

Hybrid Electronic Steering Terminal

Model : HSA-MUF

FCCID : 2AUBBHSA-MUF

Name: ElephantWin

Scan Type: Hybrid Electronic
Steering

EIRP: 44.7dBW@ 0°

TX LO: 12.8GHz

TX Frequency: 13.75~14.50GHz

POL: Full Polarization ,

Automatic Switching

Tracking Accuracy: $\leq 0.2^\circ$

Modem: XXXXX

WiFi/PWD: XXXXX

S/N: XXXXXXXXXXXXXXX

Types of Application: COTM

Mechanical Steering Type: Auto

Frequency Band: Ku

Beam Switching Time: $\leq 3\text{ms}$

G/T: 9.5dB/K@ 0°

RX LO: 9.75/10.6GHz

WEB IP/User/PWD: XXXXX



This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) This device must accept any interference received, including interference that may cause undesired operation.

StarWin China Starwin Science & Technology Co., Ltd



RX TX PWR $\pm$ LAN SYS ON/OFF

Hybrid Electronic Steering Terminal
Model: H5A-MUF
ICCID: 2AUBBH5A-MUF
Name: Liliyuan/Wu
Scan Type: Hybrid Electronic Steering
EIRP: 44.7dBW/0°
TX LO: 12.8GHz
TX Frequency: 13.75~14.50GHz
POL: Full Polarization
Automatic Switching
Tracking Accuracy: <0.2°
Modem: XXXXX
WiFi/PWD: XXXXX
S/N: XXXXXXXXXXXXX
Type of Application: 001#
Mechanical Steering Type: Auto
Frequency Band: Ku
Beam Switching Time: <3ms
G/T: 9.0dB/K@0°
RX LO: 0.75/10.6GHz
WEB IP/User/PWD: XXXXX
FC CE