

# SAR Test Report

# Report No.: AGC02931211203FH01

FCC ID	:	2AWYH-GMR2
PRODUCT DESIGNATION	:	GMRS TRANSCEIVER
BRAND NAME	:	Rugged Radios
MODEL NAME	:	GMR2
APPLICANT	:	Rugged Radios
DATE OF ISSUE	:	Jul. 27, 2022
STANDARD(S)	:	IEEE Std. 1528:2013 FCC 47 CFR Part 2§2.1093 IEEE Std C95.1 ™-2005 IEC 62209-1: 2016
REPORT VERSION	:	V1.0







#### **Report Revise Record**

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	/	Jul. 27, 2022	Valid	Initial Release



Test Report					
Applicant Name	Rugged Radios				
Applicant Address	509 Traffic Way, Arroyo Grande, California 93420, United States				
Manufacturer Name	Rugged Radios				
Manufacturer Address	509 Traffic Way, Arroyo Grande, California 93420, United States				
Factory Name	Rugged Radios				
Factory Address	509 Traffic Way, Arroyo Grande, California 93420, United States				
Product Designation	GMRS TRANSCEIVER				
Brand Name	Rugged Radios				
Model Name	GMR2				
Different Description	N/A				
EUT Voltage	DC7.4 V				
Applicable Standard	IEEE Std. 1528:2013 FCC 47 CFR Part 2§2.1093 IEEE Std C95.1 ™-2005 IEC 62209-1: 2016				
Test Date	Jan. 18, 2022				
Report Template	AGCRT- US -PTT/SAR (2021-04-20)				

Note: The results of testing in this report apply to the product/system which was tested only.

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#### TABLE OF CONTENTS

1. SUMMARY OF MAXIMUM SAR VALUE	5
2. GENERAL INFORMATION	6
2.1. EUT DESCRIPTION	6
3. SAR MEASUREMENT SYSTEM	7
3.1. THE DASY5 SYSTEM USED FOR PERFORMING COMPLIANCE TESTS CONSISTS OF FOLLOWING ITEMS	
3.3. DATA ACQUISITION ELECTRONICS DESCRIPTION	
3.4. Rовот 3.5. Light Beam Unit	-
3.6. DEVICE HOLDER	-
3.7. Measurement Server	
3.8. PHANTOM	
4. SAR MEASUREMENT PROCEDURE	
4.1. SPECIFIC ABSORPTION RATE (SAR)	
4.2. SAR MEASUREMENT PROCEDURE	
5. TISSUE SIMULATING LIQUID	15
5.1. THE COMPOSITION OF THE TISSUE SIMULATING LIQUID	-
5.2. TISSUE DIELECTRIC PARAMETERS FOR HEAD AND BODY PHANTOMS	
5.3. TISSUE CALIBRATION RESULT	
6. SAR SYSTEM CHECK PROCEDURE	
6.1. SAR System Check Procedures	
7. EUT TEST POSITION	19
7.1. BODY WORN POSITION	19
8. SAR EXPOSURE LIMITS	
9. TEST FACILITY	21
10. TEST EQUIPMENT LIST	22
11. MEASUREMENT UNCERTAINTY	23
12. POWER MEASUREMENT	
13. TEST RESULTS	
13.1. SAR TEST RESULTS SUMMARY	
APPENDIX A. SAR SYSTEM CHECK DATA	33
APPENDIX B. SAR MEASUREMENT DATA	
APPENDIX C. TEST SETUP PHOTOGRAPHS	
APPENDIX D. CALIBRATION DATA	57



# **1. SUMMARY OF MAXIMUM SAR VALUE**

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Highest Report standalone SAR Summary (50% duty cycle)

		Highest Reported 1g-SAR(W/kg)				
Frequency Band	Separation	Face Up (with 25mm separation)         Back Touch           0.794         1.394           0.279         0.510           0.718         1.375           0.660         1.304				
462.5625-462.7125MHz (2W)		0.794	1.394			
467.5625-467.7125MHz (0.5W)	12.5KHz	0.279	0.510			
462.5500-462.7250MHz (2W)		0.718	1.375			
467.5500-467.7250MHz (2W)		0.660	1.304			
462.5625-462.7125MHz (2W)		0.719	1.494			
462.5500-462.7250MHz (2W)	25KHz	0.721	1.407			
467.5500-467.7250MHz (2W)		0.750	1.377			

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure environment limits(1.6W/kg) specified in 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1, and had been tested in accordance with measurement methods and procedures specified in IEEE 1528-2013 and the following specific FCC Test Procedures:

KDB447498 D01 General RF Exposure Guidance v06

KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04

KDB 643646 D01 SAR Test for PTT Radios v01r03



# 2. GENERAL INFORMATION

# 2.1. EUT Description

General Information	
Product Name	GMRS TRANSCEIVER
Test Model	GMR2
Hardware Version	VER 2.1B
Software Version	V1.18
Exposure Category:	General Population/Uncontrolled Environments
Device Category	FM Portable Transceiver
Modulation Type	FM
TX Frequency Range	462.5500MHz-462.7250MHz (GMRS 462 MHz main channels) 462.5625MHz-462.7125MHz (GMRS 462 MHz interstitial channels) 467.5500MHz-467.7250MHz (GMRS 467 MHz main channels) 467.5625MHz-467.7125MHz (GMRS 467 MHz interstitial channels)
Rated Power	2W/0.5W (It was fixed by the manufacturer, any individual can't arbitrarily change it)
Max. Output Power	32.34dBm
Channel Spacing	12.5 KHz& 25 KHz
Antenna Type	Inseparable
Antenna Gain	1.5dBi
Body-Worn Accessories:	Belt Clip with headset
Face-Head Accessories:	None
Battery Type (s) Tested:	DC7.4V, 1400mAh (by battery)
Note: 1. The sample used for 2. The test sample ha	r testing is end product. s no any deviation to the test method of standard mentioned in page 1.
Product	Type  Production unit  Identical Prototype

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# **3. SAR MEASUREMENT SYSTEM**

# Image: Service Conversion </tr

# 3.1. The DASY5 system used for performing compliance tests consists of following items

- A standard high precision 6-axis robot with controller, teach pendant and software.
- Data acquisition electronics (DAE) which attached to the robot arm extension. The DAE consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock
- A dosimetric probe equipped with an optical surface detector system.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital Communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- A Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- Phantoms, device holders and other accessories according to the targeted measurement.



#### 3.2. DASY5 E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SPEAG. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN62209,IEC 62209, etc.)Under ISO17025.The calibration data are in Appendix D.

Model	ES3DV3
Manufacture	SPEAG
frequency	0.15GHz-0.45 GHz Linearity:±0.6%dB(K=2)(0.15MHz-0.45 GHz)
Dynamic Range	0.01W/kg-100W/kg Linearity:±0.6%dB(K=2)
Dimensions	Overall length:337mm Tip diameter:4mm Typical distance from probe tip to dipole centers:2mm
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 3 GHz with precision of better 30%.

#### Isotropic E-Field Probe Specification

#### 3.3. Data Acquisition Electronics description

The data acquisition electronics (DAE) consist if a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converte and a command decoder with a control logic unit. Transmission to the measurement sever is accomplished through an optical downlink fir data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

DAE4

Input Impedance	200MOhm	
The Inputs	Symmetrical and floating	
Common mode rejection	above 80 dB	



#### 3.4. Robot

The DASY system uses the high precision robots (DASY5:TX60) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from is used.

The XL robot series have many features that are important for our application:

- □ High precision (repeatability 0.02 mm)
- □ High reliability (industrial design)
- □ Jerk-free straight movements
- □ Low ELF interference (the closed metallic construction shields against motor control fields)
- □ 6-axis controller



#### 3.5. Light Beam Unit

The light beam switch allows automatic "tooling" of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned prob.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position. e, the same position will be reached with another aligned probe within 0





#### 3.6. Device Holder

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles. The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon$ =3 and loss tangent  $\delta$  = 0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



#### 3.7. Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chip-disk (DASY5: 128MB), RAM (DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DAYS I/O board, which is directly connected to the PC/104 bus of the CPU board. The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.





#### 3.8. PHANTOM SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left head
- □ Right head
- □ Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

#### **ELI4** Phantom

□ Flat phantom a fiberglass shell flat phantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom





# 4. SAR MEASUREMENT PROCEDURE

#### 4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of given mass density ( $\rho$ ). The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg) SAR can be obtained using either of the following equations:

Е

ρ

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \frac{dT}{dt}_{t=0}$$

Where

SAR is the specific absorption rate in watts per kilogram;

- $\sigma$  is the r.m.s. value of the electric field strength in the tissue in volts per meter;  $\sigma$  is the conductivity of the tissue in siemens per metre;
  - is the density of the tissue in kilograms per cubic metre;
- c<sub>h</sub> is the heat capacity of the tissue in joules per kilogram and Kelvin;

 $\frac{dT}{dt}$  | t = 0 is the initial time derivative of temperature in the tissue in kelvins per second



#### 4.2. SAR Measurement Procedure

#### Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance os sensor calibration points to probe tip as `defined in the probe properties,

#### Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528 and IEC62209 standards, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

	$\leq$ 3 GHz	> 3 GHz	
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	$5 \pm 1 \text{ mm}$	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$	
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30°±1°	20°±1°	
	≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm	
Maximum area scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub>	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.		

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

#### Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g abd 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.



Maximum zoom scan spatial resolution: $\Delta x_{\text{Zoom}},\Delta y_{\text{Zoom}}$			$\leq 2 \text{ GHz}: \leq 8 \text{ mm}$ 2 - 3 GHz: $\leq 5 \text{ mm}^*$	$3 - 4 \text{ GHz} \le 5 \text{ mm}^{*}$ $4 - 6 \text{ GHz} \le 4 \text{ mm}^{*}$
Maximum zoom scan spatial resolution, normal to phantom surface g	uniform (	grid: ∆z <sub>Zoom</sub> (n)	$\leq$ 5 mm	$3 - 4$ GHz: $\leq 4$ mm $4 - 5$ GHz: $\leq 3$ mm $5 - 6$ GHz: $\leq 2$ mm
	graded	∆z <sub>Zoom</sub> (1): between 1 <sup>st</sup> two points closest to phantom surface	$\leq$ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
	grid $\Delta z_{Zoom}(n>1)$ : between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$		
Minimum zoom scan volume x, y, z		$\geq$ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm	

#### Zoom Scan Parameters extracted from KDB865664 D01 SAR Measurement 100MHz to 6GHz

<sup>\*</sup> When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

#### Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.



# **5. TISSUE SIMULATING LIQUID**

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 10% are listed in 6.2

#### 5.1. The composition of the tissue simulating liquid

Ingredient (% Weight) Frequency (MHz)	Water	Nacl	Sugar	HEC	Bactericide	DGBE	1,2- Propanediol	Triton X-100
450 Head (100%)	38.56	3.95	56.32	0.98	0.19	0.0	0.0	0.0

#### 5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEC 62209-1 have been incorporated in the following table. The body tissue dielectric parameters recommended by the IEC 62209-2 have been incorporated in the following table.

Target Frequency	head		bo	ody
(MHz)	٤r	σ (S/m)	٤r	σ (S/m)
150	52.3	0.76	52.3	0.76
300	45.3	0.87	45.3	0.87
450	43.5	0.87	43.5	0.87
835	41.5	0.90	41.5	0.90
900	41.5	0.97	41.5	0.97
915	41.5	0.98	41.5	0.98
1450	40.5	1.20	40.5	1.20
1610	40.3	1.29	40.3	1.29
1800 – 2000	40.0	1.40	40.0	1.40
2450	39.2	1.80	39.2	1.80
3000	38.5	2.40	38.5	2.40

( $\epsilon r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho$  = 1000 kg/m3)



#### 5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using DASY5 Dielectric Probe Kit and R&S Network Analyzer ZVL6.

	Tissue Stimulant Measurement for 450MHz									
	Dielectric Par	ameters (±10%)	Tissue							
Fr.										
(MHz)	ɛr43.50(39.150 - 47.850)	δ[s/m]0.87(0.783 - 0.957)	[°C]							
462.000	44.21	0.87								
450.000	43.91	0.88	20.4	Jan. 18, 2022						
467.000	43.75	0.89								



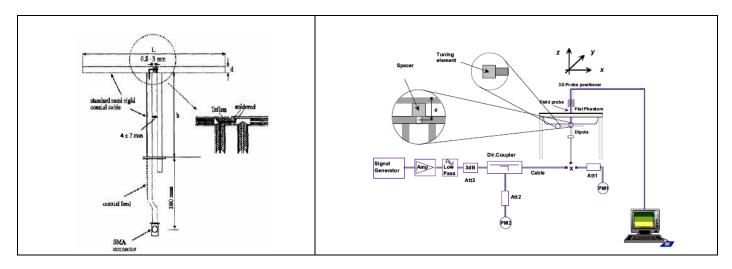
# 6. SAR SYSTEM CHECK PROCEDURE

#### 6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each DASY system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.





## 6.2. SAR System Check

# 6.2.1. Dipoles

	The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. the table below provides details for the mechanical and electrical specifications for the dipoles
--	---

Frequency	R/L (mm)	R/h (mm)	d (mm)	
450MHz	290	166.7	6.35	

#### 6.2.2. System Check Result

System Performance Check at 450MHz									
Validation Kit: D450V3 SN:1113									
Frequency		rget (W/kg)	Reference Result (± 10%)			alized (W/kg)	Tissue Temp.	Test time	
[MHz]	1g	10g	1g	10g	1g	10g	[°C]		
450 head	4.61	3.09	4.149-5.071	2.781-3.399	4.58	3.04	20.4	Jan. 18, 2022	

Note:

(1) We use a CW signal of 18dBm(450MHz)for system check, and then all SAR value are normalized to 1W forward power. The result must be within ±10% of target value.

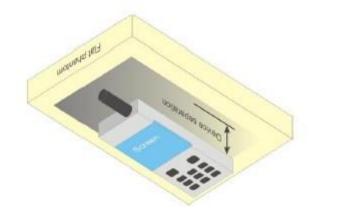


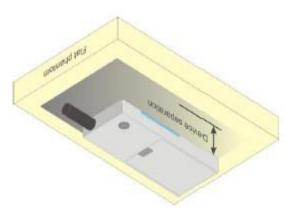
# 7. EUT TEST POSITION

This EUT was tested in Front Face and Rear Face.

#### 7.1. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **25mm** while used in front of face, and body back touch with belt clip.







# 8. SAR EXPOSURE LIMITS

#### Limits for General population/Uncontrolled exposure Environment

Type Exposure Limits	general population/uncontrolled exposure limits (W/kg)				
Spatial Average SAR (whole body)	1.6				



# 9. TEST FACILITY

Test Site	Attestation of Global Compliance (Shenzhen) Co., Ltd
Location1-2/F, Building 19, Junfeng Industrial Park, Chongqing Road, Heping C Fuhai Street, Bao'an District, Shenzhen, Guangdong, China	
Designation Number	CN1259
FCC Test Firm Registration Number	975832
A2LA Cert. No.	5054.02
Description	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by A2LA



# **10. TEST EQUIPMENT LIST**

Equipment	Manufacturer/	Identificat	Software	Current	Next calibration
description	Model	ion No.	version	calibration date	date
Stäubli Robot	Stäubli-TX60	F13/5Q2U D1/A/01	N/A	N/A	N/A
Robot Controller	Stäubli-CS8	139522	N/A	N/A	N/A
E-Field Probe	Speag- ES3DV3	SN:3337	N/A	Aug. 24, 2021	Aug. 23, 2022
SAM Twin Phantom	Speag-SAM	1790	N/A	N/A	N/A
ELI4 Phantom	ELI V5.0	1210	N/A	N/A	N/A
Device Holder	Speag-SD 000 H01 KA	SD 000 H01 KA	N/A	N/A	N/A
DAE4	Speag-SD 000 D04 BM	1398	N/A	May 17,2021	May 16,2022
SAR Software	Speag-DASY5	N/A	5.3da53	N/A	N/A
Liquid	SATIMO	N/A	N/A	N/A	N/A
Dipole	Speag-D450V3	SN:1113	N/A	Feb. 05,2021	Feb. 04,2024
Signal Generator	Agilent-E4438C	US414613 65	V5.03	Aug. 18,2021	Aug. 17,2022
Vector Analyzer	Agilent / E4440A	MY443039 16	N/A	Mar. 21,2021	Mar. 20,2022
Network Analyzer	Rhode & Schwarz ZVL6	SN101443	3.2	Oct. 28,2021	Oct. 27,2022
Attenuator	Warison /WATT-6SR1211	S/N:WRJ3 4AYM2F1	N/A	June 09,2021	June 08,2022
Amplifier	AS0104-55_55	1004793	N/A	June 10,2021	June 09,2022
Directional Couple	Werlatone/ C5571-10	SN99463	N/A	May 15,2020	May 14,2022
Power Sensor	NRP-Z21	1137.6000 .02	N/A	Sep. 07,2021	Sep. 06,2022
Power Sensor	NRP-Z23	100323	N/A	Feb. 17,2021	Feb. 16,2022
Power Viewer	R&S	V2.3.1.0	N/A	N/A	N/A
Calibration standard parts for network sub - port	R&S/ ZV-Z132	N/A	V2.3.1.0	Dec. 07, 2021	Dec. 06, 2022

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

1. There is no physical damage on the dipole;

2. System validation with specific dipole is within 10% of calibrated value;

3. Return-loss is within 20% of calibrated measurement;

4. Impedance is within  $5\Omega$  of calibrated measurement.



# **11. MEASUREMENT UNCERTAINTY**

The component of uncertainly may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainly by the statistical analysis of a series of observations is termed a Type An evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience, and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table as follow.

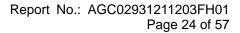
Uncertainty Distributions	Normal	Rectangular	Triangular	U-Shape	
Multi-plying Factor(a)	1/k(b)	1/√3	1/√6	1/√2	

- (a) Standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity
- (b)  $\kappa$  is the coverage factor

#### Table 13.1 Standard Uncertainty for Assumed Distribution (above table)

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is shown in the following tables.





Measu	irement ur	DASY I		ty- ES3DV averaged c		/ 10 gram.			
а	b	с	d	e f(d,k)	f	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System									
Probe calibration	E.2.1	6.65	Ν	1	1	1	6.65	6.65	8
Axial Isotropy	E.2.2	0.25	R	$\sqrt{3}$	√0.5	√0.5	0.10	0.10	8
Hemispherical Isotropy	E.2.2	1.3	R	$\sqrt{3}$	√0.5	√0.5	0.53	0.53	8
Boundary effect	E.2.3	1	R	$\sqrt{3}$	1	1	0.58	0.58	8
Linearity	E.2.4	0.3	R	$\sqrt{3}$	1	1	0.17	0.17	8
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	8
Modulation response	E2.5	3.3	R	$\sqrt{3}$	1	1	1.91	1.91	8
Readout Electronics	E.2.6	0.15	N	1	1	1	0.15	0.15	8
Response Time	E.2.7	0	R	$\sqrt{3}$	1	1	0	0	∞
Integration Time	E.2.8	1.7	R	$\sqrt{3}$	1	1	0.98	0.98	8
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	8
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
Probe positioner mechanical tolerance	E.6.2	0.4	R	$\sqrt{3}$	1	1	0.23	0.23	8
Probe positioning with respect to phantom shell	E.6.3	6.7	R	√3	1	1	3.87	3.87	8
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	4	R	√3	1	1	2.31	2.31	8
Test sample Related									·
Test sample positioning	E.4.2	2.9	Ν	1	1	1	2.90	2.90	∞
Device holder uncertainty	E.4.1	3.6	Ν	1	1	1	3.60	3.60	∞
Output power variation—SAR drift measurement	E.2.9	5	R	√3	1	1	2.89	2.89	∞
SAR scaling	E.6.5	5	R	$\sqrt{3}$	1	1	2.89	2.89	8
Phantom and tissue parameters									·
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	6.6	R	√3	1	1	3.81	3.81	8
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	Ν	1	1	0.84	1.90	1.60	8
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	М
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.15	1.30	М
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	8
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS				11.79	11.62	
Expanded Uncertainty (95% Confidence interval)			K=2				23.58	23.25	



Queter	. Chaoly w			ty- ES3DV		110			
System	n Check ui	ncertainty to	or Dipole a		over 1 gram	/ 10 gram.	h	i	
а	b	с	d	e f(d,k)	f	g	c×f/e	c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System									
Probe calibration drift	E.2.1	0.5	Ν	1	1	1	0.5	0.5	∞
Axial Isotropy	E.2.2	0.25	R	$\sqrt{3}$	0	0	0.00	0.00	8
Hemispherical Isotropy	E.2.2	1.3	R	$\sqrt{3}$	0	0	0.00	0.00	8
Boundary effect	E.2.3	1	R	$\sqrt{3}$	0	0	0.00	0.00	8
Linearity	E.2.4	0.3	R	$\sqrt{3}$	0	0	0.00	0.00	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Modulation response	E2.5	3.3	R	√3	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.15	N	1	0	0	0.00	0.00	∞
Response Time	E.2.7	0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.7	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Probe positioner mechanical tolerance	E.6.2	0.4	R	√3	1	1	0.23	0.23	∞
Probe positioning with respect to phantom shell	E.6.3	6.7	R	√3	1	1	3.87	3.87	8
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	4	R	√3	0	0	0.00	0.00	8
System check source (dipole)									
Deviation of experimental dipoles	E.6.4	2.0	Ν	1	1	1	2.00	2.00	∞
Input power and SAR drift measurement	8,6.6.4	5.0	R	√3	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	6.6	R	$\sqrt{3}$	1	1	3.81	3.81	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	8
Liquid conductivity measurement	E.3.3	4	Ν	1	0.78	0.71	3.12	2.84	М
Liquid permittivity measurement	E.3.3	5	Ν	1	0.23	0.26	1.15	1.30	М
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	8
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS				7.34	7.07	
Expanded Uncertainty (95% Confidence interval)			K=2				14.67	14.14	



System	Validation	DASY L uncertainty		ty- ES3DV e averaged		m / 10 gram	1.		
а	b	с	d	e f(d,k)	f	g	h cxf/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (±%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System						·			
Probe calibration	E.2.1	6.65	N	1	1	1	6.65	6.65	8
Axial Isotropy	E.2.2	0.25	R	√3	1	1	0.14	0.14	8
Hemispherical Isotropy	E.2.2	1.3	R	√3	0	0	0.00	0.00	8
Boundary effect	E.2.3	1	R	$\sqrt{3}$	1	1	0.58	0.58	8
Linearity	E.2.4	0.3	R	$\sqrt{3}$	1	1	0.17	0.17	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Modulation response	E2.5	3.3	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.15	N	1	1	1	0.15	0.15	∞
Response Time	E.2.7	0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.7	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R		1	1	1.73	1.73	∞
RF ambient conditions-reflections	E.6.1	3.0	R	√3	1	1	1.73	1.73	∞
Probe positioner mechanical tolerance	E.6.2	0.4	R	√3	1	1	0.37	0.37	∞
Probe positioning with respect to phantom shell	E.6.3	6.7	R	√3	1	1	3.87	3.87	8
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	4	R	√3	1	1	2.31	2.31	∞
System check source (dipole)			•						
Deviation of experimental dipole from numerical dipole	E.6.4	5.0	N	1	1	1	5.00	5.00	8
Input power and SAR drift measurement	8,6.6.4	5.0	R	√3	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2.0	R	√3	1	1	1.15	1.15	8
Phantom and tissue parameters						·			
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	6.6	R	√3	1	1	3.81	3.81	8
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	8
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	М
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.15	1.30	М
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS				11.44	11.27	
Expanded Uncertainty (95% Confidence interval)			K=2				22.88	22.54	

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# **12. POWER MEASUREMENT**

Frequency (MHz)	Channel	ERP (dBm)		
ChannelSeparation:12.5KHz				
462.5625-462.7125MHz (2W)				
462.5625	1	32.18		
462.6375	4	32.22		
462.7125	7	32.10		
467.5625-467.7125MHz (0.5W)				
467.5625	8	26.74		
467.6375	11	26.85		
467.7125	14	26.82		
462.5500-462.7250MHz (2W)	· · · · ·			
462.5500	15	32.14		
462.6500	19	32.15		
462.7250	22	32.09		
467.5500-467.7250MHz (2W)	· · · · ·			
467.5500	24	32.25		
467.6500	27	32.34		
467.7250	30	32.31		

Frequency (MHz)	Channel	ERP (dBm)
ChannelSeparation:25KHz		
462.5625-462.7125MHz (2W)		
462.5625	1	32.04
462.6375	4	32.13
462.7125	7	32.08
462.5500-462.7250MHz (2W)		·
462.5500	15	32.07
462.6500	19	32.09
462.7250	22	32.05
467.5500-467.7250MHz (2W)		
467.5500	24	32.27
467.6500	27	32.31
467.7250	30	32.24



# **13. TEST RESULTS**

#### 13.1. SAR Test Results Summary

#### 13.1.1. Test position and configuration

Face up SAR was performed with the device configured in the positions according to KDB 643646 and Body SAR was performed with the device configured with all accessories close to the Flat Phantom.

#### 13.1.2. Operation Mode

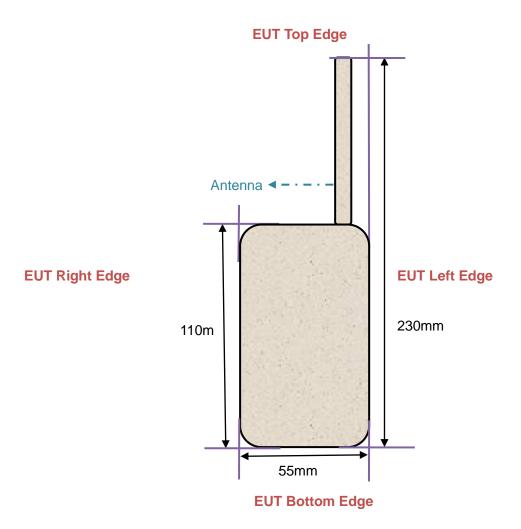
- Set the EUT to maximum output power level and transmit on lower, middle and top channel with 100% duty cycle individually during SAR measurement.
- Per KDB 643646 D01, Passive body-worn and audio accessories generally do not apply to the head SAR of PTT radios. Head SAR is measured with the front surface of the radio positioned at 2.5 cm parallel to a flat phantom.
- Per KDB 643646 D01, Body SAR is measured with the radio placed in a body-worn accessory, positioned against a flat phantom, representative of the normal operating conditions expected by users and typically with a standard default audio accessory supplied with the radio.

When testing antennas with the default battery: the same test measurement with head part.

• The EUT only contains the Testing antenna, Standard battery and default body-worn accessory specified by customer. The earphone is only for testing



13.1.3. Antenna Location: (back view)





#### 13.1.4. SAR Test Results Summary

SAR MEASUREMENT										
Depth of Liquid (cm):>15 Relative Humidity (%): 45.2										
Product: GMRS TRANSCEIVER										
Test Mode: Hold to Face with 2.5 cm separation & body back touch with clip										
Position	Freq. (MHz)	Sepa ratio n (KHz)	Power Drift (±0.2dB)	SAR 1g with 100% duty Cycle (W/kg)	SAR 1g with 50% duty cycle (W/kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/kg)	Limit W/kg	
462.5625-462.7125M	Hz (2W)									
Face Up	462.6375	12.5	-0.08	1.300	0.650	33.01	32.22	0.794	1.6	
Back Touch +Belt Clip + headset	462.5625		0.10	2.290	1.145	33.01	32.18	1.355	1.6	
Back Touch +Belt Clip + headset	462.6375		-0.26	2.190	1.095	33.01	32.22	1.394	1.6	
Back Touch +Belt Clip + headset	462.7125		-0.30	2.070	1.035	33.01	32.10	1.368	1.6	
467.5625-467.7125M	Hz (0.5W)									
Face Up	467.6375	12.5	-0.02	0.538	0.269	26.99	26.85	0.279	1.6	
Back Touch +Belt Clip + headset	467.6375		-0.02	0.983	0.492	26.99	26.85	0.510	1.6	
462.5500-462.7250M	Hz (2W)									
Face Up	462.6500		-0.22	1.120	0.560	33.01	32.15	0.718	1.6	
Back Touch +Belt Clip + headset	462.5500	12.5	-0.14	1.960	0.980	33.01	32.14	1.237	1.6	
Back Touch +Belt Clip + headset	462.6500		-0.27	2.120	1.060	33.01	32.15	1.375	1.6	
Back Touch +Belt Clip + headset	462.7250		-0.06	2.110	1.055	33.01	32.09	1.322	1.6	
467.5500-467.7250M	467.5500-467.7250MHz (2W)									
Face Up	467.6500		-0.16	1.090	0.545	33.01	32.34	0.660	1.6	
Back Touch +Belt Clip + headset	467.5500	12.5	-0.14	1.940	0.970	33.01	32.25	1.193	1.6	
Back Touch +Belt Clip + headset	467.6500		-0.19	2.140	1.070	33.01	32.34	1.304	1.6	
Back Touch +Belt Clip + headset	467.7250		-0.15	2.000	1.000	33.01	32.31	1.216	1.6	

Note:

1. During the test, EUT power is 2W&0.5W with 100% duty cycle;

2. There is just default battery and antenna in this project;

3. Max\_ Scaled = SAR\_meas\*10<sup>$$10$$</sup>

$$\frac{|\text{Drift}|}{10} * \frac{\text{P}_{\text{max}}}{\text{P}_{\text{int}}} * \text{DC}$$

P\_max = Maximum Power(W)

 $P_{int} = Initial Power(W)$ 

Drift = DASY drift results(dB)

SAR\_ meas=Measured 10-g or 1-g Avg.SAR(W/kg)

DC = Transmission mode duty cycle in % where applicable 50% duty cycle is applied for PTT operation. For conservative results, the following are applied:

If  $P_{int} > P_{max}$ , then  $P_{max}/P_{int} = 1$ . Drift = 1 for positive drift



SAR MEASUREMEN	IT										
Depth of Liquid (cm):>15				Relative	Relative Humidity (%): 45.2						
Product: GMRS TRAI	NSCEIVER										
Test Mode: Hold to F	ace with 2.5	cm sep	aration & b	ody back to	uch with cli	р					
Position	Freq. (MHz)	Sepa ratio n (KHz)	Power Drift (±0.2dB)	SAR 1g with 100% duty Cycle (W/kg)	SAR 1g with 50% duty cycle (W/kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/kg)	Limit W/kg		
462.5625-462.7125MHz (2W)											
Face Up	462.6375		-0.09	1.150	0.575	33.01	32.13	0.719	1.6		
Back Touch +Belt Clip + headset	462.5625	25	-0.32	2.220	1.110	33.01	32.04	1.494	1.6		
Back Touch +Belt Clip + headset	462.6375		-0.12	2.110	1.055	33.01	32.13	1.328	1.6		
Back Touch +Belt Clip + headset	462.7125		-0.16	2.230	1.115	33.01	32.08	1.433	1.6		
462.5500-462.7250M	Hz (2W)								<u></u>		
Face Up	462.6500		-0.10	1.140	0.570	33.01	32.09	0.721	1.6		
Back Touch +Belt Clip + headset	462.5500		-0.03	2.250	1.125	33.01	32.07	1.407	1.6		
Back Touch +Belt Clip + headset	462.6500	25	-0.00	2.090	1.045	33.01	32.09	1.292	1.6		
Back Touch +Belt Clip + headset	462.7250		-0.11	2.100	1.050	33.01	32.05	1.343	1.6		
467.5500-467.7250MHz (2W)											
Face Up	467.6500		-0.27	1.200	0.600	33.01	32.31	0.750	1.6		
Back Touch +Belt Clip + headset	467.5500	25	-0.19	2.210	1.105	33.01	32.27	1.369	1.6		
Back Touch +Belt Clip + headset	467.6500		0.12	2.130	1.065	33.01	32.31	1.217	1.6		
Back Touch +Belt Clip + headset	467.7250		0.08	2.350	1.175	33.01	32.24	1.377	1.6		

Note:

1. During the test, EUT power is 2W with 100% duty cycle;

2. There is just default battery and antenna in this project;

$$\frac{P_max}{P} + DC$$

P\_max = Maximum Power(W) P\_ int = Initial Power(W)

Drift = DASY drift results(dB)

SAR\_ meas=Measured 10-g or 1-g Avg.SAR(W/kg)

DC = Transmission mode duty cycle in % where applicable 50% duty cycle is applied for PTT operation. For conservative results, the following are applied:

If  $P_int > P_max$ , then  $P_max/P_int = 1$ . Drift = 1 for positive drift

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Repeated SAR											
Product: GMRS TRANSCEIVER											
Test Mode: Hold to Face with 2.5 cm separation & body back touch with clip											
Position	Frequency (MHz)	Separati on (KHz)	Power Drift (<±0.2dB)	Once SAR 1g with 100% duty cycle (W/kg)	Once SAR 1g with 50% duty cycle (W/kg)	Twice SAR 1g with 100% duty cycle (W/kg)	Twice SAR 1g with 50% duty cycle (W/kg)	Limit W/kg			
462.5625-462	462.5625-462.7125MHz (2W)										
Back Touch +Belt Clip + headset	462.5625	12.5	-0.05	2.08	1.04			1.6			
467.5500-467.7250MHz (2W)											
Back Touch +Belt Clip + headset	467.7250	25	0.07	2.34	1.17			1.6			



# **APPENDIX A. SAR SYSTEM CHECK DATA**

**Test Laboratory: AGC Lab** System Check Head 450MHz

DUT: Dipole 450 MHz Type: D450V3

Test date: Jan. 18, 2022

Communication System: CW; Communication System Band: CW; Duty Cycle: 1:1; Frequency: 450MHz; Medium parameters used: f = 450MHz;  $\sigma = 0.88$  mho/m;  $\epsilon r = 43.91$ ;  $\rho = 1000$  kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom; Input Power=18dBm Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

#### **DASY** Configuration:

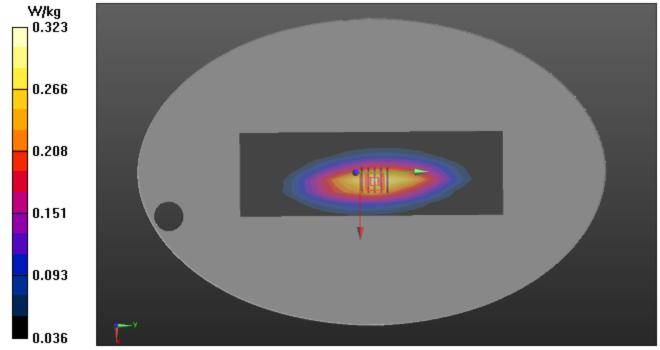
- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

Configuration/System Check 450MHz Head/Area Scan (8x23x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.318 W/kg

#### Configuration/System Check 450MHz Head/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm,

dy=8mm, dz=5mm Reference Value = 17.335 V/m; Power Drift = -0.08 dB Peak SAR (extrapolated) = 0.435 W/kg SAR(1 g) = 0.289 W/kg; SAR(10 g) = 0.192 W/kg

Maximum value of SAR (measured) = 0.323 W/kg





# APPENDIX B. SAR MEASUREMENT DATA

462.5625-462.7125MHz (2W) Test Laboratory: AGC Lab 450 Mid- face up 2.5cm (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Date: Jan. 18, 2022

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.6375 MHz; Medium parameters used: f = 450MHz;  $\sigma$ = 0.87 mho/m;  $\epsilon$ r =44.21;  $\rho$ = 1000 kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021

• Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108

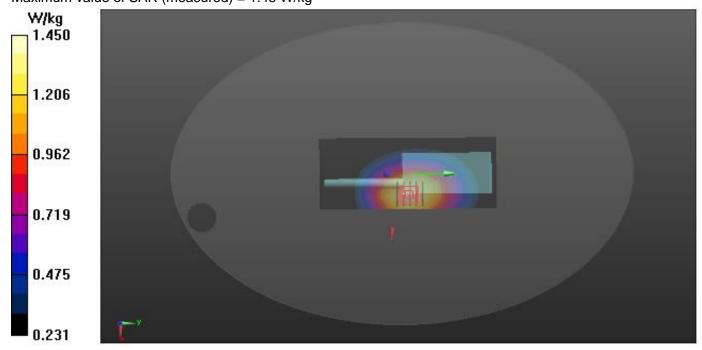
• DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

FACE UP/A-12.5K-FACE UP-4/Area Scan (7x16x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 1.43 W/kg **FACE UP/A-12.5K-FACE UP-4/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 33.345 V/m; Power Drift = -0.08 dB

Peak SAR (extrapolated) = 1.81 W/kg

SAR(1 g) = 1.3 W/kg; SAR(10 g) = 0.953 W/kg Maximum value of SAR (measured) = 1.45 W/kg





Date: Jan. 18, 2022

#### Test Laboratory: AGC Lab 450 Low -Body –Touch (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

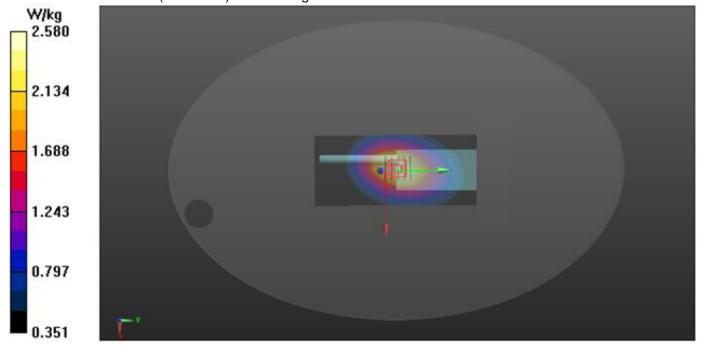
Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.5625 MHz; Medium parameters used: f = 450 MHz;  $\sigma$ = 0.87 mho/m;  $\epsilon$ r =44.21;  $\rho$ = 1000 kg/m; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

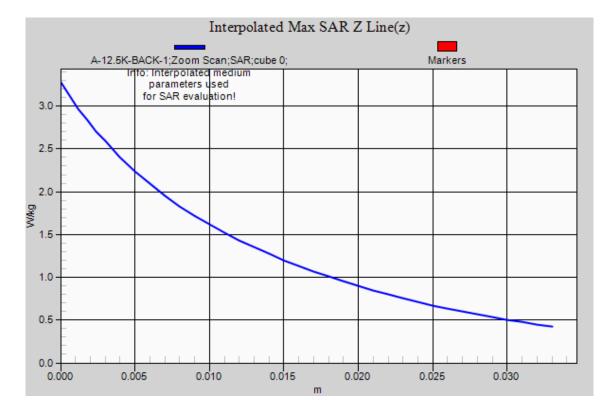
- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BODY/A-12.5K-BACK-1/Area Scan (7x15x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 2.51 W/kg BODY/A-12.5K-BACK-1/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 55.456 V/m; Power Drift = 0.10 dB Peak SAR (extrapolated) = 3.28 W/kg SAR(1 g) = 2.29 W/kg; SAR(10 g) = 1.63 W/kg Maximum value of SAR (measured) = 2.58 W/kg









## Test Laboratory: AGC Lab 450 Mid -Body –Touch (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

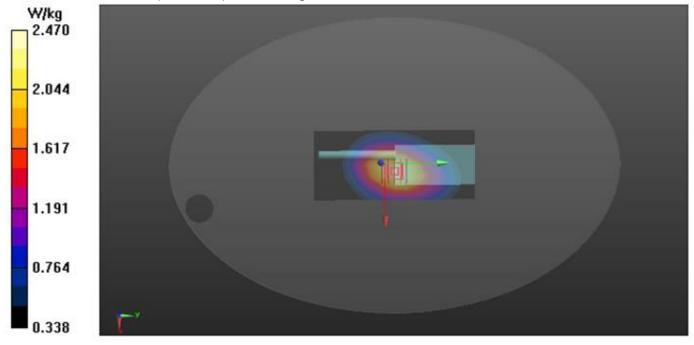
Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.6375 MHz; Medium parameters used: f = 450 MHz;  $\sigma$ = 0.87 mho/m;  $\epsilon$ r =44.21;  $\rho$ = 1000 kg/m; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BODY/A-12.5K-BACK-4/Area Scan (7x15x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 2.43 W/kg BODY/A-12.5K-BACK-4/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 54.656 V/m; Power Drift = -0.26 dB Peak SAR (extrapolated) = 3.14 W/kg SAR(1 g) = 2.19 W/kg; SAR(10 g) = 1.57 W/kg Maximum value of SAR (measured) = 2.47 W/kg





#### 467.5625-467.7125MHz (0.5W) Test Laboratory: AGC Lab 450 Mid- face up 2.5cm (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Date: Jan. 18, 2022

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 467.6375 MHz; Medium parameters used: f = 450MHz;  $\sigma$ = 0.89 mho/m;  $\epsilon$ r =43.75;  $\rho$ = 1000 kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

FACE UP/A-12.5K-FACE UP-11/Area Scan (7x16x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 0.583 W/kg

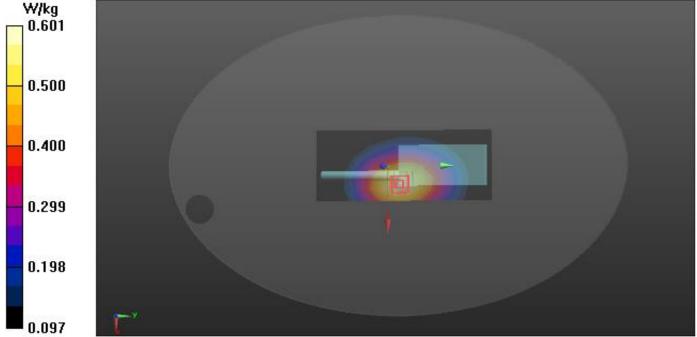
FACE UP/A-12.5K-FACE UP-11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 22.975 V/m; Power Drift = -0.02 dB

Peak SAR (extrapolated) = 0.746 W/kg

SAR(1 g) = 0.538 W/kg; SAR(10 g) = 0.396 W/kg

Maximum value of SAR (measured) = 0.601 W/kg





## Test Laboratory: AGC Lab 450 Mid -Body –Touch (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

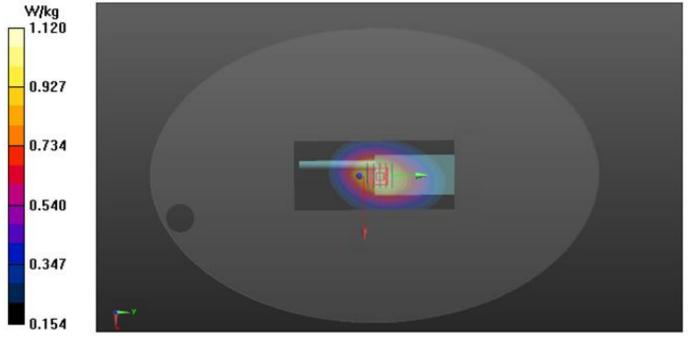
Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 467.6375MHz; Medium parameters used: f = 450 MHz;  $\sigma$ = 0.89 mho/m;  $\epsilon$ r =43.75;  $\rho$ = 1000 kg/m; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

```
BODY/A-12.5K-BACK-11/Area Scan (7x15x1): Measurement grid: dx=15mm, dy=15mm
```

Maximum value of SAR (measured) = 1.09 W/kg BODY/A-12.5K-BACK-11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 36.756 V/m; Power Drift = -0.02 dB Peak SAR (extrapolated) = 1.41 W/kg SAR(1 g) = 0.983 W/kg; SAR(10 g) = 0.703 W/kg Maximum value of SAR (measured) = 1.12 W/kg





462.5500-462.7250MHz (2W) Test Laboratory: AGC Lab 450 Mid- face up 2.5cm (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Date: Jan. 18, 2022

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.6500 MHz; Medium parameters used: f = 450MHz;  $\sigma$ = 0.87 mho/m;  $\epsilon$ r =44.21;  $\rho$ = 1000 kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

• Probe: ES3DV3 - SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;

- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

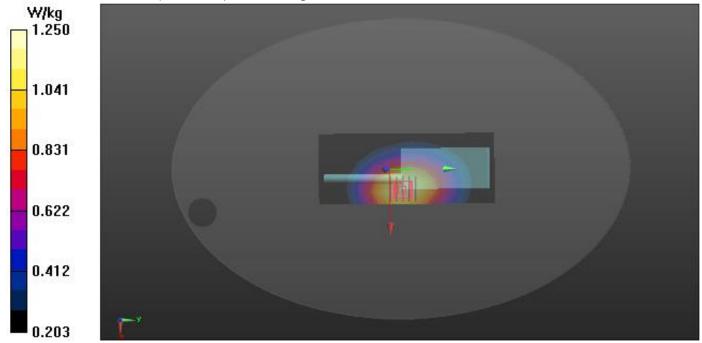
FACE UP/A-12.5K-FACE UP-19/Area Scan (7x16x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 1.26 W/kg

FACE UP/A-12.5K-FACE UP-19/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 32.415 V/m; Power Drift = -0.22 dB Peak SAR (extrapolated) = 1.55 W/kg SAR(1 g) = 1.12 W/kg; SAR(10 g) = 0.822 W/kg

Maximum value of SAR (measured) = 1.25 W/kg





## Test Laboratory: AGC Lab 450 Mid -Body –Touch (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

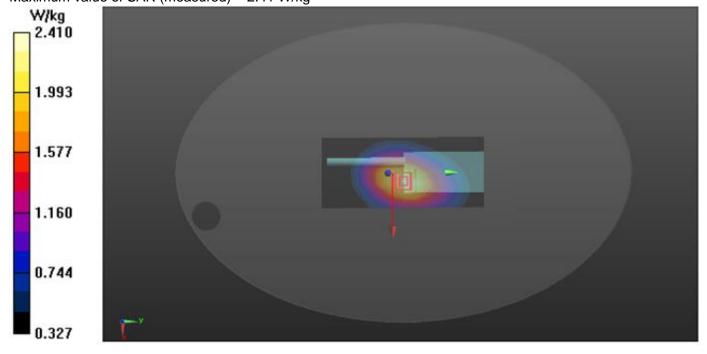
Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.6500 MHz; Medium parameters used: f = 450 MHz;  $\sigma$ = 0.87 mho/m;  $\epsilon$ r =44.21;  $\rho$ = 1000 kg/m; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

```
BODY/A-12.5K-BACK-19/Area Scan (7x15x1): Measurement grid: dx=15mm, dy=15mm
```

Maximum value of SAR (measured) = 2.40 W/kg BODY/A-12.5K-BACK-19/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 52.250 V/m; Power Drift = -0.27 dB Peak SAR (extrapolated) = 3.06 W/kg SAR(1 g) = 2.12 W/kg; SAR(10 g) = 1.51 W/kg Maximum value of SAR (measured) = 2.41 W/kg





#### 467.5500-467.7250MHz (2W) Test Laboratory: AGC Lab 450 Mid- face up 2.5cm (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Date: Jan. 18, 2022

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 467.6500MHz; Medium parameters used: f = 450MHz;  $\sigma$ = 0.89 mho/m;  $\epsilon$ r =43.75;  $\rho$ = 1000 kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

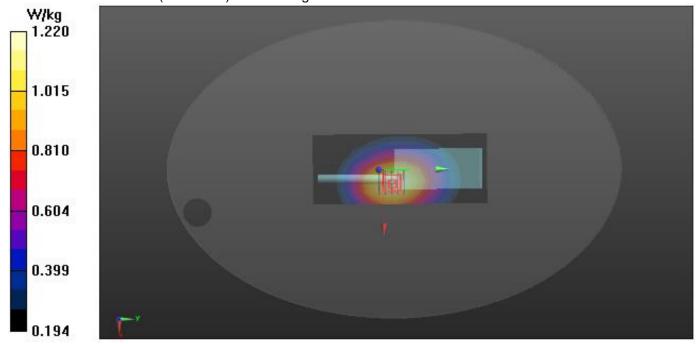
FACE UP/A-12.5K-FACE UP-27/Area Scan (7x16x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 1.22 W/kg

FACE UP/A-12.5K-FACE UP-27/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 35.363 V/m; Power Drift = -0.16 dB Peak SAR (extrapolated) = 1.52 W/kg SAR(1 g) = 1.09 W/kg; SAR(10 g) = 0.804 W/kg

Maximum value of SAR (measured) = 1.22 W/kg





## Test Laboratory: AGC Lab 450 Mid -Body –Touch (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

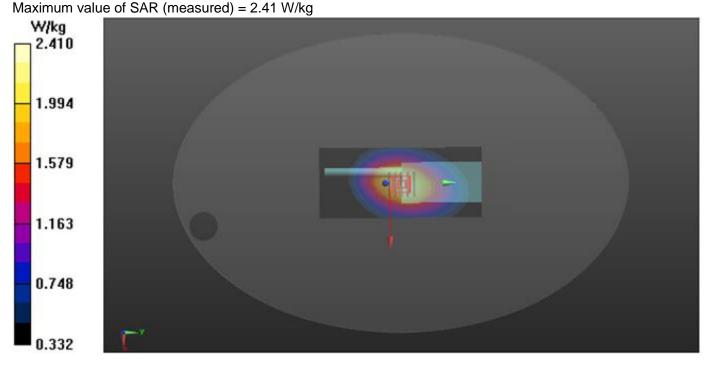
Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 467.6500 MHz; Medium parameters used: f = 450 MHz;  $\sigma$ = 0.89 mho/m;  $\epsilon$ r =43.75;  $\rho$ = 1000 kg/m; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

```
BODY/A-12.5K-BACK-27/Area Scan (7x15x1): Measurement grid: dx=15mm, dy=15mm
```

Maximum value of SAR (measured) = 2.44 W/kg BODY/A-12.5K-BACK-27/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 55.042 V/m; Power Drift = -0.19 dB Peak SAR (extrapolated) = 3.05 W/kg SAR(1 g) = 2.14 W/kg; SAR(10 g) = 1.53 W/kg





#### 462.5625-462.7125MHz (2W) Test Laboratory: AGC Lab 450 Mid- face up 2.5cm (25 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Date: Jan. 18, 2022

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.6375 MHz; Medium parameters used: f = 450MHz;  $\sigma$ = 0.87 mho/m;  $\epsilon$ r =44.21;  $\rho$ = 1000 kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

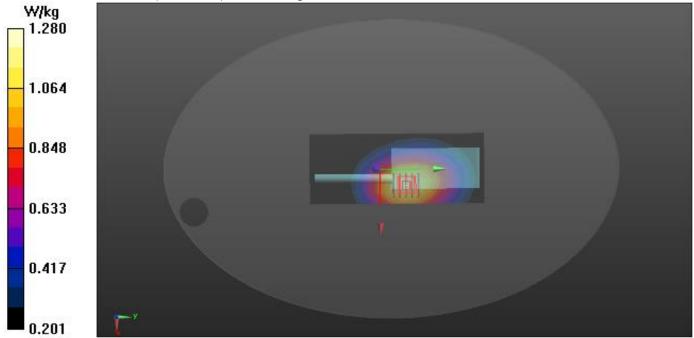
- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**FACE UP/A-25K-FACE UP-4/Area Scan (7x16x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 1.23 W/kg

**FACE UP/A-25K-FACE UP-4/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 32.313 V/m; Power Drift = -0.09 dB

Peak SAR (extrapolated) = 1.60 W/kg SAR(1 g) = 1.15 W/kg; SAR(10 g) = 0.844 W/kg

Maximum value of SAR (measured) = 1.28 W/kg





## Test Laboratory: AGC Lab 450 Low -Body –Touch (25 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.5625 MHz; Medium parameters used: f = 450 MHz;  $\sigma = 0.87$  mho/m;  $\epsilon r = 44.21$ ;  $\rho = 1000$  kg/m; Phantom Type: Elliptical Phantom

Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

**DASY Configuration:** 

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

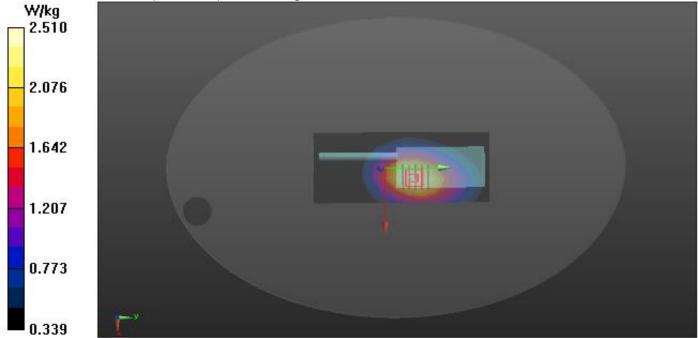
**BODY/A-25K-BACK-1/Area Scan (7x16x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 2.54 W/kg

BODY/A-25K-BACK-1/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 49.265 V/m; Power Drift = -0.32 dB Peak SAR (extrapolated) = 3.18 W/kg

SAR(1 g) = 2.22 W/kg; SAR(10 g) = 1.58 W/kg

Maximum value of SAR (measured) = 2.51 W/kg





# Test Laboratory: AGC Lab 450 High -Body –Touch (25 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.7125 MHz; Medium parameters used: f = 450 MHz;  $\sigma = 0.87$  mho/m;  $\epsilon r = 44.21$ ;  $\rho = 1000$  kg/m; Phantom Type: Elliptical Phantom

Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

**DASY Configuration:** 

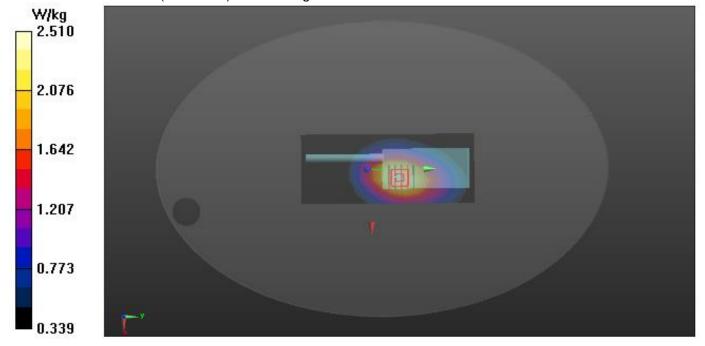
- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**BODY/A-25K-BACK-7/Area Scan (7x16x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 2.49 W/kg

BODY/A-25K-BACK-7/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 49.599 V/m; Power Drift = -0.16 dB Peak SAR (extrapolated) = 3.18 W/kg SAR(1 g) = 2.23 W/kg; SAR(10 g) = 1.59 W/kg

Maximum value of SAR (measured) = 2.51 W/kg





#### 462.5500-462.7250MHz (2W) Test Laboratory: AGC Lab 450 Mid- face up 2.5cm (25 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Date: Jan. 18, 2022

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.6500 MHz; Medium parameters used: f = 450MHz;  $\sigma$ = 0.87 mho/m;  $\epsilon$ r =44.21;  $\rho$ = 1000 kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

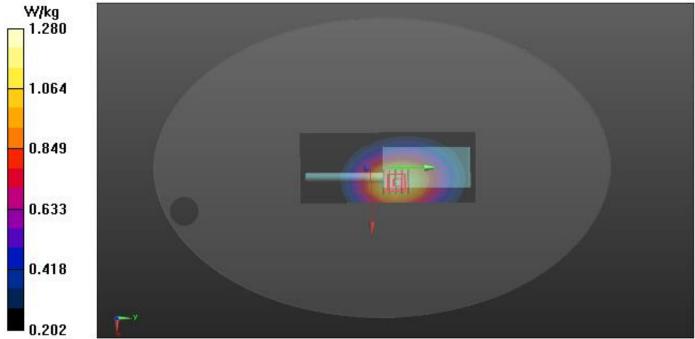
- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**FACE UP/A-25K-FACE UP-19/Area Scan (7x16x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 1.26 W/kg

FACE UP/A-25K-FACE UP-19/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 33.532 V/m; Power Drift = -0.10 dB

Peak SAR (extrapolated) = 1.59 W/kg SAR(1 g) = 1.14 W/kg; SAR(10 g) = 0.837 W/kg

Maximum value of SAR (measured) = 1.28 W/kg





## Test Laboratory: AGC Lab 450 Low -Body –Touch (25 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.5500 MHz; Medium parameters used: f = 450 MHz;  $\sigma$ = 0.87 mho/m;  $\epsilon$ r =44.21;  $\rho$ = 1000 kg/m; Phantom Type: Elliptical Phantom

Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

**DASY Configuration:** 

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

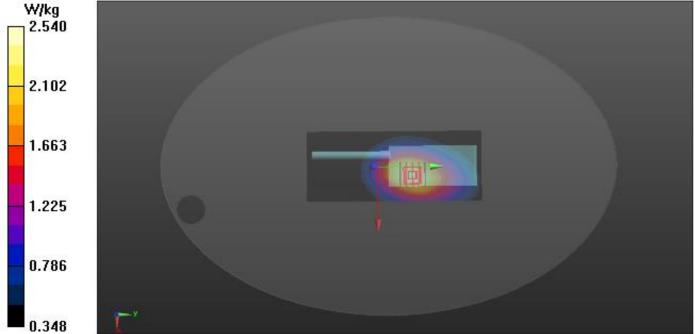
**BODY/A-25K-BACK-15/Area Scan (7x16x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 2.50 W/kg

BODY/A-25K-BACK-15/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 46.319 V/m; Power Drift = -0.03 dB Peak SAR (extrapolated) = 3.22 W/kg

SAR(1 g) = 2.25 W/kg; SAR(10 g) = 1.61 W/kg

Maximum value of SAR (measured) = 2.54 W/kg





#### 467.5500-467.7250MHz (2W) Test Laboratory: AGC Lab 450 Mid- face up 2.5cm (25 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Date: Jan. 18, 2022

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 467.6500 MHz; Medium parameters used: f = 450MHz;  $\sigma$ = 0.89 mho/m;  $\epsilon$ r =43.75;  $\rho$ = 1000 kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

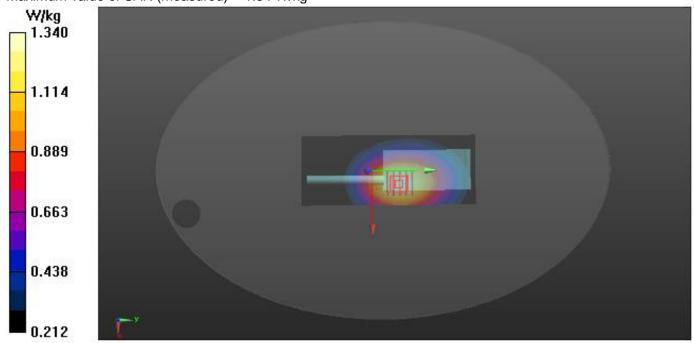
- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**FACE UP/A-25K-FACE UP-27/Area Scan (7x16x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 1.36 W/kg

FACE UP/A-25K-FACE UP-27/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 35.143 V/m; Power Drift = -0.27 dB

Peak SAR (extrapolated) = 1.67 W/kg SAR(1 g) = 1.2 W/kg; SAR(10 g) = 0.877 W/kg

Maximum value of SAR (measured) = 1.34 W/kg





# Test Laboratory: AGC Lab 450 High -Body –Touch (25 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 467.7250 MHz; Medium parameters used: f = 450 MHz;  $\sigma$ = 0.89 mho/m;  $\epsilon$ r =43.75;  $\rho$ = 1000 kg/m; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

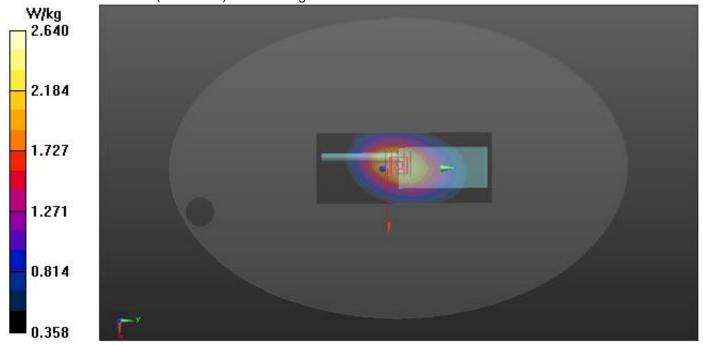
- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**BODY/A-25K-BACK-30/Area Scan (7x16x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 2.59 W/kg

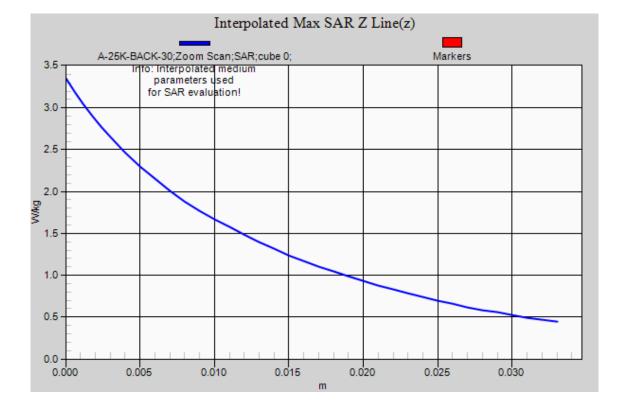
BODY/A-25K-BACK-30/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 56.443 V/m; Power Drift = 0.08 dB Peak SAR (extrapolated) = 3.35 W/kg SAR(1 g) = 2.35 W/kg; SAR(10 g) = 1.68 W/kg

Maximum value of SAR (measured) = 2.64 W/kg









#### Repeated SAR Test Laboratory: AGC Lab 450 Low -Body –Touch (12.5 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Date: Jan. 18, 2022

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 462.5625 MHz; Medium parameters used: f = 450 MHz;  $\sigma$ = 0.89 mho/m;  $\epsilon$ r =43.75;  $\rho$ = 1000 kg/m; Phantom Type: Elliptical Phantom Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BODY/A-12.5K-BACK-1-Repeat/Area Scan (7x15x1): Measurement grid: dx=15mm, dy=15mm

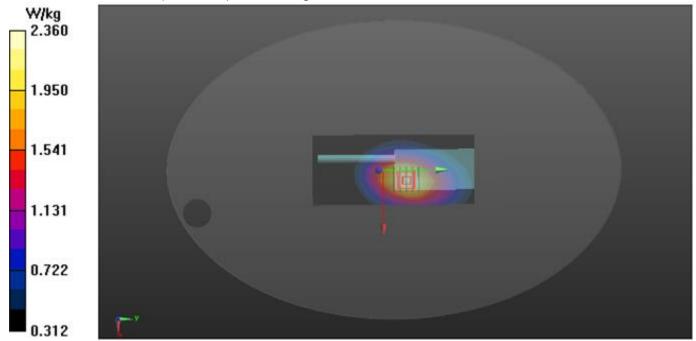
Maximum value of SAR (measured) = 2.31 W/kg

BODY/A-12.5K-BACK-1-Repeat/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 48.168 V/m; Power Drift = -0.05 dB Peak SAR (extrapolated) = 3.01 W/kg

SAR(1 g) = 2.08 W/kg; SAR(10 g) = 1.48 W/kg

Maximum value of SAR (measured) = 2.36 W/kg





# Test Laboratory: AGC Lab 450 High -Body –Touch (25 KHz) DUT: GMRS TRANSCEIVER; Type: GMR2

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency: 467.7250 MHz; Medium parameters used: f = 450 MHz;  $\sigma$ = 0.89 mho/m;  $\epsilon$ r =43.75;  $\rho$ = 1000 kg/m; Phantom Type: Elliptical Phantom

Ambient temperature (°C): 20.6, Liquid temperature (°C): 20.4

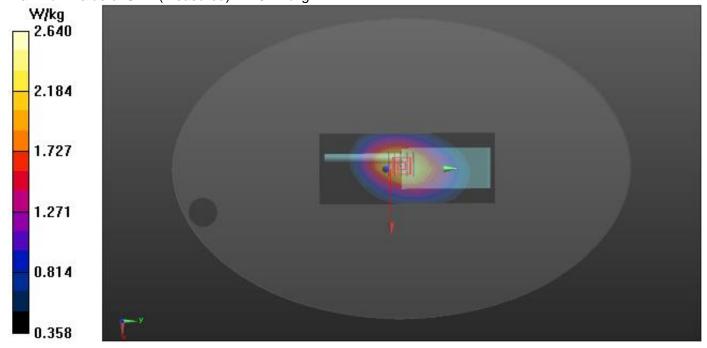
## DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(7.15, 7.15, 7.15); Calibrated: Aug. 24, 2021;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: May 17,2021
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**BODY/A-25K-BACK-30-REPEATED/Area Scan (7x16x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 2.47 W/kg

BODY/A-25K-BACK-30-REPEATED/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 56.438 V/m; Power Drift = 0.07 dB Peak SAR (extrapolated) = 3.33 W/kg SAR(1 g) = 2.34 W/kg; SAR(10 g) = 1.67 W/kg Maximum value of SAR (measured) = 2.64 W/kg

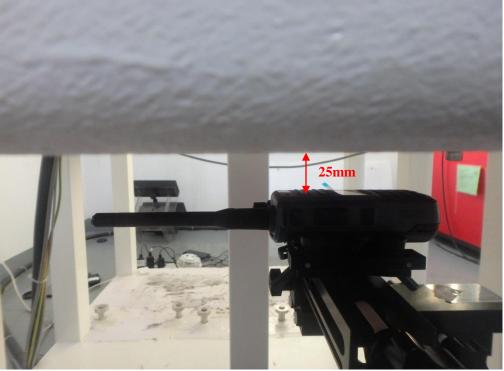




Report No.: AGC02931211203FH01 Page 54 of 57

# **APPENDIX C. TEST SETUP PHOTOGRAPHS**

Face Up with 2.5 cm Separation Distance.



Body Back Touch with all accessories



The thickness of EUT is3.3 cm

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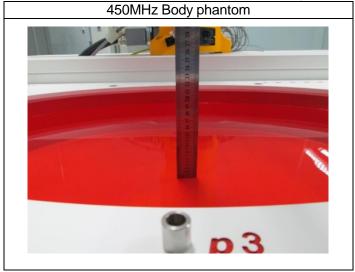


Note : The headset is just for testing. This tested and electrically similar headsets may be used.



# DEPTH OF THE LIQUID IN THE PHANTOM-ZOOM IN

Note: The position used in the measurement were according to IEEE 1528-2013





Report No.: AGC02931211203FH01 Page 57 of 57

# APPENDIX D. CALIBRATION DATA

Refer to Attached files.

----END OF REPORT----



# Conditions of Issuance of Test Reports

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3. The Company shall not be called or be liable to be called to give evidence or testimony on the Report in a court of law without its prior written consent, unless required by the relevant governmental authorities, laws or court orders.

4. In the event of the improper use of the report as determined by the Company, the Company reserves the right to withdraw it, and to adopt any other additional remedies which may be appropriate.

5. Samples submitted for testing are accepted on the understanding that the Report issued cannot form the basis of, or be the instrument for, any legal action against the Company.

6. The Company will not be liable for or accept responsibility for any loss or damage however arising from the use of information contained in any of its Reports or in any communication whatsoever about its said tests or investigations.

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8. The Company is not responsible for recalling the electronic version of the original report when any revision is made to them. The Client assumes the responsibility to providing the revised version to any interested party who uses them.

9. Subject to the variable length of retention time for test data and report stored hereinto as otherwise specifically required by individual accreditation authorities, the Company will only keep the supporting test data and information of the test report for a period of six years. The data and information will be disposed of after the aforementioned retention period has elapsed. Under no circumstances shall we provide any data and information which has been disposed of after retention period. Under no circumstances shall we be liable for damage of any kind, including (but not limited to) compensatory damages, lost profits, lost data, or any form of special, incidental, indirect, consequential or punitive damages of any kind, whether based on breach of contract of warranty, tort (including negligence), product liability or otherwise, even if we are informed in advance of the possibility of such damages.