

# **SAR Test Report**

Report No.: AGC01110201143FH01

**FCC ID** : 2AOKB-A3126

APPLICATION PURPOSE : Original Equipment

**PRODUCT DESIGNATION**: Wireless Speaker

**BRAND NAME** : Soundcore

MODEL NAME : A3126

**APPLICANT**: Anker Innovations Limited

**DATE OF ISSUE**: Dec. 28,2020

IEEE Std. 1528:2013

**STANDARD(S)**FCC 47 CFR Part 2§2.1093:2013

: IFFE 5td C05 1 ™ 2005

: IEEE Std C95.1 ™-2005 IEC 62209-1: 2016

REPORT VERSION : V1.0

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# **Report Revise Record**

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0		Dec. 28,2020	Valid	Initial Release

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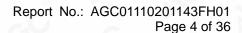
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	Test Report Certification
Applicant Name	Anker Innovations Limited
Applicant Address	Room 1318-19, Hollywood Plaza, 610 Nathan Road, Mongkok, Kowloon, Hongkong
Manufacturer Name	Anker Innovations Limited
Manufacturer Address	Room 1318-19, Hollywood Plaza, 610 Nathan Road, Mongkok, Kowloon, Hongkong
Factory Name	GANZHOU DEHUIDA TECHNOLOGY CO., LTD
Factory Address	Dehuida Science and Technology Park, Huoyanshan Road, Anyuan District, Ganzhou City, Jiangxi Province. P.R China.
Product Designation	Wireless Speaker
Brand Name	Soundcore
Model Name	A3126
EUT Voltage	DC7.2V by battery
Applicable Standard	IEEE Std. 1528:2013; FCC 47 CFR Part 2§2.1093:2013; IEEE Std C95.1 ™-2005; IEC 62209-1: 2016;
Test Date	Dec. 25,2020
Report Template	AGCRT-US-Bluetooth/SAR (2018-01-01)

Note: The results of testing in this report apply to the product/system which was tested only.

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#### 1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Frequency Band	Highest Reported 1g-SAR(W/Kg)	SAR Test Result
Bluetooth	0.865	DASS
SAR Test Limit (W/Kg)	1.6	PASS

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6W/Kg) specified in IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE/ANSI C95.1:2005 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v06
- KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04

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# 2. GENERAL INFORMATION

2.1. EUT Description

General Information	
Product Designation	Wireless Speaker
Test Model	A3126
Hardware Version	V2.0
Software Version	V0.02
Duty cycle	77%(test mode)
Device Category	Portable
RF Exposure Environment	Uncontrolled
Antenna Type	Internal
Bluetooth	
Operation Frequency	2402~2480MHz
Antenna Gain	3.25dBi
Bluetooth Version	V5.0
Type of modulation	BR/EDR: GFSK, π /4-DQPSK, 8-DPSK; BLE: GFSK;
Peak Output Power	BR/EDR: 10.450dBm; BLE: 2.670dBm;
Power Supply	DC 7.2V, 3350mAh by battery

Note: 1.The sample used for testing is end product.

2. The test sample has no any deviation to the test method of standard mentioned in page 1.

3. Duty-cycle = [on time/total time] x 100%

Product	Type		
Product	□ Production unit	☐ Identical Prototype	

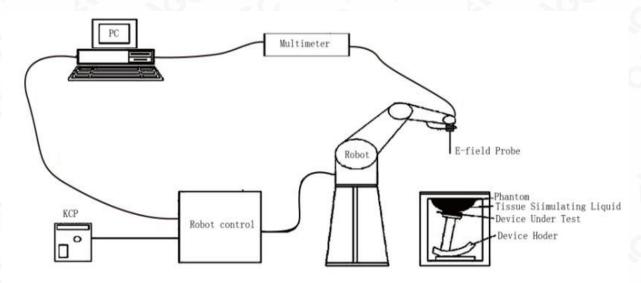
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#### 3. SAR MEASUREMENT SYSTEM

#### 3.1. The SATIMO system used for performing compliance tests consists of following items



The COMOSAR system for performing compliance tests consists of the following items:

- The PC. It controls most of the bench devices and stores measurement data. A computer running WinXP and the Opensar software.
- The E-Field probe. The probe is a 3-axis system made of 3 distinct dipoles. Each dipole returns a voltage in function of the ambient electric field.
- · The Keithley multimeter measures each probe dipole voltages.
- The SAM phantom simulates a human head. The measurement of the electric field is made inside the phantom.
- The liquids simulate the dielectric properties of the human head tissues.
- · The network emulator controls the mobile phone under test.
- The validation dipoles are used to measure a reference SAR. They are used to periodically check the bench to make sure that there is no drift of the system characteristics over time.
- •The phantom, the device holder and other accessories according to the targeted measurement.

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## 3.2. COMOSAR E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SATIMO. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SATIMO conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528 and relevant KDB files.) The calibration data are in Appendix D.

## **Isotropic E-Field Probe Specification**

Model	SSE5				
Manufacture	MVG				
Identification No.	SN 24/20 EP336				
Frequency	0.7GHz-3GHz Linearity:±0.08dB(0.7GHz-3GHz)				
Dynamic Range	0.01W/Kg-100W/Kg Linearity:±0.08dB				
Dimensions	Overall length:330mm Length of individual dipoles:4.5mm Maximum external diameter:8mm Probe Tip external diameter:5mm Distance between dipoles/ probe extremity:2.7mm				
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 3 GHz with precisin of better 30%.				

#### 3.3. Robot

The COMOSAR system uses the KUKA robot from SATIMO SA (France). For the 6-axis controller COMOSAR system, the KUKA robot controller version from SATIMO is used.

The XL robot series have many features that are important for our application:

- ☐ High precision (repeatability 0.02 mm)
- ☐ High reliability (industrial design)
- ☐ Jerk-free straight movements
- ☐ Low ELF interference (the closed metallic

construction shields against motor control fields)

□ 6-axis controller



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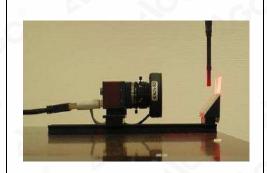
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## 3.4. Video Positioning System

The video positioning system is used in OpenSAR to check the probe. Which is composed of a camera, LED, mirror and mechanical parts. The camera is piloted by the main computer with firewire link.

During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.

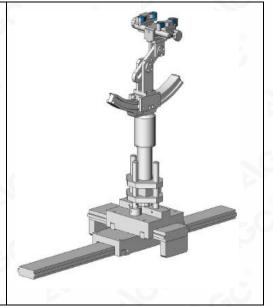


#### 3.5. Device Holder

The COMOSAR device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles. The COMOSAR device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity

 $\epsilon r = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



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#### 3.6. SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

□ Left head

☐ Right head

☐ Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

#### **ELLI39 Phantom**

The Flat phantom is a fiberglass shellphantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom



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#### 4. SAR MEASUREMENT PROCEDURE

# 4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element(dv) of given mass density ( $\rho$ ). The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg) SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \frac{dT}{dt}\Big|_{t=0}$$

Where

SAR is the specific absorption rate in watts per kilogram;
E is the r.m.s. value of the electric field strength in the tissue in volts per meter;
σ is the conductivity of the tissue in siemens per metre;
ρ is the density of the tissue in kilograms per cubic metre;
ch is the heat capacity of the tissue in joules per kilogram and Kelvin;

 $\frac{dT}{dt}$  | t=0 is the initial time derivative of temperature in the tissue in kelvins per second

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#### 4.2. SAR Measurement Procedure

#### Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance os sensor calibration points to probe tip as `defined in the probe properties,

#### Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in SATIMO software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	≤ 3 GHz	> 3 GHz	
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 ± 1 mm	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$	
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30° ± 1°	20° ± 1°	
	≤2 GHz: ≤15 mm 2 – 3 GHz: ≤12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm	
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$	When the x or y dimension of measurement plane orientation the measurement resolution of x or y dimension of the test of measurement point on the test.	on, is smaller than the above, must be ≤ the corresponding levice with at least one	

#### Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g abd 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

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#### Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

Maximum zoom scan s	Maximum zoom scan spatial resolution: Δx <sub>Zoom</sub> , Δy <sub>Zoom</sub>			3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*	
	uniform	grid: $\Delta z_{Zoom}(n)$	≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm	
Maximum zoom scan spatial resolution, normal to phantom surface	graded	Δz <sub>Zoom</sub> (1): between 1 <sup>st</sup> two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm	
	grid $\Delta z_{Zoom}(n>1)$ : between subsequent points		$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$		
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm	

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.

#### Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

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<sup>\*</sup> When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.



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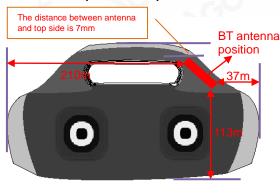
#### 4.3. RF Exposure Conditions

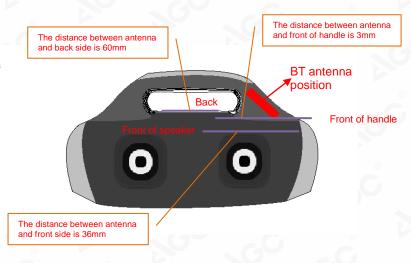
Test Configuration and setting:

The device is a bluetooth speaker and supports Bluetooth wireless technology.

For SAR testing, the device was controlled by software to test at reference fixed frequency points.

#### **Antenna Location: (Front view)**





#### **SAR Test Exclusion Consideration for Adjacent Edges**

Per KDB 447498 D01 cl. 4.3.1:

a) For 100 MHz to 6 GHz and test separation distances ≤ 50 mm, the 1-g and 10-g SAR test exclusion thresholds are determine d by the following:

[(max. power of channel, including tune-up tolerance, mW) / (min. test separation distance, mm)] • [ $\sqrt{f(GHz)}$ ]  $\leq 3.0$  for1-g SAR, and  $\leq 7.5$  for 10-g extremity SAR.

- b) For 100 MHz to 6 GHz and test separation distances > 50 mm, the 1-g and 10-g SAR test exclusion thresholds are determine d by the following:
- 1) {[Power allowed at numeric threshold for 50 mm in step a)] + [(test separation distance 50 mm)•(f(MHz)/150)]} mW, for 100 MHz to 1500 MHz
- 2) {[Power allowed at numeric threshold for 50 mm in step a)] + [(test separation distance 50 mm)•10]} mW, for > 1500 MHz an  $d \le 6$  GHz

		1-g SAR t	est exclusion thr	esholds for 2.4	GHz BT			
position Test Mode	Test	Back (60mm)	Front of speaker (36mm) Front of handle(3mm)		Top (7mm)	Right (37mm)	Bottom (113mm)	Left (210mm)
BR/EDR	SAR test exclusion thresholds(mW)	196.78	69.68	5.81	13.55	71.62	726.78	1696.78
DK/EDK	BR/EDR:SAR required (Yes/No)	No	No	Yes	No	No	No	No
BLE	SAR test exclusion thresholds(mW)	196.03	69.14	5.76	13.44	71.06	726.03	1696.03
DLE	BLE: SAR required (Yes/No)	No	No	No	No	No	No	No

#### Conclusion

**BR/EDR:**Since the Maximum Tune-up Power [10.09mW(10.450dBm)] is less than the SAR Exclusion Threshold for front of speaker, back, bottom, top, right and left edges, SAR evaluation for these adjacent edges are not required.

**BLE:** Since the Maximum Tune-up Power [1.85mW(2.670dBm)] is less than the SAR Exclusion Threshold for back, front of speaker, front of handle,top, bottom, left and Right edges, SAR evaluation for these adjacent edges are not required.

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#### 5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 10% are listed in 6.2

5.1. The composition of the tissue simulating liquid

Ingredient (% Weight) Frequency (MHz)	Water	Nacl	Polysorbate 20	DGBE	1,2 Propanediol	Triton X-100
2450 Head	71.88	0.16	0.0	7.99	0.0	19.97

#### 5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEC 62209-1 have been incorporated in the following table. The body tissue dielectric parameters recommended by the IEC 62209-2 have been incorporated in the following table.

Target Frequency	he	ead	body				
(MHz)	εr	σ (S/m)	εr	σ (S/m)			
300	45.3	0.87	45.3	0.87			
450	43.5	0.87	43.5	0.87			
835	41.5	0.90	41.5	0.90			
900	41.5	0.97	41.5	0.97			
915	41.5	1.01	41.5	1.01			
1450	40.5	1.20	40.5	1.20			
1610	40.3	1.29	40.3	1.29			
1800 – 2000	40.0	1.40	40.0	1.40			
2450	39.2	1.80	39.2	1.80			
3000	38.5	2.40	38.5	2.40			

( $\varepsilon r = relative permittivity, \sigma = conductivity and \rho = 1000 kg/m3)$ 

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#### 5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using SATIMO Dielectric Probe Kit and R&S Network Analyzer ZVL6.

	Tissue Stimulant Measurement for 2450MHz									
	Fr.	Dielectric Para	ameters (±10%)	Tissue	7 G					
	(MHz)	εr39.2(35.28-43.12)	δ[s/m]1.80(1.62-1.98)	Temp [°C]	Test time					
Head	2402	40.62	1.76	<u>®</u>						
	2441	39.28	1.79	20.2	Dec. 25,2020					
	2450	38.13	1.82	20.3	Dec. 25,2020					
	2480	37.71	1.83	0						

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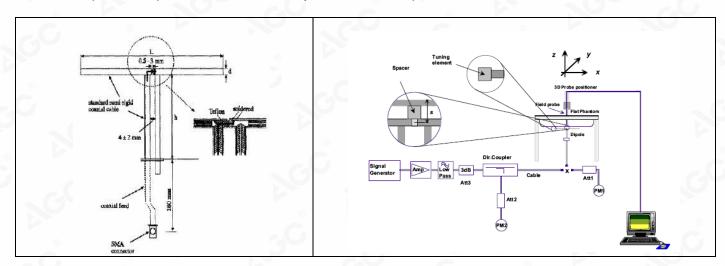
#### 6. SAR SYSTEM CHECK PROCEDURE

#### 6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each SATIMO system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the SATIMO software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.

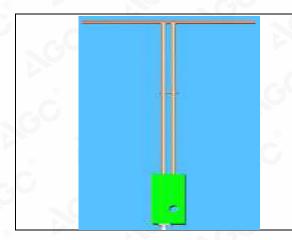


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# 6.2. SAR System Check 6.2.1. Dipoles



The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. the table below provides details for the mechanical and electrical Specifications for the dipoles.

Frequency	L (mm)	h (mm)	d (mm)		
2450MHz	51.5	30.4	3.6		

#### 6.2.2. System Check Result

System Performance Check at 2450MHz for Head									
Validation Kit: SN 46/11 DIP 2G450-189									
Frequency		get W/Kg)	Reference Result Tested Tissue (± 10%) Value(W/Kg) Temp. Test time						
[MHz]	1g	10g	1g 10g		1g	10g	[°C]	@	
2450	53.97	24.01	48.573-59.367	21.609-26.411	53.61	24.08	20.3	Dec. 25,2020	

Note:

(1) We use a CW signal of 18dBm for system check, and then all SAR values are normalized to 1W forward power. The result must be within  $\pm 10\%$  of target value.

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6.2.3. SAR System Validation

					I Cond I Parm I		CV	V validation	Mod. validation			
	Test Data	Probe S/N	Tested Freq. (MHz)	Tissue Type		Sensitivity	Probe Linearity	Probe Isotropy	Mod. Type	Duty Factor	Peak to average power ratio	
	07/23/2020	SN 24/20 EP336	2450	head	1.78	38.65	PASS	PASS	PASS	OFDM	N/A	PASS
)	07/23/2020	SN 24/20 EP336	2450	head	1.81	39.02	PASS	PASS	PASS	DSSS	PASS	N/A

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#### 7. EUT TEST POSITION

This EUT was tested in Front surface of the handle.

## 7.1. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to 0mm.

The SAR test procedure has been defined by FCC via KDB.

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# 8. SAR EXPOSURE LIMITS

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit (W/kg)
Spatial Peak SAR (1g cube tissue for brain or body)	1.60
Spatial Average SAR (Whole body)	0.08
Spatial Peak SAR (Limbs)	4.0

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# 9. TEST FACILITY

Test Site	Attestation of Global Compliance (Shenzhen) Co., Ltd
Location	1-2/F, Building 19, Junfeng Industrial Park, Chongqing Road, Heping Community, Fuhai Street, Bao'an District, Shenzhen, Guangdong, China
Designation Number	CN1259
A2LA Cert. No.	5054.02
Description	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by A2LA

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# 10. TEST EQUIPMENT LIST

Equipment description	Manufacturer/ Model	Identification No.	Current calibration date	Next calibration date	
SAR Probe	MVG	SN 24/20 EP336	Jun. 24,2020	Jun. 23,2021	
Phantom	SATIMO	SN_4511_SAM90	Validated. No cal required.	Validated. No cal required.	
Liquid	SATIMO		Validated. No cal required.	Validated. No cal required.	
Phantom	SATIMO	SN_2316_ELLI39	Validated. No cal required.	Validated. No cal required.	
Multimeter	Keithley 2000	4114939	Sep. 07,2020	Sep. 06,2021	
Dipole	SATIMO SID2450	SN 46/11 DIP 2G450-189	Apr. 26,2019	Apr. 25,2022	
Signal Generator	Agilent-E4438C	US41461365	Aug. 21,2020	Aug. 20,2021	
Vector Analyzer	Agilent / E4440A	US41421290	Sep. 06,2020	Sep. 05,2021	
Network Analyzer	Rhode & Schwarz ZVL6	SN101443	Oct. 16,2020	Oct. 15,2021	
Attenuator	Warison /WATT-6SR1211	S/N:WRJ34AYM2F1	June 10,2020	June 09,2021	
Attenuator	Mini-circuits / VAT-10+	31405	June 10,2020	June 09,2021	
Amplifier	AS0104-55_55	1004793	June 11,2020	June 10,2021	
Directional Couple	Werlatone/ C5571-10	SN99463	May 15,2020	May 14,2022	
Directional Couple	Werlatone/ C6026-10	SN99482	May 15,2020	May 14,2022	
Power Sensor	NRP-Z21	1137.6000.02	Sep. 08,2020	Sep. 07,2021	
Power Sensor	NRP-Z23	100323	Feb. 18,2020	Feb. 17,2021	
Power Viewer	R&S	V2.3.1.0	N/A	N/A	

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

- 1. There is no physical damage on the dipole;
- 2. System validation with specific dipole is within 10% of calibrated value;
- 3. Return-loss is within 20% of calibrated measurement;
- 4. Impedance is within  $5\Omega$  of calibrated measurement.

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N.4		SATIMO Un				/ 40 ====			
		uncertainty f	Prob.				1g Ui	10g Ui	Ι.
Uncertainty Component	Sec.	(+- %)	Dist.	Div.	Ci (1g)	Ci (10g)	(+-%)	(+-%)	Vİ
Measurement System					8				C
Probe calibration	E.2.1	7.000	N	1	1	1	7.000	7.000	œ
Axial Isotropy	E.2.2	0.105	R	$\sqrt{3}$	√0.5	√0.5	0.043	0.043	α
Hemispherical Isotropy	E.2.2	0.105	R	$\sqrt{3}$	√0.5	√0.5	0.043	0.043	o
Boundary effect	E.2.3	1.000	R	$\sqrt{3}$	1	1	0.577	0.577	o
Linearity	E.2.4	0.870	R	$\sqrt{3}$	1	1	0.502	0.502	α
System detection limits	E.2.4	1.000	R	$\sqrt{3}$	1	1	0.577	0.577	×
Modulation response	E2.5	3.000	R	$\sqrt{3}$	1	1	1.732	1.732	ox.
Readout Electronics	E.2.6	0.021	N	1	1	0 1	0.021	0.021	X
Response Time	E.2.7	0.000	R	$\sqrt{3}$	1	1	0.000	0.000	X
Integration Time	E.2.8	1.400	R	$\sqrt{3}$	1	1	0.808	0.808	×
RF ambient conditions-Noise	E.6.1	3.000	R	$\sqrt{3}$	1	1	1.732	1.732	8
RF ambient conditions-reflections	E.6.1	3.000	R	√3	1	1 💿	1.732	1.732	œ
Probe positioner mechanical tolerance	E.6.2	1.400	R	√3	1	1	0.808	0.808	ø
Probe positioning with respect to phantom shell	E.6.3	1.400	R	√3	<sub>®</sub> 1	1	0.808	0.808	0
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.300	R	√3	1	_1	1.328	1.328	0
Test sample Related		G	(8)						
Test sample positioning	E.4.2	2.6	N	1	1	1	2.600	2.600	α
Device holder uncertainty	E.4.1	3	N	1	1	1	3.000	3.000	o
Output power variation—SAR drift measurement	E.2.9	5	R	√3	1	1	2.887	2.887	o
SAR scaling	E.6.5	5	R	$\sqrt{3}$	1	1	2.887	2.887	o
Phantom and tissue parameter	rs		- 6		©				
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	√3	1	1	2.309	2.309	o
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.900	1.596	0
Liquid conductivity measurement	E.3.3	2.5	R	$\sqrt{3}$	0.78	0.71	1.126	1.025	o
Liquid permittivity measurement	E.3.3	4	N	1	0.78	0.71	3.120	2.840	N
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.332	0.375	0
Liquid permittivity—temperature uncertainty	E.3.4	5	N	1	0.23	0.26	1.150	1.300	N
Combined Standard Uncertainty	@		RSS		60		10.525	10.341	
Expanded Uncertainty (95% Confidence interval)	5,0	8	K=2				21.051	20.681	

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		ATIMO Uno							
System	0	uncertainty Tol	Prob.		l over 1 gran		1g Ui	10g Ui	
Uncertainty Component	Sec.	(+- %)	Dist.	Div.	Ci (1g)	Ci (10g)	(+-%)	(+-%)	vi
Measurement System	0		1	(8)	0				
Probe calibration	E.2.1	7	N	1	1	1 💿	7.000	7.000	000
Axial Isotropy	E.2.2	0.105	R	$\sqrt{3}$	1	1	0.061	0.061	00
Hemispherical Isotropy	E.2.2	0.105	R	$\sqrt{3}$	0	0	0.000	0.000	o
Boundary effect	E.2.3	1	R	$\sqrt{3}$	0 1	1	0.577	0.577	o
Linearity	E.2.4	0.870	R	$\sqrt{3}$	1	1	0.502	0.502	o
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	o
Modulation response	E2.5	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	o
Readout Electronics	E.2.6	0.021	N	1	1	1	0.021	0.021	o
Response Time	E.2.7	0.0	R	$\sqrt{3}$	0	0	0.00	0.00	o
Integration Time	E.2.8	1.4	R	$\sqrt{3}$	0	0	0.00	0.00	o
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	×
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	ox
Probe positioner mechanical tolerance	E.6.2	1.4	R	√3	- 1	1	0.81	0.81	α
Probe positioning with respect to phantom shell	E.6.3	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	X
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	1	1	1.33	1.33	ox
System validation source		8					-C		<b>(2)</b>
Deviation of experimental dipole from numerical dipole	E.6.4	5.0	N	1 🌑	1	1	5.00	5.00	ox
Input power and SAR drift measurement	8,6.6.4	5.0	R	$\sqrt{3}$	1	1	2.89	2.89	×
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	o
Phantom and set-up	60			8					
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4.0	R	√3	1 ®	1	2.31	2.31	o
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	α
Liquid conductivity (temperature uncertainty)	E.3.3	2.5	R	√3	0.78	0.71	1.13	1.02	X
iquid conductivity (measured)	E.3.3	4	N	1	0.78	0.71	3.12	2.84	N
iquid permittivity (temperature uncertainty)	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	×
Liquid permittivity (measured)	E.3.4	5	N	1	0.23	0.26	1.15	1.30	N
Combined Standard Uncertainty			RSS				10.458	10.272	
Expanded Uncertainty (95% Confidence interval)	(8)		K=2				20.916	20.544	

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Sv	stem Check	SATIMO Un				/ 10 gram			
Uncertainty Component	Sec.	Tol	Prob.	Div.	Ci (1g)	Ci (10g)	1g Ui	10g Ui	vi
Measurement System	Occ.	(+- %)	Dist.	DIV.	OI (1g)	Or (Tog)	(+-%)	(+-%)	VI
			1				T		
Probe calibration drift	E.2.1.3	0.5	N	1 -	1.	1	0.50	0.50	α
Axial Isotropy	E.2.2	0.105	R	$\sqrt{3}$	0	0	0.00	0.00	α
Hemispherical Isotropy	E.2.2	0.105	R	$\sqrt{3}$	0	0	0.00	0.00	o
Boundary effect	E.2.3	1	R	$\sqrt{3}$	0	0	0.00	0.00	0
Linearity	E.2.4	0.870	R	√3	0	0	0.00	0.00	0
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	0	0	0.00	0.00	α
Modulation response	E2.5	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	ο
Readout Electronics	E.2.6	0.021	N	1	0	0	0.00	0.00	α
Response Time	E.2.7	0	R	$\sqrt{3}$	0	0	0.00	0.00	o
Integration Time	E.2.8	1.4	R	$\sqrt{3}$	0	0	0.00	0.00	o
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	o
RF ambient conditions-reflections	E.6.1	3.0	R	√3	0	0	0.00	0.00	o
Probe positioner mechanical tolerance	E.6.2	1.4	R	$\sqrt{3}$	1	1 8	0.81	0.81	٥
Probe positioning with respect to phantom shell	E.6.3	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	0
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	0	0	0.00	0.00	0
System check source (dipole)		8			- (				
Deviation of experimental dipoles	E.6.4	2.0	N	1	1	1	2.00	2.00	α
Input power and SAR drift measurement	8,6.6.4	5.0	R	$\sqrt{3}$	1	1	2.89	2.89	o
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	o
Phantom and tissue parameter	s		9	(8)		<b>.</b> C		- C	
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	$\sqrt{3}$	1 6	1	2.31	2.31	0
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	0
Liquid conductivity measurement	E.3.3	2.5	R	√3	0.78	0.71	1.13	1.02	0
Liquid permittivity measurement	E.3.3	6 4	N	1	0.78	0.71	3.12	2.84	N
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	c
Liquid permittivity—temperature uncertainty	E.3.4	5	N	1	0.23	0.26	1.15	1.30	N
Combined Standard Uncertainty		CC	RSS	8	©		5.562	5.203	
Expanded Uncertainty (95% Confidence interval)	8		K=2		c.C	(8)	11.124	10.406	

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# 12. CONDUCTED POWER MEASUREMENT

#### Bluetooth\_BR/EDR

Modulation	Channel	Frequency(MHz)	Maximum Peak Power (dBm)
0501/	0	2402	10.324
GFSK (1DH5)	39	2441	10.268
(10113)	78	2480	8.555
/A DODOK	0	2402	10.281
π /4-DQPSK (2DH5)	39	2441	10.182
(20110)	78	2480	8.608
o DDOV	0	2402	10.450
8-DPSK (3DH5)	39	2441	10.350
(30113)	78	2480	8.757

#### Bluetooth\_BLE

Modulation	Channel	Frequency(MHz)	Maximum Peak Power (dBm)
(8)	0	2402	2.210
GFSK_1M	19	2440	2.670
	39	2480	0.500
	0	2402	2.071
GFSK_2M	19	2440	2.642
	39	2480	0.423

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#### 13. TEST RESULTS

# 13.1. SAR Test Results Summary 13.1.1. Test position and configuration

- 1. The EUT is a model of bluetooth speaker.
- 2. Based on FCC (Tracking Number 978421) guidance, use a non-standard setting for SAR testing. The operating instructions contain additional information:
  - According to KDB 447498 D01 General RF Exposure Guide v06, due to maximum peak power for Bluetooth(BR/EDR) is more than just a test exclusion threshold, which must be tested.
- 3. And an inquiry about SAR test method is request:
  - (1) Carefully remove the handle as to not break the antenna or antenna cable. Place the radio underneath the flat bottom phantom with the handle flat against the phantom (antenna side facing).
  - (2) Lab. use the head liquid with a separation of 0mm at flat phantom to test the front surface of the handle where the antenna is closest to the outer surface.
- 4. For SAR testing, the device was controlled by software to test at reference fixed frequency points.

#### 13.1.2. Operation Mode

- 1. Per KDB 447498 D01 v06 ,for each exposure position, if the highest 1-g SAR is ≤ 0.8 W/kg, testing for low and high channel is optional.
- 2. Per KDB 865664 D01 v01r04,for each frequency band, if the measured SAR is ≥0.8W/Kg, testing for repeated SAR measurement is required, that the highest measured SAR is only to be tested. When the SAR results are near the limit, the following procedures are required for each device to verify these types of SAR measurement related variation concerns by repeating the highest measured SAR configuration in each frequency band.
  - (1) When the original highest measured SAR is  $\geq$ 0.8W/Kg, repeat that measurement once.
  - (2) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is >1.20 or when the original or repeated measurement is ≥1.45 W/Kg.
  - (3) Perform a third repeated measurement only if the original, first and second repeated measurement is ≥1.5 W/Kg and ratio of largest to smallest SAR for the original, first and second measurement is ≥ 1.20.
- 3. Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:

  Maximum Scaling SAR =tested SAR (Max.) ×[maximum turn-up power (mw)/ maximum measurement

Maximum Scaling SAR =tested SAR (Max.)  $\times$  [maximum turn-up power (mw)/ maximum measurement output power(mw)]

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#### 13.1.3. Test Result

	SAR MEASUREMENT			
	Depth of Liquid (cm):>15	Relative Humidity (%): 43.9		
9	Product: Wireless Speaker			

Test Mode: Bluetooth for head liquid-BR/EDR

Position	Mode	Ch.	Fr. (MHz)	Power Drift (<±5%)	SAR (1g) (W/kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/Kg)	Limit W/kg
Front surface of the handle	1DH5	0	2402	-0.12	0.831	10.5	10.324	0.865	1.6
Front surface of the handle	1DH5	39	2441	-0.08	0.796	10.5	10.268	0.840	1.6
Front surface of the handle	1DH5	78	2480	0.17	0.742	9	8.555	0.822	1.6

#### Note

• When the 1-g SAR is  $\leq$  0.8W/kg, testing for low and high channel is optional.

• The test separation of all above table is 0mm.

Repeated SAR										
Product: Wireless Speaker										
Test Mode: Bluetooth for head liquid-BR/EDR										
Position	Mode	Ch.	Fr. (MHz)	Power Drift (<±5%)	Once SAR (1g) (W/kg)	Power Drift (<±5%)	Twice SAR (1g) (W/kg)	Power Drift (<±5%)	Third SAR (1g) (W/kg)	Limit (W/kg)
Front surface of the handle	1DH5	0	2402	0.03	0.824	<b>O</b>	- 6	@		1.6

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#### APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab Date: Dec. 25,2020

System Check Head 2450 MHz

DUT: Dipole 2450 MHz Type: SID 2450

Communication System CW; Communication System Band: D2450 (2450.0 MHz); Duty Cycle: 1:1; Conv.F=4.23 Frequency: 2450 MHz; Medium parameters used: f = 2450 MHz;  $\sigma = 1.82$  mho/m;  $\epsilon r = 38.13$ ;  $\rho = 1000$  kg/m<sup>3</sup>;

Phantom section: Flat Section; Input Power=18dBm

Ambient temperature ( $^{\circ}$ ):20.6, Liquid temperature ( $^{\circ}$ ): 20.3

#### **SATIMO Configuration**

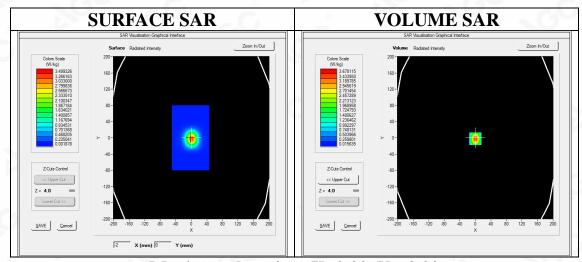
Probe: SSE5; Calibrated: Jun. 24,2020; Serial No.: SN 24/20 EP336

Sensor-Surface: 4mm (Mechanical Surface Detection)

Phantom: ELLI39 Phantom

Measurement SW: OpenSAR V4\_02\_35

Configuration/System Check 2450MHz Head/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/System Check 2450MHz Head/Zoom Scan: Measurement grid: dx=5mm,dy=5mm, dz=5mm



Maximum location: X=0.00, Y=-2.00

SAR Peak: 6.40 W/kg

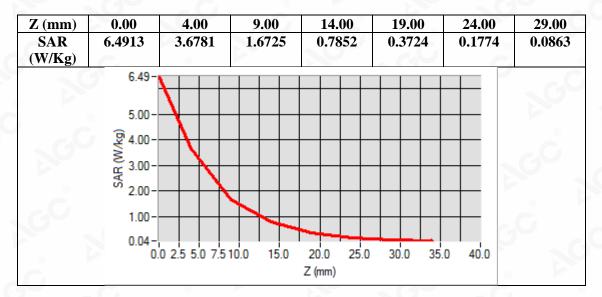
SAR 10g (W/Kg) 1.519256

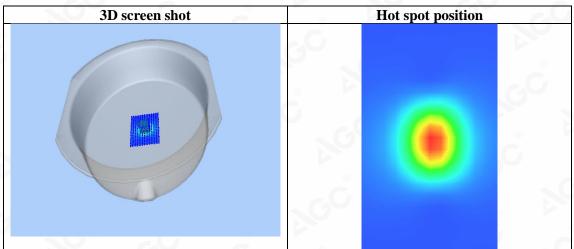
SAR 1g (W/Kg) 3.382448

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#### APPENDIX B. SAR MEASUREMENT DATA

Test Laboratory: AGC Lab Date: Dec. 25,2020

Bluetooth Low- Front (1DH5)

DUT: Wireless Speaker; Type: A3126

Communication System: BT; Communication System Band: Bluetooth; Duty Cycle:1:1.30;Conv.F=4.23;

Frequency: 2402 MHz; Medium parameters used: f = 2450 MHz;  $\sigma = 1.76$  mho/m;  $\epsilon r = 40.62$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Ambient temperature ( $^{\circ}$ ):20.6, Liquid temperature ( $^{\circ}$ ): 20.3

**SATIMO Configuration:** 

Probe: SSE5; Calibrated: Jun. 24,2020; Serial No.: SN 24/20 EP336

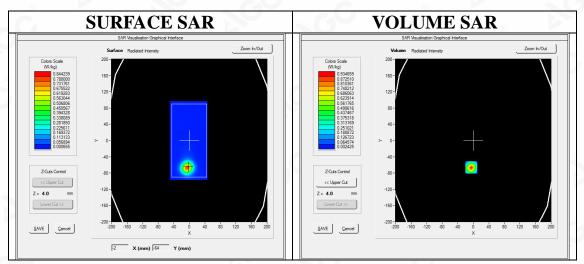
Sensor-Surface: 4mm (Mechanical Surface Detection)

Phantom: ELLI39 Phantom

Measurement SW: OpenSAR V4\_02\_35

Configuration/Bluetooth Low- Front /Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/Bluetooth Low- Front /Zoom Scan: Measurement grid: dx=5mm,dy=5mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm		
ZoomScan	7x7x7,dx=5mm dy=5mm dz=5mm		
Phantom	o ELLI		
Device Position	Front		
Band	Bluetooth		
Channels	Low		
Signal	Crest factor: 1.30		



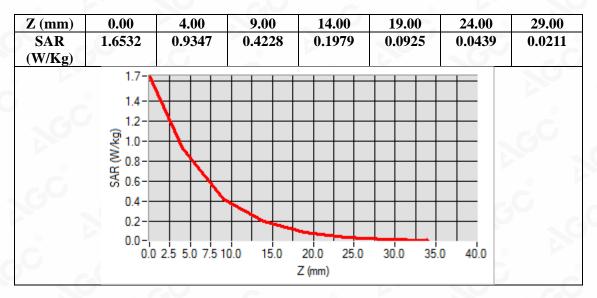
Maximum location: X=-5.00, Y=-66.00 SAR Peak: 1.64 W/kg

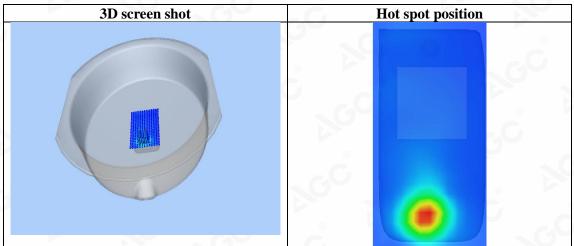
SAR 10g (W/Kg)	0.343499
SAR 1g (W/Kg)	0.830702

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Repeated SAR

Test Laboratory: AGC Lab Date: Dec. 25,2020

**Bluetooth Low- Front (1DH5)** 

DUT: Wireless Speaker; Type: A3126

Communication System: BT; Communication System Band: Bluetooth; Duty Cycle:1:1.30;Conv.F=4.23;

Frequency: 2402 MHz; Medium parameters used: f = 2450 MHz;  $\sigma = 1.76$  mho/m;  $\epsilon r = 40.62$ ;  $\rho = 1000$  kg/m<sup>3</sup>;

Phantom section: Flat Section

Ambient temperature ( $^{\circ}$ C):20.6, Liquid temperature ( $^{\circ}$ C): 20.3

SATIMO Configuration:

Probe: SSE5; Calibrated: Jun. 24,2020; Serial No.: SN 24/20 EP336

Sensor-Surface: 4mm (Mechanical Surface Detection)

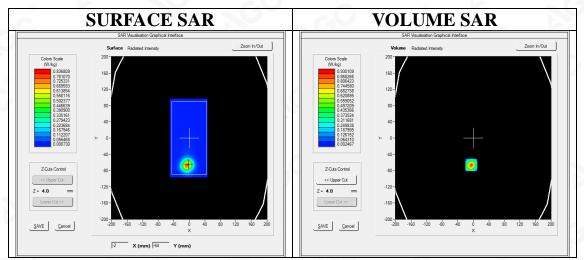
Phantom: ELLI39 Phantom

Measurement SW: OpenSAR V4\_02\_35

Configuration/Bluetooth Low- Front /Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/Bluetooth Low- Front /Zoom Scan: Measurement grid: dx=5mm,dy=5mm, dz=5mm;

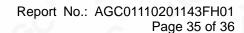
Area Scan	dx=8mm dy=8mm, h= 5.00 mm		
ZoomScan	7x7x7,dx=5mm dy=5mm dz=5mm		
Phantom	ELLI		
Device Position	Front		
Band	Bluetooth		
Channels	Low		
Signal	Crest factor: 1.30		



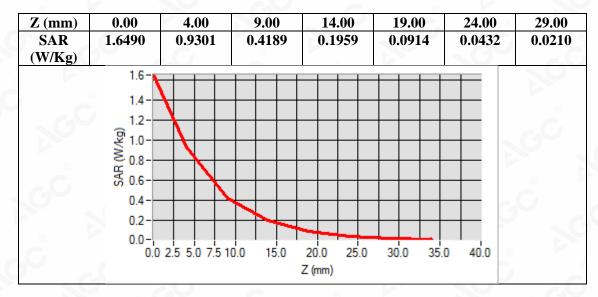
Maximum location: X=-5.00, Y=-66.00 SAR Peak: 1.63 W/kg

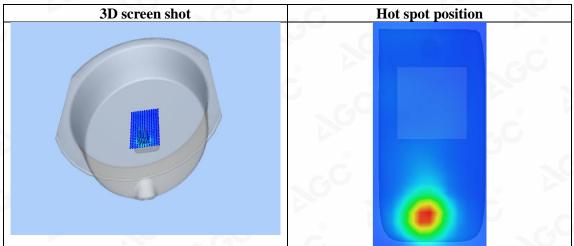
SAR 10g (W/Kg)	0.340240
SAR 1g (W/Kg)	0.823984

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# **APPENDIX C. TEST SETUP PHOTOGRAPHS**

Refer to Attached files.

# APPENDIX D. CALIBRATION DATA

Refer to Attached files.

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he test report.

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