
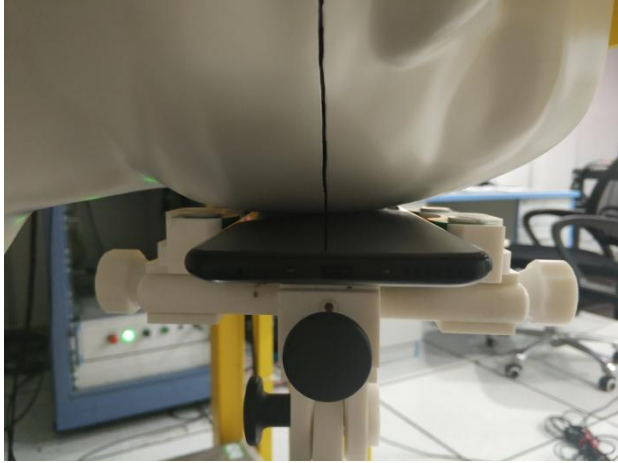
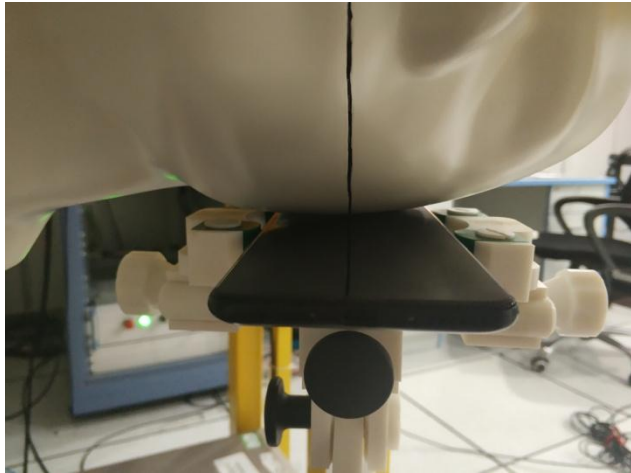
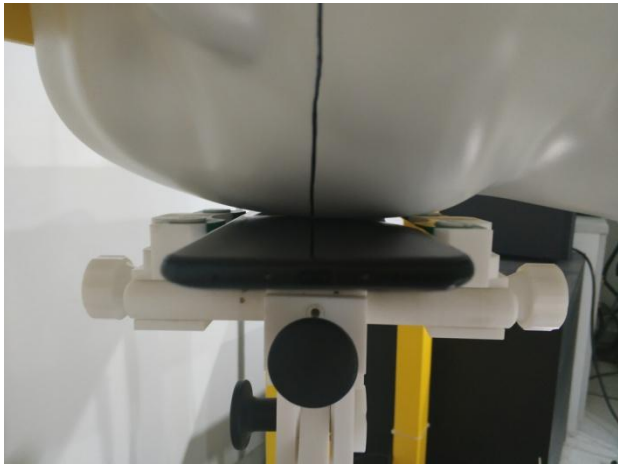
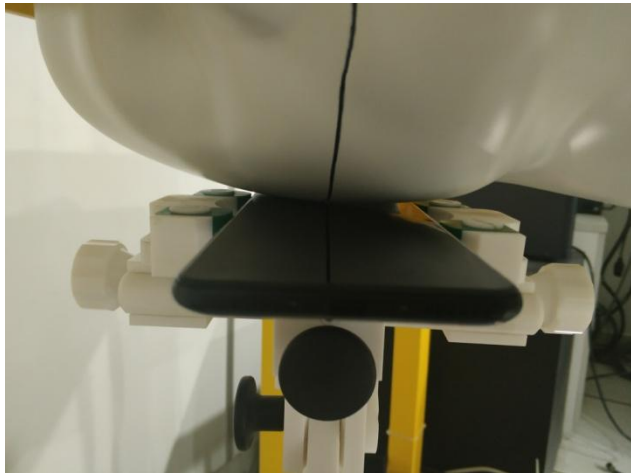
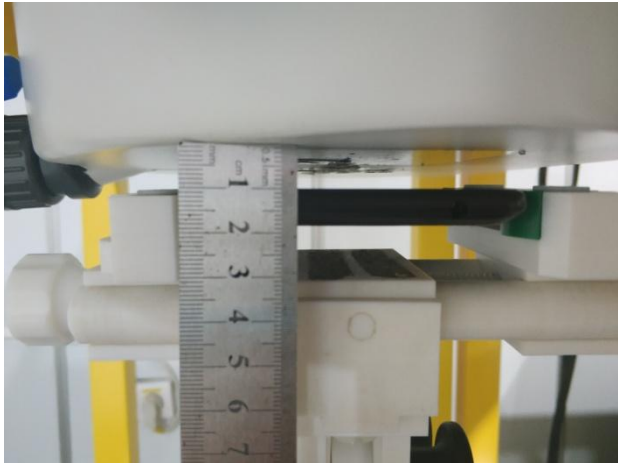
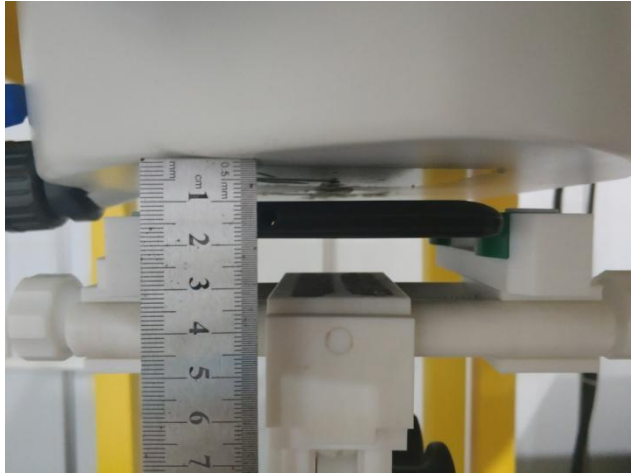

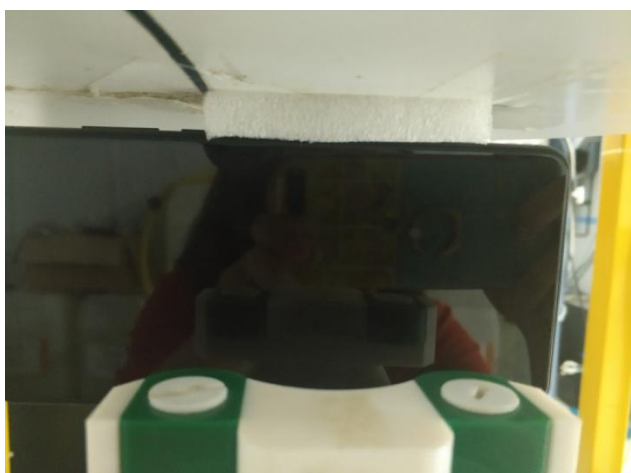





Appendix D: SAR Test Setup

<p>Photo 1: Measurement System SATIMO</p>	<p>Photo 2: Left Cheek</p>
 A photograph showing the measurement system setup in a laboratory. A white KUKA robotic arm is positioned over a white mannequin head. Various electronic equipment, including a computer monitor and a power supply, are visible on a table in the background.	 A close-up photograph of the left cheek area of the mannequin head. The head is mounted on a white plastic fixture with a black circular sensor or antenna positioned directly below the cheek.
<p>Photo 3: Left Tilt 15 °</p>	<p>Photo 4: Right Cheek</p>
 A close-up photograph of the left cheek area of the mannequin head, tilted at a 15-degree angle. The black circular sensor is positioned below the cheek.	 A close-up photograph of the right cheek area of the mannequin head. The black circular sensor is positioned below the cheek.
<p>Photo 5: Right Tilt 15 °</p>	<p>Photo 6: Face upward 10mm</p>
 A close-up photograph of the right cheek area of the mannequin head, tilted at a 15-degree angle. The black circular sensor is positioned below the cheek.	 A close-up photograph of the mannequin head with a ruler placed vertically next to it. The ruler shows a measurement of 10mm, indicating the distance between the face and the sensor.

<p>Photo 7: Back Upward 10mm</p>	<p>Photo 8: Edge A 10mm</p>
	
<p>Photo 9: Edge B 10mm</p>	<p>Photo 10: Edge C 10mm</p>
	
<p>Photo 11: Edge D 10mm</p>	<p>Photo 12: Liquid deep(15cm)</p>
	

EUT Front View	EUT Back View
