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FCC SAR Test Report

Applicant : Shenzhen Baida Moxing Co.,Ltd.

B1702A, Building 3, Phase 1, Tian'an Cloud

Address : Park Bantian Street, Longgang District,

Shenzhen, China

Product Name : LiteRadio 3 Radio Transmitter

Date : Jan. 04, 2024

Shenzhen Anbotek

Shenzhen Anb





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TEST REPORT

Applicant : Shenzhen Baida Moxing Co.,Ltd.

Manufacturer : Shenzhen Baida Moxing Co.,Ltd.

Product Name : LiteRadio 3 Radio Transmitter

Model No. : LiteRadio 3 CC2500

Trade Mark : BETAFPV

Rating(s) : Input: 5V=1A (with DC 3.7V, 2000mAh Battery inside)

Test Standard(s) : IEC/IEEE 62209-1528:2020; FCC 47 CFR Part 2.1093;

ANSI/IEEE C95.1:2005; Reference FCC KDB 447498;

The device described above is tested by Shenzhen Anbotek Compliance Laboratory Limited to determine the maximum emission levels emanating from the device and the severe levels of the device can endure and its performance criterion. The measurement results are contained in this test report and Shenzhen Anbotek Compliance Laboratory Limited is assumed full of responsibility for the accuracy and completeness of these measurements. Also, this report shows that the EUT (Equipment Under Test) is technically compliant with the IEC/IEEE 62209-1528:2020, FCC 47 CFR Part 2.1093, ANSI/IEEE C95.1:2005, and Reference KDB 447498 requirements.

This report applies to above tested sample only and shall not be reproduced in part without written approval of Shenzhen Anbotek Compliance Laboratory Limited.

| Date of Receipt | Dec. 18, 2023 |
|--|---------------------------------|
| Date of Test | Dec. 18, 2023 |
| | Ella Liang |
| Prepared By | upotek Yupo, N. W. Potek Yupote |
| | (Ella Liang) |
| | 2 Alotek Amborek Amborek |
| inbotek Anbore All botek Anbotek Anbotek | Idward pan |
| Approved & Authorized Signer | telk anbotek Anbot All botek |
| notek Anbore And tek nbotek Anbo | (Edward Pan) |







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Version

| | Version No | | Date | | ı | Descript | ion | | |
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1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing are as follows.

<Highest SAR Summary>

| Francisco Bond | | Highest Reported 1g-SAR(W/Kg) | SAR Test Limit | | |
|----------------|----------------|-------------------------------------|----------------|--|--|
| | Frequency Band | Body-worn(0mm) (W/ | | | |
| | 2.4G | borek Anbore 0.689 Nek Anborek Anto | 1.6 boxek | | |
| | Test Result | PASS potek k | upon k bu | | |

This device is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6 W/kg) specified in KDB 447498 D01 v06, 2015 and ANSI/IEEE C95.1:2005, and had been tested in accordance with the measurement methods and procedures specified in IEEE 1528-2013.



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2. General Information

2.1 Client Information

| Applicant | : Shenzhen Baida Moxing Co.,Ltd. |
|--------------|--|
| Address | B1702A, Building 3, Phase 1, Tian'an Cloud Park Bantian Street, Longgang District, Shenzhen, China |
| Manufacturer | : Shenzhen Baida Moxing Co.,Ltd. |
| Address | B1702A, Building 3, Phase 1, Tian'an Cloud Park Bantian Street, Longgang District, Shenzhen, China |
| Factory | : Shenzhen Baida Moxing Co.,Ltd. |
| Address | B1702A, Building 3, Phase 1, Tian'an Cloud Park Bantian Street, Longgang District, Shenzhen, China |

2.2 Description of Equipment Under Test (EUT)

| DVI. | | ALC: ALC: ALC: ALC: ALC: ALC: ALC: ALC: | 10° 0° 0° 0° 0° 0° 0° 0° 0° 0° 0° 0° 0° 0 |
|---------------------|---|---|--|
| Product Name | : | LiteRadio 3 Radio Transn | nitter Anborek Anborek |
| Model No. | : | LiteRadio 3 CC2500 | alk Anbotek Anbotek Anbo |
| Trade Mark | : | BETAFPV | aborek Anborek Anborek Anborek Anborek Anborek |
| Test Power Supply | : | DC 3.7V battery inside | anbotek Anbotek Anbotek |
| | | Operation Frequency: | 2403.9~2474.1 MHz |
| Product Description | : | Number of Channel: | 235 Channels |
| | | Modulation Type: | FSK Anbotek Anbote Anbote |

Remark: 1) For a more detailed features description, please refer to the manufacturer's specifications or the User's Manual.



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2.3 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue.

2.4 Applied Standard

The Specific Absorption Rate (SAR) testing specification, method, and procedure for this device is in accordance with the following standards:

- IEC/IEEE 62209-1528:2020;
- ANSI/IEEE C95.1:2005
- FCC 47 CFR Part 2.1093
- Reference FCC KDB 447498

2.5 Environment of Test Site

| Items | Required | Actual |
|-----------------|----------|--------|
| Temperature (℃) | 18-25 | 22~23 |
| Humidity (%RH) | 30-70 | 55~65 |

2.6 Test Configuration

For SAR testing, engineering testing software installed on the EUT can provide continuous transmitting RF signal.



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3. Specific Absorption Rate (SAR)

3. 1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

3.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ) . The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = C\left(\frac{\delta T}{\delta t}\right)$$

Where: C is the specific head capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of the tissue and E is the RMS electrical field strength.

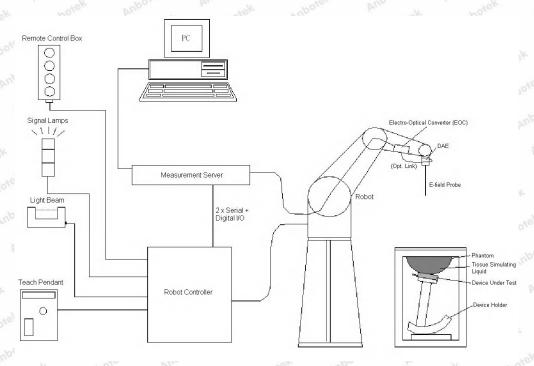
However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.





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4. SAR Measurement System



DASY System Configurations

The DASY system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (EOC) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY software
- Remove control with teach pendant and additional circuitry for robot safety such as warming lamps, etc.
- The SAM twin phantom
- A device holder
- > Tissue simulating liquid
- Dipole for evaluating the proper functioning of the system

components are described in details in the following sub-sections.









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4. 1 E-Field Probe

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

E-Field Probe Specification <EX3DV4 Probe>

| Construction | Symmetrical design with triangular core | | | | | |
|---------------|--|--|--|--|--|--|
| e e | Built-in shielding against static charges | | | | | |
| | PEEK enclosure material (resistant to | | | | | |
| | organic solvents, e.g., DGBE) | | | | | |
| Frequency | 10 MHz to 6 GHz; Linearity: ± 0.2 dB | | | | | |
| Directivity | ± 0.3 dB in HSL (rotation around probe axis) | | | | | |
| | ± 0.5 dB in tissue material (rotation normal to probe axis) | | | | | |
| Dynamic Range | 10 μW/g to 100 mW/g; Linearity: ± 0.2 dB (noise: typically < 1 μW/g) | | | | | |
| Dimensions | Overall length: 330 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) | | | | | |
| | Typical distance from probe tip to dipole centers: 1 mm | | | | | |



Photo of EX3DV4

➢ E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than \pm 10%. The spherical isotropy shall be evaluated and within \pm 0.25dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data can be referred to appendix C of this report.

4. 2 Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The input impedance of the DAE is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.







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Photo of DAE

4.3 Robot

The SPEAG DASY system uses the high precision robots (DASY5: TX60XL) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version (DASY5: CS8c) from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- ➤ High precision (repeatability ±0.035 mm)
- > High reliability (industrial design)
- Jerk-free straight movements
- > Low ELF interference (the closed metallic construction shields against motor control fields)



Photo of DASY5

4. 4 Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chip disk (DASY5: 128 MB), RAM (DASY5: 128 MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O board, which is directly connected to the PC/104 bus of the CPU board.







Report No.: 18220WC30256902 FCC ID: 2AT6X-LITERADIO3C Page 13 of 60 The measurement server performs all the real-time data evaluation for field measurements and

surface detection, controls robot movements and handles safety operations.



Photo of Server for DASY5

4.5 Phantom

<SAM Twin Phantom>

| Shell Thickness | 2 ± 0.2 mm; |
|----------------------|---|
| d and a second | Center ear point: 6 ± 0.2 mm |
| Filling Volume | Approx. 25 liters |
| Dimensions | Length: 1000 mm; Width: 500 mm; Height: adjustable feet |
| Measurement Areas | Left Hand, Right Hand, Flat Phantom |
| y. | porek Anborek Anborek Anborek Anborek |
| , a | Photo of SAM Phantom |

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.



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<ELI4 Phantom>

| 160 | 70 No. 14. 14. |
|-----------------|------------------------------|
| Shell Thickness | 2 ± 0.2 mm (sagging: <1%) |
| Filling Volume | Approx. 30 liters |
| Dimensions | Major ellipse axis: 600 mm |
| | Minor axis:400 mm |
| | Shortek Anbore An otek Opore |
| | in stek anbotek Anbo sek |
| | Anbo ak abotek Anbor An |
| | Anbor An notek anbores P |
| | Photo of ELI4 Phantom |
| | Photo of ELI4 Phantom |

The ELI4 phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.





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4. 6 Device Holder

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5 mm distance, a positioning uncertainty of ± 0.5 mm would produce a SAR uncertainty of $\pm 20\%$. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity ϵ = 3 and loss tangent δ = 0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



Device Holder



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4. 7 Data Storage and Evaluation

Data Storage

The DASY software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-lose media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation

The DASY post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

| Probe parameters: - Sensitivity | Norm _i , a _{i0} , a _{i1} , a _{i2} |
|---------------------------------|---|
|---------------------------------|---|

Conversion factor ConvF
 Diode compression point dcpi

Device parameters: - Frequency

- Crest factor cf

Media parameters: - Conductivity σ

- Density ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power.







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The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with V_i = compensated signal of channel i, (i = x, y, z)

 U_i = input signal of channel i, (i = x, y, z)

cf = crest factor of exciting field (DASY parameter)

dcp_i = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated:

E-field Probes:
$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

H-field Probes:
$$H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

with V_i = compensated signal of channel i,(i = x, y, z)

Norm_i= sensor sensitivity of channel i, (i = x, y, z), $\mu V/(V/m)^2$ for E-field Probes

ConvF= sensitivity enhancement in solution

a_{ii}= sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

E_i= electric field strength of channel i in V/m

H_i= magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

E_{tot}= total field strength in V/m

 σ = conductivity in [mho/m] or [Siemens/m]

 ρ = equivalent tissue density in g/cm³

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.







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5. Test Equipment List

| Manufacture | Name of Favrings and | Trung/Mardal | Carriel Normala an | Calib | ration | |
|--------------|----------------------------------|----------------|--------------------|--------------|--------------|--|
| Manufacturer | Name of Equipment | Type/Model | Serial Number | Last Cal. | Due Date | |
| SPEAG | 2450MHz System Validation Kit | D2450V2 | 910 | Jun. 15,2021 | Jun. 14,2024 | |
| SPEAG | Data Acquisition Electronics | DAE4 | 387 | Sept.06,2023 | Sept.05,2024 | |
| SPEAG | Dosimetric E-Field Probe | EX3DV4 | 7396 | May 06,2023 | May 05,2024 | |
| Agilent | ENA Series Network Analyzer | E5071C | MY46317418 | Oct.26, 2023 | Oct.25, 2024 | |
| SPEAG | DAK | DAK-3.5 | 1226 | NCR | NCR | |
| SPEAG | ELI Phantom | QDOVA004AA | 2058 | NCR | NCR | |
| AR And | Amplifier | ZHL-42W | QA1118004 | NCR | NCR | |
| Agilent | Power Sensor | N8481H | MY51240001 | Oct.26, 2023 | Oct.25, 2024 | |
| Agilent | Spectrum Analyzer | N9020A | MY51170037 | Oct.12, 2023 | Oct.11, 2024 | |
| Agilent | Signal Generation | N5182A | MY47420647 | Feb.23, 2023 | Feb.22, 2024 | |
| Worken | Directional Coupler | 0110A05601O-10 | COM5BNW1A2 | Oct.26, 2023 | Oct.25, 2024 | |

Note:

- The calibration certificate of DASY can be referred to appendix C of this report.
- The dipole calibration interval can be extended to 3 years with justification. The dipoles are also not physically damaged, or repaired during the interval.
- 3. The Insertion Loss calibration of Dual Directional Coupler and Attenuator were characterized via the network analyzer and compensated during system check.
- 4. The dielectric probe kit was calibrated via the network analyzer, with the specified procedure (calibrated in pure water) and calibration kit (standard) short circuit, before the dielectric measurement. The specific procedure and calibration kit are provided by Agilent.
- In system check we need to monitor the level on the power meter, and adjust the power amplifier level to have precise power level to the dipole; the measured SAR will be normalized to 1W input power according to the ratio of 1W to the input power to the dipole. For system check, the calibration of the power amplifier is deemed not critically required for correct measurement; the power meter is critical and we do have calibration for it



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6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.1. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm, which is shown as followed:



Photo of Liquid Height for Body SAR

The following table gives the recipes for tissue simulating liquid.

| Frequency | Water | Sugar | Sugar Cellulose | | Preventol | DGBE | Conductivity | Permittivity | | | | | |
|-----------|----------|-------------------|-----------------|-------|-----------|---------|--------------|--------------|--|--|--|--|--|
| (MHz) | (%) | (%) | (%) | (%) | (%) | (%) (σ) | | (εr) | | | | | |
| | For Body | | | | | | | | | | | | |
| 2450 | 68.6 | O ^{stod} | Anboro | 0,000 | 31.4 | O Amb | 1.95 | 52.7 | | | | | |

The following table shows the measuring results for simulating liquid.

| Tissue Type | Measured | Target Tissue | | | Measure | d Tissue | Liamid | | |
|----------------|--------------------|---------------|------|-------|-------------|----------|-------------|--------------------|------------|
| | Frequency (MHz) | ٤r | σ | ٤r | Dev. (%) | σ | Dev. (%) | Liquid Temp.(℃) | Test Date |
| 2450MSL | 2450 | 52.7 | 1.95 | 51.97 | -1.40 | 1.98 | 1.52 | 22.6 | 12/08/2023 |





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7. System Verification Procedures

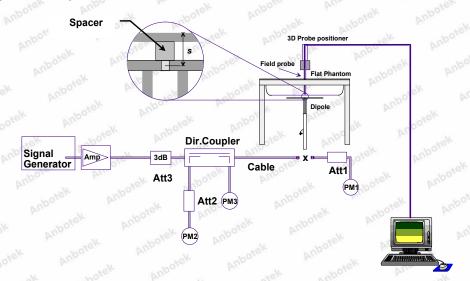
Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

System Setup

In the simplified setup for system evaluation, the EUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



System Setup for System Evaluation





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Photo of Dipole Setup

Validation Results

Comparing to the original SAR value provided by SPEAG, the verification data should be within its specification of 10%. The table below shows the target SAR and measured SAR after normalized to 1W input power. It indicates that the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

| Frequency (MHz) | Liquid Type | Power fed onto reference dipole (mW) | Targeted SAR (W/kg) | Measured SAR (W/kg) | Normalized SAR (W/kg) | Deviation (%) | Test Date |
|--------------------|----------------|---|---------------------------|---------------------------|-----------------------------|------------------|------------|
| 2450 | Body | 250 | 51.8 | 12.78 | 51.48 | -0.62 | 12/08/2023 |

Target and Measurement SAR after Normalized







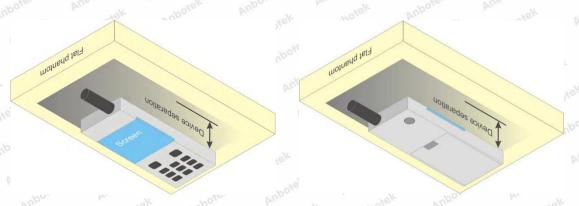
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8. EUT Testing Position

8.1. Body Worn Position

Body-worn operating configurations are tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in a normal use configuration. Per KDB 648474 D04, body-worn accessory exposure is typically related to voice mode operations when handsets are carried in body-worn accessories. The body-worn accessory procedures in FCC KDB 447498 D01 v06, 2015 should be used to test for body-worn accessory SAR compliance, without a headset connected to it. This enables the test results for such configuration to be compatible with that required for hotspot mode when the body-worn accessory test separation distance is greater than or equal to that required for hotspot mode, when applicable. When the reported SAR for body-worn accessory, measured without a headset connected to the handset is < 1.2 W/kg, the highest reported SAR configuration for that wireless mode and frequency band should be repeated for that body-worn accessory with a handset attached to the handset.

Accessories for body-worn operation configurations are divided into two categories: those that do not contain metallic components and those that do contain metallic components and those that do contain metallic components. When multiple accessories that do not contain metallic components are supplied with the device, the device is tested with only the accessory that dictates the closest spacing to the body. Then multiple accessories that contain metallic components are test with the device with each accessory. If multiple accessories share an identical metallic component (i.e. the same metallic belt-chip used with different holsters with no other metallic components) only the accessory that dictates the closest spacing to the body is tested.



Body Worn Position



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9. Measurement Procedures

The measurement procedures are as follows:

- (a) Use base station simulator (if applicable) or engineering software to transmit RF power continuously (continuous Tx) in the middle channel.
- (b) Keep EUT to radiate maximum output power or 100% duty factor (if applicable)
- (c) Measure output power through RF cable and power meter.
- (d) Place the EUT in the positions as setup photos demonstrates.
- (e) Set scan area, grid size and other setting on the DASY software.
- (f) Measure SAR transmitting at the middle channel for all applicable exposure positions.
- (g) Identify the exposure position and device configuration resulting the highest SAR
- (h) Measure SAR at the lowest and highest channels at the worst exposure position and device configuration if applicable.

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

9.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values form the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g







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9. 2 Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

9.3 Area Scan Procedures

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum found in the scanned area, within a range of the global maximum. The range (in dB0 is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE standard 1528 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan), if only one zoom scan follows the area scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of zoom scans has to be increased accordingly.

Area scan parameters extracted from FCC KDB 865664 D01 SAR measurement 100 MHz to 6 GHz.

| | | - N |
|--|---|---|
| | ≤ 3 GHz | > 3 GHz |
| Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface | 5 ± 1 mm | $\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$ |
| Maximum probe angle from probe axis to phantom surface normal at the measurement location | 30° ± 1° | $20^{\circ}\pm1^{\circ}$ |
| | \leq 2 GHz: \leq 15 mm 2 – 3 GHz: \leq 12 mm | $3 - 4 \text{ GHz:} \le 12 \text{ mm}$ $4 - 6 \text{ GHz:} \le 10 \text{ mm}$ |
| Maximum area scan spatial resolution: $\Delta x_{\text{Area}},\Delta y_{\text{Area}}$ | When the x or y dimension of measurement plane orientation the measurement resolution in x or y dimension of the test dimeasurement point on the test | n, is smaller than the above, nust be ≤ the corresponding evice with at least one |



Hotline



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9. 4 Zoom Scan Procedures

Zoom scans are used assess the peak spatial SAR values within a cubic averaging volume containing 1 gram and 10gram of simulated tissue. The zoom scan measures points (refer to table below) within a cube shoes base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the zoom scan evaluates the averaged SAR for 1 gram and 10 gram and displays these values next to the job's label.

Zoom scan parameters extracted from FCC KDB 865664 D01 SAR measurement 100 MHz to 6 GHz.

| | | | ≤ 3 GHz | > 3 GHz |
|---|---|---|--|--|
| 191 | - 400 | E. DE. | noter And | rek "upo, |
| Maximum zoom scan s | spatial reso | olution: Δx _{Zoom} , Δy _{Zoom} | \leq 2 GHz: \leq 8 mm 2 - 3 GHz: \leq 5 mm [*] | $3 - 4 \text{ GHz: } \le 5 \text{ mm}^*$ $4 - 6 \text{ GHz: } \le 4 \text{ mm}^*$ |
| | uniform | grid: Δz _{Zoom} (n) | ≤ 5 mm | $3-4$ GHz: ≤ 4 mm $4-5$ GHz: ≤ 3 mm $5-6$ GHz: ≤ 2 mm |
| Maximum zoom scan spatial resolution, normal to phantom surface | graded | Δz _{Zoom} (1); between 1 st two points closest to phantom surface | ≤4 mm | $3 - 4 \text{ GHz}$: $\le 3 \text{ mm}$ $4 - 5 \text{ GHz}$: $\le 2.5 \text{ mm}$ $5 - 6 \text{ GHz}$: $\le 2 \text{ mm}$ |
| | grid Δz _{Zoom} (n>1): between subsequent points | | ≤1.5·Δ | z _{Zoom} (n-1) |
| Minimum zoom scan volume | x, y, z | | ≥ 30 mm | 3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm |

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.



When zoom scan is required and the <u>reported</u> SAR from the <u>area scan based 1-g SAR estimation</u> procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm. ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.



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9. 5 Volume Scan Procedures

The volume scan is used for assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g aggregate SAR, the EUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing. When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

9.6 Power Drift Monitoring

All SAR testing is under the EUT install full charged battery and transmit maximum output power. In DASY measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of EUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drift more than 5%, the SAR will be retested.



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10. Conducted Power

< Conducted Power>

| Mode | Frequency (MHz) | Peak Power (dBm) | Average Power(dBm) | Tune-Up Limit(dBm) |
|----------|--------------------|---------------------|-----------------------|-----------------------|
| | 2403.9 | 21.49 | 17.99 | 18.50 |
| Transmit | 2439.0 | 20.75 | 17.32 | 18.50 |
| | 2474.1 | 20.28 | 16.91 | 18.50 |

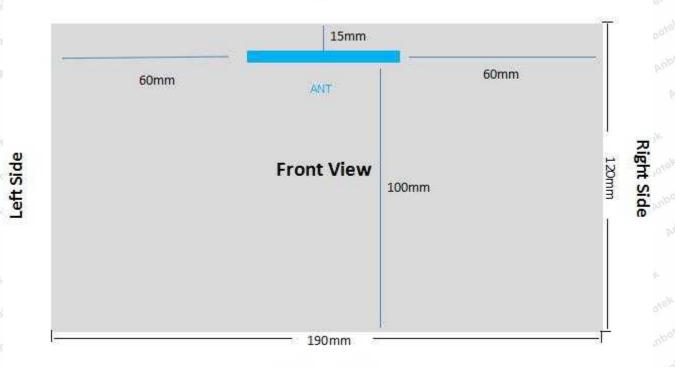
- 1. Per KDB 447498 D01 v06, the test distance less than 5mm
- 2. Per KDB 248227 D01, choose the highest output power channel to test SAR and determine further SAR exclusion.
- 3. All of the chips works at the same band and share the same antenna, so we select 6936 chip which transmit the maximum output power for test.



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11. Antenna Location

Top Side



Bottom Side

| | Distance of The Antenna vertical to the EUT surface and edge | | | | | | | | | | |
|--|--|-------|-------|-------|-------|-------|--|--|--|--|--|
| Antennas Front Back Top Side Bottom Side Left Side Right Sid | | | | | | | | | | | |
| 2.4GHz | <25mm | <25mm | <25mm | >25mm | >25mm | >25mm | | | | | |



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SAR Test Results Summary 12.

General Note:

Per KDB 447498 D01 v06, the reported SAR is the measured SAR value adjusted for maximum tune-up tolerance.

Scaling Factor = tune-up limit power (mW) / EUT RF power (mW), where tune-up limit is the maximum rated power among all production units.

Reported SAR(W/kg)= Measured SAR(W/kg)* Scaling Factor
Per KDB 447498 D01 v06, for each exposure position, if the highest output channel reported SAR≤0.8W/kg, other channels SAR testing are not necessary

< 2.4GHz>

| Plot No. | Band | Mode | Test Position | Gap (mm) | Freq. (MHz) | Average Power (dBm) | Tune-Up Limit (dBm) | Scalin g Factor | r Drift | Measure d SAR _{1g} (W/kg) | Reported SAR _{1g} (W/kg) |
|-------------|--------|----------|------------------|-------------|----------------|---------------------------|---------------------------|-----------------------|------------|---|---|
| (d. | 2.4GHz | Transmit | Back | 0 | 2403.9 | 17.99 | 18.50 | 1.125 | -0.06 | 0.338 | 0.380 |
| #1 | 2.4GHz | Transmit | Front | 000d | 2403.9 | 17.99 | 18.50 | 1.125 | 0.10 | 0.613 | 0.689 |
| -otek | 2.4GHz | Transmit | Тор | Ootek | 2403.9 | 17.99 | 18.50 | 1.125 | 0.11 | 0.423 | 0.476 |
| 100 | 2.4GHz | Transmit | Bottom | 0 | 2403.9 | 17.99 | 18.50 | 1.125 | N/A | N/A | N/A |
| Anbo | 2.4GHz | Transmit | Left | 0 | 2403.9 | 17.99 | 18.50 | 1.125 | N/A | N/A | N/A |
| p.n | 2.4GHz | Transmit | Right | 0 🕅 | 2403.9 | 17.99 | 18.50 | 1.125 | N/A | N/A | N/A |



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Simultaneous Transmission Analysis 13.

Simultaneous TX SAR Considerations

Applicable Simultaneous Transmission

NA





14. Measurement Uncertainty

| k kole and | | Nek. | 50 | 00,0 | Die | | - solor | AUD |
|---|--|---|--|--|--|--|--|--|
| Source | Uncert. | Prob. Dist. | Div. k | ci (1g) | ci (10g) | Stand.U ncert. ui (1g) | Stand.U ncert. ui (10g) | Veff N |
| Repeat Model | 0.4 | her A | ACPOH | 1 | Anbotek | 0. 4 | 0. 4 | Arbotek 9 |
| itek Anbotek Anbi | nte ^k | Instru | ment | DOPE | Dien | bolek | Anborek | Anboten |
| Probe calibration | 7ek | Nootek | 2 | Anbon 1 | » 1 | 3.5 | 3.5 | ∞ |
| Axial isotropy | 100.5 | Anbo | _ √3 | 0.7 | 0.7 | 1.9 | 1.9 | o ^{tek} ∞ |
| Die K Hotel | Aupo | -olk | 20010 | K | Anboten | hug. | otek | nboyek |
| Hemispherical isotropy | 9.4 | R | √3 | 0.7 | 0.7 | 3.9 | 3.9 | MTI ∞ SI |
| Boundary effect | 1.0 | Rotek | _ √3 | inbotek 1 | k 1 | 0.6 | 0.6 | ∞ |
| Linearity | 4.7 | R Anbor | _ √3 | 1 | otek 1ek | 2.7 | 2.7 | ∞ |
| Detection limits | 1.0 | ootek R | √3 | ie ^k 1 | 4 1 ^{look} | 0.6 | 0.6 | nboro Antoek |
| Readout electronics | 0.3 | Notek | 1 | nbotek | 1 Anh | 0.3 | 0.3 | ∞ |
| Response time | 0.8 | Rinbore | _ √3 | Anbore 1 | ot ^{el} 1 | 0.5 | 0.5 | Ant ∞ × |
| Integration time | 2.6 | otek R | √3 | 1 | nbotek 1 | 1.5 mb | 1.5 A | ,bolek ∞k |
| Ambient noise | 3.0 | Ambotek Reek | _ √3 | potek | Amba 1Amb | 1.7 | 1.7 | M. 000 000 000 000 000 000 000 000 000 0 |
| | ,borek | R ^{nbotel} | | Amborol | | 1.7 | 1.7 | Anh ∞ ⊀⊚ |
| Probe positioner mech. | 0.4 | rek R | _ √3 | 1 A | ibotek 1 obotel | 0.2 | 0.2 | botek 8 |
| Probe positioning with respect to phantom | otek | Inposek Vuposek | | ootek Anbotek | Anbi | 1.7 | 1.7 | Anbotel ∞nb/ |
| | Repeat Probe calibration Axial isotropy Hemispherical isotropy Boundary effect Linearity Detection limits Readout electronics Response time Integration time Ambient noise Ambient reflections Probe positioner mech. restrictions Probe positioning with | Repeat 0. 4 Probe calibration 7 Axial isotropy 4.7 Hemispherical isotropy 9.4 Boundary effect 1.0 Linearity 4.7 Detection limits 1.0 Readout electronics 0.3 Response time 0.8 Integration time 2.6 Ambient noise 3.0 Probe positioner mech. restrictions 0.4 Probe positioning with respect to phantom 2.9 | Repeat 0.4 N Instru Probe calibration 7 N Axial isotropy 4.7 R Hemispherical isotropy 9.4 R Boundary effect 1.0 R Linearity 4.7 R Detection limits 1.0 R Readout electronics 0.3 N Response time 0.8 R Integration time 2.6 R Ambient noise 3.0 R Probe positioner mech. restrictions 0.4 R Probe positioning with respect to phantom 3.0 R | Repeat 0.4 N 1 Instrument Probe calibration 7 N 2 Axial isotropy 4.7 R $\sqrt{3}$ Hemispherical isotropy 9.4 R $\sqrt{3}$ Boundary effect 1.0 R $\sqrt{3}$ Linearity 4.7 R $\sqrt{3}$ Detection limits 1.0 R $\sqrt{3}$ Readout electronics 0.3 N 1 Response time 0.8 R $\sqrt{3}$ Integration time 2.6 R $\sqrt{3}$ Ambient noise 3.0 R $\sqrt{3}$ Probe positioner mech. restrictions 0.4 R $\sqrt{3}$ | Repeat 0.4 N 1 1 Instrument Probe calibration 7 N 2 1 Axial isotropy 4.7 R $\sqrt{3}$ 0.7 Hemispherical isotropy 9.4 R $\sqrt{3}$ 0.7 Boundary effect 1.0 R $\sqrt{3}$ 1 Linearity 4.7 R $\sqrt{3}$ 1 Detection limits 1.0 R $\sqrt{3}$ 1 Readout electronics 0.3 N 1 1 Response time 0.8 R $\sqrt{3}$ 1 Integration time 2.6 R $\sqrt{3}$ 1 Ambient noise 3.0 R $\sqrt{3}$ 1 Probe positioner mech. restrictions 0.4 R $\sqrt{3}$ 1 | Repeat 0.4 N 1 1 1 Instrument Probe calibration 7 N 2 1 1 Axial isotropy 4.7 R $\sqrt{3}$ 0.7 0.7 Hemispherical isotropy 9.4 R $\sqrt{3}$ 0.7 0.7 Boundary effect 1.0 R $\sqrt{3}$ 1 1 Linearity 4.7 R $\sqrt{3}$ 1 1 Detection limits 1.0 R $\sqrt{3}$ 1 1 Readout electronics 0.3 N 1 1 1 Response time 0.8 R $\sqrt{3}$ 1 1 Integration time 2.6 R $\sqrt{3}$ 1 1 Ambient reflections 3.0 R $\sqrt{3}$ 1 1 Probe positioner mech. restrictions 0.4 R $\sqrt{3}$ 1 1 Probe positioning with 2.0 R $\sqrt{3}$ | Source Uncert. ai (%) Prob. Dist. bit. k Ci (1g) (10g) ncert. ui (1g) Repeat 0.4 N 1 1 1 0.4 Instrument Probe calibration 7 N 2 1 1 3.5 Axial isotropy 4.7 R $\sqrt{3}$ 0.7 0.7 1.9 Hemispherical isotropy 9.4 R $\sqrt{3}$ 0.7 0.7 3.9 Boundary effect 1.0 R $\sqrt{3}$ 1 1 0.6 Linearity 4.7 R $\sqrt{3}$ 1 1 0.6 Linearity 4.7 R $\sqrt{3}$ 1 1 0.6 Readout electronics 1.0 R $\sqrt{3}$ 1 1 0.3 Response time 0.8 R $\sqrt{3}$ 1 1 0.5 Integration time 2.6 R $\sqrt{3}$ 1 1 1.7 Ambient reflections | Source Incert. ai (%) Prob. Dist. bist. biv. (1g) ci cl (10g) ncert. ui (10g) ncert. ui (10g) Repeat 0.4 N 1 1 1 0.4 0.4 Instrument Probe calibration 7 N 2 1 1 3.5 3.5 Axial isotropy 4.7 R $\sqrt{3}$ 0.7 0.7 1.9 1.9 Hemispherical isotropy 9.4 R $\sqrt{3}$ 0.7 0.7 3.9 3.9 Boundary effect 1.0 R $\sqrt{3}$ 1 1 0.6 0.6 Linearity 4.7 R $\sqrt{3}$ 1 1 0.6 0.6 Linearity 4.7 R $\sqrt{3}$ 1 1 0.6 0.6 Readout electronics 0.3 N 1 1 1 0.5 0.5 Integration time 2.6 R $\sqrt{3}$ 1 1 < |





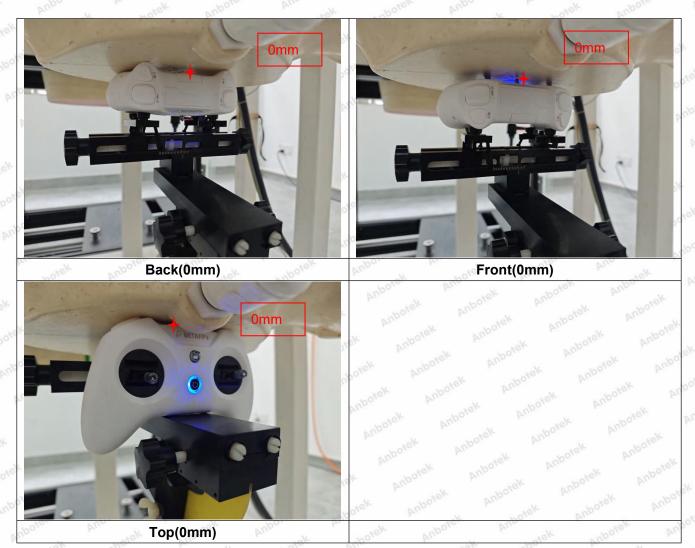
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|--------|--------------------|------|-----------------|------------|-------|---------|--------|------|------------|----|
| 15 | Max.SAR evaluation | 1.0 | ofen InboteR | $\sqrt{3}$ | 1 | Anbotel | 0.6 M | 0.6 | Manage No. | 6 |

| | apoli Air | NO. O. | PUD. | | | 404 | 1000 | D11. | v No |
|-------|------------------------------|----------------|--------------------|--------------|----------------------------|---------------------------|------------------|--------------------|--------------------|
| ek l | Anbotek Anbotes | Ans | Test samp | le rela | ted | hotek | Anbotek | Anbot | er Yur |
| botek | Anbotek Anbu | 3.8 | Hotel Al | bore | lk bi | Anbotek | Anbo | PU PU | 99 |
| 16 | Device positioning | 3.8 | noote N | ArDo* | 1 | P. I | 3.8 | 3.8 | 99 Novel |
| 17 | Device holder | 5.1 | Anb N Anb Nek | 1 Anh | nborek Knborek | 1 | 5.1 | 5.1 | 5nbore |
| P | upo, Ar potek | Aupoter | Anti | e¥_ | Anbo | e.K | Vupo, | bi. | N AND |
| 18 | Drift of output power | 5.0 | R Mahad | √3 | 1 | _{pot} e 1 | 2.9 | 2.9 | otek ∞ |
| otek | Anbore Ana anborek | Anbo | Phantom a | and set | t-up | anbotek | Anbor | Pek Viv | oboyek |
| 19 | Phantom uncertainty | 4.0 | Anb R | | 1. | Anboi | 2.3 | 2.3 | ∞ _× |
| buloc | Liquid conductivity | No. | Ann | 9 | upotek | - bu | anbotek | Anbotek | Albore |
| 20 | (target) | 5.0 | R Anbox | _ √3 | 0.64 | 0.43 | 1.8 | 1.2 | ∞ Anbs |
| 21 | Liquid conductivity | 2.5 | potek N | Anbotek | 0.64 | 0.43 | 1.6 | 1.2 | nbotek ∞.k |
| up ZI | (meas) | 2.5 AM | New N | 20/02 | yer | 0.435 | 1.0 00 | -botek | Aupoten |
| 22 | Liquid Permittivity (target) | 5.0 | Anbo An Rotek | | 0.6 | 0.49 | 1.7 | 1.5 | Anbores & |
| ř. | Anbores Anu | Anbotek | Pulpo. | 16. | N | 1070V | Pupots. | An- | 184 05 |
| 23 | Liquid Permittivity (meas) | 2.5 | N And | o 1 ek | 0.6 | 0.49 | 1.5 | ntek 1.2 | _{lb0} re‱ |
| Noole | Ann hotek Anbot | The Day | 10. 1 | , abo | iek. | Anbore | bler | -otek | Anbotek |
| haday | Combined standard | otek | RSS | U_{i} | $C = \sum_{i} C_{i} U_{i}$ | J _i | 11.4% | 11.3% | 236 |
| Ani | potek Anbotek | Anbotek Lek | Anbotek Anbotek | F Die | Anborel | 2 2 | inboten Lotek | Anborek Anborek | Anbot |
| una | Expanded certainty(P=95%) | Anbore | jk bu∫ | J = k U | ,k=2 | 2 _{botek} | 22.8% | 22.6% | ek An |
| W. | Anb | | Het B | 400,- | P | 100 | - No. | Le. M. | V. |



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Appendix A. EUT Photos and Test Setup Photos







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Appendix B. Plots of SAR System Check

2450MHz System Check Date: 12/08/2023

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:910

Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2450 MHz; σ = 1.98 S/m; ϵ_r = 51.97 ρ = 1000 kg/m³

Phantom section: Flat Section

DASY5 Configuration:

Probe: EX3DV4 - SN7396; ConvF(7.53, 7.53, 7.53); Calibrated: May 06, 2023;

Sensor-Surface: 2mm (Mechanical Surface Detection)

Electronics: DAE4 Sn387; Calibrated: Sep. 06, 2023

Phantom: SAM; Type: QD000P40CD; Serial: TP:1670

Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

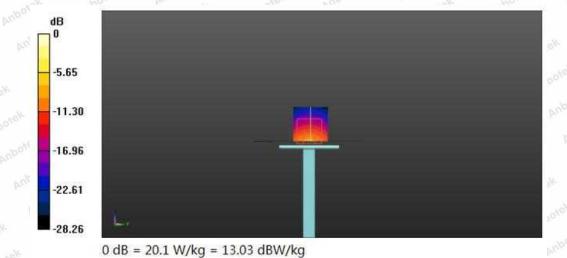
Configuration/Pin=250mW/Area Scan (81x81x1): Interpolated grid: dx=1.200 mm, dy=1.200 mm Maximum value of SAR (interpolated) = 20.43 W/kg

Configuration/Pin=250mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 88.891 V/m; Power Drift = 0.09 dB

Peak SAR (extrapolated) = 26.5 W/kg

SAR(1 g) = 12.78 W/kg; SAR(10 g) = 5.82 W/kgMaximum value of SAR (measured) = 20.11 W/kg









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Appendix C. Plots of SAR Test Data

Date: 12/18/2023

2.4G Body Front CH01

Communication System: UID 0; Frequency: 2403.9MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): f = 2403.9 MHz; $\sigma = 1.98 \text{ S/m}$; $\epsilon_r = 51.97$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY5 Configuration:

Probe: EX3DV4 - SN7396; ConvF(7.53, 7.53, 7.53); Calibrated: May 06, 2023;

Sensor-Surface: 2mm (Mechanical Surface Detection)

Electronics: DAE4 Sn387; Calibrated: Sep. 06, 2023

Phantom: SAM; Type: QD000P40CD; Serial: TP:1670

Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

Top /Area Scan (51x151x1): Measurement grid: dx=1.000mm, dy=1.000mm Maximum value of SAR (measured) = 1.423 W/kg

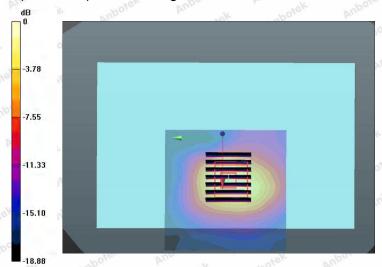
Top /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 11.128 V/m; Power Drift = 0.10 dB

Peak SAR (extrapolated) = 1.449 W/kg

SAR(1 g) = 0.613 W/kg; SAR(10 g) = 0.298 W/kg

Maximum value of SAR (measured) = 1.448 W/kg





Hotline.



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Appendix D. DASY System Calibration Certificate



Tel: +86-10-62304633-2218 Fax: +86-10-62304633-2209
E-mail: ettl@chinattl.com Http://www.chinattl.cn

Client Anbotek (Auden) Certificate No: Z23-98671

CALIBRATION CERTIFICATE

Object EX3DV4 - SN:7396

Calibration Procedure(s) FF-Z12-006-08

Calibration Procedures for Dosimetric E-field Probes

Calibration date: May 06, 2023

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22 \pm 3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | | ID# | Cal Date(Calibrated by, Certificate No.) | Scheduled Calibration |
|-------------------------|---------|-------------|--|-----------------------|
| Power Meter | NRP2 | 101919 | 20-Jun-22 (CTTL, No.J22 X07447) | Jun-21 |
| Power sensor | NRP-Z91 | 101547 | 20-Jun-22 (CTTL, No.J22 X07447) | Jun-21 |
| Power sensor | NRP-Z91 | 101548 | 20-Jun-22 (CTTL, No.J22 X07447) | Jun-21 |
| Reference10dBAttenuator | | 18N50W-10dB | 13-Mar-23(CTTL,No.J23X01547) | Mar-22 |
| Reference20dBAttenuator | | 18N50W-20dB | 13-Mar-23(CTTL, No.J23X01548) | Mar-22 |
| Reference Probe EX3DV4 | | SN 7433 | 26-Sep-22(SPEAG,No.EX3-7433_Sep22) | Sep-21 |
| DAE4 | | SN 549 | 13-Dec-22(SPEAG, No.DAE4-549_Dec22) | Dec -21 |
| Secondary Standards | | ID# | Cal Date(Calibrated by, Certificate No.) | Scheduled Calibration |
| SignalGeneratorMG3700A | | 6201052605 | 27-Jun-22 (CTTL, No.J22X04776) | Jun-21 |
| Network Analyzer E5071C | | MY46110673 | 13-Jan-23 (CTTL, No.J23X00285) | Jan -22 |
| | | Name | Function | Signature |
| Calibrated by: | | Yu Zongying | SAR Test Engineer | E |
| Reviewed by: | | Lin Hao | SAR Test Engineer | 林梅 |
| Approved by: | | Qi Dianyuan | SAR Project Leader | 2002 |
| | | | Issued: May06 | 5,2023 |

This calibration certificate shall not be reproduced except in full without written approval of the laboratory

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Glossary:

TSL tissue simulating liquid
NORMx,y,z sensitivity in free space
ConvF sensitivity in TSL / NORMx,y,z
DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal A,B,C,D modulation dependent linearization parameters

Polarization Φ Φ rotation around probe axis

Polarization θ θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i

 θ =0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
- c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization θ=0 (f≤900MHz in TEM-cell; f>1800MHz: waveguide).
 NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z* frequency_response (see Frequency Response Chart). This
 linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the
 frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z;VRx,y,z:A,B,C are numerical linearization parameters assessed based on the
 data of power sweep for specific modulation signal. The parameters do not depend on frequency nor
 media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f≤800MHz) and inside waveguide using analytical field distributions based on power measurements for f >800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from±50MHz to±100MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the
 probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

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 E-mail: cttl@chinattl.com
 <u>Http://www.chinattl.cn</u>

Probe EX3DV4

SN: 7396

Calibrated: May 06, 2023

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

Certificate No: Z23-98671

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DASY/EASY - Parameters of Probe: EX3DV4 - SN: 7396

Basic Calibration Parameters

| | Sensor X | Sensor Y | Sensor Z | Unc (k=2) |
|-------------------------|----------|----------|----------|-----------|
| $Norm(\mu V/(V/m)^2)^A$ | 0.54 | 0.53 | 0.50 | ±10.0% |
| DCP(mV) ^B | 97.8 | 104.5 | 102.5 | |

Modulation Calibration Parameters

| UID | Communication System Name | | A dB | B dBõV | С | D dB | VR mV | Unc ^E (k=2) |
|-----|---------------------------|---|---------|-----------|-----|---------|----------|---------------------------|
| 0 | CW | Х | 0.0 | 0.0 | 1.0 | 0.00 | 199.9 | ±2.4% |
| | | Y | 0.0 | 0.0 | 1.0 | | 203.3 | 1 |
| | | Z | 0.0 | 0.0 | 1.0 | | 195.0 | |

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

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A The uncertainties of Norm X, Y, Z do not affect the E2-field uncertainty inside TSL (see Page 5 and Page 6).

^B Numerical linearization parameter: uncertainty not required.

E Uncertainty is determined using the max, deviation from linear response applying rectangular distribution and is expressed for the square of the field value.



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DASY/EASY - Parameters of Probe: EX3DV4 - SN: 7396

Calibration Parameter Determined in Head Tissue Simulating Media

| f [MHz] ^C | Relative Permittivity ^F | Conductivity (S/m) ^F | ConvF X | ConvF Y | ConvF Z | Alpha ^G | Depth ^G (mm) | Unct. (k=2) |
|----------------------|---------------------------------------|------------------------------------|---------|---------|---------|--------------------|----------------------------|----------------|
| 750 | 41.9 | 0.89 | 9.82 | 9.82 | 9.82 | 0.30 | 0.85 | ±12.1% |
| 835 | 41.5 | 0.90 | 9.71 | 9.71 | 9.71 | 0.15 | 1.36 | ±12.1% |
| 900 | 41.5 | 0.97 | 9.87 | 9.87 | 9.87 | 0.16 | 1.37 | ±12.1% |
| 1750 | 40.1 | 1.37 | 8.61 | 8.61 | 8.61 | 0.25 | 1.04 | ±12.1% |
| 1900 | 40.0 | 1.40 | 8.13 | 8.13 | 8.13 | 0.24 | 1.01 | ±12.1% |
| 2100 | 39.8 | 1.49 | 8.14 | 8.14 | 8.14 | 0.24 | 1.04 | ±12.1% |
| 2300 | 39.5 | 1.67 | 7.85 | 7.85 | 7.85 | 0.40 | 0.75 | ±12.1% |
| 2450 | 39.2 | 1.80 | 7.57 | 7.57 | 7.57 | 0.50 | 0.75 | ±12.1% |
| 2600 | 39.0 | 1.96 | 7.38 | 7.38 | 7.38 | 0.64 | 0.68 | ±12.1% |
| 5250 | 35.9 | 4.71 | 5.33 | 5.33 | 5.33 | 0.45 | 1.30 | ±13.3% |
| 5600 | 35.5 | 5.07 | 4.89 | 4.89 | 4.89 | 0.45 | 1.35 | ±13.3% |
| 5750 | 35.4 | 5.22 | 4.92 | 4.92 | 4.92 | 0.45 | 1.45 | ±13.3% |

^c Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

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F At frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than \pm 1% for frequencies below 3 GHz and below \pm 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.



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DASY/EASY - Parameters of Probe: EX3DV4 - SN: 7396

Calibration Parameter Determined in Body Tissue Simulating Media

| f [MHz] ^C | Relative Permittivity ^F | Conductivity (S/m) ^F | ConvF X | ConvF Y | ConvF Z | Alpha ^G | Depth ^G (mm) | Unct. (k=2) |
|----------------------|---------------------------------------|------------------------------------|---------|---------|---------|--------------------|----------------------------|----------------|
| 750 | 55.5 | 0.96 | 10.09 | 10.09 | 10.09 | 0.30 | 0.90 | ±12.1% |
| 835 | 55.2 | 0.97 | 9.88 | 9.88 | 9.88 | 0.19 | 1.32 | ±12.1% |
| 900 | 55.0 | 1.05 | 9.82 | 9.82 | 9.82 | 0.23 | 1.15 | ±12.1% |
| 1750 | 53.4 | 1.49 | 8.24 | 8.24 | 8.24 | 0.24 | 1.06 | ±12.1% |
| 1900 | 53.3 | 1.52 | 7.97 | 7.97 | 7.97 | 0.19 | 1.24 | ±12.1% |
| 2100 | 53.2 | 1.62 | 8.18 | 8.18 | 8.18 | 0.19 | 1.39 | ±12.1% |
| 2300 | 52.9 | 1.81 | 7.88 | 7.88 | 7.88 | 0.55 | 0.80 | ±12.1% |
| 2450 | 52.7 | 1.95 | 7.53 | 7.53 | 7.53 | 0.46 | 0.89 | ±12.1% |
| 2600 | 52.5 | 2.16 | 7.38 | 7.38 | 7.38 | 0.52 | 0.80 | ±12.1% |
| 5250 | 48.9 | 5.36 | 4.93 | 4.93 | 4.93 | 0.45 | 1.80 | ±13.3% |
| 5600 | 48.5 | 5.77 | 4.19 | 4.19 | 4.19 | 0.48 | 1.90 | ±13.3% |
| 5750 | 48.3 | 5.94 | 4.52 | 4.52 | 4.52 | 0.48 | 1.95 | ±13.3% |

^c Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

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F At frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than \pm 1% for frequencies below 3 GHz and below \pm 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

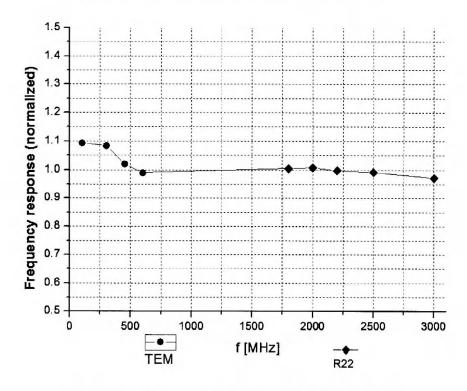


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Frequency Response of E-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ±7.4% (k=2)

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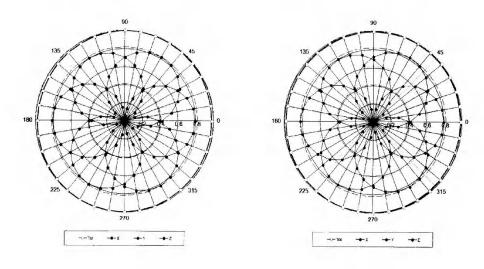


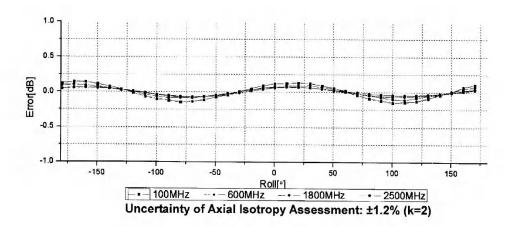
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Receiving Pattern (Φ), θ =0°

f=600 MHz, TEM

f=1800 MHz, R22





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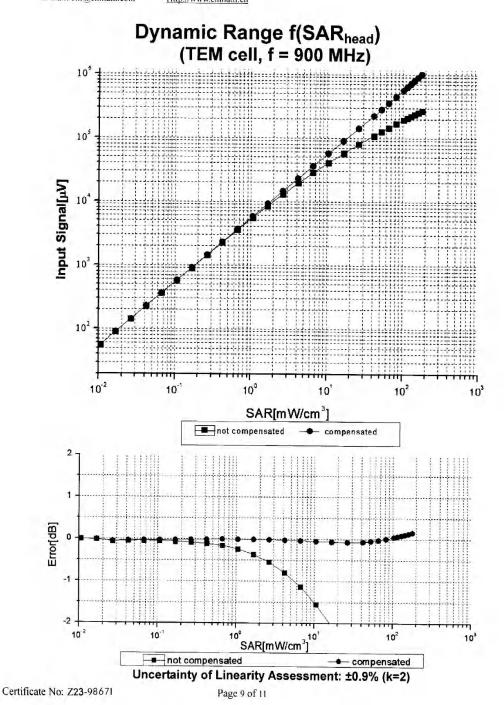
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Shenzhen Anbotek Compliance Laboratory Limited





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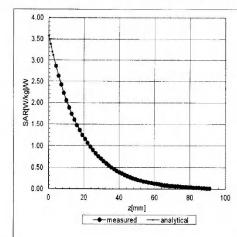


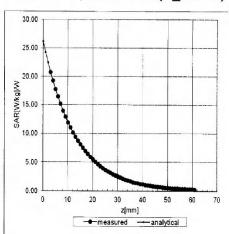
Add: No.51 Xueyuan Road, Haidian District, Beijing, 100191, China Tel: +86-10-62304633-2218 Fax: +86-10-62304633-2209 E-mail: cttl@chinattl.com Http://www.chinattl.cn

Conversion Factor Assessment

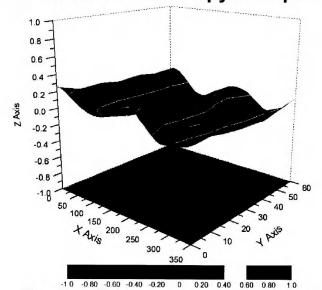
f=900 MHz, WGLS R9(H_convF)

f=1750 MHz, WGLS R22(H convF)





Deviation from Isotropy in Liquid



Uncertainty of Spherical Isotropy Assessment: ±3.2% (K=2)

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DASY/EASY - Parameters of Probe: EX3DV4 - SN: 7396

Other Probe Parameters

| Sensor Arrangement | Triangular |
|---|------------|
| Connector Angle (°) | 156.9 |
| Mechanical Surface Detection Mode | enabled |
| Optical Surface Detection Mode | disable |
| Probe Overall Length | 337mm |
| Probe Body Diameter | 10mm |
| Tip Length | 9mm |
| Tip Diameter | 2.5mm |
| Probe Tip to Sensor X Calibration Point | 1mm |
| Probe Tip to Sensor Y Calibration Point | 1mm |
| Probe Tip to Sensor Z Calibration Point | 1mm |
| Recommended Measurement Distance from Surface | 1.4mm |

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Hotline.

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400-003-0500



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Schmid & Partner Engineering AG

s p e a g

Zeughausstrasse 43, 8004 Zurich, Switzerland Phone +41 44 245 9700, Fax +41 44 245 9779 info@speag.com, http://www.speag.com

IMPORTANT NOTICE

USAGE OF THE DAE 4

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

Battery Exchange: The battery cover of the DAE4 unit is closed using a screw, over tightening the screw may cause the threads inside the DAE to wear out.

Shipping of the DAE: Before shipping the DAE to SPEAG for calibration, remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

E-Stop Failures: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, the customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

Repair: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

DASY Configuration Files: Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

Important Note:

Warranty and calibration is void if the DAE unit is disassembled partly or fully by the

Important Note:

Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the Estop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

Important Note:

To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.

Schmid & Partner Engineering

TN_BR040315AD DAE4.doc

11.12.2009







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> Calibration Laboratory of Schmid & Partner **Engineering AG** Zeughausstrasse 43, 8004 Zurich, Switzerland





Schweizerischer Kalibrierdienst Service suisse d'étalonnage Servizio svizzero di taratura Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS) The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Anbotek (Auden)

Accreditation No.: SCS 0108

Certificate No: DAE4-387_Sep10

CALIBRATION CERTIFICATE

DAE4 - SD 000 D04 BM - SN: 387 Object

Calibration procedure(s) QA CAL-06.v29

Calibration procedure for the data acquisition electronics (DAE)

September 06, 2023 Calibration date:

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID# | Cal Date (Certificate No.) | Scheduled Calibration |
|-------------------------------|--------------------|----------------------------|------------------------|
| Keithley Multimeter Type 2001 | SN: 0810278 | 15-Aug-23 (No:22092) | Aug-22 |
| Secondary Standards | ID# | Check Date (in house) | Scheduled Check |
| Auto DAE Calibration Unit | SE UWS 053 AA 1001 | 05-Jan-23 (in house check) | In house check: Jan-23 |
| | | 05-Jan-23 (in house check) | In house check: Jan-23 |

Name Function Signature Calibrated by: Dominique Steffen Laboratory Technician

Sven Kühn

Issued: September 06, 2023

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: DAE4-387_Sep10

Approved by:

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Deputy Manager









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Calibration Laboratory of Schmid & Partner **Engineering AG**

Zeughausstrasse 43, 8004 Zurich, Switzerland





Schweizerischer Kalibrierdienst Service suisse d'étalonnage C Servizio svizzero di taratura S Swiss Calibration Service

Accreditation No.: SCS 0108

Accredited by the Swiss Accreditation Service (SAS) The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Glossary

DAE data acquisition electronics

Connector angle information used in DASY system to align probe sensor X to the robot

coordinate system.

Methods Applied and Interpretation of Parameters

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
 - Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
 - AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
 - Input Offset Measurement. Output voltage and statistical results over a large number of zero voltage measurements.
 - Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - Input resistance: Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
 - Power consumption: Typical value for information. Supply currents in various operating modes.

Certificate No: DAE4-387 Sep10

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400-003-0500

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DC Voltage Measurement

A/D - Converter Resolution nominal High Range: 1LSB =

6.1µV, full range = -100...+300 mV Low Range: 1LSB = 61nV . full range = -1.....+3mV DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| Calibration Factors | х | Υ | Z |
|---------------------|-----------------------|-----------------------|-----------------------|
| High Range | 404.489 ± 0.02% (k=2) | 404.852 ± 0.02% (k=2) | 404.862 ± 0.02% (k=2) |
| Low Range | 3.97827 ± 1.50% (k=2) | | |

Connector Angle

| Connector Angle to be used in DASY system | 53.0 ° ± 1 ° |
|---|--------------|

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Appendix (Additional assessments outside the scope of SCS0108)

1. DC Voltage Linearity

| High Range | Reading (μV) | Difference (μV) | Error (%) |
|-------------------|--------------|-----------------|-----------|
| Channel X + Input | 200032.85 | -3.31 | -0.00 |
| Channel X + Input | 20007.64 | 1.88 | 0.01 |
| Channel X - Input | -20003.48 | 1.18 | -0.01 |
| Channel Y + Input | 200034.23 | -1.43 | -0.00 |
| Channel Y + Input | 20006.60 | 0.91 | 0.00 |
| Channel Y - Input | -20004.04 | 0.72 | -0.00 |
| Channel Z + Input | 200035.38 | -0.83 | -0.00 |
| Channel Z + Input | 20003.69 | -2.11 | -0.01 |
| Channel Z - Input | -20006.38 | -1.59 | 0.01 |

| Low Range | Reading (μV) | Difference (μV) | Error (%) |
|-------------------|--------------|-----------------|-----------|
| Channel X + Input | 2001.63 | 0.08 | 0.00 |
| Channel X + Input | 202.29 | 0.70 | 0.35 |
| Channel X - Input | -197.90 | 0.60 | -0.30 |
| Channel Y + Input | 2001.33 | -0.07 | -0.00 |
| Channel Y + Input | 200.86 | -0.60 | -0.30 |
| Channel Y - Input | -199.87 | -1.23 | 0.62 |
| Channel Z + Input | 2001.61 | 0.27 | 0.01 |
| Channel Z + Input | 200.60 | -0.70 | -0.35 |
| Channel Z - Input | -199.51 | -0.85 | 0.43 |

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | Common mode Input Voltage (mV) | High Range Average Reading (μV) | Low Range Average Reading (μV) |
|-----------|-----------------------------------|------------------------------------|-----------------------------------|
| Channel X | 200 | 13.50 | 11.56 |
| | - 200 | -8.64 | -11.18 |
| Channel Y | 200 | -0.81 | -1.28 |
| | - 200 | 1.05 | 0.09 |
| Channel Z | 200 | 7.17 | 6.91 |
| | - 200 | -9.46 | -9.01 |

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | Input Voltage (mV) | Channel X (μV) | Channel Y (μV) | Channel Z (μV) |
|-----------|--------------------|----------------|----------------|----------------|
| Channel X | 200 | - | -1.70 | 0.33 |
| Channel Y | 200 | 10.70 | - | -0.38 |
| Channel Z | 200 | 7.11 | 7.89 | - |

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4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

| | High Range (LSB) | Low Range (LSB) |
|-----------|------------------|-----------------|
| Channel X | 15969 | 17466 |
| Channel Y | 15661 | 16162 |
| Channel Z | 15990 | 16190 |

5. Input Offset Measurement

DÅSY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec Input $10 M \Omega$

| | Average (μV) | min. Offset (μV) | max. Offset (μV) | Std. Deviation (µV) |
|-----------|--------------|------------------|------------------|---------------------|
| Channel X | 0.73 | -2.58 | 3.29 | 0.62 |
| Channel Y | 0.41 | -0.49 | 1.23 | 0.40 |
| Channel Z | -0.80 | -1.88 | 0.30 | 0.42 |

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

| | Zeroing (kOhm) | Measuring (MOhm) |
|-----------|----------------|------------------|
| Channel X | 200 | 200 |
| Channel Y | 200 | 200 |
| Channel Z | 200 | 200 |

8. Low Battery Alarm Voltage (Typical values for information)

| Typical values | Alarm Level (VDC) | |
|----------------|-------------------|--|
| Supply (+ Vcc) | +7.9 | |
| Supply (- Vcc) | -7.6 | |

9. Power Consumption (Typical values for information)

| Typical values | Switched off (mA) | Stand by (mA) | Transmitting (mA) |
|----------------|-------------------|---------------|-------------------|
| Supply (+ Vcc) | +0.01 | +6 | +14 |
| Supply (- Vcc) | -0.01 | -8 | -9 |

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Fax: +86-10-62304633-2504 Http://www.chinattl.cn

Anbotek (Auden) **Certificate No:** Z21-97091 Client

CALIBRATION CERTIFICATE

Object D2450V2 - SN: 910

Calibration Procedure(s) FD-Z21-2-003-01

Calibration Procedures for dipole validation kits

Calibration date: Jun 15, 2021

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID# | Cal Date(Calibrated by, Certificate No.) | Scheduled Calibration |
|-------------------------|------------|--|-----------------------|
| Power Meter NRP2 | 101919 | 01-Jul-20 (CTTL, No.J20X04256) | Jun-21 |
| Power sensor NRP-Z91 | 101547 | 01-Jul-20 (CTTL, No.J20X04256) | Jun-21 |
| Reference Probe EX3DV4 | SN 7307 | 19-Feb-21(SPEAG,No.EX3-7307_Feb21) | Feb-22 |
| DAE4 | SN 771 | 02-Feb-21(CTTL-SPEAG,No.Z21-97011) | Feb-22 |
| Secondary Standards | ID# | Cal Date(Calibrated by, Certificate No.) | Scheduled Calibration |
| Signal Generator E4438C | MY49071430 | 01-Feb-21 (CTTL, No.J18X00893) | Jan-22 |
| Network Analyzer E5071C | MY46110673 | 26-Jan-21 (CTTL, No.J18X00894) | Jan-22 |
| | | | |

| | Name | Function | Signature |
|----------------|-------------|-----------------------------------|-------------|
| Calibrated by: | Zhao Jing | SAR Test Engineer | 是 |
| Reviewed by: | Qi Dianyuan | SAR Project Leader | wor |
| Approved by: | Lu Bingsong | Deputy Director of the laboratory | - In wife |
| | | | 13 MES 14 - |

Issued: Jun 17, 2021

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This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Glossary:

TSL tissue simulating liquid
ConvF sensitivity in TSL / NORMx,y,z
N/A not applicable or not measured

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) For hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
- c) IEC 62209-2, "Procedure to measure the Specific Absorption Rate (SAR) For wireless communication devices used in close proximity to the human body (frequency range of 30MHz to 6GHz)", March 2010
- d) KDB865664, SAR Measurement Requirements for 100 MHz to 6 GHz

Additional Documentation:

e) DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end
 of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed
 point exactly below the center marking of the flat phantom section, with the arms oriented
 parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole
 positioned under the liquid filled phantom. The impedance stated is transformed from the
 measurement at the SMA connector to the feed point. The Return Loss ensures low
 reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point.
 No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

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Measurement Conditions

| DASY Version | DASY52 | 52.8.8.1258 |
|------------------------------|--------------------------|-------------|
| Extrapolation | Advanced Extrapolation | |
| Phantom | Triple Flat Phantom 5.1C | |
| Distance Dipole Center - TSL | 10 mm | with Spacer |
| Zoom Scan Resolution | dx, dy, dz = 5 mm | |
| Frequency | 2450 MHz ± 1 MHz | |

Head TSL parameters

The following parameters and calculations were applied.

| | Temperature | Permittivity | Conductivity |
|---|-----------------|--------------|------------------|
| Nominal Head TSL parameters | 22.0 °C | 39.2 | 1.80 mho/m |
| Measured Head TSL parameters | (22.0 ± 0.2) °C | 39.0 ± 6 % | 1.77 mho/m ± 6 % |
| Head TSL temperature change during test | <1.0 °C | | |

SAR result with Head TSL

| SAR averaged over 1 cm^3 (1 g) of Head TSL | Condition | |
|---|--------------------|---------------------------|
| SAR measured | 250 mW input power | 13.0 mW / g |
| SAR for nominal Head TSL parameters | normalized to 1W | 52.4 mW /g ± 20.8 % (k=2) |
| SAR averaged over 10 cm ³ (10 g) of Head TSL | Condition | |
| SAR measured | 250 mW input power | 6.06 mW / g |
| SAR for nominal Head TSL parameters | normalized to 1W | 24.3 mW /g ± 20.4 % (k=2) |

Body TSL parameters

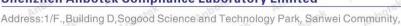
The following parameters and calculations were applied.

| | Temperature | Permittivity | Conductivity |
|---|-----------------|--------------|------------------|
| Nominal Body TSL parameters | 22.0 °C | 52.7 | 1.95 mho/m |
| Measured Body TSL parameters | (22.0 ± 0.2) °C | 52.9 ± 6 % | 1.97 mho/m ± 6 % |
| Body TSL temperature change during test | <1.0 °C | | |

SAR result with Body TSL

| SAR averaged over 1 cm^3 (1 g) of Body TSL | Condition | |
|---|--------------------|---------------------------|
| SAR measured | 250 mW input power | 13.0 mW / g |
| SAR for nominal Body TSL parameters | normalized to 1W | 51.8 mW /g ± 20.8 % (k=2) |
| SAR averaged over 10 cm ³ (10 g) of Body TSL | Condition | |
| SAR measured | 250 mW input power | 6.18 mW / g |
| SAR for nominal Body TSL parameters | normalized to 1W | 24.7 mW /g ± 20.4 % (k=2) |

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Appendix

Antenna Parameters with Head TSL

| Impedance, transformed to feed point | 54.6Ω+ 2.77jΩ | |
|--------------------------------------|---------------|--|
| Return Loss | - 25.8dB | |

Antenna Parameters with Body TSL

| Impedance, transformed to feed point | 50.7Ω+ 4.28jΩ | |
|--------------------------------------|---------------|--|
| Return Loss | - 27.3dB | |

General Antenna Parameters and Design

| Electrical Delay (one direction) | 1.263 ns |
|----------------------------------|----------|

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

| Manufactured by | SPEAG |
|-----------------|-------|
| | |

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DASY5 Validation Report for Head TSL

Test Laboratory: CTTL, Beijing, China

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 910 Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1 Medium parameters used: f = 2450 MHz; $\sigma = 1.767$ S/m; $\epsilon r = 39.01$; $\rho = 1000$ kg/m3

Phantom section: Right Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

Probe: EX3DV4 - SN7307; ConvF(7.36, 7.36, 7.36); Calibrated: 2/19/2021;

Sensor-Surface: 2mm (Mechanical Surface Detection)

Electronics: DAE4 Sn771; Calibrated: 2021-02-02

Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1

Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7372)

Date: 06.15.2021

Dipole Calibration/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm,

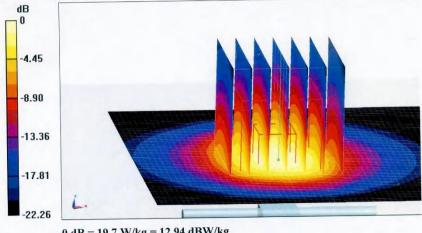
dy=5mm, dz=5mm

Reference Value = 106.5 V/m; Power Drift = 0.02 dB

Peak SAR (extrapolated) = 26.7 W/kg

SAR(1 g) = 13 W/kg; SAR(10 g) = 6.06 W/kg

Maximum value of SAR (measured) = 19.7 W/kg



0 dB = 19.7 W/kg = 12.94 dBW/kg

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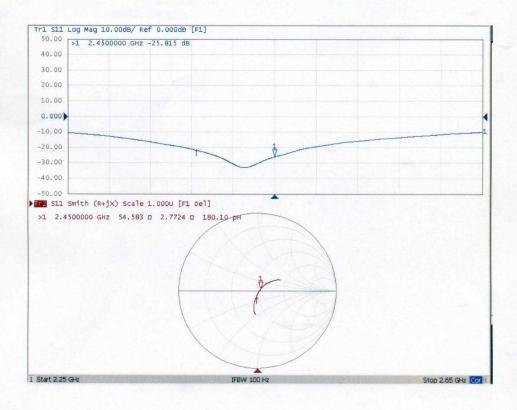








Impedance Measurement Plot for Head TSL



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DASY5 Validation Report for Body TSL

Test Laboratory: CTTL, Beijing, China

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 910 Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1 Medium parameters used: f = 2450 MHz; $\sigma = 1.972$ S/m; $\epsilon_r = 52.92$; $\rho = 1000$ kg/m³

Phantom section: Center Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 SN7307; ConvF(7.22, 7.22, 7.22); Calibrated: 2/19/2021;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn771; Calibrated: 2021-02-02
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7372)

Date: 06.15.2021

Dipole Calibration/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm,

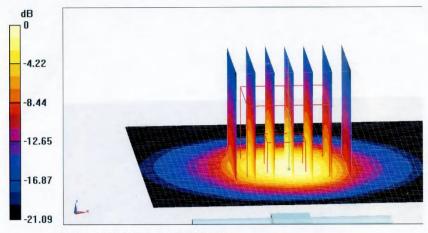
dy=5mm, dz=5mm

Reference Value = 98.89 V/m; Power Drift = 0.03 dB

Peak SAR (extrapolated) = 25.6 W/kg

SAR(1 g) = 13 W/kg; SAR(10 g) = 6.18 W/kg

Maximum value of SAR (measured) = 19.3 W/kg



0 dB = 19.3 W/kg = 12.86 dBW/kg

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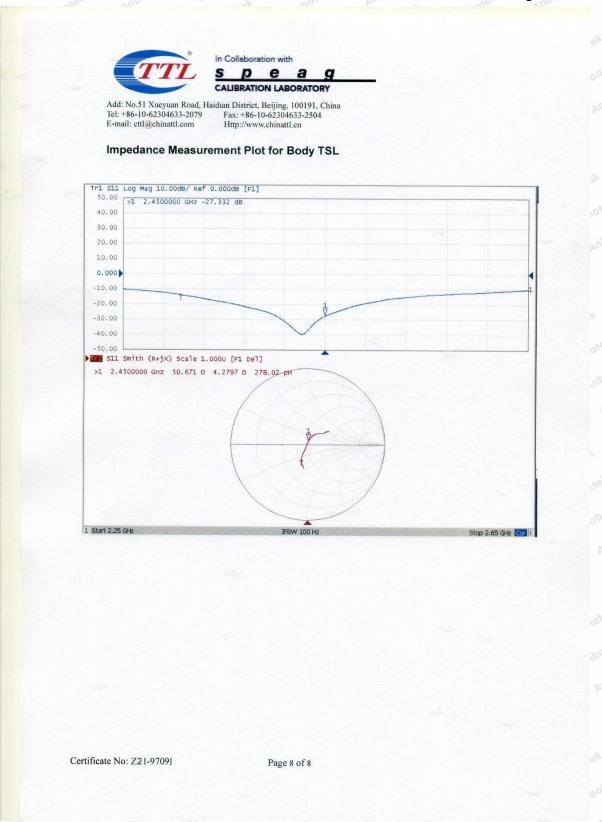








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