

DASY4 Validation Report for Head TSL

Date/Time: 27.09.2006 11:58:51

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN722

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: HSL U10 BB;

Medium parameters used: $f = 2450$ MHz; $\sigma = 1.77$ mho/m; $\epsilon_r = 37.8$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV2 - SN3025 (HF); ConvF(4.4, 4.4, 4.4); Calibrated: 28.10.2005
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 15.12.2005
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; ;
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:

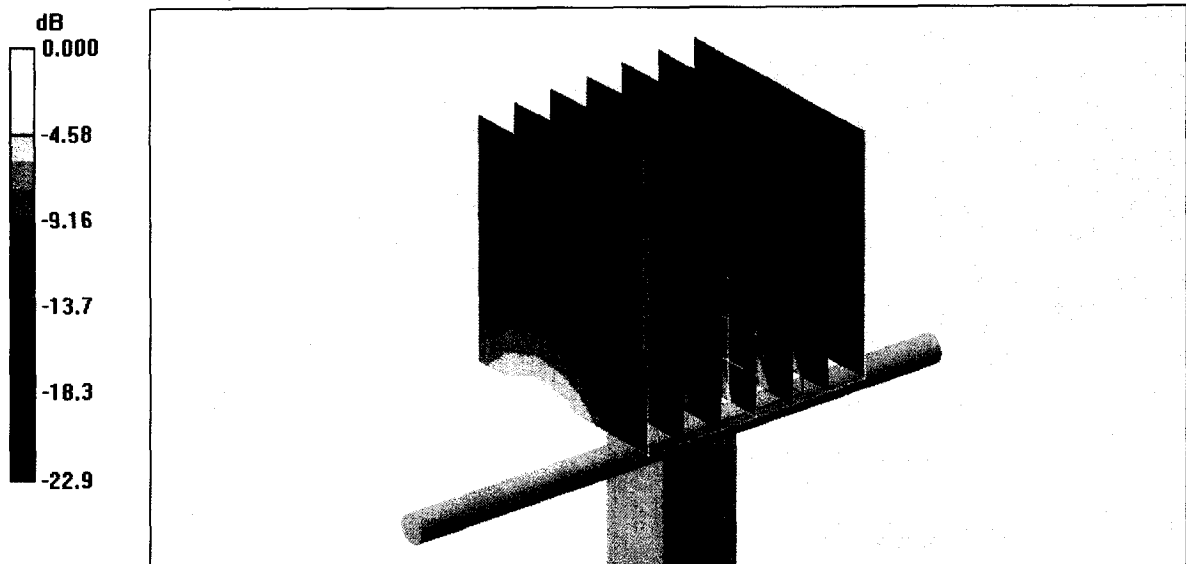
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 90.6 V/m; Power Drift = -0.016 dB

Peak SAR (extrapolated) = 28.4 W/kg

SAR(1 g) = 13.6 mW/g; SAR(10 g) = 6.31 mW/g

Maximum value of SAR (measured) = 15.2 mW/g



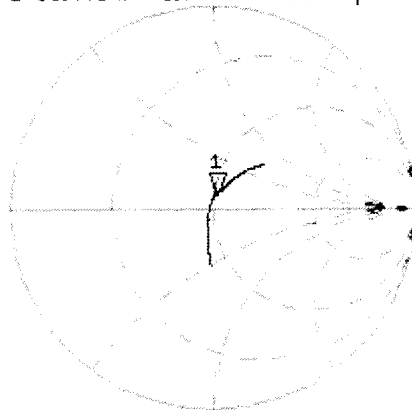
0 dB = 15.2mW/g

Impedance Measurement Plot for Head TSL

27 Sep 2006 10:24:48

CH1 S11 1 U FS 1: 50.445 Ω 6.3594 Ω 413.11 μH 2 450.000 000 MHz

*
De1
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Avg
16

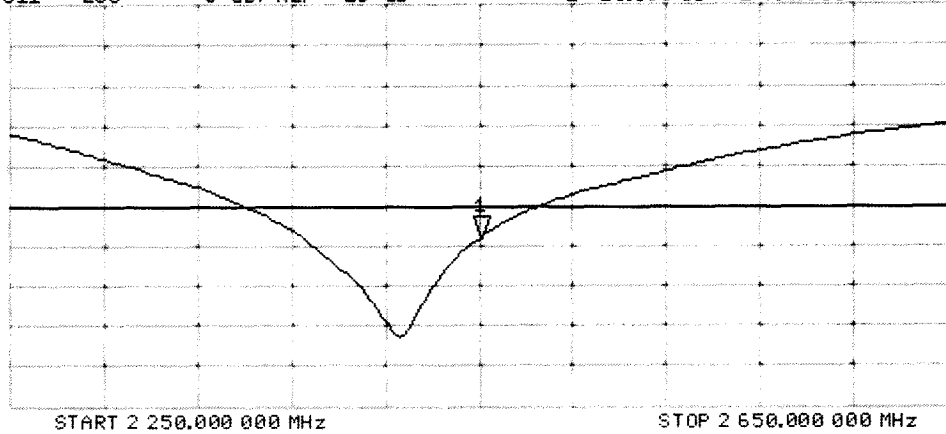
↑

CH2 S11 LOG 5 dB/REF -20 dB 1: -23.958 dB 2 450.000 000 MHz

Cor

Avg
16

↑



DASY4 Validation Report for Body TSL

Date/Time: 27.09.2006 14:44:54

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN722

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: MSL U10 BB;

Medium parameters used: $f = 2450$ MHz; $\sigma = 1.97$ mho/m; $\epsilon_r = 52.2$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV2 - SN3025 (HF); ConvF(4.06, 4.06, 4.06); Calibrated: 28.10.2005
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 15.12.2005
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; ;
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:

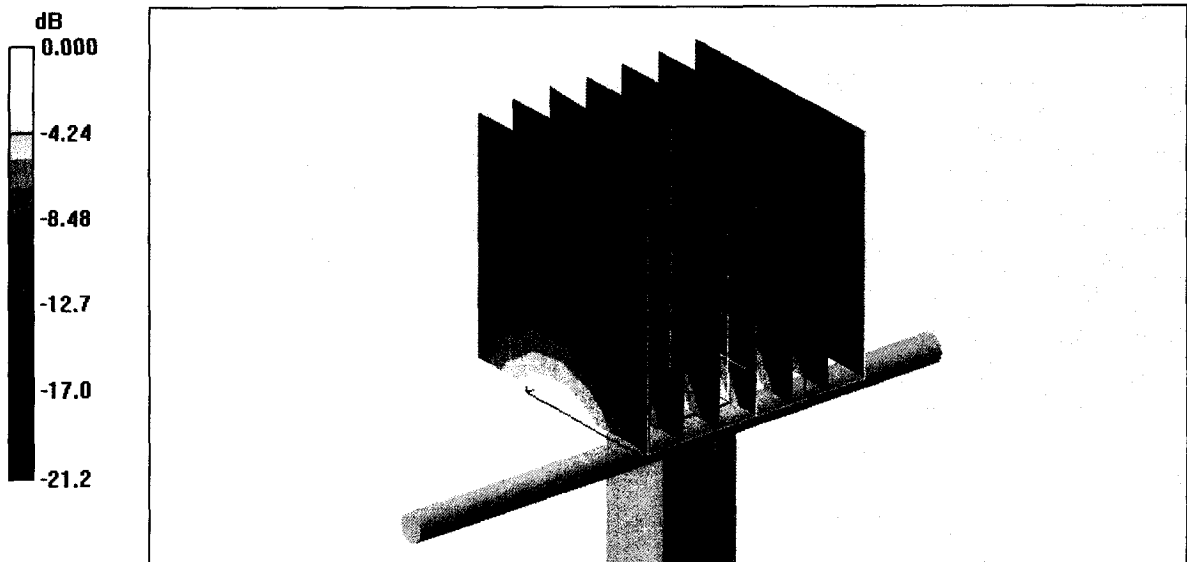
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 89.4 V/m; Power Drift = 0.005 dB

Peak SAR (extrapolated) = 29.3 W/kg

SAR(1 g) = 13.8 mW/g; SAR(10 g) = 6.39 mW/g

Maximum value of SAR (measured) = 15.7 mW/g



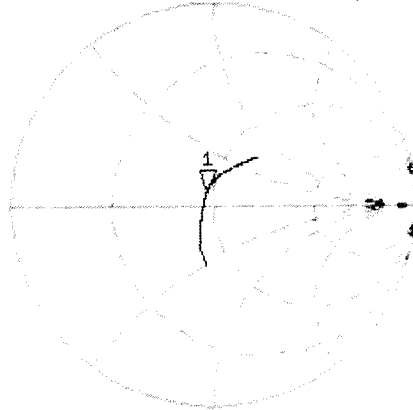
0 dB = 15.7mW/g

Impedance Measurement Plot for Body TSL

27 Sep 2006 10:26:30

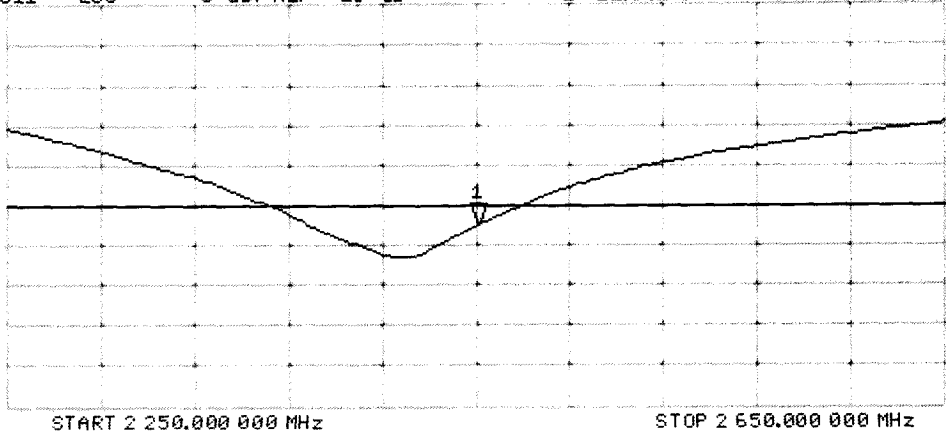
[CH1] S11 1 U FS 1: 46.539 Ω 6.2676 Ω 407.15 pF 2 450.000 000 MHz

*
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Cor
Avg
16
↑



CH2 S11 LOG 5 dB/REF -20 dB 1: -22.612 dB 2 450.000 000 MHz

Cor
Avg
16
↑





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Accreditation No.: **SCS 108**

Client **Eurofins**

Certificate No: **ET3-1711_Sep08**

CALIBRATION CERTIFICATE

Object **ET3DV6 - SN:1711**

Calibration procedure(s) **QA CAL-01.v6, QA CAL-12.v5 and QA CAL-23.v3
Calibration procedure for dosimetric E-field probes**

Calibration date: **September 17, 2008**

Condition of the calibrated item **In Tolerance**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	1-Apr-08 (No. 217-00788)	Apr-09
Power sensor E4412A	MY41495277	1-Apr-08 (No. 217-00788)	Apr-09
Power sensor E4412A	MY41498087	1-Apr-08 (No. 217-00788)	Apr-09
Reference 3 dB Attenuator	SN: S5054 (3c)	1-Jul-08 (No. 217-00865)	Jul-09
Reference 20 dB Attenuator	SN: S5086 (20b)	31-Mar-08 (No. 217-00787)	Apr-09
Reference 30 dB Attenuator	SN: S5129 (30b)	1-Jul-08 (No. 217-00866)	Jul-09
Reference Probe ES3DV2	SN: 3013	2-Jan-08 (No. ES3-3013_Jan08)	Jan-09
DAE4	SN: 660	9-Sep-08 (No. DAE4-660_Sep08)	Sep-09

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-07)	In house check: Oct-09
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-07)	In house check: Oct-08

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	
Approved by:	Niels Kuster	Quality Manager	

Issued: September 17, 2008

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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary:

TSL	tissue simulating liquid
NORM _{x,y,z}	sensitivity in free space
ConvF	sensitivity in TSL / NORM _{x,y,z}
DCP	diode compression point
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\vartheta = 0$ ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not effect the E^2 -field uncertainty inside TSL (see below *ConvF*).
- NORM(f)_{x,y,z} = NORM_{x,y,z} * frequency_response** (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of *ConvF*.
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters**: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800$ MHz) and inside waveguide using analytical field distributions based on power measurements for $f > 800$ MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z} * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy)**: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

Probe ET3DV6

SN:1711

Manufactured:	August 7, 2002
Last calibrated:	September 19, 2007
Recalibrated:	September 17, 2008

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

DASY - Parameters of Probe: ET3DV6 SN:1711Sensitivity in Free Space^ADiode Compression^B

NormX	1.92 ± 10.1%	$\mu\text{V}/(\text{V}/\text{m})^2$	DCP X	90 mV
NormY	1.86 ± 10.1%	$\mu\text{V}/(\text{V}/\text{m})^2$	DCP Y	93 mV
NormZ	2.04 ± 10.1%	$\mu\text{V}/(\text{V}/\text{m})^2$	DCP Z	92 mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

Boundary Effect

TSL	900 MHz	Typical SAR gradient: 5 % per mm		
	Sensor Center to Phantom Surface Distance		3.7 mm	4.7 mm
	SAR _{be} [%]	Without Correction Algorithm	9.8	5.8
	SAR _{be} [%]	With Correction Algorithm	0.9	0.2

TSL	1810 MHz	Typical SAR gradient: 10 % per mm		
	Sensor Center to Phantom Surface Distance		3.7 mm	4.7 mm
	SAR _{be} [%]	Without Correction Algorithm	10.4	6.5
	SAR _{be} [%]	With Correction Algorithm	0.8	0.4

Sensor Offset

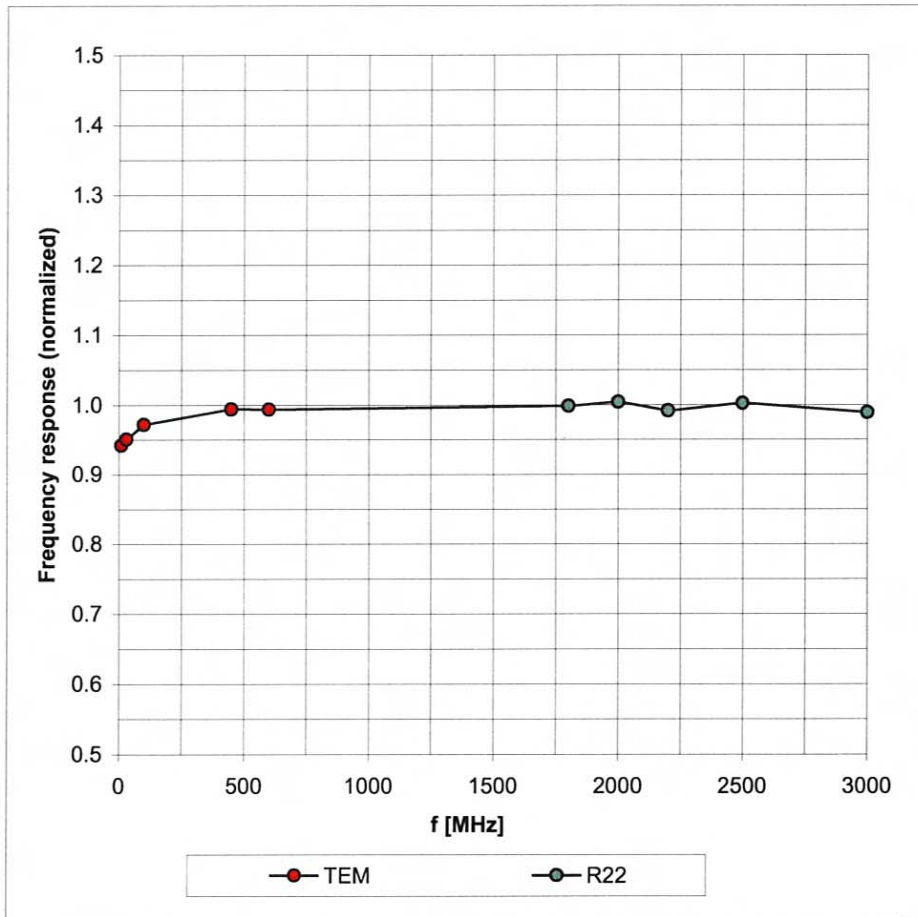
Probe Tip to Sensor Center **2.7 mm**

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A The uncertainties of NormX,Y,Z do not affect the E²-field uncertainty inside TSL (see Page 8).^B Numerical linearization parameter: uncertainty not required.

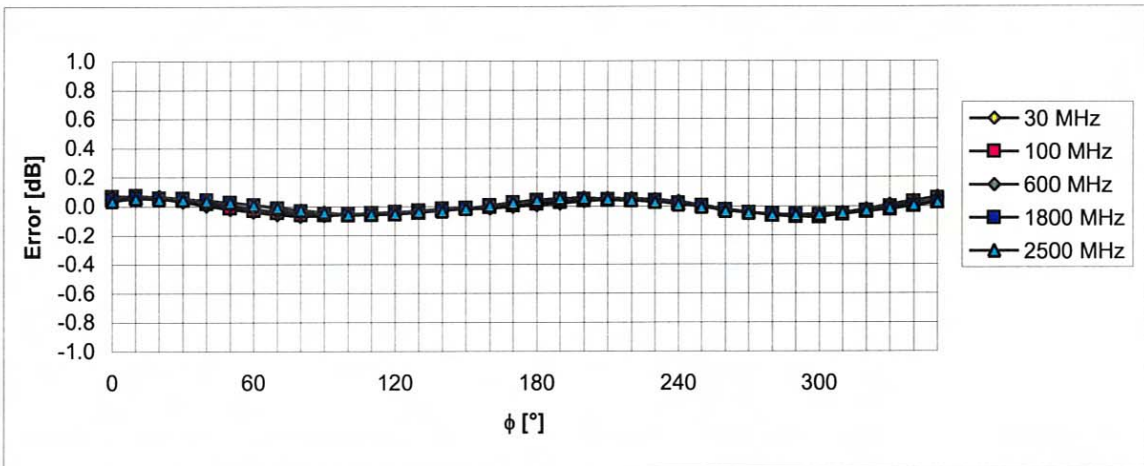
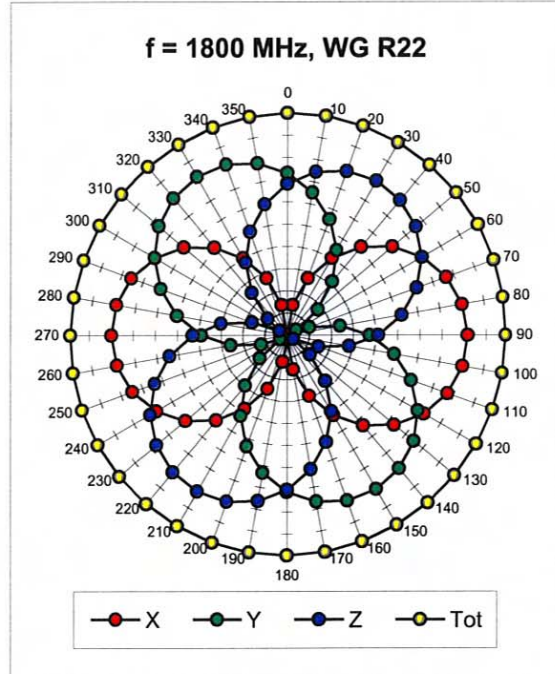
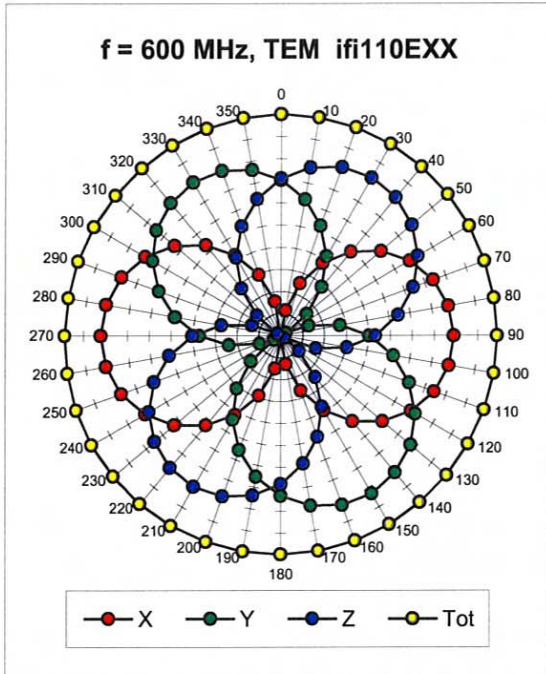
Frequency Response of E-Field

(TEM-Cell: ifi110 EXX, Waveguide: R22)



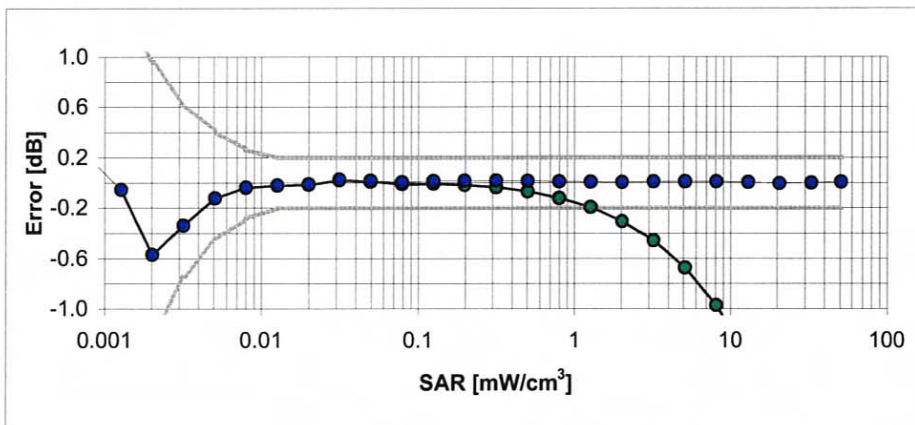
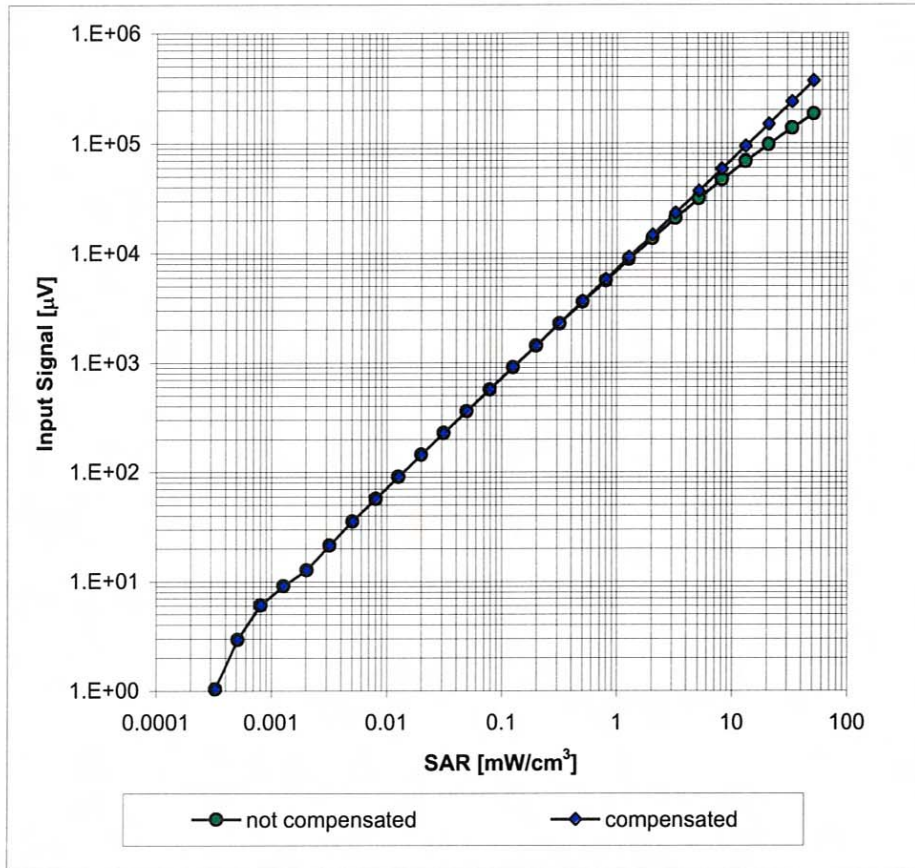
Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



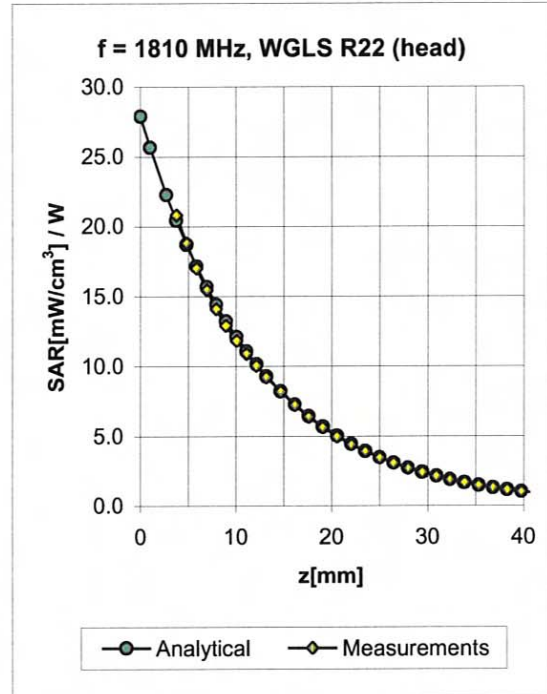
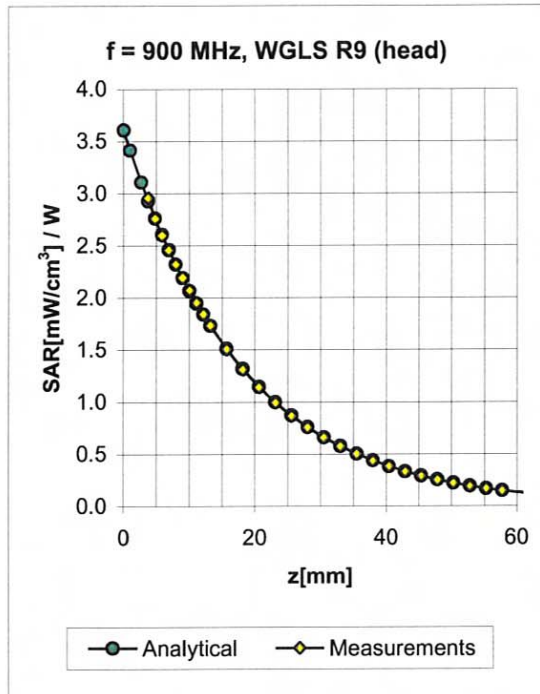
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Dynamic Range $f(\text{SAR}_{\text{head}})$ (Waveguide R22, $f = 1800 \text{ MHz}$)



Uncertainty of Linearity Assessment: $\pm 0.6\%$ ($k=2$)

Conversion Factor Assessment

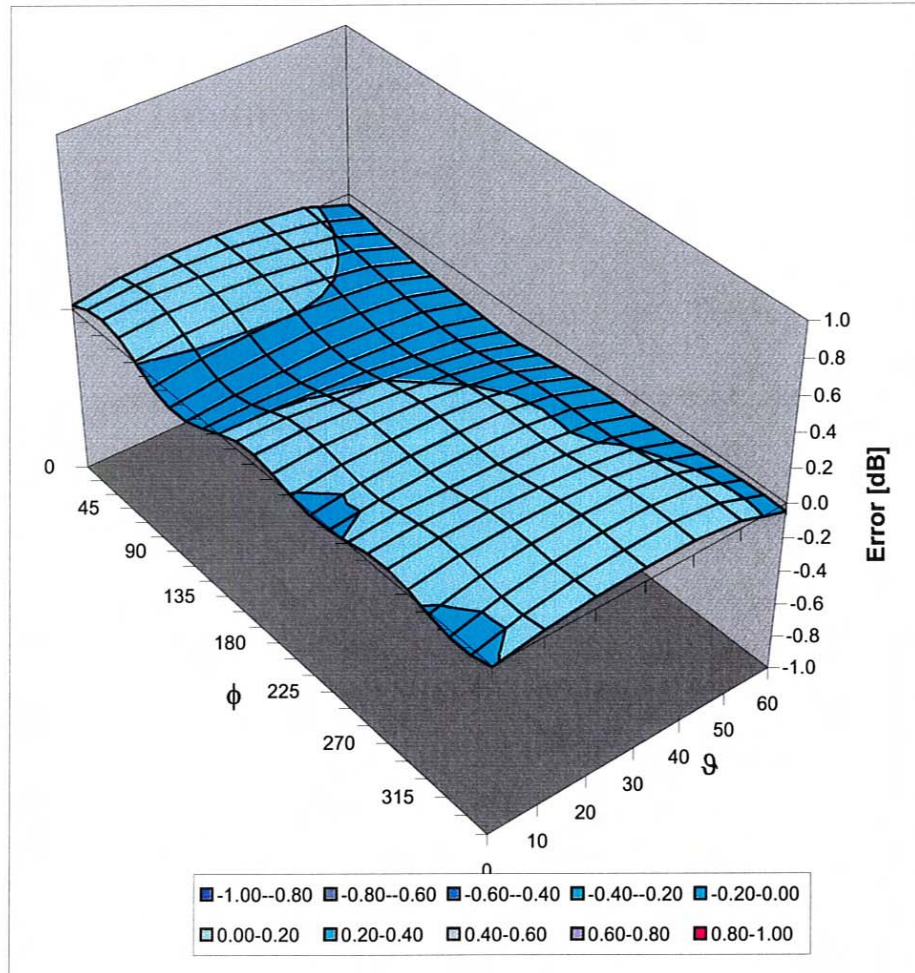


f [MHz]	Validity [MHz] ^c	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
450	± 50 / ± 100	Head	43.5 ± 5%	0.87 ± 5%	0.34	1.75	7.42 ± 13.3% (k=2)
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.30	2.88	6.17 ± 11.0% (k=2)
1810	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.67	1.95	5.17 ± 11.0% (k=2)
1950	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.79	1.69	4.96 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.85	1.50	4.55 ± 11.0% (k=2)
450	± 50 / ± 100	Body	56.7 ± 5%	0.94 ± 5%	0.28	1.82	7.91 ± 13.3% (k=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	0.38	2.65	6.01 ± 11.0% (k=2)
1810	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.70	2.03	4.57 ± 11.0% (k=2)
1950	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.76	1.82	4.51 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.85	1.55	3.81 ± 11.0% (k=2)

^c The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

Deviation from Isotropy in HSL

Error (ϕ , ϑ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)



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Accreditation No.: **SCS 108**

Client **Eurofins**

Certificate No: **DAE3-522_Sep08**

CALIBRATION CERTIFICATE

Object **DAE3 - SD 000 D03 AA - SN: 522**

Calibration procedure(s) **QA CAL-06.v12
Calibration procedure for the data acquisition electronics (DAE)**

Calibration date: **September 16, 2008**

Condition of the calibrated item **In Tolerance**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Fluke Process Calibrator Type 702	SN: 6295803	04-Oct-07 (No: 6467)	Oct-08
Keithley Multimeter Type 2001	SN: 0810278	03-Oct-07 (No: 6465)	Oct-08
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Calibrator Box V1.1	SE UMS 006 AB 1004	06-Jun-08 (in house check)	In house check: Jun-09

Calibrated by: **Name** Andrea Guntli **Function** Technician **Signature**

Approved by: **Name** Fin Bomholt **Function** R&D Director **Signature**

Issued: September 16, 2008

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Glossary

DAE data acquisition electronics
Connector angle information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle:* The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
 - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
 - *AD Converter Values with inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
 - *Input Offset Measurement:* Output voltage and statistical results over a large number of zero voltage measurements.
 - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - *Input resistance:* DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
 - *Power consumption:* Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 μ V, full range = -100...+300 mV

Low Range: 1LSB = 61nV, full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.296 \pm 0.1% (k=2)	403.979 \pm 0.1% (k=2)	404.799 \pm 0.1% (k=2)
Low Range	3.96483 \pm 0.7% (k=2)	3.94724 \pm 0.7% (k=2)	3.95304 \pm 0.7% (k=2)

Connector Angle

Connector Angle to be used in DASY system	59 $^{\circ}$ \pm 1 $^{\circ}$
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Appendix

1. DC Voltage Linearity

High Range		Input (μV)	Reading (μV)	Error (%)
Channel X	+ Input	200000	200000.1	0.00
Channel X	+ Input	20000	20004.65	0.02
Channel X	- Input	20000	-19997.96	-0.01
Channel Y	+ Input	200000	200000.2	0.00
Channel Y	+ Input	20000	20002.06	0.01
Channel Y	- Input	20000	-20002.21	0.01
Channel Z	+ Input	200000	199999.5	0.00
Channel Z	+ Input	20000	20000.45	0.00
Channel Z	- Input	20000	-20000.24	0.00

Low Range		Input (μV)	Reading (μV)	Error (%)
Channel X	+ Input	2000	2000	0.00
Channel X	+ Input	200	199.52	-0.24
Channel X	- Input	200	-199.25	-0.38
Channel Y	+ Input	2000	2000	0.00
Channel Y	+ Input	200	199.61	-0.19
Channel Y	- Input	200	-199.68	-0.16
Channel Z	+ Input	2000	2000.1	0.00
Channel Z	+ Input	200	198.97	-0.51
Channel Z	- Input	200	-200.89	0.44

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	-4.55	-4.98
	- 200	5.39	5.72
Channel Y	200	-1.09	-1.66
	- 200	-0.37	-0.36
Channel Z	200	16.19	16.11
	- 200	-17.75	-17.97

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	3.70	0.32
Channel Y	200	0.80	-	3.59
Channel Z	200	-3.13	-0.50	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15722	15373
Channel Y	15735	14486
Channel Z	16044	16908

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10MΩ

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	0.98	-0.32	2.54	0.62
Channel Y	-1.57	-3.53	-0.17	0.62
Channel Z	-0.13	-1.30	1.18	0.51

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.2000	198.1
Channel Y	0.2001	199.4
Channel Z	0.2001	196.4

8. Low Battery Alarm Voltage (verified during pre test)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9

Annex B

Measurement Plots

Test Laboratory: Eurofins Product Service GmbH

Dipol Valid.2450 (h)_250mW 18.12.08

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 722

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: Head 2450 MHz Medium parameters used (interpolated): $f = 2450$ MHz; $\sigma = 1.84$ mho/m;

$\epsilon_r = 38$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.55, 4.55, 4.55); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

Dipol 2450 (250mW)/Area Scan (61x81x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 13.5 mW/g

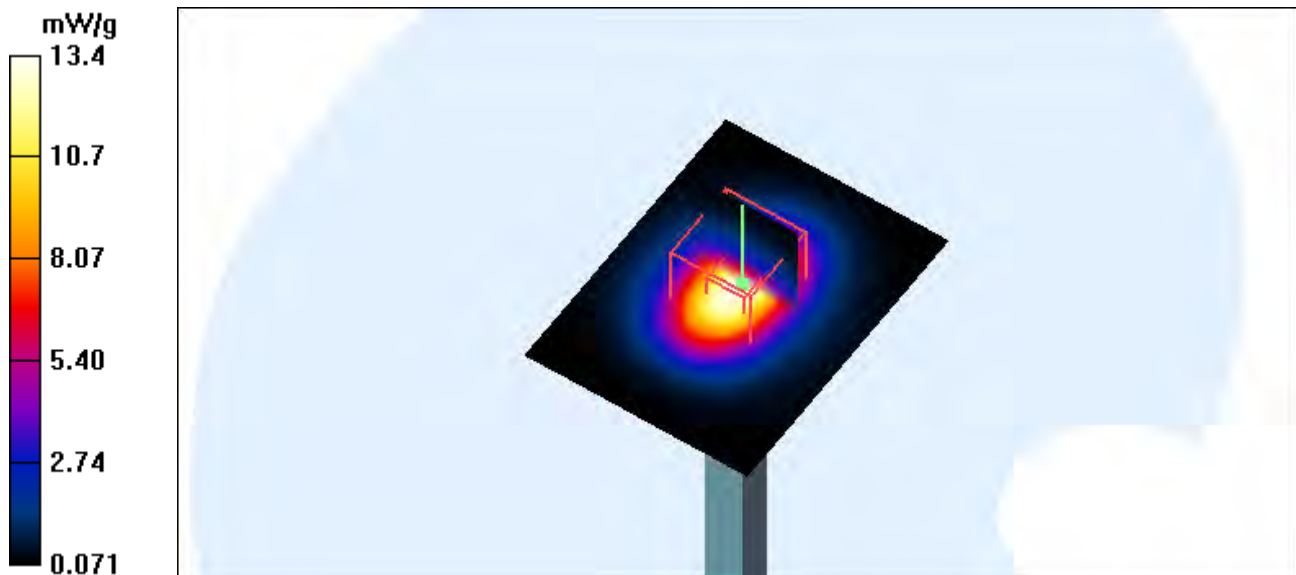
Dipol 2450 (250mW)/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 87.0 V/m; Power Drift = -0.028 dB

Peak SAR (extrapolated) = 28.4 W/kg

SAR(1 g) = 12.4 mW/g; SAR(10 g) = 5.53 mW/g

Maximum value of SAR (measured) = 13.4 mW/g



Test Laboratory: Eurofins Product Service GmbH

Bluetooth_2402_right_cheek

DUT: GO 6400HS; Type: Bluetooth Headset; Serial: without

Communication System: Bluetooth; Frequency: 2402 MHz; Duty Cycle: 1:2

Medium: Head 2450 MHz Medium parameters used (interpolated): $f = 2402$ MHz; $\sigma = 1.79$ mho/m;

$\epsilon_r = 38$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.55, 4.55, 4.55); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

GO 6400HS/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.482 mW/g

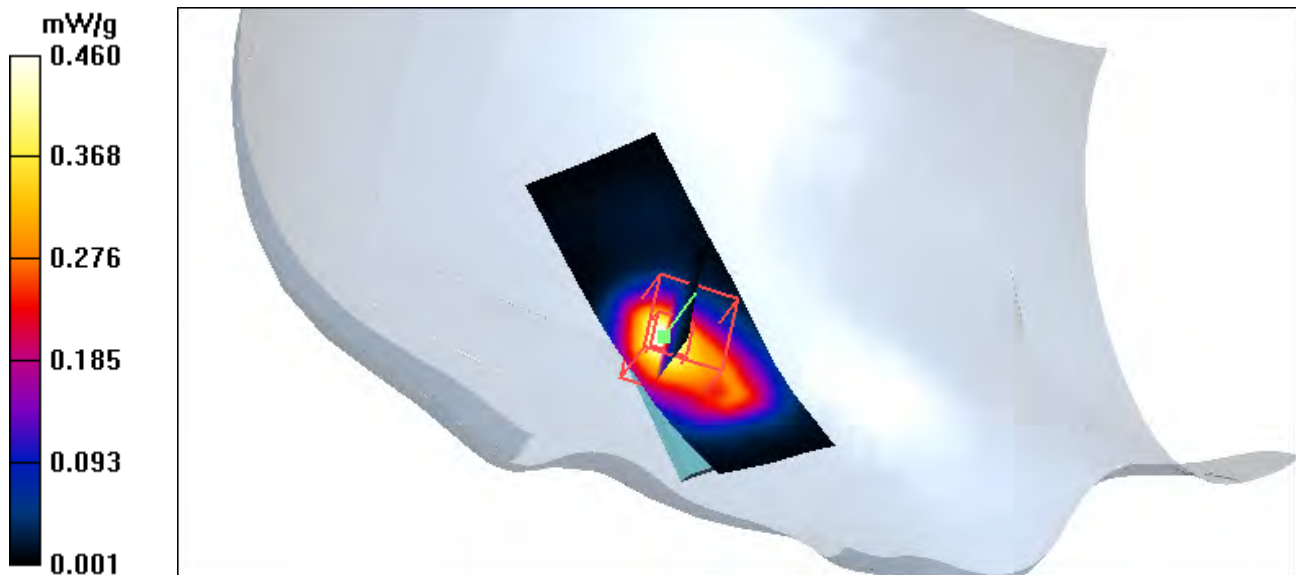
GO 6400HS/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 3.27 V/m; Power Drift = -0.065 dB

Peak SAR (extrapolated) = 0.872 W/kg

SAR(1 g) = 0.414 mW/g; SAR(10 g) = 0.185 mW/g

Maximum value of SAR (measured) = 0.460 mW/g



Test Laboratory: Eurofins Product Service GmbH

Bluetooth_2441_right_cheek

DUT: Bluetooth Headset; Type: GO 6400HS; Serial: without

Communication System: GO 6400HS; Frequency: 2441 MHz; Duty Cycle: 1:2

Medium: Head 2450 MHz Medium parameters used (interpolated): $f = 2441$ MHz; $\sigma = 1.84$ mho/m;

$\epsilon_r = 38$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.55, 4.55, 4.55); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

GO 6400HS/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.443 mW/g

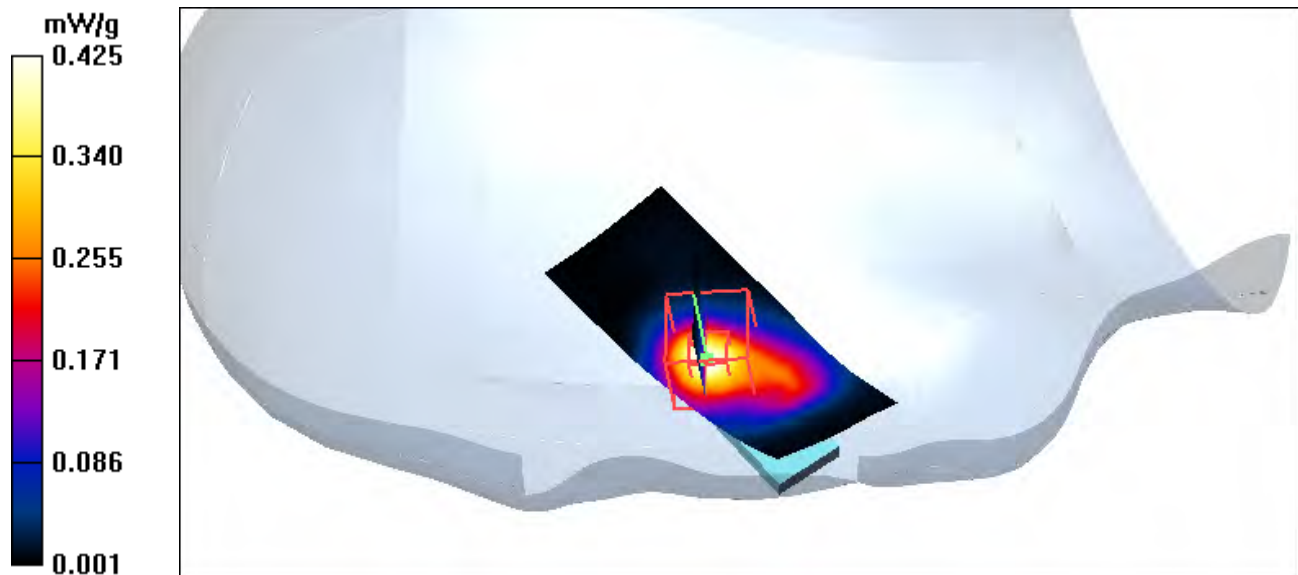
GO 6400HS/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.31 V/m; Power Drift = -0.013 dB

Peak SAR (extrapolated) = 0.821 W/kg

SAR(1 g) = 0.376 mW/g; SAR(10 g) = 0.168 mW/g

Maximum value of SAR (measured) = 0.425 mW/g



Test Laboratory: Eurofins Product Service GmbH

Bluetooth_2441_right_tilted

DUT: Bluetooth Headset; Type: GO 6400HS; Serial: without

Communication System: GO 6400HS; Frequency: 2441 MHz; Duty Cycle: 1:2

Medium: Head 2450 MHz Medium parameters used (interpolated): $f = 2441$ MHz; $\sigma = 1.84$ mho/m;

$\epsilon_r = 38$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.55, 4.55, 4.55); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

GO 6400HS/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.042 mW/g

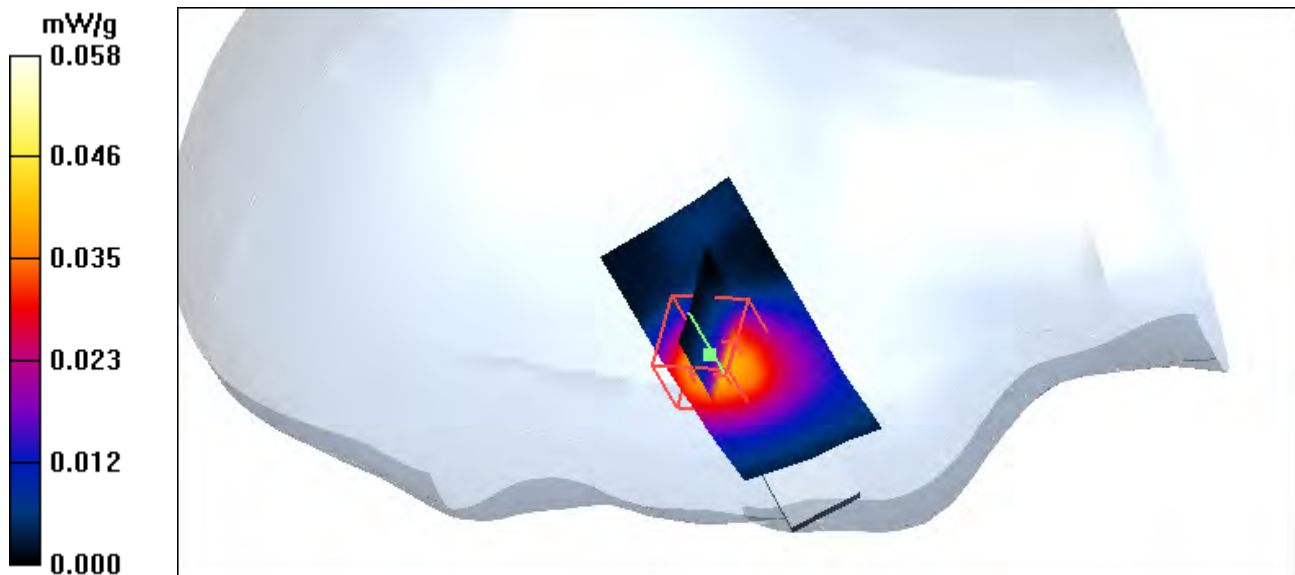
GO 6400HS/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 1.79 V/m; Power Drift = -0.191 dB

Peak SAR (extrapolated) = 0.077 W/kg

SAR(1 g) = 0.038 mW/g; SAR(10 g) = 0.020 mW/g

Maximum value of SAR (measured) = 0.041 mW/g



Test Laboratory: Eurofins Product Service GmbH

Bluetooth_2480_right_cheek

DUT: GO 6400HS; Type: Bluetooth Headset; Serial: without

Communication System: Bluetooth; Frequency: 2480 MHz; Duty Cycle: 1:2

Medium: Head 2450 MHz Medium parameters used: $f = 2480$ MHz; $\sigma = 1.87$ mho/m; $\epsilon_r = 37.8$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.55, 4.55, 4.55); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

GO 6400HS/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.555 mW/g

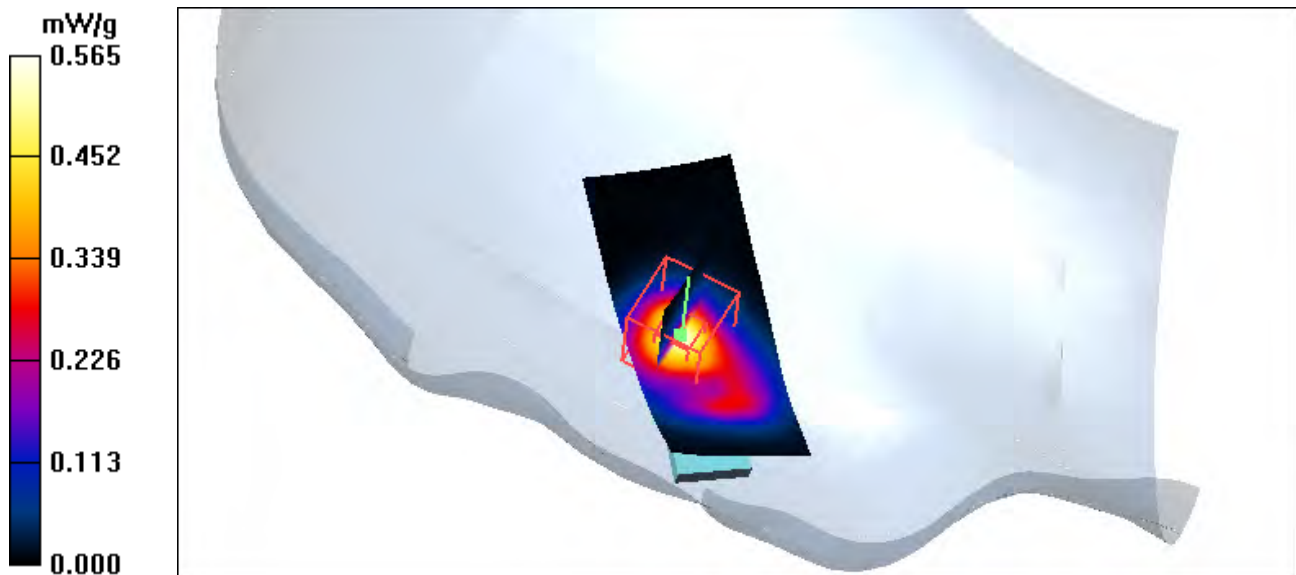
GO 6400HS/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.30 V/m; Power Drift = -0.015 dB

Peak SAR (extrapolated) = 1.13 W/kg

SAR(1 g) = 0.500 mW/g; SAR(10 g) = 0.212 mW/g

Maximum value of SAR (measured) = 0.565 mW/g



Test Laboratory: Eurofins Product Service GmbH

Bluetooth_2441_left_cheek

DUT: Bluetooth Headset; Type: GO 6400HS; Serial: without

Communication System: GO 6400HS; Frequency: 2441 MHz; Duty Cycle: 1:2

Medium: Head 2450 MHz Medium parameters used (interpolated): $f = 2441$ MHz; $\sigma = 1.84$ mho/m;

$\epsilon_r = 38$; $\rho = 1000$ kg/m³

Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.55, 4.55, 4.55); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

GO 6400HS/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.300 mW/g

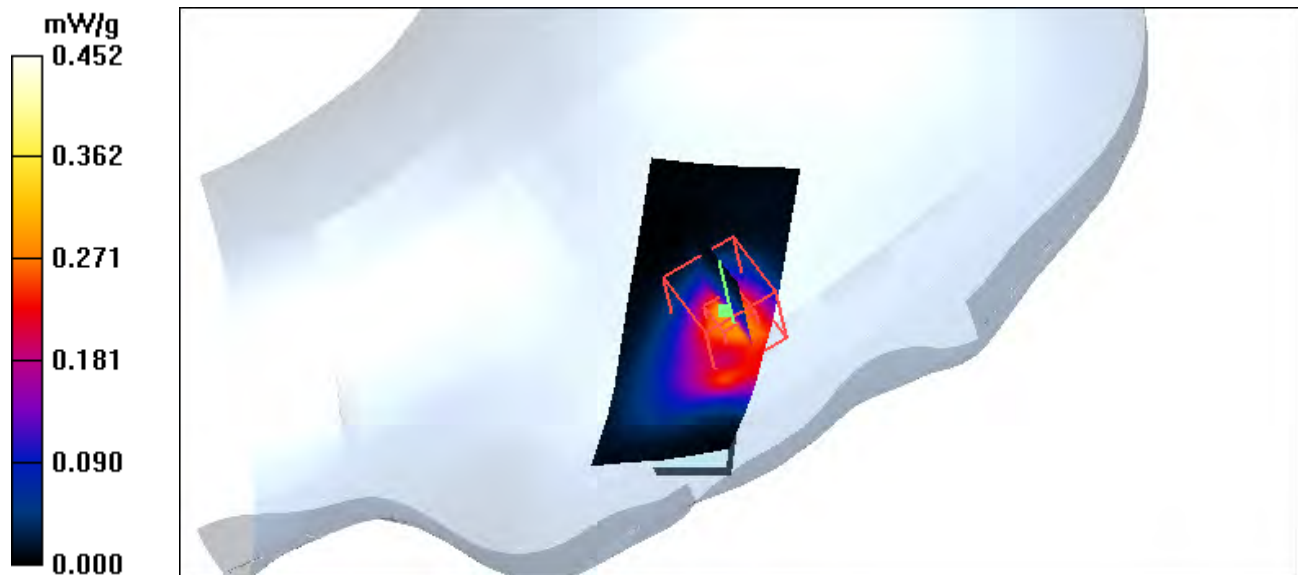
GO 6400HS/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 1.96 V/m; Power Drift = -0.041 dB

Peak SAR (extrapolated) = 0.603 W/kg

SAR(1 g) = 0.269 mW/g; SAR(10 g) = 0.130 mW/g

Maximum value of SAR (measured) = 0.292 mW/g



Test Laboratory: Eurofins Product Service GmbH

Bluetooth_2441_left_tilted

DUT: GO 6400HS; Type: Bluetooth Headset; Serial: without

Communication System: Bluetooth; Frequency: 2441 MHz; Duty Cycle: 1:2

Medium: Head 2450 MHz Medium parameters used (interpolated): $f = 2441$ MHz; $\sigma = 1.84$ mho/m;

$\epsilon_r = 38$; $\rho = 1000$ kg/m³

Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.55, 4.55, 4.55); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

GO 6400HS/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.090 mW/g

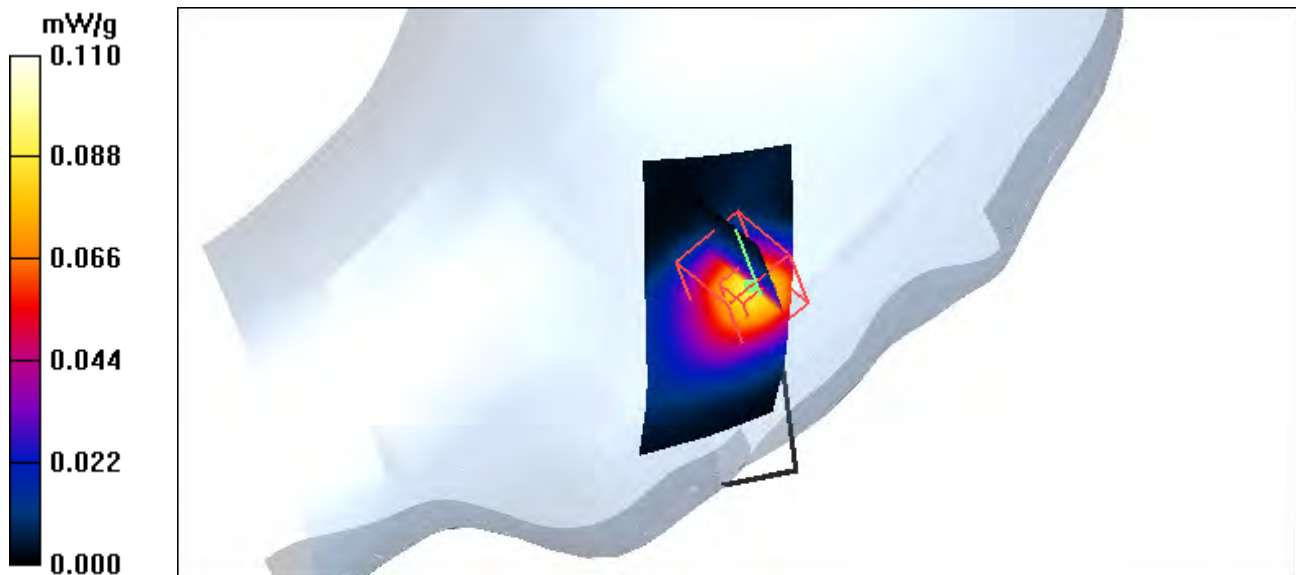
GO 6400HS/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 1.62 V/m; Power Drift = -0.192 dB

Peak SAR (extrapolated) = 0.159 W/kg

SAR(1 g) = 0.075 mW/g; SAR(10 g) = 0.039 mW/g

Maximum value of SAR (measured) = 0.079 mW/g



Test Laboratory: Eurofins Product Service GmbH

Bluetooth_2480_right_cheek_Z - axis scan

DUT: GO 6400HS; Type: Bluetooth Headset; Serial: without

Communication System: Bluetooth; Frequency: 2480 MHz; Duty Cycle: 1:2

Medium: Head 2450 MHz Medium parameters used: $f = 2480$ MHz; $\sigma = 1.87$ mho/m; $\epsilon_r = 37.8$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.55, 4.55, 4.55); Calibrated: 9/17/2008
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/16/2008
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

GO 6400HS/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.555 mW/g

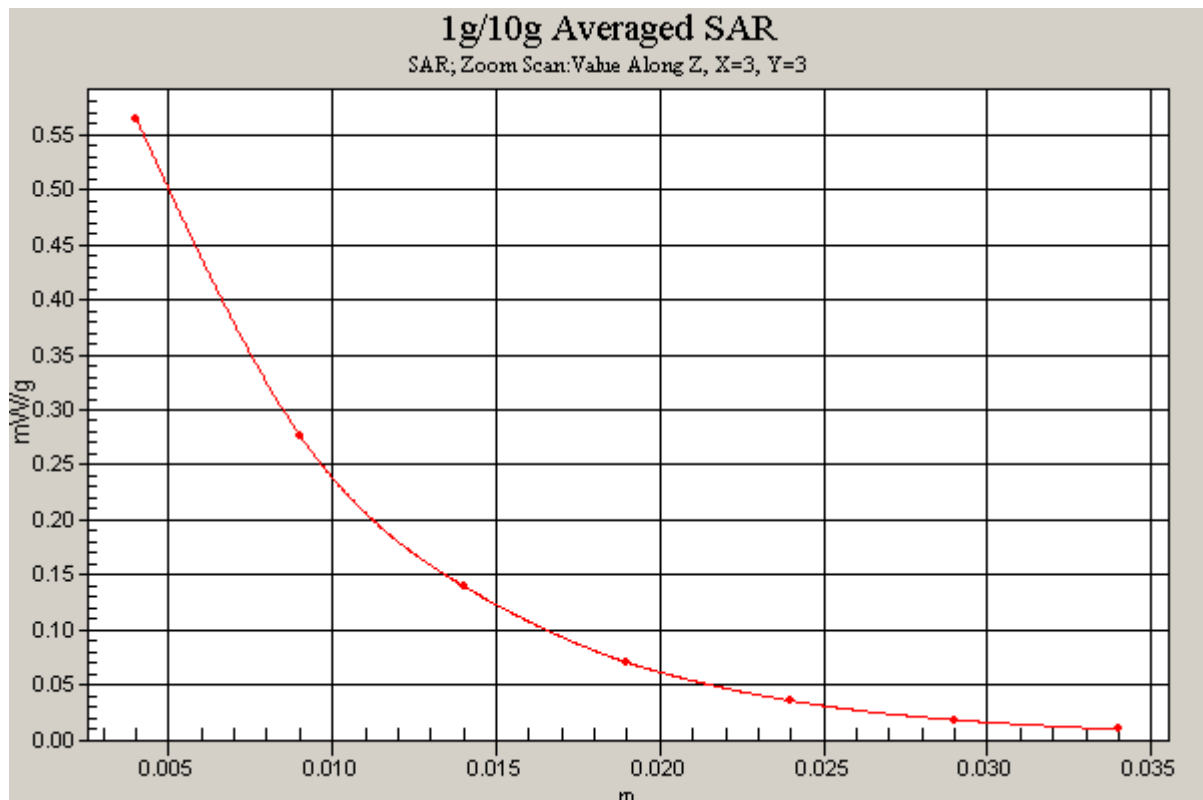
GO 6400HS/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.30 V/m; Power Drift = -0.015 dB

Peak SAR (extrapolated) = 1.13 W/kg

SAR(1 g) = 0.500 mW/g; SAR(10 g) = 0.212 mW/g

Maximum value of SAR (measured) = 0.565 mW/g



Annex C**Pictures**