability	<b>D</b>			ndard ertainty	υ <sub>i</sub> or
Туре	Source of uncertainty	+ Value	- Value	Distribution	Divisor	<b>C</b> i (10g)	+ u (%)	- u (%)	ບ <sub>eff</sub>
В	Probe calibration	12.000	12.000	normal (k=2)	2.0000	1.0000	6.000	6.000	×
В	Probe calibration drift	1.700	1.700	Rectangular	1.7321	1.0000	0.981	0.981	×
В	Probe Linearity and Detection Limits	4.700	4.700	Rectangular	1.7321	1.0000	2.714	2.714	8
В	Broadband Signal	3.000	3.000	Rectangular	1.7321	1.0000	1.732	1.732	×
В	Probe Isotropy	7.600	7.600	Rectangular	1.7321	1.0000	4.388	4.388	8
В	Data Acquisition	0.300	0.300	normal (k=1)	1.0000	1.0000	0.300	0.300	8
В	RF Ambient conditions	0.260	0.260	normal (k=1)	1.0000	1.0000	0.260	0.260	8
В	Probe Positioning	0.700	0.700	normal (k=1)	1.0000	0.1400	0.098	0.098	8
В	Data Processing Errors	4.000	4.000	Rectangular	1.7321	1.0000	2.309	2.309	×
В	Uncertainty in SAR correction for deviations in permittivity and conductivity	1.900	1.900	normal (k=1)	1.0000	0.8400	1.596	1.596	8
В	Liquid Conductivity (measured value)	5.288	5.288	normal (k=2)	2.0000	0.0000	0.000	0.000	8
В	Liquid Permittivity (measured value)	2.500	2.500	normal (k=2)	2.0000	0.0000	0.000	0.000	8
В	Liquid Conductivity (temperature uncertainty)	1.430	1.430	Rectangular	1.7321	0.7100	0.586	0.586	8
В	Liquid Permittivity (temperature uncertainty)	0.310	0.310	Rectangular	1.7321	0.7100	0.127	0.127	8
В	Phantom Shell Permittivity	14.000	14.000	Rectangular	1.7321	0.2500	2.021	2.021	8
В	Distance DUT - TSL	2.000	2.000	normal (k=1)	1.0000	2.0000	4.000	4.000	8
А	Test Sample Positioning	4.240	4.240	normal (k=1)	1.0000	1.0000	4.240	4.240	25
А	Device Holder uncertainty	6.090	6.090	normal (k=1)	1.0000	1.0000	6.090	6.090	5
В	DUT Modulation	2.400	2.400	Rectangular	1.7321	1.0000	1.386	1.386	8
В	Drift of output power	5.000	5.000	Rectangular	1.7321	1.0000	2.887	2.887	8
	Combined standard uncertainty			t-distribution			12.66	12.66	90
	Expanded uncertainty			k = 2			25.33	25.33	90

# 6. Equipment Under Test (EUT)

# 6.1. Description of Equipment Under Test (EUT)

Serial Number:	Radiated Samples	SAR1 : C08HR0XY1PL8 SAR2 : C08HR0U91PL8				
	Conducted Sample	RPT2 : C08HJ0NA1PL8				
Hardware Version Number:	Rev 1.0					
Software Version Number:	V0016					
Bluetooth FW Version:	0x004c					
Country of Manufacture:	China					
Date of Receipt:	12 Aug 2022					
DUT Description:	The device under test is a 'Siri Remote supporting Bluetooth radio'.					
Operating Configurations	Body-worn and Limbs					
Device dimension	Overall (Length x Width x Depth): 136.00 mm x 35.00 mm x 9.25 mm					
Dettern Terre	Standard – Lithium-ion battery					
Battery Type	Extended (large capacity)					

Page 15 of 49

## 6.2. Wireless Technologies

Wireless technologies	Frequency bands	Operating mode		Duty Cycle
Bluetooth	2.4 GHz	□ Core Spec. 4.0 □ Core Spec. 4.1 □ Core Spec. 4.2 ☑ Core Spec. 5.0	Basic Rate (BLE)	1-LE: 100 %
		<ul> <li>☑ Power Class 1</li> <li>☑ Power Class 2</li> <li>☑ Power Class 3</li> </ul>		

## Additional Information Related to Testing:

Antenna Type:	Internal integral
Antenna Lengths:	As specified in Appendix 12.1

Number of Antennas:	Antenna Name	Port / Core	Antenna Type	Antenna Description	Туре
	ANT1	Core 0	WPAN	Bluetooth	1 fixed

# **Wireless Technologies**

Bluetooth							
Band Description							
Bluetooth	Frequency Range: 2402 - 2480 MHz						
	Mode	Channel Number	Channel Description	Frequency (MHz)			
Didotootii		0	Low	2402.0			
	BLE	38	Middle	2440.0			
	Mode	78	High	2480.0			

# 6.3. Nominal and Maximum Output power: Bluetooth

## 6.3.1. BLE

RF Air interface	Mode	Packet Type	Channel	Maximum Power (dBm)
Bluetooth	BLE	1-LE	ALL	9.50

# 7. RF Exposure Conditions (Test Configurations)

## 7.1. Configuration Consideration

Technology Port	Configuration	Antenna-to- User Separation	Position	Antenna-to- Edge Separation (mm)	Evaluation Considered
BT (Core 0)	Body-Worn & Limbs	0mm	Front	< 50	Yes
			Back	< 50	Yes
			Тор	< 50	Yes
			Right	< 50	Yes
			Bottom	> 50	No
			Left	< 50	Yes

#### Notes:

1. The Antenna to edge separation distances are indicated in the 'Antenna Schematics' located in Section 12.1 of this report

# 7.2. SAR Test Exclusion Consideration

Frequency Band	Configuration(s)
	Body-worn & Limbs
Bluetooth	No

#### Note:

- 1. As per KDB Publication 447498, the frequency bands with rated power including upper tolerance, which qualify for standalone test exclusion, are as per the above table.
- 2. The details for the Maximum Rated Power and tolerance(s) can be found in section 6.3.1

Page 18 of 49

# **8.Conducted output power measurements**

## Wi-Fi Antennas

### 8.1. RF Output Average Power Measurement: Bluetooth

#### 8.1.2. Bluetooth 2.4 GHz – Duty Cycle

The duty cycle is calculated from the ratio of the on/off time at 0 Hz span.

	Title Ref	Noname 20.00 d			Att 3	0 dB				
Ref. Offset : 0.00 dB										
Detect : *Average										
Scale : LOG										
10.0 dB Input Z : 50 ohm										
Int. Amp : OFF										
Avg Type : PwAvg										
Trig Src : Free Run										
Swp Mode : Single										
Freq.Offset: 0.0 Sweep										
	44000	0000 GHz	z Cent	ter 2.	440000	000 GHz	z Sto	op 2.44	4000000	00 GHz
Span 0	Hz	*	RBW/*VE	3₩	1 MHz/	'3 MHz	*Sи	/p 10	.0 ms(5)	51 pts)

This screenshot shows that the ratio is 1 therefore at 100% duty cycle.

### 8.1.1. Bluetooth 2.4 GHz – Measurement Results

Channel Number	Packet Type	Frequency (MHz)	Avg Power (dBm)	Operating Mode
0	1-LE	2402.0	7.66	
38	1-LE	2440.0	7.85	BLE (GFSK)
78	1-LE	2480.0	7.91	

# 9. Dielectric Property Measurements & System Check

#### 9.1.Tissue Dielectric Parameters

The temperature of the tissue-equivalent medium used during measurement must also be within  $18^{\circ}$ C to  $25^{\circ}$ C and within  $\pm 2^{\circ}$ C of the temperature when the tissue parameters are characterized.

The dielectric parameters must be measured before the tissue-equivalent medium is used in a series of SAR measurements. The parameters should be re-measured after each 3 - 4 days of use; or earlier if the dielectric parameters can become out of tolerance; for example, when the parameters are marginal at the beginning of the measurement series.

Tissue dielectric parameters were measured at the low, middle and high frequency of each operating frequency range of the test device.

Page 20 of 49

#### IEC/IEEE 62209-1528:2020

arget Frequency	Head Sim	ulating Liquid
(MHz)	ε <sub>r</sub>	σ (S/m)
4	55.00	0.75
13	55.00	0.75
30	55.00	0.75
150	52.30	0.76
300	45.30	0.87
450	43.50	0.87
750	41.90	0.89
835	41.50	0.90
900	41.50	0.97
915	41.50	0.98
1450	40.50	1.20
1500	40.40	1.23
1610	40.30	1.29
1640	40.20	1.31
1750	40.10	1.37
1800	40.00	1.40
1900	40.00	1.40
2000	40.00	1.40
2100	39.80	1.49
2300	39.50	1.67
2450	39.20	1.80
2600	39.00	1.96
3000	38.50	2.40
3500	37.90	2.91
4000	37.40	3.43
4500	36.80	3.94
5000	36.20	4.45
5100	36.10	4.55
5200	36.00	4.66
5250	35.90	4.71
5300	35.90	4.76
5400	35.80	4.86
5500	35.60	4.96
5600	35.50	5.07
5700	35.40	5.17
5750	35.40	5.22
5800	35.30	5.27
6000	35.10	5.48
6500	34.50	6.07
7000	33.90	6.65
7500	33.30	7.24
8000	32.70	7.84
8500	32.10	8.46
9000	31.60	9.08
9500	31.00	9.71
10000	30.40	10.40

**NOTE**: For convenience, permittivity and conductivity values at some frequencies that are not part of the original data from Drossos et al. [B60] or the extension to 5800 MHz are provided (i.e., the values shown in italics). These values were linearly interpolated between the values in this table that are immediately above and below these values, except the values at 6000 MHz that were linearly extrapolated from the values at 3000 MHz and 5800 MHz.

### 9.2. System Check

SAR system verification is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

#### 9.3. Numerical SAR Target Values

The numerical SAR target values are obtained from the reference standards. The measured values are normalised to 1 Watt.

Custom Dinala		Numerical SAR Target Values (W/kg)		
System Dipole	Freq. (MHz)	1g/10g	HSL	
		1g	52.40	
D2450V2	2450	10g	24.00	

Page 22 of 49

#### 9.4. Dielectric Property Measurements & System Check Results

The 1-g SAR and 10-g SAR measured with a reference dipole, using the required tissue-equivalent medium at the test frequency, must be within  $\pm 10\%$  of the manufacturer calibrated dipole SAR target and  $\pm 15\%$  of the numerical target.

#### <u>Site 59</u>

#### 2450 Head

Date: 12 Aug 2022 Reference Dipole Antenna: D2450V2 - SN725

Simulant	Frequency (MHz)	Room Temp(°C)	Liquid Temp(°C)	Parameters	Measured Value	Target Type	Target Value	Deviation (%)	Limit (%)
	2450	22.2	22.1	٤r	38.76	Numerical	39.20	-1.13	10
				σ (S/m)	1.83	Numerical	1.80	1.47	10
Head				1 ~ (\\///.~)	52.43	Experimental	52.70	-0.50	10
пеаu	2430	22.2	22.1	1g (W/kg)	<b>19 (W/Kg)</b> 52.43 Nume	Numerical	52.40	0.07	15
				10g (W/kg)	24.59	Experimental	24.70	-0.44	10
				TUG (WV/KG)	24.59	Numerical	24.00	2.46	15

#### 2450 Head

Date: 20 Sep 2022 Reference Dipole Antenna: D2450V2 - SN725

Simulant	Frequency (MHz)	Room Temp(°C)	Liquid Temp(°C)	Parameters	Measured Value	Target Type	Target Value	Deviation (%)	Limit (%)
	2450	20.7	20.7	٤r	39.08	Numerical	39.20	-0.30	10
				σ (S/m)	1.84	Numerical	1.80	2.20	10
Head				0.7 <b>1g (W/kg)</b> 54.	54.07	Experimental	52.70	2.60	10
пеац	2430	20.7	20.7		<b>ig (w/kg)</b> 54.07	Numerical	52.40	3.19	15
				10q (W/kq)	25.14	Experimental	24.70	1.78	10
				iug (w/kg)	23.14	Numerical	24.00	4.75	15

Page 23 of 49

# **10. Measurements, Examinations and Derived Result**

# 10.1. Specific Absorption Rate - Test Results – Bluetooth

## 10.1.1.Bluetooth Body-worn 1g Max Reported SAR = 0.53 (W/kg)

					Power	(dBm)	1g: SAR Results (W/kg)				
Mode	Dist. (mm)	EUT Position	Channel Number	Freq (MHz)	Tune Up Limit	Meas.	Meas. SAR Level	Reported SAR	Transmitting Antenna	Notes	Plot No.
GFSK	0	Front	78	2480.0	9.50	7.91	0.12	0.18	Core 0	-	-
GFSK	0	Back	78	2480.0	9.50	7.91	0.12	0.18	Core 0	-	-
GFSK	0	Тор	78	2480.0	9.50	7.91	0.16	0.22	Core 0	-	-
GFSK	0	Right	78	2480.0	9.50	7.91	0.03	0.05	Core 0	-	-
GFSK	0	Left	78	2480.0	9.50	7.91	0.05	0.07	Core 0	-	-
GFSK	0	Тор	0	2402.0	9.50	7.66	0.35	0.53	Core 0	-	001
GFSK	0	Тор	38	2440.0	9.50	7.85	0.22	0.31	Core 0	-	-
Note(s):	•			•		•		•			•

#### 10.1.2.Bluetooth Limbs 10g Max Reported SAR = 0.11 (W/kg)

					Power	(dBm)	10g: SAR Results (W/kg)				
Mode	Dist. (mm)	EUT Position	Channel Number	Freq (MHz)	Tune Up Limit	Meas.	Meas. SAR Level	Reported SAR	Transmitting Antenna	Notes	Plot No.
GFSK	0	Front	78	2480.0	9.50	7.91	0.05	0.07	Core 0	-	-
GFSK	0	Back	78	2480.0	9.50	7.91	0.05	0.08	Core 0	-	-
GFSK	0	Тор	78	2480.0	9.50	7.91	0.04	0.06	Core 0	-	-
GFSK	0	Right	78	2480.0	9.50	7.91	0.02	0.02	Core 0	-	-
GFSK	0	Left	78	2480.0	9.50	7.91	0.02	0.03	Core 0	-	-
GFSK	0	Back	0	2402.0	9.50	7.66	0.05	0.07	Core 0	-	-
GFSK	0	Back	38	2440.0	9.50	7.85	0.08	0.11	Core 0	-	002

Page 24 of 49

#### 10.2. SAR Measurement Variability

In accordance with published RF Exposure KDB procedure 865664 D01 SAR measurement 100 MHz to 6 GHz. These additional measurements are repeated after the completion of all measurements requiring the same head or body tissue-equivalent medium in a frequency band. The test device should be returned to ambient conditions (normal room temperature) with the battery fully charged before it is re-mounted on the device holder for the repeated measurement(s) to minimize any unexpected variations in the repeated results.

#### Body-worn 1g-SAR:

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.8 W/Kg; steps 2) through 4) do not apply.
- 2) When the original highest measured 1g-SAR is  $\geq$  0.8 W/Kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg (~ 10% from the 1g-SAR limit).
- Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.50 W/Kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

#### Limbs 10g-SAR:

- 1) Repeated measurement is not required when the original highest measured SAR is < 2.0 W/Kg; steps 2) through 4) do not apply.
- 2) When the original highest measured 10g-SAR is  $\geq$  2.00 W/Kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 3.625 W/kg (~ 10% from the 10g-SAR limit).
- Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 3.75 W/Kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

Note: Measured 1g-SAR & 10g-SAR levels were below the thresholds hence measurement variability was not considered.

# **11. Highest Standalone SAR and Simultaneous Transmission**

## 11.1.Highest Standalone Reported SAR

# Individual Transmitter Evaluation per Band: Bluetooth

# Bluetooth Body-worn 1g

		Reported 1g - SAR (W/Kg)		Highest	
Exposure Configuration	Technology Band	Core 0	Equipment Class	Reported 1g	
		Ant 1		-SAR (W/Kg)	
Body-worn (Separation Distance 0mm)	Bluetooth	0.53	DSS	0.53	

# Bluetooth Limbs 10g

		Reported 10g - SAR (W/Kg)		Highest	
Exposure Configuration	Technology Band	Core 0	Equipment Class	Reported 10g -SAR	
		Ant 1		(Ŵ/Kg)	
Limbs (Separation Distance 0mm)	Bluetooth	0.11	DSS	0.11	

# 11.2. Simultaneous Transmission analysis

Simultaneous transmission SAR test analysis is determined for each operating configuration and exposure condition according to the *reported* standalone SAR of each applicable simultaneous transmitting antenna.

Note: No Simultaneous Transmission is required as DUT only support one Tx Antenna.

Page 26 of 49