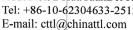
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SGS



Certificate No: Z21-60450

CALIBRATION CERTIFICATE

Object

EX3DV4 - SN: 3982

Calibration Procedure(s)

Client

FF-Z11-004-02

Calibration Procedures for Dosimetric E-field Probes

Calibration date:

December 29, 2021

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards		ID# Cal Date(Calibrated by, Certificate N		o.) Scheduled Calibration	
Power Meter NRP2		101919	15-Jun-21(CTTL, No.J21X04466)	Jun-22	
Power sensor NRP-Z91		101547	15-Jun-21(CTTL, No.J21X04466)	Jun-22	
Power sensor NRP-Z91		101548	15-Jun-21(CTTL, No.J21X04466)	Jun-22	
Reference 10dBAttenuator		18N50W-10dB	10-Feb-20(CTTL, No.J20X00525)	Feb-22	
Reference 20dBAttenuator		18N50W-20dB	10-Feb-20(CTTL, No.J20X00526)	Feb-22	
Reference Probe EX3DV4		SN 3617	27-Jan-21(SPEAG, No.EX3-3617_Jan2	21) Jan-22	
DAE4		SN 1555	20-Aug-21(SPEAG, No.DAE4-1555_Aug21/2) Aug-22		
Secondary Standards ID #		ID#	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration	
SignalGenerator MG3700A 62010		6201052605	16-Jun-21(CTTL, No.J21X04467)	Jun-22	
Network Analyzer E5071C		MY46110673	21-Jan-21(CTTL, No.J20X00515)	Jan-22	
	Nar	ne	Function	Signature	
Calibrated by:	Yu	Zongying	SAR Test Engineer	and the	
Reviewed by:	Lin Hao		SAR Test Engineer	Mills	
Approved by: Qi Diany		Dianyuan	SAR Project Leader		
			Issued: Decen	nber 31, 2021	

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This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Glossary:

TSL tissue simulating liquid NORMx,y,z sensitivity in free space

sensitivity in TSL / NORMx, y, z

ConvF DCP

diode compression point

CF A,B,C,D

crest factor (1/duty_cycle) of the RF signal modulation dependent linearization parameters

Polarization Φ

Φ rotation around probe axis

Polarization θ

θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i

 θ =0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013

b) IEC 62209-1, "Measurement procedure for the assessment of Specific Absorption Rate (SAR) from hand-held and body-mounted devices used next to the ear (frequency range of 300 MHz to 6 GHz)", July 2016

c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010

d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

NORMx, y, z: Assessed for E-field polarization θ=0 (f≤900MHz in TEM-cell; f>1800MHz: waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E^2 -field uncertainty inside TSL (see below ConvF).

 $NORM(f)x, y, z = NORMx, y, z^*$ frequency_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the

frequency response is included in the stated uncertainty of ConvF.

DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.

PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.

Ax,y,z; Bx,y,z; Cx,y,z;VRx,y,z:A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.

ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f≤800MHz) and inside waveguide using analytical field distributions based on power measurements for f >800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which iate values, i.e., the uncertainties of NORMx,y,z do Spherical isotropy (3D deviation from isotropy): in

Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat

phantom exposed by a patch antenna.

Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

Connector Angle: The angle is assessed using the information gained by determining the NORMX (no uncertainty required).

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DASY/EASY - Parameters of Probe: EX3DV4 - SN:3982

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (<i>k</i> =2)
Norm(µV/(V/m)²) ^A	0.56	0.59	0.50	±10.0%
DCP(mV) ^B	101.9	103.8	103.4	

Modulation Calibration Parameters

UID	Communication		A	В	С	D	VR	Unc E
	System Name		dB	dBõV		dB	mV	(k=2)
0	CW	X	0.0	0.0	1.0	0.00	176.4	±2.1%
		Υ	0.0	0.0	1.0		179.9	
		Z	0.0	0.0	1.0		164.2	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

^B Numerical linearization parameter: uncertainty not required.

^A The uncertainties of Norm X, Y, Z do not affect the E²-field uncertainty inside TSL (see Page 4).

E Uncertainly is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.