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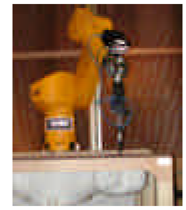


CERTIFICATE OF COMPLIANCE (SAR EVALUATION)

APPLICANT NAME & ADDRESS:	**DATE & LOCATION OF TESTING:**
UNIDEN Corporation	**Dates of Tests: Feb. 28, 2005**
2-12-7 Hatchobori, Chuo-ku	**Test Report S/N: 0502220130**
Tokyo, JAPAN 104-8512	**Test Site: PCTEST Lab, Columbia MD**

FCC ID:	**AMWUU360**
APPLICANT:	**UNIDEN CORPORATION**

EUT Type:	**2.4 GHz Wireless Microphone**
Tx Frequency:	**2407.424 – 2477.056 MHz**
Rx Frequency:	**2407.424 – 2477.056 MHz**
Max. RF Output Power:	**13.68 dBm Peak Conducted**
Max. SAR Measurement:	**0.043 W/kg Body SAR; 0.113 W/kg Face SAR**
Trade Name/Model(s):	**WHAM (xx)**
FCC Classification:	**Part 15 Digital Transmission System (DTS)**
FCC Rule Part(s):	**§2.1093; FCC/OET Bulletin 65 Supplement C [July 2001]**
Application Type:	**Certification**
Test Device Serial No.:	***identical* prototype [S/N: #4]**

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC/OET Bulletin 65 Supplement C (2001) and IEEE Std. 1528 - 2003.

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them.

Grant Conditions: Output power is conducted. This device has been tested for SAR compliance for body-worn operation. SAR compliance for body-worn operating configurations is limited to the specific belt-clip tested for this filing. End-users must be informed of the body-worn operating requirements for satisfying RF exposure compliance.

PCTEST certifies that no party to this application has been denied the FCC benefits pursuant to Section 5301 of the Anti-Drug Abuse Act of 1988, 21 U.S.C. 862.

Alfred Cirwithian
Vice President Engineering

TABLE OF CONTENTS

1. INTRODUCTION / SAR DEFINITION

The FCC has adopted the guidelines for evaluating the environmental effects of radiofrequency radiation in ET Docket 93-62 on Aug. 6, 1996 to protect the public and workers from the potential hazards of RF emissions due to FCC-regulated portable devices.[1]

The safety limits used for the environmental evaluation measurements are based on the criteria published by the American National Standards Institute (ANSI) for localized specific absorption rate (SAR) in *IEEE/ANSI C95.1-1992 Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz*. (c) 1992 by the Institute of Electrical and Electronics Engineers, Inc., New York, New York 10017.[2] The measurement procedure described in *IEEE/ANSI C95.3-1992 Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields - RF and Microwave*[3] is used for guidance in measuring SAR due to the RF radiation exposure from the Equipment Under Test (EUT). These criteria for SAR evaluation are similar to those recommended by the National Council on Radiation Protection and Measurements (NCRP) in *Biological Effects and Exposure Criteria for Radiofrequency Electromagnetic Fields,"* NCRP Report No. 86 (c) NCRP, 1986, Bethesda, MD 20814.[6] SAR is a measure of the rate of energy absorption due to exposure to an RF transmitting source. SAR values have been related to threshold levels for potential biological hazards.

SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dU) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (r). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Fig. 1.1).

$$SAR = \frac{d}{dt}\left(\frac{dU}{dm}\right) = \frac{d}{dt}\left(\frac{dU}{r\,dv}\right)$$

Figure 1.1
SAR Mathematical Equation

SAR is expressed in units of Watts per Kilogram (W/kg).

$$SAR = s\,E^2 / r$$

where:

s	=	conductivity of the tissue-simulant material (S/m)
r	=	mass density of the tissue-simulant material (kg/m^3)
E	=	Total RMS electric field strength (V/m)

NOTE: The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane.[6]

2. SAR MEASUREMENT SETUP

Robotic System

Measurements are performed using the DASY4 automated dosimetric assessment system. The DASY4 is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, Pentium III computer, near-field probe, probe alignment sensor, and the generic twin phantom containing the brain equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF) (see Fig. 2.1).

System Hardware

A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and a remote control used to drive the robot motors. The PC consists of the Gateway Pentium 4 2.53 GHz computer with Windows XP system and SAR Measurement Software DASY4, A/D interface card, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

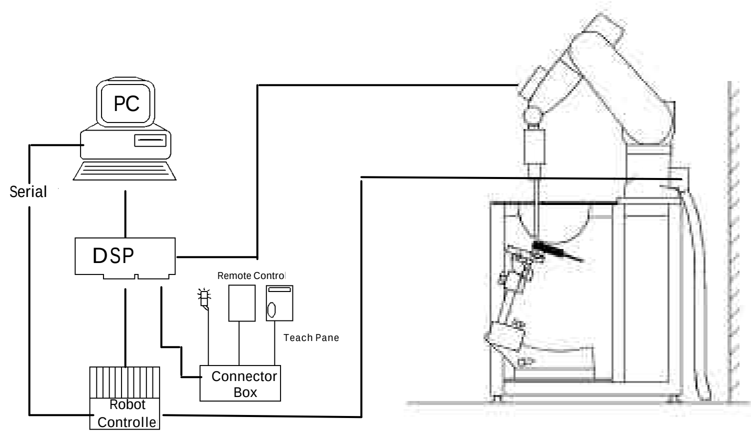


Figure 2.1 SAR Measurement System Setup

System Electronics

The DAE3 consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail in [7].

3. DASY4 E-FIELD PROBE SYSTEM

Probe Measurement System

Figure 3.1 DAE System

The SAR measurements were conducted with the dosimetric probe ET3DV6, designed in the classical triangular configuration [7] (see Fig. 3.2) and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip (see Fig. 3.3). It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting (see Fig.3.1). The approach is stopped at reaching the maximum.

Probe Specifications

Calibration:	In air from 10 MHz to 6 GHz
	In brain and muscle simulating tissue at
	Frequencies of 150 MHz, 450 MHz, 835 MHz, 900 MHz, 1900MHz, 2450MHz, 5300MHz, & 5800MHz
Frequency:	10 MHz to > 6 GHz; Linearity: ± 0.2 dB
	(30 MHz to 6 GHz)
Directivity:	± 0.2 dB in HSL (rotation around probe axis)
	± 0.4 dB in HSL (rotation normal probe axis)
Dynamic:	5 :W/g to > 100 mW/g;
Range:	Linearity: ± 0.2 dB
Dimensions:	Overall length: 330 mm
	Tip length: 16 mm
	Body diameter: 12 mm
	Tip diameter: 3 mm
	Distance from probe tip to dipole centers: 2 mm
Application:	General dosimetry up to 6 GHz
	Compliance tests of mobile phones
	Fast automatic scanning in arbitrary phantoms

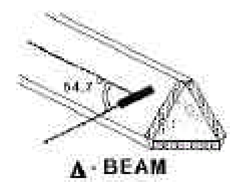


Figure 3.1 Triangular Probe Configuration

Figure 3.2 Probe Thick-Film Technique

4. Probe Calibration Process

Dosimetric Assessment Procedure

Each probe is calibrated according to a dosimetric assessment procedure described in [8] with accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure described in [9] and found to be better than +/-0.25dB. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe is tested.

Free Space Assessment

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies below 1 GHz (see Fig. 4.1), and in a waveguide above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity at the proper orientation with the field. The probe is then rotated 360 degrees.

Temperature Assessment *

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe (see Fig. 4.2).

$$\text{SAR} = C\frac{\Delta T}{\Delta t}$$

where:

Δt = exposure time (30 seconds),

C = heat capacity of tissue (brain or muscle),

ΔT = temperature increase due to RF exposure.

SAR is proportional to $\Delta T / \Delta t$, the initial rate of tissue heating, before thermal diffusion takes place. Now it's possible to quantify the electric field in the simulated tissue by equating the thermally derived SAR to the E- field;

$$\text{SAR} = \frac{|E|^2 \cdot \sigma}{\rho}$$

where:

σ = simulated tissue conductivity,

ρ = Tissue density (1.25 g/cm^3 for brain tissue)

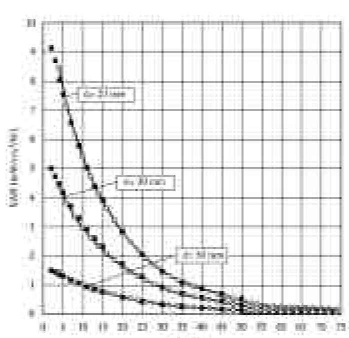


Figure 4.1 E-Field and Temperature measurements at 900MHz [7]

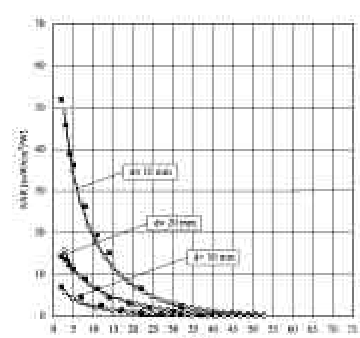


Figure 4.2 E-Field and temperature measurements at 1.9GHz [7]

**NOTE: The temperature calibration was not performed by PCTEST. For information use only.*

5. PHANTOM & EQUIVALENT TISSUES

SAM Phantom

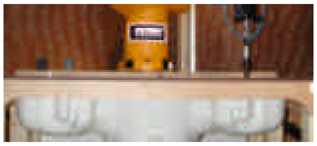


Figure 5.1 SAM Twin Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a wooden table. The shape of the shell is based on data from an anatomical study designed to determine the maximum exposure in at least 90% of all users [11][12]. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents the evaporation of the liquid. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. (see Fig. 5.1)

Brain & Muscle Simulating Mixture Characterization

Figure 5.2 Simulated Tissue

The brain and muscle mixtures consist of a viscous gel using hydroxethylcellullose (HEC) gelling agent and saline solution (see Table 6.1). Preservation with a bacteriacide is added and visual inspection is made to make sure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the desired tissue. The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 have been incorporated in the following table. Other head and body tissue parameters that have not bee specified in P1528 are derived from the issue dielectric parameters computed from the 4-Cole-Cole equations The mixture characterizations used for the brain and muscle tissue simulating liquids are according to the data by C. Gabriel and G. Hartsgrove [13].(see Fig. 5.2)

Table 5.1 Composition of the Brain & Muscle Tissue Equivalent Matter

Ingredients (% by weight)	Frequency (MHz)									
	450		835		915		1900		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	38.56	51.16	41.45	52.4	41.05	56.0	54.9	40.4	62.7	73.2
Salt (NaCl)	3.95	1.49	1.45	1.4	1.35	0.76	0.18	0.5	0.5	0.04
Sugar	56.32	46.78	56.0	45.0	56.5	41.76	0.0	58.0	0.0	0.0
HEC	0.98	0.52	1.0	1.0	1.0	1.21	0.0	1.0	0.0	0.0
Bactericide	0.19	0.05	0.1	0.1	0.1	0.27	0.0	0.1	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	0.0	0.0	0.0	0.0	44.92	0.0	0.0	26.7

Salt: 99⁺% Pure Sodium Chloride   Sugar: 98⁺% Pure Sucrose
Water: De-ionized, 16 MΩ⁺ resistivity   HEC: Hydroxyethyl Cellulose
DGBE: 99⁺% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]
Triton X-100 (ultra pure): Polyethylene glycol mono [4-(1,1, 3, 3-tetramethylbutyl)phenyl] ether

Device Holder for Transmitters

Figure 5.2 Mounting Device

In combination with the SAM Twin Phantom V4.0, the Mounting Device (see Fig. 5.2) enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation point is the ear opening. The devices can be easily, accurately, and repeatably be positioned according to the FCC specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).

* Note: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produce infinite number of configurations [12]. To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.

6. TEST SYSTEM SPECIFICATIONS

Automated Test System Specifications

Positioner

Robot: Stäubli Unimation Corp. Robot Model: RX60L
Repeatability: 0.02 mm
No. of axis: 6

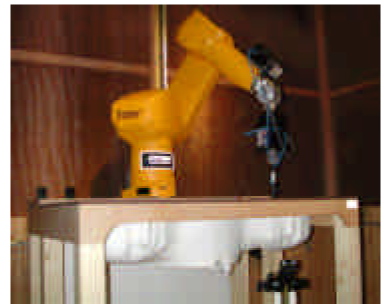


Figure 6.1 DASY4 Test System

Data Acquisition Electronic (DAE) System

Cell Controller

Processor: Pentium 4
Clock Speed: 2.53 GHz
Operating System: Windows XP Professional

Data Converter

Features: Signal Amplifier, multiplexer, A/D converter, & control logic
Software: DASY4 software
Connecting Lines: Optical downlink for data and status info.
Optical uplink for commands and clock

PC Interface Card

Function: 24 bit (64 MHz) DSP for real time processing
Link to DAE3
16 bit A/D converter for surface detection system
serial link to robot
direct emergency stop output for robot

E-Field Probes

Model: EX3DV4 S/N: 3550
Construction: Triangular core
Frequency: 10 MHz to 6 GHz
Linearity: ± 0.2 dB (30 MHz to 6 GHz)

Phantom

Phantom: SAM Twin Phantom (V4.0)
Shell Material: VIVAC Composite
Thickness: 2.0 ± 0.2 mm

7. DOSIMETRIC ASSESSMENT & PHANTOM SPECS

Measurement Procedure

The evaluation was performed using the following procedure:

1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing. This fixed location point was measured and used as a reference value.
2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 15mm x 15mm.
3. Based on the area scan data, the area of the maximum absorption was determined by spline interpolation. Around this point, a volume of 32mm x 32mm x 34mm (fine resolution volume scan, zoom scan) was assessed by measuring 7 x 7 x 7 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure (see Fig. 7.1):

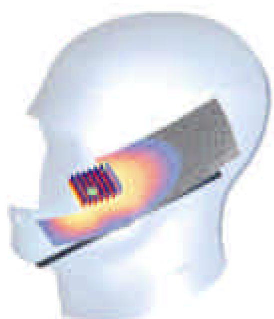


Figure 7.1 Sample SAR Area Scan

a. The data at the surface was extrapolated, since the center of the dipoles is 2.7mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2mm. The extrapolation was based on a least square algorithm [15]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.

b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the “Not a knot” condition (in x, y, and z directions) [15][16]. The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.

c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

4. The SAR reference value, at the same location as procedure #1, was re-measured. If the value changed by more than 5%, the evaluation is repeated.

Deviation from measurement procedure - None

Specific Anthropomorphic Mannequin (SAM) Specifications

The phantom for handset SAR assessment testing is a low-loss dielectric shell, with shape and dimensions derived from the anthropometric data of the 90th percentile adult male head dimensions as tabulated by the US Army. The SAM Twin Phantom shell is bisected along the mid-sagittal plane into right and left halves (see Fig. 7.2). The perimeter sidewalls of each phantom halves are extended to allow filling with liquid to a depth that is sufficient to minimized reflections from the upper surface. The liquid depth is maintained at a minimum depth of 15cm to minimize reflections from the upper surface.

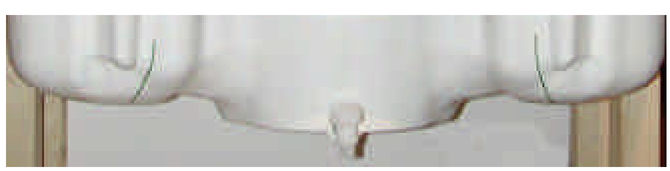


Figure 7.2 SAM Twin Phantom shell

8. DEFINITION OF REFERENCE POINTS

EAR Reference Point

Figure 8.1 shows the front, back and side views of the SAM Twin Phantom. The point "M" is the reference point for the center of the mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15mm posterior to the entrance to the ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 9.2. The plane passing through the two ear canals and M is defined as the Reference Plane. The line N-F (Neck-Front) is perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 8.2). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines are marked on the external phantom shell to facilitate handset positioning [5].

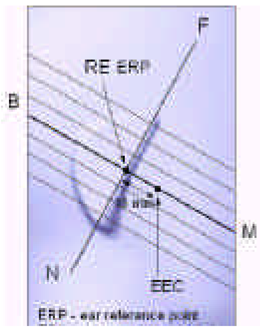


Figure 8.2 Close-up side view of ERPs

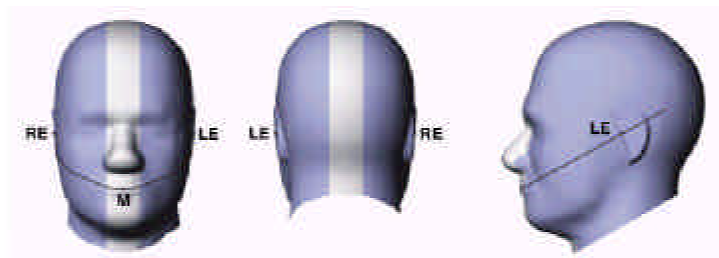


Figure 8.1 Front, back and side view of SAM Twin Phantom

Handset Reference Points

Two imaginary lines on the handset were established: the vertical centerline and the horizontal line. The test device was placed in a normal operating position with the "test device reference point" located along the "vertical centerline" on the front of the device aligned to the "ear reference point" (See Fig. 8.3). The "test device reference point" was than located at the same level as the center of the ear reference point. The test device was positioned so that the "vertical centerline" was bisecting the front surface of the handset at it's top and bottom edges, positioning the "ear reference point" on the outer surface of the both the left and right head phantoms on the ear reference point.

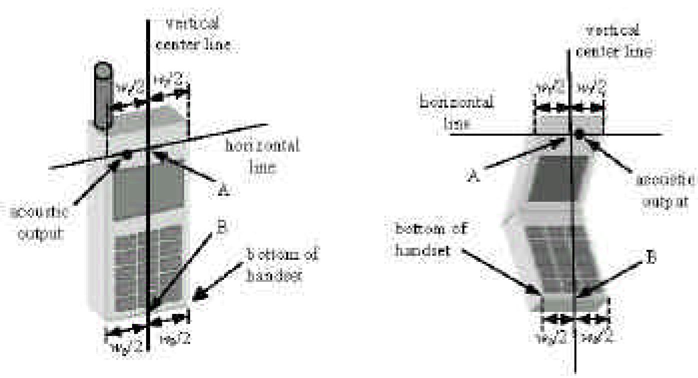


Figure 8.3 Handset Vertical Center & Horizontal Line Reference Points

9. TEST CONFIGURATION POSITIONS

Positioning for Cheek/Touch

1. The test device was positioned with the handset close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 9.1), such that the plane defined by the vertical center line and the horizontal line of the phone is approximately parallel to the sagittal plane of the phantom.

Figure 9.1 Front, Side and Top View of Cheek/Touch Position

2. The handset was translated towards the phantom along the line passing through RE & LE until the handset touches the ear.
3. While maintaining the handset in this plane, the handset was rotated around the LE-RE line until the vertical centerline was in the plane normal to MB-NF including the line MB (reference plane).
4. The phone was hen rotated around the vertical centerline until the phone (horizontal line) was symmetrical was respect to the line NF.
5. While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE, and maintaining the phone contact with the ear, the handset was rotated about the line NF until any point on the handset made contact with a phantom point below the ear (cheek). See Figure 9.2)

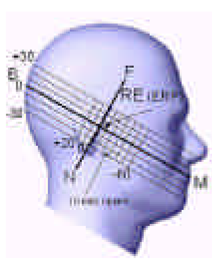


Figure 9.2 Side view w/ relevant markings

9. TEST CONFIGURATION POSITIONS (Continued)

Positioning for Ear / 15° Tilt

With the test device aligned in the "Cheek/Touch Position":

1. While maintaining the orientation of the phone, the phone was retracted parallel to the reference plane far enough to enable a rotation of the phone by 15degree.
2. The phone was then rotated around the horizontal line by 15 degree.
3. While maintaining the orientation of the phone, the phone was moved parallel to the reference plane until any part of the phone touches the head. (In this position, point A was located on the line RE-LE). The tilted position is obtained when the contact is on the pinna. If the contact was at any location other than the pinna, the angle of the phone would then be reduced. The tilted position was obtained when any part of the phone was in contact of the ear as well as a second part of the phone was in contact with the head (see Figure 9.3).

Figure 9.3 Front, Side and Top View of Ear/15° Tilt Position

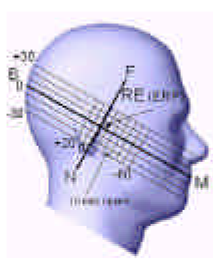


Figure 9.4 Side view w/ relevant markings

9. TEST CONFIGURATION POSITIONS (Continued)

Body Holster /Belt Clip Configurations

Body-worn operating configurations are tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in a normal use configuration (see Figure 9.5). A device with a headset output is tested with a headset connected to the device. Body dielectric parameters are used.

Accessories for Body-worn operation configurations are divided into two categories: those that do not contain metallic components and those that do contain metallic components. When multiple accessories that do not contain metallic components are supplied with the device, the device is tested with only the accessory that dictates the closest spacing to the body. Then multiple accessories that contain metallic components are supplied with the device, the device is tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (i.e. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that dictates the closest spacing to the body is tested.

Figure 9.5 Body Belt Clip & Holster Configurations

Body-worn accessories may not always be supplied or available as options for some devices intended to be authorized for body-worn use. In this case, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented.

Transmitters that are designed to operate in front of a person's face, as in push-to-talk configurations, are tested for SAR compliance with the front of the device positioned to face the flat phantom. For devices that are carried next to the body such as a shoulder, waist or chest-worn transmitters, SAR compliance is tested with the accessory(ies), including headsets and microphones, attached to the device and positioned against a flat phantom in a normal use configuration.

In all cases SAR measurements are performed to investigate the worst-case positioning. Worst-case positioning is then documented and used to perform Body SAR testing.

In order for users to be aware of the body-worn operating requirements for meeting RF exposure compliance, operating instructions and cautions statements are included in the user's manual.

10. ANSI/IEEE C95.1 - 1992 RF EXPOSURE LIMITS

Uncontrolled Environment

UNCONTROLLED ENVIRONMENTS are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

Controlled Environment

CONTROLLED ENVIRONMENTS are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

Table 10.1. Safety Limits for Partial Body Exposure [2]

	HUMAN EXPOSURE LIMITS	
	UNCONTROLLED ENVIRONMENT General Population (W/kg) or (mW/g)	CONTROLLED ENVIRONMENT General Population (W/kg) or (mW/g)
SPATIAL PEAK SAR [1] Brain	1.60	8.00
SPATIAL AVERAGE SAR [2] Whole Body	0.08	0.40
SPATIAL PEAK SAR [3] Hands, Feet, Ankles, Wrists	4.00	20.00

1 The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.
2 The Spatial Average value of the SAR averaged over the whole body.
3 The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

11. MEASUREMENT UNCERTAINTIES

a	b	c	d	e= f(d,k)	f	g	h = cxf/e	i = cxg/e	k
Uncertainty Component	**Sec.**	**Tol. (± %)**	**Prob. Dist.**	**Div.**	**c_i (1 - g)**	**c_i (10 - g)**	**1 - g u_i (± %)**	**10 - g u_i (± %)**	**v_i**
Measurement System									
Probe Calibration	E1.1	4.8	N	1	1	1	4.8	4.8	∞
Axial Isotropy	E1.2	4.7	R	√3	0.7	0.7	1.9	1.9	∞
Hemishperical Isotropy	E1.2	9.6	R	√3	0.7	0.7	3.9	3.9	∞
Boundary Effect	E1.3	1.0	R	√3	1	1	0.6	0.6	∞
Linearity	E1.4	4.7	R	√3	1	1	2.7	2.7	∞
System Detection Limits	E1.5	1.0	R	√3	1	1	0.6	0.6	∞
Readout Electronics	E1.6	1.0	N	1	1	1	1.0	1.0	∞
Response Time	E1.7	0.8	R	√3	1	1	0.5	0.5	∞
Integration Time	E1.8	2.6	R	√3	1	1	1.5	1.5	∞
RF Ambient Conditions	E5.1	3.0	R	√3	1	1	1.7	1.7	∞
Probe Positioner Mechanical Tolerance	E5.2	0.4	R	√3	1	1	0.2	0.2	∞
Probe Positioning w/ respect to Phantom	E5.3	2.9	R	√3	1	1	1.7	1.7	∞
Extrapolation, Interpolation & Integration Algorithms for Max. SAR Evaluation	E4.2	1.0	R	√3	1	1	0.6	0.6	∞
Test Sample Related									
Test Sample Positioning	E3.2.1	2.9	N	1	1	1	2.9	2.9	145
Device Holder Uncertainty	E3.1.1	3.6	N	1	1	1	3.6	3.6	5
Output Power Variation - SAR drift measurement	5.6.2	5.0	R	√3	1	1	2.9	2.9	∞
Phantom & Tissue Parameters									
Phantom Uncertainty (Shape & Thickness tolerances)	E2.1	4.0	R	√3	1	1	2.3	2.3	∞
Liquid Conductivity - deviation from target values	E2.2	5.0	R	√3	0.64	0.43	1.8	1.2	∞
Liquid Conductivity - measurement uncertainty	E2.2	2.5	N	1	0.64	0.43	1.6	1.1	∞
Liquid Permittivity - deviation from target values	E2.2	5.0	R	√3	0.6	0.5	1.7	1.4	∞
Liquid Permittivity - measurement uncertainty	E2.2	2.5	N	1	0.6	0.5	1.5	1.2	∞
Combined Standard Uncertainty (k=1)			RSS				10.3	10.0	
Expanded Uncertainty (k=2) (95% CONFIDENCE LEVEL)							20.6	20.1	

The above measurement uncertainties are according to IEEE Std. 1528-2003.

12. SYSTEM VERIFICATION

Tissue Verification

Table A.1 Simulated Tissue Verification

	2450 MHz Brain		2450 MHz Muscle	
	Target	Measured	Target	Measured
Dielectric Constant	39.20	38.21	52.70	53.64
Conductivity	1.800	1.810	1.950	1.930

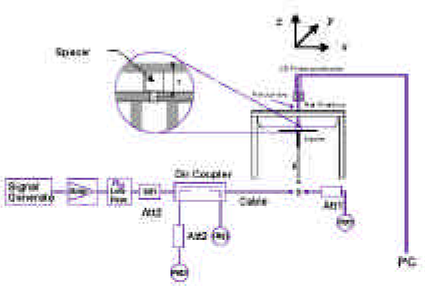
Test System Validation

Prior to assessment, the system is verified to the ±10% of the specifications at 2450 MHz by using the system validation kits. (Graphic Plots Attached)

Table A.2 System Validation

System Verification TARGET & MEASURED							
Date:	Amb. Temp (°C)	Liquid Temp(°C)	Input Power (W)	Tissue Frequency (Mhz)	Targeted SAR_{1g} (mW)	Measured SAR_{1g} (mW)	Deviation (%)
2/25/2005	23.2	21.5	0.100	2450	5.240	5.100	-2.67%

Figure 12.1 Dipole Validation Test Setup



13. SAR TEST DATA SUMMARY

See Measurement Result Data Pages

Procedures Used To Establish Test Signal

The handset was placed into simulated call mode (TDD modes) using manufacturers test codes. Such test signals offer a consistent means for testing SAR and are recommended for evaluating SAR [4]. When test modes are not available or inappropriate for testing a handset, the actual transmission is activated through a base station simulator or similar equipment. See data pages for actual procedure used in measurement.

Device Test Conditions

The handset is battery operated. Each SAR measurement was taken with a fully charged battery. In order to verify that the device was tested at full power, conducted output power measurements were performed before and after each SAR measurement to confirm the output power. If a conducted power deviation of more than 5% occurred, the test was repeated.

SAR DATA SUMMARY (Continued)

Mixture Type: 2450MHz Muscle

14.1 MEASUREMENT RESULTS (Body SAR)

FREQUENCY		Modulation	Begin / End POWER‡			Separation Distance (cm)‡‡	Antenna Position	SAR (W/kg)
MHz	Ch.		(dBm)		Battery			
2407.424	01	TDD	13.19	13.06	Standard	0.0 cm	Fixed	**0.043**
2440.192	17	TDD	13.39	13.18	Standard	0.0 cm	Fixed	0.022
2477.056	35	TDD	13.68	13.71	Standard	0.0 cm	Fixed	0.028
ANSI / IEEE C95.1 1992 - SAFETY LIMIT Spatial Peak Uncontrolled Exposure/General Population						**Muscle 1.6 W/kg (mW/g)** averaged over 1 gram		

NOTES:

1. The test data reported are the worst-case SAR value with the antenna-head position set in a typical configuration. Test procedures used are according to FCC/OET Bulletin 65, Supp.C [July 2001].
2. All modes of operation were investigated, and worst-case results are reported.
3. Battery is fully charged for all readings. Standard batteries are the only option.

	‡Power Measured	☒ Conducted	☐ ERP	☐ EIRP
4.	SAR Measurement System	☒ DASY4	☐ IDX	
	Phantom Configuration	☐ Left Head	☒ Flat Phantom	☐ Right Head
5.	SAR Configuration	☐ Head	☒ Body	☐ Hand
6.	Test Signal Call Mode	☒ Manu. Test Codes	☐ Base Station Simulator	
7.	‡‡Test Configuration	☐ With Holster	☒ Without Holster	

8. Tissue parameters and temperatures are listed on the SAR plots.
9. Both sides of the phone were tested and the worst-case side is reported.
10. Liquid tissue depth is 15.1 cm. ± 0.1

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Vice President Engineering

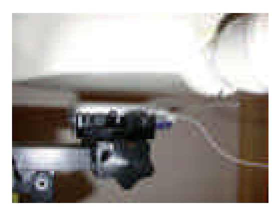

Figure 14.1 Body SAR Test Setup

SAR DATA SUMMARY (Continued)

Mixture Type: 2450MHz Muscle

14.2 MEASUREMENT RESULTS (Face SAR)

FREQUENCY		Modulation	Begin / End POWER‡			Separation Distance (cm)‡‡	Antenna Position	SAR (W/kg)
MHz	Ch.		(dBm)		Battery			
2407.424	01	TDD	13.19	13.38	Standard	0.0 cm	Fixed	**0.113**
2440.192	17	TDD	13.39	13.69	Standard	0.0 cm	Fixed	0.096
2477.056	35	TDD	13.68	13.42	Standard	0.0 cm	Fixed	0.062
ANSI / IEEE C95.1 1992 - SAFETY LIMIT Spatial Peak Uncontrolled Exposure/General Population						Muscle 1.6 W/kg (mW/g) averaged over 1 gram		

NOTES:

1. The test data reported are the worst-case SAR value with the antenna-head position set in a typical configuration. Test procedures used are according to FCC/OET Bulletin 65, Supp.C [July 2001].
2. All modes of operation were investigated, and worst-case results are reported.
3. Battery is fully charged for all readings. Standard and extended batteries are options.

	‡Power Measured	☒ Conducted	☐ ERP	❘ EIRP
4.	SAR Measurement System	☒ DASY4	☐ IDX	
	Phantom Configuration	☐ Left Head	☒ Flat Phantom	❘ Right Head
5.	SAR Configuration	☐ Head	☒ Body	❘ Hand
6.	Test Signal Call Mode	☒ Manu. Test Codes	☐ Base Station Simulator	
7.	‡‡Test Configuration	☐ With Holster	☒ Without Holster	

8. Tissue parameters and temperatures are listed on the SAR plots.
9. Both sides of the phone were tested and the worst-case side is reported.
10. Liquid tissue depth is 15.1 cm. ± 0.1

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Vice President Engineering

Figure 14.2 Face SAR Test Setup

15. SAR TEST EQUIPMENT

Equipment Calibration

Table 15.1 Test Equipment Calibration

EQUIPMENT SPECIFICATIONS			
Type		**Calibration Date**	**Serial Number**
Stäubli Robot RX60L		October 2004	599131-01
Stäubli Robot Controller		October 2004	PCT592
Stäubli Teach Pendant (Joystick)		October 2004	3323-00161
Micron Computer, 450 MHz Pentium III, Windows NT		October 2004	PCT577
SPEAG EDC3		October 2004	321
SPEAG DAE4		October 2004	637
SPEAG E-Field Probe EX3DV4		October 2004	3550
SPEAG Dummy Probe		October 2004	PCT583
SPEAG SAM Twin Phantom V4.0		October 2004	PCT666
SPEAG Light Alignment Sensor		October 2004	205
PCTEST Validation Dipole D300V2		September 2004	PCT301
SPEAG Validation Dipole D835V2		January 2005	PCT512
SPEAG Validation Dipole D1900V2		January 2005	PCT613
Brain Equivalent Matter (300MHz)		January/February 2005	PCTBEM601
Brain Equivalent Matter (835MHz)		January/February 2005	PCTBEM101
Brain Equivalent Matter (1900MHz)		January/February 2005	PCTBEM301
Muscle Equivalent Matter (300MHz)		January/February 2005	PCTMEM701
Muscle Equivalent Matter (835MHz)		January/February 2005	PCTMEM201
Muscle Equivalent Matter (1900MHz)		January/February 2005	PCTMEM401
Microwave Amp. Model: 5S1G4, (800MHz - 4.2GHz)		January 2005	22332
Gigatronics 8651A Power Meter		January 2005	1835299
HP-8648D (9kHz ~ 4GHz) Signal Generator		January 2005	PCT530
Amplifier Research 5S1G4 Power Amp		January 2005	PCT540
HP-8753E (30kHz ~ 3GHz) Network Analyzer		January 2005	PCT552
HP85070B Dielectric Probe Kit		January 2005	PCT501
Ambient Noise/Reflection, etc.	<12mW/kg/<3%of SAR	January 2005	Anechoic Room PCT01

NOTE:

The E-field probe was calibrated by SPEAG, by waveguide technique procedure. Dipole Validation measurement is performed by PCTEST Lab. before each test. The brain simulating material is calibrated by PCTEST using the dielectric probe system and network analyzer to determine the conductivity and permittivity (dielectric constant) of the brain-equivalent material.

16. CONCLUSION

Measurement Conclusion

The SAR measurement indicates that the EUT complies with the RF radiation exposure limits of the FCC. These measurements are taken to simulate the RF effects exposure under worst-case conditions. Precise laboratory measures were taken to assure repeatability of the tests. The tested device complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease). Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables.[3]

17. REFERENCES

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APPENDIX A: SAR TEST DATA

PCTEST ENGINEERING LABORATORY, INC.

DUT: WHAM; Type: Uniden 2.4GHz Wireless Microphone; Serial: Prototype

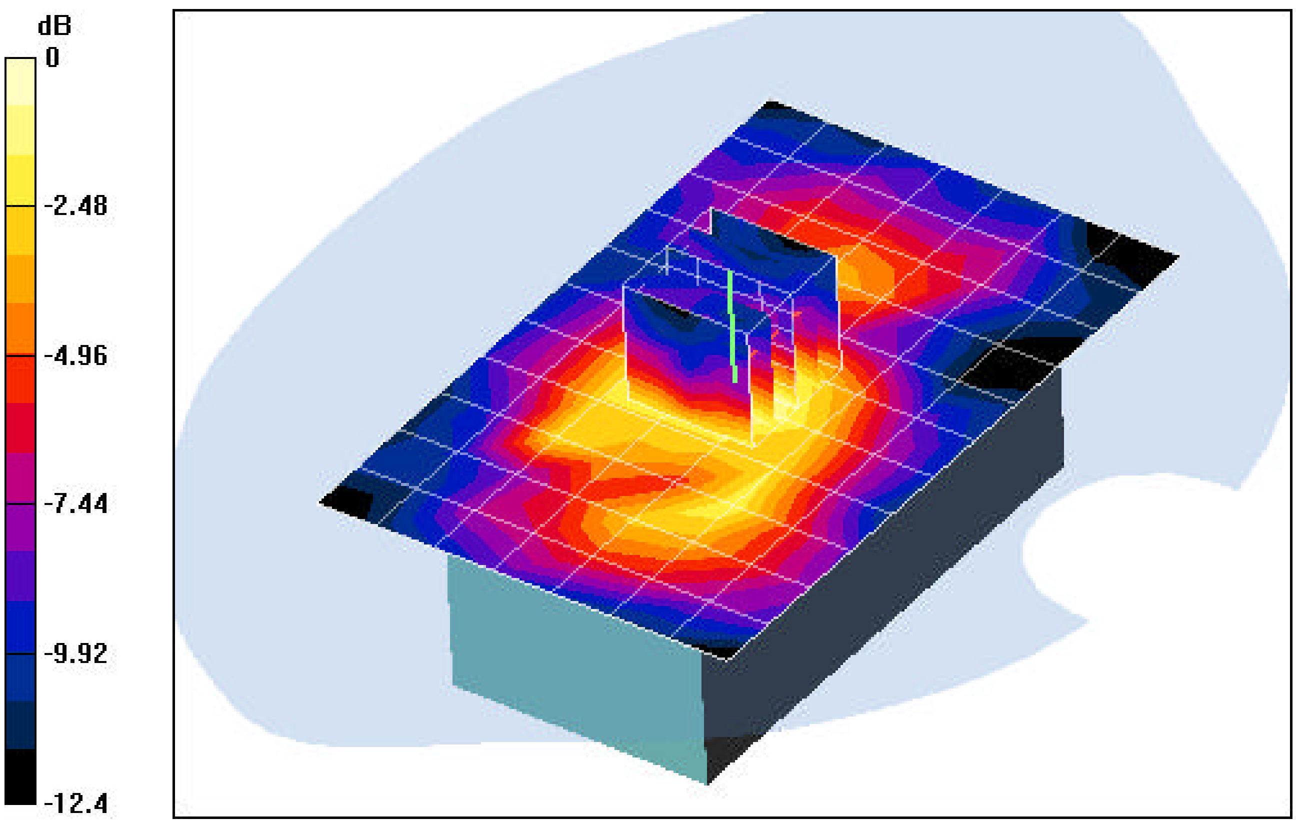
Communication System: 2.4GHz TDD; Frequency: 2407.42 MHz;Duty Cycle: 1:1
Medium: 2450 Muscle (σ = 1.93 mho/m, ε_r = 53.64, ρ = 1000 kg/m^3)
Phantom section: Flat Section; Space: 0.0 cm

Test Date: 02-25-2005; Ambient Temp: 23.4°C; Tissue Temp: 21.2°C

Probe: EX3DV4 - SN3550; ConvF(6.27, 6.27, 6.27); Calibrated: 10/26/2004
Sensor-Surface: 3mm (Mechanical Surface Detection)
Electronics: DAE4 Sn637; Calibrated: 9/22/2004
Phantom: SAM 12b; Type: SAM 4.0; Serial: TP:1197
Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

Body SAR, Ch.01

Area Scan (8x12x1): Measurement grid: dx=15mm, dy=15mm
Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 4.87 V/m
Peak SAR (extrapolated) = 0.076 W/kg
SAR(1 g) = 0.043 mW/g; SAR(10 g) = 0.025 mW/g



0 dB = 0.052mW/g

PCTEST ENGINEERING LABORATORY, INC.

DUT: WHAM; Type: Uniden 2.4GHz Wireless Microphone; Serial: Prototype

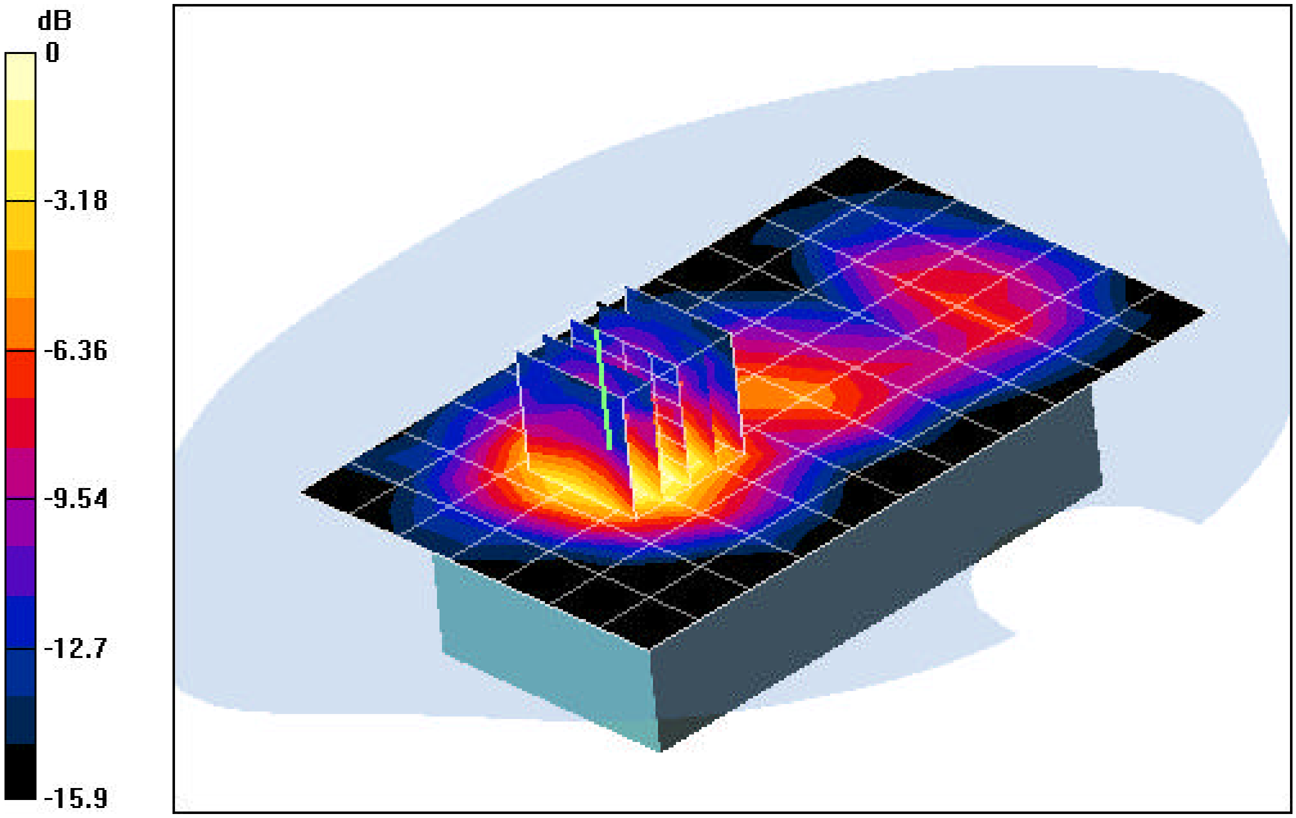
Communication System: 2.4GHz TDD; Frequency: 2407.42 MHz;Duty Cycle: 1:1
Medium: 2450 Brain (σ = 1.81 mho/m, ε_r = 38.21, ρ = 1000 kg/m^3)
Phantom section: Flat Section; Space: 0.0 cm

Test Date: 02-25-2005; Ambient Temp: 23.2°C; Tissue Temp: 21.5°C

Probe: EX3DV4 - SN3550; ConvF(6.33, 6.33, 6.33); Calibrated: 10/26/2004
Sensor-Surface: 3mm (Mechanical Surface Detection)
Electronics: DAE4 Sn637; Calibrated: 9/22/2004
Phantom: SAM 12b; Type: SAM 4.0; Serial: TP:1197
Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

Face SAR, Ch.01

Area Scan (8x12x1): Measurement grid: dx=15mm, dy=15mm
Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 3.75 V/m
Peak SAR (extrapolated) = 0.196 W/kg
SAR(1 g) = 0.113 mW/g; SAR(10 g) = 0.065 mW/g



0 dB = 0.135mW/g

PCTEST ENGINEERING LABORATORY, INC.

DUT: WHAM; Type: Uniden 2.4GHz Wireless Microphone; Serial: Prototype

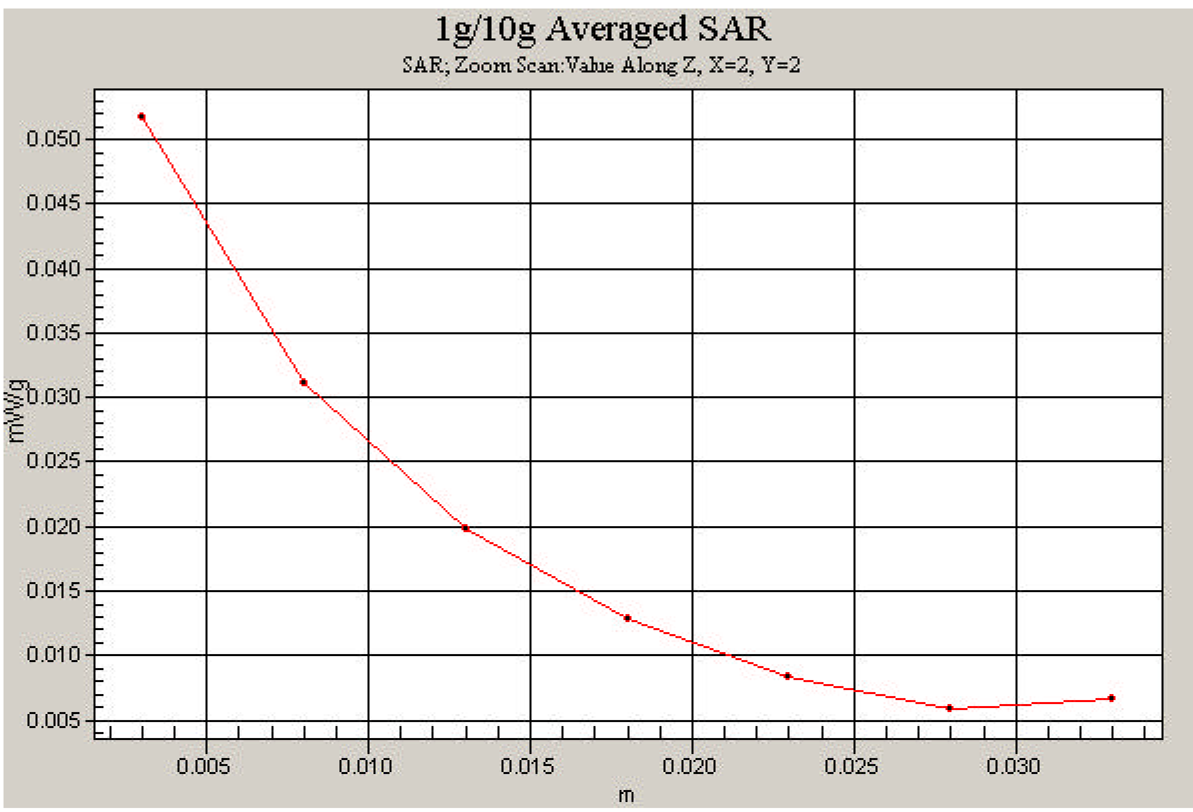
Communication System: 2.4GHz TDD; Frequency: 2407.42 MHz;Duty Cycle: 1:1
Medium: 2450 Muscle (σ = 1.93 mho/m, ε_r = 53.64, ρ = 1000 kg/m^3)
Phantom section: Flat Section; Space: 0.0 cm

Test Date: 02-25-2005; Ambient Temp: 23.4°C; Tissue Temp: 21.2°C

Probe: EX3DV4 - SN3550; ConvF(6.27, 6.27, 6.27); Calibrated: 10/26/2004
Sensor-Surface: 3mm (Mechanical Surface Detection)
Electronics: DAE4 Sn637; Calibrated: 9/22/2004
Phantom: SAM 12b; Type: SAM 4.0; Serial: TP:1197
Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

Body SAR, Ch.01

Area Scan (8x12x1): Measurement grid: dx=15mm, dy=15mm
Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 4.87 V/m
Peak SAR (extrapolated) = 0.076 W/kg
SAR(1 g) = 0.043 mW/g; SAR(10 g) = 0.025 mW/g



PCTEST ENGINEERING LABORATORY, INC.

DUT: WHAM; Type: Uniden 2.4GHz Wireless Microphone; Serial: Prototype

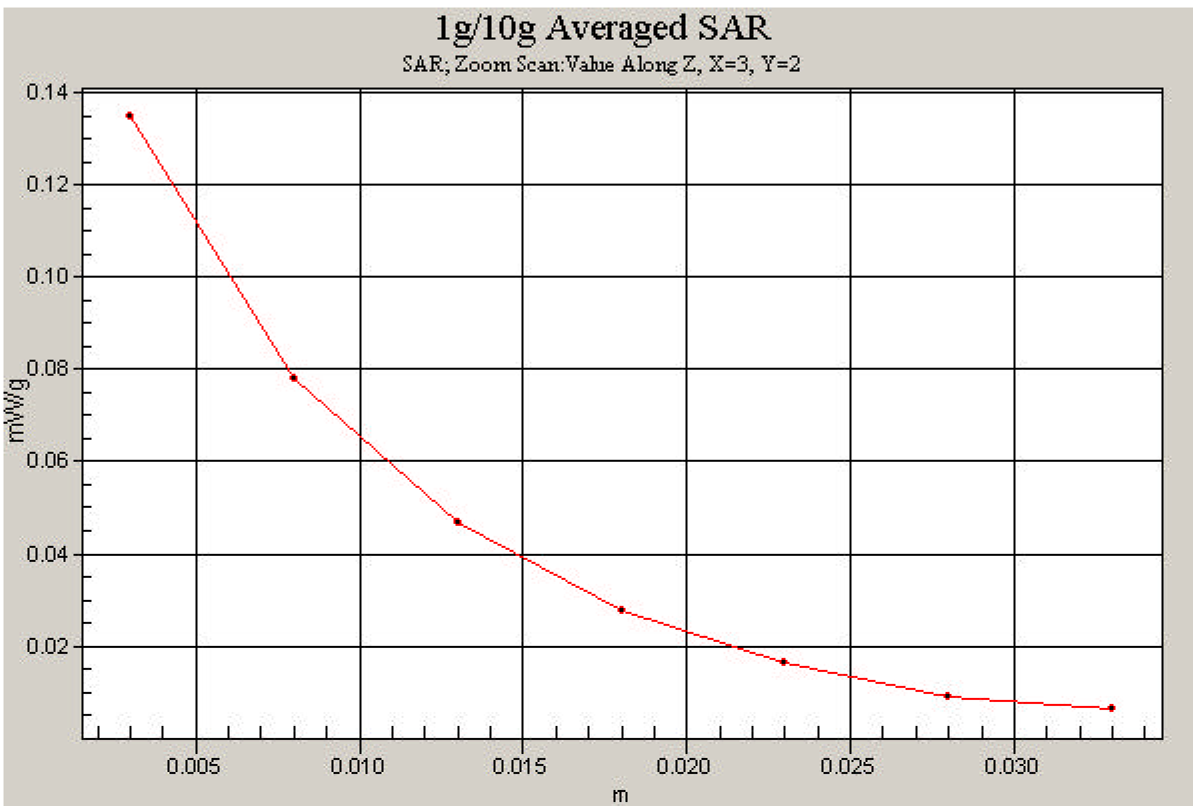
Communication System: 2.4GHz TDD; Frequency: 2407.42 MHz;Duty Cycle: 1:1
Medium: 2450 Brain (σ = 1.81 mho/m, ε_r = 38.21, ρ = 1000 kg/m^3)
Phantom section: Flat Section; Space: 0.0 cm

Test Date: 02-25-2005; Ambient Temp: 23.2°C; Tissue Temp: 21.5°C

Probe: EX3DV4 - SN3550; ConvF(6.33, 6.33, 6.33); Calibrated: 10/26/2004
Sensor-Surface: 3mm (Mechanical Surface Detection)
Electronics: DAE4 Sn637; Calibrated: 9/22/2004
Phantom: SAM 12b; Type: SAM 4.0; Serial: TP:1197
Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

Face SAR, Ch.01

Area Scan (8x12x1): Measurement grid: dx=15mm, dy=15mm
Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 3.75 V/m
Peak SAR (extrapolated) = 0.196 W/kg
SAR(1 g) = 0.113 mW/g; SAR(10 g) = 0.065 mW/g



APPENDIX B: DIPOLE VALIDATION

PCTEST ENGINEERING LABORATORY, INC.

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:719

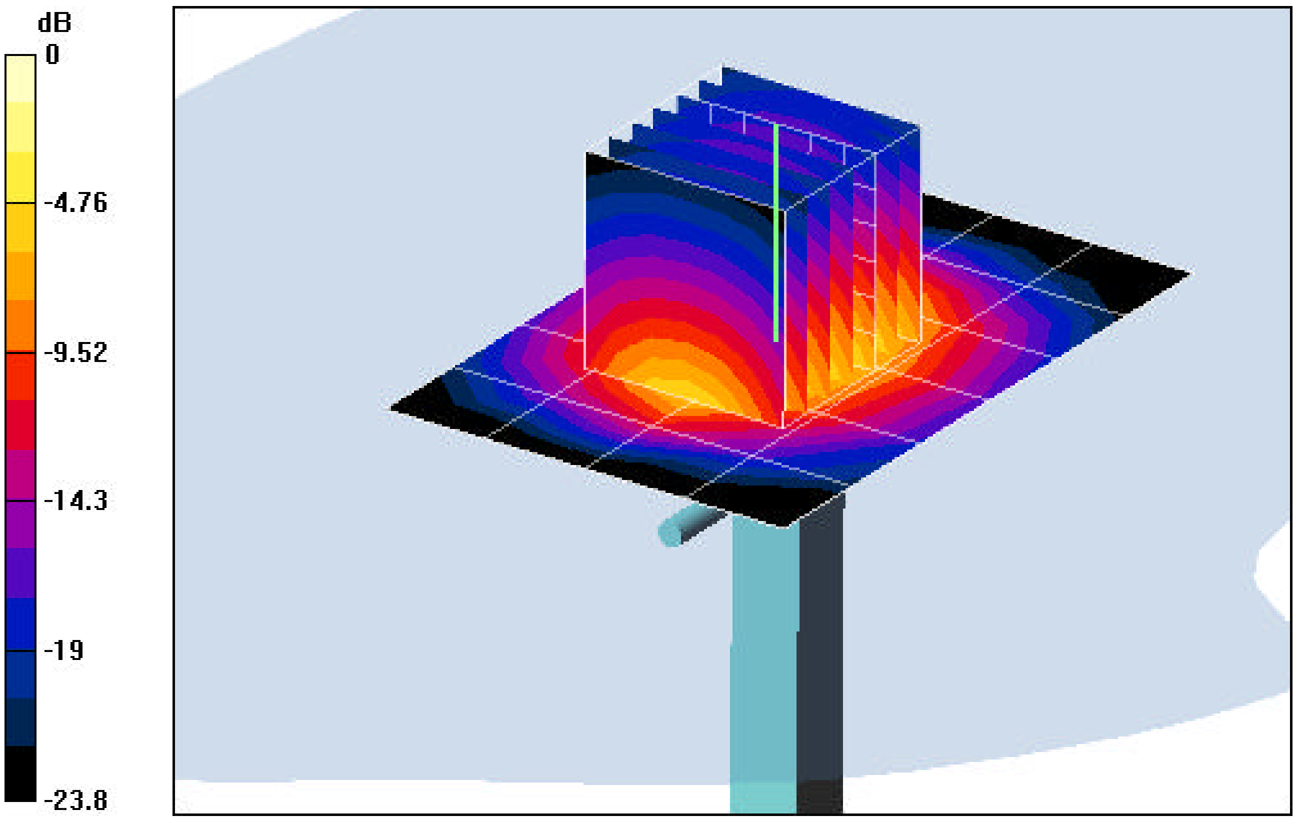
Communication System: CW; Frequency: 2450 MHz;Duty Cycle: 1:1
Medium: 2450 Brain (σ = 1.81 mho/m, ε_r = 38.21, ρ = 1000 kg/m^3)
Phantom section: Flat Section; Space: 1.0 cm

Test Date: 02-25-2005; Ambient Temp: 23.2°C; Tissue Temp: 21.5°C

Probe: EX3DV4 - SN3550; ConvF(6.33, 6.33, 6.33); Calibrated: 10/26/2004
Sensor-Surface: 3mm (Mechanical Surface Detection)
Electronics: DAE4 Sn637; Calibrated: 9/22/2004
Phantom: SAM 12b; Type: SAM 4.0; Serial: TP:1197
Measurement SW: DASY4, V4.4 Build 3; Postprocessing SW: SEMCAD, V1.8 Build 130

2450MHz Dipole Validation

Area Scan (5x7x1): Measurement grid: dx=15mm, dy=15mm
Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Input Power = 20.0 dBm (100 mW)
SAR(1 g) = 5.1 mW/g; SAR(10 g) = 2.29 mW/g
Target SAR(1g) = 5.24 mW/g; Deviation = -2.67 %



0 dB = 6.87mW/g

APPENDIX C: PROBE CALIBRATION

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

S **Schweizerischer Kalibrierdienst**
C **Service suisse d'étalonnage**
S **Servizio svizzero di taratura**
Swiss Calibration Service

Accredited by the Swiss Federal Office of Metrology and Accreditation
The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client PC Test

Certificate No: EX3-3550_Oct04

CALIBRATION CERTIFICATE

Object	EX3DV4 - SN:3550
Calibration procedure(s)	QA CAL-01.v5 and QA CAL-12.v4 Calibration procedure for dosimetric E-field probes
Calibration date:	October 26, 2004
Condition of the calibrated item	In Tolerance

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	5-May-04 (METAS, No. 251-00388)	May-05
Power sensor E4412A	MY41495277	5-May-04 (METAS, No. 251-00388)	May-05
Reference 3 dB Attenuator	SN: S5054 (3c)	3-Apr-03 (METAS, No. 251-00403)	Aug-05
Reference 20 dB Attenuator	SN: S5086 (20b)	3-May-04 (METAS, No. 251-00389)	May-05
Reference 30 dB Attenuator	SN: S5129 (30b)	3-Apr-03 (METAS, No. 251-00404)	Aug-05
Reference Probe ES3DV2	SN:3013	8-Jan-04 (SPEAG, No. ES3-3013_Jan04)	Jan-05
DAE4	SN: 617	26-May-04 (SPEAG, No. DAE4-617_May04)	May-05

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092180	18-Sep-02 (SPEAG, in house check Oct-03)	In house check: Oct 05
RF generator HP 8648C	US3642U01700	4-Aug-99 (SPEAG, in house check Dec-03)	In house check: Dec-05
Network Analyzer HP 8753E	US37390585	18-Oct-01 (SPEAG, in house check Nov-03)	In house check: Nov 04

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	
Approved by:	Niels Kuster	Quality Manager	

Issued: October 30, 2004

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S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Federal Office of Metrology and Accreditation
The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., ϑ = 0 is normal to probe axis

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization ϑ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E^2-field uncertainty inside TSL (see below *ConvF*).
- *NORM(f)x,y,z = NORMx,y,z * frequency_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of *ConvF*.
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- *ConvF and Boundary Effect Parameters:* Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z * ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY 4.3 B17 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- *Spherical isotropy (3D deviation from isotropy)*: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

Probe EX3DV4

SN:3550

Manufactured: May 19, 2004
Calibrated: October 26, 2004

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

DASY - Parameters of Probe: EX3DV4 SN:3550

Sensitivity in Free Space[A]

NormX	**0.47** ± 9.9%	$\mu V/(V/m)^2$
NormY	**0.49** ± 9.9%	$\mu V/(V/m)^2$
NormZ	**0.47** ± 9.9%	$\mu V/(V/m)^2$

Diode Compression[B]

DCP X	**92** mV
DCP Y	**92** mV
DCP Z	**92** mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

Boundary Effect

TSL 900 MHz Typical SAR gradient: 5 % per mm

Sensor Center to Phantom Surface Distance		**2.0 mm**	**3.0 mm**
SAR_{be} [%]	Without Correction Algorithm	3.8	1.1
SAR_{be} [%]	With Correction Algorithm	0.1	0.4

TSL 1750 MHz Typical SAR gradient: 10 % per mm

Sensor Center to Phantom Surface Distance		**2.0 mm**	**3.0 mm**
SAR_{be} [%]	Without Correction Algorithm	4.8	2.4
SAR_{be} [%]	With Correction Algorithm	0.8	0.9

Sensor Offset

Probe Tip to Sensor Center **1.0** mm

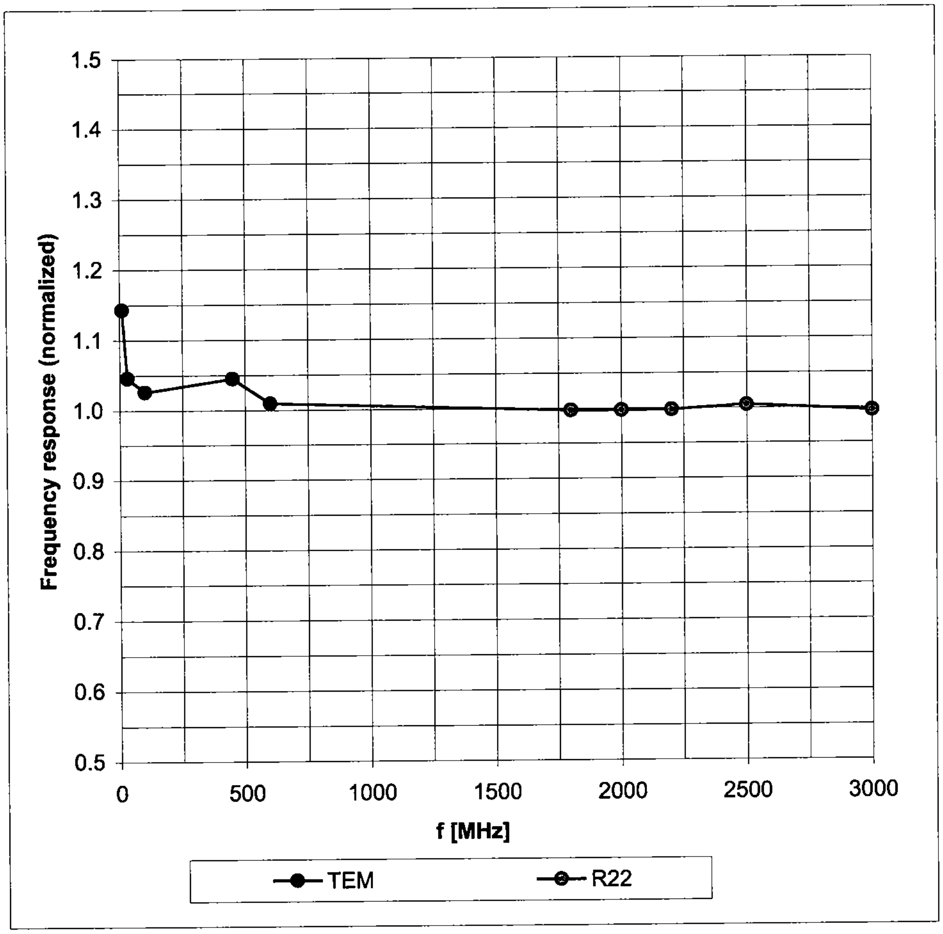
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

[A] The uncertainties of NormX,Y,Z do not affect the E^2-field uncertainty inside TSL (see Page 8).

[B] Numerical linearization parameter: uncertainty not required.

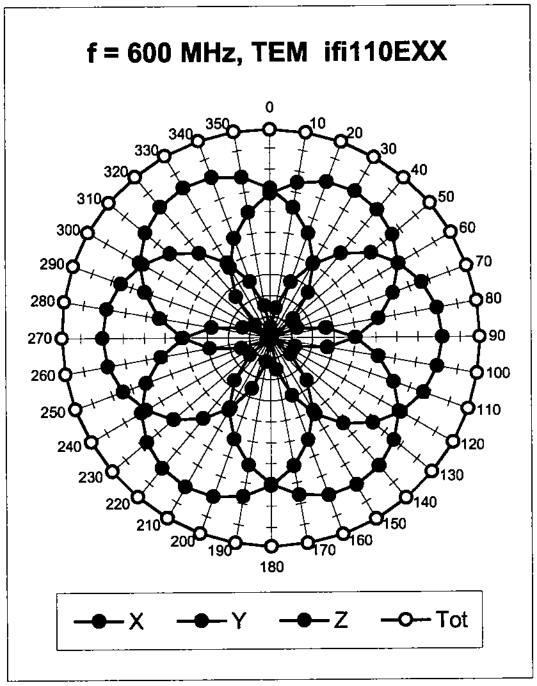
Frequency Response of E-Field

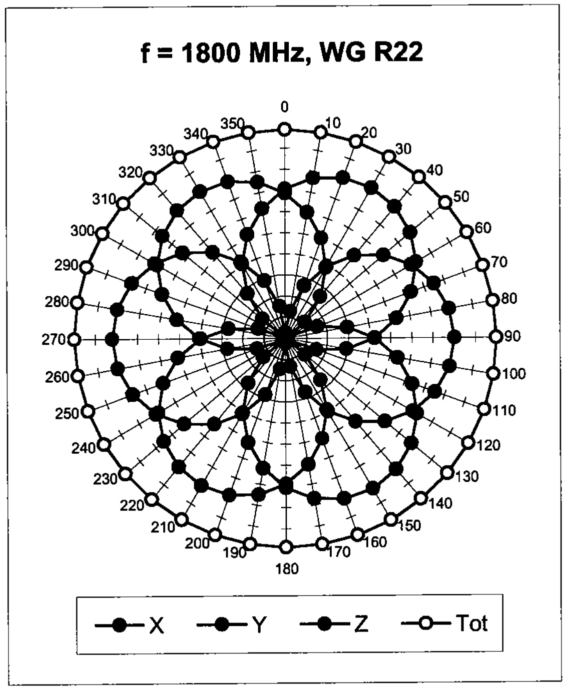
(TEM-Cell:ifi110 EXX, Waveguide: R22)

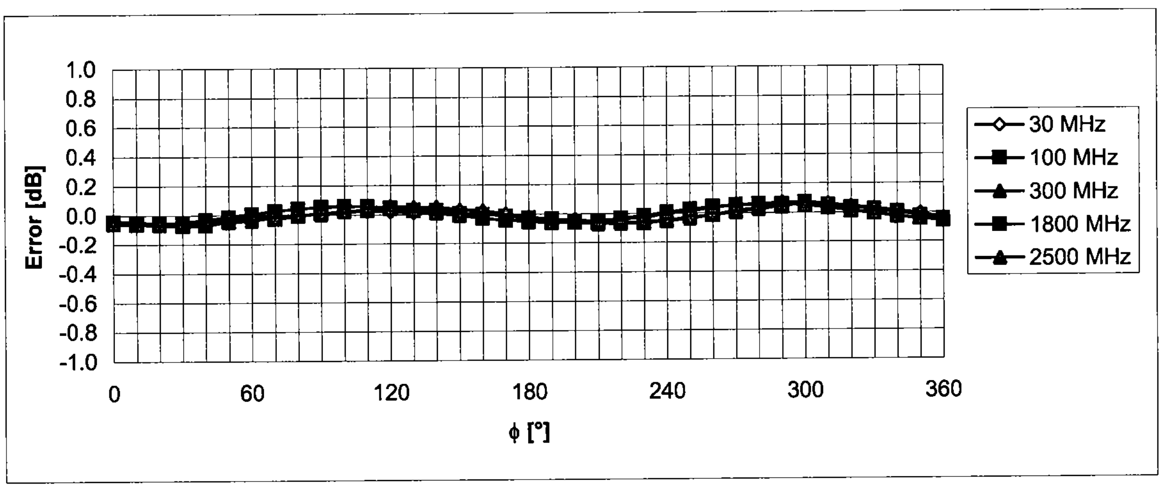


Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

Receiving Pattern (ϕ), ϑ = 0°



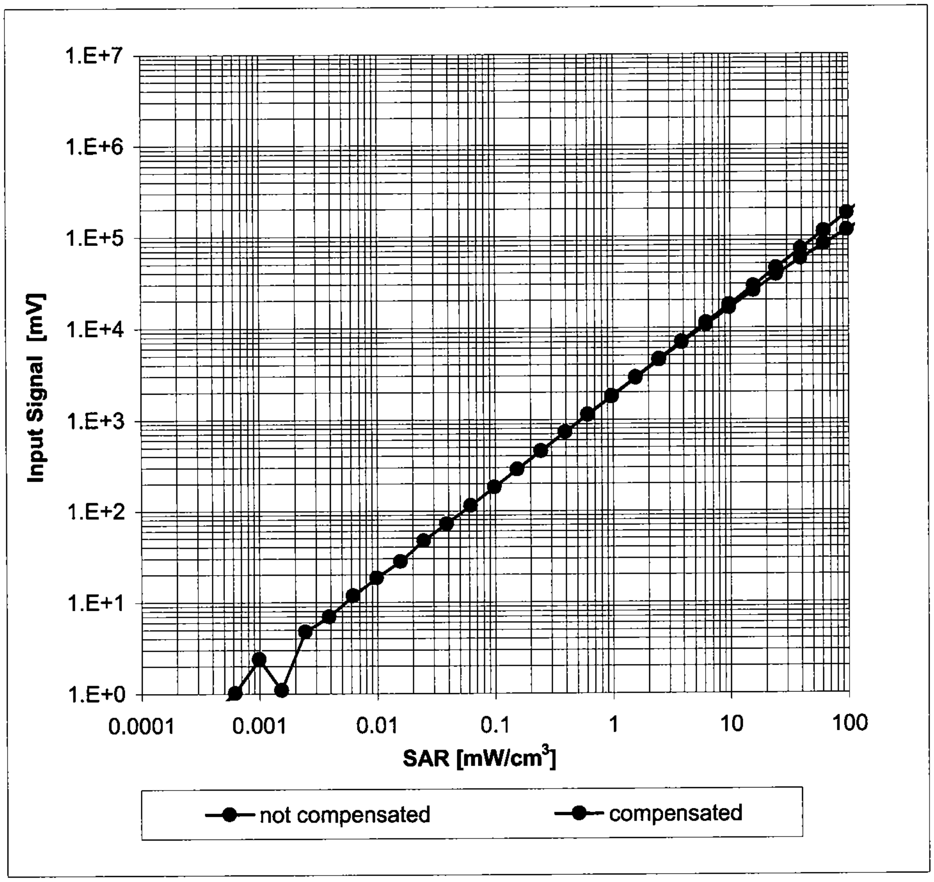


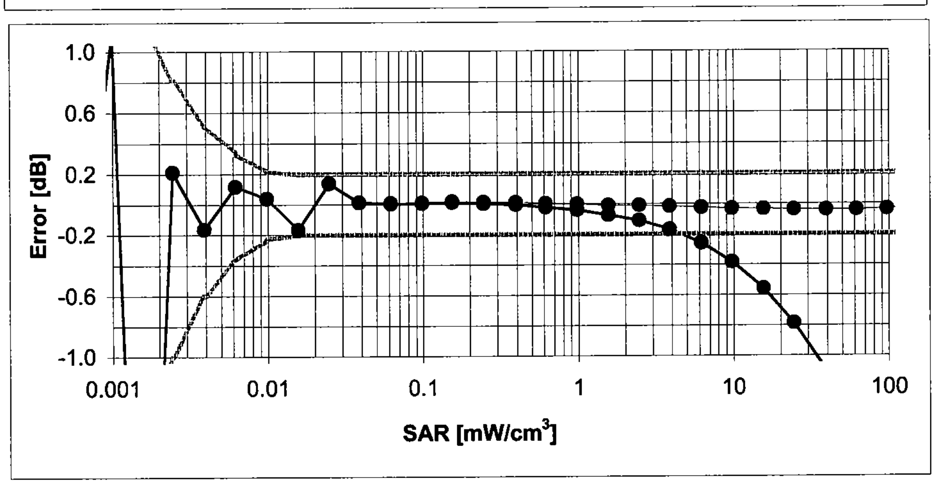


Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Dynamic Range f(SAR_{head})

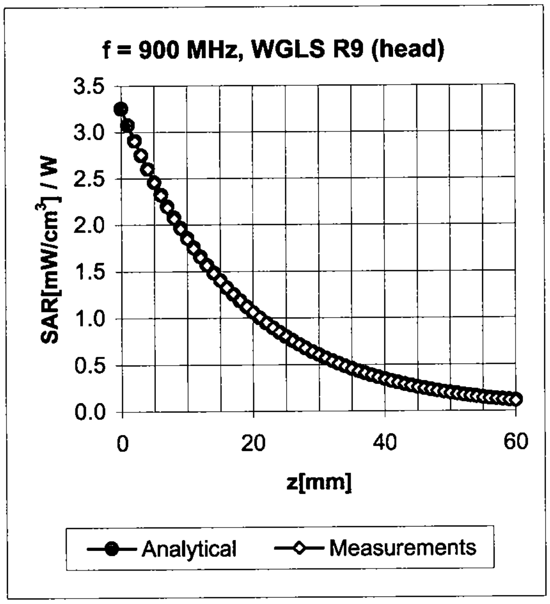
(Waveguide R22, f = 1800 MHz)

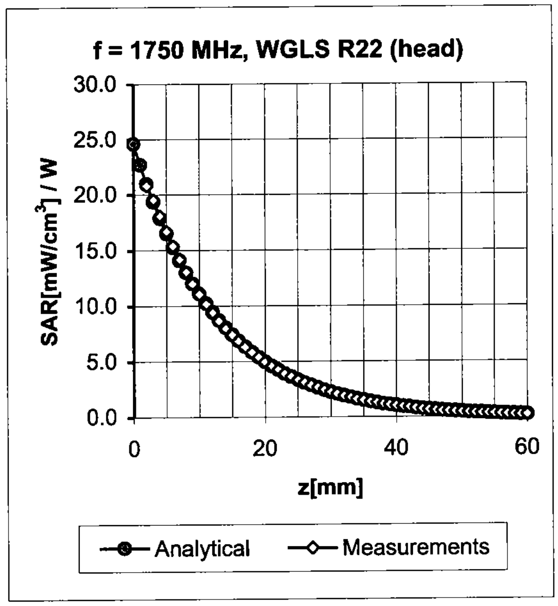




Uncertainty of Linearity Assessment: ± 0.6% (k=2)

Conversion Factor Assessment



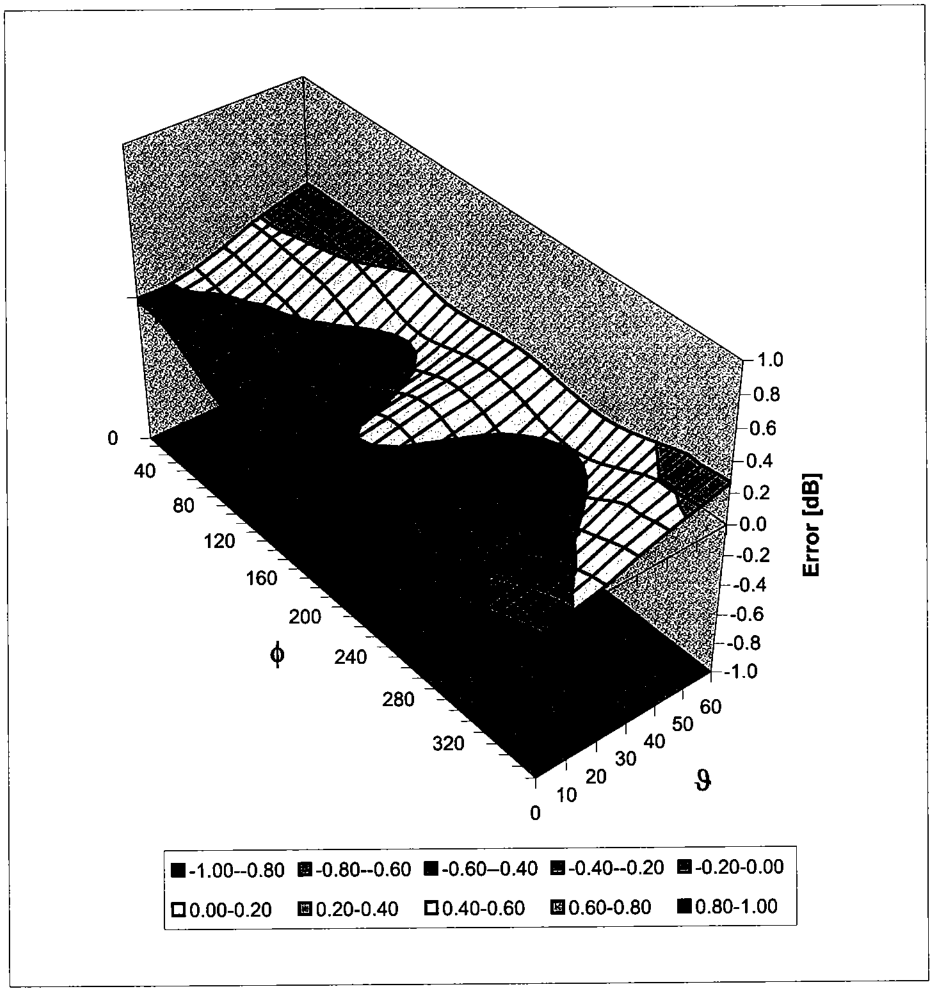


f [MHz]	Validity [MHz][C]	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF	Uncertainty
450	± 50 / ± 100	Head	43.5 ± 5%	0.87 ± 5%	-0.03	2.33	8.28	± 13.3% (k=2)
835	± 50 / ± 100	Head	41.5 ± 5%	0.90 ± 5%	0.92	0.65	8.12	± 11.0% (k=2)
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.97	0.62	7.76	± 11.0% (k=2)
1640	± 50 / ± 100	Head	40.3 ± 5%	1.29 ± 5%	0.69	0.73	7.28	± 11.0% (k=2)
1750	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.64	0.80	6.97	± 11.0% (k=2)
1900	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.54	0.96	6.75	± 11.0% (k=2)
1950	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.57	0.88	6.62	± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.61	0.78	6.33	± 11.8% (k=2)
450	± 50 / ± 100	Body	56.7 ± 5%	0.94 ± 5%	-0.08	2.62	8.05	± 13.3% (k=2)
835	± 50 / ± 100	Body	55.2 ± 5%	0.97 ± 5%	0.98	0.65	7.99	± 11.0% (k=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	1.01	0.63	7.75	± 11.0% (k=2)
1640	± 50 / ± 100	Body	53.8 ± 5%	1.40 ± 5%	0.58	0.99	6.82	± 11.0% (k=2)
1750	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.50	1.16	6.48	± 11.0% (k=2)
1900	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.47	1.32	6.35	± 11.0% (k=2)
1950	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.64	0.83	6.53	± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.83	0.64	6.27	± 11.8% (k=2)

[C] The validity of ± 100 MHz only applies for DASY 4.3 B17 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

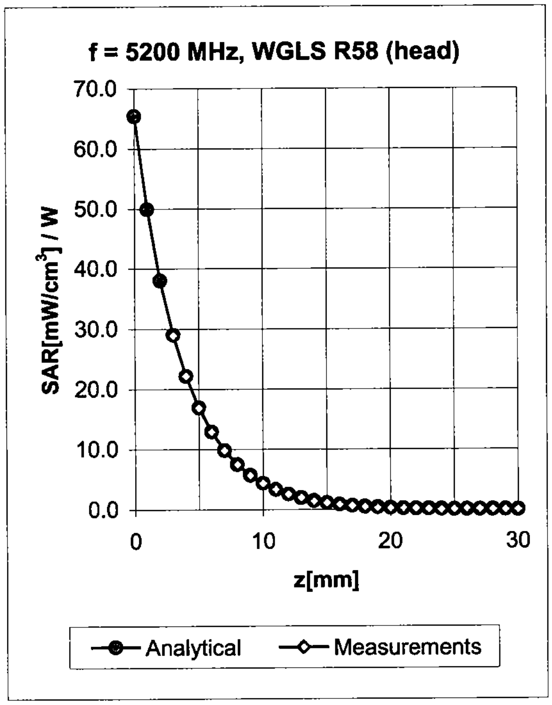
Deviation from Isotropy in HSL

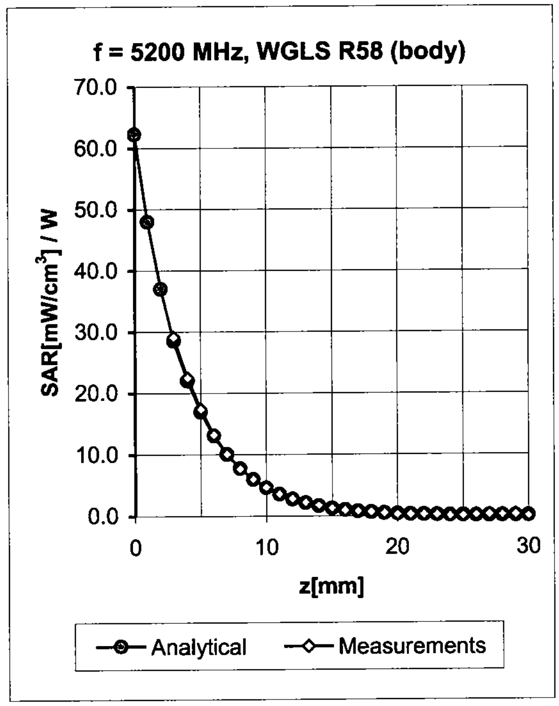
Error (ϕ, ϑ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Appendix[D]





f [MHz][D]	Validity [MHz]	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF	Uncertainty
5200	± 50	Head	36.0 ± 5%	4.76 ± 5%	0.45	1.80	4.17	± 13.6% (k=2)
5500	± 50	Head	35.6 ± 5%	4.96 ± 5%	0.47	1.80	3.77	± 13.6% (k=2)
5800	± 50	Head	35.3 ± 5%	5.27 ± 5%	0.48	1.80	3.74	± 13.6% (k=2)
5200	± 50	Body	49.0 ± 5%	5.30 ± 5%	0.50	1.90	3.72	± 13.6% (k=2)
5500	± 50	Body	48.6 ± 5%	5.65 ± 5%	0.50	1.95	3.47	± 13.6% (k=2)
5800	± 50	Body	48.2 ± 5%	6.00 ± 5%	0.50	1.95	3.48	± 13.6% (k=2)

[D] Accreditation for ConvF assessment above 3000 MHz is currently applied for. Accreditation is expected at the beginning of 2005.