

 Report No.: 18220WC20173403
 FCC ID: 2AOKB-A3302S
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# **FCC SAR Test Report**

Client Name	.P3	Anker Innovations	Limited

Address

Room 1318-19, Hollywood Plaza, 610 Nathan Road, Mongkok, Kowloon, Hong Kong

Product Name

Anker PowerConf S3

Date

Oct. 08, 2022

2



# Shenzhen Anbotek Compliance Laboratory Limited

### Shenzhen Anbotek Compliance Laboratory Limited

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# TEST REPORT

Applicant	Anker Innovations Limited
Manufacturer	: Anker Innovations Limited
Product Name	Anker PowerConf S3
Model No.	: A3302
Trade Mark	N.A.
Rating(s)	: Input: 5V- (with DC 3.6V, 5200mAh battery inside)

### Test Standard(s) : IEC 62209-2:2010; IEEE 1528:2013; FCC 47 CFR Part 2.1093;

### ANSI/IEEE C95.1:2005; Reference FCC KDB 447498

The device described above is tested by Shenzhen Anbotek Compliance Laboratory Limited to determine the maximum emission levels emanating from the device and the severe levels of the device can endure and its performance criterion. The measurement results are contained in this test report and Shenzhen Anbotek Compliance Laboratory Limited is assumed full of responsibility for the accuracy and completeness of these measurements. Also, this report shows that the EUT (Equipment Under Test) is technically compliant with the IEC 62209-2:2010, IEEE 1528:2013, FCC 47 CFR Part 2 2.1093, ANSI/IEEE C95.1:2005, and Reference KDB 447498 requirements.

This report applies to above tested sample only and shall not be reproduced in part without written approval of Shenzhen Anbotek Compliance Laboratory Limited.

Date of Receipt Date of Test

Prepared By

Aug. 01, 2022 Aug. 09, 2022

Ella Lano

(Ella Liang)

(Kingkong Jin)

Approved & Authorized Signer

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### 1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing are as follows.

### <Highest SAR Summary>

Francisco Dand	Highes	t Reported 1g-SAR(W/Kg)	SAR Test Limit
Frequency Band		(W/Kg)	
BT BDR+EDR	e Auport b	0.257	Laboret 1.6 Million
BT BLE	stek Anbote	0.232	1.6
Test Result	hotek Anboten	PASS	ak hotek A

This device is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6 W/kg) specified in KDB 447498 D01 v06, 2015 and ANSI/IEEE C95.1:2005, and had been tested in accordance with the measurement methods and procedures specified in IEEE 1528-2013.

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### 2. General Information

### 2.1 Client Information

Applicant	:	Anker Innovations Limited
Address	:	Room 1318-19, Hollywood Plaza, 610 Nathan Road, Mongkok, Kowloon, Hong Kong
Manufacturer	:	Anker Innovations Limited
Address	:	Room 1318-19, Hollywood Plaza, 610 Nathan Road, Mongkok, Kowloon, Hong Kong

### 2.2 Description of Equipment Under Test (EUT)

Product Name	:	Anker PowerConf S3	
Model No.	:	A3302	And Andrek Anbotek Anbo
Trade Mark	:	N.A.	son Annotek Anbolen Annotek
Test Power Supply	:	DC 3.6V battery inside	Anbo An Anbotek Anbote And And
Product Description	Number Modula Antenna	Operation Frequency:	BT BDR+EDR/BT BLE: 2402-2480MHz
		Number of Channel:	BT BDR+EDR: 79 Channels BT BLE: 40 Channels
		Modulation Type:	BT BDR+EDR: GFSK, π/4-DQPSK, 8-DPSK BT BLE: GFSK
		Antenna Type:	FPC Antenna
		Antenna Gain(Peak):	2.76dBi(Provided by customer)

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### 2.3 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue.

### 2.4 Applied Standard

The Specific Absorption Rate (SAR) testing specification, method, and procedure for this device is in accordance with the following standards:

IEC 62209-2:2010;

IEEE 1528:2013;

ANSI/IEEE C95.1:2005

FCC 47 CFR Part 2,1093

Reference FCC KDB 447498

### 2.5 Environment of Test Site

Items	Required	Actual
Temperature (℃)	18-25	22~23
Humidity (%RH)	30-70	55~65

### 2.6 Test Configuration

For SAR testing, engineering testing software installed on the EUT can provide continuous transmitting RF signal.

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### 3. Specific Absorption Rate (SAR)

### 3.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

### 3.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density ( $\rho$ ).The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = C\left(\frac{\delta T}{\delta t}\right)$$

Where: C is the specific head capacity,  $\delta T$  is the temperature rise and  $\delta$ tisthe exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where:  $\sigma$  is the conductivity of the tissue,  $\rho$  is the mass density of the tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

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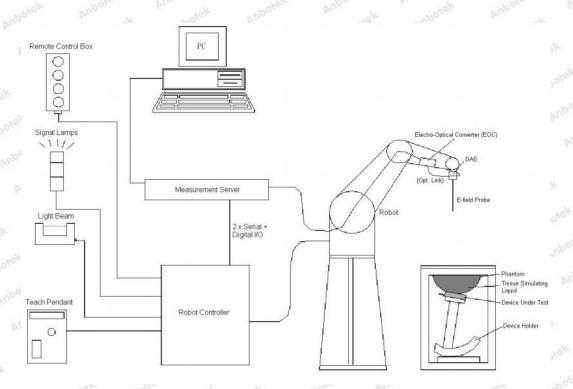
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### 4. SAR Measurement System



### **DASY System Configurations**

The DASY system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- > A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (EOC) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- > A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY software
- Remove control with teach pendant and additional circuitry for robot safety such as warming lamps, etc.
- The SAM twin phantom
- A device holder
- Tissue simulating liquid

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Dipole for evaluating the proper functioning of the system

components are described in details in the following sub-sections.

### 4.1 E-Field Probe

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

<ex3dv4 probe<="" th=""><th>Arris solen Anbo</th><th>he.</th><th>day</th><th>hore</th><th>ps</th></ex3dv4>	Arris solen Anbo	he.	day	hore	ps
Construction	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	nbot Ant		-	4 6
Frequency	10 MHz to 6 GHz; Linearity: ± 0.2 dB				3
Directivity	<ul> <li>± 0.3 dB in HSL (rotation around probe axis)</li> <li>± 0.5 dB in tissue material (rotation normal to probe axis)</li> </ul>	tek bote		ļ	
Dynamic Range	10 μW/g to 100 mW/g; Linearity: ± 0.2 dB (noise: typically < 1 μW/g)	Anb	Photo o	f EX3DV4	Arri Ite
Dimensions	Overall length: 330 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm	ek potek	Anbotek Anbotek Anbotek	Anbote Anbotek Anbotel	k otek

### E-Field Probe Specification <FX3DV4 Probe>

### E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than  $\pm$  10%. The spherical isotropy shall be evaluated and within  $\pm$  0.25dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data can be referred to appendix C of this report.

### 4.2 Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is

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accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The input impedance of the DAE is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.



Photo of DAE

### 4.3 Robot

The SPEAG DASY system uses the high precision robots (DASY5: TX60XL) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version (DASY5: CS8c) from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability ±0.035 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- > Low ELF interference (the closed metallic construction shields against motor control fields)



Photo of DASY5

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### 4.4 Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chip disk (DASY5: 128 MB), RAM (DASY5: 128 MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.



### Photo of Server for DASY5

### 4.5 Phantom

### <SAM Twin Phantom>

Shell Thickness	2 ± 0.2 mm;
	Center ear point: 6 ± 0.2 mm
Filling Volume	Approx. 25 liters
Dimensions	Length: 1000 mm; Width: 500 mm; Height: adjustable feet
Measurement	Left Hand, Right Hand, Flat
Areas	Phantom

### Photo of SAM Phantom

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

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# Report No.: 18220WC20173403 FCC ID: 2AOKB-A3302S Page 14 of 65 <ELI4 Phantom> Control Contredit Control Contro

Shell Thickness	2 ± 0.2 mm (sagging: <1%)	ten vupo, by	-Ne
	2 ± 0.2 mm (sayging. <170)	A CONTRACT OF A CONTRACT.	
Filling Volume	Approx. 30 liters		ote
Dimensions	Major ellipse axis: 600 mm		
	Minor axis:400 mm		inb
	inbotek Anboic All	o <sup>NC</sup>	p
	Anbolek Anbor Artokek	und and a state of the state of	
	Anbotek Anbor An abotek		E.
	Anbolek Anbor Arborek	Photo of ELI4 Phantom	potel
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The ELI4 phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.

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### 4.6 Device Holder

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The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5 mm distance, a positioning uncertainty of  $\pm 0.5$ mm would produce a SAR uncertainty of  $\pm 20\%$ . Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (ERP).Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon$  = 3 and loss tangent  $\delta$  = 0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



Device Holder

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### 4.7 Data Storage and Evaluation

#### Data Storage

The DASY software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-lose media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

#### Data Evaluation

The DASY post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Norm <sub>i</sub> , a <sub>i0</sub> , a <sub>i1</sub> , a <sub>i2</sub>
	- Conversion factor	ConvFi
	- Diode compression point	dcpi
Device parameters:	- Frequency	f obotek Anbore
	- Crest factor	cforek Miboli
Media parameters:	- Conductivity	σ have not
	- Density	ρ μηθε

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to

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The formula for each channel can be given as:

$$\mathbf{V}_{i} = \mathbf{U}_{i} + \mathbf{U}_{i}^{2} \cdot \frac{\mathbf{cf}}{\mathbf{dcp}}$$

with  $V_i$ = compensated signal of channel i, (i = x, y, z)

 $U_i$  = input signal of channel i, (i = x, y, z)

cf = crest factor of exciting field (DASY parameter)

dcp<sub>i</sub> = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated:

E-field Probes:  $E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$ 

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H-field Probes:  $H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$ 

with V<sub>i</sub> = compensated signal of channel i,(i = x, y, z) Norm<sub>i</sub>= sensor sensitivity of channel i, (i = x, y, z), μV/(V/m)<sup>2</sup> for E-field Probes ConvF= sensitivity enhancement in solution

aij= sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

E<sub>i</sub>= electric field strength of channel i in V/m

H<sub>i</sub>= magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$\mathbf{E_{tot}} = \sqrt{\mathbf{E_x^2 + E_y^2 + E_z^2}}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

Etot= total field strength in V/m

 $\sigma$  = conductivity in [mho/m] or [Siemens/m]

 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

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### 5. Test Equipment List

Manufacturer	None of Faultament	Turne (Mendel		Calibration		
Manufacturer	Name of Equipment	Type/Model	Serial Number	Last Cal.	Due Date	
SPEAG	835MHz System Validation Kit	D835V2	4d154	Jun. 16,2021	Jun. 15,2024	
SPEAG	Data Acquisition Electronics	DAE4	387	Sept.06,2021	Sept.05,2022	
SPEAG	Dosimetric E-Field Probe	EX3DV4	7396	May 06,2022	May 05,2023	
Agilent	ENA Series Network Analyzer	E5071C	MY46317418	Oct.26, 2021	Oct.25, 2022	
SPEAG	DAK	DAK-3.5	1226	NCR	NCR	
SPEAG	ELI Phantom	QDOVA004AA	2058	NCR	NCR	
AR	Amplifier	ZHL-42W	QA1118004	NCR	NCR	
Agilent	Power Meter	N1914A	MY50001102	Oct.26, 2021	Oct.25, 2022	
Agilent	Power Sensor	N8481H	MY51240001	Oct.26, 2021	Oct.25, 2022	
R&S	Spectrum Analyzer	N9020A	MY51170037	Oct.26, 2021	Oct.25, 2022	
Agilent	Signal Generation	N5182A	MY48180656	Oct.26, 2021	Oct.25, 2022	
Worken	Directional Coupler	0110A05601O-10	COM5BNW1A2	Oct.26, 2021	Oct.25, 2022	

#### Note:

1. The calibration certificate of DASY can be referred to appendix C of this report.

- 2. The dipole calibration interval can be extended to 3 years with justification. The dipoles are also not physically damaged, or repaired during the interval.
- 3. The Insertion Loss calibration of Dual Directional Coupler and Attenuator were characterized via the network analyzer and compensated during system check.
- 4. The dielectric probe kit was calibrated via the network analyzer, with the specified procedure (calibrated in pure water) and calibration kit (standard) short circuit, before the dielectric measurement. The specific procedure and calibration kit are provided by Agilent.
- 5. In system check we need to monitor the level on the power meter, and adjust the power amplifier level to have precise power level to the dipole; the measured SAR will be normalized to 1W input power according to the ratio of 1W to the input power to the dipole. For system check, the calibration of the power amplifier is deemed not critically required for correct measurement; the power meter is critical and we do have calibration for it

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### 6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.1. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm, which is shown as followed:



### Photo of Liquid Height for Body SAR

The following table gives the recipes for tissue simulating liquid.

Frequency (MHz)	Water (%)	Sugar (%)	Cellulose (%)	Salt (%)	Prevento I (%)	DGBE (%)	Conductivity (σ)	Permittivity (εr)		
For Body										
2450	68.6	0	0.000	0	31.4	0	1.95	52.7		

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 The following table shows the measuring results for simulating liquid.
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	Measured	Target	Tissue		Measure	ed Tissue	•	Liquid	
Tissue Type	Frequenc y (MHz)	٤r	σ	٤r	Dev. (%)	σ	Dev. (%)	Temp.(℃ )	Test Date
2450MSL	2450	52.7	1.95	52.43	-0.51	1.91	-2.05	23.3	08/09/2022

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### 7. System Verification Procedures

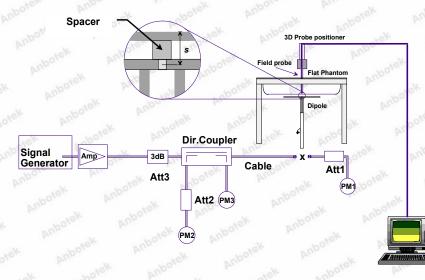
Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

### Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

### System Setup

In the simplified setup for system evaluation, the EUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



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### FCC ID: 2AOKB-A3302S System Setup for System Evaluation

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### Photo of Dipole Setup

### Validation Results

Comparing to the original SAR value provided by SPEAG, the verification data should be within its specification of 10%. The table below shows the target SAR and measured SAR after normalized to 1W input power. It indicates that the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

Frequenc y (MHz)	Liquid Type	Power fed onto reference dipole (mW)	Targeted SAR (W/kg)	Measured SAR (W/kg)	Normalized SAR (W/kg)	Deviatio n (%)	Test Date
2450	Body	250	51.8	12.89	51.48	-0.46	08/09/2022

Target and Measurement SAR after Normalized

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### 8. EUT Testing Position

### 8.1. Body Worn Position

Body-worn operating configurations are tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in a normal use configuration. Per KDB 648474 D04, body-worn accessory exposure is typically related to voice mode operations when handsets are carried in body-worn accessories. The body-worn accessory procedures in FCC KDB 447498 D01 v06, 2015 should be used to test for body-worn accessory SAR compliance, without a headset connected to it. This enables the test results for such configuration to be compatible with that required for hotspot mode when the body-worn accessory test separation distance is greater than or equal to that required for hotspot mode, when applicable. When the reported SAR for body-worn accessory, measured without a headset connected to the handset is < 1.2 W/kg, the highest reported SAR configuration for that wireless mode and frequency band should be repeated for that body-worn accessory with a handset attached to the handset.

Accessories for body-worn operation configurations are divided into two categories: those that do not contain metallic components and those that do contain metallic components and those that do contain metallic components. When multiple accessories that do not contain metallic components are supplied with the device, the device is tested with only the accessory that dictates the closest spacing to the body. Then multiple accessories that contain metallic components are test with the device with each accessory. If multiple accessories share an identical metallic component (i.e. the same metallic belt-chip used with different holsters with no other metallic components) only the accessory that dictates the closest spacing to the body is tested.

molneng leig

### **Body Worn Position**

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### 9. Measurement Procedures

The measurement procedures are as follows:

- (a) Use base station simulator (if applicable) or engineering software to transmit RF power continuously (continuous Tx) in the middle channel.
- (b) Keep EUT to radiate maximum output power or 100% duty factor (if applicable)
- (c) Measure output power through RF cable and power meter.
- (d) Place the EUT in the positions as setup photos demonstrates.
- (e) Set scan area, grid size and other setting on the DASY software.
- (f) Measure SAR transmitting at the middle channel for all applicable exposure positions.
- (g) Identify the exposure position and device configuration resulting the highest SAR
- (h) Measure SAR at the lowest and highest channels at the worst exposure position and device configuration if applicable.

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

### 9.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values form the measurement grid to the high-resolution grid

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- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- Calculation of the averaged SAR within masses of 1g and 10g (f)

### 9.2 Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

### 9.3 Area Scan Procedures

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum found in the scanned area, within a range of the global maximum. The range (in dB0 is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE standard 1528 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan), if only one zoom scan follows the area scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of zoom scans has to be increased accordingly.

Area scan parameters extracted from FCC KDB 865664 D01 SAR measurement 100 MHz to 6 GHz.

-10° ATT - 10°		10. S. S.
	$\leq$ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	$5 \pm 1 \text{ mm}$	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$
Maximum probe angle from probe axis to phantom surface normal at the measurement location	$30^{\circ} \pm 1^{\circ}$	$20^{\circ} \pm 1^{\circ}$
	$\leq$ 2 GHz: $\leq$ 15 mm 2 - 3 GHz: $\leq$ 12 mm	$3 - 4 \text{ GHz:} \le 12 \text{ mm}$ $4 - 6 \text{ GHz:} \le 10 \text{ mm}$
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$	When the x or y dimension o measurement plane orientation the measurement resolution r	on, is smaller than the above,

x or y dimension of the test device with at least one measurement point on the test device.

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### 9. 4 Zoom Scan Procedures

Zoom scans are used assess the peak spatial SAR values within a cubic averaging volume containing 1 gram and 10gram of simulated tissue. The zoom scan measures points (refer to table below) within a cube shoes base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the zoom scan evaluates the averaged SAR for 1 gram and 10 gram and displays these values next to the job's label. Zoom scan parameters extracted from FCC KDB 865664 D01 SAR measurement 100 MHz to 6 GHz.

			$\leq$ 3 GHz	> 3 GHz
Maximum zoom scan s	patial reso	olution: Δx <sub>Zoom</sub> , Δy <sub>Zoom</sub>	$\leq 2 \text{ GHz}: \leq 8 \text{ mm}$ 2 - 3 GHz: $\leq 5 \text{ mm}^*$	$3 - 4 \text{ GHz:} \le 5 \text{ mm}^*$ $4 - 6 \text{ GHz:} \le 4 \text{ mm}^*$
	uniform	grid: ∆z <sub>Zoom</sub> (n)	$\leq$ 5 mm	$3 - 4 \text{ GHz} \le 4 \text{ mm}$ $4 - 5 \text{ GHz} \le 3 \text{ mm}$ $5 - 6 \text{ GHz} \le 2 \text{ mm}$
Maximum zoom scan spatial resolution, normal to phantom surface	1 <sup>st</sup> two points closest		$\leq$ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
	grid	Δz <sub>Zoom</sub> (n>1): between subsequent points	$\leq 1.5 \cdot \Delta$	Z <sub>Zoom</sub> (n-1)
Minimum zoom scan volume	x, y, z		≥ 30 mm	$3 - 4 \text{ GHz}: \ge 28 \text{ mm}$ $4 - 5 \text{ GHz}: \ge 25 \text{ mm}$ $5 - 6 \text{ GHz}: \ge 22 \text{ mm}$

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.

\* When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is  $\leq$  1.4 W/kg,  $\leq$  8 mm,  $\leq$  7 mm and  $\leq$  5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

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### 9.5 Volume Scan Procedures

The volume scan is used for assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g aggregate SAR, the EUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing. When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

### 9.6 Power Drift Monitoring

All SAR testing is under the EUT install full charged battery and transmit maximum output power. In DASY measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of EUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drift more than 5%, the SAR will be retested.

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### 10. Conducted Power

Test Mode	Channel	Peak Power(dBm)	Average Power (dBm)	Maximum Tune-Up(dBm)
OFOK	2402	7.97	5.62	6.00
GFSK	2441	7.84	5.38	6.00
(BT BDR)	2480	7.46	5.67	6.00
	2402	8.80	5.88	6.50
π/4-DQPSK (BT EDR)	2441	8.66	5.93	6.50
(DI EDR)	2480	8.26	6.01	6.50
	2402	9.42	6.38	6.50
8-DPSK	2441	9.26	6.06	6.50
(BT EDR)	2480	8.91	6.44	6.50
OFOK	2402	8.02	5.67	6.00
GFSK	2440	7.88	5.37	6.00
(BLE_1M)	2480	7.52	5.71	6.00
OFEK	2402	7.98	5.40	6.00
GFSK	2440	7.83	5.13	6.00
(BLE_2M)	2480	7.45	5.48	6.00

<Bluetooth Conducted Power>

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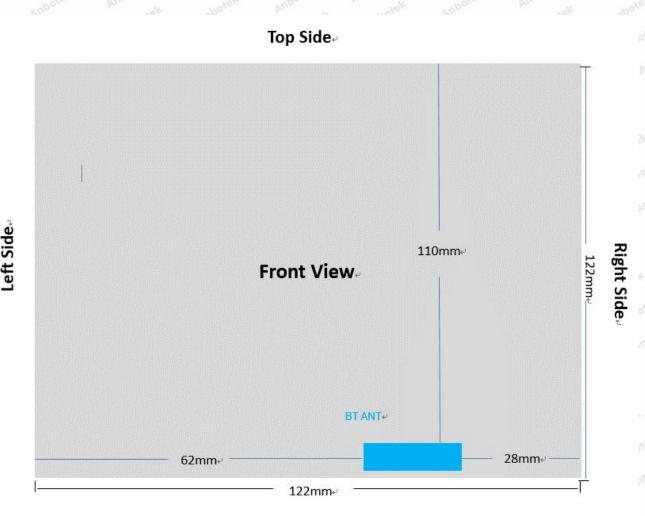
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### 11. Antenna Location



### Bottom Side.

### EUT FRONT VIEW

Distance of The Antenna to the EUT surface and edge										
Antenna Front Back Top Side Bottom Side Left Side Right										
Bluetooth	<25mm	<25mm	>25mm	<25mm	>25mm	>25mm				

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#### SAR Test Results Summary 12.

General Note:

1. Per KDB 447498 D01 v06, the reported SAR is the measured SAR value adjusted for maximum tune-up tolerance.

Scaling Factor = tune-up limit power (mW) / EUT RF power (mW), where tune-up limit is the maximum rated power among all production units.

Reported SAR(W/kg)= Measured SAR(W/kg)\* Scaling Factor 2. Per KDB 447498 D01 v06, for each exposure position, if the highest output channel reported SAR≤0.8W/kg, other channels SAR testing are not necessary

100	Didetooti		100		bo	3.0	- Ofer	0.00		No.	000
Plot No.	Band	Mode	Test Position	Gap (cm)	Freq. (MHz)	Average Power (dBm)	Tune-Up Limit (dBm)	Scalin g Factor	Drift	Measured SAR₁g (W/kg)	Reported SAR <sub>1g</sub> (W/kg)
#1	2.4GHz	<b>BT EDR</b>	Back	0	2480	6.44	6.50	1.014	0.09	0.253	0.257
det	2.4GHz	BT EDR	Front	0	2480	6.44	6.50	1.014	0.12	0.166	0.168
00	2.4GHz	BT EDR	Тор	0	2480	6.44	6.50	1.014	N/A	N/A	N/A
Pupo.	2.4GHz	BT EDR	Bottom	0	2480	6.44	6.50	1.014	0.17	0.233	0.236
pinto	2.4GHz	BT EDR	Left	0×nbr	2480	6.44	6.50	1.014	N/A	N/A	N/A
	2.4GHz	BT EDR	Right	0	2480	6.44	6.50	1.014	N/A	N/A	N/A
#2	2.4GHz	BT BLE	Back	0*6*0	2480	5.71	6.00	1.069	-0.05	0.217	0.232
- Ka	2.4GHz	BT BLE	Front	0	2480	5.71	6.00	1.069	0.03	0.148	0.158
2012	2.4GHz	BT BLE	Тор	0	2480	5.71	6.00	1.069	N/A	N/A	N/A
Anbote	2.4GHz	BT BLE	Bottom	0	2480	5.71	6.00	1.069	-0.07	0.185	0.198
anbr	2.4GHz	BT BLE	Left	0,000	2480	5.71	6.00	1.069	N/A	N/A	N/A
	2.4GHz	BT BLE	Right	0	2480	5.71	6.00	1.069	N/A	N/A	N/A

#### <Bluetooth>

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### 13. Simultaneous Transmission Analysis

### Simultaneous TX SAR Considerations

No.	Applicable Simultaneous Transmiss	ion

1. N/A

and BLE cannot transmit simultaneously.

Note: 1. Bluetooth EDR

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### 14. Measurement Uncertainty

	bolle Alle	-ter	ante		Pr	No.	5010	An	
NO	Source	Uncert. ai(%)	Prob. Dist.	Div. k	ci (1g)	ci (10g)	Stand.U ncert. ui (1g)	Stand.U ncert. ui (10g)	Veff
Anbo Anbo	Repeat	0.4	Anbotok	1Ant	1	1	0. 4	0.4	Anbone 9 spote
P	hbotek Anboli A	Anbotek	Instru	iment	Anbot	46	Anbotek	Anbornote	K Ant
2	Probe calibration	P7botel	NANDO	2	1	potel 1	3.5	3.5	ote <sup>k</sup> ∞
nbotek 3	Axial isotropy	ex 4.7	R	√3	0.7	0.7	ek 1.9	1.9	Anborek
4	Hemispherical isotropy	9.4	Anbotek R	$\sqrt{3}$	0.7	0.7	3.9	3.9	Antrate Market
ote <sup>1</sup> 5	Boundary effect	1.0	e <sup>k</sup> R pri	√3	1	nbo <sup>tek</sup>	0.6	0.6	onene en
6	Linearity	4.7	R	√3	1	Anbotr 1	2.7	2.7	Anborek ∞
700	Detection limits	1.0	Roboten	√ <u>3</u>	Antonia	1	0.6	0.6	∞) <sup>and</sup>
8	Readout electronics	0.3	N N parts	1 <sup>10</sup> 1	P1	1	0.3	0.3	~
9 9	Response time	0.8	R	√3	e <sup>M</sup> 1	AIDOTE	0.5	0.5	~
10	Integration time	2.6	An R <sup>stek</sup>	√3	potek 1at	Anb 1	1.5	Anbotek 1.5	Anbotek ∞
11	Ambient noise	3.0	R sol	√3	P1	1	1.7 ores	1.7,000	∞
12	Ambient reflections	3.0	R	√3	۲ ۲ ۲	An1otel	1.7	1.7	Multi Cool
13	Probe positioner mech. restrictions	0.4	Ant R	√3	potek Anboilk	Anbr 1 A	0.2	0.2	Anbotek Anbot

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otek	No.: 18220WC2017340 Probe positioning with	K Anb	otek I	ID: 2A	<u>}</u>	Anbotel	Anb	hotek A	34 of 6
14	respect to phantom shell	2.9	Anborek	√3	otek 1	1 <sup>mb/</sup>	1.7	1.7	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
15	Max.SAR evaluation	1.0	Anbo Ranbo	otek	Anboi	10 <sup>1</sup>	0.6	0.6	8

p.	botek Anboten P	nbatek	Test samp	ole rela	ted	pr M	Anbotek	Anboten	Anor
16	Device positioning	3.8	N Anbo	1	Ano 1 An	potek 1	3.8	3.8	99
17	Device holder	5.1	Noote <sup>X</sup> N	AN1010	1 Mex	Anbote 1 Anbot	5.1	5.1	mbotek 5 ek
18	Drift of output power	5.0	Rotek	√3	nbotek 1	1 AS	2.9	2.9	×

Phantom and set-up

	DU.	- 0 <sup>0</sup>		Nr. 1	·	202	(DO 7		10
19	Phantom uncertainty	4.0	e <sup>K</sup> Ani	√3	1	unbotek 1	2.3	2.3	
20	Liquid conductivity (target)	5.0	Anbotek R Anbotek	√3	0.64	0.43	1.8	1.2	×
21	Liquid conductivity (meas)	2.5	Anbots N Anb	otex 1	0.64	0.43	1.6	1.2	8
22	Liquid Permittivity (target)	5.0	anbot R.	√3	0.6	0.49	1.7	1.5	Anborek
23	Liquid Permittivity (meas)	2.5	Nibote	1	0.6	0.49	1.5	1.2	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
ek potek Anbotel	Combined standard	Anbore Anb	RSS	n U	$c = \sum_{i=1}^{n} C_i U_i$	U <sub>i</sub> 2 2	11.4%	11.3%	236
unc	Expanded ertainty(P=95%)	anbotek	Anborro	J = k U	,k=2	2 2	22.8%	22.6%	Anbot

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### Appendix A. EUT Photos and Test Setup Photos



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### Appendix B. Plots of SAR System Check

### 2450MHz Body System Check

Date:08/09/2022

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:910 Communication System: UID 0, CW; Frequency: 2450 MHz;Duty Cycle: 1:1 Medium parameters used: f = 2450 MHz;  $\sigma$  = 1.91 S/m;  $\epsilon_r$  = 52.43;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 SN7396; ConvF(7.53, 7.53, 7.53); Calibrated: May 06, 2022;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: Sep. 06, 2021
- Phantom: SAM; Type: QD000P40CD; Serial: TP:1670
- Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

Configuration/Pin=250mW/Area Scan (81x81x1): Interpolated grid: dx=1.200 mm, dy=1.200 mm

Maximum value of SAR (interpolated) = 19.8 W/kg

**Configuration/Pin=250mW/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 87.431 V/m; Power Drift = -0.12 dB

Peak SAR (extrapolated) = 26.9 W/kg

SAR(1 g) = 12.89 W/kg; SAR(10 g) = 5.88W/kg

Maximum value of SAR (measured) = 20.1 W/kg

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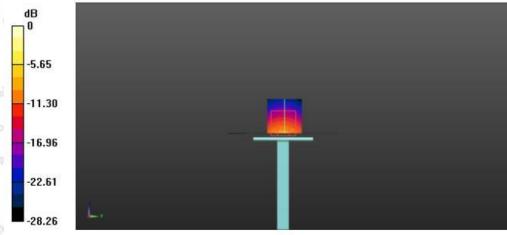
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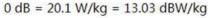




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# Appendix C. Plots of SAR Test Data

### #1

Date: 08/09/2022

### 2.4G Bluetooth EDR 8DPSK\_2480 BODY BACK

Communication System: UID 0, wifi (fcc) (0); Frequency: 2480 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): f = 2480 MHz;  $\sigma$  = 1.91 S/m;  $\epsilon_r$  = 52.43;  $\rho$  = 1000 kg/m<sup>3</sup>

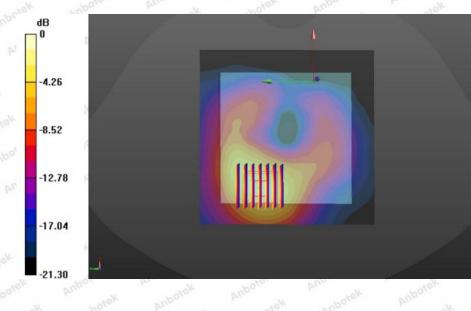
Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 SN7396; ConvF(7.53, 7.53, 7.53); Calibrated: May 06, 2022;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: Sep. 06, 2021
- Phantom: SAM; Type: QD000P40CD; Serial: TP:1670
- Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

**BODY BACK /Area Scan (141x141x1):** Interpolated grid: dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 0.536 W/kg

BODY BACK /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 7.445 V/m; Power Drift = 0.09 dB Peak SAR (extrapolated) = 0.542 W/kg SAR(1 g) = 0.253 W/kg; SAR(10 g) = 0.121 W/kg Maximum value of SAR (measured) = 0.539 W/kg



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### Report No.: 18220WC20173403 #2

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## 2.4G Bluetooth BLE GFSK\_2M\_2480 BODY BACK

Communication System: UID 0, wifi (fcc) (0); Frequency: 2437 MHz;Duty Cycle: 1:1

Medium parameters used (interpolated): f = 2437 MHz;  $\sigma$  = 1.91 S/m;  $\epsilon_r$  = 52.43;  $\rho$  = 1000 kg/m<sup>3</sup>

Phantom section: Flat Section

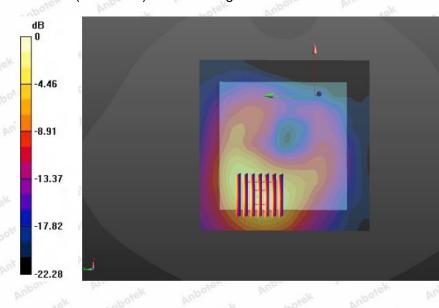
### DASY5 Configuration:

- Probe: EX3DV4 SN7396; ConvF(7.53, 7.53, 7.53); Calibrated: May 06, 2022;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: Sep. 06, 2021
- Phantom: SAM; Type: QD000P40CD; Serial: TP:1670
- Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

**BODY BACK /Area Scan (141x141x1):** Interpolated grid: dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 0.493 W/kg

**BODY BACK /Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 6.522 V/m; Power Drift = -0.05 dB Peak SAR (extrapolated) = 1.024 W/kg

SAR(1 g) = 0.217 W/kg; SAR(10 g) = 0.104 W/kgMaximum value of SAR (measured) = 0.517 W/kg



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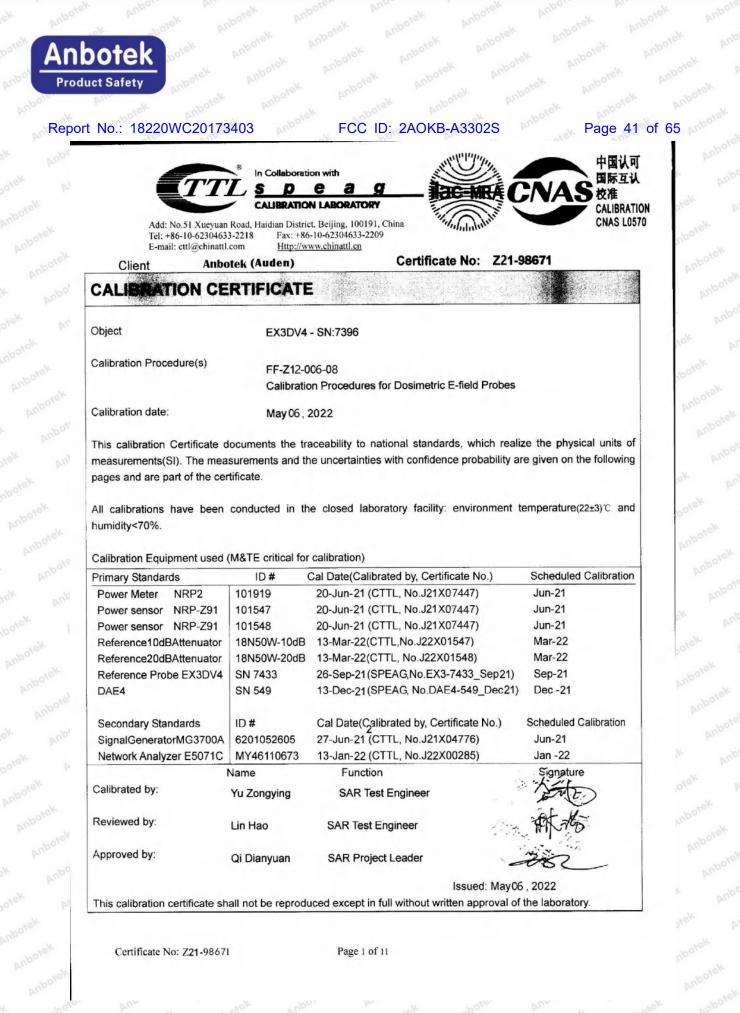
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# Appendix D. DASY System Calibration Certificate

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### In Colleboration with

CALIBRATION LABORATORY

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#### Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConvF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A,B,C,D	modulation dependent linearization parameters
Polarization Φ	Φ rotation around probe axis
Polarization 0	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i
	θ=0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
- c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010

d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORMx, y, z: Assessed for E-field polarization θ=0 (f≤900MHz in TEM-cell; f>1800MHz: waveguide). NORMx, y, z are only intermediate values, i.e., the uncertainties of NORMx, y, z does not effect the E<sup>2</sup>-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z\* frequency\_response (see Frequency Response Chart). This
  linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the
  frequency response is included in the stated uncertainty of ConvF.
- DCPx, y, z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.
- Ax,y,z; Bx,y,z; Cx,y,z; VRx,y,z:A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f≤800MHz) and inside waveguide using analytical field distributions based on power measurements for f >800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z\* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from±50MHz to±100MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the
  probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

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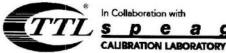
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a

# Probe EX3DV4

# SN: 7396

Calibrated: May 06, 2022

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

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# DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

### **Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm(µV/(V/m) <sup>2</sup> ) <sup>A</sup>	0.54	0.53	0.50	±10.0%
DCP(mV) <sup>B</sup>	97.8	104.5	102.5	

### **Modulation Calibration Parameters**

UID	Communication System Name		A dB	B dBõV	C	D dB	VR mV	Unc <sup>E</sup> (k=2)
0	CW	x	0.0	0.0	1.0	0.00	199.9	±2.4%
		Y	0.0	0.0	1.0		203.3	
		Z	0.0	0.0	1.0		195.0	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of Norm X, Y, Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 5 and Page 6).
<sup>B</sup> Numerical linearization parameter: uncertainty not required.

<sup>E</sup> Uncertainly is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

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# DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

### Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz] <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha <sup>G</sup>	Depth <sup>G</sup> (mm)	Unct. (k=2)
750	41.9	0.89	9.82	9.82	9.82	0.30	0.85	±12.1%
835	41.5	0.90	9.71	9.71	9.71	0.15	1.36	±12.1%
900	41.5	0.97	9.87	9.87	9.87	0.16	1.37	±12.1%
1750	40.1	1.37	8.61	8.61	8.61	0.25	1.04	±12.1%
1900	40.0	1.40	8.13	8.13	8.13	0.24	1.01	±12.1%
2100	39.8	1.49	8.14	8.14	8.14	0.24	1.04	±12.1%
2300	39.5	1.67	7.85	7.85	7.85	0.40	0.75	±12.1%
2450	39.2	1.80	7.57	7.57	7.57	0.50	0.75	±12.1%
2600	39.0	1.96	7.38	7.38	7.38	0.64	0.68	±12.1%
5250	35.9	4.71	5.33	5.33	5.33	0.45	1.30	±13.3%
5600	35.5	5.07	4.89	4.89	4.89	0.45	1.35	±13.3%
5750	35.4	5.22	4.92	4.92	4.92	0.45	1.45	±13.3%

<sup>C</sup> Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

<sup>F</sup> At frequency below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

<sup>6</sup> Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than  $\pm$  1% for frequencies below 3 GHz and below  $\pm$  2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

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# DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

#### Calibration Parameter Determined in Body Tissue Simulating Media

f [MHz] <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha <sup>G</sup>	Depth <sup>G</sup> (mm)	Unct. (k=2)
750	55.5	0.96	10.09	10.09	10.09	0.30	0.90	±12.1%
835	55.2	0.97	9.88	9.88	9.88	0.19	1.32	±12.1%
900	55.0	1.05	9.82	9.82	9.82	0.23	1.15	±12.1%
1750	53.4	1.49	8.24	8.24	8.24	0.24	1.06	±12.1%
1900	53.3	1.52	7.97	7.97	7.97	0.19	1.24	±12.1%
2100	53.2	1.62	8.18	8.18	8.18	0.19	1.39	±12.1%
2300	52.9	1.81	7.88	7.88	7.88	0.55	0.80	±12.1%
2450	52.7	1.95	7.53	7.53	7.53	0.46	0.89	±12.1%
2600	52.5	2.16	7.38	7.38	7.38	0.52	0.80	±12.1%
5250	48.9	5.36	4.93	4.93	4.93	0.45	1.80	±13.3%
5600	48.5	5.77	4.19	4.19	4.19	0.48	1.90	±13.3%
5750	48.3	5.94	4.52	4.52	4.52	0.48	1.95	±13.3%

<sup>C</sup> Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

<sup>F</sup> At frequency below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

<sup>G</sup> Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than  $\pm$  1% for frequencies below 3 GHz and below  $\pm$  2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

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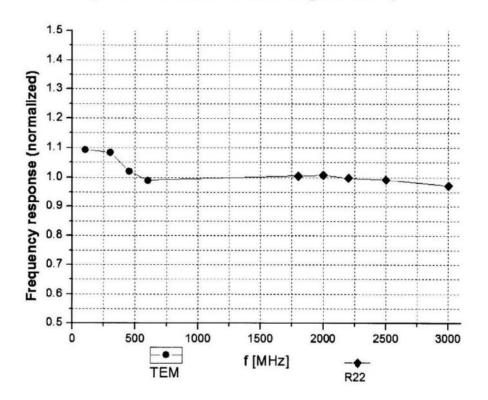


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### Frequency Response of E-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ±7.4% (k=2)

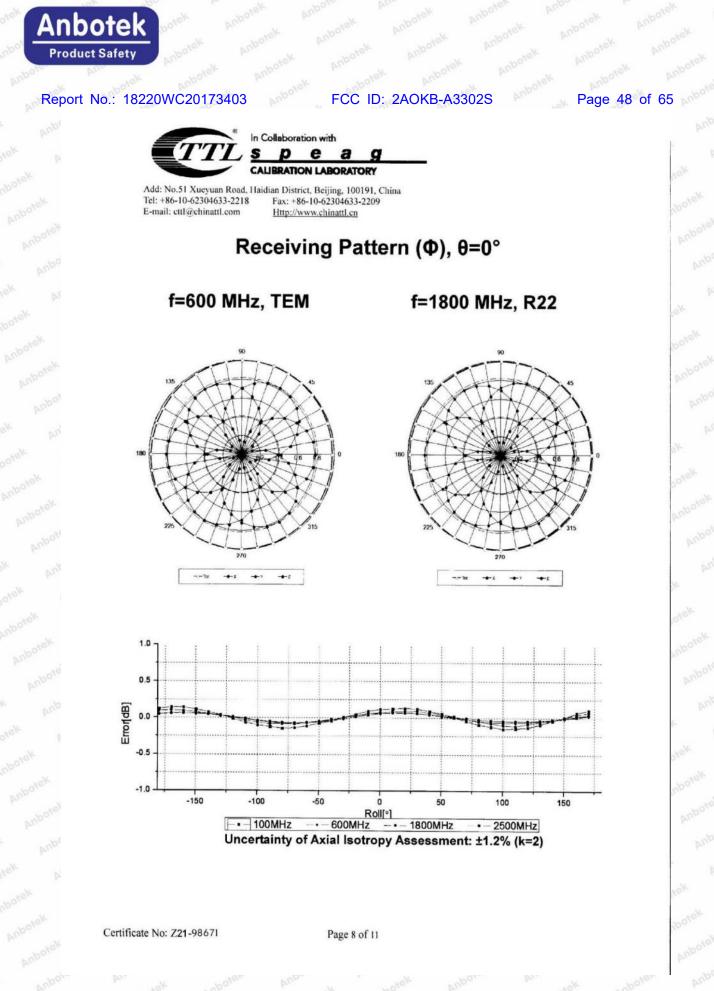
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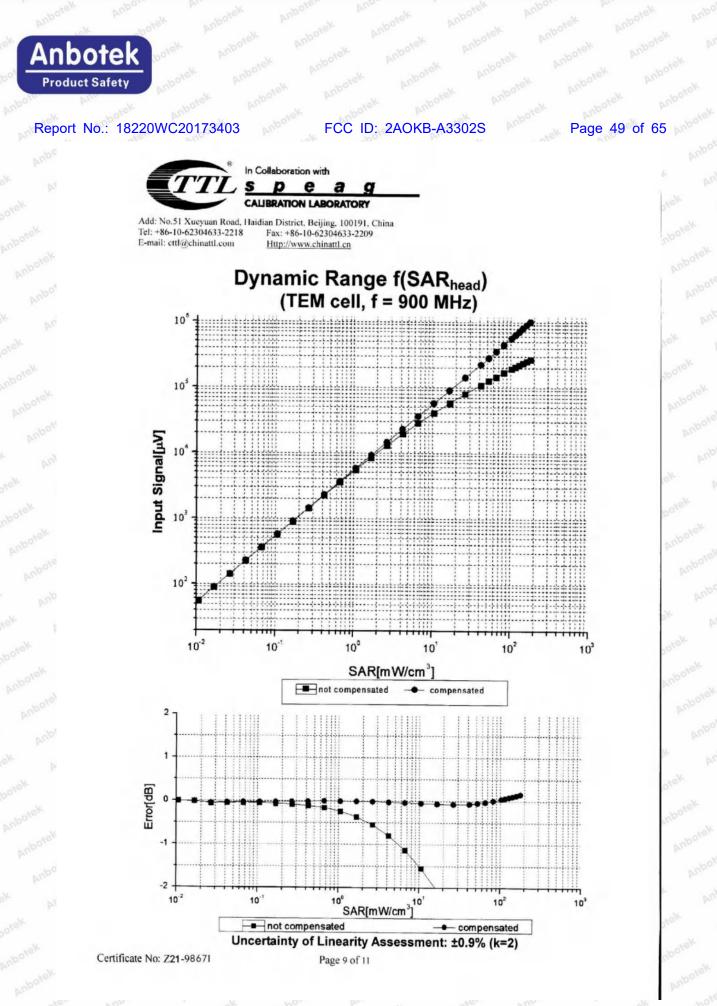




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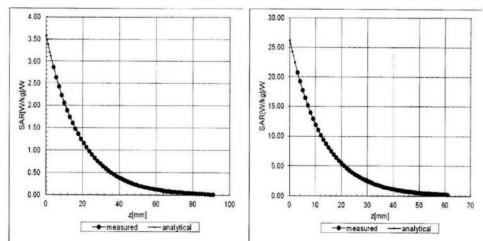
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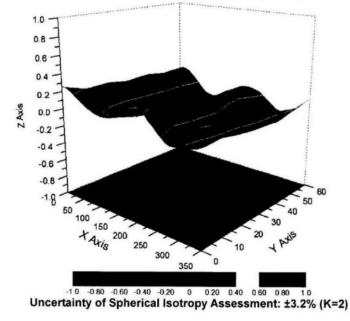
# **Conversion Factor Assessment**

### f=900 MHz, WGLS R9(H\_convF)

f=1750 MHz, WGLS R22(H\_convF)



# **Deviation from Isotropy in Liquid**



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# DASY/EASY - Parameters of Probe: EX3DV4 - SN: 7396

### **Other Probe Parameters**

Sensor Arrangement	Triangular
Connector Angle (°)	156.9
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disable
Probe Overall Length	337mm
Probe Body Diameter	10mm
Tip Length	9mm
Tip Diameter	2.5mm
Probe Tip to Sensor X Calibration Point	1mm
Probe Tip to Sensor Y Calibration Point	1mm
Probe Tip to Sensor Z Calibration Point	1mm
Recommended Measurement Distance from Surface	1.4mm

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FCC ID: 2AOKB-A3302S

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Schmid & Partner Engineering AG

#### s p e a g

Zeughausstrasse 43, 8004 Zurich, Switzerland Phone +41 44 245 9700, Fax +41 44 245 9779 info@speag.com, http://www.speag.com

### **IMPORTANT NOTICE**

#### USAGE OF THE DAE 4

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

Battery Exchange: The battery cover of the DAE4 unit is closed using a screw, over tightening the screw may cause the threads inside the DAE to wear out.

Shipping of the DAE: Before shipping the DAE to SPEAG for calibration, remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

E-Stop Failures: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, the customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

Repair: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

DASY Configuration Files: Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

#### Important Note:

Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.

#### Important Note:

Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the Estop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

#### Important Note:

To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.

Schmid & Partner Engineering

TN\_BR040315AD DAE4.doc

11.12.2009

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Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland



Schweizerischer Kalibrierdienst Service suisse d'étalonnage Servizio svizzero di taratura Swiss Calibration Service

#### Accreditation No.: SCS 0108

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Accredited by the Swiss Accreditation Service (SAS) The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Client Anbotek (Auden)

Certificate No: DAE4-387\_Sep10

Dbject	DAE4 - SD 000 D	04 BM - SN: 387	
Calibration procedure(s)	QA CAL-06.v29		
	Calibration procee	dure for the data acquisition elec	ctronics (DAE)
Calibration date:	September 06, 20	21	
he measurements and the un	certainties with confidence pro	nal standards, which realize the physical un obability are given on the following pages ar	nd are part of the certificate.
Il calibrations have been conc	lucted in the closed laboratory	r facility: environment temperature (22 $\pm$ 3)°	C and humidity < 70%.
Calibration Equipment used (M	&TE critical for calibration)		
	&TE critical for calibration)	Cal Date (Certificate No.)	Scheduled Calibration
rimary Standards		Cal Date (Certificate No.) 15-Aug-20 (No:21092)	Scheduled Calibration Aug-21
Primary Standards Keithley Multimeter Type 2001	ID #		
rimary Standards eithley Multimeter Type 2001 econdary Standards uto DAE Calibration Unit	ID # SN: 0810278 ID # SE UWS 053 AA 1001	15-Aug-20 (No:21092) Check Date (in house) 05-Jan-21 (in house check)	Aug-21 Scheduled Check In house check: Jan-22
Primary Standards Keithley Multimeter Type 2001 Secondary Standards Auto DAE Calibration Unit	ID # SN: 0810278 ID # SE UWS 053 AA 1001	15-Aug-20 (No:21092) Check Date (in house)	Aug-21 Scheduled Check
Calibration Equipment used (M Primary Standards Keithley Multimeter Type 2001 Secondary Standards Auto DAE Calibration Unit Calibrator Box V2.1	ID # SN: 0810278 ID # SE UWS 053 AA 1001	15-Aug-20 (No:21092) Check Date (in house) 05-Jan-21 (in house check)	Aug-21 Scheduled Check In house check: Jan-22 In house check: Jan-22
Primary Standards Keithley Multimeter Type 2001 Secondary Standards Auto DAE Calibration Unit	ID # SN: 0810278 ID # SE UWS 053 AA 1001 SE UMS 006 AA 1002	15-Aug-20 (No:21092) Check Date (in house) 05-Jan-21 (in house check) 05-Jan-21 (in house check)	Aug-21 Scheduled Check In house check: Jan-22
Primary Standards Keithley Multimeter Type 2001 Secondary Standards Juto DAE Calibration Unit Calibrator Box V2.1	ID # SN: 0810278 ID # SE UWS 053 AA 1001 SE UMS 006 AA 1002	15-Aug-20 (No:21092) Check Date (in house) 05-Jan-21 (in house check) 05-Jan-21 (in house check) Function	Aug-21 Scheduled Check In house check: Jan-22 In house check: Jan-22 Signature
Primary Standards Keithley Multimeter Type 2001 Secondary Standards Juto DAE Calibration Unit Calibrator Box V2.1	ID # SN: 0810278 ID # SE UWS 053 AA 1001 SE UMS 006 AA 1002	15-Aug-20 (No:21092) Check Date (in house) 05-Jan-21 (in house check) 05-Jan-21 (in house check) Function	Aug-21 Scheduled Check In house check: Jan-22 In house check: Jan-22

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Schweizerischer Kalibrierdienst Service suisse d'étalonnage Servizio svizzero di taratura Swiss Calibration Service

Accreditation No.: SCS 0108

Accredited by the Swiss Accreditation Service (SAS) The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

#### Glossary

DAE Connector angle data acquisition electronics information used in DASY system to align probe sensor X to the robot coordinate system.

#### Methods Applied and Interpretation of Parameters

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
  - Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
  - AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
  - Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
  - Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - Input resistance: Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
  - Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
  - *Power consumption:* Typical value for information. Supply currents in various operating modes.

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#### DC Voltage Measurement

High Range:	1LSB =	6.1µV.	full range =	-100+300 mV
Low Range:	1LSB =	61nV .	9	-1+3mV

<b>Calibration Factors</b>	X	Y	z
High Range	404.489 ± 0.02% (k=2)	404.852 ± 0.02% (k=2)	404.862 ± 0.02% (k=2)
Low Range	3.97827 ± 1.50% (k=2)	3.95875 ± 1.50% (k=2)	3.97982 ± 1.50% (k=2)

#### **Connector Angle**

Connector Angle to be used in DASY system	53.0 ° ± 1 °
---	--------------

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### Appendix (Additional assessments outside the scope of SCS0108)

### 1. DC Voltage Linearity

High Range	Reading (µV)	Difference (µV)	Error (%)
Channel X + Input	200032.85	-3.31	-0.00
Channel X + Input	20007.64	1.88	0.01
Channel X - Input	-20003.48	1.18	-0.01
Channel Y + Input	200034.23	-1.43	-0.00
Channel Y + Input	20006.60	0.91	0.00
Channel Y - Input	-20004.04	0.72	-0.00
Channel Z + Input	200035.38	-0.83	-0.00
Channel Z + Input	20003.69	-2.11	-0.01
Channel Z - Input	-20006.38	-1.59	0.01

Reading (µV)	Difference (µV)	Error (%)
2001.63	0.08	0.00
202.29	0.70	0.35
-197.90	0.60	-0.30
2001.33	-0.07	-0.00
200.86	-0.60	-0.30
-199.87	-1.23	0.62
2001.61	0.27	0.01
200.60	-0.70	-0.35
-199.51	-0.85	0.43
	2001.63 202.29 -197.90 2001.33 200.86 -199.87 2001.61 200.60	2001.63         0.08           202.29         0.70           -197.90         0.60           2001.33         -0.07           200.86         -0.60           -199.87         -1.23           2001.61         0.27           200.60         -0.70

#### 2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	13.50	11.56
	- 200	-8.64	-11.18
Channel Y	200	-0.81	-1.28
	- 200	1.05	0.09
Channel Z	200	7.17	6.91
	- 200	-9.46	-9.01

#### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (µV)	Channel Y (µV)	Channel Z (µV)
Channel X	200	-	-1.70	0.33
Channel Y	200	10.70	-	-0.38
Channel Z	200	7.11	7.89	-

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### 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15969	17466
Channel Y	15661	16162
Channel Z	15990	16190

#### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec Input 10  $M\Omega$ 

	Average (µV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (µV)
Channel X	0.73	-2.58	3.29	0.62
Channel Y	0.41	-0.49	1.23	0.40
Channel Z	-0.80	-1.88	0.30	0.42

#### 6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

### 7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

### 8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)	
Supply (+ Vcc)	+7.9	
Supply (- Vcc)	-7.6	

### 9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9

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	Name	Function	Signature
Calibrated by:	Zhao Jing	SAR Test Engineer	221
Reviewed by:	Qi Dianyuan	SAR Project Leader	too
Approved by:	Lu Bingsong	Deputy Director of the laboratory	m. usos
This solibustion on tit		Issued: Jun 17	

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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 Http://www.chinattl.cn

#### Glossary: TSL ConvF N/A

Anbotek

tissue simulating liquid sensitivity in TSL / NORMx,y,z not applicable or not measured

In Collaboration with

### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) For hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
- c) IEC 62209-2, "Procedure to measure the Specific Absorption Rate (SAR) For wireless communication devices used in close proximity to the human body (frequency range of 30MHz to 6GHz)", March 2010
- d) KDB865664, SAR Measurement Requirements for 100 MHz to 6 GHz

### Additional Documentation:

e) DASY4/5 System Handbook

### Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end
  of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed
  point exactly below the center marking of the flat phantom section, with the arms oriented
  parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole
  positioned under the liquid filled phantom. The impedance stated is transformed from the
  measurement at the SMA connector to the feed point. The Return Loss ensures low
  reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

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#### Measurement Conditions

 DASY system configuration, as far as not given on page 1.

 DASY Version
 DASY52
 52.8.8.1258

 Extrapolation
 Advanced Extrapolation

 Phantom
 Triple Flat Phantom 5.1C

 Distance Dipole Center - TSL
 10 mm
 with Spacer

 Zoom Scan Resolution
 dx, dy, dz = 5 mm

 Frequency
 2450 MHz ± 1 MHz

#### **Head TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	39.0 ± 6 %	1.77 mho/m ± 6 %
Head TSL temperature change during test	<1.0 °C		

#### SAR result with Head TSL

SAR averaged over 1 $cm^3$ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	13.0 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	52.4 mW /g ± 20.8 % (k=2)
SAR averaged over 10 $cm^3$ (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	6.06 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	24.3 mW /g ± 20.4 % (k=2)

#### Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	52.9 ± 6 %	1.97 mho/m ± 6 %
Body TSL temperature change during test	<1.0 °C		

#### SAR result with Body TSL

SAR averaged over 1 $cm^3$ (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	13.0 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	51.8 mW /g ± 20.8 % (k=2)
SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	Condition	
SAR measured	250 mW input power	6.18 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	24.7 mW /g ± 20.4 % (k=2)

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#### Appendix

#### Antenna Parameters with Head TSL

Impedance, transformed to feed point	54.6Ω+ 2.77jΩ
Return Loss	- 25.8dB

#### Antenna Parameters with Body TSL

Impedance, transformed to feed point	50.7Ω+ 4.28jΩ	
Return Loss	- 27.3dB	

#### **General Antenna Parameters and Design**

Electrical Delay (one direction)	1.263 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

#### **Additional EUT Data**

Manufactured by	SPEAG

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### **DASY5 Validation Report for Head TSL**

Test Laboratory: CTTL, Beijing, China

Date: 06.15.2021

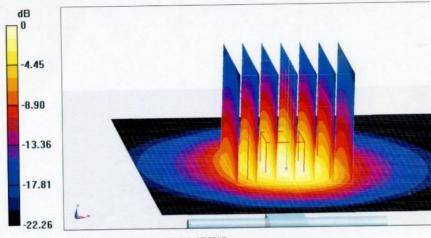
**DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 910** Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1 Medium parameters used: f = 2450 MHz;  $\sigma = 1.767$  S/m;  $\epsilon r = 39.01$ ;  $\rho = 1000$  kg/m3 Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 SN7307; ConvF(7.36, 7.36, 7.36); Calibrated: 2/19/2021;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn771; Calibrated: 2021-02-02
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7372)

**Dipole Calibration**/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 106.5 V/m; Power Drift = 0.02 dB Peak SAR (extrapolated) = 26.7 W/kg SAR(1 g) = 13 W/kg; SAR(10 g) = 6.06 W/kg Maximum value of SAR (measured) = 19.7 W/kg



0 dB = 19.7 W/kg = 12.94 dBW/kg

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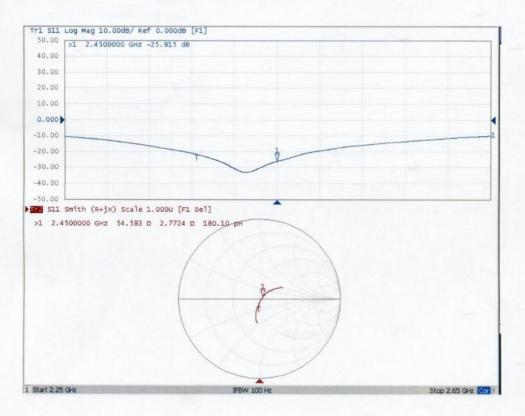
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#### Impedance Measurement Plot for Head TSL



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 Http://www.chinattl.cn

#### DASY5 Validation Report for Body TSL Test Laboratory: CTTL, Beijing, China

Date: 06.15.2021

**DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 910** Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1 Medium parameters used: f = 2450 MHz;  $\sigma = 1.972$  S/m;  $\epsilon_r = 52.92$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Center Section Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

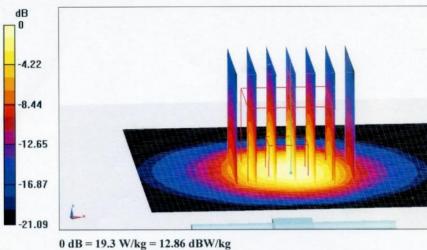
DASY5 Configuration:

- Probe: EX3DV4 SN7307; ConvF(7.22, 7.22, 7.22); Calibrated: 2/19/2021;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn771; Calibrated: 2021-02-02
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7372)

**Dipole Calibration**/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 98.89 V/m; Power Drift = 0.03 dBPeak SAR (extrapolated) = 25.6 W/kgSAR(1 g) = 13 W/kg; SAR(10 g) = 6.18 W/kg

Maximum value of SAR (measured) = 19.3 W/kg



0 dB = 19.5 W/kg = 12.80 dB W/

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#### Shenzhen Anbotek Compliance Laboratory Limited

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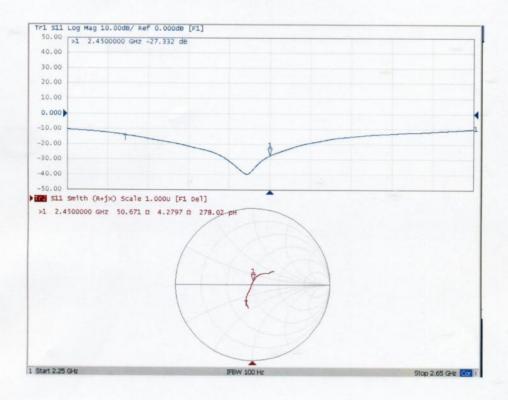


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#### Impedance Measurement Plot for Body TSL



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# \*\*\*\*\*END OF REPORT\*\*\*\*\*

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