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Report No.:LCS1509221225E

SAR TEST REPORT

For

Motic China Group Co., LTD 10.1 inch Quad core capacitive touch tablet Model No.:MGT101

Prepared for Address

Prepared by Address

Tel Fax Web Mail

Date of receipt of test sample Number of tested samples Serial number Date of Test Date of Report Motic China Group Co., LTD
Motic Building, Torch Hi-Tech Industrial Development Zone, Xiamen, P.R.C

Shenzhen LCS Compliance Testing Laboratory Ltd. 1/F., Xingyuan Industrial Park, Tongda Road, Bao'an Avenue, Bao'an District, Shenzhen, Guangdong, China (86)755-82591330 (86)755-82591332 www.LCS-cert.com webmaster@LCS-cert.com

September 26, 2015 1 Prototype September 26, 2015 - September 29, 2015 September 29, 2015

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Report No.:LCS1509221225E

Report Reference No	LCS1509221225E	
Date Of Issue: September 29, 2015		
Testing Laboratory Name: Shenzhen LCS Compliance Testing Laboratory Ltd.		
Address: 1/F., Xingyuan Industrial Park, Tongda Road, Bao'an Avenue, Bao'an District, Shenzhen, Guangdong, China		
esting Location/ Procedure	Full application of Harmonised standards ■ Partial application of Harmonised standards □ Other standard testing method □	
pplicant's Name:	Motic China Group Co., LTD	
Address	Motic Building, Torch Hi-Tech Industrial Development Zone Xiamen, P.R.C	
Cest Specification:	16 ³ 16 ³ 16 ³ 16 ³	
caled SAR Max. Values is	Body: 0.859 W/Kg (1g).	
'estStandard	ANSI/IEEE C95.1:2005/ANSI/IEEE C95.3 :2002 IEEE1528 :2003	
Sest Report Form No	LCSEMC-1.0	
'RF Originator	Shenzhen LCS Compliance Testing Laboratory Ltd.	
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This publication may be reproduct thenzhen LCS Compliance Testi f the material. Shenzhen LCS Co ot assume liability for damages ue to its placement and context. Cest Item Description Trade Mark	 ced in whole or in part for non-commercial purposes as long as the ng Laboratory Ltd. is acknowledged as copyright owner and source ompliance Testing Laboratory Ltd. takes noresponsibility for and wiresulting from the reader's interpretation of the reproduced material 10.1 inch Quad core capacitive touch tablet Motic MGT101 DC 3.7V by battery(6000mAh) Adapter parameters: Input: AC 100~240V, 50/60Hz 0.4A 	

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Report No.: LCS1509221225E

SAR -- TEST REPORT

Test Report No. : L	CS1509221225E	September 29, 2015 Date of issue	
63 °.63	165 65 163 6	3 500 500	
Type / Model	: MGT101	23	
EUT	: 10.1 inch Quad core capae	citive touch tablet	
Applicant	: Motic China Group Co.,	, LTD	
Address	: Motic Building, Torch Hi-Tech Industrial Development Zone, Xiamen, P.R.C		
Telephone	:/		
Fax	; 1 ²		
Manufacturer	: Shenzhen Huaruian Tec	chnology Co., Ltd	
Address		The Third Industrial Park, Gushu Shenzhen, Guangdong, China	
Telephone	:/	23 23	
Fax	:/		
Factory			
Address		The Third Industrial Park, Gushu, Shenzhen, Guangdong, China	
Telephone			
Fax			

Test Result

Positive

The test report merely corresponds to the test sample. It is not permitted to copy extracts of these test result without the written permission of the test laboratory.

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1.TEST STANDARDS AND TEST DESCRIPTION

1.1. Test Standards

The tests were performed according to following standards:

ANSI/IEEE C95.1: 2005:IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fileds,3 kHz to 300 GHz.

<u>ANSI/IEEE C95.3: 2002:</u>IEEE Recommended Practice for Measurements and Computations of Radio Frequency Electromagnetic Fields With Respect to Human Exposure to SuchFields,100 kHz—300 GHz.

<u>IEEE1528:2003:</u>Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate. <u>KDB447498 D01v05r02:General RF Exposure Guidance.</u>

KDB248227 D01 802.11 Wi-Fi SAR v02:SAR measure for 802.11 a/b/g.

KDB865664 D01v01r03:SAR measurement 100MHz to 6GHz.

KDB865664 D02v01r01:SAR Report.

KDB690783 D01v01r03:SAR lisitings on Grants.

KDB616217 D04v01r01: SAR for laptop and tablets v01r01

FCC Part 2:2012: frequency alloca-tions and radio treaty mat-ters; general rules and reg-ulations

1.2. Test Description

The EUT battery must be fully charged and checked periodically during the test to ascertain uniform power . And Test device is identical prototype.

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1.3. Product Description

Product Name:	10.1 inch Quad core capacitive touch tablet		
Trade Mark:	Motic		
Model/Type reference:	MGT101		
Listed Model(s):	MGT101		
Hardware Version	TX-A1006-RK3188 V1.0		
Software Version:	V1.0.0.2.KTU84Q.20150827.181751		
Power supply:	DC 3.7V by battery(6000mAh) Adapter parameters: Input: AC 100~240V, 50/60Hz 0.4A Output: DC 5V/2A		
WIFI			
Supported type:	802.11b/802.11g/802.11n		
Modulation:	802.11b: DSSS 802.11g/802.11n:OFDM		
Operation frequency:	802.11b/802.11g/802.11n(HT20):2412MHz~2462MHz;		
Channel number:	802.11b/802.11g/802.11n(HT20):11		
Channel separation:	5MHz		
Bluetooth			
Version:	V4.0		
Modulation:	GFSK		
Operation frequency:	2402MHz~2480MHz		
Channel number:	40		
Channel separation:	2MHz		

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1.4. Summary SAR Results

Table 1:Max. SAR Measured(1g)

Exposure Configuration	Technolohy Band	Highest Measured SAR 1g(W/Kg)	
Body-worn (Separation Distance 0mm)	WLAN2450	0.859	

The SAR values found for the Mobile Phone are below the maximum recommended levels of 1.6W/Kg as averaged over any 1g tissue accordintg to the ANSI C95.1-1999.

For body worn operation, this devices has been tested and meets FCC RF exposure guidelines when used with any accessory that conrtains no metal and which provides a minimum separation distance of 0mm between this devices and the body of the user. User of other accessories may not ensure compliance with FCC RF exposure guidelines.

In the front of EUT has two speakers, just used to public.

The EUT battery must be fully charged and checked periodically during the test to ascertain iniform power output

1.5. EUT operation mode

The EUT has been tested under typical operating condition and The Transmitter was operated in the normal operating mode. The TX frequency was fixed which was for the purpose of the measurements.

1.6. EUT configuration

The following peripheral devices and interface cables were connected during the measurement:

- - supplied by the manufacturer
- Solution supplied by the lab

				6.22	
0	Power Cable	Length (m) :	1 5		
3	5 PS	Shield :	1	Land	Bee
G	Boss	Detachable :	1	Bass	100
0	O Multimeter	Manufacturer :	1	NO	1,35
30	S Bas	Model No. :	1	631	N.C.

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2.TEST ENVIRONMENT

2.1. Test Facility

The test facility is recognized, certified, or accredited by the following organizations: Site Description EMC Lab. : CNAS Registration Number is I 4595

CNAS Registration Number. is L4595.
FCC Registration Number. is 899208.
Industry Canada Registration Number. is 9642A-1.
VCCI Registration Number. is C-4260 and R-3804.
ESMD Registration Number. is ARCB0108.
UL Registration Number. is 100571-492.
TUV SUD Registration Number. is SCN1081.
TUV RH Registration Number. is UA 50296516-001

2.2. Environmental conditions

During the measurement the environmental conditions were within the listed ranges:

Temperature:	18-25 ° C		
19 19 190 Los	1.50 1.60 1		
Humidity:	40-65 %		
2 B B B B B	Burge Bland		
Atmospheric pressure:	950-1050mbar		
	13 0		

2.3. SAR Limits

EXPOSURE LIMITS	FCC Limit (1g Tissue) SAR (W/kg) (General Population / Uncontrolled Exposure Environment)		
Spatial Average(averaged over the whole body)	0.08		
Spatial Peak(averaged over any 1 g of tissue)	1.6		
Spatial Peak(hands/wrists/ feet/anklesaveraged over 10 g)	4.0		

Population/Uncontrolled Environments are defined as locations where there is the exposure of individual who have no knowledge or control of their exposure.

Occupational/Controlled Environments are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure (i.e. as a result of employment or occupation).

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2.4. Equipments Used during the Test

			- DU 02		0.1652
	Manufact			Calib	ration
Test Equipment	urer Type/Model		Serial Number	Calibration Date	Calibration Due
PC	Lenovo	G5005	MY42081102	N/A	N/A
Signal Generator	Angilent	E4438C	MY42081396	09/25/2015	09/24/2016
Multimeter	Keithley	MiltiMeter 2000	4059164	10/01/2014	09/30/2015
S-parameter Network Analyzer	Agilent	8753ES	US38432944	09/25/2015	09/24/2016
Power Meter	R&S	NRVS	100444	06/18/2015	06/17/2016
Power Meter	R&S	NRVS	100469	06/18/2015	06/17/2016
Power Sensor	R&S	NRV-Z51	100458	06/18/2015	06/17/2016
Power Sensor	R&S	NRV-Z32	100657	06/18/2015	06/17/2016
E-Field PROBE	SATIMO	SSE5	SN 17/14 EP220	10/01/2014	09/30/2015
E-Field PROBE	SATIMO	SSE5	SN 17/14 EP221	09/01/2015	08/31/2016
DIPOLE 2450	SATIMO	SID 2450	SN 07/14 DIP 2G450-306	10/01/2014	09/30/2015
COMOSAR OPEN Coaxial Probe	SATIMO	OCPG 68	SN 40/14 OCPG68	10/01/2014	09/30/2015
Communication Antenna	SATIMO	ANTA57	SN 39/14 ANTA57	10/01/2014	09/30/2015
Mobile Phone POSITIONING DEVICE	SATIMO	MSH98	SN 40/14 MSH98	N/A	N/A
DUMMY PROBE	SATIMO	DP60	SN 03/14 DP60	N/A	N/A
SAM PHANTOM	SATIMO	SAM117	SN 40/14 SAM117	N/A	N/A
Simulated Tissue 2450 MHz Body and Head	SATIMO	SAM-24-H	SN 21/14 HLJ445	Each Time	N/A
PHANTOM TABLE	SATIMO	TABP98	SN 40/14 TABP98	N/A	N/A
6 AXIS ROBOT	KUKA	KR6-R900	501217	N/A	N/A
High Power Solid State Amplifier (80MHz~1000MHz)	Instrumen ts for Industry	CMC150	M631-0627	09/25/2015	09/24/2016
Medium Power Solid State Amplifier (0.8~4.2GHz)	Instrumen ts for Industry	S41-25	M629-0539	09/25/2015	09/24/2016
Wave Tube Amplifier 48 GHz at 20Watt	Hughes Aircraft Company	1277H02F00 0	102	09/25/2015	09/24/2016

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3.SAR MEASUREMENTS SYSTEM CONFIGURATION

3.1. SARMeasurement Set-up

The OPENSAR system for performing compliance tests consist of the following items:

A standard high precision 6-axis robot (KUKA) with controller and software.

KUKA Control Panel (KCP)

A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with a Video Positioning System(VPS).

The stress sensor is composed with mechanical and electronic when the electronic part detects a change on the electro-mechanical switch, It sends an "Emergency signal" to the robot controller that to stop robot's moves

A computer operating Windows XP.

OPENSAR software

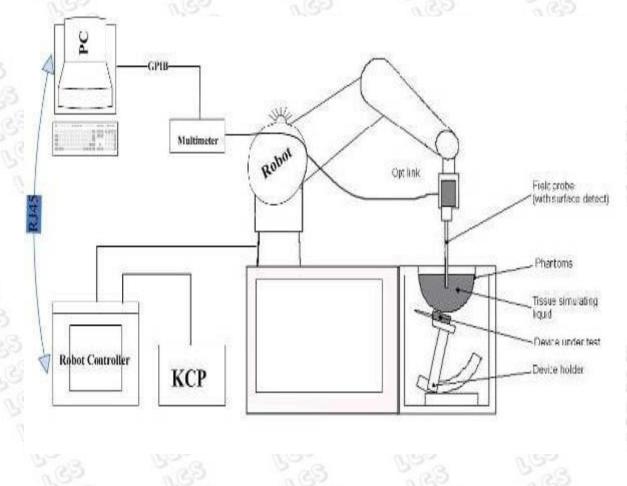
Remote control with teaches pendant and additional circuitry for robot safety such as warning lamps, etc.

The SAM phantom enabling testing left-hand right-hand and body usage.

The Position device for handheld EUT

Tissue simulating liquid mixed according to the given recipes .

System validation dipoles to validate the proper functioning of the system.



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3.2. OPENSAR E-field Probe System

The SAR measurements were conducted with the dosimetric probe EP220 (manufactured by SATIMO), designed in the classical triangular configuration and optimized for dosimetric evaluation.

Probe Specification

ConstructionSymmetrical design with triangular core Interleaved sensors Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)

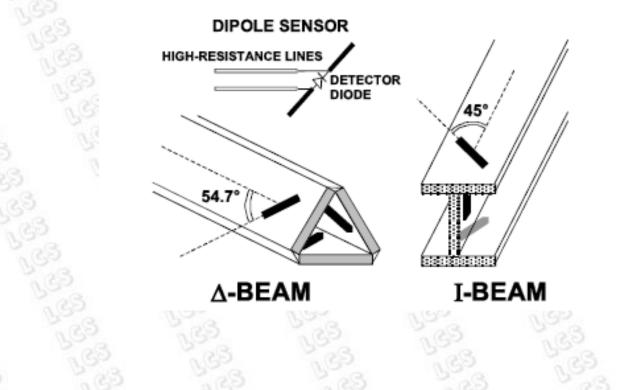
CalibrationISO/IEC 17025 calibration service available.

	Frequency	700 MHz to 3 GHz; Linearity:0.25dB(700 MHz to 3GHz)
	Directivity	0.25 dB in HSL (rotation around probe axis) 0.5 dB in tissue material (rotation normal to probe axis)
5	Dynamic Range	0.01W/kg to > 100 W/kg; Linearity: 0.25 dB
3	Dimensions	Overall length: 330 mm (Tip: 16mm) Tip diameter: 5 mm (Body: 8 mm) Distance from probe tip to sensor centers: 2.5 mm
S	Application	General dosimetry up to 3 GHz Dosimetry in strong gradient fields Compliance tests of Mobile Phones

Isotropic E-Field Probe

The isotropic E-Field probe has been fully calibrated and assessed for isotropicity, and boundary effect within a controlled environment. Depending on the frequency for which the probe is calibrated the method utilized for calibration will change.

The E-Field probe utilizes a triangular sensor arrangement as detailed in the diagram below:



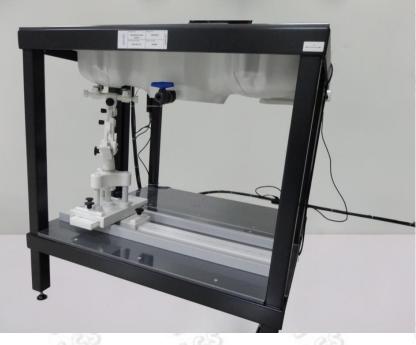
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3.3. Phantoms

The SAM Phantom SAM117 is constructed of a fiberglass shell ntegrated in a wooden table. The shape of the shell is in compliance with the specification set in IEEE P1528 and CENELEC EN62209-1, EN62209-2:2010. The phantom enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents the evaporation of the liquid. Reference markings on the Phantom allow the complete setup of allpredefined phantom positions and measurement grids by manually teaching three points in the robo

System checking was performed using the flat section, whilst Head SAR tests used the left and right head profile sections. Body SAR testing also used the flat section between the head profiles.



SAM Twin Phantom

3.4. Device Holder

In combination with the Generic Twin PhantomSAM117, the Mounting Device enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation points is the ear opening. The devices can be easily, accurately, and repeatedly positioned according to the FCC and CENELEC specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).



Device holder supplied by SATIMO

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3.5. Scanning Procedure

The procedure for assessing the peak spatial-average SAR value consists of the following steps

Power Reference Measurement

The reference and drift jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method.

Area Scan

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. Thesophisticated interpolation routines implemented in OPENSAR software can find the maximum locations even in relatively coarse grids. The scan area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom. When the area scan's property sheet is brought-up, grid was at to 15 mm by 15 mm and can be edited by a user.

Zoom Scan

Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default zoom scan measures 7 x 7 x 7 points within a cube whose base faces are centered around the maximum found in a preceding area scan job within the same procedure. If the preceding Area Scan job indicates more then one maximum, the number of Zoom Scans has to be enlarged accordingly (The default number inserted is 1).

Power Drift measurement

The drift job measures the field at the same location as the most recent reference job within the same procedure, and with the same settings. The drift measurement gives the field difference in dB from the reading conducted within the last reference measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. In the properties of the Drift job, the user can specify a limit for the drift and have OPENSAR software stop the measurements if this limit is exceeded.

3.6. Data Storage and Evaluation

Data Storage

The OPENSAR software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm²], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation

The OPENSAR software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Normi,	ai0, ai1, ai
160	- Conversion factor	ConvF	i 🔧
	- Diode compression p	oint	Dcpi
Device parameters	: - Frequency	N.FO	
	- Crest factor	cf	
Media parameters:	- Conductivity	σ	
	- Density	ρ	

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These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the OPENSAR components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

With Vi = compensated signal of channel i (i = x, y, z) Ui = input signal of channel i (i = x, y, z) cf = crest factor of exciting field dcpi = diode compression point

From the compensated input signals the primary field data for each channel can be evaluated:

$$E - field probes : \qquad E_i = \sqrt{\frac{1}{Norm}}$$

H – fieldprobes :

 $H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f}{f}$ (i = x, y, z) (i = x, y, z)

 $i_i \cdot ConvF$

Vi	= compensated signal of channel i
Normi	= sensor sensitivity of channel i
	[mV/(V/m)2] for E-field Probes
ConvF	= sensitivity enhancement in solution
aij =	sensor sensitivity factors for H-field probes
	ConvF

= carrier frequency [GHz]

= electric field strength of channel i in V/m

= magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units. σ

 $SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1'000}$

with SAR

Ei

Hi

σ

R = local specific absorption rate in mW/g Etot = total field strength in V/m

- = conductivity in [mho/m] or [Siemens/m]
- = equivalent tissue density in g/cm3

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

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- Body worn Position (1) To position the EUT parallel to the phantom surface.
 - (2) To adjust the EUT parallel to the flat phantom.
 - (3) To adjust the distance between the EUT surface and the flat phantom to 0mm.

For body SAR test we applied to FCC KDB447498 D01v05r02, KDB248227 D01v01r02, KDB616217 D04v01r01, KDB 447498 D01

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3.7. Tissue Dielectric Parameters for Head and Body

The liquid used for the frequency range of 100MHz-6G consisted of water, sugar, salt and Cellulose. The liquid has been previously proven to be suited for worst-case. The following Tableshows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528 and IEC 62209.

The simulating liquids should be checked at the beginning of a series of SAR measurements to determine of the determine of the dielectric parameter are within the tolerances of the specified target values. The measured conductivity and relative permittivity should be within \pm 5% of the target values.

The following materials are used for producing the tissue-equivalent materials.

Ingredients	Frequency (MHz)								
(% by weight)	835	900	1800	2000	2450				
Water	41.45	40.92	16.33	54.89	46.70				
Sugar	56.0	56.5	1	1	3.97				
Salt	4.45	1.48	0.41	0.18	1				
Preventol	0.19	0.1	5-1	-1	150				
Cellulose	0.1	0.4	357	1	1.35				
Clycol Monobutyl	1	557	65.3	44.93	53.3				
Dielectric ParametersTarget Value	f=835MHz ε =41.5 σ =0.90	f=900MHz ε =41.5 σ =0.97	f=1800MHz ε =40.0 σ =1.40	f=1950 MHz ε =40.0 σ =1.40	f=2450 MHz ε =39.2 σ =1.80				

Table 3. Composition of the Body Tissue Equivalent Matter

Ingredients	Frequency (MHz)							
(% by weight)	835	1800	1900	2450	2600			
Water	52.4	69.91	69.91	73.2	64.493			
Sugar	45.0 0.0		0.0	0.0	0.0			
Salt	1.4	0.13	0.13	0.04	0.024			
HEC	1.0	0.0	0.0	0.0	0.0			
Bactericide	0.1	0.0	0.0	0.0	0.0			
Triton X-100	0.0	0.0	0.0	0.0	0.0			
DGBE	0.0	29.96	29.96	26.7	32.252			
Dielectric ParametersTarget Value	f=835MHz ε =55.2 σ =0.97	f=1800MHz ε =53.30 σ =1.52	f=1900MHz ε =53.30 σ =1.52	f=2450 MHz ε =52.7 σ =1.95	f=2450 MHz ε =52.5 σ =2.16			

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SHENZHEN LCS COMPLI	ANCE TESTING LABORATORY LTD.	FCC ID:2AF2V-MGT101

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Frequency (MHz)	Liquid Type	Liquid Type (\pm 5% Range	Permittivity (٤)	\pm 5% Range		
150	Head	0.76	0.72~0.80	52.3	49.69~54.92		
300	Head	0.87	0.83~0.91	45.3	43.04~47.57		
450	Head	0.87	0.83~0.91	43.5	41.33~45.68		
835	Head	0.90	0.86~0.95	41.5	39.43~43.58		
900	Head	0.97	0.92~1.02	41.5	39.43~43.58		
915	Head	0.98	0.93~1.03	41.5	39.43~43.58		
1450	Head	1.20	1.14~1.26	40.5	38.48~42.53		
1610	Head	1.29	1.23~1.35	40.3	38.29~42.32		
1800-2000	Head	1.40	1.33~1.47	40.0	38.00~42.00		
2450	Head	1.80	1.71~1.89	39.2	37.24~41.16		
3000	Head	2.40	2.28~2.52	38.5	36.58~40.43		
5800	Head	5.27	5.01~5.53	35.3	33.54~37.07		
150	Body	0.80	0.76~0.84	61.9	58.81~65.00		
300	Body	0.92	0.87~0.97	58.2	55.29~61.11		
450	Body	0.94	0.89~0.99	56.7	53.87~59.54		
835	Body	0.97	0.92~1.02	55.2	52.44~57.96		
900	Body	1.05	1.00~1.10	55.0	52.25~57.75		
915	Body	1.06	1.01~1.11	55.0	52.25~57.75		
1450	Body	1.30	1.24~1.37	54.0	51.30~56.70		
1610	Body	1.40	1.33~1.47	53.8	51.11~56.49		
1800-2000	Body	1.52	1.44~1.60	53.3	50.64~55.97		
2450	Body	1.95	1.85~2.05	52.7	50.07~55.34		
3000	Body	2.73	2.59~2.87	52.0	49.40~54.60		
5800	Body	6.00	5.70~6.30	48.2	45.79~50.61		

3.8. Dielectric Performance

Dielectric Performa	nce of Head and Body	Tissue Simulat	ing Liquid
Measurement is made at temperature 22.0°Ca	and relative humidity 5	52%.	
Liquid temperature during the test: 22.0° C	S 5	3 1	B. Bas
Measurement Date: 2450 MHz September 28	3, 2015;	23	Read Read
Frequency	as b	Body Tissu	e Solo
(MHz)	O'(S/m)	L'S'A	εr
2450	1.93	Read	53.61
10-	1190	0.60	0.000

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3.9. Basic SAR system validation requirements

The SAR system must be validated against its performance specifications before it is deployed when SAR probe and system component or sorftware are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such component. Reference dipoles are used with the required tissure-equivalent media for system validation

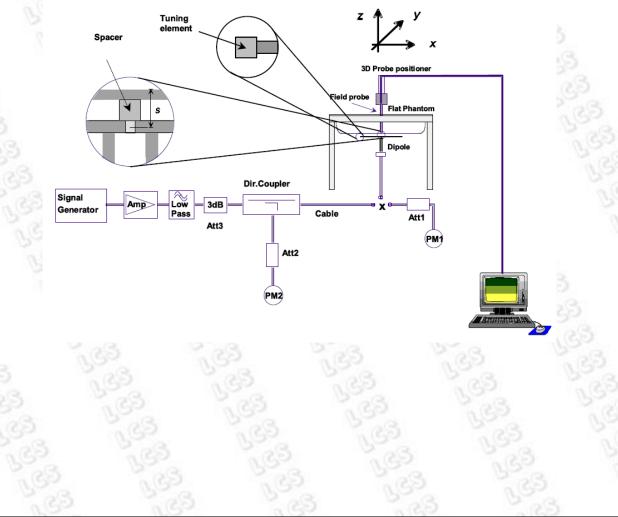
The detailed system validation result are maintained by each test laboratory, which are normally not required for equip-ment approval. Only a tabulated summary of the system validation status, according to the validation date(s) measure-ment frequencies, SAR probe and tissue dielectric parameters is required in the SAR report.

LCS lab has performed the system validation at 10/28/2014, and all the measured results within \pm 10% of the system calibrated SAR targets.

3.10. System setup

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of system in order to guarantee reproducieble results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of component, but indicates situations where the system uncertainty is exceeded due to drift or failure.

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



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Ree		1.90	System Valio	ation of Body	00	5	1.68
	P	Measurement is ma	de at temperature	22.0 °C and relati	ve humidity 52%.		
0	દુરુ	Measurer	ment Date: 2450 M	Hz September 28	, 2015	as	12-
Verification	cation Frequency (W/kg)				sured (W/kg)	Devia	tion
Results	(MHz)	1 g Average	10 g Average	1 g Average	10 g Average	1 g Average	10 g Average
Body	2450	54.65	24.58	54.56	25.11	0.165	2.16

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3.11. Measurement procedure

The following procedure shall be performed for each of the test conditions

- 1. Measure the local SAR at a test point within 4 mm or less in the normal direction from the inner surface of the phantom.
- 2. Measure the two-dimensional SAR distribution within the phantom (area scan procedure). The boundary of the measurement area shall not be closer than 20 mm from the phantom side walls. The distance between the measurement points should enable the detection of the location of localmaximum with an accuracy of better than half the linear dimension of the tissue cube after interpolation. A maximum grip spacing of 20 mm for frequencies below 3 GHz and (60/f [GHz]) mm for frequencies of 3GHz and greater is recommended. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz andoln(2)/2 mm for frequencies of 3 GHz and greater, whereois theplane wave skin depth and ln(x) is the natural logarithm. The maximum variation of thesensor-phantom surface shall be ±1 mm for frequencies below 3 GHz and ±0.5 mm forfrequencies of 3 GHz and greater. At all measurement points the angle of the probe with respect to the line normal to the surface should be less than 5°. If this cannot be achieved for ameasurement distance to the phantom inner surface shorter than the probe diameter, additionalmeasurement distance to the phantom inner surface shorter than the probe diameter, additionalmeasurement distance to the phantom inner surface shorter than the probe diameter, additionalmeasurement distance to the phantom inner surface shorter than the probe diameter, additionalmeasurement distance to the phantom inner surface shorter than the probe diameter, additionalmeasurement distance to the phantom inner surface shorter than the probe diameter, additionalmeasurement distance to the phantom inner surface shorter than the probe diameter, additionalmeasurement distance to the phantom inner surface shorter than the probe diameter, additionalmeasurement distance to the phantom inner surface shorter than the probe diameter, additionalmeasurement distance to the phantom inner surface shorter than the probe diameter.
- 3. From the scanned SAR distribution, identify the position of the maximum SAR value, in addition identify the positions of any local maxima with SAR values within 2 dB of the maximum value that are not within the zoom-scan volume; additional peaks shall be measured only when the primary peak is within 2 dB of the SAR limit. This is consistent with the 2 dB threshold already stated;
- 4. Measure the three-dimensional SAR distribution at the local maxima locations identified in step
- 5. The horizontal grid step shall be (24 / f[GHz]) mm or less but not more than 8 mm. The minimum zoom size of 30 mm by 30 mm and 30 mm for frequencies below 3 GHz. For higher frequencies, the minimum zoom size of 22 mm by 22 mm and 22 mm. The grip step in the vertical direction shall be (8-f[GHz]) mm or less but not more than 5 mm, if uniform spacing is used. If variable spacing is used in the vertical direction, the maximum spacing between the two closest measured points to the phantom shell shall be (12 / f[GHz]) mm or less but not more than 4 mm, and the spacing between father points shall increase by an incremental factor not exceeding 1.5. When variable spacing is used, extrapolation routines shall be tested with the same spacing as used in measurements. The maximum distance between the geometrical centre of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\delta \ln(2)/2$ mm for frequencies of 3 GHz and greater, where δ is the plane wave skin depth and In(x) is the natural logarithm. Separate grids shall be centered on each of the local SAR maxima foundin step c). Uncertainties due to field distortion between the media boundary and the dielectricenclosure of the probe should also be minimized, which is achieved is the distance between thephantom surface and physical tip of the probe is larger than probe tip diameter. Other methodsmay utilize correction procedures for these boundary effects that enable high precisionmeasurements closer than half the probe diameter. For all measurement points, the angle of theprobe with respect to the flat phantom surface shall be less than 5. If this cannot be achieved an additional uncertainty evaluation is needed.
- 6. Use post processing(e.g. interpolation and extrapolation) procedures to determine the localSAR values at the spatial resolution needed for mass averaging.

4.OUTPUT POWER VERIFICATION

4.1. Test condition:

- 1. All test measurements carried out are traceable to national standard. The uncertainty of the measurement at a confidence level of approximately 95% (in the case where distributions are nomal), with a coverage factor of 2, In the range of 30MHz-40GHz is ±1.5dB.
- 2. Evironment conditions:

Temperature23℃Relative Humidy53%Atmospheric Pressure1019mbar26,2015~September 29,2015

3. Test Date: September 26,2015~September 29,2015 Tested By:Dick

4.2. Test Procedure:

EUT radio output power measurement

- 1. Select lowest, middle, and highest channels for each band and different possible test mode.
- 2. Measure the conducted average bust power from EUT antenna port.

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4.3. Conducted Power Measurement

Mode	channel	Frequency (MHz)	Conducted output AVG power(dBm)	Test Rate Date
ES I	3 1 °	2412	16.74	1Mbps
802.11b	6	2437	16.09	1Mbps
	311	2462	15.31	1Mbps
LES	195	2412	17.83	6Mbps
802.11g	6	2437	17.63	6Mbps
	11	2462	16.28	6Mbps
a BG	1 3	2412	16.72	6.5Mbps
802.11n 20MHz	6	2.437	16.06	6.5Mbps
	23 11	2462	15.18	6.5Mbps

Conducted power measurements of Wifi 2.4GHz

Note:

According to the KDB248227, for WiFi 2.4G, highest average RF output power channel for the lowest date rate of 802.11b mode was selected for SAR evaluation. SAR test at higher date rates and higher order modulations(including 802.11g/n) were not required since the maximum average output powerfor each of these configurations is not more than 1/4dB higher than the tested channnel for the lowest date rate of 802.11b mode.

Conducted power measurement of BluetoothV4.0

Mode	channel	Frequency (MHz)	Conducted output power (dBm)
s cs	1 23	2402	3.803
BLE	20	2440	3.351
	40	2480	2.013

Note:

According to KDB447498 D01 General RF Exposure Guidence v05r01 standalone SAR test exclusion considerations,SAR test is not required in 100MHz to 6GHz at test separation distances ≤50mm, if the output of EUT satisfay the fllowing eqation:

[(max power of channel,including tune-up tolerance,mW)/(min test separation distance,mm)].[$f^{1/2}_{(GHz)}$]. \leq 3.0 For 1-g SAR and \leq 7.5 for 10-g extremity SAR.

- a. $f_{(GHz)}$ is the RF channel transmit frequency in GHz.
- b. Power and distance are rounded to the nearest mW and mm before calculation
- c. The result is rounded to one decimal place for comparison
- d. 3.5 and 7.5 are referred to as the numeric thresholds

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5.SAR TEST RESULT

5.1. Test condition:

1. SAR Measuremnt

The distance between the EUT and the antenna of the emulator is more than 50cm and the out put power radiated from the emulator antenna is at least 30dB less than the output power of EUT.

- 2. Measurement Uncertainty: See page 36and37 for detail
- 3. Environmental Conditions

Temperature Relative Humidity Atmospheric Pressure 6,2015~September 29,2015

23℃ 53% 1019mbar

 Test Date: September 26,2015~September 29,2015 Test By: Dick

5.2. Operation Mode

• According to KDB 447498 D01 v05r02 ,for each exposure position, if the highest 1-g SAR is \leq 0.8 W/kg, testing for low and high channel is optional.

• Per KDB 865664 D01 v01r03, for each frequency band, if the measured SAR is ≥ 0.8 W/Kg, testing for repeated SAR measurement is required, that the highest measured SAR is only to be tested. When the SAR results are near the limit, the following procedures are required for each device to verify these types of SAR measurement related variation concerns by repeating the highest measured SAR configuration in each frequency band.

(1) When the original highest measured SAR is \geq 0.8W/Kg, repeat that measurement once.

(2) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is >1.20 or when the original or repeated measurement is \ge 1.45 W/Kg.

(3) Perform a third repeated measurement only if the original, first and second repeated measurement is \geq 1.5 W/Kg and ratio of largest to smallest SAR for the original, first and second measurement is \geq 1.20.

• According to 616217 D04 the procedures are applicable only when the overall diagonal dimen of the keyboard and/or display section of a laptop or tablet is >20cm.

• According to 248227 D01, SAR is not required for 802.11g channels when the maximum average output power is less than 1/4dB higher than measured on the corresponding 802.11b channels.

• Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:

Maximum Scaling SAR =tested SAR (Max.) \times [maximum turn-up power (mw)/ maximum measurement output power(mw)]

5.3. SAR summary Test result

Fred	quency	Conducted		Test SAD(4x) Bower Conducted Up Scaled			Scaled	Limit		
MHz	Channel	Mode/Band	Test Position	SAR(1g) (W/kg)	Power Drift(%)	Power (dBm)	Power		1g(W/kg)	
2437	6	802.11b	Left	0.181	-1.01	16.09	17	0.223	1.60	
2437	6	802.11b	Rear	0.697	0.18	16.09	17	0.859	1.60	

SAR Values for WLAN2450 Band -Body

Note:

1.When the SAR measured for the middle channel is ≤ 50% of the limit, test in the low and high channel is optional. 2. The result was tested under the lowest data rate 1Mbps for 802.11b.

5.4. Testreduction procedure

Length: 263 m

тор

The following picture showed that the antenna position of the DUT.So according to KDB447498 and KDB 616217 for SAR testing.

LEFT Jara Image: Constraint of the state of the s

Figure 1: The diagonal dimension of the DUT

160
SAR Conclusion
Tested
No
No
Tested
No

Per KDB941225 D06, for the antenna-to-edge distance is greater than 2.5cm, so the right, top, Bottom sides Does not need to be tested.

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5.5. Measurement Uncertainty (700MHz-3GHz)

UNCERTAINTY FOR SYSTEM PERFORMANCE CHECK

		Tol.	Prob.		G	G	1 g	10 g	
		(± %)	Dist.	Div.	(1 g)	(10 g)	UI I	u,	
Uncertainty Component		(=)			(1.8)	(10 g)	(± %)	(± %)	V
Measurement System									
Probe Calibration	7.2.1	5.8	N	1	1	1	5.80	5.80	00
Axial Isotropy	7.2.1.1	3.5	R	√3	$(1-c_p)^{1/2}$	$(1-c_{\rm p})^{1/2}$	1.43	1.43	00
Hemispherical Isotropy	7.2.1.1	5.9	R	√3	√Cp	√Cp	2.41	2.41	00
Boundary Effect	7.2.1.4	1	R	√3	1	1	0.58	0.58	00
Linearity	7.2.1.2	4.7	R	√3	1	1	2.71	2.71	00
System Detection Limits	7.2.1.2	1	R	√3	1	1	0.58	0.58	00
Modulation response	7.2.1.3	0	N	1	1	1	0.00	0.00	00
Readout Electronics	7.2.1.5	0.5	N	1	1	1	0.50	0.50	00
Response Time	7.2.1.6	0	R	√3	1	1	0.00	0.00	00
Integration Time	7.2.1.7	1.4	R	√3	1	1	0.81	0.81	80
RF Ambient Conditions - Noise	7.2.3.7	3	R	√3	1	1	1.73	1.73	00
	7.2.3.7	3	R	√3	1	1	1.73	1.73	00
Probe Positioner Mechanical		1.4							
Tolerance	7.2.2.1		R	√3	1	1	0.81	0.81	00
Probe Positioning with respect to		1.4							
Phantom Shell	7.2.2.3		R	√3	1	1	0.81	0.81	00
Extrapolation, interpolation and									
Integration Algorithms for Max. SAR		2.3	_	1-					
E valuation	7.2.4		R	√3	1	1	1.33	1.33	00
Dipole		1			1				
Deviation of experimental source				1	1	1			
from numerical source		4	N				4.00	4.00	00
Input Power and SAR drift	7			. 10			0.00	0.00	
measurement	7.2.3.6	5		√3	1	1	2.89	2.89	00
Dipole Axis to Liquid Distance Phantom and Tissue Parameters		2	ĸ	√3	1	1			00
Phantom Uncertainty (shape and		1			1				
thickness tolerances)		4	R	√3	1	1	2.31	2.31	00
Uncertainty in SAR correction for			ĸ	13	1		2.31	2.31	~
deviation (in permittivity and		2	N	1	1	0.84	2.00	1.68	00
conductivity)	7.2.6	2			'	0.04	2.00	1.00	~
Liquid Conductivity (temperature	1.2.0								
uncertainty)	7.2.3.5	2.5	N	1	0.78	0.71	1.95	1.78	5
Liquid Conductivity - measurement	1.2.3.3								
uncertainty	7.2.3.3	4	N	1	0.23	0.26	0.92	1.04	5
Liquid Permittivity (temperature	1.2.0.0								
uncertainty)	7.2.3.5	2.5	N	1	0.78	0.71	1.95	1.78	00
Liquid Permittivity - measurement		-		-					
uncertainty	7.2.3.4	5	N	1	0.23	0.26	1.15	1.30	00
Combined Standard Uncertainty			RSS				10.15	10.05	
Expanded Uncertainty									
(95% CONFIDENCE INTERVAL)			k				20.29	20.10	

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UNCERTAINTY EVALUATION FOR HANDSET SAR TEST

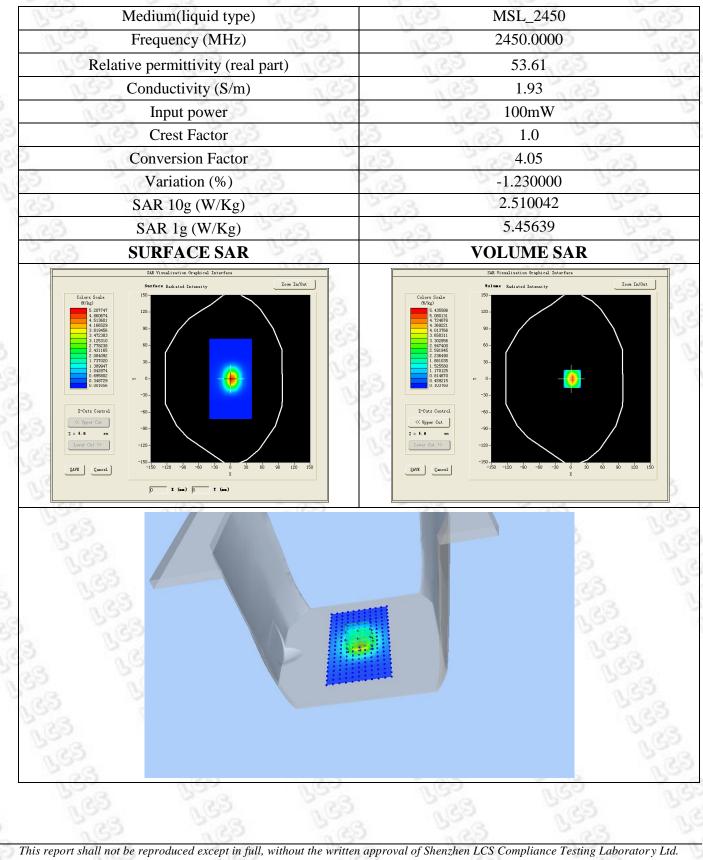
		Tol.	Prob.		ō	٥	1 g	10 g	
		(± 96)	Dist.	Div.	(1 g)	(10 g)	U	U	
Uncertainty Component	Description	()			(1.8/	(10.8/	(± %)	(± %)	Vj
Measurement System									
Probe Calibration	7.2.1	5.8	N	1	1	1	5.8	5.8	
Axial Is otropy	7.2.1.1	3.5	R	√3	$(1-c_p)^{1/2}$	$(1-c_p)^{1/2}$	1.43	1.43	8
Hemispherical Is otropy	7.2.1.1	5.9	R	√3	√ Cp	√Cp	2.41	2.41	
Boundary Effect	7.2.1.4	1	R	√3	1	1	0.58	0.58	
Linearity	7.2.1.2	4.7	R	√3	1	1	2.71	2.71	8
System Detection Limits	7.2.1.2	1	R	√3	1	1	0.58	0.58	
Modulation response	7.2.1.3	3	N	1	1	1	3.00	3.00	8
Readout Electronics	7.2.1.5	0.5	N	1	1	1	0.50	0.50	
Res pons e Time	7.2.1.6	0	R	√3	1	1	0.00	0.00	
Integration Time	7.2.1.7	1.4	R	√3	1	1	0.81	0.81	
RF Ambient Conditions - Noise	7.2.3.7	3	R	√3	1	1	1.73	1.73	
RF Ambient Conditions - Reflections	7.2.3.7	3	R	√3	1	1	1.73	1.73	
Probe Positioner Mechanical									
Tolerance	7.2.2.1	1.4	R	√3	1	1	0.81	0.81	60
Probe Positioning with respect to			_	10					
Phantom Shell	7.2.2.3	1.4	R	√3	1	1	0.81	0.81	
Extrapolation, interpolation and									
Integration Algorithms for Max. SAR		2.3	R	√3	1	1	1.33	1.33	
Evaluation	7.2.4								
Test sample Related									
Test Sample Positioning	7.2.2.4.4	2.6	N	1	1	1	2.60	2.60	11
	7.2.2.4.2	3	N	1	1	1	3.00	3.00	7
Device Holder Uncertainty	7.2.2.4.3								
Output Power Variation - SAR drift		5	R	√3	1	1	2.89	2.89	00
measurement	7.2.3.6	-	_	1.0					
SAR scaling	7.2.5	2	R	√3	1	1	1.15	1.15	
Phantom and Tissue Parameters	-								
Phantom Uncertainty (shape and		4	R	√3	1	1	2.31	2.31	
thickness tolerances)	7.2.2.2								
Uncertainty in SAR correction for									
deviation (in permittivity and		2	N	1	1	0.84	2.00	1.68	00
conductivity)	7.2.6								
Liquid Conductivity (temperature		2.5	N	1	0.78	0.71	1.95	1.78	5
uncertainty)									-
	7.2.3.5								
Liquid Conductivity - measurement		4	N	1	0.23	0.26	0.92	1.04	5
uncertainty	7.2.3.5		N	1	0.23	0.26	0.92	1.04	5
uncertainty Liquid Permittivity (temperature	7.2.3.3	4							5
uncertainty Liquid Permittivity (temperature uncertainty)			N	1	0.23 0.78	0.28	0.92 1.95	1.04 1.78	
uncertainty Liquid Permittivity (temperature uncertainty) Liquid Permittivity - measurement	7.2.3.3	4			0.78	0.71	1.95	1.78	
uncertainty Liquid Permittivity (temperature uncertainty) Liquid Permittivity - measurement uncertainty	7.2.3.3	4 2.5	N	1			1.95 1.15	1.78 1.30	
uncertainty Liquid Permittivity (temperature uncertainty) Liquid Permittivity - measurement uncertainty Combined Standard Uncertainty	7.2.3.3	4 2.5	N	1	0.78	0.71	1.95	1.78	
uncertainty Liquid Permittivity (temperature uncertainty) Liquid Permittivity - measurement uncertainty	7.2.3.3	4 2.5	N	1	0.78	0.71	1.95 1.15	1.78 1.30	

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5.6. System Check Results

Test mode:2450MHz(Body) Product Description:Validation Model:Dipole SID2450 E-Field Probe:SSE5(SN17/14 EP220) Test Date:September 28, 2015



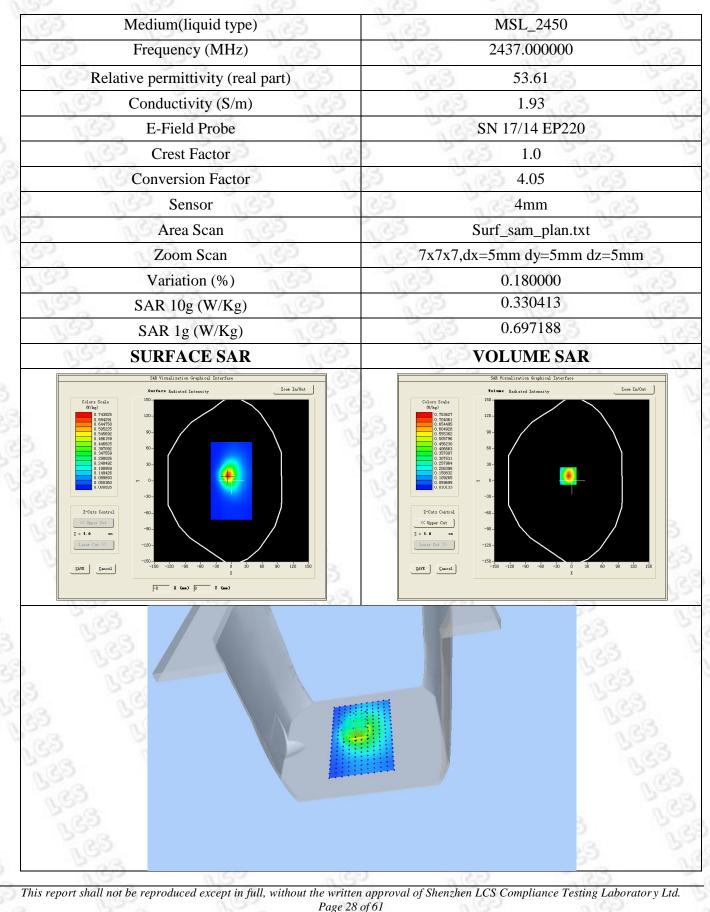
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5.7. SAR Test Graph Results

Test Mode:802.11b,Mid channel(Body SAR-LCD DOWN) Product Description: 10.1 inch Quad core capacitive touch tablet Model:MGT101

Test Date: September 28, 2015



6.CALIBRATION CERTIFICATES

SARTIMO Calibration Certificate-Extended Dipole Calibrations

According to KDB 450824 D02, Dipoles must be recalibrated at least once every three years; however, immediate re-calibration is required for following conditions. The test laboratory must ensure that the required supporting information and documentation have been included in the SAR report to qualify for extended 3-year calibration interval.

- 1) When the most recent return-loss, measured at least annually, deviates by more than 20% from theprevious measurement (i.e. 0.2 of the dB value) or not meeting the required -20 dB return-loss specification
- 2) When the most recent measurement of the real or imaginary parts of the impedance, measured at least annually, deviates by more than 5 ∩ from the previous measurement

Summary Result:

SID 2450	CED .	63, 63	1 CS
Frquency	Return Loss(dB)	Requirement(dB)	Impedence
2450	-25.61	-20	44.9Ω-0.9jΩ

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