

## APPENDIX F: POWER REDUCTION VERIFICATION

Per FCC KDB Publication 616217 D04v01r02, demonstration of proper functioning of the power reduction mechanisms is required to support the corresponding SAR configurations. The verification process was divided into two parts: (1) evaluation of output power levels for individual or multiple triggering mechanisms and (2) evaluation of the triggering distances for proximity-based sensors.

### F.1 Power Verification Procedure

The power verification was performed according to the following procedure:

1. A base station simulator was used to establish a conducted RF connection and the output power was monitored. The power measurements were confirmed to be within expected tolerances for all states before and after a power reduction mechanism was triggered.
2. Step 1 was repeated for all relevant modes and frequency bands for the mechanism being investigated.
3. Steps 1 and 2 were repeated for all individual power reduction mechanisms and combinations thereof. For the combination cases, one mechanism was switched to a 'triggered' state at a time; powers were confirmed to be within tolerances after each additional mechanism was activated.

### F.2 Distance Verification Procedure

The distance verification procedure was performed according to the following procedure:

1. A base station simulator was used to establish an RF connection and to monitor the power levels. The device being tested was placed below the relevant section of the phantom with the relevant side or edge of the device facing toward the phantom.
2. The device was moved toward and away from the phantom to determine the distance at which the mechanism triggers and the output power is reduced, per KDB Publication 616217 D04v01r02 and FCC Guidance. Each applicable test position was evaluated. The distances were confirmed to be the same or larger (more conservative) than the minimum distances provided by the manufacturer. Triggering states within  $\pm 5$  mm of the triggering distance, moving towards and away from the phantom, are tabulated below. The influence of table tilt angles to proximity sensor triggering was also evaluated at the smallest sensor triggering distance by rotating the device the edge next to the phantom in 10 degree increments between  $\pm 45$  degrees.
3. Steps 1 and 2 were repeated for low, mid, high, and ultra-high bands, as appropriate (see first note under section F.3 for more details).
4. Steps 1 through 3 were repeated for all distance-based power reduction mechanisms.

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### F.3 Main Antenna Verification Summary

- Low band refers to: GSM850, UMTS B5, LTE B5/12/13/14/26/71, NR 5/12/26/71; Mid band refers to: GSM1900, UMTS B2/4, LTE B2/4/25/66, NR n25/66/70; High band refers to: LTE B7/30/38/41; Ultra High Band refers to: LTE B48, NR n48/77
- This device uses different Exposure Condition Indices (ECI) to configure different time averaged power levels based on certain exposure scenarios. For this device ECI = 0 is configured when the device's grip sensors are not triggered. ECI = 1 represents the case where the device grip sensors are triggered. ECI = 2 represents the case where grip sensor #3 is triggered for antenna M1.
- Note: Antennas S1 and S3 were not evaluated due to equipment limitations.

**Table F-1  
Power Measurement Verification for Main Antenna M1**

| Mechanism(s) |      | Mode/Band        | Exposure Condition Index (ECI) |                        |                        |
|--------------|------|------------------|--------------------------------|------------------------|------------------------|
| 1st          | 2nd  |                  | Free Space                     | Mechanism #1 (Grip #2) | Mechanism #2 (Grip #3) |
| Grip         |      | Low Band Ant M1  | 0                              | 1                      |                        |
| Grip         | Grip | Mid Band Ant M1  | 0                              | 1                      | 2                      |
| Grip         | Grip | High Band Ant M1 | 0                              | 1                      | 2                      |

**Table F-2  
Power Measurement Verification for Main Antenna M2**

| Mechanism(s) |  | Mode/Band              | Exposure Condition Index (ECI) |                        |
|--------------|--|------------------------|--------------------------------|------------------------|
| 1st          |  |                        | Free Space                     | Mechanism #1 (Grip #6) |
| Grip         |  | Ultra High Band Ant M2 | 0                              | 1                      |

**Table F-3  
Power Measurement Verification for Sub Antenna S2**

| Mechanism(s) |  | Mode/Band        | Exposure Condition Index (ECI) |                        |
|--------------|--|------------------|--------------------------------|------------------------|
| 1st          |  |                  | Free Space                     | Mechanism #1 (Grip #5) |
| Grip         |  | Mid Band Ant S2  | 0                              | 1                      |
| Grip         |  | High Band Ant S2 | 0                              | 1                      |

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**Table F-4  
Power Measurement Verification for Sub Antenna S4**

| Mechanism(s) | Mode/Band              | Exposure Condition Index (ECI) |                        |
|--------------|------------------------|--------------------------------|------------------------|
| 1st          |                        | Free Space                     | Mechanism #1 (Grip #5) |
| Grip         | Ultra High Band Ant S4 | 0                              | 1                      |

**F.4 WIFI Verification Summary**

**Table F-5  
Power Measurement Verification WIFI – Antenna WIFI 0**

| Mechanism(s) | Mode/Band                | Conducted Powers   |                                      |
|--------------|--------------------------|--------------------|--------------------------------------|
| 1st          |                          | Un-triggered (Max) | Mechanism #1 (Grip Sensor #1 Active) |
| Grip         | 802.11b                  | 18.25              | 10.88                                |
| Grip         | 802.11g                  | 17.21              | 11.36                                |
| Grip         | 802.11n (2.4GHz)         | 17.17              | 10.92                                |
| Grip         | 802.11ax (2.4GHz)        | 14.72              | 11.40                                |
| Grip         | 802.11a                  | 15.51              | 6.10                                 |
| Grip         | 802.11n (5GHz, 20MHz BW) | 15.35              | 6.21                                 |
| Grip         | 802.11n (5GHz, 40MHz BW) | 15.64              | 6.55                                 |
| Grip         | 802.11ac (20MHz BW)      | 15.36              | 6.31                                 |
| Grip         | 802.11ac (40MHz BW)      | 14.88              | 6.43                                 |
| Grip         | 802.11ac (80MHz BW)      | 12.39              | 6.30                                 |
| Grip         | 802.11ac (160MHz BW)     | 11.01              | 5.99                                 |
| Grip         | 802.11ax (20MHz BW)      | 9.21               | 6.83                                 |
| Grip         | 802.11ax (40MHz BW)      | 9.32               | 6.77                                 |
| Grip         | 802.11ax (80MHz BW)      | 9.53               | 6.68                                 |
| Grip         | 802.11ax (160MHz BW)     | 9.90               | 6.52                                 |

\*Note: MIMO WIFI modes were not evaluated due to equipment limitations.

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**Table F-6  
Power Measurement Verification for WIFI – Antenna WIFI 1**

| Mechanism(s) | Mode/Band                | Conducted Powers   |                                      |
|--------------|--------------------------|--------------------|--------------------------------------|
| 1st          |                          | Un-triggered (Max) | Mechanism #1 (Grip Sensor #3 Active) |
| Grip         | 802.11b                  | 18.91              | 11.78                                |
| Grip         | 802.11g                  | 17.48              | 11.52                                |
| Grip         | 802.11n (2.4GHz)         | 17.50              | 11.48                                |
| Grip         | 802.11ax (2.4GHz)        | 14.55              | 11.52                                |
| Grip         | 802.11a                  | 15.88              | 6.89                                 |
| Grip         | 802.11n (5GHz, 20MHz BW) | 15.79              | 6.90                                 |
| Grip         | 802.11n (5GHz, 40MHz BW) | 15.15              | 6.33                                 |
| Grip         | 802.11ac (20MHz BW)      | 15.63              | 6.69                                 |
| Grip         | 802.11ac (40MHz BW)      | 13.46              | 7.02                                 |
| Grip         | 802.11ac (80MHz BW)      | 11.52              | 7.20                                 |
| Grip         | 802.11ac (160MHz BW)     | 11.50              | 7.15                                 |
| Grip         | 802.11ax (20MHz BW)      | 9.72               | 7.06                                 |
| Grip         | 802.11ax (40MHz BW)      | 10.36              | 7.34                                 |
| Grip         | 802.11ax (80MHz BW)      | 10.21              | 7.13                                 |
| Grip         | 802.11ax (160MHz BW)     | 10.25              | 7.25                                 |

\*Note: MIMO WIFI modes were not evaluated due to equipment limitations.

## F.5 Distance Verification Summary

**Table F-7  
Distance Measurement Verification for Grip #1**

| GRIP #1       |            |                     |                |             |
|---------------|------------|---------------------|----------------|-------------|
| Test Position | Activation | Distance[Open] (mm) | Moving towards | Moving away |
| <i>Back</i>   | O          | 23                  | <b>23</b>      | <b>34</b>   |
| <i>Top</i>    | O          | 25                  | <b>25</b>      | <b>31</b>   |
| <i>Left</i>   | O          | 16                  | <b>16</b>      | <b>23</b>   |

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**Table F-8  
Distance Measurement Verification for Grip Sensor #2**

| <b>GRIP #2</b>       |                   |                            |                       |                    |
|----------------------|-------------------|----------------------------|-----------------------|--------------------|
| <b>Test Position</b> | <b>Activation</b> | <b>Distance[Open] (mm)</b> | <b>Moving towards</b> | <b>Moving away</b> |
| <i>Back</i>          | 0                 | 22                         | 22                    | 25                 |
| <i>Top</i>           | 0                 | 26                         | 26                    | 31                 |

**Table F-9  
Distance Measurement Verification for Grip Sensor #3**

| <b>GRIP #3</b>       |                   |                            |                       |                    |
|----------------------|-------------------|----------------------------|-----------------------|--------------------|
| <b>Test Position</b> | <b>Activation</b> | <b>Distance[Open] (mm)</b> | <b>Moving towards</b> | <b>Moving away</b> |
| <i>Back</i>          | 0                 | 23                         | 23                    | 34                 |
| <i>Top</i>           | 0                 | 26                         | 26                    | 33                 |
| <i>Right</i>         | 0                 | 16                         | 16                    | 23                 |

**Table F-10  
Distance Measurement Verification for Grip Sensor #4**

| <b>GRIP #4</b>       |                   |                            |                       |                    |
|----------------------|-------------------|----------------------------|-----------------------|--------------------|
| <b>Test Position</b> | <b>Activation</b> | <b>Distance[Open] (mm)</b> | <b>Moving towards</b> | <b>Moving away</b> |
| <i>Back</i>          | 0                 | 26                         | 26                    | 33                 |
| <i>Bottom</i>        | 0                 | 28                         | 28                    | 31                 |
| <i>Right</i>         | 0                 | 16                         | 16                    | 23                 |

**Table F-11  
Distance Measurement Verification for Grip Sensor #5**

| <b>GRIP #5</b>       |                   |                            |                       |                    |
|----------------------|-------------------|----------------------------|-----------------------|--------------------|
| <b>Test Position</b> | <b>Activation</b> | <b>Distance[Open] (mm)</b> | <b>Moving towards</b> | <b>Moving away</b> |
| <i>Back</i>          | 0                 | 26                         | 26                    | 30                 |
| <i>Bottom</i>        | 0                 | 28                         | 28                    | 32                 |

**Table F-12**  
**Distance Measurement Verification for Grip Sensor #6**

| GRIP #6       |            |                     |                |             |
|---------------|------------|---------------------|----------------|-------------|
| Test Position | Activation | Distance[Open] (mm) | Moving towards | Moving away |
| Back          | 0          | 26                  | 26             | 33          |
| Bottom        | 0          | 28                  | 28             | 32          |
| Left          | 0          | 16                  | 16             | 23          |

**Table F-13**  
**Back Side, Moving Toward Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Toward Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |     |     |     |     |
|---|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]   | 31  | 30  | 29  | 28  | 27  | 26  | 25  | 24  | 23  | 22  | 21  | 20  | 19  | 18  | 17  |
| Grip #1   |     |     |     | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |     |
| Grip #2   |     |     |     |     | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |
| Grip #3   |     |     |     | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |     |
| Grip #4   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |     |     |     |     |
| Grip #5   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |     |     |     |     |
| Grip #6   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |     |     |     |     |

**Table F-14**  
**Back Side, Moving Away From Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Away From Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |     |     |     |     |     |     |     |     |     |
|--|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]  | 20  | 21  | 22  | 23  | 24  | 25  | 26  | 27  | 28  | 29  | 30  | 31  | 32  | 33  | 34  | 35  | 36  | 37  | 38  | 39  |
| Grip #1  |     |     |     |     |     |     |     |     |     | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |
| Grip #2  | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |     |     |     |     |     |     |     |     |     |
| Grip #3  |     |     |     |     |     |     |     |     |     | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |
| Grip #4  |     |     |     |     |     |     |     |     |     | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |
| Grip #5  |     |     |     |     | Red | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |     |     |     |     |
| Grip #6  |     |     |     |     |     |     |     |     |     | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |

**Table F-15**  
**Top Edge, Moving Toward Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Toward Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |     |
|---|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]   | 31  | 30  | 29  | 28  | 27  | 26  | 25  | 24  | 23  | 22  | 21  | 20  |
| Grip #1   |     | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |
| Grip #2   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |     |
| Grip #3   |     | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |

**Table F-16**  
**Top Edge, Moving Away From Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Away From Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |     |     |
|--|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]  | 26  | 27  | 28  | 29  | 30  | 31  | 32  | 33  | 34  | 35  | 36  | 37  | 38  |
| Grip #1  | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |     |     |
| Grip #2  | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |     |     |
| Grip #3  |     |     | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |

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**Table F-17**  
**Bottom Edge, Moving Toward Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Toward Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |
|---|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]   | 33  | 32  | 31  | 30  | 29  | 28  | 27  | 26  | 25  | 24  | 23  |
| Grip #4   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |
| Grip #5   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |
| Grip #6   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |

**Table F-18**  
**Bottom Edge, Moving Away From Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Away From Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |     |
|--|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]  | 26  | 27  | 28  | 29  | 30  | 31  | 32  | 33  | 34  | 35  | 36  | 37  |
| Grip #4  | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max | Max |
| Grip #5  | Red | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |
| Grip #6  | Red | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |

**Table F-19**  
**Left Edge, Moving Toward Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Toward Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |
|---|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]   | 21  | 20  | 19  | 18  | 17  | 16  | 15  | 14  | 13  | 12  | 11  |
| Grip #1   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |
| Grip #6   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |

**Table F-20**  
**Left Edge, Moving Away From Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Away From Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |     |
|--|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]  | 17  | 18  | 19  | 20  | 21  | 22  | 23  | 24  | 25  | 26  | 27  | 28  |
| Grip #1  | Red | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |
| Grip #6  | Red | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |

**Table F-21**  
**Right Edge, Moving Toward Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Toward Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |
|---|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]   | 21  | 20  | 19  | 18  | 17  | 16  | 15  | 14  | 13  | 12  | 11  |
| Grip #3   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |
| Grip #4   | Max | Max | Max | Max | Max | Red | Red | Red | Red | Red | Red |

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**Table F-22**  
**Right Edge, Moving Away From Phantom**

| KDB 616217 Section 6.2 Measured Power Moving Away From Phantom [dBm] |     |     |     |     |     |     |     |     |     |     |     |     |
|--|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Distance [mm]  | 17  | 18  | 19  | 20  | 21  | 22  | 23  | 24  | 25  | 26  | 27  | 28  |
| Grip #3  | Red | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |
| Grip #4  | Red | Red | Red | Red | Red | Red | Max | Max | Max | Max | Max | Max |

**Table F-23**  
**Triggering States by Tilt Angle for each Sensor per KDB 616217 Section 6.4 – Top Edge**

| KDB 616217 Section 6.4 Measured Tilt Angle |     |     |     |     |    |    |    |    |    |    |    |  |
|--|-----|-----|-----|-----|----|----|----|----|----|----|----|--|
| Tilt Angle                                 | -45 | -35 | -25 | -15 | -5 | 0  | 5  | 15 | 25 | 35 | 45 |  |
| Grip #1                                    | 25  | 25  | 25  | 25  | 25 | 25 | 25 | 25 | 25 | 25 | 25 |  |
| Grip #2                                    | 26  | 26  | 26  | 26  | 26 | 26 | 26 | 26 | 26 | 26 | 26 |  |
| Grip #3                                    | 26  | 26  | 26  | 26  | 26 | 26 | 26 | 26 | 26 | 26 | 26 |  |

**Table F-24**  
**Triggering States by Tilt Angle for each Sensor per KDB 616217 Section 6.4 – Bottom Edge**

| KDB 616217 Section 6.4 Measured Tilt Angle |     |     |     |     |    |    |    |    |    |    |    |  |
|--|-----|-----|-----|-----|----|----|----|----|----|----|----|--|
| Tilt Angle                                 | -45 | -35 | -25 | -15 | -5 | 0  | 5  | 15 | 25 | 35 | 45 |  |
| Grip #4                                    | 28  | 28  | 28  | 28  | 28 | 28 | 28 | 28 | 28 | 28 | 28 |  |
| Grip #5                                    | 28  | 28  | 28  | 28  | 28 | 28 | 28 | 28 | 28 | 28 | 28 |  |
| Grip #6                                    | 28  | 28  | 28  | 28  | 28 | 28 | 28 | 28 | 28 | 28 | 28 |  |

**Table F-25**  
**Triggering States by Tilt Angle for each Sensor per KDB 616217 Section 6.4 – Left Edge**

| KDB 616217 Section 6.4 Measured Tilt Angle |     |     |     |     |    |    |    |    |    |    |    |  |
|--|-----|-----|-----|-----|----|----|----|----|----|----|----|--|
| Tilt Angle                                 | -45 | -35 | -25 | -15 | -5 | 0  | 5  | 15 | 25 | 35 | 45 |  |
| Grip #1                                    | 16  | 16  | 16  | 16  | 16 | 16 | 16 | 16 | 16 | 16 | 16 |  |
| Grip #6                                    | 16  | 16  | 16  | 16  | 16 | 16 | 16 | 16 | 16 | 16 | 16 |  |

**Table F-26**  
**Triggering States by Tilt Angle for each Sensor per KDB 616217 Section 6.4 – Right Edge**

| KDB 616217 Section 6.4 Measured Tilt Angle |     |     |     |     |    |    |    |    |    |    |    |  |
|--|-----|-----|-----|-----|----|----|----|----|----|----|----|--|
| Tilt Angle                                 | -45 | -35 | -25 | -15 | -5 | 0  | 5  | 15 | 25 | 35 | 45 |  |
| Grip #3                                    | 16  | 16  | 16  | 16  | 16 | 16 | 16 | 16 | 16 | 16 | 16 |  |
| Grip #4                                    | 16  | 16  | 16  | 16  | 16 | 16 | 16 | 16 | 16 | 16 | 16 |  |

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