# **Technical Description**

The Equipment Under Test (EUT) is a Home Theater Sound Bar. It can accept analog input sources: RCA aux-in and 3.5mm phone jack line-in; and digital input sources: optical and wireless Bluetooth device. The Bluetooth module in the EUT is operating in the frequency range from 2402MHz to 2480MHz (79 channels with 1MHz channel spacing). The audio signal is amplified and fed to the built-in stereo loudspeakers. The EUT is powered by 13VDC from an AC/DC adaptor. The AC/DC adaptor can accept only 120AC input voltage (100V-120VAC).

The EUT is using non-adaptive frequency hopping as declared by applicant.

# 2.4GHz Bluetooth Module: Modulation Type: GFSK

**Antenna Type: Integral, Internal (PCB Trace)** 

Frequency Range: 2402MHz - 2480MHz, 1MHz channel spacing, 79 channels

Nominal field strength is 93.8dBµV/m @ 3m Production Tolerance of field strength is +/- 3dB Antenna gain is 0dBi

The functions of main ICs are mentioned below.

#### 1. BlueTooth module BM81SPK01NB2 (BT1):

- 1) U1 (IS1681S) acts as the 2.4GHz radio core of Bluetooth module BT1 (BM81SPK01NB2), which is integrating with audio CODEC.
- 2) 16MHz crystal (X1) provides clock for Bluetooth RF IC IS1681S (U1).
- 3) U2 (24C32) is serial EEPROM for parameter backup of U1 (IS1681S).
- 4) IC17 (4558) acts as buffering amplifier driving the input of IC3 (CSC2314).

#### 2. Digital Audio Portion:

- 1) U6 (CS8416) acts as digital audio receiver which accepts SPDIF input.
- 2) JK5 (DLR1180) is optical receiver of TOSLINK optical input.
- 3) X2 (12.288MHz) provides 256Xfs (fs=48kHz) digital audio clock for U6.
- 4) U3 (DA1134) is 24bit/192kHz digital-to-analog converter for audio output.

#### 3. Analog audio processor module:

1) IC3 (CSC2314) acts as analog audio function including input selection, Volume, loudness, level, balance, bass and treble control.

#### 4. Power Amplifier portion:

1) IC1 (TDA7491P) is 2X10W power amplifier driving internal stereo speaker.

#### 5. MCU portion:

1) IC6 (BJ8F101M20A) is 8-bit MCU for system control.

## Channel Frequency Table of Bluetooth Module

CH. NO.	FRE.	Hex Value	CH. NO.	FRE.	Hex Value	CI	H. NO	FRE.	Hex Value	(	CH. NO	FRE.	Hex Value
CH0	2402MHz	0	CH26	2428MHz	1A	(	CH52	2454MHz	34		CH78	2480MHz	4E
CH1	2403MHz	1	CH27	2429MHz	1B	(	CH53	2455MHz	35				
CH2	2404MHz	2	CH28	2430MHz	1C	(	CH54	2456MHz	36				2
CH3	2405MHz	3	CH29	2431MHz	1D		CH55	2457MHz	37				
CH4	2406MHz	4	CH30	2432MHz	1E	(	CH56	2458MHz	38				V
CH5	2407MHz	5	CH31	2433MHz	1F	(	CH57	2459MHz	39				
CH6	2408MHz	6	CH32	2434MHz	20	(	CH58	2460MHz	3A				*
CH7	2409MHz	7	CH33	2435MHz	21	(	CH59	2461MHz	3B				
CH8	2410MHz	8	CH34	2436MHz	22	(	CH60	2462MHz	3C				V
CH9	2411MHz	9	CH35	2437MHz	23		CH61	2463MHz	3D				
CH10	2412MHz	Α	CH36	2438MHz	24		CH62	2464MHz	3E				
CH11	2413MHz	В	CH37	2439MHz	25		CH63	2465MHz	3F				
CH12	2414MHz	С	CH38	2440MHz	26		CH64	2466MHz	40				V
CH13	2415MHz	D	CH39	2441MHz	27	(	CH65	2467MHz	41				
CH14	2416MHz	E	CH40	2442MHz	28	(	CH66	2468MHz	42				2
CH15	2417MHz	F	CH41	2443MHz	29		CH67	2469MHz	43				
CH16	2418MHz	10	CH42	2444MHz	2A		CH68	2470MHz	44				V.
CH17	2419MHz	11	CH43	2445MHz	2B	(	CH69	2471MHz	45				
CH18	2420MHz	12	CH44	2446MHz	2C	(	CH70	2472MHz	46				9
CH19	2421MHz	13	CH45	2447MHz	2D		CH71	2473MHz	47				
CH20	2422MHz	14	CH46	2448MHz	2E		CH72	2474MHz	48				V
CH21	2423MHz	15	CH47	2449MHz	2 <b>F</b>	(	CH73	2475MHz	49				
CH22	2424MHz	16	CH48	2450MHz	30	(	CH74	2476MHz	4A				
CH23	2425MHz	17	CH49	2451MHz	31		CH75	2477MHz	4B				
CH24	2426MHz	18	CH50	2452MHz	32	(	CH76	2478MHz	4C				V
CH25	2427MHz	19	CH51	2453MHz	33		CH77	2479MHz	4D				



# **BM81SPK01**

**Bluetooth 3.0+EDR Wireless Speaker Module** 



# **Product Description**

The ISSC BM81SPK01 is a highly integrated Bluetooth 3.0+EDR stereo module, designed for high data rate, short-range wireless communication in the 2.4 GHz ISM band. With ISSC Bluetooth stack and profile, the ISSC BM81SPK01 provides a low power and ultra-low cost Bluetooth 3.0+EDR solution for wireless voice/audio applications.

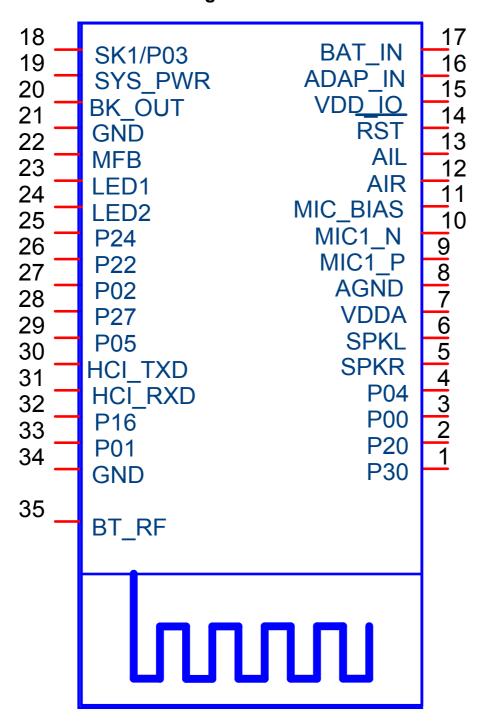
#### **Features**

- Main Chip: ISSC IS1681S
- Bluetooth 3.0+EDR compliant
- Typical +2dBm Class 2 output power
- Receiver Sensitivity: GFSK typical -91dBm, π/4 PSK typical -92dBm, 8DPSK typical -84dBm
- Piconet and Scatter net support
- HCI UART interface
- CVSD, A-law, μ-law CODEC algorithms for voice applications
- SBC decode for Bluetooth audio streaming
- Build-in High performance stereo audio codec
- Cap-less/single end headphone driver
- Audio DAC: 94dB SNR
- Build in Max. 350mAH Li-ion battery charger
- HSP, HFP, A2DP, AVRCP profile support
- 3V operating voltage
- ROM version: 32Kb EEPROM
- 34 pins for DIP module, 35pins for SMT module (with additional 35th pin antenna port for external antenna option)
- Size: 15mm x29mm
- Build-in PCB Antenna
- RoHS compliant

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# **Device Pinout Diagram**



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# **Pin Definition**

Pin De Pin No.	1/0	Name	Description
140.	., 0	1101110	GPIO, default pull-high input
1	Р	P30	Line-in detection, 1: no line-in detected; 0: line-in
'   '		1 00	detected
			GPIO, default pull-high input
2	1/0	P20	System Configuration, H: Application L:
_	"	. 20	Baseband(IBDK Mode)
_			GPIO, default pull-low input.
3	I/O	P00	Slide Switch Detector
_			GPIO, default pull-high input
4	I/O	P04	Audio AMP Enable
_	4.0	ODKD	R-channel analog headphone output, single-ended
5	AO	SPKR	application only
•	^	CDKI	L-channel analog headphone output, single-ended
6	AO	SPKL	application only
7	<b>4</b> D	\/DDA	Reserve for external cap to fine tune audio
7	AP	VDDA	frequency response
8	AP	AGND	Audio ground
9	Al	MIC1_P	Mic 1 mono differential analog positive input
10	Al	MIC1_N	Mic 1 mono differential analog negative input
11	AP	MIC_BIAS	Microphone biasing voltage
12	Al	AIR	Stereo analog line in, R-channel
13	Al	AIL	Stereo analog line in, L-channel
14	I/O	RST_N	System Reset Pin
15	Р	VDDIO	VDDIO pin, for calibration only
15	Г	VIDIO	Do not add external power to this pin
16	Р	ADAP_IN	Power adaptor input
17	Р	BAT_IN	Battery input
18	I/O	SK1/P03	Default SAR input for battery detection
10	",	01(1/1/03	This pin can be re-defined as GPIO P03
19	Р	SYS_PW	System Power Output
20	Р	BK_OUT	Buck feedback sense pin
21	Р	GND	Digital ground

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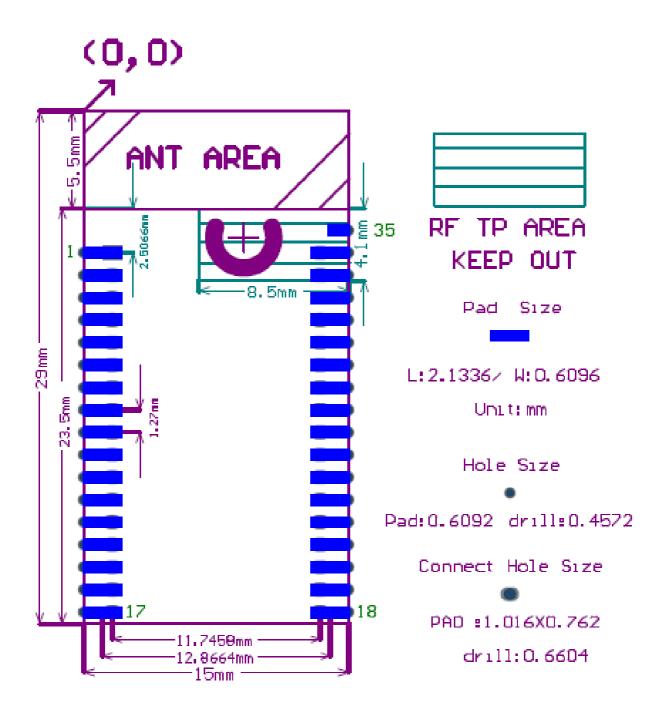
# Preliminary Datasheet BM81SPK01

			T
22	Р	MFB	Multi-Function Push Button key
			Combined Play/Pause key when A2DP enabled.
23	Р	LED1	LED Driver 1
24	Р	LED2	LED Driver 2
25	I/O	P24	GPIO, default pull-high input
25	1/0	P24	System Configuration, H: Boot Mode
26	1/0	Daa	GPIO, default pull-low input.
26	I/O	P22	External LDO enable
0.7	1/0	DOO	GPIO, default pull-high input
27	I/O	P02	PLAY/PAUSE button
00	1/0	D07	GPIO, default pull-high input
28	I/O	P27	Foward button
20	1/0	Doc	GPIO, default pull-high input
29	I/O	P05	REW button
30	0	HCI_TXD	HCI TX data
31	I	HXI_RXD	HCI RX data
20	1/0	D46	GPIO, default pull-high input
32	I/O	P16	Volumn down button
22	1/0	P01	GPIO, default pull-high input
33	33   I/O   P0		Volumn up button
34	Р	GND	Digital ground
25	A10	DT DE	NC for on board PCB antenna
35	AIO	BT_RF	Antenna matching if an external antenna is used
			•

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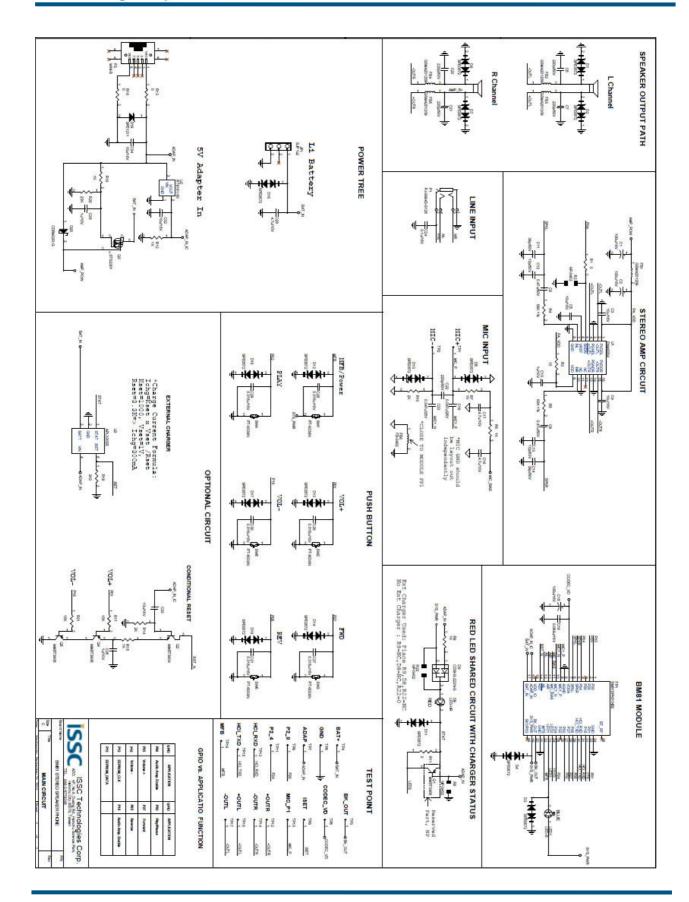


# **Outline Dimension (Module Foot print)**



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# Bluetooth 3.0+EDR Multimedia SOC

# 1. General Description

ISSC IS1681S is a compact, high integration, ultra-low cost, CMOS single-chip RF + baseband IC for Bluetooth v3.0+EDR (Enhanced Data Rate) 2.4GHz applications. This chip is fully compliant with Bluetooth specification and completely backward-compatible with Bluetooth 1.1, 1.2, 2.0 or 2.1 systems.

It incorporates Bluetooth 1M/2M/3Mbps RF, single-cycle 8051, TX/RX modem, memory controller, task/hopping controller, UART interface, and ISSC Bluetooth software stack to achieve the required Bluetooth v3.0+EDR functions.

The IS1681S is designed to support high quality audio applications, an audio engine and a high performance stereo CODEC are integrated for this purpose.

The audio engine provides the A-law/µ-law/CVSD voice encoding/decoding and also the SBC audio decoding. hanced noise reduction and echo cancellation to offer the best voice quality in the both sending and receiving sides.

In addition, to minimize the external components required for portable devices, a voltage sensor for battery, Li-ion battery charger, a switching regulator and LDOs are integrated to reduce BOM cost for various Bluetooth applications.

The device incorporates built-in self-test (BIST) and auto-calibration functions to simplify production test.

Phone: 886-3-577-8385 Fax: 886-3-577-8501



#### 2. Features

#### **System Specification**

Compliant with Bluetooth Specification v.3.0 + EDR in 2.4 GHz ISM band

#### **Baseband Hardware**

- 16MHz main clock input
- Built-in internal ROM for program memory
- Built-in 32 KB RAM for data storage and baseband data transfer buffering
- Enhanced Power Control
- Bluetooth 2.1 features
  - Encryption Pause and Resume
  - Erroneous Data Reporting
  - Extended Inquiry Response
  - Link Supervision Timeout Changed Event
  - Non-Flushable Packet Boundary Flag
  - Secure Simple Pairing
  - Sniff Subtracting
- Support both Pico-net and Scatter-net applications
- Hard-wired logic for modulation, demodulation, access code correlation, whitening, forward error correction (FEC), header error check (HEC), shorten hamming code, CRC generation/checking, frame check sequence (FCS), encryption bit stream generation, and transmit pulse shaping
- Adaptive Frequency Hopping (AFH) avoids occupied RF channels

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Fast Connection supported

#### **RF Hardware**

- Fully Bluetooth 3.0 + EDR system in 2.4 GHz ISM band.
- Combined TX/RX RF terminal simplifies external matching and reduces external antenna switches.
- Max. +4dBm output power with 20 dB level control from register control.
- Build-in T/R switch for Class 2/3 application
- Build-in channel filter.
- To avoid temperature variation, temperature sensor with temperature calibration is utilized into bias current and gain control.
- Fully integrated synthesizer has been created. There requires no external VCO,
   varactor diode, resonator and loop filter.
- Crystal oscillation with build-in digital trimming for temperature/process variations.

#### Audio processor

- Support 64 kb/s A-Law or μ-Law PCM format, or CVSD (Continuous Variable Slope Delta Modulation) for SCO channel operation.
- Noise suppression
- Echo suppression
- SBC decoding
- Packet error concealment

#### **Audio Codec**

16 bit stereo codec

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- 94dB SNR DAC playback
- Integrate headphone amplifier for  $16\Omega$  speakers

# **Peripherals**

- Built-in Lithium-ion battery charger
- Integrate 3V, 1.8V LDO and Switching mode regulator
- Built-in 10-bit Aux-ADC for battery monitor and voltage sense.
- LED driver

#### Flexible HCI interface

• High speed HCI-UART (Universal Asynchronous Receiver Transmitter) interface

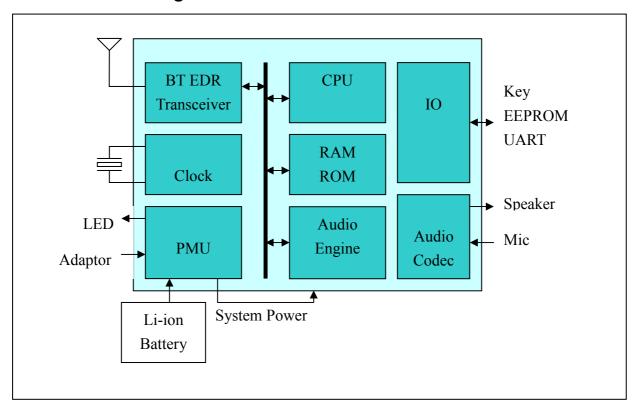
# **Package**

• 7x7mm<sup>2</sup> 56 pins, 0.4mm pitch SAW QFN standard package

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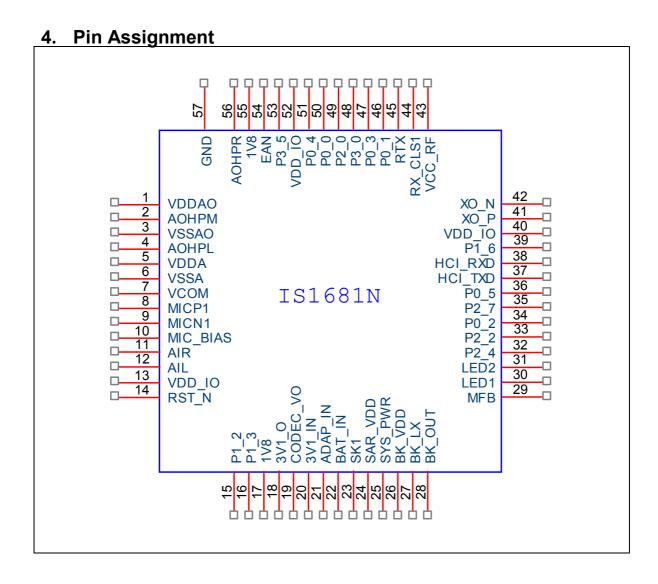


# 3. Functional Diagram



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# **5 Pin Descriptions**

Pin No.	I/O	Pin Name	Pin Descriptions
1	Р	VDDAO	Positive power supply dedicated to CODEC output amplifiers.
2	AO	AOHPM	Headphone common mode output/sense input
3	Р	VSSAO	Negative power supply dedicated to CODEC output amplifiers
4	AO	AOHPL	L-channel analog headphone output
5	Р	VDDA	Positive power supply/reference voltage for CODEC
6	Р	VSSA	Negative reference/power supply for CODEC
7	AO	VCOM	Internal biasing voltage for CODEC
8	Al	MICP1	Mic 1 mono differential analog positive input
9	Al	MICN1	Mic 1 mono differential analog negative input
10	Р	MIC_BIAS	Electric microphone biasing voltage
11	Al	AIR	R-channel single-ended analog inputs
12	Al	AIL	L-channel single-ended analog inputs
13	Р	VDD_IO	I/O power supply input
14	٨١	DCT N	KEY PIN for FT Test
14	Al	RST_N	System Reset Pin
			GPIO, default pull-high input
15	I/O	P1 2	KEY PIN for FT Test
15	1/0		EEPROM clock SCL
			Clock signal for OLED
			GPIO, default pull-high input
16	1/0	D4 2	KEY PIN for FT Test
10	1/0	P1_3	EEPROM data SDA
			Data signal for OLED
17	Р	1V8	Core 1.8V power input
18	Р	3V1_O	3.1V LDO output
19	Р	CODEC_VO	3.1V LDO output for CODEC power
20	Р	3V1_VIN	3.1V LDO input
21	Р	ADAP_IN	Power adaptor input
22	Р	BAT_IN	Battery input

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Pin No.	I/O	Pin Name	Pin Descriptions
23	Al	SK1	ADC analog input 1
24	Р	SAR_AVDD	SAR 1.8V input
25	Р	SYS_PWR	System Power Output
26	Р	BK_VDD	Buck VDD Power Input
27	Р	BK_LX	Buck feedback input
28	Р	BK_OUT	Buck output
29	Р	MFB	Multi-Function Push Button key, push high
30	Al	LED1	LED Driver 1
31	Al	LED2	LED Driver 2
			GPIO, default pull-high input
32	I/O	P2_4	KEY PIN for FT Test
			System Configuration, H: Boot Mode
			GPIO, default pull-low input.
33	I/O	P2_2	Keep alive for external LDO power enable
			application.
34	I/O	P0_2	GPIO, default pull-high input
34	1/0	F 0_2	Play/Pause key as the default setting
			GPIO, default pull-high input
35	I/O	P2_7	FWD key when class 2 RF
			FWD key(short press) when class 1 RF
			GPIO, default pull-high input
36	I/O	P0_5	KEY PIN for FT Test
	., 0	0_0	REV key when class 2 RF
			REV key(short press) when class 1 RF
37	0	HCI TXD	KEY PIN for FT Test
		1101_17.5	HCI TX data
38	1	HCI_RXD	KEY PIN for FT Test
	-		HCI RX data
			GPIO P1_6, default pull-high input
39	I/O	P1_6	Volume down key when class 2 RF
			Audio AMP Enable when class 1 RF
40	Р	VDD_IO	I/O power supply input
41	- 1	XO_P	16MHz Crystal input positive

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Pin No.	I/O	Pin Name	Pin Descriptions
42	ı	XO_N	16MHz Crystal input negative
43	RP	VCC_RF	RF power input for both synthesizer and TX/RX block
44	I	RX_CLASS1	Class1 RF RX path
45	I/O	RTX	Class2 RTX path; Class1/Class2 TX path
			GPIO, default pull-high input
46	I/O	DO 1	Volume up key when class 2 RF.
46	1/0	P0_1	Class1 Control signal of external TR switch when
			class 1 RF
			GPIO, default pull-high input
47	1/0	DO 3	KEY PIN for FT Test
47	I/O	P0_3	Class1 Control signal of external TR switch when
			class 1 RF
48	I/O	D2 0	GPIO, default pull-high input
40	1/0	P3_0	Reverved charger LED driver
			GPIO, default pull-high input
49	1/0	D2 0	KEY PIN for FT Test
49	I/O	P2_0	System Configuration, H: Application L:
			Baseband(IBDK Mode)
			GPIO, default pull-low input.
50	I/O	P0_0	KEY PIN for FT Test
			Slide Switch Detector
51	I/O	P0_4	GPIO, default pull-high input
51	1/0	F0_4	Audio AMP Enable when class 2 RF
52	Р	VDD_IO	I/O power supply input
53	I/O	P3_5	GPIO 3_5, default pull-high input.
55	1/0	F 3_3	Buzzer Signal Output
54	I	EAN	Embedded ROM/External Flash enable
54	ı	LAIN	H: Embedded; L: External Flash
55	Р	1V8	Core 1.8V power input
56	AO	AOHPR	R-channel single ended analog headphone output
57	Р	GND	Exposed pad as ground

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#### Application Note for GPIO Setting:

- 1) KEY PIN for internal test HCI\_RXD, HCI\_TXD, RST\_N, P2\_0, P2\_4, P1\_3, P1\_2, P0\_3, P0\_5, P0\_0
- 2) For Class2 RF application: VOL+:P0\_1, VOL-: P1\_6, FWD:P2\_7, REV:P0\_5, AUDIO AMP ENABLE: P0\_4
- 3) For Class1 RF application: VOL+:P2\_7(Long Press), VOL-: P0\_5(Long Press), FWD:P2\_7(Short Press), REV: P0\_5(Short Press), AUDIO AMP ENABLE: P1\_6
- 4) Play/Pause: P0\_2
- 5) P1\_2:EEPROM Clock/Clock Signal for OLED P1\_3:EEPROM Data/Data Signal for OLED
- 6) Slide switch detect: P0 0
- 7) Buzzer Signal Output: P3\_5
- 8) Class 1 RF TX: P0\_1, CLASS 1 RF RX: P0\_3
- 9) External LDO power enable keep alive: P2 2
- 10) System Configuration: P2 0, P2 4

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# **6 Functional Description**

#### 6.1 Overall Architecture

The ISSC IS1681S integrates an enhanced EDR Bluetooth RF & BB core, HCI controller, audio engine and an ENHANCED 8051 processor with an internal mask ROM for program memory and SRAM for data memory. An innovative interconnection structure called the Common-Memory Architecture (CMA) is designed to provide a fast and flexible data movement scheme between the embedded processor, Bluetooth core, and peripheral hardware.

For audio application and power management, IS1681S has build-in an audio processor, mono codec and power management unit to reduce the external components.

## 6.2 Radio Frequency (RF)

#### 6.2.1 Transmitter

The internal PA has a maximum output power of +4dBm with level control 20dB from amplitude control. This is applied into Class 2/3 radios without external RF PA. For Class1 application, the build-in level control can be used with external PA for power control requirement.

The transmitter features IQ direct conversion to minimize the frequency drift. And it can excess 30dB power range with temperature compensation machine.

#### 6.2.2 Receiver

The LNA can be operated into two type modes. One type is TR-combined mode for single port application. The other type is TR-separated mode for external PA/LNA application.

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An ADC is used to sample input analogue wave for digital demodulation. Before the ADC, a channel filter has been integrated into receiver channel to increase the anti-interference capacity and also reduce the external component count.

For avoiding temperature variation issues, a temperature sensor with temperature calibration is utilized into bias current and gain control of LNA, Mixers, and RF AMP.

#### 6.2.3 Synthesizer

The internal loop filter is used to reduce external RC components. This can reduce cost and variations for components. This internal LC tank for VCO is utilized to reduce variation for components. The cost is down at the same time.

A fully integrated synthesizer has been created. There requires no external VCO, varactor diode, resonator and loop filter.

#### 6.3 MODEM

There are three different modulations for Bluetooth v3.0 + EDR. Table 6.3 summarizes these modulations and data rate.

Figure 6.3 Modulation type for Bluetooth v3.0 + EDR

Data Rate	Modulation	Bits/Symbol
BDR: 1 Mbps	GFSK	1
EDR: 2 Mbps	π/4 DQPSK	2
EDR: 3 Mbps	8DPSK	3

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#### 6.3.1 Basic Data Rate MODEM (BDR)

On the Bluetooth v1.2 specification and below, 1 Mbps was the standard data rate based on Gaussian Frequency Shift Keying (GFSK) modulation scheme. This basic rate modem meets BDR requirements of Bluetooth v3.0+EDR specification.

Figure 6.3.1 Data format for BDR

Access Code Heade	Payload
-------------------	---------

# 6.3.2 Enhanced Data Rate MODEM (EDR)

On the Bluetooth v3.0+EDR specification, Enhanced Data Rate (EDR) has been introduced to provide 2 and 3 Mbps data rates as well as 1 Mbps. This enhanced data rate modem meets EDR requirements of Bluetooth v3.0+EDR specification. For the viewpoint of baseband, both BDR and EDR utilize the same 1MHz symbol rate and 1.6 KHz slot rate. For BDR, 1 symbol represents 1 bit. However each symbol in the payload part of EDR packets represents 2 or 3 bits. This is achieved by using two different modulations,  $\pi/4$  DQPSK and 8DPSK.

Figure 6.3.2.A Data format for EDR

Access Code	Header	Guard	Sync	Payload	Trailer	
-------------	--------	-------	------	---------	---------	--

For  $\pi/4$  DQPSK modulation, each symbol carries 2 bits of information. For its constellation diagram, although there are 8 possible phase states, the encoding scheme guarantees the trajectory of the modulation between symbols is restricted to 4 states. For a given starting



point, every phase change between symbols is restricted to +45°, +135°, -45°, and -135°.

Figure 6.3.2.B Phase shift & bit pattern for 2 MHz data rate

Phase Shift	Bit Pattern
+45° (+π/4)	00
+135° (+3π/4)	01
-135°(-3π/4)	11
-45°(-π/4)	10

For 8DPSK modulation, each symbol carries 3 bits of information. For its constellation diagram, it is similar to  $\pi/4$  DQPSK but the trajectory of the modulation between symbols has 8 possible phase states. For a given starting point, every phase change between symbols is restricted to 0°, +45°, +90°, +135°, +180°, -135°, -90°, and -45°.

Figure 6.3.2.C Phase shift & bit pattern for 3 MHz data rate

Phase Shift	Bit Pattern
0° (+0)	000
+45° (+π/4)	001
+90° (+π/2)	011
+135° (+3π/4)	010
+180° (+π)	110
-135° (-3π/4)	111
-90° (-π/2)	101

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-45° (-π/4)	100

#### 6.4 Baseband

The following modules implemented in hardware constitute the Bluetooth Baseband Core.

The frequency hopping sequence generator produces the correct hop frequency control sequence based on the Bluetooth clock, Bluetooth device address, and the current operating mode.

The access code generates the access code based on the Lower Address Part (LAP) of the Bluetooth device address. The access code is comprised of the preamble, sync word and trailer bits. The detection of the access code uses correlation to detect a valid access code.

Bluetooth uses two types of FEC: 1/3 repetition code and (15, 10) shorten Hamming code respectively. The former basically repeats each transmitted bit three times while the latter has 15 bits of codeword which contains 5 parity bits. The code has capability of correction of all single-bit errors in each codeword.

The purpose of HEC is to protect the header bits. Dedicated header error code generator calculates the HEC bits in the header of a transmitted packet. While on the receiver side, HEC detects corrupted headers.

A 16-bit CRC is adopted to protect payload data transmitted using certain types of Bluetooth packets.

Information confidentiality can be protected by encryption of the packet payload.

Dedicated encryption/decryption hardware is designed into the baseband core.



## 6.5 MCU

The embedded processor for IS1681S is a single-cycle 8051 CPU. The embedded processor will be referred to as simply the processor, 8051, or MCU throughout the remainder of this document. There are a few minor differences between a standard 8051 and this CPU. These include:

- Alteration of memory timings to match internal and external memory configurations.
- 2. Modification of idle mode to disable internal CPU clocking. Only externally-clocked interrupt sources can allow the CPU to recover from idle mode.

A single-port synchronous interface is provided to memory. From this single port, the bandwidth is divided among the 7 interfaces spread amongst 5 physical busses described below:

- Embedded processor bus
- Baseband TX bus
- Baseband RX bus
- HCl TX bus
- HCI RX bus
- Audio bus
- DMA bus

In addition, attached to the embedded processor bus are a register bank, a dedicated single-port memory (data segment 1), and flash memory (program segment). The processor coordinates all link control procedures and data movement using a set of pointer registers. For example, when an HCI packet (from the host via USB or UART) is received into the HCI buffer, the processor is interrupted. The processor can then read a

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status register to determine the HCl packet type and determine whether to set up the Baseband pointer registers for this memory region for RF-retransmission, or to otherwise directly perform packet processing with the CPU.

#### 6.6 Bluetooth Clock and Timers

A Bluetooth standard 28-bit counter running at 3.2 kHz implements the native clock defined by Bluetooth specification. This clock provides the transmission and receiving timing of a half time slot (312.5 µs). Another finer counter implemented in 16 bits is also provided as the phase of a half time slot. This phase information is very helpful when a Bluetooth slave wants to adapt to its master's clock. The counter is pre-scalable for the purpose of power saving operations. The diagram below describes a standard Bluetooth native clock and master clock. The clock signal is also used as a slot boundary signal to trigger a baseband packet transmission or receipt.

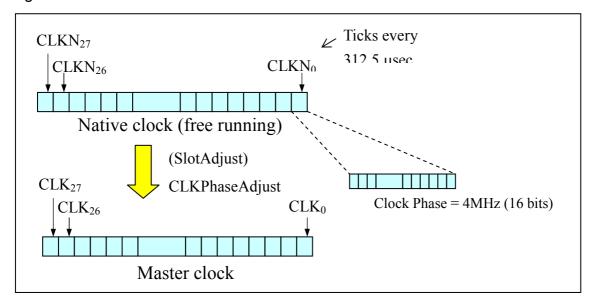
There are several timers provided by the system, two timers for TX/RX and the others for general purpose.

The powerful pre-scheduling functions for the transceiver are realized different sets of programmable timers. Each set of timers is associated with the task of transmission or receiving. When the timer is configured by firmware, it will automatically execute the TX or RX task at a specific time. Sub-tasks and timing for a TX task remain to be defined.

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Figure 6.6 Bluetooth clock



## 6.7 HCI Control Logic for USB/UART

Hardwired control logic is presented in front of the UART devices for HCI protocol handling and packet buffering. This control logic is part of the HCI controller defined in Bluetooth specification 1.2. This logic is partially responsible for the HCI protocol handling to/from the host and it also maps the registers of the UART devices indirectly to the 8051 such that the system can receive or send a HCI packet to/from the respective host interface. Major functions of this logic include:

- HCI packet formatter and de-formatter (identifying the packet type)
- Frame boundary determination, segmentation and reassembly of HCI packets.
- HCI packet transmission, receiving, and buffering (using common memory HCI buffer).
- Independent receive / transmit channels
- Universal device interface

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#### 6.7.1 HCI UART Interface

An embedded HCI UART (Universal Asynchronous Receiver Transmitter) with programmable data rate up to 3Mbps is included in this design. The HCI UART supports the following functions:

- Full-Duplex operation
- Programmable BAUD rate (using 16-bit input clock divider to obtain Baud Rate x16 or x24 or x13 clock base)
- 7 or 8 Data bits
- 1 or 2 Stop bits
- Even / Odd / Mark / Space / None Parity configurations
- Break Generation / Detection
- Maskable individual interrupts to CPU and combined Error interrupt to HCI
- Selectable Direct CPU interface or interface to HCI module

#### 6.8 General Purpose I/O

The IS1681S provides 14 general purpose I/O ports. These general I/Os can be defined as input or output port individually by setting specific register bit. While setting as an input port, a build-in  $50 \text{K}\Omega$  pull high or pull low resistor can be enabled for different application purpose.

#### 6.9 Audio Processor

The IS1681S builds in an enhanced audio engine to offer high quality of audio for voice application. The standard A-law/ $\mu$ -law/CVSD voice functions are implemented in the audio engine. The enhanced audio functions, like AEC, noise reduction, can be achieved with

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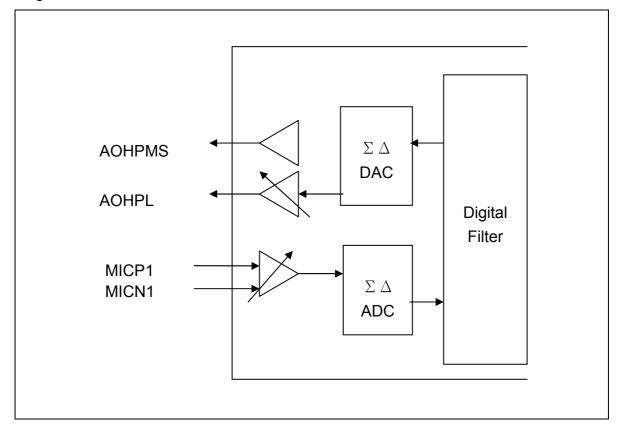


enhanced algorithm.

#### 6.10 Audio Codec

The build in codec contains a analog to digital convert (ADC), a digital to analog converter (DAC) and additional analog circuits like headphone driver and microphone amplifier.

Figure 6.10 Audio Codec



#### 6.10.1 ADC

The ADC interface supports variety sampling rate from 8k Hz to 48k Hz. The microphone input has 42 dB programmable analog gain and 48db digital gain. A regulated MIC\_Bias is available.

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#### 6.10.2 DAC

The DAC output is available for both line level and through the headphone amplifier to drive a low impedance headphone. The headphone output volume is adjustable by the combination of the digital/analog gain control.

# 6.11 Auxiliary ADC

The 10-bit auxiliary analog to digital converter (SAR ADC) provides one dedicated channel for battery power detection and one other channel for external peripheral sensing. This ADC has 10 bits resolution that provides an accurate monitoring for battery voltage. The operating current is very low and almost consumes no power when disabled.

#### 6.12 Power Management (PMU)

The power management unit of IS1681S includes several power control blocks, linear regulators, switch-mode regulator, Aux-ADC, LED driver and Lithium-ion/Polymer battery charger.

## 6.12.1 3V1\_LDO

The IS1681S has build-in the programmable output voltage LDOs (1.8~3.2V) for codec and digital IO power supply. The programmable LDO is used to regulate the high input voltage from battery or adapter. This LDO needs 1uF bypass capacitor.

#### 6.12.2 Buck regulator

The built-in programmable output voltage buck (1.8~2.4V) converts battery voltage for RF and baseband core power supply. This converter has high conversion efficiency and fast

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transient response.

#### 6.12.3 Aux-ADC

The 10-bit Successive-Approximation analog to digital converter (SAR ADC) monitors the battery power and adapter power for charging and power management control.

#### 6.12.4 Li-ion Battery Charger

IS1681S includes a built-in battery charger optimized for use with lithium polymer batteries.

The charger features a current sensor for charging control, user programmable current regulation and high accuracy voltage regulation. It charges the battery in four phases:

- reviving mode: 2mA charging current to charge BAT to 2.5V
- pre-charge mode: 0.1C charging current to charge BAT to 3.0V
- constant current mode : 0.xC (default 0.7C) charging current to charge BAT to 4.2V (programmable)
- constant voltage mode: charging is terminated while the charging current drops below 0.YC (default 0.13C)

Charging current in the constant current mode can be configured to provide a wide range of charging current up to 180mA (1mA per step). Charger will re-start charging if the battery voltage falls below an internal threshold.

System operation is allowed when the battery is charging.

#### 6.13 Miscellaneous (Watchdog Timer, and Clock Divider)

System related functions such as watchdog timer, Endian control, and interrupt vectors are

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# Preliminary Datasheet IS1681S

also provided. The purpose of the watchdog timer is to provide a reset to CPU in case when the CPU fails to service the watchdog timer in a pre-defined (programmable) period.

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# 7 Electrical Characteristics

# **Absolute Maximum Ratings**

Rating		Min	Max	Max
Operation Temperature	;	-40°C +85°C		
Core supply voltage	VDD_CORE, VCC_RF, AVDD_SAR, AVDD_PLL	1.7V	1.98V	V
Codec supply voltage	VDD_AUDIO		3.3	V
I/O voltage	VDD_IO		3.3	V
Supply voltage	BK_VDD		4.7	V
	3V1_VIN		5	V
	BAT_IN		4.3	V
	ADAP_IN		6	V
	LED[1:0]		5	V
	Power switch		6	V

# **Recommended Operate Condition**

Symbol	Parameter	Min	Typical	Max	Unit
$V_{DD18}$	Digital core supply voltage				
	SAR ADC supply voltage	1.62	1.8	1.92	V
	CODEC supply voltage				
$V_{DDIO}$	I/O supply voltage	2.5	2.7	2.2	\/
	RF supply voltage	2.5	2.7	3.3	V
T <sub>OPERATION</sub>	Operating temperature range	-20	+25	+70	°C
T <sub>stg</sub>	Storage temperature	-40		+125	°C
$V_{LDO}$	LDO supply voltage	1.8		3.3	V
V <sub>BAT_IN</sub>	Input voltage for SAR ADC	0.9		3.3	V

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# **Radio Characteristics:**

# **Transmitter section for BDR**

VCC_RF = 2.7V	Temperature =	Min	Тур	Max	Bluetooth	Unit
25°C		IVIIII	тур	IVIAX	specification	Offic
Maximum RF transmit power			3	4.0	-6 to 4	dBm
RF power variation over temperature range with compensation enabled			±2			dB
RF power control range			20		≥16	dB
RF power range cor	ntrol resolution		0.5			dB
20dB bandwidth for	modulated carrier		900		≤1000	KHz
ACP	$F = F_0 \pm 2MHz$		-28		≤-20	dBm
	$F = F_0 \pm 3MHz$		-46		≤-40	dBm
Note: F <sub>0</sub> =2441MHz	$F = F_0 \pm > 3MHz$		-54		≤-40	dBm
$\Delta f_{1avg}$ maximum modulation		150		165	140<∆f <sub>1avg</sub> <17 5	KHz
$\Delta f_{2max}$ maximum mo	dulation	140		150	≥115	KHz
$\Delta f_{2avg}/\Delta f_{1avg}$		0.95	1		≥0.80	
ICFT (abs)		0	5	10	75	KHz
Drift rate (abs)		2		7	≤20	KHz/50u
Drift (single slot packet, abs)			12		≤25	KHz
2 <sup>nd</sup> harmonic content @ Tx= 4dBm			-53		≤-47	dBm
3 <sup>rd</sup> harmonic conten	t @ Tx= 4dBm		-55		≤-47	dBm

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# **Receiver section for BDR**

Temperature = 25°C	Frequency (GHz)	Min	Тур	Max	Bluetooth specification	Unit
Sensitivity at 0.1% BER for all basic rate packet types	2.402		-91			
	2.441		-91		≤-70	dBm
	2.480		-91			
Maximum received signal at 0.1% BER			-10		≥-20	dBm
C/I co-channel			5		≤11	dB
Adjacent channel selectivity C/I  Note: F <sub>0</sub> =2441MHz	$F = F_0 + 1MHz$		-7		≥0	dB
	$F = F_0-1MHz$		-7		≥0	dB
	$F = F_0 + 2MHz$		-36		≤-30	dB
	$F = F_0-2MHz$		-22		≤-9	dB
	$F = F_0-3MHz$		-24		≤-20	dB
	$F = F_0 + 5MHz$		-50		≤-40	dB
	F = F <sub>image</sub>		-22		≤-9	dB
Maximum level of intermodulation interferers			-38		≥-39	dB

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# **Transmitter Section for EDR**

Temperature = 25°C		Min	Тур	Max	Bluetooth specification	Unit
Relative transmit power			-1.6		-4 to 1	dB
π/4 DQPSK max carrier frequency stability	$ \omega_{\circ} $ freq. error		5		≤10 for all blocks	KHz
	$ \omega_i $ initial freq. error		10		≤75 for all blocks	KHz
	$ \omega_o + \omega_i $ block freq. error		10		≤75 for all blocks	KHz
	$ \omega_o $ freq. error		5		≤10 for all blocks	KHz
8DPSK max carrier frequency stability	$ \omega_i $ initial freq. error		10		≤75 for all blocks	KHz
	$ \omega_o + \omega_i $ block freq.		10		≤75 for all blocks	KHz
#/4 DODSK	RMS DEVM		7		≤20	%
m/4 DQPSK modulation accuracy @ Tx= 2dBm	99% DEVM		Pass		≤30	%
	Peak DEVM			25	≤35	%
8DQPSK modulation accuracy @ Tx= 2dBm	RMS DEVM		7		≤13	%
	99% DEVM		Pass		≤20	%
	Peak DEVM			20	≤25	%

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	F > F <sub>0</sub> +3MHz	<-54	≤-40	dBm
	$F = F_0$ -3MHz	-46	≤-40	dBm
In-band spurious	$F = F_0$ -2MHz	-28	≤-20	dBm
emissions	$F = F_0-1MHz$	-30	≤-26	dBm
Note: F <sub>0</sub> =2441MHz	$F = F_0 + 1MHz$	-30	≤-26	dBm
	$F = F_0 + 2MHz$	-28	≤-20	dBm
	$F = F_0 + 3MHz$	-46	≤-40	dBm
EDR differential phase	encoding	100	≥99	%

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### **Receiver Section for EDR**

Temperature = 25°0	Frequenc y (GHz)	Modulatio n	Min	Тур	Max	Bluetooth specificatio n	Unit
	2.402	π/4 DQPSK		-92			
	2.441	π/4 DQPSK		-92		≤-70	dBm
Sensitivity at 0.01 BER	2.480	π/4 DQPSK		-92			
	2.402	8DPSK		-84			
	2.441	8DPSK		-84		≤-70	dBm
	2.480	8DPSK		-84			
	Maximum received signal at 0.1%			-10		≥-20	dBm
BER		8DPSK		-10		≥-20	
C/I co-channel at 0.	C/I co-channel at 0.1% BER			4		≤13	dB
		8DPSK		5		≤21	dB
	$F = F_0 + 1MHz$	π/4 DQPSK		-14		≤0	dB
		8DPSK		-8		≤5	dB
Adjacent channel selectivity C/I	$F = F_0-1MHz$	π/4 DQPSK		-13		≤0	dB
		8DPSK		-8		≤5	dB
Note: F <sub>0</sub> =2441MHz	$F = F_0 + 2MHz$	π/4 DQPSK		-38		≤-30	dB
		8DPSK		-34		≤-25	dB
	$F = F_0$ -2MHz	π/4 DQPSK		-21		≤-7	dB



# Preliminary Datasheet IS1681S

	8DPSK	-21	≤0	dB
$F = F_0$ -3MHz	π/4 DQPSK	-27	≤-20	dB
	8DPSK	-20	≤-13	dB
$F = F_0 + 5MH$	π/4 z DQPSK	-52	≤-40	dB
	8DPSK	-45	≤-33	dB
F = F <sub>image</sub>	π/4 DQPSK	-21	≤-7	dB
	8DPSK	-21	≤0	dB



**Audio Codec: ADC** 

**Test Condition:** 

T= 25°C, Vdd=2.8V, 1KHz sine wave input, Bandwidth = 20~20KHz

Parameter	Conditio	n	Min.	Тур.	Max.	Unit
Input full-scale	Full scale (lir	ne-in)			2.2	Vpp
Resolution				16		bits
Input Sampling Rate			8		48	kHz
SNR	f <sub>in</sub> =1KHz	8KHz		83		
	B/W=20~20KHz	16KHz		83		
	A-weighted THD+N < 1% 150mVpp input	32KHz		83		dB
		44.1KHz		83		
		48KHz		83		
SNR	A-weighted 1KHz@full scale,			75		dB
	Microphone boo	st enable				
THD+N (Mic input)				0.04		%
@30mVrms input						
THD+N (line input)				0.01		%
Mic Boost Gain				20		dB
Digital Gain			-54		4.85	dB
Analog Gain					26	dB
Digital Gain Step				6		dB
Analog Gain Step				1.7		dB
Input impedance	Input impedance			6	10	ΚΩ
(microphone mode)	Input capaci	tance			20	pF
Analog supply voltage (AVDD)			1.8	2.8	3.0	V

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**Audio Codec: DAC** 

Audio Codec. DAC								
Test Condition: T= 25°C, Vdd=2.8V, 1KHz sine wave input, Bandwidth= 20~20KHz								
Condition	on	Min.	Тур.	Max.	Unit			
Full sca	le		2.1		Vpp			
		16			bits			
		8		48	KHz			
f <sub>in</sub> =1KHz	8KHz		94		dB			
B/W=20~20KHz	16KHz		94		dB			
THD+N < 0.01%	32KHz		94		dB			
0dBFS signal	44.1KHz		94		dB			
Load=100K()	48KHz		94		dB			
R <sub>L</sub> =16Ohm			35		mW			
R <sub>L</sub> =32Ohm			17		mW			
16Ohm load				0.05	%			
100KΩ load				0.01	%			
		-54		4.85	dB			
			6		dB			
		-28		3	dB			
			1		dB			
R <sub>L</sub>		8	16		Ohm			
Ср				500	pF			
L vs. R, measured at			00	90	dB			
-10dBFS@1KHz input			-90	-00	UD			
		1 Ω	28	3.0	V			
		1.0	2.0	3.0	v			
	Full scan  f <sub>in</sub> =1KHz  B/W=20~20KHz  A-weighted  THD+N < 0.01%  0dBFS signal  Load=100KΩ  R <sub>L</sub> =16Ol  R <sub>L</sub> =32Ol  16Ohm lo	$ \begin{array}{c c} \textbf{Condition} \\ \hline Full scale \\ \hline \\ \hline \\ f_{in}=1 \text{KHz} \\ B/W=20 \sim 20 \text{KHz} \\ A-\text{weighted} \\ THD+N < 0.01\% \\ 0dBFS \ \text{signal} \\ Load=100 \text{K} \Omega \\ \hline \\ \hline \\ R_L=16 \text{Ohm} \\ R_L=32 \text{Ohm} \\ \hline \\ 16 \text{Ohm load} \\ \hline \\ 100 \text{K} \Omega \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	$ \begin{array}{c c} \textbf{Condition} & \textbf{Min.} \\ \hline Full scale & & 16 \\ \hline & & 16 \\ \hline & & 8 \\ \hline f_{\text{in}} = 1 \text{KHz} & 8 \text{KHz} \\ \hline B/W = 20 \sim 20 \text{KHz} \\ A \text{-weighted} & 16 \text{KHz} \\ \hline A \text{-weighted} & 32 \text{KHz} \\ \hline 0 \text{dBFS signal} & 44.1 \text{KHz} \\ \hline Load = 100 \text{K} \Omega & 48 \text{KHz} \\ \hline & R_L = 16 \text{Ohm} \\ \hline & R_L = 32 \text{Ohm} \\ \hline & 16 \text{Ohm load} \\ \hline & 100 \text{K} \Omega & \text{load} \\ \hline & & -54 \\ \hline & & -28 \\ \hline & R_L & 8 \\ \hline & Cp \\ \hline L \text{ vs. R, measured at} \\ \hline \end{array} $	Condition       Min.       Typ.         Full scale       2.1         16         8         16         8 KHz       94         16KHz       94         16KHz       94         32KHz       94         44.1KHz       94         48KHz       94         R <sub>L</sub> =16Ohm       35         R <sub>L</sub> =32Ohm       17         16Ohm load         100KΩ load         -54         6         -28         1         R <sub>2</sub> 1         R <sub>2</sub> 1         1         R <sub>2</sub> 1         1         1         1         1         1         1         1         1         1         1 <t< th=""><th>Condition       Min.       Typ.       Max.         Full scale       2.1         16         16         8       48         8 KHz       94         BW=20~20KHz         A-weighted         16KHz       94         32KHz       94         48KHz       94         <td co<="" th=""></td></th></t<>	Condition       Min.       Typ.       Max.         Full scale       2.1         16         16         8       48         8 KHz       94         BW=20~20KHz         A-weighted         16KHz       94         32KHz       94         48KHz       94 <td co<="" th=""></td>			

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### **Battery Charger**

Charging Mode (BAT_IN	rising to 4.2V)	Min	Тур	Max	Unit
Operation Temperature		-20		70	$^{\circ}\!\mathbb{C}$
Input Voltage (Vin)					
Note: It needs more time t	o get battery fully	4.5		6	V
charged when Vin=4.5V					
Battery trickle charge current (BAT_IN < trickle charge voltage threshold)			0.1C		mA
Trickle charge voltage threshold			3		V
Maximum battery	Headroom > 0.7V		350		mA
charge current	Headroom = 0.3V		150		mA
Minimum battery	Headroom > 0.7V		1		mA
charge current	Headroom = 0.3V		1		mA
Battery charge termination current, % of fast charge current			10		%
Battery recharge hysteresis (Note1)			100		mV
Battery recharge current Note: C → Battery capacit			0.25C		mA

Note1: When charging complete and the adapter is still in, the battery voltage will slowly drop down. When the voltage drop is larger than 100mV from the full voltage, the re-charging cycle will start.

Note2: If the battery voltage during plug in is larger than 4V, the charging current will be limited to 0.25C to avoid the battery voltage overshoot.

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# **Switching Regulator**

Normal Operation		Min	Тур	Max	Unit
Operation Temperature		-20		70	$^{\circ}\!\mathbb{C}$
Input Voltage (Vin)		3	3.7	4.5	V
Output Voltage (Vout)		1.6	1.85	2.4	mA
Output Ripple				20	mVrms
Max. Average Load Curre	ent(lload)	120			mA
Max. Output Current (pea	Max. Output Current (peak)				mA
	I <sub>load</sub> =50mA		88		
Conversion Efficiency (Bat.@3.7V)	I <sub>load</sub> ≥ 10mA		80		%
(bat.@3.7 v)	I <sub>load</sub> ≥ 250uA		65		
Switching Frequency			800		KHz
Start-up current Limit		0	50	210	mA
Start-up Settling Time			1.2	2	ms
Shutdown Current				<1	uA

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#### LDO

Normal Operation		Min	Тур	Max	Unit
Input Voltage (Vin)		3.0		4.5	V
Output Voltage (V <sub>OUT</sub> )	V <sub>OUT</sub> = 2.9V (2.4~3.4V)		2.9		V
(1) V <sub>OUT_CODEC</sub> (2) V <sub>OUT_IO</sub>	V <sub>OUT</sub> = 1.8V (1.3~2.3V)		1.8		V
Accuracy (V <sub>IN</sub> =3.7V, I <sub>LC</sub>	<sub>DAD</sub> =100mA, 27'C)		±5		%
Output Voltage adjusta	able step		100		mV/Step
Output adjustment range			±0.5		\
Start-up inrush current			200	400	mA
Start-up Settling Time			250	500	μs
Output current(average	e)			100	mA
Output Current(peak)				150	mA
Drop-out voltage (I <sub>load</sub> : current)	= maximum output			300	mV
Quiescent Current (excluding load, I <sub>load</sub> < 1mA)			45		μA
Load Regulation (I <sub>load</sub> = 0mA to 100mA), ΔVout				80	mV
Shutdown Current				<1	μA

Note: Two 100mA LDOs, one for IO and one for audio CODEC.

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## Clock

Parameters	MIN	TYP	MAX	Unit
Crystal Frequency		16		MHz
Frequency Tolerence		±20		ppm
Operating Temperature	-20		70	οС
Trimming Capacitance		6.4		pF
Trimming Step Size		0.2		pF

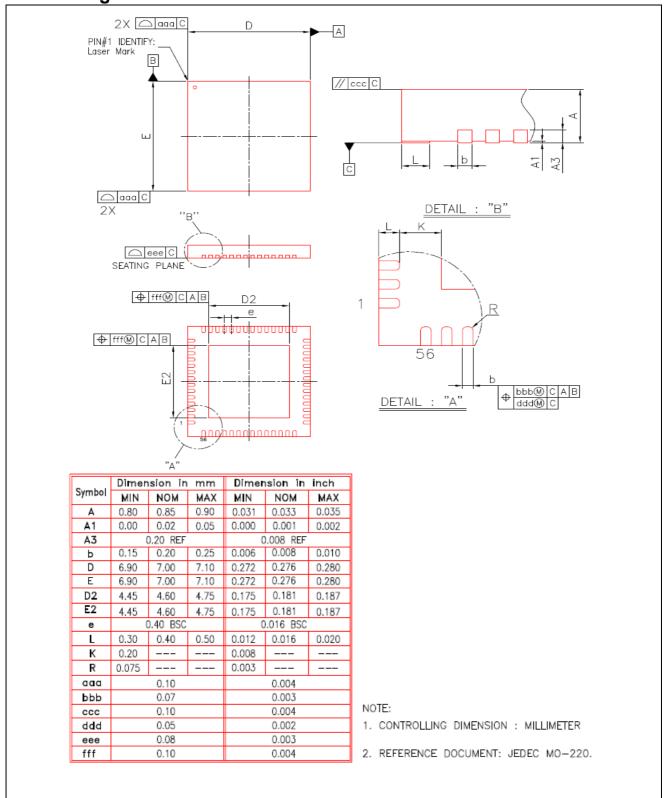
# Digital GPIO (2.8V)

Parameters	MIN	TYP	MAX	Unit
Input Voltage	2.7	3	3.6	V
V <sub>IH</sub> (Input High Voltage)	2.0		Vdd	٧
V <sub>IL</sub> (Input Low Voltage)	0		0.8	٧
Input Reference Resistor				
R <sub>PU</sub> (Pull-Up Resistor)		50K		Ohm
R <sub>PD</sub> (Pull-Down Resistor)		50K		Ohm
Output Voltage				
V <sub>OH</sub> (Output High Voltage)	2.4		Vdd	V
V <sub>OL</sub> (Output Low Voltage)	0		0.4	V

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## 8 Package Information





## Appendix A. Reflow Profile

1.) Follow: IPC/JEDEC J-STD-020 C

### 2.) Condition:

Average ramp-up rate (217° $\mathbb{C}$  to peak): 1~2° $\mathbb{C}$ /sec max.

Preheat: 150~200C \ 60~180 seconds

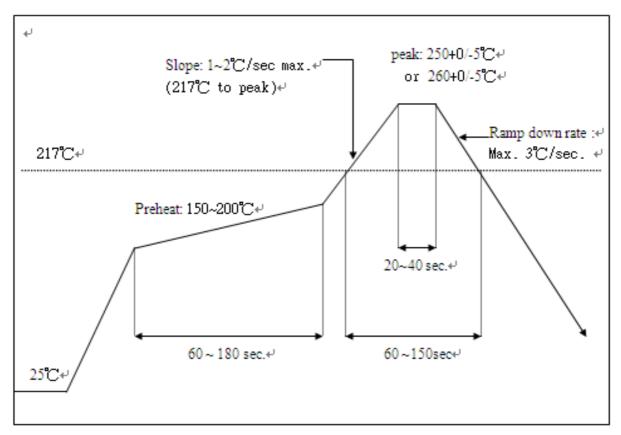
Temperature maintained above  $217^{\circ}$ C:  $60\sim150$  seconds Time within  $5^{\circ}$ C of actual peak temperature:  $20\sim40$  sec.

Peak temperature :  $250+0/-5^{\circ}$ C or  $260+0/-5^{\circ}$ C

Ramp-down rate : 3°C/sec. max.

Time 25°C to peak temperature : 8 minutes max.

Cycle interval: 5 minus



Time (sec)↔

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# Appendix B. BQB certification

TPG Project	ISSC Bluetooth 3.0+EDR	Single Ch	nip (Compo	onent (Tested))		
Qualified Design ID (QD ID)	B016749   Export PICS					
PRD 1.0 ID (QP ID)						
Design Name	ISSC Bluetooth 3.0+EDR	Single Ch	nip			
Wi-Fi® Certification ID						
Subsetted Designs	Date Created	Туре	PICS			
	Jun 28, 2010	Main	<u>PICS</u>			
Member Company	ISSC Technologies Corp.					
Specification Name	3.0					
Core Spec Addenda	N/A					
Design Model Number	IS1XYZ, where X, Y and Z means 1~9					
Hardware Version Number	ISBT_BB_v30					
Software Version Number	ISBT_BB_v30					
Qualification Assessment Date	July/21/2010					
Listing Date	July/21/2010					
Design Description	ISSC Bluetooth 3.0+EDR	Single Ch	nip			
Product Type	Component (Tested)					
Technical Data Sheet (RIN)	** Open Reference Integr	ation Note	es (RIN) **	•		
Listed By	<u>Charlie Lee</u>					
BQE	Jan-Willem Vonk					
Profile / Protocol	Role / Version (If Any)					
Baseband						
Radio						
Link Manager						

Version: 0.96 - 39 - 9/26/2011