

# Hybrid Electronic Steering Terminal

**Model :** HT-ESA

**FCCID :** 2AUBBHSA-MAC

**Name:** LeopardWin

**Scan Type:** Hybrid Electronic  
Steering

**EIRP:** 48.7dBW@ 0°

**TX Frequency:** 29.25~30GHz

**POL:** Full Polarization ,  
Automatic Switching

**Tracking Accuracy:**  $\leq 0.2^\circ$

**Modem:** XXXXX

**WiFi/PWD:** XXXXX

**S/N:** XXXXXXXXXXXXXXX

**Types of Application:** C0TM

**Mechanical Steering Type:** Auto

**Frequency Band:** Ka

**Beam Switching Time:**  $\leq 3\text{ms}$

**G/T:** 11.4dB/K@ 0°

**RX LO:** 18.25/19.25 GHz

**WEB IP/User/PWD:** XXXXX



This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) This device must accept any interference received, including interference that may cause undesired operation.

**StarWin** China Starwin Science & Technology Co., Ltd'





Hybrid Electronic Steering Terminal  
Model: HT-E5A  
FCCID: 2AURR5A-MAC  
Name: LaserRadar  
Scan Type: Hybrid Electronic  
Steering  
EIRP: 18.7dBm/60°  
TX Frequency: 76-78GHz  
POL: Full Polarization  
Automatic Switching  
Tracking Accuracy: <0.2°  
Modem: XXXXX  
WiFi PWD: XXXXX  
S/N: XXXXXXXXXXXX  
Type of Application: 011W  
Mechanical Steering Type: Auto  
Frequency Band: Ka  
Scan Switching Time: 0.3ms  
G/T: 11.4dB/K @ 0°  
RX LO: 16.7-17.3GHz  
WEB IP / User: PWD: XXXXX  
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