

SAR TEST REPORT

FCC 47 CFR Part 2.1093 ISED RSS-102

RF-Exposure evaluation of portable equipment

Testing Laboratory: Eurofins Product Service GmbH

Address: Storkower Str. 38c

15526 Reichenwalde

Germany

Accreditation:





FCC Test Firm Designation Number: DE0008

IC Testing Laboratory site: 3470A-2

Applicant's name peiker CEE GmbH

Address: Gartenstraße 25

61352 Bad Homburg

GERMANY

Test specification:

Standard..... FCC 47 CFR Part 2 §2.1093

447498 D01 General RF Exposure Guidance v06

IEEE Std. 1528 - 2013 ISED RSS-102 Issue 5

Non-standard test method...... None

Test scope.....: complete Radio compliance test

Equipment under test (EUT):

Product description CEECOACH

Model No. CC2
Additional Model(s) None

Brand Name(s) CEECOACH

Hardware version 2.0 Firmware / Software version 2.0

FCC-ID: 2ANUYCC2 IC: 23265-CEECOACH

Test result Passed



Possible test case verdicts:

- neither assessed nor tested...... N/N

- required by standard but not appl. to test object......: N/A

- required by standard but not tested N/T

- not required by standard for the test object...... N/R

- test object does meet the requirement...... P (Pass)

- test object does not meet the requirement..... F (Fail)

Testing:

Date (s) of performance of tests 2017-11-07

Compiled by Burkhard Pudell

Tested by (+ signature)...... Burkhard Pudell (Responsible for Test)

Approved by (+ signature)...... (Deputy Head of Lab)

Date of issue 2021-06-14

Total number of pages 82

General remarks:

The test results presented in this report relate only to the object tested.

The results contained in this report reflect the results for this particular model and serial number. It is the responsibility of the manufacturer to ensure that all production models meet the intent of the requirements detailed within this report.

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Additional comments:



Version History

	Version History							
Version	Issue Date	Remarks	Revised By					
01	2017-11-27	Initial Release						
02	2021-06-14	Replaced document: G0M-1709-6878-TFC093SR-V01 Replaced by: G0M-1709-6878-TFC093SR-V02 Reason: Applicant's name corrected.	B. Pudell					



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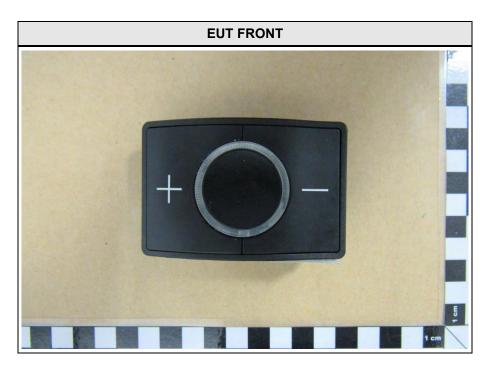


1 Equipment (Test item) Description

Description	CEECOACH				
Model	CC2				
Additional Model(s)	None				
Brand Name(s)	CEECOACH				
Serial number	None				
Hardware version	2.0				
Software / Firmware version	2.0				
PMN	CEECOACH2				
HVIN	CC2, CC21				
FVIN	N/A				
HMN	N/A				
FCC-ID	2ANUYCC2				
IC	23265-CEECOA	ACH			
Equipment type	End product				
Prototype or production unit	Production Unit				
Device category	Handset				
Environment	General public				
Radio technologies	Bluetooth - Classic				
Operating frequency ranges	2402 – 2480 MH	l z			
Number of modules	2 (CSR8670) sa	ame type			
Number of antennas	2 (1 per module) same type				
Modulations	GFSK; π/4-DQPSK; 8-DPSK				
	Туре	integrated			
Antenna	Model	PCB			
Antonia	Manufacturer	peiker			
	Gain	max. 2 dBi same type (declaration)			
Power supply	V _{NOM}	3.7 VDC (Lithium Battery)			
	Model	KSA01A5210100D5			
AC/DC-Adaptor	Vendor	I.T.E. Power Supply			
A0/D0-Adaptor	Input	100-240 V AC			
	Output	2x 5V DC (1,0A + 2,1A)			
Accessories	Belt clip; wireles	s Headset; wired Headset			
Manufacturer	peiker CEE GmbH Gartenstraße 25 61352 Bad Homburg GERMANY				



1.1 Equipment photos



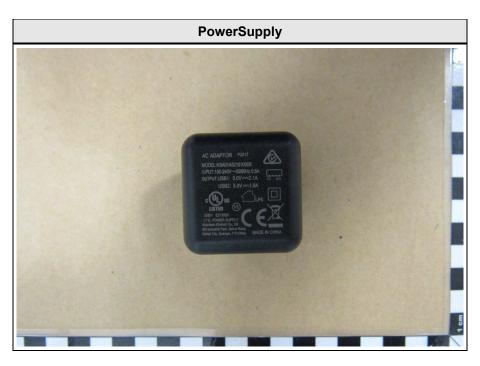












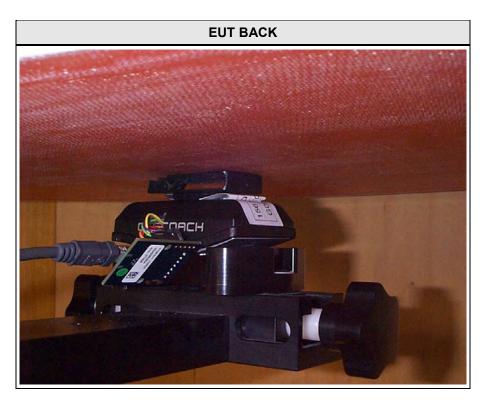


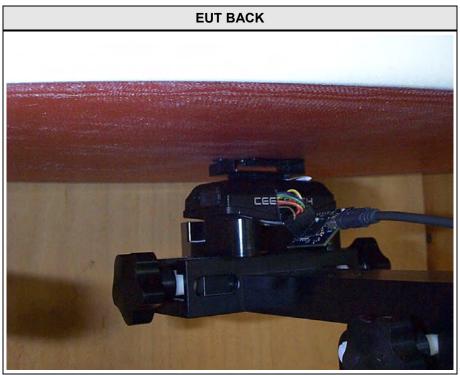






1.2 Equipment setup photos

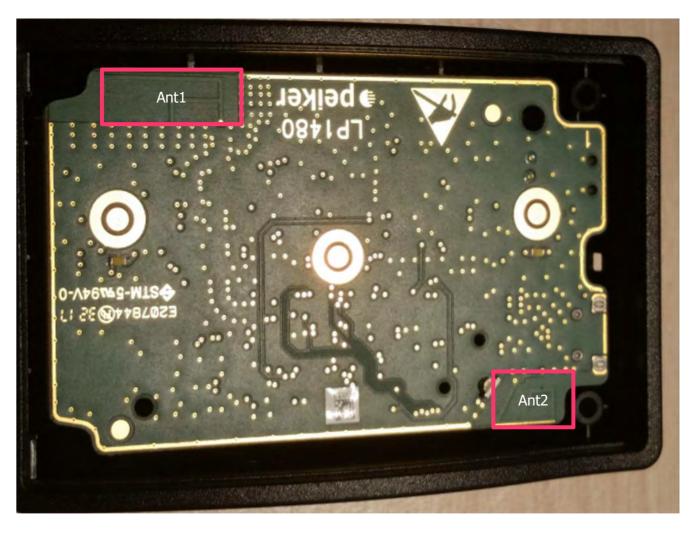




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CEECOACH Positionen Antennen zu Gehäuse



Ant1 PCB Antenne max. 20 dBm Ant2 PCB Antenne max. 4 dBm

Platine 67 * 42mm





76 * 50mm Gehäuse

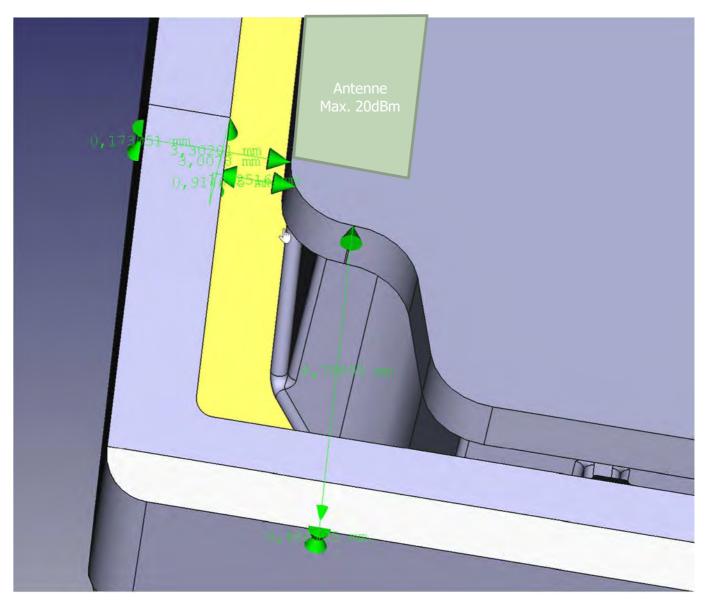
Gehäusehöhe Steckerseite (rechts) 20mm

Mitte 24mm Linke Seite 17mm

Halteeelement Gürtelclip Höhe 3,7mm Zusätzlich Gürtelclip Höhe 10mm

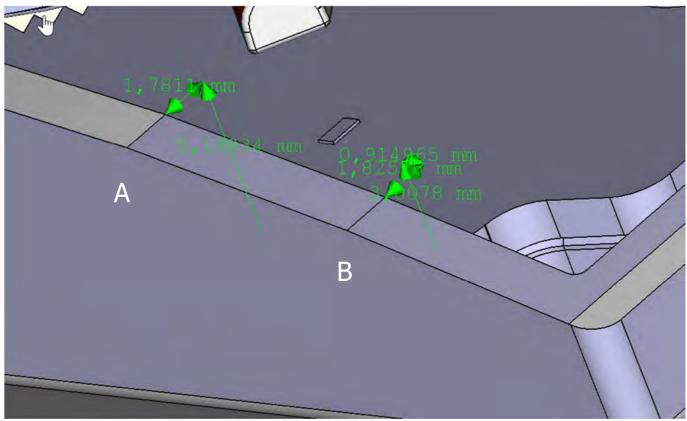


Antenne 1 (max. 20dbm)



Antenne 1 – Gehäuse Längsseite 3,3 mm Antenne 1 – Gehäuse Schmalseite min 8,78 mm Antenne 1 – Gehäuse Unterseite 13,1mm





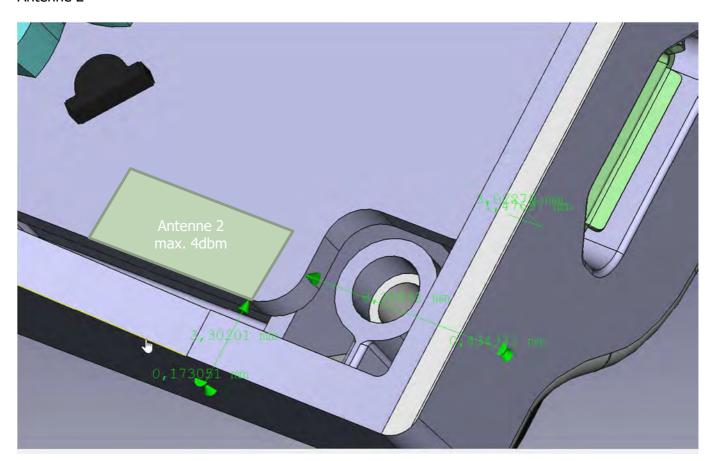
Antenne 1 – Gehäuse Oberseite

5,2mm Punkt A 3,0mm Punkt B

(da gebogene Kante) 4,1mm Mittelwert



Antenne 2



Abstand

Antenne 2 – Längsseite Gehäuse aussen	3,3 mm
Antenne 2 – Schmalseite Gehäuse aussen	8,2 mm
Antenne 2 – Oberseite Gehäuse	3,0 mm
Antenne 2 – Unterseite Gehäuse Boden	13,1 mm



1.3 Reference Documents

Document
KDB Publication 447498 : Mobile and Portable Device RF Exposure Procedures and Equipment Authorization Polices
KDB Publication 648474 : SAR Evaluation Considerations for Handsets with Multiple Transmitters and Antennas
KDB Publication 648474 : Review and Approval Policies for SAR Evaluation of Handsets with Multiple Transmitters and Antennas
KDB Publication 865664 : SAR measurement procedures for devices operating between 100 MHz to 6 GHz
KDB Publication 941225: SAR Measurement Procedures for 3G Devices
KDB Publication 941225: 3GPP R6 HSPA and R7 HSPA+ SAR Guidance
KDB Publication 941225: Recommended SAR Test Reduction Procedures for GSM/GPRS/EDGE
KDB Publication 941225: SAR Test Consideration for LTE Handsets and Data Modems
KDB Publication 447498 : SAR Measurement Procedures for USB Dongle Transmitters
KDB Publication 248227 : SAR Measurement Procedures for 802.11 a/b/g Transmitters
KDB Publication 450824 : SAR Probe Calibration and System Verification considerations for measurements from 150 MHz to 3 GHz



1.4 Supporting Equipment Used During Testing

Product Type*	Device	Manufacturer	Model No.	Comments
SIM	Communication tester	R&S	CBT	BT-Tester
SIM	LAPTOP	DELL	E5330	Control unit

*Note: Use the following abbreviations:

AE : Auxiliary/Associated Equipment, or SIM : Simulator (Not Subjected to Test)

CABL: Connecting cables



1.5 Supported standalone operating modes

Mode	Modulation	Frequency range	Duty cycle		
BT-BR	GFSK	2400 MHz - 2483.5 MHz	77%		

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1.6 Conducted Power Values FCC

Bluetooth BR only – Average Output Power									
	Source-base time-average power [d	Bm] includes Tune up tolerance 2dB							
Frequency [MHz]	BR (GFSK) DH5								
[1411.12]	Module 1	Module 2							
2402	14.8	0.4							
2441	13.7	0.3							
2480 12.9 0.5									
Date, Operator:	07.11.2017 , B. Pudell								

1.7 Radiated Power Values ISED

Bluetooth BR only – Average Output Power								
	Source-base time-average power	[dBm] includes Tune up tolerance 2 dB						
Frequency [MHz]	BF	R (GFSK)						
	Module 1	Module 2						
2402	16.8*	2.4*						
2441	15.7*	2.3*						
2480	14.9*	2.5*						
Date, Operator: 07.11.2017 , B. Pudell								
*includes antenna gain: +2 dB								



1.8 Standalone Operational Mode Test Exclusion for FCC

According to KDB 447498 D01 v06 for standalone SAR evaluation the test exclusion power condition is given by

$$\frac{\max Power, mW}{test\ distance, mm} \cdot \sqrt{f_{GHz}} \leq 3.0$$

for test separation distance \leq 50mm. For test separation distances > 50mm, the SAR test exclusion threshold is:

$$P_{TH}[mW] = Power \ allowed \ at \ numeric \ threshold \ for \ 50mm + (test \ distance, mm - 50mm) \cdot \frac{f[MHz]}{150} \ ,$$

$$100 \ MHz < f < 1500 \ MHz$$

 $P_{TH}[mW] = Power \ allowed \ at \ numeric \ threshold \ for \ 50mm + (test \ distance, mm - 50mm) \cdot 10$, $1500 \ MHz < f < 6 \ GHz$

SAR Test Exclusion															
									EUT	Edge					
				To	р	Le	eft	Rig	ght	Bot	tom	Ва	ick	Fro	ont
Mode	P [mW]	Ant.	Reg.	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]
BT-BR	30.2	1	FCC	-	•	1	1	-	-	1	•	26.8	48	1	1
Comments: All bold Threshold values are above the limit and have to be measured															
Date, Operator:							07.1	1.2017	7 , B. F	Pudell					

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1.9 Standalone Operational Mode Exemption limits for IC

	Exemption Limits (mW)									
Frequency	At separation	At separation	At separation	At separation	At separation					
(MHz)	distance of ≤5 mm	distance of 10 mm	distance of 15 mm	distance of 20 mm	distance of 25 mm					
≤300	71 mW	101 mW	132 mW	162 mW	193 mW					
450	52 mW	70 mW	88 mW	102 mW	123 mW					
835	17 mW	30 mW	42 mW	55 mW	67 mW					
1900	7 mW	10 mW	18 mW	34 mW	60 mW					
2450	4 mW	7 mW	15 mW	30 mW	52 mW					
3500	2 mW	6 mW	16 mW	32 mW	55 mW					
5800	1 mW	6 mW	15 mW	27 mW	41 mW					
	Exemption Limits (mW)									
Frequency	At separation	At separation	At separation	At separation	At separation					
(MHz)	distance of	distance of	distance of	distance of	distance of					
	30 mm	35 mm	40 mm	45 mm	≥50 mm					
≤300	223 mW	254 mW	284 mW	315 mW	345 mW					
450	141 mW	159 mW	177 mW	195 mW	213 mW					
835	80 mW	92 mW	105 mW	117 mW	130 mW					
1900	99 mW	153 mW	225 mW	316 mW	431 mW					
2450	83 mW	123 mW	173 mW	235 mW	309 mW					
3500	86 mW	124 mW	170 mW	225 mW	290 mW					
5800	56 mW	71 mW	85 mW	97 mW	106 mW					

SAR Test Exclusion															
				EUT Edge											
				To	р	Le	eft	Rig	ght	Bot	tom	Ва	ick	Fro	ont
Mode	P [mW]	Ant. [dBi]	Reg.	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]	Antenna distance to user [mm]	SAR Test Exclusion Threshold [mW]
BT-BR	47.83	2	IC	-	,	,			,	,	-	26.8	52	-	•
Comments: All bold Threshold values are above the limit and have to be measured															
	Date, Operator:						07.1	1.2017	7 , B. F	Pudell					

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1.10 Supported concurrent (multi-transmitter) operating modes

No multi-transmitter evaluation



1.11 Supported use cases

Use case	Distance to human body	corresponding test configuration				
EUT placed at human body	0 mm (worst case)	body-worn device				
Comment: means case surface include belt clip						



1.12 Radio Test Modes

Mode	Settings
BT1-BR	Mode = BT-DUT mode Modulation = GFSK Duty cycle = 77.5% Power level = maximum (BT1 20 dBm) Antenna = integrated
Mode = standalone TX mode Modulation = GFSK BT2-BR Duty cycle = 77% Power level = maximum (BT2 4dBm) Antenna = integrated	
Comment:	BT1 and BT2 activ at the same time



1.13 Test Positions

Position	Description
BACK - 0MM	EUT back side with belt clip facing the phantom. Separation distance between EUT and phantom are 0 mm



1.14 Test Equipment Used During Testing

SAR Measurement						
Description	Manufacturer	Model	Identifier	Cal. Date	Cal. Due	
Stäubli Robot	Stäubli	RX90B L	EF00271	functional test	functional test	
Stäubli Robot Controller	Stäubli	CS7MB	EF00272	functional test	functional test	
DASY 5 Measurement Server	Schmid & Partner	-	EF00273	functional test	functional test	
Control Pendant	Stäubli	-	EF00274	functional test	functional test	
Dell Computer	Schmid & Partner	Intel	EF00275	functional test	functional test	
Data Acquisition Electronics	Schmid & Partner	DAE3V1	EF00276	2017-09	2018-09	
Dosimetric E-Field Probe	Schmid & Partner	EX3DV4	EF00826	2017-09	2018-09	
System Validation Kit	Schmid & Partner	D2450V2	EF00284	2015-09	2018-09	
Flat phantom	Schmid & Partner	V 4.4	EF00328	no calibration required	no calibration required	
Oval flat phantom	Schmid & Partner	ELI 4	EF00289	functional test	functional test	
Mounting Device	Schmid & Partner	V 3.1	EF00287	functional test	functional test	
Millivoltmeter	Rohde & Schwarz	URV 5	EF00126	2016-08	2019-08	
Power sensor	Rohde & Schwarz	NRV-Z2	EF00125	2017-07	2019-07	
RF signal generator	Rohde & Schwarz	SMP 02	EF00165	2017-07	2019-07	
Insertion unit	Rohde & Schwarz	URV5-Z4	EF00322	2017-08	2019-08	
Directional Coupler	HP	HP 87300B	EF00288	functional test	functional test	
BT Communication Tester	Rohde & Schwarz	СВТ	EF00358	2017-03	2019-03	
Network Analyzer 300 kHz to 3 GHz	Agilent	8752C	EF00140	2017-07	2018-07	
Dielectric Probe Kit	Agilent	85070C	EF00291	functional test	functional test	
Dielectric Probe Kit	SPEAG	DAK-3.5	EF00945	2017-09	2018-09	
DAK Measurement Software	SPEAG	DAKS	EF00965	-	-	
Thermometer	LKM electronic GmbH	DTM3000	EF00967	2016-11	2017-11	



2 Result Summary

447498 D01 General RF Exposure Guidance, RSS-102						
Product Specific Standard Section	Requirement - Test	Reference Method	Maximum SAR [W/kg]	Result	Remarks	
447498 D01 General RF Exposure Guidance RSS-102 Section 3	Single-band conformity Body	KDB Publication 447498 KDB Publication 941225 KDB Publication 865664	0.006	PASS		
447498 D01 General RF Exposure Guidance RSS-102 Section 3	Single-band conformity Limbs	KDB Publication 447498 KDB Publication 941225 KDB Publication 865664	N/A			
447498 D01 General RF Exposure Guidance RSS-102 Section 3	Multi-band conformity	KDB Publication 447498 KDB Publication 941225 KDB Publication 865664	N/A	N/R	No concurrent transmission modes	
Remarks:						



3 Definitions

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (ρ_t), expressed in watts per kilogram (W/kg)

SAR = d/dt (dW/dm) = d/dt (dW/
$$\rho_t$$
dV) = σ/ρ_t |E_t|²

where

$$dW/dt = \int_V E J dV = \int_V \sigma E^2 dV$$

3.1 Controlled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category and the general population/uncontrolled exposure limits apply to these devices.

3.2 Uncontrolled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on the risk of potential exposure risks.

3.3 Localized SAR

Compliance with the localized SAR limits is demonstrated using the head and trunk limit because this SAR limit is only half the limbs limit value. The values are obtained by SAR measurements according to EN 62209-2.

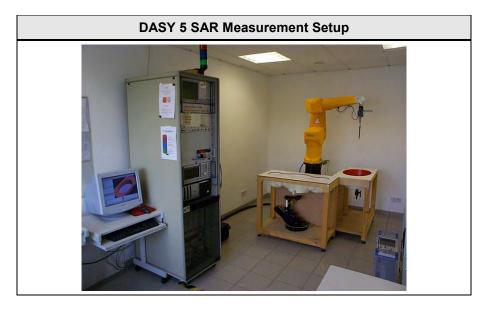


4 Localized SAR Measurement Equipment

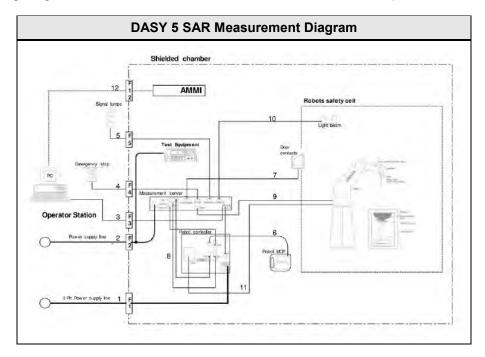
The measurements were performed with Dasy5 automated near-field scanning system comprised of high precision robot, robot controller, computer, e-field probe, probe alignment unit, phantoms, non-conductive phone positioned and software extension.

4.1 Complete SAR DASY5 Measurement System

Measurements are performed using the DASY5 automated assessment system made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland.



The following Diagram show the elements involved in the measurement setup.



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The DASY5 system for performing compliance tests consists of the following items:

DASY5 SAR Measurement System					
Device	Description:				
RX90BL	A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software.				
Probe Alignment Unit	A probe alignment unit which improves the (absolute) accuracy of the probe positioning.				
Teach Pendant	The Manual Control Pendant (MCP), also called the manual teach pendant, is the user interface to the robot. In DASY, it is used for certain installation and teach procedures				
Signal Lamps	External warning lamp which indicates when the robot arm is powered-on and if the robot is under software control or in manual mode (controlled with the teach pendant).				
DAE	The data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.				
E-Field Probes	Isotropic E-Field probe optimized and calibrated for E-field measurements in free space.				
EOC	The electro-optical converter (EOC) performs the conversion between optical and electrical signals				
Measurement Server	The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.				
Control Computer	A computer operating Windows 2000 or Windows NT with DASY 4 Software.				
Control Software	DASY4 and SEMCAD post processing Software				
SAM Twin Phantom	The SAM twin phantom enabling testing left-hand and right-hand usage.				
Flat Phantom	Flat Phantom (only for body-mounted transceivers operating below 800 MHz).				
Tissue simulating liquid	Tissue simulating liquid mixed according to the given recipes.				
Device Holder	The device holder for handheld mobile phones.				
System Validation Dipoles	System validation dipoles allowing to validate the proper functioning of the system.				

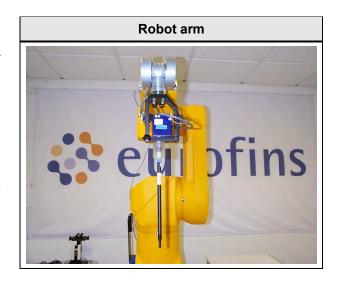


4.2 Robot Arm

The DASY5 system uses the high precision robots RX90BL type out of the newer series from Stäubli SA (France).

The RX robot series have many features that are important for our application:

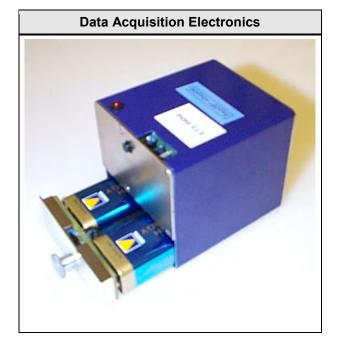
- ➤ High precision (repeatability 0.02 mm)
- > High reliability (industrial design)
- Jerk-free straight movements
- ➤ Low ELF interference (the closed metallic construction shields against motor control fields)
- ➢ 6-axis controller



4.3 Data Acquisition Electronics

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 is 200M Ohm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.





4.4 Isotropic E-Field Probe ≤ 6 GHz

Probe Specifications

Construction:

One dipole parallel, two dipoles normal to probe axis built-in shielding against static charges.

Calibration:

In air from 10 MHz to 6 GHz, In brain and muscle simulating tissue at Frequencies of 2450, 5200, 5500, 5800

Frequency:

10MHz to 6GHz, Linearity ±0.2dB (30MHz to 6GHz)

Directivity:

 ± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis)

Dynamic Range:

 $10\mu W/g \text{ to } > 100 \text{mW/g}$

Linearity:

 $\pm 0.2 dB$

Dimensions:

Overall Length: 337mm (Tip: 20mm), Tip Diameter: 2.5mm (Body: 12mm),

Distance from probe tip to dipole centers: 1mm

Application:

General dosimetry up to 6 GHz Compliance tests of mobile phones Fast automatic scanning in arbitrary phantoms

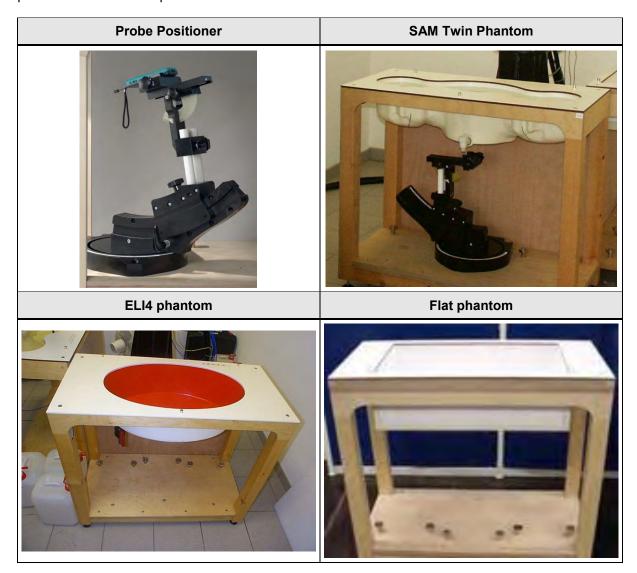




4.5 Test phantom and positioner

The positioner and test phantoms are manufactured by SPEAG. The test phantoms are used for all tests i.e. for both validation testing and device testing. The positioner and test phantom conforms to the requirements of EN 62209 and IEEE 1528.

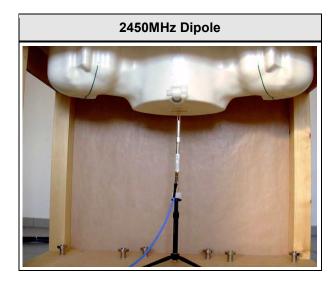
The SPEAG device holder was used to position the test device in all tests whilst a tripod was used to position the validation dipoles in the test arch.





4.6 System Validation Dipoles

A set of calibration dipoles (D2450V2) is included as a part of the SAR measurement setup. These are used for the validation of the test setup after its installation and prior to the EUT measurements. The calibration dipole is placed in the position normally occupied by the EUT. All calibration dipoles have the same height which allows an exact fitting below the center point of the test phantom. The dipole center is 10mm below the surface of the test phantom.





5 Single-band SAR Measurement

After successful completion of the tissue and system verification the SAR values of the EUT are measured according to the following description.

5.1 General measurement description

The measurement is performed for each frequency band of the device. If the width of the transmit frequency band exceeds 1% of its center frequency, than the channels at the lowest and highest frequencies should also be tested. Furthermore, if the width of the transmit band exceeds 10% of its center frequency the following formula is used to determine the number of channels:

$$N_C=2 \cdot roundup[10 \cdot (f_{high} - f_{low})/f_c] + 1$$

First the device is tested on the center channel of each frequency band used by the device. An operation mode and configuration with maximum transmit power is established. If battery operated equipment is used, the batteries are fully charged.

SAR measurements are performed using the steps outlined in the next section for all relevant operational modes, EUT configurations and measurement positions.

For the condition (position, configuration, operational mode) that provides the highest spatial-average SAR value on the center channel, the other channels are also tested.

Additionally all other conditions where the spatial-average SAR value is within 3dB of the SAR limit are also tested on all determined test frequencies.

5.2 SAR measurement description

First the local SAR value at a test point within 10mm or less in normal direction from the inner surface of the phantom is measured. This SAR value is used to determine the measurement drift during SAR measurement.

Next an area scan is performed over an area larger than the projection of the EUT with antenna on the surface of the phantom with a spatial grid step of 10mm.

From the scanned SAR distribution the position of maximum SAR value is identified as well as any local SAR maxima within 2dB of the maximum value that are not within the zoom scan volume. (The additional peaks are only measured when the primary peak is within 2dB of the SAR limit.)

The zoom-scan volume constructed on the peak SAR position is scanned with a grid step of 5mm. The measured data are extracted and the local SAR value for each measurement point is calculated. The measured values are interpolated over a fine-mesh within the scan volume and the average SAR value over 10g mass is calculated.

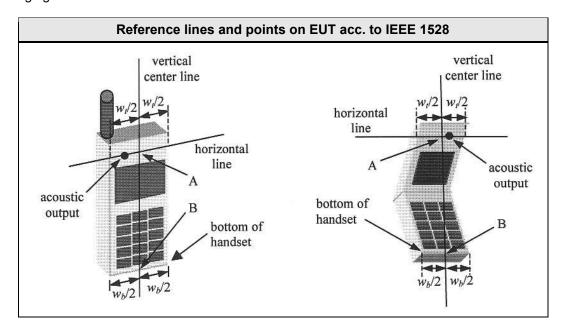
At the end of the measurement the reference point measured at the beginning of the measurement is measured again and from the difference the drift is calculated.

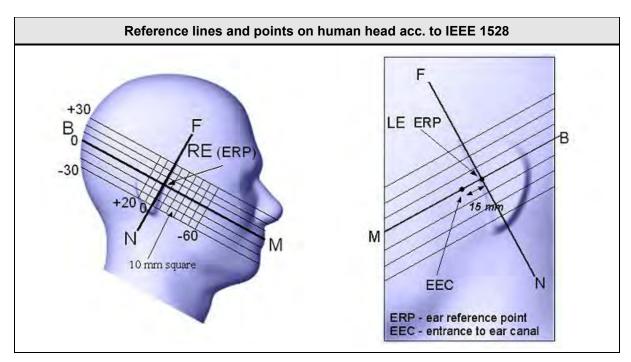


5.3 Reference lines and points for Handsets

For all measurement positions of the EUT, the EUT has to be place in a specific orientation with respect to the phantom. The orientation of the EUT relative to the phantom is defined by reference lines and points.

According to IEEE 1528, the reference lines and points shall be positioned at the EUT as shown in the following figure.

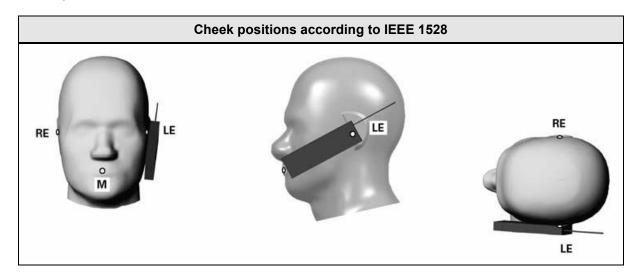






5.4 Test positions relative to the Head

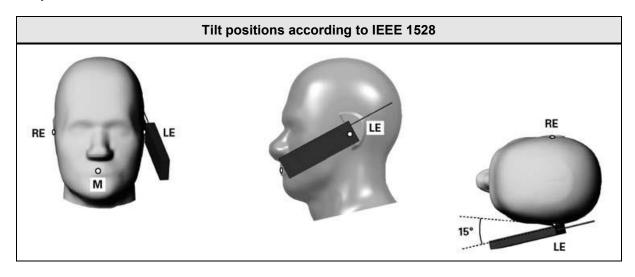
Cheek position



The handset is positioned close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure), such that the plane defined by the vertical centerline and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom. Next the handset is translated towards the phantom along the line passing through RE and LE until handset point A touches the pinna at the ERP.

While the handset is maintained in this plane, it is rotated around the LE-RE line until the vertical centerline is in the plane normal to the plane containing B-M and N-F lines, i.e., the Reference Plane. Then it is rotated around the vertical centerline until the handset (horizontal line) is parallel to the N-F line. While the vertical centerline is maintained in the Reference Plane, point A is kept on the line passing through RE and LE, and the handset is maintained in contact with the pinna, the handset is rotated about the N-F line until any point on the handset is in contact with a phantom point below the pinna on the cheek.

Tilt position



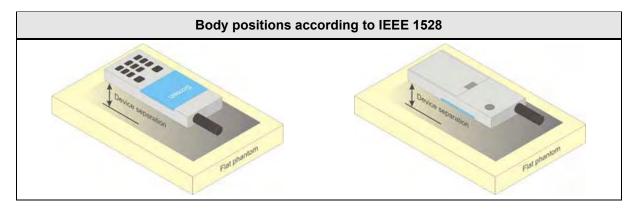
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First the EUT is placed in the cheek position. Next the handset is moved away from the pinna along the line passing through RE and LE far enough to allow a rotation of the handset away from the cheek by 15°. Then the handset is rotated around the horizontal line by 15°.

The handset is moved towards the phantom on the line passing through RE and LE until any part of the handset touches the ear. The tilt position is obtained when the contact point is on the pinna. See Figure. If contact occurs at any location other than the pinna, e.g., the antenna at the back of the phantom head, the angle of the handset should be reduced. In this case, the tilt position is obtained if any point on the handset is in contact with the pinna and a second point on the handset is in contact with the phantom, e.g., the antenna with the back of the head

5.5 Test positions relative to the human body



In body worn configuration the device is positioned parallel to the phantom surface with either top or bottom side of the EUT facing against the phantom.

The separation distance of the EUT is selected according to the use case of the EUT (e.g. with belt clip or holster).



5.6 Measurement Uncertainty

Error Description	Uncertainty Value	Probability Distribution	Div.	c _i (1g)	c _i (10g)	Std. Unc.	Std. Unc.
Measurement System	'9	109					
Probe Calibration	±6.55%	N	1	1	1	±6.55%	±6.55%
Axial Isotropy	±4.7%	R	$\sqrt{3}$	0.7	0.7	±1.9%	±1.9%
Hemispherical Isotropy	±9.6%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	0.7	0.7	±3.9%	±3.9%
Linearity	+4.7%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±2.7%	±2.7%
Modulation Response	±2.4%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±1.4%	±1.4%
System Detection Limits	±1.0%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±0.6%	±0.6%
Boundary effects	±2.0%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±1.2%	±1.2%
Readout Electronics	±0.3%	N	1	1	1	±0.3%	±0.3%
Response Time	±0.8%	R	$\frac{1}{\sqrt{3}}$	1	1	±0.5%	±0.5%
Integration Time	±2.6%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±1.5%	±1.5%
RF Ambient Noise	±3.0%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±1.7%	±1.7%
RF Ambient Reflections	+3.0%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±1.7%	±1.7%
Probe Positioner	±0.8%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±0.5%	±0.5%
Probe Positioning	±6.7%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±3.9%	±3.9%
Post processing	±4.0%	R	$\frac{\sqrt{3}}{\sqrt{3}}$	1	1	±2.3%	±2.3%
Test Sample Related			, -				
Device Holder	±3.6%	N	1	1	1	±3.6%	±3.6%
Test Sample Positioning	±2.9%	N	1	1	1	±2.9%	±2.9%
Power Scaling	±0%	R	$\sqrt{3}$	1	1	±0%	±0%
Power Drift	±5.0%	R	$\sqrt{3}$	1	1	±2.9%	±2.9%
Phantom and Setup Rela	ated						•
Phantom Uncertainty	±7.9%	R	$\sqrt{3}$	1	1	±4.6%	±4.6%
SAR correction	±1.9%	R	$\sqrt{3}$	1	0.84	±1.1%	±0.9%
Liquid conductivity (measured)	±2.5%	N	1	0.78	0.71	±2.0%	±1.8%
Liquid permittivity (measured)	±2.5%	N	1	0.26	0.26	±0.1%	±0.1%
Temperature uncertainty - Conductivity	±5.2%	R	$\sqrt{3}$	0.78	0.71	±2.3%	±2.1%
Temperature uncertainty - Permittivity	±0.8%	R	$\sqrt{3}$	0.23	0.26	±0.1%	±0.1%
Combined Standard Unce	ertainty			1	•	±12.8%	±12.7%
Expanded Standard Unc	ertainty					±25.6%	±25.4%

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Product Service

Measurement Uncertainty according to EN 62209-1								
Error Description	Uncertainty Value	Probability Distribution	Div.	c _i (1g)	c _i (10g)	Std. Unc. 1g	Std. Unc. 10g	
Measurement System								
Probe Calibration	±6.0%	N	1	1	1	±6.0%	±6.0%	
Axial Isotropy	±4.7%	R	$\sqrt{3}$	0.7	0.7	±1.9%	±1.9%	
Hemispherical Isotropy	±9.6%	R	$\sqrt{3}$	0.7	0.7	±3.9%	±3.9%	
Boundary effects	±1.0%	R	$\sqrt{3}$	1	1	±0.6%	±0.6%	
Linearity	±4.7%	R	$\sqrt{3}$	1	1	±2.7%	±2.7%	
System Detection Limits	±1.0%	R	$\sqrt{3}$	1	1	±0.6%	±0.6%	
Readout Electronics	±0.3%	N	1	1	1	±0.3%	±0.3%	
Response Time	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%	
Integration Time	±2.6%	R	$\sqrt{3}$	1	1	±1.5%	±1.5%	
RF Ambient Noise	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%	
RF Ambient Reflections	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%	
Probe Positioner	±0.4%	R	$\sqrt{3}$	1	1	±0.2%	±0.2%	
Probe Positioning	±2.9%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%	
Max. SAR Evaluation	±2.0%	R	$\sqrt{3}$	1	1	±1.2%	±1.2%	
Test Sample Related								
Device Positioning	±2.9%	N	1	1	1	±2.9%	±2.9%	
Device Holder	±3.6%	N	1	1	1	±3.6%	±3.6%	
Power Drift	±5.0%	R	$\sqrt{3}$	1	1	±2.9%	±2.9%	
Power Scaling	±0%	R	$\sqrt{3}$	1	1	±0.0%	±0.0%	
Phantom and Setup Rela	ated							
Phantom Uncertainty	±6.1%	R	$\sqrt{3}$	1	1	±3.5%	±3.5%	
SAR correction	±1.9%	R	$\sqrt{3}$	1	0.84	±1.1%	±0.9%	
Liquid conductivity (measured)	±2.5%	N	1	0.78	0.71	±2.0%	±1.8%	
Liquid permittivity (measured)	±2.5%	N	1	0.26	0.26	±0.6%	±0.7%	
Temperature uncertainty - Conductivity	±5.2%	R	√3	0.78	0.71	±2.3%	±2.1%	
Temperature uncertainty - Permittivity	±0.8%	R	$\sqrt{3}$	0.23	0.26	±0.1%	±0.1%	
Combined Standard Unce	rtainty				_	±11.4%	±11.3%	
Expanded Standard Und	ertainty					±22.9%	±22.7%	

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Product Service

Measurement System Probe Calibration ±6.55% N 1 1 1 ±6.55% Axial Isotropy ±4.7% R √3 0.7 0.7 ±1 Hemispherical Isotropy ±9.6% R √3 0.7 0.7 ±3 Linearity ±4.7% R √3 1 1 ±2 Modulation Response ±2.4% R √3 1 1 ±1 System Detection Limits ±1.0% R √3 1 1 ±1 Boundary effects ±2.0% R √3 1 1 ±1 Readout Electronics ±0.3% N 1 1 1 ±0 Response Time ±0.8% R √3 1 1 ±0 Integration Time ±2.6% R √3 1 1 ±1 RF Ambient Reflections ±3.0% R √3 1 1 ±1 Probe Positioner ±0.8% R	Measurement Uncertainty according to EN 62209-2							
Probe Calibration ±6.55% N 1 1 1 ±6 Axial Isotropy ±4.7% R √3 0.7 0.7 ±1 Hemispherical Isotropy ±9.6% R √3 0.7 0.7 ±3 Linearity ±4.7% R √3 1 1 ±2 Modulation Response ±2.4% R √3 1 1 ±1 System Detection Limits ±1.0% R √3 1 1 ±0 Boundary effects ±2.0% R √3 1 1 ±0 Readout Electronics ±0.3% N 1 1 1 ±0 Response Time ±0.8% R √3 1 1 ±0 Response Time ±0.8% R √3 1 1 ±1 RF Ambient Noise ±3.0% R √3 1 1 ±1 Probe Positioner ±0.8% R √3 1	Error Description			Div.	c _i (1g)	c _i (10g)	Std. Unc. 1g	Std. Unc. 10g
Axial Isotropy ±4.7% R √3 0.7 0.7 ±1 Hemispherical Isotropy ±9.6% R √3 0.7 0.7 ±2 Linearity ±4.7% R √3 1 1 ±2 Modulation Response ±2.4% R √3 1 1 ±1 System Detection Limits ±1.0% R √3 1 1 ±1 Boundary effects ±2.0% R √3 1 1 ±1 Readout Electronics ±0.3% N 1 1 1 ±0 Response Time ±0.8% R √3 1 1 ±0 Integration Time ±2.6% R √3 1 1 ±1 RF Ambient Noise ±3.0% R √3 1 1 ±1 RF Ambient Reflections ±3.0% R √3 1 1 ±1 Trobe Positioner ±0.8% R √3 1 1 ±1 Trobe Positioning ±6.7% R √3 1 1 ±1 Test Sample Related Device Holder ±3.6% N 1 1 1 ±2 Power Scaling ±0.% R √3 1 1 ±2 Phantom and Setup Related Phantom Uncertainty ±7.9% R √3 1 1 ±2 Phantom and Setup Related Phantom Uncertainty ±7.9% R √3 1 1 ±2 Phantom and Setup Related Phantom Uncertainty ±2.5% N 1 0.78 0.71 ±2 Temperature uncertainty ±5.2% R √3 0.78 0.7	easurement System							
Hemispherical Isotropy	robe Calibration	±6.55%	N	1	1	1	±6.55%	±6.55%
Linearity $\pm 4.7\%$ R $\sqrt{3}$ 1 1 1 $\pm 2.2\%$ Modulation Response $\pm 2.4\%$ R $\sqrt{3}$ 1 1 1 $\pm 1.2\%$ System Detection Limits $\pm 1.0\%$ R $\sqrt{3}$ 1 1 1 $\pm 1.2\%$ Boundary effects $\pm 2.0\%$ R $\sqrt{3}$ 1 1 1 $\pm 1.2\%$ Readout Electronics $\pm 0.3\%$ N 1 1 1 $\pm 1.2\%$ Response Time $\pm 0.8\%$ R $\sqrt{3}$ 1 1 $\pm 1.2\%$ Response Time $\pm 2.6\%$ R $\sqrt{3}$ 1 1 $\pm 1.2\%$ RF Ambient Noise $\pm 3.0\%$ R $\sqrt{3}$ 1 1 $\pm 1.2\%$ RF Ambient Reflections $\pm 3.0\%$ R $\sqrt{3}$ 1 1 $\pm 1.2\%$ Probe Positioner $\pm 0.8\%$ R $\sqrt{3}$ 1 1 $\pm 1.2\%$ Probe Positioning $\pm 6.7\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ Power Scaling $\pm 0.2\%$ N 1 1 1 $\pm 1.2\%$ Power Scaling $\pm 0.2\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ Phantom and Setup Related Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ Part of the properture uncertainty $\pm 2.5\%$ N 1 0.26 0.26 $\pm 0.2\%$ Properature uncertainty $\pm 2.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty $\pm 0.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty $\pm 0.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty	xial Isotropy	±4.7%	R	$\sqrt{3}$	0.7	0.7	±1.9%	±1.9%
Modulation Response $\pm 2.4\%$ R $\sqrt{3}$ 1 1 ± 1 System Detection Limits $\pm 1.0\%$ R $\sqrt{3}$ 1 1 ± 0 Boundary effects $\pm 2.0\%$ R $\sqrt{3}$ 1 1 ± 1 Readout Electronics $\pm 0.3\%$ N 1 1 1 ± 0 Response Time $\pm 0.8\%$ R $\sqrt{3}$ 1 1 ± 0 Integration Time $\pm 2.6\%$ R $\sqrt{3}$ 1 1 ± 0 Integration Time $\pm 2.6\%$ R $\sqrt{3}$ 1 1 ± 0 Integration Time $\pm 2.6\%$ R $\sqrt{3}$ 1 1 ± 1 Response Time $\pm 0.8\%$ R $\sqrt{3}$ 1 1 ± 1 Integration Time $\pm 2.6\%$ R $\sqrt{3}$ 1 1 ± 1 RF Ambient Noise $\pm 3.0\%$ R $\sqrt{3}$ 1 1 ± 1 Probe P	emispherical Isotropy	±9.6%	R	$\sqrt{3}$	0.7	0.7	±3.9%	±3.9%
System Detection Limits $\pm 1.0\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Boundary effects $\pm 2.0\%$ R $\sqrt{3}$ 1 1 $\pm 1.0\%$ Readout Electronics $\pm 0.3\%$ N 1 1 1 $\pm 0.0\%$ Response Time $\pm 0.8\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Integration Time $\pm 2.6\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ RF Ambient Noise $\pm 3.0\%$ R $\sqrt{3}$ 1 1 $\pm 1.0\%$ RF Ambient Reflections $\pm 3.0\%$ R $\sqrt{3}$ 1 1 $\pm 1.0\%$ Probe Positioner $\pm 0.8\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Post processing $\pm 6.7\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$	nearity	±4.7%	R	$\sqrt{3}$	1	1	±2.7%	±2.7%
Boundary effects $\pm 2.0\%$ R $\sqrt{3}$ 1 1 ± 1 Readout Electronics $\pm 0.3\%$ N 1 1 1 $\pm 0.0\%$ Response Time $\pm 0.8\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Integration Time $\pm 2.6\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ RF Ambient Noise $\pm 3.0\%$ R $\sqrt{3}$ 1 1 $\pm 1.0\%$ RF Ambient Reflections $\pm 3.0\%$ R $\sqrt{3}$ 1 1 $\pm 1.0\%$ Probe Positioner $\pm 0.8\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Probe Positioning $\pm 6.7\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$ Test Sample Related Device Holder $\pm 3.6\%$ N 1 1 $\pm 2.0\%$ Power Drift $\pm 5.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$	odulation Response	±2.4%	R	$\sqrt{3}$	1	1	±1.4%	±1.4%
Readout Electronics $\pm 0.3\%$ N 1 1 1 $\pm 0.8\%$ Response Time $\pm 0.8\%$ R $\sqrt{3}$ 1 1 $\pm 0.8\%$ Integration Time $\pm 2.6\%$ R $\sqrt{3}$ 1 1 $\pm 1.0\%$ RF Ambient Noise $\pm 3.0\%$ R $\sqrt{3}$ 1 1 $\pm 1.0\%$ RF Ambient Reflections $\pm 3.0\%$ R $\sqrt{3}$ 1 1 $\pm 1.0\%$ Probe Positioner $\pm 0.8\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Probe Positioning $\pm 0.7\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$ Test Sample Related Device Holder $\pm 3.6\%$ N 1 1 $\pm 2.0\%$ Power Drift $\pm 5.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$	ystem Detection Limits	±1.0%	R	$\sqrt{3}$	1	1	±0.6%	±0.6%
Response Time $\pm 0.8\%$ R $\sqrt{3}$ 1 1 1 $\pm 0.8\%$ R $\sqrt{3}$ 1 0.84 $\pm 0.8\%$ R $\sqrt{3}$ 1 0.78 0.71 $\pm 0.8\%$ R $\sqrt{3}$ 0.78 0.71	oundary effects	±2.0%	R	$\sqrt{3}$	1	1	±1.2%	±1.2%
Integration Time	eadout Electronics	±0.3%	N	1	1	1	±0.3%	±0.3%
RF Ambient Noise $\pm 3.0\%$ R $\sqrt{3}$ 1 1 ± 1 RF Ambient Reflections $\pm 3.0\%$ R $\sqrt{3}$ 1 1 ± 1 Probe Positioner $\pm 0.8\%$ R $\sqrt{3}$ 1 1 ± 0 Probe Positioning $\pm 6.7\%$ R $\sqrt{3}$ 1 1 ± 3 Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 3 Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 3 Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 3 Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 2 Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 2 Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 2 Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 3 Power Dri	esponse Time	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%
RF Ambient Reflections $\pm 3.0\%$ R $\sqrt{3}$ 1 1 ± 1 Probe Positioner $\pm 0.8\%$ R $\sqrt{3}$ 1 1 $\pm 0.0\%$ Probe Positioning $\pm 6.7\%$ R $\sqrt{3}$ 1 1 $\pm 3.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 3.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$ Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$ Test Sample Related Device Holder $\pm 5.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.0\%$ Phantom Scaling $\pm 5.0\%$ R $\sqrt{3}$ 1 1	tegration Time	±2.6%	R	$\sqrt{3}$	1	1	±1.5%	±1.5%
Probe Positioner $\pm 0.8\%$ R $\sqrt{3}$ 1 1 ± 0.00 Probe Positioning $\pm 6.7\%$ R $\sqrt{3}$ 1 1 ± 3.00 Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 2.00 Test Sample Related Device Holder $\pm 3.6\%$ N 1 1 1 ± 3.00 Test Sample Positioning $\pm 2.9\%$ N 1 1 1 ± 3.00 Power Scaling $\pm 0.00\%$ R $\sqrt{3}$ 1 1 ± 3.00 Power Drift $\pm 5.0\%$ R $\sqrt{3}$ 1 1 ± 3.00 Phantom and Setup Related Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 ± 4.00 Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 ± 4.00 SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 ± 1.00 Liquid conductivity (measured) $\pm 2.5\%$ N	F Ambient Noise	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
Probe Positioning $\pm 6.7\%$ R $\sqrt{3}$ 1 1 ± 3 Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 2 Test Sample Related Device Holder $\pm 3.6\%$ N 1 1 1 ± 3 Test Sample Positioning $\pm 2.9\%$ N 1 1 1 ± 2 Power Scaling $\pm 0\%$ R $\sqrt{3}$ 1 1 ± 2 Power Drift $\pm 5.0\%$ R $\sqrt{3}$ 1 1 ± 2 Phantom and Setup Related Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 ± 4 SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 ± 1 Liquid conductivity (measured) $\pm 2.5\%$ N 1 0.78 0.71 ± 2 Liquid permittivity (measured) $\pm 2.5\%$ N 1 0.26 0.26 ± 0 Temperature uncertainty - Conductivity	F Ambient Reflections	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
Post processing $\pm 4.0\%$ R $\sqrt{3}$ 1 1 ± 2 Test Sample Related Device Holder $\pm 3.6\%$ N 1 1 1 $\pm 3.6\%$ N 1 1 $\pm 3.6\%$ N 1 $\pm 3.6\%$ N $\pm 3.6\%$ N 1 $\pm 3.6\%$ N 1 $\pm 3.6\%$ N 1	robe Positioner	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%
Test Sample Related Device Holder $\pm 3.6\%$ N 1 1 1 1 $\pm 3.6\%$ Test Sample Positioning $\pm 2.9\%$ N 1 1 1 1 $\pm 2.2\%$ Power Scaling $\pm 0\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ Power Drift $\pm 5.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ Phantom and Setup Related Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 $\pm 1.2\%$ Liquid conductivity (measured) $\pm 2.5\%$ N 1 0.78 0.71 $\pm 2.2\%$ Liquid permittivity (measured) $\pm 2.5\%$ N 1 0.26 0.26 $\pm 0.26\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$	robe Positioning	±6.7%	R	$\sqrt{3}$	1	1	±3.9%	±3.9%
Device Holder $\pm 3.6\%$ N 1 1 1 1 $\pm 3.6\%$ Test Sample Positioning $\pm 2.9\%$ N 1 1 1 1 $\pm 2.2\%$ Power Scaling $\pm 0.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ Power Drift $\pm 5.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ Phantom and Setup Related Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 $\pm 4.2\%$ SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 $\pm 1.2\%$ Liquid conductivity (measured) $\pm 2.5\%$ N 1 0.78 0.71 $\pm 2.2\%$ Liquid permittivity (measured) $\pm 2.5\%$ N 1 0.26 0.26 $\pm 0.26\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$	ost processing	±4.0%	R	$\sqrt{3}$	1	1	±2.3%	±2.3%
Test Sample Positioning $\pm 2.9\%$ N 1 1 1 1 $\pm 2.5\%$ Power Scaling $\pm 0\%$ R $\sqrt{3}$ 1 1 1 $\pm 2.5\%$ Power Drift $\pm 5.0\%$ R $\sqrt{3}$ 1 1 1 $\pm 2.5\%$ Phantom and Setup Related Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 1 $\pm 4.5\%$ SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 $\pm 1.5\%$ Liquid conductivity (measured) $\pm 2.5\%$ N 1 0.78 0.71 $\pm 2.5\%$ Liquid permittivity (measured) $\pm 2.5\%$ N 1 0.26 0.26 $\pm 0.26\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.5\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.5\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.5\%$	est Sample Related							
Power Scaling $\pm 0\%$ R $\sqrt{3}$ 1 1 $\pm 2\%$ Power Drift $\pm 5.0\%$ R $\sqrt{3}$ 1 1 1 $\pm 2\%$ Phantom and Setup Related Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 1 $\pm 4\%$ SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 $\pm 1\%$ Liquid conductivity (measured) $\pm 2.5\%$ N 1 0.78 0.71 $\pm 2\%$ Liquid permittivity (measured) $\pm 2.5\%$ N 1 0.26 0.26 $\pm 2\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2\%$	evice Holder	±3.6%	N	1	1	1	±3.6%	±3.6%
Power Drift $\pm 5.0\%$ R $\sqrt{3}$ 1 1 $\pm 2.2\%$ Phantom and Setup Related Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 $\pm 4.2\%$ SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 $\pm 1.2\%$ Liquid conductivity (measured) $\pm 2.5\%$ N 1 0.78 0.71 $\pm 2.2\%$ Liquid permittivity (measured) $\pm 2.5\%$ N 1 0.26 0.26 $\pm 0.2\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$	est Sample Positioning	±2.9%	N	1	1	1	±2.9%	±2.9%
Phantom and Setup RelatedPhantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 11 ± 4 SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 ± 1 Liquid conductivity (measured) $\pm 2.5\%$ N1 0.78 0.71 ± 2 Liquid permittivity (measured) $\pm 2.5\%$ N1 0.26 0.26 ± 0 Temperature uncertainty - Conductivity $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 ± 2 Temperature uncertainty - Conductivity $\pm 0.8\%$ R $\sqrt{3}$ 0.78 0.71 ± 2	ower Scaling	±0%	R	$\sqrt{3}$	1	1	±0%	±0%
Phantom Uncertainty $\pm 7.9\%$ R $\sqrt{3}$ 1 1 $\pm 4.4\%$ SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 $\pm 1.4\%$ Liquid conductivity (measured) $\pm 2.5\%$ N 1 0.78 0.71 $\pm 2.5\%$ Liquid permittivity (measured) $\pm 2.5\%$ N 1 0.26 0.26 $\pm 0.26\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.5\%$ Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.5\%$	ower Drift	±5.0%	R	$\sqrt{3}$	1	1	±2.9%	±2.9%
SAR correction $\pm 1.9\%$ R $\sqrt{3}$ 1 0.84 ± 1 Liquid conductivity (measured) $\pm 2.5\%$ N 1 0.78 0.71 ± 2 Liquid permittivity (measured) $\pm 2.5\%$ N 1 0.26 0.26 ± 0 Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 ± 2 Temperature uncertainty $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 ± 2	hantom and Setup Rela	ited						
Liquid conductivity (measured) $\pm 2.5\%$ N1 0.78 0.71 $\pm 2.5\%$ Liquid permittivity (measured) $\pm 2.5\%$ N1 0.26 0.26 ± 0.26 Temperature uncertainty - Conductivity $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty - Temperature uncertainty - $\pm 0.8\%$ D ± 0.23 ± 0.26 ± 0.23	hantom Uncertainty	±7.9%	R	$\sqrt{3}$	1	1	±4.6%	±4.6%
(measured) $\pm 2.5\%$ N1 0.78 0.71 $\pm 2.5\%$ Liquid permittivity (measured) $\pm 2.5\%$ N1 0.26 0.26 ± 0.26 Temperature uncertainty - Conductivity $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty - Temperature uncertainty $\pm 0.8\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$	AR correction	±1.9%	R	$\sqrt{3}$	1	0.84	±1.1%	±0.9%
(measured) $\pm 2.5\%$ N I 0.26 0.26 ± 0.26 Temperature uncertainty - Conductivity $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 $\pm 2.2\%$ Temperature uncertainty $\pm 0.8\%$ R $\sqrt{3}$ 0.26 $\pm 0.26\%$ R $\sqrt{3}$ 0.26 $\pm 0.26\%$		±2.5%	N	1	0.78	0.71	±2.0%	±1.8%
- Conductivity $\pm 5.2\%$ R $\sqrt{3}$ 0.78 0.71 ± 2 Temperature uncertainty $\pm 0.8\%$ R $\sqrt{3}$ 0.23 0.26 ± 0.23		±2.5%	N	1	0.26	0.26	±0.1%	±0.1%
		±5.2%	R	$\sqrt{3}$	0.78	0.71	±2.3%	±2.1%
		±0.8%	R	$\sqrt{3}$	0.23	0.26	±0.1%	±0.1%
Combined Standard Uncertainty ±13	ombined Standard Unce	rtainty			•	•	±12.8%	±12.7%
Expanded Standard Uncertainty ±2	xpanded Standard Unc	ertainty					±25.6%	±25.4%



6 Test Conditions and Results

6.1 Recipes for Tissue Simulating Liquids

	Body Tissue Simulating Liquids										
Ingredient	M 450-B weight (%)	M 900-B weight (%)	M 1800-B weight (%)	M 1950-A weight (%)	M 2450-B weight (%)						
Water	46.21	50.75	70.17	69.79	68.64						
Sugar	51.17	48.21	-	-	-						
Cellulose	0.18	-	-	-	-						
Salt	2.34	-	0.39	0.2	-						
Preventol	0.08	0.1	-	-	-						
DGBE	-	-	29.44	30	31.37						
	ŀ	Head Tissue Sim	ulating Liquids								
Ingredient	HSL 450-A weight (%)	HSL 900-B weight (%)	HSL 1800-F weight (%)	HSL 1950-B weight (%)	HSL 2450-B weight (%)						
Water	38.91	40.29	55.24	55.41	55						
Sugar	56.93	57.9	-	-	-						
Cellulose	0.25	0.24	-	-	-						
Salt	3.79	1.38	0.31	0.08	-						
Preventol	0.12	0.18	-	-	-						
DGBE	-	-	44.45	44.51	45						

Water: deionized water, resistivity \geq 16 M Ω

Sugar: refined white sugar

Salt: pure NaCl

Cellulose: Hydroxyethyl-cellulose Preservative: Preventol D-7

DGBE: Diethylenglycol-monobuthyl ether

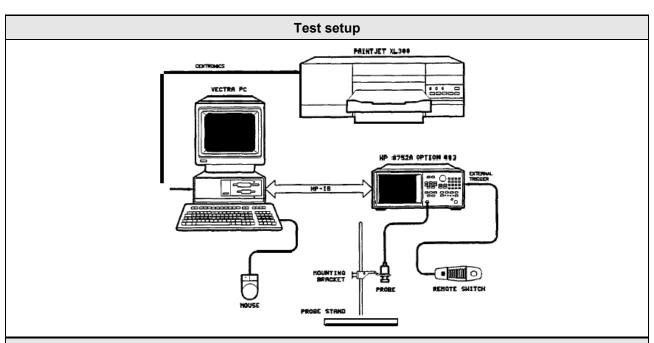
The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., IEEE 1528-2003, IEC 62209-1)

The HBBL3-6GHz and MBBL 3-6 GHz liquids are direct from Speag.



6.2 Test Conditions and Results - Tissue Validation

Test ac	cording to	Reference Method				
	ent reference	865664	D01 SAR Measure	ment 100 MHz t	o 6 GHz	
		Target V	'alues			
	Hea	d	Bod	у	Permitted	
Frequency [MHz]	Relative dielectric constant ε _r	Conductivity σ [S/m]	Relative dielectric constant ε _r	Conductivity σ [S/m]	tolerance [%]	
150	52.3	0.76	61.9	0.80	≤ ±5	
300	45.3	0.87	58.2	0.92	≤ ±5	
450	43.5	0.87	56.7	0.94	≤ ±5	
835	41.5	0.90	55.2	0.97	≤ ±5	
900	41.5	0.97	55.0	1.05	≤ ±5	
915	41.5	0.98	55.0	1.06	≤ ±5	
1450	40.5	1.20	54.0	1.30	≤ ±5	
1610	40.3	1.29	53.8	1.40	≤ ±5	
1800 – 2000	40.0	1.40	53.3	1.52	≤ ±5	
2450	39.2	1.80	52.7	1.95	≤ ±5	
3000	38.5	2.40	52.0	2.73	≤ ±5	
5200	36.0	4.66	49.0	5.30	≤ ±5	
5500	35.6	4.96	48.6	5.65	≤ ±5	
5800	35.3	5.27	48.2	6.00	≤ ±5	



Test procedure

- 1. The dielectric probe kit is calibrated using the standards air, short circuit and deionized water
- 2. The tissue simulating liquid is measured using the dielectric probe
- 3. Target values are compared to the measurement values and deviations are determined

	Test results										
Frequency [MHz]	Tissue	Measured ε _r	Target ε _r	Delta ε _r [%]	Measured σ [S/m]	Target σ [S/m]	Delta σ [%]				
2450	Body	50.559	52.7	-4.06	2.012	1.95	3.18				
2402	Body	50.971	52.7	-3.28	1.926	1.95	-1.23				
2441*	Body	50.563	52.7	-4.06	1.998	1.95	2.46				
2480	Body	50.610	52.7	-3.97	2.041	1.95	4.67				

Comments: * Measured radio frequencies

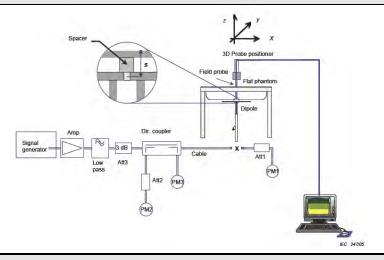


6.3 Test Conditions and Results – System Validation

System Validation acc. to 865664 D01 SAR Measurement 100 MHz to 6 GHz / ISED RSS-102 Verdict: PAS						
Test according to	Reference Method					
measurement reference	865664 D01 SAR Measurement 100 MHz to 6 GHz / IEEE 1528					
Toot frequency range	Tested frequencies	3				
Test frequency range	2450 MHz					
Test mode	unmodulated CW					
	Target Values					
Frequency [MHz]	Target SAR value [W/kg (1g)]	Permitted tolerance [%]				
2450	12.5 @ 250mW	≤ ±10				
The target reference values are taken from the calibration sheets (see annex)						

The target reference values are taken from the calibration sheets (see annex)

Test setup



Test procedure

- 1. The dipole antenna input power is set to 250mW
- 2. The reference dipole is positioned under the phantom
- 3. With the dipole antenna powered the SAR value is measured
- 4. The measured SAR values are compared to the target SAR values

	Test results									
Frequency [MHz]	Input power [mW]	Measured SAR value [W/kg (1g)]	Target SAR value [W/kg (1g)]	Delta [%]						
2450	250	13.1	12.38	5.82						
Comments:										

Test Report No.: G0M-1709-6878-TFC093SR-V02



6.4 Test Conditions and Results - Standalone SAR Measurement

	Standalone SAR acc. to 865664 D01 SAR Measurement 100 MHz to 6 SHz / ISED RSS-102 Verdict: PASS							ict: PASS	
Tost	according to		Reference Method						
	Test according to measurement reference		86	865664 D01 SAR Measurement 100 MHz to 6 GHz ISED RSS-102 Issue 5					
Roon	n temperature	;			2	3.0 – 23.6 °C			
Li	quid depth					15.5 cm			
Er	nvironment				g	eneral public			
	Limits								
	Region		Occupational SAR values [W/kg]			General public SAR values [W/kg]			
Whole b	ody average S	AR	0.4			0.08			
	AR (Head and eraging mass =			8		1.6			
	ed SAR (Limbs raging mass =		20 4						
	Test results								
Mode	Position	Channel	Frequency [MHz]	Drift [dB]	Scaling Factor*	Measured SAR [W/kg (1g)]	Reported SAR [W/kg (1g)] **	SAR Limit [W/kg (1g)]	
BT-TX	BACK 0mm	39	2441	0.13	2.51	0.00237	0.006	1.6	
	Comments:*tune up limit power (mW) / measured conducted power (mW) = scaling factor * attached measurement plot: highest SAR value for the communication system								

According to KDB 865664 D02 v01r02 only the SAR plots for the highest SAR results for each EUT configuration and operating condition are given in the "SAR Results" part of the report.



6.5 Test Conditions and Results - Multi-transmitter SAR Result

No multi-transmitter evaluation



ANNEX A Calibration Documents

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





Schweizerischer Kalibrierdienst Service suisse d'étalonnage Servizio svizzero di taratura Swiss Calibration Service

Accreditation No.: SCS 0108

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA

Multilateral Agreement for the recognition of calibration certificates

Client Eurofins Certificate No: DAE3-522_Sep17

CALIBRATION CERTIFICATE

Object DAE3 - SD 000 D03 AA - SN: 522

Calibration procedure(s) QA CAL-06.v29

Calibration procedure for the data acquisition electronics (DAE)

Calibration date: September 18, 2017

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID#	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	31-Aug-17 (No:21092)	Aug-18
Secondary Standards	ID#	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	05-Jan-17 (in house check)	In house check: Jan-18
Calibrator Box V2.1	SE LIMS 006 AA 1002	05-Jan-17 (in house check)	In house check: Jan-18

Name Dominique Steffen

Sven Kühn

Function

Laboratory Technician

Approved by:

Calibrated by:

Deputy Manager

Issued: September 18, 2017

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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Accreditation No.: SCS 0108

Glossary

DAE data acquisition electronics

Connector angle information used in DASY system to align probe sensor X to the robot

coordinate system.

Methods Applied and Interpretation of Parameters

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
 - Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
 - AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
 - Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
 - Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - Input resistance: Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
 - Power consumption: Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

Calibration Factors	X	Υ	Z
High Range	404.509 ± 0.02% (k=2)	404.695 ± 0.02% (k=2)	404.120 ± 0.02% (k=2)
Low Range	3.92852 ± 1.50% (k=2)	3.91800 ± 1.50% (k=2)	3.91819 ± 1.50% (k=2)

Connector Angle

Connector Angle to be used in DASY system	57.5 ° ± 1 °
0.00 (0	0,10 = 1

Appendix (Additional assessments outside the scope of SCS0108)

1. DC Voltage Linearity

High Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	199994.82	-0.56	-0.00
Channel X + Input	20003.33	1.87	0.01
Channel X - Input	-20000.12	1,10	-0.01
Channel Y + Input	199991.86	-3.71	-0.00
Channel Y + Input	20004.92	3.31	0.02
Channel Y - Input	-19993.60	7.50	-0.04
Channel Z + Input	199990.86	-4.57	-0.00
Channel Z + Input	20000.33	-1.19	-0.01
Channel Z - Input	-20002.88	-1.70	0.01

Low Range	Reading (μV)	Difference (μV)	Error (%)	
Channel X + Input	2001.30	0.28	0.01	
Channel X + Input	201.10	-0.28	-0.14	
Channel X - Input	-198.17	0.25	-0.13	
Channel Y + Input	2000.80	-0.32	-0.02	
Channel Y + Input	200.72	-0.83	-0.41	
Channel Y - Input	-198.48	-0.12	0.06	
Channel Z + Input	2001.19	0.18	0.01	
Channel Z + Input	200.52	-0.87	-0.43	
Channel Z - Input	-199.09	-0.55	0.28	

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec: Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	3.13	1.90
	- 200	-0.92	-2.67
Channel Y	200	3.67	3.47
	- 200	-4.61	-4.74
Channel Z	200	-6.36	-6.38
	- 200	4.03	4.15

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec: Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200		-0.13	-3.67
Channel Y	200	7.29	.2	-0.19
Channel Z	200	7.08	5.65	1

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	16113	16236
Channel Y	16216	16793
Channel Z	16308	16730

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec Input 10MO

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	1.18	-0.73	3.40	0.58
Channel Y	0.14	-1.02	1.30	0.46
Channel Z	0.24	-0.72	1.24	0.45

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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Accreditation No.: SCS 0108

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Client Eurofins

Certificate No: EX3-3893_Sep17

CALIBRATION CERTIFICATE

Object EX3DV4 - SN:3893

Calibration procedure(s) QA CAL-01.v9, QA CAL-12.v9, QA CAL-14.v4, QA CAL-23.v5,

QA CAL-25.v6

Calibration procedure for dosimetric E-field probes

Calibration date: September 25, 2017

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	04-Apr-17 (No. 217-02521/02522)	Apr-18
Power sensor NRP-Z91	SN: 103244	04-Apr-17 (No. 217-02521)	Apr-18
Power sensor NRP-Z91	SN: 103245	04-Apr-17 (No. 217-02525)	Apr-18
Reference 20 dB Attenuator	SN: S5277 (20x)	07-Apr-17 (No. 217-02528)	Apr-18
Reference Probe ES3DV2	SN: 3013	31-Dec-16 (No. ES3-3013_Dec16)	Dec-17
DAE4	SN: 660	7-Dec-16 (No. DAE4-660_Dec16)	Dec-17
Secondary Standards	ID	Check Date (in house)	Scheduled Check
Power meter E4419B	SN: GB41293874	06-Apr-16 (in house check Jun-16)	In house check: Jun-18
Power sensor E4412A	SN: MY41498087	06-Apr-16 (in house check Jun-16)	In house check: Jun-18
Power sensor E4412A	SN: 000110210	06-Apr-16 (in house check Jun-16)	In house check: Jun-18
RF generator HP 8648C	SN: US3642U01700	04-Aug-99 (in house check Jun-16)	In house check: Jun-18
Network Analyzer HP 8753E	SN: US37390585	18-Oct-01 (in house check Oct-16)	In house check: Oct-17

Name Function Signature
Calibrated by: Jeton Kastrati Laboratory Technician

Approved by: Katja Pokovic Technical Manager

Issued: September 25, 2017

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Glossary:

TSL tissue simulating liquid NORMx,y,z sensitivity in free space

ConvF sensitivity in TSL / NORMx,y,z DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal A, B, C, D modulation dependent linearization parameters

Polarization φ φ rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., 9 = 0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

 a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013

b) IEC 62209-1, ", "Measurement procedure for the assessment of Specific Absorption Rate (SAR) from hand-held and body-mounted devices used next to the ear (frequency range of 300 MHz to 6 GHz)", July 2016

c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010

d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization 9 = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not affect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z * frequency_response (see Frequency Response Chart). This linearization is
 implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included
 in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z; Dx,y,z; VRx,y,z: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom
 exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

Probe EX3DV4

SN:3893

Manufactured: October 9, 2012

Calibrated:

September 25, 2017

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3893

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm $(\mu V/(V/m)^2)^A$	0.54	0.41	0.32	± 10.1 %
DCP (mV) ^B	101.5	103.5	100.2	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB√μV	С	D dB	VR mV	Unc ^E (k=2)	
0	CW	CW	X	0.0	0.0	1.0	0.00	145.1	±2.5 %
		Υ	0.0	0.0	1.0		132.0		
		Z	0.0	0.0	1.0		136.0		

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^B Numerical linearization parameter: uncertainty not required.

A The uncertainties of Norm X,Y,Z do not affect the E2-field uncertainty inside TSL (see Pages 5 and 6).

E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3893

Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unc (k=2)
300	45.3	0.87	12.50	12.50	12.50	0.08	1.20	± 13.3 %
450	43.5	0.87	11.59	11.59	11.59	0.14	1.20	± 13.3 %
750	41.9	0.89	11.04	11.04	11.04	0.48	0.81	± 12.0 %
900	41.5	0.97	10.32	10.32	10.32	0.48	0.82	± 12.0 %
1750	40.1	1.37	9.11	9.11	9.11	0.39	0.80	± 12.0 %
1810	40.0	1.40	8.79	8.79	8.79	0.41	0.81	± 12.0 %
1950	40.0	1.40	8.41	8.41	8.41	0.32	0.86	± 12.0 %
2150	39.7	1.53	8.35	8.35	8.35	0.39	0.84	± 12.0 %
2450	39.2	1.80	7.73	7.73	7.73	0.35	0.87	± 12.0 %
2600	39.0	1.96	7.55	7.55	7.55	0.44	0.84	± 12.0 %
5200	36.0	4.66	5.25	5.25	5.25	0.35	1.80	± 13.1 %
5500	35.6	4.96	5.14	5.14	5.14	0.40	1.80	± 13.1 %
5800	35.3	5.27	4.98	4.98	4.98	0.40	1.80	± 13.1 %

^C Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

F At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to \pm 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to \pm 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

EX3DV4-SN:3893

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3893

Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unc (k=2)
300	58.2	0.92	11.86	11.86	11.86	0.05	1.20	± 13.3 %
450	56.7	0.94	11.71	11.71	11.71	0.10	1,20	± 13.3 %
750	55.5	0.96	10.63	10.63	10.63	0.52	0.81	± 12.0 %
900	55.0	1.05	10.31	10.31	10.31	0.48	0.80	± 12.0 %
1750	53.4	1.49	8.76	8.76	8.76	0.38	0.80	± 12.0 %
1810	53.3	1.52	8.51	8.51	8.51	0.33	0.90	± 12.0 %
1950	53.3	1.52	8.57	8.57	8.57	0.31	0.98	± 12.0 %
2150	53.1	1.66	8.36	8.36	8.36	0.39	0.81	± 12.0 %
2450	52.7	1.95	7.96	7.96	7.96	0.35	0.86	± 12.0 %
2600	52.5	2.16	7.73	7.73	7.73	0.27	0.95	± 12.0 %
5200	49.0	5.30	4.88	4.88	4.88	0.40	1.90	± 13.1 %
5500	48.6	5.65	4.32	4.32	4.32	0.45	1.90	± 13.1 %
5800	48.2	6.00	4.41	4.41	4.41	0.45	1.90	± 13.1 %

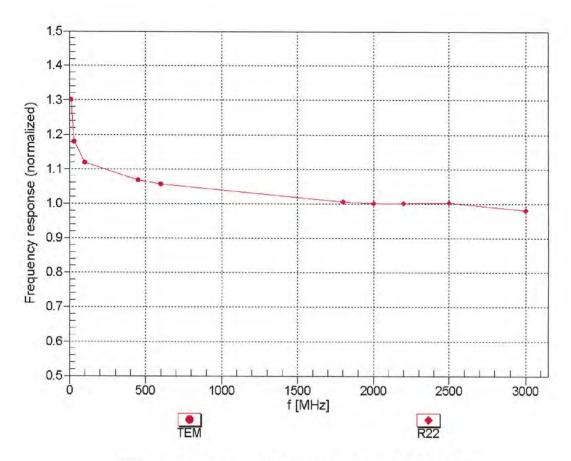
^c Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

validity can be extended to \pm 110 MHz.

F At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to \pm 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to \pm 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

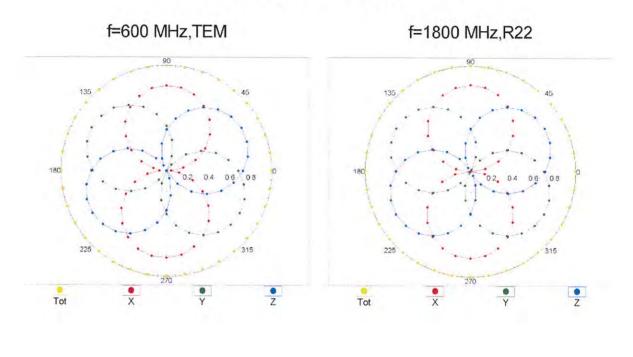
^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

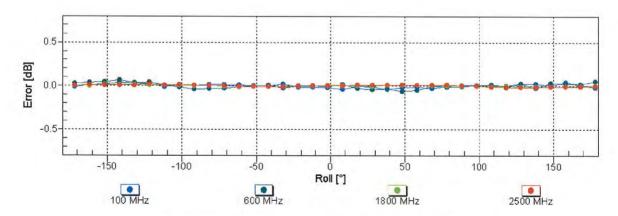
Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

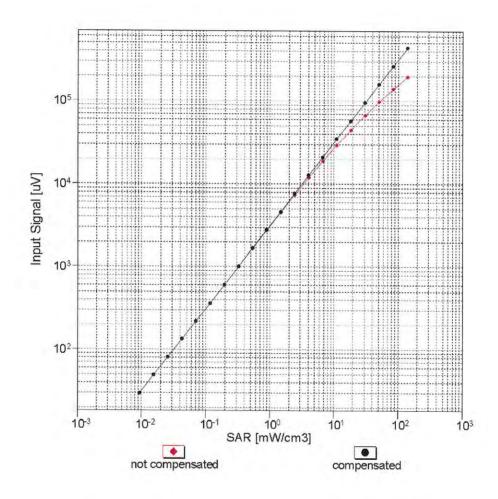
Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$

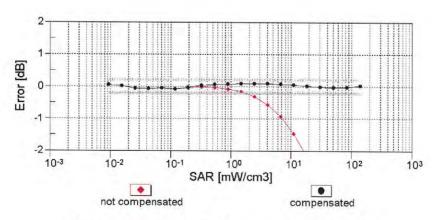




Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Dynamic Range f(SAR_{head}) (TEM cell , f_{eval}= 1900 MHz)

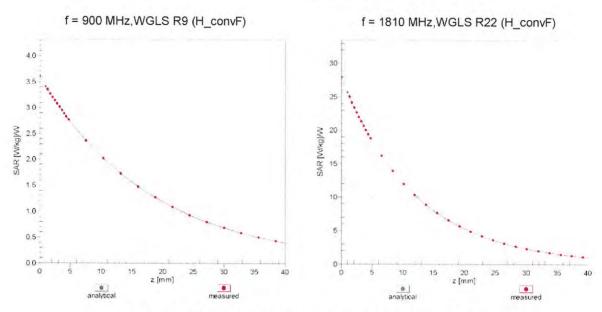




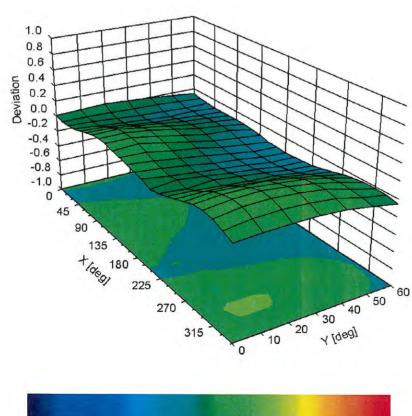
Uncertainty of Linearity Assessment: ± 0.6% (k=2)

EX3DV4-SN:3893

Conversion Factor Assessment



Deviation from Isotropy in Liquid Error (φ, θ), f = 900 MHz



DASY/EASY - Parameters of Probe: EX3DV4 - SN:3893

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	-21.9
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	1.4 mm

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst
Service suisse d'étalonnage
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Swiss Calibration Service

Accreditation No.: SCS 0108

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Client

Eurofins

Certificate No: D2450V2-722_Sep15

CALIBRATION CERTIFICATE

Object D2450V2 - SN: 722

Calibration procedure(s) QA CAL-05.v9

Calibration procedure for dipole validation kits above 700 MHz

Calibration date: September 28, 2015

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID#	Cal Date (Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	07-Oct-14 (No. 217-02020)	Oct-15
Power sensor HP 8481A	US37292783	07-Oct-14 (No. 217-02020)	Oct-15
Power sensor HP 8481A	MY41092317	07-Oct-14 (No. 217-02021)	Oct-15
Reference 20 dB Attenuator	SN: 5058 (20k)	01-Apr-15 (No. 217-02131)	Mar-16
Type-N mismatch combination	SN: 5047.2 / 06327	01-Apr-15 (No. 217-02134)	Mar-16
Reference Probe EX3DV4	SN: 7349	30-Dec-14 (No. EX3-7349_Dec14)	Dec-15
DAE4	SN: 601	17-Aug-15 (No. DAE4-601_Aug15)	Aug-16
Secondary Standards	ID#	Check Date (in house)	Scheduled Check
RF generator R&S SMT-06	100972	15-Jun-15 (in house check Jun-15)	In house check: Jun-18
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (in house check Oct-14)	In house check: Oct-15

Calibrated by:

Name Jeton Kastrati Function Laboratory Technician Signature

Approved by:

Katja Pokovic

Technical Manager

Issued: September 28, 2015

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Calibration Laboratory of

Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland





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Servizio svizzero di taratura
Swiss Calibration Service

Accreditation No.: SCS 0108

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Glossary:

TSL tissue simulating liquid

ConvF sensitivity in TSL / NORM x,y,z N/A not applicable or not measured

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Additional Documentation:

e) DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed
 point exactly below the center marking of the flat phantom section, with the arms oriented
 parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point.
 No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.8.8
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy , $dz = 5 mm$	
Frequency	2450 MHz ± 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	39.2 ± 6 %	1.86 mho/m ± 6 %
Head TSL temperature change during test	< 0.5 °C		(

SAR result with Head TSL

SAR averaged over 1 cm ³ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	12.7 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	50.0 W/kg ± 17.0 % (k=2)

SAR averaged over 10 cm ³ (10 g) of Head TSL	condition	
SAR measured	250 mW input power	5.90 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	23.4 W/kg ± 16.5 % (k=2)

Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	53.2 ± 6 %	2.00 mho/m ± 6 %
Body TSL temperature change during test	< 0.5 °C	1	1 1 1 44 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1

SAR result with Body TSL

SAR averaged over 1 cm ³ (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	12.5 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	49.5 W/kg ± 17.0 % (k=2)

SAR averaged over 10 cm ³ (10 g) of Body TSL	condition	
SAR measured	250 mW input power	5.88 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	23.4 W/kg ± 16.5 % (k=2)

Appendix (Additional assessments outside the scope of SCS 0108)

Antenna Parameters with Head TSL

Impedance, transformed to feed point	$51.7 \Omega + 9.2 j\Omega$		
Return Loss	- 20.8 dB		

Antenna Parameters with Body TSL

Impedance, transformed to feed point	$46.3~\Omega + 8.6~\mathrm{j}\Omega$		
Return Loss	- 20.2 dB		

General Antenna Parameters and Design

	200. 21M = 4
Electrical Delay (one direction)	1.152 ns
The state of the s	(1) (1) (1) (1) (1) (1) (1) (1) (1) (1)

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG
Manufactured on	October 16, 2002

DASY5 Validation Report for Head TSL

Date: 28.09.2015

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 722

Communication System: UID 0 - CW; Frequency: 2450 MHz

Medium parameters used: f = 2450 MHz; $\sigma = 1.86 \text{ S/m}$; $\varepsilon_r = 39.2$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

• Probe: EX3DV4 - SN7349; ConvF(7.67, 7.67, 7.67); Calibrated: 30.12.2014;

• Sensor-Surface: 1.4mm (Mechanical Surface Detection)

• Electronics: DAE4 Sn601; Calibrated: 17.08.2015

Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001

DASY52 52.8.8(1222); SEMCAD X 14.6.10(7331)

Dipole Calibration for Head Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

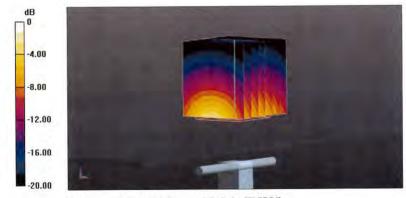
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 111.4 V/m; Power Drift = 0.00 dB

Peak SAR (extrapolated) = 26.1 W/kg

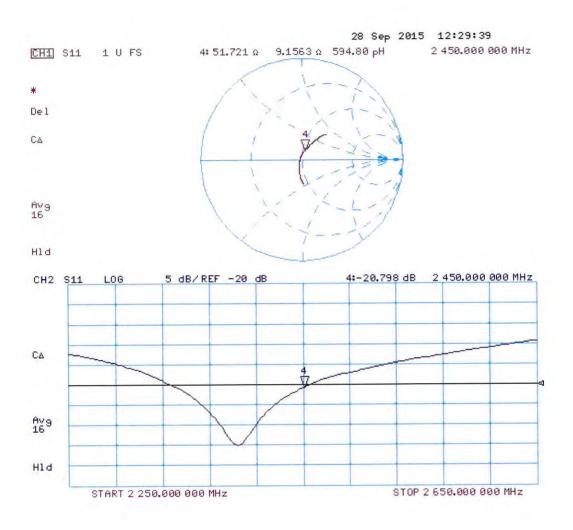
SAR(1 g) = 12.7 W/kg; SAR(10 g) = 5.9 W/kg

Maximum value of SAR (measured) = 21.1 W/kg



0 dB = 21.1 W/kg = 13.24 dBW/kg

Impedance Measurement Plot for Head TSL



DASY5 Validation Report for Body TSL

Date: 28.09.2015

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 722

Communication System: UID 0 - CW; Frequency: 2450 MHz

Medium parameters used: f = 2450 MHz; $\sigma = 2 \text{ S/m}$; $\varepsilon_r = 53.2$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

Probe: EX3DV4 - SN7349; ConvF(7.53, 7.53, 7.53); Calibrated: 30.12.2014;

• Sensor-Surface: 1.4mm (Mechanical Surface Detection)

• Electronics: DAE4 Sn601; Calibrated: 17.08.2015

Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; Serial: 1002

• DASY52 52.8.8(1222); SEMCAD X 14.6.10(7331)

Dipole Calibration for Body Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 105.8 V/m; Power Drift = -0.01 dB

Peak SAR (extrapolated) = 24.7 W/kg

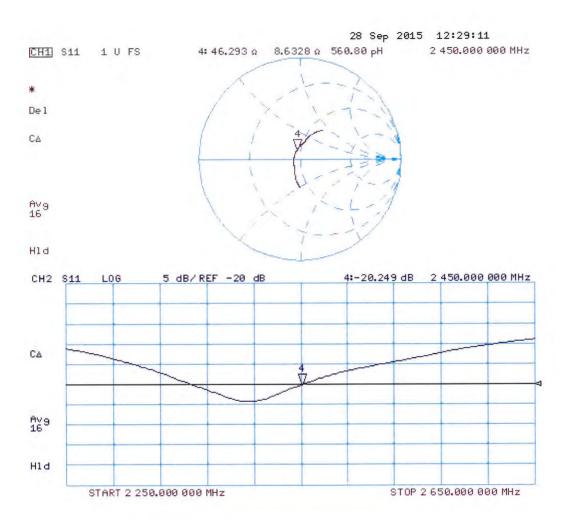
SAR(1 g) = 12.5 W/kg; SAR(10 g) = 5.88 W/kg

Maximum value of SAR (measured) = 20.5 W/kg



0 dB = 20.5 W/kg = 13.12 dBW/kg

Impedance Measurement Plot for Body TSL





Validation Report No. VAL 0284 EF 2017-11

Kind of doc.: QM Template

Е	UF	₹О	FI	NS	PR	OD	UCT	SER\	/ICE	Gmbl	4

Storkower Str. 38c, 15526 Reichenwalde, Germany

Customer

Eurofins Product Service GmbH

2 (Ͻbj	ject
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Equipment Number EF00284

Equipment Name: System validation dipole

Equipment Type: D2450V2 Serial Number:

Manufacturer: Schmid & Partner Engineering AG

State of Measurement

 \boxtimes Validation: Performance Control: \boxtimes Other:

Performance of Measurement

(e.g. object of validation such as specific setup, non-standard method or SW, specification of the requirements, test set-up configuration, risk analysis etc.)

Dipol verification

4.2 Validation procedure / measurement

(e.g. comparison of results achieved with other methods, interlaboratory comparison, systematic assessment of factors influencing the result, assessment of the uncertainty of the results based on scientific understanding of the theoretical principles of the method and practical experience; criteria/requirements for approval/rejection etc.)

According KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz v01r04 3.2.2 Dipole calibration

Limits for the verification: return loss <20% to the original measurement or >20 dB minimum return-loss

Impedance <5 Ω to the original measurement.

4.3 Used reference equipment

Equipment name	Equipment type	Manufacturer	Equipment number	Cal. Date	Cal. Due Date
RF Network analyzer	8752 C	Hewlett-Packard Company Santa Clara	EF00140	2017-07-28	2018-07-28

-	new acquired (incl. calibration)	
-	new calibrated	
-	check reference standard	\boxtimes

4.4 **Environmental conditions**

Temperature:	_23_°C <u>+</u> 2°C
Relative Air Humidity:	_50_ rH <u>+</u> 5%
Air Pressure:	_1020_ hPa <u>+</u> 5%



Validation Report

No. VAL 0284 EF 2017-11

Kind of doc.: QM Template

EUROFINS PRODUCT SERVICE GmbH

Storkower Str. 38c, 15526 Reichenwalde, Germany

5 Results

5.1 General:

(e.g. measurement results, user instructions such as handling, transport, storage, preparation; checks to be made before the work started; information about how to install (operations)-, to maintain-, to train and to use; safety measures etc.)

	Original measurement	Verification measurement	Margin
Impedance, transformend to feed point	46.3 Ω + 8.6 jΩ	48.60 Ω + 9.94 jΩ	2.51 Ω
Return Loss	-20.2 dB	-21.24 dB	-5.2 % / -1.24 dB
Tissue Validation εr	52.7	50.559	-4.06 %
Tissue Validation σ [S/m]	1.95	2.12	3.18 %
System validation	12.38 W/kg (1g)	13.1 W/kg (1g)	5.82 %
Date:	28.09.2015	27.06.2017	

Measurement uncertainty

The reported expanded uncertainty of measurement is stated as the standard uncertainty multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%. +/- 2.5 %

5.3	Results of Validation		
Valid	lated	· ·	\boxtimes
Not v	validated		
6	Operator		
Pude	lle	P. Probell	
Nam	е	Signature	
Place	e and Date of Verification:	Reichenwalde, 07.11.2017	

Attachment:

Impedance, Return Loss, System validierung

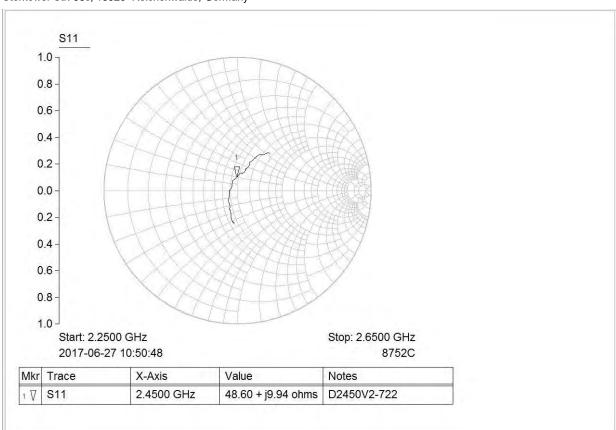


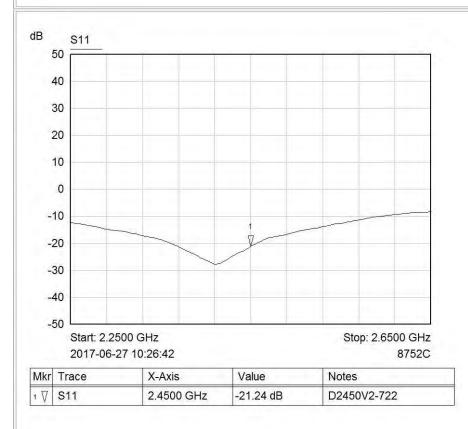
Validation Report No. VAL 0284 EF 2017-11

Kind of doc.: QM Template

EUROFINS PRODUCT SERVICE GmbH

Storkower Str. 38c, 15526 Reichenwalde, Germany





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Validation Report No. VAL 0284 EF 2017-11

Kind of doc.: QM Template

EUROFINS PRODUCT SERVICE GmbH

Storkower Str. 38c, 15526 Reichenwalde, Germany

Date Time: 2017-11-07 14:09:47

Test Laboratory: Eurofins Product Service GmbH

Dipol Valid.2450 (m) 250mW ELI4 07.11.2017

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 722

Communication System: UID 0 - n/a, CW; Frequency: 2450 MHz; Duty Cycle: 1:1 Medium: Muscle 2450 MHz Medium parameters used (interpolated): f = 2450 MHz; $\sigma = 2.012$ S/m; $\varepsilon_{\tau} = 2.012$ MHz; $\sigma = 2.012$ S/m; $\sigma = 2.012$ S/m;

50.559; ρ = 1000 kg/m³ Phantom section: Flat Section

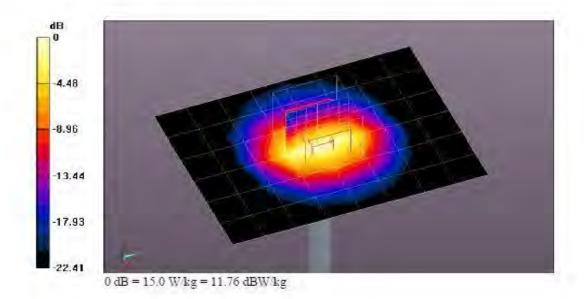
Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5.2 Configuration:

- Probe: EX3DV4 SN3893; ConvF(7.96, 7.96, 7.96); Calibrated: 2017-09-25;
- · Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 2017-09-18
- Phantom: Flat Phantom ELI4.0; Type: QDOVA001BB; Serial: SN:1013
- Measurement SW: DASY52, Version 52.8 (6); SEMCAD X Version 14.6.9 (7117)

System Performance Check at Frequencies above 1 GHz/d=10mm, Pin=250 mW, dist=4.0mm (EX-Probe)/Area Scan (7x9x1): Measurement grid: dx=15mm. dy=15mm Maximum value of SAR (measured) = 15.0 W/kg

System Performance Check at Frequencies above 1 GHz/d=10mm, Pin=250 mW, dist=4.0mm (EX-Probe)/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 80.629 V/m; Power Drift = -0.01 dB
Peak SAR (extrapolated) = 26.7 W/kg
SAR(1 g) = 13.1 W/kg; SAR(10 g) = 6.04 W/kg
Maximum value of SAR (measured) = 15.2 W/kg



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ANNEX B System Validation Reports

Date/Time: 2017-11-07 14:09:47

Test Laboratory: Eurofins Product Service GmbH

Dipol Valid.2450 (m) 250mW ELI4 07.11.2017

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 722

Communication System: UID 0 - n/a, CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz Medium parameters used (interpolated): f = 2450 MHz; $\sigma = 2.012$ S/m; $\varepsilon_r =$

50.559; $\rho = 1000 \text{ kg/m}^3$ Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5.2 Configuration:

• Probe: EX3DV4 - SN3893; ConvF(7.96, 7.96, 7.96); Calibrated: 2017-09-25;

• Sensor-Surface: 4mm (Mechanical Surface Detection)

• Electronics: DAE3 Sn522; Calibrated: 2017-09-18

• Phantom: Flat Phantom ELI4.0; Type: QDOVA001BB; Serial: SN:1013

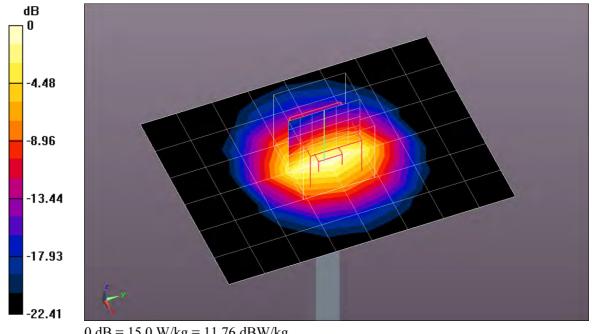
• Measurement SW: DASY52, Version 52.8 (6); SEMCAD X Version 14.6.9 (7117)

System Performance Check at Frequencies above 1 GHz/d=10mm, Pin=250 mW, dist=4.0mm (EX-Probe)/Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 15.0 W/kg

System Performance Check at Frequencies above 1 GHz/d=10mm, Pin=250 mW, dist=4.0mm (EX-Probe)/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 80.629 V/m; Power Drift = -0.01 dB Peak SAR (extrapolated) = 26.7 W/kg

SAR(1 g) = 13.1 W/kg; SAR(10 g) = 6.04 W/kg

Maximum value of SAR (measured) = 15.2 W/kg



0 dB = 15.0 W/kg = 11.76 dBW/kg



ANNEX C SAR Measurement Reports

Date/Time: 2017-11-07 11:36:53

Test Laboratory: Eurofins Product Service GmbH

2.4G_2xBT-DH5-mid-_Flat_Back_0mm

DUT: CEECOACH; Type: BT-Headset; Serial: Sample1

Communication System: UID 0 - n/a, BT 2.4GHz DH5; Frequency: 2441 MHz; Duty Cycle: 1:1.38388 Medium: Muscle 2450 MHz Medium parameters used (interpolated): f = 2441 MHz; $\sigma = 1.998$ S/m; $\varepsilon_r = 1.998$

50.563; $\rho = 1000 \text{ kg/m}^3$ Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5.2 Configuration:

• Probe: EX3DV4 - SN3893; ConvF(7.96, 7.96, 7.96); Calibrated: 2017-09-25;

• Sensor-Surface: 4mm (Mechanical Surface Detection)

• Electronics: DAE3 Sn522; Calibrated: 2017-09-18

• Phantom: Flat Phantom ELI4.0; Type: QDOVA001BB; Serial: SN:1013

• Measurement SW: DASY52, Version 52.8 (6); SEMCAD X Version 14.6.9 (7117)

Configuration/CEECOACH/Area Scan (10x13x1): Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (measured) = 0.00561 W/kg

Configuration/CEECOACH/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 1.269 V/m; Power Drift = 0.13 dB

Peak SAR (extrapolated) = 0.0280 W/kg

SAR(1 g) = 0.00237 W/kg; SAR(10 g) = 0.000544 W/kg

Maximum value of SAR (measured) = 0.00598 W/kg

