

# **SAR Test Report**

## Report No.: AGC09128190902FH01

FCC ID	ċ	2AUMTWT-F21
PRODUCT DESIGNATION	:	Two way radio
BRAND NAME	:	Wanneton, Airiton, GUUGEI
MODEL NAME		WT-F21, GF-21, WT-F12, WT-F14, WT-F24, WT-F25, WT-F33, WT-F38, AI-1, AI-2
APPLICANT	è	Quanzhou Wanneton Electronic&Technology Co.,Ltd
DATE OF ISSUE	:	Nov. 20,2019
STANDARD(S)	Ç	IEEE Std. 1528:2013 FCC 47 CFR Part 2§2.1093:2013 IEEE C95.1TM:2005
REPORT VERSION	:	V1.1

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Report No.: AGC09128190902FH01 Page 2 of 44

## **Report Revise Record**

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0		Oct. 30,2019	Invalid	Initial Release
V1.1	1 <sup>st</sup>	Nov. 20,2019	Valid	Add system verification on page 19 and explain the difference among the battery models on page 3.





	Test Report
Applicant Name	Quanzhou Wanneton Electronic&Technology Co.,Ltd
Applicant Address	Baijie International Centre, Qiaonan District, Chidian Town, Quanzhou, China
Manufacturer Name	Quanzhou Wanneton Electronic&Technology Co.,Ltd
Manufacturer Address	Baijie International Centre, Qiaonan District, Chidian Town, Quanzhou, China
Factory Name	Quanzhou Wanneton Electronic&Technology Co.,Ltd
Factory Address	Baijie International Centre, Qiaonan District, Chidian Town, Quanzhou, China
Product Designation	Two way radio
Brand Name	Wanneton, Airiton, GUUGEI
Model Name	WT-F21, GF-21, WT-F12, WT-F14, WT-F24, WT-F25, WT-F33, WT-F38, AI-1, AI-2
Different Description	<ul> <li>a) The only differences are the model and brand, the plastic shell of the body speaker has different lines, the corresponding relationship are as follow:</li> <li>b) Airiton is corresponding Al-1, Al-2; Wanneton is corresponding WT-F21, WT-F11, WT-F12, WT-F14, WT-F24, WT-F25, WT-F33, WT-F38;</li> <li>c) GUUGEI is corresponding GF-21.</li> <li>d) WT-F12, WT-F14, Al-1 use battery PB-F1; GF-21,WT-F21, WT-F24, WT-F25, Al-2 use battery PB-F2; WT-F33, WT-F38 use battery PB-F3; (PB-F1, PB-F2 and PB-F3 are just different in plastic casing design, and the internal electrical parts are exactly the same.</li> </ul>
EUT Voltage	DC3.7 V
Applicable Standard	IEEE Std. 1528:2013 FCC 47 CFR Part 2§2.1093:2013 IEEE C95.1TM:2005
Test Date	Sep. 18,2019
Report Template	AGCRT- US -PTT/SAR (2018-02-02)

Note: The results of testing in this report apply to the product/system which was tested only.

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## TABLE OF CONTENTS

1. SUMMARY OF MAXIMUM SAR VALUE	
2. GENERAL INFORMATION	6
2.1. EUT DESCRIPTION	6
3. SAR MEASUREMENT SYSTEM	
3.1. THE DASY5 SYSTEM USED FOR PERFORMING COMPLIANCE TESTS CONSISTS OF FOLLOWING ITEMS 3.2. DASY5 E-FIELD PROBE	8
3.3. DATA ACQUISITION ELECTRONICS DESCRIPTION	
3.5. LIGHT BEAM UNIT	9
3.6. Device Holder	
3.8. PHANTOM	
4. SAR MEASUREMENT PROCEDURE	12
4.1. SPECIFIC ABSORPTION RATE (SAR)	
5. TISSUE SIMULATING LIQUID	
5.1. THE COMPOSITION OF THE TISSUE SIMULATING LIQUID	15
5.2. TISSUE DIELECTRIC PARAMETERS FOR HEAD AND BODY PHANTOMS	
6. SAR SYSTEM CHECK PROCEDURE	
6.1. SAR SYSTEM CHECK PROCEDURES	
7. EUT TEST POSITION	
7. EUT TEST POSITION	
8. SAR EXPOSURE LIMITS	
9. TEST FACILITY	
10. TEST EQUIPMENT LIST	
11. MEASUREMENT UNCERTAINTY	
12. POWER MEASUREMENT	
13. TEST RESULTS	
13.1. SAR TEST RESULTS SUMMARY	
APPENDIX A. SAR SYSTEM CHECK DATA	
APPENDIX B. SAR MEASUREMENT DATA	
APPENDIX C. TEST SETUP PHOTOGRAPHS	
APPENDIX D. CALIBRATION DATA	44





## **1. SUMMARY OF MAXIMUM SAR VALUE**

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Highest Report standalone SAR Summary (50% duty cycle)

Frequency Pand	Separation	Highest Reported 1g-SAR(W/Kg)		
Frequency Band	Separation	Face Up (with 25mm separation)	Back Touch	
462.5500-462.7250MHz(2W)	12.5KHz	0.729	1.410	

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure environment limits(1.6W/Kg) specified in 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1, and had been tested in accordance with measurement methods and procedures specified in IEEE 1528-2013 and the following specific FCC Test Procedures:

KDB447498 D01 General RF Exposure Guidance v06 KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04 KDB 643646 D01 SAR Test for PTT Radios v01r03





## 2. GENERAL INFORMATION

## 2.1. EUT Description

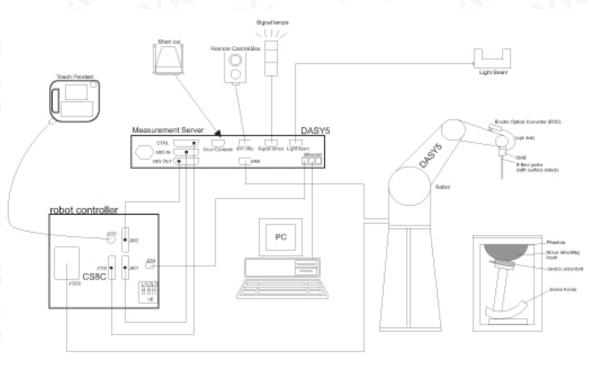
General Information	
Product Name	Two way radio
Test Model	WT-F21
Hardware Version	WLT-F2-01V02
Software Version	v1
Exposure Category:	General Population/Uncontrolled Environments
Modulation Type	FM
TX Frequency Range	462.5500MHz-462.7250MHz(2W)
Rated Power	2W (It was fixed by the manufacturer, any individual can't arbitrarily change it)
Max. Output Power	32.75dBm
Channel Spacing	12.5 KHz
Antenna Type	Inseparable
Antenna Gain	1.5dBi
Body-Worn Accessories:	Belt Clip with headset
Face-Head Accessories:	None
Battery Type (s) Tested:	DC3.7V, 1000mAh (by battery)
Note: The sample used for the	esting is end product.
Product	Type         Image: Second state of the second st





## **3. SAR MEASUREMENT SYSTEM**

## 3.1. The DASY5 system used for performing compliance tests consists of following items



- A standard high precision 6-axis robot with controller, teach pendant and software.
- Data acquisition electronics (DAE) which attached to the robot arm extension. The DAE consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock
- A dosimetric probe equipped with an optical surface detector system.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital Communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- A Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- Phantoms, device holders and other accessories according to the targeted measurement.





#### 3.2. DASY5 E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SPEAG. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN62209,IEC 62209, etc.)Under ISO17025.The calibration data are in Appendix D.

Model	ES3DV3			
Manufacture	SPEAG	6		
frequency	0.15GHz-0.45 GHz Linearity:±0.6%dB(K=2)(0.15MHz-0.45 GHz)			
Dynamic Range	0.01W/Kg-100W/Kg Linearity:±0.6%dB(K=2)			
Dimensions	Overall length:337mm Tip diameter:4mm Typical distance from probe tip to dipole centers:2mm			
Application	High precision dosimetric measurements in any (e.g., very strong gradient fields). Only probe w compliance testing for frequencies up to 3 GHz 30%.	hich enables	tter	Yee

#### Isotropic E-Field Probe Specification

### 3.3. Data Acquisition Electronics description

The data acquisition electronics (DAE) consist if a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converte and a command decoder with a control logic unit. Transmission to the measurement sever is accomplished through an optical downlink fir data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

Input Impedance	200MOhm	THEFT	CONTRACT OF
The Inputs	Symmetrical and floating	Contraction of the second seco	EAL Bad 2 C
Common mode rejection	above 80 dB	E	





#### 3.4. Robot

The DASY system uses the high precision robots (DASY5:TX60) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from is used.

The XL robot series have many features that are important for our application:

- □ High precision (repeatability 0.02 mm)
- □ High reliability (industrial design)
- □ Jerk-free straight movements
- □ Low ELF interference (the closed metallic construction shields against motor control fields)
- □ 6-axis controller



#### 3.5. Light Beam Unit

The light beam switch allows automatic "tooling" of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned prob.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position. e, the same position will be reached with another aligned probe within 0







#### 3.6. Device Holder

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles. The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon$ =3 and loss tangent  $\delta$  = 0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



#### 3.7. Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chip-disk (DASY5: 128MB), RAM (DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DAYS I/O board, which is directly connected to the PC/104 bus of the CPU board. The measurement server performs all the real-time data

evaluation for field measurements and surface detection, controls robot movements and handles safety operations.







#### 3.8. PHANTOM SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

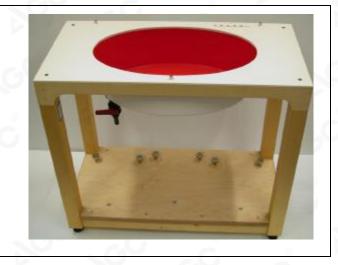
- Left head
- Right head
- □ Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

#### ELI4 Phantom

□ Flat phantom a fiberglass shell flat phantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom







## 4. SAR MEASUREMENT PROCEDURE

#### 4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of given mass density ( $\rho$ ). The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg) SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \frac{dT}{dt}_{t=0}$$

Where

SA E	R	
	σ	
	ρ	
	0	

is the specific absorption rate in watts per kilogram; is the r.m.s. value of the electric field strength in the tissue in volts per meter; is the conductivity of the tissue in siemens per metre; is the density of the tissue in kilograms per cubic metre; is the heat capacity of the tissue in joules per kilogram and Kelvin;

 $\frac{dT}{dt}$  | t = 0 is the initial time derivative of temperature in the tissue in kelvins per second





#### 4.2. SAR Measurement Procedure

#### Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance os sensor calibration points to probe tip as `defined in the probe properties,

#### Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in SATIMO software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528 and IEC62209 standards, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	$\leq$ 3 GHz	> 3 GHz	
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	$5 \pm 1 \text{ mm}$	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$	
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30°±1°	$20^{\circ} \pm 1^{\circ}$	
	$\leq$ 2 GHz: $\leq$ 15 mm 2 - 3 GHz: $\leq$ 12 mm	$\begin{array}{l} 3-4 \hspace{0.1 cm} \text{GHz:} \leq 12 \hspace{0.1 cm} \text{mm} \\ 4-6 \hspace{0.1 cm} \text{GHz:} \leq 10 \hspace{0.1 cm} \text{mm} \end{array}$	
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.		

#### Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g abd 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.



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	Maximum zoom scan spatial resolution: $\Delta x_{\text{Zoom}}, \Delta y_{\text{Zoom}}$			$\leq 2 \text{ GHz}: \leq 8 \text{ mm}$ 2 - 3 GHz: $\leq 5 \text{ mm}^*$	$3 - 4 \text{ GHz} \le 5 \text{ mm}^*$ $4 - 6 \text{ GHz} \le 4 \text{ mm}^*$
	uniform		grid: ∆z <sub>Zoom</sub> (n)	$\leq$ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
- N	Maximum zoom scan spatial resolution, normal to phantom surface	ution,	$\Delta z_{Zoom}(1)$ : between 1 <sup>st</sup> two points closest to phantom surface	$\leq$ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
		grid	grid Δz <sub>Zoom</sub> (n>1): between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$	
	Minimum zoom scan volume	x, y, z		$\geq$ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm
	Note: δ is the penetration	on depth o	f a plane-wave at norma	l incidence to the tissue mediu	m; see draft standard IEEE

Zoom Scan Parameters extracted from KDB865664 D01 SAR Measurement 100MHz to 6GHz

P1528-2011 for details.

When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is  $\leq 1.4$  W/kg,  $\leq 8$  mm,  $\leq 7$  mm and  $\leq 5$  mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

#### Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.





## **5. TISSUE SIMULATING LIQUID**

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 5.3

### 5.1. The composition of the tissue simulating liquid

Ingredient (% Weight) Frequency (MHz)	Water	Nacl	Sugar	HEC	Bactericide	DGBE	1,2- Propanediol	Triton X-100
450 Head (100%)	38.56	3.95	56.32	0.98	0.19	0.0	0.0	0.0
450 Body (100%)	51.16	1.49	46.78	0.52	0.05	0.0	0.0	0.0

#### 5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in IEEE 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in IEEE 1528.

Target Frequency	h	ead	b	ody
(MHz)	٤r	σ (S/m)	٤٢	σ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800 – 2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	51.6	2.73

( $\epsilon r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho$  = 1000 kg/m3)



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#### 5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using DASY5 Dielectric Probe Kit and R&S Network Analyzer ZVL6.

	Tissue Stimula	nt Measurement for 450MHz		
-0-	Dielectric Pa	rameters (±5%)		0
Fr.	Fr. (MHz)         Dielectric Par           450         εr43.50(41.325 - 45.675)           462         42.47           Fr.         Dielectric Par	lead	Tissue Temp	Test time
(MHZ)	εr43.50(41.325 - 45.675)	δ[s/m]0.87(0.8265 - 0.9135)	[°C]	NOU.
450	42.47	0.86	21.2	Sop 19 2010
462	42.12	0.89	21.3	Sep. 18,2019
	Dielectric Pa	rameters (±5%)	Tissue	
	Fr. (MHz)         Dielectric Para           450         εr43.50(41.325 - 45.675)           450         42.47           462         42.12           Fr. (MHz)         Dielectric Para           Fr. (MHz)         Er56.7(53.865 to 59.535)           450         54.87	Body	Temp	Test time
(101112)	εr56.7(53.865 to 59.535)	δ[s/m] 0.94(0.893 to 0.987)	[°C]	0
450	54.87	0.92	21.4	Son 19 2010
462	54.13	0.93	21.4	Sep. 18,2019





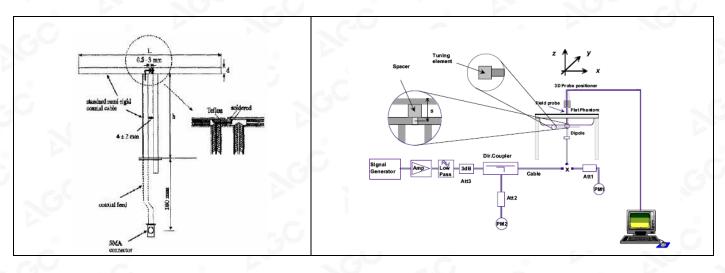
## 6. SAR SYSTEM CHECK PROCEDURE

#### 6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each DASY system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.

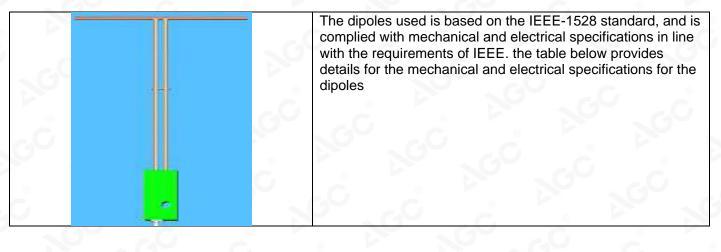






# 6.2. SAR System Check 6.2.1. Dipoles

6.2.1. Dipoles



Frequency	R/L (mm)	R/h (mm)	d (mm)
450MHz	290	166.7	6.35

## 6.2.2. System Check Result

System Perf	ormance	Check at	450MHz					
Validation K	it: SN 46/	'11DIP 0G	450-184					
Frequency [MHz]		rget (W/Kg)	Reference (± 1	Normalized to 1W(W/Kg)		Tissue Temp.	Test time	
	1g	10g	1g	10g	1g	10g	[°C]	
450 head	4.74	3.12	4.266-5.214	2.808-3.432	4.60	3.19	21.3	Sep. 18,2019
450 body	4.78	3.19	4.302-5.258	2.871-3.509	4.88	3.42	21.4	Sep. 18,2019

Note:

(1) We use a CW signal of 18dBm(450MHz)for system check, and then all SAR value are normalized to 1W forward power. The result must be within ±10% of target value.





Report No.: AGC09128190902FH01 Page 19 of 44

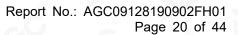
## 6.2.3. System Validation

						CV	V validatior	า	Mo	od. valida	ition
Test Data	Probe S/N	Tested Freq. (MHz)	Tissue Type	Cond.	Perm	Sensitivity	Probe Linearity	Probe Isotropy	Mod. Type	Duty Factor	Peak to average power ratio
30/07/2019	ES3DV3	450	body	0.95	55.89	PASS	PASS	PASS	FM	N/A	PASS
30/07/2019	ES3DV3	450	head	0.88	44.05	PASS	PASS	PASS	FM	N/A	PASS

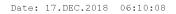


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Trc1 S11 Smith Ref1U Cal int 450.00000 MHz •1 47.792 Ω S11 -j6.489 Ω 2.295 nH 0.5 0.5 0.2 0 -0.5 Ch1 Start 350 MHz Pwr -10 dBm Stop 550 MHz Date: 17.DEC.2018 06:11:53 ۲ Trc1 S11 dB Mag 10 dB / Ref-20 dB Calint •1 450.00000 MHz -22.542 dB S11 20 10 0 -10--20 -30 -40--50 -60-



Ch1 Start 350 MHz



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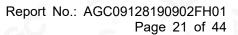
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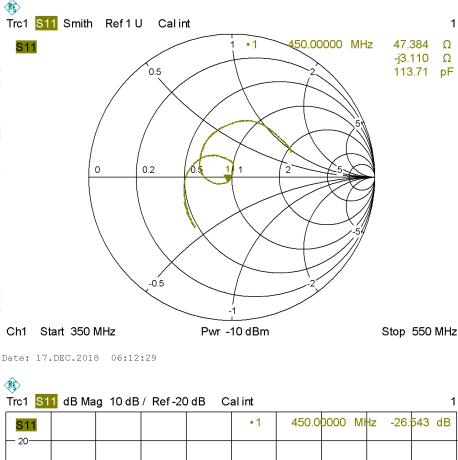
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Pwr -10 dBm

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Stop 550 MHz





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## 7. EUT TEST POSITION

This EUT was tested in Front Face and Rear Face.

## 7.1. Body Worn Position

WHICH IELS

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **25mm** while used in front of face, and body back touch with belt clip.





## 8. SAR EXPOSURE LIMITS

## Limits for General population/Uncontrolled exposure Environment

Type Exposure Limits	general population/uncontrolled exposure limits (W/Kg)
Spatial Average SAR (whole body)	1.6





## 9. TEST FACILITY

Test Site	Attestation of Global Compliance (Shenzhen) Co., Ltd
Location	1-2/F, Building 19, Junfeng Industrial Park, Chongqing Road, Heping Community, Fuhai Street, Bao'an District, Shenzhen, Guangdong, China
Designation Number	CN1259
FCC Test Firm Registration Number	975832
A2LA Cert. No.	5054.02
Description	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by A2LA



## **10. TEST EQUIPMENT LIST**

Equipment description	Manufacturer/ Model	Identification No.	Current calibration date	Next calibration date
Stäubli Robot	Stäubli-TX60	F13/5Q2UD1/A/01	N/A	N/A
Robot Controller	Stäubli-CS8	139522	N/A	N/A
E-Field Probe	Speag- ES3DV3	SN:3337	July 23,2019	July 22,2020
SAM Twin Phantom	Speag-SAM	1790	N/A	N/A
ELI4 Phantom	ELI V5.0	1210	N/A	N/A
Device Holder	Speag-SD 000 H01 KA	SD 000 H01 KA	N/A	N/A
DAE4	Speag-SD 000 D04 BM	1398	Feb. 16,2019	Feb. 15,2020
SAR Software	Speag-DASY5	DASY52.8	N/A	N/A
Liquid	SATIMO	- C	N/A	N/A
Dipole	SATIMO SID450	SN46/11 DIP 0G450-184	Mar. 10,2017	Mar. 09,2020
Signal Generator	Agilent-E4438C	US41461365	Nov. 01,2018	Oct. 31,2019
Vector Analyzer	Agilent / E4440A	US41421290	Feb. 27,2019	Feb. 26,2020
Network Analyzer	Rhode & Schwarz ZVL6	SN101443	Nov. 01,2018	Oct. 31,2019
Attenuator	Warison /WATT-6SR1211	S/N:WRJ34AYM2F1	June 11,2019	June 10, 2020
Amplifier	EM30180	SN060552	Feb. 27,2019	Feb. 26,2020
Directional Couple	Werlatone/ C5571-10	SN99463	June 12,2019	June 11,2020
Power Sensor	NRP-Z21	1137.6000.02	Sep. 09,2019	Sep. 08,2020
Power Sensor	NRP-Z23	US38261498	Feb. 19,2019	Feb. 18,2020
Power Viewer	R&S	V2.3.1.0	N/A	N/A

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

1. There is no physical damage on the dipole;

2. System validation with specific dipole is within 10% of calibrated value;

3. Return-loss is within 20% of calibrated measurement;

4. Impedance is within  $5\Omega$  of calibrated measurement.





## **11. MEASUREMENT UNCERTAINTY**

The component of uncertainly may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainly by the statistical analysis of a series of observations is termed a Type An evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience, and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table as follow.

Uncertainty Distributions	Normal	Rectangular	Triangular	U-Shape
Multi-plying Factor(a)	1/k(b)	1/√3	1/√6	$1/\sqrt{2}$

- (a) Standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity
- (b)  $\kappa$  is the coverage factor

#### Table 13.1 Standard Uncertainty for Assumed Distribution (above table)

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is shown in the following tables.



Measu	urement u	ncertainty fo		ty- ES3DV averaged c		/ 10 gram.			
a	b	с	d	e f(d,k)	f	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System		202		G	8				.0
Probe calibration	E.2.1	6.65	N	1	1	1	6.65	6.65	∞
Axial Isotropy	E.2.2	0.25	R	$\sqrt{3}$	√0.5	√0.5	0.10	0.10	∞
Hemispherical Isotropy	E.2.2	1.3	R	$\sqrt{3}$	√0.5	√0.5	0.53	0.53	∞
Boundary effect	E.2.3	1	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Linearity	E.2.4	0.3	R	$\sqrt{3}$	1	1	0.17	0.17	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Modulation response 调制响应	E2.5	3.3	R	√3	1	1	1.91	1.91	∞
Readout Electronics	E.2.6	0.15	N		1	1	0.15	0.15	8
Response Time	E.2.7	0	R	$\sqrt{3}$	1	1	0	0	8
ntegration Time	E.2.8	1.7	R	$\sqrt{3}$	1	1	0.98	0.98	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	~
Probe positioner mechanical olerance	E.6.2	0.4	R	$\sqrt{3}$	1	G	0.23	0.23	~
Probe positioning with respect to bhantom shell	E.6.3	6.7	R	√3	1	1	3.87	3.87	~
Extrapolation, interpolation, and ntegrations algorithms for max. SAR evaluation	E.5	4	R	√3	1	C1	2.31	2.31	∞
Test sample Related	- 6		C.	®				~ ~ ~	1
Test sample positioning	E.4.2	2.9	N	1	1	1	2.90	2.90	∞
Device holder uncertainty	E.4.1	3.6	N	1	1	1	3.60	3.60	∞
Output power variation—SAR drift measurement	E.2.9	5	R	√3	1	10	2.89	2.89	8
SAR scaling	E.6.5	5	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Phantom and tissue parameters			- <u>S</u> C		- 6	Ś			~
Phantom shell uncertainty—shape, hickness, and permittivity	E.3.1	6.6	R	√3	1	10	3.81	3.81	∞
Jncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	Ν	1	1	0.84	1.90	1.60	~
_iquid conductivity measurement	E.3.3	4	N	10	0.78	0.71	3.12	2.84	N
_iquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.15	1.30	N
iquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	∞
iquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty	- 6		RSS			< <u>C</u>	11.79	11.62	
Expanded Uncertainty (95% Confidence interval)	0	~ G <sup>C</sup>	K=2	C	8		23.58	23.25	.0



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System	n Check u			ty- ES3DV	over 1 gram	n / 10 gram			
a	b	c	d	e f(d,k)	f	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System		(= /0)		~	- C	0	(=/0)	(=/*)	~
Probe calibration drift	E.2.1	0.5	Ν	1	1	1	0.5	0.5	∞
Axial Isotropy	E.2.2	0.25	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Hemispherical Isotropy	E.2.2	1.3	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Boundary effect	E.2.3	1	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Linearity	E.2.4	0.3	R	$\sqrt{3}$	0	0	0.00	0.00	° ∞
System detection limits	E.2.4	1.0	R	√3 ⊚	0	0	0.00	0.00	∞
Modulation response	E2.5	3.3	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.15	N	1	0	0	0.00	0.00	8
Response Time	E.2.7	0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.7	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-reflections	ିE.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Probe positioner mechanical tolerance	E.6.2	0.4	R	$\sqrt{3}$	1	1	0.23	0.23	∞
Probe positioning with respect to phantom shell	E.6.3	6.7	R	$\sqrt{3}$	1	1	3.87	3.87	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	4	R	√3	0	0	0.00	0.00	∞
System check source (dipole)	S		G	0				- 64	1
Deviation of experimental dipoles	E.6.4	2.0	Ν	1	1	1	2.00	2.00	8
Input power and SAR drift measurement	8,6.6.4	5.0	R	√3	1	1	2.89	2.89	8
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and tissue parameters		20-		0	0			Υ.	. C
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	6.6	R	√3	1	1	3.81	。3.81	~
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	8
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	М
Liquid permittivity measurement	E.3.3	。 5	N	1	0.23	0.26	1.15	1.30	Μ
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty	0		RSS				7.34	7.07	
Expanded Uncertainty (95% Confidence interval)	00		K=2	0		N	14.67	14.14	



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System	0	uncertainty	÷	e averaged e	1	m / To gran	1. h	1	
a	b	C	d	f(d,k)	f	g	c×f/e	c×g/e	k
Uncertainty Component	Sec.	Tol (±%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System			- <u>S</u> C	<u> </u>	C.S				
Probe calibration	E.2.1	6.65	Ν	1	1		6.65	6.65	8
Axial Isotropy	E.2.2	0.25	R	$\sqrt{3}$	1	1	0.14	0.14	00
Hemispherical Isotropy	E.2.2	1.3	R	$\sqrt{3}$	0	0	0.00	0.00	00
Boundary effect	E.2.3	1	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Linearity	E.2.4	0.3	R	$\sqrt{3}$	1	1	0.17	0.17	∞
System detection limits	E.2.4	1.0	R	√3 ⊚	1	1	0.58	0.58	∞
Modulation response	E2.5	3.3	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.15	N	1	1	1	0.15	0.15	∞
Response Time	E.2.7	0 💿	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.7	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
Probe positioner mechanical tolerance	E.6.2	0.4	R	$\sqrt{3}$	1	1	0.37	0.37	∞
Probe positioning with respect to phantom shell	E.6.3	6.7	R	√3	1	1	3.87	3.87	8
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	4	R	√3	1	1	2.31	2.31	∞
System check source (dipole)	<b>S</b>		G	0					1
Deviation of experimental dipole from numerical dipole	E.6.4	5.0	Ν	C1	1	1	5.00	5.00	8
Input power and SAR drift measurement	8,6.6.4	5.0	R	√3	1	1	2.89	2.89	ø
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	8
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	6.6	R	√3	61	10	3.81	3.81	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	Ν	1	1	0.84	1.90	1.60	8
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	М
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.15	1.30	М
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty	<u> </u>		RSS		10		11.44	11.27	
Expanded Uncertainty (95% Confidence interval)	GO	C.C	K=2	8	0		22.88	22.54	



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## **12. POWER MEASUREMENT**

Frequency (MHz)	Channel	ERP (dBm)		
462.5500-462.7250MHz(2W)				
462.5500	1	32.69		
462.6375	8	32.75		
462.7250	15	32.71		





## **13. TEST RESULTS**

#### 13.1. SAR Test Results Summary

#### 13.1.1. Test position and configuration

Face up SAR was performed with the device configured in the positions according to KDB 643646 and Body SAR was performed with the device configured with all accessories close to the Flat Phantom.

#### 13.1.2. Operation Mode

- Set the EUT to maximum output power level and transmit on lower, middle and top channel with 100% duty cycle individually during SAR measurement.
- Per KDB 643646 D01, Passive body-worn and audio accessories generally do not apply to the head SAR of PTT radios. Head SAR is measured with the front surface of the radio positioned at 2.5 cm parallel to a flat phantom.
- Per KDB 643646 D01, Body SAR is measured with the radio placed in a body-worn accessory, positioned against a flat phantom, representative of the normal operating conditions expected by users and typically with a standard default audio accessory supplied with the radio.

When testing antennas with the default battery: the same test measurement with head part.

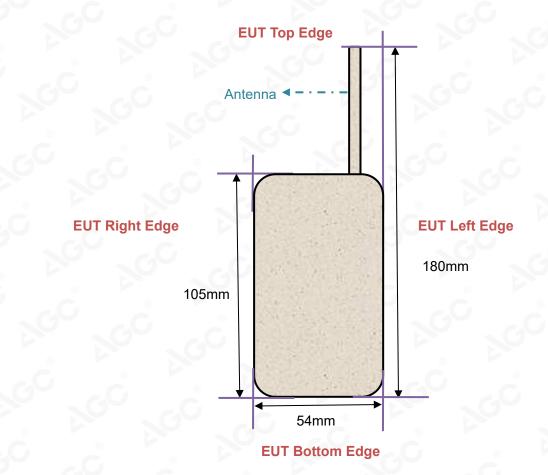
• The EUT only contains the Testing antenna, Standard battery and default body-worn accessory specified by customer. The earphone is only for testing





Report No.: AGC09128190902FH01 Page 32 of 44

## 12.1.3. Antenna Location:( back view )





## 13.1.4. SAR Test Results Summary

SAR MEASUREME	NT									
Depth of Liquid (cm):>15					Relative Humidity (%): 45.4					
Product: Two way ra	adio									
Test Mode: Hold to Face with 2.5 cm separation & body back touch with clip										
Position	Freq. (MHz)	Separa tion (KHz)	Power Drift (±0.2dB)	SAR 1g with 100% duty Cycle (W/kg)	SAR 1g with 50% duty cycle (W/Kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/Kg)	Limit W/kg	
462.5500-462.7250MHz(2W)										
Face Up	462.6375	12.5	0.05	1.39	0.695	33.01	32.75	0.729	1.6	
Back Touch +Belt Clip + headset	462.5500		-0.29	2.45	1.225	33.01	32.69	1.410	1.6	
Back Touch +Belt Clip + headset	462.6375		-0.62	2.15	1.075	33.01	32.75	1.316	1.6	
Back Touch +Belt Clip + headset	462.7250		-0.23	2.17	1.085	33.01	32.71	1.226	1.6	

Note:

1. During the test, EUT power is 2 W with 100% duty cycle;

2. There is just default battery and antenna in this project;

3. Max\_Scaled = SAR \_ meas \*10<sup>$$\frac{-Dim}{10} * \frac{P_{max}}{P_{int}} * DC$$</sup>

P\_ max = Maximum Power(W) P\_ int = Initial Power(W)

Drift = DASY drift results(dB)

SAR\_ meas=Measured 10-g or 1-g Avg.SAR(W/kg)

DC = Transmission mode duty cycle in % where applicable 50% duty cycle is applied for PTT operation. For conservative results, the following are applied:

If P\_int > P\_max, then P\_max/P\_int =1. Drift = 1 for positive drift





Repeated SAR									
Product: Two way radio									
Test Mode: Hold to Face with 2.5 cm separation & body back touch with clip									
Position	Frequency (MHz)	Separati on (KHz)	Power Drift (<±0.2dB)	Once SAR 1g with 100% duty cycle (W/kg)	Once SAR 1g with 50% duty cycle (W/Kg)	Twice SAR 1g with 100% duty cycle (W/kg)	Twice SAR 1g with 50% duty cycle (W/kg)	Limit W/kg	
462.5500-462.7250MHz(2W)									
Back Touch +Belt Clip + headset	462.6375	12.5	-0.27	2.28	1.14	- 20	? ?	1.6	





Test date: Sep. 18,2019

## APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab System Check Head 450MHz

DUT: Dipole 450 MHz Type: SID 450

Communication System: CW; Communication System Band: CW; Duty Cycle: 1:1;

Frequency: 450MHz; Medium parameters used: f = 450MHz;  $\sigma = 0.86 \text{ mho/m}$ ;  $\epsilon r = 42.47$ ;  $\rho = 1000 \text{ kg/m}^3$ ; Phantom Type: Elliptical Phantom; Input Power=18dBm

Ambient temperature (°C): 21.6, Liquid temperature (°C): 21.3

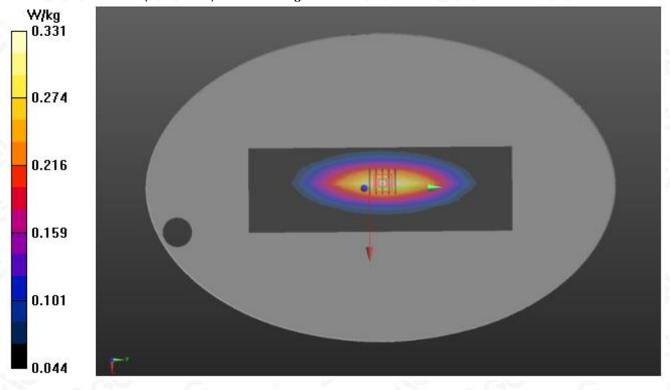
DASY Configuration:

- Probe:ES3DV3 SN3337; ConvF(6.99, 6.99, 6.99); Calibrated: July 23,2019;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: Feb. 16,2019
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**Configuration/System Check 450MHz Head/Area Scan (8x23x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.334 W/kg

**Configuration/System Check 450MHz Head/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 19.558 V/m; Power Drift = 0.07 dB Peak SAR (extrapolated) = 0.420 W/kg SAR(1 g) = 0.290 W/kg; SAR(10 g) = 0.201 W/kg Maximum value of SAR (measured) = 0.331 W/kg





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**Test Laboratory: AGC Lab** 

System Check Body 450MHz

#### Test date: Sep. 18,2019

**DUT: Dipole 450 MHz Type: SID 450** Communication System: CW; Communication System Band: CW; Duty Cycle: 1:1; Frequency: 450MHz; Medium parameters used: f = 450MHz;  $\sigma$  = 0.92 mho/m;  $\epsilon$  r =54.87;  $\rho$  = 1000 kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom; Input Power=18dBm Ambient temperature (°C): 21.6, Liquid temperature (°C): 21.4

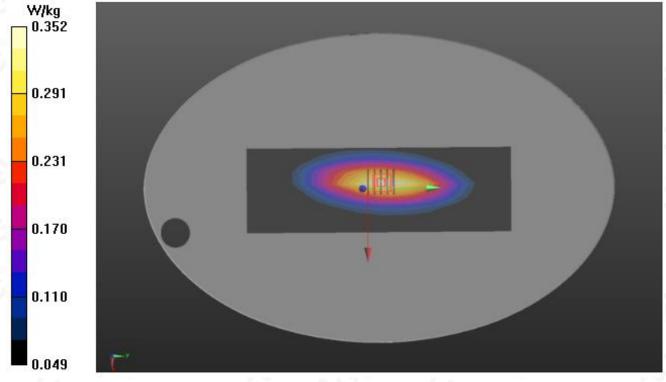
DASY Configuration:

- Probe:ES3DV3 SN3337; ConvF(7.09, 7.09, 7.09); Calibrated: July 23,2019;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: Feb. 16,2019
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**Configuration/System Check 450MHz Body/Area Scan (8x23x1):**Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.354 W/kg

**Configuration/System Check 450MHz Body/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 18.509 V/m; Power Drift = 0.08 dB Peak SAR (extrapolated) = 0.445 W/kg SAR(1 g) = 0.308 W/kg; SAR(10 g) = 0.216 W/kg Maximum value of SAR (measured) = 0.352 W/kg







Report No.: AGC09128190902FH01 Page 37 of 44

## APPENDIX B. SAR MEASUREMENT DATA

462.5500-462.7250MHz(2W) Test Laboratory: AGC Lab 450 Mid- face up 2.5cm (12.5 KHz) DUT: Two way radio; Type: WT-F21

Date: Sep. 18,2019

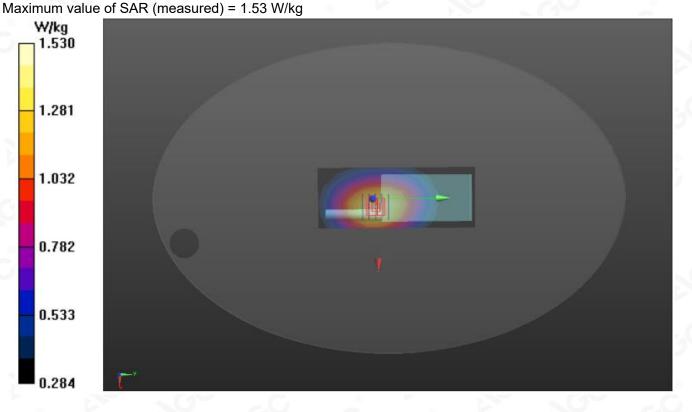
Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency:462.6375 MHz; Medium parameters used: f = 450MHz;  $\sigma$  = 0.89 mho/m;  $\epsilon$  r =42.12;  $\rho$  = 1000 kg/m<sup>3</sup>; Phantom Type: Elliptical Phantom Ambient temperature (°C): 21.6, Liquid temperature (°C): 21.3

DASY Configuration:

- Probe:ES3DV3 SN3337; ConvF(6.99, 6.99, 6.99); Calibrated: July 23,2019;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: Feb. 16,2019
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**FACE UP/A-12.5K-FACE UP/Area Scan (6x14x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 1.51 W/kg

FACE UP/A-12.5K-FACE UP/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 39.910 V/m; Power Drift = 0.05 dB Peak SAR (extrapolated) = 1.80 W/kg SAR(1 g) = 1.39 W/kg; SAR(10 g) = 1.05 W/kg







Test Laboratory: AGC Lab 450 Low -Body –Touch (12.5 KHz) DUT: Two way radio; Type: WT-F21 Date: Sep. 18,2019

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency:462.5500MHz; Medium parameters used: f = 450 MHz;  $\sigma$  = 0.93mho/m;  $\epsilon$  r =54.13;  $\rho$  = 1000 kg/m; Phantom Type: Elliptical Phantom Ambient temperature (°C): 21.6, Liquid temperature (°C): 21.4

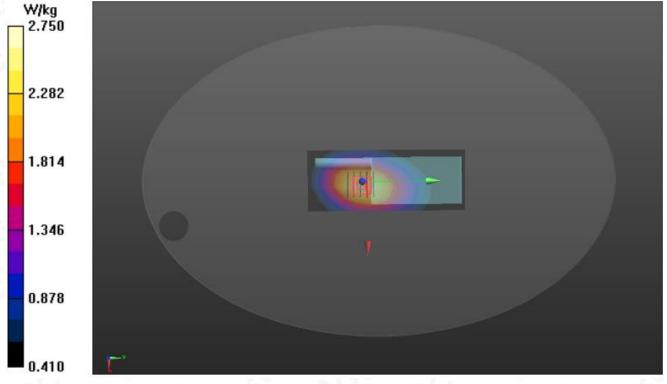
DASY Configuration:

- Probe:ES3DV3 SN3337; ConvF(7.09, 7.09, 7.09); Calibrated: July 23,2019;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: Feb. 16,2019
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**BODY/A-12.5K-BACK-L/Area Scan (6x14x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 2.73 W/kg

BODY/A-12.5K-BACK-L/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 49.777 V/m; Power Drift = -0.29 dB Peak SAR (extrapolated) = 3.35 W/kg SAR(1 g) = 2.45 W/kg; SAR(10 g) = 1.79 W/kg

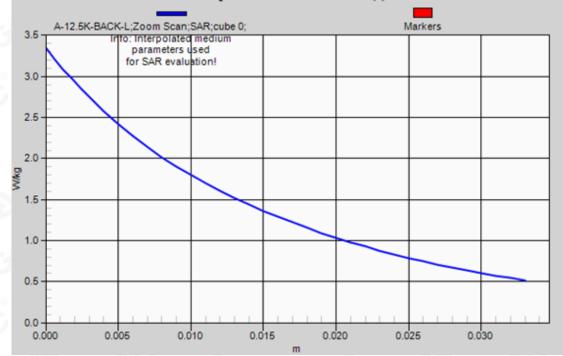
Maximum value of SAR (measured) = 2.75 W/kg







Report No.: AGC09128190902FH01 Page 39 of 44



#### Interpolated Max SAR Z Line(z)





Repeated SAR Test Laboratory: AGC Lab 450 Low -Body –Touch (12.5 KHz) DUT: Two way radio; Type: WT-F21

Date: Sep. 18,2019

Communication System: 450; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Frequency:462.5500MHz; Medium parameters used: f = 450 MHz;  $\sigma$  = 0.93mho/m;  $\epsilon$  r =54.13;  $\rho$  = 1000 kg/m; Phantom Type: Elliptical Phantom Ambient temperature (°C): 21.6, Liquid temperature (°C): 21.4

DASY Configuration:

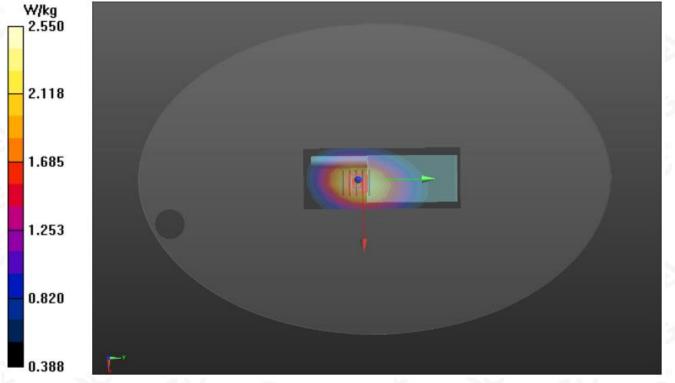
- Probe:ES3DV3 SN3337; ConvF(7.09, 7.09, 7.09); Calibrated: July 23,2019;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0,
- Electronics: DAE4 SN1398; Calibrated: Feb. 16,2019
- Phantom: ELI v5.0; Type: QDOVA002AA; Serial: TP:1108
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

**BODY/A-12.5K-BACK-L-REPEAT/Area Scan (6x14x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 2.55 W/kg

BODY/A-12.5K-BACK-L-REPEAT/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 48.062 V/m; Power Drift = -0.27 dB Peak SAR (extrapolated) = 3.09 W/kg SAR(1 g) = 2.28 W/kg; SAR(10 g) = 1.67 W/kg

Maximum value of SAR (measured) = 2.55 W/kg



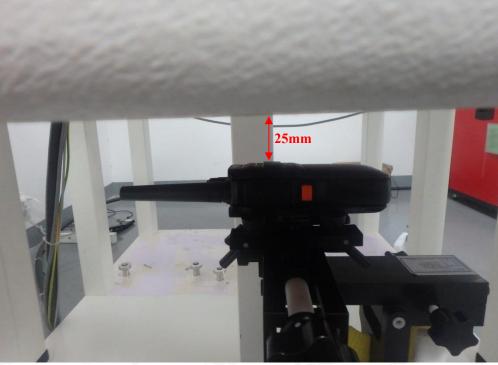




Report No.: AGC09128190902FH01 Page 41 of 44

## **APPENDIX C. TEST SETUP PHOTOGRAPHS**

Face Up with 2.5 cm Separation Distance.



Body Back Touch with all accessories





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Report No.: AGC09128190902FH01 Page 42 of 44

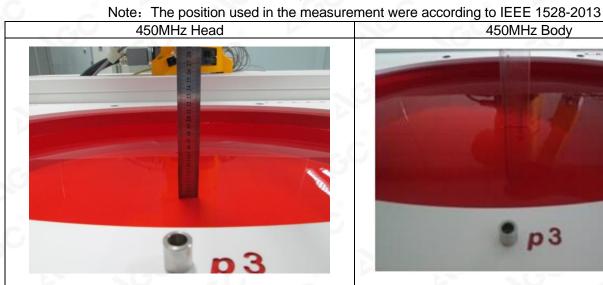


The thickness of EUT is 3.0cm Note : The headset is just for testing. This tested and electrically similar headsets may be used.





Report No.: AGC09128190902FH01 Page 43 of 44



## DEPTH OF THE LIQUID IN THE PHANTOM-ZOOM IN





Report No.: AGC09128190902FH01 Page 44 of 44

## APPENDIX D. CALIBRATION DATA

Refer to Attached files.

