

APPENDIX D: MEASUREMENT UNCERTAINTIES

Applicable for SAR measurements with MAGPy-H3D probe and Module WPT

| Item | Uncertainty Source | Tolerance (dB) | Distr. | Div. | ci | Std.Unc. (dB) |
|------------------------------|---|----------------|--------|------------|----|---------------|
| Probe uncertainty | | | | | | |
| 1 | Amplitude calibration uncertainty | 0.47 | norm | 1 | 1 | 0.47 |
| 2 | Gradient calibration uncertainty | N/A | norm | 1 | 1 | N/A |
| 3 | Probe anisotropy | 0.5 | rect | $\sqrt{3}$ | 1 | 0.29 |
| 4 | Probe dynamic linearity | 0.15 | rect | $\sqrt{3}$ | 1 | 0.09 |
| 5 | Probe frequency domain response | 0.25 | rect | $\sqrt{3}$ | 1 | 0.14 |
| 6 | Modulation response | N/A | rect | $\sqrt{3}$ | 1 | N/A |
| 7 | Spatial averaging (maximum gradient) | N/A | rect | $\sqrt{3}$ | 1 | N/A |
| 8 | Gradient uncertainty | 0.1 | rect | $\sqrt{3}$ | 1 | 0.06 |
| 9 | Gradient detection uncertainty | N/A | rect | $\sqrt{3}$ | 1 | N/A |
| 10 | Parasitic E-field sensitivity | 0.1 | rect | $\sqrt{3}$ | 1 | 0.06 |
| 11 | Detection limit | 0.15 | rect | $\sqrt{3}$ | 1 | 0.09 |
| 12 | Readout electronics | 0 | norm | 1 | 1 | 0 |
| 13 | Response time | N/A | norm | 1 | 1 | N/A |
| 14 | Probe positioning | 0.19 | norm | 1 | 1 | 0.19 |
| 15 | Shaping, filtering, signal conditioning | N/A | norm | 1 | 1 | N/A |
| 16 | Nominal position | N/A | rect | $\sqrt{3}$ | 1 | N/A |
| 17 | Repeatability | 0.1 | norm | 1 | 1 | 0.10 |
| Numerical simulations | | | | | | |
| 18 | Numerical method | 0 | rect | $\sqrt{3}$ | 1 | 0 |
| 19 | Grid resolution | 0.02 | rect | $\sqrt{3}$ | 1 | 0.01 |
| 20 | Tissue parameters | N/A | rect | $\sqrt{3}$ | 1 | N/A |
| 21 | Averaging method | 0.05 | rect | $\sqrt{3}$ | 1 | 0.03 |
| 22 | Model and exposure location | 0 | rect | $\sqrt{3}$ | 1 | 0 |
| 23 | Convergence | 0 | rect | $\sqrt{3}$ | 1 | 0 |
| 24 | Boundary conditions | 0.2 | rect | $\sqrt{3}$ | 1 | 0.12 |
| 25 | Post-processing, interpolation | 0.30 | rect | $\sqrt{3}$ | 1 | 0.17 |
| Field reconstruction | | | | | | |
| 26 | Reconstruction algorithm; i.e., calculation of vector potential from measured magnetic flux density | 0.09 | rect | $\sqrt{3}$ | 1 | 0.05 |
| | Combined uncertainty (k=1) | | | | | 0.66 |
| | Expanded uncertainty (k=2) | | | | | 1.31 |

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| FCC ID: A3LSMS911U | FCC URS (UNINTENTIONAL RADIATOR RF SOURCES) RF EXPOSURE EVALUATION | Approved by: Technical Manager |
| Apparatus/Device: Portable Handset | | Appendix D Page 1 of 3 |

Applicable for SAR measurements with EX3DVx Probe:

| a | b | c | d | e= f(d,k) | f | g | h= c x f/e | i= c x g/e | k |
|---|----------------------|---------------|----------------|--------------|-----------------------|--------------------------|-------------------|----------------------------------|----------------|
| Uncertainty Component | IEEE 1528 Sec. | Tol. (± %) | Prob. Dist. | Div. | c _i lgm | c _i 10 gms | lgm u (± %) | 10gms u _i (± %) | v _i |
| Measurement System | | | | | | | | | |
| Probe Calibration | E.2.1 | 9.3 | N | 1 | 1 | 1 | 9.3 | 9.3 | ∞ |
| Axial Isotropy | E.2.2 | 0.25 | N | 1 | 0.7 | 0.7 | 0.2 | 0.2 | ∞ |
| Hemishperical Isotropy | E.2.2 | 1.3 | N | 1 | 0.7 | 0.7 | 0.9 | 0.9 | ∞ |
| Boundary Effect | E.2.3 | 2 | R | 1.732 | 1 | 1 | 1.2 | 1.2 | ∞ |
| Linearity | E.2.4 | 0.3 | N | 1 | 1 | 1 | 0.3 | 0.3 | ∞ |
| System Detection Limits | E.2.4 | 0.25 | R | 1.732 | 1 | 1 | 0.1 | 0.1 | ∞ |
| Readout Electronics | E.2.6 | 0.3 | N | 1 | 1 | 1 | 0.3 | 0.3 | ∞ |
| Response Time | E.2.7 | 0.8 | R | 1.732 | 1 | 1 | 0.5 | 0.5 | ∞ |
| Integration Time | E.2.8 | 2.6 | R | 1.732 | 1 | 1 | 1.5 | 1.5 | ∞ |
| RF Ambient Conditions - Noise | E.6.1 | 3 | R | 1.732 | 1 | 1 | 1.7 | 1.7 | ∞ |
| RF Ambient Conditions - Reflections | E.6.1 | 3 | R | 1.732 | 1 | 1 | 1.7 | 1.7 | ∞ |
| Probe Positioner Mechanical Tolerance | E.6.2 | 0.4 | R | 1.732 | 1 | 1 | 0.2 | 0.2 | ∞ |
| Probe Positioning w/ respect to Phantom | E.6.3 | 6.7 | R | 1.732 | 1 | 1 | 3.9 | 3.9 | ∞ |
| Extrapolation, Interpolation & Integration algorithms for Max. SAR Evaluation | E.5 | 4 | R | 1.732 | 1 | 1 | 2.3 | 2.3 | ∞ |
| Test Sample Related | | | | | | | | | |
| Test Sample Positioning | E.4.2 | 2.70 | N | 1 | 1 | 1 | 2.7 | 2.7 | 35 |
| Device Holder Uncertainty | E.4.1 | 1.67 | N | 1 | 1 | 1 | 1.7 | 1.7 | 5 |
| Output Power Variation - SAR drift measurement | E.2.9 | 5 | R | 1.732 | 1 | 1 | 2.9 | 2.9 | ∞ |
| SAR Scaling | E.6.5 | 0 | R | 1.732 | 1 | 1 | 0.0 | 0.0 | ∞ |
| Phantom & Tissue Parameters | | | | | | | | | |
| Phantom Uncertainty (Shape & Thickness tolerances) | E.3.1 | 7.6 | R | 1.73 | 1.0 | 1.0 | 4.4 | 4.4 | ∞ |
| Liquid Conductivity - measurement uncertainty | E.3.3 | 4.2 | N | 1 | 0.78 | 0.71 | 3.3 | 3.0 | 76 |
| Liquid Permittivity - measurement uncertainty | E.3.3 | 4.1 | N | 1 | 0.23 | 0.26 | 0.9 | 1.1 | 75 |
| Liquid Conductivity - Temperature Uncertainty | E.3.4 | 3.4 | R | 1.732 | 0.78 | 0.71 | 1.5 | 1.4 | ∞ |
| Liquid Permittivity - Temperature Uncertainty | E.3.4 | 0.6 | R | 1.732 | 0.23 | 0.26 | 0.1 | 0.1 | ∞ |
| Liquid Conductivity - deviation from target values | E.3.2 | 5.0 | R | 1.73 | 0.64 | 0.43 | 1.8 | 1.2 | ∞ |
| Liquid Permittivity - deviation from target values | E.3.2 | 5.0 | R | 1.73 | 0.60 | 0.49 | 1.7 | 1.4 | ∞ |
| Combined Standard Uncertainty (k=1) | RSS | | | | | | 13.3 | 13.1 | 191 |
| Expanded Uncertainty (95% CONFIDENCE LEVEL) | k=2 | | | | | | 26.5 | 26.1 | |

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Applicable for Power Density Measurements:

| a | b | c | d | e | f = c x f/e | g |
|---|----------------|----------------|------|----------------|--------------------------|----------------|
| Uncertainty Component | Unc. (± dB) | Prob. Dist. | Div. | c _i | u _i (± dB) | v _i |
| Measurement System | | | | | | |
| Calibration | 0.49 | N | 1 | 1 | 0.49 | ∞ |
| Probe Correction | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Frequency Response | 0.20 | R | 1.73 | 1 | 0.12 | ∞ |
| Sensor Cross Coupling | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Isotropy | 0.50 | R | 1.73 | 1 | 0.29 | ∞ |
| Linearity | 0.20 | R | 1.73 | 1 | 0.12 | ∞ |
| Probe Scattering | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Probe Positioning offset | 0.30 | R | 1.73 | 1 | 0.17 | ∞ |
| Probe Positioning Repeatability | 0.04 | R | 1.73 | 1 | 0.02 | ∞ |
| Sensor Mechanical Offset | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Probe Spatial Resolution | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Field Impedance Dependence | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Amplitude and Phase Drift | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Amplitude and Phase Noise | 0.04 | R | 1.73 | 1 | 0.02 | ∞ |
| Measurement Area Truncation | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Data Acquisition | 0.03 | N | 1 | 1 | 0.03 | ∞ |
| Sampling | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Field Reconstruction | 2.00 | R | 1.73 | 1 | 1.15 | ∞ |
| Forward Transformation | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Power Density Scaling | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Spatial Averaging | 0.10 | R | 1.73 | 1 | 0.06 | ∞ |
| System Detection Limit | 0.04 | R | 1.73 | 1 | 0.02 | ∞ |
| Test Sample Related | | | | | | |
| Probe Coupling with DUT | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Modulation Response | 0.40 | R | 1.73 | 1 | 0.23 | ∞ |
| Integration Time | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Response Time | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Device Holder Influence | 0.10 | R | 1.73 | 1 | 0.06 | ∞ |
| DUT alignment | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| RF Ambient Conditions | 0.04 | R | 1.73 | 1 | 0.02 | ∞ |
| Ambient Reflections | 0.04 | R | 1.73 | 1 | 0.02 | ∞ |
| Immunity/Secondary Reception | 0.00 | R | 1.73 | 1 | 0.00 | ∞ |
| Drift of DUT | 0.21 | R | 1.73 | 1 | 0.12 | ∞ |
| Combined Standard Uncertainty (k=1) | | RSS | | | 1.34 | ∞ |
| Expanded Uncertainty (95% CONFIDENCE LEVEL) | | k=2 | | | 2.68 | |

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