S2E-17-0209_IM_WR2120_C



INSTALLATION MANUAL

MODEL: WEATHER RADAR TYPE: WR2120



www.furuno.com

SAFETY INSTRUCTIONS

The operator and installer must read the appropriate safety instructions before attempting to install or operate the equipment.

Indicates a hazardous situation which, if not avoided, will result in death or serious injury.	
Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.	
Indicates a potentially hazardous situation which, if not avoided, can result in minor or moderate injury.	

- Warning, Caution
- Prohibitive Action

Mandatory Action



Radio Frequency Radiation Hazard

The radar antenna emits the electromagnetic radio frequency (RF) energy which can be harmful, particularly to your eyes. Do not look at the Antenna Unit from a close distance while the radar is in operation, or expose yourself to the transmitting antenna at a close distance.

The distances at which RF radiation levels of 10 W/m² exist are shown in the table below.

DO NOT approach closer than 9.1m (Safety standard is 10 W/m²) when radar is transmitting.

NOTE: This value is applied when radar is installed in a public space. Value is defined as on human body surface over a 6-minute period with the flux density averaged from the measurement. Moreover, this measured value is measured by pointing the center of the antenna towards a human. However this is the worst value, definition required by actual regulation is written here as on safe side.

Distance from Antenna	9.1m
Power flux density	10 W/m ²

WARNING



Do not open the radome.

Electrical shock can occur. Only qualified personnel should work inside the equipment. Turn off the circuit breaker in the JCU if opening the radome is required.

Wear a hard hat and safety belt when mounting the Antenna Unit. Serious injury or death can result from falls or dropped items while installing or servicing the radar components.



Do not use any other power except 100 to 240 VAC. Connection of an incorrect power supply can cause fire or damage the equipment.

Turn off the power immediately if water leaks into the equipment or smoke or fire is coming from the equipment. Failure to turn off the equipment can cause fire or electrical shock.

Do not operate the equipment with wet hands. Electrical shock can occur.







Do not put liquid-filled containers on the top of the equipment. Fire or electrical shock can occur if a liquid spills into the equipment.



Establish best possible surrounding space for apparatus.

This helps eliminate performance degradation and failure.



Serious injury may occur due to broken glass.

WARNING LABEL

Warning labels are attached to the equipment. Do not remove any label. If a label is missing or damaged, contact us for the replacement.



Name: Radiation Warning Label Type: 03-142-3201-0 Code No.: 100-266-890-10

WR2120 restrictions

There are restrictions frequency band as follows to use at Switzerland, Lithuania and Slovakia. Operate the WR2120 using one of the following four channels: CH1: 9422.5MHz, CH2: 9427.5MHz, CH3: 9432.5MHz, CH4: 9437.5MHz

POWER SUPPLY LABEL

100-240 VAC SINGLE PHASE, 50/60 Hz POWER CONSUMPTION: MAX. 350W RATED AMPERE: 3.5-2.4A (100-150VAC) 1.8-1.5A (200-240VAC)



TABLE OF CONTENS

SAFETY	INSTRUCTIONSi
1. SYST	EM SUMMARY1
1.1.	Type of Radar Bands1
1.2.	Anatomy of Weather Radar2
1.3.	Mechanical Operation2
1.4.	Multi-radar System
1.5.	Side Lobe4
1.6.	Location of Radar Installation6
1.7.	Radar System Certificate7
1.8.	Requirement of Calibration8
1.9.	Peripheral Devices8
2. SPEC	IFICATIONS
2.1.	Antenna Unit9
2.2.	Signal Processing Unit10
2.3.	Data Processing Unit 11
2.4.	Accessories 12
2.5.	Construction Materials List13
3. PRIOF	R CONFIRMATION
3.1.	Confirmation Items 14
3.2.	Power Equipment14
3.3.	Measurements14
3.4.	LAN Equipment14
3.5.	Peripherals Equipment15
4. PREC	AUTIONARY ITEM16
5. CONS	TRUCTION
5.1.	Antenna Unit17
	5.1.1. Method to divide the unit 17
	5.1.2. Method of transport 19
	5.1.3. Lifting tool
	5.1.4. Mount the antenna unit
	5.1.5. Leveling the antennaunit21
	5.1.6. Open the radome temporary23
	5.1.7. Box connector
5.2.	Signal Processing Unit
5.3.	Data Processing Unit
6. INITIA	L SETTING OF AZIMUTH
7. ANTE	NNA POINTING ADJUSTMENT
7.1.	Software Items
7.2.	PC Time Setting
7.3.	Solar Position Simulator
7.4.	Antenna Position Analysis
7.5.	Solar Observation
7.6.	Antenna Pointing Adjustment

ftware39
40
44

APPENDIX:

A: LIGHTNING PROTECTION ASSE	SSMENT46
B: COMMUNICATION NETWORK	57
C: STORAGE MEDIA	59
D: UPS SETTING	60
E: TEAMVIEWER	61

1. SYSTEM SUMMARY

RADAR (Radio Detection and Ranging) developed during World War II as a method to detect the presence of ships and aircraft (the military considered weather targets as noise). Since WWII, there have been many advances in radar technology (e.g., Doppler techniques). It is used on land, sea, and in space for both research and operational needs.

1.1. Type of Radar Bands

There are several different categories according to the wavelength of using on radar in the world. Type of bands are L, S, C, X, and K band.

- L band radars: "L" for "long". This band is mostly used for clear air turbulence studies. It operates on 15-30 cm wavelength and a frequency of 1-2 GHz.
- **S band radars:** "S" for "short". It is not easily attenuated and is useful for near and long range weather observation. It operates on 8-15 cm wavelength and a frequency of 2-4 GHz. Some weather services use it on a wavelength of just over 10 cm. The drawback to this band of radar is that it requires a large antenna dish and large, complex motors to power it. It is not uncommon for an S band dish to exceed 7.62 m in diameter.
- **C band radars:** "C" for "compromise". The dish size does not need to as large so it is more affordable for TV stations. It operates on 4-8 cm wavelength and a frequency of 4-8 GHz. It is best used for shorter range weather observation because the signal is more easily attenuated by dry weather and rain. The frequency allows C band radars to create a narrower beam width using a smaller dish. C band radars also do not require as much power as an S band radar.
- X band radars: "X" is derived from the XX2 secret band. It uses smaller wavelength, is more sensitive and can detect smaller particles. It operates on 2.5-4 cm wavelength and a frequency of 8-12 GHz. These radars are used for studies of cloud development because they can detect the tiny water particles and also used to detect light precipitation such as snow. X band radars also attenuate very easily so they are used for only shorter range weather observation. Also due to the small size of the radar it can easily transported, like the "Doppler on Wheels" radar. Most commercial airplanes are equipped with X band radar to pick up turbulence and other weather phenomenon.
- **K band radars:** "K" for "kurz (German for short). This band is split down the middle due to a strong absorption line in water vapor and it is similar to the X band but is just more sensitive. It operates on 0.75-1.2 cm or 1.7-2.5 cm wavelength and a corresponding frequency of 27-40 GHz and 12-18 GHz.



Figure 1.1: 3 general types of weather radar band

1.2. Anatomy of Weather Radar



Antenna: The main purpose of the antenna is to focus the transmitted power into a small pencil beam and also to receive and collect the returned signal.

Radome: Protects the antenna from high winds, dusts, and rain.

Sub reflector: Directs the signal from the transmitter onto the antenna and also directs the return signal from the antenna to the receiver.

Receiver: Detects the signal returned from a target.

Transmitter: Generates the microwave signal at the correct phase and amplitude. For X-band weather radar, the wavelength of the signal is approximately 3cm.



Figure 1.2: Antenna Type

1.3. Mechanical Operation

This system observes the development of rain clouds outputs the intensity of precipitation, the speed of rain clouds (Doppler speed) and observes rainfall phenomena. It is capable of high resolution rain observation, rain cloud, precipitation density and speed observation. The solid-state transmitter replaces previous aging devices such as a magnetron.



The area sampled by the radar increases with distance. The wider the beam the greater the likelihood of sampling a mixture of precipitation types and also a greater the likelihood of sampled both inside and outside a cloud. Obstacles can also block a portion of the radar beam resulting in an artificially high power return.



NOTE: Required accuracy for leveling

Although 0.4 degrees is an acceptable level, it may cause a 209.4m difference at a 30km distance from radar. For best target accuracy make mount level 0.0 to 0.1 degrees.



1.4. Multi-radar System

The single X-band weather radar can be difficult to avoid problems with blind areas due to buildings, mountains or strong signal extinction by heavy rain.

Furuno provide multi-radar system that consists of three radar systems. While two radar systems are detecting and tracking rain clouds and observing their movements, the other one is working as RHI sector scan mode at high speed and cutting through the clouds to observe their internal structures. It is very difficult to complete signal processing of all the radar systems on single PC because of the CPU performance. Therefore signal processing is distributed among the PC of each radar system, and all the data are gathered on the central PC and composited into one synchronized image.



Figure 1.3: Image of using 3 radars



1.5. Side Lobe

The energy radiated from an antenna forms a field having a definite **radiation pattern**. A radiation pattern is a way of plotting the radiated energy from an antenna. This energy is measured at various angles at a constant distance from the antenna. The shape of this pattern depends on the type of antenna used.

To plot this pattern, two different types of graphs, rectangular-and polar-coordinate graphs are used. The **polar-coordinated graph** has proved to be of great use in studying radiation patterns. In the polar-coordinate graph, points are located by projection along a rotating axis (radius) to an intersection with one of several concentric, equally-spaced circles. The polar-coordinate graph of the measured radiation is shown in Figure 1.7.

The **main beam** (or **main lobe**) is the region around the direction of maximum radiation (usually the region that is within 3 dB of the peak of the main beam). The main beam in Figure 1.7 is northbound.

The **side lobes** are smaller beams that are away from the main beam. These side lobes are usually radiation in undesired directions which can never be completely eliminated. The side lobe level (or side lobe ratio) is an important parameter used to characterize radiation patterns. It is the maximum value of the side lobes away from the main beam and is expressed in Decibels. One side lobe is called **back lobe**. This is the portion of radiation pattern that is directed opposing the main beam direction.

The now following graph shows the **rectangular-coordinated graph** for the same source. In the rectangular-coordinate graph, points are located by projection from a pair of stationary, perpendicular axes. The horizontal axis on the rectangular-coordinate graph corresponds to the circles on the polar-coordinate graph. The vertical axis on the rectangular-coordinate graph corresponds to the rotating axis (radius) on the polar-coordinate graph. The measurement scales in the graphs can have linear as well as logarithmic steps.

Beam Width:

The angular range of the antenna pattern in which at least half of the maximum power is still emitted is described as a "Beam With". Bordering points of this main lobe are therefore the points at which the field strength has fallen in the room around 3 dB regarding the maximum field strength. This angle is then described as beam width or aperture angle or half power (- 3 dB) angle - with notation Θ (also ϕ). The beam width Θ is exactly the angle between the 2 red marked directions in the upper pictures. The angle Θ can be determined in the horizontal plane (with notation Θ_{AZ}) as well as in the vertical plane (with notation Θ_{EL}).

Main and Side Lobes (Minor Lobes):

The pattern shown in the upper figures has radiation concentrated in several lobes. The radiation intensity in one lobe is considerably stronger than in the other. The strongest lobe is called **main lobe**; the others are (minor) **side lobes**. Since the complex radiation patterns associated with arrays frequently contain several lobes of varying intensity, you should learn to use appropriate terminology. In general, main lobes are those in which the greatest amount of radiation occurs. Side or minor lobes are those in which the radiation intensity is least.

Front-to-Back Ratio:

The front-to-back ratio of an antenna is the proportion of energy radiated in the principal direction of radiation to the energy radiated in the opposite direction. A high front-to-back ratio is desirable because this means that a minimum amount of energy is radiated in the undesired direction.



Figure 1.5: Antenna pattern in a polar-coordinate graph

Figure 1.7 shows the high level echo that appears side lobes.

> Azimuth direction:

Antenna side lobes show both P0N (unmodulated pulse emission for radars) and Q0N (frequency modulation within each pulse) covered area.

Range direction:

Pulse compression (Range) side lobes show Q0N only. It improves sensitivity of long pulse but increase bling range. However this blind area can recover using un-modulated pulse.

Figure 1.6: The same antenna pattern in a rectangular-coordinate graph



Figure 1.7: High level echo with side lobes

Pulse compression is useful for weather radar to increase the average transmitted power by transmitting a longer pulse but without reducing the range resolution of the radar.

Side lobe suppression is helping to eliminate the problem. For a radar pulse signal after compression, the narrower pulse main lobe is always accompanied by higher side lobes. So, all pulse compression radars suffer from range side lobes which cause energy from strong reflections to leak into adjacent range cells. High suppression of side lobes is not required in some other non-meteorological radar, but is important for meteorological radar because weather phenomena can have significant reflectivity gradients, and ground clutter echo can be much larger than medium rain. Furthermore, the side lobes of strong signal will falsely be recognized as an existence of small target. Therefore, range side lobes must be suppressed by a large amount to prevent contamination in adjacent range cells.



Figure 1.10: Distance of main lobe

1.6. Location of Radar Installation

1. Confirm the observed region in relation the topography features:

In this example the radar must cover an altitude of 1500 meters maximum and a 70km distance radius within the rainfall forecast area. Therefore there should not be any structures or objects higher than radar around the installation point.



2. When installing antenna on building rooftop or a tall tower in urban area.

Mount the radar on the stand or tower, NOTE: it must be higher than any surrounding obstruction (building, structure) for proper radar operation. The tower must be designed strong enough to withstand heavy storms, winds and severe weather conditions.

Also note that a crane or aerial work platform vehicle might be necessary to mount the radar and install the tower. It is important to consider any additional space required for crane operation during installation or repair.

3. Lightning protection and grounding considerations:

Provide a lightning rod near or around the radar area to improve lightning protection performance based on JIS A 4201, JIS Z 9290 and IEC 62305. Refer to APPENDIX A.

The protection systems should include surge protectors/absorbers.

The grounding system will typically consist of an underground grid, radials, or rods which provide a ground resistance of not more than 1 ohm. It should have a connection point at the base of the tower. Refer to APPENDIX A for more detail.

4. Survey antenna surroundings:

Ensure no interference to any surrounding antenna (e.g.: Broadcast, mobile (cell) phone station, radio, BS/CS, etc.) and no obstacles should be around the antenna. Moreover, secure a service space of 1 m or more around the antenna. In addition, strong reflections can damage the receiver if there are obstacles nearby.

5. Power supply requirements:

Radar needs 100VAC (up to 240VAC), single phase 50/60Hz with GND. The minimum electric current must be installed for voltage used, 100V is 10A, and 240V is 4.2A.

6. Telecommunication line and internet requirements:

Use telecommunication line for transferring weather observation data and operating the radar by remote. The minimum require continuous speed to transfer all data in real time is 8 Mbps or faster. A wireless network may have enough speed for just operating the system but we recommend you to use a fast speed network like a fiber optic network when possible.

7. Building/ground structure:

The installed location of the radar must have proper load bearing resistance and durability to support a tower or stand. However a structural plan from a professional architect and any required permits may still be required for building or ground installation of the radar tower/mount.

8. Human health considerations:

Build the radar stand at least 2 meters high if the radar is installed where people have easy access to radar. A sign board must also be placed at the entrance or ladder at radar access point.

9. Heating and cooling system:

Air conditioning is necessary to keep temperature stability for the room/cabinet (rack) of DPU.

10. Pseudo echo:

Set the sector blank to the obstacle direction nearby. When transmitting in the direction of the obstacle, some pseudo echoes will be indicated due to reflections, therefore set the sector blank until the pseudo echo disappear.

- **Note: DO NOT** look at the antenna closer than noted below while radar is in operation. This energy can be extremely damaging to the human body, especially the eyes. Furthermore **DO NOT** points the antenna at any individuals closer than noted below while transmitting.
- * As shown in Installation manual preface warnings (Table on page i, Radio Frequency Radiation Hazard), the danger distance of transmit radio wave is set to 10W/m² value for safe standard, therefore do not go closer than 9.1m to the radar.

1.7. Radar System Certificate

Most countries by law have specific certificates for operating radar as a radio station. The radar frequency is in a shared radio spectrum with many other radio services, providing functions ranging from air traffic control to amateur radio operations. Although the radio frequency spectrum is not a physical resource, the use of a frequency at a given location usually precludes that same frequency from being used by others in the same geographic area. This need to have exclusive geographic use to prevent harmful interference has led to the current spectrum regulations and established spectrum use rules. Such rules grant licenses for spectrum use, and partitioning of spectrum for shared use between radio services.

These certifications are approved by the Ministry of Internal Affairs and Communications (Japan), Federal Communications Commission (USA), or other agencies of the specific country. It is important to apply when deciding the radar location because it will take time to get certification approval. It sometimes takes up to a year.

1.8. Requirement of Calibration

Calibration is the activity of checking or measuring and comparing with a specific standard reference instrument. It may also include adjustment of the system to bring it into alignment with the standard.

1.9. Peripheral Devices

- External HDD (Hard Disk Drive): Useful for saving large amounts of data. Use USB3.0 device type to transfer the data at high speed. Recommendations include using a 6TB storage device to save around one half years data (compressed).
- UPS (Uninterrupted Power Supply): Avoid risk of DPU crash by instantaneous power failure due to electric power company trouble, facility power or natural disaster such as thunderstorms. When possible use an outlet ON/OFF type selection device that allows individual device power to be set ON or OFF remotely via the internet.

Sample images:







2. SPECIFICATIONS

2.1. Antenna Unit

Parameter	Descriptions	Remarks	
Unit name	WR2120-ATU		
Operating Frequency	9.4 GHz band Carrier Frequency		
Maximum range	70km	Displayable observation level : 70km	
Doppler measurement	Max. ±64m/sec		
Power supply	100 to 240VAC, Single Phase, 50/60 Hz		
Power consumption	Below 250W	Max. 350W	
Rated Ampere	1.5 to 3.5A		
Size	Ф980mm×H1068mm	Radome size	
Weight	68kg (149.9 lb)	Weight of radome only: Upper 15kg, Bottom 11kg(incl. 12pcs of M10x35 stopper hexagon bolt) Weight of radar only: 42kg	
Operating Temperature	-10 to +50 °C	Humidity 93% without condensation	
Storage Temperature	-40 to +70°C		
Water & Dust proof	IP55		
Maximum wind survival	90 m/sec		
Occupied Band Width	Below 6 MHz		
Type of Emission	PON, QON, VON		
Amplifier	Solid state module		
Peak Power	100 W	each Horizontal and Vertical	
Duty Ratio	Up to 10 %		
Pulse Width	Below 50µs		
Pulse Repetition Frequency	Below 2000 Hz		
Frequency Shift	Below 4 MHz	Except P0N	
Antenna Type	Gregorian	Refer to Figure 2.1	
Aperture Size	Φ750 mm		
Antenna Gain	more than 33.0 dBi		
Antenna Polarity	Dual polarimetric	Horizontal, Vertical	
Beam Width	2.7 degree	Pencil beam	
AZ Rotation Speed	0.5 to 16 rpm	Adjustable	
Horizontal Scan Angle	360 degrees	Continuously-rotating	
Vertical Scan Angle	-2 to 182 degrees	Adjustable	
Resolution of Angle	0.1 degrees		
Precision of Angle	0.2 degrees		

*1 P0N : Sequence of pulses without modulation.
*2 Q0N : Sequence of pulses, frequency modulation within each pulse.
*3 V0N : Combination of P0N and Q0N.

2.2. Signal Processing Unit

Parameter	Descriptions	Remarks
Unit name	WR2120-SPU	
Data Output ^{*1}	Rainfall intensity R (mm/h), Reflectivity factor Zh (dBZ), Doppler velocity V (m/s), Doppler velocity spectrum width W (m/s), Cross polarization difference phase ødp (deg), Specific differential phase KDP (deg/km), Co-poral correlation coefficient pHV, Differential reflectivity ZDR	
Scan modes	PPI, Volume scan, PPI/RHI (Sector Scan also availiable)	
Ground clutter Rejection	Enable	
Data Correction	Distance attenuation, Rain attenuation, Excessive Doppler velocity, Suppression of signal returns from lan, Clutter suppression	
Interface	LAN 1 port, Ethernet 1000 Base-T (Cat5e or more)	
Power supply	100 to 240VAC, Single Phase, 50/60 Hz	
Power consumption	Max. 650W include Antenna Unit	
Rated Ampere	2.7 to 6.5A	
Size	W756mm×D300mm×H750mm	
Weight	50kg (111lb)	
Operating Temperature range	-10 to +50°C	
Storage Temperature range	-20 to +60°C	
Water & Dust proof	IPX5	

^{*1}: Detail of processing by the main unit.

2.3. Data Processing Unit Receive data from Antenna Unit (ATU) to indicate a picture of rainfall in real time.

Hardware				
Parameter	Descriptions			
Unit name	WR2120-DPU			
Power supply	100t to 125VAC, 50/60Hz Note: Bundled AC power cable (Socket IEC C13 / Plug type B) is only for US and Japan. Do not use the bundled cable in other area, it may cause fire or damage the equipment. Please prepare AC cable by user to fit the site.			
Power Voltage	100-240VAC			
Power consumption	Max. 150W			
Rated Ampere	0.8 to 2.0A			
OS	Windows 10 IoT Enterprise 64bit			
Internal LAN	2 port, 1000base-T			
I/O	USB3.0×6 port			
Size	W205 x D227x H88 (mm), Power supply unit: W141 x D193x H91 (mm)			
Weight	2.5kg			
Temp. range	0 to +50 °C			
LAN Adapter	1000base-T adapter			
	Display Software			
	For weather observation system			
Name	RainMap, RainPlay			
Data indication	Rainfall intensity R (mm/h), Reflectivity factor Zh (dBZ), Doppler velocity V (m/s), Doppler velocity spectrum width W (m/s),			
Status display	Indicate ATU and DPU status			
File output	Save and output one scan period of data			
	For remote maintenance			
Name	TeamViewer GmbH			
Version	TeamViewer Host (For remote server) 12			
Function	Remotely operate the software, view and download the observation data.			
Requirement	It must be connecting to internet			

Notice of the data communication:

Condition of the data communication (Transfer efficiency: 50%)

Baud rate	Cycle (Data transmission possibilities)
1Mbps/min or more	4 elevations/ 5min.
4Mbps/min or more	2 elevations/ 1min.
8Mbps/min or more	4 elevations / 1min.

2.4. Accessories

Cables & Tube Antenna Unit (radome) Signal Processing Unit					
Items			Descriptions	Length	Qty
LAN cable	100Base-T measure va	(STP Ca lue. Incl	at5e or better), Length depends on . LAN connector w/ cover	5m ^(*1)	2
AC Power cable	Shielded VCTF 2sq 3core or equivalent5m(*1)Incl. crimped Terminal5m(*1)			1	
Control cable	26pin cable	(Both I	HDR-26pin)	5m ^(*1)	1
Control cable	14pin cable	(Both I	HDR-14pin)	5m ^(*1)	1
Signal cable	3D-2W (Bo	th SMA	-P Connector)	5m ^(*1)	3
Protective tube	Protective tu	ube con	duit Inner diameter : 28 mm, IP65	10m ^(*2)	1
Box connector	IP65(Water/	Dust pr	oof) φ28	-	4
A	ccessori	es for	r installation (Fixed radome and s	stand)	_
Items Descriptions Qty					Qty
Security Lock	ity Lock For SPU box with keyx2		1		
M16 Hex Nut		Material : SUS304		12	
M16 Flat Washer		Material : SUS304		12	
M16 Split Lock Washer Material : SUS304		8			
M16x200mm Hexagon Bolt Material : SUS304		4			
M16 Large Flat Washer Material : SUS304		4			
M16x40mm High Nut Material : SUS304		4			
Lifting Tool Material : SUS304		4			
PXI Philips Screwd	river #1				1
SMA torque wrencl	SMA torque wrench 7mm			1	
	Α	ccess	sories for maintenance		
ltems			Descriptions		Qty
Maintenance tool b	ох	Size: L	_410x150x100 [mm]		1
M10 x400 Maintena	x400 Maintenance bolt Holding the radome cover up above in order to access inside the radome when maintenance		8		
M10 Hex nut		Fix the length of maintenance bold for lifting up the radome			8
Spring clamp	amp Holding the radome cover up above in order to access inside the radome when maintenance			8	
Handle		Lifting radar out/in from radome 4			4

*1) Basic length of cable between ATU and SPU is 5m, NOTE: there are 10m, 15m and 20m options. These cables have extra length for inside equipment. (e.g.: 5m cable = 5m + approx.2m)
 *2) Cut the tube into two pieces to adjust a length between ATU and SPU.

Note: For tower radar installations this depends on the overall installation environment and consultation will be necessary.





Figure 2.1: Maintenance tool

2.5. Construction Material list (Local contractor/client supply)

Cables & Tube					
Caples & Tupe Signal Processing Unit Data Processing Unit					
Items		Descriptions	Length	Qty	
LAN cable	1000Base-T (S measure value	TP Cat5e or better), Length depends on . Incl. LAN connector w/ cover	by measure	2	
AC power cable	Shielded VCTF Incl. crimped T	⁻ 2sq 3core or equivalent. erminal	by measure	1	
Protective tube	PF tube condu IP55 (Water/D	it Inner diameter: φ28 mm, ust proof) or better	by measure	1	
Box connector	IP65(Water/Du	st proof) φ28	-	2	
	Ba	sic expendable supplies			
Items Descriptions			Qty		
Heavy Duty Cable	Tie (2 types)	Nylon 6/6 w/ weather resistance 100mm,	150mm	Multi	
Crimp terminal 2sq		φ4.3 for electric cable		Multi	
LAN connector		RJ45 for LAN cable		Multi	
Power cable 3 cores		For electric supply		Multi	
LAN cable		1000Base-T, CAT5e or better, STP		Multi	
	В	asic construction tools			
ltem	Items Descriptions				
Hex key (Ball-head	l type)	M4 (3mm)			
Ratcheting Wrench	ו	M5 (8mm), M12 (19mm), M16 (24mm), Adjustable wrenches (up to 30mm)			
Socket Wrench		M10 (17mm) for fixing radome top/bottom			
Exclusive Philips S	Crewdriver #1	Multiuse			
Philips Screwdriver #2		Multiuse			
Slotted Screwdriver 3mm		Multiuse			
Cable/Wire cutting scissors		Multiuse			
Flat nippers		Multiuse			
Wire Strippers		For electric wiring work			
Ratchet Wire Crim	per 2sq	For electric wiring work			
LAN cable stripper	S	For LAN cable work			
LAN Ratchet Crimp	ber	For LAN cable work			
LAN cable tester		For LAN cable work			

3. PRIOR CONFIRMATION

3.1. Confirmation Items

- 1) The mount plate must be installed properly for Antenna Unit (radome).
- 2) Power cable (AC100V-240V) must be routed safely.
- 3) Power cable gauge should be selected depending on its length.
- 4) Frequency of AC power source must be 50Hz or 60Hz sine wave and single-phase current.
- 5) All engineers must wear safety appliances including helmet and safety shoes during an installation of Antenna Unit. It is dangerous that antenna could hit an individual by turning.
- 6) Secure a service space of 1 m or more around the radome. In addition, strong reflections can damage the receiver if there are obstacles nearby.
- 7) Set the sector blank to the obstacle direction nearby. When transmitting in the direction of the obstacle, some pseudo echoes will be indicated due to reflections, therefore set the sector blank until the pseudo echo disappear.

Note: **DO NOT** look at the antenna closer than noted below while radar is in operation. This energy can be extremely damaging to the human body, especially the eyes. Furthermore **DO NOT** points the antenna at any individuals closer than noted below while transmitting.

* As shown in Installation manual preface warnings (Table on page i, Radio Frequency Radiation Hazard), the danger distance of transmit radio wave is set to 10W/m² value for safe standard, therefore do not go closer than 9.1m to the radar.

3.2. Power Equipment

- 1) This equipment requires 1KVA x1 power line with grounded outlet (3 pin type).
- 2) The AC power cable attached to the DPU power supply is shipped with items conforming to the PSE standard (Japan) and UL standard (US). Please prepare the power cable according to the safety standards of the area to be equipped on the customer side.

3.3. Measurements

Notice: Measure the main AC power before powering on the radar.

Items	Descriptions			Remarks
Digital Multimeter	<u>Voltage</u> AC : 85 to 240V DC : 1 to 50V	Current AC : 1 to 10 A DC : 1mA to 1A	Resistor 0.1 to 10M ohm	Tester Lead Cables

3.4. LAN Equipment

- 1) Use Cat5e (or better grade) of 100Base-Tx LAN cable for transferring data from the Data Processing Unit to the output equipment.
- 2) Prepare a high speed broadband connection (approx.100Mbps) for remote maintenance access.

*Low speed broadband may cause slow access on remote support system.

3.5. Peripherals Equipment

It has to be prepared by the local contractor or client supply.

1. Wired router

Router is using for internet purposes.

0	
Function	Connect with an external network
WAN port	1000BASE-T, 1 port, MDI/MDI-X auto switch
LAN port	1000BASE-T, 4 port or more, MDI/MDI-X auto switch
Input voltage	AC100V-240V, Single phase, 50/60 Hz
Remarks	YAMAHA RTX810 or equivalent

2. SW HUB

Switching hub is for expanding network to several devices purpose.

Function	Connect with LAN
LAN port	1000BASE-T, 5 port or more, MDI/MDI-X auto switch
Input voltage	AC100-240V, Single phase, 50/60 Hz
Remarks	ELECOM EHC-G05MN-HJ or equivalent

3. Uninterrupted Power Supply

It provides enough power to keep the system running for few minutes when instantaneous voltage occurs and it will automatically shut down the pc safely. Some UPS can support by remote network.

Function	Connecting with all devices to keep the power safe.
Output voltage	More than 1,000VA
Input voltage	AC100-240V, Single phase, 50/60 Hz
Remarks	APC Smart-UPS series w/ network, Tripp Lite Smart 1000RMXL2U (AC83-147V) / SMX1000RT2U (AC182-278V) or equivalent

4. External data storage device

It is a purpose for saving more data.

Function	Save scan data
Capacity	3TB or more
Interface	USB3.0 (Note: Plug in USB3.0 cable in to the USB3.0 port of DPU)
Input voltage	AC100-240V, Single phase, 50/60 Hz
Remarks	WD 3TB or equivalent
	Note: Disable automatic sleep function (also called ECO mode). It is unsuitable for weather radar and will cause data loss. This is because is sleep mode initiates between data transfer intervals data will not transfer. Also the DPU cannot wake storage device from sleep mode. DPU would require restart before storage device will recover from sleep mode.

Please refer to UPS, Router, and other equipment documents separately.

4. PRECAUTIONARY ITEM

- 1) Use only single phase 100-240VAC commercial power supply.
- 2) DO NOT overhaul or modify.
- 3) DO NOT work on during electrical storm.
- 4) DO NOT scratch, cut, forcedly bend, pull, twist, bundle, or damage the power cable. Also do not put heavy items on top or around.
- 5) DO NOT touch inside equipment with a wet hand.
- 6) Connect ground conductor for equipment protection and electric shock prevention from lightning induction and ground leakage.
- 7) Cleaning instructions: Use dry soft cloth to wipe the surface. If it is difficult to remove stains use the cloth soak with a neutral detergent to clean surfaces. Please DO NOT use an alcohol or an organic solvent (e.g.: thinner) to clean surfaces.
- 8) When install the radar stand, level of stand should be within ±0.2 degrees.



Figure 4.1

5. CONSTRUCTION

During the environmental survey all installation places for DPU, cables, pipes, and mounting plate should be carefully considered.

5.1. Antenna Unit

This radar can be divided into 3 parts as shown below.



5.1.1. Method to divide the unit

1) Put antenna unit on a workbench



Loosen the 12, M10 bolts around the radome and remove the top part of the radome. Lift up the top part of radome high enough to check the position of antenna. Because the antenna may hit the flange inside the top part of radome, change the position of the antenna feed arm upward if it is facing horizontally.

Use some pillows or lumber under the bottom edge of the radome top that will make easier to put hands under radome when lifting up. Do not place directly on the floor or it will be hard to lift up without space under the radome.



Antenna

2) Remove internal unit from the base of radome by completely removing M8 hexagon head bolts and M16 hexagon head bolt set. The internal unit will get damaged if placed directly on the floor without removing the M16 hexagon head bolts. It may also damage them if placed on the floor with M16 high hex nut loosened.



3) Mount 4 handles in the internal unit. Insert the handles until it hits to the bottom for not to come off when lifting unit. **Note**: Turn too much handles may damage radome base.



4) Hold handles to lift up the internal unit.

Note: Beware the antenna feed arm can easy to damage or break. Any deformation of the antenna arm can cause functional issues and degrade antenna performance.

Attention point



- 5) Follow the steps 1 to 4 in the reverse order to reinstate equipment to the original configuration. Beware to the following points:
 - Do not remove handles during step 3.
 - M16 high hex nut should be tightened in step 2.
 - It may damage the internal unit if M16 high hex nut is not tightened when reinstalled.
 - Do not damage the antenna feed arm when covering the radome in step 1.

5.1.2. Method of transport

Hold flange area of radome when lifting by hand.





5.1.3. Lifting tool

Rotate lifting tools from storage (shipping) position to installation position before using it. Note: Do not loosen the M16 high hex nuts. * If these are loosening, the internal unit may be damage while lifting. Turn the lifting tool outward by slightly loosening M16 hex nut. It might be easier to remove all under hex nut (flat-washer (L), regular flat-washer, split lock washer, and hex nut) before lifting the radome to insert into the base hole. High hex nut Use a soft protective cover to shield radome from Damages some kind of cotton cover to protect radome from scratch and Hook shackle into damage lifting tool hole at φ20 to hoist up Hook the shackle on the hole of $\varphi 20$ and hoist it up Set all 4 bolts with the same length between hex nut & hex nut might make easier for leveling.

5.1.4. Mount the antenna unit



5.1.5. Leveling the antenna unit



Confirm all four hex nuts that are securely tightened and without having any strain to radome or stand after leveling the radar. (1) Hex nut, (2) flat washer (L) and (3) radar stand should not have any gap when tightening the (4) Hex nut.





Do not tighten (4) hex nut before (1) hex nut and (2) Flat washer touch firmly to (3) Radar stand. Otherwise the chassis of the antenna unit may be distorted and broken. Also any foreign matters should be removed before fastening the (1) hex nut.

%Tighten up hex nuts by finger.

5.1.6. Opening the radome temporary

When open radome temporary, please use long tension bolts to secure top of radome for maintenance work if it is not possible to remove the top radome. One set of tension bolts is in the maintenance tool box. Put these bolts from bottom through top holes of radome. Ensure to keep bolt distances balanced as shown below:

- Caution: DO NOT open top of radome during strong wind or radome may become airborne, causing harm to individual(s) or radar.
- (1) Loosen all fixed bolts
- (2) Rotate top radome to right and align each thru-hole (radome base) with associated nut insert (radome top) as shown in image 5.3.
- (3) Setup hex nut about 10mm from end of a maintenance bolt.
- (4) Insert the maintenance bolts into each thru-hole from bottom radome up into top radome nut insert. Lift up the radome top until M10 hex nut (Step (3) contacts radome base.
- (5) Attach a spring clamp on each maintenance bolt to secure all bolts.





(2)

1. Loosen the 12, M10 bolts that attach the bottom of radome. This M10 bolt has a detent structure, loosen the bolt until it moves freely up and down. The bolt will come out if keep turning it loosen. The missing bolt can be replaced by putting the bolt in a smaller side of hole and tighten it. Radome base Move up and down M10 detent bolt Loosen Tighten 2. Lift up the radome slightly and rotate it counterclockwise around 30 degrees, the fixed hex nut will fit in to the recess part of top radome. The nut insert can be seen from the thru hole. Rotate the upper radome counterclockwise URUNO Locating hole with recess Figure 5.3: Before rotating top of radome

.





- 10. For reducing from the wind-induced movement, fasten the spring clamp above the base flange and tighten bottom hex nut by hand.
 - * Do not damage the radome gasket when fasten the spring clamps.
 - * Use the spring clamp properly as examples shown below.



Figure 5.6: Fasten properly by spring

Bad examples:



Figure 5.7: Space between spring clamp and radome base flange



Figure 5.8: Spring clamp is inclined



Figure 5.9: Fasten spring clamp only partially



5.1.7. Box connector



Note: Tighten up the disuse box connector with a cap inside.





5.2. Signal Processing Unit (Store into storage box)





5.3. Data Processing Unit



- 1. Setup Data Processing Unit
 - (1) Connect DC power cable of DPU-PS to DPU.
 - (2) Connect AC power cable to DPU-PS and connect AC power cable to electrical outlet.
 - Note: Power "ON" ATU first and then power "ON" DPU.
 - **Note:** By default DPU will boot up automatically and RainMap (radar software) come up automatically when DC power supplied.
 - (3) Connect display to DVI port, And connect keyboard and mouse to USB port.
 - (4) Connect LAN cable from ATU (SPU module inside the ATU) to LAN1 port.
 - (5) Connect LAN cable from MONI-CON (inside the ATU) to USB port via bundled USB-LAN adapter.
 - (6) Connect LAN cable from router to LAN2 port for using Internet. And the router and the LAN cable for Internet is local supply.

Notice:

- Bundled cable is dedicated for Japan and US use and can be used up to 125V. Appropriate power cable should be prepared for each site location.
- 2) Do not use the same IP address on ATU.
- 3) Do not put heavy object on the DPU. It may deform the DPU chassis.



6. INITIAL SETTING OF AZIMUTH

The installed radar orientation and actual geographical azimuth are normally different causing an incorrect initial echo indication. An azimuth adjustment is required for proper echo orientation. Determine actual radar antenna azimuth (see orientation diagram below) and then determine geographical azimuth by using a magnetic compass (It is necessary to convert it from magnetic azimuth), GPS heading system or solar measuring tool. Enter RainMap software and select menu setup, "Azimuth Offset". The unit resolution is 0.01 degree of the measured value.

Measurement range: +0 to 360 degrees.

e.g.: Enter the value of "Azimuth Offset" to 315 degrees when the origin of radar is as below image 1.





Notice: Ground clutter rejection must be "OFF" during this operation.

- 1) Turn ON DPU power. Enter User name as radar, and password as radar.
- 2) Remain a safe distance from radar. Radar transmit radio wave can damage human body especially eyes within the danger zone.
- 3) Connect ATU/SPU to main power outlet.
- 4) Use a map with local geographical features of installed radar unit (e.g. Google map).
- 5) Setup "Display range [km]", "Data Type", in [Display] setting menu of RainMap.

✓ Setting	Key	Value
Display	Display range [km]	30.0
Data Acquisition	Display data type	R[mm/h]
Radar Site Location	Echo transparency [%]	50
Scan	Antenna sweep line	ON
Units	Radiowave shielding area	OFF

D2

.

04

05

- 6) Setup "PPI elevation" in [Scan] setting menu of RainMap.
- 7) Setup "AZ offset to north" based on difference between physical radar orientation and measured azimuth in [Antenna Origin] setting menu of RainMap.

 Setting 	Key	Value	^
Display	AZ offset to north	315.00	
Data Acquisition			
- Radar Site Location			
Scan			
Units			
Advanced Setting			
Radar			
Serial Number			
Application Startup			
Antenna Origin			
Network			



- **Note**: Elevation angle written here is one example. It depends on geographical feature where radar is located. For another example, if it is in a flat country like Denmark, a water tower in Lund, and Sweden, it used -1 degree, 10 km range and was able to detect coastline and the city boarders of Copenhagen.
 - 1) Click [STBY] in [Radar operation] to Stop TRX.
 - 2) Add a map file to RainMap and display on screen (or use other PC to see a map).
 - 3) Locate a characteristic geographical feature like a mountain line ridge or form, note distance, and relative bearing on map.
 - 4) Set radar to a higher elevation until no echo is received from lower buildings or structures, possibly 5 degrees (in some cases 3 to 7 degrees may be required) in RainMap.
 - 5) Set a distance to more easily confirm the geographical feature "6)" in "Range [km]" in [View] setting menu of RainMap.
 - 6) Setup "Reflective Intensity [H]" in "DataType" using [View] setting menu of RainMap.
 - 7) Confirm echo after starting [TX] from [Radar operation]. Purple observations indicate strong echoes that may be from mountains.
 - Click [STBY] in [Radar operation] before making any changes to setting. To change "Azimuth Offset" angle in [RDR Parameter] service menu of RainMap, compare shape of echo with "6)" and "10)". Echo indication will be rotated clockwise if a large value entered in "Azimuth Offset". (Available range: -360 to 360)
- 9) Repeat steps "10)" to "11)" until an echo aligns with the geographic feature
- 10) Click [STBY] in [Radar operation] after finished "12)".
- 11) Set 0 degree at [Elevation] in [View] setting menu of RainMap.
- 12) Set a distance suitable for the area at "Range [km]" in [View] setting menu of RainMap.
- 13) Select "Rainfall Intensity" at [DataType] in [View] setting menu of RainMap.
- 14) Finish setup.

7. ANTENNA POINTING ADJUSTMENT

This tool is to adjust the antenna position precisely by observing the solar noise after setting offset value to [AZ offset to north] in section 6.

Note: ATU must install horizontally for adjusting elevation by solar measurement. If adjust the elevation in a tilted state, the error may become larger on the opposite side in the sun direction.

7.1. Software Items

The following conditions are necessary to use the software. Display screen resolution: FHD (1920×1080) or higher.

The following software must be installed in DPU.

- 1) LabVIEW[™] Run-time Engine 2017
- 2) Solar_position.exe
- 3) Antenna_position_analysis.exe
- If software has not been installed in DPU, click "setup.exe" inside "Installer_with_runtime" folder to start installation. (Windows needs to restart after installation). "Solar_position.exe" and "Antenna_position_analysis.exe" will install into DPU.
- If software does not exist in DPU, please contact Furuno directly for assistance.

7.2. DPU Time Setting

Set correct value for time zone, time, and date in WindowsTM. Process:

Open [Control panel] -> [Time & Date] -> Change to correct [time & date] and [Time zone] **Note:** This procedure requires administrative rights.

7.3. Solar Position Simulator

- 1. Click "Solar position simulator.exe" to startup the software.
- Check the time indication "UTC_Date(YYYY/MM/DD)" "UTC_TIME(hh:mm:ss))". Check time setting of PC if incorrect (See section 7.2.)
- 3. Input radar site latitude and longitude information in the RainMap ([setting] -> [antenna]).



- 4. Latitude and longitude will be displayed on the screen graph.
 - Blue line means solar position and orbit.
 - Red point means solar position (atmospheric refraction included in measurement) with current time.

Note: Red point will only indicate during day time, and not available during night time.

- The angle of current solar azimuth and elevation is shown with the number of degree.





Figure 7.2

7.4. Antenna Position Analysis Operation

- 1. Click "Antenna_pointing_Analysis.exe" on your DPU desktop or installed folder to start software.
- 2. Drag & Drop the observed data folder icon (observed from solar_position) into [Radar_data_path] or click folder icon to choose the data folder.
- 3. Click [♣] mark in the menu bar to start the program to see a graph of observed data files (.scn, .rhi, .sppi). (Refer to operator's manual for file type descriptions.
- 4. The right sample screen shot is a solar scanning result using Sector RHI scan.
- 5. The [Spectrum] graph is the solar radiation intensity.
- 6. Graph of [Solar_Azimuthal_Angle] and [Solar_ Elevation_Angle] will be calculated in the value of the solar altitude and azimuth during observed time.
- 7. It determines the precise antenna position by comparing the peak of solar radiation intensity and the calculated solar altitude value.
- 8. Figure 7.5 shows two or more observed measured solar data points (All data must be acquired using same scan mode).
- 9. The [solar vs. antenna] graph shows the Sector RHI upward elevation point plot peak in blue color and the downward plot peak in red color. (Antenna moves up and down to scan solar radiation)

It is determined by solar radiation peak value that estimated the Gaussian (normal) distribution spectrum.

It simply and precisely checks the antenna graph.

Sector PPI will rotate clockwise and counterclockwise during antenna scan.

10. Graph of [3D plot] displays multiple observed data. It can capture the solar intensity in 3 dimensions using sector scan:

Color indicates solar radiation intensity / Horizontal indicates azimuth / Vertical indicates elevation.

7.5. Solar Observation

It is necessary to change the RainMap settings for observing solar radiation.

Press [Alt] + [Ctrl] + click [setting] menu of RainMap for using the advanced setting.

1. Setup TX Sector Blank for all angles shown below: Blank area 1: ON AZ start angle [deg]: 0.00 AZ end angle [deg]: 360.00 EL start angle [deg]: -2.00

EL end angle [deg]: 182.00









Figure 7.4



Figure 7.5

7.6. Antenna Pointing Adjustment

Adjust the antenna using solar measurement when installing the radar, after maintenance, or repair the antenna drive system. The following information explains the process of adjusting antenna using dedicated software.

Requirements for use:

- 1) The weather at radar site area must be clear and/or sunshine.
 - (Clouds, rain and any obstacles prevent proper adjustment)
- 2) ATU must be installed horizontally. Otherwise it will deviate further in the direction other than the sun if adjust the value obtained by solar measurement.

Process outline:

- 1) Scan Azimuth by [Sector PPI].
- 2) Deviation azimuth analysis and adjustment.
- 3) Confirm that azimuth deviation is revised by [Sector PPI].

4) Scan Elevation by [Sector RHI].

- 5) Deviation elevation analysis and adjustment.
- 6) Confirm that elevation deviation is revised by [Sector RHI].
- 7) Re-confirm that azimuth deviation is revised by [Sector PPI].
- 8) Turn OFF the Sector Blank and restore observation setting to the original.
- 1. Confirm the current position (Azimuth & Elevation) of the sun by Solar position.exe. (See section 7.3)
- 2. Measure the Sector PPI first and then RHI next especially if sun is getting close to maximum altitude.

a) Sector PPI

Measure the azimuth of sun using Sector PPI. Setup Sector PPI scan from scan setting as follows: AZ rotation speed: 0.5 AZ start angle: Current solar azimuth angle of sun -15 deg. AZ end angle: Current solar azimuth angle of sun +15 deg.

: Current solar elevation of sun ±1 deg. EL angle 0 (Predict elevation 1 minute after sun moves)

EL angel 1 : Same as EL angle 0.

Display Data acquisition Radar ste location	Scan set	•3	
Scan	Key	Value	
- Units	Scan mode	Sector PPI Scan	4
	AZ rotation speed [rpm]	10.00	
	AZ start angle [deg]	0.0	
	AZ end angle (deg)	20.0	
	EL angle 0 [deg]	0.0	
	EL angle 1 [deg]		
	EL angle 2 [deg]		
	EL angle 30 [deg]		
	EL angle 31 [deg]		
			1
	OK	Cancel	Apply



02

OK

Figure 7.8

13

Cancel Apply

O1

b) Sector RHI

Measure the azimuth of the sun using Sector RHI. Setup Sector RHI scan from scan setting as follows:

EL rotation speed: 0.5

AZ start angle: Current solar azimuth angle of sun ±1 deg. (Predict the azimuth of 1 minute after the sun moved)

AZ end angle: Same as AZ start angle

AZ step angle: 2.00

EL start angle: Current solar elevation angle of sun -15 deg.

- Note: Minimum elevation must be higher than 25 deg. (If this elevation is lower, then it means it did not measure accurately
- EL end angle: Current solar elevation angle of the sun +15 deg.
- 3. Start observation by clicking [TX].
- 4. Click [STBY] to stop radar after getting 20 data files. It has to take twice (e.g: 1st start on 10:00am, 2nd start on 10:30)

5. After observed around 20 data files, save them into the following folder below:

- Folder for Sector PPI: "sppi_before" (Use current offset value that set in Section 6), "sppi_after" (After offset adjustment)
- Folder for Sector RHI: "rhi before" (Use current offset value), "rhi after" (After offset adjustment).

- S2E-17-0209_IM_WR2120_C
- 6. Drag & Drop a folder (sppi_before, sppi_after, rhi_before, rhi_after) into [Antenna_position_analysis.exe] to check the graph.
 - Refer to section 7.4 for instructions.
 - Solar radiation spectrum has difficulty to check when sun is blocked by clouds or position of sun is poor during scan.



7. Add the average values of the figure 7.9 to the original offset value if need to change the value.

8. Add the average values of SPPI and SRHI as follows: Press [Alt] + [Ctrl] + click [setting] menu of RainMap, [Setting] > [Advanced Setting] > [Zero position offset] > a) Sector PPI into [AZ offset to north] b) Sector RHI into [Origin EL position offset correction [deg]]

Note: Take a screenshot of the original value before change the setting of offset value.

-



Upward

Solar

Downward

Figure 7.10

- 9. Repeat from step 2 to 6 to observe data of "SPPI after".
- 10. Do the same things for Sector RHI start from step 2. Go to the next step when all adjustment is completed.
- 11. Confirm the RainMap echo indication either using Sector PPI scan and Sector RHI scan. Repeat the process 9 if it did not update.
- **Note:** Do not forget to do the [Auto ground clutter mapping] after changed value of the [AZ offset to north] and [Origin EL position offset correction]. (Refer to the Operator's manual for operation)

7.7. Uninstall the Software

Follow the instruction below to uninstall the [Solar_Position_tools], [LabVIEWTM Run-time Engine 2014] software.

- 1. Open [Program and function] in [Control Panel].
- 2. Choose the name of software to uninstall.
- 3. Click the Uninstall button
- 4. Complete

Note: Choose [National Instruments Software] to uninstall [LabVIEW[™] Run-time Engine 2014].

7.8. Conclusion

Calculation of the solar positon:

This software uses "Astronomical algorithms" created by Jean Meeus to calculate algorithms of the solar positon.

The accuracy of this algorithm on longitude is +/- 72 degrees of range within 0.0167 degrees. However accuracy depends on atmospheric temperature, pressure, and humidity. Therefore under certain circumstances accuracy may be very poor.

Currently the solar azimuth value is properly corrected when refraction of atmospheric conditions are properly considered.

Reference: U. S. Department of Commerce / National Oceanic & Atmospheric Administration / NOAA Research / Earth System Research Laboratory (ESRL) <u>https://www.esrl.noaa.gov/gmd/grad/solcalc/calcdetails.html</u>

Figure 7.9

0.76

-0.91

e.g.: [Upward -0.76] subtract [Downward -0.91] divided by 2 = -0.84

8. OUTLINE DRAWING

1) Antenna Unit



2) Signal Processing Unit (Storage box)

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S2E-17-0209_IM_WR2120_C

4) Data Processing Unit

S2E-17-0209_IM_WR2120_C

5) Data Processing Unit (DPU Power Supply)

9. SYSTEM DIAGRAM

WR2120 Configuration:

APPENDIX:

A. LIGHTNING PROTECTION ASSESSMENT

1. Introduction

This document outlines lightning protection based on the international standard IEC (International Electrotechnical Commission) 62305 series. The series consists of four documents as shown below:

IEC 62305 series: Protection against lightning

IEC 62305-1:2010 Part 1: General principles IEC 62305-2:2010 Part 2: Risk management IEC 62305-3:2010 Part 3: Physical damage to structures and life hazard IEC 62305-4:2010 Part 4: Electrical and electronic systems within structure

2. Risk Assessment

2.1. Specific procedure to evaluate the need of protection

According to IEC 62305-1, the risk shall be considered in the evaluation by protection requirements against lightning. For each risk to be considered the following steps shall be taken:

- Identification of the components R_X which make up the risk;
- Calculation of the identified risk components R_X ;
- Calculation of the total risk R;
- Identification of the tolerable risk R_T ;
- Comparison of the risk R with the tolerable value R_T .

If $R \le xR_T$, lightning protection is not necessary.

If $R > R_T$, protection measure shall be adopted in order to reduce $R \le xR_T$ for all risks to which the structure is subjected.

The procedure to evaluate the need for protection is given in the Figure A-1.

According to IEC 62305-2, risk components are as shown in the Table A-1.

Components	Risks for weather radar	Remarks
	S_1 : flashes to the structure	
Source	S_2 : flashes near the structure	
of damage	S_3 : flashes to the lines connected to the structure	
	S_4 : flashes near the lines connected to the structure	
Types of damage	D_3 : failure of electrical and electronic systems	
Types	L_2 : Loss of service to the public	Tolerance for L_2 and L_4 :
of loss	L ₄ : Loss of economic value	$R_T = 10^{-3} [y^{-1}]$
Dieke	R_2 : risk of loss of service to the public	
IVI9V9	R_4 : risk of loss of economic values	

Table A-1: Risk components (IEC 62305-2)

Figure A-1: Procedure for deciding the protection requirements and selecting protection measures

2.2. Assessment of Risk Components

Each risk component R_B , R_C , R_M , R_V , R_W and R_Z , consists R_2 and R_4 may be expressed by the following general equation:

where

 $R_X = N_X \times P_X \times L_X$

 N_x is the number of dangerous events per annum

 P_{X} is the probability of damage to a structure

 L_X is the consequent loss

The number N_X of dangerous events is affected by lightning ground flash density (N_G) and by the physical characteristics of the structure to be protected, its surroundings, connected lines and the soil.

The probability of damage P_X is affected by characteristics of the structure to be protected, the connected lines and the protection measures provided.

The consequent loss L_X is affected by the use to which the structure is assigned, the attendance of persons, the type of service provided to public, the value of goods affected by the damage and the measures provided to limit the amount of loss.

2.2.1. Composition of risk components

Composition of each risk components are as follows:

 R_2 : Risk of loss of service to the public: $R_2 = R_{B2} + R_{C2} + R_{M2} + R_{V2} + R_{W2} + R_{Z2}$ R_4 : Risk of loss of economic values: $R_4 = R_{B4} + R_{C4} + R_{M4} + R_{V4} + R_{W4} + R_{Z4}$

2.2.1.1. Risk components for a structure due to flashes to the structure

 R_B : Component related to physical damage caused by dangerous sparking inside the structure triggering fire or explosion which will also endanger the environment. All types of loss (L1, L2, L3 and L4) will arise.

 R_c : Component related to failure of internal systems caused by lightning electromagnetic impulse (LEMP). Loss of type L2 and L4 could occur in all cases along with type L1 in the case of structures with risk of explosion, and hospitals or other structures where failure of internal

 R_M : Component related to failure of internal systems caused by LEMP. Loss of type L2 and L4 could occur in all cases, along with type L1 in the case of structures with risk of explosion, and hospitals or other structures where failure of internal systems immediately endangers human life.

2.2.1.2. Risk components for a structure due to flashes to a line connected to the structure

 R_U : Component related to injury to living beings caused by electric shock due to touch voltage inside the structure. Loss of type L1 and, in the case of agricultural properties, loss of type L4 with possible loss of animals could also occur.

 R_V : Component related to physical damage (fire or explosion triggered by dangerous sparking between external installation and metallic parts generally at the entrance point of the line into the structure) due to lightning current transmitted through or along incoming lines. All types of loss (L1, L2, L3 and L4) will occur.

 R_W : Component related to failure of internal systems caused by overvoltages induced on incoming lines and transmitted to the structure. Loss of type L2 and L4 could occur in all cases, along with type L1 in the case of structures with risk of explosion, and hospitals or other structures where failure of internal systems immediately endangers human life.

2.2.1.3. Risk components for a structure due to flashes near a line connected to the structure

 R_Z : Component related to failure of internal systems caused by overvoltage induced on incoming lines and transmitted to the structure. Loss of type L2 and L4 could occur in all cases, along with type L1 in the case of structures with risk of explosion, and hospitals or other structures where failure of internal systems immediately endanger human life.

2.2.2. Assessment of annual number N_X of dangerous events

According to the statistic information provided by the National Environment Agency of Singapore, average thunderstorm days per year (T_D) at Changi is 168. The lightning ground flash density N_G will be leaded as follows:

 $N_G \neq E.1 T_D = 16.8 [flashes/km^2/year]$

2.2.2.1. Number of dangerous events N_D for the structure

 N_D may be evaluated as the product:

$$N_D = N_G \times A_D \times C_D \times 10^{-6}$$

where

- N_G is the lightning ground flash density [*flashes/km²/year*]
- A_D is the collection area of the structure $[m^2]$
- C_D is the location factor of the structure, 0.5 for CWRP

1) Determination of the collection area A_D

For isolated structures on flat ground, the collection area A_D is the area defined by the intersection between the ground surface and a straight line with 1/3 slope which passes from the upper parts of the structure (touching it there) and rotating around it. Determination of the value of A_D will be performed graphically or mathematically.

For an isolated rectangular structure with length L, width W, and height H on flat ground, the collection area is then equal to:

$$A_D = L \times W + 2 \times (3 \times H) \times (L + W) + \pi \times (3 \times H)^2$$

where L, W and H are expressed in meters.

Figure A-2: Collection area A_D of an isolated structure (IEC 62305-2)

2) Relative location of the structure

The relative location of the structure, compensating for surrounding structures or an exposed location, will be taken into account by a location factor C_D . For the weather radar at CWRP, $C_D = 0.5$ (Structure surrounded by objects of the same height or smaller).

2.2.2.2. Assessment of the average annual number of dangerous events N_M due to flashes near a structure

 N_M may be evaluated as the product:

$$N_M = N_G \times A_M \times 10^{-6}$$

where

 $[flashes/km^2/year]N_G$ is the lightning ground flash density

 A_M is the collection area of flashes striking near the structure $[m^2]$

The collection A_M extends to a line located at a distance of 500 m from the perimeter of the structure:

$$A_M = 2 \times 500 \times (L+W) + \pi \times 500^2$$

where length L and width W of the structure are expressed in meter. Therefore the A_M and N_M will be leaded as follows:

 $A_M = 2 \times 500 \times (0.95 + 0.95) + \pi \times 500^2 = 787298.16$ $N_M = 16.8 \times 787298.16 \times 10^{-6} = 13.227$

2.2.2.3. Assessment of the average annual number of dangerous events N_L due to flashes to a line

 $N_L = N_G \times A_L \times C_I \times C_E \times C_T \times 10^{-6}$ Therefor $C_I = 1$, $C_T = 1$, $C_E = 0.01$, $A_L = 2000$ for CWRP condition, $N_L = 3.36 \times 10^{-4}$

2.2.2.4. Assessment of the average annual number of dangerous events N_I due to flashes near a line $N_I = N_0 \times A_1 \times C_1 \times C_2 \times C_2 \times 10^{-6}$

 $N_I = N_G \times A_I \times C_I \times C_E \times C_T \times 10^{-6}$ Therefor $C_I = 1$, $C_T = 1$, $C_E = 0.01$, $A_I = 200000$ for CWRP condition, $N_L = 3.36 \times 10^{-2}$

2.2.3. Assessment of probability P_X of damage

The probabilities are given in the Annex B of IEC 62305-2. Based on practical condition, the values are shown in the Table A-2.

· · · · · · · · · · · · · · · · · · ·	-) A		J				· · · · ·
Characteristics of structure	LPL	P _B	P _C	P _M	P_V	P_W	P_{Z}
No protection device		1	1	1	1	1	1
	IV	0.2	0.05	1.04 x 10 ⁻⁵	0.05	0.05	0.05
Protected by	- 111	0.1	0.05	1.04 x 10 ⁻⁵	0.05	0.05	0.05
required components		0.05	0.02	4.15 x 10 ⁻⁶	0.02	0.02	0.02
		0.02	0.01	2.07 x 10 ⁻⁶	0.01	0.01	0.01

Table A-2: Values of probability P_X depending on the protection measures to reduce physical damage

2.2.4. Assessment of amount of loss L_X

The values of amount of loss L_X should be evaluated and fixed by the lightning protection designer (or the owner of the structure). The typical mean values of loss L_X in a structure given in the Annex C of IEC 62305-2 are merely values proposed by the IEC.

The loss L_X refers to the mean relative amount of a particular type of damage for one dangerous event caused by a lightning flash, considering both its extent and effects. The loss value L_X varies the type of loss considered the weather radar will be classified to L2 and L4.

Table A-3: Type of loss L2 and L4: Loss v	alues for each type of damage
---	-------------------------------

	Type of damage			
Loss	D2	D3		
L2	$L_B = L_V = r_p \times r_f \times L_F \times n_z / n_t$	$L_C = L_M = L_W = L_Z = L_O \times n_z / n_t$		
L4	$L_B = L_V = r_p \times r_f \times L_F \times (c_a + c_b + c_c + c_s) \times c_t$	$L_C = L_M = L_W = L_Z = L_O \times c_s / c_t$		

where

 L_o is the typical mean relative value of all goods damaged by failure of internal systems (D3) due to one dangerous event. It will be 10^{-2} for structures of hospital, industrial, office, hotel and commercial.

 L_F is the typical mean relative value of all goods damaged by physical damage (D2) due to one dangerous event. It will be 0.5 for structures of hospital, industrial, museum and agricultural.

 r_f is the factor reducing the loss due to physical damage depending on the risk of fire. It will be 0 for the weather radar.

Finally, we can get the values as follows:

$$L_B = L_V = 0$$

 $L_C = L_M = L_W = L_Z = 10^{-2}$

2.3. Risk Assessment Conclusion

Values of the risk components for the unprotected structure are reported in the regulation.

The public service loss (L2) and the economic loss (L4) are relevant for this type of structure. It is required to evaluate the need for protection. This implies the determination of the risk R_2 for L2 and risk R_4 for L4 with the risk components R_B , R_C , R_M , R_V , R_W and R_Z and to compare it with the tolerable risk $R_T = 10^{-3}$. Suitable protection measures will be selected to reduce the risk to or below the tolerable risk.

According to the IEC 62305-2, calculation of the risk parameters is shown as follows:

Table A-4 [•] Risk com	ponents for different ty	nes of damage and	source of damage	(IEC 62305-2)
	ponents for unreferring	pes of damage and	Source of duringe	

Domogo	Source of damage				
Damage	S1 S2 S3 S4				
D2	$R_B = N_D \times P_B \times L_B$		$R_V = \left(N_L + N_{DJ}\right) \times P_V \times L_V$		
D3	$R_C = N_D \times P_C \times L_C$	$R_M = N_M \times P_M \times L_M$	$R_W = \left(N_L + N_{DJ}\right) \times P_W \times L_W$	$R_Z = N_I \times P_Z \times L_Z$	

Calculation of the risk components requirement is as shown in the Table A-5.

Input parameter	Symbol	Value
Ground flash density [1/km ² /year]	N _G	16.8
	N _D	2.709 x 10 ⁻³
	N _{DI}	0
Number of over voltages [1/year]	N _M	13.227
	N_L	3.36 x 10 ⁻⁴
	N _I	3.36 x 10 ⁻²
Structure dimensions [m]	L, W, H	0.95, 0.95, 3.177
Location factor of structure	Cn	0.5

Table A-5: Weather radar at CWRP: Environment and structure characteristics

Use the エラー! 参照元が見つかりません。A-4 and the Table A-5, risk assessment result will be calculated. The result is shown in the Table A-6. Therefore considering current condition, the weather radar is not protected by existing lightning rods. Total risk value is exceeded of the tolerable risk value.

We'll propose solution for this later, protecting the radar by additional lightning rod and adapt LPL Class IV. Assessment for this solution is also shown in the Table A-6. According to the result is almost half of the tolerable risk value, so the condition of the radar turned into safe.

Type of damage	Symbol	Current Condition	Protected by LPL IV
D2: Physical Damage	R_B	0	0
D2. Physical Damage	R_V	0	0
	R _C	0.01	0.0005
D3 failure of	R _M	0.1323	1.37 x 10 ⁻⁶
internal systems	R _W	3.36 x 10 ⁻⁶	1.68 x 10⁻ ⁷
	R _Z	3.36 x 10 ⁻⁴	1.68 x 10⁻⁵
Total		0.134	0.00052
Tolerable $R_T = 0.001$		NG	Safety

Table A-6: Risk assessment result at CWRP

3. Solution: Ways to make a current installation safer

Lightning protection level definition

Lightning protection level (LPL) is defined in the regulation based on peak current. LPL will be selected for installation situations where LPL IV is generally used. Protection area will be made using rolling sphere, its radius is determined in the Table A-7. Example of an actual condition is shown in the Figure A-3.

LPL	Probability for min value	Minimum peak current [kA]	Probability for max value	Minimum peak current [kA]	Rolling sphere radius [m]
	0.99	3	0.99	200	20
Π	0.97	5	0.98	150	30
	0.91	10	0.95	100	45
IV	0.84	16	0.95	100	60

Figure A-3: Protection of aerials and other external equipment (IEC 62305-4)

3.2. Modification Plan

As shown in Table A-6 the current condition is not enough to protect the weather radar. We would propose the following modification plan to protect the weather radar.

3.2.1. Extend existing lightning rod

We installed new lightning rod to protect the radar, but it is insufficient due to some restrictions. Now we are considering how to adapt the LPL by extending the lightning rod.

As shown in Table 8 we need to extend the rod at least 5.1 m from the current length, but it is not allowed due to site height restrictions.

3.2.2. Add extra lightning rod

This is an example of adding a lightning rod to compensate for existing lightning rod limitations:

It is installed next to a chimney, 8 meters away from the radar. In this case the chimney is fixed, therefore it is better to install a new lightning rod as shown in Figure A-4.

The weather radar will be properly covered by the combination of new and existing lightning rods.

The height requirement for the new lightning rod for each LPL is shown in Table A-9. The length will be selected depending on the height limitation, therefore it is better to use a longer one.

Unfortunately in this case it is not enough for protecting the weather radar from lightning.

In order to provide a solution for this situation we suggest adding a new lightning rod installed nearby.

Basically a newly prepared rod should be designed as long as possible, but it needs to be within the height limitation.

Figure A-4: Drawing at rooftop and candidate place to install the new lightning rod

Table A-9: Height requirement for the new lightning rod

4. Protection of Structures Against Lightning

4.1. Old lightning and angle of protection standard

Old standard stated the protection angle of lightning rods for protecting of people from lightning, electrical facilities, petroleum complexes, gas tanks, plant, and equipment was 60° or less for general buildings. Factory handling hazardous materials such as explosives, flammable gas, liquids, and etc., would be slightly narrower as 45°. Because these specifications were old they did not take height in consideration. Also the protection area was too large and therefore not safe enough even within the protection angle.

The basic data of this standard was created using results of an experiment that tested using an artificial lightning generation apparatus. Since the electrical discharge size generated was too small when compared to actual lightning, it was found that the experiment data results varied from actual lightning observation.

Figure A-5: Protection range α: Protected angle

4.2. New standard lightning and angle of protection

Lightning rod height and protection efficiencies were revised when IEC standards were renewed in 2003, replacing the older 1990 standard. The angle of protection decreases as the height of protected structure gets higher. Any protection level of structure over 60 meters will not be enacted in the protection angle because a lightning rod is ineffective for buildings over 60 meters when a side-on lighting strike hits side of a building.

Protection	Protection	Rolling sphere method	Protection angle method (height: h)	Mesh method
level	eniciency	Radius(m)		(m)
I	0.98	20		5
11	0.95	30	See Figure 6 below	10
III	0.9	45		15
IV	0.8	60		20

*: Applicable only to rolling sphere and mesh methods.

IEC 2646/10

Figure A-6: Protection angle corresponding to the class of LPS (IEC62305-3)

R R Protected structure GL Envelope range

Figure A-7: Lightning rod angle of protection at protection level IV (Protection efficiency 0.80)

Figure A-8: Protective range of rolling sphere method

5. Conclusion

For some installations it is difficult to add a tall lightning rod because of area height regulations and restrictions. It may be necessary to carefully consider all potential lightning protection solutions.

B. COMMUNICATION NETWORK

Radar needs an internet connection to provide remote maintenance service, main operation, and transfer of collected observation data.

There are several types of communication network in the world. Only the following types are fast enough to support proper radar operations.

- 1) Cable (Broadband Internet Connection): Through the use of a cable modem you can have a broadband Internet connection that is designed to operate over cable TV lines. Cable Internet works by using TV channel space for data transmission, with certain channels used for downstream transmission, and other channels for upstream transmission. Because the coaxial cable used by cable TV provides much greater bandwidth than telephone lines, a cable modem can be used to achieve extremely fast access. Cable providers typically implement a cap to limit capacity and accommodate more customers. Cable speeds range is approx. 512 Kbps to 20 Mbps.
- 2) Wireless Internet Connections: or wireless broadband is one of the newest Internet connection types. Instead of using telephone or cable networks for your Internet connection, you use radio frequency bands. Wireless Internet provides an always-on connection which can be accessed from anywhere — as long as you geographically within a network coverage area. Wireless access is still considered to be relatively new, and it may be difficult to find a wireless service provider in some areas. It is typically more expensive and mainly available in metropolitan areas.
- 3) T (Tier / Transmission System) -1 Line (Lease Line): A popular leased line option for businesses connecting to the Internet and for Internet Service Providers (ISPs) connecting to the Internet backbone. It is a dedicated phone connection supporting data rates of 1.544Mbps. A T-1 line actually consists of 24 individual channels, each of which supports 64Kbits per second. Each 64Kbit/second channel can be configured to carry voice or data traffic. Most telephone companies allow you to buy just one or some of these individual channels. This is known as fractional T-1access. T-1 Lines support speeds of 1.544 Mbps. Fractional T-1 speeds are 64 Kbps per channel (up to 1.544 Mbps), depending on number of leased channels. T-1 standards is basically use in ANSI, Northern America. There is a similar type (actually consists of 30 individual channels, each of which supports 64Kbps (up to 2.048Mbps)) in Europe called E-1 Line.
- 4) Bonded T-1: Two or more T-1 lines that have been joined (bonded) together to increase bandwidth. Where a single T-1 provides approximately 1.5Mbps, two bonded T1s provide 3Mbps or 46 channels for voice or data. Two bonded T-1s allow you to use the full bandwidth of 3Mbps where two individual T-1s can still only use a maximum of 1.5Mbps at one time. To be bonded the T-1 must run into the same router at the end, meaning they must run to the same ISP. Typical Bonded T-1 (two bonded T-1 lines) speed is around 3 Mbps.
- 5) T-3 Lines (Dedicated Lease Line): Dedicated phone connections supporting data rates of about 43 to 45 Mbps. It too is a popular leased line option. A T-3 line actually consists of 672 individual channels, each of which supports 64 Kbps. T-3 lines are used mainly by Internet Service Providers (ISPs) connecting to the Internet backbone and for the backbone itself. A typical T-3 support speeds ranging is approx. 43 to 45 Mbps. T-3 is a bigger, faster, more expensive version of T1. It can get up to 44Mbitps upload and download speeds. It is great for medium/large businesses, as it provides a good deal of bandwidth. T2, T4, T5 all exist as well, with the higher numbers being faster, however T1 and T3 are the more common ones. T-3 standards is basically use in ANSI, Northern America. There is a similar type (16 individual channels (34.368Mbps/480 channel)) in Europe called E-3 Line.
- 6) OC3 (Optical Carrier): Short for Optical Carrier, level 3 it is used to specify the speed of fiber optic networks conforming to the SONET standard. OC3 is typically used as a fiber optic backbone for large networks with large voice, data, video, and traffic needs. Speeds are 155.52 Mbps, or roughly the speed of 100 T1 lines.

- 7) IoS (Internet over Satellite): It allows a user to access the Internet via a satellite that orbits the earth. A satellite is placed at a static point above the earth's surface, in a fixed position. Because of the enormous distances signals must travel from the earth up to the satellite and back again, IoS is slightly slower than high-speed terrestrial connections over copper or fiber optic cables. Typical Internet over satellite connection speeds (standard IP services) average around 492 up to 512 Kbps.
- 8) Fiber Optic Network: The fastest way to access the Internet, but it's also the most expensive. Fiber converts electrical signals to light which travels through tiny glass filaments. Transmission speeds vary greatly depending on several factors, including the distance between the transmitting location and the receiving location, the amount of bandwidth allotted by the Internet service provider, and use of the fiber-optic lines for other services. The FCC says that most modern fiber connections transmit at speeds of tens to hundreds of Mbps faster than other broadband options

Summary:

We recommend you to use the fiber optical network or any faster network for transferring the weather observation data to the data center server or office. If the radar location does not have access to any fast network (up/download minimum 8 Mbps constantly) but can connect to a wireless network then use the internet just for remote operation and save the data to an external HDD. A 6TB HDD can save up to 6 months of data depending on observation settings without requiring network transfer.

In addition there are ISP's (Internet Service Provider) that may make a separate contract to provide internet access with a suitable communication network (DSL, wireless, fiber optic network, etc.).

A LAN (Local Area Network) setting must be made for using internet access on DPU. First it requires an IP (Internet Protocol) address setup in DPU. An IP address is basically a numerical form address that identifies the location of DPU device. This is similar to a home address. It is 4 sets of numbers between 0 and 255 (these represent 8 bits or 8 ones and zeros).

In order for a device to send information on a local area network when connected to the same switch it needs a "private" IP address. These usually fall within the 192.168.X.X or 10.X.X.X realm. X represents a number between 0 and 255.

Once it reaches the Internet via a router it needs to have a "unique" IP address called a "public" IP. This is given by an Internet Service Provider. Every computer has its own unique number which cannot be duplicated on the Internet. Any traffic for this IP address will be routed to it.

Computers need their own numbers. However there is no way to remember the IP of all websites. To help DNS was created. DNS is the Domain Name System and it translates the web address into an actual "public" IP. It can be displayed by using the command prompt (start > run > type cmd.exe) and type "ping" for the web address. At first there is a pause while DNS translates the IP and then it will display the ping as the unique IP address number formatted as xxx.xxx.xxx which is specific to the web address's web server.

Class	Start	End	Subnet mask	No. of addresses
А	10.0.0.0	10.255.255.255	255.0.0.0	16,777,216
В	172.16.0.0	172.1.255.255	255.240.0.0	1,048,576
С	192.168.0.0	192.168.255.255	255.255.0.0	65,536

The SPU system is using IPv4: 192.168.1.55 and it is using the private address inside LAN.

It also must setup the Subnetwork and Subnet mask. Address space of subnetwork is indicated by subnet mask. Ex. Subnet mask is 255.255.255.0, which supports 254 addresses. Regarding IP address, 0 indicates the network itself, 255 is a broadcast address. In this case it can use xxx.xxx.xxx.1 to xxx.xxx.254

When choosing LAN cable it is important to note use of Category of Ethernet cables, Cat. 5e (enhanced category 5) or better quality is required. Larger category numbers have better shielding. General uses and easy to purchase cables are unshielded and called UTP (unshielded twist pair) **Note:** STP (shielded twist pair) is required which is same as marine products. Maximum length of about 50 meters between switch and device is best to keep consistent data transfer. For LAN cable lengths longer than 50 meters, fiber optic cable with media converters should be used.

Check the marking on cables to ensure compatibility

C. STORAGE MEDIA

Hard Disk Drive (HDD) uses several types of connecting interfaces. If using an external HDD for saving observed data it should use USB 3.0 or faster interface because of large data files. Transfer speed of USB2.0 is 480Mbps, and USB3.0 is 4Gbps.

Standard USB have 2 types:

USB2.0 (High Speed)	CERTIFIED USE	
USB3.0 (SuperSpeed) USB3.1 (SuperSpeed)		

Although not standardized generally insulator color of USB 3.0 is blue, and USB 3.1 is teal blue.

D. UPS SETTING

Try to prepare a high function UPS to avoid PC data loss during power outages and immediate shutdown that damage the internal circuitry of the PC mainly hard disk. There is a function to send a command to shut down the PC before run out of UPS battery. Reference information of setting UPS is shown below. (It describes from APC Smart-UPS 1500RM model)

General	Power Parameters	High Transfer [V]	265	
		Low Transfer [V]	196	
		Sensitivity	High	
		Nominal Output [V]	220	
		Audible Warning	On Battery	
Server	Shutdown	Command File	Not Enabled	
Shutdown	Sequence	Operating System	Delay [mins]	00:00
			Duration [mins]	01:30
	Power Failure	When power fails, begin a shutdown procedure	At runtime limit	
		When power returns, reboot UPS	After the following occurs	Battery charges to 0% And the elapsed time is: 60sec
		Shutdown Type	Shutdown	

Note: Rest of the above settings would be default settings.

E. TEAMVIEWER (Remote control management tool)

NOTE: This software is the place allows using remote control via internet. If your facility is prohibited of using it, please uninstall this software. Furthermore, TeamViewer may behave as unauthorized access.

1. Installation

- 1. Download the software of TeamViewer "**Host**" (For remote server) from the following web site: <u>https://www.teamviewer.com/ja/download/</u>
- 2. Double click "TeamViewer_Host_Setup.exe" to install the software.
- **Note:** Operator who wants to access by remote to the host TeamViewer must need the local TeamViewer with the same or newer version. Moreover, the host software must be installed version 12 or newer.
 - (1) Double click the icon

(3) Select "company / commercial use", and then click [Next]

(5) Make password and computer name Password: rmsrms (enter this password) Computer name: Enter location's name and then click [Exit]

(4) Check on "License Agreement", and then click [Next]

(6) "Your ID" will be issued automatically. (* Remember this ID) And then click [OK]

- 3. After installed software, please inform "Your ID" to the headquarter of Furuno who is in charge.
- 4. Use other DPU to confirm remote access by TeamViewer.

S2E-17-0209_IM_WR2120_C

2. Uninstallation

- 1) Change the login user to the "Control" account. (See the password from APPENDIX A.2. in the operator's manual)
- 2) If TeamViewer icon is in the task bar, click "Exit Teamviewer" to close the software.
- 3) From the Start Menu, select Control Panel.
- 4) Under Programs click the Uninstall a Program link.
- 5) Select the program (TeamViewer) to remove and right click then select Uninstall/Change.
- 6) Follow the prompts to finish the uninstallation of the software.

Show status dialog
Options
Add to Computers & Contacts
Activate license
Check for license updates
Open log files
TeamViewer website
About TeamViewer
Check for new version
Exit TeamViewer

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