

**Address** 

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# **FCC SAR Test Report**

Revopoint 3D Technologies Inc. **Applicant** 

Office 902, 9/F, Tinno Building, Tongfa South

: Rd, Xili Street, Nanshan District, Shenzhen,

518000, China

Product Name 3D Scanner

Jan. 03, 2024 **Date** 

Shenzhen Anbotek Compliance Laboratory Limited









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# **TEST REPORT**

Applicant : Revopoint 3D Technologies Inc.

Manufacturer : Revopoint 3D Technologies Inc.

Product Name : 3D Scanner

Model No. : MIRACO, MIRACO Pro, MIRACO Plus, MIRACO SE, ACCUONE

Trade Mark : REVOPOINT

Rating(s) : Input: 7-11V=5A (with DC 3.89V, 5000mAh battery inside)

Test Standard(s) : IEC/IEEE 62209-1528:2020; FCC 47 CFR Part 2.1093;

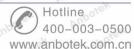
ANSI/IEEE C95.1:2005; Reference FCC KDB 447498; KDB 248227;

KDB 616217

The device described above is tested by Shenzhen Anbotek Compliance Laboratory Limited to determine the maximum emission levels emanating from the device and the severe levels of the device can endure and its performance criterion. The measurement results are contained in this test report and Shenzhen Anbotek Compliance Laboratory Limited is assumed full of responsibility for the accuracy and completeness of these measurements. Also, this report shows that the EUT (Equipment Under Test) is technically compliant with the IEC/IEEE 62209-1528:2020, FCC 47 CFR Part 2.1093, ANSI/IEEE C95.1:2005 and Reference KDB 447498, KDB 248227, KDB 616217 requirements.

This report applies to above tested sample only and shall not be reproduced in part without written approval of Shenzhen Anbotek Compliance Laboratory Limited.

Date of Receipt	Dec.18 , 2023
Date of Test	Dec.19-20 , 2023
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	Ella Liang
Prepared By	Anbotek Anbotek Anbotek Anbote
	(Ella Liang)
	Bolward pan
Approved & Authorized Signer	Anbors Ot All hotek Anborek Anbo
	(Edward Pan)







Version

	Version No.		Date	Description
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### 1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing are as follows.

### <Highest SAR Summary>

Highest Reported 1g-SAR(W/Kg)		
Frequency Band	Body-worn(0mm)	
WIFI 5.2G ANT1	botek proport 0.655	OAD To at Limit
WIFI 5.2G ANT2	0.604	SAR Test Limit
WIFI 5.3G ANT1	0.481	(W/Kg)
WIFI 5.3G ANT2	0.244	-
Simultaneous	nborek Anbo Ak 1,259 Anbort	ste <sup>V</sup>
Test Result	aborek Andoo kan Andoo Andoo Andoo	tek spotek

This device is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6 W/kg) specified in KDB 447498 D01 v06, 2015 and ANSI/IEEE C95.1:2005, and had been tested in accordance with the measurement methods and procedures specified in IEEE 1528-2013.

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### 2. General Information

### 2.1 Client Information

Applicant	: Revopoint 3D Technologies Inc.	
Address	Office 902, 9/F, Tinno Building, Tongfa South Rd, Xili Street, Nanshan Distriction Shenzhen, 518000, China	
Manufacturer	: Revopoint 3D Technologies Inc.	
Address	Office 902, 9/F, Tinno Building, Tongfa South Rd, Xili Street, Nanshan District, Shenzhen, 518000, China	
Factory	Zhejiang Revopoint Optoelectronics Technology Co., Ltd	
Address	2F, Building 7, No.1, Weizhong Road, Weitang Street, Jiashan County, Jiaxi city, Zhejiang Province, China	

### 2.2 Description of Equipment Under Test (EUT)

Product Name		3D Scanner Anborek Anborek Anborek Anborek	anl
Model No.	•	MIRACO, MIRACO Pro, MIRACO Plus, MIRACO SE, ACCUONE (Note: All samples are the same except the model number and DDR capacities so we prepare "MIRACO" for test only.)	s,
Trade Mark	:	REVOPOINT	
Test Power Supply		DC 3.89V Battery inside	00,
Test Sample No.	:	1-2-2(Engineering Sample)	PUL
Product Description		802.11a/n(HT20)/ac(HT20)/ax(HE20): U-NII Band 1: 5180MHz to 5240MHz U-NII Band 2A: 5260MHz to 5320MHz  802.11n(HT40)/ac(HT40)/ax(HE40): U-NII Band 1: 5190MHz to 5230MHz U-NII Band 2A: 5270MHz to 5310MHz  802.11ac(HT80)/ax(HE80): U-NII Band 1: 5210MHz U-NII Band 2A: 5290MHz	Anbrotel Anbrotel
		Number of Channel: 802.11a/n(HT20)/ac(HT20)/ax(HE20): U-NII Band 1: 4	





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Anbotek	U-NII Band 2A: 4  802.11n(HT40)/ac(HT40)/ax(HE40): U-NII Band 1: 2 U-NII Band 2A: 2  802.11ac(HT80)/ax(HE80): U-NII Band 1: 1
Modulation Type:	U-NII Band 2A: 1  802.11a: OFDM(BPSK, QPSK, 16QAM, 64QAM); 802.11n: OFDM (BPSK, QPSK, 16QAM, 64QAM); 802.11ac: OFDM (BPSK, QPSK, 16QAM, 64QAM, 256QAM)  802.11ax: OFDMA (BPSK, QPSK, 16QAM, 64QAM, 256QAM, 1024QAM)

**Remark:** 1) For a more detailed features description, please refer to the manufacturer's specifications or the User's Manual.





### 2.3 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue.

### 2.4 Applied Standard

The Specific Absorption Rate (SAR) testing specification, method, and procedure for this device is in accordance with the following standards:

- · IEC/IEEE 62209-1528:2020
- ANSI/IEEE C95.1:2005
- FCC 47 CFR Part 2.1093
- Reference FCC KDB 447498; KDB 248227; KDB 616217

#### 2.5 Environment of Test Site

Items	Required	Actual
Temperature (°C)	18-25	22~23
Humidity (%RH)	30-70	55~65

### 2.6 Test Configuration

For WIFI and Bluetooth SAR testing, engineering testing software installed on the EUT can provide continuous transmitting RF signal.



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400-003-0500



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### 2.7 Description of Test Facility

The test facility is recognized, certified, or accredited by the following organizations:

### FCC-Registration No.: 434132

Shenzhen Anbotek Compliance Laboratory Limited, EMC Laboratory has been registered and fully described in a report filed with the (FCC) Federal Communications Commission. The acceptance letter from the FCC is maintained in our files. Registration No. 434132.

### ISED-Registration No.: 8058A

Shenzhen Anbotek Compliance Laboratory Limited, EMC Laboratory has been registered and fully described in a report filed with the (ISED) Innovation, Science and Economic Development Canada. The acceptance letter from the ISED is maintained in our files. Registration 8058A.

#### Test Location

Shenzhen Anbotek Compliance Laboratory Limited.

1/F, Building D, Sogood Science and Technology Park, Sanwei community, Hangcheng Street, Bao'an District, Shenzhen, Guangdong, China.

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# 3. Specific Absorption Rate (SAR)

### 3.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

#### 3.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density  $(\rho)$ . The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = C\left(\frac{\delta T}{\delta t}\right)$$

Where: C is the specific head capacity,  $\delta T$  is the temperature rise and  $\delta t$ isthe exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where:  $\sigma$  is the conductivity of the tissue,  $\rho$  is the mass density of the tissue and E is the RMS electrical field strength.

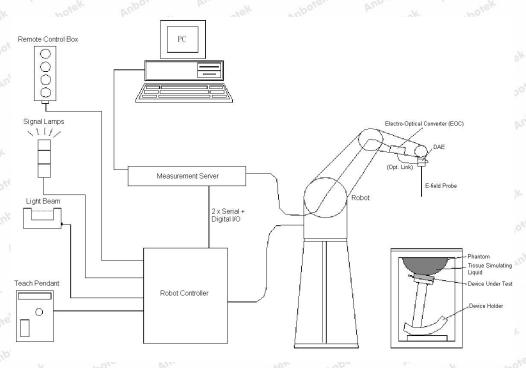
However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.





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### 4. SAR Measurement System



**DASY System Configurations** 

The DASY system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- > A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (EOC) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY software
- Remove control with teach pendant and additional circuitry for robot safety such as warming lamps, etc.
- The SAM twin phantom
- A device holder
- Tissue simulating liquid
- Dipole for evaluating the proper functioning of the system

components are described in details in the following sub-sections.









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#### 4.1 E-Field Probe

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

### E-Field Probe Specification <EX3DV4 Probe>

Construction	Symmetrical design with triangular core
P	Built-in shielding against static charges
	PEEK enclosure material (resistant to
	organic solvents, e.g., DGBE)
Frequency	10 MHz to 6 GHz; Linearity: ± 0.2 dB
Directivity	± 0.3 dB in HSL (rotation around probe axis)
s.	± 0.5 dB in tissue material (rotation normal to probe axis)
Dynamic Range	10 μW/g to 100 mW/g; Linearity: ± 0.2
	dB (noise: typically < 1 μW/g)
Dimensions	Overall length: 330 mm (Tip: 20 mm)
3	Tip diameter: 2.5 mm (Body: 12 mm)
	Typical distance from probe tip to
	dipole centers: 1 mm



Photo of EX3DV4

### E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than  $\pm$  10%. The spherical isotropy shall be evaluated and within  $\pm$  0.25dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data can be referred to appendix C of this report.

### 4.2 Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.







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The input impedance of the DAE is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.



Photo of DAE

### 4.3 Robot

The SPEAG DASY system uses the high precision robots (DASY5: TX60XL) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version (DASY5: CS8c) from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- ➤ High precision (repeatability ±0.035 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- > Low ELF interference (the closed metallic construction shields against motor control fields)



**Photo of DASY5** 





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### 4.4 Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chip disk (DASY5: 128 MB), RAM (DASY5: 128 MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.



**Photo of Server for DASY5** 

#### 4.5 Phantom

### <SAM Twin Phantom>

Shell Thickness	2 ± 0.2 mm;	790.
Y .	Center ear point: 6 ± 0.2 mm	P
Filling Volume	Approx. 25 liters	,ter
Dimensions	Length: 1000 mm; Width: 500 mm; Height: adjustable feet	nbo*
Measurement	Left Hand, Right Hand, Flat	
Areas	Phantom	Anbo Anborek
	Anbotek Anbotek Anbotel	Photo of SAM Phantom

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.





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<ELI4 Phantom>

760	and the second	A
Shell Thickness	2 ± 0.2 mm (sagging: <1%)	who will all
Filling Volume	Approx. 30 liters	ote
Dimensions	Major ellipse axis: 600 mm	
	Minor axis:400 mm	No.
	abotek Anbore Anti-	DOTE
	An Anbotek Anbotek	
	Anborek Anbore	A.T.
	Anbore Amborek Anborek	1
	k Anboten Ando	Anbor An Tiek anbore
	rek spotek Anbore Am	Photo of ELI4 Phantom

The ELI4 phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.





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#### 4.6 Device Holder

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5 mm distance, a positioning uncertainty of  $\pm 0.5$ mm would produce a SAR uncertainty of  $\pm 20\%$ . Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon$  = 3 and loss tangent  $\delta$  = 0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



**Device Holder** 



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### 4.7 Data Storage and Evaluation

### Data Storage

The DASY software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-lose media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

#### Data Evaluation

The DASY post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity	Norm <sub>i</sub> , $a_{i0}$ , $a_{i1}$ , $a_{i2}$

Conversion factor ConvF<sub>i</sub>
 Diode compression point dcp<sub>i</sub>

**Device parameters**: - Frequency f

- Crest factor cf

Media parameters: - Conductivity σ

- Density p

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power.









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The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with  $V_i$ = compensated signal of channel i, (i = x, y, z)

 $U_i$  = input signal of channel i, (i = x, y, z)

cf = crest factor of exciting field (DASY parameter)

dcpi = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated:

E-field Probes: 
$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

H-field Probes: 
$$H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

with  $V_i$  = compensated signal of channel i,(i = x, y, z)

Norm<sub>i</sub>= sensor sensitivity of channel i, (i = x, y, z),  $\mu V/(V/m)^2$  for E-field Probes

ConvF= sensitivity enhancement in solution

a<sub>ij</sub>= sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

E<sub>i</sub>= electric field strength of channel i in V/m

H<sub>i</sub>= magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

E<sub>tot</sub>= total field strength in V/m

 $\sigma$  = conductivity in [mho/m] or [Siemens/m]

 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.









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### 5. Test Equipment List

Manufacture	Name of Favinance	Truno/Model	Coriol Normalson	Calib	ration
Manufacturer	Name of Equipment	Type/Model	Serial Number	Last Cal.	Due Date
SPEAG	5GHz System Validation Kit	D5GHzV2	1160	Oct. 02, 2021	Oct. 01, 2024
SPEAG	2450MHz System Validation Kit	D2450V2	910	Jun. 15,2021	Jun. 14,2024
SPEAG	Data Acquisition Electronics	DAE4	387	Sept.06,2023	Sept.05,2024
SPEAG	Dosimetric E-Field Probe	EX3DV4	7396	May 06,2023	May 05,2024
Agilent	ENA Series Network Analyzer	E5071C	MY46317418	Oct.26, 2023	Oct.25, 2024
SPEAG	DAK	DAK-3.5	1226	NCR	NCR
SPEAG	ELI Phantom	QDOVA004AA	2058	NCR	NCR
AR	Amplifier	ZHL-42W	QA1118004	NCR	NCR
Agilent	Power Sensor	N8481H	MY51240001	Oct.26, 2023	Oct.25, 2024
Agilent	Spectrum Analyzer	N9020A	MY51170037	Oct.12, 2023	Oct.11, 2024
Agilent	Signal Generation	N5182A	MY47420647	Feb.23, 2023	Feb.22, 2024
Worken	Directional Coupler	0110A05601O-10	COM5BNW1A2	Oct.26, 2023	Oct.25, 2024

### Note:

- 1. The calibration certificate of DASY can be referred to appendix C of this report.
- 2. The dipole calibration interval can be extended to 3 years with justification. The dipoles are also not physically damaged, or repaired during the interval.
- The Insertion Loss calibration of Dual Directional Coupler and Attenuator were characterized via the network analyzer and compensated during system check.
- 4. The dielectric probe kit was calibrated via the network analyzer, with the specified procedure (calibrated in pure water) and calibration kit (standard) short circuit, before the dielectric measurement. The specific procedure and calibration kit are provided by Agilent.
- In system check we need to monitor the level on the power meter, and adjust the power amplifier level to have precise power level to the dipole; the measured SAR will be normalized to 1W input power according to the ratio of 1W to the input power to the dipole. For system check, the calibration of the power amplifier is deemed not critically required for correct measurement; the power meter is critical and we do have calibration for it



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### 6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.1. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm, which is shown as followed:



**Photo of Liquid Height for Body SAR** 

The following table gives the recipes for tissue simulating liquid.

Frequency	Water	Sugar	Cellulose	Salt	Preventol	DGBE	Conductivity	Permittivity	
(MHz)	(%)	(%)	(%)	(%)	(%)	(%)	(σ)	(εr)	
	For Body								
5200	78.6	orel <sup>o</sup> 0	10.7	Arra O otek	10.7	0.000	5.27	49.0	
5300	78.4	00 N	10.7	0	10.9	O An	5.52	48.74	

The following table shows the measuring results for simulating liquid.

Tissue	Measured	Measured Tissue				Liquid			
Type	Frequency (MHz)	ε <sub>r</sub>	σ	٤r	Dev. (%)	σ	Dev. (%)	Temp. (℃)	Test Date
5200MSL	5200	49.00	5.27	48.23	-1.60	5.20	-1.35	22.6	12/19/2023
5300MSL	5300	48.74	5.52	48.56	-0.37	5.43	-1.63	22.5	12/20/2023



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### 7. System Verification Procedures

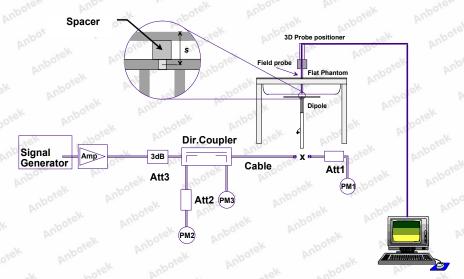
Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

### Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

### System Setup

In the simplified setup for system evaluation, the EUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



**System Setup for System Evaluation** 





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**Photo of Dipole Setup** 

### **Validation Results**

Comparing to the original SAR value provided by SPEAG, the verification data should be within its specification of 10%. The table below shows the target SAR and measured SAR after normalized to 1W input power. It indicates that the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

o X	Frequency (MHz)	Liquid Type	Power fed onto reference dipole (mW)	Targeted SAR (W/kg)	Measured SAR (W/kg)	Normalized SAR (W/kg)	Deviation (%)	Test Date
	5200	Body	100	77.8	7.63	76.30	-1.93	12/19/2023
ĺ	5300	Body	100	78.4	7.69	76.9	-1.91	12/20/2023

Target and Measurement SAR after Normalized



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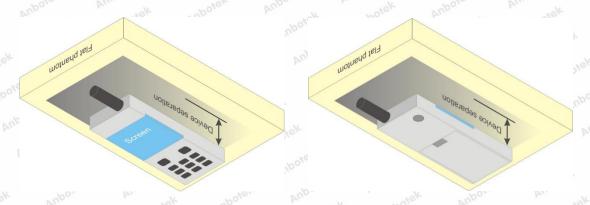
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### 8. EUT Testing Position

### 8.1 Body Worn Position

Body-worn operating configurations are tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in a normal use configuration. Per KDB 648474 D04, body-worn accessory exposure is typically related to voice mode operations when handsets are carried in body-worn accessories. The body-worn accessory procedures in FCC KDB 447498 D01 v06, 2015 should be used to test for body-worn accessory SAR compliance, without a headset connected to it. This enables the test results for such configuration to be compatible with that required for hotspot mode when the body-worn accessory test separation distance is greater than or equal to that required for hotspot mode, when applicable. When the reported SAR for body-worn accessory, measured without a headset connected to the handset is < 1.2 W/kg, the highest reported SAR configuration for that wireless mode and frequency band should be repeated for that body-worn accessory with a handset attached to the handset.

Accessories for body-worn operation configurations are divided into two categories: those that do not contain metallic components and those that do contain metallic components and those that do contain metallic components. When multiple accessories that do not contain metallic components are supplied with the device, the device is tested with only the accessory that dictates the closest spacing to the body. Then multiple accessories that contain metallic components are test with the device with each accessory. If multiple accessories share an identical metallic component (i.e. the same metallic belt-chip used with different holsters with no other metallic components) only the accessory that dictates the closest spacing to the body is tested.



**Body Worn Position** 



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### 9. Measurement Procedures

The measurement procedures are as follows:

- (a) Use base station simulator (if applicable) or engineering software to transmit RF power continuously (continuous Tx) in the middle channel.
- (b) Keep EUT to radiate maximum output power or 100% duty factor (if applicable)
- (c) Measure output power through RF cable and power meter.
- (d) Place the EUT in the positions as setup photos demonstrates.
- (e) Set scan area, grid size and other setting on the DASY software.
- (f) Measure SAR transmitting at the middle channel for all applicable exposure positions.
- (g) Identify the exposure position and device configuration resulting the highest SAR
- (h) Measure SAR at the lowest and highest channels at the worst exposure position and device configuration if applicable.

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

### 9.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values form the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g







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#### 9.2 Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

### 9.3 Area Scan Procedures

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum found in the scanned area, within a range of the global maximum. The range (in dB0 is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE standard 1528 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan), if only one zoom scan follows the area scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of zoom scans has to be increased accordingly.

Area scan parameters extracted from FCC KDB 865664 D01 SAR measurement 100 MHz to 6 GHz.

AND DATE BUT DESCRIPTION OF THE PROPERTY OF TH		A STATE OF THE STA	
	≤3 GHz	> 3 GHz	
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 ± 1 mm	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$	
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30° ± 1°	20° ± 1°	
	$\leq$ 2 GHz: $\leq$ 15 mm 2 – 3 GHz: $\leq$ 12 mm	$3 - 4 \text{ GHz:} \le 12 \text{ mm}$ $4 - 6 \text{ GHz:} \le 10 \text{ mm}$	
Maximum area scan spatial resolution: $\Delta x_{\text{Area}},\Delta y_{\text{Area}}$	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.		



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### 9.4Zoom Scan Procedures

Zoom scans are used assess the peak spatial SAR values within a cubic averaging volume containing 1 gram and 10gram of simulated tissue. The zoom scan measures points (refer to table below) within a cube shoes base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the zoom scan evaluates the averaged SAR for 1 gram and 10 gram and displays these values next to the job's label.

Zoom scan parameters extracted from FCC KDB 865664 D01 SAR measurement 100 MHz to 6 GHz.

			≤ 3 GHz	> 3 GHz
Maximum zoom scan s	spatial reso	olution: Δx <sub>Zoom</sub> , Δy <sub>Zoom</sub>	$\leq$ 2 GHz: $\leq$ 8 mm 2 – 3 GHz: $\leq$ 5 mm <sup>*</sup>	$3 - 4 \text{ GHz: } \le 5 \text{ mm}^*$ $4 - 6 \text{ GHz: } \le 4 \text{ mm}^*$
	uniform	grid: Δz <sub>Zoom</sub> (n)	≤ 5 mm	$3 - 4$ GHz: $\leq 4$ mm $4 - 5$ GHz: $\leq 3$ mm $5 - 6$ GHz: $\leq 2$ mm
Maximum zoom scan spatial resolution, normal to phantom surface	graded	Δz <sub>Zoom</sub> (1): between 1 <sup>st</sup> two points closest to phantom surface	≤ 4 mm	$3 - 4 \text{ GHz:} \le 3 \text{ mm}$ $4 - 5 \text{ GHz:} \le 2.5 \text{ mm}$ $5 - 6 \text{ GHz:} \le 2 \text{ mm}$
surface	grid  Δz <sub>Zoom</sub> (n>1): between subsequent points		≤1.5	$\Delta z_{Zoom}(n-1)$
Minimum zoom scan volume	x, y, z		≥ 30 mm	$3 - 4 \text{ GHz}$ : $\geq 28 \text{ mm}$ $4 - 5 \text{ GHz}$ : $\geq 25 \text{ mm}$ $5 - 6 \text{ GHz}$ : $\geq 22 \text{ mm}$

Note:  $\delta$  is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.



When zoom scan is required and the <u>reported</u> SAR from the <u>area scan based 1-g SAR estimation</u> procedures of KDB 447498 is  $\leq 1.4$  W/kg,  $\leq 8$  mm,  $\leq 7$  mm and  $\leq 5$  mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.



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#### 9.5 Volume Scan Procedures

The volume scan is used for assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g aggregate SAR, the EUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing. When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

### 9.6 Power Drift Monitoring

All SAR testing is under the EUT install full charged battery and transmit maximum output power. In DASY measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of EUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drift more than 5%, the SAR will be retested.



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### 10. Conducted Power

### <WIFI 5GHz Conducted Power>

### Band 1

ANT 1:

TestMode	Channel	Average Power[dBm]	Tune-Up Limit(dBm)	Test Rate Data	
Anboten Anbo	5180	16.76	17.50	6M	
802.11a	5200	16.99	17.50	6M	
	5240	16.57	17.50	6M	
K Polek VI	5180	14.64	15.00	MCS0	
802.11n(HT20)	5200	14.56	15.00	MCS0	
	5240	14.28	15.00	MCS0	
000 44~(UT40)	5190	14.32	14.50	MCS0	
802.11n(HT40)	5230	14.04	14.50	MCS0	
Arth otek Anbo	5180	14.80	15.00	MCS0	
802.11ac(HT20)	5200	14.54	15.00	MCS0	
	5240	14.14	15.00	MCS0	
000 44(UT40)	5190	14.33	14.50	MCS0	
802.11ac(HT40)	5230	14.09	14.50	MCS0	
802.11ac(HT80)	5210	14.25	14.50	MCS0	
Anbo. ok k. bot	5180	14.97	15.00	MCS0	
802.11ax20	5200	14.83	15.00	MCS0	
	5240	14.80	15.00	MCS0	
902 446 40	5190	14.57	15.00	MCS0	
802.11ax40	5230	14.39	15.00	MCS0	
802.11ax80	5210	14.85	15.00	MCS0	





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ANT 2:

ANT Z.	aren Anbo	You	TOOL VI	V.	
TestMode	Channel	Average Power[dBm]	Tune-Up Limit(dBm)	Test Rate Data	
ok anotek Ant	5180	16.32	17.00	6M	
802.11a	5200	16.40	17.00	6M	
	5240	16.52	17.00	6M	
sotek Anboten	5180	12.74	13.00	MCS0	
802.11n(HT20)	5200	12.84	13.00	MCS0	
	5240	12.92	13.00	MCS0	
000 44~(UT40)	5190	12.58	13.50	MCS0	
802.11n(HT40)	5230	13.03	13.50	MCS0	
otek Anbotek P	5180	13.62	14.50	MCS0	
802.11ac(HT20)	5200	13.55	14.50	MCS0	
	5240	14.04	14.50	MCS0	
000 44aa(UT40)	5190	12.33	13.00	MCS0	
802.11ac(HT40)	5230	12.93	13.00	MCS0	
802.11ac(HT80)	5210	12.84	13.00	MCS0	
ok hotek b	5180	12.98	14.00	MCS0	
802.11ax20	5200	13.43	14.00	MCS0	
	5240	13.77	14.00	MCS0	
902 44 ov 40	5190	12.31	14.50	MCS0	
802.11ax40	5230	14.49	14.50	MCS0	
802.11ax80	5210	13.10	13.50	MCS0	



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MIMO:

Test Mode	Frequency	FOWEI (UDIII)				Test Rate
	(MHz)	Antenna 1	Antenna 2	Total	Bm)	Data
Vun	5180	14.64	12.74	16.80	17.00	MCS0
802.11n(HT20)	5200	14.56	12.84	16.79	17.00	MCSC
otek Aupoten	5240	14.28	12.92	16.66	17.00	MCSO
902 44p/UT40\	5190	14.32	12.58	16.55	17.00	MCS
802.11n(HT40)	5230	14.04	13.03	16.57	17.00	MCSC
Anbores And	5180	14.80	13.62	17.26	17.50	MCSC
802.11ac(HT20)	5200	14.54	13.55	17.08	17.50	MCSC
	5240	14.14	14.04	17.10	17.50	MCSC
000 44(UT40)	5190	14.33	12.33	16.45	17.00	MCSC
802.11ac(HT40)	5230	14.09	12.93	16.56	17.00	MCSC
802.11ac(HT80)	5210	14.25	12.84	16.61	17.00	MCSC
aborek Anbore	5180	14.97	12.98	17.10	17.50	MCS
802.11ax20	5200	14.83	13.43	17.20	17.50	MCS
	5240	14.80	13.77	17.33	17.50	MCSC
902 44 ov 40	5190	14.57	12.31	16.60	17.50	MCSC
802.11ax40	5230	14.39	14.49	17.45	17.50	MCSC
802.11ax80	5210	14.85	13.10	17.07	17.50	MCSC



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Band 2 ANT 1:

LOTO ATT	181	Y. V.	WO 3	Ville	
TestMode	Channel	Average Power[dBm]	Tune-Up Limit(dBm)	Test Rate Data	
ak Aupon K	5260	13.84	14.50	6M	
802.11a	5300	14.19	14.50	6M	
	5320	14.15	14.50	6M	
Jun rek upotek	5260	13.60	14.50	MCS0	
802.11n(HT20)	5300	13.99	14.50	MCS0	
	5320	14.13	14.50	MCS0	
902 44×/UT40)	5270	13.47	14.00	MCS0	
802.11n(HT40)	5310	13.89	14.00	MCS0	
ek abotek	5260	13.62	14.50	MCS0	
802.11ac(HT20)	5300	13.80	14.50	MCS0	
	5320	14.12	14.50	MCS0	
000 44 (UT 40)	5270	13.51	14.50	MCS0	
802.11ac(HT40)	5310	14.00	14.50	MCS0	
802.11ac(HT80)	5290	13.96	14.00	MCS0	
k pin solek	5260	15.02	16.00	MCS0	
802.11ax20	5300	15.15	16.00	MCS0	
	5320	15.53	16.00	MCS0	
1000 44 40	5270	14.64	15.50	MCS0	
802.11ax40	5310	15.22	15.50	MCS0	
802.11ax80	5290	14.83	15.00	MCS0	



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ANT 2:

TestMode	Channel	Average Power[dBm]	Tune-Up Limit(dBm)	Test Rate Data	
Anto-	5260	13.46	13.50	6M	
802.11a	5300	13.23	13.50	6M	
otek Anbore	5320	12.38	13.50	6M	
hotek Anboten	5260	12.64	13.00	MCS0	
802.11n(HT20)	5300	12.13	13.00	MCS0	
	5320	11.60	13.00	MCS0	
902 44×/UT40)	5270	12.37	12.50	MCS0	
802.11n(HT40)	5310	11.68	12.50	MCS0	
stek Anboten A	5260	12.81	13.00	MCS0	
802.11ac(HT20)	5300	12.70	13.00	MCS0	
	5320	12.56	13.00	MCS0	
902 44ee/UT40\	5270	12.38	12.50	MCS0	
802.11ac(HT40)	5310	11.99	12.50	MCS0	
802.11ac(HT80)	5290	12.67	13.00	MCS0	
ek opotek N	5260	13.20	13.50	MCS0	
802.11ax20	5300	13.01	13.50	MCS0	
	5320	12.53	13.50	MCS0	
902 44 ev 40	5270	12.59	13.00	MCS0	
802.11ax40	5310	12.32	13.00	MCS0	
802.11ax80	5290	13.14	13.50	MCS0	



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MIMO:

Test Mode	Frequency (MHz)		ed Average O Power(dBm)	Maximum Tune-Up(d	Test Rate	
	(141112)	Antenna 1	Antenna 2	Total	Bm)	Data
An otek on	5260	13.60	12.64	16.16	16.50	MCS0
802.11n(HT20)	5300	13.99	12.13	16.17	16.50	MCS0
	5320	14.13	11.60	16.06	16.50	MCS0
902 44 m/UT40)	5270	13.47	12.37	15.97	16.00	MCS0
802.11n(HT40)	5310	13.89	11.68	15.93	16.00	MCS0
And stek anbote	5260	13.62	12.81	16.24	16.50	MCS0
802.11ac(HT20)	5300	13.80	12.70	16.30	16.50	MCS0
	5320	14.12	12.56	16.42	16.50	MCS0
000 44 (UT40)	5270	13.51	12.38	15.99	16.50	MCS0
802.11ac(HT40)	5310	14.00	11.99	16.12	16.50	MCS0
802.11ac(HT80)	5290	13.96	12.67	16.37	16.50	MCS0
Anbo ek botel	5260	15.02	13.20	17.21	17.50	MCS0
802.11ax20	5300	15.15	13.01	17.22	17.50	MCS0
	5320	15.53	12.53	17.29	17.50	MCS0
902 44 av 40	5270	14.64	12.59	16.75	17.50	MCS0
802.11ax40	5310	15.22	12.32	17.02	17.50	MCS0
802.11ax80	5290	14.83	13.14	17.08	17.50	MCS0

### Note:

- 1. Per KDB 447498 D02 v02r01, the test distance less than 5mm
- 2. Per KDB 248227 D01, choose the highest output power channel to test SAR and determine further SAR exclusion.
  - 3. Per KDB 248227 D01, In the 5 GHz band, separate SAR procedures are applied to DSSS and OFDM configurations to simplify DSSS test requirements. SAR is not required for the following 5 GHz OFDM conditions:
    - 1) When KDB Publication 447498 SAR test exclusion applies to the OFDM configuration.
    - 2) When the highest reported SAR for DSSS is adjusted by the ratio of OFDM to DSSS specified maximum output power and the adjusted SAR is ≤ 1.2 W/kg.



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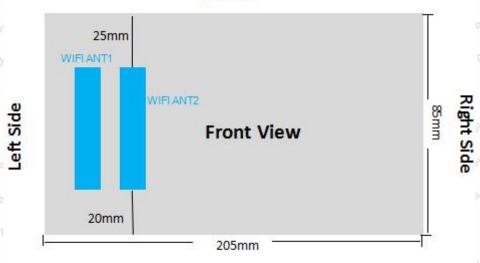
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### **Antenna Location**

### **Top Side**



**Bottom Side** 

Distance of The Antenna to the EUT surface and edge													
Antennas	Antennas Front Back Top Side Bottom Side Left Side Right Side												
WiFi ANT1	<25mm	<25mm	<25mm	<25mm	<25mm	>25mm							
WiFi ANT2	<25mm	<25mm	<25mm	<25mm	<25mm	>25mm							

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#### **SAR Test Results Summary** 12.

### General Note:

Per KDB 447498 D01 v06, the reported SAR is the measured SAR value adjusted for maximum tune-up tolerance.

Scaling Factor = tune-up limit power (mW) / EUT RF power (mW), where tune-up limit is the maximum rated power among all production units.

Reported SAR(W/kg)= Measured SAR(W/kg)\* Scaling Factor
Per KDB 447498 D01 v06, for each exposure position, if the highest output channel reported SAR≤0.8W/kg, other channels SAR testing are not necessary

### <WIFI 5GHz>

### Band1

ANT1:

Plot No.	Band	Mode	Test Position	Gap (cm)	Ch.	Freq. (MHz	۵	Tune-U p Limit (dBm)	Scalin g Factor	r Drift	Measure d SAR <sub>1g</sub> (W/kg)	Reporte d SAR <sub>1g</sub> (W/kg)
k-	WIFI 5.2GHz	802.11 a	Left	0 AT	40	5200	16.99	17.50	1.125	0.01	0.271	0.305
oter	WIFI 5.2GHz	802.11 a	Right	0/8/10	40	5200	16.99	17.50	1.125	N/A	N/A	N/A
'upo	WIFI 5.2GHz	802.11 a	Тор	Up Osk	40	5200	16.99	17.50	1.125	0.12	0.123	0.138
Di.	WIFI 5.2GHz	802.11 a	Bottom	AOO4	40	5200	16.99	17.50	1.125	0.02	0.112	0.126
	WIFI 5.2GHz	802.11 a	Front	0 kul	40	5200	16.99	17.50	1.125	0.11	0.258	0.290
#1	WIFI 5.2GHz	802.11 a	Back	0	40	5200	16.99	17.50	1.125	0.11	0.582	0.655

### ANT2:

Plot No.	Band	Mode	Test Position	Gap (cm)	Ch.	Freq. (MHz	۵ ۵	Tune-U p Limit (dBm)	Scalin g Factor	r Drift	Measure d SAR <sub>1g</sub> (W/kg)	Reporte d SAR <sub>1g</sub> (W/kg)
ler.	WIFI 5.2GHz	802.11 a	Left	O	48	5240	16.52	17.00	1.117	0.09	0.236	0.264
upo,	WIFI 5.2GHz	802.11 a	Right	0.0	48	5240	16.52	17.00	1.117	N/A	N/A	N/A
VU.	WIFI 5.2GHz	802.11 a	Тор	AnOstel	48	5240	16.52	17.00	1.117	0.08	0.117	0.131
	WIFI 5.2GHz	802.11 a	Bottom	0.00	48	5240	16.52	17.00	1.117	0.06	0.103	0.115
18k	WIFI 5.2GHz	802.11 a	Front	0	48	5240	16.52	17.00	1.117	0.09	0.215	0.240
#2	WIFI 5.2GHz	802.11 a	Back	0	48	5240	16.52	17.00	1.117	0.07	0.541	0.604







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Band2 ANT1:

Plo No.	I Rand I	Mode	Test Position	Gap (cm)	Ch.	Freq. (MHz		Tune-U p Limit (dBm)	Scalin g Factor	r Drift	Measure d SAR <sub>1g</sub> (W/kg)	Reporte d SAR <sub>1g</sub> (W/kg)
Anbo	WIFI 5.3GHz	802.11 ax20	Left	o <sup>1</sup> 0	46	5320	15.53	16.00	1.114	0.10	0.168	0.187
P.C	WIFI 5.3GHz	802.11 ax20	Right	VU/Oye	46	5320	15.53	16.00	1.114	N/A	N/A	N/A 🚧
v	WIFI 5.3GHz	802.11 ax20	Тор	0	46	5320	15.53	16.00	1.114	0.15	0.098	0.109
ie.	WIFI 5.3GHz	802.11 ax20	Bottom	м O	46	5320	15.53	16.00	1.114	-0.01	0.085	0.095
, bot	WIFI 5.3GHz	802.11 ax20	Front	o**0	46	5320	15.53	16.00	1.114	0.08	0.159	0.177
#3	WIFI 5.3GHz	802.11 ax20	Back	rup <b>o</b> tek	46	5320	15.53	16.00	1.114	0.09	0.432	0.481

### ANT2:

Plot No.	Band	Mode	Test Position	Gap (cm)		Freq. (MHz	م ا	Tune-U p Limit (dBm)	Scalin g Factor	r Drift	Measure d SAR <sub>1g</sub> (W/kg)	Reporte d SAR <sub>1g</sub> (W/kg)
Anb	WIFI 5.3GHz	802.11 a	Left	up gen	52	5260	13.46	13.50	1.009	0.09	0.113	0.114
P	WIFI 5.3GHz	802.11 a	Right	0	52	5260	13.46	13.50	1.009	N/A	N/A	N/A
V	WIFI 5.3GHz	802.11 a	Тор	0	52	5260	13.46	13.50	1.009	0.06	0.065	0.066
h-Otek	WIFI 5.3GHz	802.11 a	Bottom	<sub>1</sub> ⊗ <sup>1</sup> 0	52	5260	13.46	13.50	1.009	0.03	0.058	0.059
upo No-	WIFI 5.3GHz	802.11 a	Front	10°0'	52	5260	13.46	13.50	1.009	0.11	0.102	0.103
#4	WIFI 5.3GHz	802.11 a	Back	NO Ote	52	5260	13.46	13.50	1.009	0.13	0.242	0.244



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### 13. Simultaneous Transmission Analysis

### **Simultaneous TX SAR Considerations**

No. Applicable Simultaneous Transmission

1. WIFI 5.2G ANT1 +WIFI 5.2G ANT2

2. WIFI 5.3G ANT1 +WIFI 5.3G ANT2

### **Simultaneous Transmission Procedures**

This device contains transmitters that may operate simultaneously. Therefore simultaneous transmission analysis is required. Per FCC KDB 447498 D01v05r02, simultaneous transmission SAR test exclusion may be applied when the sum of the 1-g SAR for all the simultaneous transmitting antennas in a specific a physical test configuration is  $\leq 1.6$  W/kg.

### WIFI 5.2G ANT1 +WIFI 5.2G ANT2:

Test Position			MAX. ΣSAR <sub>1-g</sub> (W/Kg)	SAR <sub>1-g</sub> Limit (W/Kg)	Simut. Meas. Required
Left	0.305	0.264	0.569	1.6	N/A
Right	N/A	N/A	N/A	1.6	N/A
Тор	0.138	0.131	0.269	1.6 Anbott	N/A
Bottom	0.126	0.115	0.241	1.6 nt	N/A MA
Front	0.290	0.240	0.530	1.6	N/A M
Back	0.655	0.604	1.259	1.6	N/A



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Test Position	WiFi ANT 1 SAR <sub>1-g</sub> (W/Kg)	WiFi ANT 2 SAR <sub>1-g</sub> (W/Kg)	MAX. ΣSAR <sub>1-g</sub> (W/Kg)	SAR <sub>1-g</sub> Limit (W/Kg)	Simut. Meas. Required
Left And	0.187	0.114	0.301	1.6	N/A
Right	N/A	N/A	N/A	1.6	N/A
Тор	0.109	0.066	0.175	1.6	N/A
Bottom	0.095	0.059	0.154	1.6	N/A
Front	0.177	0.103	0.28	1.6	N/A
Back	0.481	0.244	0.725	1.6	N/A





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# **Measurement Uncertainty**

Anb	otek Aupotes Aus	mbotek	Aupotek	bz	potek	. P	Stand.U	Stand.U	Anbot
NO	Source	Uncert.	Prob. Dist.	Div. k	ci (1g)	ci (10g)	ncert. ui (1g)	ncert. ui (10g)	Veff
potek 1,el	Repeat	0. 4	o <sup>tek</sup> p	Upote.	* 1	Anbotel	0. 4	0. 4	Mildrek
Aupolo -p.	otek Ambotek Amb	orek p	Instru			Anbe	-potek	Anbotek	Aupotek
2	Probe calibration	nbo nbok	Nootek	2	Anbore 1	e* 1	3.5	3.5	∞
3	Axial isotropy	4.7	kek R Ar	√3×6×	0.7	0.7	1.9	1.9 An	otek «
4.00	Hemispherical isotropy	9.4	And R	√3 <sup>-</sup>	0.7	0.7	3.9	3.9	Anbotek & bote
5	Boundary effect	1.0	R Anbot	_ √3	Anklot	1 1	0.6	0.6	w Anb
6	Linearity	4.7	R An	√3	An <sup>1</sup>	anbotek	2.7	2.7	nbotek
,700°	Detection limits	1.0	Anbotek R	√3	<sub>otek</sub> obotet	Anbot 1 An	0.6	0.6	Anbores .
8 🗠	Readout electronics	0.3	Anbor N	y 1	AnbPie	1	0.3	0.3	∞ Wup
√o\8	Response time	0.8	ek R Ant	_ √3	Anb 1	otek obo <mark>1</mark> ek	0.5	0.5	rek    -otel∞
10	Integration time	2.6	R R	√3	1 1	Aphore	1.5	1.5	Vupote <sub>k</sub>
Anbo	Ambient noise	3.0	Arribotek R	_ <u>_</u> √3	hotel anb1el	Ani 1	unbotek 1.7	Anbotek 1.7 <sub>otek</sub>	Anbor ∞ <sub>Anbo</sub>
× 12	Ambient reflections	3.0	Anbo R Anb	_ √3	Anbr	hotek hotek	1.7	1.7	rek Ar
13	Probe positioner mech. restrictions	0.4	otek nbotiR	√3	1 1 ck	Anbotel	0.2	0.2	Anbotek Anbotek
14	Probe positioning with respect to phantom shell	2.9	Anborek R	_ √3	Anbotek Anbotek	iek 1	nbotek Angotek Angotek Anbotek	Anborek 1.7	Anbot Anbot ek ∞ An





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15	Max.SAR evaluation	1.0	R √3	otek 1	Anbotek 1	. 0.6	0.6	Anborek ∞

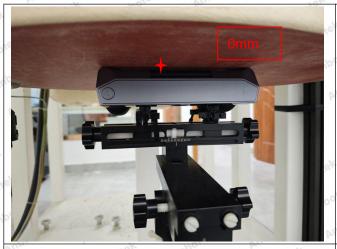
	bote And	reV-	apo.		la.	-\/-	- b010	Vien	
3K	Anbotek Anbotek	Anbore	Test samp	ole rel	ated	hotek	Anbotek	Anbo	er Ar
	Anboten Anbo	F	otek A	horo	P.	, otel	anbo	ISK PL	b.
16	Device positioning	3.8	<sub>abot</sub> eN	Andoor	1	Anbo.	3.8	3.8	99
17	Device holder	5.1	Aud <mark>N</mark>	1 <sup>Anl</sup>	ote. 1 Anbotek	1 A	5.1	5.1	5.nbot
	upo, W. Wolek	Anbore.	VUL	ek_	Anbo	ek	Aupo.	by.	ek An
18	Drift of output power	5.0	RAnbo	√3	1	bote	2.9	2.9	ovey ∞
otek	Anbote, And	Anb	Phantom a	and se	et-up	Anbotek	Anbo'	ter bu	nbotek
nbotek	Aupo, br	rek A	upote.	VILLE	rek	Anbo	lek bu	00.	hotek
19	Phantom uncertainty	4.0	anb R	√3	1,4	1	2.3	2.3	∞
ber	Liquid conductivity	10 rek	abotek	1	Upo,	r bu	worek.	Anbores	VUP
20	(target)	5.0	R	√3	0.64	0.43	1.8	1.2	∞
Nor	Liquid conductivity	VUD	ek ad	potek	AU	, o	hoj.	ek Anb	0,00
21	(meas)	2.5	notekN K	anbore!	0.64	0.43	1.6	1.2	mbotek w
Upo,	Liquid Permittivity	Ser Vi	-rek	Anb'	otek.	Vupo,	er.	hotek	Anbores
22	(target)	5.0	Anbor R	√3	0.6	0.49	1.7	1.5	∞ ,
PL	Liquid Permittivity	Anbore	Vien	N.	arbote	16-	Vupo.	hotel	Anb'
23	(meas)	2.5	N <sup>nbote</sup>	otel.	0.6	0.49	1.5	1.2	NeV ∞
lek.	Anbors Arek Anborek	Anbot	otek Vu	horek		Anbotek	Aupor	otek b	nbotek
botek	Combined standard	ek An	porto.	The The	$C = \sqrt{\sum_{i=1}^{n}}$	$C^2H^2$	ik Aup	. o.k	-potek
doo't	ek Anbor Anz	ootek	RSS	Anbo	$V = \sqrt{\frac{2}{i=1}}$		11.4%	11.3%	236
Dir	otek Anbotek An	no/-	botek	P.	por	, An	Lotek	Anboien	Vupe
unce	Expanded ertainty(P=95%)	Anbotek	Aupore	J = Κ L	/ ,k=	2,e/L	22.8%	22.6%	lek Aupo





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# **Appendix A.EUT Photos and Test Setup Photos**





Front(0mm)

Back(0mm)







Left (0mm)

### **Shenzhen Anbotek Compliance Laboratory Limited**







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### **Appendix B.Plots of SAR System Check**

5200MHz Body System Check Date:12/19/2023

DUT: Dipole 5GHz; Type: D5GHzV2; Serial: D5GHzV2 - SN:1160

Communication System: UID 0, CW; Frequency: 5200 MHz; Duty Cycle: 1:1 Medium parameters used: f = 5200 MHz;  $\sigma = 5.2$  S/m;  $\varepsilon_r = 48.23$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

### DASY5 Configuration:

Probe: EX3DV4 – SN7396; ConvF(4.93, 4.93, 4.93); Calibrated: May 06, 2023;

Sensor-Surface: 2mm (Mechanical Surface Detection)

Electronics: DAE4 Sn387; Calibrated: Sep. 06, 2023

Phantom: SAM; Type: QD000P40CD; Serial: TP:1670

Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

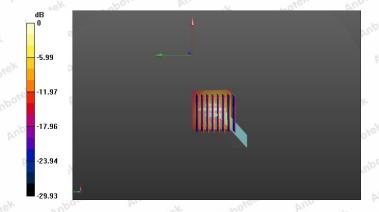
Configuration/Pin=100mW/Area Scan (71x71x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 20.9 W/kg

Configuration/Pin=100mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm

Reference Value = 59.857 V/m; Power Drift = 0.04 dB

Peak SAR (extrapolated) = 34.58 W/kg

SAR(1 g) = 7.63 W/kg; SAR(10 g) = 2.21 W/kg Maximum value of SAR (measured) = 20.8 W/kg





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DUT: Dipole 5GHz; Type: D5GHzV2; Serial: D5GHzV2 - SN:1160

Communication System: UID 0, CW; Frequency: 5300 MHz; Duty Cycle: 1:1 Medium parameters used: f = 5300 MHz;  $\sigma = 5.43$  S/m;  $\epsilon_r = 48.56$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

### **DASY5** Configuration:

Probe: EX3DV4 – SN7396; ConvF(4.93, 4.93, 4.93); Calibrated: May 06, 2023;

• Sensor-Surface: 2mm (Mechanical Surface Detection)

Electronics: DAE4 Sn387; Calibrated: Sep. 06, 2023

Phantom: SAM; Type: QD000P40CD; Serial: TP:1670

Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

Configuration/Pin=100mW/Area Scan (71x71x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 20.2 W/kg

Configuration/Pin=100mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm dz=1.4mm

Reference Value = 58.488 V/m; Power Drift = 0.07 dB

Peak SAR (extrapolated) = 33.8 W/kg

SAR(1 g) = 7.69 W/kg; SAR(10 g) = 2.17 W/kg Maximum value of SAR (measured) = 20.7 W/kg







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### Appendix C.Plots of SAR Test Data

#1 Date: 12/19/2023

### WIFI 5.2G\_802.11a\_CH40 BODY BACK

Communication System: UID 0, wifi (fcc) (0); Frequency: 5200 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): f = 5200 MHz;  $\sigma = 5.20$  S/m;  $\varepsilon_r = 48.23$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

### DASY5 Configuration:

Probe: EX3DV4 - SN7396; ConvF(4.93, 4.93, 4.93); Calibrated: May 06, 2023;

Sensor-Surface: 1.4mm (Mechanical Surface Detection)

• Electronics: DAE4 Sn387; Calibrated: Sep. 06, 2023

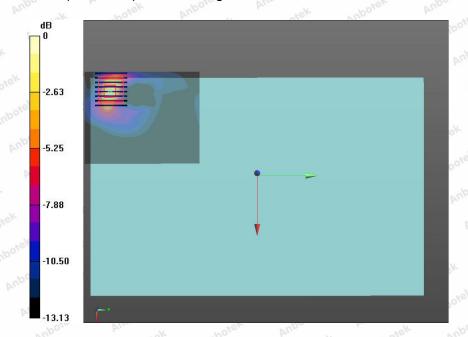
• Phantom: SAM; Type: QD000P40CD; Serial: TP:1670

Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

**BODY BACK /Area Scan (81x101x1):** Measurement grid: dx=1.000mm, dy=1.000mm Maximum value of SAR (interpolated) = 1.652 W/kg

**BODY BACK /Zoom Scan (8x8x8)/Cube 0:** Measurement grid: dx=4mm, dy=4mm, dz=1.4mm Reference Value = 6.458 V/m; Power Drift = 0.11 dB Peak SAR (extrapolated) = 1.325 W/kg

**SAR(1 g) = 0.582 W/kg; SAR(10 g) = 0.262 W/kg** Maximum value of SAR (measured) = 1.632 W/kg





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