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HEARING AID COMPATIBILITY

Applicant Name:

Samsung Electronics Co., Ltd. 129, Samsung-ro, Maetan dong, Yeongtong-gu, Suwon-si Gyeonggi-do 16677, Korea

Date of Testing: 8/2/2021 - 8/4/2021 **Test Site/Location:** PCTEST, Columbia, MD, USA **Test Report Serial No.:** 1M2108050089-01.A3L Date of Issue: 8/7/2021

FCC ID: A3LSMF926B

APPLICANT: SAMSUNG ELECTRONICS CO., LTD.

Scope of Test: RF Emissions Testing **Application Type:** Class II Permissive Change

FCC Rule Part(s): CFR §20.19(b) **HAC Standard:** ANSI C63.19-2011

285076 D01 HAC Guidance v05

285076 D02 T-Coil testing for CMRS IP v03

DUT Type: Portable Handset Model: SM-F926B/DS Additional Model(s): SM-F926B

Test Device Serial No.: Pre-Production Sample [S/N: 0528M]

Class II Permissive Change(s): See FCC Change Document

M4 (RF EMISSIONS CATEGORY; Flat C63.19-2011 HAC Category:

Configuration only)

This report and category pertain only to the flat configuration supported by this wireless portable device. The overall category rating of the device is determined by the lowest rating obtained over all air interfaces supported by the device. This wireless portable device has been shown to be hearing-aid compatible under the above rated category, specified in ANSI/IEEE Std. C63.19-2011 and has been tested in accordance with the specified measurement procedures. Hearing-Aid Compatibility is based on the assumption that all production units will be designed electrically identical to the device tested in this report. Test results reported herein relate only to the item(s) tested. North America bands only.

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them.







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1. INTRODUCTION

On July 10, 2003, the Federal Communications Commission (FCC) adopted new rules requiring wireless manufacturers and service providers to provide digital wireless phones that are compatible with hearing aids. The FCC has modified the exemption for wireless phones under the Hearing Aid Compatibility Act of 1998 (HAC Act) in WT Docket 01-309 RM-8658¹ to extend the benefits of wireless telecommunications to individuals with hearing disabilities. These benefits encompass business, social and emergency communications, which increase the value of the wireless network for everyone. An estimated more than 10% of the population in the United States show signs of hearing impairment and of that fraction, almost 80% use hearing aids. Approximately 500 million people worldwide suffer from hearing loss.

Compatibility Tests Involved:

The standard calls for wireless communications devices to be measured for:

- RF Electric-field emissions
- T-coil mode, magnetic-signal strength in the audio band
- T-coil mode, magnetic-signal frequency response through the audio band
- T-coil mode, magnetic-signal and noise articulation index

The hearing aid must be measured for:

- RF immunity in microphone mode
- RF immunity in T-coil mode

In the following tests and results, this report includes the evaluation for a wireless communications device.



Figure 1-1 Hearing Aid in-vitu

¹ FCC Rule & Order, WT Docket 01-309 RM-8658

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2. DUT DESCRIPTION



FCC ID: A3LSMF926B

Manufacturer: Samsung Electronics Co., Ltd.

129, Samsung-ro, Maetan dong,

Yeongtong-gu, Suwon-si Gyeonggi-do 16677, Korea

Model: SM-F926B/DS
Additional Model(s): SM-F926B
Serial Number: 0528M

Antenna Configurations: Internal Antenna
DUT Type: Portable Handset

I. Flat Configuration Testing

This device supports held to ear scenarios in both the folded (closed) and flat (open) configurations. The overall worst case configuration from the original certification test report (Report S/N: 1M2104190044-21-R1.A3L) was additionally evaluated in the flat (open) configuration for this report.

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Table 2-1 A3LSMF926B HAC Air Interfaces

| | ASESMIF 920B FIAC All Title Haces | | | | | | |
|----------------|-----------------------------------|----------------|------------------|--------------------------------|-----------------------|--|--|
| Air-Interface | Band (MHz) | Type Transport | HAC Tested | Simultaneous But Not Tested | Name of Voice Service | | |
| | 850 | | No ¹ | Versi MIEL en DT | CMADC Maria | | |
| GSM | 1900 | VO | Yes ¹ | Yes: WIFI or BT | CMRS Voice | | |
| | GPRS/EDGE | VD | No ¹ | Yes: WIFI or BT | Google Duo | | |
| | 850 | | | | | | |
| LINATE | 1700 | VD | No ¹ | Yes: WIFI or BT | CMRS Voice | | |
| UMTS | 1900 | | | | | | |
| | HSPA | VD | No ¹ | Yes: WIFI or BT | Google Duo | | |
| | 700 (B12) | | | | | | |
| | 700 (B17) | | No ¹ | Yes: NR, WIFI, or BT | VoLTE, Google Duo | | |
| | 780 (B13) | | | | | | |
| | 850 (B5) | VD | | | | | |
| LTE (FDD) | 850 (B26) | | | | | | |
| | 1700 (B4) | | | | | | |
| | 1700 (B66) | | | | | | |
| | 1900 (B2) | | | | | | |
| | 1900 (B25) | | | | | | |
| LTE (TDD) | 2600 (B41) | VD | No ¹ | Yes: NR, WIFI or BT | VoLTE, Google Duo | | |
| ND (EDD) | 850 (n5) | VD | No ¹ | VocaLTE MUSI or DT | Canala Dua | | |
| NR (FDD) | 1700 (n66) | VD | NO | Yes: LTE, WIFI, or BT | Google Duo | | |
| | 2450 | | | | | | |
| | 5200 (U-NII 1) | | | | | | |
| | 5300 (U-NII 2A) | | | | | | |
| | 5500 (U-NII 2C) | | | | | | |
| WIFI | 5800 (U-NII 3) | VD | No ¹ | Yes: GSM, UMTS, LTE, or NR | VoWIFI, Google Duo | | |
| | 6175 (U-NII 5) | | | | | | |
| | 6475 (U-NII 6) | | | | | | |
| | 6700 (U-NII 7) | | | | | | |
| | 7000 (U-NII 8) | | | | | | |
| BT | 2450 | DT | No | Yes: GSM, UMTS, LTE, or NR | N/A | | |
| Type Transport | | | Notes: | | | | |

VO = Voice Only

DT = Digital Data - Not intended for Voice Services

VD = CMRS and/or IP Voice over Data Transport

1. This report only pertains to GSM1900 mode. For full data, please refer to the Original

Certification Test Report (Report S/N: 1M2104190044-21-R1.A3L)

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3. **ANSI/IEEE C63.19 PERFORMANCE CATEGORIES**

I. **RF EMISSIONS**

The ANSI Standard presents performance requirements for acceptable interoperability of hearing aids with wireless communications devices. When these parameters are met, a hearing aid operates acceptably in close proximity to a wireless communications device.

| Category | Telephone RF Parameters | | | |
|---|------------------------------------|--|--|--|
| Near field Category | E-field emissions CW dB(V/m) | | | |
| | f < 960 MHz | | | |
| M1 | 50 to 55 | | | |
| M2 | 45 to 50 | | | |
| М3 | 40 to 45 | | | |
| M4 | < 40 | | | |
| | f > 960 MHz | | | |
| M1 | 40 to 45 | | | |
| M2 | 35 to 40 | | | |
| М3 | 30 to 35 | | | |
| M4 | < 30 | | | |
| Table 3-1 WD near-field categories as defined in ANSI C63.19-2011 | | | | |

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4. SYSTEM SPECIFICATIONS

EF3DV3 E-Field Probe Description

Construction: One dipole parallel, two dipoles normal to probe axis

Built-in shielding against static charges

Calibration: In air from 30 MHz to 6.0 GHz

(absolute accuracy ±5.1%, k=2)

Frequency: 30 MHz to > 6 GHz;

Linearity: ± 0.2 dB (30 MHz to 6 GHz)

Directivity ± 0.2 dB in air (rotation around probe axis)

± 0.4 dB in air (rotation normal to probe axis)

Dynamic Range 2 V/m to > 1000 V/m

(M3 or better device readings fall well below diode

compression point)

Linearity: ± 0.2 dB

Dimensions Overall length: 337 mm (Tip: 20 mm)

Tip diameter: 4.0 mm (Body: 12 mm)

Distance from probe tip to dipole centers: 1.5 mm



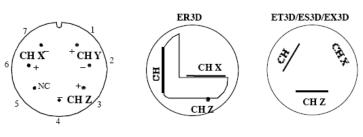
Figure 4-1 E-field Free-space Probe

Probe Tip Description

HAC field measurements take place in the close near field with high gradients. Increasing the measuring distance from the source will generally decrease the measured field values (in case of the validation dipole approx. 10% per mm).

The electric field probes have an irregular internal geometry because it is physically not possible to have the 3 orthogonal sensors situated with the same center. The effect of the different sensor centers is accounted for in the HAC uncertainty budget ("sensor displacement").

Connector Plan



(seen from back) (seen from front)

The antistatic shielding inside the probe is connected to the probe connector case.

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Equation 1

Conversion of Connector Voltage u, to E-Field E,

$$E_i = \sqrt{\frac{u_i + (u_i^2 \cdot CF)/(DCP)}{Norm_i \cdot ConvF}}$$

whereby

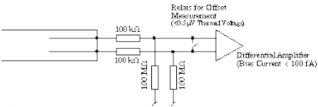
Ei: electric field in V/m

voltage of channel i at the connector in μV иí. sensitivity of channel i in $\mu V/(V/m)^2$ Norm_i: ConvF: enhancement factor in liquid (ConvF=1 for Air)

DCP: diode compression point in µV

CF: signal crest factor (peak power/average power)

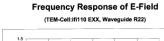
Conditions of Calibration



- a lower input impedance of the amplifier will result in different sensitivity factors Norm, and DCP
- larger bias currents will cause higher offset

Probe Response to Frequency

The E-field sensors have inherently a very flat frequency response. They are calibrated with a number of frequencies resulting in a common calibration factor, with the frequency behavior documented in the calibration certificate (See also below).



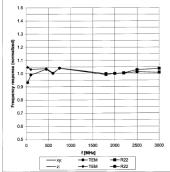


Figure 4-2 E-Field Probe Frequency Response

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SPEAG Robotic System

E-field measurements are performed using the DASY5 automated dosimetric assessment system. The DASY5 is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, Intel CORE i7 computer, near-field probe, probe alignment sensor, and the HAC phantom. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF).



Figure 4-3 SPEAG Robotic System

System Hardware

A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and a remote control used to drive the robot motors. The PC consists of the computer with operating system and RF Measurement Software DASY5 v52.8 (with HAC Extension), A/D interface card, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

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System Electronics

The DAE consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

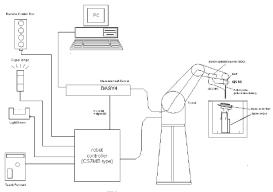


Figure 4-4 SPEAG Robotic System Diagram

DASY5 Instrumentation Chain

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$\begin{aligned} V_i &= U_i + U_i^2 \cdot \frac{cf}{dcp_i} \\ \text{with} \quad V_i &= \text{compensated signal of channel i} & (i = x, y, z) \\ U_i &= \text{input signal of channel i} & (i = x, y, z) \\ cf &= \text{crest factor of exciting field} & (\text{DASY parameter}) \\ dcp_i &= \text{diode compression point} & (\text{DASY parameter}) \end{aligned}$$

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From the compensated input signals the primary field data for each channel can be evaluated:

$$\mathbf{E} - \text{fieldprobes}: \qquad E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

with V_i = compensated signal of channel i (i = x, y, z) $Norm_i$ = sensor sensitivity of channel i (i = x, y, z)

 $\mu V/(V/m)^2$ for E-field Probes

ConvF = sensitivity enhancement in solution E_i = electric field strength of channel i in V/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

The measurement/integration time per point, as specified by the system manufacturer is >500ms.

The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/off switch of the power source with an integration time of 500ms and a probe response time of <5 ms. In the current implementation, DASY5 waits longer than 100ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization. The tolerances for the different systems had the worst-case of 2.6%.

Environmental Conditions

Environmental conditions such as temperature and relative humidity are monitored to ensure there are no impacts on system specifications. Proper voltage and power line frequency conditions are maintained with three phase power sources. Environmental noise and reflections are monitored through system checks.

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5. TEST PROCEDURE

I. RF EMISSIONS

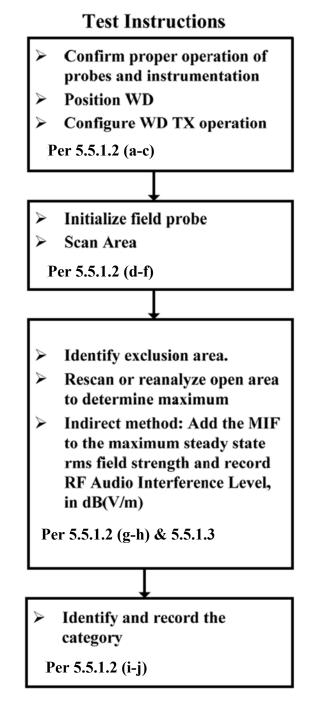


Figure 5-1 RF Emissions Flow Chart

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Test Setup

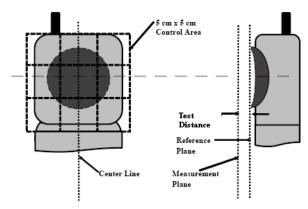


Figure 5-2 E-Field Emissions Test Setup Diagram (See Test Photographs for actual WD scan grid overlay)

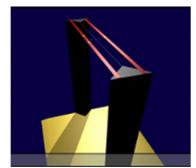


Figure 5-3 **HAC Phantom**

RF Emissions Test Procedure:

The following illustrate a typical RF emissions test scan over a wireless communications device:

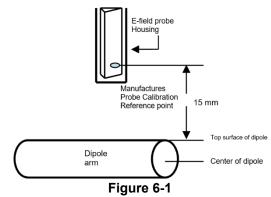
- 1. Proper operation of the field probe, probe measurement system, other instrumentation, and the positioning system was confirmed.
- 2. WD is positioned in its intended test position, acoustic output point of the device perpendicular to the field probe.
- 3. The WD operation for maximum rated RF output power was configured and confirmed with the base station simulator, at the test channel and other normal operating parameters as intended for the test. The battery was ensured to be fully charged before each test.
- The center sub-grid was centered over the center of the acoustic output (also audio band magnetic output, if applicable). The WD audio output was positioned tangent (as physically possible) to the measurement plane.
- 5. A surface calibration was performed before each setup change to ensure repeatable spacing and proper maintenance of the measurement plane using the HAC Phantom.
- 6. The measurement system measured the field strength at the reference location.
- Measurements at 2mm or 5mm increments in the 5 x 5 cm region were performed at a distance 15 mm from the center point of the probe measurement element to the WD. Of the 9 subgrids (see Figure 5-2), 3 contiguous subgrids may be excluded from the measurement in order to account for localized areas of higher field intensities. The center subgrid containing the acoustic output or audio band magnetic output may not excluded. A 360° rotation about the azimuth axis at the maximum interpolated position was measured. For the worst-case condition, the peak reading from this rotation was used in re-evaluating the HAC category.
- 8. The system performed a drift evaluation by measuring the field at the reference location. If the power drift deviated by more than 5%, the HAC test and drift measurements were repeated.

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I. System Check Parameters

The input signal was an un-modulated continuous wave. The following points were taken into consideration in performing this check:

- Average Input Power P = 100mW RMS (20dBm RMS) after adjustment for return loss
- The test fixture must meet the 2 wavelength separation criterion
- The proper measurement of the 15 mm probe to dipole separation, which is measured from top surface of the dipole to the calibration reference point of the sensor, defined by the probe manufacturer is shown in the following diagram:



Separation Distance from Dipole to Field Probe

RF power was recorded using both an average reading meter and a peak reading meter. Readings of the probe are provided by the measurement system.

To assure proper operation of the near-field measurement probe the input power to the dipole shall be commensurate with the full rated output power of the wireless device [e.g. - for a cellular phone wireless device the average peak antenna input power will be on the order of 100mW (20dBm) RMS] after adjustment for any mismatch.

II. Validation Procedure

A dipole antenna meeting the requirements given in C63.19 was placed in the position normally occupied by the WD.

The length of the dipole was scanned, and the average peak value was recorded.

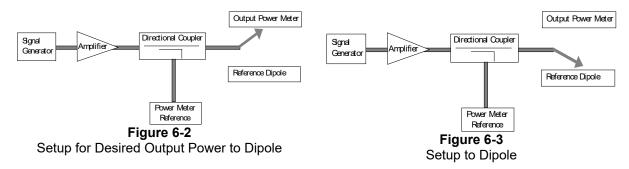
Measurement of CW

Using the near-field measurement system, scan the antenna over the radiating dipole and record the greatest field reading observed. Due to the nature of E-fields about free-space dipoles, the two E-field peaks measured over the dipole are averaged to compensate for non-parallelity of the setup (see manufacturer method on dipole calibration certificates, page 2). Field strength measurements shall be made only when the probe is stationary.

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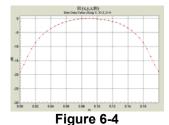
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RF power was recorded using both an average and a peak power reading meter.

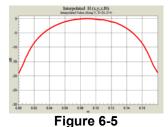


Using this setup configuration, the signal generator was adjusted for the desired output power (100mW) at a specified frequency. The reference power from the coupled port of the directional coupler is recorded. Next, the output cable is connected to the reference dipole, as shown in Figure 6-3.

The input signal level was adjusted until the reference power from the coupled port of the directional coupler was the same as previously recorded, to compensate for the impedance mismatch between the output cable and the reference dipole. To assure proper operation of the near-field measurement probe the input power to the reference dipole was verified to the full rated output power of the wireless device. The dipole was secured in a holder in a manner to meet the 20 dB reflection. The near-field measurement probe was positioned over the dipole. The antenna was scanned over the appropriate sized area to cover the dipole from end to end. SPEAG uses 2D interpolation algorithms between the measured points. Please see below two dimensional plots showing that the interpolated values interpolate smoothly between 5mm steps for a free-space RF dipole:



2-D Raw Data from scan along dipole axis



2-D Interpolated points from scan along dipole axis

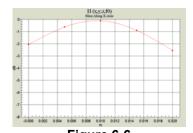


Figure 6-6
2-D Raw Data from scan along transverse axis

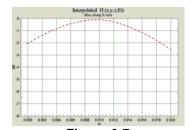


Figure 6-7
2-D Interpolated points from scan along transverse axis

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III. **System Check Results**

Validation Results

| Date | Frequency (MHz) | Probe S/N | DAE S/N | Dipole S/N | Input Power (dBm) | E-field Result (V/m) | Target Field (V/m) | % Deviation |
|----------|--------------------|-----------|---------|------------|-------------------------|----------------------------|--------------------------|----------------|
| 8/2/2021 | 1880 | 4035 | 1530 | 1137 | 20.0 | 86.5 | 87.9 | -1.6% |

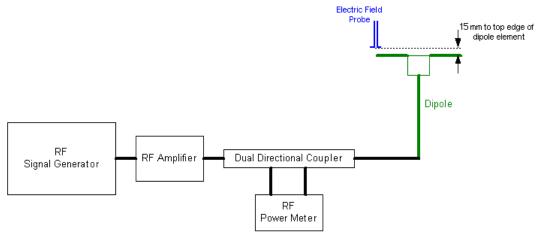


Figure 6-8 System Check Setup

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7. **MODULATION INTERFERENCE FACTOR**

I. **Measuring Modulation Interference Factors**

For any specific fixed and repeatable modulated signal, a modulation interference factor (MIF, expressed in dB) may be determined that relates its interference potential to its steady-state RMS signal level or average power level. This factor is a function only of the audio-frequency amplitude modulation characteristics of the signal and is the same for field-strength and conducted power measurements. The MIF is valid only for a specific repeatable audio-frequency amplitude modulation characteristic; any change in modulation characteristic requires determination and application of a new MIF.

The MIF may be determined using a radiated RF field or a conducted RF signal:

- a. Using RF illumination or conducted coupling, apply the specific modulated signal in question to the measurement system at a level within its confirmed operating dynamic range.
- b. Measure the steady-state RMS level at the output of the fast probe or sensor.
- c. Measure the steady-state average level at the weighting output.
- d. Without changing the square-law detector or weighting system, and using RF illumination or conducted coupling, substitute for the specific modulated signal a 1 kHz, 80% amplitude modulated carrier at the same frequency and adjust its strength until the level at the weighting output equals the step c) measurement.
- e. Without changing the carrier level from step d), remove the 1 kHz modulation and again measure the steady-state RMS level indicated at the output of the fast probe or sensor.
- The MIF for the specific modulation characteristic is provided by the ratio of the step e) measurement to the step b) measurement, expressed in dB (20 × logf(step e)/(step b)1).

The following procedure was used to measure the MIF using the SPEAG Audio Interference Analyzer (AIA), Type No: SE UMS 170 CB, Serial No.: 1010:

- 1. The device was placed into a simulated call using a base station simulator or set to transmit using test software for a given mode.
- 2. The device was then set to continuously transmit at maximum power.
- 3. Using a coupler if needed, the device output signal was connected to the RF In port of the AIA, which was connected to a desktop computer. Alternatively, a radiated RF signal may be used with the AIA's built-in antenna.
- 4. The MIF measurement procedure in the DASY software was run, and the resulting MIF value was recorded.
- 5. Steps 1-4 were repeated for all CMRS air interfaces, frequency bands, and modulations.

The modulation interference factors obtained were applied to readings taken of the actual wireless device in order to obtain an accurate audio interference level reading using the formula:

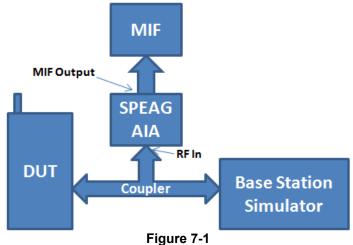
Audio Interference Level [dB(V/m)] = 20 * log[Raw Field Value (V/m)] + MIF (dB)

Because the MIF value is output power independent, MIF values for a given mode should be constant across all devices; however, per C63.19-2011 §D.7, MIF values should be measured for each device being evaluated. The applicable modes for this device have been investigated in this section of the report.

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MIF Measurement Block Diagrams II.



MIF Measurement Setup for licensed modes

III. **Measured Modulation Interference Factors:**

Table 7-1 GSM Modulation Interference Factors¹

| Ma | GSM1900 | |
|------|---------|------|
| IVIC | Mode | |
| GSM | Voice | 3.52 |

¹ Note: Measured MIF values may be lower than sample MIF values provided in ANSI C63.19-2011 Annex D.7 Table D.5 due to manufacturing variations for each device, however per Annex D.7, the sample MIF values of Table D.5 are not intended to substitute for measurements of actual devices under test and their respective operating modes.

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8. CONDUCTED POWER CONFIGURATIONS AND TARGETS

I. Procedures Used to Establish RF Signal for HAC Testing

The handset was configured to transmit the required air interface in a shielded chamber. Measurements were taken with a fully charged battery.

II. HAC Target Powers

All applicable modes supported by the device have their held-to-ear conducted power targets listed below and were used for the individual mode evaluations in Section 9. All conducted power targets have a tolerance of +1.0dB and -1.5dB unless otherwise noted.

III. RF Conducted Power Measurement Setup and Conditions

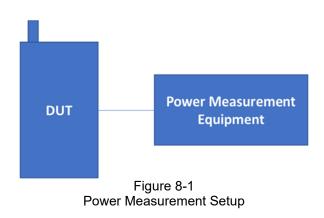
Output Power Verification

Maximum output power is verified for all applicable test channels for all air interfaces which require test scans. See Table 8-1 for air interface specific settings of transmit power parameters. See Table 9-1 for more information regarding which modes required test scans and had conducted power measurements taken.

Table 8-1
Power Control Parameters and Settings by Air Interface

| Air Interface: | Parameter Name: | Parameter Set To: |
|----------------|-----------------|-------------------|
| GSM | PCL | GSM1900: "0" |

The general setup for conducted powers included in Section 10 is shown in Figure 8-1 below. The power measurement equipment could be a base station simulator, signal analyzer, or power meter depending on the applicable air interface.



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IV. GSM Target Powers

Table 8-2 GSM Conducted Power Target

| Com Conducted I ower ranger | | | | | | | |
|-----------------------------|---|--|--|--|--|--|--|
| Band | Modulated Average Output Power (in dBm) | | | | | | |
| | Voice | | | | | | |
| GSM 1900 | 29.2 | | | | | | |

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9. JUSTIFICATION OF HELD TO EAR MODES TESTED

I. Analysis of RF Air Interface Technologies

An analysis was performed, following the guidance of §4.3 and §4.4 of the ANSI standard, of the RF air interface technologies being evaluated. The factors that will affect the RF interference potential were evaluated, and the worst-case operating modes were identified and used in the evaluation. A WD's interference potential is a function both of the WD's average near-field field strength and of the signal's audio-frequency amplitude modulation characteristics. Per §4.4, RF air interface technologies that have low power have been found to produce sufficiently low RF interference potential, so it is possible to exempt them from the product testing specified in Clause 5 of the ANSI standard. An RF air interface technology of a device is exempt from testing when its average antenna input power plus its MIF is ≤17dBm for all of its operating modes. RF air interface technologies exempted from testing in this manner are automatically assigned an M4 rating to be used in determining the overall rating for the WD.

The worst-case MIF plus the worst-case average antenna input power for all modes are investigated below to determine the testing requirements for this device.

II. Individual Mode Evaluations

Table 9-1
Max Power + MIF calculations for Low Power Exemptions

| Air Interface | Maximum | Worst Case | Total | C63.19 |
|---------------|---------------|------------|----------|----------|
| | Average Power | MIF | (Power + | Testing |
| | (dBm) | (dB) | MIF, dB) | Required |
| GSM - GSM1900 | 21.01* | 3.52 | 24.53 | Yes |

^{*} Note: ANSI C63.19-2011 Sec. 4.4 Footnote 20 indicates the use of a long averaging time for measuring the antenna input power when using this method of exclusion. Therefore, the frame averaged power was calculated for these modes in this investigation.

III. Low-Power Exemption Conclusions

Per ANSI C63.19-2011, RF Emissions testing for this device is required only for the GSM1900 voice mode in the flat configuration. Please refer to the original certification test report for full evaluation in the folded (closed) configuration.

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OVERALL MEASUREMENT SUMMARY 10.

| FCC ID: | A3LSMF926B |
|---------|------------|
| S/N: | 0528M |

I. **E-FIELD EMISSIONS:**

Table 10-1 HAC Data Summary for GSM E-field

| | Tirto Data Callillary for Colli 2 flora | | | | | | | | | | | |
|------------------|---|--------------------------|-------------|-----------------------------------|-----------------------------|---------------------------------|-------------|---|----------------------|--------------------|--------|------------------------|
| Mode | Channel | Device Posture / Side | Scan Center | Conducted Power at BS (dBm) | Time Avg. Field (V/m) | Time Avg. Field [dB(V/m)] | MIF (dB) | Audio Interference Level [dB(V/m)] | FCC Limit (dBV/m) | FCC Margin (dB) | Result | Excl Blocks per 5.5 |
| E-Field Emission | ons | | | | | | | | | | | |
| GSM1900 | 512 | FLAT - BACK | Acoustic | 29.08 | 6.83 | 16.69 | 3.52 | 20.21 | 35.00 | -14.79 | M4 | 2,3,6 |
| G3W1300 | 512 | FLAT - FRONT | Acoustic | 29.08 | 8.58 | 18.67 | 3.52 | 22.19 | 35.00 | -12.81 | M4 | 1,2,3 |

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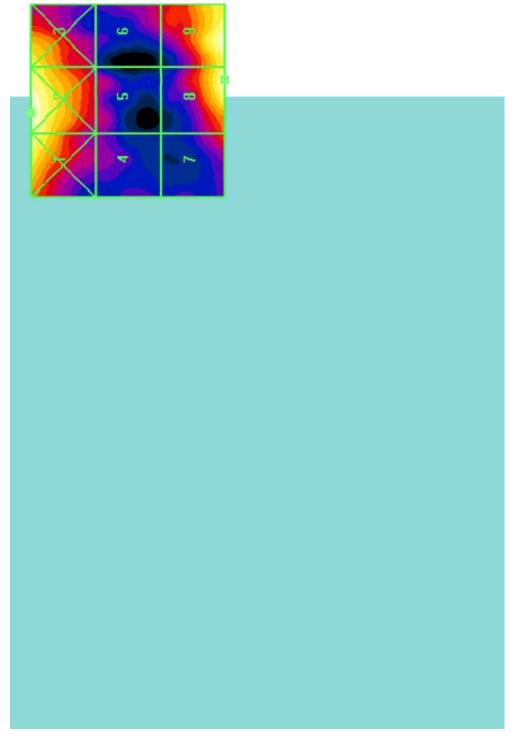


Figure 10-1
Sample E-field Scan Overlay (FLAT – FRONT)
(See Test Setup Photographs for actual WD overlay and FLAT – FRONT and FLAT – BACK Acoustic Centered Scan Area)

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II. Worst-case Configuration Evaluation

Table 10-2
Peak Reading 360° Probe Rotation at Azimuth axis

| | | | can inca | aning 500 | 11000 | Notatioi | I at Aziii | iutii axis | , | | |
|----------------|------------------------------|--------------------------|-------------|-----------------------------|---------------------------------|-------------|---|----------------------|--------------------|--------|------------------------|
| Mode | Channel | Device Posture / Side | Scan Center | Time Avg. Field (V/m) | Time Avg. Field [dB(V/m)] | MIF (dB) | Audio Interference Level [dB(V/m)] | FCC Limit (dBV/m) | FCC Margin (dB) | Result | Excl Blocks per 5.5 |
| Probe Rotation | Probe Rotation at Worst-Case | | | | | | | | | | |
| GSM1900 | 512 | FLAT - FRONT | Acoustic | 9.25 | 19.32 | 3.52 | 22.84 | 35.00 | -12.16 | M4 | 1,2,3 |

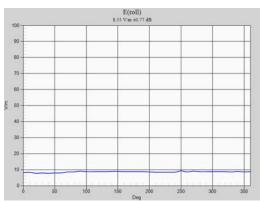


Figure 10-2
Worst-Case Probe Rotation about Azimuth axis

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^{*} Note: Locations of probe rotation (with and without exclusions) are shown in Figure 10-1 denoted by the green square markers.

11. **EQUIPMENT LIST**

Table 11-1 Equipment List

| Manufacturer | Model | Description | Cal Date | Cal Interval | Cal Due | Serial Number |
|-----------------------|-----------|-------------------------------------|-----------|--------------|-----------|---------------|
| Agilent | E4438C | ESG Vector Signal Generator | 5/6/2021 | Annual | 5/6/2022 | MY42082659 |
| Agilent | N5182A | MXG Vector Signal Generator | 9/25/2020 | Annual | 9/25/2021 | US46240505 |
| Keysight Technologies | N9020A | MXA Signal Analyzer | 9/22/2020 | Annual | 9/22/2021 | MY54500644 |
| Amplifier Research | 15S1G6 | Amplifier | N/A | CBT* | N/A | 433978 |
| Anritsu | MA24106A | USB Power Sensor | 3/2/2021 | Annual | 3/2/2022 | 1244524 |
| Anritsu | MA2411B | Pulse Power Sensor | 2/5/2021 | Annual | 2/5/2022 | 0846215 |
| Anritsu | ML2496A | Power Meter | 2/19/2021 | Annual | 2/19/2022 | 1138001 |
| Control Company | 4040 | Therm./ Clock/ Humidity Monitor | 3/6/2020 | Biennial | 3/6/2022 | 200170289 |
| Mini-Circuits | NLP-2950+ | Low Pass Filter DC to 2700 MHz | N/A | CBT* | N/A | N/A |
| Mini-Circuits | BW-N20W5 | Power Attenuator | N/A | CBT* | N/A | 1226 |
| Pasternack | PE2237-20 | Bidirectional Coupler | N/A | CBT* | N/A | N/A |
| Rohde & Schwarz | CMW500 | Wideband Radio Communication Tester | 3/22/2021 | Annual | 3/22/2022 | 162125 |
| Seekonk | NC-100 | Torque Wrench (8" lb) | 8/4/2020 | Biennial | 8/4/2022 | N/A |
| SPEAG | AIA | Audio Interference Analzyer | N/A | CBT* | N/A | 1010 |
| SPEAG | EF3DV3 | Freespace E-field Probe | 2/15/2021 | Biennial | 2/15/2023 | 4035 |
| SPEAG | CD1880V3 | Freespace 1880 MHz Dipole | 1/14/2021 | Biennial | 1/14/2023 | 1137 |
| SPEAG | DAE4 | Dasy Data Acquisition Electronics | 1/13/2021 | Annual | 1/13/2022 | 1530 |

Calibration traceable to the National Institute of Standards and Technology (NIST).

*Note: CBT (Calibrated Before Testing). Prior to testing, the measurement paths containing a cable, attenuator, coupler or filter were connected to a calibrated source (i.e. a signal generator) to determine the losses of the measurement path. The power meter offset was then adjusted to compensate for the measurement system losses. This level offset is stored within the power meter before measurements are made. This calibration verification procedure applies to the system verification and output power measurements. The calibrated reading is then taken directly from the power meter after compensation of the losses for all final power measurements.

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12. MEASUREMENT UNCERTAINTY

Table 12-1Uncertainty Estimation Table

| Wireless Communications Device Near-Field Measurement | | | | | | | | | | |
|--|----------|-----------|---|------|---|------|---------------------------------|--|--|--|
| Uncertainty Estimation | | | | | | | | | | |
| Uncertainty Component Data (dB) Data Type Prob. Dist. Divisor Ci (E) Unc. (dB) Notes/Comments | | | | | | | | | | |
| Measurement System | | | | | | | | | | |
| RF System Reflections | 0.50 | Tolerance | N | 1.00 | 1 | 0.50 | * Refl. < -20 dB | | | |
| Field Probe Calibration | 0.21 | Tolerance | N | 1.00 | 1 | 0.21 | | | | |
| Field Probe Isotropy | 0.01 | Tolerance | N | 1.00 | 1 | 0.01 | | | | |
| Field Probe Frequency Response | 0.135 | Tolerance | N | 1.00 | 1 | 0.14 | | | | |
| Field Probe Linearity | 0.013 | Tolerance | N | 1.00 | 1 | 0.01 | | | | |
| Modulation Interference Factor | 0.20 | Tolerance | R | 1.73 | 1 | 0.12 | Applicable for M-rating testing | | | |
| Boundary Effects | 0.105 | Accuracy | R | 1.73 | 1 | 0.06 | * | | | |
| Probe Positioning Accuracy | 0.20 | Accuracy | R | 1.73 | 1 | 0.12 | * | | | |
| Probe Positioner | 0.050 | Accuracy | R | 1.73 | 1 | 0.03 | * | | | |
| Extrapolation/Interpolation | 0.045 | Tolerance | R | 1.73 | 1 | 0.03 | * | | | |
| Resolution to 2mm error | 0.21 | Tolerance | N | 1.00 | 1 | 0.21 | | | | |
| System Detection Limit | 0.05 | Tolerance | R | 1.73 | 1 | 0.03 | * | | | |
| Readout Electronics | 0.015 | Tolerance | N | 1.00 | 1 | 0.02 | * | | | |
| Integration Time | 0.11 | Tolerance | R | 1.73 | 1 | 0.06 | * | | | |
| Response Time | 0.033 | Tolerance | R | 1.73 | 1 | 0.02 | * | | | |
| Phantom Thickness | 0.10 | Tolerance | R | 1.73 | 1 | 0.06 | * | | | |
| System Repeatability (Field x 2=power) | 0.17 | Tolerance | N | 1.00 | 1 | 0.17 | * | | | |
| Test Sample Related | | | | | | | | | | |
| Device Positioning Vertical | 0.2 | Tolerance | R | 1.73 | 1 | 0.12 | * | | | |
| Device Positioning Lateral | 0.045 | Tolerance | R | 1.73 | 1 | 0.03 | * | | | |
| Device Holder and Phantom | 0.1 | Tolerance | R | 1.73 | 1 | 0.06 | * | | | |
| Power Drift | 0.21 | Tolerance | R | 1.73 | 1 | 0.12 | | | | |
| Combined Standard Uncertainty (k=1) | | | | | | 0.66 | 16.3% | | | |
| Expanded Uncertainty [95% confidence] | | | | | | 1.31 | 32.6% | | | |
| Expanded Uncertainty [95% confidence] | on Field | | | | | 0.66 | 16.3% | | | |

Notes:

- Test equipments are calibrated according to techniques outlined in NIS81, NIS3003 and NIST Tech Note 1297. All
 equipments have traceability according to NIST. Measurement Uncertainties are defined in further detail in NIS 81
 and NIST Tech Note 1297 and UKAS M3003.
- 2. * Uncertainty specifications from Schmidt & Partner Engineering AG (not site specific)

Measurement uncertainty reflects the quality and accuracy of a measured result as compared to the true value. Such statements are generally required when stating results of measurements so that it is clear to the intended audience that the results may differ when reproduced by different facilities. Measurement results vary due to the measurement uncertainty of the instrumentation, measurement technique, and test engineer. Most uncertainties are calculated using the tolerances of the instrumentation used in the measurement, the measurement setup variability, and the technique used in performing the test. While not generally included, the variability of the equipment under test also figures into the overall measurement uncertainty. Another component of the overall uncertainty is based on the variability of repeated measurements (so-called Type A uncertainty). This may mean that the Hearing Aid immunity tests may have to be repeated by taking down the test setup and resetting it up so that there are a statistically significant number of repeat measurements to identify the measurement uncertainty. By combining the repeat measurement results with that of the instrumentation chain using the technique contained in NIS 81 and NIS 3003, the overall measurement uncertainty was estimated.

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13. TEST DATA

See following Attached Pages for Test Data.

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Date: 8/2/2021



DUT: CD1880V3 - SN1137

Type: CD1880V3 Serial: 1137

Communication System: CW; Frequency: 1880 MHz;

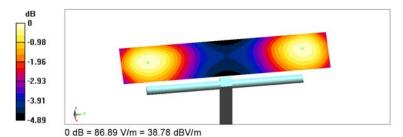
Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY5 Configuration:

- Probe: EF3DV3 SN4035; Calibrated: 2/15/2021
- Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE4 Sn1530; Calibrated: 1/13/2021
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA;
- Measurement SW: DASY52, Version 52.10 (4);

1880 MHz / 100mW HAC Dipole Validation at 15mm/Hearing Aid Compatibility Test (41x181x1):

Interpolated grid: dx=0.5000 mm, dy=0.5000 mm
Device Reference Point: 0, 0, -6.3 mm
Reference Value = 158.8 V/m; Power Drift = 0.05 dB
Applied MIF = 0.00 dB
Average Value of Peak (interpolated) = 86.5 V/m



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DUT: A3LSMF926B

Type: Portable Handset Serial: 0528M Backlight off Duty Cycle: 1:8.3

Communication System: GSM; Frequency: 1850.2 MHz;

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY5 Configuration:

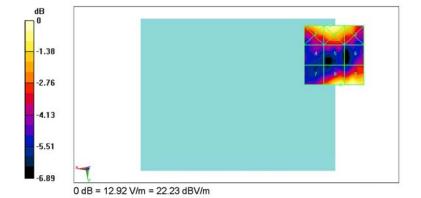
- Probe: EF3DV3 SN4035; Calibrated: 2/15/2021
- Sensor-Surface: (Fix Surface)
- Electronics: DAE4 Sn1530; Calibrated: 1/13/2021
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA;
- Measurement SW: DASY52, Version 52.10 (4);

GSM1900 Low Channel, FLAT - FRONT /Hearing Aid Compatibility Test (101x101x1):

Interpolated grid: dx=0.5000 mm, dy=0.5000 mm
Device Reference Point: 0, 0, -6.3 mm
Reference Value = 6.880 V/m; Power Drift = 0.11 dB
Applied MIF = 3.52 dB
RF audio interference level = 22.19 dBV/m
Emission category: M4

MIF scaled E-field

| Grid 1 M4 | Grid 2 M4 | Grid 3 M4 |
|-------------|-------------|-------------|
| 21.82 dBV/m | 22.24 dBV/m | 21.34 dBV/m |
| Grid 4 M4 | Grid 5 M4 | Grid 6 M4 |
| 18.22 dBV/m | 18.67 dBV/m | 18.81 dBV/m |
| Grid 7 M4 | Grid 8 M4 | Grid 9 M4 |
| 19.7 dBV/m | 22.19 dBV/m | 22.17 dBV/m |



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CALIBRATION CERTIFICATES 14.

The following pages include the probe calibration used to evaluate HAC for the DUT.

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6/22/2020

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Client

PC Test

Certificate No: EF3_4035_Feb21

C

Calibration procedure(s) Calibration procedure(s) Calibration procedure(s) Calibration procedure for E-field probes optimized for close near field evaluations in air Calibration date: February 15, 2021 This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%. Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID | Cal Date (Certificate No.) | Scheduled Calibration |
|----------------------------|------------------|-----------------------------------|------------------------|
| Power meter NRP | SN: 104778 | 01-Apr-20 (No. 217-03100/03101) | Apr-21 |
| Power sensor NRP-Z91 | SN: 103244 | 01-Apr-20 (No. 217-03100) | Apr-21 |
| Power sensor NRP-Z91 | SN: 103245 | 01-Apr-20 (No. 217-03101) | Apr-21 |
| Reference 20 dB Attenuator | SN: CC2552 (20x) | 31-Mar-20 (No. 217-03106) | Apr-21 |
| DAE4 | SN: 789 | 23-Dec-20 (No. DAE4-789_Dec20) | Dec-21 |
| Reference Probe ER3DV6 | SN: 2328 | 05-Oct-20 (No. ER3-2328_Oct20) | Oct-21 |
| Secondary Standards | ID | Check Date (in house) | Scheduled Check |
| Power meter E4419B | SN: GB41293874 | 06-Apr-16 (in house check Jun-20) | In house check: Jun-22 |
| Power sensor E4412A | SN: MY41498087 | 06-Apr-16 (in house check Jun-20) | In house check; Jun-22 |
| Power sensor E4412A | SN: 000110210 | 06-Apr-16 (in house check Jun-20) | In house check: Jun-22 |
| RF generator HP 8648C | SN: US3642U01700 | 04-Aug-99 (in house check Jun-20) | In house check: Jun-22 |
| Network Analyzer E8358A | SN: US41080477 | 31-Mar-14 (in house check Oct-20) | In house check: Oct-21 |

| Name | Function | Signature |
|---------------|--|--|
| Michael Weber | Laboratory Technician | 1/11// |
| | | MINESEL |
| Kafia Pokovic | ToobserlW | |
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| | | Issued: February 16, 2021 |
| | SCAR DISTACCIONISCIMINATES CON ARCES CONTRACTOR CONTRAC | Michael Weber Laboratory Technician |

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Glossary:

NORMx,y,z sensitivity in free space DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal modulation dependent linearization parameters A, B, C, D incident E-field orientation normal to probe axis En Εp incident E-field orientation parallel to probe axis

Polarization φ ϕ rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., $\vartheta = 0$ is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005

b) CTIA Test Plan for Hearing Aid Compatibility, Rev 3.1.1, May 2017

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z*: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- $NORM(f)x,y,z = NORMx,y,z * frequency_response$ (see Frequency Response Chart).
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z; Dx,y,z; VRx,y,z: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

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EF3DV3 - SN:4035 February 15, 2021

DASY/EASY - Parameters of Probe: EF3DV3 - SN:4035

Basic Calibration Parameters

| | Sensor X | Sensor Y | Sensor Z | Unc (k=2) |
|------------------------|----------|----------|----------|-----------|
| Norm $(\mu V/(V/m)^2)$ | 0.90 | 0.73 | 1.19 | ± 10.1 % |
| DCP (mV) ^B | 96.3 | 101.2 | 98.2 | |

| Frequency | Target E-Field | Measured | Deviation | Measured | Deviation | Unc (k=2) |
|-----------|----------------|--------------|-----------|--------------|-----------|-----------|
| MHz | V/m | E-field (En) | E-normal | E-field (Ep) | E-normal | % ´ |
| | | V/m | in % | V/m | in % | |
| 30 | 77.1 | 77.0 | -0.2% | 77.2 | 0.1% | ± 5.1 % |
| 100 | 77.2 | 78.3 | 1.4% | 77.8 | 0.7% | ± 5.1 % |
| 450 | 77.2 | 78.4 | 1.6% | 77.9 | 1.0% | ± 5.1 % |
| 600 | 77.1 | 77.9 | 1.1% | 77.4 | 0.5% | ± 5.1 % |
| 750 | 77.1 | 77.8 | 0.9% | 77.3 | 0.3% | ± 5.1 % |
| 1800 | 143.1 | 139.0 | -2.8% | 139.4 | -2.6% | ± 5.1 % |
| 2000 | 135.1 | 131.3 | -2.7% | 131.5 | -2.6% | ± 5.1 % |
| 2200 | 127.7 | 123.4 | -3.3% | 124.5 | -2.5% | ± 5.1 % |
| 2500 | 125.5 | 122.4 | -2.5% | 123.5 | -1.6% | ± 5.1 % |
| 3000 | 79.4 | 75.6 | -4.7% | 76.7 | -3.3% | ± 5.1 % |
| 3500 | 256.9 | 246.8 | -3.9% | 243.9 | -4.8% | ± 5.1 % |
| 3700 | 251.2 | 240.8 | -4.2% | 237.9 | -5.0% | ± 5.1 % |
| 5200 | 50.8 | 51.4 | 1.3% | 51.7 | 1.9% | ± 5.1 % |
| 5500 | 47.0 | 46.8 | -0.5% | 48.2 | 2.7% | ± 5.1 % |
| 5800 | 48.8 | 48.6 | -0.6% | 47.1 | -3.6% | ± 5.1 % |

Calibration Results for Modulation Response

| UID | Communication System Name | | A dB | B dB√μV | С | D dB | VR mV | Max dev. | Unc ^E (k=2) |
|-----|---------------------------|---|---------|------------|-----|---------|----------|-------------|---------------------------|
| 0 | CW | X | 0.0 | 0.0 | 1.0 | 0.00 | 141.8 | ± 3.8 % | ± 4.7 % |
| | | Y | 0.0 | 0.0 | 1.0 | | 172.6 | | |
| | | Z | 0.0 | 0.0 | 1.0 | | 171.7 | | |

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

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B Numerical linearization parameter: uncertainty not required.
E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

EF3DV3 - SN:4035 February 15, 2021

DASY/EASY - Parameters of Probe: EF3DV3 - SN:4035

Sensor Frequency Model Parameters

| | Sensor X | Sensor Y | Sensor Z |
|----------------------|----------|----------|----------|
| Frequency Corr. (LF) | 0.22 | 0.19 | 5.72 |
| Frequency Corr. (HF) | 2.82 | 2.82 | 2.82 |

Other Probe Parameters

| Sensor Arrangement | Rectangular |
|---|-------------|
| Connector Angle (°) | -126.8 |
| Mechanical Surface Detection Mode | enabled |
| Optical Surface Detection Mode | disabled |
| Probe Overall Length | 337 mm |
| Probe Body Diameter | 12 mm |
| Tip Length | 25 mm |
| Tip Diameter | 4 mm |
| Probe Tip to Sensor X Calibration Point | 1.5 mm |
| Probe Tip to Sensor Y Calibration Point | 1.5 mm |
| Probe Tip to Sensor Z Calibration Point | 1.5 mm |

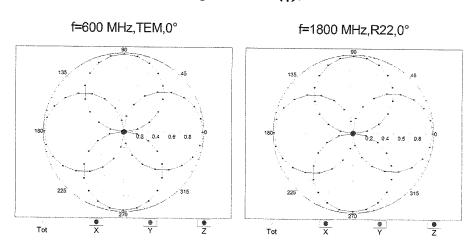
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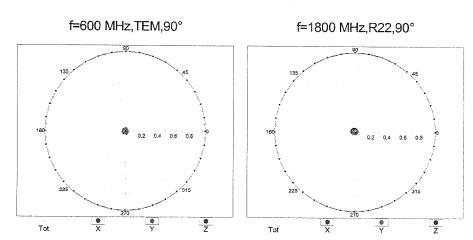
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Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$



Receiving Pattern (ϕ), $\vartheta = 90^{\circ}$



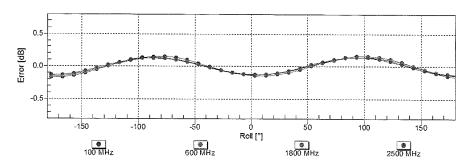
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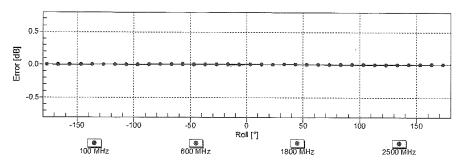
EF3DV3 – SN:4035 February 15, 2021

Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Receiving Pattern (ϕ), $\vartheta = 90^{\circ}$



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

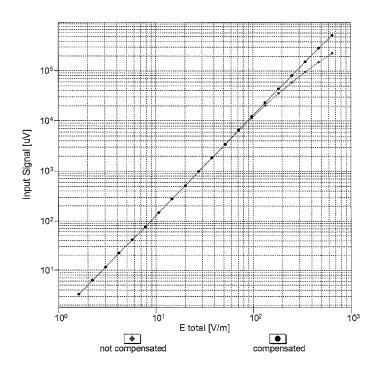
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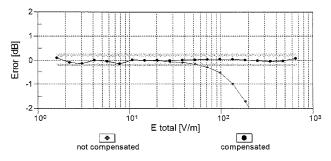
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Dynamic Range f(E-field) (TEM cell, f = 900 MHz)





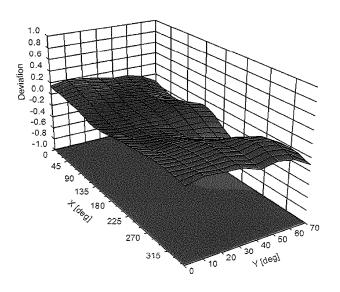
Uncertainty of Linearity Assessment: ± 0.6% (k=2)

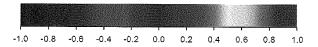
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Deviation from Isotropy in Air Error (ϕ, ϑ) , f = 900 MHz





Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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PC Test

Certificate No: CD1880V3-1137_Jan21

| Object | CD1880V3 - SN: | 1137 | |
|--|-----------------------------------|---|--|
| Calibration procedure(s) | QA CAL-20.v7 Calibration Proce | dure for Validation Sources in ai | r |
| Calibration date: | January 14, 2021 | | |
| The measurements and the uncert | ainties with confidence p | onal standards, which realize the physical unrobability are given on the following pages an y facility: environment temperature $(22 \pm 3)^{\circ}$ 0 | nd are part of the certificate. |
| Primary Standards | ID# | Cal Data (Cartificate No.) | Cabadulad Calibration |
| Power meter NRP | SN: 104778 | Cal Date (Certificate No.) 01-Apr-20 (No. 217-03100/03101) | Scheduled Calibration Apr-21 |
| Power sensor NRP-Z91 | SN: 103244 | 01-Apr-20 (No. 217-03100) | Apr-21 |
| Power sensor NRP-Z91 | SN: 103245 | 01-Apr-20 (No. 217-03100) | Apr-21 |
| Reference 20 dB Attenuator | SN: BH9394 (20k) | 31-Mar-20 (No. 217-03101) | |
| Type-N mismatch combination | SN: 310982 / 06327 | | Apr-21 |
| Probe EF3DV3 | SN: 4013 | 31-Mar-20 (No. 217-03104) | Apr-21 |
| DAE4 | SN: 781 | 28-Dec-20 (No. EF3-4013_Dec20) 23-Dec-20 (No. DAE4-781_Dec20) | Dec-21 Dec-21 |
| Secondary Standards | I ID# | Oberly Bets (In house) | |
| | | Check Date (in house) | Scheduled Check |
| Power meter Agilent 4419B Power sensor HP E4412A | SN: GB42420191 | 09-Oct-09 (in house check Oct-20) | In house check: Oct-23 |
| Power sensor HP E4412A Power sensor HP 8482A | SN: US38485102 | 05-Jan-10 (in house check Oct-20) | In house check: Oct-23 |
| | SN: US37295597 | 09-Oct-09 (in house check Oct-20) | In house check: Oct-23 |
| RF generator R&S SMT-06 Network Analyzer Agilent E8358A | SN: 837633/005 SN: US41080477 | 10-Jan-19 (in house check Oct-20) 31-Mar-14 (in house check Oct-20) | In house check: Oct-23 In house check: Oct-21 |
| | Name | Function | Signature |
| Calibrated by: | Leif Klysner | Laboratory Technician | 0.000 |
| | | | Sed alger |
| Approved by: | Katia Dakayla | Tabalad Massac | |
| Approved by: | Katja Pokovic | Technical Manager | Mas- |
| | | | - |

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References

[1] ANSI-C63.19-2011

American National Standard, Methods of Measurement of Compatibility between Wireless Communications Devices and Hearing Aids.

Methods Applied and Interpretation of Parameters:

- Coordinate System: y-axis is in the direction of the dipole arms. z-axis is from the basis of the antenna
 (mounted on the table) towards its feed point between the two dipole arms. x-axis is normal to the other axes.
 In coincidence with the standards [1], the measurement planes (probe sensor center) are selected to be at a
 distance of 15 mm above the top metal edge of the dipole arms.
- Measurement Conditions: Further details are available from the hardcopies at the end of the certificate. All
 figures stated in the certificate are valid at the frequency indicated. The forward power to the dipole connector
 is set with a calibrated power meter connected and monitored with an auxiliary power meter connected to a
 directional coupler. While the dipole under test is connected, the forward power is adjusted to the same level.
- Antenna Positioning: The dipole is mounted on a HAC Test Arch phantom using the matching dipole positioner with the arms horizontal and the feeding cable coming from the floor. The measurements are performed in a shielded room with absorbers around the setup to reduce the reflections. It is verified before the mounting of the dipole under the Test Arch phantom, that its arms are perfectly in a line. It is installed on the HAC dipole positioner with its arms parallel below the dielectric reference wire and able to move elastically in vertical direction without changing its relative position to the top center of the Test Arch phantom. The vertical distance to the probe is adjusted after dipole mounting with a DASY5 Surface Check job. Before the measurement, the distance between phantom surface and probe tip is verified. The proper measurement distance is selected by choosing the matching section of the HAC Test Arch phantom with the proper device reference point (upper surface of the dipole) and the matching grid reference point (tip of the probe) considering the probe sensor offset. The vertical distance to the probe is essential for the accuracy.
- Feed Point Impedance and Return Loss: These parameters are measured using a Vector Network Analyzer.
 The impedance is specified at the SMA connector of the dipole. The influence of reflections was eliminating by applying the averaging function while moving the dipole in the air, at least 70cm away from any obstacles.
- E-field distribution: E field is measured in the x-y-plane with an isotropic E-field probe with 100 mW forward power to the antenna feed point. In accordance with [1], the scan area is 20mm wide, its length exceeds the dipole arm length (180 or 90mm). The sensor center is 15 mm (in z) above the metal top of the dipole arms. Two 3D maxima are available near the end of the dipole arms. Assuming the dipole arms are perfectly in one line, the average of these two maxima (in subgrid 2 and subgrid 8) is determined to compensate for any non-parallelity to the measurement plane as well as the sensor displacement. The E-field value stated as calibration value represents the maximum of the interpolated 3D-E-field, in the plane above the dipole surface.

| The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the |
|---|
| coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95% |

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Measurement Conditions

DASY system configuration, as far as not given on page 1.

| DASY Version | DASY5 | V52.10.4 |
|------------------------------------|--------------------------------------|----------|
| Phantom | HAC Test Arch | |
| Distance Dipole Top - Probe Center | 15 mm | |
| Scan resolution | dx, dy = 5 mm | |
| Frequency | 1730 MHz ± 1 MHz 1880 MHz ± 1 MHz | |
| Input power drift | < 0.05 dB | |

Maximum Field values at 1730 MHz

| E-field 15 mm above dipole surface | condition | Interpolated maximum |
|------------------------------------|--------------------|-------------------------|
| Maximum measured above high end | 100 mW input power | 94.2 V/m = 39.48 dBV/m |
| Maximum measured above low end | 100 mW input power | 93.8 V/m = 39.44 dBV/m |
| Averaged maximum above arm | 100 mW input power | 94.0 V/m ± 12.8 % (k=2) |

Maximum Field values at 1880 MHz

| E-field 15 mm above dipole surface | condition | Interpolated maximum |
|------------------------------------|--------------------|-------------------------|
| Maximum measured above high end | 100 mW input power | 88.0 V/m = 38.89 dBV/m |
| Maximum measured above low end | 100 mW input power | 87.8 V/m = 38.87 dBV/m |
| Averaged maximum above arm | 100 mW input power | 87.9 V/m ± 12.8 % (k=2) |

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Appendix (Additional assessments outside the scope of SCS 0108)

Antenna Parameters

Nominal Frequencies

| Frequency | Return Loss | Impedance |
|-----------|-------------|-----------------|
| 1730 MHz | 22.8 dB | 54.0 Ω + 6.4 jΩ |
| 1880 MHz | 21.4 dB | 56.8 Ω + 6.0 jΩ |
| 1900 MHz | 22.7 dB | 57.2 Ω + 3.0 jΩ |
| 1950 MHz | 27.9 dB | 52.3 Ω - 3.4 jΩ |
| 2000 MHz | 20.4 dB | 42.8 Ω + 5.2 jΩ |

3.2 Antenna Design and Handling

The calibration dipole has a symmetric geometry with a built-in two stub matching network, which leads to the enhanced bandwidth.

The dipole is built of standard semirigid coaxial cable. The internal matching line is open ended. The antenna is therefore open for DC signals.

Do not apply force to dipole arms, as they are liable to bend. The soldered connections near the feedpoint may be damaged. After excessive mechanical stress or overheating, check the impedance characteristics to ensure that the internal matching network is not affected.

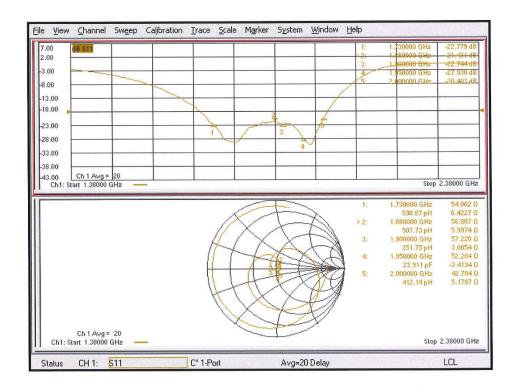
After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

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Impedance Measurement Plot



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DASY5 E-field Result

Date: 14.01.2021

Test Laboratory: SPEAG Lab2

DUT: HAC Dipole 1880 MHz; Type: CD1880V3; Serial: CD1880V3 - SN: 1137

Communication System: UID 0 - CW; Frequency: 1880 MHz, Frequency: 1730 MHz

Medium parameters used: $\sigma = 0$ S/m, $\varepsilon_r = 1$; $\rho = 0$ kg/m³

Phantom section: RF Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: EF3DV3 SN4013; ConvF(1, 1, 1) @ 1880 MHz, ConvF(1, 1, 1) @ 1730 MHz; Calibrated: 28.12.2020
- · Sensor-Surface: (Fix Surface)
- Electronics: DAE4 Sn781; Calibrated: 23.12.2020
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA; Serial: 1070
- DASY52 52.10.4(1527); SEMCAD X 14.6.14(7483)

Dipole E-Field measurement @ 1880MHz/E-Scan - 1880MHz d=15mm/Hearing Aid Compatibility Test (41x181x1):

Interpolated grid: dx=0.5000 mm, dy=0.5000 mm

Device Reference Point: 0, 0, -6.3 mm

Reference Value = 157.0 V/m; Power Drift = 0.02 dB

Applied MIF = 0.00 dB

RF audio interference level = 38.89 dBV/m

Emission category: M2

MIF scaled E-field

| Grid 1 M2 | Grid 2 M2 | Grid 3 M2 |
|------------------|------------------|------------------|
| 38.7 dBV/m | 38.87 dBV/m | 38.68 dBV/m |
| Grid 4 M2 | Grid 5 M2 | Grid 6 M2 |
| 36.04 dBV/m | 36.09 dBV/m | 35.98 dBV/m |
| Grid 7 M2 | Grid 8 M2 | Grid 9 M2 |
| 38.81 dBV/m | 38.89 dBV/m | 38.56 dBV/m |

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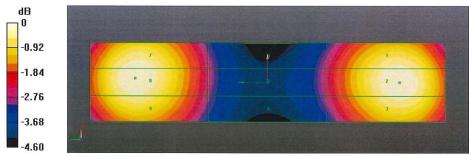
Dipole E-Field measurement @ 1880MHz/E-Scan - 1730MHz d=15mm/Hearing Aid Compatibility Test (41x181x1):

Interpolated grid: dx=0.5000 mm, dy=0.5000 mm Device Reference Point: 0, 0, -6.3 mm Reference Value = 169.8 V/m; Power Drift = 0.01 dB Applied MIF = 0.00 dB RF audio interference level = 39.48 dBV/m

Emission category: M2

MIF scaled E-field

| Grid 1 M2 | Grid 2 M2 | Grid 3 M2 |
|------------------|------------------|------------------|
| 39.27 dBV/m | 39.44 dBV/m | 39.24 dBV/m |
| Grid 4 M2 | Grid 5 M2 | Grid 6 M2 |
| 36.67 dBV/m | 36.74 dBV/m | 36.58 dBV/m |
| Grid 7 M2 | Grid 8 M2 | Grid 9 M2 |
| 39.39 dBV/m | 39.48 dBV/m | 39.13 dBV/m |



0 dB = 87.99 V/m = 38.89 dBV/m

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15. CONCLUSION

The measurements indicate that the flat (open) configuration for the referenced wireless communications device complies with the HAC limits specified in accordance with the ANSI C63.19 Standard and FCC WT Docket No. 01-309 RM-8658. Precise laboratory measures were taken to assure repeatability of the tests. The tested device complies with the requirements in respect to all parameters specific to the test. The test results and statements relate only to the item(s) tested.

Please note that the M-rating for this equipment only represents the field interference possible against a hypothetical and typical hearing aid. The measurement system and techniques presented in this evaluation are proposed in the ANSI standard as a means of best approximating wireless device compatibility with a hearing-aid. The literature is under continual re-construction.

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