





TEST REPORT

No. I18D00140-SAR01

For

Client: Wingtech Group (Hong Kong) Limited

Production: arrows hello AT01

Model Name: AT01

FCC ID: 2APXW-YDE022

Hardware Version: 81119_1_10

Software Version: YD_AT01_1.0.1(SW_Q81119BA1_V001_M1

Issued date: 2018-8-30

Note:

The test results in this test report relate only to the devices specified in this report. This report shall not be reproduced except in full without the written approval of ECIT Shanghai.

Test Laboratory:

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Revision Version

Reported No.: I18D00140-SAR01

Report Number	Revision	Date Memo	
I18D00140-SAR01	00	2018-8-30	Initial creation of test report

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1. Test Laboratory

1.1. Testing Location

Company Name:	ECIT Shanghai, East China Institute of Telecommunications				
Address:	7-8F, G Area,No. 668, Beijing East Road, Huangpu District, Shanghai, P. R. China				
Postal Code:	200001				
Telephone:	(+86)-021-63843300				
Fax:	(+86)-021-63843301				
IC SAR Teat Site Registration Number:	10766A				

1.2. Testing Environment

Normal Temperature:	18-25℃
Relative Humidity:	25-75%
Ambient noise & Reflection:	< 0.012 W/kg

1.3. Project Data

Project Leader:	Chen Minfei
Testing Start Date:	2018-8-28
Testing End Date:	2018-8-28

1.4. Signature

Yan Hang (Prepared this test report) Fu Erliang (Reviewed this test report)

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Zheng Zhongbin (Approved this test report)



2. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for AT01 are as follows .

Table 2.1: Max. Reported SAR (1g)

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Band	Position/Distance	SAR 1g (W/Kg)
2.4G Wi-Fi	Body(5mm)	0.435

The SAR values found for the Mobile Phone are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1g tissue according to the ANSI C95.1-1999.



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3. Client Information

3.1. Applicant Information

Company Name: Wingtech Group (Hong Kong) Limited

Address: Flat/RM 1903, 19/F, Podium Plaza 5 Hanoi Road, Tsim Sha Tsui Kowloon,

Hong Kong

Email: sharui@wingtech.com

3.2. Manufacturer Information

Company Name: Wingtech Group (Hong Kong) Limited

Address: Flat/RM 1903, 19/F, Podium Plaza 5 Hanoi Road, Tsim Sha Tsui Kowloon,

Hong Kong

Email: sharui@wingtech.com

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4. Equipment Under Test (EUT) and Ancillary Equipment (AE)

4.1. About EUT

Description:	arrows hello AT01
Model name:	AT01
Operation Model(s):	WIFI2450,BT
Tx Frequency:	2412- 2462 MHz (Wi-Fi) 2400-2483.5 MHz (BT)
Test device Production information:	Production unit
Device type:	Portable device
Antenna type:	Inner antenna
Accessories/Body-worn	N/A
configurations:	
Dimensions:	11.7cm×4.8 cmx1.4cm
Hotspot Mode:	N/A
FCC ID:	2APXW-YDE022

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4.2. Internal Identification of EUT used during the test

EUT ID*	SN or IMEI	HW Version	SW Version	Receive Date
N12	L2180616009596	81119_1_10	YD_AT01_1.0.1(SW_Q81119B A1_V001_M1	2018-8-2

^{*}EUT ID: is used to identify the test sample in the lab internally.

4.3. Internal Identification of AE used during the test

AE ID*	Description	Model	SN	Manufacturer
N/A	N/A	N/A	N/A	N/A

^{*}AE ID: is used to identify the test sample in the lab internally.

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5. TEST METHODOLOGY

5.1. Applicable Limit Regulations

ANSI C95.1–1999:IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.

FCC 47 CFR Part 2 (2.1093): Radiofrequency radiation exposure evaluation: portable devices. It specifies the maximum exposure limit of 1.6 W/kg as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

5.2. Applicable Measurement Standards

IEEE 1528–2013: Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Experimental Techniques.

KDB248227 D01 802 11 Wi-Fi SAR v02r02: SAR measurement procedures for 802.112abg transmitters. **KDB447498 D01 General RF Exposure Guidance v06:**Mobile and Portable Devices RF Exposure Procedures and Equipment Authorization Policies.

KDB865664 D01 SAR Measurement 100 MHz to 6 GHz v01r04:SAR Measurement Requirements for 100 MHz to 6 GHz

KDB865664 D02 RF Exposure Reporting v01r02:provides general reporting requirements as well as certain specific information required to support MPE and SAR compliance.

NOTE: KDB is not in A2LA Scope List.

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6. Specific Absorption Rate (SAR)

6.1. Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

6.2. SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt}(\frac{dW}{dm}) = \frac{d}{dt}(\frac{dW}{\rho dv})$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = c(\frac{\delta T}{\delta t})$$

Where: C is the specific head capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

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7. Tissue Simulating Liquids

7.1. Targets for tissue simulating liquid

Table 7.1: Targets for tissue simulating liquid

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Frequency(MHz)	Liquid Type	Conductivity(σ)	± 5% Range	Permittivity(ε)	± 5% Range
2450	Body	1.95	1.85~2.05	52.7	50.1~55.3

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7.2. Dielectric Performance

Table 7.2: Dielectric Performance of Tissue Simulating Liquid

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Measurement Value								
Liquid Tem	Liquid Temperature: 22.5 $^{\circ}\mathrm{C}$							
Туре	Frequency	Permittivity ε	Drift (%)	Conductivity σ	Drift (%)	Test Date		
Body	2450 MHz	52.830	0.25%	1.900	-2.56%	2018-8-28		

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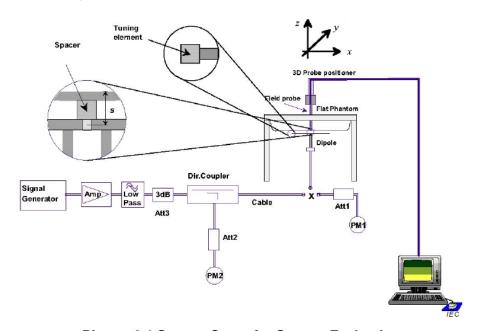


8. System verification

8.1. System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

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Picture 8.1 System Setup for System Evaluation



Picture 8.2 Photo of Dipole Setup

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8.2. System Verification

SAR system verification is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device.

Table 8.1: System Verification of Body

Verification	Results							
Input power level: 1W								
	Target value (W/kg)		Measured value (W/kg)		Devi	ation	Toot	
Frequency	10 g	1 g	10 g	1 g	10 g	1 g	Test date	
	Average	Average	Average	Average	Average	Average	uale	
2450 MHz	24.7	53.1	24.2	53.6	-2.02%	0.94%	2018-8-28	

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9. Measurement Procedures

9.1. Tests to be performed

In order to determine the highest value of the peak spatial-average SAR of a handset, all device positions, configurations and operational modes shall be tested for each frequency band according to steps 1 to 3 below. A flowchart of the test process is shown in Picture 11.1.

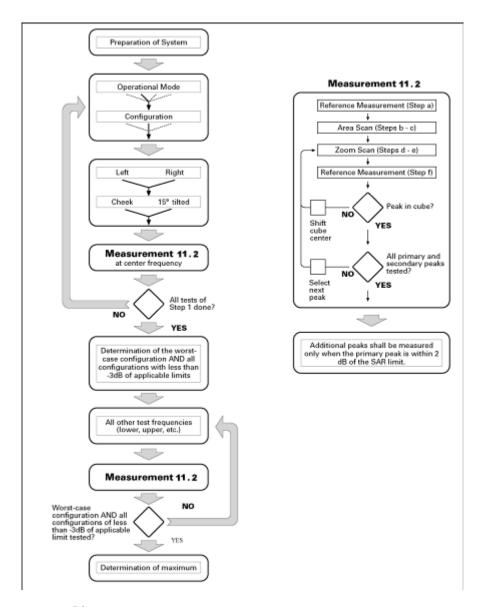
Step 1: The tests described in 11.2 shall be performed at the channel that is closest to the centre of the transmit frequency band (f_c) for:

- a) all device positions (cheek and tilt, for both left and right sides of the SAM phantom, as described in Chapter 8),
- b) all configurations for each device position in a), e.g., antenna extended and retracted, and
- c) all operational modes, e.g., analogue and digital, for each device position in a) and configuration in b) in each frequency band.

If more than three frequencies need to be tested according to 11.1 (i.e., $N_c > 3$), then all frequencies, configurations and modes shall be tested for all of the above test conditions. Step 2: For the condition providing highest peak spatial-average SAR determined in Step 1, perform all tests described in 11.2 at all other test frequencies, i.e., lowest and highest frequencies. In addition, for all other conditions (device position, configuration and operational mode) where the peak spatial-average SAR value determined in Step 1 is within 3 dB of the applicable SAR limit, it is recommended that all other test frequencies shall be tested as well.

Step 3: Examine all data to determine the highest value of the peak spatial-average SAR found in Steps 1 to 2.





Picture 9.1Block diagram of the tests to be performed

9.2. General Measurement Procedure

The following procedure shall be performed for each of the test conditions (see Picture 11.1) described in 11.1:

- a) Measure the local SAR at a test point within 8 mm or less in the normal direction from the inner surface of the phantom.
- b) Measure the two-dimensional SAR distribution within the phantom (area scan procedure). The boundary of the measurement area shall not be closer than 20 mm from the phantom side walls. The distance between the measurement points should enable the detection of the location of local maximum with an accuracy of better than half the linear dimension of the tissue cube after interpolation. A maximum grip spacing of 20 mm

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for frequencies below 3 GHz and (60/f [GHz]) mm for frequencies of 3GHz and greater is recommended. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and δ In(2)/2 mm for frequencies of 3 GHz and greater, where δ is the plane wave skin depth and In(x) is the natural logarithm. The maximum variation of the sensor-phantom surface shall be ± 1 mm for frequencies below 3 GHz and ± 0.5 mm for frequencies of 3 GHz and greater. At all measurement points the angle of the probe with respect to the line normal to the surface should be less than 5° . If this cannot be achieved for a measurement distance to the phantom inner surface shorter than the probe diameter, additional uncertainty evaluation is needed.

- c) From the scanned SAR distribution, identify the position of the maximum SAR value, in addition identify the positions of any local maxima with SAR values within 2 dB of the maximum value that are not within the zoom-scan volume; additional peaks shall be measured only when the primary peak is within 2 dB of the SAR limit. This is consistent with the 2 dB threshold already stated;
- d) Measure the three-dimensional SAR distribution at the local maxima locations identified in step c). The horizontal grid step shall be (24/f[GHz]) mm or less but not more than 8 mm. The minimum zoom size of 30 mm by 30 mm and 30 mm for frequencies below 3 GHz. For higher frequencies, the minimum zoom size of 22 mm by 22 mm and 22 mm. The grip step in the vertical direction shall be (8-f[GHz]) mm or less but not more than 5 mm, if uniform spacing is used. If variable spacing is used in the vertical direction, the maximum spacing between the two closest measured points to the phantom shell shall be (12 / f[GHz]) mm or less but not more than 4 mm, and the spacing between father points shall increase by an incremental factor not exceeding 1.5. When variable spacing is used, extrapolation routines shall be tested with the same spacing as used in measurements. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\delta \ln(2)/2$ mm for frequencies of 3 GHz and greater, where δ is the plane wave skin depth and ln(x) is the natural logarithm. Separate grids shall be centered on each of the local SAR maxima found in step c). Uncertainties due to field distortion between the media boundary and the dielectric enclosure of the probe should also be minimized, which is achieved is the distance between the phantom surface and physical tip of the probe is larger than probe tip diameter. Other methods may utilize correction procedures for these boundary effects that enable high precision measurements closer than half the probe diameter. For all measurement points, the angle of the probe with respect to the

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flat phantom surface shall be less than 5° . If this cannot be achieved an additional uncertainty evaluation is needed.

e) Use post processing(e.g. interpolation and extrapolation) procedures to determine the local SAR values at the spatial resolution needed for mass averaging.

9.3. Bluetooth & Wi-Fi Measurement Procedures for SAR

Normal network operating configurations are not suitable for measuring the SAR of 802.11 transmitters in general. Unpredictable fluctuations in network traffic and antenna diversity conditions can introduce undesirable variations in SAR results. The SAR for these devices should be measured using chipset based test mode software to ensure that the results are consistent and reliable.

Chipset based test mode software is hardware dependent and generally varies among manufacturers. The device operating parameters established in a test mode for SAR measurements must be identical to those programmed in production units, including output power levels, amplifier gain settings and other RF performance tuning parameters. The test frequencies should correspond to actual channel frequencies defined for domestic use. SAR for devices with switched diversity should be measured with only one antenna transmitting at a time during each SAR measurement, according to a fixed modulation and data rate. The same data pattern should be used for all measurements.

9.4. Power Drift

To control the output power stability during the SAR test, DASY4 system calculates the power drift by measuring the E-field at the same location at the beginning and at the end of the measurement for each test position. These drift values can be found in Section 13 labeled as: (Power Drift [dB]). This ensures that the power drift during one measurement is within 5%.



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10. Area Scan Based 1-g SAR

10.1 Requirement of KDB

According to the KDB447498 D01 v06, when the implementation is based the specific polynomial fit algorithm as presented at the 29th Bioelectromagnetics Society meeting (2007) and the estimated 1-g SAR is $\leq 1.2 \, \text{W/kg}$, a zoom scan measurement is not required provided it is also not needed for any other purpose; for example, if the peak SAR location required fo simultaneous transmission SAR test exclusion can be determined accurately by the SAR system or manually to discriminate between distinctive peaks and scattered noisy SAR distributions from area scans.

There must not be any warning or alert messages due to various measurement concerns identified by the SAR system; for example, noise in measurements, peaks too close to scan boundary, peaks are too sharp, spatial resolution and uncertainty issues etc. The SAR system verification must also demonstrate that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR (See Annex B). When all the SAR results for each exposure condition in a frequency band and wireless mode are based on estimated 1-g SAR, the 1-g SAR for the highest SAR configuration must be determined by a zoom scan.

10.2 Fast SAR Algorithms

The approach is based on the area scan measurement applying a frequency dependent attenuation parameter. This attenuation parameter was empirically determined by analyzing a large number of phones. The MOTOROLA FAST SAR was developed and validated by the MOTOROLA Research Group in Ft. Lauderdale.

In the initial study, an approximation algorithm based on Linear fit was developed. The accuracy of the algorithm has been demonstrated across a broad frequency range (136-2450 MHz) and for both 1- and 10-g averaged SAR using a sample of 264 SAR measurements from 55 wireless handsets. For the sample size studied, the root-mean-squared errors of the algorithm are 1.2% and 5.8% for 1- and 10-g averaged SAR, respectively. The paper describing the algorithm in detail is expected to be published in August 2004 within the Special Issue of Transactions on MTT. In the second step, the same research group optimized the fitting algorithm to an Polynomial fit whereby the frequency validity was extended to cover the range 30-6000MHz. Details of this study can be found in the BEMS 2007 Proceedings. Both algorithms are implemented in DASY software.



11. Conducted Output Power

Manufacturing tolerance

Table 11.9: WiFi

WiFi 802.11b 2.4G									
Channel	Channel 1	Channel 6	Channel 11						
Maximum Target Value (dBm)	16	16.5	17						
WiFi 802.11g 2.4G									
Channel	Channel 1	Channel 6	Channel 11						
Maximum Target Value (dBm)	17	17	18						
	WiFi 802.11n 20M 2.4G								
Channel	Channel 1	Channel 6	Channel 11						
Maximum Target Value (dBm)	° 17		18						

Table 11.10: Bluetooth

Bluetooth								
Channel	Channel 0	Channel 39	Channel 78					
Maximum Target Value (dBm)	6	7.5	5.5					

Table 11.11: Bluetooth 4.0

Bluetooth								
Channel	Channel 0	Channel 19	Channel 39					
Maximum Target Value (dBm)	1	1	1					

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11.1. Wi-Fi and BT Measurement result

Table 11.18: The conducted power for Bluetooth

GFSK									
Channel	Ch0 (2402 MHz)	Ch39 (2441MHz)	CH78 (2480MHz)						
Highest Power (dBm)	est Power (dBm) 5.28		4.677						
π/4 DQPSK									
Channel	Ch0 (2402 MHz)	Ch39 (2441MHz)	CH78 (2480MHz)						
Highest Power (dBm)	5.631	7.089	5.028						
8DPSK	8DPSK								
Channel	Ch0 (2402 MHz)	Ch39 (2441MHz)	CH78 (2480MHz)						
Highest Power (dBm) 5.914		7.34	5.257						

Table 11.19: The conducted power for Bluetooth4.0

GFSK								
Channel	Ch0 (2402 MHz)	Ch19 (2440MHz)	CH39 (2480MHz)					
Highest Power (dBm)	-0.878	0.686	-1.336					

NOTE: According to KDB447498 D01 BT standalone SAR are not required, because maximum average output power is less than 10mW.

The default power measurement procedures are:

- a) Power must be measured at each transmit antenna port according to the DSSS and OFDM transmission configurations in each standalone and aggregated frequency band.
- b) Power measurement is required for the transmission mode configuration with the highest maximum output power specified for production units.
- 1) When the same highest maximum output power specification applies to multiple transmission modes, the largest channel bandwidth configuration with the lowest order modulation and lowest data rate is measured.
- 2) When the same highest maximum output power is specified for multiple largest channel bandwidth configurations with the same lowest order modulation or lowest order modulation and lowest data rate, power measurement is required for all equivalent 802.11 configurations with the same maximum output power.
- c) For each transmission mode configuration, power must be measured for the highest and lowest channels; and at the mid-band channel(s) when there are at least 3 channels. For configurations with multiple mid-band channels, due to an even number of channels, both channels should be measured.

During WLAN SAR testing EUT is configured with the WLAN continuous TX tool, and the transmission duty factor was monitored on the spectrum analyzer with zero-span setting, the duty cycle is 100%.



Table 11.20: The average conducted power for WiFi

Mode	Channel	Frequence	Average power(dBm)
	1	2412 MHZ	15.12
802.11 b	6	2437 MHZ	16.05
	11	2462 MHZ	16.74
	1	2412 MHZ	16.30
802.11 g	6	2437 MHZ	16.75
	11	2462 MHZ	17.76
902.41 n	1	2412 MHZ	16.39
802.11 n 20M	6	2437 MHZ	16.44
ZUIVI	11	2462 MHZ	17.87

2.4 GHz 802.11g/n OFDM SAR Test Exclusion Requirements

When SAR measurement is required for 2.4 GHz 802.11g/n OFDM configurations, the measurement and test reduction procedures for OFDM are applied. SAR is not required for the following 2.4 GHz OFDM conditions.

- a) When KDB Publication 447498 D01 SAR test exclusion applies to the OFDM configuration.
- b) When the highest *reported* SAR for DSSS is adjusted by the ratio of OFDM to DSSS specified maximum output power and the adjusted SAR is $\leq 1.2 \text{ W/kg}$.

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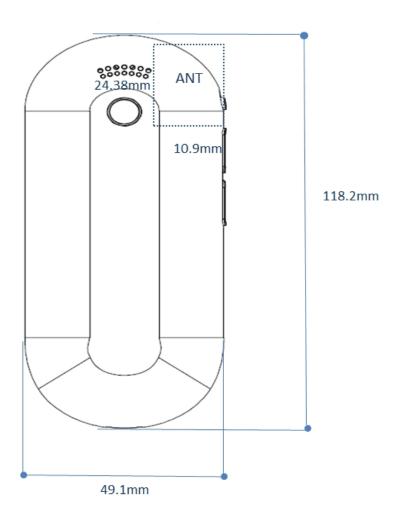
12. Simultaneous TX SAR Considerations

12.1. Introduction

The following procedures adopted from "FCC SAR Considerations for Cell Phones with Multiple Transmitters" are applicable to handsets with built-in unlicensed transmitters such as 802.11 a/b/g and Bluetooth devices which may simultaneously transmit with the licensed transmitter.

For this device, the BT and Wi-Fi can transmit simultaneous with other transmitters.

12.2. Transmit Antenna Separation Distances



Picture 12.1 Antenna Locations

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12.3. Standalone SAR Test Exclusion Considerations

Standalone 1-g head or body SAR evaluation by measurement or numerical simulation is not required when the corresponding SAR Exclusion Threshold condition, listed below, is satisfied.

The 1-g SAR test exclusion threshold for 100 MHz to 6 GHz at test separation distances≤ 50 mm are determined by:

[(max. power of channel, including tune-up tolerance, mW)/(min. test separation distance, mm)] .

 $[\sqrt{f(GHz)}] \le 3.0$ for 1-g SAR, where

- f(GHz) is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation
- The result is rounded to one decimal place for comparison

According to the KDB447498 appendix A, the SAR test exclusion threshold for 2450MHz at 5mm test separation distances is 10mW.

Based on the above equation, Bluetooth SAR was not required:

Evaluation=1.771 < 3.0

Based on the above equation, WiFi SAR was required:

Evaluation=19.8>3.0

12.4. SAR Measurement Positions

According to the KDB941225 D06 Hot Spot SAR v01, the edges with less than 2.5 cm distance to the antennas need to be tested for SAR.

SAR Measurement Positions								
Antenna	Phantom	Ground	Left	Right	Тор	Bottom		
Mode								
WLAN	Yes	Yes	No	Yes	Yes	No		



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13. SAR Test Result

Table 13.1: Duty Cycle

Duty Cycle					
WiFi 2450	1:1				

Table 13.16: SAR Values (Wi-Fi 802.11b - Body)

						•		• • • • • • • • • • • • • • • • • • • •			
Frequency Mode Test	Figure Measured	Measured	Maximum	Scaling	Duty	Measured	Reported	Power			
	1	(number of	Positio		average	allowed		Cycle	SAR(1g)	SAR(1g)	Drift
MHz	Ch.	timeslots)	n	No.	power(dBm)	Power (dBm	factor	factor	(W/kg)	(W/kg)	(dB)
2462	11	Wi-Fi 2450	Phantom	Fig.1	16.74	17	1.062	1:1	0.410	0.435	0.04
2462	11	Wi-Fi 2450	Ground	/	16.74	17	1.062	1:1	0.406	0.431	0.11
2462	11	Wi-Fi 2450	Left	/	16.74	17	1.062	1:1	0.055	0.058	0.08
2462	11	Wi-Fi 2450	Right	/	16.74	17	1.062	1:1	0.252	0.268	0.11
2462	11	Wi-Fi 2450	Тор	/	16.74	17	1.062	1:1	0.118	0.125	0.12
2462	11	Wi-Fi 2450	Bottom	/	16.74	17	1.062	1:1	0.027	0.029	-0.01

Note: The distance between the EUT and the phantom bottom is 5mm.

Remark: SAR is not required for the following 2.4 GHz OFDM conditions.

- 1) When KDB Publication 447498 SAR test exclusion applies to the OFDM configuration.
- 2) When the highest reported SAR for DSSS is adjusted by the ratio of OFDM to DSSS specified maximum output power and the adjusted SAR is ≤ 1.2 W/kg.

The highest reported SAR for DSSS is adjusted by the ratio of OFDM to DSSS specified maximum output power and the adjusted SAR is ≤ 1.2 W/kg. So 2.4 GHz OFDM mode is not required.

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14. Evaluation of Simultaneous

The EUT only one TX antenna, So simultaneous transmission SAR evaluation is not required.

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15. SAR Measurement Variability

SAR measurement variability must be assessed for each frequency band, which is determined by the SAR probe calibration point and tissue-equivalent medium used for the device measurements. When both head and body tissue-equivalent media are required for SAR measurements in a frequency band, the variability measurement procedures should be applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium. The following procedures are applied to determine if repeated measurements are required.

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg ($\sim 10\%$ from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

Table 15.1: SAR Measurement Variability for Body Value (1g)

Frequency		Frequency		Original SAR	First Repeated	The Ratio
MHz	Ch.	Configuration	Position	(W/kg)	SAR (W/kg)	The Ratio
-	-	-	-	-	-	-

Note: According to the KDB 865664 D01repeated measurement is not required when the original highest measured SAR is < 0.8 W/kg.

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16. Measurement Uncertainty

Measurement uncertainty for 750 MHz to 3 GHz averaged over 1 gram

Measurement uncertainty for 750 Minz to 5 Ghz averaged over 1 grain										
Uncertainty Component	Uncertainty	Prob.	Div.	C _{i (1g)}	Std. Unc. (1-g)	V _i or Veff				
Measurement System	Measurement System									
Probe Calibration (k=1)	5.4	Normal	2	1	5.40	∞				
Probe Isotropy	4.70	Rectangular	√3	0.7	1.90	∞				
Modulation Response	2.40	Rectangular	√3	1	1.39	∞				
Hemispherical Isotropy	2.60	Rectangular	√3	0.7	1.05	∞				
Boundary Effect	1.00	Rectangular	√3	1	0.58	∞				
Linearity	4.70	Rectangular	√3	1	2.71	∞				
System Detection Limit	1.00	Rectangular	√3	1	0.58	∞				
Readout Electronics	0.30	Normal	1	1	0.30	∞				
Response Time	0.80	Rectangular	√3	1	0.46	∞				
Integration Time	2.60	Rectangular	√3	1	1.50	∞				
RF Ambient Noise	0.00	Rectangular	√3	1	0.00	∞				
RF Ambient Reflections	0.00	Rectangular	√3	1	0.00	∞				
Probe Positioner	0.40	Rectangular	√3	1	0.23	∞				
Probe Positioning	2.90	Rectangular	√3	1	1.67	∞				
Post-processing	1.00	Rectangular	√3	1	0.58	∞				
Test sample Related										
Test sample Positioning	1.2	Normal	1	1	1.2	5				
Device Holder Uncertainty	3.2	Normal	1	1	3.2	71				
Power drift	5	Rectangular	√3	1	2.89	∞				
Power Scaling	0	Rectangular	√3	1	0.00	∞				
Phantom and Tissue Parame	ters									
Phantom Uncertainty	4	Rectangular	√3	1	2.31	∞				
SAR correction	1.9	Rectangular	√3	1	1.10	∞				
Liquid Conductivity (meas)	4.19	Rectangular	1	0.78	3.27	∞				
Liquid Permittivity (meas)	4.4	Rectangular	1	0.26	1.14	∞				
Temp. unc Conductivity	0.18	Rectangular	√3	0.78	0.08	∞				
Temp. unc Permittivity	0.54	Rectangular	√3	0.23	0.07	∞				
Combined Std. Uncertainty		RSS			9.39					
Expanded STD Uncertainty		<i>k</i> =2			18. 77%					

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System check uncertainty for 750 MHz to 3 GHz averaged over 1 gram								
Uncertainty Component	Uncertainty	Prob.	Div.	C _{i (1g)}	Std. Unc. (1-g)	V _i or Veff		
Measurement System								
Probe Calibration (k=1)	5.40	Normal	1	1	5.40	∞		
Probe Isotropy	4.70	Rectangular	√3	0.7	1.90	8		
Modulation Response	2.40	Rectangular	√3	1	1.39	∞		
Hemispherical Isotropy	2.60	Rectangular	√3	0.7	1.05	∞		
Boundary Effect	1.00	Rectangular	√3	1	0.58	∞		
Linearity	4.70	Rectangular	√3	1	2.71	∞		
System Detection Limit	1.00	Rectangular	√3	1	0.58	∞		
Readout Electronics	0.30	Normal	1	1	0.30	∞		
Response Time	0.80	Rectangular	√3	1	0.46	∞		
Integration Time	2.60	Rectangular	√3	1	1.50	∞		
RF Ambient Noise	0.00	Rectangular	√3	1	0.00	∞		
RF Ambient Reflections	0.00	Rectangular	√3	1	0.00	∞		
Probe Positioner	0.40	Rectangular	√3	1	0.23	∞		
Probe Positioning	2.90	Rectangular	√3	1	1.67	∞		
Post-processing	1.00	Rectangular	√3	1	0.58	∞		
Field source		-		•	1			
Deviation of the experimental source from numerical source	5.5	Normal	1	1	5.5	∞		
Source to liquid distance	2	Rectangular	√3	1	1.15	∞		
Power drift	5	Rectangular	√3	1	2.89	∞		
Phantom and Tissue Parame	ters			1		•		
Phantom Uncertainty	4	Rectangular	√3	1	2.31	∞		
SAR correction	1.9	Rectangular	√3	1	1.10	∞		
Liquid Conductivity (meas)	4.19	Normal	1	0.78	3.27	∞		
Liquid Permittivity (meas)	4.4	Normal	1	0.26	1.14	∞		
Temp. unc Conductivity	0.18	Rectangular	√3	0.78	0.08	∞		
Temp. unc Permittivity	0.54	Rectangular	√3	0.23	0.07	∞		
Combined Std. Uncertainty		RSS			10.39			
Expanded STD Uncertainty		<i>k</i> =2			20.79%			





17. Main Test Instrument

Table 17.1: List of Main Instruments

No.	Name	Туре	Serial Number	Calibration Date	Valid Period
01	Network analyzer	N5242A	MY51221755	Dec 25, 2017	1 year
02	Power meter	NRVD	102257		_
03 Power sensor	NRV-Z5	100241	May 11, 2017	1 year	
		100644			
04	Signal Generator	E4438C	MY49072044	May 11, 2017	1 Year
05	Amplifier	NTWPA-0086010F	12023024	No Calibration Requested	
06	Coupler	778D	MY4825551	May 11, 2017	1 year
07	BTS	E5515C	MY50266468	Dec 25, 2017	1 year
08	E-field Probe	ES3DV3	3252	Aug 31, 2017	1 year
09	DAE	SPEAG DAE4	1244	Dec 4,2017	1 year
10	Dipole Validation Kit	SPEAG D2450V2	858	Oct 30,2015	3 year

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ANNEX A. GRAPH RESULTS

Fig.1 WIFI 802.11 b Phantom Mode High

Date/Time: 2018/8/28

Electronics: DAE4 Sn1244

Medium parameters used: f = 2462 MHz; $\sigma = 1.915$ S/m; $\varepsilon_r = 52.789$; $\rho = 1000$

kg/m³

Ambient Temperature:22.5 ℃ Liquid Temperature:22.5 ℃

Communication System: Wifi 2450 2450MHz; Frequency: 2462 MHz; Duty Cycle:

1:1

Probe: ES3DV3 - SN3252ConvF(4.42, 4.42, 4.42); Calibrated: 8/31/2017

wifi 802.11 b Phantom Mode High/Area Scan (61x101x1):

Measurement grid: dx=10 mm, dy=10 mm

Maximum value of SAR (Measurement) = 0.418 W/kg

wifi 802.11 b Phantom Mode High/Zoom Scan (7x7x7)/Cube 0:

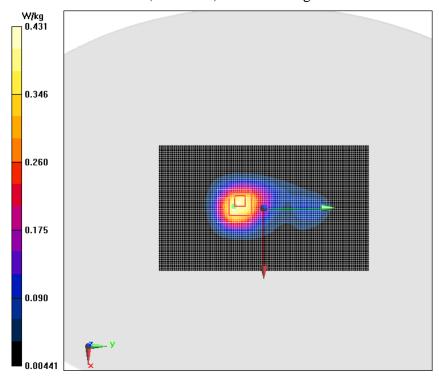
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 9.832 V/m; Power Drift = 0.04 dB

Peak SAR (extrapolated) = 0.786 W/kg

SAR(1 g) = 0.410 W/kg; SAR(10 g) = 0.217 W/kg

Maximum of SAR (measured) = 0.431 W/kg



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ANNEX B. SYSTEM VALIDATION RESULTS

Body 2450MHz

Date/Time: 2018/8/28 Electronics: DAE4 Sn1244

Medium parameters used: f = 2450 MHz; $\sigma = 1.9 \text{ S/m}$; $\varepsilon_r = 52.83$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature:22.5 ℃ Liquid Temperature:22.5 ℃

Communication System: CW 2450MHz; Frequency: 2450 MHz; Duty Cycle: 1:1

Probe: ES3DV3 - SN3252ConvF(4.42, 4.42, 4.42); Calibrated: 8/31/2017

System Validation/Area Scan (91x71x1):

Measurement grid: dx=10 mm, dy=10 mm

Maximum value of SAR (Measurement) = 16.3 W/kg

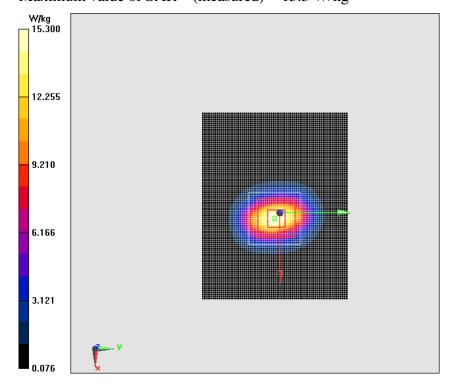
System Validation/Zoom Scan (7x7x7) (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 88.73 V/m; Power Drift = -0.15 dB

Peak SAR (extrapolated) = 28.6 W/kg

SAR(1 g) = 13.4 W/kg; SAR(10 g) = 6.05 W/kgMaximum value of SAR (measured) = 15.3 W/kg

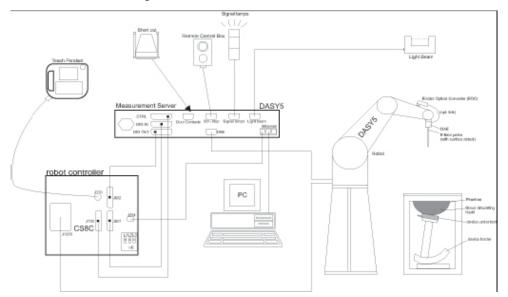




ANNEX C. SAR Measurement Setup

C.1. Measurement Set-up

The DASY5 system for performing compliance tests is illustrated above graphically. This system consists of the following items:



Picture C.1 SAR Lab Test Measurement Set-up

- A standard high precision 6-axis robot (Stäubli TX=RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy
 of the probe positioning.

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A computer running WinXP and the DASY5 software.



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- Remote control and teach pendant as well as additional circuitry for robot safety such as
- warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

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C.2. DASY5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY5 software reads the reflection durning a software approach and looks for the maximum using 2ndord curve fitting. The approach is stopped at reaching the maximum.

Probe Specifications:

Model: ES3DV3,EX3DV4

Frequency 10MHz — 6GHz(EX3DV4) Range: 10MHz — 4GHz(ES3DV3)

Calibration: In head and body simulating tissue at

Frequencies from 835 up to 5800MHz

Linearity: $\pm 0.2 \text{ dB}(30 \text{ MHz to 4 GHz}) \text{ for ES3DV3}$

± 0.2 dB(30 MHz to 6 GHz) for EX3DV4

Dynamic Range: 10 mW/kg — 100W/kg

Probe Length: 330 mm

Probe Tip

Length: 20 mm Body Diameter: 12 mm

Tip Diameter: 2.5 mm (3.9 mm for ES3DV3)
Tip-Center: 1 mm (2.0mm for ES3DV3)
Application: SAR Dosimetry Testing

Compliance tests of mobile phones

Dosimetry in strong gradient fields

Picture7-2 Near-field Probe



Picture 7-3 E-field Probe

C.3. E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by

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subjecting the probe to a known E-field density (1 mW/cm²) using an RF Signal generator, TEM cell, and RF Power Meter.

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/ cm². E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

Where:

 Δt = Exposure time (30 seconds),

C = Heat capacity of tissue (brain or muscle),

 ΔT = Temperature increase due to RF exposure.

$$SAR = \frac{\left|E\right|^2 \cdot \sigma}{\rho}$$

Where:

 σ = Simulated tissue conductivity,

 ρ = Tissue density (kg/m³).

C.4. Other Test Equipment

C.4.1. Data Acquisition Electronics(DAE)

The data acquisition electronics consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe

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collision detection.

The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



PictureC.4: DAE



C.4.2. Robot

The SPEAG DASY system uses the high precision robots (DASY5: RX90L) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchron motors; no stepper motors)
- Low ELF interference (motor control fields shielded via the closed metallic construction shields)



Picture C.5 DASY 5

C.4.3. Measurement Server

The Measurement server is based on a PC/104 CPU broad with CPU (DASY5: 400 MHz, Intel Celeron), chipdisk (DASY5: 128MB), RAM (DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O broad, which

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is directly connected to the PC/104 bus of the CPU broad.

The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized pinout, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.



Picture C.6 Server for DASY 5

C.4.4. Device Holder for Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5mm distance, a positioning uncertainty of ±0.5mm would produce a SAR uncertainty of ±20%. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point

(ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity ε =3 and loss tangent δ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

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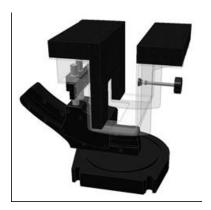


<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM and ELI phantoms.



Picture C.7: Device Holder



Picture C.8: Laptop Extension Kit

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C.4.5. Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a table. The shape of the shell is based on data from an anatomical study designed to Represent the 90th percentile of the population. The phantom enables the dissymmetric evaluation of SAR for both left and right handed handset usage, as well as body-worn usage using the flat phantom region. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. The shell phantom has a 2mm shell thickness (except the ear region where shell thickness increases to 6 mm).

Shell Thickness: 2 ± 0. 2 mm

Filling Volume: Approx. 25 liters

Dimensions: 810 x 1000 x 500 mm (H x L x W)

Available: Special



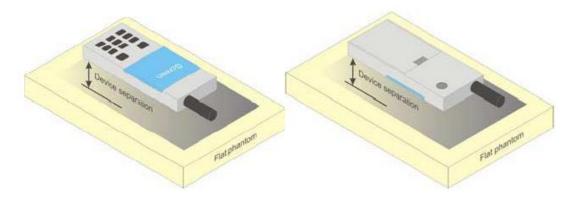
Picture C.9: SAM Twin Phantom



ANNEX D. Position of the wireless device in relation to the phantom

D.1. Body-worn device

A typical example of a body-worn device is a mobile phone, wireless enabled PDA or other battery operated wireless device with the ability to transmit while mounted on a person's body using a carry accessory approved by the wireless device manufacturer.



Picture D.1Test positions for body-worn devices

D.2. Desktop device

A typical example of a desktop device is a wireless enabled desktop computer placed on a table or desk when used.

The DUT shall be positioned at the distance and in the orientation to the phantom that corresponds to the intended use as specified by the manufacturer in the user instructions. For devices that employ an external antenna with variable positions, tests shall be performed for all antenna positions specified. Picture 8.5 show positions for desktop device SAR tests. If the intended use is not specified, the device shall be tested directly against the flat phantom.

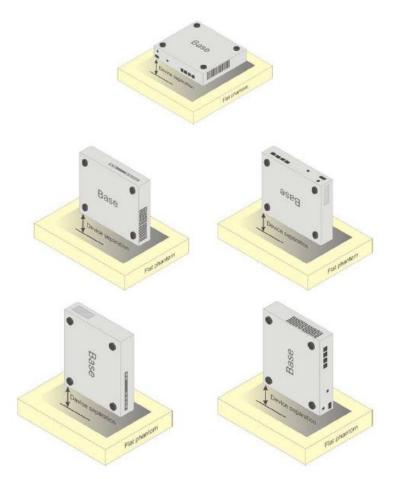
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Picture D.2 Test positions for desktop devices

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D.4. DUT Setup Photos



Picture D.3 DSY5 system Set-up

Note:

The photos of test sample and test positions show in additional document.



ANNEX E. Equivalent Media Recipes

The liquid used for the frequency range of 800-3000 MHz consisted of water, sugar, salt, preventol, glycol monobutyl and Cellulose. The liquid has been previously proven to be suited for worst-case. The Table E.1 shows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528 and IEC 62209.

Table E.1: Composition of the Tissue Equivalent Matter

Fragues av (MIII-)	835	835	1900	1900	2450	2450
Frequency (MHz)	Head	Body	Head	Body	Head	Body
Ingredients (% by v	weight)					
Water	41.45	52.5	55.242	69.91	58.79	72.60
Sugar	56.0	45.0	\	\	\	\
Salt	1.45	1.4	0.306	0.13	0.06	0.18
Preventol	0.1	0.1	\	\	\	\
Cellulose	1.0	1.0	\	\	\	\
Glycol Monobutyl	\	\	44.452	29.96	41.15	27.22
Dielectric	c=41 E	c=55.0	s=40.0	c=52.2	c=20.2	c=50.7
Parameters	ε=41.5	ε=55.2	ε=40.0	ε=53.3	ε=39.2	ε=52.7
Target Value	σ=0.90	σ=0.97	σ=1.40	σ=1.52	σ=1.80	σ=1.95



ANNEX F. System Validation

The SAR system must be validated against its performance specifications before it is deployed. When SAR probes, system components or software are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such components.

Table F.1: System Validation Part 1

Syste	Probe	Tuno	Liquid	Validation	Frequency	Permittivity	Conductivity
m No.	SN.	Type	name	date	point	ε	σ (S/m)
32	3252	Body	2450MHz	Aug.28, 2018	2450 MHz	53.830	1.900

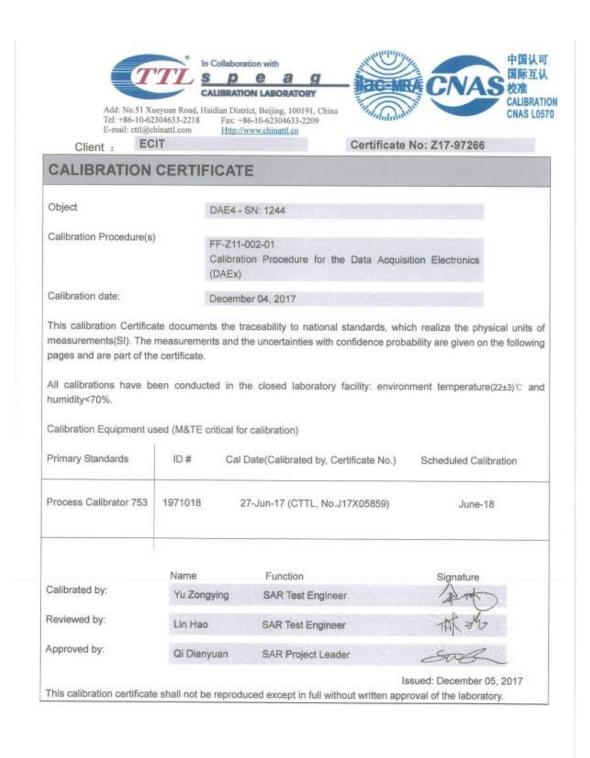
Table F.2: System Validation Part 2

0111	Sensitivity	PASS	PASS
CW Validation	Probe linearity	PASS	PASS
vandation	Probe Isotropy	PASS	PASS
	MOD.type	GMSK	GMSK
Mod	MOD.type	OFDM	OFDM
Validation	Duty factor	PASS	PASS
	PAR	PASS	PASS

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ANNEX G. Probe and DAE Calibration Certificate



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Reported No.: I18D00140-SAR01



 Add: No.51 Xueyuan Road, Haidian District, Beijing, 100191, China

 Tel: +86-10-62304633-2218
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 E-mail: cttl@chinattl.com
 Http://www.chinattl.cn

Glossary:

DAE

data acquisition electronics

Connector angle

information used in DASY system to align probe sensor X

to the robot coordinate system.

Methods Applied and Interpretation of Parameters:

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The report provide only calibration results for DAE, it does not contain other performance test results.

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DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1μV , full range = -100...+300 mV

Low Range: 1LSB = 61nV , full range = -1......+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	Х	Υ	Z 404.516 ± 0.15% (k=2)	
High Range	403.862 ± 0.15% (k=2)	403.603 ± 0.15% (k=2)		
Low Range	3.95366 ± 0.7% (k=2)	3.96972 ± 0.7% (k=2)	3.97929 ± 0.7% (k=2)	

Connector Angle

Connector Angle to be used in DASY system	22.5° ± 1 °

Certificate No: Z17-97266

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Reported No.: I18D00140-SAR01







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ECIT Certificate No: Z17-97112 Client

CALIBRATION CERTIFICATE

Object ES3DV3 - SN:3252

Calibration Procedure(s)

FF-Z11-004-01

Calibration Procedures for Dosimetric E-field Probes

Calibration date: August 31, 2017

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID#	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	27-Jun-17 (CTTL, No.J17X05857)	Jun-18
Power sensor NRP-Z91	101547	27-Jun-17 (CTTL, No.J17X05857)	Jun-18
Power sensor NRP-Z91	101548	27-Jun-17 (CTTL, No.J17X05857)	Jun-18
Reference10dBAttenuator	18N50W-10dB	13-Mar-16(CTTL,No.J16X01547)	Mar-18
Reference20dBAttenuator	18N50W-20dB	13-Mar-16(CTTL, No.J16X01548)	Mar-18
Reference Probe EX3DV4	SN 7433	26-Sep-16(SPEAG,No.EX3-7433_Sep16)	Sep-17
DAE4	SN 549	13-Dec-16(SPEAG, No.DAE4-549_Dec16)	Dec -17
Secondary Standards	ID#	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
SignalGeneratorMG3700A	6201052605	27-Jun-17 (CTTL, No.J17X05858)	Jun-18
Network Analyzer E5071C	MY46110673	13-Jan-17 (CTTL, No.J17X00285)	Jan -18
	Name	Function	Signature
Calibrated by:	Yu Zongying	SAR Test Engineer	AND
Reviewed by:	Lin Hao	SAR Test Engineer	种的
Approved by:	Qi Dianyuan	SAR Project Leader	7.72

Issued: September 01, 2017

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This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Reported No.: I18D00140-SAR01

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Glossary:

tissue simulating liquid TSL NORMx,y,z sensitivity in free space ConvF sensitivity in TSL / NORMx,y,z DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal A.B.C.D modulation dependent linearization parameters

Polarization Φ Φ rotation around probe axis

Polarization θ θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i

 θ =0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013

- b) IEC 62209-1, "Measurement procedure for the assessment of Specific Absorption Rate (SAR) from hand-held and body-mounted devices used next to the ear (frequency range of 300 MHz to 6 GHz)", July 2016
- c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March
- d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORMx, y, z: Assessed for E-field polarization θ=0 (f≤900MHz in TEM-cell; f>1800MHz: waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E²-field uncertainty inside TSL (see below ConvF).
- $NORM(f)x,y,z = NORMx,y,z^*$ frequency_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z; VRx,y,z:A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f≤800MHz) and inside waveguide using analytical field distributions based on power measurements for f >800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ±50MHz to ±100MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required)

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Glossary:

tissue simulating liquid TSL NORMx,y,z sensitivity in free space ConvF sensitivity in TSL / NORMx,y,z DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal A.B.C.D modulation dependent linearization parameters

Polarization Φ Φ rotation around probe axis

Polarization θ θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i

 θ =0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013

- b) IEC 62209-1, "Measurement procedure for the assessment of Specific Absorption Rate (SAR) from hand-held and body-mounted devices used next to the ear (frequency range of 300 MHz to 6 GHz)", July 2016
- c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March
- d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORMx, y, z: Assessed for E-field polarization θ=0 (f≤900MHz in TEM-cell; f>1800MHz: waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E²-field uncertainty inside TSL (see below ConvF).
- $NORM(f)x,y,z = NORMx,y,z^*$ frequency_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z; VRx,y,z:A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f≤800MHz) and inside waveguide using analytical field distributions based on power measurements for f >800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ±50MHz to ±100MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required)

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DASY/EASY - Parameters of Probe: ES3DV3 - SN: 3252

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm(µV/(V/m) ²) ^A	1.32	1.40	1.37	±10.0%
DCP(mV) ^B	101.5	101.9	101.5	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dBõV	С	D dB	VR mV	Unc ^E (k=2)
0 CW	CW	Х	0.0	0.0	1.0	0.00	278.4	±2.5%
		Y	0.0	0.0	1.0		287.4	
		Z	0.0	0.0	1.0		284.8	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

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A The uncertainties of Norm X, Y, Z do not affect the E²-field uncertainty inside TSL (see Page 5 and Page 6).

B Numerical linearization parameter: uncertainty not required.

E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.





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DASY/EASY - Parameters of Probe: ES3DV3 - SN: 3252

Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz] ^C	Relative Permittivity ^F	Conductivity (S/m) F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unct. (k=2)
750	41.9	0.89	6.25	6.25	6.25	0.50	1.25	±12.1%
835	41.5	0.90	6.19	6.19	6.19	0.32	1.66	±12.1%
900	41.5	0.97	6.16	6.16	6.16	0.36	1.62	±12.1%
1750	40.1	1.37	5.30	5.30	5.30	0.42	1.62	±12.1%
1900	40.0	1.40	5.11	5.11	5.11	0.73	1.18	±12.1%
2000	40.0	1.40	4.97	4.97	4.97	0.76	1.19	±12.1%
2300	39.5	1.67	4.90	4.90	4.90	0.90	1.10	±12.1%
2450	39.2	1.80	4.75	4.75	4.75	0.90	1.10	±12.1%
2600	39.0	1.96	4.44	4.44	4.44	0.90	1.15	±12.1%

^c Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

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F At frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than \pm 1% for frequencies below 3 GHz and below \pm 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.



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DASY/EASY - Parameters of Probe: ES3DV3 - SN: 3252

Calibration Parameter Determined in Body Tissue Simulating Media

f [MHz] ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unct. (k=2)
750	55.5	0.96	6.34	6.34	6.34	0.60	1.20	±12.1%
850	55.2	0.99	6.14	6.14	6.14	0.38	1.63	±12.1%
900	55.0	1.05	6.06	6.06	6.06	0.46	1.49	±12.1%
1750	53.4	1.49	4.95	4.95	4.95	0.49	1.52	±12.1%
1900	53.3	1.52	4.69	4.69	4.69	0.67	1.33	±12.1%
2000	53.3	1.52	4.89	4.89	4.89	0.69	1.25	±12.1%
2300	52.9	1.81	4.58	4.58	4.58	0.57	1.65	±12.1%
2450	52.7	1.95	4.42	4.42	4.42	0.68	1.42	±12.1%
2600	52.5	2.16	4.22	4.22	4.22	0.56	1.66	±12.1%

^c Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10 , 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

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FAt frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to $\pm 10\%$ if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to $\pm 5\%$. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than \pm 1% for frequencies below 3 GHz and below \pm 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

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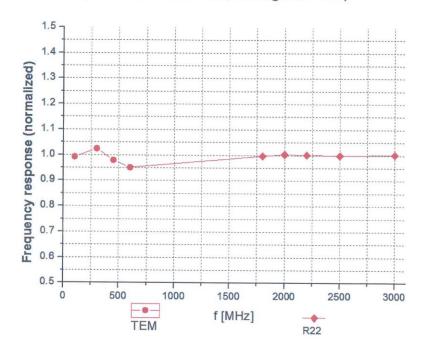


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Frequency Response of E-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ±7.4% (k=2)

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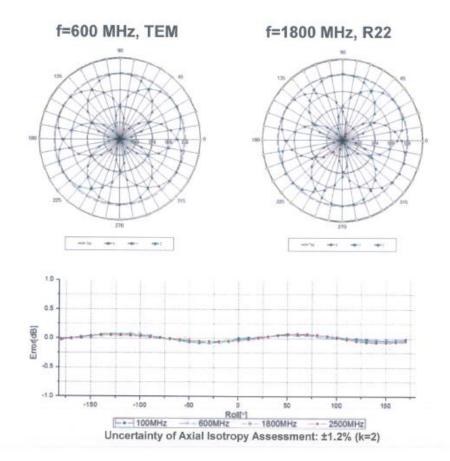
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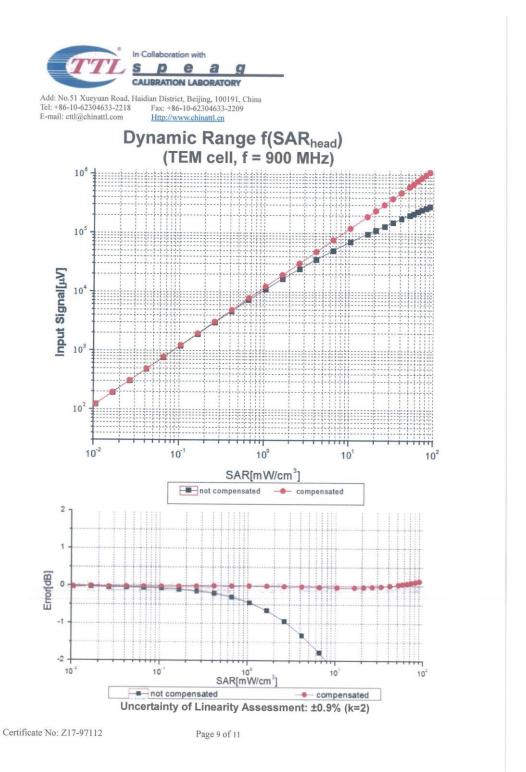


Receiving Pattern (Φ), θ=0°



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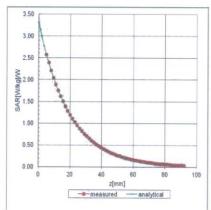
 Tel: +86-10-62304633-2218
 Fax: +86-10-62304633-2209

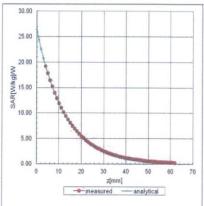
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Conversion Factor Assessment

f=835 MHz, WGLS R9(H_convF)





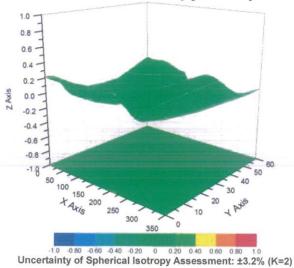


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Deviation from Isotropy in Liquid



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DASY/EASY - Parameters of Probe: ES3DV3 - SN: 3252

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	130.2
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disable
Probe Overall Length	337mm
Probe Body Diameter	10mm
Tip Length	10mm
Tip Diameter	4mm
Probe Tip to Sensor X Calibration Point	2mm
Probe Tip to Sensor Y Calibration Point	2mm
Probe Tip to Sensor Z Calibration Point	2mm
Recommended Measurement Distance from Surface	3mm

Certificate No: Z17-97112

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Certificate No: Z15-97171

CALIBRATION CERTIFICATE

ECIT

Object

D2450V2 - SN: 858

Calibration Procedure(s)

Client

FD-Z11-2-003-01

Calibration Procedures for dipole validation kits

Calibration date:

October 30, 2015

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID#	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	01-Jul-15 (CTTL, No.J15X04256)	Jun-16
Power sensor NRP-Z91	101547	01-Jul-15 (CTTL, No.J15X04256)	Jun-16
Reference Probe EX3DV4	SN 3617	26-Aug-15(SPEAG,No.EX3-3617_Aug15)	Aug-16
DAE4	SN 777	26-Aug-15(SPEAG,No.DAE4-777_Aug15)	Aug-16
Secondary Standards	ID#	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Signal Generator E4438C	MY49071430	02-Feb-15 (CTTL, No.J15X00729)	Feb-16
Network Analyzer E5071C	MY46110673	03-Feb-15 (CTTL, No.J15X00728)	Feb-16

	Name	Function	Signature
Calibrated by:	Zhao Jing	SAR Test Engineer	是影
Reviewed by:	Qi Dianyuan	SAR Project Leader	dos
Approved by:	Lu Bingsong	Deputy Director of the laboratory	Jason Ja
		Januari Ma	0.0045

Issued: November 6, 2015

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Certificate No: Z15-97171

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Glossary:

TSL tissue simulating liquid
ConvF sensitivity in TSL / NORMx,y,z
N/A not applicable or not measured

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) For hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
- c) KDB865664, SAR Measurement Requirements for 100 MHz to 6 GHz

Additional Documentation:

d) DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end
 of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed
 point exactly below the center marking of the flat phantom section, with the arms oriented
 parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole
 positioned under the liquid filled phantom. The impedance stated is transformed from the
 measurement at the SMA connector to the feed point. The Return Loss ensures low
 reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point.
 No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

Certificate No: Z15-97171

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Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY52	52.8.8.1222
Extrapolation	Advanced Extrapolation	
Phantom	Triple Flat Phantom 5.1C	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	2450 MHz ± 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	40.1 ± 6 %	1.82 mho/m ± 6 %
Head TSL temperature change during test	<1.0 °C		

SAR result with Head TSL

SAR averaged over 1 cm ³ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	13.2 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	52.9 mW /g ± 20.8 % (k=2)
SAR averaged over 10 cm ³ (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	6.06 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	24.3 mW /g ± 20.4 % (k=2)

Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	53.1 ± 6 %	1.94 mho/m ± 6 %
Body TSL temperature change during test	<1.0 °C		

SAR result with Body TSL

SAR averaged over 1 cm ³ (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	13.2 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	53.1 mW /g ± 20.8 % (k=2)
SAR averaged over 10 cm ³ (10 g) of Body TSL	Condition	
SAR measured	250 mW input power	6.16 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	24.7 mW /g ± 20.4 % (k=2)

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Appendix

Antenna Parameters with Head TSL

Impedance, transformed to feed point	53.2Ω+ 6.03jΩ		
Return Loss	- 23.6dB		

Antenna Parameters with Body TSL

Impedance, transformed to feed point	49.9Ω+ 7.39jΩ		
Return Loss	- 22.6dB		

General Antenna Parameters and Design

Electrical Delay (one direction)	1.261 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG

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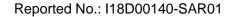
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DASY5 Validation Report for Head TSL

Test Laboratory: CTTL, Beijing, China

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 858 Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2450 MHz; $\sigma = 1.816$ S/m; $\epsilon r = 40.14$; $\rho = 1000$ kg/m3

Phantom section: Left Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 SN3617; ConvF(7.24, 7.24, 7.24); Calibrated: 8/26/2015;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn777; Calibrated: 8/26/2015
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7331)

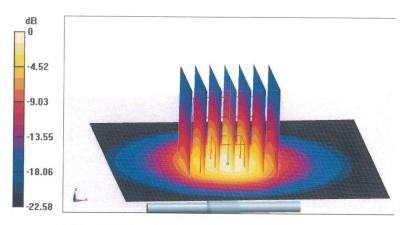
Dipole Calibration/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm,

dy=5mm, dz=5mm

Reference Value = 106.3 V/m; Power Drift = -0.04 dB

Peak SAR (extrapolated) = 27.5 W/kg

SAR(1 g) = 13.2 W/kg; SAR(10 g) = 6.06 W/kgMaximum value of SAR (measured) = 20.3 W/kg



0 dB = 20.3 W/kg = 13.07 dBW/kg

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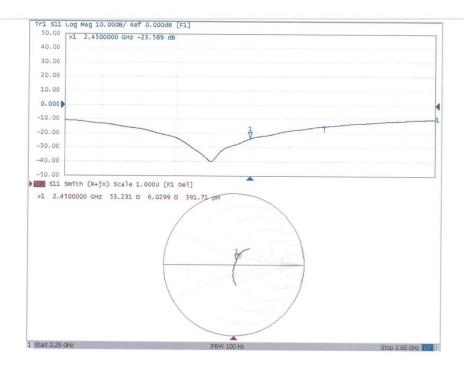






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Impedance Measurement Plot for Head TSL



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DASY5 Validation Report for Body TSL

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Test Laboratory: CTTL, Beijing, China

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 858

Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2450 MHz; $\sigma = 1.936$ S/m; $\epsilon_r = 53.11$; $\rho = 1000$ kg/m³

Phantom section: Center Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 SN3617; ConvF(7.35, 7.35, 7.35); Calibrated: 8/26/2015;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn777; Calibrated: 8/26/2015
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7331)

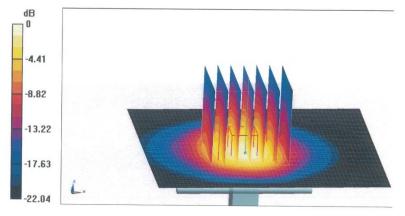
Dipole Calibration/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 99.98 V/m; Power Drift = 0.07 dB

Peak SAR (extrapolated) = 26.6 W/kg

SAR(1 g) = 13.2 W/kg; SAR(10 g) = 6.16 W/kg

Maximum value of SAR (measured) = 19.8 W/kg

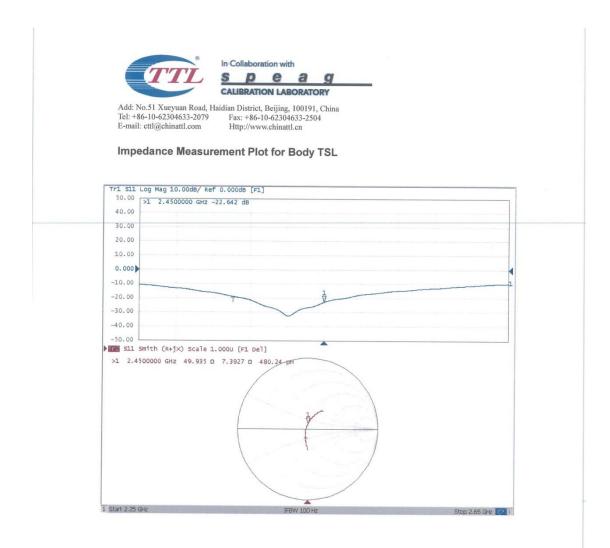


0 dB = 19.8 W/kg = 12.97 dBW/kg

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D2450V2, Serial No.858 Extended Dipole Calibrations

Per IEEE Std 1528-2013, the dipole should have a return loss better than -20dB at the test frequency to reduce uncertainty in the power measurement.

Per KDB 865664 D01,if dipoles are verified in return loss(<-20dB,within 20% of prior calibration),and in impedance (within 5 ohm of prior calibration),the annual calibration is not necessary and the calibration interval can be extended.

Justification of the extended calibration

D2450V2 Serial No.858						
	2450 Head					
Date of Measurement	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)
10.30.2015	-23.589	-	53.231		6.0299	
10.29.2016	-23.466	0.52	50.672	2.559	6.4162	0.386

D2450V2 Serial No.858 2450 Body						
Date of Measurement	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)
10.30.2015	-22.642		49.935		7.3927	
10.29.2016	-23.075	1.91	46.903	3.032	5.6814	1.711

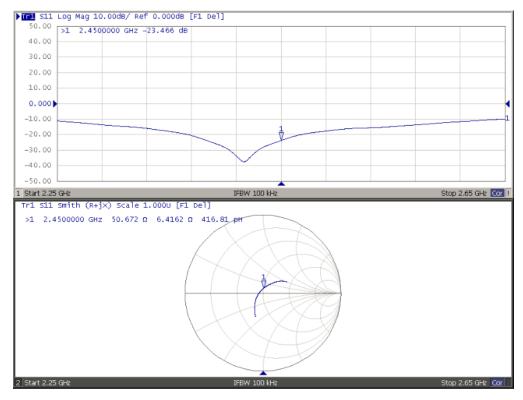
The return loss is < -20dB, within 20% of prior calibration; the impedance is within 5 ohm of prior calibration. Therefore the verification result should support extended calibration.

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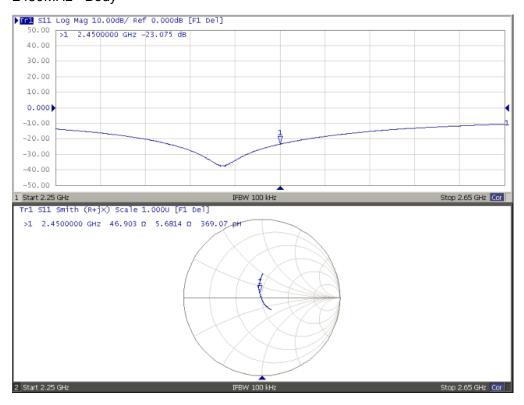
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Dipole Verification Data D2450V2 Serial No.858 2450MHz-Head



2450MHz - Body



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Justification of the extended calibration

D2450V2 Serial No.858											
2450 Head											
Date of Measurement	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)					
10.30.2015	-23.589	-	53.231		6.0299						
10.29.2016	-23.466	0.52	50.672	2.559	6.4162	0.386					
10.27.2017	-22.956	2.17	52.563	1.891	6.85	0.434					

Reported No.: I18D00140-SAR01

D2450V2 Serial No.858										
2450 Body										
Date of Measurement	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)				
10.30.2015	-22.642		49.935		7.3927					
10.29.2016	-23.075	1.91	46.903	3.032	5.6814	1.711				
10.27.2017	-22.414	2.86	50.694	3.791	7.616	1.935				

The return loss is < -20dB, within 20% of prior calibration; the impedance is within 5 ohm of prior calibration. Therefore the verification result should support extended calibration.

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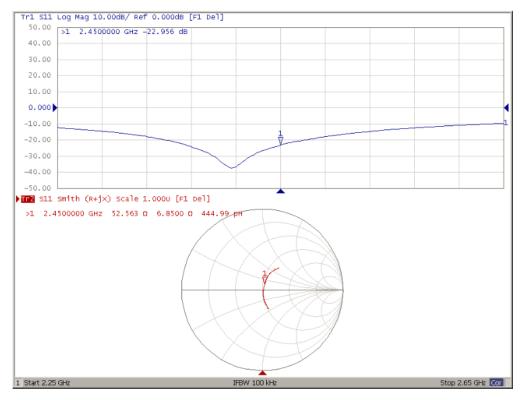


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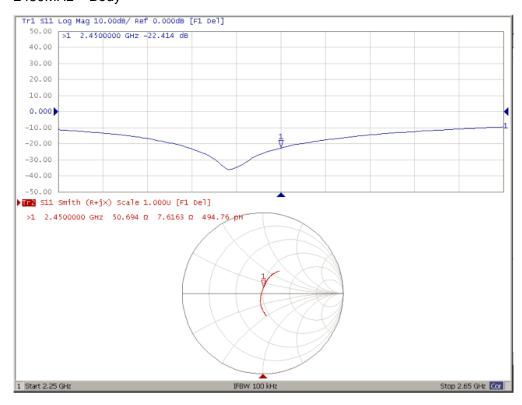
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Dipole Verification Data D2450V2 Serial No.858 2450MHz-Head



2450MHz - Body





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Acceptable Conditions for SAR Measurements Using Probes and Dipoles Calibrated under the SPEAG-TMC Dual-Logo Calibration Program to Support FCC Equipment Certification

The acceptable conditions for SAR measurements using probes, dipoles and DAEs calibrated by TMC (Telecommunication Metrology Center of MITT in Beijing, China), under the Dual-Logo Calibration Certificate program and quality assurance (QA) protocols established between SPEAG (Schmid & Partner Engineering AG, Switzerland) and TMC, to support FCC (U.S. Federal Communications Commission) equipment certification are defined and described in the following.

- The agreement established between SPEAG and TMC is only applicable to calibration services performed by TMC where its clients (companies and divisions of such companies) are headquartered in the Greater China Region, including Taiwan and Hong Kong. This agreement is subject to renewal at the end of each calendar year between SPEAG and TMC. TMC shall inform the FCC of any changes or early termination to the agreement.
- Only a subset of the calibration services specified in the SPEAG-TMC agreement, while it remains valid, are applicable to SAR measurements performed using such equipment for supporting FCC equipment certification. These are identified in the

 - a) Calibration of dosimetric (SAR) probes EX3DVx, ET3DVx and ES3DVx.
 i) Free-space E-field and H-field probes, including those used for HAC (hearing aid compatibility) evaluation, temperature probes, other probes or equipment not identified in this document, when calibrated by TMC, are excluded and cannot be used for measurements to support FCC equipment certification.
 - ii) Signal specific and bundled probe calibrations based on PMR (probe modulation response) characteristics are handled according to the requirements of KDB 865664; that is, "Until standardized procedures are available to make such determination, the applicability of a signal specific probe calibration for testing specific wireless modes and technologies is determined on a case-by-case basis through KDB inquiries, including SAR system verification requirements."

 b) Calibration of SAR system validation dipoles, excluding HAC dipoles.
 c) Calibration of data acquisition electronics DAE3Vx, DAE4Vx and DAEasyVx.

 - d) For FCC equipment certification purposes, the frequency range of SAR probe and dipole calibrations is limited to 700 MHz 6 GHz and provided it is supported by the equipment identified in the TMC QA protocol (a separate attachment to this document).
 - e) The identical system and equipment setup, measurement configurations, hardware, evaluation algorithms, calibration and QA protocols, including the format of calibration certificates and reports used by SPEAG shall be applied by TMC.
 - f) The calibrated items are only applicable to SPEAG DASY 4 and DASY 5 or

1



Reported No.: I18D00140-SAR01

DET
June 26, 2013

- 3) The SPEAG-TMC agreement includes specific protocols identified in the following to ensure the quality of calibration services provided by TMC under this SPEAG-TMC Dual-Logo calibration agreement are equivalent to the calibration services provided by SPEAG. TMC shall, upon request, provide copies of documentation to the FCC to substantiate program implementation.
 - the FCC to substantiate program implementation.

 a) The Inter-laboratory Calibration Evaluation (ILCE) stated in the TMC QA protocol shall be performed between SPEAG and TMC at least once every 12 months. The ILCE acceptance criteria defined in the TMC QA protocol shall be satisfied for the TMC, SPEAG and FCC agreements to remain yalid.
 - satisfied for the TMC, SPFAG and FCC agreements to remain valid.

 b) Check of Calibration Certificate (CCC) shall be performed by SPEAG for all calibrations performed by TMC. Written confirmation from SPEAG is required for TMC to issue calibration certificates under the SPEAG-TMC Dual-Logo calibration program. Quarterly reports for all calibrations performed by TMC under the program are also issued by SPEAG.
 - c) The calibration equipment and measurement system used by TMC shall be verified before each calibration service according to the specific reference SAR probes, dipoles, and DAE calibrated by SPEAG. The results shall be reproducible and within the defined acceptance criteria specified in the TMC QA protocol before each actual calibration can commence. TMC shall maintain records of the measurement and calibration system verification results for all calibrations.
 - d) Quality Check of Calibration (QCC) certificates shall be performed by SPEAG at least once every 12 months. SPEAG shall visit TMC facilities to verify the laboratory, equipment, applied procedures and plausibility of randomly selected certificates.
- A copy of this document, to be updated annually, shall be provided to TMC clients that accept calibration services according to the SPEAG-TMC Dual-Logo calibration program, which should be presented to a TCB (Telecommunication Certification Body), to facilitate FCC equipment approval.
- TMC shall address any questions raised by its clients or TCBs relating to the SPEAG-TMC Dual-Logo calibration program and inform the FCC and SPEAG of any critical issues.

Change Note: Revised on June 26 to clarify the applicability of PMR and Bundled probe calibrations according to the requirements of KDB 865664.

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ANNEX H. Accreditation Certificate



Accredited Laboratory

A2LA has accredited

EAST CHINA INSTITUTE OF TELECOMMUNICATIONS

Shanghai, People's Republic of China

for technical competence in the field of

Electrical Testing

This laboratory is accredited in accordance with the recognized International Standard ISO/IEC 17025:2005

General requirements for the competence of testing and calibration laboratories. This accreditation demonstrates technical competence for a defined scope and the operation of a laboratory quality management system (refer to joint ISO-ILAC-IAF Communiqué dated 8 January 2009).



Presented this 15th day of March 2017.

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President and CEO
For the Accreditation Council
Certificate Number 3682.01
Valid to February 28, 2019

For the tests to which this accreditation applies, please refer to the laboratory's Electrical Scope of Accreditation.

********END OF REPORT*******