 <small>A Phoenix Mecano Company</small>	Issue Department: Bedding Division	Date:	2021-06-28
	<b>System Instruction</b>	Author:	
<b>Instruction of RF5019</b>		Edition:	1.1
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### Instruction of RF5019

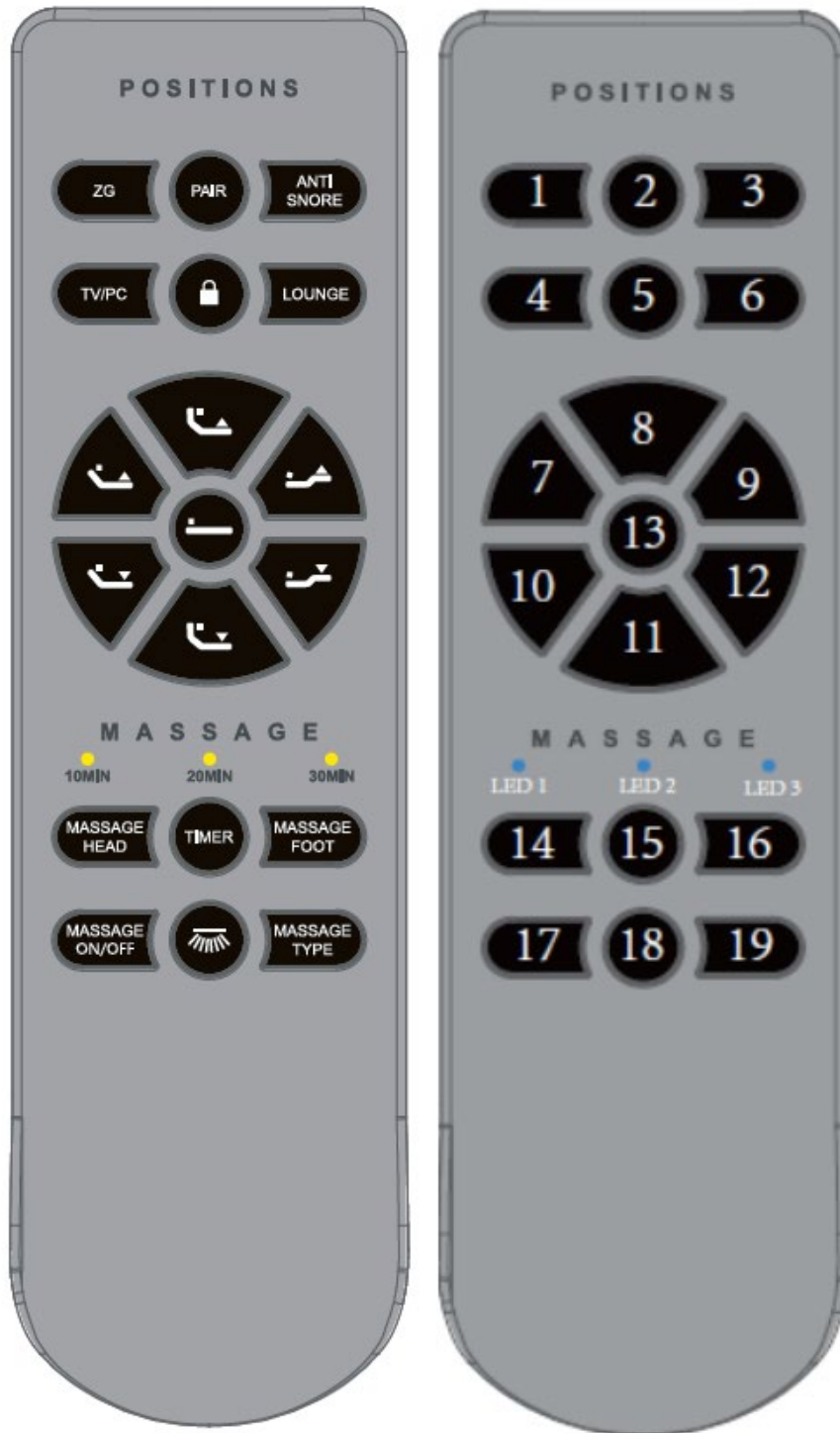



Figure 1 button of remote

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## 1 Item

### 1.1 ZG button (button 1 in figure 1)

Click the ZG button, the actuator moves to ZG position, stop when click any button during the movement;

Press and hold the ZG button for 5s, timer LED of remote flashes, the control box records current position as ZG position;

When in the process of moving to memory positions, the head and foot actuators move first, then the tilt and lumbar actuators move;

### 1.2 AntiSnore button (button 3 in figure 1)

Click AntiSnore button, actuators move to AntiSnore position, stop when click any button during movement;

Press and hold AntiSnore button for 5s, timer LED of remote flashes, the control box records current position as AntiSnore position;

When in the process of moving to memory positions, the head and foot actuators move first, then the tilt and lumbar actuators move;

### 1.3 TV/PC button (button 4 in figure 1)

Click TV/PC button, actuators move to TV/PC position, stop when click any button during movement;


Press and hold TV/PC button for 5s, timer LED of remote flashes, the control box records current position as TV/PC position;

When in the process of moving to memory positions, the head and foot actuators move first, then the tilt and lumbar actuators move;

### 1.4 LOUNGE button (button 6 in figure 1)

Click LOUNGE button, actuators move to LOUNGE position, stop when click any button during movement;

Press and hold LOUNGE button for 5s, timer LED of remote flashes, the control box records

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current position as LOUNGE position;

When in the process of moving to memory positions, the head and foot actuators move first, then the tilt and lumbar actuators move;

### **1.5 Reset all memory positions to default settings (button 1 and 11 in figure 1)**

Pressa and hold ZG+FLAT buttons (button 1 and 16 in figure 2) for 5s, timer LED of remote flashes, the control box reset all memory positions to default settings;

### **1.6 Head up (button 7 in figure 1)**

Press and hold HEAD UP button of remote, head actuator moves out, stop when released;

### **1.7 Head down (button 9 in figure 1)**

Press and hold HEAD DOWN button of remote, head actuator moves in, stop when released;

### **1.8 Foot up (button 8 in figure 1)**


Pressa and hold FOOT UP button of remote, foot actuator moves out, stop when released;

### **1.9 foot down (button 10 in figure 1)**

Press and hold FOOT DOWN button of remote, foot actuator moves in , stop when released;  
When moving to flat position, lumbar actuator and tilt actuator move first, after 500ms, head and foot actuators start moving;

### **1.10 Flat (button 11 in figure 1)**

Click FLAT button, the bed goes flat, stop when click any button during the process of going flat;

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### 1.11 Message head (button 12 in figure 1)

Click MESSAGE HEAD button, head message motor switches message intensity, message intensity switches among 0-1-2-3;

### 1.12 Message timer (button 13 in figure 1)

If the message motors do not work, the button is invalid, if the message motors work, click the button to switch the message time, when message time switch to 0, turn off the message;

### 1.13 Message ON/OFF (button 15 in figure 1)


Click Message ON/OFF button, if the message motors are on, then it turns off message motors, if message motors are off, then it turns on the message motors;

### 1.14 Under bed light (button 16 in figure 1)

Click the under bed light button, the under bed light switch its on/off state; After the under bed light opens, if do not manually close, it will automatically turn off after 5 minutes;

### 1.15 Message Type (button 17 in figure 1)

Click message type button, to switch the message mode of message motors, message mode switches among type0→type1→type2→type3→type0; this button can only switch the message mode, it can not open message motors;

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**FCC Warning:**

Please take attention that changes or modification not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

**ISED RSS Warning:**

This device complies with Industry Canada licence-exempt RSS standard(s). Operation is subject to the following two conditions:

- (1) this device may not cause interference, and
- (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radioexempts de licence. L'exploitation est autorisée aux deux conditions suivantes :

- (1) l'appareil ne doit pas produire de brouillage, et
- (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.