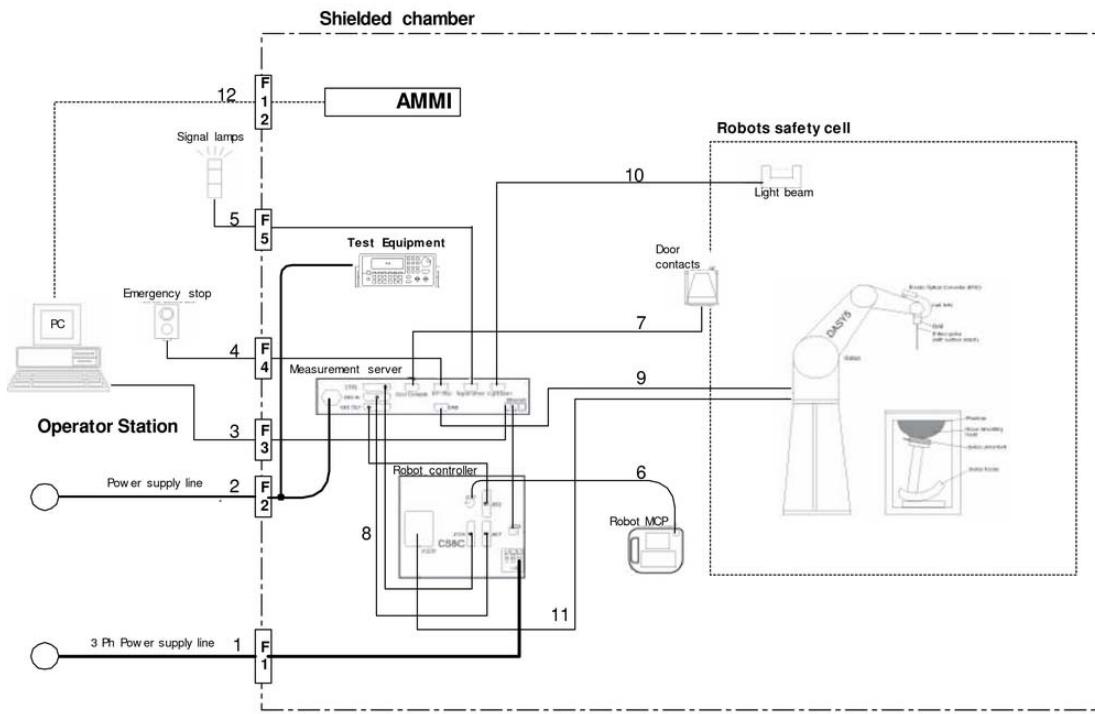


APPENDIX 3 : System specifications

1. Configuration and peripherals



The DASY5 system for performing compliance tests consist of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller and software.
An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronic (DAE), which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection.
The EOC is connected to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY5 software.
- Remote control with teaches pendant and additional circuitry for robot safety such as warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

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2. Specifications

a)Robot TX60L

Number of Axes	:	6
Nominal Load	:	2 kg
Maximum Load	:	5kg
Reach	:	920mm
Repeatability	:	+/-0.03mm
Control Unit	:	CS8c
Programming Language	:	VAL3
Weight	:	52.2kg
Manufacture	:	Stäubli Robotics

b)E-Field Probe

Model	:	EX3DV3
Serial No.	:	3507
Construction	:	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycol ether)
Frequency	:	10 MHz to > 6 GHz Linearity: ± 0.2 dB (30 MHz to 6 GHz)
Directivity	:	+/-0.3 dB in HSL (rotation around probe axis) +/-0.5 dB in tissue material (rotation normal probe axis)
Dynamic Range	:	10uW/g to > 100 mW/g; Linearity +/-0.2 dB(noise: typically < 1uW/g)
Dimensions	:	Overall length: 337 mm (Tip: 20 mm) Tip diameter: 2.5mm (Body: 12 mm)
Application	:	Typical distance from probe tip to dipole centers: 1 mm Highprecision dosimetric measurement in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6GHz with precision of better 30%.
Manufacture	:	Schimid & Partner Engineering AG



EX3DV3 E-field Probe

c)Data Acquisition Electronic (DAE4)

Features	:	Signal amplifier, multiplexer, A/D converter and control logic Serial optical link for communication with DASY5 embedded system (fully remote controlled) Two step probe touch detector for mechanical surface detection and emergency robot stop
Measurement Range	:	-100 to +300 mV (16 bit resolution and two range settings: 4mV, 400mV)
Input Offset voltage	:	< 5 µV (with auto zero)
Input Resistance	:	200 MΩ
Input Bias Current	:	< 50 fA
Battery Power	:	> 10 h of operation (with two 9.6 V NiMH accus)
Dimension	:	60 x 60 x 68 mm
Manufacture	:	Schimid & Partner Engineering AG

d)Electro-Optic Converter (EOC)

Version	:	EOC 61
Description	:	for TX60 robot arm, including proximity sensor
Manufacture	:	Schimid & Partner Engineering AG

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e)DASY5 Measurement server

Features : Intel ULV Celeron 400MHz
 128MB chip disk and 128MB RAM
 16 Bit A/D converter for surface detection system
 Vacuum Fluorescent Display
 Robot Interface
 Serial link to DAE (with watchdog supervision)
 Door contact port (Possibility to connect a light curtain)
 Emergency stop port (to connect the remote control)
 Signal lamps port
 Light beam port
 Three Ethernet connection ports
 Two USB 2.0 Ports
 Two serial links
 Expansion port for future applications

Dimensions (L x W x H) : 440 x 241 x 89 mm
Manufacture : Schimid & Partner Engineering AG

f) Light Beam Switches

Version : LB5
Dimensions (L x H) : 110 x 80 mm
Thickness : 12 mm
Beam-length : 80 mm
Manufacture : Schimid & Partner Engineering AG

g)Software

Item : Dosimetric Assesment System DASY5
Type No. : SD 000 401A, SD 000 402A
Software version No. : DASY52, Version 52.6 (1)
Manufacture / Origin : Schimid & Partner Engineering AG

h)Robot Controll Unit

Weight : 70 Kg
AC Input Voltage : selectable
Manufacturer : Stäubli Robotics

i) Phantom and Device Holder

Phantom

Type	:	SAM Twin Phantom V4.0
Description	:	The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528 and IEC 62209-1. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by teaching three points with the robot.
Material	:	Vinylester, glass fiber reinforced (VE-GF)
Shell Material	:	Fiberglass
Thickness	:	2.0 +/-0.2 mm
Dimensions	:	Length: 1000 mm Width: 500 mm Height: adjustable feet
Volume	:	Approx. 25 liters
Manufacture	:	Schimid & Partner Engineering AG
 Type	 :	 2mm Flat phantom ELI4.0
Description	:	Phantom for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with the latest draft of the standard IEC 62209 Part II and all known tissue simulating liquids. ELI4 has been optimized regarding its performance and can be integrated into our standard phantom tables. A cover prevents evaporation of the liquid. Reference markings on the phantom allow installation of the complete setup, including all predefined phantom positions and measurement grids, by teaching three points. The phantom is supported by software version DASY4.5 and higher and is compatible with all SPEAG dosimetric probes and dipoles.
Material	:	Vinylester, glass fiber reinforced (VE-GF)
Shell Thickness	:	2.0 +/-0.2 mm (sagging: <1%)
Filling Volume	:	approx. 30 liters
Dimensions	:	Major ellipse axis: 600 mm Minor axis: 400 mm
Manufacture	:	Schimid & Partner Engineering AG

Device Holder

In combination with the Twin SAM Phantom V4.0/V4.0c or ELI4, the Mounting Device enables the rotation of the mounted transmitter device in spherical coordinates. Rotation point is the ear opening point. Transmitter devices can be easily and accurately positioned according to IEC, IEEE, FCC or other specifications. The device holder can be locked for positioning at different phantom sections (left head, right head, flat).

Material	:	POM
-----------------	---	-----

Laptop Extensions kit

Simple but effective and easy-to-use extension for Mounting Device that facilitates the testing of larger devices according to IEC 62209-2 (e.g., laptops, cameras, etc.). It is lightweight and fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM, ELI4 Phantoms.

Material	:	POM, Acrylic glass, Foam
-----------------	---	--------------------------

Urethane

For this measurement, the urethane foam was used as device holder.

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i) Simulated Tissues (Liquid)

The following tissue formulations are provided for reference only as some of the parameters have not been thoroughly verified. The composition of ingredients may be modified accordingly to achieve the desired target tissue parameters required for required for routine SAR evaluation.

Mixture (%)	Frequency (MHz)									
	450		900		1800		1950		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	38.91	46.21	40.29	50.75	55.24	70.17	55.41	69.79	55.0	68.64
Sugar	56.93	51.17	57.90	48.21	-	-	-	-	-	-
Cellulose	0.25	0.18	0.24	0.00	-	-	-	-	-	-
Salt (NaCl)	3.79	2.34	1.39	0.94	0.31	0.39	0.08	0.2	-	-
Preventol	0.12	0.08	0.18	0.10	-	-	-	-	-	-
DGMBE	-	-	-	-	44.45	29.44	44.51	30.0	45.0	31.37
Dielectric Constant	43.42	58.0	42.54	56.1	42.0	56.8	39.9	54.0	39.8	52.5
Conductivity (S/m)	0.85	0.83	0.91	0.95	1.0	1.07	1.42	1.45	1.88	1.78

Note:DGMBE(Diethylenglycol-monobutyl ether)

Mixture (%)	Frequency(MHz)	
	5800	
Tissue Type	Head	Body
Water	64.0	78.0
Mineral Oil	18.0	11.0
Emulsifiers	15.0	9.0
Additives and salt	3.0	2.0

Decision on Simulated Tissues of 5GHz band

In the current standards (e.g., IEC62209-2, IEEE P1528, OET 65 Supplement C), the dielectric parameters suggested for head and body tissue simulating liquid are given at 3000MHz and 5800MHz. As an intermediate solution, dielectric parameters for the frequencies between 5000to 5800 MHz were obtained using linear interpolation.

Therefore the dielectric parameters of 5200MHz,5300MHz,5600MHz and 5500MHz(The frequency for the validation) were decided as following.

f (MHz)	Head Tissue		Body Tissue		Reference
	ϵ_r	σ [mho/m]	ϵ_r	σ [mho/m]	
3000	38.5	2.40	52.0	2.73	Standard
5800	35.3	5.27	48.2	6.00	Standard
5000	36.2	4.45	49.3	5.07	Interpolated
5100	36.1	4.55	49.1	5.18	Interpolated
5200	36.0	4.66	49.0	5.30	Interpolated
5300	35.9	4.76	48.9	5.42	Interpolated
5400	35.8	4.86	48.7	5.53	Interpolated
5500	35.6	4.96	48.6	5.65	Interpolated
5600	35.5	5.07	48.5	5.77	Interpolated
5700	35.4	5.17	48.3	5.88	Interpolated

Standard and interpolated dielectric parameters for head and body tissue simulating liquid in the frequency range 3000 to 5800MHz.

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3. Dosimetric E-Field Probe Calibration (EX3DV4,S/N: 3540)

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 Schmid & Partner
 Engineering AG
 Zeughausstrasse 43, 8004 Zurich, Switzerland



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Accreditation No.: SCS 108

Client

PTT

Certificate No: EX3-3540_Jul11

CALIBRATION CERTIFICATE

Object	EX3DV4 - SN:3540		
Calibration procedure(s)	QA CAL-01.v8, QA CAL-12.v7, QA CAL-14.v3, QA CAL-23.v4, QA CAL-25.v4 Calibration procedure for dosimetric E-field probes		
Calibration date:	July 21, 2011		
<p>This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.</p> <p>All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.</p> <p>Calibration Equipment used (M&TE critical for calibration)</p>			
Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	31-Mar-11 (No. 217-01372)	Apr-12
Power sensor E4412A	MY41498097	31-Mar-11 (No. 217-01372)	Apr-12
Reference 3 dB Attenuator	SN: S5054 (3d)	29-Mar-11 (No. 217-01369)	Apr-12
Reference 20 dB Attenuator	SN: S5086 (20b)	29-Mar-11 (No. 217-01367)	Apr-12
Reference 30 dB Attenuator	SN: S5129 (30b)	29-Mar-11 (No. 217-01370)	Apr-12
Reference Probe ES3DV2	SN: 3013	28-Dec-10 (No. ES3-3013_Dec10)	Dec-11
DAE4	SN: 654	3-May-11 (No. DAE4-654_May11)	May-12
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8848C	US3642U01700	4-Aug-09 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	UG37390585	18-Oct-01 (in house check Oct-10)	In house check: Oct-11
Calibrated by:	Name	Function	Signature
	Katja Pekovic	Technical Manager	
Approved by:	Name	Function	Signature
	Niels Kuster	Quality Manager	

Issued: July 21, 2011

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: EX3-3540_Jul11

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Accreditation No.: SCS 108

Glossary:

TSL	tissue simulating liquid
NORM _{x,y,z}	sensitivity in free space
ConvF	sensitivity in TSL / NORM _{x,y,z}
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\theta = 0$ is normal to probe axis

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- $NORM_{x,y,z}$: Assessed for E-field polarization $\theta = 0$ ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide). $NORM_{x,y,z}$ are only intermediate values, i.e., the uncertainties of $NORM_{x,y,z}$ does not affect the E^2 -field uncertainty inside TSL (see below ConvF).
- $NORM(\theta)x,y,z = NORM_{x,y,z} * frequency_response$ (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- $DCP_{x,y,z}$: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR : PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- $A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}$: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters*: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800$ MHz) and inside waveguide using analytical field distributions based on power measurements for $f > 800$ MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to $NORM_{x,y,z} * ConvF$ whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical Isotropy (3D deviation from isotropy)*: In a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

EX3DV4 – SN:3540

July 21, 2011

Probe EX3DV4

SN:3540

Manufactured: August 23, 2005
Calibrated: July 21, 2011

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

EX3DV4- SN:3540

July 21, 2011

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3540**Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu\text{V}/(\text{V}/\text{m})^2$) ^A	0.45	0.53	0.54	$\pm 10.1\%$
DCP (mV) ^B	100.9	101.2	99.2	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc ^E (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	139.8	$\pm 2.2\%$
			Y	0.00	0.00	1.00	119.0	
			Z	0.00	0.00	1.00	112.5	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A The uncertainties of NormX,Y,Z do not affect the E²-field uncertainty inside TSL (see Pages 5 and 6).

^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

EX3DV4- SN:3540

July 21, 2011

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3540**Calibration Parameter Determined in Head Tissue Simulating Media**

f (MHz) ^c	Relative Permittivity ^f	Conductivity (S/m) ^f	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
300	45.3	0.87	11.39	11.39	11.39	0.20	0.71	± 13.4 %
450	43.5	0.87	10.47	10.47	10.47	0.12	1.87	± 13.4 %
835	41.5	0.90	10.02	10.02	10.02	0.60	0.73	± 12.0 %
900	41.5	0.97	9.62	9.82	9.82	0.57	0.77	± 12.0 %
1450	40.5	1.20	9.81	9.81	9.81	0.36	1.13	± 12.0 %
1640	40.3	1.29	9.35	9.35	9.35	0.69	0.60	± 12.0 %
1750	40.1	1.37	9.13	9.13	9.13	0.77	0.55	± 12.0 %
1810	40.0	1.40	8.81	8.81	8.81	0.76	0.55	± 12.0 %
1900	40.0	1.40	8.65	8.65	8.65	0.64	0.62	± 12.0 %
1950	40.0	1.40	8.46	8.46	8.46	0.74	0.56	± 12.0 %
2000	40.0	1.40	8.59	8.59	8.59	0.72	0.56	± 12.0 %
2450	39.2	1.80	7.65	7.65	7.65	0.61	0.62	± 12.0 %
2600	39.0	1.96	7.52	7.52	7.52	0.51	0.72	± 12.0 %
3500	37.9	2.91	7.24	7.24	7.24	0.25	1.20	± 13.1 %
5200	36.0	4.66	4.71	4.71	4.71	0.35	1.85	± 13.1 %
5300	35.9	4.76	4.39	4.39	4.39	0.35	1.85	± 13.1 %
5500	35.6	4.96	4.30	4.30	4.30	0.45	1.85	± 13.1 %
5600	35.5	5.07	4.00	4.00	4.00	0.50	1.85	± 13.1 %
5800	35.3	5.27	4.16	4.16	4.16	0.45	1.85	± 13.1 %

^c Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

^f At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

EX3DV4- SN:3540

July 21, 2011

DASY/EASY - Parameters of Probe: EX3DV4- SN:3540**Calibration Parameter Determined in Body Tissue Simulating Media**

f (MHz) ^c	Relative Permittivity ^f	Conductivity (S/m) ^f	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
300	58.2	0.92	11.11	11.11	11.11	0.17	1.15	± 13.4 %
450	56.7	0.94	11.61	11.61	11.61	0.03	1.00	± 13.4 %
835	55.2	0.97	10.29	10.29	10.29	0.79	0.64	± 12.0 %
900	55.0	1.05	10.05	10.05	10.05	0.67	0.74	± 12.0 %
1450	54.0	1.30	9.02	9.02	9.02	0.56	0.78	± 12.0 %
1640	53.8	1.40	9.11	9.11	9.11	0.68	0.65	± 12.0 %
1750	53.4	1.49	8.21	8.21	8.21	0.76	0.80	± 12.0 %
1810	53.3	1.52	8.00	8.00	8.00	0.70	0.63	± 12.0 %
1900	53.3	1.52	7.95	7.95	7.95	0.58	0.89	± 12.0 %
1950	53.3	1.52	8.27	8.27	8.27	0.70	0.62	± 12.0 %
2000	53.3	1.52	8.19	8.19	8.19	0.60	0.88	± 12.0 %
2450	52.7	1.95	7.64	7.64	7.64	0.80	0.54	± 12.0 %
2600	52.5	2.16	7.51	7.51	7.51	0.80	0.50	± 12.0 %
3500	51.3	3.31	6.56	6.56	6.56	0.20	1.60	± 13.1 %
5200	49.0	5.30	3.94	3.94	3.94	0.55	1.90	± 13.1 %
6300	48.9	5.42	3.59	3.59	3.59	0.55	1.90	± 13.1 %
5500	48.6	5.65	3.56	3.56	3.56	0.58	1.90	± 13.1 %
5800	48.5	5.77	3.26	3.25	3.25	0.60	1.90	± 13.1 %
5800	48.2	6.00	3.40	3.40	3.40	0.60	1.90	± 13.1 %

^c Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

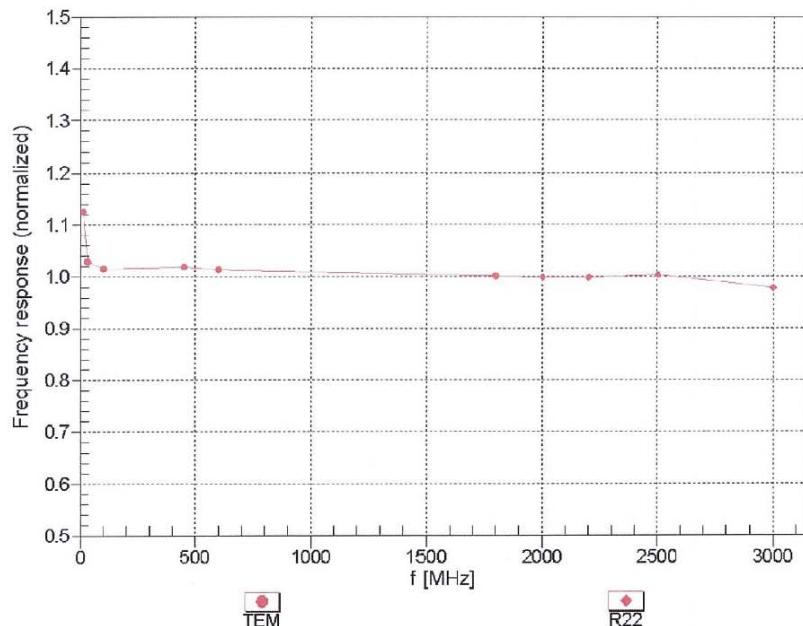
^f At frequencies below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

EX3DV4– SN:3540

July 21, 2011

Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)



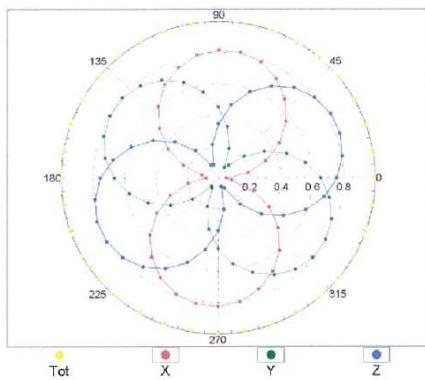
Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

EX3DV4- SN:3540

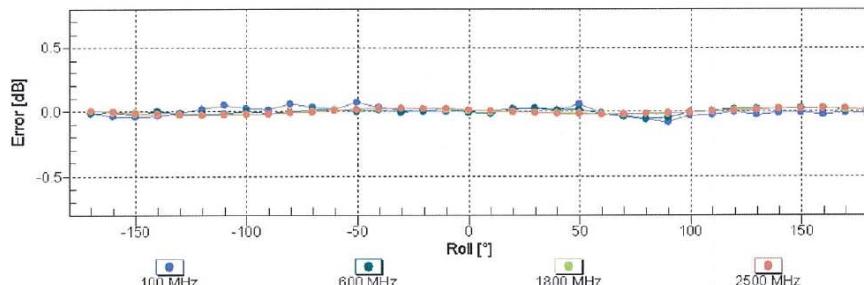
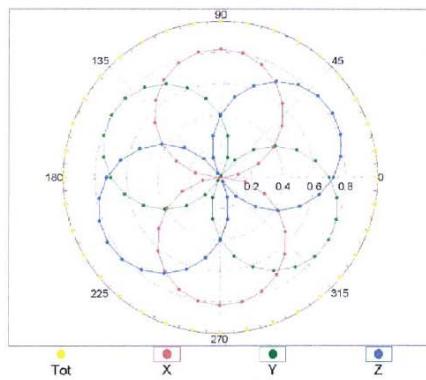
July 21, 2011

Receiving Pattern (ϕ), $\theta = 0^\circ$

f=600 MHz, TEM



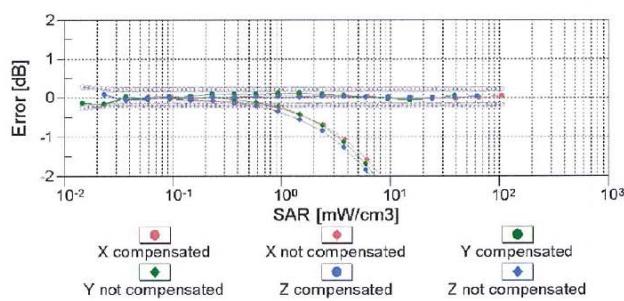
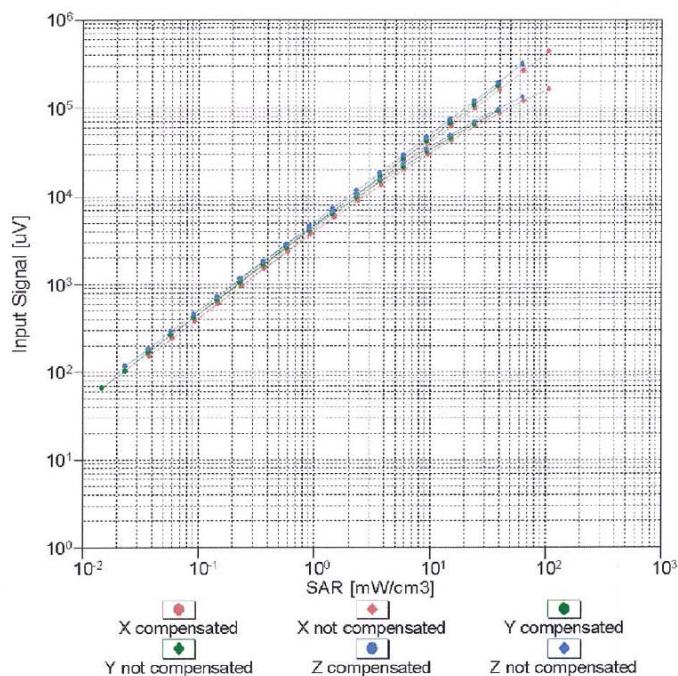
f=1800 MHz, R22

**Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)**

EX3DV4- SN:3540

July 21, 2011

Dynamic Range f(SAR_{head}) (TEM cell, f = 900 MHz)



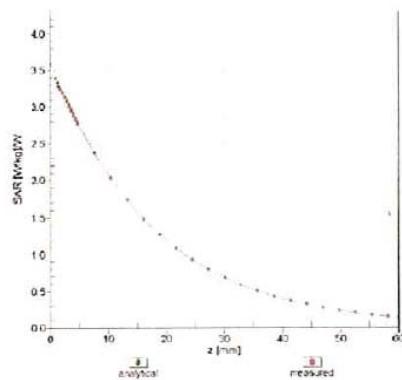
Uncertainty of Linearity Assessment: $\pm 0.6\% (k=2)$

EX3DV4– SN:3540

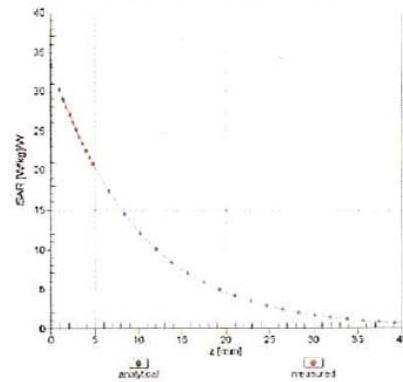
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Conversion Factor Assessment

$f = 900 \text{ MHz}, \text{WGLS R9 (H_convF)}$

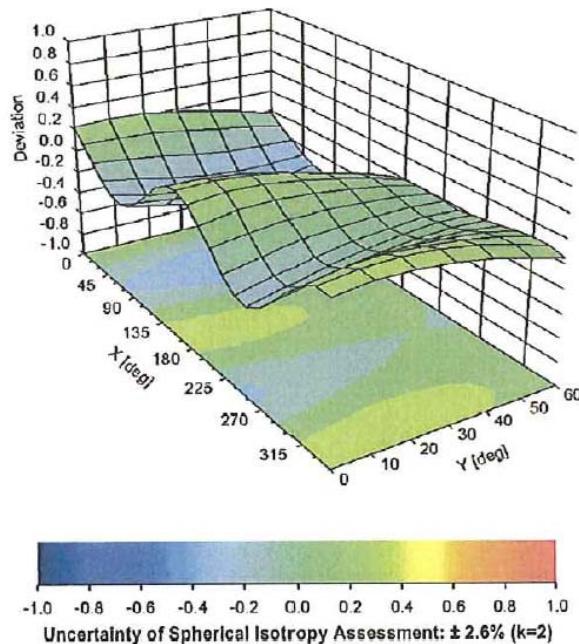


$f = 2450 \text{ MHz}, \text{WGLS R22 (H_convF)}$



Deviation from Isotropy in Liquid

Error (ϕ, θ), $f = 900 \text{ MHz}$



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EX3DV4- SN:3540

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DASY/EASY - Parameters of Probe: EX3DV4 - SN:3540**Other Probe Parameters**

Sensor Arrangement	Triangular
Connector Angle (°)	Not applicable
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	2 mm