

SAR Test Report

Report No.: AGC02294200304FH01

FCC ID : 2AJGM-F17

PRODUCT DESIGNATION: TWO WAY RADIO

BRAND NAME : POFUNG, BAOFENG

MODEL NAME : F17, BF-T17, F17G, F175M, F17Z

APPLICANT: PO FUNG ELECTRONIC(HK) INTERNATIOANL GROUP COMPANY

DATE OF ISSUE : Jun. 01,2020

IEEE Std. 1528:2013

STANDARD(S)FCC 47 CFR Part 2§2.1093:2013

: IEEE 5td CO5 1 ™-2005

IEEE Std C95.1 ™-2005

IEC 62209-1: 2016

REPORT VERSION : V1.0

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Report Revise Record

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	2 160	Jun. 01,2020	Valid	Initial Release



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Test Report					
Applicant Name	PO FUNG ELECTRONIC(HK) INTERNATIOANL GROUP COMPANY				
Applicant Address	3/F FULOK BLDG 131-133 WING LOK ST SHEUNG WAN, Hong Kong				
Manufacturer Name	PO FUNG ELECTRONIC(HK) INTERNATIOANL GROUP COMPANY				
Manufacturer Address	3/F FULOK BLDG 131-133 WING LOK ST SHEUNG WAN, Hong Kong				
Factory Name	PO FUNG ELECTRONIC(HK) INTERNATIOANL GROUP COMPANY				
Factory Address	3/F FULOK BLDG 131-133 WING LOK ST SHEUNG WAN, Hong Kong				
Product Designation	TWO WAY RADIO				
Brand Name	POFUNG, BAOFENG				
Model Name	F17, BF-T17, F17G, F175M, F17Z				
Different Description	All the same except the model name. The test model is F17.				
EUT Voltage	DC3.7V				
Applicable Standard	IEEE Std. 1528:2013 FCC 47 CFR Part 2§2.1093:2013 IEEE Std C95.1 ™-2005 IEC 62209-1: 2016				
Test Date	May 05,2020				
Report Template	AGCRT- US -PTT/SAR (2018-02-02)				

Note: The results of testing in this report apply to the product/system which was tested only.

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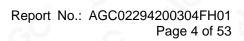




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1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Highest Report standalone SAR Summary (50% duty cycle)

	Type of		Highest Reported 1g-SAR(W/Kg)			
Frequency Band	signal	Separation	Face Up (with 25mm separation)	Back Touch		
462.5625-462.7125MHz(2W)	-0	12.5KHz	0.625	1.263		
467.5625-467.7125MHz(0.5W)	Analog	12.5KHz	0.308	1.017		
462.5500-462.7250MHz(2W)		12.5KHz	0.489	1.152		

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure environment limits(1.6W/Kg) specified in 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1, and had been tested in accordance with measurement methods and procedures specified in IEEE 1528-2013 and the following specific FCC Test Procedures:

KDB447498 D01 General RF Exposure Guidance v06 KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04 KDB 643646 D01 SAR Test for PTT Radios v01r03





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2. GENERAL INFORMATION

2.1. EUT Description

General Information	
Product Name	TWO WAY RADIO
Test Model	F17
Hardware Version	BF-T17-A21-V1.3-A
Software Version	BF-T17-A21-V1.3-A
Exposure Category:	General Population/Uncontrolled Environments
Modulation Type	F3E
TX Frequency Range	462.5625MHz -462.7125MHz(2W) 467.5625MHz -467.7125MHz(0.5W) 462.5500MHz-462.7250MHz(2W)
Rated Power	2W/0.5W (It was fixed by the manufacturer, any individual can't arbitrarily change it.)
Max. Output Power	32.71dBm
Channel Spacing	12.5 KHz
Antenna Type	Inseparable
Antenna Gain	1.5dBi
Body-Worn Accessories:	Belt Clip with headset
Face-Head Accessories:	None
Battery Type (s) Tested:	DC3.7V, 1500mAh (by battery)

Note: 1.	The sar	mple	used	for	testing	is	end	product.

2. The test sample has no any deviation to the test method of standard mentioned in page 1.

Draduet	Type	CO C C
Product	Production unit	☐ Identical Prototype

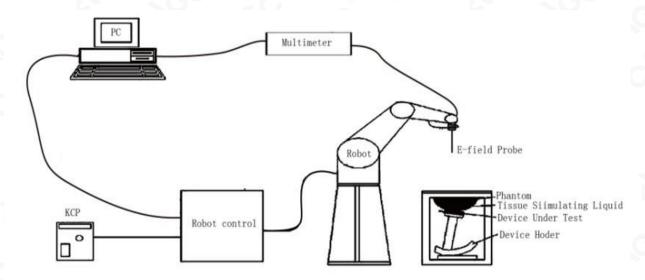






3. SAR MEASUREMENT SYSTEM

3.1. The SATIMO system used for performing compliance tests consists of following items



The COMOSAR system for performing compliance tests consists of the following items:

- The PC. It controls most of the bench devices and stores measurement data. A computer running WinXP and the Opensar software.
- The E-Field probe. The probe is a 3-axis system made of 3 distinct dipoles. Each dipole returns a voltage in function of the ambient electric field.
- The Keithley multimeter measures each probe dipole voltages.
- The SAM phantom simulates a human head. The measurement of the electric field is made inside the phantom.
- The liquids simulate the dielectric properties of the human head tissues.
- · The network emulator controls the mobile phone under test.
- The validation dipoles are used to measure a reference SAR. They are used to periodically check the bench to make sure that there is no drift of the system characteristics over time.
- •The phantom, the device holder and other accessories according to the targeted measurement.



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3.2. COMOSAR E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SATIMO. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SATIMO conducts the probe calibration in compliance with international and national standards (e.g. EN62209, etc.)Under ISO17025.The calibration data are in Appendix D.

Isotropic E-Field Probe Specification

Model	SSE2
Manufacture	MVG
Identification No.	SN 41/18 EPGO334
Frequency	0.45GHz-6GHz Linearity:±0.08dB(0.45GHz-6GHz)
Dynamic Range	0.01W/Kg-100W/Kg Linearity:±0.08dB
Dimensions	Overall length:330mm Length of individual dipoles:2mm Maximum external diameter:8mm Probe Tip external diameter:2.5mm Distance between dipoles/ probe extremity:1mm
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precisin of better 30%.

3.3. Robot

The COMOSAR system uses the KUKA robot from SATIMO SA (France). For the 6-axis controller COMOSAR system, the KUKA robot controller version from SATIMO is used.

The XL robot series have many features that are important for our application:

- ☐ High precision (repeatability 0.02 mm)
- ☐ High reliability (industrial design)
- ☐ Jerk-free straight movements
- ☐ Low ELF interference (the closed metallic
- construction shields against motor control fields)
- ☐ 6-axis controller





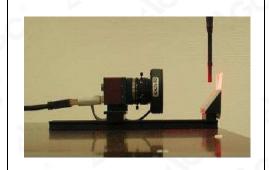


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3.4. Video Positioning System

The video positioning system is used in Open SAR to check the probe. Which is composed of a camera, LED, mirror and mechanical parts. The camera is piloted by the main computer with fire wire link. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.

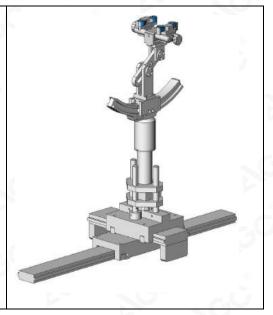


3.5. Device Holder

The COMOSAR device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles. The COMOSAR device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity

 $\epsilon r = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.





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3.6. SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

□ Left head

☐ Right head

☐ Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

ELLI39 Phantom

The Flat phantom is a fiberglass shell phantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom





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4. SAR MEASUREMENT PROCEDURE

4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of given mass density (p). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg) SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \frac{dT}{dt}\Big|_{t=0}$$

Where

SAR is the specific absorption rate in watts per kilogram;
E is the r.m.s. value of the electric field strength in the tissue in volts per meter;
σ is the conductivity of the tissue in siemens per metre;
ρ is the density of the tissue in kilograms per cubic metre;
ch is the heat capacity of the tissue in joules per kilogram and Kelvin;

 $\frac{dT}{dt}$ | t=0 is the initial time derivative of temperature in the tissue in kelvins per second



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4.2. SAR Measurement Procedure

Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance os sensor calibration points to probe tip as `defined in the probe properties,

Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in SATIMO software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528 and IEC62209 standards, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	≤ 3 GHz	> 3 GHz	
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 ± 1 mm	½·δ·ln(2) ± 0.5 mm	
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30° ± 1°	20° ± 1°	
	≤2 GHz: ≤15 mm 2 – 3 GHz: ≤12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm	
Maximum area scan spatial resolution: Δx_{Area} , Δy_{Area}	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.		

Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g abd 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.



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Zoom Scan Parameters extracted from KDB865664 D01 SAR Measurement 100MHz to 6GHz

Maximum zoom scan spatial resolution: Δx_{Zoom} , Δy_{Zoom}			\leq 2 GHz: \leq 8 mm 2 – 3 GHz: \leq 5 mm [*]	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform ;	grid: $\Delta z_{Zoom}(n)$	≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
	graded	Δz _{Zoom} (1): between 1 st two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
	grid $\Delta z_{Zoom}(n>1)$: between subsequent points		≤ 1.5·Δz	Zoom(n-1)
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.

Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.



^{*} When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.



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5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 10% are listed in 6.2

5.1. The composition of the tissue simulating liquid

Ingredient (% Weight) Frequency (MHz)	Water	Nacl	Sugar	HEC	Bactericide	DGBE	1,2- Propanediol	Triton X-100
450 Head (100%)	38.56	3.95	56.32	0.98	0.19	0.0	0.0	0.0

5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEC 62209-1 have been incorporated in the following table. The body tissue dielectric parameters recommended by the IEC 62209-2 have been incorporated in the following table.

Target Frequency	ŀ	nead	bo	ody
(MHz)	εr	σ (S/m)	εr	σ (S/m)
150	52.3	0.76	52.3	0.76
300	45.3	0.87	45.3	0.87
450	43.5	0.87	43.5	0.87
835	41.5	0.90	41.5	0.90
900	41.5	0.97	41.5	0.97
915	41.5	0.98	41.5	0.98
1450	40.5	1.20	40.5	1.20
1610	40.3	1.29	40.3	1.29
1800 – 2000	40.0	1.40	40.0	1.40
2450	39.2	1.80	39.2	1.80
3000	38.5	2.40	38.5	2.40

($\epsilon r = relative permittivity$, $\sigma = conductivity$ and $\rho = 1000 \text{ kg/m3}$)



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5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using SATIMO Dielectric Probe Kit and R&S Network Analyzer ZVL6.

	Tissue Stimula	nt Measurement for 450MHz		
	Dielectric Pa	rameters (±10%)	_ (3	1
Fr.		Head	Tissue Temp Test	
(MHz)	εr43.50(39.15 – 47.85)	δ[s/m]0.87(0.783 - 0.957)	[°C]	0
450.000	42.52	0.85		a.C
462	41.89	0.87	20.8	May 05,2020
467	41.65	0.88	8	





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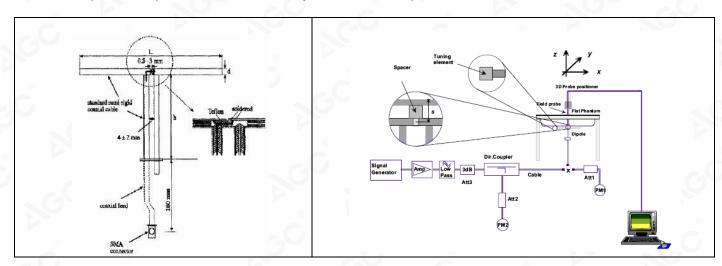
6. SAR SYSTEM CHECK PROCEDURE

6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each SATIMO system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the SATIMO software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.



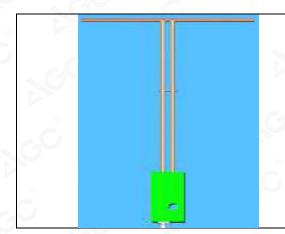


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6.2. SAR System Check 6.2.1. Dipoles



The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. the table below provides details for the mechanical and electrical specifications for the dipoles

Frequency	R/L (mm)	R/h (mm)	d (mm)
450MHz	290	166.7	6.35

6.2.2. System Check Result

System Perf	System Performance Check at 450MHz											
Validation Kit: SN 30/14DIP 0G450-330												
Frequency Value(W/Kg)		0	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Reference Result (± 10%)			Tissue Temp.	Test time				
[MHz]	1g	10g	1g	10g	1g	10g	[°C]					
450 head	4.80	3.08	4.320-5.280	2.772-3.388	4.86	3.25	20.8	May 05,2020				

Note:

(1) We use a CW signal of 18dBm for system check, and then all SAR value are normalized to 1W forward power. The result must be within ±10% of target value.



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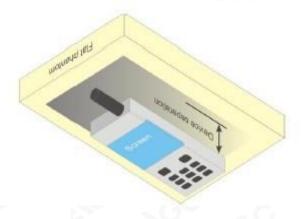
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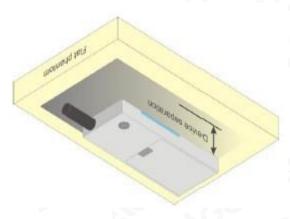
7. EUT TEST POSITION

This EUT was tested in Front Face and Rear Face.

7.1. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.
 (2) To adjust the EUT parallel to the flat phantom.
 (3) To adjust the distance between the EUT surface and the flat phantom to 25mm while used in front of face, and body back touch with belt clip.







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8. SAR EXPOSURE LIMITS

Limits for General population/Uncontrolled exposure Environment

Type Exposure Limits	general population/uncontrolled exposure limits (W/Kg)
Spatial Average SAR (whole body)	1.6



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9. TEST FACILITY

Test Site	Attestation of Global Compliance (Shenzhen) Co., Ltd
Location	1-2/F, Building 19, Junfeng Industrial Park, Chongqing Road, Heping Community, Fuhai Street, Bao'an District, Shenzhen, Guangdong, China
Designation Number	CN1259
FCC Test Firm Registration Number	975832
A2LA Cert. No.	5054.02
Description	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by A2LA





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10. TEST EQUIPMENT LIST

Equipment description	Manufacturer/ Model	Identification No.	Current calibration date	Next calibration date
SAR Probe	MVG	SN 41/18 EPGO334	Jun. 04,2019	Jun. 03,2020
Phantom	SATIMO	SN_4511_SAM90	Validated. No cal required.	Validated. No cal required.
Phantom	SATIMO	SN_2316_ELLI39	Validated. No cal required.	Validated. No cal required.
Liquid	SATIMO	<u> </u>	N/A	N/A
Multimeter	Keithley 2000	4114939	Sep. 09,2019	Sep. 08,2020
Dipole	SATIMO SID450	SN 30/14 DIP0G450-330	Aug. 15,2017	Aug. 14,2020
Signal Generator	Agilent-E4438C	US41461365	Oct. 08,2019	Oct. 07,2020
Vector Analyzer	Agilent / E4440A	US41421290	Sep. 09,2019	Sep. 08,2020
Network Analyzer	Rhode & Schwarz ZVL6	SN101443	Oct. 08,2019	Oct. 07,2020
Attenuator	Warison /WATT-6SR1211	S/N:WRJ34AYM2F1	June 11,2019	June 10, 2020
Attenuator	Mini-circuits / VAT-10+	31405	June 11,2019	June 10, 2020
Amplifier	AS0104-55_55	1004793	June 12,2019	June 11,2020
Directional Couple	Werlatone/ C5571-10	SN99463	June 12,2019	June 11,2020
Power Sensor	NRP-Z21	1137.6000.02	Sep. 09,2019	Sep. 08,2020
Power Sensor	NRP-Z23	US38261498	Feb. 18,2020	Feb. 17,2021
Power Viewer	R&S	V2.3.1.0	N/A	N/A

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

- 1. There is no physical damage on the dipole;
- 2. System validation with specific dipole is within 10% of calibrated value;
- 3. Return-loss is within 20% of calibrated measurement;
- 4. Impedance is within 5Ω of calibrated measurement.





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11 MEASUREMENT UNCERTAINTY

NA	S/ easurement	ATIMO Unce				10 gram			
a	b	C C	d	е	f	g g	h	d.	k
Uncertainty Component	Sec.	Tol (+- %)	Prob.	f(d,k) Div.	Ci (1g)	Ci (10g)	cxf/e 1g Ui	c×g/e 10g Ui	vi
Measurement System		(+- 70)	Dist.		-0		(±%)	(±%)	
Probe calibration	E.2.1	5.831	N	1	1	1	5.83	5.83	∞
Axial Isotropy	E.2.2	0.685	R	$\sqrt{3}$	√0.5	√0.5	0.28	0.28	00
Hemispherical Isotropy	E.2.2	1.14	R	$\sqrt{3}$	◎ √0.5	√0.5	0.47	0.47	000
Boundary effect	E.2.3	1	R	$\sqrt{3}$	1	1	0.58	0.58	00
Linearity	E.2.4	0.935	R	$\sqrt{3}$	1	1	0.54	0.54	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	00
Modulation response	E2.5	3.0	R	√3 √3	1	1	1.73	1.73	∞
Readout Electronics	E.2.6	0.021	N	1	1	1	0.021	0.021	8
Response Time	E.2.7	0.021	R	√3	1_ 1_	1	0.021	0.021	∞
Integration Time	E.2.8	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
RF ambient conditions-Noise	E.6.1	3.0	R		1	10	1.73	1.73	
RF ambient		3.0	K	√3			1.73	1.73	∞
conditions-reflections	E.6.1	3.0	R	√3	1	1	1.73	1.73	00
Probe positioner mechanical colerance	E.6.2	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Probe positioning with respect o phantom shell	E.6.3	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	œ
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	1	1	1.33	1.33	8
Test sample Related									3)
Test sample positioning	E.4.2	2.6	N	1 🔊	1	1	2.6	2.6	∞
Device holder uncertainty	E.4.1	3	N	1	1	1	3	3	∞
Output power variation—SAR drift measurement	E.2.9	5	R	$\sqrt{3}$	1	1	2.89	2.89	×
SAR scaling	E.6.5	5	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Phantom and tissue parameter	s		4	0				a.C1	
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	$\sqrt{3}$	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	8
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	М
Liquid permittivity measurement	E.3.3	_© 5	N	1	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	00
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty		~GC	RSS		0		9.796	9.597	
Expanded Uncertainty (95% Confidence interval)	®		K=2		6,0		19.593	19.194	



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System		FIMO Unce uncertainty				n / 10 gram.			
a	b	С	d	e f(d,k)	f	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (±%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System		10		G	8				O
Probe calibration	E.2.1	5.831	N	1	1	1	5.831	5.831	∞
Axial Isotropy	E.2.2	0.685	R	$\sqrt{3}$	1	1	0.395	0.395	∞
Hemispherical Isotropy	E.2.2	1.14	R	√3	0	0	0.000	0.000	∞
Boundary effect	E.2.3	1	R	$\sqrt{3}$	1	1	0.577	0.577	∞
Linearity	E.2.4	0.935	R	$\sqrt{3}$	1	1	0.540	0.540	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Modulation response	E2.5	3.0	R	√3	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.021	N	1	1	1	0.021	0.021	∞
Response Time	E.2.7	0.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.4	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	1	1 💿	1.73	1.73	× ×
Probe positioner mechanical tolerance	E.6.2	1.4	R	√3	1	10	0.81	0.81	∞
Probe positioning with respect to phantom shell	E.6.3	1.4	R	√3	_® 1	1	0.81	0.81	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	1	1	1.33	1.33	∞
System check source (dipole)			8				0		
Deviation of experimental dipole from numerical dipole	E.6.4	5.0	N	1	1	1	5.00	5.00	∞
Input power and SAR drift measurement	8,6.6.4	5.0	R	√3	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and tissue parameters		~ GU							
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4.0	R	√3	1	1 8	2.31	2.31	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	8
Liquid conductivity measurement	E.3.3	4.0	N	1	0.78	0.71	3.12	2.84	М
Liquid permittivity measurement	E.3.3	5.0	N	1	0.23	0.26	1.15	1.30	М
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS	0		1	9.724	9.524	
Expanded Uncertainty (95% Confidence interval)	-C		K=2			N.C	19.449	19.048	



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(8)	stem Check u			veraged ov e		4	® h	i	
a	b	c Tol	d Prob.	f(d,k)	f	g	cxf/e 1g Ui	cxg/e 10g Ui	k
Uncertainty Component	Sec.	(+- %)	Dist.	Div.	Ci (1g)	Ci (10g)	(+-%)	(+-%)	Vi
Measurement System						0			W
Probe calibration drift	E.2.1.3	5	N	1	1	1	5	5	∞
Axial Isotropy	E.2.2	0.685	R	$\sqrt{3}$	0	0	0	0	∞
Hemispherical Isotropy	E.2.2	1.14	R	$\sqrt{3}$	0	0	0	0	∞
Boundary effect	E.2.3	1	R	$\sqrt{3}$	0	0	0	0	∞
Linearity	E.2.4	0.935	R	$\sqrt{3}$	0	0	0 @	0	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Modulation response	E2.5	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.021	N	1	0	0	0.00	0.00	∞
Response Time	E.2.7	0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.4	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions reflections	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Probe positioner mechanical tolerance	E.6.2	1.4	R	√3	1	1	0.81	0.81	∞
Probe positioning with respect to phantom shell	E.6.3	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	√3	0	0	0.00	0.00	∞
System check source (dipole)	1	<u> </u>				9	a.C		3)
Deviation of experimental dipoles	E.6.4	2	N	1 9	1	1	2	2	∞
Input power and SAR drift measurement	8,6.6.4	5	R	√3	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and tissue parameters	s			(8)				a.C	
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	√3	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	∞
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	М
Liquid permittivity measurement	E.3.3	© 5	N	1	0.23	0.26	1.15	1.30	М
iquid conductivity—temperature uncertainty	E.3.4	2.5	R	√3	0.78	0.71	1.13	1.02	000
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	√3	0.23	0.26	0.33	0.38	8
Combined Standard Uncertainty	70	~GC	RSS	G	00		7.462	7.199	C
Expanded Uncertainty (95% Confidence interval)	©		K=2		GC	-6	14.925	14.398	





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12. POWER MEASUREMENT

Frequency (MHz)	Channel	ERP (dBm)
462.5625-462.7125MHz(2W)		
462.5625	1	32.63
462.6375	4	32.67
462.7125	7	32.59
467.5625-467.7125MHz (0.5V	V)	
467.5625	8	26.88
467.6375	11	26.93
467.7125	14	26.90
462.5500-462.7250MHz(2W)		
462.5500	15	32.68
462.6500	19	32.71
462.7250	22	32.65



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13. TEST RESULTS

13.1. SAR Test Results Summary

13.1.1. Test position and configuration

Face up SAR was performed with the device configured in the positions according to KDB 643646 and Body SAR was performed with the device configured with all accessories close to the Flat Phantom.

13.1.2. Operation Mode

- Set the EUT to maximum output power level and transmit on lower, middle and top channel with 100% duty cycle individually during SAR measurement.
- Per KDB 643646 D01, Passive body-worn and audio accessories generally do not apply to the head SAR of PTT radios. Head SAR is measured with the front surface of the radio positioned at 2.5 cm parallel to a flat phantom.
- Per KDB 643646 D01, Body SAR is measured with the radio placed in a body-worn accessory, positioned against a flat phantom, representative of the normal operating conditions expected by users and typically with a standard default audio accessory supplied with the radio.

When testing antennas with the default battery: the same test measurement with head part.

• The EUT only contains the Testing antenna, Standard battery and default body-worn accessory specified by customer. The earphone is only for testing





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13.1.3. Antenna Location: (back view)







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13.1.4. SAR Test Results Summary

10.11.4. OAR TOST		aiiiiiai y							
SAR MEASUREME	NT								
Depth of Liquid (cm):>15			Relative	Humidity	(%): 49.7			
Product: TWO WAY	RADIO								
Test Mode: Hold to	Face with 2.	5 cm sepa	aration & I	oody back to	uch with cli	р			
Position	Freq. (MHz)	Separa tion (KHz)	Power Drift (<±5%)	SAR 1g with 100% duty Cycle (W/kg)	SAR 1g with 50% duty cycle (W/Kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/Kg)	Limit W/kg
462.5625-462.7125	MHz(2W)				- G	(6)			
Face Up	462.6375		-0.12	1.155	0.5775	33.01	32.67	0.625	1.6
Back Touch +Belt Clip + headset	462.5625	60	-0.09	1.901	0.9505	33.01	32.63	1.037	1.6
Back Touch +Belt Clip + headset	462.6375	12.5	0.32	2.335	1.1675	33.01	32.67	1.263	1.6
Back Touch +Belt Clip + headset	462.7125	-6	-0.26	1.827	0.9135	33.01	32.59	1.006	1.6
467.5625-467.7125	MHz(0.5W)		60		8				
Face Up	467.6375		-0.18	0.608	0.304	26.99	26.93	0.308	1.6
Back Touch +Belt Clip + headset	467.5625		-0.06	1.717	0.8585	26.99	26.88	0.881	1.6
Back Touch +Belt Clip + headset	467.6375	12.5	-0.27	2.007	1.0035	26.99	26.93	1.017	1.6
Back Touch +Belt Clip + headset	467.7125		0.10	1.718	0.859	26.99	26.90	0.877	1.6
462.5500-462.7250	MHz(2W)	a.C		(8)			G		
Face Up	462.6500		0.21	0.912	0.456	33.01	32.71	0.489	1.6
Back Touch +Belt Clip + headset	462.5500	8	-0.05	1.912	0.956	33.01	32.68	1.031	1.6
Back Touch +Belt Clip + headset	462.6500	12.5	-0.27	2.150	1.075	33.01	32.71	1.152	1.6
Back Touch +Belt Clip + headset	462.7250		0.13	1.976	0.988	33.01	32.65	1.073	1.6

Note:

- During the test, EUT power is 2W&0.5W with 100% duty cycle;
 There is just default battery and antenna in this project;





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Repeated SAR

Product: TWO WAY RADIO

Test Mode: Hold to Face with 2.5 cm separation & body back touch with clip

rest mode. Floid to Face with 2.0 off separation a body back todain with slip								
Position	Frequenc y(MHz)	Separa tion (KHz)	Power Drift (<±5%)	Once SAR 1g with 100% duty cycle (W/kg)	Once SAR 1g with 50% duty cycle (W/Kg)	Twice SAR 1g with 100% duty cycle (W/kg)	Twice SAR 1g with 50% duty cycle (W/kg)	Limit W/kg
Back Touch +Belt Clip + headset	462.6375	12.5	0.21	2.295		- ·	-30-	1.6
Back Touch +Belt Clip + headset	467.6375	12.5	-0.05	1.766	-,0-		-	1.6
Back Touch +Belt Clip + headset	467.6500	12.5	-0.21	1.981	\	- 5) - C	1.6





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APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab
System Check Head 450MHz
Test date: May 05,2020

DUT: Dipole 450 MHz Type: SID 450

Communication System: CW; Communication System Band: D450 (450.0 MHz); Duty Cycle: 1:1; Conv.F=1.42 Frequency: 450MHz; Medium parameters used: f = 450MHz; $\sigma = 0.85$ mho/m; $\epsilon = 42.52$; $\rho = 1000$ kg/m³;

Phantom Type: Flat Section; Input Power=18dBm

Ambient temperature (°C): 21.1, Liquid temperature (°C): 20.8

SATIMO Configuration:

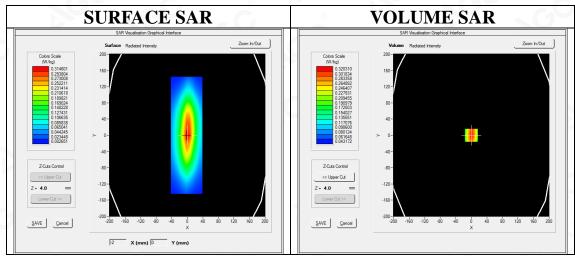
Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

• Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: SAM twin phantom

Measurement SW: OpenSAR V4_02_35

Configuration/System Check CW 450 MHz Head/Area Scan: Measurement grid: dx=8mm,dy=8mm Configuration/System Check CW 450 MHz Head /Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm,

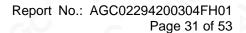


Maximum location: X=0.00, Y=0.00 SAR Peak: 0.44 W/kg

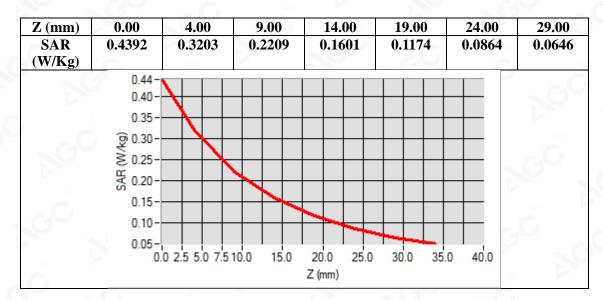
SAR 10g (W/Kg)	0.205139		
SAR 1g (W/Kg)	0.306760		

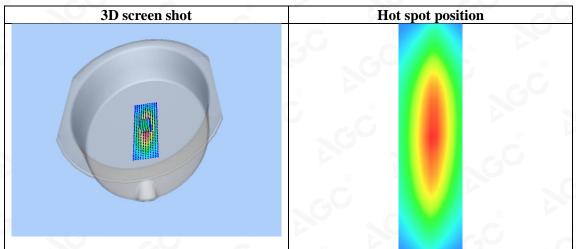


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Date: May 05,2020

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APPENDIX B. SAR MEASUREMENT DATA

462.5625-462.7125MHz(2W)
Test Laboratory: AGC Lab
450 Mid-face up 2.5cm (12.5 KHz)
DUT: TWO WAY RADIO; Type: F17

Communication System: 450; Communication System Band: CW 450 MHz;; Duty Cycle: 1:1; Conv.F=1.42

Frequency: 462.6375 MHz; Medium parameters used: f = 450MHz; $\sigma = 0.87$ mho/m; $\epsilon r = 41.89$; $\rho = 1000$ kg/m³;

Phantom Type: Flat Section

Ambient temperature (°C): 21.1, Liquid temperature (°C): 20.8

SATIMO Configuration:

Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

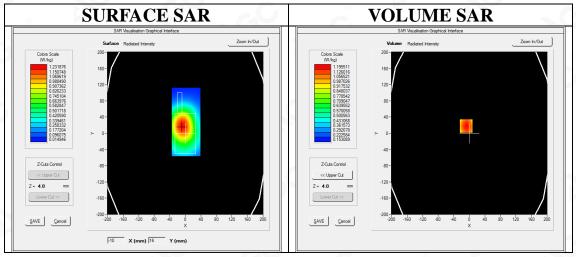
• Sensor-Surface: 4mm (Mechanical Surface Detection)

· Phantom: SAM twin phantom

Measurement SW: OpenSAR V4_02_35

Configuration/450 for Mid-Face up/Area Scan: Measurement grid: dx=8mm, dy=8mm Configuration/450 for Mid-Face up/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm 5x5x7,dx=8mm dy=8mm dz=5mm	
Zoom Scan		
Phantom	ELLI	
Device Position	Face up 2.5 cm separation to Phantom	
Band	450	
Channels	Middle	
Signal	Crest factor: 1	

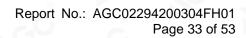


Maximum location: X=-8.00, Y=18.00 SAR Peak: 1.54 W/kg

STATE TOWN THE TOTAL THE				
SAR 10g (W/Kg)	0.816730			
SAR 1g (W/Kg)	1.155097			

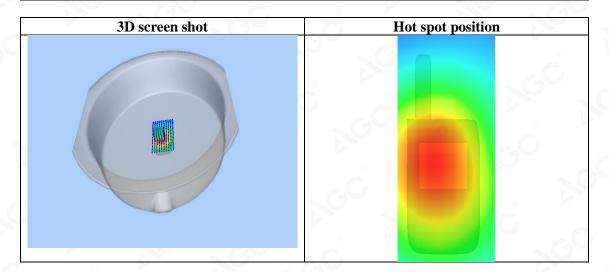


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Z (mm)	0.00	4.00	9.00	14.00	19.00	24.00	29.00
SAR (W/Kg)	1.5401	1.1955	0.8734	0.6428	0.4756	0.3533	0.2623
	1.5- 1.4						
	1.2	\longrightarrow					
	9 1.0	+N				+	
	SAR (%	+++	lack				
	o.6-						
	0.4-						
	0.2-	2.5 5.0 7.5 1	0.0 15.0	20.0 25.0	30.0 35.	0 40.0	
				Z (mm)			







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Test Laboratory: AGC Lab

Date: May 05,2020

450 Mid -Body -Touch (12.5 KHz) DUT: TWO WAY RADIO; Type: F17

Communication System: 450; Communication System Band: CW 450 MHz;; Duty Cycle: 1:1; Conv.F=1.42 Frequency: 462.6375 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.87$ mho/m; $\epsilon r = 41.89$; $\rho = 1000$ kg/m;

Phantom Type: Flat Section

Ambient temperature ($^{\circ}$): 21.1, Liquid temperature ($^{\circ}$): 20.8

SATIMO Configuration:

Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

• Sensor-Surface: 4mm (Mechanical Surface Detection)

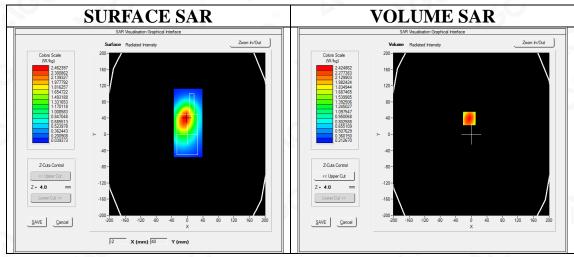
· Phantom: SAM twin phantom

• Measurement SW: OpenSAR V4 02 35

Configuration/450 for Mid-Body Back /Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/450 for Mid-Body Back /Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm		
Phantom	ELLI		
Device Position	Back close to Phantom with Accessories		
Band	450		
Channels	Middle		
Signal	Crest factor: 1		

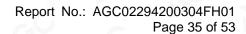


Maximum location: X=-5.00, Y=39.00 SAR Peak: 3.23 W/kg

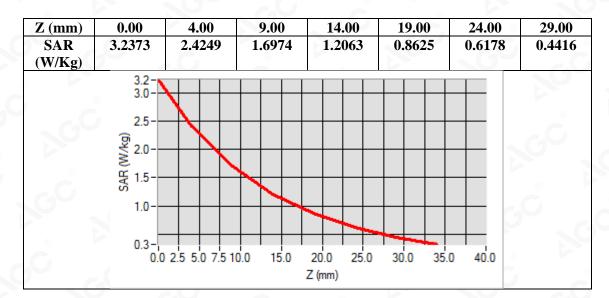
SAR 10g (W/Kg)	1.575066		
SAR 1g (W/Kg)	2.334671		

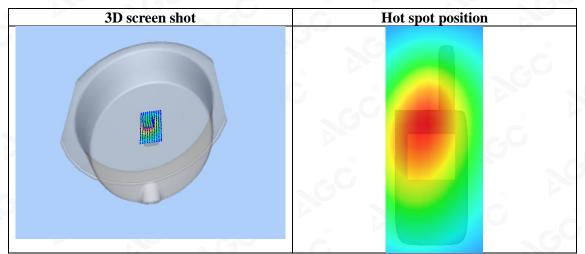


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467.5625-467.7125MHz(0.5W)
Test Laboratory: AGC Lab
450 Mid- face up 2.5cm (12.5 KHz)
DUT: TWO WAY RADIO; Type: F17

Communication System: 450; Communication System Band: CW 450 MHz;; Duty Cycle: 1:1; Conv.F=1.42

Frequency: 467.6375 MHz; Medium parameters used: f = 450MHz; $\sigma = 0.88$ mho/m; $\epsilon r = 41.65$; $\rho = 1000$ kg/m³;

Phantom Type: Flat Section

Ambient temperature ($^{\circ}$ C): 21.1, Liquid temperature ($^{\circ}$ C): 20.8

SATIMO Configuration:

• Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

• Sensor-Surface: 4mm (Mechanical Surface Detection)

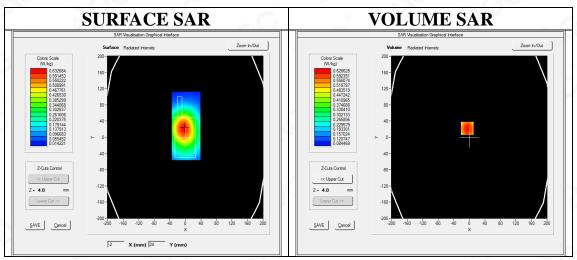
• Phantom: SAM twin phantom

• Measurement SW: OpenSAR V4 02 35

Configuration/450 for Mid-Face up/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/450 for Mid-Face up/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Phantom	ELLI
Device Position	Face up 2.5 cm separation to Phantom
Band	450
Channels	Middle
Signal	Crest factor: 1



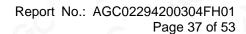
Maximum location: X=-5.00, Y=22.00

SAR Peak: 0.81 W/kg

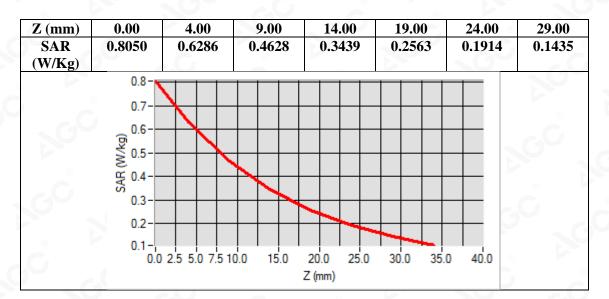
SAR 10g (W/Kg)	0.433153		
SAR 1g (W/Kg)	0.607883		

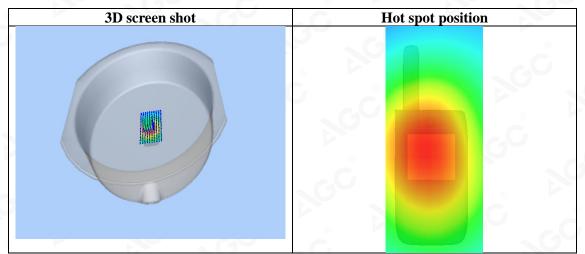


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Test Laboratory: AGC Lab 450 Mid -Body -Touch (12.5 KHz) DUT: TWO WAY RADIO; Type: F17

Communication System: 450; Communication System Band: CW 450 MHz;; Duty Cycle: 1:1; Conv.F=1.42 Frequency: 467.6375 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.88$ mho/m; $\epsilon r = 41.65$; $\rho = 1000$ kg/m;

Phantom Type: Flat Section

Ambient temperature ($^{\circ}$): 21.1, Liquid temperature ($^{\circ}$): 20.8

SATIMO Configuration:

• Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

• Sensor-Surface: 4mm (Mechanical Surface Detection)

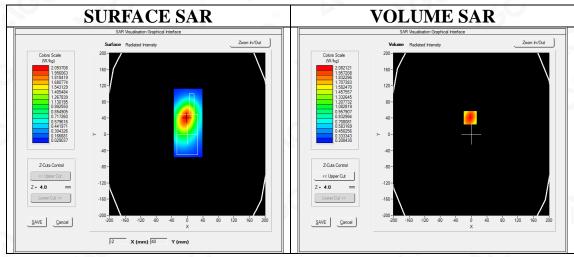
· Phantom: SAM twin phantom

• Measurement SW: OpenSAR V4 02 35

Configuration/450 for Mid-Body Back /Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/450 for Mid-Body Back /Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm		
Phantom	ELLI		
Device Position	Back close to Phantom with Accessories		
Band	450		
Channels	Middle		
Signal	Crest factor: 1		



Maximum location: X=-3.00, Y=41.00 SAR Peak: 2.76 W/kg

SAR 10g (W/Kg)	1.366164
SAR 1g (W/Kg)	2.007183

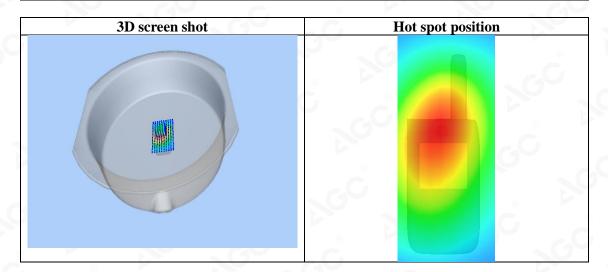


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Z (mm)	0.00	4.00	9.00	14.00	19.00	24.00	29.00
SAR (W/Kg)	2.7566	2.0821	1.4722	1.0562	0.7633	0.5534	0.4040
	2.8- 2.5-						10
	SAR (W./kg)						
	≥ 1.5 ⊊						
	1.0-		+N				
	0.5						
	0.3-¦ 0.0	2.5 5.0 7.5 1	0.0 15.0	20.0 25.0	30.0 35.	0 40.0	
			7	Z (mm)		5	







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462.5500-462.7250MHz(2W)
Test Laboratory: AGC Lab

450 Mid- face up 2.5cm (12.5 KHz) DUT: TWO WAY RADIO; Type: F17

Communication System: 450; Communication System Band: CW 450 MHz;; Duty Cycle: 1:1; Conv.F=1.42

Frequency: 462.6500 MHz; Medium parameters used: f = 450MHz; $\sigma = 0.87$ mho/m; $\epsilon r = 41.89$; $\rho = 1000$ kg/m³;

Phantom Type: Flat Section

Ambient temperature (°C): 21.1, Liquid temperature (°C): 20.8

SATIMO Configuration:

• Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

• Sensor-Surface: 4mm (Mechanical Surface Detection)

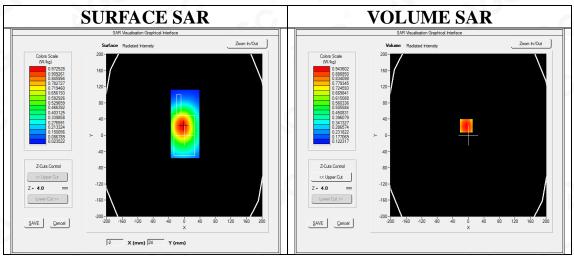
• Phantom: SAM twin phantom

• Measurement SW: OpenSAR V4 02 35

Configuration/450 for Mid-Face up/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/450 for Mid-Face up/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm		
Phantom	ELLI		
Device Position	Face up 2.5 cm separation to Phantor		
Band	450		
Channels	Middle		
Signal	Crest factor: 1		



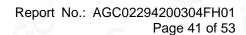
Maximum location: X=-5.00, Y=23.00

SAR Peak: 1.21 W/kg

SAR 10g (W/Kg)	0.649417	
SAR 1g (W/Kg)	0.912391	

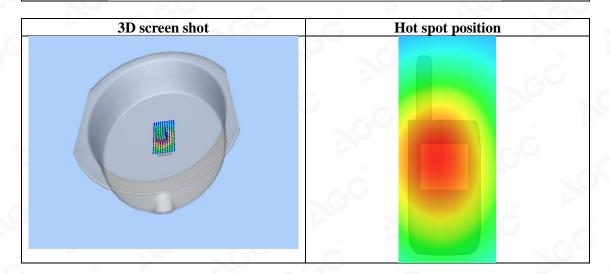


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0.00 4.00 9.00 14.00 19.00 24.00 29.00 Z (mm) 1.2107 0.9436 0.5122 0.3807 0.2825 0.2099 SAR 0.6928 (W/Kg) 1.2-1.0 SAR (W/kg) 0.4 0.2 - 0.0 2.5 5.0 7.5 10.0 15.0 20.0 25.0 30.0 35.0 Z (mm)







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Test Laboratory: AGC Lab Date: May 05,2020

450 Mid -Body -Touch (12.5 KHz) DUT: TWO WAY RADIO; Type: F17

Communication System: 450; Communication System Band: CW 450 MHz;; Duty Cycle: 1:1; Conv.F=1.42 Frequency: 462.6500 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.87$ mho/m; $\epsilon r = 41.89$; $\rho = 1000$ kg/m;

Phantom Type: Flat Section

Ambient temperature ($^{\circ}$): 21.1, Liquid temperature ($^{\circ}$): 20.8

SATIMO Configuration:

Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

• Sensor-Surface: 4mm (Mechanical Surface Detection)

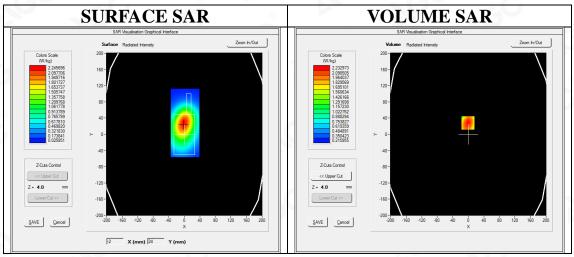
· Phantom: SAM twin phantom

• Measurement SW: OpenSAR V4 02_35

Configuration/450 for Mid-Body Back /Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/450 for Mid-Body Back /Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm		
Phantom	ELLI		
Device Position	Back close to Phantom with Accessories		
Band	450		
Channels	Middle		
Signal	Crest factor: 1		

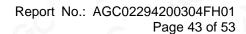


Maximum location: X=-1.00, Y=28.00 SAR Peak: 2.96 W/kg

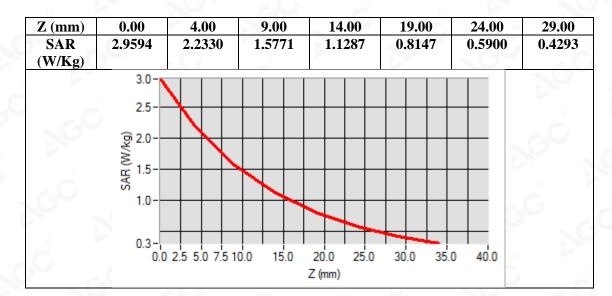
SAR 10g (W/Kg)	1.463429
SAR 1g (W/Kg)	2.149558

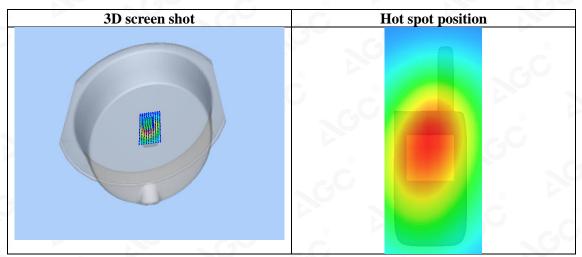


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Repeated SAR

Test Laboratory: AGC Lab Date: May 05,2020

450 Mid -Body -Touch (12.5 KHz) DUT: TWO WAY RADIO; Type: F17

Communication System: 450; Communication System Band: CW 450 MHz;; Duty Cycle: 1:1; Conv.F=1.42 Frequency: 462.6375 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.87$ mho/m; $\epsilon r = 41.89$; $\rho = 1000$ kg/m;

Phantom Type: Flat Section

Ambient temperature ($^{\circ}$ C): 21.1, Liquid temperature ($^{\circ}$ C): 20.8

SATIMO Configuration:

Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

• Sensor-Surface: 4mm (Mechanical Surface Detection)

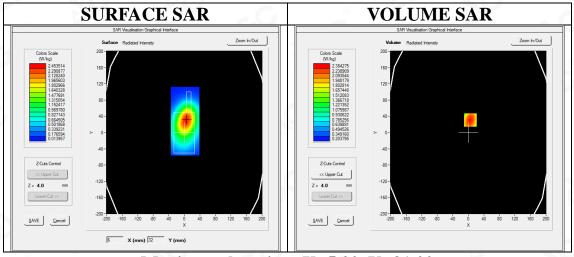
· Phantom: SAM twin phantom

Measurement SW: OpenSAR V4_02_35

Configuration/450 for Mid-Body Back /Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/450 for Mid-Body Back /Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm		
Phantom	ELLI		
Device Position	Back close to Phantom with Accessories		
Band	450		
Channels	Middle		
Signal	Crest factor: 1		



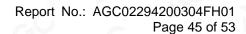
Maximum location: X=5.00, Y=31.00

SAR Peak: 3.18 W/kg

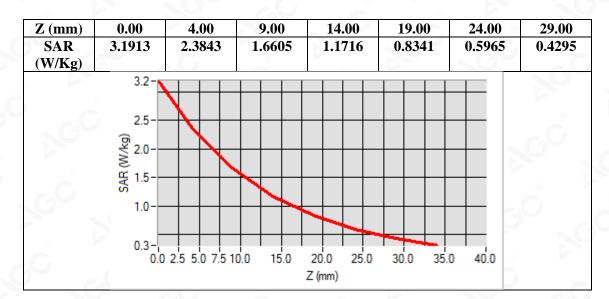
SAR 10g (W/Kg)	1.541265		
SAR 1g (W/Kg)	2.294692		

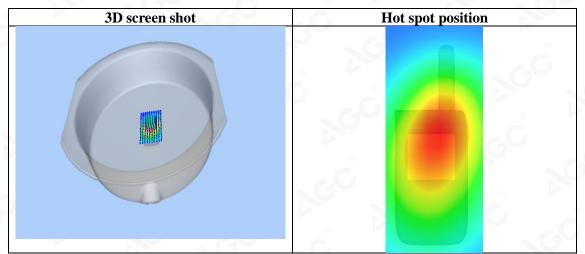


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Test Laboratory: AGC Lab Date: May 05,2020

450 Mid -Body -Touch (12.5 KHz) DUT: TWO WAY RADIO; Type: F17

Communication System: 450; Communication System Band: CW 450 MHz;; Duty Cycle: 1:1; Conv.F=1.42 Frequency: 467.6375 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.88$ mho/m; $\epsilon r = 41.65$; $\rho = 1000$ kg/m;

Phantom Type: Flat Section

Ambient temperature ($^{\circ}$): 21.1, Liquid temperature ($^{\circ}$): 20.8

SATIMO Configuration:

Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

• Sensor-Surface: 4mm (Mechanical Surface Detection)

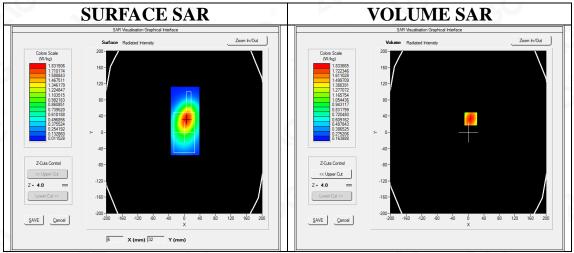
· Phantom: SAM twin phantom

• Measurement SW: OpenSAR V4 02 35

Configuration/450 for Mid-Body Back /Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/450 for Mid-Body Back /Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm		
Phantom	ELLI		
Device Position	Back close to Phantom with Accessories		
Band	450		
Channels	Middle		
Signal	Crest factor: 1		

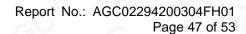


Maximum location: X=6.00, Y=33.00 SAR Peak: 2.45 W/kg

1.187896
1.765834

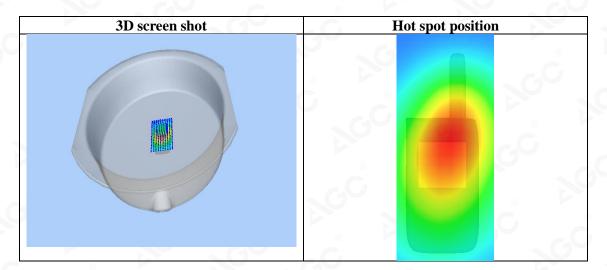


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0.00 4.00 9.00 14.00 19.00 24.00 29.00 Z (mm) 2.4542 1.8337 1.2802 0.9100 0.4690 0.3382 SAR 0.6507 (W/Kg)2.5-2.0 SAR (W/kg) 1.0-0.5-0.2 - 0.0 2.5 5.0 7.5 10.0 20.0 25.0 30.0 35.0 Z (mm)







Date: May 05,2020

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Test Laboratory: AGC Lab 450 Mid -Body –Touch (12.5 KHz)

DUT: TWO WAY RADIO; Type: F17

Communication System: 450; Communication System Band: CW 450 MHz;; Duty Cycle: 1:1; Conv.F=1.42 Frequency: 462.6500 MHz; Medium parameters used: f = 450 MHz; $\sigma = 0.87$ mho/m; $\epsilon r = 41.89$; $\rho = 1000$ kg/m;

Phantom Type: Flat Section

Ambient temperature ($^{\circ}$): 21.1, Liquid temperature ($^{\circ}$): 20.8

SATIMO Configuration:

Probe: SSE2; Calibrated: Jun. 04,2019; Serial No.: SN 41/18 EPGO334

• Sensor-Surface: 4mm (Mechanical Surface Detection)

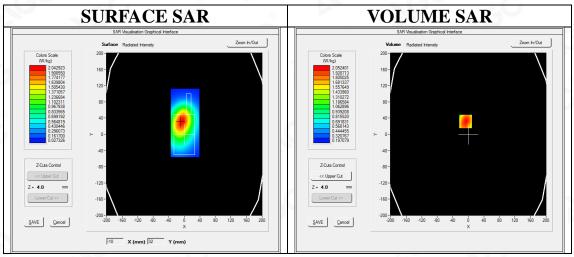
· Phantom: SAM twin phantom

• Measurement SW: OpenSAR V4 02_35

Configuration/450 for Mid-Body Back /Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/450 for Mid-Body Back /Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm		
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm		
Phantom	ELLI		
Device Position	Back close to Phantom with Accessories		
Band	450		
Channels	Middle		
Signal	Crest factor: 1		

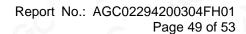


Maximum location: X=-7.00, Y=32.00 SAR Peak: 2.73 W/kg

SAR 10g (W/Kg)	1.358621
SAR 1g (W/Kg)	1.981365

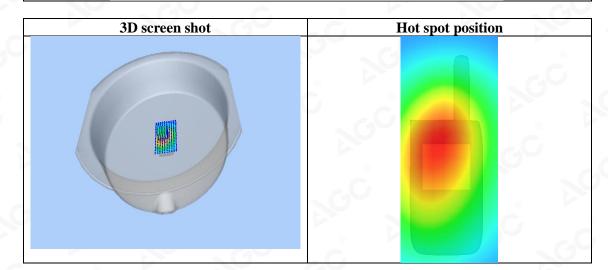


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0.00 4.00 9.00 14.00 19.00 24.00 29.00 Z (mm) 2.7145 2.0524 1.0419 0.7518 0.5453 0.3977 SAR 1.4518 (W/Kg)2.7-2.5-2.0· 1.5· 1.0· 1.0-0.5-0.3 - 0.0 2.5 5.0 7.5 10.0 20.0 30.0 35.0 25.0 Z (mm)







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APPENDIX C. TEST SETUP PHOTOGRAPHS

Face Up with 2.5 cm Separation Distance.



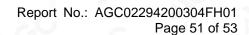
Body Back Touch with all accessories



The thickness of EUT is 2.4 cm



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Note: The headset is just for testing. This tested and electrically similar headsets may be used.

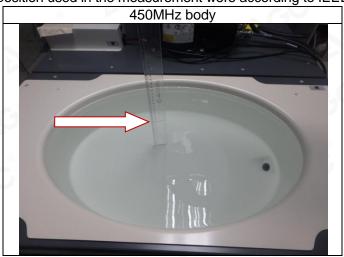




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DEPTH OF THE LIQUID IN THE PHANTOM—ZOOM IN

Note: The position used in the measurement were according to IEEE 1528-2013





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APPENDIX D. CALIBRATION DATA

Refer to Attached files.



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