English



Instruction and operation manual



Thermal mass flow sensor (with data logger)

FCC ID: 2ASK2-SUT0-003



Dear Customer,

Thank you for choosing our product.

Please read the operating instructions and carefully observed them before you start up the device. The manufacturer cannot be held liable for any damage which occurs as a result of non-observance or noncompliance with this manual.

Should the device be tampered with in any manner other than a procedure which is described and specified in the manual, the warranty is canceled and the manufacturer is exempt from liability.

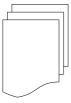
The device is destined exclusively for the described application.

SUTO offers no guarantee for the suitability for any other purpose. SUTO is also not liable for consequential damage resulting from the delivery, capability or use of this device.

Table of contents

1 Safety instructions	4
2 Application	7
3 Features	7
4 Technical Data	8
4.1 General	8
4.2 Electrical data	9
4.3 Data logger	9
4.4 Output signals	
4.5 Accuracy	
4.6 Additional data for models with pressure sensor	
5 Dimensional drawing	
6 Installation	
6.1 Installation considerations	
6.2 Electrical connection	
7 Sensor signal outputs	.13
7.1 Analog output	
7.2 Pulse output	
7.2.1 Pulse connection diagram	
7.3 Modbus output	
8 Configuration	
9 Data logging	
9.1 Features	
9.2 Operations	
9.2.1 Logger settings	
9.2.2 Log analysis and export	
10 Calibration	
11 Disposal or waste	
12 Warranty	.20
Appendix A Specifications	
A.1 Flow ranges	
A.2 Error codes	
Appendix B Modbus communication example	
Appendix C LRC and CRC calculation	.27

1 Safety instructions



Please check if this instruction manual accords to the product type.

Please observe all notes and instructions indicated in this manual. It contains essential information which must be observed before and during installation, operation and

maintenance. Therefore this instruction manual must be read carefully by the technician as well as by the responsible user / qualified personnel.

This instruction manual must be available at the operation site of the dew point sensor at any time. In case of any obscurities or questions, regarding this manual or the product, please contact the manufacturer.



WARNING!

Compressed air!

Any contact with quickly escaping air or bursting parts of the compressed air system can lead to serious injuries or even death!

- Do not exceed the maximum permitted pressure range (see sensors label).
- Only use pressure tight installation material.
- Avoid that persons get hit by escaping air or bursting parts of the instrument.
- The system must be pressureless during maintenance work.



WARNING!

Voltage used for supply!

Any contact with energized parts of the product, may lead to an electrical shock which can lead to serious injuries or even death!

- Consider all regulations for electrical installations.
- The system must be disconnected from any power supply during maintenance.
- Any electrical work on system is only allowed by authorized qualified personal.



WARNING!

Permitted operating parameters!

Observe the permitted operating parameters, any operation exceeding this parameters can lead to malfunctions and may lead to damage on the instrument or the system.

- Do not exceed the permitted operating parameters.
- Make sure the product is operated in its permitted limitations.
- Do not exceed or undercut the permitted storage and operation temperature and pressure.
- The product should be maintained and calibrated frequently, at least annually.

General safety instructions

- It is not allowed to use the product in explosive areas.
- Please observe the national regulations before/during installation and operation.

Remarks

• It is not allowed to disassemble the product.



ATTENTION!

Measurement values can be affected by malfunction!

The product must be installed properly and frequently maintained, otherwise it may lead to wrong measurement values, which can lead to wrong results.

- Always observe the direction of the flow when installing the sensor. The direction is indicated on the housing.
- Do not exceed the maximum operation temperature at the sensors tip.
- Avoid condensation on the sensor element as this will affect accuracy enormously.

Storage and transportation

 Make sure that the transportation temperature is between -30°C ... 70°C,

- For storage and transportation it is recommended to use the packaging which comes with the sensor.
- Please make sure that storage temperature of the sensor is between -10 °C ... 50 °C.
- Avoid direct UV and solar radiation during storage.
- For the storage the humidity has to be <90%, no condensation.

2 RF Exposure Information and Statement

This equipment complies with FCC RF radiation exposure limits set forth for an uncontrolled environment. This equipment should be installed and operated with minimum distance of 20 cm between the radiator and your body.

This device complies with part 15 of the FCC rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

NOTE: The manufacturer is not responsible for any radio or TV interference caused by unauthorized modifications to this equipment. Such modifications could void the user's authority to operate the equipment.

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.



- Increase the separation between the equipment and receiver.

-Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.

-Consult the dealer or an experienced radio/TV technician for help

-This device and its antenna(s) must not be co-located or operating in conjunction with any other antenna or transmitter.

3 Application

The S 418 is a thermal mass flow sensor which is designed to measure the consumption of compressed air and other gases within the permissible operating parameters. These parameters can be found in the technical data section.

The S 418 can measure the following values:

- Volumetric flow
- Total consumption
- Temperature of the fluid
- Pressure of the fluid (optional)

The default factory settings are:

- Volumetric flow in l/min
- Consumption in m³
- Temperature in °C
- Pressure in bar

Other units are configurable using the service App S4C-FS which can be downloaded from the Google Play store or our Website.

4 Features

- Inline thermal mass flow sensor virtually independent of pressure and temperature changes.
- Process connection of G-type thread with DN8, DN15, DN20 and DN25 available
- Very short response time.
- Particularly suitable for measuring at-the-point-of-use flow and consumption of compressed air and other gases.
- Integrated display showing volumetric flow and consumption.
- Options for output signals:
 - Analogue 4 ... 20 mA and pulse output
 - Modbus interface
 - M-Bus interface
- BlueTooth interface for remote sensor settings
- Configurable through Android devices
- Data logger capable of recording 5-million measurement samples

5 Technical Data

5.1 General

CE FC FCC ID: 2ASK2-SU	JTO-003			
Parameters	Flow selectable: Volumetric flow, Actual Volumetric flow: I/min, m ³ /h, m ³ /min, cfm Consumption: m ³ , ft ³ Medium temperature: °C, °F Medium pressure: bar, psi			
Reference conditions	 Selectable by users. Default ex-factory settings: Compressed air: ISO1217 20 °C, 1000 hPa Other gas: DIN1343 0 °C, 1013.25 hPa 			
Principle of measurement	Thermal mass flow			
Sensor	Glass coated resistive sensor			
Measuring medium	Non-corrosive gases, up to 2 calibrated gases			
Operating temperature	0 50 °C fluid temperature and casing			
Humidity of the meas. medium	< 90%, no condensation			
Operating pressure	0 1.0 MPa			
Pressure drop	 Maximum pressure drop at the maximum flow of S calibration range: DN8 type : 30 hPa DN15 type: 100 hPa DN20 type: 100 hPa DN25 type: 200 hPa 			
Casing	Process connection: aluminum alloy Wetted parts: aluminum alloy Top casing: PC + ABS			
Protection class	IP54			
Dimensions	See dimensional drawing on the next page			
Display	4-digit LED display			
Tube diameter	DN 8, DN 15, DN 20, DN 25			
Process connection:	G inner thread ISO 228-1			

Weight	0.43 kg (DN8), 0.46 kg (DN15)
	0.96 kg (DN20), 0.97 kg (DN25)

5.2 Electrical data

Power supply 15 ... 30 VDC, 120 mA @ 24 VDC

5.3 Data logger

Memory size	Up to 8,000,000 samples.
Recording channels	Up to 4: flow, consumption, temperature and pressure.
Logger programming	Through mobile app S4C-FS (free, download from Google Play Store)
Logger read out	Through windows software S4A via USB

5.4 Output signals

Analogue output	Signal: 4 20 mA, isolated Scaling: 0 to max flow Max load: 250R		
Pulse output	1 pulse per consumption unit (m ³ or ft ³) isolated switch, max. 30 VDC, 200 mA (pulse length: 10 120 ms, depends on flow rate)		
Modbus output	See chapter 7.3		

5.5 Accuracy

Accuracy	± 1.5 % of reading ± 0.3% FS
Temperature coefficient	< 0.1%/K FS
Pressure coefficient	<0.5% / bar
Turndown ratio	100:1
Stated accuracy at	Ambient/process temperature 23 °C ± 3 °C Ambient/process humidity <90%

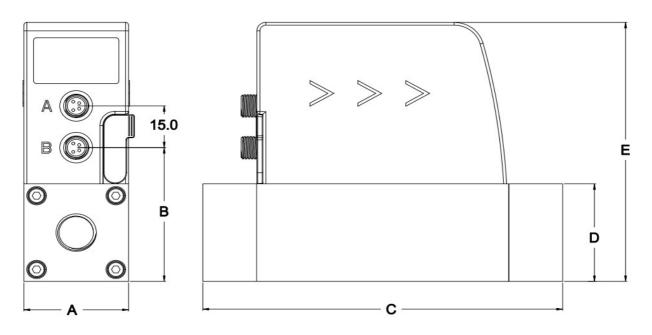


	Process pressure at 0.6 Mpa	
Repeatability	± 0.5% of reading	
Sampling rate	10 samples / second	

5.6 Additional data for models with pressure sensor

Accuracy	± 0.5% FS
Parameters	Pressure: bar (default) or psi
Sensor	Piezzo-resistive sensor
Measuring range	0 10 barg

6 Dimensional drawing



	A (mm)	B (mm)	C (mm)	D (mm)	E (mm)
DN 8/15	35.0	48.0	120.4	35.0	93.0
DN 20/25	48.0	61.0	178.0	48.0	106.0

7 Installation

S 418 is delivered with following components:

Qty.	Description	Order no.
1	S 418 Thermal mass flow meter	S695 4180 S695 4181 S695 4182 S695 4183 S695 4185 S695 4185 S695 4187 S695 4188
1	5 m cable with M8 connector and open ends	A553 0136
1	USB cable	A553 0130
1	Instruction and operation manual	No P/N
1	Calibration certificate	No P/N
1	Serial number for activating software S4A. S4A software can be downloaded from our Web site	M599 7020

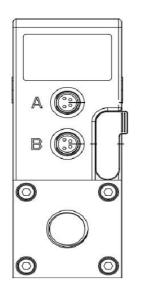
7.1 Installation considerations

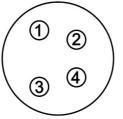
In order to maintain the accuracy stated in the technical data, the sensor must be installed inline and fitted to tubes with the same diameter.

- The sensor is for indoor use only! At an outdoor installation, the sensor must be protected from solar radiation and rain.
- It is strongly recommend not to install S 418 permanently in wet environment as it exists usually right after a compressor outlet.

7.2 Electrical connection

The flow sensor is equipped with two Connector plugs "A" and "B". By default the sensor is delivered with one 5 m cable with a M8 connector on one side and open wires on the other side. To operate the S 418 one cable connection is sufficient however if the pulse output is to be used or the supply and signal should be on separate cables a second connection cable has to be ordered.





-	
GND:	Ground for Modbus
-VB:	Negative supply voltage
+VB:	Positive supply voltage
I+:	Positive 420 mA signal
I-:	Negative 4 20 mA signal
D+:	Modbus data +
D-:	Modbus data -
P:	Pulse signal
M:	M-Bus data
NC:	Not connected

Legend to pin assignment

SUO

Pin assignment connector plug M8

Output Version	Connector	Pin 1	Pin 2	Pin 3	Pin 4
Modbus	Α	D-	-VB	+VB	D+
	В	D-	GND	GND	D+
Pulse and analog	А	I-	-VB	+VB	I+
	В	I-	Р	Р	I+
M-Bus	А	М	-VB	+VB	М
	В	М	NC	NC	М
Wire color		brown	white	blue	black





ATTENTION!

Do not screw the M8 plug using force. Otherwise, it may damage the connecting pins.

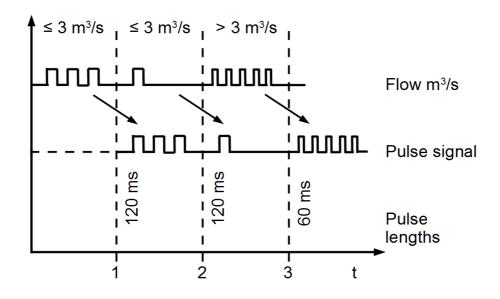
8 Sensor signal outputs

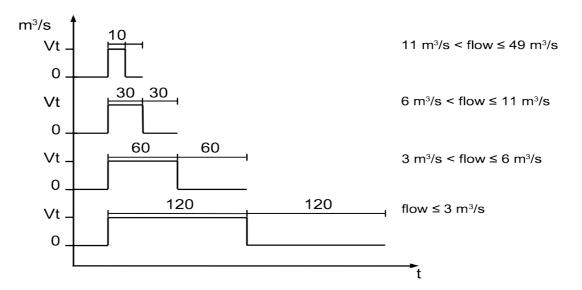
8.1 Analog output

The sensor has an analog output range of 4 ... 20 mA. This output can be scaled to match a desired measuring range. Standard scaling is from 0 to the max flow. The corresponding flow in different pipe sizes can be found in Appendix A.

8.2 Pulse output

The sensor will send out one pulse per consumption unit. This pulse output can be connected to an external pulse counter to count the total consumption. The number of m³ per second are summed up and indicated after one second. Pulse length depends on flow rate.

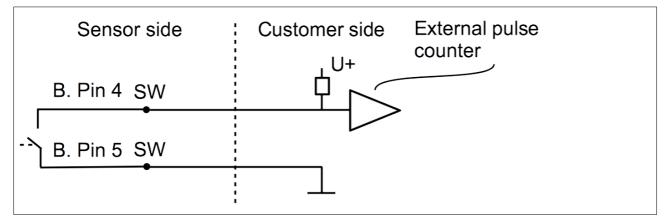




Volumetric flow [m ³ /s]	Volumetric flow [m³/h]	Pulse length [ms]	Max. pulse output per hour
≦ 3	≦ 10800	120	1080
> 3	> 10800	60	2880
> 6	> 21600	30	3960

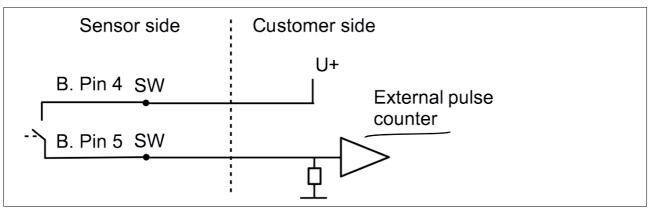
8.2.1 Pulse connection diagram

Variant 1:



SUO

Variant 2:



8.3 Modbus output

Mode	: RTU
Baud rate	: 19200
Device address	: 1
Framing / parity / stop bit	:8,N,1
Response timeout	: 1 second
Response delay	: 0 ms
Inter-frame spacing	: 7 char
- ·	

Remarks

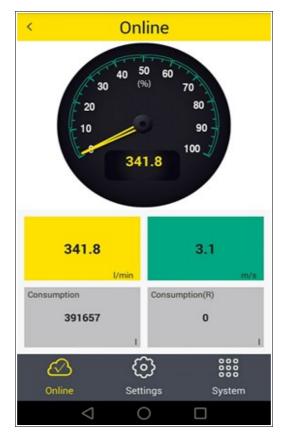
 Modbus communication settings can be changed by the service appS4C-FS.

Index	Channel description	Resolution	Format	Length	Modbus address
1	Flow	0.1	FLOAT	4-byte	6
2	Consumption	1	UNIT32	4-byte	8
3	Temperature	0.1	FLOAT	4-byte	0
4	Pressure	0.01	FLOAT	4-byte	2

Remarks

- All numbers are in little-endian format.
- Function code: 03.
- The measurement value is always available in the programmed physical unit.

9 Configuration



To change any settings on the S 418, please download and install the service App **S4C-FS** which is available on the Google Play store or our Website. This App runs on any Android system with BlueTooth supported.

To be allowed to change settings, the App needs to scan the QR code on the calibration certificate at first. This ensures that only valid users can access the sensor settings. For more information about instructions, see the *S4C-FS Instruction and operation manual*.



ATTENTION!

Changes on the settings may lead to wrong measurement results! Contact manufacturer in case you are not familiar with the settings.

10 Data logging

The S 418 provides the data logger function to help you record and analyze data measured over time.

10.1 Features

Before you use the data logger, learn about how it works:

- You can use the Android App S4C-FS to enable or disable the data logger function and set a sampling rate as needed.
- By default the data logger is disabled. Once you enable the data logger, the S 418 starts logging data. Once you disable the data logger, the S 418 stops logging.
- The S 418 saves all sampled data records into one file. Each record includes a time stamp and all measurement data sampled at this time point, such as flow, consumption, pressure and temperature.
- The S 418 log file supports up to 5.6 million records due to its memory size, which is equivalent to 64-day data at the one-second sampling rate.
- When the S 418 runs out of memory, the new record will replace the oldest one.
- To read out the logs recorded in the S 418 memory, install S4A (1.1.2 or later versions), which is a specialized log analysis software from SUTO, on a Windows-based computer. Also, connect the PC with the S 418 through the USB port.
- Although data records are saved in one file in the S 418, S4A reads them out into multiple log files in the following situations:
 - When the sampling rate is changed, S4A reads out the data records into a different file.
 - When the S 418 stops logging (for example, poweroff) and resumes in less than 24 hours, S4A still reads out the data records into one file; However, if the time gap is larger than 24 hours, S4A reads out the new data records to a different file.
- S4A enables you to have a graphic view on measurement data recorded in a log file.

10.2 Operations

10.2.1 Logger settings

Control and configure the S 418 data logger through the S4C-FS App.

1. Install and launch the **S4C-FS** App.

For more information, see the *S4C-FS Instruction and Operation Manual*.

2. Access **Settings** > **Logger Settings** to perform all logger-related operations as listed below.

Parameter	Description
Logger Status	To start or stop the logger.
Start Date & Time	To view the time stamp of the first log recorded.
Stop Date & Time	To view the time stamp of the last log recorded.
Number of Samples	To view the number of log records in the S 418 data logger.
Sampling Rate(mm:ss)	To specify the sampling rate.

10.2.2 Log analysis and export

Use the S4A software to read, analyze and export the measurement data recorded in the S 418.

- Download the S4A software from Support > Downloads > Apps on the SUTO Website (<u>http://www.suto-itec.com</u>).
- 2. Install the software by double clicking the EXE file.
- 3. Launch the software.
- 4. Click the **Detect** menu to detect and build the communication with the S 418.
- 5. Click the **Read** menu to read out data records logged during a time period that you specify.

Rec. Numbers	569		
Time period	10.16.2018 18:21:13 - 1	0.29.2018 11:11:33	
C Last hour) Last day 🔵 Last wee	C 🔾 Last month 💿 Time pe	riod
Which period you want to Date	select? Hour	Date	Hour
Which period you want to		Date Mon 10/29/2018 9	Hour 11

6. Click the **File** menu to have graphic views on measurement data in a log file; and if needed, to export this log file to the Excel or CSV format.

For more information about operations on S4A, click the **Help** button on the top right corner.

.SUO

11 Calibration

The sensor is calibrated ex work. The exact calibration date is printed on the certificate which is supplied together with the sensor. The accuracy of the sensor is regulated by the on site conditions, parameters like oil, high humidity or other impurities can affect the calibration and furthermore the accuracy. However we recommend to calibrate the instrument at least once per year. The calibration is excluded from the instruments warranty. For this please contact the manufacturer.

12 Disposal or waste



Electronic devices are recyclable material and do not belong in the household waste.

The sensor, the accessories and its packings must be disposed according to your local statutory requirements. The dispose can also be carried by the manufacturer of the product, for this please contact the manufacturer.

13 12 Warranty

SUTO provides a warranty for this product of 24 months covering the material and workmanship under the stated operating conditions from the date of delivery. Please report any findings immediately and within the warranty time. If faults occurring during the warranty time SUTO will repair or replace the defective unit, without charge for labour and material costs but there is a charge for other service such as transport and packing costs.

Excluded from this warranty is:

- Damage caused by:
 - Improper use and non-adherence to the instruction manual.
 - Use of unsuitable accessories.
 - External influences (e.g. damage caused by vibration, damage during transportation, excess heat or moisture).



The warranty is canceled:

- If the user opens the measurement instrument without a direct request written in this instruction manual.
- If repairs or modifications are undertaken by third parties or unauthorized persons.
- If the serial number has been changed, damaged or removed.

Other claims, especially those for damage occurring outside the instrument are not included unless responsibility is legally binding.

Warranty repairs do not extend the period of warranty.



ATTENTION!

Batteries have a reduced warranty time of 12 month.

14 Appendix A Specifications

14.1 Flow ranges

Flow ranges in sl/min of **air** at ISO 1217: 20°C and 1000 mbar:

	DN8	DN15	DN20	DN25	
Size numbering*	0,5	1,6	2, 7	3, 8	
Standard range (S)	250	1000	2000	3500	
Low range (L)	50	200	400	700	
* Indicates the last digit in the S 418 order number. For more details, see the <i>Order Table</i> on the next page.					

Flow ranges in sl/min of N_2 at 0°C and 1013.25 mbar:

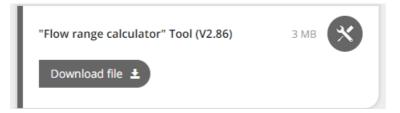
	DN8	DN15	DN20	DN25
Size numbering*	0, 5	1, 6	2, 7	3, 8
Standard range (S)	222	890	1780	3110
Low range (L)	44.5	178	356	622

Flow ranges in sl/min of **O**₂ at 0°C and 1013.25 mbar:

	DN8	DN15	DN20	DN25
Size numbering*	0, 5	1,6	2, 7	3, 8
Standard range (S)	238	953	1907	3337
Low range (L)	47.7	191	381	667

ATTENTION: Oil and grease free cleaning is required.

Tip: To determine measuring range for other gases, you can use our toll "Flow range calculator" which is available for download on our Website.



SUO

	Order Table						
Order no.	Size	Range	Output	Gas 1	Gas 2	Description	
S695 418						S 418, thermal mass flow meter, 1.5% o.RDG., 24 VDC	
	0					DN8 G inner thread	
	1					DN15 G inner thread	
	2					DN20 G inner thread	
	3					DN25 G inner thread	
	5					DN8 G inner thread, inc. pressure	
	6					DN15 G inner thread, inc. pressure	
	7					DN20 G inner thread, inc. pressure	
	8					DN25 G inner thread, inc. pressure	
	-	S				Standard range version of S 418	
A1453		L				Low range version of S 418	
A1455	A1455		А			Analogue 4 20 mA, pulse	
A1456		В			Digital Modbus/RTU		
A1457	A1457		С			Digital M-Bus	
				A-Z	B-Z	See gas table below	
A1459						S 418 with imperial units instead of SI units	

Gas table					
	Gas type				
A	Air				
В	CO2				
С	O2 (oil & grease free)				
D	N2				
E	N2O				
F	Ar				
G	Natural gas (mix ratio)				
Н	H ₂				
I	Other gas (specify)				
J	He (real gas calibration)				
К	C3H8				
Z	No gas				

14.2 Error codes

When an error code shows on the LED display, use the following table to identify the error cause.

Error code	Description			
Er. 01	Real time clock failure			
Er. 02	ADC failure			
Er. 04	EEPROM failure			
Er. 08	NADN flash failure			
Er. 10	Pressure sensor failure			
Er. 20	Flow sensor failure			
Er. 30	Temperature sensor failure			
Er. 40	Bluetooth failure			
Er. 50	Logger failure			

15 Appendix B Modbus communication example

03 (0x03) Read holding register

Request		Response		
Slave address	1 byte	Slave address	1 byte	
Function code	1 byte	Function code	1 byte	
Starting address Hi	1 byte	Byte count	1 byte	
Starting address Lo	1 byte	Register Hi	1 byte	
No. of points Hi	1 byte	Register Lo	1 byte	
No. of points Lo	1 byte	:	:	
CRC	2 bytes	Register Hi	1 byte	
		Register Lo	1 byte	
		CRC	2 bytes	

05 (0x05) Write single coil

Request		Response			
Slave address	ve address 1 byte		1 byte		
Function code	1 byte	Function code	1 byte		
Coil address Hi	1 byte	Coil address Hi	1 byte		
Coil address Lo 1 byte		Coil address Lo	1 byte		
Data Hi	1 byte	Data Hi	1 byte		
Data Lo	1 byte	Data L	1 byte		
CRC	RC 2 bytes		2 bytes		

.SUO

16 (0x10) Write multiple registers

Request		Response			
Slave address	1 byte	Slave address	1 byte		
Function code	1 byte	Function code	1 byte		
Starting address Hi	1 byte	Starting address Hi	1 byte		
Starting address Lo	1 byte	Starting address Lo	1 byte		
No. of registers Hi	1 byte	No. of registers Hi	1 byte		
No. of registers Lo	1 byte	No. of registers Lo	1 byte		
Byte count	1 byte	CRC	2 bytes		
Data Hi	1 byte				
Data Lo	1 byte				
:	:				
Data Hi	1 byte				
Data Lo	1 byte				
CRC	2 bytes				

17 (0x11) Report slave ID

Request		Response	Response			
Slave address	1 byte	Slave address	1 byte			
Function code	1 byte	Function code	1 byte			
CRC	2 bytes	Byte count	1 byte			
		Slave ID	2 bytes			
		Device run indicator	2 bytes			
		Product code	2 bytes			
		Product name	20 bytes			
		CRC	2 bytes			

16 Appendix C LRC and CRC calculation

LRC generation

The Longitudinal Redundancy Checking (LRC) field is one byte, containing an 8-bit binary value. The LRC value is calculated by the transmitting device, which appends the LRC to the message. The device that receives recalculates an LRC during receipt of the message, and compares the calculated value to the actual value it received in the LRC field. If the two values are not equal, an error results.

The LRC is calculated by adding together successive 8-bit bytes in the message, discarding any carries, and then two's complementing the result. The LRC is an 8-bit field, therefore each new addition of a character that would result in a value higher than 255 decimal simply 'rolls over' the field's value through zero. Because there is no ninth bit, the carry is discarded automatically.

A procedure for generating an LRC is:

- 1. Add all bytes in the message, excluding the starting 'colon' and ending CRLF. Add them into an 8-bit field, so that carries will be discarded.
- 2. Subtract the final field value from FF hex (all 1's) to produce the ones-complement.
- 3. Add 1 to produce the twos-complement.

Placing the LRC into the Message

When the 8-bit LRC (2 ASCII characters) is transmitted in the message, the high-order character will be transmitted first, followed by the loworder character. For example, if the LRC value is 61 hex (0110 0001):

Colon	Addr	Func	Data Count	Data	Data	Data	Data	LRC Hi	LRC Lo	CR	LF
								<i>``6″</i>	"1″		
								0x36	0x31		

Example: an example of a C language function performing LRC generation is shown below.

The function takes two arguments:

unsigned char *auchMsg; /* A pointer to the message buffer containing binary data */ /* to be used for generating the LRC, */

unsigned short usDataLen; /* The quantity of bytes in the message buffer.

LRC generation function

*/



static unsigned char LRC(unsigned char *auchMsg, unsigned short usDataLen)
{

```
unsigned char uchLRC = 0 ; /* LRC char initialized */
while (usDataLen--) /* pass through message buffer */
uchLRC += *auchMsg++ ; /* add buffer byte without carry */
return ((unsigned char)(-((char)uchLRC))) ; /* return twos complement */
```

```
}
```

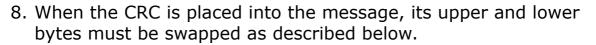
CRC generation

The **C**yclical **R**edundancy **C**hecking (CRC) field is two bytes, containing a 16-bit binary value. The CRC value is first generated by the transmitting device, which appends the CRC to the message. The device that receives recalculates a CRC during receipt of the message, and compares the calculated value to the actual value it received in the CRC field. If the two values are not equal, an error results.

There are many ways of calculating a CRC checksum. To ensure correct calculation, please refer to [Reference 1] Modbus over serial line, where detailed descriptions and programming examples are available. Even more information and programming examples in different programming languages can be found on: www.modbus.org searching for CRC.

Below is a short text description of how the CRC is calculated. This description is then followed by a C programming example.

- 1. Load a 16-bit register with FFFF hex (all 1's). Call this the CRC register.
- 2. Exclusive OR the first 8-bit byte of the message with the low-order byte of the 16-bit CRC register, putting the result in the CRC register.
- 3. Shift the CRC register one bit to the right (toward the LSB), zerofilling the MSB. Extract and examine the LSB.
- 4. (If the LSB was 0): Repeat step 3 (another shift). (If the LSB was 1): Exclusive OR the CRC register with the polynomial value 0xA001 (1010 0000 0000 0001).
- 5. Repeat steps 3 and 4 until 8 shifts have been performed. When this is done, a complete 8-bit byte will have been processed.
- 6. Repeat steps 2 through 5 for the next 8-bit byte of the message. Continue doing this until all bytes have been processed.
- 7. The final content of the CRC register is the CRC value.



Placing the CRC into the message

When the 16-bit CRC (two 8-bit bytes) is transmitted in the message, the low-order byte will be transmitted first, followed by the high-order byte.

For example, if the CRC value is 1241 hex (0001 0010 0100 0001):

Addr	Func	Data count	Data	Data	Data	CRC Lo	CRC Hi
						0x41	0x12

High-order byte table

/* Table of CRC values for high-order byte */ static unsigned char auchCRCHi[] = { 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81, 0x40, 0x01, 0xC0, 0x80, 0x41, 0x01, 0xC0, 0x80, 0x41, 0x00, 0xC1, 0x81,0x40 };

Low-order byte table

/* Table of CRC values for low-order byte */ static char auchCRCLo[] = { 0x00, 0xC0, 0xC1, 0x01, 0xC3, 0x03, 0x02, 0xC2, 0xC6, 0x06, 0x07, 0xC7, 0x05, 0xC5, 0xC4, 0x04, 0xCC, 0x0C, 0x0D, 0xCD, 0x0F, 0xCF, 0xCE, 0x0E, 0x0A, 0xCA, 0xCB, 0x0B, 0xC9, 0x09, 0x08, 0xC8, 0xD8, 0x18, 0x19, 0xD9, 0x1B, 0xDB, 0xDA, 0x1A, 0x1E, 0xDE, 0xDF, 0x1F, 0xDD, 0x1D, 0x1C, 0xDC, 0x14, 0xD4, 0xD5, 0x15, 0xD7, 0x17, 0x16, 0xD6, 0xD2, 0x12, 0x13, 0xD3, 0x11, 0xD1, 0xD0, 0x10, 0xF0, 0x30, 0x31, 0xF1, 0x33, 0xF3, 0xF2, 0x32, 0x36, 0xF6, 0xF7, 0x37, 0xF5, 0x35, 0x34, 0xF4, 0x3C, 0xFC, 0xFD, 0x3D, 0xFF, 0x3F, 0x3E, 0xFE, 0xFA, 0x3A, 0x3B,

SUO

0xFB, 0x39, 0xF9, 0xF8, 0x38, 0x28, 0xE8, 0xE9, 0x29, 0xEB, 0x2B, 0x2A, 0xEA, 0xEE, 0x2E, 0x2F, 0xEF, 0x2D, 0xED, 0xEC, 0x2C, 0xE4, 0x24, 0x25, 0xE5, 0x27, 0xE7, 0xE6, 0x26, 0x22, 0xE2, 0xE3, 0x23, 0xE1, 0x21, 0x20, 0xE0, 0xA0, 0x60, 0x61, 0xA1, 0x63, 0xA3, 0xA2, 0x62, 0x66, 0xA6, 0xA7, 0x67, 0xA5, 0x65, 0x64, 0xA4, 0x6C, 0xAC, 0xAD, 0x6D, 0xAF, 0x6F, 0x6E, 0xAE, 0xAA, 0x6A, 0x6B, 0xAB, 0x69, 0xA9, 0xA8, 0x68, 0x78, 0xB8, 0xB9, 0x79, 0xBB, 0x7B, 0x7A, 0xBA, 0xBE, 0x7E, 0x7F, 0xBF, 0x7D, 0xBD, 0xBC, 0x7C, 0xB4, 0x74, 0x75, 0xB5, 0x77, 0xB7, 0xB6, 0x76, 0x72, 0xB2, 0xB3, 0x73, 0xB1, 0x71, 0x70, 0xB0, 0x50, 0x90, 0x91, 0x51, 0x93, 0x53, 0x52, 0x92, 0x96, 0x56, 0x57, 0x97, 0x55, 0x95, 0x94, 0x54, 0x9C, 0x5C, 0x5D, 0x9D, 0x5F, 0x9F, 0x9E, 0x5E, 0x5A, 0x9A, 0x9B, 0x5B, 0x99, 0x59, 0x58, 0x98, 0x88, 0x48, 0x49, 0x89, 0x4B, 0x8B, 0x8A, 0x4A, 0x4E, 0x8E, 0x8F, 0x4F, 0x8D, 0x4D, 0x4C, 0x8C, 0x44, 0x84, 0x85, 0x45, 0x87, 0x47, 0x46, 0x86, 0x82, 0x42, 0x43, 0x83, 0x41, 0x81, 0x80, 0x40 }; unsigned short CRC16(unsigned char *puchMsg, unsigned short usDataLen){ unsigned char uchCRCHi = 0xFF; /* high byte of CRC initialized */ /* low byte of CRC initialized unsigned char uchCRCLo = 0xFF; */ unsigned uIndex ; /* will index into CRC lookup table */ while(usDataLen-) /* pass through message buffer */ { uIndex = uchCRCHi ^ *puchMsg++ ; /* calculate the CRC */ uchCRCHi = uchCRCLo ^ auchCRCHi[uIndex] ; uchCRCLo = auchCRCLo[uIndex]; } return (unsigned short int)((uchCRCHi << 8) | uchCRCLo); }







SUTO iTEC GmbH

Werkstr. 2 79426 Buggingen Germany

Tel: +49 (0) 7631 936889-0 Fax: +49 (0) 7631 936889-19 Email: <u>sales@suto-itec.com</u> Website: <u>http://www.suto-itec.com</u>

SUTO iTEC (ASIA) Co., Ltd.

Room 10, 6/F, Block B, Cambridge Plaza 188 San Wan Road, Sheung Shui, N.T. Hong Kong

Tel: +852 2328 9782 Fax: +852 2671 3863 Email: <u>sales@suto-itec.asia</u> Website: <u>http://www.suto-itec.com</u>

All rights reserved $\ensuremath{\mathbb{C}}$

Modifications and errors reserved. S418_im_en_2018-6